

RA8D1 Group

Evaluation Kit for RA8D1 Microcontroller Group
EK-RA8D1 v1
User's Manual

Renesas RA Family
RA8 Series

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General Precautions in the Handling of Microprocessing Unit and Microcontroller Unit Products

The following usage notes are applicable to all Microprocessing unit and Microcontroller unit products from Renesas. For detailed usage notes on the products covered by this document, refer to the relevant sections of the document as well as any technical updates that have been issued for the products.

1. Precaution against Electrostatic Discharge (ESD)

A strong electrical field, when exposed to a CMOS device, can cause destruction of the gate oxide and ultimately degrade the device operation. Steps must be taken to stop the generation of static electricity as much as possible, and quickly dissipate it when it occurs. Environmental control must be adequate. When it is dry, a humidifier should be used. This is recommended to avoid using insulators that can easily build up static electricity. Semiconductor devices must be stored and transported in an anti-static container, static shielding bag or conductive material. All test and measurement tools including work benches and floors must be grounded. The operator must also be grounded using a wrist strap. Semiconductor devices must not be touched with bare hands. Similar precautions must be taken for printed circuit boards with mounted semiconductor devices.

2. Processing at power-on

The state of the product is undefined at the time when power is supplied. The states of internal circuits in the LSI are indeterminate and the states of register settings and pins are undefined at the time when power is supplied. In a finished product where the reset signal is applied to the external reset pin, the states of pins are not guaranteed from the time when power is supplied until the reset process is completed. In a similar way, the states of pins in a product that is reset by an on-chip power-on reset function are not guaranteed from the time when power is supplied until the power reaches the level at which resetting is specified.

3. Input of signal during power-off state

Do not input signals or an I/O pull-up power supply while the device is powered off. The current injection that results from input of such a signal or I/O pull-up power supply may cause malfunction and the abnormal current that passes in the device at this time may cause degradation of internal elements. Follow the guideline for input signal during power-off state as described in your product documentation.

4. Handling of unused pins

Handle unused pins in accordance with the directions given under handling of unused pins in the manual. The input pins of CMOS products are generally in the high-impedance state. In operation with an unused pin in the open-circuit state, extra electromagnetic noise is induced in the vicinity of the LSI, an associated shoot-through current flows internally, and malfunctions occur due to the false recognition of the pin state as an input signal become possible.

5. Clock signals

After applying a reset, only release the reset line after the operating clock signal becomes stable. When switching the clock signal during program execution, wait until the target clock signal is stabilized. When the clock signal is generated with an external resonator or from an external oscillator during a reset, ensure that the reset line is only released after full stabilization of the clock signal. Additionally, when switching to a clock signal produced with an external resonator or by an external oscillator while program execution is in progress, wait until the target clock signal is stable.

6. Voltage application waveform at input pin

Waveform distortion due to input noise or a reflected wave may cause malfunction. If the input of the CMOS device stays in the area between V_{IL} (Max.) and V_{IH} (Min.) due to noise, for example, the device may malfunction. Take care to prevent chattering noise from entering the device when the input level is fixed, and also in the transition period when the input level passes through the area between V_{IL} (Max.) and V_{IH} (Min.).

7. Prohibition of access to reserved addresses

Access to reserved addresses is prohibited. The reserved addresses are provided for possible future expansion of functions. Do not access these addresses as the correct operation of the LSI is not guaranteed.

8. Differences between products

Before changing from one product to another, for example to a product with a different part number, confirm that the change will not lead to problems. The characteristics of a microprocessing unit or microcontroller unit products in the same group but having a different part number might differ in terms of internal memory capacity, layout pattern, and other factors, which can affect the ranges of electrical characteristics, such as characteristic values, operating margins, immunity to noise, and amount of radiated noise. When changing to a product with a different part number, implement a system-evaluation test for the given product.

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Precautions

This Evaluation Kit is only intended for use in a laboratory environment under ambient temperature and humidity conditions. A safe separation distance should be used between this and any sensitive equipment. Its use outside the laboratory, classroom, study area, or similar such area invalidates conformity with the protection requirements of the Electromagnetic Compatibility Directive and could lead to prosecution.

The product generates, uses, and can radiate radio frequency energy and may cause harmful interference to radio communications. There is no guarantee that interference will not occur in a particular installation. If this equipment causes harmful interference to radio or television reception, which can be determined by turning the equipment off or on, you are encouraged to try to correct the interference by one or more of the following measures:

- Ensure attached cables do not lie across the equipment.
- Reorient the receiving antenna.
- Increase the distance between the equipment and the receiver.
- Connect the equipment into an outlet on a circuit different from that which the receiver is connected.
- Power down the equipment when not in use.
- Consult the dealer or an experienced radio/TV technician for help.

Note: It is recommended that wherever possible shielded interface cables are used.

The product is potentially susceptible to certain EMC phenomena. To mitigate against them it is recommended that the following measures be undertaken:

- The user is advised that mobile phones should not be used within 10 m of the product when in use.
- The user is advised to take ESD precautions when handling the equipment.

The Evaluation Kit does not represent an ideal reference design for an end product and does not fulfill the regulatory standards for an end product.

Renesas RA Family

EK-RA8D1 v1
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1. Kit Overview

The EK-RA8D1, an Evaluation Kit for RA8D1 MCU Group, enables users to seamlessly evaluate the features of the RA8D1 MCU group and develop embedded systems applications using Flexible Software Package (FSP) and e² studio IDE. The users can utilize rich on-board features along with their choice of popular ecosystems add-ons to bring their big ideas to life.

The EK-RA8D1 kit consists of three boards: the EK-RA8D1 board featuring the RA8D1 MCU, MIPI Graphics Expansion Board, and Camera Expansion Board.

The key features of the EK-RA8D1 board are categorized in three groups (consistent with the architecture of the kit, with a few exceptions) as follows:

MCU Native Pin Access

- R7FA8D1BHECBD MCU (referred to as RA MCU)
- 480 MHz, Arm[®] Cortex[®]-M85 core
- 2 MB Code Flash, 1 MB SRAM
- 224 pins, BGA package
- Native pin access through 6 x 20-pin, and 1 x 40-pin male header
- MCU current measurement points for precision current consumption measurement
- Multiple clock sources – RA MCU oscillator and sub-clock oscillator crystals, providing precision 20.000 MHz and 32,768 Hz reference clocks. Additional low-precision clocks are available internal to the RA MCU

System Control and Ecosystem Access

- USB Full Speed Host and Device (micro-AB connector)
- Four 5 V input sources
 - USB (Debug, Full Speed, High Speed)
 - External power supply (using surface mount clamp test points and power input vias)
- Three Debug modes
 - Debug on-board (SWD and JTAG)
 - Debug in (ETM, SWD, SWO and JTAG)
 - Debug out (SWD, SWO and JTAG)
- User LEDs and buttons
 - Three User LEDs (red, blue, green)
 - Power LED (white) indicating availability of regulated power
 - Debug LED (yellow) indicating the debug connection
 - Two User buttons
 - One Reset button
- Five most popular ecosystems expansions
 - Two Seeed Grove[®] system (I²C/I³C/Analog) connectors (not populated)
 - SparkFun[®] Qwiic[®] connector (not populated)
 - Two Digilent Pmod[™] (SPI, UART and I²C) connectors
 - Arduino[™] (Uno R3) connector
 - MikroElektronika[™] mikroBUS connector
- MCU boot configuration jumper

Special Feature Access

- Ethernet (RJ45 RMII interface)
- USB High Speed Host and Device (micro-AB connector)
- 64 MB (512 Mb) External Octo-SPI Flash (present in the MCU Native Pin Access area)
- 64 MB (512 Mb) SDRAM (present in the MCU Native Pin Access area)
- MIPI Graphics Expansion Port (present in the MCU Native Pin Access area)
- Parallel Graphics Expansion Port (present in the MCU Native Pin Access area)
- Camera Expansion Port (present in the MCU Native Pin Access area)

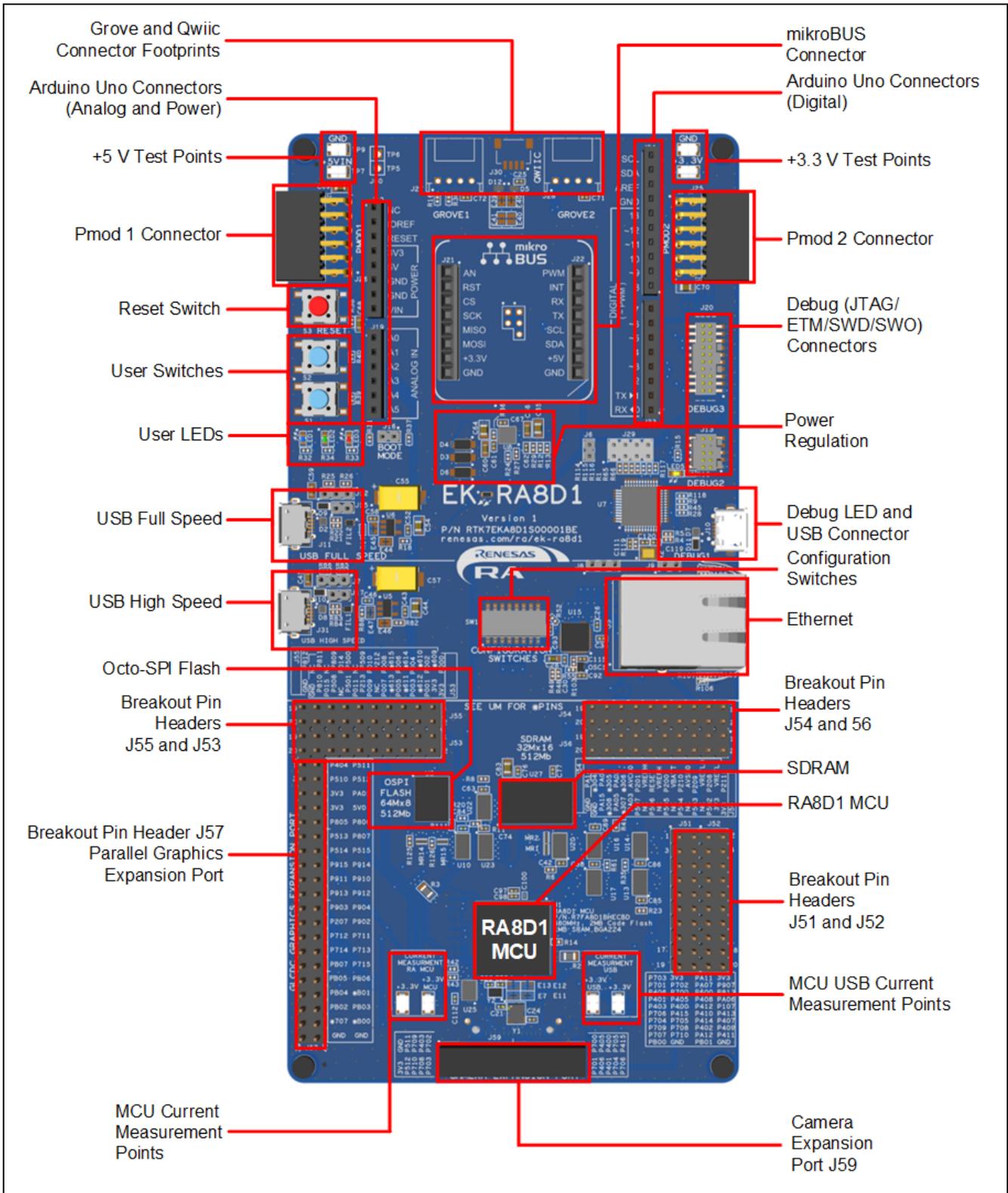


Figure 1. EK-RA8D1 Board Top Side

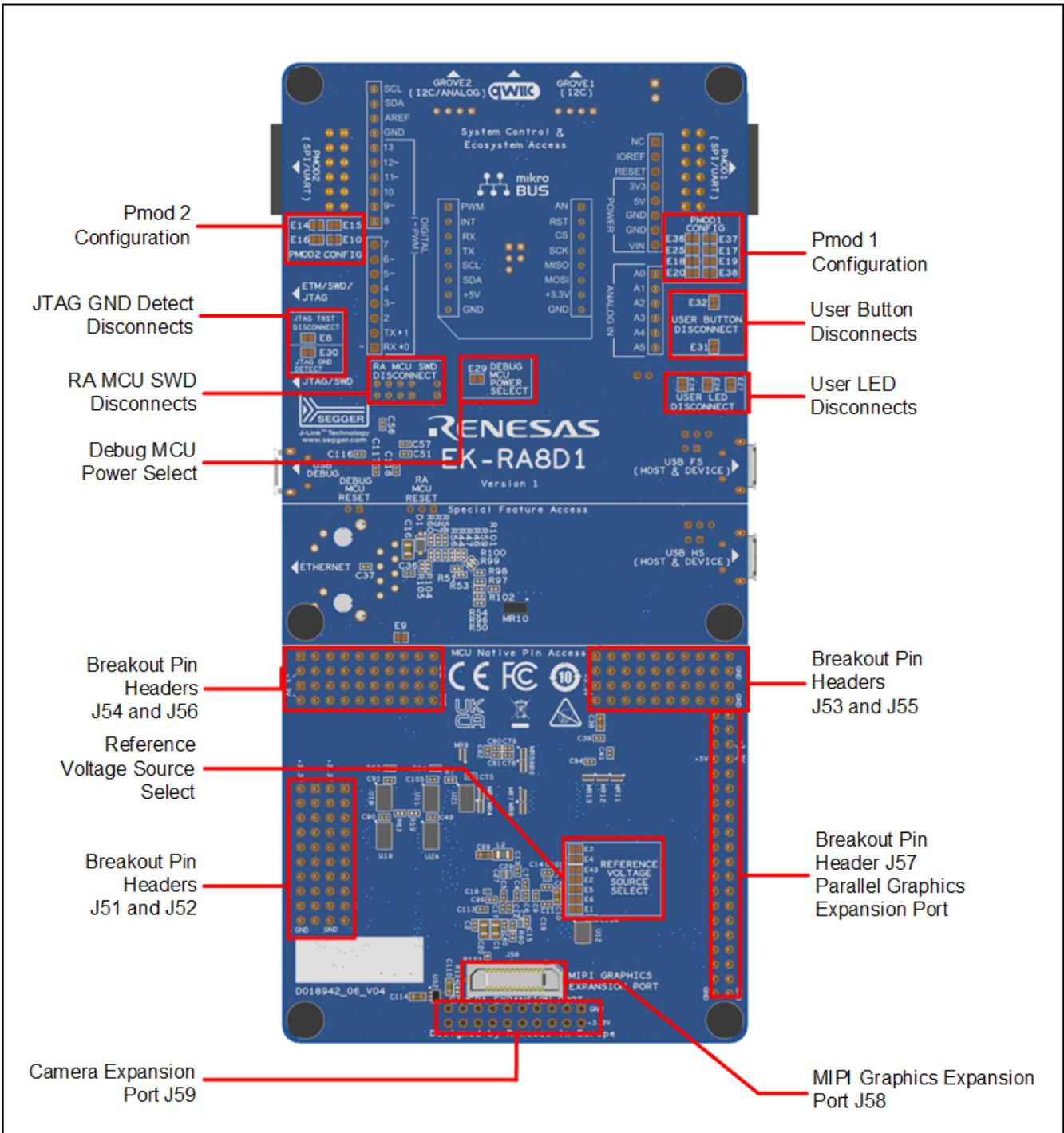


Figure 2. EK-RA8D1 Board Bottom Side

The key features of the included expansion boards are as follows:

MIPI Graphics Expansion Board

- 4.5 Inch backlit TFT display, 16.7M display colors
- 480 x 854 pixels resolution
- 2-lane MIPI interface
- Capacitive touch overlay (I²C)

Camera Expansion Board

- Off-the-shelf Arducam CMOS OV3640 Camera Module
- ¼ Inch 3.1 Megapixel image sensor
- Up to 15 fps in QXGA (2048x1536 pixels) resolution

1.1 Assumptions and Advisory Notes

1. It is assumed that the user has a basic understanding of microcontrollers and embedded systems hardware.
2. It is recommended that the user refers to the *EK-RA8D1 Quick Start Guide* to get acquainted with the kit and the Quick Start example project that EK-RA8D1 board comes pre-programmed with.
3. Flexible Software Package (FSP) and Integrated Development Environment (IDE) such as e² studio are required to develop embedded applications on EK-RA8D1 kit.
4. Instructions to download and install software, import example projects, build them and program the EK-RA8D1 board are provided in the quick start guide.
5. The MCU fitted to the EK board may not contain the latest version of the on-chip boot firmware.

2. Kit Contents

The following components are included in the kit:

1. EK-RA8D1 v1 board
2. Micro USB device cable (type-A male to micro-B male)
3. Micro USB host cable (type-A female to micro-B male)
4. Ethernet patch cable
5. Camera Expansion Board
6. MIPI Graphics Expansion Board
7. Nylon mounting stands (4x long, 2x short), nylon screws (6x)

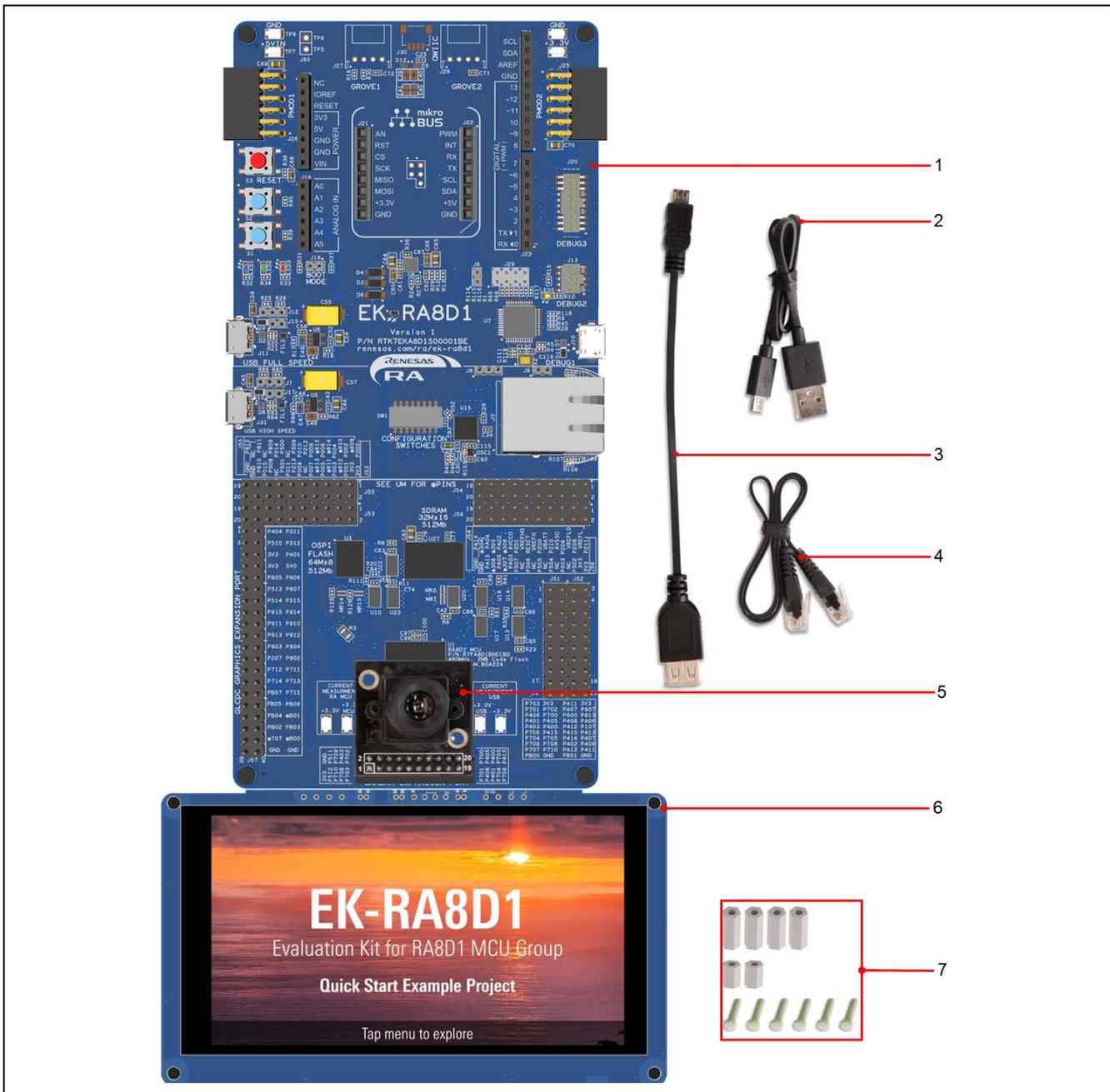


Figure 3. EK-RA8D1 Kit Contents

3. Ordering Information

- EK-RA8D1 v1 kit orderable part number: RTK7EKA8D1S01001BE

Notes: 1. The underlined character in the orderable part number represents the kit version.

2. The MIPI Graphics Expansion Board part number: RTKMIPILCDB00000BE.

3. The Camera Expansion Board orderable part number: ArduCam B0156

- Dimensions
 - EK-RA8D1 board: 80 mm (width) x 170 mm (length)
 - MIPI Graphics Expansion Board: 120 mm (width) x 90 mm (length)
 - Camera Expansion Board: 30.5 mm (width) x 30.5 mm (length)

4. Hardware Architecture and Default Configuration

4.1 Kit Architecture

The EK-RA8D1 board is designed with three sections or areas to help shorten the learning curve of users and maximize the design and knowledge reuse among similar kits. The contents of these three areas are conceptually standardized among similar kits.

Table 1. Kit Architecture

| Kit area | Area features | Area present on all similar kits | Functionality is: |
|--|---|----------------------------------|-------------------------------------|
| MCU Native Pin Access Area | RA MCU, breakout pin headers for all MCU I/O and power, current measurement MIPI Graphics Expansion Port, Parallel Graphics Expansion Port Camera Expansion Port, Octo-SPI Flash, and SDRAM | Yes | MCU dependent |
| Special Feature Access Area | Configuration Switches MCU special features: Ethernet and USB High Speed Host and Device | No | MCU dependent |
| System Control and Ecosystem Access Area | Power, Debug MCU, User LED and buttons, reset, ecosystem connectors, USB Full Speed Host and Device, and Boot configuration | Yes | Same or similar across similar kits |

Note: The Octo-SPI Flash and SDRAM are among the Special Feature Access features. Normally, they would be in the Special Feature Access Area, however, to optimize the layout, routing, and performance, they are placed in the MCU Native Pin Access area.

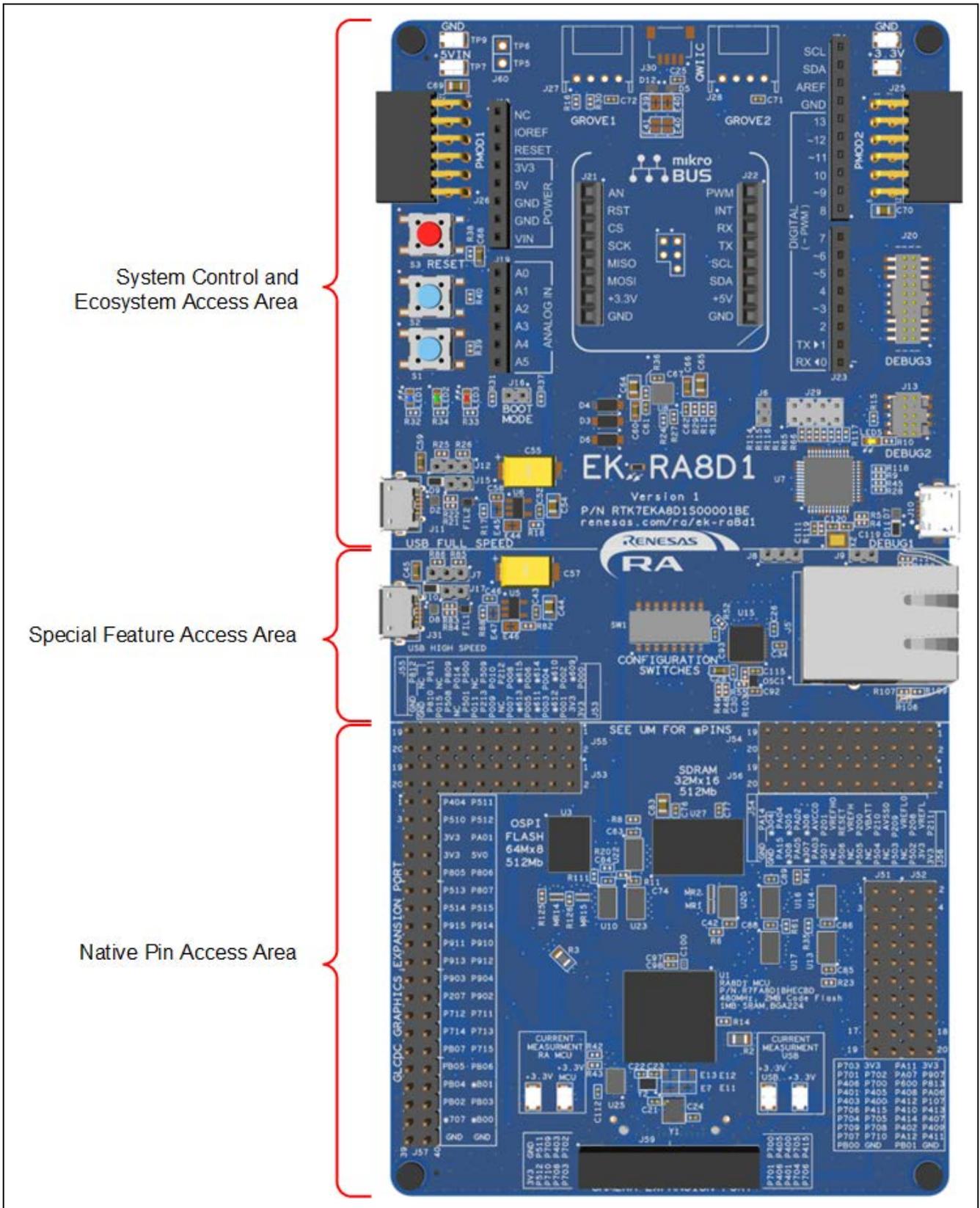


Figure 4. EK-RA8D1 Board Functional Area Definitions

4.2 System Block Diagram

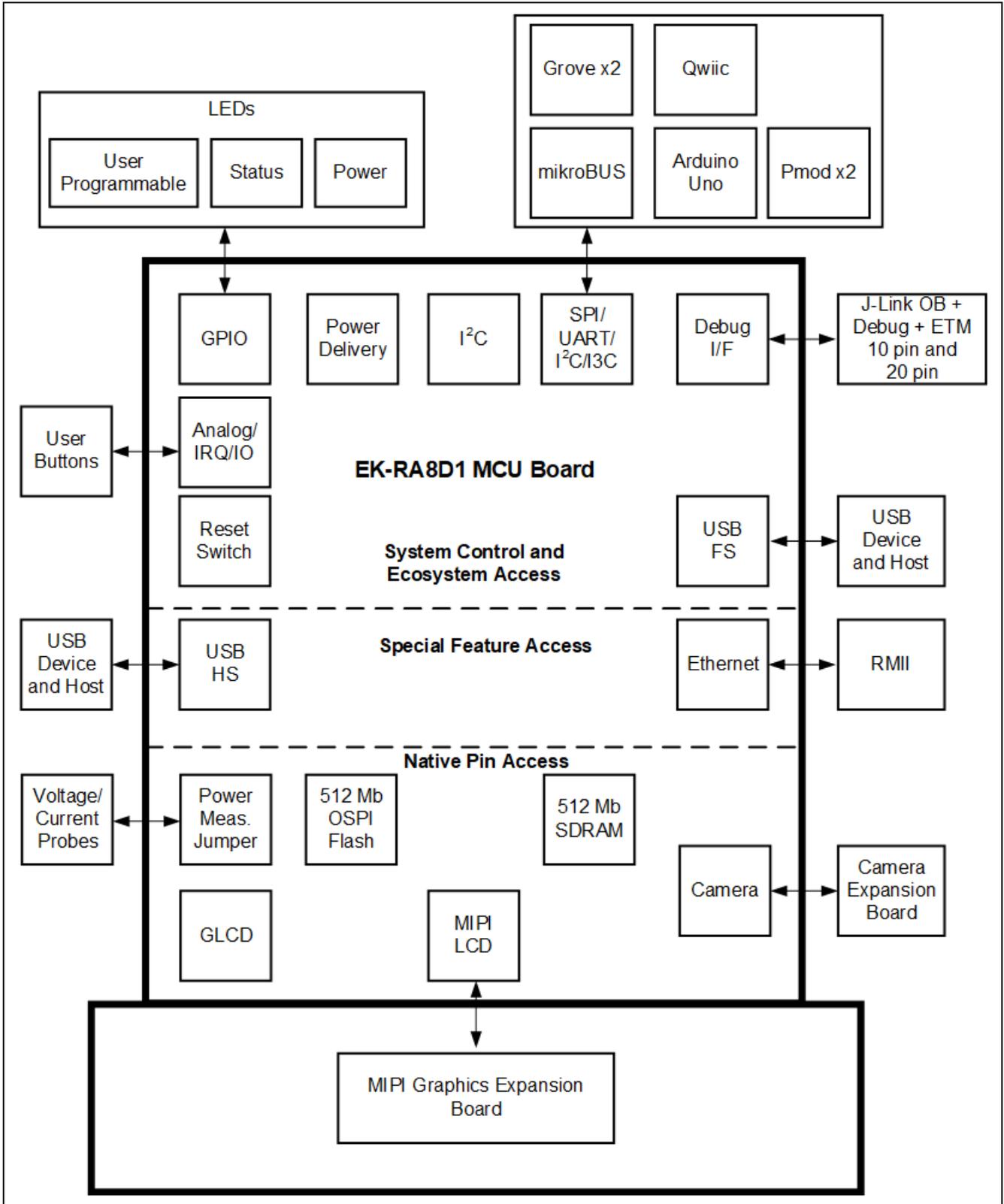


Figure 5. EK-RA8D1 Board Block Diagram

4.3 Jumper Configuration

Two types of jumpers are provided on the EK-RA8D1 board.

1. Copper jumpers (trace-cut type and solder bridge type)
2. Traditional pin header jumpers

The following sections describe each type and their default configuration.

4.3.1 Copper Jumpers

Copper jumpers are of two types, designated **trace-cut** and **solder-bridge**.

A **trace-cut jumper** is provided with a narrow copper trace connecting its pads. The silk screen overlay printing around a trace-cut jumper is a solid box. To isolate the pads, cut the trace between pads adjacent to each pad, then remove the connecting copper foil either mechanically or with the assistance of heat. Once the etched copper trace is removed, the trace-cut jumper is turned into a solder-bridge jumper for any later changes.

A **solder-bridge** jumper is provided with two isolated pads that may be joined together by one of three methods:

- Solder may be applied to both pads to develop a bulge on each and the bulges joined by touching a soldering iron across the two pads.
- A small wire may be placed across the two pads and soldered in place.
- A SMT resistor, size 0805, 0603, or 0402, may be placed across the two pads and soldered in place. A zero-ohm resistor shorts the pads together.

For any copper jumper, the connection is considered **closed** if there is an electrical connection between the pads (default for trace-cut jumpers.) The connection is considered **open** if there is no electrical connection between the pads (default for the solder-bridge jumpers.)

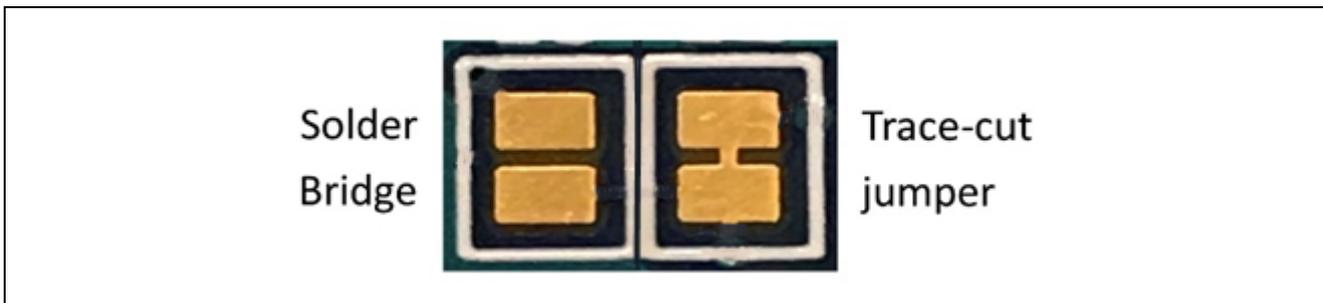


Figure 6. Copper Jumpers

4.3.2 Traditional Pin Header Jumpers

These jumpers are traditional small pitch jumpers that require an external shunt to open/close them. The traditional pin jumpers on the EK-RA8D1 board are 2 mm pitch headers and require compatible 2 mm shunt jumpers.

4.3.3 Default Jumper Configuration

The following table describes the default configuration for each jumper on the EK-RA8D1 board. This includes copper jumpers (Ex designation) and traditional pin jumpers (Jx designation).

The Circuit Group for each jumper is the designation found in the board schematic (available in the Design Package). Functional details for many of the listed jumpers may be found in sections associated with each functional area of the kits.

Table 2. Default Jumper Configuration

| Location | Circuit Group | Default Open/Closed | Function |
|----------|---------------|---------------------|---|
| J6 | J-Link OB | Open | Configures J-Link OB connection to MCU mode |
| J8 | J-Link OB | Jumper on pins 1-2 | Configures the MCU for normal operation |
| J9 | J-Link OB | Open | Configures JLOB_RESET# for on-board debugger mode |
| J29 | J-Link OB | Jumper on pins 1-2 | Connects the J-Link OB debugger to the RA MCU |

| Location | Circuit Group | Default Open/Closed | Function |
|----------|-----------------|--|--|
| | | Jumper on pins 3-4 Jumper on pins 5-6 Jumper on pins 7-8 | |
| J16 | MCU Boot Mode | Open | Configures the MCU for normal boot mode |
| J12 | USB FS | Jumper on pins 2-3 | Sets USB FS power to device mode |
| J15 | USB FS | Closed | Connects micro-USB power to system power |
| J7 | USB HS | Jumper on pins 2-3 | Sets USB HS power to device mode |
| J17 | USB HS | Closed | Connects micro-USB power to system power |
| E1 | MCU Power | Closed | Connects VREFL0 to GND |
| E2 | MCU Power | Closed | Connects VREFH to +3.3 V |
| E3 | MCU Power | Closed | Connects AVCC0 to +3.3 V |
| E4 | MCU Power | Closed | Connects AVSS0 to GND |
| E5 | MCU Power | Closed | Connects VREFL to GND |
| E6 | MCU Power | Closed | Connects VREFH0 to +3.3 V |
| E8 | Debug | Closed | Connects debugger JTAG_RESET# to JTAG connectors |
| E9 | Debug | Open | Connects JTAG_RESET# from JTAG connectors to J56 pin 15 |
| E7 | MCU Clock | Closed | Connects P212/EXTAL to 20 MHz crystal |
| E11 | MCU Clock | Closed | Connects P213/XTAL to 20 MHz crystal |
| E12 | MCU Clock | Open | Connects P213/XTAL pin to pin headers |
| E13 | MCU Clock | Open | Connects P212/EXTAL pin to pin headers |
| E26 | User LED | Closed | Connects P414 to User LED2 |
| E27 | User LED | Closed | Connects P600 to User LED1 |
| E28 | User LED | Closed | Connects P107 to User LED3 |
| E29 | Debug MCU Power | Closed | Connects the Debug MCU power to +3.3 V |
| E30 | JTAG | Closed | Connects the JTAG GND Detect pin on J20 and J13 to GND |
| E31 | User Switch | Closed | Connects P009 to User Switch S1 |
| E32 | User Switch | Closed | Connects P008 to User Switch S2 |
| E17 | Pmod1 | Open | Connects P613 (CTS0) to Pmod 1 pin1 |
| E18 | Pmod1 | Open | Connects P612 (RTS0) to Pmod 1 pin4 |
| E19 | Pmod1 | Closed | Connects P612 (SS0/CTS_RTS0) to Pmod 1 pin1 |
| E20 | Pmod1 | Closed | Connects P611 (SCK0) to Pmod 1 pin4 |
| E25 | Pmod1 | Closed | Connects +3.3 V to Pmod 1 |
| E36 | Pmod1 | Open | Connects +5.0 V to Pmod 1 |
| E37 | Pmod1 | Open | Connects P512 (SCL1) to Pmod 1 |
| E38 | Pmod1 | Open | Connects P511 (SDA1) to Pmod 1 |
| E10 | Pmod2 | Open | Connects PA06 (CTS2) to Pmod 2 pin 1 |
| E14 | Pmod2 | Open | Connects PA05 (RTS2) to Pmod 2 pin 4 |
| E15 | Pmod2 | Closed | Connects PA05 (SS2/CTS_RTS2) to Pmod 2 pin1 |
| E16 | Pmod2 | Closed | Connects PA04 (SCK2/RTS2) to Pmod 2 pin 4 |
| E39 | Grove 2 | Closed | Connects I3C SCL to Grove 2 |
| E40 | Grove 2 | Closed | Connects I3C SDA to Grove 2 |
| E41 | Grove 2 | Open | Connects P002 (AN102) to Grove 2 |
| E42 | Grove 2 | Open | Connects P005 (AN001) to Grove 2 |
| E43 | Arduino | Closed | Connects VREFH to the Arduino AREF pin |
| E44 | USBFS | Closed | Connects P500 to the VBUS power supply enable pin for USB Full Speed |

| Location | Circuit Group | Default Open/Closed | Function |
|----------|---------------|---------------------|--|
| E45 | USBFS | Closed | Connects P501 to the USB VBUS Fault signal for USB Full Speed |
| E46 | USBHS | Closed | Connects PB00 to the VBUS power supply enable pin for USB High Speed |
| E47 | USBHS | Closed | Connects P707 to the USB OVRCURA for USB High Speed |

4.3.4 Default Switch Configuration

The following table describes the function and default configuration for each switch that selects the operational peripheral pins on the EK-RA8D1 board.

The Circuit Group for each switch is the designation found in the board schematic (available in the Design Package). Functional details for many of the listed switches may be found in sections associated with each functional area of the kits.

Table 3. Default Switch Configuration (SW1)

| Location | Circuit Group | Default ON/Off | Function / Restrictions |
|----------|--------------------|----------------|---|
| SW1-1 | Pmod 1 | Off | Pmod 1 connectivity conflicts with SDRAM |
| SW1-2 | DEBUG TRACE | Off | TRACE connectivity conflicts with ETH-A and SDRAM |
| SW1-3 | CAMERA | ON | CAMERA conflicts with ETH-B and I3C |
| SW1-4 | ETHERNET A | Off | ETH-A conflicts with ETH-B, TRACE and SDRAM |
| SW1-5 | ETHERNET B | Off | ETH-B conflicts with ETH-A, CAMERA and I3C |
| SW1-6 | GLCD (not MIPI) | Off | GLCD conflicts with USB-HS |
| SW1-7 | SDRAM | ON | SDRAM conflicts with TRACE, ETH-A and Pmod 1 |
| SW1-8 | I3C | Off | I3C conflicts with ETH-B and CAMERA |

Table 4. Permitted Switch Configuration (SW1)

IMPORTANT: Ensure that invalid switch configuration is not made to avoid potential failures

| SWITCH S1 | SW1-1 Pmod 1 | SW1-2 TRACE | SW1-3 CAMERA | SW1-4 ETH-A | SW1-5 ETH-B | SW1-6 GLCD | SW1-7 SDRAM | SW1-8 I3C | USB-HS |
|--------------|--------------|-------------|--------------|-------------|-------------|------------|-------------|-----------|-----------|
| SW1-1 Pmod 1 | - | OK | OK | OK | OK | OK | NO | OK | OK |
| SW1-2 TRACE | OK | - | OK | NO | OK | OK | NO | OK | OK |
| SW1-3 CAMERA | OK | OK | - | OK | NO | OK | OK | NO | OK |
| SW1-4 ETH-A | OK | NO | OK | - | NO | OK | NO | OK | OK |
| SW1-5 ETH-B | OK | OK | NO | NO | - | OK | OK | NO | OK |
| SW1-6 GLCD | OK | OK | OK | OK | OK | - | OK | NO | NO |
| SW1-7 SDRAM | NO | NO | OK | NO | OK | OK | - | OK | OK |
| SW1-8 I3C | OK | OK | NO | OK | NO | NO | OK | - | OK |
| USB-HS | OK | OK | OK | OK | OK | NO | OK | OK | - |

5. System Control and Ecosystem Access Area

The following figure shows the System Control and Ecosystem Access area on the EK-RA8D1 board. Subsequent sections detail the features and functionality provided in the area.

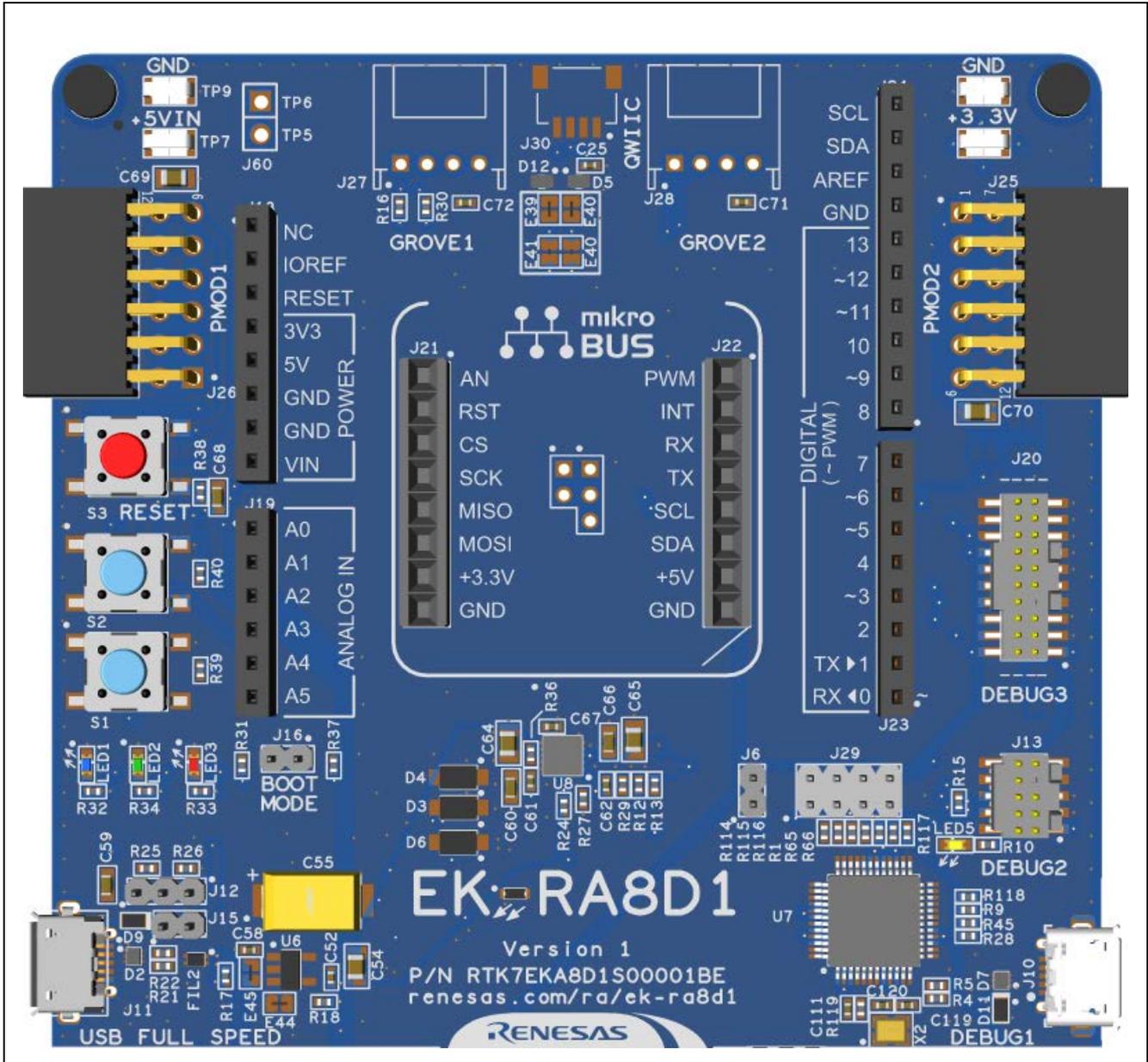


Figure 7. System Control and Ecosystem Access Area

5.1 Power

The EK-RA8D1 kit is designed for +5 V operation. An on-board Low Dropout Regulator (LDO) is used to convert the 5 V supply to a 3.3 V supply. The 3.3 V supply is used to power the RA MCU and other peripheral features.

5.1.1 Power Supply Options

This section describes the different ways in which EK-RA8D1 kit can be powered.

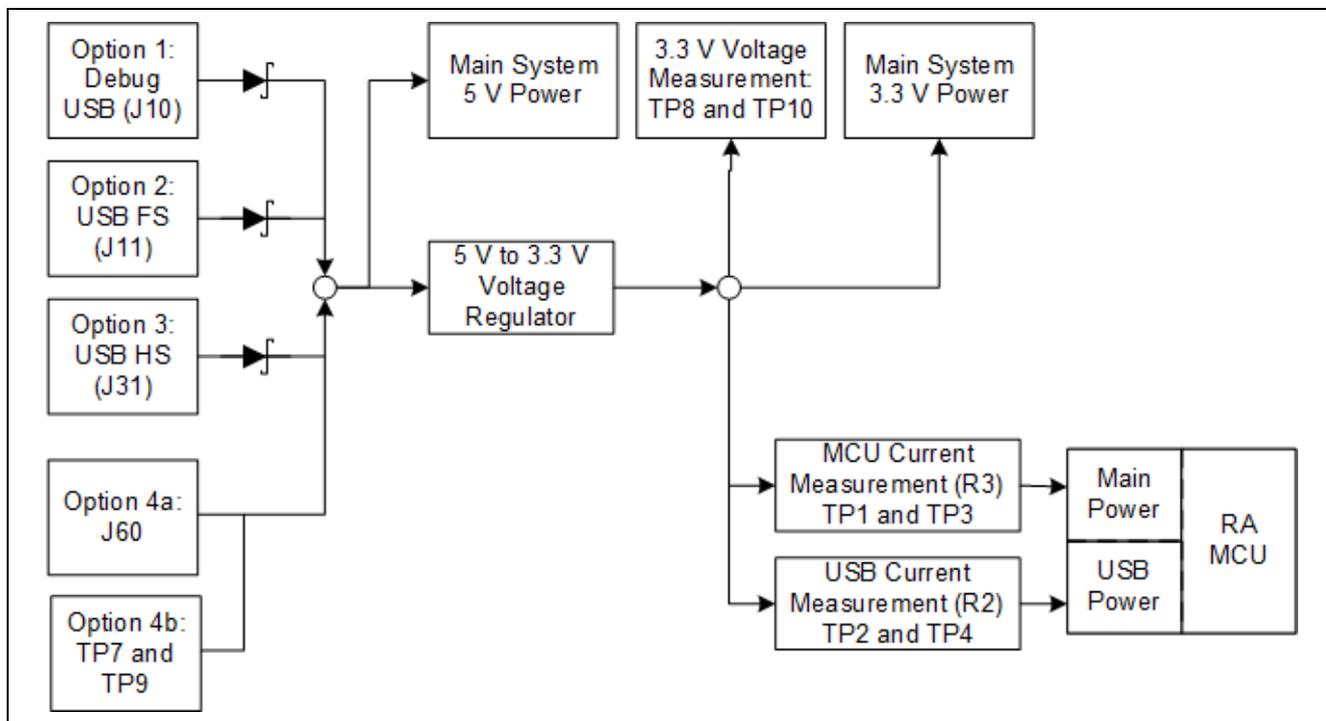


Figure 8. Power Supply Options

5.1.1.1 Option 1: Debug USB

5 V may be supplied from an external USB host to the USB Debug connector (J10) labelled DEBUG on the board. Power from this source is connected to the main system 5 V power. Reverse current protection is provided between this connector and the main system 5 V power.

5.1.1.2 Option 2: USB Full Speed

5 V may be supplied from an external USB host to the USB Full Speed connector (J11) labelled USB FULL SPEED on the board. Power from this source is connected to the main system 5 V power. Reverse current protection is provided between this connector and the main system 5 V power.

5.1.1.3 Option 3: USB High Speed

5 V may be supplied from an external USB host to the USB High Speed connector (J31) labelled USB HIGH SPEED on the board. Power from this source is connected to the main system 5 V power. Reverse current protection is provided between this connector and the main system 5 V power.

5.1.1.4 Option 4: 5 V Test Points

5 V may be supplied from an external power supply to test points on the board. TP7 (5 V) and TP9 (GND) are loop-style test points, and J60 provides large via style test points that can accommodate a 0.1" pin header or connector. The two types of test points are electrically equivalent, and both are provided for user convenience. Power from this source is connected to the main system 5 V power. These test points can be found at the top left of the board above Pmod1.

Please note that reverse current protection is not provided when the device is powered using this option. Please ensure that any source connected has reverse current protection on its own.

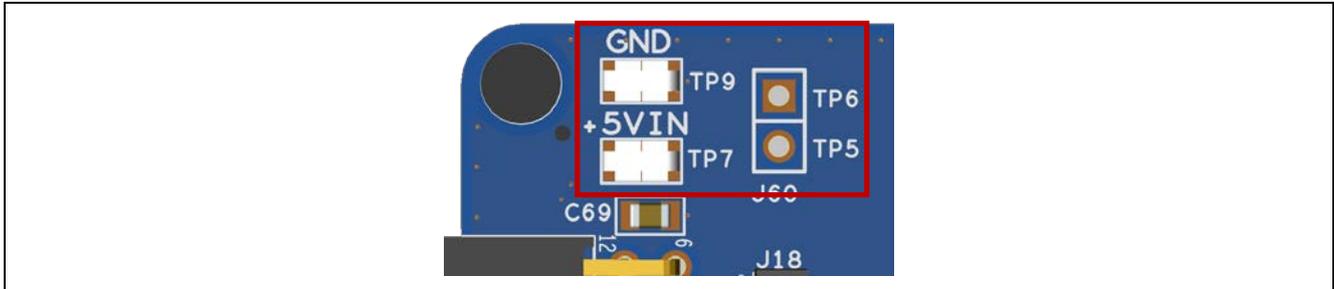


Figure 9. Test Point Location

5.1.2 Power Supply Considerations

The on-board LDO regulator which supplies +3.3 V has a built-in current limit of 2.0 A. Make sure the total current required by the RA MCU, any active on-board features, and any connected peripheral devices does not exceed this limit.

Note: The total current available from a typical enumerated USB host is 500 mA maximum. Depending on the configuration of the kit, multiple power sources may be required.

5.1.3 Power-up Behavior

When powered, the white LED near the center of the board (the “dash” in the EK-RA8D1 name) will light up. For more details on initial power up behavior, see the *EK-RA8D1 Quick Start Guide*.

5.2 Debug and Trace

The EK-RA8D1 board supports the following three debug modes.

Table 5. Debug Modes

| Debug Modes | Debugger MCU (the device that connects to the IDE on PC) | Target MCU (the device that is being debugged) | Debugging Interface/Protocol | Connector Used |
|----------------|--|--|------------------------------|--|
| Debug on-board | RA4M2 (on-board) | RA8D1 (on-board) | SWD, JTAG | Micro USB (J10) |
| Debug in | External debugging tools | RA8D1 (on-board) | SWD, SWO ,ETM, JTAG, | 20-pin connector (J20) or 10-pin connector (J13) |
| Debug out | RA4M2 (on-board) | Any external RA MCU | SWD, SWO, JTAG | Micro USB (J10) plus either 20-pin connector (J20) or 10-pin connector (J13) |

Notes:

- See Table 7 for the Debug USB connector pin definition.
- See Table 10 for the 20-pin JTAG connector pin definition.
- See Table 11 for the 10-pin JTAG connector pin definition.

The following table summarizes the jumper configuration for each of the debug modes.

Table 6. Jumper Connection Summary for Different Debug Modes

| Debug Modes | J6 | J8 | J9 | J29 |
|----------------|------|--------------------|--------|------------------------------------|
| Debug on-board | Open | Jumper on pins 1-2 | Open | Jumpers on pins 1-2, 3-4, 5-6, 7-8 |
| Debug in | Open | Jumper on pins 1-2 | Closed | Jumpers on pins 1-2, 3-4, 5-6, 7-8 |
| Debug out | Open | Jumper on pins 2-3 | Open | All pins open |

5.2.1 Debug On-Board

The on-board debug functionality is provided using Renesas RA4M2 Debug MCU and SEGGER J-Link® firmware. Debug USB Micro-B connector (J10) connects the RA4M2 Debug MCU to an external USB Full Speed Host, allowing re-programming and debugging of the target RA MCU firmware. This connection is the default debug mode for the EK-RA8D1 board.

The RA4M2 Debug MCU connects to the target RA MCU using the SWD interface or the JTAG interface.

Table 7. Debug USB Port Assignments

| Debug USB Port Assignments | | EK-RA8D1 |
|----------------------------|--|--------------------|
| Pin | Description | Signal/Bus |
| J10-1 | +5VDC | +5V_USB_DBG |
| J10-2 | Data- | USB_JLOB_N (U7-14) |
| J10-3 | Data+ | USB_JLOB_P (U7-15) |
| J10-4 | USB ID, jack internal switch, cable inserted | N.C. |
| J10-5 | Ground | GND |

A yellow indicator, LED5, shows the visual status of the debug interface. When the EK-RA8D1 board is powered on, and LED5 is blinking, it indicates that the RA4M2 Debug MCU is not connected to a programming host. When LED5 is on solid, it indicates that the RA4M2 Debug MCU is connected to a programming interface.

To configure the EK-RA8D1 board to use the Debug On-Board mode, configure the jumpers using the following table.

Table 8. Debug On-Board Jumper Configuration

| Location | Default Open/Closed | Function |
|----------|------------------------------------|--|
| J6 | Open | Target RA MCU MD connected to debug |
| J8 | Jumper on pins 1-2 | Target RA MCU RESET# connected to debug RESET# |
| J9 | Open | RA4M2 Debug MCU in normal operation mode |
| J29 | Jumpers on pins 1-2, 3-4, 5-6, 7-8 | Target RA MCU debug signals connected to the debug interface |

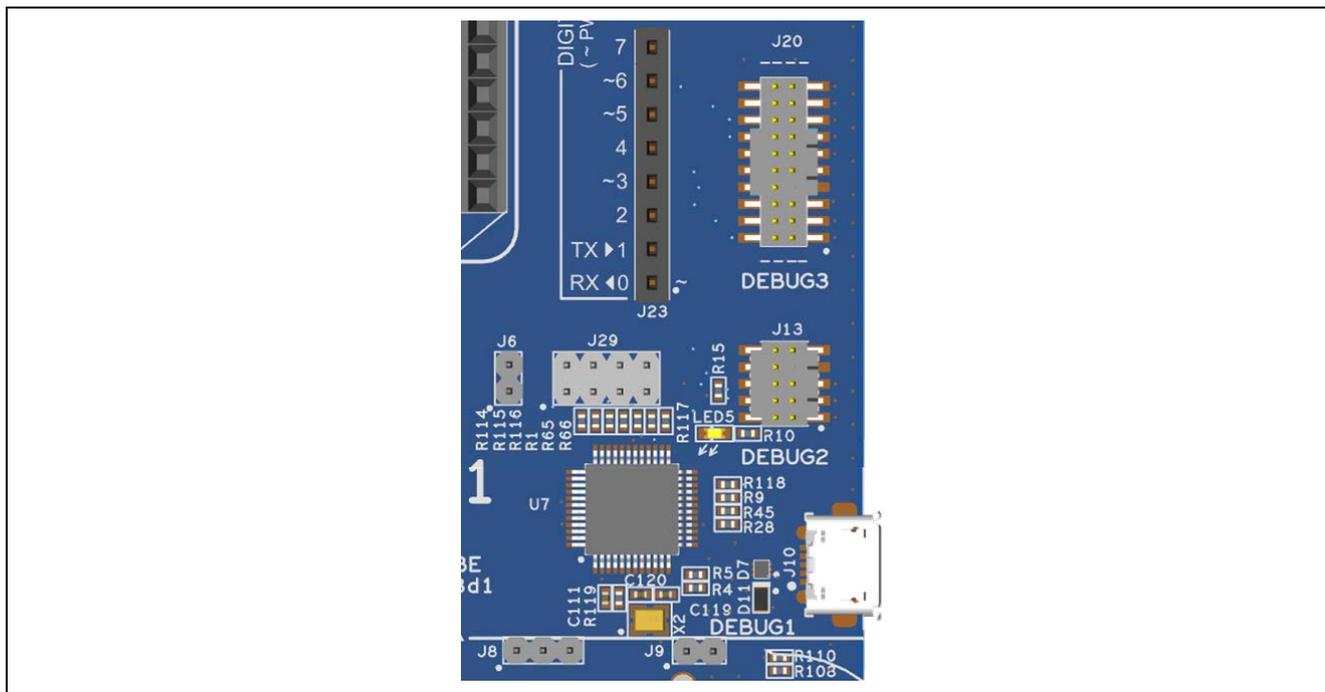


Figure 10. EK-RA8D1 Debug Interface

5.2.2 Debug In

One 20-pin Cortex® Debug Connector at J20 supports JTAG, SWD, SWO and ETM (TRACE) debug. One 10-pin Cortex® Debug Connector at J13 supports JTAG, SWD and SWO. Either of these connectors may be used for external debug of the target RA MCU.

To configure the EK-RA8D1 board to use the Debug In mode, configure the jumpers as shown in Table 9.

Table 9. Debug In Mode Jumper Configuration

| Location | Default Open/Closed | Function |
|----------|------------------------------------|--|
| J6 | Open | Target RA MCU MD connected to debug |
| J8 | Jumper on pins 1-2 | Target RA MCU RESET# connected to debug RESET# |
| J9 | Closed | RA4M2 Debug MCU is held in RESET |
| J29 | Jumpers on pins 1-2, 3-4, 5-6, 7-8 | Target RA MCU debug signals connected to the debug interface |

Table 10. JTAG/SWO/SWD/ETM Debug Port Assignments

| JTAG Port Assignments | | | | EK-RA8D1 |
|-----------------------|---------------|--------------|--------------|-----------------------|
| Pin | JTAG Pin Name | SWD Pin Name | ETM Pin Name | Signal/Bus |
| J20-1 | Vtref | Vtref | Vtref | +3V3 |
| J20-2 | TMS | SWDIO | TMS / SWDIO | P210/SWDIO/TMS |
| J20-3 | GND | GND | GND | GND |
| J20-4 | TCK | SWCLK | TCK / SWCLK | P211/SWCLK/TCK |
| J20-5 | GND | GND | GND | GND |
| J20-6 | TDO | SWO | TDO / SWO | P209/SWO/TDO |
| J20-7 | Key | Key | Key | N.C. |
| J20-8 | TDI | N/A | TDI / N/A | P208/TDI |
| J20-9 | GNDDetect | GNDDetect | GNDDetect | GND (cut E30 to open) |
| J20-10 | nSRST | nSRST | nSRST | RESET# |
| J20-11 | GND | GND | GND | GND |
| J20-12 | N/A | N/A | TCLK | P308/TCLK* |
| J20-13 | GND | GND | GND | GND |
| J20-14 | N/A | N/A | TDATA0 | P307/TDATA0* |
| J20-15 | GND | GND | GND | GND |

| JTAG Port Assignments | | | | EK-RA8D1 |
|-----------------------|---------------|--------------|--------------|-----------------|
| Pin | JTAG Pin Name | SWD Pin Name | ETM Pin Name | Signal/Bus |
| J20-16 | N/A | N/A | TDATA1 | P306/TDATA1*,** |
| J20-17 | GND | GND | GND | GND |
| J20-18 | N/A | N/A | TDATA2 | P305/TDATA2* |
| J20-19 | GND | GND | GND | GND |
| J20-20 | N/A | N/A | TDATA3 | P304/TDATA3* |

* Option selection by SW1-2

** Option to isolate with E9

Table 11. JTAG/SWO/SWD Debug Port Assignments

| JTAG Port Assignments | | | EK-RA8D1 |
|-----------------------|---------------|--------------|-----------------------|
| Pin | JTAG Pin Name | SWD Pin Name | Signal/Bus |
| J13-1 | Vtref | Vtref | +3V3 |
| J13-2 | TMS | SWDIO | P210/SWDIO/TMS |
| J13-3 | GND | GND | GND |
| J13-4 | TCK | SWCLK | P211/SWCLK/TCK |
| J13-5 | GND | GND | GND |
| J13-6 | TDO | SWO | P209/SWO/TDO |
| J13-7 | Key | Key | N.C. |
| J13-8 | TDI | N/A | P208/TDI |
| J13-9 | GNDDetect | GNDDetect | GND (cut E30 to open) |
| J13-10 | nSRST | nSRST | RESET# |

Note: The Cortex® Debug Connector is fully described in the Arm® CoreSight™ Architecture Specification.

5.2.3 Debug Out

The EK-RA8D1 board can be configured to use the RA4M2 Debug MCU to debug target RA MCU on an external board.

A yellow indicator, LED5, shows the visual status of the debug interface. When the EK-RA8D1 board is powered on, and LED5 is blinking, this indicates that the RA4M2 Debug MCU is not connected to a programming host. When LED5 is on solid, this indicates that the RA4M2 Debug MCU is connected to a programming interface. When the debug interface is actively in use, the LED will flicker randomly.

To configure the EK-RA8D1 board to use the Debug Out mode, configure the jumpers according to the following table.

Table 12. Debug Out Jumper Configuration

| Location | Default Open/Closed | Function |
|----------|---------------------|--|
| J6 | Open | No connection to RA MCU |
| J8 | Jumper on pins 2-3 | On-board RA MCU is held in RESET |
| J9 | Open | RA4M2 Debug MCU in normal operation mode |
| J29 | All jumpers removed | Disconnects the on-board RA MCU debug signals from the Debug Interface |

5.3 Ecosystem

The System Control and Ecosystem area provides users the option to simultaneously connect several third-party add-on modules compatible with five most popular ecosystems using the following connectors:

1. Two Seeed Grove® system (I²C/I³C/Analog) connectors (not populated)
2. One SparkFun® Qwiic® connector (not populated)
3. Two Digilent Pmod™ (SPI, UART and I²C) connectors
4. Arduino™ (Uno R3) connector
5. MikroElektronika™ mikroBUS connector

5.3.1 Seeed Grove® Connectors

5.3.1.1 Grove 1

A Seeed Grove I²C connector footprint is provided at J27. The RA MCU acts as a two-wire serial master, and a connected module acts as a two-wire serial slave.

Table 13. Grove 1 Port Assignments

| Grove 1 Connector | | EK-RA8D1 |
|-------------------|-------------|-------------|
| Pin | Description | Signal/Bus |
| J27-1 | SCL | P512 (SCL1) |
| J27-2 | SDA | P511 (SDA1) |
| J27-3 | VCC | +3.3 V |
| J27-4 | GND | GND |

5.3.1.2 Grove 2

A Seeed Grove I³C connector footprint is provided at J28. The RA MCU acts as a two-wire serial master, and a connected module acts as a two-wire serial slave.

Option links E39, E40, E41 and E42 provide the capability to convert this connector to an analog Seeed Grove implementation.

Table 14. Grove 2 Port Assignments

| Grove 2 Connector | | EK-RA8D1 | |
|-------------------|-------------|---------------------------|---------------------------|
| Pin | Description | Signal/Bus | |
| J28-1 | I3C_SCL | P400 (SCL0) ^{*1} | P005(AN001) ^{*2} |
| J28-2 | I3C_SDA | P401 (SDA0) ^{*1} | P002(AN102) ^{*2} |
| J28-3 | VCC | +3.3 V | |
| J28-4 | GND | GND | |

^{*1} Option selection by SW1-8

^{*2} Jumpers E39 and E40 are open, E41 and E42 are closed

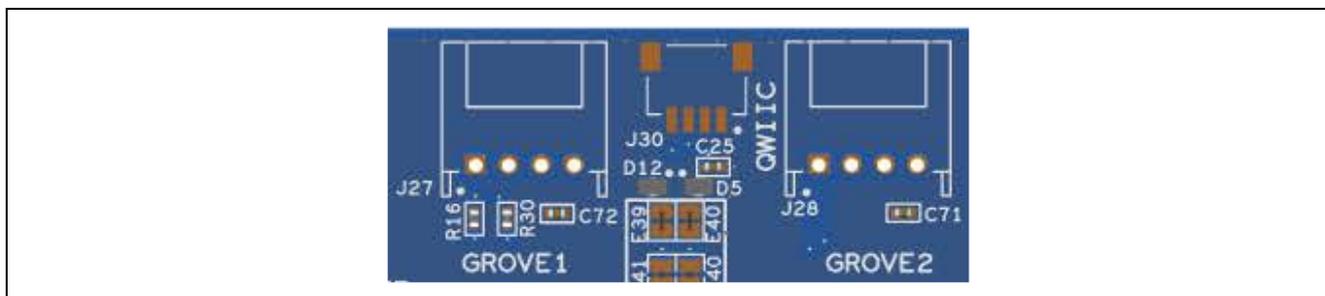


Figure 11. Seeed Grove and SparkFun Qwiic® Connector Footprints

5.3.2 SparkFun Qwiic® Connector

A SparkFun Qwiic connector footprint is provided at J30. The main MCU acts as a two-wire serial master, and a connected module acts as a two-wire serial slave (data lines shared with Grove 2).

Table 15. Qwiic Port Assignments

| Qwiic Connector | | EK-RA8D1 |
|-----------------|-------------|--------------|
| Pin | Description | Signal/Bus |
| J30-1 | GND | GND |
| J30-2 | VCC | +3.3 V |
| J30-3 | SDA | P400 (SCL0)* |
| J30-4 | SCL | P401 (SDA0)* |

* Option selection by SW1-8

* Note: The SDA and SCL connections are incorrectly swapped compared to the SparkFun Qwiic definition. Please manage the connection swap by modifying the cable.

5.3.3 Diligent Pmod™ Connectors

Two 12-pin connectors are provided to support Pmod modules where the RA MCU acts as the master, and the connected module acts as a slave device.

These interfaces may be configured in firmware to support several Pmod types such as Type-2A (expanded SPI) and Type-3A (expanded UART).

The EK-RA8D1 board also provides solder links so the 12-pin connector may alternatively be used for Pmod Type-6A (I²C).

The default 12-pin Pmod interface supports +3.3 V devices. Please ensure that any Pmod device installed is compatible with a +3.3 V supply*.

Note: Both Pmods use the SCI peripheral in “Simple SPI” mode, and so do not offer the full functionality of the SPI peripheral. Please see the hardware manual for full details of the SCI “Simple SPI” mode.

5.3.3.1 Pmod 1

A 12-pin Pmod connector is provided at J26, Pmod 1.

This Pmod connector is controlled by a switch option (SW1-1) as the signals needed are shared with the SDRAM. Pmod 1 and SDRAM cannot be used concurrently.

Table 16. Pmod 1 Port Assignments

| Pmod 1 Connector | | | | EK-RA8D1 | Pmod 1 Configuration | |
|------------------|------------------------------------|-------------------------------------|---|-------------------|----------------------|----------|
| Pin | Option Type-2A (SPI) ^{*1} | Option Type-3A (UART) ^{*1} | Option Type-6A (I ² C) ^{*1} | Signal/Bus | Short | Open |
| J26-1 | SS | | | P612 (SS0) | E19 | E17, E18 |
| | | CTS | | P613 (CTS0) | E17 | E19, E18 |
| J26-2 | MOSI | TXD | | P609 (MOSI0/TXD0) | | |
| J26-3 | MISO | RXD | | P610 (MISO0/RXD0) | | E37 |
| | | | SCL ^{*2} | P512 (SCL1) | E37 | |
| J26-4 | SCK | | | P611 (SCK0) | E20 | E18, E38 |
| | | RTS0 | | P612 (RTS0) | E18 | E20, E38 |
| | | | SDA ^{*2} | P511 (SDA1) | E38 | E18, E20 |
| J26-5 | GND | | | GND | | |
| J26-6 | VCC | | | +3.3 V | E25 | E36 |
| | | | | +5.0 V | E36 | E25 |
| J26-7 | IRQ | | | P006 (IRQ11) | | |
| J26-8 | RESET (master to slave) | | | PA12 | | |
| J26-9 | GPIO | | | P614 | | |
| J26-10 | GPIO | | | P615 | | |
| J26-11 | GND | | | GND | | |
| J26-12 | VCC | | | +3.3 V | E25 | E36 |
| | | | | +5.0 V | E36 | E25 |

^{*1} If using Option Type-2A (SPI) or Type-3A (UART), SW1-1 is on.

If using Option Type-6A (I²C), SW1-1 is off.

^{*2} Option selection by SW1-8

Caution: 5 V optional supply is provided (J26-6 and J26-12), however the interface must only be driven with 3.3 V signals from the Pmod 1. The EK-RA8D1 will only provide 3.3 V signal levels to the Pmod 1.

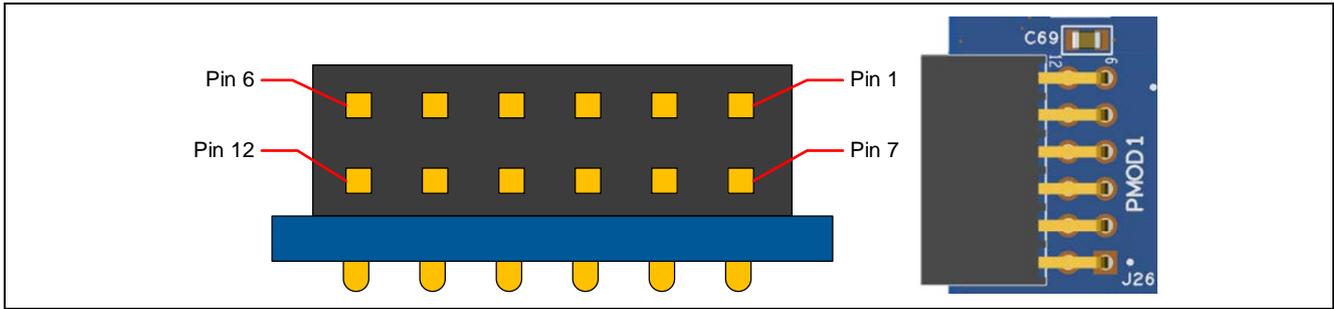


Figure 12. Pmod 1 Connector

5.3.3.2 Pmod 2

A 12-pin Pmod connector is provided at J25, Pmod 2.

Table 17. Pmod 2 Port Assignments

| Pmod 2 Connector | | | EK-RA8D1 | Pmod 2 Configuration | |
|------------------|-------------------------|-----------------------|-------------------|----------------------|------|
| Pin | Option Type-2A (SPI) | Option Type-3A (UART) | Signal/Bus | Short | Open |
| J25-1 | SS | | PA05 (SS2) | E15 | E10 |
| J25-1 | | CTS | PA06 (CTS2) | E10 | E15 |
| J25-2 | MOSI | TXD | PA03 (MOSI2/TXD2) | | |
| J25-3 | MISO | RXD | PA02 (MISO2/RXD2) | | |
| J25-4 | SCK | | PA04 (SCK2) | E16 | E14 |
| J25-4 | | RTS | PA05 (RTS2) | E14 | E16 |
| J25-5 | GND | | GND | | |
| J25-6 | VCC | | +3.3 V | | |
| J25-7 | IRQ | | P508 (IRQ1) | | |
| J25-8 | RESET (master to slave) | | P809 | | |
| J25-9 | GPIO | | P810 | | |
| J25-10 | GPIO | | P811 | | |
| J25-11 | GND | | GND | | |
| J25-12 | VCC | | +3.3 V | | |

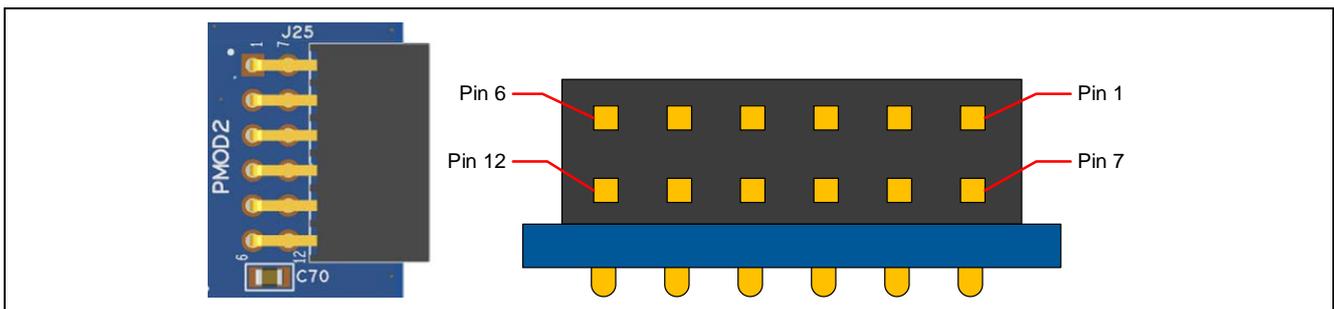


Figure 13. Pmod 2 Connector

5.3.4 Arduino™ Connector

Near the center of the System Control and Ecosystem Access area is an Arduino™ Uno R3 compatible connector interface.

Table 18. Arduino Uno Port Assignments

| Arduino Compatible Connectors | | EK-RA8D1 |
|-------------------------------|-------------|------------|
| Pin | Description | Signal/Bus |
| J18-1 | N.C. | N.C. |
| J18-2 | IOREF | +3.3 V |

| Arduino Compatible Connectors | | | | EK-RA8D1 |
|-------------------------------|--------------|----------|-----|-----------------------|
| Pin | Description | | | Signal/Bus |
| J18-3 | RESET | | | P813 |
| J18-4 | 3.3 V | | | +3.3 V |
| J18-5 | 5 V | | | +5 V |
| J18-6 | GND | | | GND |
| J18-7 | GND | | | GND |
| J18-8 | VIN | | | N.C. |
| J19-1 | A0 | | | P004 (AN000) |
| J19-2 | A1 | | | P003 (AN104) |
| J19-3 | A2 | | | P007 (AN004) |
| J19-4 | A3 | | | P011 (AN106) |
| J19-5 | A4 | | | P014 (AN007/DA0) |
| J19-6 | A5 | | | P015 (AN105/DA1) |
| J23-1 | D0 | RXD | PWM | P408 (RXD3/GTIOC10A) |
| J23-2 | D1 | TXD | | P409 (TXD3) |
| J23-3 | D2 | INT0 | | P509 (IRQ2) |
| J23-4 | D3 | INT1 | PWM | P907 (IRQ10/GTIOC13A) |
| J23-5 | D4 | | | P506 |
| J23-6 | D5 | | PWM | PA11 (GTIOC6A) |
| J23-7 | D6 | | PWM | PA06 (GTIOC7B) |
| J23-8 | D7 | | | P505 |
| J24-1 | D8 | | | P504 |
| J24-2 | D9 | | PWM | PA07 (GTIOC7A) |
| J24-3 | D10 | SPI_SS | | P413 (SSLA0) |
| J24-4 | D11 | SPI_MOSI | PWM | P411 (MOSIA/GTIOC9A) |
| J24-5 | D12 | SPI_MISO | PWM | P410 (MISOA/GTIOC9B) |
| J24-6 | D13 | SPI_SCK | | P412 (RSPCKA) |
| J24-7 | GND | | | GND |
| J24-8 | ARDUINO_AREF | | | +3.3 V |
| J24-9 | I3C_SDA | | | P401 (SDA0)* |
| J24-10 | I3C_SCL | | | P400 (SCL0)* |

* Option selection by SW1-8

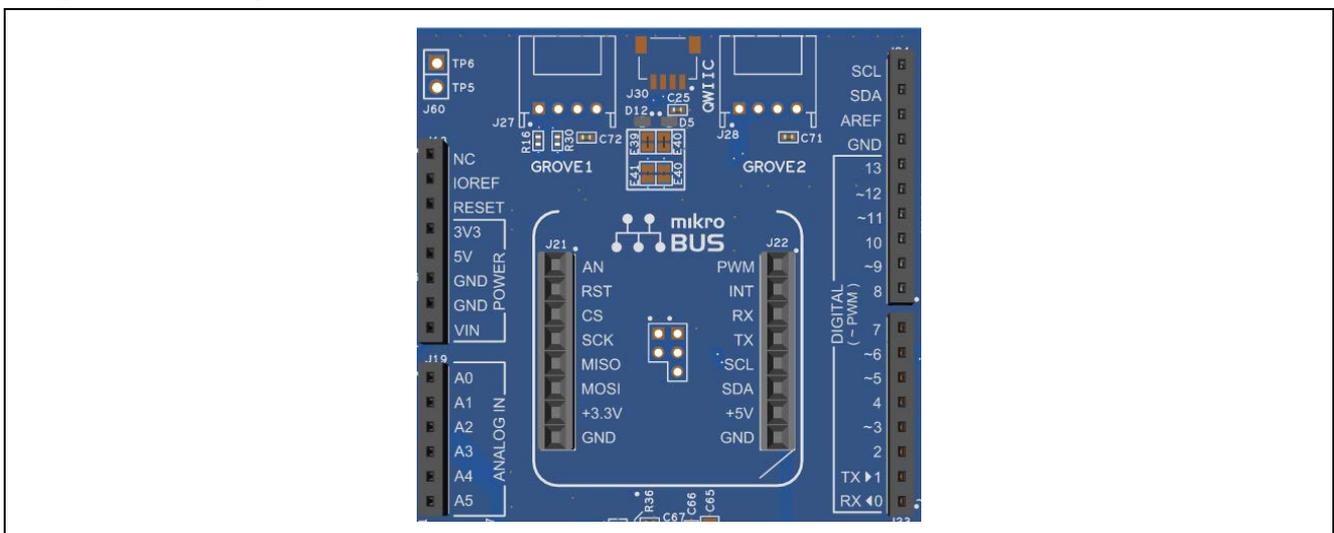


Figure 14. Arduino Uno Connectors

5.3.5 MikroElektronika™ mikroBUS Connector

In the center of the System Control and Ecosystem Access area is a mikroBUS compatible connector interface. This interface is compliant with mikroBUS Standard Specifications revision 2.00.

Table 19. mikroBUS Assignments

| mikroBUS Connectors | | EK-RA8D1 |
|---------------------|--------------------------|-----------------|
| Pin | Description | Signal/Bus |
| J21-1 | AN (Analog) | P004 (AN000) |
| J21-2 | RST (Reset) | P507 |
| J21-3 | CS (SPI Chip Select) | P413 (SSLA0) |
| J21-4 | SCK (SPI Clock) | P412 (RSPCKA) |
| J21-5 | MISO | P410 (MISOA) |
| J21-6 | MOSI | P411 (MOSIA) |
| J21-7 | +3.3 V | +3.3 V |
| J21-8 | GND | GND |
| J22-1 | PWM | P907 (GTIOC13A) |
| J22-2 | INT (Hardware Interrupt) | P010 (IRQ14) |
| J22-3 | RX (UART Receive) | P408 (RXD3) |
| J22-4 | TX (UART Transmit) | P409 (TXD3) |
| J22-5 | SCL (I3C Clock) | P400 (SCL0)* |
| J22-6 | SDA (I3C Data) | P401 (SDA0)* |
| J22-7 | +5 V | +5 V |
| J22-8 | GND | GND |

* Option selection by SW1-8

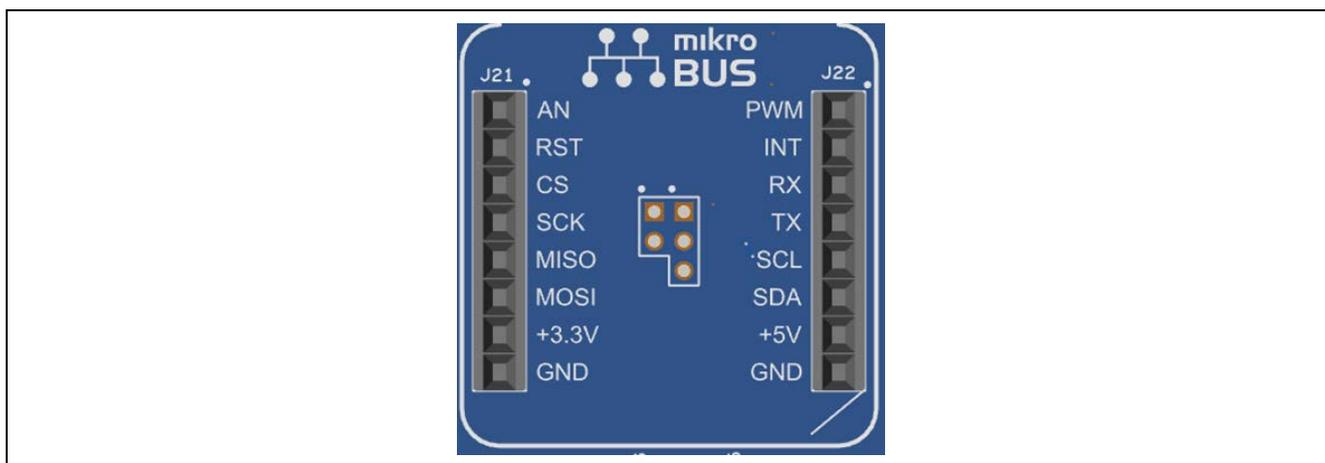


Figure 15. mikroBUS Connector

5.4 Connectivity

5.4.1 USB Full Speed

The USB micro-AB connection jack (J11) connects the RA MCU USB Full Speed interface to an external USB interface, allowing communications for testing and use of the RA MCU firmware. This connection can be configured as either a USB device or a USB host interface.

For a USB Device configuration, set jumper J12 to pins 2-3, install a jumper on J15 pins 1-2, and configure the RA MCU firmware to use the USB Full Speed ports in device mode. Power from an external USB Host on this connection can be used to provide power to the EK-RA8D1 board.

For a USB Host configuration, set jumper J12 to pins 1-2, remove the jumper from J15, and configure the RA MCU firmware to use the USB Full Speed ports in host mode. In this configuration, power to J11 is supplied from U6. The total current available from U6 is 500 mA. Note that the input power sources must be configured with enough power for both the EK-RA8D1 board and the USB Full Speed port in host mode. Connect the included USB type-A female to micro-B male cable to J11. USB device cables or devices can be connected to the USB Full Speed port using this cable.

Table 20. USB Full Speed Port Assignments

| USB Full Speed Connector | | EK-RA8D1 |
|--------------------------|--|--|
| Pin | Description | Signal/Bus |
| J11-1 | +5VDC | +5V_USBFS (Host Mode) ^{*1} P407/USB_VBUS = 2/3 of +5V_USBFS at J11 ^{*2} |
| J11-2 | DM | USBFS_N |
| J11-3 | DP | USBFS_P |
| J11-4 | USB ID, jack internal switch, cable inserted | N.C. |
| J11-5 | Ground | GND |

^{*1} When J12 is linked 1-2 and J15 is open

^{*2} When J12 is linked 2-3 and J15 is open

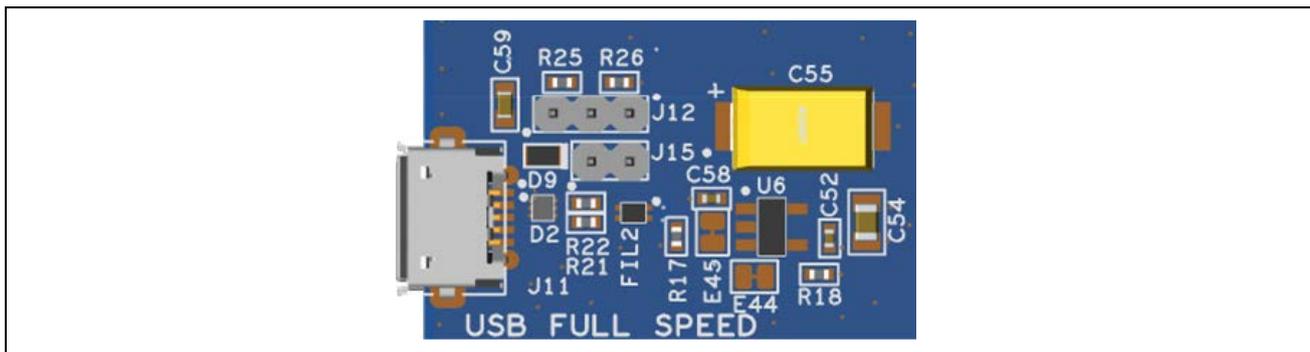


Figure 16. USB Full Speed Connector

5.4.2 I3C

The Arduino, mikroBUS, Grove 2 and Qwiic connectors connect the RA MCU I3C interface to external I3C or I²C devices allowing communications between devices.

Please ensure that SW1-8 is set correctly. Set signal high to port PB02 and P711 when I²C is in use. For I3C set the pins to high impedance unless the I3C specification requires pull ups. In which case, drive PB02 and P711 high. Please refer to the I3C specification for management and control of the I3C pull-ups. The required configurations can be seen in Table 21 where “x” means the configuration doesn’t matter.

Table 21. I²C/I3C Pullup Configuration

| I ² C/I3C/N.C. | SW1-8 | PB02/P711 |
|---------------------------|-------|--|
| I3C | On | High impedance (inputs) or output high (please refer to the I3C specification) |
| I ² C | On | Output high |
| N.C. | Off | x |

5.5 Miscellaneous

5.5.1 User and Power LEDs

Five LEDs are provided on the EK-RA8D1 board. In addition, the Ethernet connector has built-in link status and link speed LEDs.

Behavior of the LEDs on the EK-RA8D1 board is described in the following table.

Table 22. EK-RA8D1 Board LED Functions

| Designator | Color | Function | MCU Control Port |
|------------|--------|--------------------|------------------|
| LED1 | Blue | User LED | P600 |
| LED2 | Green | User LED | P414 |
| LED3 | Red | User LED | P107 |
| LED4 | White | Power on indicator | +3.3 V |
| LED5 | Yellow | Debug LED | J-Link OB MCU |

The user LEDs may be isolated from the main MCU, so the associated ports can be used for other purposes. To separate LED1 from P600, trace cut jumper E27 must be open. To separate LED2 from P414, trace cut jumper E26 must be open. To separate LED3 from P107, trace cut jumper E28 must be open.

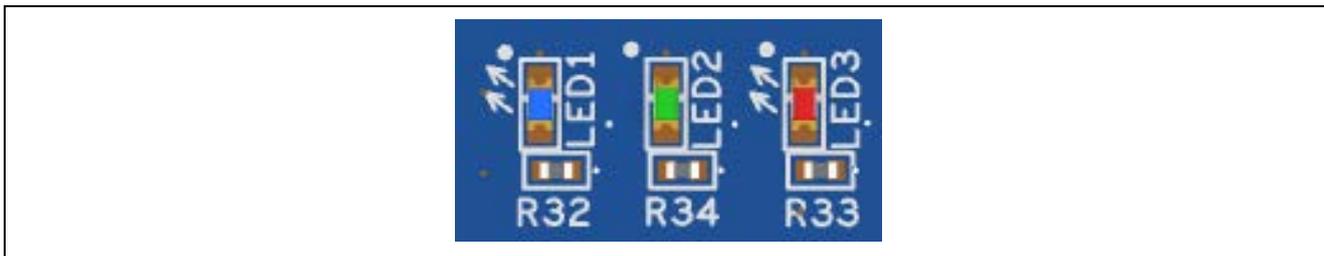


Figure 17. User LEDs



Figure 18. Power LED

5.5.2 User and Reset Switches

Three miniature, momentary, mechanical push-button type SMT switches are mounted on the EK-RA8D1 board.

Pressing the reset switch (S3) generates a reset signal to restart the RA MCU.

Table 23. EK-RA8D1 Board Switches

| Designator | Function | MCU Control Port | Button Color |
|------------|------------------|------------------|--------------|
| S3 | MCU Reset Switch | RESET# | Red |
| S2 | User Switch | P008 (IRQ12-DS) | Blue |
| S1 | User Switch | P009 (IRQ13-DS) | Blue |

The user switches S1 and S2 may be isolated from the main MCU, so the associated ports can be used for other purposes. To separate S1 from P009, trace cut jumper E31 must be open. To separate S2 from P008, trace cut jumper E32 must be open.

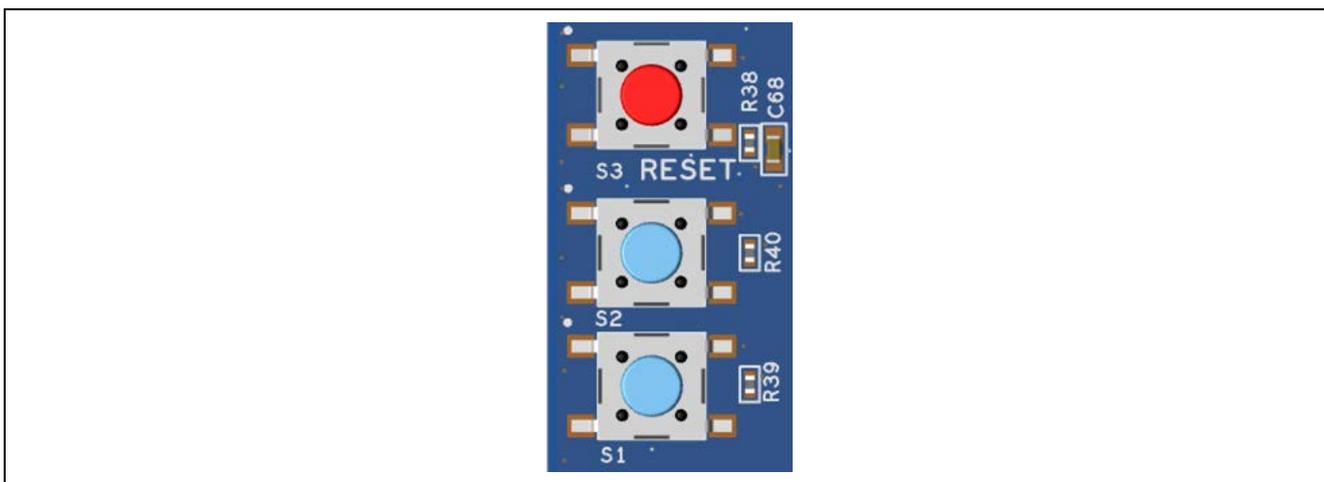


Figure 19. Reset and User Switches

5.5.3 MCU Boot Mode

A two-pin header (J16) is provided to select the boot mode (P201) of the RA MCU. For normal operation, or Single-Chip mode, leave J16 open. To enter SCI Boot mode or USB boot mode, place a jumper on J16.

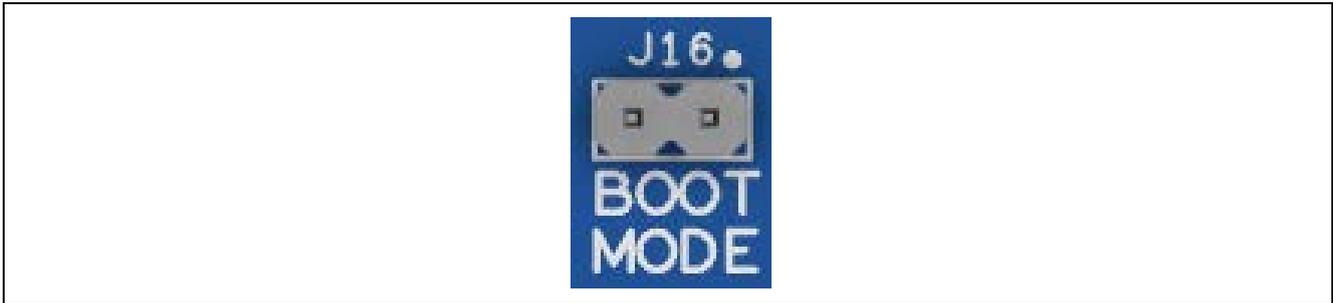


Figure 20. Boot Mode

6. Special Feature Access Area

The Special Feature Access area provides features specific to the RA8D1 MCU group such as Ethernet MAC controller and USB High Speed (Host and Device). The switches to control the peripheral interface selection is also provided.

Note: Normally the SDRAM and Octo-SPI devices would be in this area, however, to optimize the layout for this high-speed device, these components have been placed in the MCU Native Pin Access area.

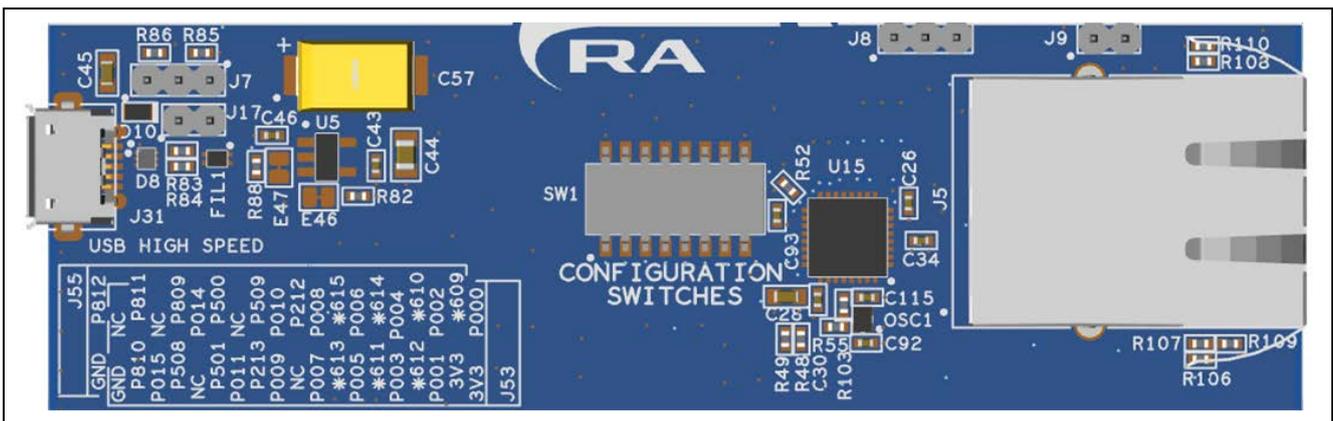


Figure 21. Special Feature Access Area

6.1 Ethernet

The Ethernet interface uses an RMII Ethernet Physical Layer Transceiver (PHY) (U15), connected to an RJ45 standard Ethernet connector (J5) with integrated magnetics and status indicators. The Ethernet clock is sourced from a precision 50 MHz clock oscillator connected directly to the Ethernet PHY.

The RMII signals used for the Ethernet port are connected from the RA MCU through two sets of bus switches. This is to allow different feature sets of the RA8D1 device to be evaluated, that would otherwise become unavailable. The switches SW1-4 and SW1-5 control the peripheral interface option used to communicate with the Ethernet PHY device. To isolate the Ethernet PHY from the RA MCU, turn off SW1-4 and SW1-5. Please see the section 4.3.4 for details.

Table 24. Ethernet Port Assignments

| Ethernet Signal Description | EK-RA8D1 | |
|-----------------------------|-----------------------|-----------------------|
| | Signal/Bus | |
| | SW1-4 ON SW1-5 OFF | SW1-5 ON SW1-4 OFF |
| INT | P000 | P000 |
| MDC | P308 | P401 |
| MDIO | P307 | P402 |
| TXD1 | P305 | P406 |
| TXD0 | P304 | P700 |
| TXD_EN | P306 | P405 |
| RXD1 | P301 | P703 |
| RXD0 | P302 | P702 |
| RMII/RXDV | P112 | P705 |
| RX_ER | P300 | P704 |
| REFCLK | P303 | P701 |
| RESET_N | PA13 | P706 |
| LINKSTA | P114 | P403 |

CAUTION: Do not enable SW1-4 and SW1-5 together

Both SW1-4 and SW1-5 can be disabled to allow these ports to be used as GPIO pins or other peripheral functions.

Table 25. Ethernet Components

| Component | Manufacturer | Manufacturer Part Number |
|-------------------|-----------------------|--------------------------|
| Ethernet PHY | Renesas | ICS1894-32 |
| RJ45 Connector | Pulse | J0011D21BNL |
| 50 MHz Oscillator | ECS Inc International | ECS-1612MV |

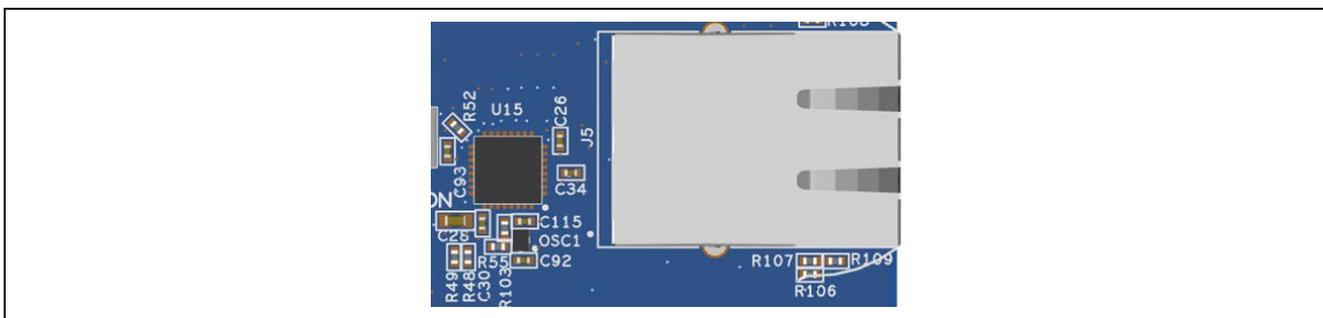


Figure 22. Ethernet Connector

6.2 USB High Speed

The USB Micro-AB connection jack (J31) connects the RA MCU USB High Speed interface to an external USB interface, allowing communications for testing and use of the RA MCU firmware. This connection can be configured as either a USB Device or a USB Host interface.

For a USB Device configuration, set jumper J7 to pins 2-3, install a jumper on J17 pins 1-2, and configure the RA MCU firmware to use the USB High Speed ports in device mode. Power from an external USB Host on this connection can be used to provide power to the EK-RA8D1 board.

For a USB Host configuration, set jumper J7 to pins 1-2, remove the jumper from J17, and configure the RA MCU firmware to use the USB High Speed ports in host mode. In this configuration, power to J7 is supplied from U5. The total current available from U5 is 500 mA. Note that the input power sources must be configured with enough power for both the EK-RA8D1 board and the USB Full Speed port in host mode. Connect the included USB type-A female to micro-B male cable to J31. USB device cables or devices can be connected to the USB High Speed port using this cable.

The USB High Speed support on this board is optional and cannot be used with the GLCD (Parallel LCD data bus) module. SW1-6 when turned on for GLCD will disable the USB Host, VBUS and Overcurrent controls.

Table 26. USB High Speed Port Assignments

| USB High Speed Connector | | EK-RA8D1 |
|--------------------------|--|---|
| Pin | Description | Signal/Bus |
| J31-1 | +5 VDC | +5V_USBHS (Host Mode) PB01/USBHS_VBUS = 2/3 of +5V_USBHS at J31* |
| J31-2 | DM | USBHS_N |
| J31-3 | DP | USBHS_P |
| J31-4 | USB ID, jack internal switch, cable inserted | N.C. |
| J31-5 | Ground | GND |

* Option SW1-6

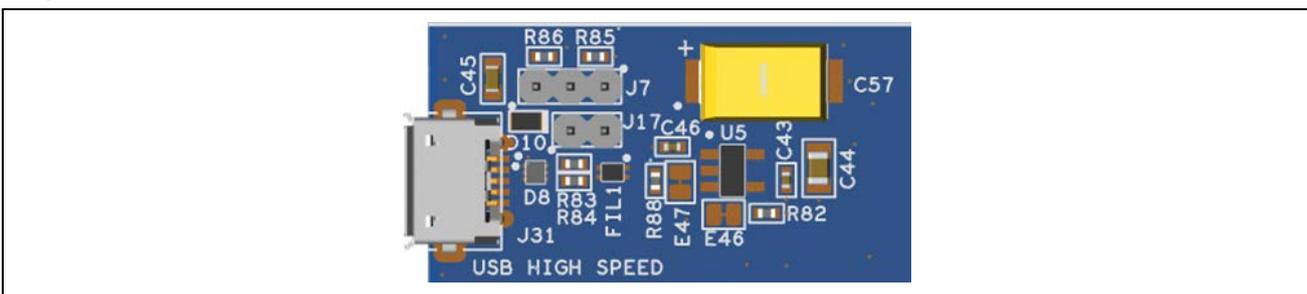


Figure 23. USB High Speed Connector

6.3 Octo-SPI Flash

Included on the EK-RA8D1 board is a 512 Mb (64 MB) Octo serial flash memory (S28HL512TFPBHI010). The Octo-SPI serial flash device (U3) connects to the Octo-SPI peripheral on the RA MCU and defaults to standard SPI mode initially. The flash memory is enabled for XIP (Execute-In-Place) mode directly after power-on.

The Octo-SPI signals are not provided on an external pin header due to the high speed of this interface.

Table 27. Octo-SPI Flash Assignments

| Octo-SPI Flash Signal Description | EK-RA8D1 |
|-----------------------------------|----------|
| OSPI_RESET# | P106 |
| OSPI_INT# | P105 |
| OSPI_CK | P808 |
| OSPI_CS# | P104 |
| OSPI_DS | P801 |
| OSPI_DQ0 | P100 |
| OSPI_DQ1 | P803 |
| OSPI_DQ2 | P103 |
| OSPI_DQ3 | P101 |
| OSPI_DQ4 | P102 |
| OSPI_DQ5 | P800 |
| OSPI_DQ6 | P802 |
| OSPI_DQ7 | P804 |

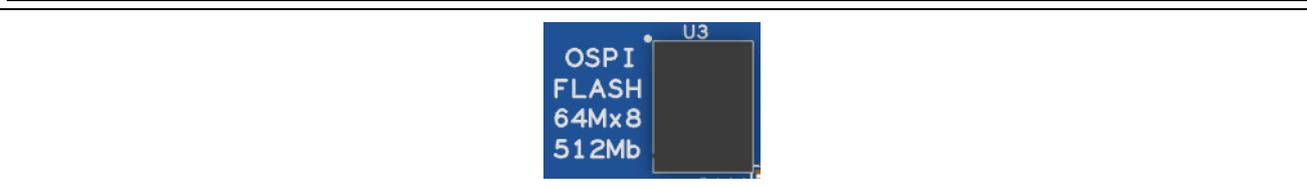


Figure 24. Octo-SPI Flash

6.4 SDRAM

Included in the EK-RA8D1 board is a 512 Mb (64 MB organized as 32M x 16 bits) SDRAM (IS42S16320F-6BLI). The SDRAM can be isolated from the MCU bus by turning SW1-7 off to allow the ports to be used for other purposes.

Table 28. SDRAM Assignments

| SDRAM | EK-RA8D1 |
|--------------------|-------------------|
| Description | Signal/Bus |
| SDRAM_A0 | P300 |
| SDRAM_A1 | P301 |
| SDRAM_A2 | P302 |
| SDRAM_A3 | P303 |
| SDRAM_A4 | P304 |
| SDRAM_A5 | P305 |
| SDRAM_A6 | P306 |
| SDRAM_A7 | P307 |
| SDRAM_A8 | P308 |
| SDRAM_A9 | P309 |
| SDRAM_A10 | P310 |
| SDRAM_A11 | P311 |
| SDRAM_A12 | P312 |
| SDRAM_BA0 | P905 |
| SDRAM_BA1 | P906 |
| SDRAM_D0 | P601 |
| SDRAM_D1 | P602 |
| SDRAM_D2 | P603 |
| SDRAM_D3 | P604 |
| SDRAM_D4 | P605 |
| SDRAM_D5 | P606 |
| SDRAM_D6 | P607 |
| SDRAM_D7 | PA00 |
| SDRAM_D8 | P609 |
| SDRAM_D9 | P610 |
| SDRAM_D10 | P611 |
| SDRAM_D11 | P612 |
| SDRAM_D12 | P613 |
| SDRAM_D13 | P614 |
| SDRAM_D14 | P615 |
| SDRAM_D15 | PA08 |
| SDRAM_CKE | P113 |
| SDRAM_SDCLK | PA09 |
| SDRAM_DQM1 | P112 |
| SDRAM_DQM0 | PA10 |
| SDRAM_WE | P114 |
| SDRAM_CAS | P909 |
| SDRAM_RAS | P908 |
| SDRAM_CS | P115 |

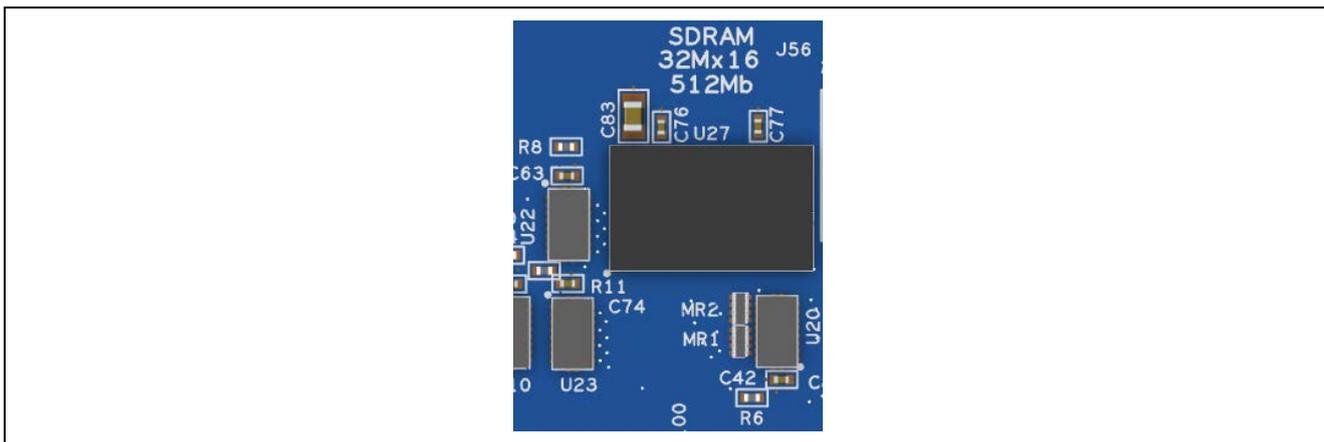


Figure 25. SDRAM

6.5 Parallel Graphics Expansion Port

The RA MCU parallel graphics expansion port can be configured with 8-8-8, 6-6-6, and 5-6-5 color depth. Table 29 shows the Parallel Graphics Expansion Port Assignments and signal names for the EK-RA8D1 board.

Note that P510, which is used as the interrupt for the capacitive touch portion of the LCD, must have the internal pull-up feature enabled in the RA8D1 MCU configuration. This will ensure proper responsiveness of the LCD capacitive touch overlay.

Some signals used on the parallel graphics expansion port are also used by USB-HS. To ensure correct operation, please check Table 3 and Table 4.

Table 29. Parallel Graphics Expansion Port Assignments

| Parallel Graphics Expansion Port | | EK-RA8D1 | | | |
|----------------------------------|-------------|------------|---------------------|---------------------|---------------------|
| Pin | Description | Signal/Bus | RGB Signal (RGB888) | RGB Signal (RGB666) | RGB Signal (RGB565) |
| J57-1 | DISP_BLEN | P404 | BLN | BLN | BLN |
| J57-2 | IIC_SDA | P511 | SDA | SDA | SDA |
| J57-3 | DISP_INT | P510 | INT | INT | INT |
| J57-4 | IIC_SCL | P512 | SCL | SCL | SCL |
| J57-5 | +3.3 V | +3.3 V | +3.3 V | +3.3 V | +3.3 V |
| J57-6 | DISP_RST | PA01 | RST | RST | RST |
| J57-7 | +3.3 V | +3.3 V | +3.3 V | +3.3 V | +3.3 V |
| J57-8 | +5 V | +5 V | +5 V | +5 V | +5 V |
| J57-9 | LCDC_TCON0 | P805 | TCON0 | TCON0 | TCON0 |
| J57-10 | LCDC_CLK | P806 | CLK | CLK | CLK |
| J57-11 | LCDC_TCON2 | P513 | TCON2 | TCON2 | TCON2 |
| J57-12 | LCDC_TCON1 | P807 | TCON1 | TCON1 | TCON1 |
| J57-13 | LCDC_EXTCLK | P514 | EXTCLK | EXTCLK | EXTCLK |
| J57-14 | LCDC_TCON3 | P515 | TCON4 | TCON4 | TCON4 |
| J57-15 | LCDC_DATA01 | P915 | B1 | B3 | B4 |
| J57-16 | LCDC_DATA00 | P914 | B0 | B2 | B3 |
| J57-17 | LCDC_DATA03 | P911 | B3 | B5 | B6 |
| J57-18 | LCDC_DATA02 | P910 | B2 | B4 | B5 |
| J57-19 | LCDC_DATA05 | P913 | B5 | B7 | G2 |
| J57-20 | LCDC_DATA04 | P912 | B4 | B6 | B7 |
| J57-21 | LCDC_DATA07 | P903 | B7 | G3 | G4 |
| J57-22 | LCDC_DATA06 | P904 | B6 | G2 | G3 |
| J57-23 | LCDC_DATA09 | P207 | G1 | G5 | G6 |
| J57-24 | LCDC_DATA08 | P902 | G0 | G4 | G5 |
| J57-25 | LCDC_DATA11 | P712 | G3 | G7 | R3 |
| J57-26 | LCDC_DATA10 | P711 | G2 | G6 | G7 |

| Parallel Graphics Expansion Port | | EK-RA8D1 | | | |
|----------------------------------|-------------|------------|---------------------|---------------------|---------------------|
| Pin | Description | Signal/Bus | RGB Signal (RGB888) | RGB Signal (RGB666) | RGB Signal (RGB565) |
| J57-27 | LCDC_DATA13 | P714 | G5 | R3 | R5 |
| J57-28 | LCDC_DATA12 | P713 | G4 | R2 | R4 |
| J57-29 | LCDC_DATA15 | PB07 | G7 | R5 | R7 |
| J57-30 | LCDC_DATA14 | P715 | G6 | R4 | R6 |
| J57-31 | LCDC_DATA17 | PB05 | R1 | R7 | N.C. |
| J57-32 | LCDC_DATA16 | PB06 | R0 | R6 | N.C. |
| J57-33 | LCDC_DATA19 | PB04 | R3 | N.C. | N.C. |
| J57-34 | LCDC_DATA18 | PB01 | R2 | N.C. | N.C. |
| J57-35 | LCDC_DATA21 | PB02 | R5 | N.C. | N.C. |
| J57-36 | LCDC_DATA20 | PB03 | R4 | N.C. | N.C. |
| J57-37 | LCDC_DATA23 | P707 | R7 | N.C. | N.C. |
| J57-38 | LCDC_DATA22 | PB00 | R6 | N.C. | N.C. |
| J57-39 | GND | GND | GND | GND | GND |
| J57-40 | GND | GND | GND | GND | GND |

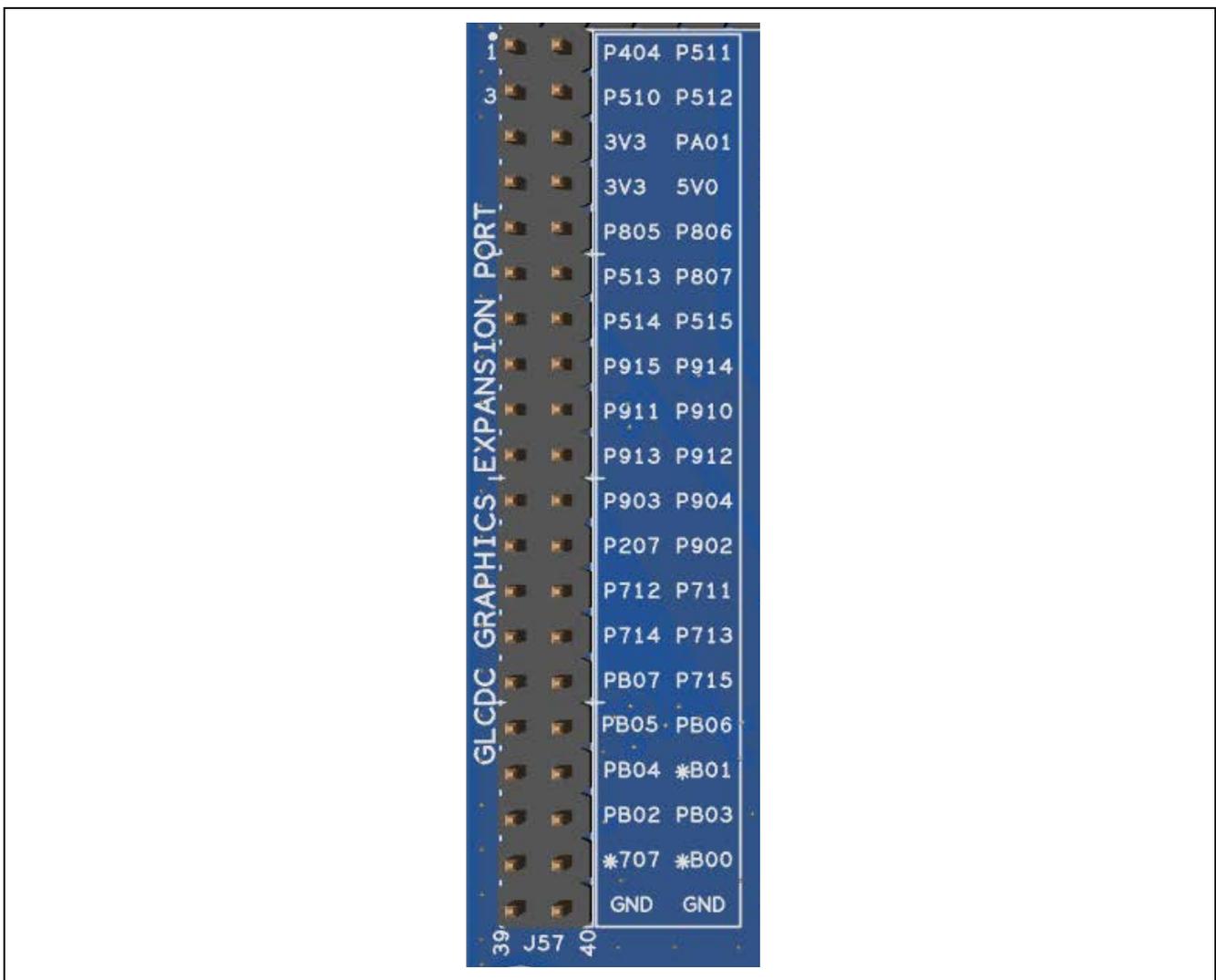


Figure 26. Parallel Graphics Expansion Port

7. MCU Native Pin Access Area

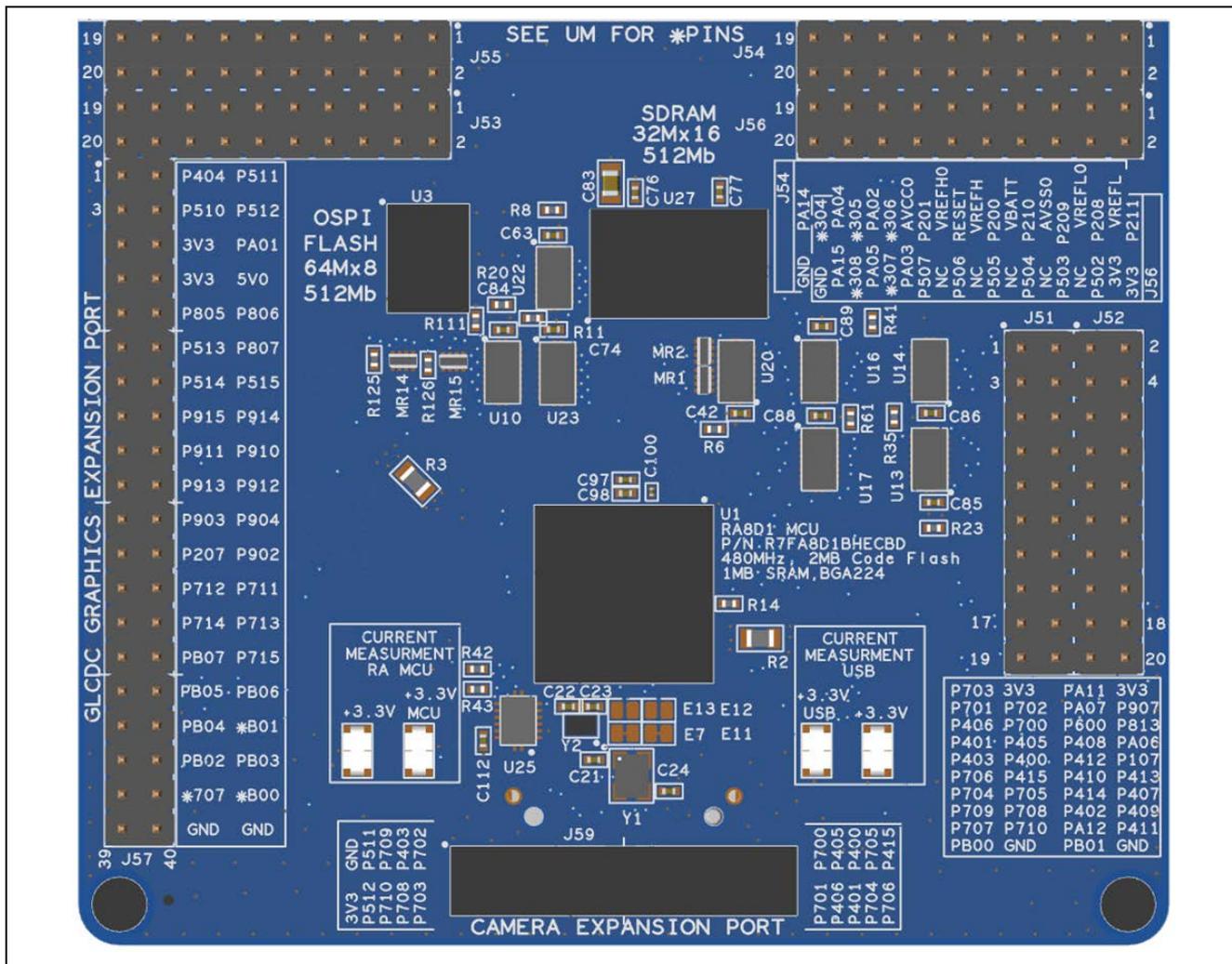


Figure 27. Native Pin Access Area

7.1 Breakout Pin Headers

The EK-RA8D1 board pin headers, J51, J52, J53, J54, J55 and J56 provide access to nearly all RA MCU interface signals, and to voltages for all RA MCU power ports. Each header pin is labelled with the voltage or port connected to that pin. Refer to the RA8D1 MCU Group User's Manual for details of each port function, and the EK-RA8D1 board schematic for pin header port assignments.

The placement of the breakout pin headers allows for a standard 2.54 mm (0.100") center breadboard to be placed on all pin headers simultaneously. This can be used for prototyping and testing of custom circuitry for use with the RA8D1 MCU.

7.2 MCU and USB Current Measurement

Included in the Native Pin Access area are current measurement resistors and test points to measure the MCU USB controller current and the MCU core power current.

The EK-RA8D1 board provides precision 5 mΩ resistors (Vishay, part number WSLP08055L000FEA18) for current measurement of the main 3.3 V MCU power and the 3.3 V USB MCU power. Measure the voltage drop across these resistors and use Ohm's Law to calculate the current. For convenience, TP1 and TP3 are provided to measure the main 3.3 V MCU power, and TP2 and TP4 are provided to measure the 3.3 V USB MCU power. See Figure 30 for the location of TP1, TP2, TP3 and TP4.

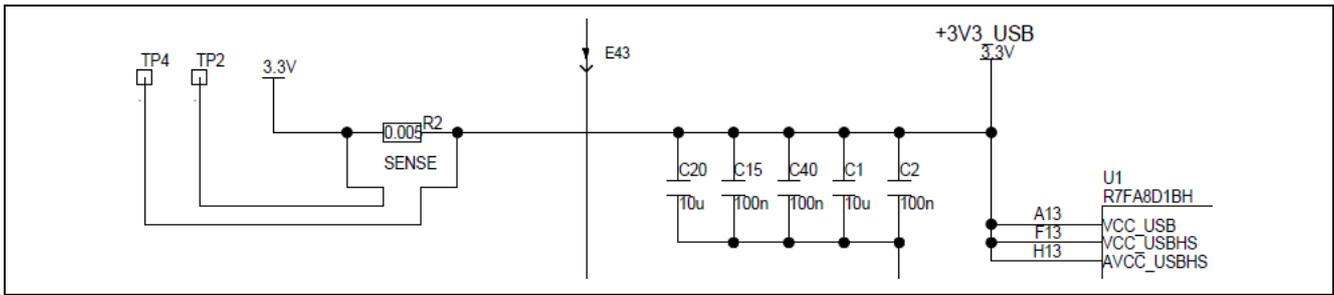


Figure 28. RA USB Current Measurement Circuit

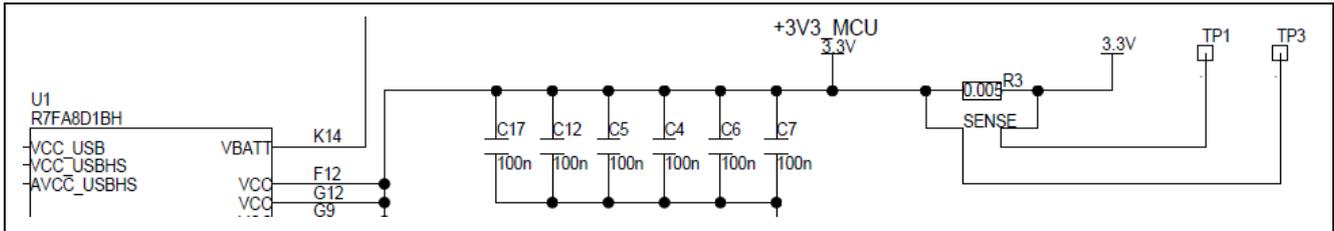


Figure 29. RA +3.3 V Current Measurement Circuit

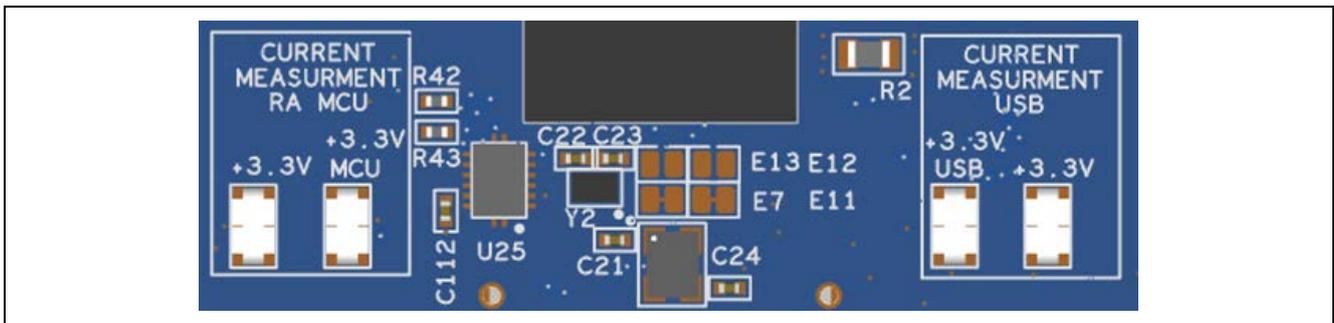


Figure 30. RA MCU and USB Current Measurement

8. Expansion Boards

The EK-RA8D1 kit includes the MIPI Graphics and Camera expansion boards.

8.1 MIPI Graphics Expansion Board

8.1.1 Connecting the Graphics Expansion Board to the EK-RA8D1 Board

The MIPI Graphics Expansion Board connects to the EK-RA8D1 board via 2-lane MIPI interface. It features a 4.5 inch TFT LCD with capacitive touch overlay and must be securely mounted to the EK-RA8D1 board using the provided nylon pillars prior to operation.

Some of the key features of the TFT LCD used on the MIPI Graphics Expansion Board are as follows:

- Display type: TFT LCD with capacitive touch overlay and backlight
- Diagonal size: 4.5 inch
- Dimensions: 61.54x110.09 mm
- Resolution: 854x480 pixels
- Display colors: 16.7M
- Viewing angle: 12:00
- Display mode: transmissive/normally white
- Display brightness: 276

The part number of the TFT LCD used on the MIPI Graphics Expansion Board is E45RA-MW276-C. For more details, please visit focusLCDs.com

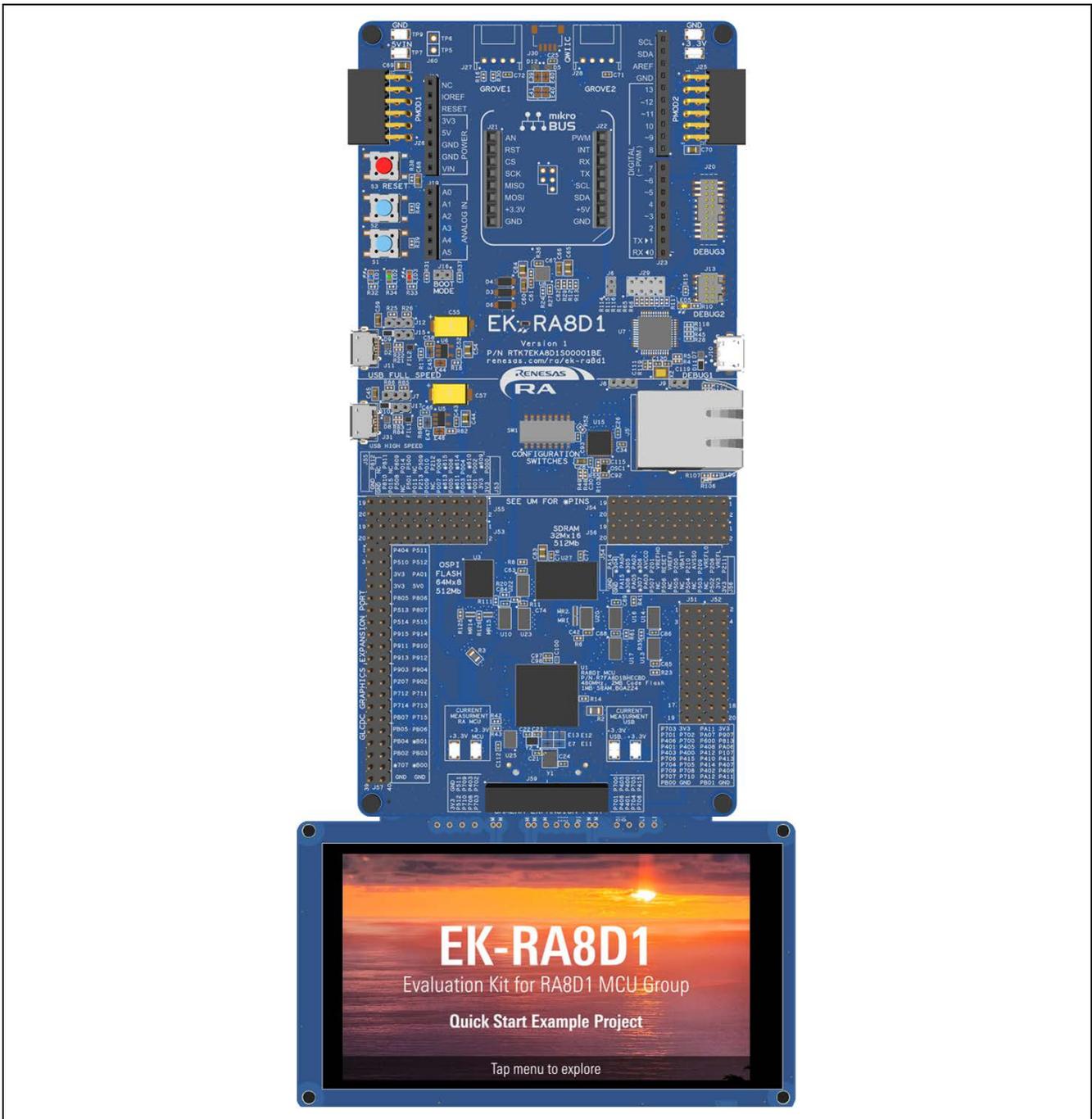


Figure 31. EK-RA8D1 Board Connected with MIPI Graphics Expansion Board

8.1.2 Signal Assignments

The MIPI Graphics Expansion Port (J58) connects the EK-RA8D1 board to the MIPI Graphics Expansion Board supplied as part of the kit.

Table 30. MIPI Graphics Expansion Port Assignments

| MIPI Expansion Port Assignments | | EK-RA8D1 |
|---------------------------------|----------------------|------------|
| Pin | Description | Signal/Bus |
| J58-1 | GND | GND |
| J58-2 | GND | GND |
| J58-3 | MIPI_DL0_P | MIPI_DL0_P |
| J58-4 | MIPI_DL1_P | MIPI_DL1_P |
| J58-5 | MIPI_DL0_N | MIPI_DL0_N |
| J58-6 | MIPI_DL1_N | MIPI_DL1_N |
| J58-7 | GND | GND |
| J58-8 | GND | GND |
| J58-9 | MIPI_CL_P | MIPI_CL_P |
| J58-10 | MIPI | P206 |
| J58-11 | MIPI_CL_N | MIPI_CL_N |
| J58-12 | GND | GND |
| J58-13 | GND | GND |
| J58-14 | I ² C SDA | P511 |
| J58-15 | DISP_BLEN | P404 |
| J58-16 | I ² C SCL | P512 |
| J58-17 | DISP_INT | P510 |
| J58-18 | DISP_RST | PA01 |
| J58-19 | GND | GND |
| J58-20 | GND | GND |
| J58-21 | +1.8 V | +1.8 V |
| J58-22 | +1.8 V | +1.8 V |
| J58-23 | +3.3 V | +3.3 V |
| J58-24 | +3.3 V | +3.3 V |
| J58-25 | +5 V | +5 V |
| J58-26 | +5 V | +5 V |

8.2 Camera Expansion Board

8.2.1 Connecting the Camera Expansion Board to the EK-RA8D1 Board

The Camera Expansion Board included in the EK-RA8D1 kit is off-the-shelf “Arducam 1/4” 3 Mega pixel M12 Mount OV3640 Camera Module with JPEG Output.” It connects to the EK-RA8D1 board using the Camera Expansion Port. Some of the key features of the Camera Expansion Board are as follows:

- External ¼ inch high quality M12x0.5 lens, size:1/4”
- Active array size: 2048 x 1536
- Interface: Parallel RAW, RGB, YUV, JPEG output
- Output formats: (8-bit): YUV (422/420) / YCbCr422, RGB565/555/444, CCIR656, 8-bit compression data, 8/10-bit raw RGB data
- Maximum image transfer rate:
 - 3 megapixel (2048 x 1536): 15 fps (and any size scaling down from 3 megapixel)
 - XGA (1024 x 768): 30 fps
- Scan mode: progressive
- Input clock frequency: 6 ~ 54 MHz
- Shutter: rolling shutter

The part number of the Camera Expansion Board is ArduCam B0156. For more details, please visit arducam.com

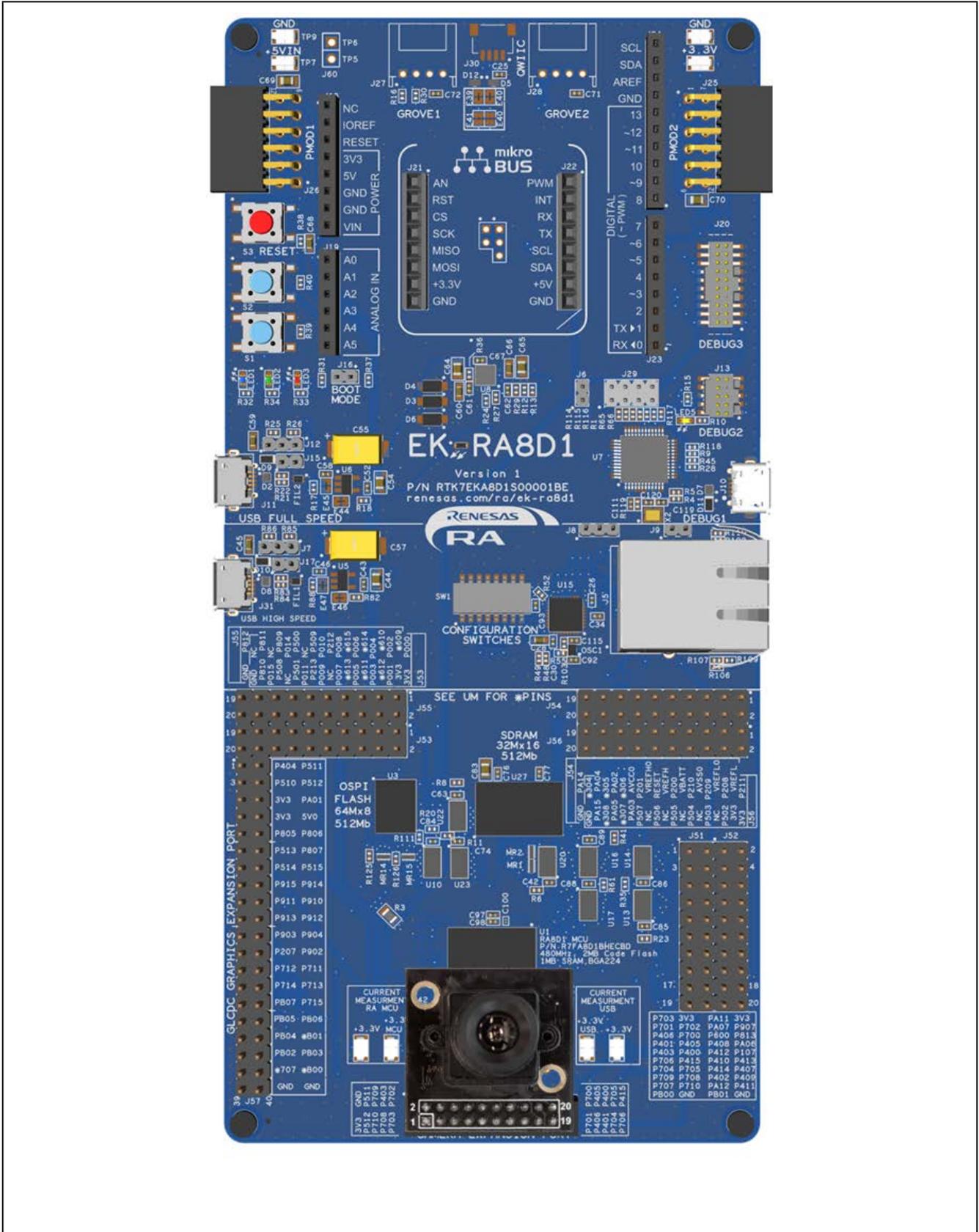


Figure 32. EK-RA8D1 Board Connected with Camera Expansion Board

8.2.2 Signal Assignments

The camera connector J59 connects the EK-RA8D1 board to the camera module supplied as part of the kit.

Table 31. Camera Expansion Port Assignments

| Camera Expansion Port Assignments | | EK-RA8D1 |
|-----------------------------------|----------------------|-------------|
| Pin | Description | Signal/Bus |
| J59-1 | GND | GND |
| J59-2 | +3.3 V | +3.3 V |
| J59-3 | I ² C SDA | P511 (SDA1) |
| J59-4 | I ² C SCL | P512 (SCL1) |
| J59-5 | CAM_HD | P709 |
| J59-6 | CAM_VD | P710 |
| J59-7 | CAM_XCLK | P403 |
| J59-8 | CAM_CLK | P708 |
| J59-9 | CAM_D6 | P702 |
| J59-10 | CAM_D7 | P703 |
| J59-11 | CAM_D4 | P700 |
| J59-12 | CAM_D5 | P701 |
| J59-13 | CAM_D2 | P405 |
| J59-14 | CAM_D3 | P406 |
| J59-15 | CAM_D0 | P400 |
| J59-16 | CAM_D1 | P401 |
| J59-17 | CAM_D9 | P705 |
| J59-18 | CAM_D8 | P704 |
| J59-19 | CAM_D12 | P415 |
| J59-20 | CAM_D10 | P706 |

9. Certifications

The EK-RA8D1 v1 kit meets the following certifications/standards. See page 3 of this user's manual for the disclaimer and precautions.

9.1 EMC/EMI Standards

- FCC Notice (Class A)



This device complies with part 15 of the FCC Rules. Operation is subject to the following two conditions: (1) This device may not cause harmful interference, and (2) this device must accept any interference received, including interference that may cause undesired operation.

NOTE- This equipment has been tested and found to comply with the limits for a Class A digital device, pursuant to Part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation. This equipment generates, uses and can radiate radio frequency energy and, if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause harmful interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following measures:

- Reorient or relocate the receiving antenna.
- Increase the separation between the equipment and receiver.
- Connect the equipment into an outlet on a circuit different from that to which the receiver is connected.
- Consult the dealer or an experienced radio/television technician for help.

- Innovation, Science and Economic Development Canada ICES-003 Compliance:

CAN ICES-3 (A)/NMB-3(A)

- CE Class A (EMC)



This product is herewith confirmed to comply with the requirements set out in the Council Directives on the Approximation of the laws of the Member States relating to Electromagnetic Compatibility Directive 2014/30/EU.

Warning – This is a Class A product. In a domestic environment this product may cause radio interference in which case the user may be required to take adequate measures to correct this interference.

- UKCA Class A (EMC)



This product is in conformity with the following relevant UK Statutory Instrument(s) (and its amendments): 2016 No. 1091 Electromagnetic Compatibility Regulations 2016.

Warning – This is a Class A product. In a domestic environment this product may cause radio interference in which case the user may be required to take adequate measures to correct this interference.

- Taiwan: Chinese National Standard 13438, C6357 compliance, Class A limits
- Australia/New Zealand AS/NZS CISPR 32:2015, Class A

9.2 Material Selection, Waste, Recycling and Disposal Standards

- EU RoHS
- WEEE
- China SJ/T 113642014, 10-year environmental protection use period.

9.3 Safety Standards

- UL 94V-0

10. Design and Manufacturing Information

The design and manufacturing information for the EK-RA8D1 v1 kit is available in the “EK-RA8D1 v1 Design Package” available on renesas.com/ra/ek-ra8d1.

- Design package file name: ek-ra8d1kit-v1-designpackage.zip
- Design package contents:
 1. EK-RA8D1 Board design package: ek-ra8d1-v1-designpackage.zip
 2. MIPI Graphics Expansion Board design package: mgeb-v1-designpackage.zip

Table 32. EK-RA8D1 Board Design Package Contents

| File Type | Content | File/Folder Name |
|------------|---------------------|------------------------------|
| File (PDF) | Schematics | ek-ra8d1-v1-schematics |
| File (PDF) | Mechanical Drawing | ek-ra8d1-v1-mechdwg |
| File (PDF) | 3D Drawing | ek-ra8d1-v1-3d |
| File (PDF) | BOM | ek-ra8d1-v1-bom |
| Folder | Manufacturing Files | Manufacturing Files |
| Folder | Design Files | Design Files-Cadence Allegro |

Table 33. MIPI Graphics Expansion Board Design Package Contents

| File Type | Content | File/Folder Name |
|------------|---------------------|------------------------------|
| File (PDF) | Schematics | mgeb-v1-schematics |
| File (PDF) | Mechanical Drawing | mgeb-v1-mechdwg |
| File (PDF) | 3D Drawing | mgeb-v1-3d |
| File (PDF) | BOM | mgeb-v1-bom |
| Folder | Manufacturing Files | Manufacturing Files |
| Folder | Design Files | Design Files-Cadence Allegro |

11. Website and Support

Visit the following URLs to learn about the kit and the RA family of microcontrollers, download tools and documentation, and get support.

| | |
|--------------------------|---|
| EK-RA8D1 Resources | renesas.com/ek-ra8d1 |
| RA Kit Information | renesas.com/ra/kits |
| RA Product Information | renesas.com/ra |
| RA Product Support Forum | renesas.com/ra/forum |
| RA Videos | renesas.com/ra/videos |
| Renesas Support | renesas.com/support |

Revision History

| Rev. | Date | Description | |
|------|-----------|---|--|
| | | Page | Summary |
| 1.00 | Nov.16.23 | — | Initial release |
| 1.01 | Jan.12.24 | 5, 6, 10, 12, 17, 22, 23, 26, 39, 41 | Added note regarding Qwiic connections. Updated wording and images to account for J27, J28 and J30 no longer being fitted. |
| 1.02 | Jan.31.25 | 27 | Updated the description for the I ² C/I3C pull-up resistors. |

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