

Eight Output Differential Buffer for PCI-Express

Recommended Application:

DB800 Intel Yellow Cover part with PCI-Express support.

Output Features:

- 8 - 0.7V current-mode differential output pairs
- Supports zero delay buffer mode and fanout mode
- Bandwidth programming available

Key Specifications:

- Outputs cycle-cycle jitter < 50ps
- Outputs skew: 50ps
- +/- 300ppm frequency accuracy on output clocks

Features/Benefits:

- Supports tight ppm accuracy clocks for Serial-ATA
- Spread spectrum modulation tolerant, 0 to -0.5% down spread and +/- 0.25% center spread
- Supports undriven differential output pair in PD# and SRC_STOP# for power management.

Pin Configuration

| | | | |
|-------------|----|----|-----------|
| SRC_DIV# | 1 | 48 | VDDA |
| VDD | 2 | 47 | GNDA |
| GND | 3 | 46 | IREF |
| SRC_IN | 4 | 45 | LOCK |
| SRC_IN# | 5 | 44 | OE_7 |
| OE_0 | 6 | 43 | OE_4 |
| OE_3 | 7 | 42 | DIF_7 |
| DIF_0 | 8 | 41 | DIF_7# |
| DIF_0# | 9 | 40 | GND |
| GND | 10 | 39 | VDD |
| VDD | 11 | 38 | DIF_6 |
| DIF_1 | 12 | 37 | DIF_6# |
| DIF_1# | 13 | 36 | OE_6 |
| OE_1 | 14 | 35 | OE_5 |
| OE_2 | 15 | 34 | DIF_5 |
| DIF_2 | 16 | 33 | DIF_5# |
| DIF_2# | 17 | 32 | GND |
| GND | 18 | 31 | VDD |
| VDD | 19 | 30 | DIF_4 |
| DIF_3 | 20 | 29 | DIF_4# |
| DIF_3# | 21 | 28 | HIGH_BW# |
| BYPASS#/PLL | 22 | 27 | SRC_STOP# |
| SCLK | 23 | 26 | PD# |
| SDATA | 24 | 25 | GND |

48-pin SSOP & TSSOP

Pin Description

| PIN # | PIN NAME | PIN TYPE | DESCRIPTION |
|-------|-------------|----------|--|
| 1 | SRC_DIV# | IN | Active low Input for determining SRC output frequency SRC or SRC/2. 0 = SRC/2, 1= SRC |
| 2 | VDD | PWR | Power supply, nominal 3.3V |
| 3 | GND | PWR | Ground pin. |
| 4 | SRC_IN | IN | 0.7 V Differential SRC TRUE input |
| 5 | SRC_IN# | IN | 0.7 V Differential SRC COMPLEMENTARY input |
| 6 | OE_0 | IN | Active high input for enabling outputs. 0 = tri-state outputs, 1= enable outputs |
| 7 | OE_3 | IN | Active high input for enabling outputs. 0 = tri-state outputs, 1= enable outputs |
| 8 | DIF_0 | OUT | 0.7V differential true clock outputs |
| 9 | DIF_0# | OUT | 0.7V differential complement clock outputs |
| 10 | GND | PWR | Ground pin. |
| 11 | VDD | PWR | Power supply, nominal 3.3V |
| 12 | DIF_1 | OUT | 0.7V differential true clock outputs |
| 13 | DIF_1# | OUT | 0.7V differential complement clock outputs |
| 14 | OE_1 | IN | Active high input for enabling outputs. 0 = tri-state outputs, 1= enable outputs |
| 15 | OE_2 | IN | Active high input for enabling outputs. 0 = tri-state outputs, 1= enable outputs |
| 16 | DIF_2 | OUT | 0.7V differential true clock outputs |
| 17 | DIF_2# | OUT | 0.7V differential complement clock outputs |
| 18 | GND | PWR | Ground pin. |
| 19 | VDD | PWR | Power supply, nominal 3.3V |
| 20 | DIF_3 | OUT | 0.7V differential true clock outputs |
| 21 | DIF_3# | OUT | 0.7V differential complement clock outputs |
| 22 | BYPASS#/PLL | IN | Input to select Bypass(fan-out) or PLL (ZDB) mode 0 = Bypass mode, 1= PLL mode |
| 23 | SCLK | IN | Clock pin of SMBus circuitry, 5V tolerant. |
| 24 | SDATA | I/O | Data pin for SMBus circuitry, 5V tolerant. |

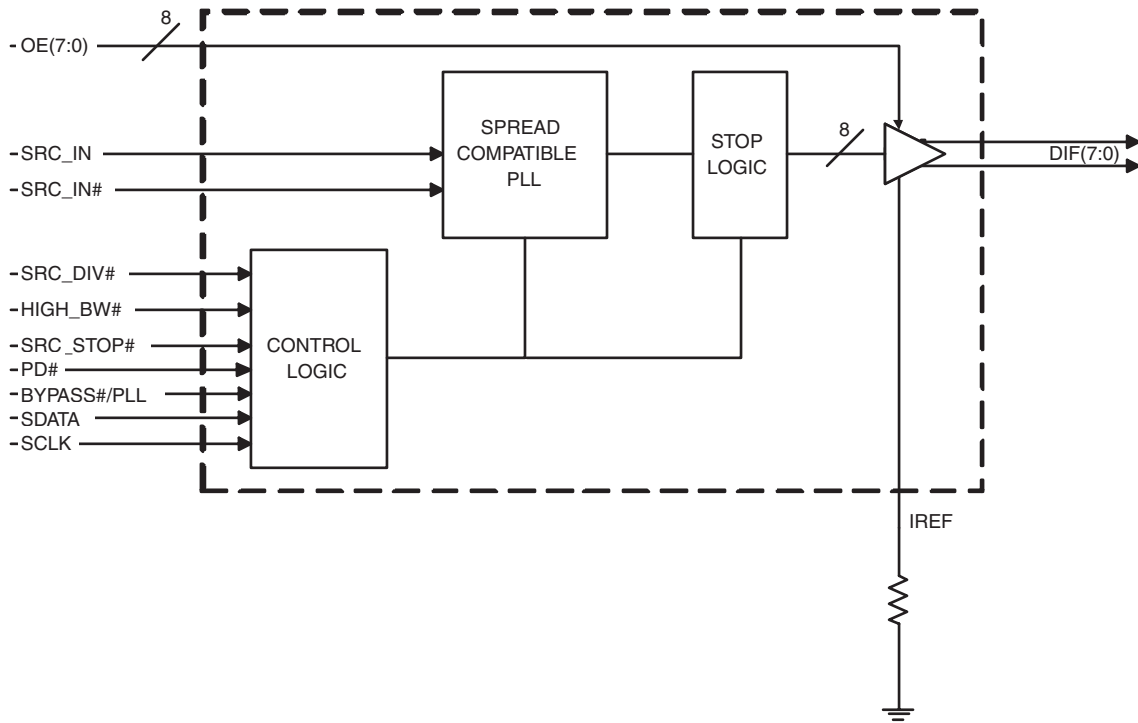
Pin Description (Continued)

| PIN # | PIN NAME | PIN TYPE | DESCRIPTION |
|-------|-----------|----------|---|
| 25 | GND | PWR | Ground pin. |
| 26 | PD# | IN | Asynchronous active low input pin used to power down the device. The internal clocks are disabled and the VCO and the crystal are stopped. |
| 27 | SRC_STOP# | IN | Active low input to stop diff outputs. |
| 28 | HIGH_BW# | PWR | 3.3V input for selecting PLL Band Width 0 = High, 1= Low |
| 29 | DIF_4# | OUT | 0.7V differential complement clock outputs |
| 30 | DIF_4 | OUT | 0.7V differential true clock outputs |
| 31 | VDD | PWR | Power supply, nominal 3.3V |
| 32 | GND | PWR | Ground pin. |
| 33 | DIF_5# | OUT | 0.7V differential complement clock outputs |
| 34 | DIF_5 | OUT | 0.7V differential true clock outputs |
| 35 | OE_5 | IN | Active high input for enabling outputs. 0 = tri-state outputs, 1= enable outputs |
| 36 | OE_6 | IN | Active high input for enabling outputs. 0 = tri-state outputs, 1= enable outputs |
| 37 | DIF_6# | OUT | 0.7V differential complement clock outputs |
| 38 | DIF_6 | OUT | 0.7V differential true clock outputs |
| 39 | VDD | PWR | Power supply, nominal 3.3V |
| 40 | GND | PWR | Ground pin. |
| 41 | DIF_7# | OUT | 0.7V differential complement clock outputs |
| 42 | DIF_7 | OUT | 0.7V differential true clock outputs |
| 43 | OE_4 | IN | Active high input for enabling outputs. 0 = tri-state outputs, 1= enable outputs |
| 44 | OE_7 | IN | Active high input for enabling outputs. 0 = tri-state outputs, 1= enable outputs |
| 45 | LOCK | OUT | 3.3V output indicating PLL Lock Status. This pin goes high when lock is achieved. |
| 46 | IREF | IN | This pin establishes the reference current for the differential current-mode output pairs. This pin requires a fixed precision resistor tied to ground in order to establish the appropriate current. 475 ohms is the standard value. |
| 47 | GNDA | PWR | Ground pin for the PLL core. |
| 48 | VDDA | PWR | 3.3V power for the PLL core. |

General Description

ICS9DB108 follows the Intel DB400 Differential Buffer Specification. This buffer provides four SRC clocks for PCI-Express, next generation I/O devices. **ICS9DB108** is driven by a differential input pair from a CK409/CK410 main clock generator, such as the ICS952601 or ICS954101. **ICS9DB108** can run at speeds up to 200MHz. It provides outputs meeting tight cycle-to-cycle jitter (50ps) and output-to-output skew (50ps) requirements.

Block Diagram



Absolute Max

| Symbol | Parameter | Min | Max | Units |
|----------------------|---------------------------------------|---------|-----------------------|-------|
| VDD_A | 3.3V Core Supply Voltage | | 4.6 | V |
| VDD_In | 3.3V Logic Supply Voltage | | 4.6 | V |
| V _{IL} | Input Low Voltage | GND-0.5 | | V |
| V _{IH} | Input High Voltage | | V _{DD} +0.5V | V |
| T _s | Storage Temperature | -65 | 150 | °C |
| T _{ambient} | Ambient Operating Temp | 0 | 70 | °C |
| T _{case} | Case Temperature | | 115 | °C |
| ESD prot | Input ESD protection human body model | 2000 | | V |

Electrical Characteristics - Input/Supply/Common Output Parameters

T_A = 0 - 70°C; Supply Voltage V_{DD} = 3.3 V +/-5%

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS | NOTES |
|----------------------------------|----------------------|---|-----------|--------------------|-----------------------|-------|-------|
| Input High Voltage | V _{IH} | 3.3 V +/-5% | 2 | | V _{DD} + 0.3 | V | |
| Input Low Voltage | V _{IL} | 3.3 V +/-5% | GND - 0.3 | | 0.8 | V | |
| Input High Current | I _{IH} | V _{IN} = V _{DD} | -5 | | 5 | uA | |
| Input Low Current | I _{IL1} | V _{IN} = 0 V; Inputs with no pull-up resistors | -5 | | | uA | |
| | I _{IL2} | V _{IN} = 0 V; Inputs with pull-up resistors | -200 | | | uA | |
| Operating Supply Current | I _{DD3.3OP} | Full Active, C _L = Full load; | | | 250 | mA | |
| Powerdown Current | I _{DD3.3PD} | all diff pairs driven | | | 60 | mA | |
| | | all differential pairs tri-stated | | | 12 | mA | |
| Input Frequency ³ | F _i | V _{DD} = 3.3 V | 80 | 100/133 166/200 | 220 | MHz | 3 |
| Pin Inductance ¹ | L _{pin} | | | | 7 | nH | 1 |
| Input Capacitance ¹ | C _{IN} | Logic Inputs | 1.5 | | 5 | pF | 1 |
| | C _{OUT} | Output pin capacitance | | | 6 | pF | 1 |
| PLL Bandwidth | BW | PLL Bandwidth when PLL_BW=0 | | 4 | | MHz | 1 |
| | | PLL Bandwidth when PLL_BW=1 | | 2 | | MHz | 1 |
| Clk Stabilization ^{1,2} | T _{STAB} | From V _{DD} Power-Up and after input clock stabilization or de-assertion of PD# to 1st clock | | | 1 | ms | 1,2 |
| Modulation Frequency | | Triangular Modulation | 30 | | 33 | kHz | 1 |
| Tdrive_SRC_STOP# | | DIF output enable after SRC_Stop# de-assertion | | | 10 | ns | 1,3 |
| Tdrive_PD# | | DIF output enable after PD# de-assertion | | | 300 | us | 1,3 |
| Tfall | | Fall time of PD# and SRC_STOP# | | | 5 | ns | 1 |
| Trise | | Rise time of PD# and SRC_STOP# | | | 5 | ns | 2 |

¹Guaranteed by design and characterization, not 100% tested in production.

²See timing diagrams for timing requirements.

³Time from deassertion until outputs are >200 mV

Electrical Characteristics - DIF 0.7V Current Mode Differential Pair

$T_A = 0 - 70^\circ\text{C}$; $V_{DD} = 3.3\text{ V} \pm 5\%$; $C_L = 2\text{pF}$, $R_S = 33.2\Omega$, $R_P = 49.9\Omega$, $I_{REF} = 475\mu\text{A}$

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS | NOTES |
|---------------------------------|---------------|--|--------|-----|---------|----------|-------|
| Current Source Output Impedance | Z_o^1 | $V_O = V_x$ | 3000 | | | Ω | 1 |
| Voltage High | VHigh | Statistical measurement on single ended signal using oscilloscope math function. | 660 | | 850 | mV | 1,3 |
| Voltage Low | VLow | | -150 | | 150 | | 1,3 |
| Max Voltage | Vovs | Measurement on single ended signal using absolute value. | | | 1150 | mV | 1 |
| Min Voltage | Vuds | | -300 | | | | 1 |
| Crossing Voltage (abs) | Vcross(abs) | | 250 | | 550 | mV | 1 |
| Crossing Voltage (var) | d-Vcross | Variation of crossing over all edges | | | 140 | mV | 1 |
| Long Accuracy | ppm | see Tperiod min-max values | | | 0 | ppm | 1,2 |
| Average period | Tperiod | 200MHz nominal | 4.9985 | | 5.0015 | ns | 2 |
| | | 200MHz spread | 4.9985 | | 5.0266 | ns | 2 |
| | | 166.66MHz nominal | 5.9982 | | 6.0018 | ns | 2 |
| | | 166.66MHz spread | 5.9982 | | 6.0320 | ns | 2 |
| | | 133.33MHz nominal | 7.4978 | | 7.5023 | ns | 2 |
| | | 133.33MHz spread | 7.4978 | | 5.4000 | ns | 2 |
| | | 100.00MHz nominal | 9.9970 | | 10.0030 | ns | 2 |
| | | 100.00MHz spread | 9.9970 | | 10.0533 | ns | 2 |
| Absolute min period | T_{absmin} | 200MHz nominal | 4.8735 | | | ns | 1,2 |
| | | 166.66MHz nominal/spread | 5.8732 | | | ns | 1,2 |
| | | 133.33MHz nominal/spread | 7.3728 | | | ns | 1,2 |
| | | 100.00MHz nominal/spread | 9.8720 | | | ns | 1,2 |
| Rise Time | t_r | $V_{OL} = 0.175\text{V}$, $V_{OH} = 0.525\text{V}$ | 175 | | 700 | ps | 1 |
| Fall Time | t_f | $V_{OH} = 0.525\text{V}$, $V_{OL} = 0.175\text{V}$ | 175 | | 700 | ps | 1 |
| Rise Time Variation | $d-t_r$ | | | | 125 | ps | 1 |
| Fall Time Variation | $d-t_f$ | | | | 125 | ps | 1 |
| Duty Cycle | d_{t3} | Measurement from differential waveform | 45 | | 55 | % | 1 |
| Skew | t_{sk3} | $V_T = 50\%$ | | | 50 | ps | 1 |
| Jitter, Cycle to cycle | $t_{jyc-cyc}$ | PLL mode, Measurement from differential waveform | | | 50 | ps | 1 |
| | | BYPASS mode as additive jitter | | | 50 | ps | 1 |

¹Guaranteed by design and characterization, not 100% tested in production.

²All Long Term Accuracy and Clock Period specifications are guaranteed with the assumption that the input clock complies with CK409/CK410 accuracy requirements

³ $I_{REF} = V_{DD}/(3 \times R_R)$. For $R_R = 475\Omega$ (1%), $I_{REF} = 2.32\text{mA}$. $I_{OH} = 6 \times I_{REF}$ and $V_{OH} = 0.7\text{V}$ @ $Z_O = 50\Omega$.

General SMBus serial interface information for the ICS9DB108

How to Write:

- Controller (host) sends a start bit.
- Controller (host) sends the write address $DC_{(h)}$
- ICS clock will **acknowledge**
- Controller (host) sends the beginning byte location = N
- ICS clock will **acknowledge**
- Controller (host) sends the data byte count = X
- ICS clock will **acknowledge**
- Controller (host) starts sending **Byte N through Byte N + X - 1**
- ICS clock will **acknowledge** each byte **one at a time**
- Controller (host) sends a Stop bit

How to Read:

- Controller (host) will send start bit.
- Controller (host) sends the write address $DC_{(h)}$
- ICS clock will **acknowledge**
- Controller (host) sends the beginning byte location = N
- ICS clock will **acknowledge**
- Controller (host) will send a separate start bit.
- Controller (host) sends the read address $DD_{(h)}$
- ICS clock will **acknowledge**
- ICS clock will send the data byte count = X
- ICS clock sends **Byte N + X - 1**
- ICS clock sends **Byte 0 through byte X (if $X_{(h)}$ was written to byte 8).**
- Controller (host) will need to acknowledge each byte
- Controller (host) will send a not acknowledge bit
- Controller (host) will send a stop bit

| Index Block Write Operation | | | |
|-----------------------------|-----------|----------------------|-----|
| Controller (Host) | | ICS (Slave/Receiver) | |
| T | starT bit | | |
| Slave Address $DC_{(h)}$ | | | |
| WR | WRite | | |
| | | ACK | |
| Beginning Byte = N | | | |
| | | ACK | |
| Data Byte Count = X | | | |
| | | ACK | |
| Beginning Byte N | | X Byte | |
| | | | ACK |
| ◊ | | | ◊ |
| ◊ | | | ◊ |
| ◊ | | | ◊ |
| Byte N + X - 1 | | ACK | |
| P | stoP bit | | |

| Index Block Read Operation | | | |
|----------------------------|-----------------|----------------------|------------------|
| Controller (Host) | | ICS (Slave/Receiver) | |
| T | starT bit | | |
| Slave Address $DC_{(h)}$ | | | |
| WR | WRite | | |
| | | ACK | |
| Beginning Byte = N | | | |
| | | ACK | |
| RT | Repeat starT | | |
| Slave Address $DD_{(h)}$ | | | |
| RD | ReaD | | |
| | | ACK | |
| | | Data Byte Count = X | |
| ACK | | X Byte | |
| ACK | | | Beginning Byte N |
| ◊ | | | ◊ |
| ◊ | | | ◊ |
| ◊ | | | ◊ |
| | | Byte N + X - 1 | |
| N | Not acknowledge | | |
| P | stoP bit | | |

SMBus Table: Frequency Select Register, READ/WRITE ADDRESS (DC/DD)

| Byte 0 | Pin # | Name | Control Function | Type | 0 | 1 | PWD |
|--------|-------|-------------|------------------|------|----------|--------|-----|
| Bit 7 | - | PD# | drive mode | RW | driven | Hi-Z | 0 |
| Bit 6 | - | SRC_Stop# | drive mode | RW | driven | Hi-Z | 0 |
| Bit 5 | - | Reserved | | RW | Reserved | | X |
| Bit 4 | - | Reserved | | RW | Reserved | | X |
| Bit 3 | - | Reserved | | RW | Reserved | | X |
| Bit 2 | - | PLL_BW# | adjust | RW | High BW | Low BW | 1 |
| Bit 1 | - | BYPASS#/PLL | | RW | fan-out | ZDB | 1 |
| Bit 0 | - | SRC_DIV# | | RW | x/2 | 1x | 1 |

SMBus Table: Output Control Register

| Byte 1 | Pin # | Name | Control Function | Type | 0 | 1 | PWD |
|--------|-------|-------|------------------|------|---------|--------|-----|
| Bit 7 | 42,41 | DIF_7 | Output Control | RW | Disable | Enable | 1 |
| Bit 6 | 38,37 | DIF_6 | Output Control | RW | Disable | Enable | 1 |
| Bit 5 | 34,33 | DIF_5 | Output Control | RW | Disable | Enable | 1 |
| Bit 4 | 30,29 | DIF_4 | Output Control | RW | Disable | Enable | 1 |
| Bit 3 | 20,21 | DIF_3 | Output Control | RW | Disable | Enable | 1 |
| Bit 2 | 16,17 | DIF_2 | Output Control | RW | Disable | Enable | 1 |
| Bit 1 | 12,13 | DIF_1 | Output Control | RW | Disable | Enable | 1 |
| Bit 0 | 8,9 | DIF_0 | Output Control | RW | Disable | Enable | 1 |

SMBus Table: Output Control Register

| Byte 2 | Pin # | Name | Control Function | Type | 0 | 1 | PWD |
|--------|-------|-------|------------------|------|----------|-----------|-----|
| Bit 7 | 42,41 | DIF_7 | Output Control | RW | Reserved | | 0 |
| Bit 6 | 38,37 | DIF_6 | Output Control | RW | Free-run | Stoppable | 0 |
| Bit 5 | 34,33 | DIF_5 | Output Control | RW | Free-run | Stoppable | 0 |
| Bit 4 | 30,29 | DIF_4 | Output Control | RW | Reserved | | 0 |
| Bit 3 | 20,21 | DIF_3 | Output Control | RW | Reserved | | 0 |
| Bit 2 | 16,17 | DIF_2 | Output Control | RW | Free-run | Stoppable | 0 |
| Bit 1 | 12,13 | DIF_1 | Output Control | RW | Free-run | Stoppable | 0 |
| Bit 0 | 8,9 | DIF_0 | Output Control | RW | Reserved | | 0 |

SMBus Table: Output Control Register

| Byte 3 | Pin # | Name | Control Function | Type | 0 | 1 | PWD |
|--------|-------|------|------------------|------|----------|---|-----|
| Bit 7 | | | Reserved | RW | Reserved | | X |
| Bit 6 | | | Reserved | RW | Reserved | | X |
| Bit 5 | | | Reserved | RW | Reserved | | X |
| Bit 4 | | | Reserved | RW | Reserved | | X |
| Bit 3 | | | Reserved | RW | Reserved | | X |
| Bit 2 | | | Reserved | RW | Reserved | | X |
| Bit 1 | | | Reserved | RW | Reserved | | X |
| Bit 0 | | | Reserved | RW | Reserved | | X |

SMBus Table: Vendor & Revision ID Register

| Byte 4 | Pin # | Name | Control Function | Type | 0 | 1 | PWD |
|--------|-------|------|------------------|------|---|---|-----|
| Bit 7 | - | RID3 | REVISION ID | R | - | - | 0 |
| Bit 6 | - | RID2 | | R | - | - | 0 |
| Bit 5 | - | RID1 | | R | - | - | 0 |
| Bit 4 | - | RID0 | | R | - | - | 1 |
| Bit 3 | - | VID3 | VENDOR ID | R | - | - | 0 |
| Bit 2 | - | VID2 | | R | - | - | 0 |
| Bit 1 | - | VID1 | | R | - | - | 0 |
| Bit 0 | - | VID0 | | R | - | - | 1 |

SMBus Table: DEVICE ID

| Byte 5 | | Pin # | Name | Control Function | Type | 0 | 1 | PWD |
|--------|---|-------|-------------------|------------------|------|----------|---|-----|
| Bit 7 | - | | Device ID 7 (MSB) | | RW | Reserved | | 0 |
| Bit 6 | - | | Device ID 6 | | RW | Reserved | | 0 |
| Bit 5 | - | | Device ID 5 | | RW | Reserved | | 0 |
| Bit 4 | - | | Device ID 4 | | RW | Reserved | | 0 |
| Bit 3 | - | | Device ID 3 | | RW | Reserved | | 1 |
| Bit 2 | - | | Device ID 2 | | RW | Reserved | | 0 |
| Bit 1 | - | | Device ID 1 | | RW | Reserved | | 0 |
| Bit 0 | - | | Device ID 0 | | RW | Reserved | | 0 |

SMBus Table: Byte Count Register

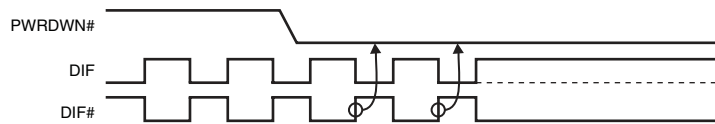
| Byte 6 | | Pin # | Name | Control Function | Type | 0 | 1 | PWD |
|--------|---|-------|------|---|------|---|---|-----|
| Bit 7 | - | | BC7 | Writing to this register configures how many bytes will be read back. | RW | - | - | 0 |
| Bit 6 | - | | BC6 | | RW | - | - | 0 |
| Bit 5 | - | | BC5 | | RW | - | - | 0 |
| Bit 4 | - | | BC4 | | RW | - | - | 0 |
| Bit 3 | - | | BC3 | | RW | - | - | 0 |
| Bit 2 | - | | BC2 | | RW | - | - | 1 |
| Bit 1 | - | | BC1 | | RW | - | - | 0 |
| Bit 0 | - | | BC0 | | RW | - | - | 1 |

PD#, Power Down

The PD# pin cleanly shuts off all clocks and places the device into a power saving mode. PD# must be asserted before shutting off the input clock or power to insure an orderly shutdown. PD is asynchronous active-low input for both powering down the device and powering up the device. When PD# is asserted, all clocks will be driven high, or tri-stated (depending on the PD# drive mode and Output control bits) before the PLL is shut down.

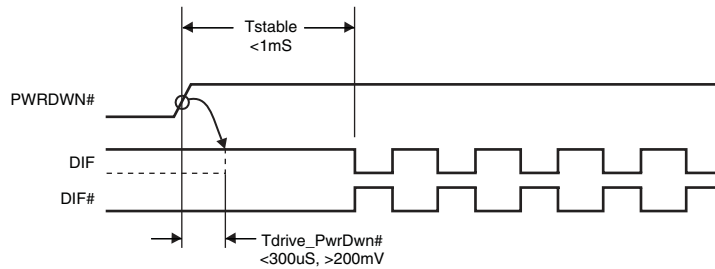
PD# Assertion

When PD# is sampled low by two consecutive rising edges of DIF#, all DIF outputs must be held High, or tri-stated (depending on the PD# drive mode and Output control bits) on the next High-Low transition of the DIF# outputs. When the PD# drive mode bit is set to '0', all clock outputs will be held with DIF driven High with $2 \times I_{REF}$ and DIF# tri-stated. If the PD# drive mode bit is set to '1', both DIF and DIF# are tri-stated.



PD# De-assertion

Power-up latency is less than 1 ms. This is the time from de-assertion of the PD# pin, or VDD reaching 3.3V, or the time from valid SRC_IN clocks until the time that stable clocks are output from the device (PLL Locked). If the PD# drive mode bit is set to '1', all the DIF outputs must driven to a voltage of >200 mV within 300 ms of PD# de-assertion.



SRC_STOP#

The SRC_STOP# signal is an active-low asynchronous input that cleanly stops and starts the DIF outputs. A valid clock must be present on SRC_IN for this input to work properly. The SRC_STOP# signal is de-bounced and must remain stable for two consecutive rising edges of DIF# to be recognized as a valid assertion or de-assertion.

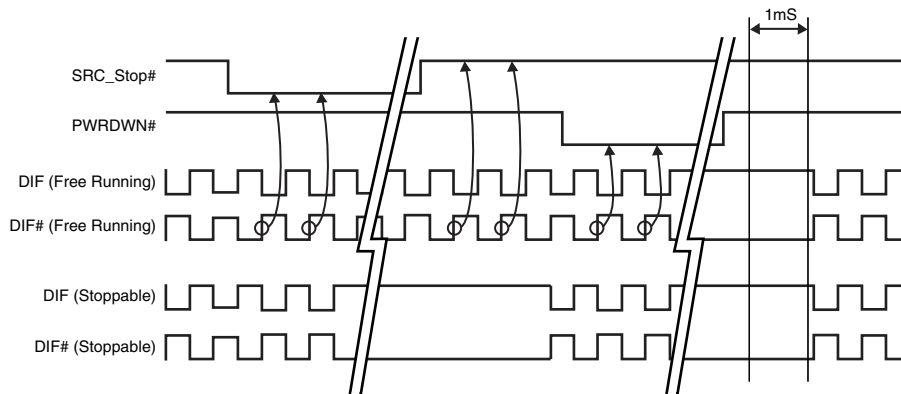
SRC_STOP# - Assertion

Asserting SRC_STOP# causes all DIF outputs to stop after their next transition (if the control register settings allow the output to stop). When the SRC_STOP# drive bit is '0', the final state of all stopped DIF outputs is DIF = High and DIF# = Low. There is no change in output drive current. DIF is driven with $6 \times I_{REF}$. DIF# is not driven, but pulled low by the termination. When the SRC_STOP# drive bit is '1', the final state of all DIF output pins is Low. Both DIF and DIF# are not driven.

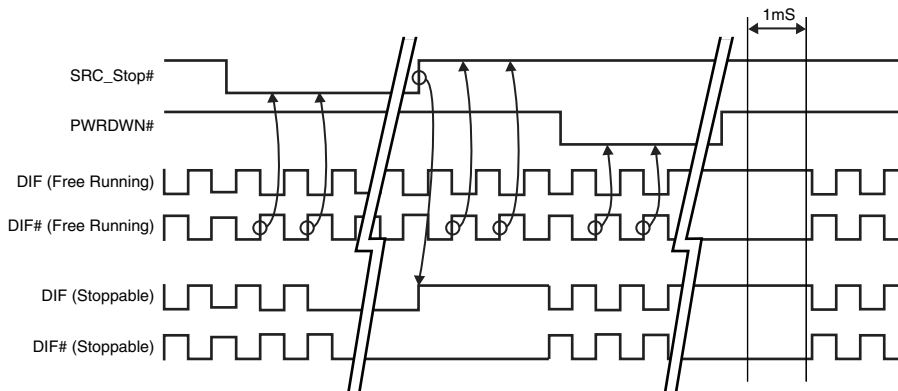
SRC_STOP# - De-assertion (transition from '0' to '1')

All stopped differential outputs resume normal operation in a glitch-free manner. The de-assertion latency to active outputs is 2-6 DIF clock periods, with all DIF outputs resuming simultaneously. If the SRC_STOP# drive control bit is '1' (tri-state), all stopped DIF outputs must be driven High (>200 mV) within 10 ns of de-assertion.

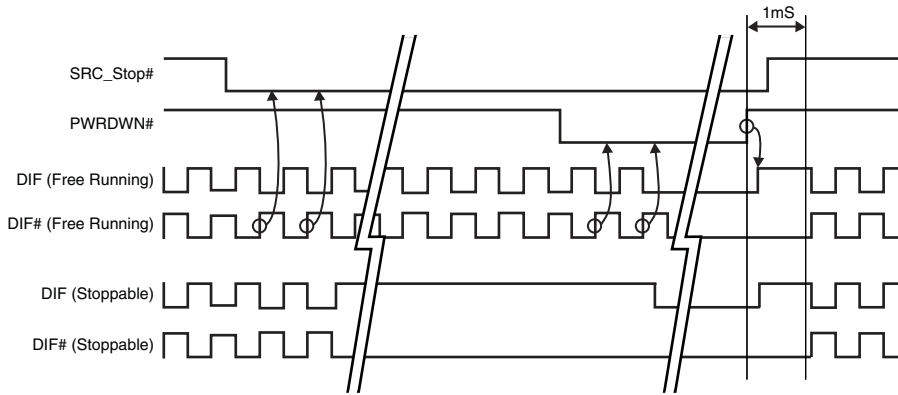
SRC_STOP_1 (SRC_Stop = Driven, PD = Driven)



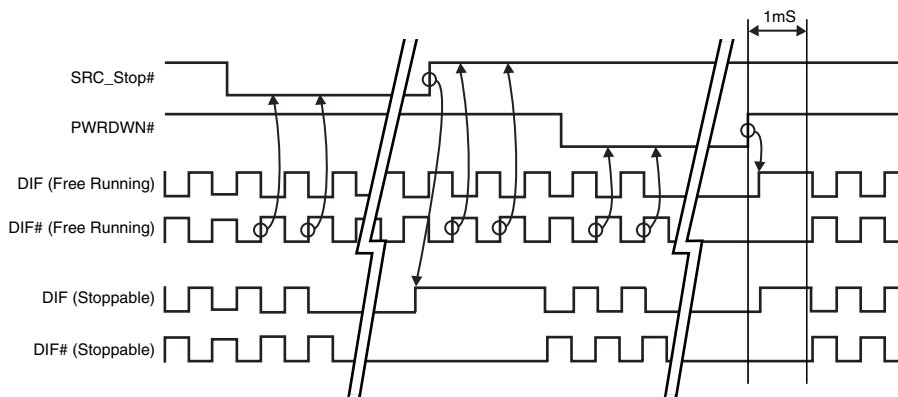
SRC_STOP_2 (SRC_Stop = Tristate, PD = Driven)

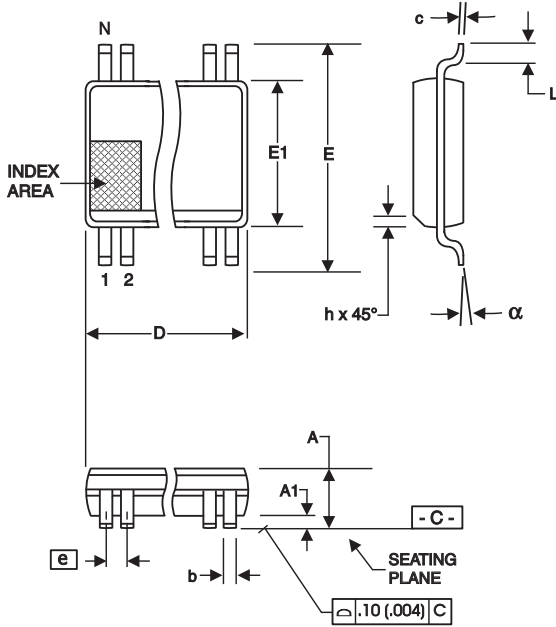


SRC_STOP_3 (SRC_Stop = Driven, PD = Tristate)



SRC_STOP_4 (SRC_Stop = Tristate, PD = Tristate)





| SYMBOL | In Millimeters COMMON DIMENSIONS | | In Inches COMMON DIMENSIONS | |
|--------|-------------------------------------|-------|--------------------------------|-------|
| | MIN | MAX | MIN | MAX |
| A | 2.41 | 2.80 | .095 | .110 |
| A1 | 0.20 | 0.40 | .008 | .016 |
| b | 0.20 | 0.34 | .008 | .0135 |
| c | 0.13 | 0.25 | .005 | .010 |
| D | SEE VARIATIONS | | SEE VARIATIONS | |
| E | 10.03 | 10.68 | .395 | .420 |
| E1 | 7.40 | 7.60 | .291 | .299 |
| e | 0.635 BASIC | | 0.025 BASIC | |
| h | 0.38 | 0.64 | .015 | .025 |
| L | 0.50 | 1.02 | .020 | .040 |
| N | SEE VARIATIONS | | SEE VARIATIONS | |
| alpha | 0° | 8° | 0° | 8° |

VARIATIONS

| N | D mm. | | D (inch) | |
|----|-------|-------|----------|------|
| | MIN | MAX | MIN | MAX |
| 48 | 15.75 | 16.00 | .620 | .630 |

Reference Doc.: JEDEC Publication 95, MO-118

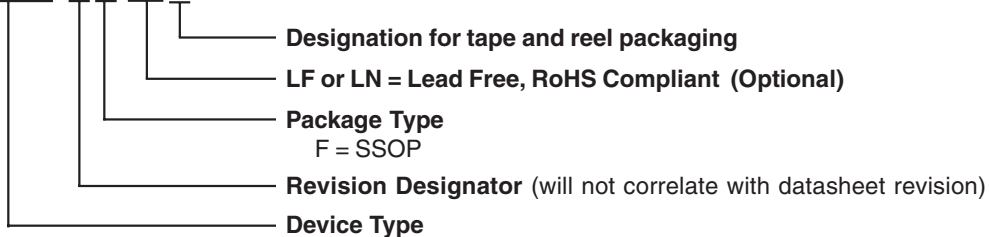
10-0034

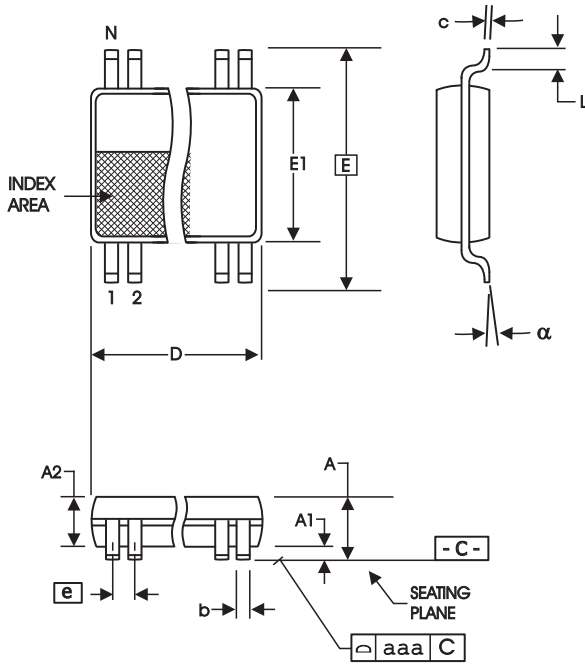
Ordering Information

9DB108yFLxT

Example:

XXXX **y** **F** **Lx** **T**





48-Lead, 6.10 mm. Body, 0.50 mm. Pitch TSSOP
(240 mil) (20 mil)

| SYMBOL | In Millimeters COMMON DIMENSIONS | | In Inches COMMON DIMENSIONS | |
|--------|-------------------------------------|------|--------------------------------|------|
| | MIN | MAX | MIN | MAX |
| A | -- | 1.20 | -- | .047 |
| A1 | 0.05 | 0.15 | .002 | .006 |
| A2 | 0.80 | 1.05 | .032 | .041 |
| b | 0.17 | 0.27 | .007 | .011 |
| c | 0.09 | 0.20 | .0035 | .008 |
| D | SEE VARIATIONS | | SEE VARIATIONS | |
| E | 8.10 BASIC | | 0.319 BASIC | |
| E1 | 6.00 | 6.20 | .236 | .244 |
| e | 0.50 BASIC | | 0.020 BASIC | |
| L | 0.45 | 0.75 | .018 | .030 |
| N | SEE VARIATIONS | | SEE VARIATIONS | |
| a | 0° | 8° | 0° | 8° |
| aaa | -- | 0.10 | -- | .004 |

VARIATIONS

| N | D mm. | | D (inch) | |
|----|-------|-------|----------|------|
| | MIN | MAX | MIN | MAX |
| 48 | 12.40 | 12.60 | .488 | .496 |

Reference Doc.: JEDEC Publication 95, MO-153

10-0039

Ordering Information

9DB108yGLxT

Example:

XXXX y G Lx T

- Designation for tape and reel packaging
- LF or LN = Lead Free, RoHS Compliant (Optional)
- Package Type
G = TSSOP
- Revision Designator (will not correlate with datasheet revision)
- Device Type (consists of 3 to 7 digit numbers)

Revision History

| Rev. | Issue Date | Description | Page # |
|------|------------|--|--------|
| E | 10/26/2005 | Updated LF Ordering Information to LF or LN. | 14, 15 |
| F | 12/17/2000 | Updated SMBus Serial Interface Information. | 7 |
| G | 12/2/2008 | removed lcs prefix from ordering information | 14-15 |
| | | | |

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