The ISL29501-CS-EVKIT1Z is a distance measurement reference design consisting of an optical board and a controller board. It combines the ISL29501 chip with an OSRAM SFH 4550 IR emitting LED and OSRAM SFH 213FA photodiode. The two circuit boards are connected together with a flat flex cable. Included is a USB flash drive containing the evaluation software for a PC and related technical documents.

The ISL29501-CS-EVKIT1Z kit also allows quick evaluation of the ISL29501 performance for a 2m sensing system.

**Specifications**

This board has been configured and optimized for the following operating conditions:

- Micro USB 2.0 connection
- $V_{IN} = 5\text{V}$ (USB power)
- $I_{DD}$ maximum = 225mA
- $P_{optical}$ maximum = 70mW
- Wavelength = 860nm
- Optical duty cycle maximum = 50%
- Emission angle = $\pm3^\circ$
- Coherent light - No

**Features**

- Self contained measurement system
- Enables proximity detection and distance measurement
- Emitter DAC with programmable current up to 255mA
- Operates in continuous or single shot mode
- On-chip active ambient light rejection
- Regulated power 2.7V to 3.3V USB or external supply
- $I^2C$ interface supporting 1.8V and 3.3V bus
- Small size 38mmx20mm

**Kit Contents**

- Evaluation Board
- USB cable
- Software
- Technical documentation

![Figure 1. Cat Shark Block Diagram](image)

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**UG081 Rev.1.00**

Apr 5, 2022

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1. Functional Description

The ISL29501-CS-EVKIT1Z is both a reference design and evaluation kit that provides a single platform to evaluate the features of the ISL29501. The ISL29501-CS-EVKIT1Z circuit board and supplied enclosure deliver maximum electrical and optical performance.

The system sends out light pulses through the emitter LED and receives returned light pulses that reflect off a target on the optics board. The difference in phase of the emitted signal and the return signal is converted to distance by the ISL29501 and is graphed in the evaluation software. The magnitude of the return signal is graphed as well. This and additional data are available in the chip registers, see UG054, ISL29501 Evaluation Software Manual for additional details.

1.1 Operating Features

The ISL29501-CS-EVKIT1Z evaluation kit is shown in Figure 2 and Figure 3. The hardware enable function is controlled by a software switch. A Power-Good (PG) LED indicates that the LDO is regulating properly when not lit.

1.1.1 External Power Supply

For high current/high duty cycle setups USB power may not be able to power the board.

1.1.2 External Microprocessor

For debugging of customer written software, it might be useful to connect the Cat Shark to a different microprocessor. All signals are available on the optics board connector J1. See the schematic for details. SCL and SDA are compatible with 1.8V microprocessors but unfortunately the support pins require 3V signaling.

1.1.3 System Calibration

Before meaningful measurements can be made the calibration registers in the chip need to be loaded. This can be done in two ways. The first is to load a profile that contains data into the GUI. This can be one of the Renesas provided profiles or one that was saved previously by the user. See UG054, ISL29501 Evaluation Software Manual for further details. The second is to calibrate the board directly.

1.1.4 Calibrating Cat Shark

There are three separate standard calibrations that need to be executed to calibrate the system. These are magnitude, crosstalk, and distance calibrations.

1.1.4.1 Magnitude Calibration

Magnitude calibration is done after the emitter current and duty cycle settings are programmed. It is a dark (no light) calibration that takes less than 1s to run. Run this calibration from the GUI.

1.1.4.2 Crosstalk Calibration

Crosstalk is defined as a signal that reaches the ISL29501 chip directly without bouncing off the target. This can be electrical or optical. At close range and large return signal values, crosstalk has a minor impact on distance measurements. At the far end of the distance range, the crosstalk might exceed the signal, adding error to measurements.

For this calibration, the user makes a distance measurement with the return signal blocked from reaching the photodiode. This can be done in two ways. The first is to cover the emitter or photodiode optically preventing any of the emitted signals from reaching the photodiode. The second is to point the board toward infinity so there is no return signal. Note: Care must be taken because small amounts of signal is returned by objects up to 4 meters away. The emitting angle of the light is ±3° so you must ensure that there are no objects within this cone when doing this calibration.

Because the chip sees none of the emitted signal, anything received is crosstalk. Run this calibration from the GUI after running Magnitude calibration.
1.1.4.3 Distance Calibration

Variation in delay of emitters, photodiodes, and the ISL29501 change the signal path delay. To compensate for this, a reference point at a known distance needs to be established. This reference is calculated during distance calibration. The process involves making a distance measurement at a known distance. While it is not critical it is best to use a reference distance about 25% of the intended range. The GUI writes the correct registers that establish the reference distance inside the chip.

It is important that there are no objects inside the ±3° emitting angle other than the target.

When these calibration registers are written, all succeeding distances have this measured value subtracted from the real-time value. Run this calibration from the GUI after running crosstalk calibration. See UG054, ISL29501 Evaluation Software Manual for details on how to run the calibrations in the GUI.

1.2 Operating Range

The controller circuit board contains an LDO to convert the input voltage to the ISL29501 operating voltage range, 2.7V to 3.3V. By default, the controller board is configured for USB power. The LDO resistors are rationed to create a 3.0V power rail. All other set-up conditions can be configured through the chip registers and evaluation software.

1.3 Quick Start Guide

To start making distance measurements follow these simple steps.

1. The board set comes assembled with the optics board connected to the controller board with an 8-pin flex cable. This cable should be as short as possible to minimize voltage drops.
2. Plug the USB cable into the controller board design and the PC.
3. Point the emitter toward the desired target.
4. Double click TOF.exe to start the GUI.
5. From the GUI click on File → Load Profile → filename to load safe initial register settings and calibration data.
6. Click either Start or Step to begin making distance measurements.

1.4 Changing Settings

When the board is running and making measurements, the user may want to change settings. The user has the ability to change any of the chip registers with the evaluation software, see UG054, ISL29501 Evaluation Software Manual for details. Important: If the pulse duty cycle or the emitter current is changed, the user must redo the standard calibrations. This process is described in the sections under Calibrating Cat Shark.

1.5 Temperature Compensation

The ISL29501 has a temperature compensation built into the chip. This is an advanced calibration, which involves collecting temperature vs distance data and programming the compensation registers. Initially, Renesas generates these coefficients from customer collected data. The process for collecting data is described in AN1967, ISL29501 Temperature and Ambient Light Data Collection.

Renesas strongly recommends that customers evaluate these parameters as a last step in their evaluation. To avoid temperature effects low integration times, reg 0x10 < 0x06 should be used.
2. Board Design

2.1 Layout Guidelines

The ISL29501-CS-EVKIT1Z PCB layout has been optimized for electrical and thermal performance. Care needs to be placed in decoupling circuits and noise isolation. Cat Shark follows good design techniques but additional suggestions are available in AN1917, ISL29501 Layout Design Guide (see ISL29501-CS1Z PCB Layers and ISL2UEV1Z PCB Layers).

Note: Visible on the bottom side of the board are the emitter LED and photodiode. Each is surrounded by a brass tube. These tubes are grounded and serve as terminators for any electric fields. They prevent crosstalk from the emitter to the photodiode.
2.2 Schematic Diagrams

2.2.1 ISLI2UEV1Z

Figure 5. ISLI2UEV1Z Schematic
2.2.2 ISL29501-CS1Z Optics Board

Figure 6. ISL29501-CS1Z Schematic - Optics Sheet
# 2.3 Bill of Materials

## 2.3.1 ISLI2UEV1Z

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<th>Manufacturer</th>
<th>Manufacturer Part</th>
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<td>U1</td>
<td>IC-PROGRAMMED USB µCONTROLER, 32P, LQFP, 8-BIT, 48MIPS, ROHS</td>
<td>SILICON LABORATORIES</td>
<td>C8051F387-GQ</td>
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<td>U4</td>
<td>IC-1A LDO ADJ.VOLT REGULATOR, 10P, DFN, 3x3, ROHS</td>
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### 2.3.2 ISL29501-CS1Z Optics Board

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<td>BLM15BD471SN1D</td>
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<td>0</td>
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<td>DO NOT POPULATE OR PURCHASE</td>
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<tr>
<td>1</td>
<td>AFFIX TO BACK OF PCB</td>
<td>LABEL-DATE CODE_LINE 1: YRWK/REV#, LINE 2: BOM NAME</td>
<td>Renesas</td>
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## 2.3.3 ISL29501-CS-EVKIT1Z Cat Shark Assembly

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<td>MOLEX</td>
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<td>INSTRUCTIONS</td>
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<td>QUALTEK ELECTRONICS</td>
<td>3025010-03</td>
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<td>Renesas</td>
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<td>4</td>
<td>SEE ASSEMBLY</td>
<td>SCREW, M2.5, 4mm, METRIC, PANHEAD, SLOTTED, STEEL, ROHS</td>
<td>KEYSTONE</td>
<td>29300</td>
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<td>SEE ASSEMBLY</td>
<td>STANDOFF, M2.5, 8mm, METRIC, F/F, HEX, THREAD, BRASS, ROHS</td>
<td>ASSMANN ELECTRONICS INC</td>
<td>V6516B</td>
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<td>Place assy in bag</td>
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<td>ULINE</td>
<td>S-6660</td>
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<td>Face boards top to top. Insert screws from bottom of boards and attach standoffs between board tops. Connect cable between J1 on ISL29501-CS1Z and J5 on ISL2IUEV1Z. Lift retainers on connectors, insert cable, and lower retainers to secure cable.</td>
<td>Instructions for assembly.</td>
<td>Renesas</td>
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2.4 Board Layout

2.4.1 ISL29501-CS1Z PCB Layers

Figure 7. Layer 1

Figure 8. Layer 2

Figure 9. Layer 3

Figure 10. Layer 4
2.4.2 ISL2UEV1Z PCB Layers

![Figure 11. Layer 1 (Viewed from Top)](image1)

![Figure 12. Layer 2 (Viewed from Top)](image2)

3. Ordering Information

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<td>ISL29501 Cat Shark evaluation kit</td>
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4. Revision History

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<td>Apr 5, 2022</td>
<td>Applied new template.</td>
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<tr>
<td>0.00</td>
<td>Jun 27, 2016</td>
<td>Initial release</td>
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