

RL78G13

Renesas Starter Kit Software Help Manual
(IAR Embedded Workbench)

RENESAS MCU
RL Family / G1X Series

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- ensure attached cables do not lie across the equipment
- reorient the receiving antenna
- increase the distance between the equipment and the receiver
- connect the equipment into an outlet on a circuit different from that which the receiver is connected
- power down the equipment when not in use
- consult the dealer or an experienced radio/TV technician for help NOTE: It is recommended that wherever possible shielded interface cables are used.

The product is potentially susceptible to certain EMC phenomena. To mitigate against them it is recommended that the following measures be undertaken;

- The user is advised that mobile phones should not be used within 10m of the product when in use.
- The user is advised to take ESD precautions when handling the equipment.

The Renesas Starter Kit does not represent an ideal reference design for an end product and does not fulfil the regulatory standards for an end product.

How to Use This Manual

1. Purpose and Target Readers

This manual is designed to provide the user with an understanding of the sample projects.

The manual comprises of an overview of each sample and what is required by the user to successfully execute the samples.

Particular attention should be paid to the precautionary notes when using the manual. These notes occur within the body of the text, at the end of each section, and in the Usage Notes section.

The revision history summarizes the locations of revisions and additions. It does not list all revisions. Refer to the text of the manual for details.

The following documents apply to the RL78G13 Group. Make sure to refer to the latest versions of these documents. The newest versions of the documents listed may be obtained from the Renesas Electronics Web site.

Document Type	Description	Document Title	Document No.
User's Manual	Describes the technical details of the RSK hardware.	RSKRL78G13 User's Manual	R20UT0776EG
Tutorial	Provides a guide to setting up RSK environment, running sample code and debugging programs.	RSKRL78G13 Tutorial Manual	R20UT0614EG
Quick Start Guide	Provides simple instructions to setup the RSK and run the first sample, on a single A4 sheet.	RSKRL78G13 Quick Start Guide	R20UT0615EG
Software Help Manual	Describes the functionality of the sample code.	RSKRL78G13 Software Help Manual	R20UT0747EG
Schematics	Full detail circuit schematics of the RSK.	RSKRL78G13 Schematics	R20UT0458EG
Hardware Manual	Provides technical details of the RL78G13 microcontroller.	RL78G13 Hardware Manual	R01UH0146EJ

2. List of Abbreviations and Acronyms

Abbreviation	Full Form
ADC	Analogue to Digital Converter
DMAC	Direct Memory Access Controller
IIC	Inter Integrated Circuit
LCD	Liquid Crystal Display
LED	Light Emitting Diode
LIN	Local Interconnect Network
LVD	Low Voltage Detection
MCU	Microcontroller Unit
PC	Personal Computer
RSK	Renesas Starter Kit
RTC	Real Time Clock
WDT	Watchdog Timer

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1. Overview

1.1 Purpose

This RSK is an evaluation tool for Renesas microcontrollers. This manual explains the operation of the sample code provided, and its interaction with the APIs used which were generated using Applilet3 for Renesas RL78G13. Applilet is a separate tool used for generating code for configuring the on-board device peripherals and modules depending on user setting selections. Applilet also generates code for interrupt handling as well as peripheral start and stop functions.

This manual is not intended to be a tutorial on using Applilet, or how it works – it simply aims to describe the sample codes functionality.

2. Introduction

This document explains by text the functionality of the sample code and the steps required to observe the correct operation of each sample.

3. RSK Sample Code Concept

3.1 Sample Code Structure

The basic structure of all RSK sample code is shown in Figure 2-1 below. The first two functions, ‘__low_level_init’ and ‘R_Systeminit’, configure the MCU before the main program code executes.

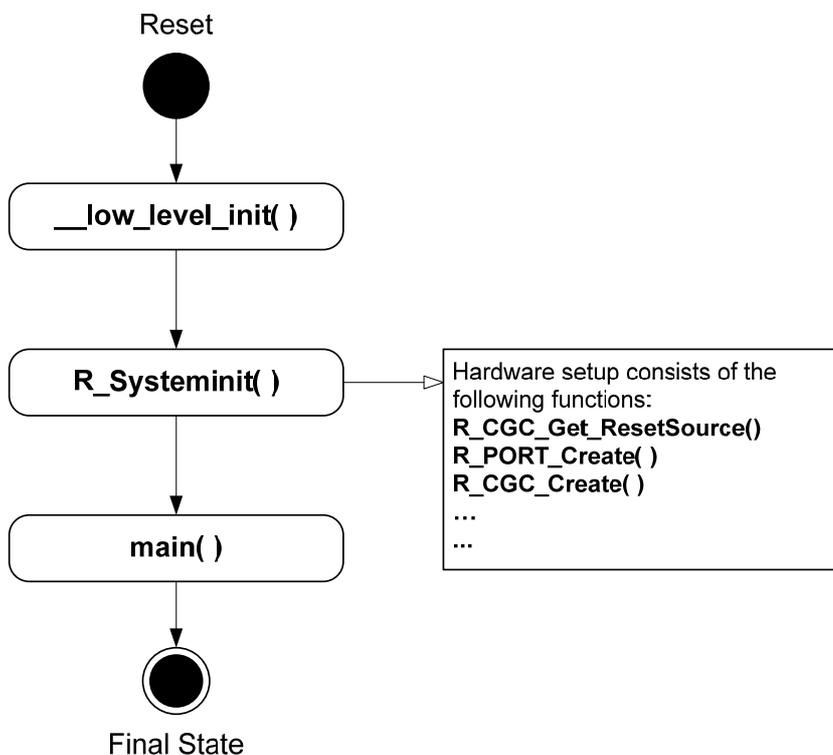


Figure 2-1: Sample Code Structure

All sample code projects are configured with the main function as the entry point after a successful build and programming of the board. The program code is automatically executed after programming the device and stopped at the first instruction inside the main function. As a result, the user will not be able to step through the hardware initialisation code. IAR Embedded Workbench permits the user to change the program entry point by specifying another function other than main. Please refer to the Tutorial manual for more information on this.

The sample code descriptions in this manual focus on the program execution within the main function.

3.2 List of Sample Code

Table 2-2 below lists the sample code supplied with the RSKRL78G13T, and describes their function.

Sample Code	Description
ADC_OneShot	Demonstrates usage of the 10bit and 8bit ADC module, in one shot mode.
ADC_Repeat	Demonstrates usage of the 10bit and 8bit ADC module, in repeat mode.
Application	Blank project, used for development.
Async_Serial	Demonstrates usage of the SCI module, in asynchronous mode.
DMAC	Demonstrates usage of the DMAC module, by performing interrupt requested transfers.
IIC	Demonstrates usage of the IIC module in master or slave mode.
LIN	Demonstrates usage of the LIN module in master or slave mode.
LVD	Demonstrates usage of the LVD circuit to generate interrupts on low voltage detections.
Sync_Serial	Demonstrates usage of the SCI module, in synchronous mode.
Timer	Demonstrates usage of the Timer's multifunction capabilities in 4 different modes.
Tutorial	Demonstrates basic usage of the debugger, and RSK hardware.
Watchdog	Demonstrates usage of the watchdog timer, by causing a WDT overflow interrupt.

Table 2-1: Sample Code List

4. Tutorial Sample

4.1 Tutorial

The sample code in this section is basic tutorial code, used to demonstrate basic usage of the RSK and help the user to begin writing his/her own basic sample code.

4.1.1 Description

The tutorial sample code demonstrates basic usage of the debugger and RSK hardware, and is common to all RSKs. This sample is supplied programmed onto the MCU, and executes out of the box when power is applied.

The sample calls three main functions to demonstrate port pin control, interrupt usage and C variable initialisation. These functions are shown in Figure 3-1 below.

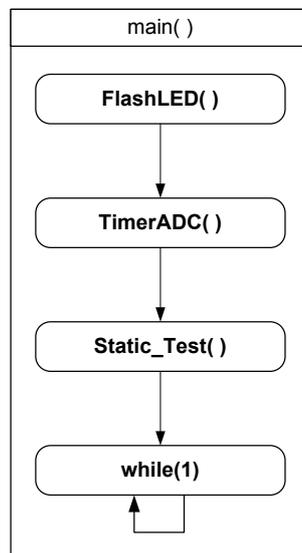


Figure 4-1: Tutorial Sample Flow

4.1.2 Operation

1. All peripherals and modules are configured prior to the program calling the main function.
2. The tutorial code initialises the LCD module, and displays 'Renesas' on the first line of the LCD, and the name of the MCU on the second line.
3. The tutorial code calls the FlashLED function, which creates a delay to toggle the LEDs repeatedly and waits in a loop until either a switch is pressed or the LEDs flash 200 times.
4. The tutorial then calls the TimerADC function which starts an ADC channel configured to run continuously. It also starts a periodic timer channel.
5. When the timer channel's period elapses, the user LEDs are toggled once. The A/D result is read then used to update the timer's period.
6. After calling TimerADC and setting up the timer & ADC interrupts, the tutorial calls the Statics_Test function.
7. The Statics_Test function displays the string STATIC on the second line of the debug LCD, and replaces it letter by letter with the constant string, TESTTEST. Once replacement is complete, the LCD reverts back to its original display. The tutorial then waits in an infinite while loop. The user LEDs toggling continues to run due to the periodic timer. The user may vary the period by varying the ADC's potentiometer shaft.

4.2 Application

4.2.1 Description

The application sample is intended as a starting platform for the user to write his/her own code. The sample includes all the necessary initialisation code and configuration settings from previous samples. The main() function contains no sample code, and performs no additional functionality.

5. Peripheral Samples

The sample code in this section provides examples of initialisation and usage of some of the MCU's peripheral modules. The sample code also provides examples of how to debug MCU peripherals.

5.1 ADC_OneShot

5.1.1 Description

This sample code demonstrates usage of the on-chip 10-bit and 8-bit analogue to digital converter (ADC), in one shot mode. The sample configures the ADC to read from the potentiometer fitted to the RSK (RV1) when user switch 'SW3' is pressed.

Note: The potentiometer is fitted to offer an easy method of supplying a variable analogue input to the microcontroller. It does not necessarily reflect the accuracy of the controllers ADC. Refer to the device hardware manual for further details.

5.1.2 Operation

1. All peripherals and modules are configured prior to the program calling the main function. The A/D channel connected to the potentiometer is initially configured for 10-bit precision operations.
2. The sample first initialises the debug LCD, and displays instructions on the screen.
3. The sample then enables the external interrupts connected to the user switches.
4. The sample then waits in an infinite while loop, and the rest of the sample's functionality is completed through interrupts.
5. When switch SW1 is pressed, the corresponding external interrupt handler is called. This starts an A/D conversion and waits for conversion to complete. After completion, the interrupt handler checks the precision mode status. The result is saved according to the precision mode before converting the integer A/D value to a specially arranged string in a buffer array. The string is then displayed on the debug LCD before the interrupt handler exits and program execution returns to the main function.
6. Pressing switch SW2 calls the corresponding external interrupt handler which changes the precision mode to 8-bits and sets the precision mode status to '2' to indicate selection of 8-bits precision. The interrupt handler exits and returns to the main function.
7. Pressing switch SW3 calls the corresponding interrupt handler which changes the precision mode to 10-bits and sets the precision mode status to '3' to indicate that the current mode is 10-bits.

5.2 ADC_Repeat

5.2.1 Description

This sample code demonstrates usage of the on-chip 10-bit and 8-bit analogue to digital converter (ADC), in repeat mode. The sample configures the ADC to repeatedly take readings of the potentiometer voltage (RV1). The sample then updates the conversion value displayed on the LCD, through periodic interrupts from the timer module.

Note: The potentiometer is fitted to offer an easy method of supplying a variable analogue input to the microcontroller. It does not necessarily reflect the accuracy of the controllers ADC. Refer the device hardware manual for further details.

5.2.2 Operation

1. All peripherals and modules are configured prior to the program calling the main function. The A/D channel connected to the potentiometer is initially configured for 10-bit precision operations.
2. The sample first initialises the debug LCD, and displays the name of the sample.
3. The sample then enables the external interrupts connected to the user switches SW1 and SW3.
4. The sample then starts the ADC and the periodic timer channel.
5. The sample then waits in an infinite while loop, and the rest of the sample's functionality is completed through interrupts.
6. On completion of an A/D conversion, the A/D interrupt handler is called. It checks to see which user switch was last pressed before saving the A/D result using the appropriate format, being 10-bit or 8-bit.
7. When user switch SW1 is pressed, the corresponding external interrupt handler. The handler changes the precision mode to 8-bits and sets a flag to indicate that user switch SW1 was pressed.
8. When user switch SW3 is pressed, the corresponding external interrupt handler. The handler changes the precision mode to 10-bits and sets a flag to indicate that user switch SW3 was pressed.
9. The timer channel's interrupt handler is called on each timer overflow. The A/D integer result is converted and stored in a specially arranged string in a buffer array before being displayed on the debug LCD.

5.3 LIN

5.3.1 Description

This sample code demonstrates usage of Local Interconnect Network (LIN), configured in master or slave mode, depending on user selection. The mode can be selected by including or excluding the pre-processor instruction in:

```
#define MASTER_LIN
```

Note: The slave mode requires resistor link changes. Please refer to the Description.txt file for the resistor references. This sample requires an external 5V regulated power supply.

5.3.2 Operation

1. Using a three-way LIN connector, connect the RSKRL78G13 to the slave/master device.
2. All peripherals and modules are configured prior to the program calling the main function.
3. Connect and turn on the 5V regulated power supply.
4. The sample initialises the LCD module, and displays either "LIN Mstr" or "LIN Slav" on the first line of the debug LCD, depending on the selected operation mode.
5. The sample then enables the external interrupt INTP0.
6. The off-chip LIN transceiver is enabled and user LED1 is turned off.
7. In master mode, the sample periodically transmits the LIN header until data reception from the slave is detected. Detection is handled using interrupts. The corresponding interrupt handler stores the received data to a specified address range. On detection of slave data reception, the function LIN_Master_Receive is also called; stopping the timer operation and disabling serial operations. A checksum is calculated using the received data before being compared to the received checksum. If the checksums match, the received data is converted to a string and displayed on the debug LCD. The process is repeated infinitely until program execution is stopped.
8. In slave mode, the sample periodically awaits the LIN header transmitted by the master. The sample uses interrupts to detect the LIN header data. When the received slave address matches 0x10, function LIN_Slave_Transmit is called. This function starts an A/D conversion, waits for the conversion to complete, stores the integer result, converts it to a specially arranged string buffer array then transmits the data. The function exits and returns to main. The received slave address storage is cleared before the next header is received. The process is repeated infinitely until program execution is stopped.

5.4 Async_Serial

5.4.1 Description

This sample code demonstrates usage of serial array unit (SAU), configured in asynchronous mode. The SAU module is setup to communicate to a PC running a terminal emulator program, via an RS-232 cable.

5.4.2 Operation

1. Before the sample begins, the user should connect the RSK to a PC via an RS-232 cable and start the terminal program.
2. All peripherals and modules are configured prior to the program calling the main function.
3. The sample initialises the LCD module, and displays 'Async' on the first line and 'Serial' on the second.
4. The sample enables SAU0's channel 0 for RS-232 operations and starts the interval timer.
5. The rest of the program is handled at interrupt level.
6. The interval timer generates a periodic interrupt every 100ms, handled by the corresponding interrupt handler. The interrupt handler checks the character entered in the terminal emulator, and transmits an incrementing ASCII number (loops back to 0 after 9) to the terminal display if the character was not 'z'. LED0 is turned on to indicate transmission is in progress. If the character was 'z' transmission is stopped and LED0 is turned off.

5.5 Sync_Serial

5.5.1 Description

This sample code demonstrates usage of serial array unit (SAU), configured in synchronous mode. The SAU module is setup to perform loop back communication between two SAU channels, using a 3-wire interface.

Make the following connections:

TxD0 [JA2- pin 6]	↔	RxD1 [JA6- pin 7]
RxD0 [JA2- pin 8]	↔	TxD1 [JA6- pin 8]
SCK00 [JA2- pin 10]	↔	SCK10 [JA6-pin 10]

5.5.2 Operation

1. All peripherals and modules are configured prior to the program calling the main function.
2. The sample initialises the LCD module, and displays 'Sync' on the first line and 'Serial' on the second.
3. The sample then calls the Sync_Transfer function which clears the reserved SAU data buffers. SAU channels CSI00 and CSI10 are enabled and operational with data transfer between the two channels. Channel CSI00 is configured as the master and outputs the clocking signal to channel CSI10 which is configured as the slave. Both channel's data transmission and reception are handled using interrupts. A delay is created using a timer channel to allow the transfer to complete before the user can check the outcome. A "Failure" message will be displayed on the second line of the debug LCD when an error occurs during data transfer, otherwise data transfer between the two channels are compared at the end of transfer and "Success" is displayed on the second line of the debug LCD. If any of the data did not match, the message "Failure" is displayed instead.
4. The sample then enters an infinite while loop.

5.6 LVD

5.6.1 Description

In this sample, the LVD (Low Voltage Detection) circuit is configured to generate an interrupt when the power supply equals or falls below the detection level. The detection level is approximately 4.06Volts.

5.6.2 Operation

1. All peripherals and modules are configured prior to the program calling the main function.
2. The sample initialises the LCD module, and displays 'LVD' on the first line.
3. The sample calls enable LVD operations as well as start a periodic timer before entering an infinite while loop.
4. The rest of the sample is handled at interrupt level.
5. As long as power supply is maintained above 4.06 Volts, the period timer will generate interrupts which will synchronously flash all user LEDs. The timer's interrupt handler checks the status of a user-defined flag indicating user LEDs synchronisation. If the flag was set, user LEDs LED0-LED2 are toggled to synchronise the LEDs with LED3. The second line of the debug LCD is cleared before all user LEDs' states are toggled.
6. On detection of a low power supply, the LVD interrupt handler is called. It stops the timer and displays "Detected" on the second line of the debug LCD if the LVD flag is set and turns off user LEDs LED0-LED2. LED3 is left turned on; with the user-defined synchronisation flag cleared to indicate that the user LEDs are not synchronised. The timer is re-started.

5.7 IIC_Master

5.7.1 Description

This sample demonstrates usage of the IIC unit in master mode, by performing read and write operations to an EEPROM memory device or an RSKRL78G13 running the IIC_Slave sample. The sample is configured to work with 8-bit word addressed EEPROM devices. A total of 8 data bytes are transferred to the slave device starting from slave memory location 0. When writing to an EEPROM memory device, the second data is incremented after each write (from 0 to 9). For writes to a slave RSKRL78G13, the second data byte is incremented instead. The sample is configured for communication with an EEPROM memory device. To use an RSKRL78G13 as the slave, uncomment the following line found in source file `r_cg_typedefine.h`:

```
///define SLAVE_RL78G13
```

Make the following connections between the RSKRL78G13 and the slave device:

SDAA0 [JA1, pin 25]	↔	Device SDA
SCLA0 [JA1, pin 26]	↔	Device SDA
CON_5V [JA1, pin 25]	↔	Device Vcc
0v [JA1, pin 25]	↔	Device Vss

Note: Use a 4.7KΩ pull-up resistor on the data and clock line. This sample requires an external 5V regulated power supply.

5.7.2 Operation

1. All peripherals and modules are configured prior to the program calling the main function.
2. Connect and turn on the 5V regulated power supply.
3. The sample initialises the LCD module, and displays "IIC Mstr" on the first line.
4. The sample then enables user-switch interrupts before calling the Master_EEPROM function.

5. Inside the Master EEPROM function, the second buffer array location is set to 0x30 which represents the ASCII character '0'.
6. The sample enters and infinite while loop with the program never returning to the main function. Data transfer is handled using interrupts with transmission or reception selected by SW1 and SW3 switch presses, respectively. A write operation should always precede a read operation to verify data transferred to the slave device. If a read operation is done before a write, data is read from the slave device but not displayed on the second line of the LCD. Instead, the message "IIC Push" is displayed on the first line and "SW1->SW3" displayed on the second line informing the user to press SW1 then SW3.
7. Pressing switch SW2 allows the user to display the last data sent to the slave device.
8. After a write and read operations have taken place, data sent and received are compared. If data mismatch occurs, messages "IIC Mstr" "W/R Diff" are displayed on the first and second LCD lines, respectively.

5.8 IIC_Slave

5.8.1 Description

This sample demonstrates usage of the IIC unit in slave mode, by simulating a simple 8 byte EEPROM memory device.

5.8.2 IIC Slave Commands

(1) Write Operation

- To write to the simulated EEPROM, the master should send a start condition followed by the EEPROM device address (default address: 0x10), and wait for an ACK (acknowledgement) signal from the slave.
- The master should proceed by sending 8 bytes of data, including the 8bit EEPROM memory address (not used) and then wait for an ACK response from the slave. The memory address byte is disregarded since the slave saves the received bytes starting at the same address for each 8 byte transfer.
- The master should wait for an ACK response after each data byte. The slave is configured and expects to receive 8 bytes of data.
- Once the final byte has been sent, the master should send a stop signal to end the transaction.
- The simulated EEPROM's internal address pointer will auto increment with each byte written during the transfer.



(2)

(3) Read Operation

- The read operation will always start from a specified internal simulated EEPROM memory pointer, and auto increment to the next byte until the address reaches the maximum value and a stop condition is detected.
- The EEPROM slave should then reply with an ACK signal, and send the data located at the current memory location and auto increment the internal pointer to the next byte location.
- In order to read another byte, the master should send an ACK signal. The master should repeat this until 8 bytes have been read, and should end the operation with a stop condition.



Make the following connections between the RSKRL78G13 and the slave device:

SDAA0 [JA1, pin 25]	↔	Device SDA
SCLA0 [JA1, pin 26]	↔	Device SDA
CON_5V [JA1, pin 25]	↔	Device Vcc
0v [JA1, pin 25]	↔	Device Vss

Note: Use a 4.7K Ω pull-up resistor on the data and clock line.

5.8.3 Operation

1. All peripherals and modules are configured prior to the program calling the main function.
2. The sample initialises the LCD module, and displays “IIC Slav” on the first line.
3. The sample then calls the Slave_EEPROM function to specify the start addresses of data to be sent to and received from the master device. The sample returns to the main function with data transfers handled at interrupt level.
4. Data received from the master device is stored in the 8-byte buffer array ‘Master_Data’. The same data is also sent to the master when a slave read is requested by the master.

5.9 Timer

5.9.1 Description

This sample configures the timer array unit (TAU) channels to run one of four applications. A total of four TAU channels have been used in the sample. The four TAU channels used are channel 0, channel 1, channel 3 and channel 5. The implemented applications are Square-wave output, Capture, Event Count and PWM (pulse width modulation). The project is configured to run the PWM application by default. To change the application change the following pre-processor directive definition with a value corresponding to desired application definition number:

```
#define __Current_TMR_APP 1
```

This can be found in the file r_cg_typedefine.h

5.9.2 Operation

1. All peripherals and modules are configured prior to the program calling the main function.
2. The sample initialises the LCD module.
3. Depending on the selected application, the user will observe one of the following:
 4. When PWM is selected, connect an oscilloscope to pin 9 of JA5.
 5. For PWM output the sample displays “Tr.PWM” on the first line of the debug LCD, enables switches SW1 and SW2’s external interrupts before starting TAU channel 0 which is configured to output a PWM waveform. The sample then enters the main while loop, and the rest of the functionality is performed at interrupt level. TAU channel 0’s period is set to 1 ms with the duty varying between 0%-90%. The waveform is output on channel 0’s output pin TO01 observed on pin 9 of application header JA5. Pressing switch SW1 will freeze the duty cycle from varying and display the percentage on line two of the debug LCD, subsequently, switch SW2 presses resumes the variations and clears the debug LCD’s line 2.
 6. When Square-wave output is selected, connect an oscilloscope to pin 20 of JA2.
 7. For Square-wave output the sample displays “Tr.SqOut” on the first line of the debug LCD and “JA2-20” on the second. A 1KHz square-wave is output on channel 5’s output pin TO05 observed on pin 20 of the application header JA2.
 8. For Interval measurement the sample displays “Tr.Intvl” on the first line of the debug LCD and “Push SW1” on the second. The external interrupt pin connected to switch SW1 is enabled before the sample enters an infinite while loop. The rest of the sample is handled using interrupts. TAU’s channel 5 is configured to periodically generate interrupts at 1ms intervals. Pressing down on SW1 generates an interrupt handled by the corresponding interrupt handler. The interrupt handler firstly verifies the signal edge detection before either starting or stopping channel 5’s counting. If the edge detection is falling edge detection the interrupt count variable gTimerTick is cleared and the edge detection is changed to rising edge detection. Channel 5’s counting is then

started prior to the interrupt handler exiting and returning to the main function. The count continues for the duration of SW1 being held down. TAU Channel 5's interrupt handler is called several times, incrementing `gTimer_Tick` by a value of 1, within this duration. As soon as SW1 is released, the corresponding interrupt handler is called to stop TAU channel 5's counting, check if the counting is less than 10000. If less, the hex count value is converted to a binary coded decimal (BCD) string and displayed on the second line of the debug LCD in milliseconds. If the value exceeds 10000 then the string " > 10s" is displayed instead to indicate that the duration exceeds 10 seconds. The signal detection is changed back to falling edge detection before exiting the interrupt handler and returning to the main function until the next time SW1 is pressed.

9. For Event Count the sample displays "Tr.Event" on the first line of the debug LCD and "Count: " on the second. Count variable `gEventCount` is cleared before TAU channel 3's count is started. The sample then enters an infinite while loop with the rest of the application handled by interrupts. TAU channel 3 is configured to be clocked by an external clock signal on its input signal pin TI03. This pin is multiplexed with the output signal TO03 as well as the external event interrupt signal (INTP4) connected to SW3. The external even interrupt is disabled and the falling edge signals of SW3 clocks TAU channel 3. An interrupt request is generated on each falling edge signal and handled by the corresponding interrupt handler. The interrupt handler checks if the count of detected events is less than 99 and increments the count if this is true, otherwise the count is set to one. The hex count value is converted to a string and displayed on the debug LCD's second line.

5.10 DMAC

5.10.1 Description

This sample demonstrates usage of the DMAC (Direct Memory Access Controller), by performing a DMA transfer to an incrementing location in an array when switch SW1 is pressed.

- Open the Memory window from the menu bar View → Memory → Memory1
- Scroll to address range 0xFFA00 – 0xFFBFF
- Observe the random data stored within these locations.

5.10.2 Operation

1. All peripherals and modules are configured prior to the program calling the main function.
2. The sample initialises the LCD module, and displays "DMAC" on the first line and "Push SW1" on the second. All user LEDs are turned on.
3. The sample enables switch SW1 interrupts and waits for the user to press SW1.
4. The sample then calls the `DMAC_DataTransfer` function, which configures the DMAC and channel 0 of SAU0. The SAU0's channel 0 is configured for transmission with each transmitted data byte transferred to memory by the DMAC inside a while loop. A total transfer of 512 bytes takes place before the loop is exited.
5. All user LEDs are turned off once the transfer ends. The second line of the LCD module will display "END".
6. The sample then enters an infinite while loop.
7. Stop the program execution and observe the memory contents.
8. Memory locations 0xFFA00 – 0xFFBFF should be filled up with the string "Renesas RL78G13".

5.11 WDT

5.11.1 Description

This sample demonstrates usage of the WDT (Watch Dog Timer). The WDT has been configured to generate an interrupt when the timer's count reaches 75% of its period. A TAU channel is configured to generate periodic interrupts whose period varies with the ADC value set by the potentiometer's positioning and restart the WDT's count. Before executing the program, ensure the potentiometer is turned fully counter-clockwise.

5.11.2 Operation

1. All peripherals and modules are configured prior to the program calling the main function.
2. The sample initialises the LCD module, and displays “WDT” on the first line and “Running.” on the second.
3. The sample then starts the WDT, ADC and TAU channel before entering an infinite while loop. All subsequent operations are handled by interrupts.
4. The ADC continuously converts the voltage set by the potentiometer and the result is stored in a global variable `gWDT_Period_Updater` within the ADC’s interrupt handler. The TAU channel’s interrupt handler is called on every count overflow. It stops the channel’s count, checks if the less than 75% of the period and restarts the WDT’s count if this is true. The TAU channel’s period is updated using the ADC result multiplied by a factor of 58. The user LEDs’ states are toggled and the TAU channel’s counting is restarted. Turning the potentiometer clockwise will reduce the user TAU channel’s period and user LEDs’ flashing rate; eventually resulting to the TAU channel’s period being greater than the WDT’s and resulting in the WDT reaching 75% and generating an interrupt. The WDT interrupt handler stops the ADC and TAU operations, displays “75%” on the second line of the debug LCD before entering an infinite while loop. To prevent the WDT causing a device reset, the WDT’s count is restarted within the loop.
5. Reset the RSK to restart the test.

5.12 RTC

5.12.1 Description

This sample demonstrates usage of the RTC (Real Time Clock) with the time displayed on the debug LCD. The RTC is configured to use the sub-clock to generate 1 Hz periodic interrupts and output a 1Hz signal on the RTC1HZ pin which is also multiplexed with other signals, though they are not used. The 1Hz can be observed on pin 16 of J2.

5.12.2 Operation

1. All peripherals and modules are configured prior to the program calling the main function.
2. The sample initialises the LCD module, and displays “RTC” on the first line and “00:00:00” on the second.
3. The sample then enables the output of the RTC’s 1Hz signal before enabling the RTC module and entering an infinite while loop.
4. The rest of the sample is handled using interrupts.
5. Each 1Hz count, corresponding to 1 second, generates an interrupt. The interrupt handler executes the callback function `RTC_ConstPeriodInterruptCallback` which reads the RTC registers, converts them to ASCII equivalent values then displayed on the debug LCD.

6. Additional Information

Technical Support

For more details on how to use IAR Embedded Workbench, refer to [Help > Content] from the menu bar within the IAR Embedded Workbench.

For information about the RL78G13 series microcontrollers refer to the RL78G13 Group hardware manual.

For information about the RL78G13 assembly language, refer to the RL78 Series Software Manual.

Online technical support and information is available at: <http://www.renesas.com/rskrl78g13>

Technical Contact Details

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General information on Renesas Microcontrollers can be found on the Renesas website at:

<http://www.renesas.com/>

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