

ZSSC4132KIT

Evaluation Kit Description

Description

The ZSSC4132 Evaluation Kit is designed to support customer in evaluation, initial laboratory setup and development of calibration procedure for ZSSC4132 Sensor Signal Conditioner (SSC).

To support the above tasks, the single IC in 24-QFN socket can be used or a user's sensor module can be connected to the kit. The kit also includes a sensor replacement board that can be used in place of an actual sense element for basic evaluation purposes only.

The main purpose of the ZSSC4132 Evaluation Kit is to provide a communication interface to the IC. Those the ZSSC4132 evaluation board is controlled by the microcontroller board "SSC Communication Board" (included in the kit).

This will be connected via USB to the computer and controlled by PC-software via a graphical user interface.

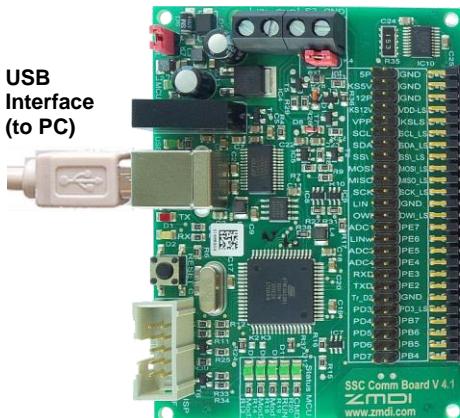
Features

- USB 2.0 compatible "Plug & Play" connection between the user's computer and Evaluation Kit board for communication
- Communication interface enables configuration, calibration, and performance evaluation
- Powered by USB port or an external power supply (8V to 16V)
- Internal generated 12VDC and 5VDC supply
- Providing LIN (v1.3 and v2.x) and I2C communication to IC
- Sensor replacement board for quick and easy first IC feature evaluation
- Software is available for download from website: www.IDT.com/ZSSC4132

Kit Contents

- SSC Communication Board (SSC-CB)
- ZSSC4132 Evaluation Board (SSC-EVB)
- SSC Sensor Replacement Board (SSC-SRB)
- ZSSC4132 24-QFN Sample Board
- USB (type B) connection cable
- 5 samples ZSSC4132 (24-QFN; 4 x 4 mm)
- Tweezers (provided for safe handling)
- Quick Start Guide with link to GUI software

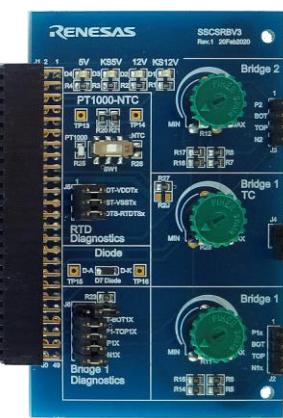
SSC Communication Board (SSC-CB)



ZSSC4132 Evaluation Board (SSC-EVB)



Sensor Replacement Board (SSC-SRB)



ZSSC4132 QFN24 Sample Board

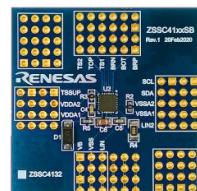


Figure 1. ZSSC4132 Evaluation Kit

Important Notes**Disclaimer**

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- (ii). non-observance of instructions contained in this manual and in any other documentation provided to user, or
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Restrictions in Use

Renesas's ZSSC4132 Evaluation Kit, consisting of the SSC Communication Board, SSC Board ZSSC4132, Sensor Replacement Board, and ZSSC4132 GUI software, is designed for sensor module evaluation, laboratory setup, and module calibration development only. Renesas's SSC Evaluation Kit hardware and software must not be used for qualification, module production or production test setups, or any other use not expressly authorized herein.



Important Equipment Warning: Ensure the correct connection of all cables. Ensure the correct connection of the board-to-board pin connectors. Ensure the correct position of the IC in the socket. Supplying the board and/or IC using the wrong polarity could result in damage to the IC, board and/or the equipment. Check that all jumpers have been set properly before applying power.

Only trained professional staff should connect the equipment and operate the software.

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1. Setup

1.1 Required or Recommended User Equipment

A Windows®-based computer with free USB-port is required for interfacing with the kit. The kit can be powered by the USB port.

The following lab equipment can be alternatively used to power the kit and IC:

- Power supply: 8V to 16V; current capability >100mA; over current/short circuit protected supply is recommended

1.2 User Computer Requirements and Setup

1.2.1. Computer Requirements

A Windows®-based computer is required for interfacing with the kit and configuring the part.

The computer must meet the following requirements:

- Windows® 7 / Windows® 8 / Windows® 10
- Microsoft .NET Framework 4 or higher
- Supported architecture: x86 and x64
- Available USB port

The user must have administrative rights on the computer to download and install the Evaluation Software for the kit.

1.2.2. Software Installation and Setup

The zip format of the latest revision of ZSSC4132 Evaluation Software (GUI), which is required for the kit, must be downloaded from the web site at www.IDT.com/ZSSC4132.

Note: FTDI USB drivers are needed for communication with the SCC Communication Board. If these drivers are not already installed on the user's computer, the software automatically installs the correct drivers after user confirmation.

Follow these procedures to install the Evaluation Kit Software on the user's computer:

1. Download and extract the contents of the zip file to the user's computer.
2. Double click on the extracted *setup.exe* file.
3. Follow the resulting standard installation instructions displayed on the screen, altering the installation path if needed. If the default path settings is used, the software automatically completes the installation and creates an access link on the user's computer under *Start > Renesas > ZSSC4132C*.
The installation dialog offers the option to create a desktop shortcut icon for the software if selected.
4. Connect the kit hardware as described in section 1.3 before starting the software program for the first time.
5. Read License Terms and Conditions of the software and check "I agree to the Terms and Conditions" in order to proceed.

Figure 2 shows the initial display of the software when it is started.

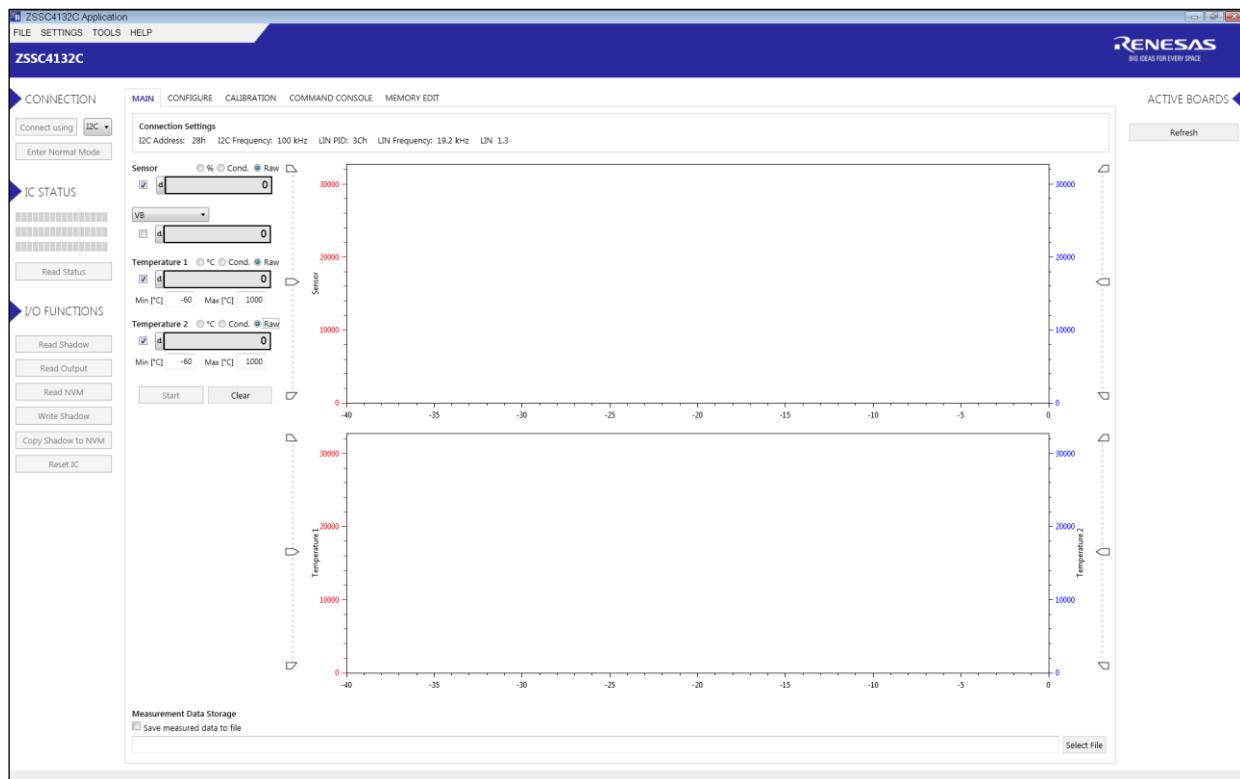


Figure 2. Initial Display of the Evaluation Software (No Board Connected)

1.3 Kit Hardware Connections

The ZSSC4132 Evaluation Kit contains the hardware needed for communication and application of the ZSSC4132 sensor signal conditioning ICs. The user can run the software to communicate with the ZSSC4132 DUT via the SSC Communication Board connected to the user's computer by a USB cable.

The Evaluation Kit hardware consists of the following three boards as shown in Figure 3 and includes samples of the ZSSC4132 (24-QFN):

- SSC Communication Board – Connects to computer through a USB 2.0 cable and handles the I2C (trademark of NXP) and LIN interface communication between the PC-based software and the ZSSC4132. For detailed description please see also check on web site: www.IDT.com/SSC-CB
- ZSSC4132 Evaluation Board – This board contains a 24-QFN socket for the ZSSC4132 single IC, access points for connection to instrumentation, and an external sensor circuitry/module. See Figure 3 for the location of pin 1 for proper IC orientation. Install jumpers initially as shown in Figure 3. This board also offers a connector to a Sensor Replacement Board.
- Sensor Replacement Board – This board provides equivalent input signals for easy evaluation of functionality without an actual sensor bridge or stimulus. Remove it when connecting a real external sense element.

Note: There is a “dummy” IC in the socket on the SSC Board ZSSC4132 that has to be replaced with an actual ZSSC4132 device under test (DUT). See Figure 3 for the location of pin 1 for proper IC orientation.

Follow these procedures to set up the kit as shown in Figure 3:

1. Connect the SSC Communication Board, the ZSSC4132 Evaluation Board, and the SSC Sensor Replacement Board via board-to-board connectors as shown in Figure 3
2. Insert IC into the 24-QFN socket; see Figure 3 for the location of pin 1 for proper IC orientation.
3. Connect SSC Communication Board via USB cable to the user's computer.

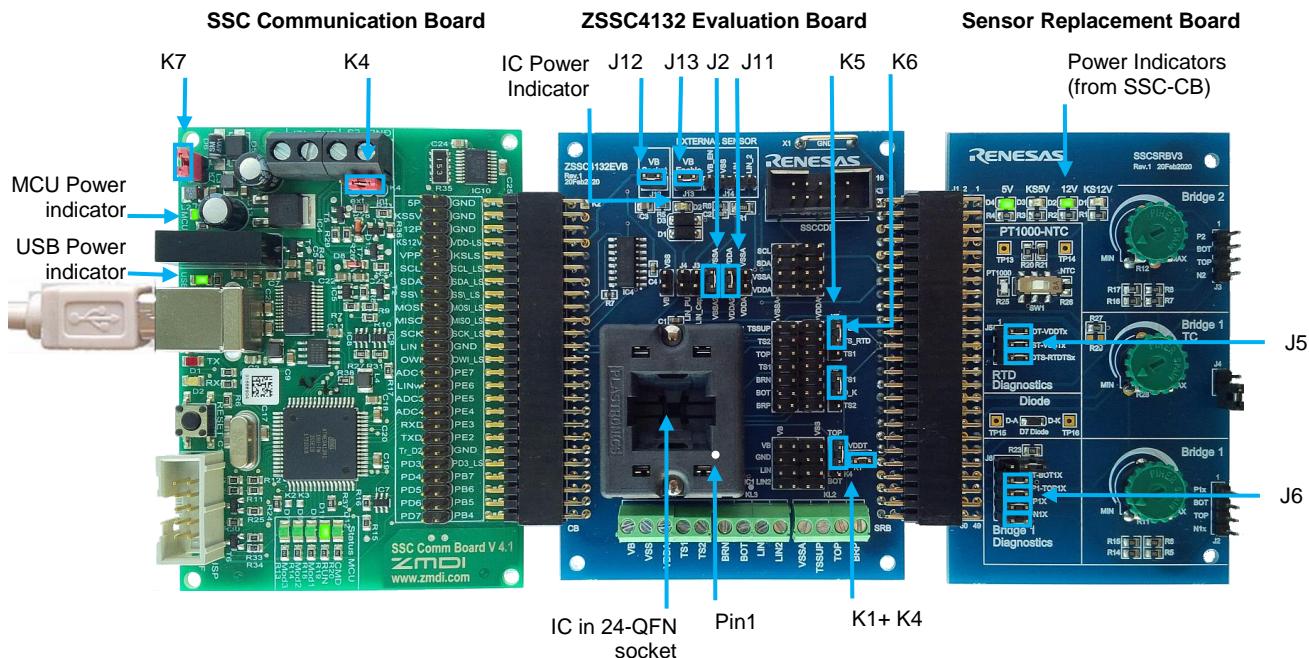


Figure 3. Default Evaluation Kit Connections

Table 1. Evaluation Kit Connection and Jumper Descriptions (Default Setup)

| Board | Connector | Type | Description |
|------------------|-----------|--|--|
| SSC-CB | K7 | 2-Pin Header – Male | “enable 12P int.” – Set jumper to enable on-board generated 12VDC supply. |
| SSC-CB | K4 | 3-Pin Header – Male | Set jumper to “int.” for selecting internal power source (default configuration) for VDD-LS supplies (1.8 V, 3.3 V). |
| SSC-CB / SSC-EB | K1 / K2 | 50-Pin Board Connector | Bi-directional connection from SSC Communication Board to ZSSC4132 Evaluation Board. |
| SSC-EB | J12 | 2-Pin Header – Male | Set jumper to connect the “KS12V” (the switched 12VDC supply) from SSC communication board to the QFN socket. The proper VB supply is indicated by LED D2. |
| SSC-EB | J12 | 2-Pin Header – Male | Set jumper to connect the “KS12V” (the switched 12VDC supply) from SSC communication board to the “External Sensor” connector J14 |
| SSC-EB | J11 | 2-Pin Header – Male | Set jumper to connect VDDA and VDDA2 (required to be shorted for proper operation). |
| SSC-EB | J2 | 2-Pin Header – Male | Set jumper to connect VSSA and VSSA2 (required to be shorted for proper operation). |
| SSC-EB / SSC-SRB | K3 / J1 | 50-Pin Board Connector | Bi-directional connection from ZSSC4132 Evaluation Board to Sensor Replacement Board. |
| SSC-EB | K5 | 3-Pin Header – Male | Set jumper to connect TS1 or TS2 pin to external resistive temperature sense element on Sensor Replacement Board (TS_RTD). |
| SSC-EB | K6 | 3-Pin Header – Male | Set jumper to connect TS1 or TS2 pin to cathode of external diode temperature sense element on Sensor Replacement Board (D_K). |
| SSC-EB | K4 K1 | 3-Pin Header – Male 2-Pin Header - Male | Set both jumper to provide reference supply (VDDT) to resistive temperature sense half-bridge on Sensor Replacement Board (TS_RTD). |
| SSC-SRB | SW1 | Switch | Switch to select PTC (PT1000) or NTC for external TS_RTD sense element. |
| SSC-SRB | J5 | 3x2-Pin Header - Male | Set jumpers (pins 1-2, 3-4, 5-6) to connect RTD sense element to J1 board connector. |
| SSC-SRB | J6 | 5x2-Pin Header - Male | Set jumpers (pins 1-2, 3-4, 5-6, 7-8) to connect Bridge 1 sense element to J1 board connector. Note: disconnect jumper (pins 9-10, P1-N1) to remove short of P1-N1! |

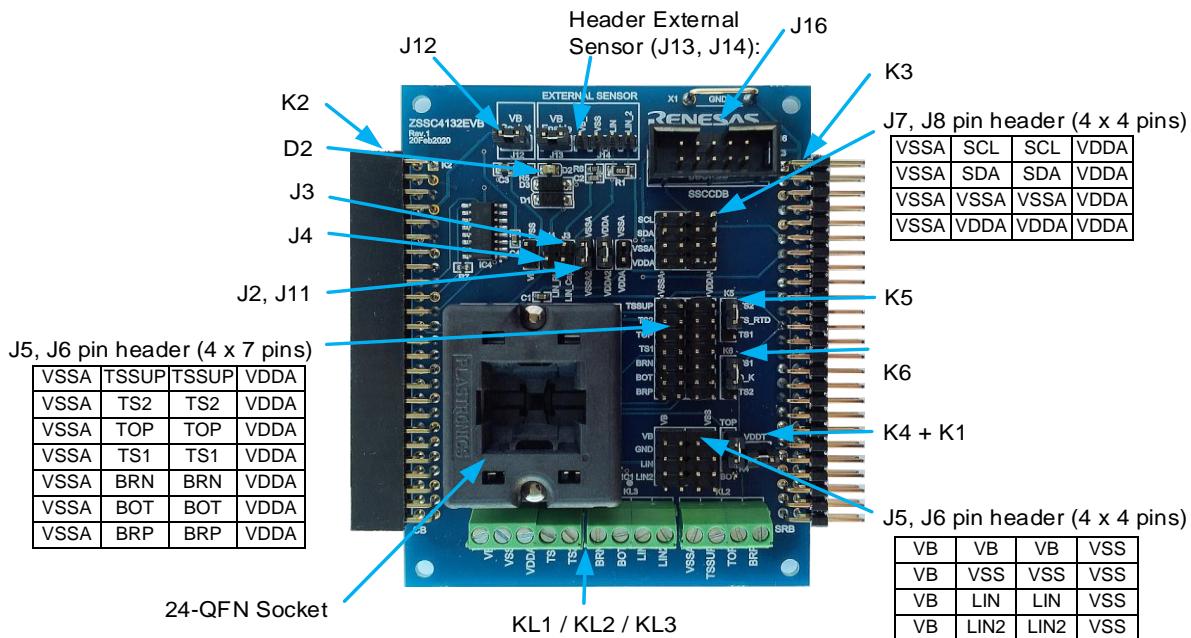
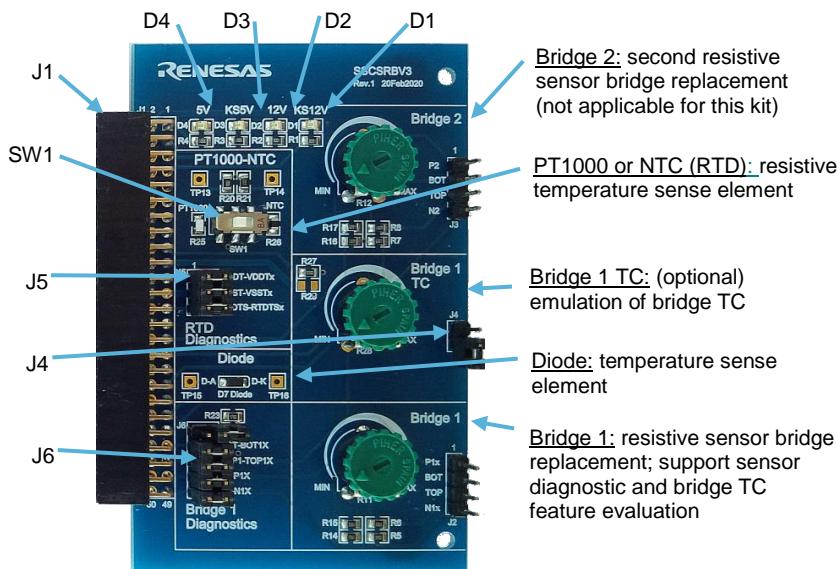


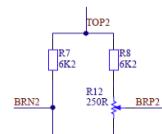
Figure 4. ZSSC4132 Evaluation Board (ZSSC4132EVB Rev. 1) – Overview

Table 2. Sensor Replacement Board (SSCSR BV3 Rev.1) – Indicator, Jumper and Connector Descriptions

| Element | Type | Description |
|---------------|---------------------------|--|
| D2 | LED | Indicator for status of the switched 12V supply ("KS12V") from SSC-CB; IC supply |
| J2 | 2-Pin Header – Male | Set jumper to connect VSSA and VSSA2 (required to be shorted for proper operation). |
| J3 | 2-Pin Header – Male | Set jumper to enable additional capacitance of 220pF between LIN and GND |
| J4 | 2-Pin Header – Male | To connect a custom pull-up resistor between LIN and KS12V (VB supply) |
| J5, J6 | 4x7-Pin Header - Male | Provide access to pins: TSSUP, TS2, TOP, TS1, BRN, BOT, BRP, VSSA, VDDA |
| J7, J8 | 4x4-Pin Header - Male | Provide access to pins: SCL, SDA, VSSA, VDDA |
| J11 | 2-Pin Header – Male | Set jumper to connect VDDA and VDDA2 (required to be shorted for proper operation). |
| J12 | 2-Pin Header – Male | Set jumper to connect the "KS12V" (the switched 12VDC supply) from SSC communication board to the QFN socket. The proper VB supply is indicated by LED D2. |
| J13 | 2-Pin Header – Male | Set jumper to connect the "KS12V" (the switched 12VDC supply) from SSC communication board to the "External Sensor" connector J14 |
| J14 | 4-Pin Header – Male | To optional connect an external sensor module; providing signals: VB, GND, LIN and LIN_2 |
| J16 | 2x5-Pin Box Header - Male | SSCCDB connector |
| K2 | 50-Pin Socket | Bi-directional board connection to SSC Communication Board |
| K3 | 50-Pin Header - Male | Bi-directional board connection to Sensor Replacement Board |
| K5 | 3-Pin Header – Male | Set jumper to connect TS1 or TS2 pin to external resistive temperature sense element on Sensor Replacement Board (TS_RTD). |
| K6 | 3-Pin Header – Male | Set jumper to connect TS1 or TS2 pin to cathode of external diode temperature sense element on Sensor Replacement Board (D_K). |
| K4, K1 | 3-Pin Header – Male | Set both jumper to provide reference supply (VDDT) to resistive temperature sense half-bridge for NTC/ PT1000 on Sensor Replacement Board (TS_RTD). |
| KL1, KL2, KL3 | Screw Terminals | Screw terminals for optional connection to external supply and sensor bridges |



Bridge 2:



Bridge 1 + Bridge 1 TC:

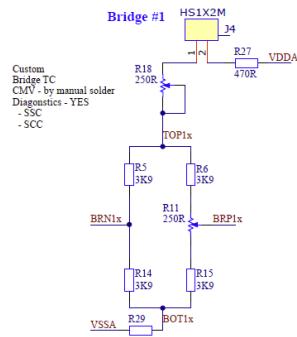


Figure 5. Sensor Replacement Board (SSCSR BV3 Rev.1) – Overview

Table 3. Sensor Replacement Board (SSCSR BV3 Rev.1) – Indicator and Jumper Descriptions

| Element | Type | Description |
|---------|------------------------|---|
| D1 | LED | Indicator for status of the switched 12V supply ("KS12V") from SSC-CB |
| D2 | LED | Indicator for status of the permanent 12V supply ("12P") from SSC-CB |
| D3 | LED | Indicator for status of the switched 5V supply ("KS5V") from SSC-CB |
| D4 | LED | Indicator for status of the permanent 5V supply ("5P") from SSC-CB |
| J1 | 50-Pin Board Connector | Bi-directional connection to ZSSC4132 Evaluation Board |
| J4 | 2-Pin Header – Male | Set this optional jumper to enable "Bridge 1 TC" functionality. (default = open) |
| J5 | 3x2-Pin Header - Male | Set jumpers (pins 1-2, 3-4, 5-6) to connect RTD sense element to J1 board connector. It can be used to evaluate RTD diagnostic features. |
| J6 | 5x2-Pin Header - Male | Set jumpers (pins 1-2, 3-4, 5-6, 7-8) to connect Bridge 1 sense element to J1 board connector. It can be used to evaluate bridge sensor diagnostic features. Note: disconnect jumper (pins 9-10, P1-N1) to remove short of P1-N1! |
| SW1 | Switch | Switch to select PTC (PT1000) or NTC for TS_RTD sense element. |

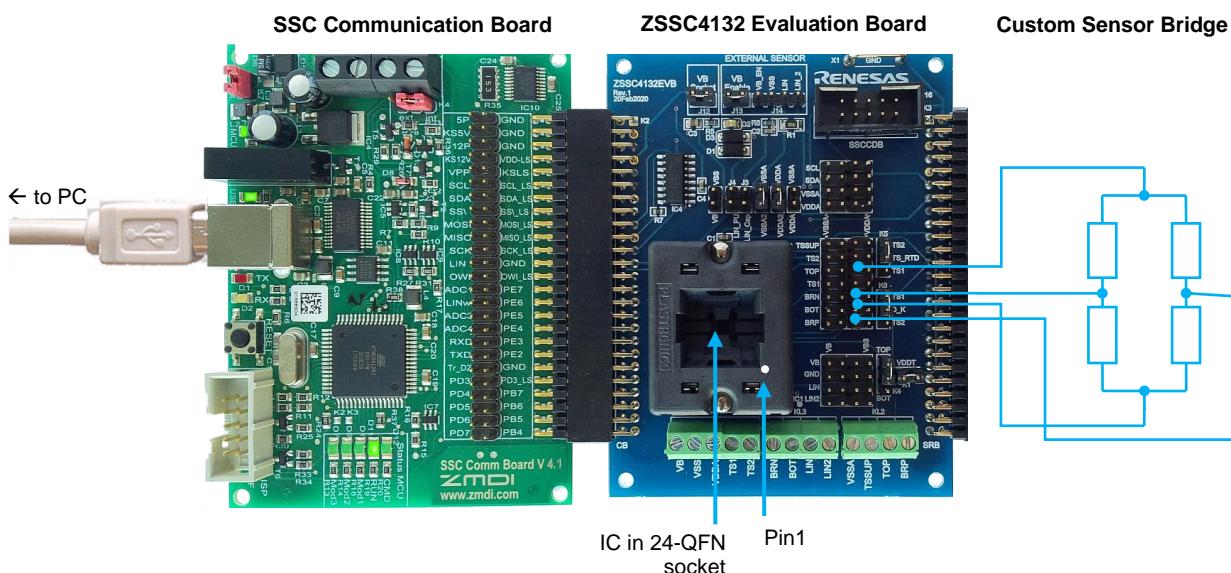


Figure 6. Evaluation Kit Connections Example 2: Connecting External Resistive Sensor Bridge

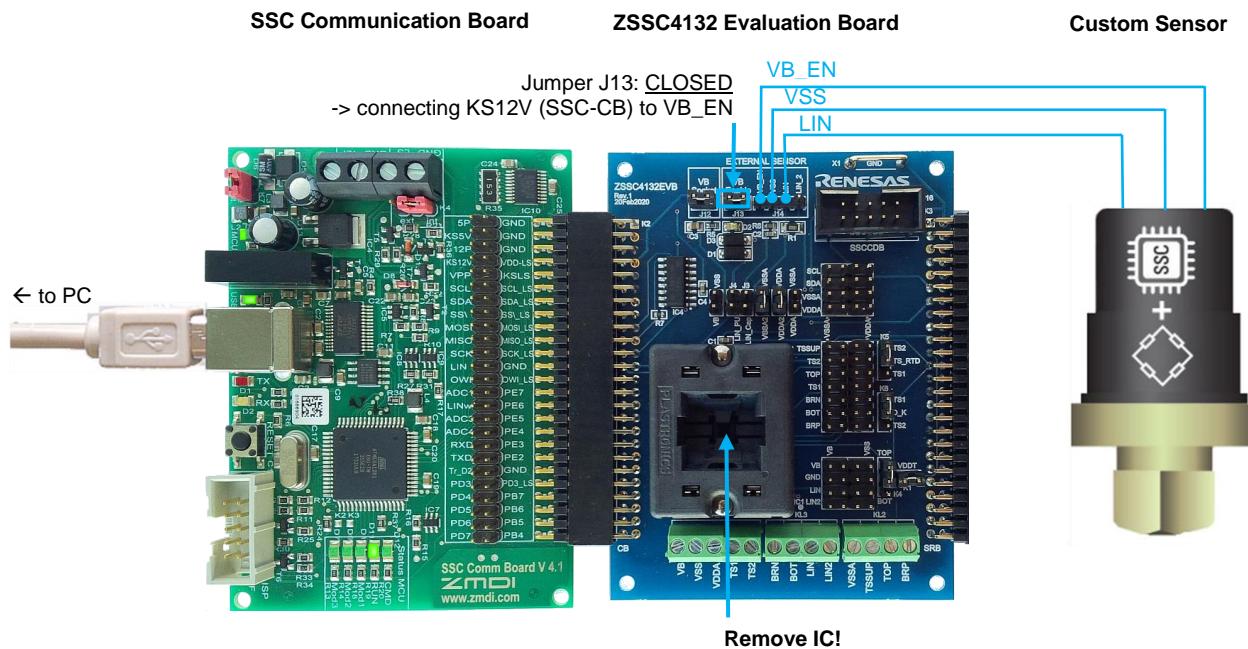


Figure 7. Evaluation Kit Connections Example 3: Connecting External Sensor Including SSC

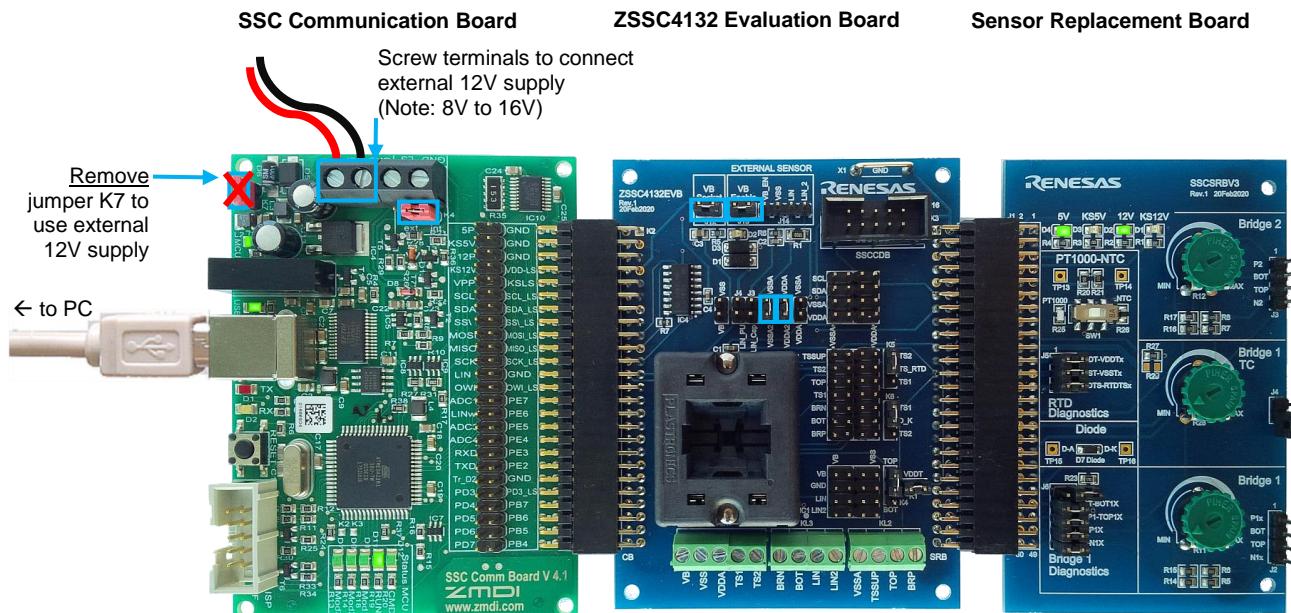


Figure 8. Evaluation Kit Connections Example 4: External 12V Supply via SSC-CB

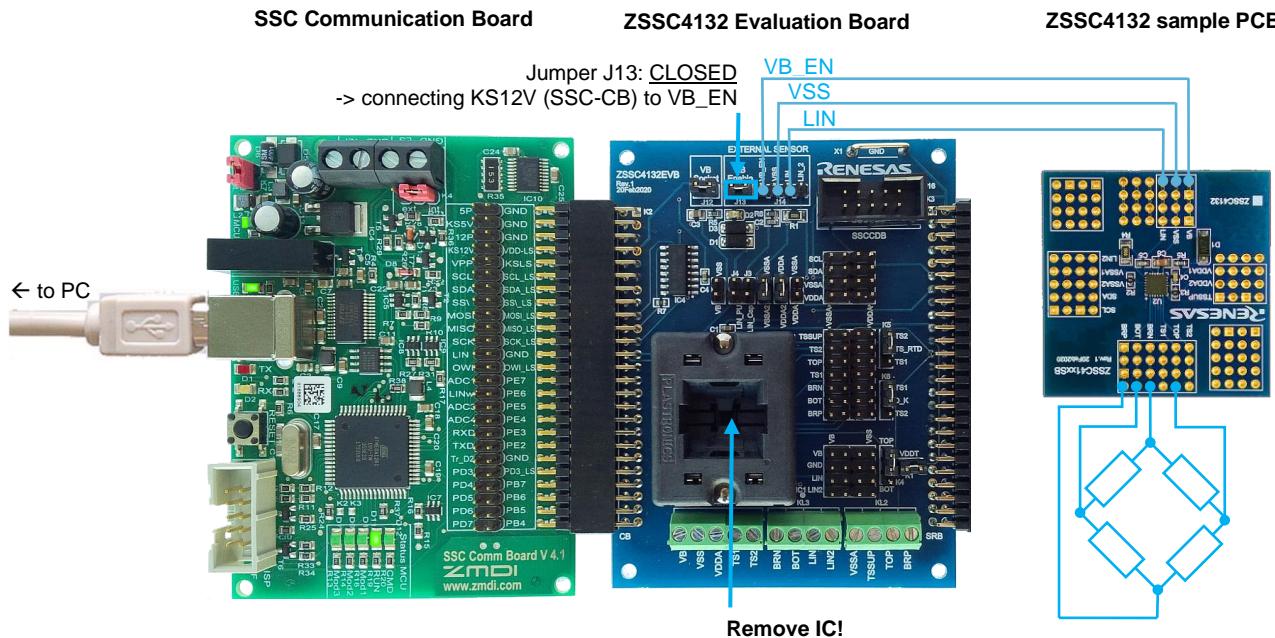


Figure 9. Evaluation Kit Connections Example 5: Connect sample PCB + External Sensor Bridge

1.4 External Equipment Connections

Follow these procedures to connect the lab equipment and the user's computer to the kit as shown in Figure 3:

1. Depending on the use case, connect the boards, external sense element and/or sensors as shown in section 1.3. For a first IC evaluation, use default setup as shown in Figure 3.
2. Connect kit with the PC via USB cable.

1.5 Power-up and Connection Procedure

In the default setup, the evaluation kit is powered by the USB port of the PC (see Figure 3).

Once the evaluation kit is properly connected and powered, the LEDs D4 (5P) and D2 (12P) on the Sensor Replacement Board lights up, indicating that the permanent 5V and 12V supplies are available. The green LED D4 (MCU) indicates a powered microcontroller on the SSC-CB.

Note: The LED D2 (on SSC-EB) does not light up to indicate that the Evaluation Board and IC has power until the board is activated (connected) as described in section 1.5.

When the Evaluation Kit is connected, start the ZSSC4132 Evaluation Software. The window opens with the "MAIN" application tab displayed (see Figure 10).

"ACTIVE BOARDS" panel on the right side of the window lists the active, correctly connected devices, which will include the SSC Communication Board (see "ZMDI SSC CB V4.1"). Multiple devices can be connected to the user's computer.

Follow these steps to set up communication with the kit:

1. Click on the desired device in the "ACTIVE BOARDS" list. Click "Refresh" after changing any connections.
2. Select a communication protocol (I2C or LIN) in the dropdown menu under "CONNECTION" in the left panel.

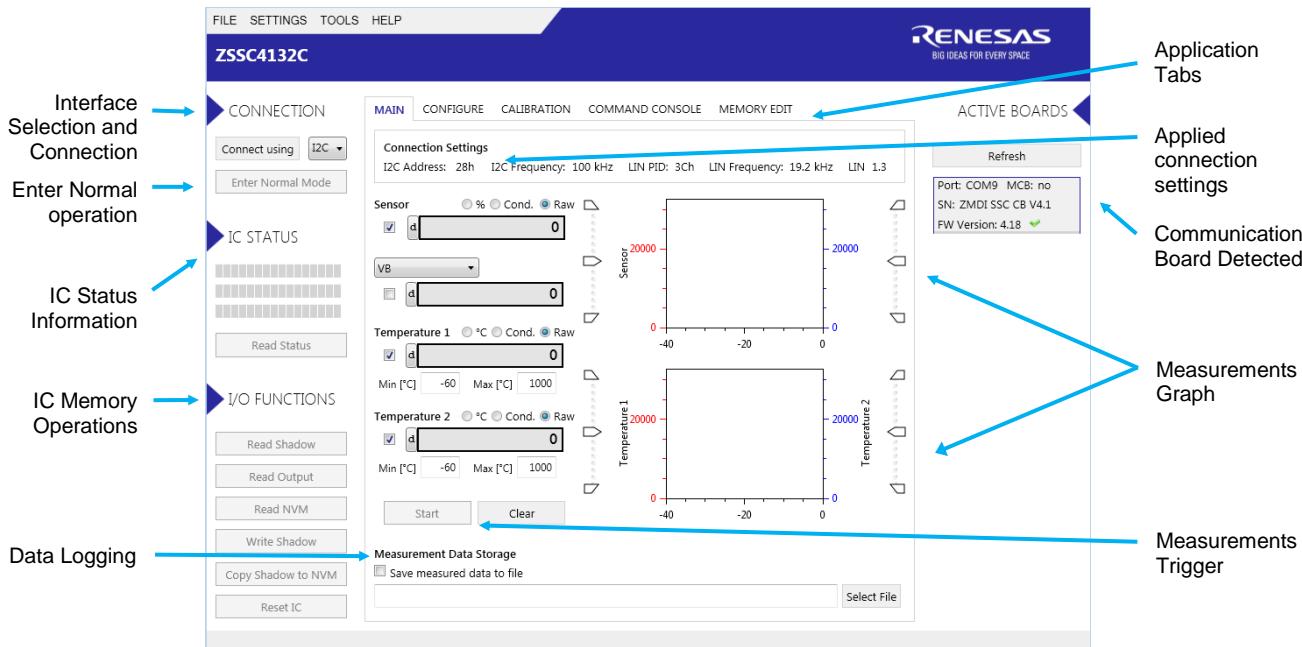


Figure 10. Initial Display Explained (Evaluation Kit properly connected to USB; IC not activated)

Note: If necessary, configure the I2C and LIN specific settings via the “SETTINGS” menu on the top banner shown in Figure 11. The new settings are applied when a connection is re-established with ZSSC4132. Settings can be changed only if no IC is connected. The I2C address must be set correctly in order to establish successful I2C communication. The LIN version must be set correctly in order to use LIN communication. LIN version must always be set correctly, because LIN interface is used in Normal mode, even if I2C communication is set.

Note: For proper LIN support, use SSC Communication Board with firmware revision v4.14.17 (and later). The revision is given by the “ACTIVE BOARDS” information box. A suitable firmware is indicated by a green checkmark.

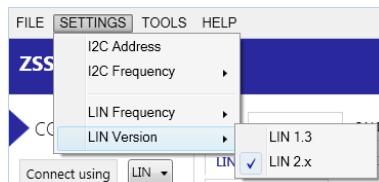


Figure 11. Settings Menu

- Click “Connect using” button to power the IC and establish communication with the device. This enables the switched supplies (KS12V, KS5V). The D2 LED on SSC Evaluation Board turn on to indicate that the Evaluation Board (IC) is powered and connection with IC is properly established.

When communication is correctly established, “Connect using” button changes to “Disconnect”.

The software generates the corresponding data frame structure with initial values gathered from the IC.

IC is entered in Command Mode, memory content (NVM, RAM) and IC status information is read.

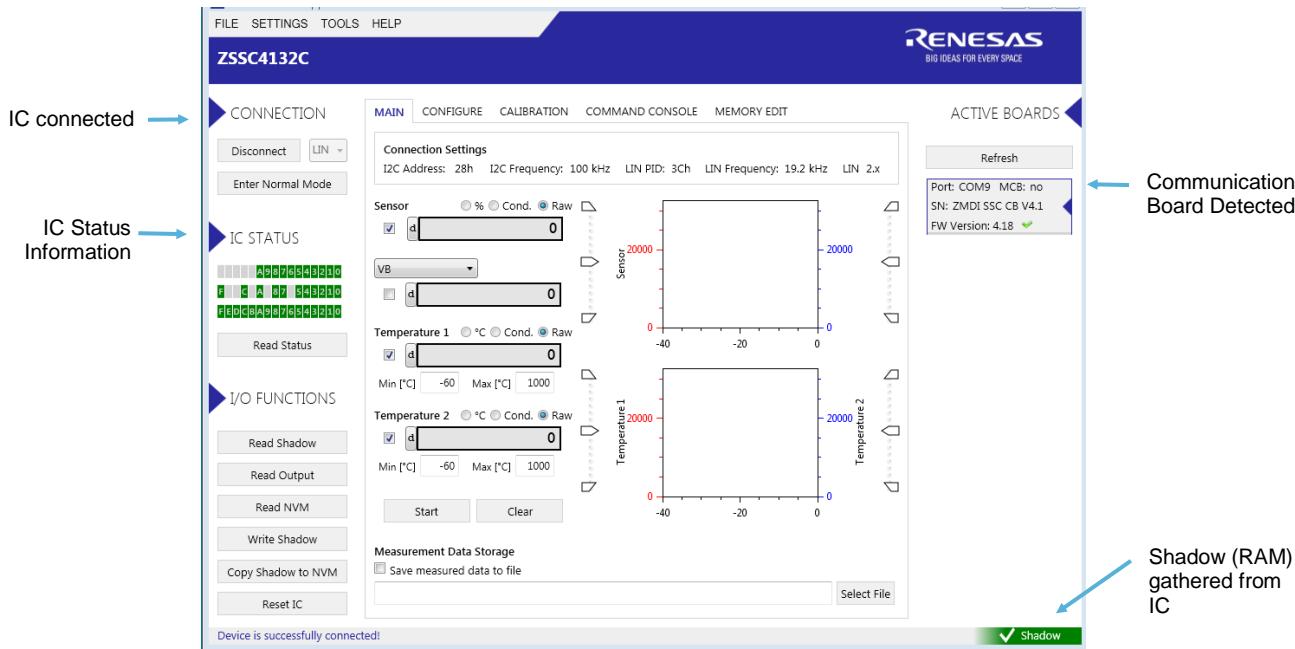


Figure 12. Initial Display after Evaluation Kit and IC Properly Connected

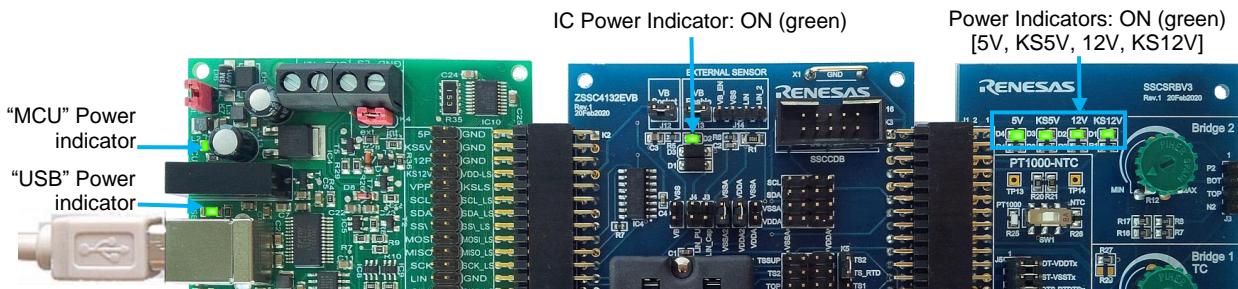


Figure 13. Evaluation Kit – IC connected – Status of Power Indicators

2. User Guide

The ZSSC4132 evaluation software is intended for demonstration purposes for configuration and calibration of single units.

2.1 General GUI Handling and Settings

2.1.1 Saving and Loading the GUI Configuration File (.cfgx)

Software related settings (for example, connection interface, speed, MAIN tab diagram limits, or calibration settings) can be saved and loaded by file.

A default initial configuration file, `<program_path>\Resources\DefaultConfigurationSettings.cfgx`, is provided with the software.

At first start, a standard configuration file is created at the default user applications folder:

`%USERPROFILE%\AppData\Roaming\Renesas\ZSSC4132 Demonstrator\Resources\StandardConfigurationSettings.cfgx`.

This file is used for quick “Save GUI Configuration”.

For loading a different GUI configuration, follow these steps:

1. Click FILE > “Load GUI Configuration” (see Figure 14)
2. Browse to file location and click the “Open” button.
The “Load GUI Configuration” window appears.
3. Click the “Yes” button to accept overwriting the current configuration settings.

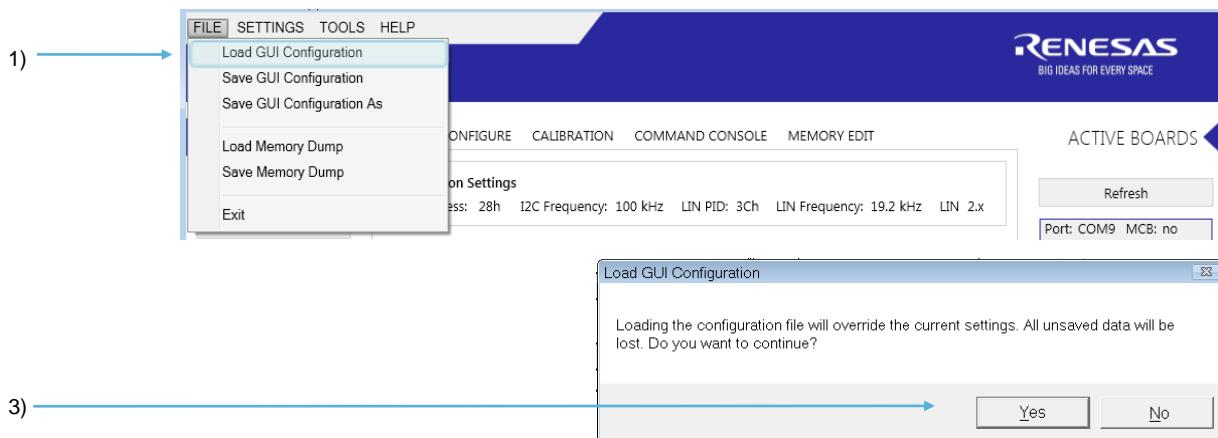


Figure 14. Loading the GUI Configuration File

When the Evaluation Software is closed, a “Save Configuration Settings?” window opens.

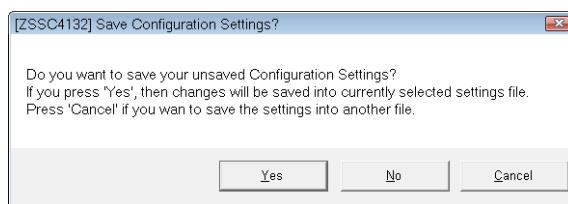


Figure 15. Save Configuration Dialog Window at Closing

By clicking “No”, the settings are not saved. By clicking “Yes”, the current configuration of the GUI is saved in the actual *.cfgx file. By clicking “Cancel”, a different file can be selected to save.

The latest saved file is loaded automatically when the software is started the next time.

2.2 Saving and Loading an IC Memory Dump

2.2.1. Saving IC Memory Data

Follow these steps to save IC Memory Data to Memory Dump File (.dmpx):

1. Select FILE > Save Memory Dump to save a file containing the IC memory data (see Figure 17). A file explorer window will open.
2. Browse to the target file location, enter a file name, and click the “Save” button.

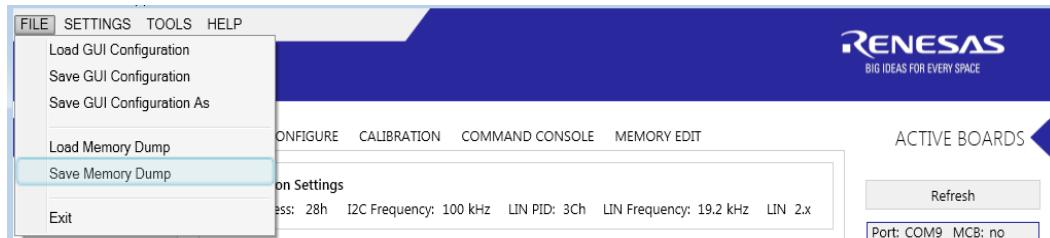


Figure 16. Save the Memory Data to a File

Note: The memory dump file contains RAM Shadow, RAM Output Memory and non-volatile memory (NVM) data by default.

2.2.2. Loading RAM Shadow Data

Follow these steps to load RAM Shadow data from Memory Dump File (.dmpx):

1. Select FILE > Load Memory Dump to load a file containing the IC RAM Shadow memory data (see Figure 17).
2. Browse to the file location, and click the “Open” button.
3. In the “Load MTP Dump” window, click the “Yes” button to accept overwriting current RAM Shadow data in the GUI.

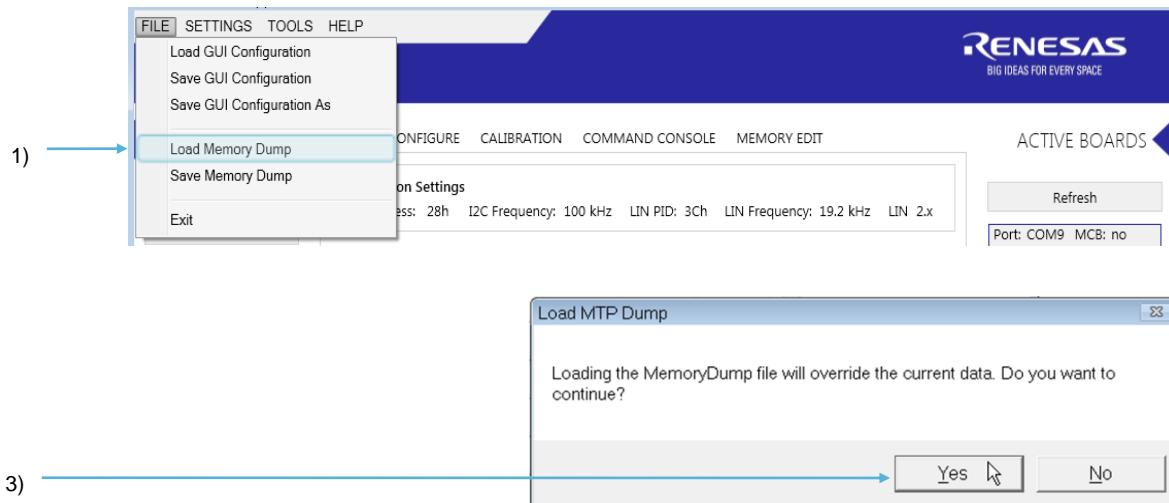


Figure 17. Load the RAM Shadow Data into GUI

Note: The GUI loads only RAM Shadow content. Pre-calibrated IC parameters (non-user settings) are not overwritten in the GUI.

Note: Loading certain settings can trigger the GUI to offer certain recommended settings (e.g. PTC settings) by a pop-up window. Please decline this automated settings in order to properly load the saved data!

If the register content is the same as the content from the last reading, the indicator in the bottom right corner of the window stays green as shown on Figure 18.



Figure 18. Memory Indicator: Same Content

If a register is modified, the indicator becomes red as shown on Figure 19.



Figure 19. Memory Indicator: Modified Content

2.2.3. Writing the Memory Content to the IC

1. Click the “Write Shadow” button to download the RAM Shadow data into the IC (see Figure 20).
2. Click the “Copy Shadow to NVM” button to copy the content of the Shadow memory to NVM and update the CRCs.
3. In the “Copy Shadow to NVM” window, click the “Yes” button to accept permanent overwrite of the NVM memory.

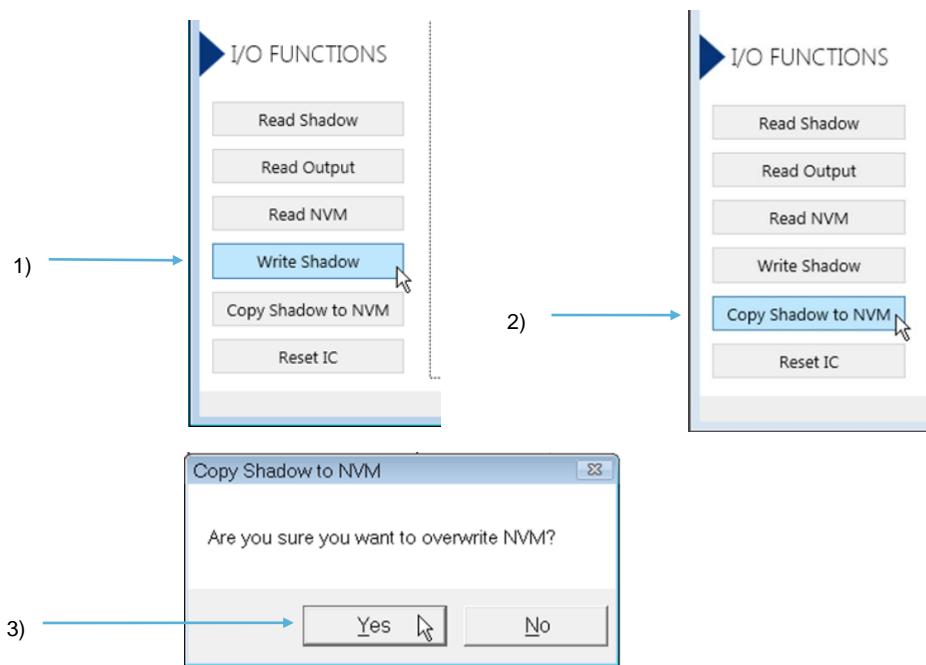


Figure 20. Writing the Configuration into the RAM Shadow and NVM

Note: The “Reset IC” button is performing a power cycle of the IC, and forcing the IC to load configuration from NVM (into Shadow). Any IC settings that are not written to NVM will be lost. In addition, the evaluation software is refreshed.

2.3 IC Configuration and Calibration Procedures

2.3.1. “CONFIGURE” Application Tab

The “CONFIGURE” application tab offers sub-tabs for settings divided by functional blocks as described in Table 4. These tabs are used for configuring the ZSSC4132 to adapt to the specific application use case and requirements.

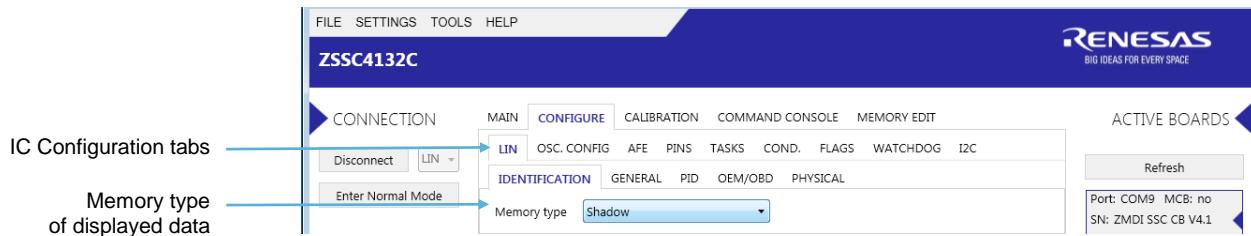


Figure 21. CONFIGURE Tab

Table 4. Sub-tabs of the “CONFIGURE” Tab

| Sub-tab | Description |
|----------------------|--|
| LIN | LIN interface related settings |
| LIN - IDENTIFICATION | LIN identification (NAD related settings) |
| LIN - GENERAL | General LIN interface configuration (Revision, SNPD, sleep mode support) |
| LIN - PID | LIN frame settings (identification, format and arrangement of unconditional frame) |
| LIN - OEM/OBD | OEM/OBD data settings accessible via LIN interface |
| LIN - PHYSICAL | Advanced LIN transceiver related settings |
| OSC. CONFIG | Oscillator settings (setup for oscillator spread spectrum) |
| AFE | Analog Front End settings (advanced settings) |
| PINS | Functional settings of the physical sensor pins (for example, operation mode) |
| TASKS | Measurement cycle task settings (for example, measurement task enabling, task specific ADC and PGA settings (for example, input, resolution, gain, offset), measurement cycle flow settings) |
| COND. | Sensor Signal Conditioning settings (for example, formula select, coefficients, digital output filtering) Note: Certain settings can be overwritten by the CALIBRATION tab. |
| FLAGS | Setup of diagnostics (for example, monitors, limits, counters) |
| WATCHDOG | Watchdog configuration and calculation |
| I2C | I2C interface configuration |

Settings are given by short names (referring to the field names of the memory allocation document). A more descriptive long name is shown by placing the cursor over the input field. Please refer to the *ZSSC4132 Memory Allocation* document for more detailed description of the settings (see product website: www.IDT.com/ZSSC4132).

The “Memory type” drop-down menu shows the memory, which is the source of the displayed data.

Note: GUI only allows directly changing settings in Shadow memory. A changed setting is not automatically written to the IC memory. All fields that differ from the last reading of chip memory are marked in red.

Follow these steps to write the changed values to the IC:

1. Click the “Write Shadow” button to change the Shadow memory, which is temporary.
2. Click “Copy Shadow to NVM” button to also change the NVM memory, to make it permanent.

All fields with blue background are read-only by the GUI. Do not change such fields as they can be calibrated parameters.

2.3.2. “CALIBRATION” Application Tab

“CALIBRATION” tab combines all tabs to support for calibration that can be applied to ZSSC4132. It offers four sub-tabs:

- BRIDGE-SENSOR
- TEMPERATURE 1
- TEMPERATURE 2
- BRIDGE-SENSOR CHECK

The “CALIBRATION” tab is used for acquiring raw measurement data and calculating the coefficients for the signal linearization and temperature compensation.

2.3.2.1. “BRIDGE-SENSOR” Sub-Tab

“BRIDGE-SENSOR” sub-tab implements the different calibration options for the bridge sensor (BRS) signal conditioning.

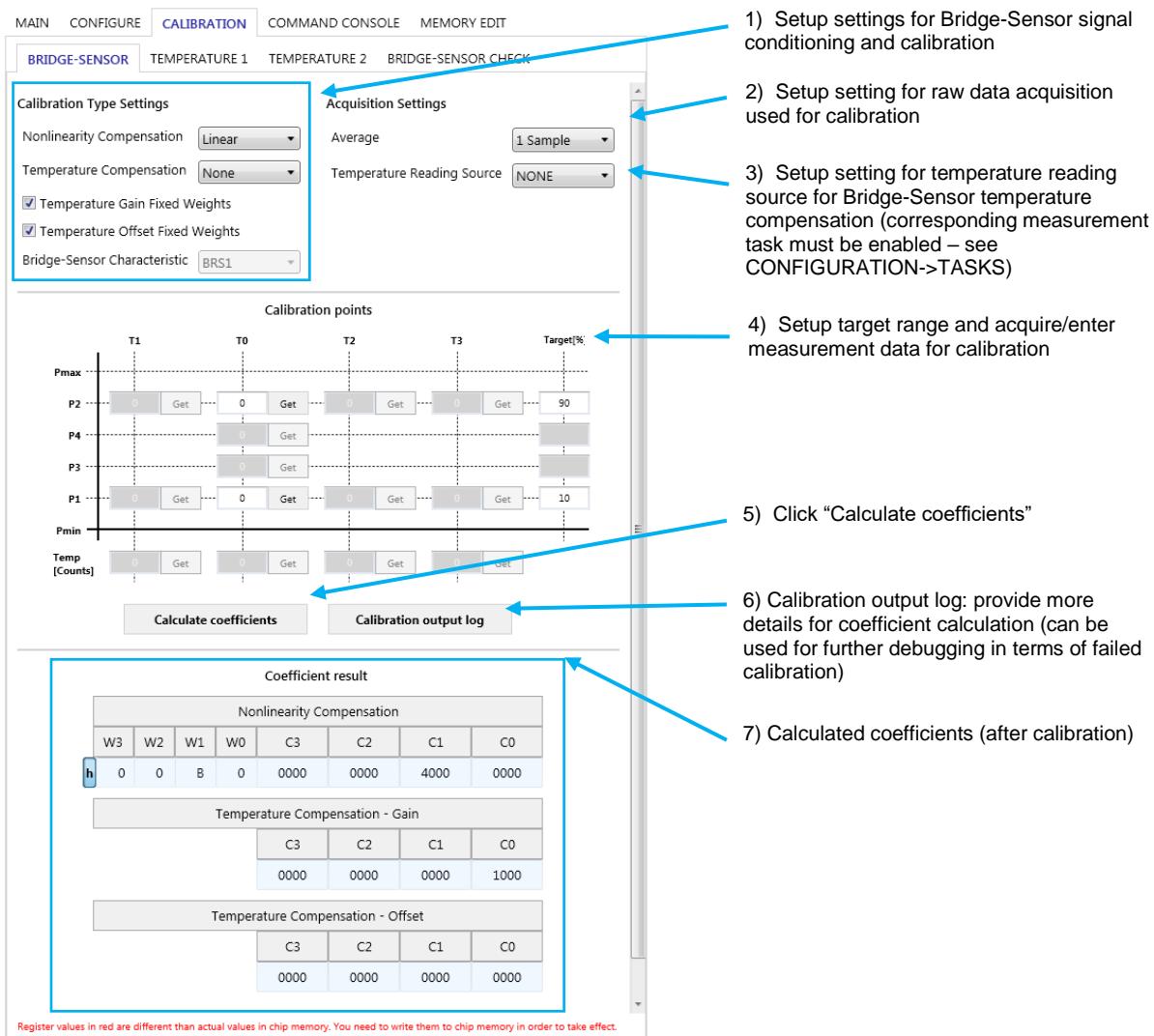


Figure 22. CALIBRATION/“BRIDGE-SENSOR” Sub-tab – Calibration Procedure

Table 5. Bridge Sensor - Calibration Type Settings

| Setting | Description |
|--|---|
| Nonlinearity Compensation (drop down menu) | Select the order of the nonlinearity of the bridge-sensor measurement to be compensated. By increasing the order, also the number of bridge measurement points to be acquired is increased. Adapting this setting influences the calculation of the coefficients. |
| Temperature Compensation (drop down menu) | Select the order of temperature dependent nonlinearity of the bridge sensor that should be compensated. The order of temperature compensations, also defines the number of temperatures where measurement points need to be acquired. Adapting this setting influences the calculation of the coefficients. |
| Temperature Gain Fixed Weights ^{[a] [c]} (checkbox) | Select conditioning formula which is used for temperature dependent gain compensation. This setting will be considered for the coefficient calculation. |
| Temperature Offset Fixed Weights ^{[b] [c]} (checkbox) | Select conditioning formula which is used for temperature dependent gain compensation. This setting will be considered for the coefficient calculation. |
| Bridge-Sensor Characteristic (drop down menu) | Determines which characteristic is going to be calibrated either "BRS1" or "BRS2". This menu is only available if "LinBrs2Ena" is enabled. As "BRS2" coefficients overlap with NTC coefficients in the memory, only one of these two features can be used at once. |

[a] Also changes corresponding IC setting ("BrsCondGainPolynomOrderSel") to be written to Shadow.

[b] Also changes corresponding IC setting ("BrsCondOffsPolynomOrderSel") to be written to Shadow.

[c] As long as temperature dependency up to second order is expected/targeted, it is recommended to uncheck the option to select the second order polynomial with flexible weights. This offers more flexibility and precision for the coefficient calculation, also increasing the chance to find suitable coefficients and a more precise calibration result.

Table 6. Bridge Sensor Calibration - Acquisition Settings

| Setting | Description |
|--|---|
| Average (drop down menu) | Determines the number of samples that are going to be acquired and averaged for each raw measurement. Use Averaging (for example, 8 or 16 samples) for calibration is recommended. |
| Temperature Reading Source ^[a] (drop down menu) | Determines the source of acquired temperature measurement data, also used for the BRS temperature compensation by the IC. Please assure that the corresponding measurement task is enabled, see CONFIGURATION/TASKS in section 2.3.1. |

[a] Adapting this setting also changes corresponding IC setting ("BrsCondTSel") to be written to Shadow.

After the "Calibration Type Settings" are set, the "Calibration points" section is used for acquiring the raw measurement points used for the calibration. Dependent on the calibration type settings, different text boxes are enabled representing the required points of calibration.

"Target" column contains the fields where the desired percentage of the output (referred to full scale) is filled in for each raw of measurements. Empty fields are assumed with value 0.

"Get" buttons are enabled only if a chip is connected.

The calibration can be also done by filling in all text boxes manually without a chip connected.

Coefficients can be calculated after all enabled text boxes are filled in. "Calibration output log" provides more details of the calculation of the coefficients. For example, it shows intermediate results. The results are shown in "Coefficient result" section.

Successful calculation of the coefficients is indicated by green "SUCCESS" message in the "Coefficient result" paragraph. Failed calculation is indicated by an error message and red "FAILED" indication.

Click "Write Shadow" to write the calculated coefficients to the IC.

You can check the calibration result in the MAIN tab, see section 2.4.1 for details. Click the "Start" button to start a measurement cycle and enable "Cond." or "%" checkboxes for displaying the conditioned values.

Note: Click "Copy Shadow to NVM" to copy settings to NVM (permanently).

2.3.2.2. "TEMPERATURE 1" Sub-Tab

"TEMPERATURE 1" sub-tab is used for linearization of temperature 1 reading. It is recommended to use Temperature 1 for the primary/main temperature measurement (usually external medium temperature).

For temperature 1, there are four types of calibration available: Quadratic, Cubic, NTC and PTC.

By selecting the "Calibration Type Setting", the selected Polynomial also changes the corresponding IC setting ("T1CondFormulaSel") and needs to be written to Shadow memory.

For details of the implemented conditioning formulas, please check the *ZSSC4132 Functional Description* document.

Quadratic and Cubic Formula Type

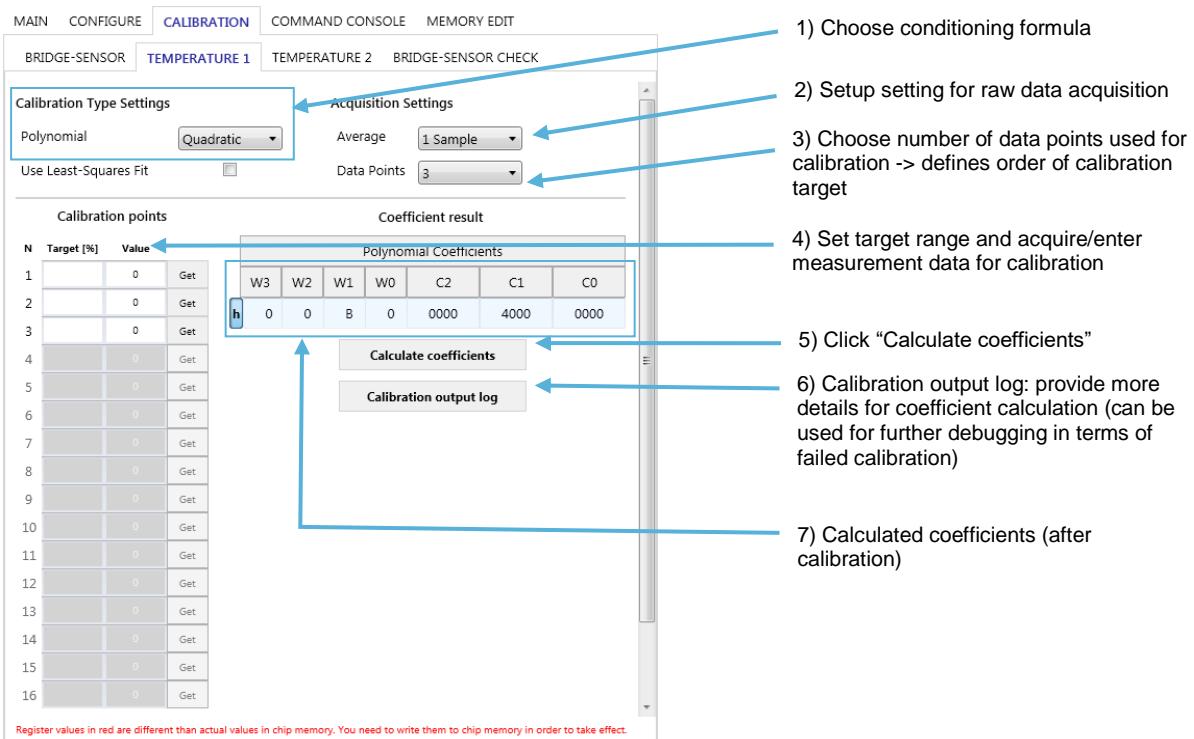


Figure 23. "TEMPERATURE 1" Sub-tab – Calibration type: Quadratic

Choose either of these polynomials to use for conditioning and calibration:

- Quadratic: using second order polynomial temperature conditioning formula (with variable weights).
- Cubic: using third order polynomial temperature conditioning formula (with fixed weights).

The maximum number of data points depends on the calibration type.

Choosing the number of "Data Points", defines the target for calibration:

- 2 points: linear approximation (1st order).
- 3 points: quadratic approximation (2nd order).
- 4 points: cubic approximation (3rd order).

Each data point consists of a target value [%] and a measured value.

Measurement result can be acquired as average result from raw measurement (choose number of averaging by the "Average" drop-down menu in the "Acquisition Settings") or can be filled manually without a connected chip.

The results are shown in "Coefficient result" section after clicking the "Calculate coefficients" button. "Calibration output log" show intermediate results of the calculation.

For linear approximation, it is also possible to use Least-Square Fit method. This increases the number of possible data points to the maximum of 16.

PTC Formula Type

PTC measurement requires chip configuration changes related to the recommended setup, see the [ZSSC4132 Functional Description](#) document for more details of recommended PTC configuration and setup.

When "PTC" is selected from the "Calibration Type Settings" menu, a window pops up with the recommended settings (see Figure 24). By clicking "Yes", the settings are applied on the GUI. By clicking "No", the settings need to be done manually.

Note that these changes only take effect on IC when “Write Shadow” is clicked. Click the “Copy Shadow to NVM” button to apply the changes persistent to the NVM memory..



Figure 24. IC Settings for PT1000 Setup (Configure Pin TS1 and TS2. Measurement Uses Pin TS1)

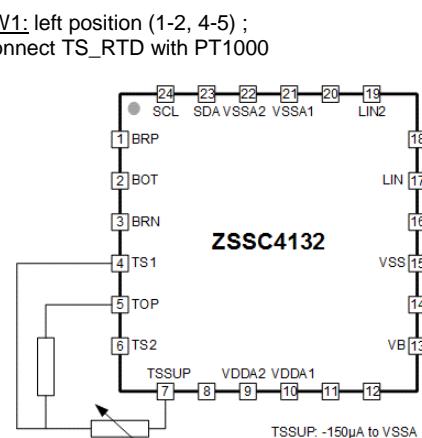
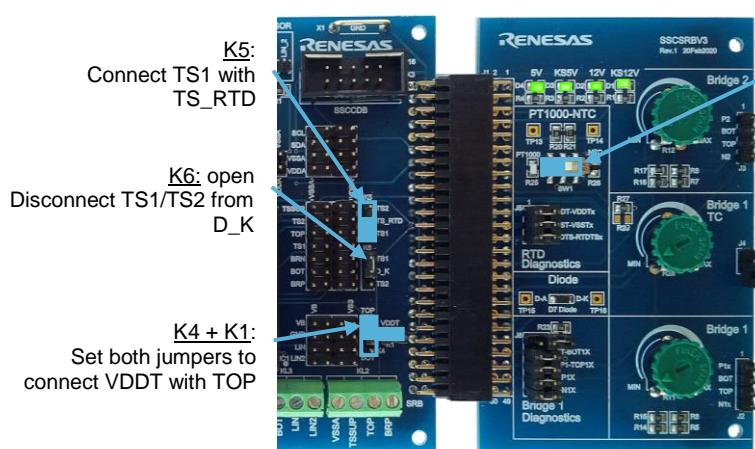


Figure 25. PTC Setup on SSC-EB and SSC-SRB (PT1000 Measured at TS1)

The evaluation software offers support for a PTC 1-point calibration dedicated to PT-type sense elements (for example, PT1000, PT500, etc.).

PTC calibration requires six parameters to be assigned:

- a0, a1, a2: to be derived from PTC manufacturer data sheet.
- Rs: typical series resistance of the half-bridge (15 kOhm default on SSC-SRB).
- [Tmin,Tmax] or [Trsl, Toff]: determining the target temperature range (full scale) for calibration.

A single measurement point at the calibration temperature is acquired using “Get” button.

“Calculate coefficients” performs calculation of the coefficients and fills in the calibration result in “Coefficient result” section.

Note: The calibration procedure intends to compensate for variations in the series resistance (Rs) of the single sensor build.

| N | Target [°C] | Value |
|----|-------------|-------|
| 1 | 25 | Get |
| 2 | 6.7 | Get |
| 3 | | Get |
| 4 | | Get |
| 5 | | Get |
| 6 | | Get |
| 7 | | Get |
| 8 | | Get |
| 9 | | Get |
| 10 | | Get |
| 11 | | Get |
| 12 | | Get |
| 13 | | Get |
| 14 | | Get |
| 15 | | Get |
| 16 | | Get |

Initial Conditioning Coefficients

| | | | | | |
|--|-------|-----|-----------------------------------|-----------|------------------|
| a0 | 1000 | Ω | a2 | -0.000587 | Ω/K ² |
| a1 | 3.906 | Ω/K | Rs | 15000 | Ω |
| <input checked="" type="radio"/> Min & Max | | | <input type="radio"/> Trsl & Toff | | |
| Min | -60 | °C | Max | 300 | °C |

Coefficient result

| Polynomial Coefficients | | | |
|-------------------------|------|------|------|
| C PTC | C2 | C1 | C0 |
| 00B0 | 0000 | 4000 | 0000 |

h

Calculate coefficients

Calibration output log

Register values in red are different than actual values in chip memory. You need to write them to chip memory in order to take effect.

Figure 26. "TEMPERATURE 1" Sub-Tab – Calibration Type: PTC

NTC Formula Type

NTC measurement requires mandatory changes in chip configuration related to the recommended setup, see the *ZSSC4132 Functional Description* document for more details of NTC configuration and setup.

When "NTC" is selected from the "Calibration Type Settings" menu, a window pops up with the recommended settings (see Figure 27). By clicking "Yes", the settings are applied on the GUI. By clicking "No", the settings need to be done manually.

Note that the changes only take effect temporary on the IC when “Write Shadow” is clicked. Click the “Copy Shadow to NVM” button to apply the changes persistently to the NVM memory.

Note: NTC coefficients share the same registers in memory as the coefficients for a second bridge characteristic (BRS2). Only one of the two features can be used at the same configuration.



Figure 27. IC Settings for NTC (Configure Pin TS1 and TS2. Measurement Uses Pin TS1)

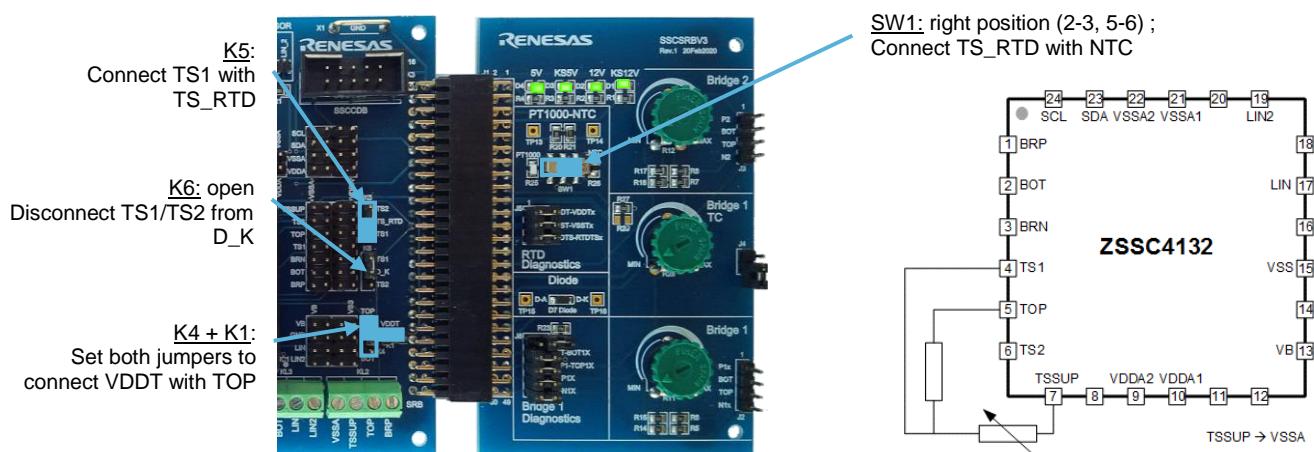


Figure 28. NTC Setup on SSC-EB and SSC-SRB (NTC Measured at TS1)

The GUI does not support import of NTC characteristic and direct calculation/calibration of the spline coefficients for NTC configuration.

The coefficients have to be determined separately (for example, by a separate tool) and can be filled in the sub-tab as shown on Figure 29.

MAIN CONFIGURE **CALIBRATION** COMMAND CONSOLE MEMORY EDIT

BRIDGE-SENSOR TEMPERATURE 1 TEMPERATURE 2 BRIDGE-SENSOR CHECK

Calibration Type Settings

Polynomial NTC

| Calibration points | | | Coefficient result | | | | |
|--------------------|------------|-------|--------------------|-------|-------|-------|--------|
| N | Target [%] | Value | Spline 0 | | | | |
| 1 | | Get | | 3 | 2 | 1 | 0 |
| 2 | | Get | Weight | 4 | 9 | 3 | 4 |
| 3 | | Get | Nonlinearity | 17540 | 96 | 21885 | -32499 |
| 4 | | Get | Grid Point 0 928 | | | | |
| 5 | | Get | Spline 1 | | | | |
| 6 | | Get | | 3 | 2 | 1 | 0 |
| 7 | | Get | Weight | 3 | 0 | 3 | 1 |
| 8 | | Get | Nonlinearity | 16644 | 27916 | 12683 | 12428 |
| 9 | | Get | Grid Point 1 8720 | | | | |
| 10 | | Get | Spline 2 | | | | |
| 11 | | Get | | 3 | 2 | 1 | 0 |
| 12 | | Get | Weight | 6 | 8 | 3 | 1 |
| 13 | | Get | Nonlinearity | 176 | 0 | 16384 | 0 |
| 14 | | Get | | | | | |
| 15 | | Get | | | | | |
| 16 | | Get | | | | | |

Register values in red are different than actual values in chip memory. You need to write them to chip memory in order to take effect.

Figure 29. "TEMPERATURE 1" – Calibration Type: NTC

2.3.2.3. "TEMPERATURE 2" Sub-Tab

"TEMPERATURE 2" sub-tab is used for linearization of temperature 2 reading. It is recommended to use Temperature 2 for the second/auxiliary temperature measurement.

For temperature 2, there are two types of calibration available: None and Quadratic.

- None: means that temperature 2 reading would not be linearized.
- Quadratic: using second order polynomial temperature conditioning formula (with fixed weights).

By selecting the "Calibration Type Setting", the selected Polynomial also changes the corresponding IC setting ("T2CondFormulaSel") and needs to be written to Shadow.

Choosing the number of "Data Points", defines the target for calibration:

- 2 points: linear approximation (1st order).
- 3 points: quadratic approximation (2nd order).

Each data point consists of a target value [%] and a measured value.

Measurement result can be acquired as average result from raw measurement (choose number of averaging by the "Average" drop-down menu in the "Acquisition Settings") or can be filled manually without a connected chip.

The results are shown in "Coefficient result" section after clicking the "Calculate coefficients" button. "Calibration output log" show intermediate results of the calculation.

For linear approximation, it is also possible to use Least-Square Fit method. This increases the number of possible data points to the maximum of 16.

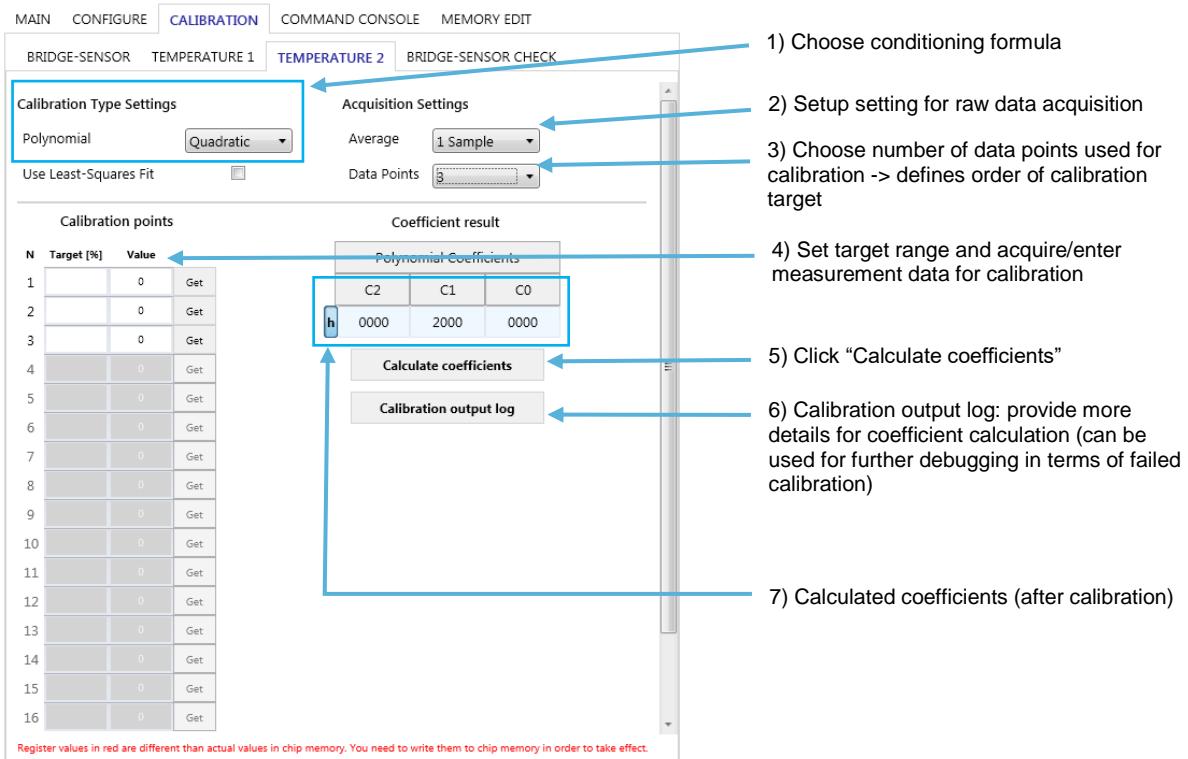


Figure 30. "TEMPERATURE 2" Sub-Tab – Calibration Type: Quadratic

2.3.2.4. "BRIDGE-SENSOR CHECK" Sub-Tab

If bridge sensor diagnostics is required, the tab Bridge-Sensor Check calibration supports three types of procedures covering different levels of diagnostic.

For a more detailed description of bridge sensor diagnostic features, please refer to the product documentation (such as *ZSSC4132 Functional Description*).

Table 7. Bridge Sensor Check – Diagnostic Levels and Calibration Procedures

| Setting/Diagnostic Level | Description |
|---|--|
| Wire Break Detection | No calibration required; only comparator mode used. |
| Wire Break and Short Detection | To be calibrated by acquiring two data points at single temperature (for example, 25 °C). Using comparator and analog limit mode without temperature compensation. Recommended for bridge sensors with low temperature coefficient (-1000ppm/K < tc < 1000ppm/K). |
| Wire Break and Short Detection with Temperature Dependent BRS | To be calibrated by acquiring six data points at two different temperatures. Using limit mode with temperature compensation and comparator mode of BRSC in parallel. Note that it requires an enabled RPTAT measurement. Recommended for bridge sensors with “high” temperature coefficient (tc > 750ppm/K). |

By selecting one of the procedures, a dialog window is displayed to automatically set the appropriate IC settings. Clicking “Yes” applies the necessary changes.

Note that these changes only take effect on IC when “Write Shadow” button is clicked. Click the “Copy Shadow to NVM” button to apply the changes persistently to the NVM.

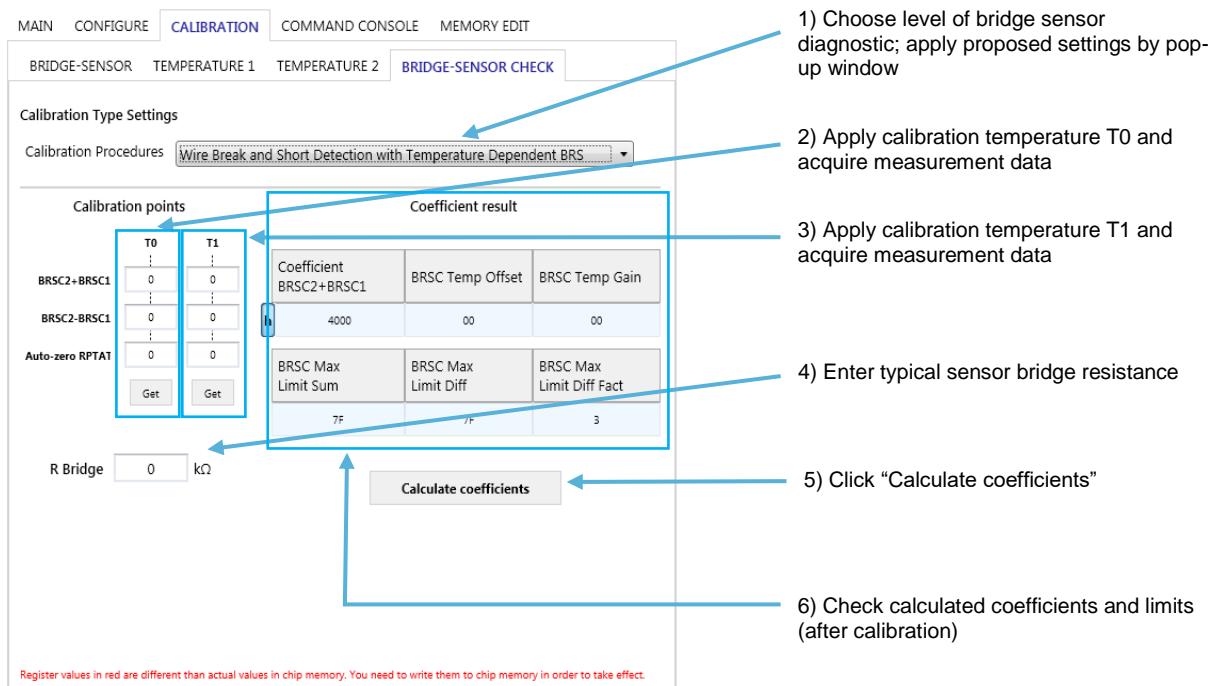


Figure 31. "BRIDGE SENSOR CHECK" Sub-Tab – Wire Break and Short Detection with Temperature Compensation

The reading of data points are triggered using the “Get” buttons, which are only active when a DUT is connected. The parameters can also be filled in manually for a dry run, when there is no chip connected. “Calculate coefficients” button gives the result in the “Coefficient result” section.

2.4 Evaluation Procedures

The effect and results can be evaluated if the required application settings and calibrations are done.

It is possible to check the effect of Shadow memory settings on the “IC STATUS” section of GUI and on the “MAIN” tab. These settings can be written to NVM.

Use the “Normal Mode” to check for correct operation in application based on NVM settings.

2.4.1. “MAIN” Application Tab

Primary functions of the “MAIN” tab on Figure 32:

- “Start” button: start measurement cycle and begin acquiring and recording measurement data. The measurement cycle is using the settings from RAM/Shadow. Once it’s clicked, “Start” button changes to “Stop”.
- “Stop” button: stop measurement and reading.
- Check boxes on the left side: determine which values are going to be displayed. Readings are taken from RAM output memory using the connected interface. Readings are displayed as numerical values and graphs.

Note: The IC stays in Command Mode using current settings in Shadow memory. Operation settings that are only valid in Normal Mode (like Watchdog settings) are not active.

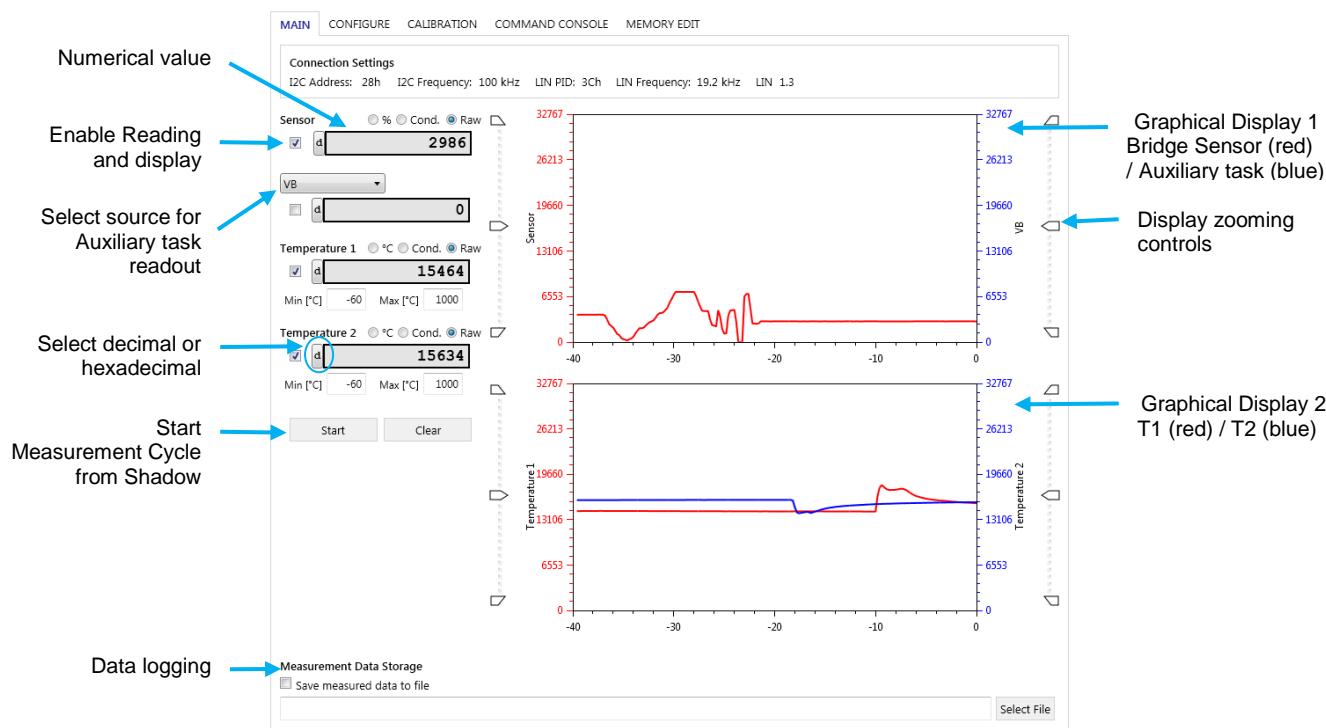


Figure 32. Measurement Readings on "MAIN" Tab

Table 8. MAIN Tab – Measurement Readings

| Signal | Description |
|-----------|---|
| Sensor | Bridge Sensor measurement; reading as: <ul style="list-style-type: none"> “Raw”: raw measurement result (auto-zero corrected). “Cond.”: conditioned and filtered result (without LIN output scaling). “%”: conditioned result as percentage of full scale range. |
| Auxiliary | Select one of the following parameters: VB, VDDA, VDDD, LPTAT, RPTAT, Gain1, Gain2, Gain_diff, TSC, TSC_diff_abs, BrSC1, BrSC2, BrSC_add, and BrSC_diff. |

| Signal | Description |
|-----------------------------|---|
| Temperature 1/Temperature 2 | T1/T2 measurement; reading as: <ul style="list-style-type: none"> • “Raw”: raw measurement result (auto-zero corrected). • “Cond.”: conditioned and filtered result (before LIN output scaling). • “°C”: conditioned result in degree Celsius rated by “Min [°C]” and “Max [°C]” limits. |

Note: Measurement tasks need to be enabled to get valid readings (see section 2.3.1 and TASKS settings for details).

For the raw and conditioned numerical values, the format (hexadecimal or decimal) is selected by clicking the small button on the left of the value display box (see Figure 32).

The values are also displayed in a graph:

- The top graph shows “Sensor” and “Auxiliary” measurements.
 - Sensor measurement is displayed in red color with its vertical axis is on the left of the graph.
 - Auxiliary measurement is displayed in blue color with vertical axis is on the right.
- The bottom graph shows “Temperature 1” and “Temperature 2” measurements.
 - Temperature 1 measurement is displayed in red color with its vertical axis is on the left.
 - Temperature 2 measurement is displayed in blue color with its vertical axis is on the right.

Enable the “Measurement Data Storage” check box to allow: data logging of the reading.

2.4.2. “IC STATUS” Section

In the left panel under “IC STATUS”, the status of the device is indicated by the color of the virtual LEDs (see Figure 33):

- Green: The corresponding status bit is ok.
- Red: A flag has been raised.
- Gray: Inactive.

The three lines of status indicator represent as follows:

1. “RdIcStatus” command (0x60) response. Read once after the end of a continuous measurement.
2. “FailStatToLin” memory register in Output Memory (address 0x25). Read after each reading in a continuous measurement.
3. “FailureStatus” memory register in Output Memory (address 0x26). Read after each reading in a continuous measurement.

Click the “Read status” button to read the current IC-status flags.

The IC status Panel is also updated regularly while MAIN tab measurement is running.

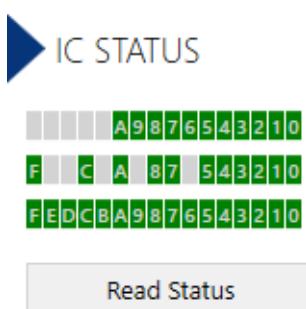


Figure 33. IC STATUS Panel

2.4.3. “Normal Mode” Window

Click “Enter Normal Mode” button to open “Normal Mode” window. Opening this window puts the IC in normal mode operation and reads the LIN output (regardless of the selected interface for connection).

It reads the two LIN publisher frame configurations (based on NVM settings) and draws three graphs based on the reading: “Bridge Sensor”, “Temperature 1” and “Temperature 2”, if available in the frame. Readings of PID0 frame are shown in green and readings of PID1 frame are shown in yellow.

On the bottom of the window, all included signals of the two frames are displayed as numerical readings (decimal and hexadecimal).

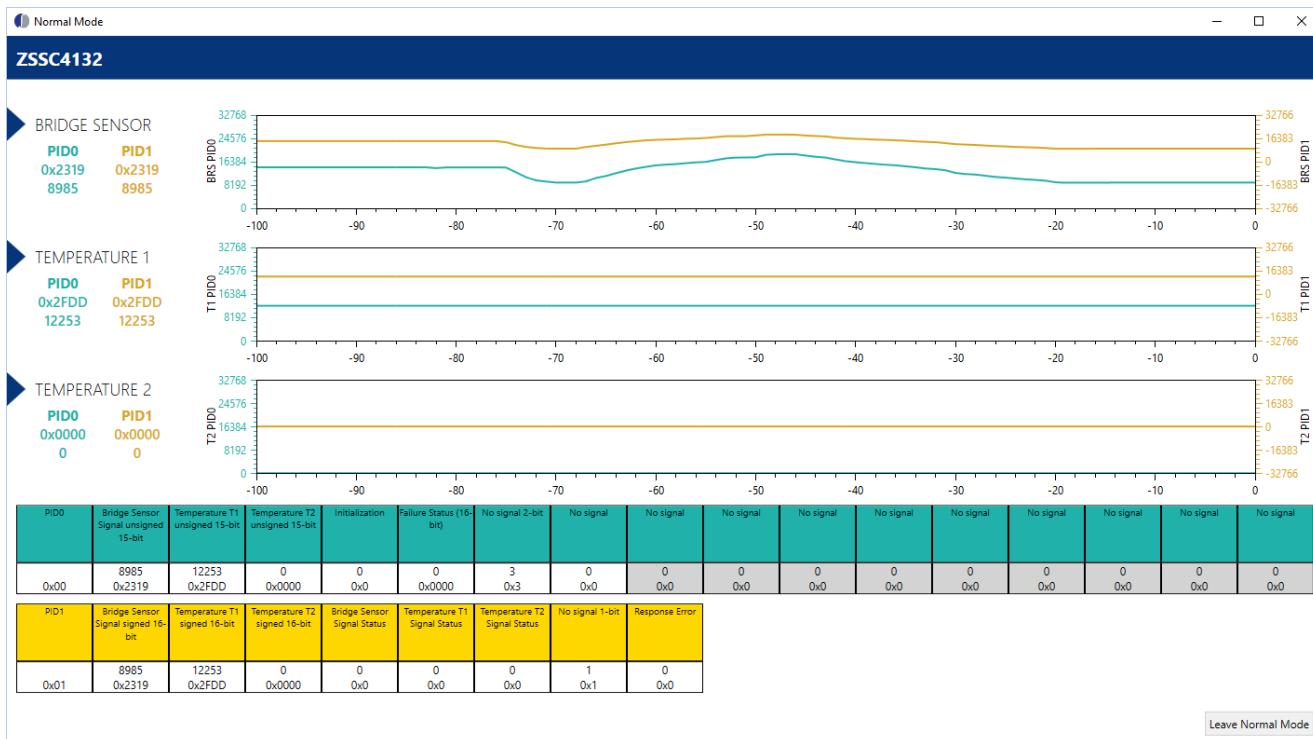


Figure 34. LIN Publisher Frame Output in “Normal Mode” Window

Note: Starting the Normal Mode means that the IC copies the settings from NVM to Shadow and start normal operation. Temporary settings in Shadow are lost, if not copied to NVM before. The IC leaves Command Mode.

Click “Leave Normal Mode” to stop normal operation and close the Normal Mode window. The IC enters Command Mode. The GUI settings are updated by reading Shadow and Output memory from IC.

2.5 “Command Console” Tab

On the “COMMAND CONSOLE” tab, the user can write commands directly to evaluation kit (and IC) and see the response in the output window.

A previously edited script file can be loaded and executed directly as a command sequence by clicking the “Browse” button, selecting a file, and clicking the “Execute Script” button shown in Figure 35. The script file must be a text file (*.txt) with valid commands. Comments can be present in the script file using the special symbol “#” at the beginning of the line.

Predefined commands can be generated by using the drop-down menu “Command” and adding the additional data in “Data” text box. It’s up on user to check for correctness. In order to read an IC response, a read command needs to be triggered.

Previously sent commands can be called again by pressing Up Arrow key when single command text box is in focus.

The output data can be copied and saved for further analysis by right-clicking on the results in the display.

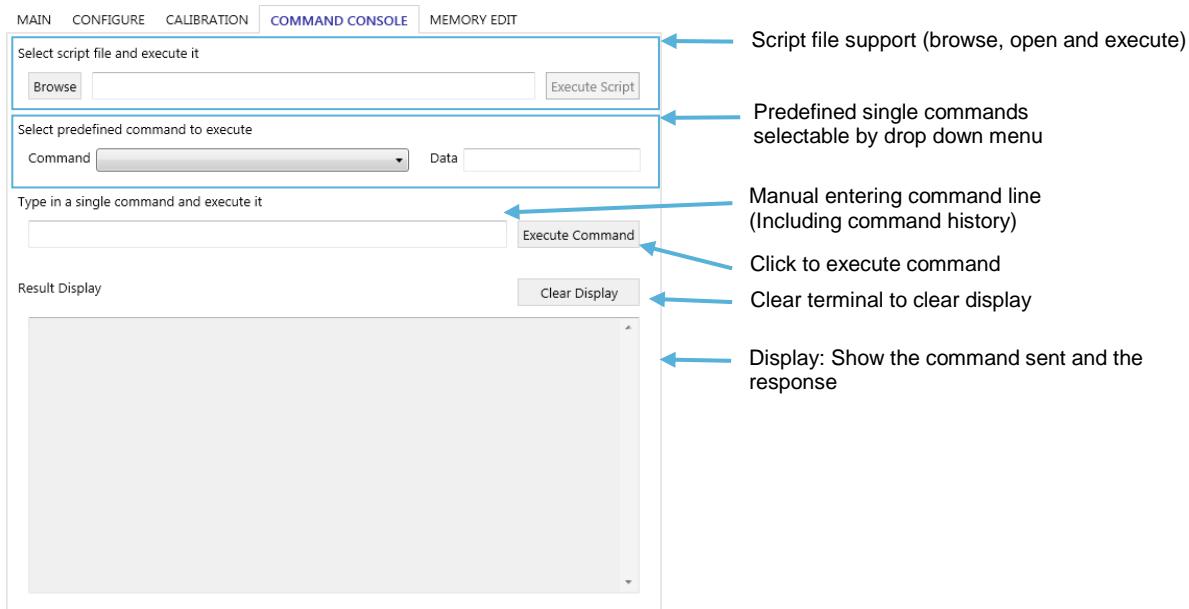


Figure 35. “COMMAND CONSOLE” Tab

The syntax of the SSC communication board is used for handling the different communication interfaces (LIN, I2C) to the IC.

For details check SSC communication board syntax (SSC_CB_Command_Syntax_Version_4_xx.xlsx) included in the firmware update package. It can be downloaded on the SSC-CB webpage: www.IDT.com/SSC-CB

The IC specific commands are described in the command description document.

The LIN specific services supported by the IC are described in the *ZSSC4132 LIN Data Link Layer Manual* document on the www.IDT.com/ZSSC4132

Table 9. Command Console – General Setup Commands

| Command | Description | Expected Response (example) |
|----------------------|---|---|
| V | Read firmware version string of the SSC-CB | <ACK>V4.18 ? ZMD AG 2019 - CB SVN: 10144 |
| V_HW | Read hardware information of connected CB and EVB) | <ACK>SSC CB V4.1 : SSC EB N032 - ZSSC4132 |
| T11050 | Setup Trigger: switch on both supplies (KS12V, KS5V) with 50ms delay between power-on and first command. | <ACK> |
| T00000 | Power off | <ACK> |
| IS_07 (IS_11, IS_10) | Setup I2C speed to 400kHz (100kHz, 50kHz) | <ACK> |
| LOV1 | Set LIN interface version to v1.3 | <ACK> |
| LOV2 | Set LIN interface version to v2.x | <ACK> |
| LO_20000001 | Set LIN interface settings (19.2kHz, 13 bit Break Field, no Break Delimiter, no Inter-Byte Space Header, no Response Space, no Inter-Byte Space Response, no Inter-Frame Space Response, calculate CRC automatically) = default | <ACK> |
| TWAITxxxx | Delays a specific amount of milliseconds (xxxxx - milliseconds to wait). – e.g. TWAIT10 = 10ms delay | <ACK> |
| PS_A51 | Turn on KS5V (switchable 5V) | <ACK> |
| PS_A61 | Turn on KS12V (switchable 12V) | <ACK> |
| PS_A50 | Turn off KS5V (switchable 5V) | <ACK> |
| PS_A60 | Turn off KS12V (switchable 12V) | <ACK> |
| ... \ ... | List of commands ("\" = separator) | <ACK> ... \ |

2.5.1. I2C Commands (Example)

Table 10 lists some examples using I2C interface commands.

Table 10. Command Console – I2C Commands (Example)

| Command | Description | Expected Response (example) |
|----------------------------|---|--|
| IW_aabbdd.. | Write I2C command, with: <ul style="list-style-type: none">aa: I2C addressbbb: number of bytes to writedd: bytes to be written (= command code + arguments) | <ACK> |
| IR_aabb | Read I2C response, with: <ul style="list-style-type: none">aa: I2C addressbbb: number of bytes to read | Returned bytes |
| IWTaabbdd... | PowerOn using predefined Trigger & Write I2C command | <ACK> |
| Examples | | |
| IWT28003727EA9 IR_28001 | Power On & send "Start Command Mode" Read command response (1 byte) | <ACK> <ACK>72 |
| IW_280017C IR_28003 | Send "Read Product Version Code"(0x7C) Read command response (3 byte) | <ACK> <ACK>7C 0624 • 0x7C = command response (success); • 0x0624 = Product Version Code |
| IW_2800160 IR_28003 | Send "Read IC Status Register" (0x60) Read command response (3 byte) | <ACK> <ACK>60 0000 • 0x60 = command response (success); • 0x0000 = no flags |
| IW_2800326007F IR_28257 | Send "Read NVM in Burst Mode"(0x26) with Shadow start address: 0x00, word count: 0x7F (-> 128 words) Read command response -> read 257 bytes (= 2x128 + 1) | <ACK> <ACK>22 0080 0019 ... B01E • 0x26 = command response (success) • 0x0080 = data of shadow addr. 0x00 • 0x0019 = data of Shadow addr. 0x01 .. 0xB01E = data of Shadow addr. 0x7F |
| IW_2800322007B IR_28249 | Send "Read Shadow Memory in Burst Mode"(0x22) with Shadow start address: 0x00, word count: 0x7B (-> 124 words) Read command response -> read 249 bytes (= 2x124 + 1) | <ACK> <ACK>22 0080 0019 ... 0311 • 0x22 = command response (success) • 0x0080 = data of shadow addr. 0x00 • 0x0019 = data of Shadow addr. 0x01 • .. • 0x0311 = data of Shadow addr. 0x7B |
| IW_2800103 | Send "Start Measurement and Conditioning Cycle from Shadow Memory" (0x03) | <ACK> |
| IW_280012C IR_28079 | Send "Read Output Memory"(0x2C) with start address 0x00 and word count 38 (=39 words) Read command response -> read 79 bytes (= 2x39 + 1) | <ACK> <ACK>2C XXXX YYYY ... • 0x2C = command response (success) • 0xXXXX = data of OutMem addr. 0x00 • 0xYYYY = data of OutMem addr. 0x01 .. |
| IW_2800107 | Send "Stop Run"(0x07) of measurement cycle | <ACK> |

| Command | Description | Expected Response (example) |
|--|---|---|
| IW_28003096400 (TWAITxxxx) IR_28001 | Send "Start Measurement" (0x09) with Averaging = 8 samples, auto-zero compensation = enabled, using normal operation measurement cycle from Shadow (consider wait time for execution) Read command response (1 byte) -> when finished, the averaged measurement results can be read from Output memory section in RAM | <ACK> <ACK>09 • 0x09 = command successful finished • (0x00 = command in execution) |
| IW_28251 23 007B0080 0019..0311 | Send "Write Shadow Memory in Burst Mode"(0x23) ^[a] with Shadow start address = 0x00, word count = 0x7B (124 words), 124 data words (= 248 bytes): 0x0080 @ addr.0x00; 0x0019 @ addr.0x01; ...; 0x0311 @ addr.0x007B | <ACK> |
| IW_28003153C5B | Send "Write NVM Write Authorization" (0x15) with NVM Write Authorization Key 0x3C5B | <ACK> |
| IW_2800114 IR_28003 | Send "Read NVM Write Authorization Status" (0x14) Read command response | <ACK> <ACK>14 0001 • 0x14 = command response (success) • 0x0001 = NVM Write Enabled |
| IW_280031A0007 wait ≈ 744ms IR_28003 | Send "Copy Shadow Memory to NVM" (0x20) with all pages (ShdwPgLinObd, ShdwPgApplCfg, ShdwPgLinId) selected and CRCs calculated Wait ≈ 744 ms (124 register * 6 ms max. programming time per word); Read command response | <ACK> <ACK>1A 0000 • 0x1A = command response (success) • NVM successfully written |
| IW_2800101 | Send "Start Normal Mode" | <ACK> |

[a] Do not change calibrated parameters! For details, please check Memory Allocation document.

2.5.2. LIN Commands (Example)

Table 11 lists some examples using LIN interface commands.

For detailed description of LIN services and handling supported by the IC, see *ZSSC4132 LIN Data Link Layer Manual* document on product webpage.

Table 11. Command Console – LIN Commands (Example)

| Command | Description | Expected Response (Example) |
|-------------------|--|-----------------------------|
| General | | |
| LW_aabbdd.. | Write LIN command, with: • aa: LIN frame identifier (ID) • bbb: number of bytes to write • dd: bytes to be written = 2 x byte count | <ACK> |
| LR_aabb | Read LIN slave response, with: • aa: LIN address • bbb: number of bytes to read | <ACK>Returned bytes |
| LWTaabbdd... | Power On using predefined Trigger & Write LIN command | <ACK> |
| LW_aabbdd\LR_aabb | List of a LIN write and LIN read (separator = "\"); Used in order to request the LIN slave response before discarded by timeout (≈1s) | <ACK>\Returned bytes |

| Command | Description | Expected Response (Example) |
|---|---|---|
| General Example | | |
| LW_3C0087F04B4xxxxyFFFF | <p>Send a single LIN frame command</p> <p>Via Diagnostic frame (transport layer) using the LIN Data-Dump service (SID 0xB4) – with:</p> <ul style="list-style-type: none"> • 0x3C = Frame ID reserved for Master Request frame • 008 = 8 data bytes to send • 0x7F = NAD (Broadcast) • 0x04 = PCI (single frame, 4 bytes) • 0xB4 = SID for the Data-Dump service • xx = Command code (1byte, hex) • yyyy = Optional argument (2 byte, hex) • 0xFFFF = Unused bytes filled with 0xFF | <ACK> |
| LR_3D008 | <p>Read command response – with:</p> <ul style="list-style-type: none"> • 0x3D = Frame ID reserved for Slave Response frame | <ACK>19 04 F4 xx yyyy FFFF <ul style="list-style-type: none"> • 0x19 = configured NAD of IC • 0x04 = PCI (single frame, 4bytes) • 0xF4 = RSID for Data-Dump service • xx = command response (hex) • yyyy = Return data (optional, hex) • 0xFFFF = unused bytes filled with 0xFF |
| Examples | | |
| LWT3C0087F04B4727EA9FFFF \ LR_3D008 | <p>Power On & send “Start Command Mode”</p> <p>via LIN Data-Dump service (SID 0xB4)</p> <p>Read command response (8 data byte)</p> | <ACK> \ 19 04 F4 727272 FFFF <ul style="list-style-type: none"> • 0x19 = NAD; 0x04=PCI; 0xF4=RSID; 0x727272=“StrtCmdMd” success |
| LW_3C0087F02B47CFFFFFFF \ LR_3D008 | <p>Send “Read Product Version Code”(0x7C) via LIN Data-Dump service (SID 0xB4)</p> <p>Read command response (8 data byte)</p> | <ACK> \ 19 04 F4 7C 0624 FFFF <ul style="list-style-type: none"> • 0x19 = NAD; 0x04=PCI; 0xF4=RSID; • 0x7C = command response; • 0x0624 = Product Version Code |
| LW_3C0087F02B460FFFFFFF \ LR_3D008 | <p>Send “Read IC Status Register” (0x60)</p> <p>Read command response (8 data byte)</p> | <ACK> \ 1904F4600000FFFF <ul style="list-style-type: none"> • 0x19 = NAD; 0x04=PCI; 0xF4=RSID; • 0x60 = command response; • 0x0000 = no flags |
| LW_3C0087F04B4240000FFFF \ LR_3D008 ..to be repeated for each NVM address/word | <p>Send “Read NVM Word ”(0x24)</p> <p>via LIN Data-Dump service (SID 0xB4) from NVM address = 0x0000</p> <p>Read command response (8 data byte)</p> | <ACK> \ 19 04 F4 24 00 80 FFFF <ul style="list-style-type: none"> • 0x19 = NAD; 0x04=PCI; 0xF4=RSID; • 0x24 = command response; • 0x00 = High byte of NVM addr. 0x00 • 0x80 = Low byte of NVM addr. 0x00 0xFFFF = unused bytes filled with 0xFF |

| Command | Description | Expected Response (Example) |
|--------------------------|--|---|
| LW_3C0087F0523212700F8FF | Read Shadow Memory content from RAM via LIN “Read-Memory-By-Address” service (SID 0x23) <ul style="list-style-type: none"> • 0x7F = NAD (Broadcast) • 0x05 = PCI (single frame, 5 bytes) • 0x23 = SID for the Read-Memory-By-Address • 0x21 = fixed byte (D1) • 0x27= Start address of Shadow in RAM • 0x00F8 = byte count = 248 bytes (= 124 words * 2) | <ACK> |
| LR_3D008 | Read First frame | <ACK>19 1 0F9 63 8000 1900 <ul style="list-style-type: none"> • 0x19 = configured NAD • 0x1 = PCI • 0x0F9 = LENgth (= 248 + 1 bytes) • 0x63 = RSID (Read-Mem.-By-Addr.) • 0x80 =Low byte of Shadow addr. 0x00 • 0x00 = High byte of Shadow addr. 0x00 • 0x19 = Low byte of Shadow addr. 0x01 • 0x00 = High byte of Shadow addr. 0x01 |
| LR_3D008 | Read Consecutive frame 1 | <ACK>19 1 0F9 63 8000 1900 <ul style="list-style-type: none"> • 0x19 = configured NAD; • 0x1 = PCI • 0x0F9 = LENgth (= 248 + 1 bytes) • 0x63 = RSID (Read-Mem.-By-Addr.) • 0x80 =Low byte of Shadow addr. 0x00 • 0x00 = High byte of Shadow addr. 0x00 • 0x19 = Low byte of Shadow addr. 0x01 • 0x00 = High byte of Shadow addr. 0x01 |
| LR_3D008 | Read Consecutive frame 2 | <ACK>19 2 2 00 19 00 00 00 00 <ul style="list-style-type: none"> • 0x19 = NAD; 0x2 = PCI • 0x2 = Frame count = 2; • ..data bytes |
| .. | .. | .. |
| LR_3D008 | Read Consecutive frame 15 | <ACK>19 2 F 00 00 00 00 00 40 <ul style="list-style-type: none"> • 0x19 = NAD; 0x2 = PCI • 0xF = Frame count = 15; • ..data bytes |
| LR_3D008 | Read Consecutive frame 16 | <ACK>19 2 0 00 00 00 00 00 00 <ul style="list-style-type: none"> • 0x19 = NAD; 0x2 = PCI • 0x0 = Frame count = 0 (restart count); • .. data bytes |
| .. | .. | .. |
| LR_3D008 | Read Consecutive frame 31 | <ACK>19 2 F 00 00 00 00 00 00 <ul style="list-style-type: none"> • 0x19 = NAD; 0x2 = PCI; • 0xF = Frame count = 15; • .. data bytes |
| .. | .. | .. |
| LR_3D008 | Read Consecutive frame 41 | <ACK>19 2 9 00 00 11 03 FFFF <ul style="list-style-type: none"> • 0x19 = NAD; 0x2 = PCI; • 0x9 = Frame count = 9; • 0x00 = Low byte of Shadow addr. 0x7A • 0x00 =High byte of Shadow addr. 0x7A • 0x11 = Low byte of Shadow addr. 0x7B • 0x03 = High byte of Shadow addr.0x7B |
| LW_3C0087F02B403FFFFFF | Send “Start Measurement and Conditioning Cycle from Shadow Memory” (0x03) | <ACK> |

| Command | Description | Expected Response (Example) |
|---|---|--|
| LW_3C0087F05232100004EFF | Read Output Memory content from RAM via LIN “Read-Memory-By-Address” service (SID 0x23) with OutMem start address in RAM = 0x00, byte count: 0x004E (78 bytes = 39 words * 2) | <ACK> |
| LR_3D008 | Read First frame | <ACK>19 1 04F 63 0100 780B • 0x19 = configured NAD; • 0x1 = PCI • 0x0F9 = LENgth (= 248 + 1 bytes) • 0x63 = RSID (Read-Mem.-By-Addr.) • 0x0001 = data OutMem addr. 0x00 • 0xB78 = data OutMem addr. 0x01 |
| LR_3D008 | Read Consecutive frame 1 | <ACK>19 2 1 0100 EC36 0100 • 0x19 = NAD; 0x2 = PCI; • 0x1 = Frame count = 1; • 0x0001 = data OutMem addr. 0x02 • 0x36EC = data OutMem addr. 0x03 • 0x0001 = data OutMem addr. 0x04 |
| .. | .. | .. |
| LR_3D008 | Read Consecutive frame 13 | <ACK> 19 2 D 0000 FFFF FFFF • 0x19 = NAD; 0x2 = PCI; • 0x9 = Frame count = 13; • 0x0000 = data OutMem addr. 0x26 • 0xFFFF FFFF = unused bytes filled |
| LW_3C0087F02B407FFFFFF | Send “Stop Run”(0x07) of measurement cycle via LIN Data-Dump service (SID 0xB4) | <ACK> |
| LW_3C0087F04B4096400FFFF (TWAITxxxx) LR_3D008 | Send “Start Measurement” (0x09) with Averaging = 8 samples, auto-zero compensation = enabled, using normal operation measurement cycle from Shadow (consider wait time for execution, but <1s) Read command response (1 byte) -> when finished, the averaged measurement results can be read from Output memory section in RAM | <ACK> <ACK>1904F4090909FFFF • 0x090909 = successful finished • (0x000000 = in execution) |

| Command | Description | Expected Response (Example) |
|---------------------------|--|-----------------------------|
| LW_3C0087F10FD3D212700F8 | <p>Write Shadow Memory content to RAM ^[a] via LIN “Write-Memory-By-Address” service (SID 0x3D)</p> <ul style="list-style-type: none"> • 0x7F = NAD (Broadcast) • 0x1 = PCI • 0x0FD = 253 bytes to write (= 124 words * 2 + 5) • 0x3D = SID for the Write-Memory-By-Address • 0x21 = fixed byte (D1) • 0x27= Start address of Shadow in RAM • 0x00F8 = byte count = 248 bytes (= 124 words * 2) <p>..</p> | <ACK> |
| LW_3C0087F2180001900480F | <p>Write Consecutive frame 1</p> <ul style="list-style-type: none"> • 0x7F = NAD (Broadcast); • 0x2 = PCI • 0x1 = frame count = 1 • 0x80 =Low byte of Shadow addr. 0x00 • 0x00 = High byte of Shadow addr. 0x00 • 0x19 = Low byte of Shadow addr. 0x01 • 0x00 = High byte of Shadow addr. 0x01 • 0x48 = Low byte of Shadow addr. 0x02 • 0x0F =High byte of Shadow addr. 0x02 | <ACK> |
| LW_3C0087F220000000000019 | <p>Write Consecutive frame 2</p> <ul style="list-style-type: none"> • 0x7F = NAD (Broadcast); • 0x2 = PCI • 0x2 = frame count = 2 • 0x00/00 =Low/High byte of Shadow addr. 0x03 • 0x00/00 =Low/High byte of Shadow addr. 0x04 • 0x00/19 =Low/High byte of Shadow addr. 0x05 <p>..</p> | <ACK> |
| LW_3C0087F2F0010B0000000 | <p>Write Consecutive frame 15</p> <ul style="list-style-type: none"> • 0x7F = NAD; 0x2 = PCI; • 0xF = Frame count = 15; • ..data bytes | <ACK> |
| LW_3C0087F20000000400000 | <p>Write Consecutive frame 16</p> <ul style="list-style-type: none"> • 0x7F = NAD; 0x2 = PCI; • 0x0 = Frame count = 0 (restart count with “0”); • .. data bytes (0x0000, 0x4000, 0x0000) <p>..</p> | <ACK> |
| LW_3C0087F2F0000000000000 | <p>Write Consecutive frame 31</p> <ul style="list-style-type: none"> • 0x7F = NAD; 0x2 = PCI; • 0xF = Frame count = 15; • ..data bytes (0x0000, 0x0000, 0x0000) <p>..</p> | <ACK> |
| LW_3C0087F2A1103FFFFFF | <p>Write Consecutive frame 41</p> <ul style="list-style-type: none"> • 0x7F = NAD (Broadcast); • 0x2 = PCI • 0xA = frame count = 10 • 0x11/03 =Low/High byte of Shadow addr. 0x7B • 0xFFFFFFFF = unused bytes filled with 0xFF | <ACK> |
| LW_3C0087F04B4153C5BFFFF | Send “Write NVM Write Authorization” (0x15) with NVM Write Authorization Key 0x3C5B via LIN Data-Dump service (SID 0xB4) | <ACK> |
| LW_3C0087F02B414FFFFFF | Send “Read NVM Write Authorization Status” (0x14) via LIN Data-Dump service (SID 0xB4) | <ACK> |
| \ | | \ |

| Command | Description | Expected Response (Example) |
|--|---|---|
| LR_3D008 | Read command response | 1904F4140001FFFF • 0x14 = command response (success) • 0x0001 = NWM Write Enabled |
| LW_3C0087F04B41A0007FFFF \ TWAIT744 \ LR_3D008 | Send "Copy Shadow Memory to NVM" (0x20) with all pages (ShdwPgLinObd, ShdwPgApplCfg, ShdwPgLinId) selected and CRCs calculated Wait ≈ 744 ms (= 124 register * 6ms NVM programming time (max)); <1s Read command response | <ACK> \ \<ACK>1904F41A0000FFFF • 0x1A 0000 = command response (success) -> NVM successfully written |
| LW_3C0087F02B401FFFFFF | Send "Start Normal Mode" | <ACK> |

[a] Do not change calibrated parameters! For details, please check Memory Allocation document.

2.5.3. Command Script (Example)

```
# Check SSC-Communication Board connection, read firmware and hardware version
V
V_HW

# Setup Trigger (KS12V, KS5V, 50ms communication delay)
T11050

# Set LIN interface settings
LO_20000001

# Triggered Power-ON + Start Command Mode - via LIN Data-Dump (SID 0xB4)
LWT3C0087F04B4727EA9FFF
# Read Command Response
LR_3D008

# Send: ClrOutMem
LW_3C0087F02B41FFFFFF
# check response
LR_3D008

# Send: StrtMeasCyc sequence with - short with only mandatory argument:
# settings: Avg=2(4 samples), CpShdwCfgDis=0(ShadowSettingsCopiedToRegisters),
InfiniteCycling=0(disabled), AzEna=1(enabled), MeasCycMd=0(normal)
LW_3C0087F04B4094400FFF

# # Read OutMem - via LIN Read-Memory-By-Address (SID 0x23)
# Read Averaged Raw Measurement Results for BRS, T1, T2, RPTAT
LW_3C0087F05232100000CFF
LR_3D008
LR_3D008
LR_3D008
```

2.6 “MEMORY EDIT” Application Tab

The “MEMORY EDIT” tab shows the current state of the chip memory.

It allows the user to edit and write memory contents. All the fields in blue color (NVM and Output memory) are read-only registers. Changing values directly to the memory can be done by entering the new hexadecimal value in the grid box of the corresponding address. The new content must be updated in the chip by clicking the “Write Shadow” button. The “Copy Shadow to NVM” button copies the content of the Shadow memory to NVM and updates the CRCs.

The display grid updates automatically when the settings changes in the “CONFIGURE” and “CALIBRATION” application tabs; the values that are not yet written in the chip memory are shown in red. Note that these values are not written automatically in the ZSSC4132 memory, to do this, click “Write Shadow” button.

If a register is modified, the indicator in the bottom right corner of the window becomes red as shown on Figure 36. If the content in the table is the same as the content read at the last reading, the indicator stays green.



Figure 36. Memory Indicator: Modified Content

The data is displayed as hexadecimal (16 bits) for each address in the memory.

Registers names of each address are displayed if you hover the mouse cursor over the corresponding grid box.

To display the actual DUT memory contents in the table, read the complete memory by clicking on the “Read Shadow”, “Read Output”, and “Read NVM” buttons.

| MAIN | CONFIGURE | CALIBRATION | COMMAND CONSOLE | MEMORY EDIT | | | | | | | | |
|--------|-----------|-------------|-----------------|-------------|------|------|------|------|--|--|--|--|
| Shadow | 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | | | | |
| 0h | C180 | 0019 | 9B69 | 0000 | 0000 | 1900 | 0000 | 0000 | | | | |
| 8h | 0842 | 150D | 291D | 3931 | 004C | 0000 | 0000 | 0000 | | | | |
| 10h | 0000 | 0000 | 0000 | 0000 | 24F4 | 01E4 | 0024 | 8FFF | | | | |
| 18h | 0008 | 2300 | 0075 | 17E2 | C0A2 | C822 | 6789 | 1722 | | | | |
| 20h | 3000 | 0000 | 0002 | 0000 | 0000 | 0000 | 0000 | 0000 | | | | |
| 28h | 0000 | 0000 | 1000 | 00B0 | 0000 | 0000 | 4000 | 0000 | | | | |
| 30h | 0000 | 0000 | 0000 | 0000 | 0000 | 0000 | 0000 | 1000 | | | | |
| 38h | 00B0 | 0000 | 0000 | 4000 | 0000 | 00B0 | 0000 | 4000 | | | | |
| 40h | 0000 | 0000 | 2000 | 0000 | 4000 | 0000 | 78DE | 4444 | | | | |
| 48h | 0000 | 0000 | 7FFF | 0000 | 7FFF | 0000 | 7FFF | FF00 | | | | |
| 50h | FF00 | FF00 | FFFF | FF00 | FF00 | FF00 | FF00 | FF00 | | | | |
| 58h | FF00 | BC96 | 0000 | 0000 | 0000 | 0000 | 0000 | 0000 | | | | |
| 60h | 0000 | 0000 | 0000 | 0000 | 0000 | 0000 | 0000 | 0000 | | | | |
| 68h | 0000 | 0000 | 0000 | 0000 | 0000 | 0000 | 0000 | 0000 | | | | |
| 70h | 0000 | 0000 | 0000 | 0000 | 0000 | 0000 | 0000 | 0000 | | | | |
| 78h | 0000 | 0000 | 0000 | 0311 | | | | | | | | |

Figure 37. "MEMORY EDIT" Tab – Shadow Memory

By clicking the “Start Read Output Memory Continuously” button, a continuous measurement cycle from Shadow is started and the content of the output memory will be read continuously.

Activating the checkbox “Output memory in decimal format” shows values as decimal.

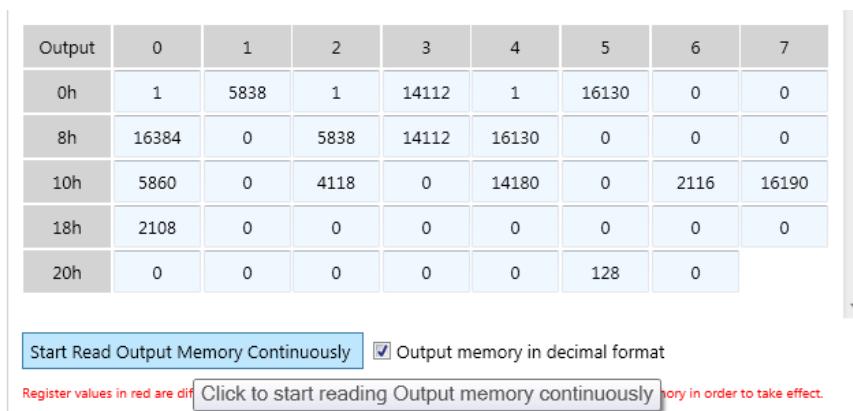


Figure 38. "MEMORY EDIT" Tab – Output Memory (Decimal)

2.7 Tools

Clicking on the “TOOLS” menu, see Figure 39, the following options will be provided:

- Open the Log files for:
 - Error: includes general error logging events (for example, calibration error)
 - Communication: includes communication logs with the evaluation kit and IC
 - Calibration: includes calibration logging information
- Open the Log file folder: to open the logging folder in an explorer window.

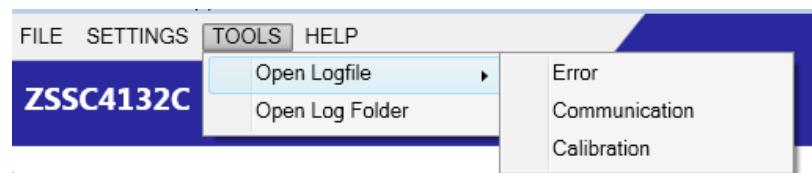


Figure 39. TOOLS Menu Options

2.8 Help

Clicking on the “HELP” menu, see Figure 40, the following options will be provided:

- “Show License” agreement: to show the license agreement and disclaimer information that was also agreed at the installation process.
- Click “About” window: to show a pop-up window with information about the GUI revision, release date, FTDI driver version, and communication board firmware revision. This information is useful, when support on the GUI is required.



Figure 40. HELP Menu Options

3. Schematics

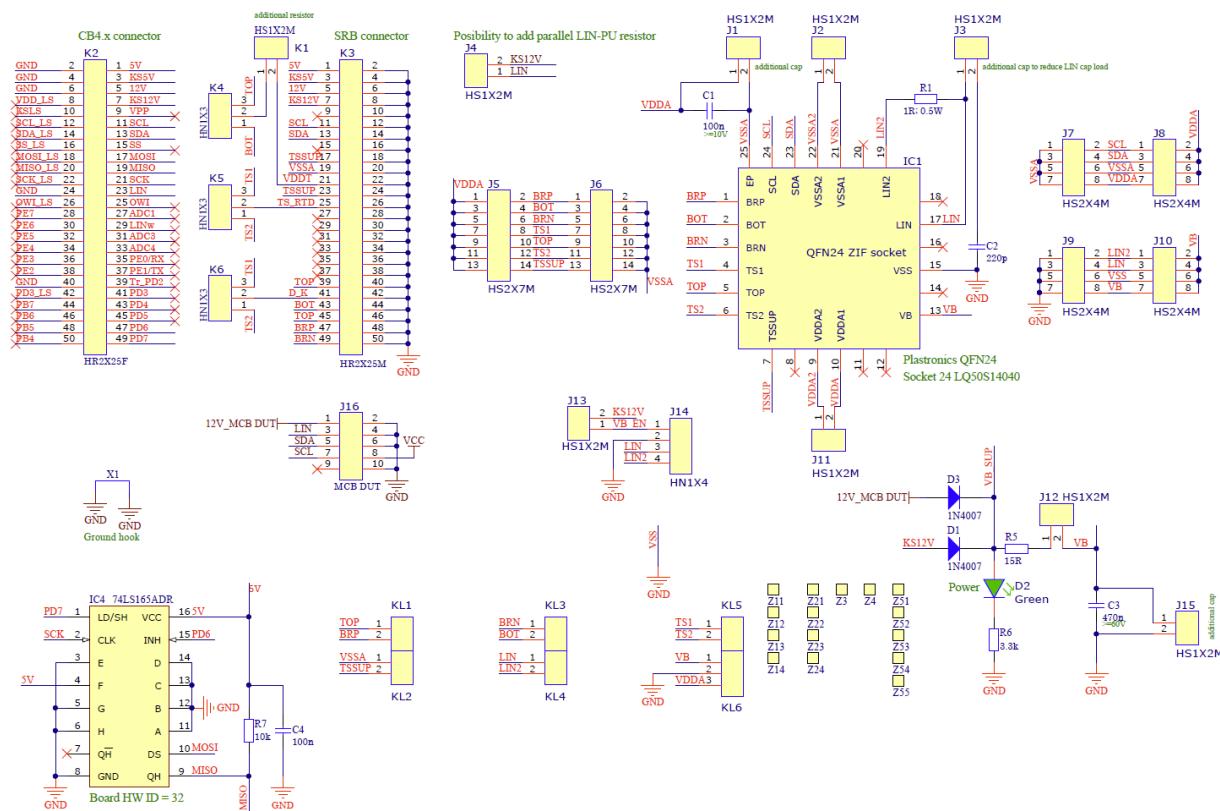


Figure 41. Schematic – ZSSC4132 Evaluation Board: ZSSC4132EVB_Rev.1 (20Feb2020)

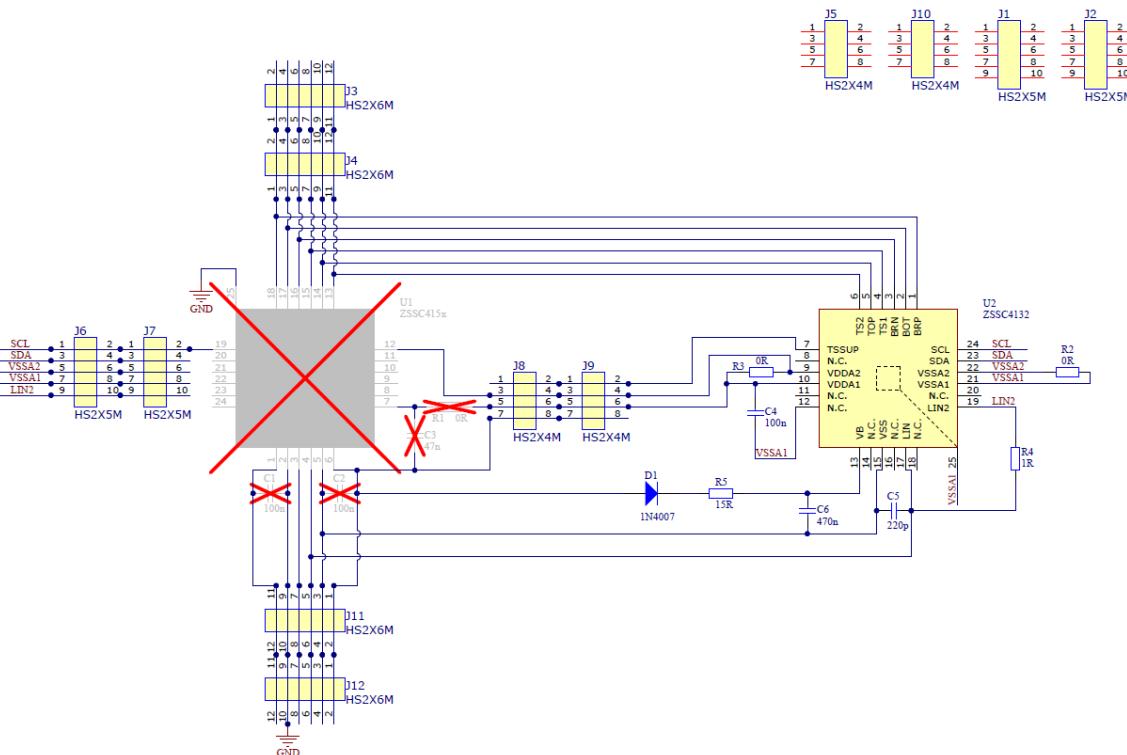


Figure 42. Schematic – ZSSC4132 Sample Board: ZSSC41xxSB_Rev.1 (20Feb2020); Bottom (ZSSC4132)

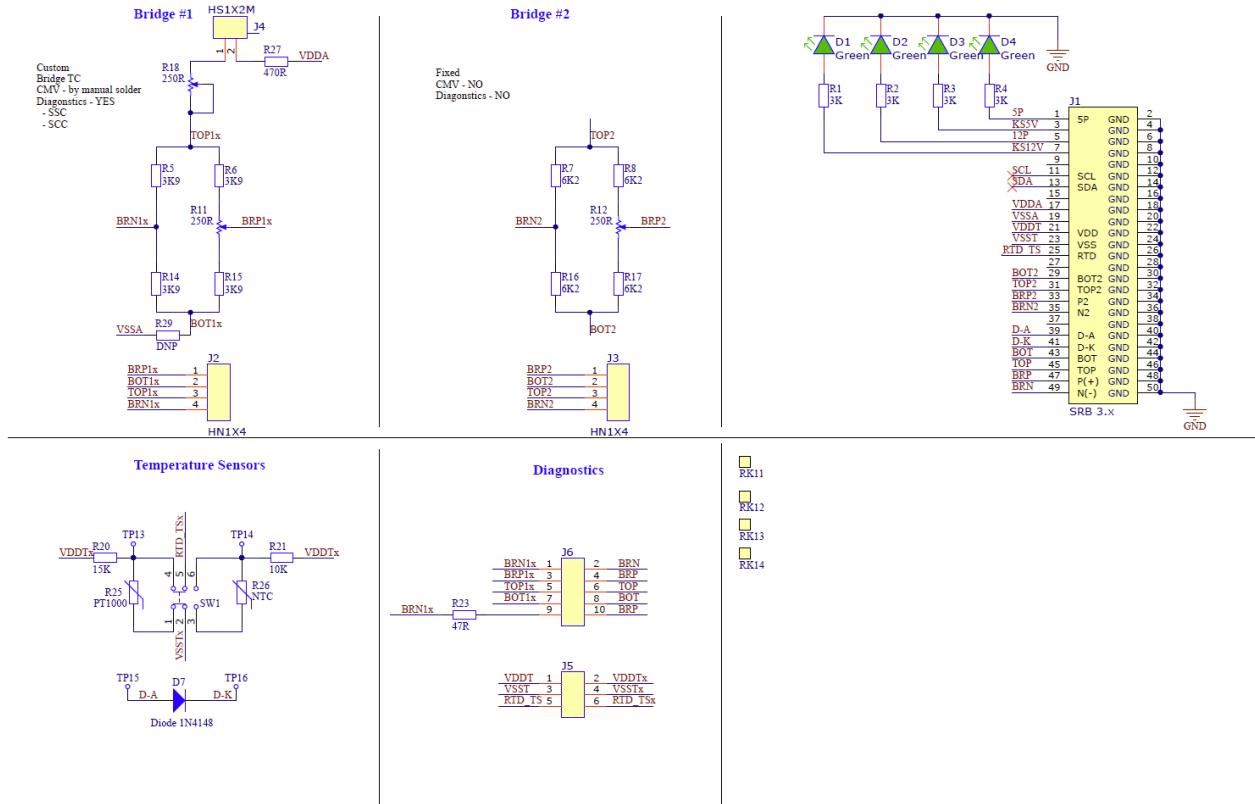


Figure 43. Schematic – Sensor Replacement Board: SSCSRBV3_Rev.1 (20Feb2020)

4. Bill of Materials (BOM)

Table 12. BOM - ZSSC4132 Evaluation Board: ZSSC4132EVB, Rev.1, 20Feb2020

| Designator | Value | Package | Description | Manufacturer P/N | Manufacturer | Qty. |
|--|-------------|---------------|---|-----------------------|--------------------------|------|
| C1, C4 | 100 nF | 0603 | CAP SMD 0603, 100 nF, 25 V, X7R, +10% | VJ0603Y104KXXPW1BC | VISHAY | 2 |
| C2 | 220 pF | 0603 | CAP SMD 0603, 220 pF, 50 V, COG, +5%, 30ppm | GRM1885C1H221JA01D | MURATA ELECTRONICS | 1 |
| C3 | 470 nF | 0603 | CAP SMD 0603, 0.47 µF, 16 V, X7R, ± 5%, C Series | C0603C474J4RACTU | KEMET | 1 |
| D1, D3 | 1N4007 | SMA | Diode, 1000 V, 1 A, UFM1.1V/1A, IFM30A, IR5uA | M7 | SM TECHNOLOGY | 2 |
| D2 | LED Green | 0805 | LED, 2.0x1.25 mm, 450 mcd/20mA, 525 nm True Green, 120° | OSG50805C1E | OPTOSUPPLY INTERNATIONAL | 1 |
| IC1 | | 24-QFN Socket | ZIF socket, 24-QFN | 24LQ50S14040-E | PLASTRONICS | 1 |
| IC4 | | SOP-16 | CMOS High Speed Logic - 74HC/AHC/AC Series | 74HC165D | NEXPERIA | 1 |
| J1, J2, J3, J4, J11, J12, J13, J15, K1 | Header 1x2 | HS1X2M | Board to Board/Wire Header, contact height 6.0mm, 1x2, straight PCB TH, P2.54mm | CH31022V200 | CVILUX | 9 |
| J5, J6 | Header 2x7 | HS2X7M | Board to Board/Wire Header, contact height 6.0mm, 2x7(40), straight PCB TH, P2.54mm | CH81802V200 (cut) | CVILUX | 2 |
| J7, J8, J9, J10 | Header 2x4 | HS2X4M | Board to Board/Wire Header, contact height 6.0mm, 2x4(40), straight PCB TH, P2.54mm | CH81802V200 (cut) | CVILUX | 4 |
| J14 | Header 1x4 | HN1X4 | Board to Board/Wire Header, contact height 6.0mm, 1x4, straight PCB TH, P2.54mm | CH31042V200 | CVILUX | 1 |
| J16 | Header 2x4 | BH10S | Box Header Connector 2x5 | CH87102V200 | CVILUX | 1 |
| K2 | Socket 2x25 | HR2X25F | BL 2X25W 2,54, 2x 25-pin socket terminal strip, angled, RM 2.54 | BL 2X25W 2,54 | Reichelt | 1 |
| K3 | Header 2x25 | HR2X25M | SL 2X25W 2,54, 2 x 25-pin header, angled, pitch 2.54 | SL 2X25W 2,54 | Reichelt | 1 |
| K4, K5, K6 | Header 1x3 | HN1X3 | Board to Board/Wire Header, contact height 6.0mm, 1x3, straight PCB TH, P2.54mm | CH31032V200 | CVILUX | 3 |
| KL1, KL2, KL3, KL4, KL5 | - | DG350-3.5-02P | Screw terminal, 2 port, 10A 300V AC AWG24-18 3.5mm | DG350-3.5-02P-14-00AH | DEGSON | 5 |
| KL6 | - | DG350-3.5-03P | Screw terminal, 3 port, 10A 300V AC AWG24-18 3.5mm | DG350-3.5-03P-14-00AH | DEGSON | 1 |
| R1 | 1 Ω | 1206 | RES SMD 1206, Thick film, 1R, 1%, 0.5 W, MCWF12P Series, 200 V | MCWF12P1R00FTL | Multicomp Pro | 1 |
| R5 | 15 Ω | 0603 | RES SMD 0603, 15R, 1%, 100ppm, 1/10W | RC0603FR-0715RL | YAG/ASJ | 1 |
| R6 | 3.3 kΩ | 0603 | RES SMD 0603, 3.3K, 1%, 100ppm, 1/10W | RC0603FR-073K3L | YAG/ASJ | 1 |
| R7 | 10 kΩ | 0603 | RES SMD 0603, 10K, 1%, 100ppm, 1/10W | RC0603FR-0710KL | YAG/ASJ | 1 |

| Designator | Value | Package | Description | Manufacturer P/N | Manufacturer | Qty. |
|------------|-------|------------------|---|------------------|----------------|------|
| X1 | - | 10.16mm | D3082F05 - Track Pin, Uninsulated, Shorting Link, 0.4 ", 25 Pack | D3082F05 (cut) | HARWIN | 1 |
| - | - | W:102mm; L:152mm | ESD Bag; open; W: 102mm; L: 152mm; D: 50um | ERS-207710406 | EUROSTAT GROUP | 1 |
| - | - | 3mm | PD.2075BL - Bumper / Feet, Stick On, Pack 60, Adhesive, PU (Polyurethane), 3 mm, Round, Black | PD.2075BL(cut) | MULTICOMP | 4 |
| - | - | 2.54, 6mm | Jumper 2.54; h 6mm | CS01602B100 | CVILUX | 8 |

Table 13. BOM – Sensor Replacement Board: SSCSRBV3, Rev.1, 20Feb2020

| Designator | Value | Package | Description | Manufacturer P/N | Manufacturer | Qty. |
|------------------|--------------|------------|---|-------------------|--------------------------|------|
| D1, D2, D3, D4 | LED Green | 0805 | LED, 2.0x1.25 mm, 450 mcd/20mA, 525 nm True Green, 120° | OSG50805C1E | OPTOSUPPLY INTERNATIONAL | 4 |
| D7 | Diode 1N4148 | SOD-123 | Diode 1N4148, 100V, 150mA, 4ns, 2pF | 1N4148W | DIODES/ZETEX | 1 |
| J1 | Socket 2x25 | HR2X25F | BL 2X25W 2,54, 2x 25-pin socket terminal strip, angled, RM 2.54 | BL 2X25W 2,54 | Reichelt | 1 |
| J2, J3 | Header 1x4 | HN1X4 | Board to Board/Wire Header, contact height 6.0mm, 1x4, straight PCB TH, P2.54mm | CH31042V200 | CVILUX | 2 |
| J4 | Header 1x2 | HN1X2 | Board to Board/Wire Header, contact height 6.0mm, 1x2, straight PCB TH, P2.54mm | CH31022V200 | CVILUX | 1 |
| J5 | Header 2x3 | HS2X3M | Board to Board/Wire Header, contact height 6.0mm, 2x3(40), straight PCB TH, P2.54mm | CH81802V200 (cut) | CVILUX | 1 |
| J6 | Header 2x5 | HS2X5M | Board to Board/Wire Header, contact height 6.0mm, 2x5(40), straight PCB TH, P2.54mm | CH81802V200 (cut) | CVILUX | 1 |
| R1, R2, R3, R4 | 3.0 kΩ | 0805 | RES SMD 0805, 3.0K, 1%, 100ppm, 1/8W | 0805S8F0302T50 | UNI OHM | 4 |
| R5, R6, R14, R15 | 3.9 kΩ | 0805 | RES SMD 0805, 3.9K, 1%, 100ppm, 1/8W | RC0805FR-073K9L | YAG/ASJ | 4 |
| R7, R8, R16, R17 | 6.2 kΩ | 0805 | RES SMD 0805, 6.2K, 1%, 100ppm, 1/8W | 0805S8F0622T50 | UNI OHM | 4 |
| R11, R12, R18 | 250 Ω | Rtrim_PT10 | Trimmer Resistor – Through-hole, 250 Ohm, 10mm, Rnd, Top adj | 531-PT10MV-250 | AMPHENOL PIHER | 3 |
| R20 | 15 kΩ | 0805 | RES SMD 0805, 15K, 1%, 100ppm, 1/8W | RC0805FR-0715KL | YAG/ASJ | 1 |
| R21 | 10 kΩ | 0805 | RES SMD 0805, 10K, 1%, 100ppm, 1/8W | RC0805FR-0710KL | YAG/ASJ | 1 |
| R23 | 47 Ω | 0805 | RES SMD 0805, 47R, 1%, 200ppm, 1/8W | 0805S8F0470T50 | UNI OHM | 1 |
| R25 | PT1000 | 0805 | RTD Sensor PT1000, Class B, 0805, -50 °C, +150 °C, 1 kohm | P1K0.0805.1FC.B.S | IIST | 1 |
| R26 | NTC_10K | 0805 | Thermistor, NTC, 10 kohm, B57620C5 Series, 3730 K, SMD | B57620C5103J062 | EPCOS | 1 |
| R27 | 470 Ω | 0805 | RES SMD 0805, 470R, 1%, 100ppm, 1/8W | RC0805FR-07470RL | YAG/ASJ | 1 |

| Designator | Value | Package | Description | Manufacturer P/N | Manufacturer | Qty. |
|---------------------------|--------|---------------------|---|------------------------|-------------------|------|
| R29 | DNP | 0805 | RES SMD 0805 | - | - | 1 |
| RK11, RK12, RK18 | - | - | Thumbwheel for Piher pot. PT10M,G, diam. 11.5mm, H=6mm, green | PT10M,G- THUMBWHEEL | AMPHENOL PIHER | 3 |
| SW1 | switch | CL-SB-22B | CL-SB-22B-01T - Slide Switch, DPDT, Surface Mount, CL-SB Series, 200 mA | CL-SB-22B-01T | Nidec | 1 |
| TP13, TP14, TP15, TP16 | DNP | - | Test point | - | - | 4 |
| - | - | W:102mm; L:152mm | ESD Bag; open; W: 102mm; L: 152mm; D: 50um | ERS-207710406 | EUROSTAT GROUP | 1 |
| - | - | 3mm | PD.2075BL - Bumper / Feet, Stick On, Pack 60, Adhesive, PU (Polyurethane), 3 mm, Round, Black | PD.2075BL(cut) | MULTICOMP | 2 |
| - | - | 2.54, 6mm | Jumper 2.54; h 6mm | CS01602B100 | CVILUX | 9 |

Table 14. BOM – ZSSC4132 Sample Board: ZSSC41xxSB, Rev.1, 20Feb2020 – Bottom Layer (ZSSC4132)

| Designator | Value | Package | Description | Manufacturer P/N | Manufacturer | Qty. |
|---------------------|-----------|----------------------|--|--------------------|---------------|------|
| C4 | 100 nF | 0603 | CAP SMD 0603, 100nF, 25V, X7R, +10% | VJ0603Y104KXXPW1BC | VISHAY | 1 |
| C5 | 220 pF | 0603 | CAP SMD 0603, 220pF, 100V, COG, +5% | MC0603N221J101CT | MULTICOMP | 1 |
| C6 | 470 nF | 0805 | CAP SMD 0805, 0.47μF, 100 V, ± 10%, X7R | 08051C474KAT2A | AVX | 1 |
| D1 | 1N4007 | SMA | Diode, 1000V, 1A, UFM1.1V/1A, IFM30A, IR5uA | 1N4007(M7) | SM TECHNOLOGY | 1 |
| R2, R3 | 0 Ω | 0603 | RES SMD 0603, JUMPER, MAX 50mOhm | 0603SAJ000JT50 | UNI OHM | 2 |
| R4 | 1 Ω | 1206 | RES SMD 1206, 1 ohm, MCWF12P Series, 200 V, Thick Film, 500 mW | MCWF12P1R00FTL | MULTICOMP | 1 |
| R5 | 15 Ω | 0603 | RES SMD 0603, 15R, 1%, 100ppm, 1/10W | RC0603FR-0715RL | YAG/ASJ | 1 |
| U2 | ZSSC4132C | 24-QFN | IC, Sensor Signal Conditioner, ZSSC4132C | ZSSC4132CE4R | Renesas (IDT) | 1 |
| - | - | W: 50mm; L: 101mm | ESD Bag; metallized, open; W: 50mm; L: 101mm | 10024 | SCS | 1 |
| J6, J7 | DNP | HS2X5M | 2x5-pin header, vertical, P2.54 mm | CH81402V200 | CVILUX | 2 |
| J3, J4, J11, J12 | DNP | HS2X6M | 2x6-pin header, vertical, P2.54 mm | CH81402V200 | CVILUX | 4 |
| J8, J9 | DNP | HS2X4M | 2x4-pin header, vertical, P2.54 mm | CH81402V200 | CVILUX | 2 |

5. Board Layout

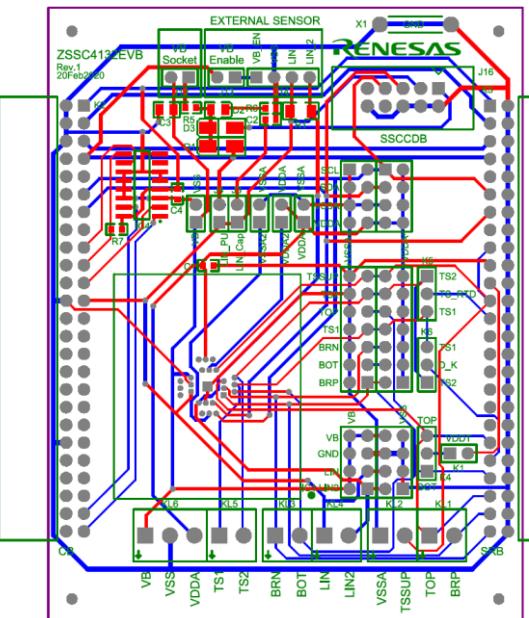


Figure 44. Layout - ZSSC4132 Evaluation Board: ZSSC4132EVB, Rev.1, 20Feb2020 – Top/Bottom Layer

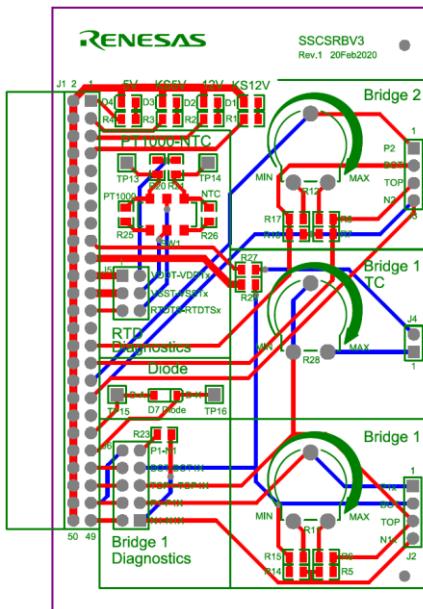


Figure 45. Layout - Sensor Replacement Board: SSCSRBV3, Rev.1, 20Feb2020 – Top/Bottom Layer

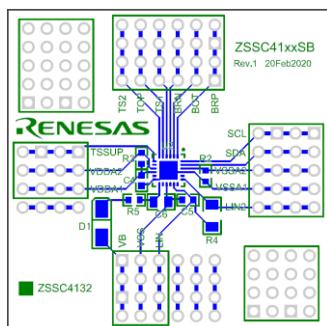


Figure 46. Layout - ZSSC4132 Sample Board: ZSSC41xxSB, Rev.1, 20Feb2020 – Bottom Layer ZSSC4132

6. Related Documents and Software Locations

Visit the following product pages on Renesas's website www.IDT.com to download the latest version of the ZSSC4132 Evaluation Software, related documents, and the latest version of this document, or contact Renesas via the contact information on the last page.

- Product page: www.IDT.com/ZSSC4132
- Kit product page: www.IDT.com/ZSSC4132KIT
- SSC Communication Board: www.IDT.com/SSC-CB

7. Glossary

| Term | Description |
|----------|---|
| ADC | Analog-to-Digital Converter |
| Addr. | Address |
| AFE | Analog Frontend |
| BOM | Bill Of Material |
| BRS | Bridge Sensor |
| BRSC | Bridge Sensor Connection |
| BSM | Bus Shunt Method (LIN) |
| CB | Communication Board |
| CMC | Calibration Microcontroller |
| CmdMd | Command Mode |
| CRC | Cyclic Redundancy Check |
| DEC | Decimal |
| DLL | Dynamic Link Library |
| DUT | Device Under Test |
| EB, EVB | Evaluation Board |
| GUI | Graphical User Interface – refers to the software application used for communication with the kit |
| HEX, hex | Hexadecimal |
| I2C | Inter-Integrated Circuit; serial two-wire data bus; trademark of NXP |
| IC | Integrated Circuit |
| LED | Light Emitting Diode |
| LIN | Local Interconnect Network |
| LSB | Least Significant Bit |
| MCU | Microcontroller Unit |
| MRF | Master Request Frame (LIN) |
| MSB | Most Significant Bit |
| MTP | Multiple Times Programmable (Memory) |
| NAD | Node Address (LIN) |
| NOM | Normal Operation Mode |
| NTC | Negative Temperature Coefficient |
| NVM | Non-Volatile Memory |
| PC | Personal Computer |
| PCB | Printed Circuit Board |
| PCI | Protocol Control Information (LIN) |
| PGA | Programmable Gain Amplifier |
| PID | Protected Identifier (LIN) |
| PTAT | Proportional To Absolute Temperature (IC internal temperature) |
| PTC | Positive Temperature Coefficient |
| (P)QFN | (Power) Quad Flat No-lead (device package) |
| RAM | Random Access Memory (Volatile Memory for Configuration and Conditioning Coefficients) |
| RSID | Response Service Identifier (LIN) |
| RTD | Resistance Temperature Device/Detector |
| SID | Service Identifier (LIN) |
| SMD | Surface-Mounted Device |
| SNPD | Slave Node Position Detection (LIN) |
| SRB | Sensor Replacement Board |
| SSC | Sensor Signal Conditioner |

| Term | Description |
|---------|-------------------------------|
| SSC-CB | SSC communication board |
| SSC-EB | SSC Evaluation Board ZSSC4132 |
| SSC-SRB | SSC Sensor Replacement Board |
| TC | Temperature Coefficient |
| TSC | Temperature Sensor Check |
| USB | Universal Serial Bus |

8. Ordering Information

| Orderable Part Number | Description |
|-----------------------|--|
| ZSSC4132KIT | ZSSC4132 SSC Evaluation Kit - including: SSC Communication Board, ZSSC4132 Evaluation Board, Sensor Replacement Board, ZSSC4132 Sample Board, USB Cable A-Male to B-Male, 5 sample ZSSC4132, tweezers |

9. Revision History

| Date | Description |
|-----------|------------------|
| Jun.3.20. | Initial release. |

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