

# R-Car Salvator Board X(S) System Evaluation Board

## R-Car CAN Extension Board

User's Manual: Hardware

Y-RCAR-CAN-EXT-BRD

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## General Precautions in the Handling of Microprocessing Unit and Microcontroller Unit Products

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### 1. Handling of Unused Pins

Handle unused pins in accordance with the directions given under Handling of Unused Pins in the manual.

- The input pins of CMOS products are generally in the high-impedance state. In operation with an unused pin in the open-circuit state, extra electromagnetic noise is induced in the vicinity of LSI, an associated shoot-through current flows internally, and malfunctions occur due to the false recognition of the pin state as an input signal become possible. Unused pins should be handled as described under Handling of Unused Pins in the manual.

### 2. Processing at Power-on

The state of the product is undefined at the moment when power is supplied.

- The states of internal circuits in the LSI are indeterminate and the states of register settings and pins are undefined at the moment when power is supplied.  
In a finished product where the reset signal is applied to the external reset pin, the states of pins are not guaranteed from the moment when power is supplied until the reset process is completed.  
In a similar way, the states of pins in a product that is reset by an on-chip power-on reset function are not guaranteed from the moment when power is supplied until the power reaches the level at which resetting has been specified.

### 3. Prohibition of Access to Reserved Addresses

Access to reserved addresses is prohibited.

- The reserved addresses are provided for the possible future expansion of functions. Do not access these addresses; the correct operation of LSI is not guaranteed if they are accessed.

### 4. Clock Signals

After applying a reset, only release the reset line after the operating clock signal has become stable. When switching the clock signal during program execution, wait until the target clock signal has stabilized.

- When the clock signal is generated with an external resonator (or from an external oscillator) during a reset, ensure that the reset line is only released after full stabilization of the clock signal. Moreover, when switching to a clock signal produced with an external resonator (or by an external oscillator) while program execution is in progress, wait until the target clock signal is stable.

### 5. Differences between Products

Before changing from one product to another, i.e. to a product with a different part number, confirm that the change will not lead to problems.

- The characteristics of Microprocessing unit or Microcontroller unit products in the same group but having a different part number may differ in terms of the internal memory capacity, layout pattern, and other factors, which can affect the ranges of electrical characteristics, such as characteristic values, operating margins, immunity to noise, and amount of radiated noise. When changing to a product with a different part number, implement a system-evaluation test for the given product.

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## 1. Introduction

The R-Car CAN Extension Board is part of the R-Car Salvator X(S) Evaluation Board System and serves as a simple and easy to use platform for evaluating features and performance of Renesas Electronics' R-Car H3, M3-W, or M3-N SiPs. The CAN Extension Board is an add-on board for the Salvator-X(S) boards to provide two CAN/CANFD interfaces. It cannot be used as a standalone board. It can only be used together with a Salvator X(S) board connected via the CN28 connector. The power is supplied from Salvator-X(S) board via 7pin cable to the CAN Extension Board power connector.

### Notes

1. This document describes the functionality of the R-Car CAN extension board and guides the user through its operation.  
For details regarding the operation of the R-Car SoC, refer to the device's Hardware User's Manual.
2. In this document low active signals are marked by an appended 'Z' to the pin or signal name. E.g., the reset pin is named RESETZ.
3. In this document following abbreviations are used:
  - H level, L level: high or low signal level of a digital signal, the absolute voltage value depends on the signal

### 1.1 Package Components

The Y-RCAR-CAN-EXT-BRD product package consists of the following items. After you have unpacked the box, check if your Y-RCAR-CAN-EXT-BRD package contains all these items. *Table 1.1 Package Components for the Y-RCAR-CAN-EXT-BRD* shows the packing components of the Y-RCAR-CAN-EXT-BRD package.

**Table 1.1 Package Components for the Y-RCAR-CAN-EXT-BRD**

Item	Description	Quantity
D017688	CAN Extension board for the R-Car H3, M3-W, or M3-N Salvator-X(S) board	1
D010816-24	China RoHS document	1
D017688-24	Product contents list	1
D017460-04-V02	CAN Extension board schematic printout	43
JST PHR 7-pin power connection cable	In the bag	1

### Note

Please keep the Y-RCAR-CAN-EXT-BRD packing box at hand for later reuse in sending the product for repairs or for other purposes. Always use the original packing box when transporting the Y-RCAR-CAN-EXT-BRD. If packing of your product is not complete, it may be damaged during transportation.

## 1.2 Supported Salvator X(S) Boards

This CAN Extension board cannot be used as a standalone board, it can only be used in combination with an R-Car H3, M3-W, or M3-N Salvator X(S) evaluation board. The following Salvator X(S) boards are supported:

- Y-R-CAR-H3-SIP-BOARD-SKT-xxxx
- Y-R-CAR-M3-SIP-BOARD-SKT-xxxx
- Y-R-CAR-M3N-SIP-BOARD-SKT-xxxx

## 1.3 Main Features

- 2 CAN Channels
  - IF0 using R-Car H3, M3-W, or M3-N CAN(FD)0\_TX\_A and CAN(FD)0\_RX\_A
  - IF1 using R-Car H3, M3-W, or M3-N CAN(FD)1\_TX\_A and CAN(FD)1\_RX\_A
- Operating temperature from 0 °C to +40 °C

## 1.4 R-Car CAN Extension Board Views

Following figures provide a top view of the R-Car CAN Extension board and a system view with a Salvator X(S) board.

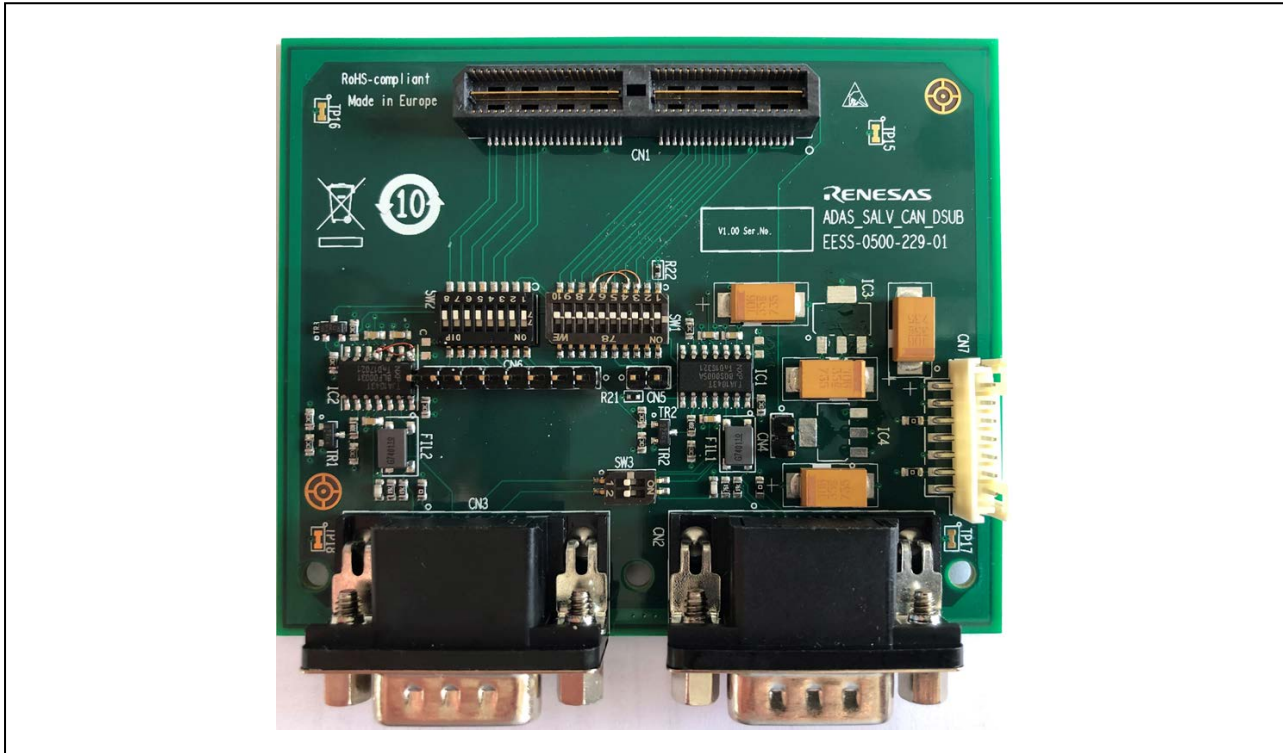


Figure 1.1 R-Car CAN Extension Board top view

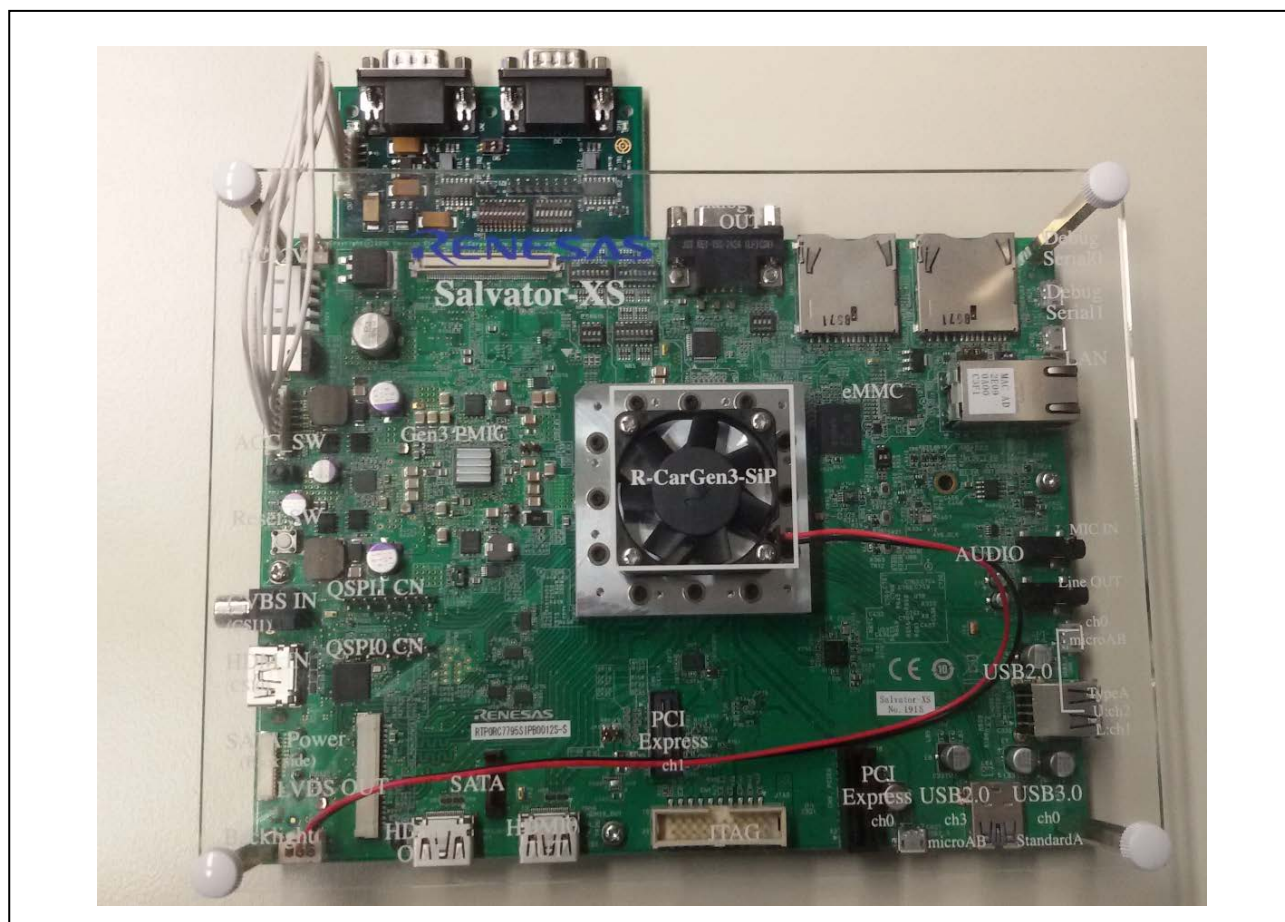
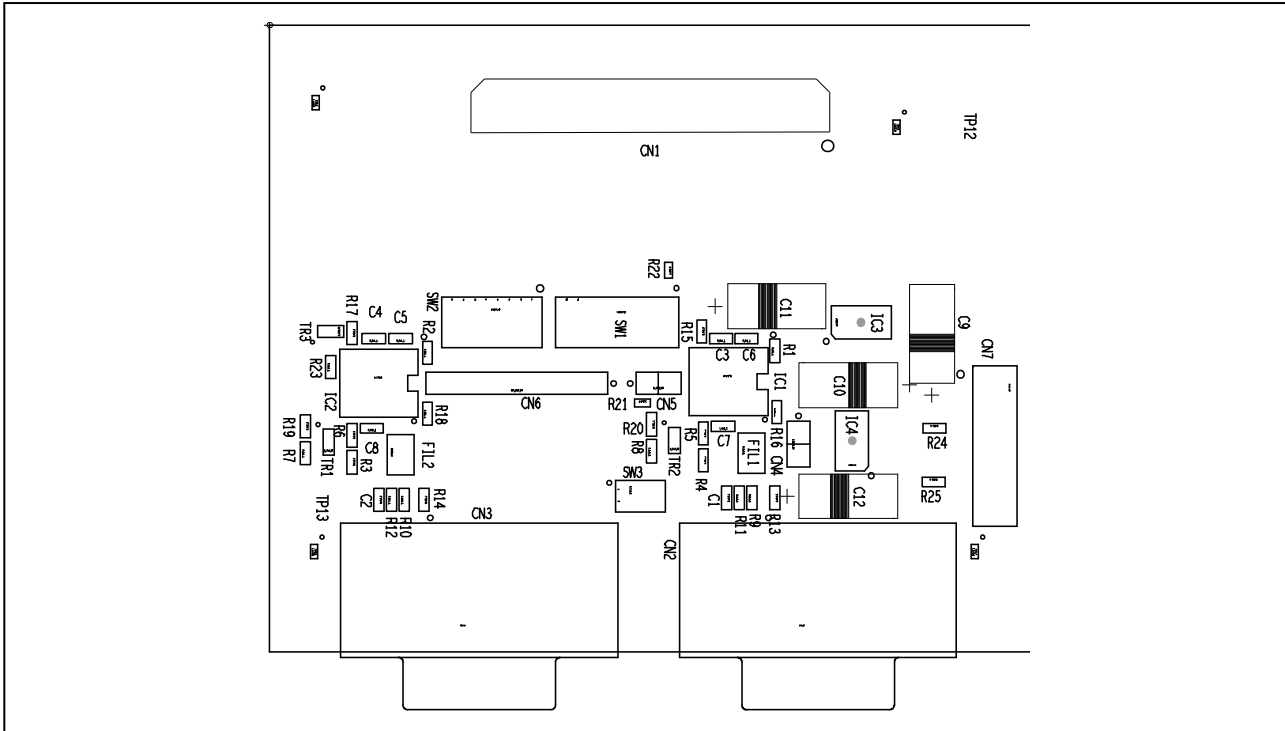


Figure 1.2 System View Salvator X(S)- and CAN Extension Board



## 2. DIP Switches

This section provides the CAN Extension Board DIP switch setting need to use both CAN interfaces.  
 The placement of these components on the board is depicted in the figure below.



**Figure 2.1 Placement of DIP Switch and Connectors**

### 2.1 DIP Switch SW1 Overview

The following table provides an overview of DIP switch SW1

**Table 2.1 SW1 Overview**

Switch	Function	Setting to use both CAN Interfaced
1	Power Control (wake up on CAN)	OFF
2	CAN0 Tx pin	ON
3	CAN0 Transceiver EN pin mapped to SoC GP1_12	ON
4	CAN0 Transceiver STB_EN pin mapped to SoC GP1_11	ON
5	---	OFF
6	CAN1 Transceiver EN pin mapped to SoC GP1_12	ON
7	CAN1 Transceiver STB_EN pin mapped to SoC GP1_11	ON
8	---	OFF

## 2.2 Connectors Overview

The following table provides an overview of all connectors.

**Table 2.2 Connector overview**

Connector	Function	Remark
CN1	Salvator X(S) Board connector	
CN2	CAN Connector IF0	
CN3	CAN Connector IF1	
CN7	Power Connector	

### 3. Connectors

#### 3.1 Connectors to the Salvator X(S) Board CN1 and CN7

The connectors CN1 and CN7 are available to connect the CAN Extension board to a Salvator X(S) Board.

The signals of each connector are summarized in the following tables.

##### 3.1.1 Salvator X(S) Board Connector

Pin	CAN Extension Board function
1	n.c.
3,7,17	GND
5, 9	n.c.
11	CANFD0_TX / SCL6
13	CANFD1_RX
15	n.c.
19	GP1_12
21	GP1_11
23	GP1_10
25	n.c.
27	SDA6
29	GP1_07
31	GP1_06
33	GP1_05
35 – 43	n.c.
45	GND
47 -61	n.c.
63	GND
65	TXD2
67	RXD2
69	SYNC2
71	SCK2
73 – 77	n.c.
81 - 87	GND

Pin	Main Board function
2	n.c.
4,8,18	GND
6,10	n.c.
12	GND
14	CANFD1_TX
16 -26	n.c.
28	PRESET
30-44	n.c.
46	GND
48	CANFD0_RX
50 - 52	n.c.
54	GND
56	n.c.
58	GND
60 – 66	n.c.
68	EX_PWRON
70 - 80	n.c.
82 – 88	GND

### 3.1.2 Power Connector CN7

Pin	Function
1	12 V
2	GND
3	5 V
4	n.c.
5	GND
6	3.3 V
7	n.c.

### 3.2 CAN Interface Connector CN2 and CN3

CN2 (IFO)	
Pin	Function
1	n.c.
2	MCANL0
3	GND via Pulldown 0 $\Omega$
4	n.c.
5	n.c.
6	n.c.
7	MCANH0
8	n.c.
9	n.c.
10	GND
11	GND

CN3(IF1)	
Pin	Function
1	n.c.
2	MCANL1
3	GND via Pulldown 0 $\Omega$
4	n.c.
5	n.c.
6	n.c.
7	MCANH1
8	n.c.
9	n.c.
10	GND
11	GND

## 4. Linux Bring Up and Restrictions

### 4.1 Linux Bring Up

To use the board with Linux, both the transceivers need to be enabled to switch from Normal state to the default standby state. Please check the README file of the zip-archive 'can-ext-board\_Vxxxx' available at:

<http://www.renesas.eu/update?oc=Y-RCAR-CAN-EXT-BRD#packageInfo>

### 4.2 Restrictions of the CAN Extension Board V1.00

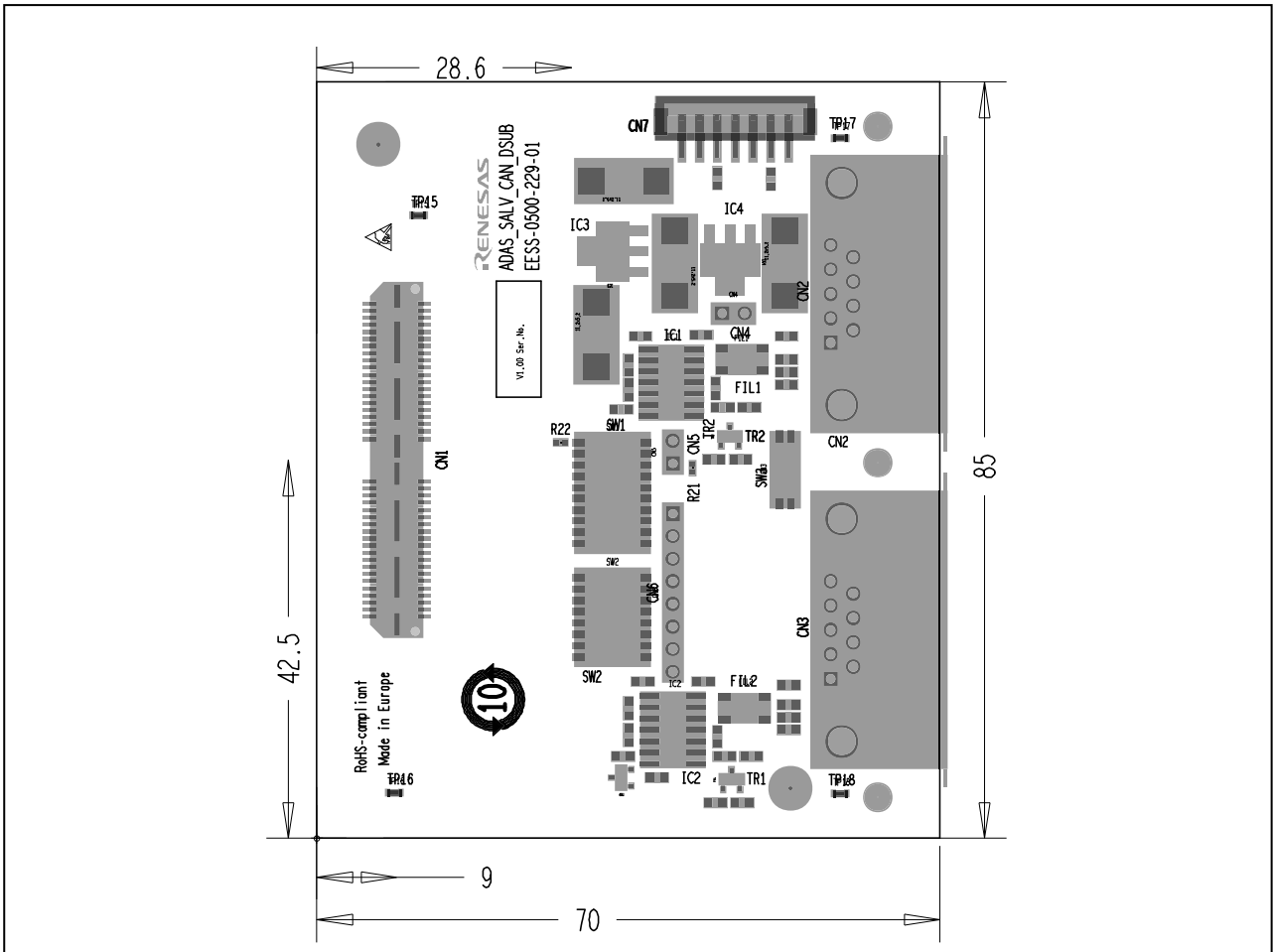
Please notice the following restrictions:

- a) JTAG and CAN0 co-existence: JTAG and the CAN board (CAN0 usage) cannot work together
- b) DU and CAN0 co-existence: DU and CAN0 may not work together as the CAN0 transceiver pin clashes with DU

### 4.3 Rework

CAN(FD)1\_TX & CAN(FD)1\_RX pins: The Rx and Tx pins are swapped, and the board is reworked for this issue

**5. Mechanical Dimensions**

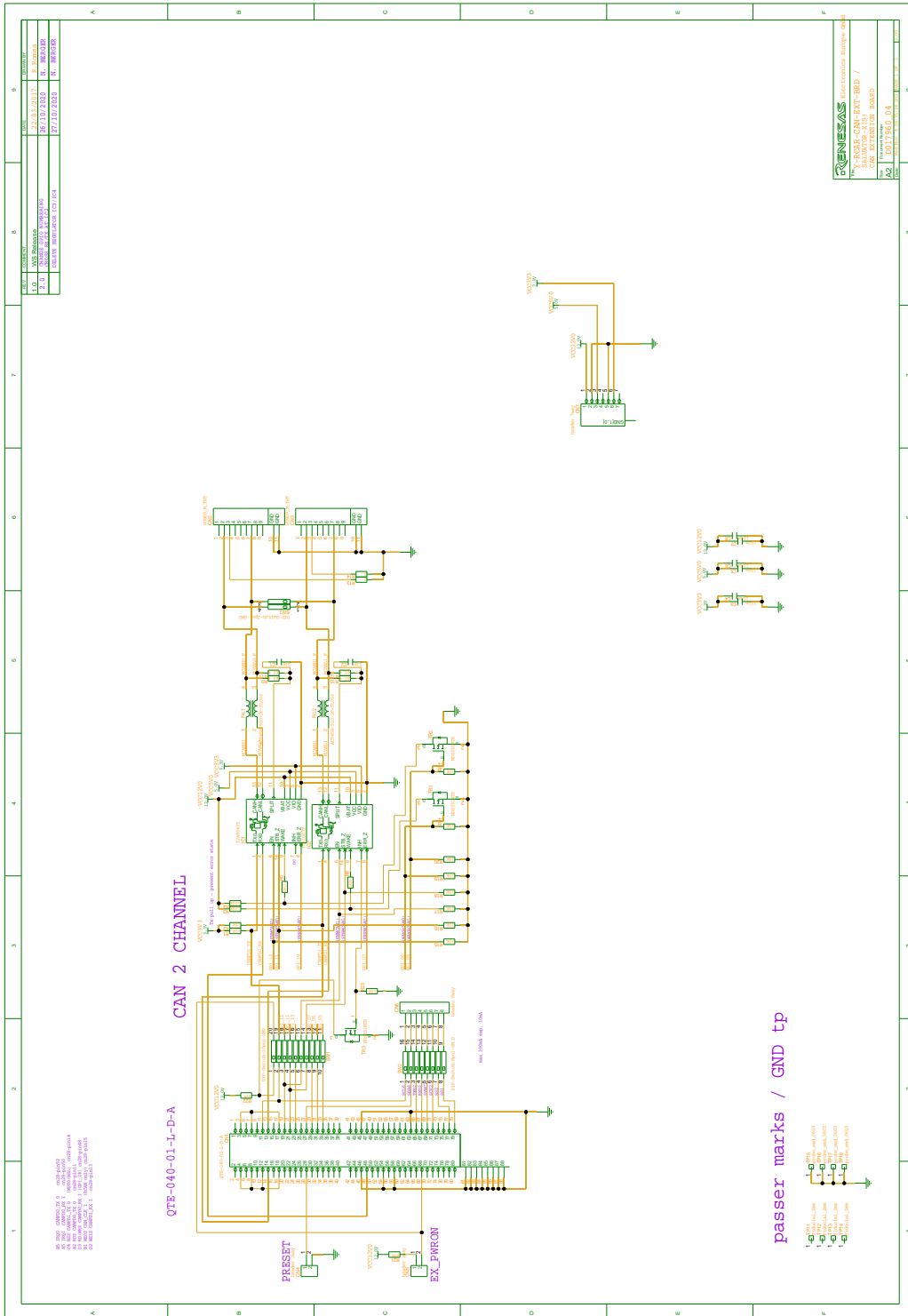


**Figure 5.1 Mechanical dimensions**

**6. Schematics**

**CAUTION**

The schematics shown in this document are not intended to be used as a reference for mass production. Any usage in an application design is in sole responsibility of the customer.



These intangible goods are not subject to Annex I of common Dual-Use list (428/2009) in its current version.

## Revision History

Rev.	Date	Description	
		Page	Summary
V1.00	August 16, 2021	–	Initial release

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