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**Customer Notification** 

# QB-703425

In-Circuit-Emulator

**Operating Precautions** 

Target Device - V850E/Dx3

uPD70(F)3420/421/422/423/424/425<sup>TM</sup>

Global Document No. U18405EE1V0IF00 (1st edition) Document No. EEDT-OP-0029-1.0 Date Published February 2006

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## (A) Table of Operating Precautions

				QB-703425		
		CtrlCode	С			
		Date	07.02.06			
		HW Version IO	V2.11			
		FPGA Version	V3.00			
No.	Outline					
1	Ring OSC frequency is fixed to 200 kHz (Technical limitation)					
2	<ul> <li>Fout- and WDT-clock supply differ from device in stand by mode (Specification change notice)</li> </ul>					
3	PSM.OSCDIS reset value different to device (Specification change notice)					
4	Timing different to device for oscillation stabilisation time (Specification change notice)					
5	Break precaution related to ADC macro (Specification change notice)					

#### N: Not applicable

Y: Applicable

Note: The control code is the second letter from the left of the 10 digit serial number or in case of update the latest control code is mentioned on the version up sticker.

## (B) Description of Operating Precautions

No. 1	Ring OSC frequency is fixed to 200 kHz			
	<u>Details:</u> The Ring OSC frequency may differ from the device version to be emulated. <u>Workaround:</u> None			

No. 2	Fout- and WDT-clock supply differ from device in stand by mode			
	<u>Details:</u> In stand by mode, the FOUT clock supply (Ring-clock, if ROSTP=1 is set) will not stop. In stand by mode, the FOUT clock supply (Sub-clock, if SOSTP=1 is set) will not stop. In stand by mode, the WDT clock supply (Ring-clock, if ROSTP=1 is set) will not stop. In stand y mode, the WDT clock supply (Sub-clock, if SOSTP=1 is set) will not stop. <i>Workaround:</i> None.			

No. 3	PSM.OSCDIS reset value different to device
	<u>Details:</u> The reset value of the OSCDIS is '1'. On real chip OSCDIS is set to '0' during firmware execution.
	<u>Workaround:</u> Initialise the OSCDIS after RESET or use the functions of the Debugger to initialize the OSCDIS before program start.
No. 4	Timing different to device for oscillation stabilization time
	<u>Details:</u> The oscillation stabilization time indicated by OSCSTAT differ to real device. In emulation mode the oscillator run permanently, so the time for oscillation start is not given.

After reset, out of the different OSCDIS setting, the oscillation stabilization counter start is different.

<u>Workaround:</u> None

No. 5	Break precaution related to ADC macro				
	Details: [Explanation]				
	The following Behaviour is valid for the IECUBE emulator "only" in case the peripheral break mode is active for the ADC macro:				
	1.) In case the peripheral break signal (SVSTOP = 1) is set while or after the conversion control bit ADA0CE has been set, the AD conversion is not started and the concerned interrupt INTAD will not be generated. Furthermore the AD conversion will not start conversion even in case the Supervisor mode has been left and the debugger operates in RUN mode.				
	In case the ADA0CE bit will be set during normal RUN mode again without issuing the peripheral break signal, the ADC will operate as specified.				
	The conditions the peripheral break signal is issued are as follows:				
	a.) - When one of these break is executed on the AD0ACE bit write instruction Software break Before-execution hardware break After-execution hardware break				
	b.) - When one of these break is executed on the first instruction following the AD0ACE bit write instruction Software break Before-execution hardware break				
	c.) - When the following break is executed on the second instruction following the AD0ACE bit write instruction Software break				
	2.) In case the peripheral break mode (SVSTOP=1) has been configured and the debugger operates in the debug (supervisor-) mode, a write operation to the ADC concerned registers:				
	ADA0M0, (ADA0M1(#)), ADA0M2, ADA0S, ADA0PFT, ADAPFM (#) when ADA0CE=1, the re-write of ADA0M1 is prohibited and will not cause the start of the ADC's reconversion.				
	It doesn't make a difference if the concerned write operations to the above mentioned ADC registers are executed via the debugger itself or via DMA that is not stopped when entering the supervisor mode. Both write operations will cause the limitation.				

No. 5	Break precaution related to ADC macro (2nd page)			
	Workaround: [Restrictions]			
	a) When a software break is executed in case the peripheral break mode has been configured for the ADC macro, set the software break not for the instruction the ADA0CE bit is set or at one of the following two instructions:			
	Example:			
	set1 7, ADA0M0 software break is prohibited nop software break is prohibited nop software break is prohibited nop software break is possible to set from here on			
	b) When a "before-execution hardware break" is executed and the peripheral break mode has been configured for the ADC macro, don't set that breakpoint for the instruction that sets the ADA0CE bit or for the following instruction:			
	Example:			
	set1 7, ADA0M0 before-execution hardware break is prohibited nop before-execution hardware break is prohibited nop before-execution hardware break is possible to set from here on			
	c) When a "before-execution hardware break" is executed in peripheral break mode and the peripheral break mode has been configured for the ADC macro, don't set that breakpoint for the instruction that sets the ADA0CE bit:			
	Example:			
	set1 7, ADA0M0 after-execution hardware break is prohibited nop after-execution hardware break is possible to set from here on			
	d) When users want to proceed the write operation for the AD related registers during BREAK (debugger operates within the supervisor mode), don't use peripheral break mode.			
	e) When users want to proceed the DMA transfer which has AD related registers set as source/destination for this DMA transfer <<<, don't use peripheral break mode.			
Glo	Note: In case a condition mentioned under "Workarounds: a), b), c)" will occur when setting one of the concerned breakpoints on the location of an interrupt-vector, no limitation will become valid due to the clock-cycles that are requested for the interrupt-response time! al Document No. U18405EE1V0IF00 (1st edition)			

## (C) Valid Specification

ltem	Date published	Document No.	Document Title
1	February 2006	EEDT-OP-0029-1.0	This document
2	December 2005	U17678EE1V0UM00	Preliminary User's Manual

## (D) Revision History

ltem	Date published	Document No.	Comment
1	February 2006	EEDT-OP-0029-1.0	1st release