S14AD Scan Conversion Sample Code (Using CMSIS Driver Package) for RE01 1500KB Group

R_ADC Sample Code Using CMSIS Driver Package

Summary
This application note describes a sample code using the RE01 1500KB Group CMSIS driver package. The sample code can be found in the project delivered with this application note.

The overview of this sample code is shown in the table below.

<table>
<thead>
<tr>
<th>Overview of Sample Code Operation</th>
<th>Peripheral Module Mainly Used</th>
<th>Driver Module Mainly Used</th>
</tr>
</thead>
<tbody>
<tr>
<td>Performs A/D conversion using the ADC driver.</td>
<td>ADC</td>
<td>R_ADC</td>
</tr>
</tbody>
</table>

Target Device
RE01 1500KB Group

Note
When applying the sample code covered in this application note to another microcomputer, modify the code according to the specifications for the target microcomputer and conduct an extensive evaluation of the modified program.

Related Document
Startup Guide to Development Using CMSIS Package for RE01 1500KB Group (R01AN4660)
Contents

1. Specifications .......................................................................................................................... 3
   1.1 Description of Project ........................................................................................................... 3
   1.2 Pins Used ............................................................................................................................. 3
   1.3 Folder Structure .................................................................................................................... 3
   1.4 File Configuration ............................................................................................................... 4
   1.5 Option-Setting Memory ....................................................................................................... 4

2. Operating Conditions ............................................................................................................. 5

3. Description of Software ........................................................................................................ 6
   3.1 System Configuration ......................................................................................................... 6
   3.2 List of Functions ............................................................................................................... 7
   3.3 Flowcharts ........................................................................................................................ 8

4. Specifications of Driver APIs ................................................................................................ 9
   4.1 External Specification ......................................................................................................... 9

5. Usage Notes of R_ADC Driver ............................................................................................ 10
   5.1 Usage of Auto-Read Commands Using DMAC ................................................................. 10
   5.2 Registering Interrupts to NVIC ........................................................................................ 11
   5.3 Using A/D Converter in Snooze Mode ............................................................................. 12
   5.4 Pin Settings ....................................................................................................................... 12
   5.5 Calibration ....................................................................................................................... 15
   5.6 Combinations of Functions to Be Used ............................................................................. 16

6. Troubleshooting .................................................................................................................... 17
   6.1 Occurrence of Build Error with IAR compiler ................................................................. 17
   6.2 Occurrence of HardFault Error when API of CMSIS Driver Is Called ......................... 17
   6.3 Peripheral Function Fails to Operate when API Is Called ............................................. 17
   6.4 Normal API Return Value But No Pin Output from Peripheral Function ........................ 17
   6.5 Peripheral Function’s Input or Output Does Not Operate as Expected .......................... 17

7. Sample Code ......................................................................................................................... 18

8. Reference Documents .......................................................................................................... 18

Revision History ...................................................................................................................... 19
1. Specifications

1.1 Description of Project

A sample code project "an4701_hal_ad_re" is provided with this application note.

The an4701_hal_ad_re project has been tested using the Evaluation Kit RE01 1500KB (RTK70E015DSxxxxBE). This project is configured to match the settings of R7F0E015D2CFB mounted on the Evaluation Kit RE01 1500KB. When using another device, change the device settings in the project to those of the target device.

1.2 Pins Used

The pins used by the sample code are shown below.

<table>
<thead>
<tr>
<th>Pin Used</th>
<th>Purpose of Use</th>
</tr>
</thead>
<tbody>
<tr>
<td>P007</td>
<td>LED2</td>
</tr>
<tr>
<td>P008</td>
<td>LED1</td>
</tr>
<tr>
<td>P000</td>
<td>AN000</td>
</tr>
<tr>
<td>P001</td>
<td>AN001</td>
</tr>
</tbody>
</table>

1.3 Folder Structure

The folder structure of the sample code is shown below.

![Folder Structure Diagram]

**Figure 1.1 Folder Structure**
1.4 File Configuration
Table 1-1 shows the files that are added or modified for this sample code.

Table 1-1  Files Added or Modified for this Sample Code

<table>
<thead>
<tr>
<th>File Name</th>
<th>Overview of Processing or Configuration</th>
<th>Remarks</th>
</tr>
</thead>
<tbody>
<tr>
<td>main.c</td>
<td>Main processing</td>
<td></td>
</tr>
</tbody>
</table>

1.5 Option-Setting Memory
Table 1-2 shows the option-setting memory setting for the sample code. Set suitable values for a user system if required.

Table 1-2  Option-Setting Memory Setting for Sample Code

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Address</th>
<th>Setting</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>AWS</td>
<td>0100A164h to 0100A167h</td>
<td>FFFF FFFFh</td>
<td>No access window settings</td>
</tr>
<tr>
<td>OSIS</td>
<td>0100A150h to 0100A15Fh</td>
<td>FFFF FFFFh</td>
<td>No ID code protection (All FFh)</td>
</tr>
<tr>
<td>SECMPUxxx</td>
<td>00000408h to 0000043Bh</td>
<td>FFFF FFFFh</td>
<td>MPU is disabled.</td>
</tr>
<tr>
<td>OFS1</td>
<td>00000404h to 00000407h</td>
<td>FFFF FFFFh</td>
<td>After a reset, the voltage monitor 0 reset is disabled.</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>After a reset, HOCO oscillation is disabled.</td>
</tr>
<tr>
<td>OFS0</td>
<td>00000400h to 00000403h</td>
<td>FFFF FFFFh</td>
<td>Automatic activation of IWDT is disabled.</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Automatic activation of WDT is disabled.</td>
</tr>
</tbody>
</table>
2. Operating Conditions

The operation of the sample code provided with this application note has been tested under the following conditions (Table 2-1).

Table 2-1  Operating Conditions

<table>
<thead>
<tr>
<th>Item</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Microcontroller used</td>
<td>R7F0E015D2CFB 144pin</td>
</tr>
<tr>
<td>Operating frequency</td>
<td>PLL is selected as the system clock</td>
</tr>
<tr>
<td></td>
<td>- Main clock: 32 MHz</td>
</tr>
<tr>
<td></td>
<td>- PLL: 64 MHz (main clock frequency is divided by 4 and then multiplied by 8)</td>
</tr>
<tr>
<td></td>
<td>- System clock (ICLK): 64 MHz (PLL)</td>
</tr>
<tr>
<td></td>
<td>- Peripheral module clock A (PCLKA): 64 MHz (PLL frequency is not divided)</td>
</tr>
<tr>
<td></td>
<td>- Peripheral module clocks B(PCLKB): 32 MHz (PLL frequency is divided by 2)</td>
</tr>
<tr>
<td>Operating voltage</td>
<td>3.3V</td>
</tr>
<tr>
<td>Target board</td>
<td>Evaluation Kit RE01 1500KB (RTK70E015DSxxxxxBE)</td>
</tr>
<tr>
<td>Integrated Development Environment</td>
<td>GCC Renesas e² studio Version 7</td>
</tr>
<tr>
<td></td>
<td>IAR IAR Embedded Workbench for ARM Version 8.32</td>
</tr>
<tr>
<td>C compiler</td>
<td>GCC GCC ARM Embedded Version 6.3.1.20170620</td>
</tr>
<tr>
<td></td>
<td>GNU 6-2017-q2-update</td>
</tr>
<tr>
<td></td>
<td>IAR IAR C/C++ Compiler for ARM Version 8.32</td>
</tr>
<tr>
<td>Debugger</td>
<td>Segger J-Link OB</td>
</tr>
<tr>
<td>I/O header Version</td>
<td>Rev1.00</td>
</tr>
<tr>
<td>Sample code Version</td>
<td>Rev1.00</td>
</tr>
</tbody>
</table>
3. Description of Software

This sample code performs A/D conversion in continuous-scan mode using the R_ADC driver.

The pins to be used in A/D conversion are AN000 and AN001.

The sample code performs the following operations.

- After release from the reset state, initializes the A/D converter so that AN000 and AN001 are converted in continuous-scan mode.
- Starts A/D conversion.
- Performs the following processing every time 100 ms elapses.
  - Acquires the A/D-converted value of AN000, and turns LED0 on if the value is lower than 1/2 AVCC and turns LED0 off if the value is 1/2 AVCC or higher.
  - Acquires the A/D-converted value of AN001, and turns LED1 on if the value is lower than 1/2 AVCC and turns LED1 off if the value is 1/2 AVCC or higher.

<table>
<thead>
<tr>
<th>Item</th>
<th>Setting</th>
</tr>
</thead>
<tbody>
<tr>
<td>Number of A/D conversion channels</td>
<td>2</td>
</tr>
<tr>
<td>A/D conversion mode</td>
<td>Continuous-scan mode</td>
</tr>
<tr>
<td>Conditions for A/D conversion start</td>
<td>Software trigger</td>
</tr>
</tbody>
</table>

3.1 System Configuration

![System Configuration Diagram](image-url)
3.2 List of Functions
The functions added to the sample code are described here.

<table>
<thead>
<tr>
<th>Function</th>
<th>Overview</th>
<th>Header</th>
<th>Declaration</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>main</td>
<td>Main processing</td>
<td>None</td>
<td>void main(void)</td>
<td>This function calls the system initialization function to make initial settings of the ADC.</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>After that, this function performs A/D conversion every 100 ms and turns LED0 and LED1 on or off according to the conversion result.</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>Argument: None</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>Return Value: None</td>
</tr>
<tr>
<td>system_init</td>
<td>System initialization processing</td>
<td>None</td>
<td>static void system_init (void)</td>
<td>This function initializes sections, the system, the R_LPM driver, and calls the IO power supply setting function.</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>Argument: None</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>Return Value: None</td>
</tr>
</tbody>
</table>
3.3 Flowcharts

Figure 3.2 shows a flowchart of the main processing.

![Flowchart of the main processing](image)

Figure 3.2 Main Processing

![Flowchart of system initialization processing](image)

Figure 3.3 System Initialization Processing
4. Specifications of Driver APIs

4.1 External Specification

This driver contains documents that describe the external API specification. These files are contained in the Driver Specification folder within the Documents.

![Tree View]

Figure 4-1 Location of External API Specifications
5. Usage Notes of R_ADC Driver

This chapter introduces the main points to concern regarding the R_ADC driver. Note that not all notes are given here.

For other notes, see the external specification document described in "4 Specifications of Driver APIs".

5.1 Usage of Auto-Read Commands Using DMAC

When acquiring the A/D conversion result by the DMAC using an auto-read command (AD_CMD_AUTO_READ_NORMAL, AD_CMD_AUTO_READ_BLOCK, or AD_CMD_AUTO_READ_COMPARE), set the DMA resource to be used for the target interrupt source in r_adc_cfg.h.

Table 5-1 shows the definitions of configuration parameters for A/D conversion end or compare match event notification. Table 5-2 shows the definitions of values indicating methods of A/D conversion end or compare match event notification.

### Table 5-1 Definitions of Configuration Parameters for A/D Conversion End or Compare Match Event Notification

<table>
<thead>
<tr>
<th>Definition (*1)</th>
<th>Initial Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>S14AD_ADI_CONTROL</td>
<td>S14AD_USED_INTERRUPT</td>
<td>ADI conversion end notification (Initial value: Interrupt)</td>
</tr>
<tr>
<td>S14AD_GBADI_CONTROL</td>
<td>S14AD_USED_INTERRUPT</td>
<td>GBADI conversion end notification (Initial value: Interrupt)</td>
</tr>
<tr>
<td>S14AD_GCADI_CONTROL</td>
<td>S14AD_USED_INTERRUPT</td>
<td>GCADI conversion end notification (Initial value: Interrupt)</td>
</tr>
<tr>
<td>S14AD_WCMPM_CONTROL</td>
<td>S14AD_USED_INTERRUPT</td>
<td>Compare match notification (Initial value: Interrupt)</td>
</tr>
<tr>
<td>S14AD_WCMPUM_CONTROL</td>
<td>S14AD_USED_INTERRUPT</td>
<td>Compare mismatch notification (Initial value: Interrupt)</td>
</tr>
</tbody>
</table>

Note. Only an interrupt can be used for notification of CMPAI or CMPBI (notification by DMA is not possible).

### Table 5-2 Definitions of Values Indicating Methods of A/D Conversion End or Compare Match Event Notification

<table>
<thead>
<tr>
<th>Definition</th>
<th>Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>SCI_USED_INTERRUPT</td>
<td>(0)</td>
<td>A/D conversion end or compare result is notified through an interrupt or polling.</td>
</tr>
<tr>
<td>SCI_USED_DMAC0</td>
<td>(1&lt;&lt;0)</td>
<td>A/D conversion end or compare result is notified through DMAC0.</td>
</tr>
<tr>
<td>SCI_USED_DMAC1</td>
<td>(1&lt;&lt;1)</td>
<td>A/D conversion end or compare result is notified through DMAC1.</td>
</tr>
<tr>
<td>SCI_USED_DMAC2</td>
<td>(1&lt;&lt;2)</td>
<td>A/D conversion end or compare result is notified through DMAC2.</td>
</tr>
<tr>
<td>SCI_USED_DMAC3</td>
<td>(1&lt;&lt;3)</td>
<td>A/D conversion end or compare result is notified through DMAC3.</td>
</tr>
<tr>
<td>SCI_USED_DTC</td>
<td>(1&lt;&lt;15)</td>
<td>A/D conversion end or compare result is notified through DTC.</td>
</tr>
</tbody>
</table>
5.2 Registering Interrupts to NVIC

When using interrupts in the ADC or polling for interrupts, register the interrupts to the NVIC in `r_system_cfg.h` and then enable the interrupts in the Control function.

Table 5-3 shows the definition of NVIC registration for each intended use. Figure 5.1 shows an example of registering interrupts to the NVIC.

### Table 5-3 Definition of NVIC Registration for Each Intended Use

<table>
<thead>
<tr>
<th>Intended Use</th>
<th>Definition of NVIC Registration</th>
<th>Remarks</th>
</tr>
</thead>
<tbody>
<tr>
<td>When using the ADI interrupt</td>
<td><code>SYSTEM_CFG_EVENT_NUMBER_ADC140_ADI</code></td>
<td></td>
</tr>
<tr>
<td>When using the GBADI interrupt</td>
<td><code>SYSTEM_CFG_EVENT_NUMBER_ADC140_GBADI</code></td>
<td></td>
</tr>
<tr>
<td>When using the GCADI interrupt</td>
<td><code>SYSTEM_CFG_EVENT_NUMBER_ADC140_GCADI</code></td>
<td></td>
</tr>
<tr>
<td>When using the CMPAI interrupt</td>
<td><code>SYSTEM_CFG_EVENT_NUMBER_ADC140_CMPAI</code></td>
<td></td>
</tr>
<tr>
<td>When using the CMPBI interrupt</td>
<td><code>SYSTEM_CFG_EVENT_NUMBER_ADC140_CMPBI</code></td>
<td></td>
</tr>
<tr>
<td>When using the WCMPM interrupt</td>
<td><code>SYSTEM_CFG_EVENT_NUMBER_ADC140_WCMPM</code></td>
<td></td>
</tr>
<tr>
<td>When using the WCMPUM interrupt</td>
<td><code>SYSTEM_CFG_EVENT_NUMBER_ADC140_WCMPUM</code></td>
<td></td>
</tr>
<tr>
<td>When using an auto-read command (*1) (DMAC is used)</td>
<td><code>SYSTEM_CFG_EVENT_NUMBER_DMACm_INT</code> <code>m = 0 to 3</code> (*2)</td>
<td></td>
</tr>
<tr>
<td>When using an auto-read command (*1) (DTC is used)</td>
<td>(*3)</td>
<td></td>
</tr>
</tbody>
</table>

Note 1. The auto-read commands are as follows:
- `AD_CMD_AUTO_READ_NORMAL`
- `AD_CMD_AUTO_READ_BLOCK`
- `AD_CMD_AUTO_READ_COMPARE`

Note 2. When NULL is set as the argument in the callback function (callback function is not used), this setting is not needed.

Note 3. Perform NVIC registration in accordance with the source of auto read.
- When ADI is used as the source: `SYSTEM_CFG_EVENT_NUMBER_ADC140_ADI`
- When GBADI is used as the source: `SYSTEM_CFG_EVENT_NUMBER_ADC140_GBADI`
- When GCADI is used as the source: `SYSTEM_CFG_EVENT_NUMBER_ADC140_GCADI`
- When WCMPM is used as the source: `SYSTEM_CFG_EVENT_NUMBER_ADC140_WCMPM`
- When WCMPUM is used as the source: `SYSTEM_CFG_EVENT_NUMBER_ADC140_WCMPUM`

```
#define SYSTEM_CFG_EVENT_NUMBER_WDT_NMIUNDF (SYSTEM_IRQ_EVENT_NUMBER_NOT_USED) /**< Numbers 0/4/8/12/16/20/24/28 only */
#define SYSTEM_CFG_EVENT_NUMBER_ADC140_ADI (SYSTEM_IRQ_EVENT_NUMBER0) /**< Numbers 0/4/8/12/16/20/24/28 only */
#define SYSTEM_CFG_EVENT_NUMBER_ADC140_WCMPM (SYSTEM_IRQ_EVENT_NUMBER_NOT_USED) /**< Numbers 0/4/8/12/16/20/24/28 only */
```

Figure 5.1 Example of Registering Interrupts to NVIC (When Using ADI)
5.3 Using A/D Converter in Snooze Mode

When performing A/D conversion in snooze mode, set `ADC_CMPAI_SNOOZE_USE` or `ADC_CMPBI_SNOOZE_USE` in `r_adc_cfg.h` to (1).

When (1) is set, registering CMPAI or CMPBI to the NVIC is skipped. Therefore, they cannot be used in interrupts.

5.4 Pin Settings

The pins to be used by this driver will be set when the Open function is executed. Table 5-4 shows the pins that are set by default. To change the pins to be used, modify code in the `R_S14AD_Pinset` and `R_S14AD_Pinclr` functions of `pin.c`.

Figure 5.2 and Figure 5.3 show an example of changing pin settings in which AN000 to AN003 are the only analog input pins used and the ADTRG pin is changed to P500.

Table 5-4  Pins Used by Default

<table>
<thead>
<tr>
<th>Channel</th>
<th>Pin Function</th>
<th>Assigned Port</th>
</tr>
</thead>
<tbody>
<tr>
<td>ADC</td>
<td>AN000</td>
<td>P000</td>
</tr>
<tr>
<td></td>
<td>AN001</td>
<td>P001</td>
</tr>
<tr>
<td></td>
<td>AN002</td>
<td>P002</td>
</tr>
<tr>
<td></td>
<td>AN003</td>
<td>P003</td>
</tr>
<tr>
<td></td>
<td>AN004</td>
<td>P004</td>
</tr>
<tr>
<td></td>
<td>AN005</td>
<td>P005</td>
</tr>
<tr>
<td></td>
<td>AN006</td>
<td>P006</td>
</tr>
<tr>
<td></td>
<td>AN016</td>
<td>P010</td>
</tr>
<tr>
<td></td>
<td>AN017</td>
<td>P011</td>
</tr>
<tr>
<td></td>
<td>AN020</td>
<td>P014</td>
</tr>
<tr>
<td></td>
<td>AN021</td>
<td>P015</td>
</tr>
<tr>
<td></td>
<td>AN022</td>
<td>P500</td>
</tr>
<tr>
<td></td>
<td>AN023</td>
<td>P501</td>
</tr>
<tr>
<td></td>
<td>AN024</td>
<td>P502</td>
</tr>
<tr>
<td></td>
<td>AN025</td>
<td>P503</td>
</tr>
<tr>
<td></td>
<td>AN026</td>
<td>P504</td>
</tr>
<tr>
<td></td>
<td>AN027</td>
<td>P505</td>
</tr>
<tr>
<td></td>
<td>AN028</td>
<td>P506</td>
</tr>
<tr>
<td></td>
<td>ADTRG0</td>
<td>P204</td>
</tr>
</tbody>
</table>
void R_S14AD_Pinset(void)  // @suppress("Source file naming") @suppress("API function naming")
    @suppress("Function length")
{
    /* Disable protection for PFS function (Set to PWPR register) */
    R_SYS_RegisterProtectDisable(SYSTEM_REG_PROTECT_MPC);

    /* AN000 : P000 */
    PFS->P000PFS_b.ISEL = 0U;
    PFS->P000PFS_b.PSEL = 0U;
    PFS->P000PFS_b.PMR  = 0U;
    PFS->P000PFS_b.PDR  = 0U;
    PFS->P000PFS_b.ASEL = 1U;

    /* AN001 : P001 */
    PFS->P001PFS_b.ISEL = 0U;
    PFS->P001PFS_b.PSEL = 0U;
    PFS->P001PFS_b.PMR  = 0U;
    PFS->P001PFS_b.PDR  = 0U;
    PFS->P001PFS_b.ASEL = 1U;

    /* AN002 : P002 */
    PFS->P002PFS_b.ISEL = 0U;
    PFS->P002PFS_b.PSEL = 0U;
    PFS->P002PFS_b.PMR  = 0U;
    PFS->P002PFS_b.PDR  = 0U;
    PFS->P002PFS_b.ASEL = 1U;

    /* Commented out because AN003 to AN028 are not used */
    #if 0
    /* AN003 : P003 */
    PFS->P003PFS_b.ISEL = 0U;
    PFS->P003PFS_b.PSEL = 0U;
    PFS->P003PFS_b.PMR  = 0U;
    PFS->P003PFS_b.PDR  = 0U;
    PFS->P003PFS_b.ASEL = 1U;
    ...
    /* AN028 : P506 */
    PFS->P506PFS_b.ISEL = 0U;
    PFS->P506PFS_b.PSEL = 0U;
    PFS->P506PFS_b.PMR  = 0U;
    PFS->P506PFS_b.PDR  = 0U;
    PFS->P506PFS_b.ASEL = 1U;
    #endif

    /* Commented out because ADTRG0 is changed from P204 (default) to P500 */
    // /* ADTRG0 : P204 */
    // PFS->P204PFS_b.ISEL = 0U;
    // PFS->P204PFS_b.PSEL = R_PIN_PRV_S14AD_PSEL;
    // PFS->P204PFS_b.PMR  = 1U;

    /* Uncommented because ADTRG0 is changed from P204 (default) to P500 */
    /* ADTRG0 : P500 */
    PFS->P500PFS_b.ISEL = 0U;
    PFS->P500PFS_b.PSEL = R_PIN_PRV_S14AD_PSEL;
    PFS->P500PFS_b.PMR  = 0U;

    /* Enable protection for PFS function (Set to PWPR register) */
    R_SYS_RegisterProtectEnable(SYSTEM_REG_PROTECT_MPC);
}/* End of function R_S14AD_Pinset() */
```c
/**************************************************************************
* @brief This function clears the pin setting of S14AD.
**************************************************************************/
/* Function Name : R_S14AD_Pinclr */
void R_S14AD_Pinclr(void) /*@suppress("Source file naming")@suppress("API function naming")*/
{
    /* Disable protection for PFS function (Set to PWPR register) */
    R_SYS_RegisterProtectDisable(SYSTEM_REG_PROTECT_MPC);

    /* AN000 : P000 */
    PFS->P000PFS &= R_PIN_PRV_CLR_MASK;

    /* AN001 : P001 */
    PFS->P001PFS &= R_PIN_PRV_CLR_MASK;

    /* AN002 : P002 */
    PFS->P002PFS &= R_PIN_PRV_CLR_MASK;

    /* AN003 : P003 */
    PFS->P003PFS &= R_PIN_PRV_CLR_MASK;
    ...

    /* AN028 : P506 */
    PFS->P506PFS &= R_PIN_PRV_CLR_MASK;

    /* Commented out because AN003 to AN028 are not used */
    #if 0
    /* AN003 : P003 */
    PFS->P003PFS &= R_PIN_PRV_CLR_MASK;
    ...
    /* AN028 : P506 */
    PFS->P506PFS &= R_PIN_PRV_CLR_MASK;
    #endif

    /* Commented out because ADTRG0 is changed from P204 (default) to P500 */
    // /* ADTRG0 : P204 */
    // PFS->P204PFS &= R_PIN_PRV_CLR_MASK;

    /* Uncommented because ADTRG0 is changed from P204 (default) to P500 */
    /* ADTRG0 : P500 */
    PFS->P500PFS &= R_PIN_PRV_CLR_MASK;

    /* Enable protection for PFS function (Set to PWPR register) */
    R_SYS_RegisterProtectEnable(SYSTEM_REG_PROTECT_MPC);
}/* End of function R_S14AD_Pinclr() */
```

Figure 5.3  Example of Changing Pin Settings (2/2)
5.5 Calibration

After the Open function has been executed following release from the reset state, execute calibration (execute the Control function with the AD_CMD_CALIBRATION command set as the argument) before the ScanSet function is executed.

Figure 5.4 shows an example of performing calibration.

```c
extern DRIVER_S14AD Driver_S14AD;  
DRIVER_S14AD *gsp_adc_dev = &Driver_S14AD;

/*********************************************************************************
* Function Name: main
* Description : Main Function
* Arguments : none
* Return Value : none
***********************************************************************************/
void main(void)
{
    st_adc_pins_t scanset_pin;

    gsp_adc_dev->Open(ADC_REPEAT_SCAN, 0x10, NULL); /* ADC driver is opened */
    gsp_adc_dev->Control(AD_CMD_CALIBRATION, NULL); /* Calibration is executed */

    /** Channel Select */
    scanset_pin.an_chans = ADC_MSEL_AN00 | ADC_MSEL_AN01;
    scanset_pin.sensor   = ADC_SENSOR_NOTUSE;
    gsp_adc_dev->ScanSet(ADC_GROUP_A, scanset_pin, ADC_TRIGER_SOFT);
    ...
```

**Figure 5.4 Example of Executing Calibration**
5.6 Combinations of Functions to Be Used

Some functions cannot be used at the same time. Confirm the possible combinations in the table below.

<table>
<thead>
<tr>
<th></th>
<th>Double-trigger</th>
<th>Group-scan</th>
<th>Self-diagnosis</th>
<th>Addition/Average</th>
<th>Group A priority control</th>
<th>Sensor</th>
<th>Compare match</th>
<th>Disconnection detection assist</th>
<th>Automatic clear</th>
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</tbody>
</table>
6. Troubleshooting

6.1 Occurrence of Build Error with IAR compiler

A-1) Have the include directories been specified correctly?

When using EWARM, we recommend that the include directories are specified as shown in the example below.

The include directories can be specified from IDE Options [C/C++ Compiler] → [Preprocessor].

6.2 Occurrence of HardFault Error when API of CMSIS Driver Is Called

A) The API has possibly not been copied to RAM.

Before calling an API function that is mapped to RAM, make sure that it has been copied to RAM by the R_SYS_CodeCopy function. For details, refer to the related document No. R01AN4660.

6.3 Peripheral Function Fails to Operate when API Is Called

A) Has the API been set up correctly?

Check the API’s return value to see if an error has occurred.

In particular, errors are often caused by problems related to interrupts not being set in r_system_cfg.h.
For details, refer to the related document No. R01AN4660.

6.4 Normal API Return Value But No Pin Output from Peripheral Function

A) Are the pin settings correct?

Check to make sure the pins have been set up correctly by the functions in pin.c.
For details, refer to the related document No. R01AN4660.

6.5 Peripheral Function’s Input or Output Does Not Operate as Expected

A) Check to make sure the VOCR register has been set up correctly before making the initial settings for peripheral functions.
For details, refer to the related document No. R01AN4660.
7. Sample Code
Sample code can be downloaded from the Renesas Electronics website.

8. Reference Documents

User’s Manual: Hardware
  RE01 1500KB Group User’s Manual: Hardware R01UH0796
  (The latest version can be downloaded from the Renesas Electronics website.)

RE01 1500KB CMSIS Package Startup Guide
  RE01 1500KB Group Startup Guide to Development Using CMSIS Package R01AN4660
  (The latest version can be downloaded from the Renesas Electronics website.)

Technical Update/Technical News
  (The latest version can be downloaded from the Renesas Electronics website.)

User’s Manual: Development Tools
  (The latest version can be downloaded from the Renesas Electronics website.)
## Revision History

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<th>Description</th>
<th>Page</th>
<th>Summary</th>
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<td>1.00</td>
<td>Sep. 19, 2019</td>
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General Precautions in the Handling of Microprocessing Unit and Microcontroller Unit Products

The following usage notes are applicable to all Microprocessing unit and Microcontroller unit products from Renesas. For detailed usage notes on the products covered by this document, refer to the relevant sections of the document as well as any technical updates that have been issued for the products.

1. Precaution against Electrostatic Discharge (ESD)
   A strong electrical field, when exposed to a CMOS device, can cause destruction of the gate oxide and ultimately degrade the device operation. Steps must be taken to stop the generation of static electricity as much as possible, and quickly dissipate it when it occurs. Environmental control must be adequate. When it is dry, a humidifier should be used. This is recommended to avoid using insulators that can easily build up static electricity. Semiconductor devices must be stored and transported in an anti-static container, static shielding bag or conductive material. All test and measurement tools including work benches and floors must be grounded. The operator must also be grounded using a wrist strap. Semiconductor devices must not be touched with bare hands. Similar precautions must be taken for printed circuit boards with mounted semiconductor devices.

2. Processing at power-on
   The state of the product is undefined at the time when power is supplied. The states of internal circuits in the LSI are indeterminate and the states of register settings and pins are undefined at the time when power is supplied. In a finished product where the reset signal is applied to the external reset pin, the states of pins are not guaranteed from the time when power is supplied until the reset process is completed. In a similar way, the states of pins in a product that is reset by an on-chip power-on reset function are not guaranteed from the time when power is supplied until the power reaches the level at which resetting is specified.

3. Input of signal during power-off state
   Do not input signals or an I/O pull-up power supply while the device is powered off. The current injection that results from input of such a signal or I/O pull-up power supply may cause malfunction and the abnormal current that passes in the device at this time may cause degradation of internal elements. Follow the guideline for input signal during power-off state as described in your product documentation.

4. Handling of unused pins
   Handle unused pins in accordance with the directions given under handling of unused pins in the manual. The input pins of CMOS products are generally in the high-impedance state. In operation with an unused pin in the open-circuit state, extra electromagnetic noise is induced in the vicinity of the LSI, an associated shoot-through current flows internally, and malfunctions occur due to the false recognition of the pin state as an input signal become possible.

5. Clock signals
   After applying a reset, only release the reset line after the operating clock signal becomes stable. When switching the clock signal during program execution, wait until the target clock signal is stabilized. When the clock signal is generated with an external resonator or from an external oscillator during a reset, ensure that the reset line is only released after full stabilization of the clock signal. Additionally, when switching to a clock signal produced with an external resonator or by an external oscillator while program execution is in progress, wait until the target clock signal is stable.

6. Voltage application waveform at input pin
   Waveform distortion due to input noise or a reflected wave may cause malfunction. If the input of the CMOS device stays in the area between $V_{IL}$ (Max.) and $V_{IH}$ (Min.) due to noise, for example, the device may malfunction. Take care to prevent chattering noise from entering the device when the input level is fixed, and also in the transition period when the input level passes through the area between $V_{IL}$ (Max.) and $V_{IH}$ (Min.).

7. Prohibition of access to reserved addresses
   Access to reserved addresses is prohibited. The reserved addresses are provided for possible future expansion of functions. Do not access these addresses as the correct operation of the LSI is not guaranteed.

8. Differences between products
   Before changing from one product to another, for example to a product with a different part number, confirm that the change will not lead to problems. The characteristics of a microprocessing unit or microcontroller unit products in the same group but having a different part number might differ in terms of internal memory capacity, layout pattern, and other factors, which can affect the ranges of electrical characteristics, such as characteristic values, operating margins, immunity to noise, and amount of radiated noise. When changing to a product with a different part number, implement a system-evaluation test for the given product.
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