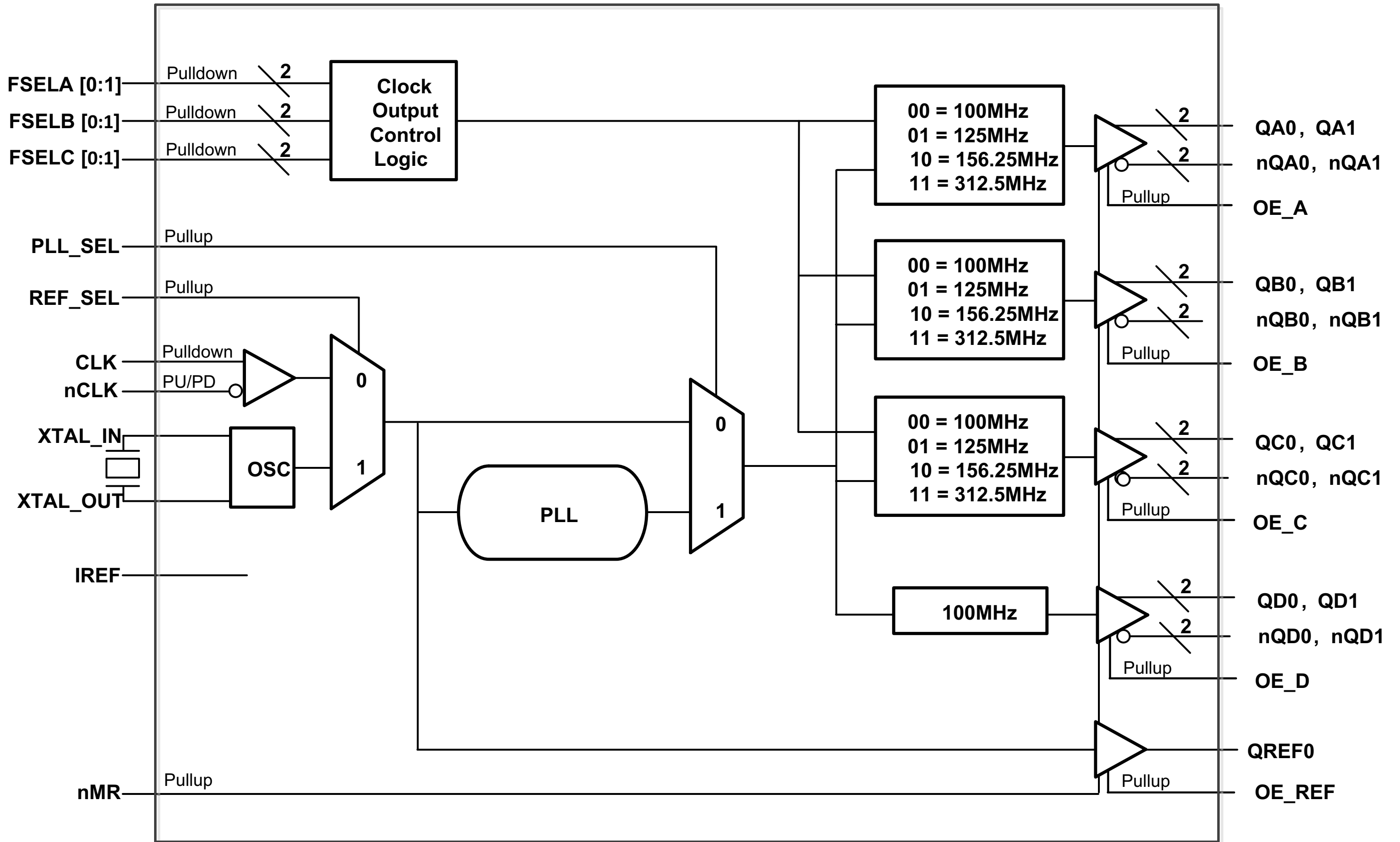
Block Diagram



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Pin Descriptions and Pin Characteristics

Table 1. Pin Descriptions

Number	Name	Type		Description
1, 12, 23	GND	Power		Power supply ground.
2, 3	FSEL_A0. FSEL_A1	Input	Pulldown	Selects the QAx, nQAx output frequency. See Table 3A. LVCMOS/LVTTL interface levels.
4, 5	FSEL_B0, FSEL_B1	Input	Pulldown	Selects the QBx, nQBx output frequency. See Table 3A. LVCMOS/LVTTL interface levels.
6, 7	FSEL_C0, FSEL_C1	Input	Pulldown	Selects the QCx, nQCx output frequency. See Table 3A. LVCMOS/LVTTL interface levels.
8	V_{DDA}	Power		Analog supply pin.
9, 10	XTAL_IN, XTAL_OUT	Input		Parallel resonant crystal interface. XTAL_OUT is the output, XTAL_IN is the input.
11	REF_SEL	Input	Pullup	Input source control pin. See Table 3C. LVCMOS/LVTTL interface levels.
13, 24, 38	V_{DD}	Power		Core supply pins.
14	PLL_SEL	Input	Pullup	PLL bypass control pin. See Table 3B. LVCMOS/LVTTL interface levels.
15	CLK	Input	Pulldown	Non-inverting differential clock input.
16	nCLK	Input	Pullup/ Pulldown	Inverting differential clock input. Internal resistor bias to $V_{DD}/2$.
17	OE_A	Input	Pullup	Active HIGH output enable for Bank A outputs. See Table 3D. LVCMOS/LVTTL interface levels.
18	V_{DDO_A}	Power		Bank A (HCSL) output supply pin. 3.3 V supply.
19, 20	QA0, nQA0	Output		Differential output pair. HCSL interface levels.
21, 22	QA1, nQA1	Output		Differential output pair. HCSL interface levels.
25	OE_B	Input	Pullup	Active HIGH output enable for Bank B outputs. See Table 3D. LVCMOS/LVTTL interface levels.
26, 27	QB0, nQB0	Output		Differential output pair. HCSL interface levels.
28, 29	QB1, nQB1	Output		Differential output pair. HCSL interface levels.
30	V_{DDO_B}	Power		Bank B (HCSL) output supply pin. 3.3V supply.
31	V_{DDO_C}	Power		Bank C (HCSL) output and HCSL reference circuit supply pin. Must be connected to 3.3V to use any of the HCSL outputs.
32, 33	QC0, nQC0	Output		Differential output pair. HCSL interface levels.
34, 35	QC1, nQC1	Output		Differential output pair. HCSL interface levels.
36	OE_C	Input	Pullup	Active HIGH output enable for Bank C outputs. See Table 3D. LVCMOS/LVTTL interface levels.
37	I_{REF}	Input		External fixed precision resistor (475Ω) from this pin to ground provides a reference current used for differential current-mode QAx:QDx, nQAx:Dx outputs.
39	V_{DDO_D}	Power		Bank D (HCSL) output supply pin. 3.3V supply.
40, 41	QD0, nQD0	Output		Differential output pair. HCSL interface levels.
42, 43	QD1, nQD1	Output		Differential output pair. HCSL interface levels.
44	OE_D	Input	Pullup	Active HIGH output enable for Bank D outputs. See Table 3D. LVCMOS/LVTTL interface levels.

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Absolute Maximum Ratings

NOTE: Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These ratings are stress specifications only. Functional operation of product at these conditions or any conditions beyond those listed in the *DC Characteristics or AC Characteristics* is not implied. Exposure to absolute maximum rating conditions for extended periods may affect product reliability.

Item	Rating
Supply Voltage, V_{DD}	4.6V
Inputs, V_I XTAL_IN Other Inputs	 0V to V_{DD} -0.5V to V_{DD} + 0.5V
Outputs, V_O (LVCMOS, HCSL)	-0.5V to V_{DDO_X} + 0.5V
Package Thermal Impedance, θ_{JA}	30.5°C/W (0 mps)
Storage Temperature, T_{STG}	-65°C to 150°C

DC Electrical Characteristics

Table 4A. Power Supply DC Characteristics, $V_{DD} = V_{DDO_X}$ = 3.3V ± 5%, T_A = -40°C to 85°C

Symbol	Parameter	Test Conditions	Minimum	Typical	Maximum	Units
V_{DD}	Core Supply Voltage		3.135	3.3	3.465	V
V_{DDA}	Analog Supply Voltage		V_{DD} – 0.16	3.3	V_{DD}	V
V_{DDO_X}	Output Supply Voltage		3.135	3.3	3.465	V
I_{DD}	Power Supply Current				85	mA
I_{DDA}	Analog Supply Current				16	mA
I_{DDO_X}	HCSL Output Supply Current	No Load, CLK selected			17	mA
I_{DDO_QREF}	LVCMOS Output Supply Current	No Load, CLK selected			8	mA

NOTE: V_{DDO_X} denotes $V_{DDO_[A:D}$, V_{DDO_QREF}.
NOTE: I_{DDO_X} denotes $I_{DDO_A} + I_{DDO_B} + I_{DDO_C} + I_{DDO_D}$.

Table 4B. Power Supply DC Characteristics, V_{DD} = 3.3V ± 5%, V_{DDO_QREF} = 2.5V ± 5%, T_A = -40°C to 85°C

Symbol	Parameter	Test Conditions	Minimum	Typical	Maximum	Units
V_{DD}	Core Supply Voltage		3.135	3.3	3.465	V
V_{DDA}	Analog Supply Voltage		V_{DD} – 0.16	3.3	V_{DD}	V
V_{DDO_QREF}	Output Supply Voltage		2.375	2.5	2.625	V
I_{DD}	Power Supply Current				85	mA
I_{DDA}	Analog Supply Current				16	mA
I_{DDO_QREF}	Output Supply Current	No Load, CLK selected			8	mA

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Table 4C. LVCMOS/LVTTL DC Characteristics, V_{DD} = 3.3V ± 5%, V_{DDO_QREF} = 3.3V ± 5% or 2.5V ± 5%, T_A = -40°C to 85°C

Symbol	Parameter		Test Conditions	Minimum	Typical	Maximum	Units
V_{IH}	Input High Voltage			2.2		V_{DD} + 0.3	V
V_{IL}	Input Low Voltage			-0.3		0.8	V
I_{IH}	Input High Current	FSEL_A[0:1], FSEL_B[0:1], FSEL_C[0:1]	V_{DD} = V_{IN} = 3.465V			150	µA
		REF_SEL, PLL_SEL, OE_REF, OE_A, nMR OE_B, OE_C, OE_D	V_{DD} = V_{IN} = 3.465V			10	uA
I_{IL}	Input Low Current	FSEL_A[0:1], FSEL_B[0:1], FSEL_C[0:1]	V_{DD} = 3.465V, V_{IN} = 0V	-10			µA
		REF_SEL, PLL_SEL, OE_REF, OE_A, nMR OE_B, OE_C, OE_D	V_{DD} = 3.465V, V_{IN} = 0V	-150			uA
V_{OH}	Output High Voltage	QREF0	V_{DDO_QREF} = 3.465V I_{OH} = -12mA	2.6			V
			V_{DDO_QREF} = 2.625V I_{OH} = -12mA	1.8			V
V_{OL}	Output Low Voltage	QREF0	V_{DDO_QREF} = 3.465V or 2.625V I_{OL} = 12mA			0.6	V

Table 4D. Differential DC Characteristics, V_{DD} = 3.3V ± 5%, T_A = -40°C to 85°C

Symbol	Parameter		Test Conditions	Minimum	Typical	Maximum	Units
I_{IH}	Input High Current	CLK, nCLK	V_{DD} = V_{IN} = 3.465V			150	µA
I_{IL}	Input Low Current	CLK	V_{DD} = 3.465V, V_{IN} = 0V	-10			µA
		nCLK	V_{DD} = 3.465V, V_{IN} = 0V	-150			µA
V_{PP}	Peak-to-Peak Input Voltage; NOTE 1			0.15		1.3	V
V_{CMR}	Common Mode Input Voltage; NOTE 1, 2			0.5		V_{DD} – 0.85	V

NOTE 1: V_{IL} should not be less than -0.3V.
NOTE 2. Common mode voltage is defined as V_{IH}.

Table 5. Crystal Characteristics

Parameter	Test Conditions	Minimum	Typical	Maximum	Units
Mode of Oscillation			Fundamental		
Frequency			25		MHz
Equivalent Series Resistance (ESR)				50	Ω
Shunt Capacitance				7	pF

NOTE: Characterized using an 18pF parallel resonant crystal.

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Table 6. Input Frequency Characteristics, V_{DD} = 3.3V ± 5%, $V_{DDO_[A:D]}$ = 3.3V ± 5%; or V_{DD} = 3.3V ± 5%, V_{DDO_QREF} = 3.3V ± 5% or 2.5V ± 5%, T_A = -40°C to 85°C

Symbol	Parameter		Test Conditions	Minimum	Typical	Maximum	Units
f_{IN}	Input Frequency	CLK, nCLK			25		MHz
		XTAL_IN, XTAL_OUT			25		MHz

AC Electrical Characteristics

Table 7A. PCI Express Jitter Specifications, V_{DD} = $V_{DDO_[A:D]}$ = 3.3V ± 5%, T_A = -40°C to 85°C

Symbol	Parameter	Test Conditions	Minimum	Typical	Maximum	PCIe Industry Specification	Units
t_j (PCIe Gen 1)	Phase Jitter Peak-to-Peak; NOTE 1, 4	f = 100MHz, 25MHz Crystal Input Evaluation Band: 0Hz - Nyquist (clock frequency/2)		14.09	21.18	86	ps
$t_{REFCLK_HF_RMS}$ (PCIe Gen 2)	Phase Jitter RMS; NOTE 2, 4	f = 100MHz, 25MHz Crystal Input High Band: 1.5MHz - Nyquist (clock frequency/2)		1.72	3.03	3.10	ps
$t_{REFCLK_LF_RMS}$ (PCIe Gen 2)	Phase Jitter RMS; NOTE 2, 4	f = 100MHz, 25MHz Crystal Input Low Band: 10kHz - 1.5MHz		0.06	0.10	3.0	ps
t_{REFCLK_RMS} (PCIe Gen 3)	Phase Jitter RMS; NOTE 3, 4	f = 100MHz, 25MHz Crystal Input Evaluation Band: 0Hz - Nyquist (clock frequency/2)		0.44	0.79	0.8	ps

NOTE: Electrical parameters are guaranteed over the specified ambient operating temperature range, which is established when the device is mounted in a test socket with maintained transverse airflow greater than 500 lfpm. The device will meet specifications after thermal equilibrium has been reached under these conditions. For additional information, refer to the PCI Express Application Note section in the datasheet.
NOTE: All HCSL outputs running at 100MHz and QREF0 running at 25MHz.
NOTE 1: Peak-to-Peak jitter after applying system transfer function for the Common Clock Architecture. Maximum limit for PCI Express Gen 1 is 86ps peak-to-peak for a sample size of 106 clock periods.
NOTE 2: RMS jitter after applying the two evaluation bands to the two transfer functions defined in the Common Clock Architecture and reporting the worst case results for each evaluation band. Maximum limit for PCI Express Generation 2 is 3.1ps RMS for tREFCLK_HF_RMS (High Band) and 3.0ps RMS for tREFCLK_LF_RMS (Low Band).
NOTE 3: RMS jitter after applying system transfer function for the common clock architecture. This specification is based on the PCI Express Base Specification Revision 0.7, October 2009 and is subject to change pending the final release version of the specification.
NOTE 4: This parameter is guaranteed by characterization. Not tested in production.

Table 7B. Serial Rapid IO Switch Jitter Specification, V_{DD} = $V_{DDO_[A:C]}$ = 3.3V ± 5%, T_A = -40°C to 85°C

Symbol	Parameter	Test Conditions	Minimum	Typical	Maximum	IDT sRIO Specification	Units
J_{CLK_REF}	Total Phase Jitter, RMS	f = 312.5MHz, 25MHz Crystal Input, HCSL Output Clocks		0.39	0.60	3	ps

NOTE: Electrical parameters are guaranteed over the specified ambient operating temperature range, which is established when the device is mounted in a test socket with maintained transverse airflow greater than 500 lfpm. The device will meet specifications after thermal equilibrium has been reached under these conditions. For additional information, refer to the *Serial Rapid IO Application Note section* in the datasheet.

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Table 7C. AC Characteristics, $V_{DD} = V_{DDO_[A:D]} = V_{DDO_QREF}$ = 3.3V ± 5%; or V_{DD} = 3.3V ± 5%, V_{DDO_QREF} = 2.5V ± 5%, T_A = -40°C to 85°C

Symbol	Parameter	Output	Test Conditions	Minimum	Typical	Maximum	Units
f_{OUT}	Output Frequency	Q[Ax:Cx], nQ[Ax:Cx]	FSEL_[Ax:Cx] = 00		100		MHz
		Q[Ax:Cx], nQ[Ax:Cx]	FSEL_[Ax:Cx] = 01		125		MHz
		Q[Ax:Cx], nQ[Ax:Cx]	FSEL_[Ax:Cx] = 10		156.25		MHz
		Q[Ax:Cx], nQ[Ax:Cx]	FSEL_[Ax:Cx] = 11		312.5		MHz
		QDx, nQDx			100		MHz
		QREF0			25		MHz

NOTE: Electrical parameters are guaranteed over the specified ambient operating temperature range, which is established when the device is mounted in a test socket with maintained transverse airflow greater than 500 lfpm. The device will meet specifications after thermal equilibrium has been reached under these conditions.

Table 7D. AC Characteristics, $V_{DD} = V_{DDO_[A:D]} = V_{DDO_QREF}$ = 3.3V ± 5%; or V_{DD} = 3.3V ± 5%, V_{DDO_QREF} = 2.5V ± 5%, T_A = -40°C to 85°C

Symbol	Parameter	Output	Output Configurations	Minimum	Typical	Maximum	Units
R_J	Random Jitter; NOTE 1	QAx, nQAx	QAx, nQAx = QDx, nQDx = 100MHz QBx, nQBx = 125MHz QCx, nQCx = 312.5MHz QREF0 = 25MHz		2	3	ps
		QBx, nQBx			3	5	ps
		QCx, nQCx			4	6	ps
		QDx, nQDx			3	3	ps
		QREF0			3	5	ps
D_J	Deterministic Jitter; NOTE 1	QAx, nQAx	QAx, nQAx = QDx nQDx = 100MHz QBx, nQBx = 125MHz QCx, nQCx = 312.5MHz QREF0 = 25MHz		13	30	ps
		QBx, nQBx			32	72	ps
		QCx, nQCx			46	93	ps
		QDx, nQDx			19	47	ps
		QREF0			4	19	ps
tjit(Ø)	RMS Phase Jitter, (Random) Integration Range: (12kHz to 20MHz)	QAx, nQAx	QAx, nQAx = QDx nQDx = 100MHz QBx, nQBx = 125MHz QCx, nQCx = 312.5MHz QREF0 = 25MHz		0.73	1.05	ps
		QBx, nQBx			0.71	1.00	ps
		QCx, nQCx			0.68	1.01	ps
		QDx, nQDx			0.73	1.04	ps
		QREF0			0.72	0.96	ps

NOTE: Electrical parameters are guaranteed over the specified ambient operating temperature range, which is established when the device is mounted in a test socket with maintained transverse airflow greater than 500 lfpm. The device will meet specifications after thermal equilibrium has been reached under these conditions.
NOTE: Refer to Applications Section for peak-to-peak jitter calculations.
NOTE 1: Measured using a Wavecrest SIA-3000.

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Table 7E. AC Characteristics, $V_{DD} = V_{DDO_[A:D]} = V_{DDO_QREF}$ = 3.3V ± 5%; and V_{DD} = 3.3V ± 5%, V_{DDO_QREF} = 3.3V ± 5% or 2.5V ± 5%, T_A = -40°C to 85°C

Symbol	Parameter		Test Conditions	Minimum	Typical	Maximum	Units
V_{RB}	Ring-Back Voltage Margin; NOTE 1, 2	Q[Ax:Dx], nQ[Ax:Dx]		-100		100	mV
t_{STABLE}	Time before V_{RB} is allowed; NOTE 1, 2	Q[Ax:Dx], nQ[Ax:Dx]		500			ps
V_{MAX}	Absolute Max Output Voltage; NOTE 3, 4	Q[Ax:Dx], nQ[Ax:Dx]				1150	mV
V_{MIN}	Absolute Min Output Voltage; NOTE 3, 5	Q[Ax:Dx], nQ[Ax:Dx]		-300			mV
V_{CROSS}	Absolute Crossing Voltage; NOTE 3, 6, 7	Q[Ax:Dx], nQ[Ax:Dx]		250		550	mV
ΔV_{CROSS}	Total Variation of V_{CROSS} over All Edges; NOTE 3, 6, 8	Q[Ax:Dx], nQ[Ax:Dx]				140	mV
t_{SLEW+}	Rising Edge Rate; NOTE 1, 9	Q[Ax:Dx], nQ[Ax:Dx]		0.6		5.5	V/ns
t_{SLEW-}	Falling Edge Rate; NOTE 1, 9	Q[Ax:Dx], nQ[Ax:Dx]		0.6		5.5	V/ns
odc	Output Duty Cycle	Q[Ax:Dx], nQ[Ax:Dx]		48		52	%
tjit(Ø)	RMS Phase Jitter, (Random)	QREF0	25MHz, Integration Range: (10kHz to 5MHz)		0.70	0.97	ps
t_R / t_F	Output Rise/Fall Time	QREF0	20% to 80%	0.40		1.5	ns
odc	Output Duty Cycle	QREF0	measured at $V_{DDO_QREF}/2$	45	50	55	%

NOTE: Electrical parameters are guaranteed over the specified ambient operating temperature range, which is established when the device is mounted in a test socket with maintained transverse airflow greater than 500 lfpm. The device will meet specifications after thermal equilibrium has been reached under these conditions.
All parameters measured at f_{OUT} unless noted otherwise.
NOTE 1: Measurement taken from differential waveform.
NOTE 2: t_{STABLE} is the time the differential clock must maintain a minimum ±150mV differential voltage after rising/falling edges before it is allowed to drop back into the V_{RB} ±100mV range. See Parameter Measurement Information Section.
NOTE 3: Measurement taken from single-ended waveform.
NOTE 4: Defined as the maximum instantaneous voltage including overshoot. See Parameter Measurement Information Section.
NOTE 5: Defined as the minimum instantaneous voltage including undershoot. See Parameter Measurement Information Section.
NOTE 6: Measured at the crosspoint where the instantaneous voltage value of the rising edge of Q[Ax:Dx] equals the falling edge of nQ[Ax:Dx].
NOTE 7: Refers to the total variation from the lowest crosspoint to the highest, regardless of which edge is crossing. Refers to all crosspoints for this measurement.
NOTE 8: Defined as the total variation of all crossing voltages of rising Q[Ax:Dx] and falling nQ[Ax:Dx]. This is the maximum allowed variance in Vcross for any particular system.
NOTE 9: Measured from -150mV to +150mV on the differential waveform (derived from Q[Ax:Dx] minus nQ[Ax:Dx]). The signal must be monotonic through the measurement region for rise and fall time. The 300mV measurement window is centered on the differential zero crossing.

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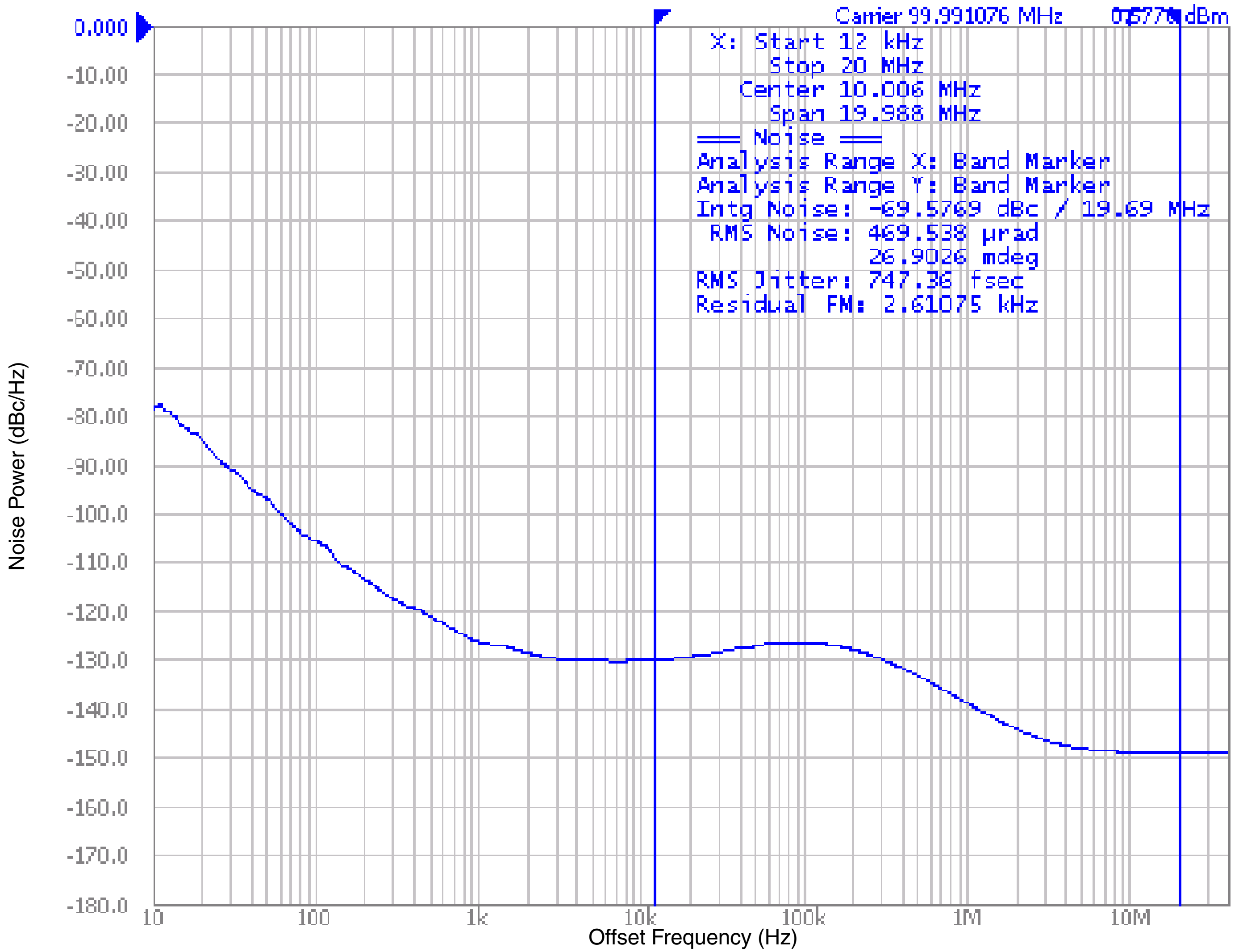
Typical Phase Noise at 100MHz



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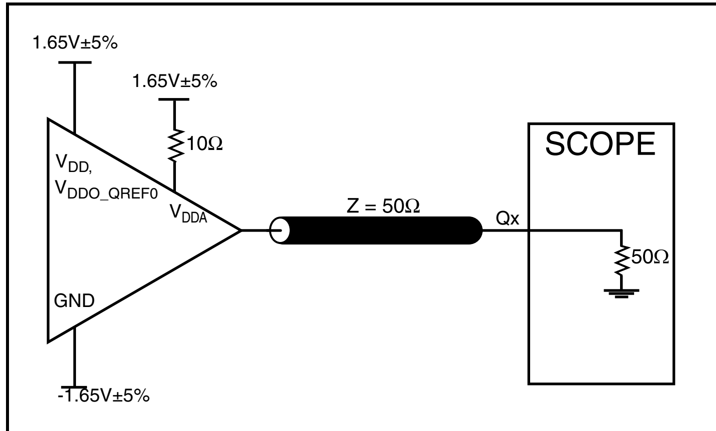
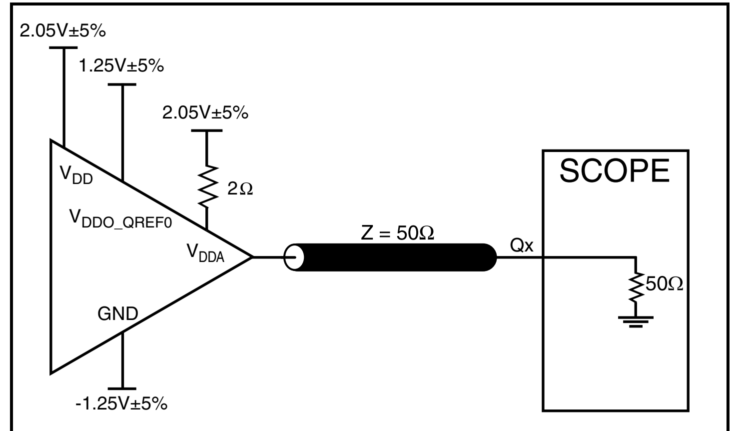
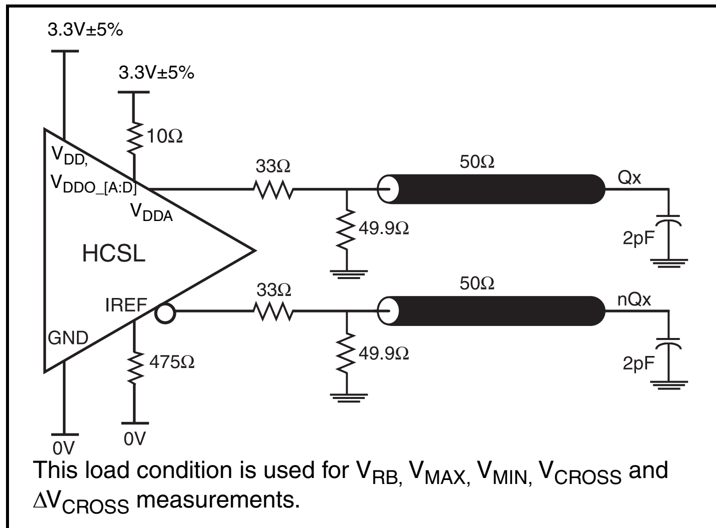
Parameter Measurement Information



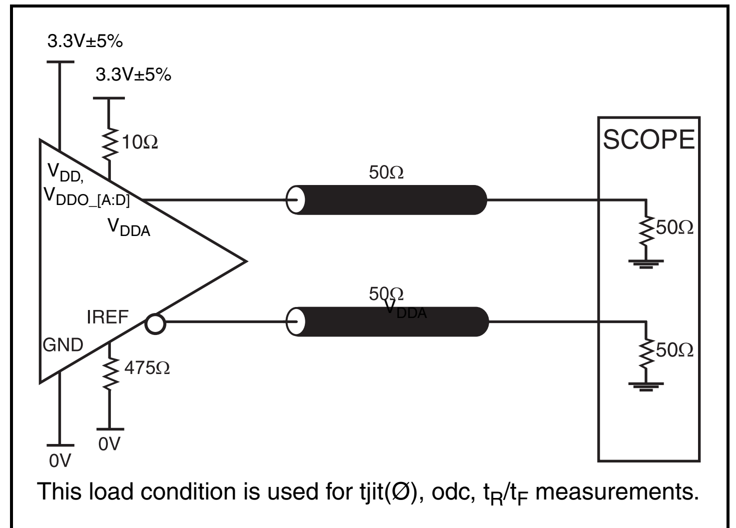
3.3V Core/3.3V LVCMOS Output Load Test Circuit



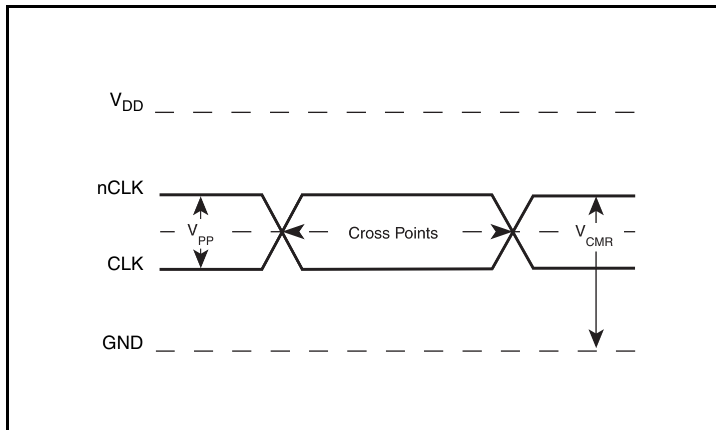
3.3V Core/2.5V LVCMOS Output Load Test Circuit



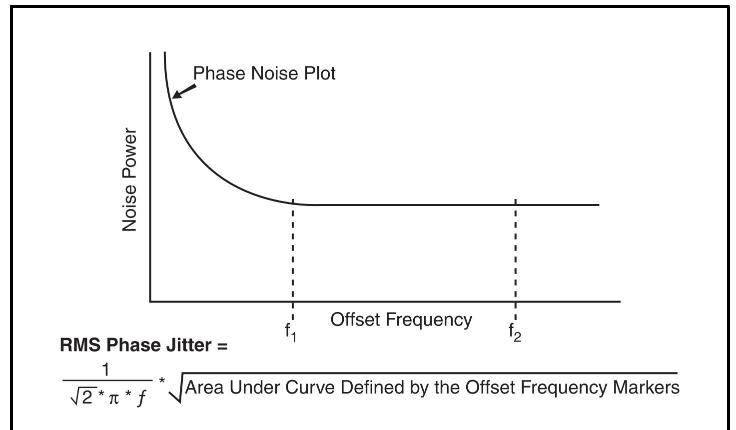
3.3V Core/3.3V HCSL Output Load Test Circuit



3.3V Core/3.3V HCSL Output Load Test Circuit



Differential Input Level



RMS Phase Jitter

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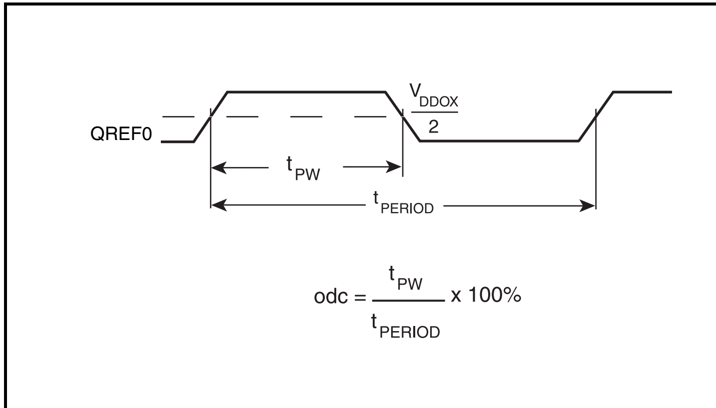
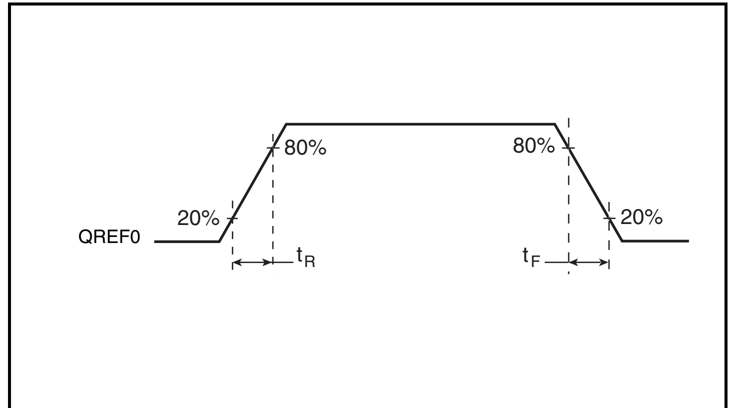
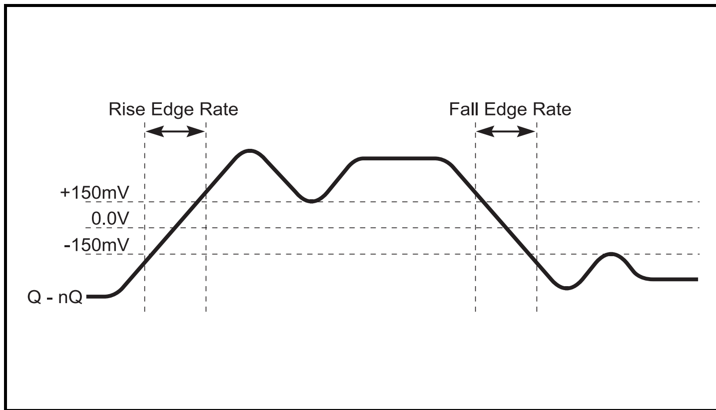
Parameter Measurement Information, continued



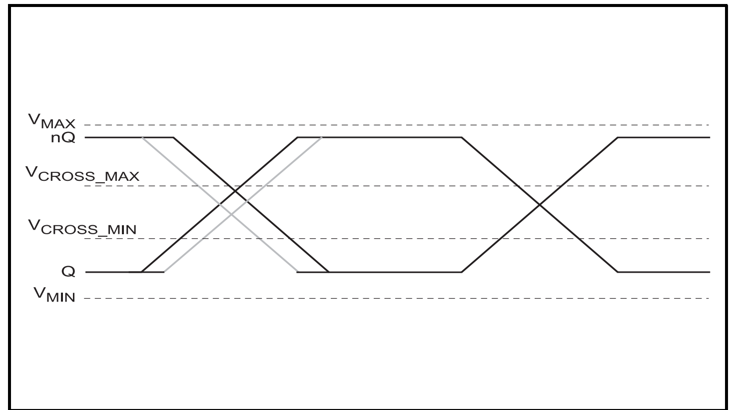
LVCMOS Output Duty Cycle/Pulse Width



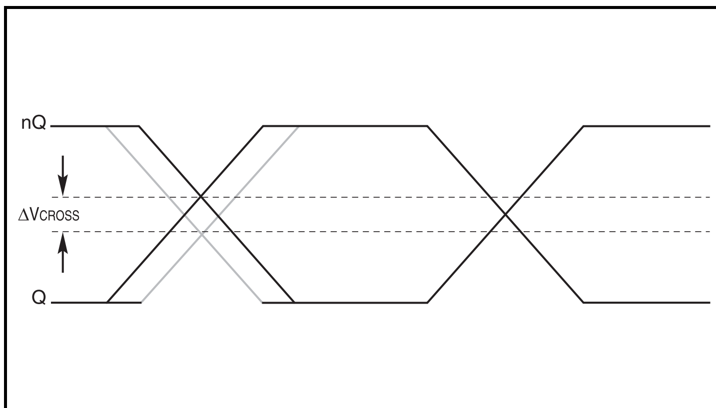
LVCMOS Output Rise/Fall Time



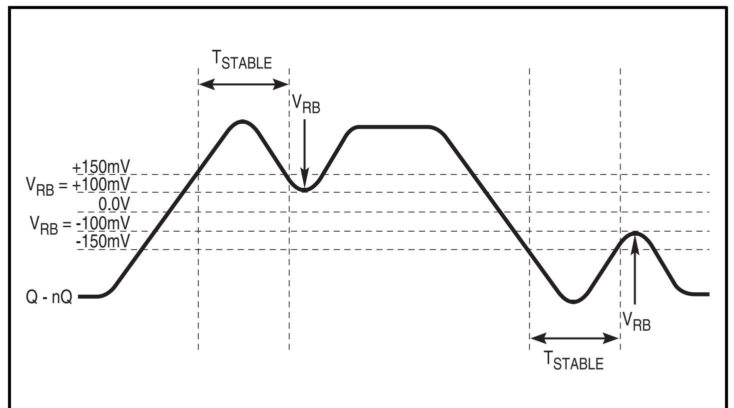
Differential Measurement Points for Rise/Fall Time Edge Rate



Single-ended Measurement Points for Absolute Cross Point/Swing



Single-ended Measurement Points for Delta Cross Point



Differential Measurement Points for Ringback

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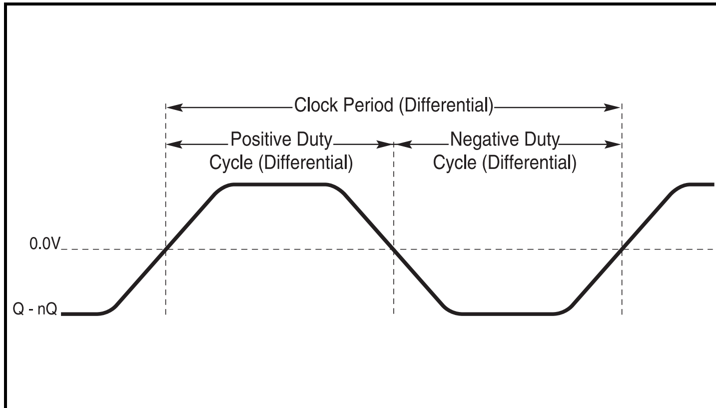
Parameter Measurement Information, continued



Differential Measurement Points for Duty Cycle/Period

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Peak-to-Peak Jitter Calculations

A standard deviation of a statistical population or data set is the square root of its variance. A standard deviation is used to calculate the probability of an anomaly or to predict a failure. Many times, the term "root mean square" (RMS) is used synonymously for standard deviation. This is accurate when referring to the square root of the mean squared deviation of a signal from a given baseline and when the data set contains a Gaussian distribution with no deterministic components. A low standard deviation indicates that the data set is close to the mean with little variation. A large standard deviation indicates that the data set is spread out and has a large variation from the mean.

A standard deviation is required when calculating peak-to-peak jitter. Since true peak-to-peak jitter is random and unbounded, it is important to always associate a bit error ratio (BER) when specifying a peak-to-peak jitter limit. Without it, the specification does not have a boundary and will continue get larger with sample size. Given that a BER is application specific, many frequency timing devices specify jitter as an RMS. This allows the peak-to-peak jitter to be calculated for the specific application and BER requirement. Because a standard deviation is the variation from the *mean* of the data set, it is important to always calculate the peak-to-peak jitter using the typical RMS value.

The table shows the BER with its appropriate RMS Multiplier. There are two columns for the RMS multiplier, one should be used if your signal is data and the other should be used if the signal is a repetitive clock signal. The difference between the two is the data transition density (DTD). The DTD is the number of rising or falling transitions divided by the total number of bits. For a clock signal, they are equal, hence the DTD is 1. For Data, on average, most common encoding standards have a 0.5 DTD.

Once the BER is chosen, there are two circumstances to consider. Is the data set purely Gaussian or does it contains any deterministic component? If it is Gaussian, then the peak to peak jitter can be calculated by simply multiplying the RMS multiplier with the typical RMS specification. For example, if a 10^{-12} BER is required for a clock signal, multiply 14.260 times the typical jitter specification.

Jitter (Peak-to-Peak) = RMS Multiplier x RMS (typical)

This calculation is not specific to one type of Jitter classification. It can be used to calculate BER on various types of RMS jitter. It is important that the user understands their jitter requirement to ensure that they are calculating the correct BER for their jitter requirement.

If the dataset contains deterministic components, then the random jitter (R_J) and deterministic jitter (D_J) must be separated and analyzed separately. R_J, also known as Gaussian jitter, is not bounded and the peak to peak will continue to get larger as the sample size increases. Alternatively, peak-to-peak value of D_J is bounded and can easily be observed and predicted. Therefore, the peak to peak jitter for the random component must be added to the deterministic component. This is called total jitter (T_J).

Total Jitter (Peak-to-Peak) = [RMS Multiplier x Random Jitter (R_J)] + Deterministic Jitter (D_J)

This calculation is not specific to one type of jitter classification. It can be used to calculate BER on various types of RMS jitter. It is important that the user understands their jitter requirement to ensure they are calculating the correct BER for their jitter requirement.

BER	RMS Multiplier Data, "DTD = 0.5"	RMS Multiplier Clock, "DTD = 1.0"
10^{-3}	6.180	6.582
10^{-4}	7.438	7.782
10^{-5}	8.530	8.834
10^{-6}	9.507	9.784
10^{-7}	10.399	10.654
10^{-8}	11.224	11.462
10^{-9}	11.996	12.218
10^{-10}	12.723	12.934
10^{-11}	13.412	13.614
10^{-12}	14.069	14.260
10^{-13}	14.698	14.882
10^{-14}	15.301	15.478
10^{-15}	15.883	16.028

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Applications Information

Wiring the Differential Input to Accept Single-Ended Levels

Figure 1 shows how a differential input can be wired to accept single ended levels. The reference voltage $V_1 = V_{DD}/2$ is generated by the bias resistors R1 and R2. The bypass capacitor (C1) is used to help filter noise on the DC bias. This bias circuit should be located as close to the input pin as possible. The ratio of R1 and R2 might need to be adjusted to position the V_1 in the center of the input voltage swing. For example, if the input clock swing is 2.5V and V_{DD} = 3.3V, R1 and R2 value should be adjusted to set V_1 at 1.25V. The values below are for when both the single ended swing and V_{DD} are at the same voltage. This configuration requires that the sum of the output impedance of the driver (Ro) and the series resistance (Rs) equals the transmission line impedance. In addition, matched termination at the input will attenuate the signal in half. This can be done in one of two ways. First, R3 and R4 in parallel should equal the transmission line impedance. For most 50Ω applications, R3 and R4 can be 100Ω. The values of the resistors can be increased to reduce the loading for slower and weaker LVCMOS driver. When using single-ended signaling, the noise rejection benefits of differential signaling are reduced. Even though the differential input can handle full rail LVCMOS signaling, it is recommended that the amplitude be reduced. The datasheet specifies a lower differential amplitude, however this only applies to differential signals. For single-ended applications, the swing can be larger, however V_{IL} cannot be less than -0.3V and V_{IH} cannot be more than V_{DD} + 0.3V. Though some of the recommended components might not be used, the pads should be placed in the layout. They can be utilized for debugging purposes. The datasheet specifications are characterized and guaranteed by using a differential signal.

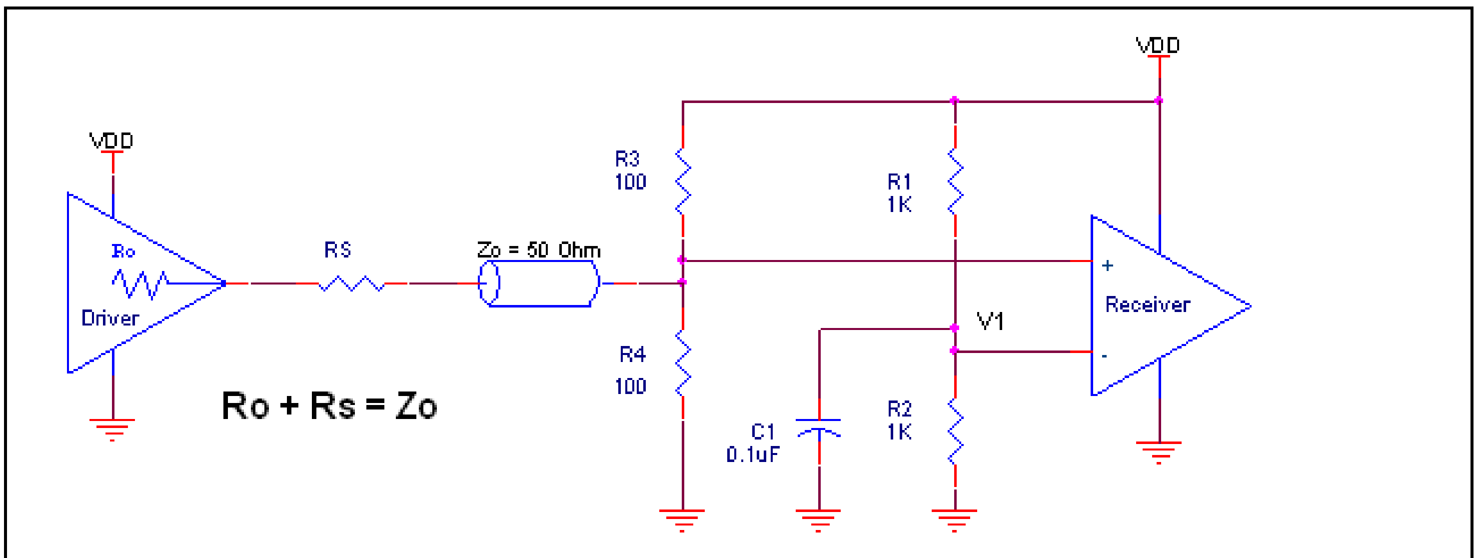

Figure 1. Recommended Schematic for Wiring a Differential Input to Accept Single-ended Levels

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Differential Clock Input Interface

The CLK /nCLK accepts LVDS, LVPECL, LVHSTL, HCSL and other differential signals. Both signals must meet the V_{PP} and V_{CMR} input requirements. *Figures 2A to 2E* show interface examples for the CLK/nCLK input driven by the most common driver types. The input interfaces suggested here are examples only. Please consult with the vendor of the driver component to confirm the driver termination requirements. For example, in Figure 2A, the input termination applies for IDT open emitter LVHSTL drivers. If you are using an LVHSTL driver from another vendor, use their termination recommendation.

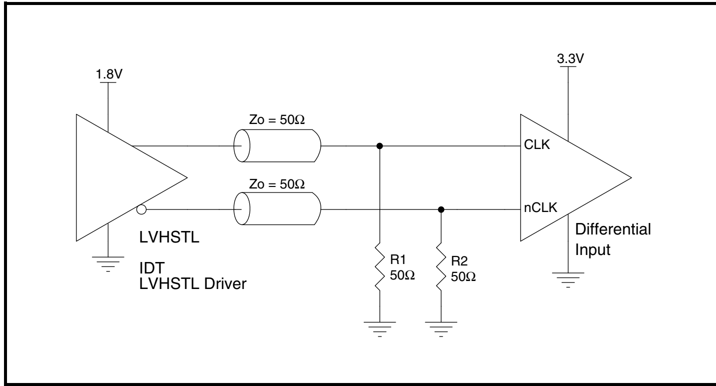

Figure 2A. CLK/nCLK Input Driven by an IDT Open Emitter LVHSTL Driver

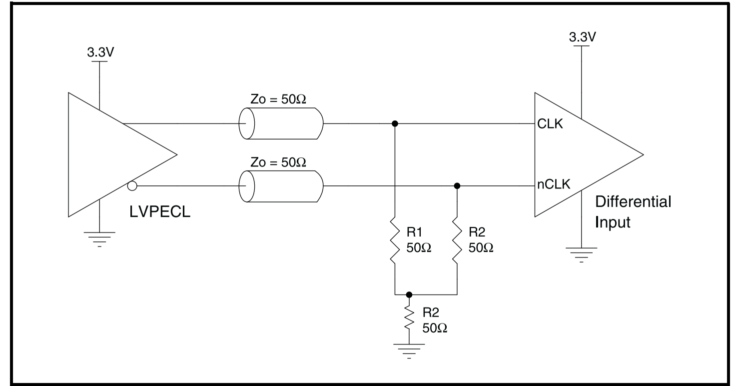

Figure 2B. CLK/nCLK Input Driven by a 3.3V LVPECL Driver

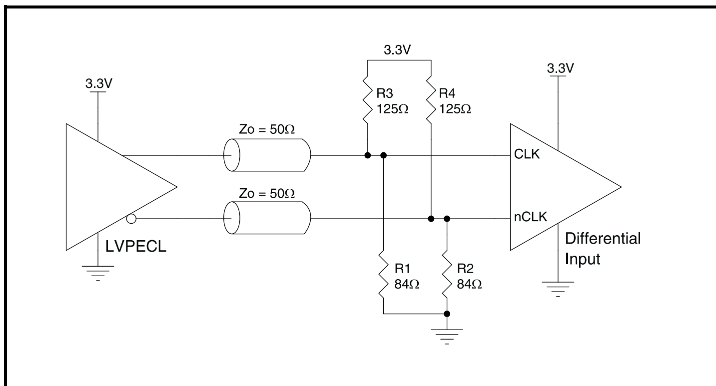

Figure 2C. CLK/nCLK Input Driven by a 3.3V LVPECL Driver

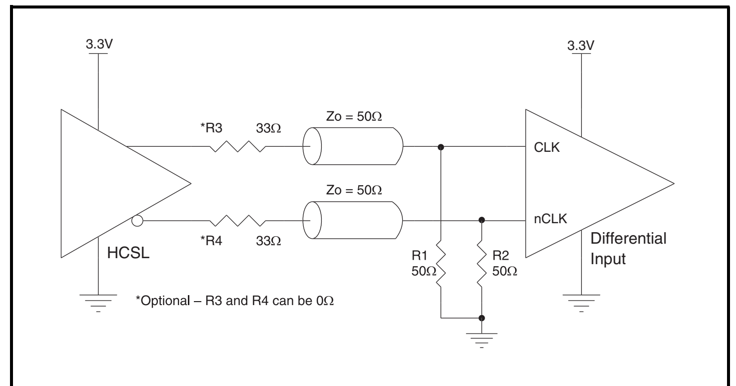

Figure 2D. CLK/nCLK Input Driven by a 3.3V HCSL Driver

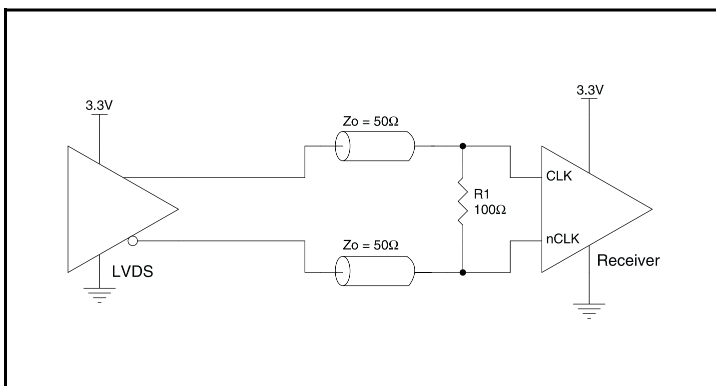

Figure 2E. CLK/nCLK Input Driven by a 3.3V LVDS Driver

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Recommendations for Unused Input and Output Pins

Inputs:

LVCMOS Control Pins

All control pins have internal pullup or pulldown resistors; additional resistance is not required but can be added for additional protection. A 1kΩ resistor can be used.

Crystal Inputs

For applications not requiring the use of the crystal oscillator input, both XTAL_IN and XTAL_OUT can be left floating. Though not required, but for additional protection, a 1kΩ resistor can be tied from XTAL_IN to ground.

CLK/nCLK Inputs

For applications not requiring the use of the differential input, both CLK and nCLK can be left floating. Though not required, but for additional protection, a 1kΩ resistor can be tied from CLK to ground.

Outputs:

LVCMOS Outputs

The unused LVCMOS output can be left floating. There should be no trace attached.

Differential Outputs

All unused differential output pairs can be left floating. We recommend that there is no trace attached. Both sides of the differential output pair should either be left floating or terminated.

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Recommended Termination

Figure 4A is the recommended source termination for applications where the driver and receiver will be on a separate PCBs. This termination is the standard for PCI Express™ and HCSL output types. All traces should be 50Ω impedance single-ended or 100Ω differential.

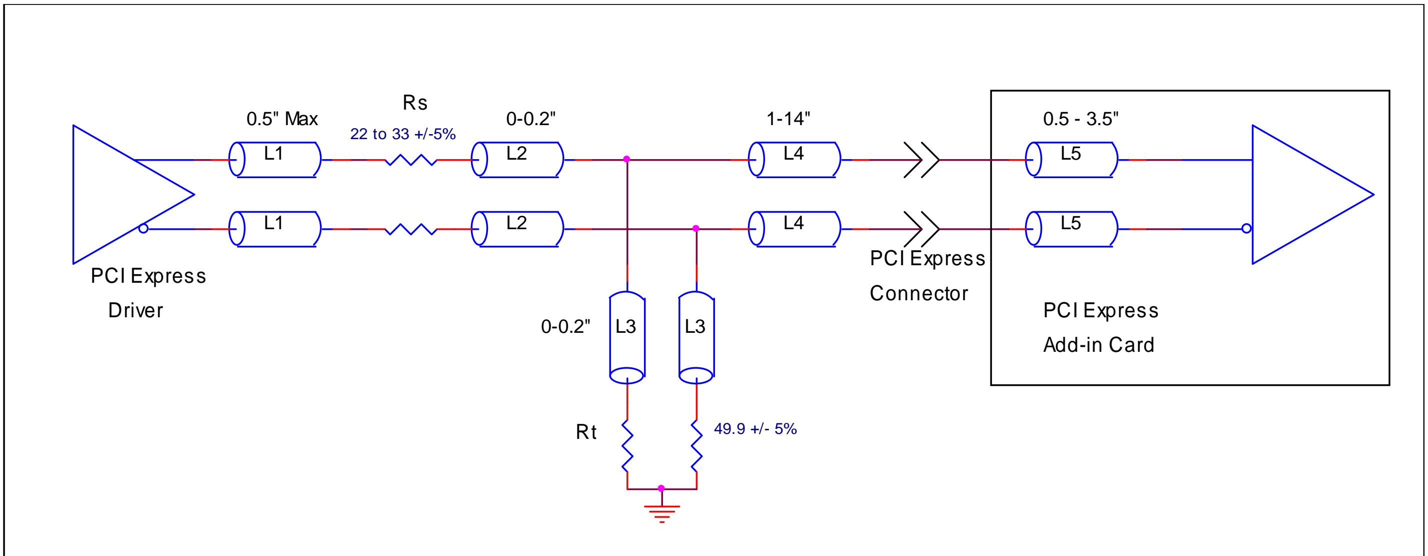

Figure 4A. Recommended Source Termination (where the driver and receiver will be on separate PCBs)

Figure 4B is the recommended termination for applications where a point-to-point connection can be used. A point-to-point connection contains both the driver and the receiver on the same PCB. With a matched termination at the receiver, transmission-line reflections will be minimized. In addition, a series resistor (Rs) at the driver offers flexibility and can help dampen unwanted reflections. The optional resistor can range from 0Ω to 33Ω. All traces should be 50Ω impedance single-ended or 100Ω differential.

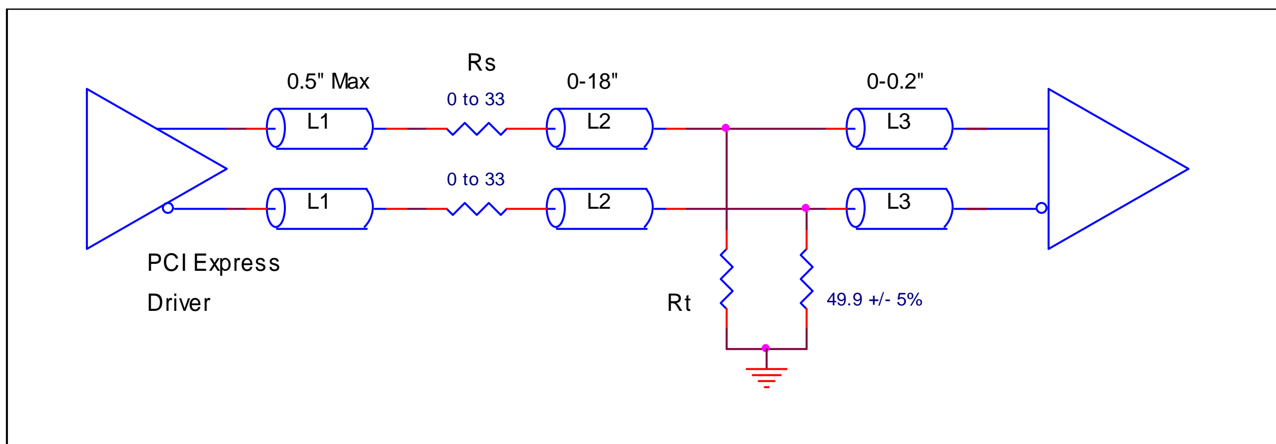

Figure 4B. Recommended Termination (where a point-to-point connection can be used)

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PCI Express Application Note

PCI Express jitter analysis methodology models the system response to reference clock jitter. The block diagram below shows the most frequently used *Common Clock Architecture* in which a copy of the reference clock is provided to both ends of the PCI Express Link.

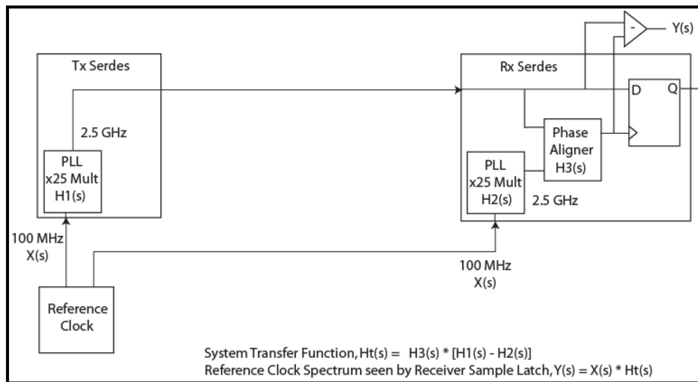
In the jitter analysis, the transmit (Tx) and receive (Rx) serdes PLLs are modeled as well as the phase interpolator in the receiver. These transfer functions are called H1, H2, and H3 respectively. The overall system transfer function at the receiver is:

$$Ht(s) = H3(s) \times [H1(s) - H2(s)]$$

The jitter spectrum seen by the receiver is the result of applying this system transfer function to the clock spectrum X(s) and is:

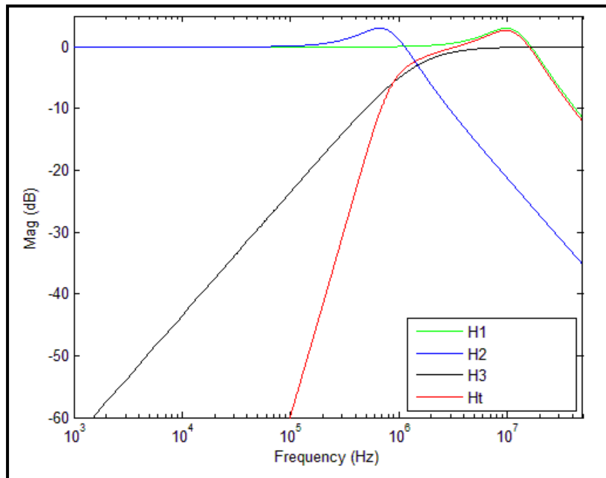
$$Y(s) = X(s) \times H3(s) \times [H1(s) - H2(s)]$$

In order to generate time domain jitter numbers, an inverse Fourier Transform is performed on X(s)*H3(s) * [H1(s) - H2(s)].



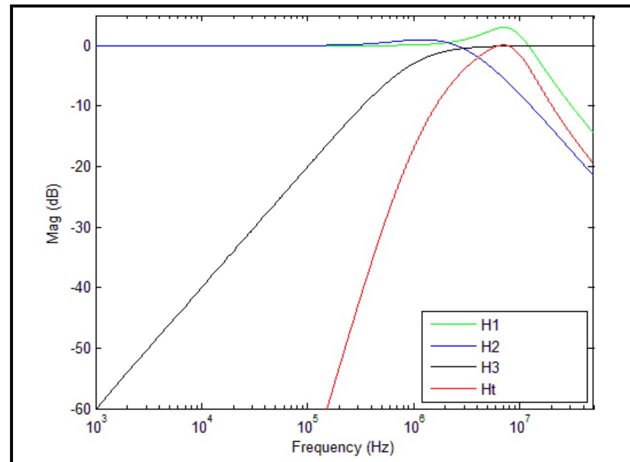
PCI Express Common Clock Architecture

For **PCI Express Gen 1**, one transfer function is defined and the evaluation is performed over the entire spectrum: DC to Nyquist (e.g for a 100MHz reference clock: 0Hz – 50MHz) and the jitter result is reported in peak-peak.

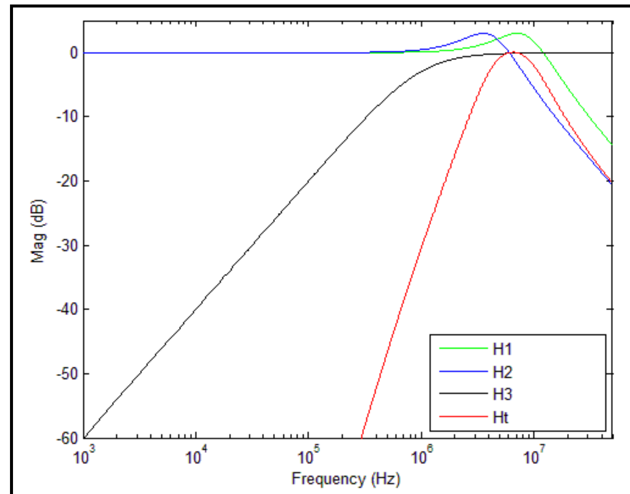


PCIe Gen 1 Magnitude of Transfer Function

For **PCI Express Gen 2**, two transfer functions are defined with 2 evaluation ranges and the final jitter number is reported in rms. The two evaluation ranges for PCI Express Gen 2 are 10kHz – 1.5MHz (Low Band) and 1.5MHz – Nyquist (High Band). The plots show the individual transfer functions as well as the overall transfer function Ht.

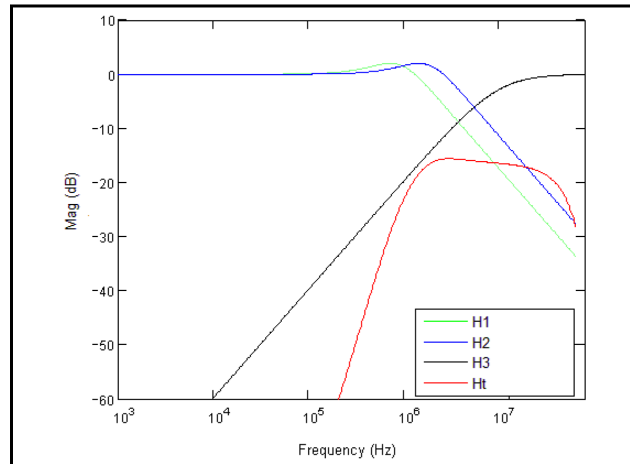


PCIe Gen 2A Magnitude of Transfer Function



PCIe Gen 2B Magnitude of Transfer Function

For **PCI Express Gen 3**, one transfer function is defined and the evaluation is performed over the entire spectrum. The transfer function parameters are different from Gen 1 and the jitter result is reported in RMS.



PCIe Gen 3 Magnitude of Transfer Function

For a more thorough overview of PCI Express jitter analysis methodology, please refer to IDT Application Note *PCI Express Reference Clock Requirements.*

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VFQFN EPAD Thermal Release Path

In order to maximize both the removal of heat from the package and the electrical performance, a land pattern must be incorporated on the Printed Circuit Board (PCB) within the footprint of the package corresponding to the exposed metal pad or exposed heat slug on the package, as shown in *Figure 5.* The solderable area on the PCB, as defined by the solder mask, should be at least the same size/shape as the exposed pad/slug area on the package to maximize the thermal/electrical performance. Sufficient clearance should be designed on the PCB between the outer edges of the land pattern and the inner edges of pad pattern for the leads to avoid any shorts.

While the land pattern on the PCB provides a means of heat transfer and electrical grounding from the package to the board through a solder joint, thermal vias are necessary to effectively conduct from the surface of the PCB to the ground plane(s). The land pattern must be connected to ground through these vias. The vias act as “heat pipes”. The number of vias (i.e. “heat pipes”) are application specific and dependent upon the package power dissipation as well as electrical conductivity requirements. Thus, thermal and electrical analysis and/or testing are recommended to determine the minimum number needed. Maximum thermal and electrical performance is achieved when an array of vias is incorporated in the land pattern. It is recommended to use as many vias connected to ground as possible. It is also recommended that the via diameter should be 12 to 13mils (0.30 to 0.33mm) with 1oz copper via barrel plating. This is desirable to avoid any solder wicking inside the via during the soldering process which may result in voids in solder between the exposed pad/slug and the thermal land. Precautions should be taken to eliminate any solder voids between the exposed heat slug and the land pattern. Note: These recommendations are to be used as a guideline only. For further information, please refer to the Application Note on the Surface Mount Assembly of Amkor’s Thermally/ Electrically Enhance Leadframe Base Package, Amkor Technology.

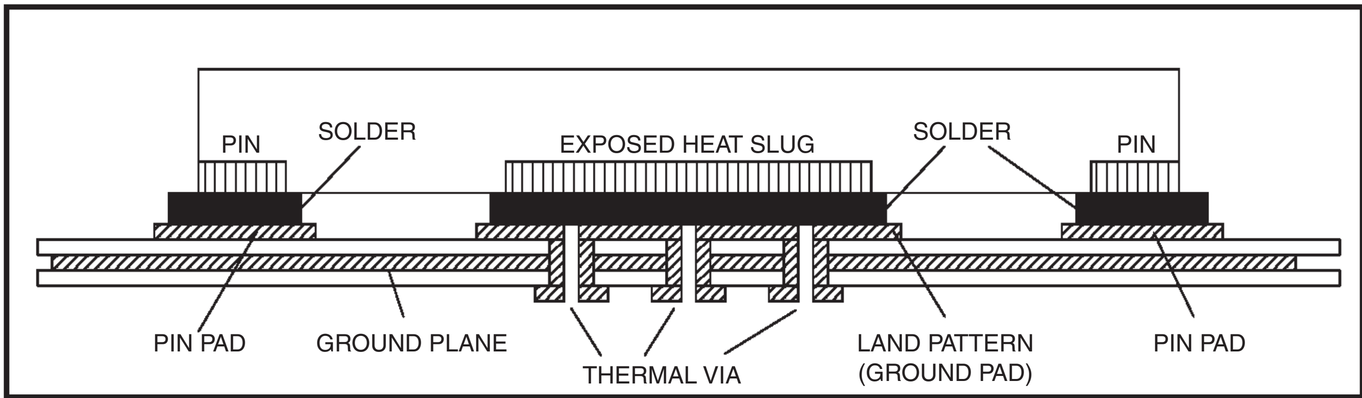

Figure 5. P.C. Assembly for Exposed Pad Thermal Release Path – Side View (drawing not to scale)

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Serial Rapid IO Application Note

The Serial Rapid IO jitter analysis methodology models the system response to reference clock jitter. The total RMS phase jitter allowed on the reference clock of the Tsi57x and Tsi620 is specified at 3ps (max). In this jitter analysis, the TSI57x and Tsi620 SERDES PLL is modeled by the transfer response function H(s) shown in *Figure 6.* To model the response of the switch on the reference clock jitter, a phase noise measurement is executed and a frequency domain analysis is performed. In the phase noise plot, the mask of the transfer function H(s) is applied to the phase noise response of the reference clock. The area under the resultant phase noise curve is referred to as Phase Jitter. In the frequency domain, the random and deterministic jitter can be calculated quickly and accurately. RMS Phase Jitter is also referred to as random jitter and the spurs on the phase noise plot can be interpreted as deterministic jitter. Total RMS Phase Jitter includes both random and deterministic jitter.

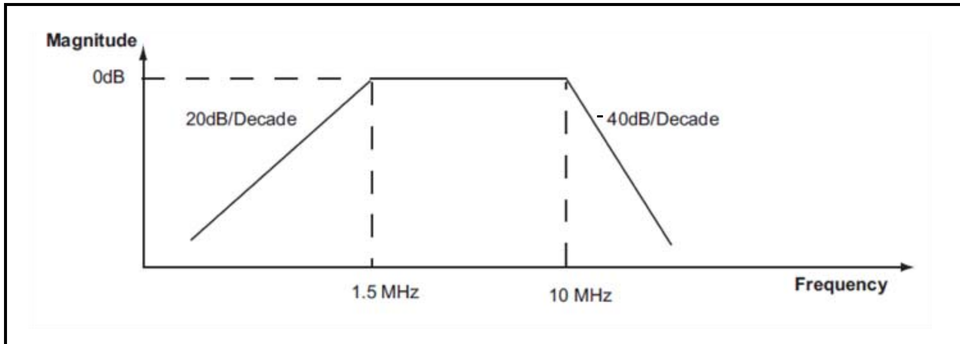

Figure 6. Weighing Function for Jitter Calculation

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Schematic Layout

Figure 7 (next page) shows an example of 8413S09 application schematic. In this example, the device is operated at $V_{DD} = V_{DDA} = V_{DDO_A} = V_{DDO_B} = V_{DDO_C} = V_{DDO_D}$ = 3.3V and V_{DDO_QREF} = 3.3V. The schematic example focuses on functional connections and is not configuration specific. Refer to the pin description and functional tables in the datasheet to ensure that the logic control inputs are properly set.

An 18pF parallel resonant 25MHz crystal is used. For this device, the crystal load capacitors are required for proper operation. The load capacitance, C1 = 22pF and C2 = 10pF, are recommended for frequency accuracy. Depending on the variation of the parasitic stray capacity of the printed circuit board traces between the crystal and the XTAL_IN and XTAL_OUT pins, the values of C1 and C2 might require a slight adjustment to optimize the frequency accuracy. Crystals with other load capacitance specifications can be used, but this will require adjusting C1 and C2.

The ePAD provides a low thermal impedance connection between the internal device and the PCB. It also provides an electrical connection to the die and must be connected to ground.

As with any high speed analog circuitry, the power supply pins are vulnerable to random noise. To achieve optimum jitter performance, power supply isolation is required. The 8413S09 provides separate power supplies to isolate any high switching noise from coupling into the internal PLL.

In order to achieve the best possible filtering, it is recommended that the placement of the filter components be on the device side of the PCB as close to the power pins as possible. If space is limited, the 0.1uf capacitor in each power pin filter should be placed on the device side. The other components can be on the opposite side of the PCB. Power supply filter recommendations are a general guideline to be used for reducing external noise from coupling into the devices. The filter performance is designed for a wide range of noise frequencies. This low-pass filter starts to attenuate noise at approximately 10kHz. If a specific frequency noise component is known, such as switching power supplies frequencies, it is recommended that component values be adjusted and if required, additional filtering be added. Additionally, good general design practices for power plane voltage stability suggests adding bulk capacitance in the local area of all devices.

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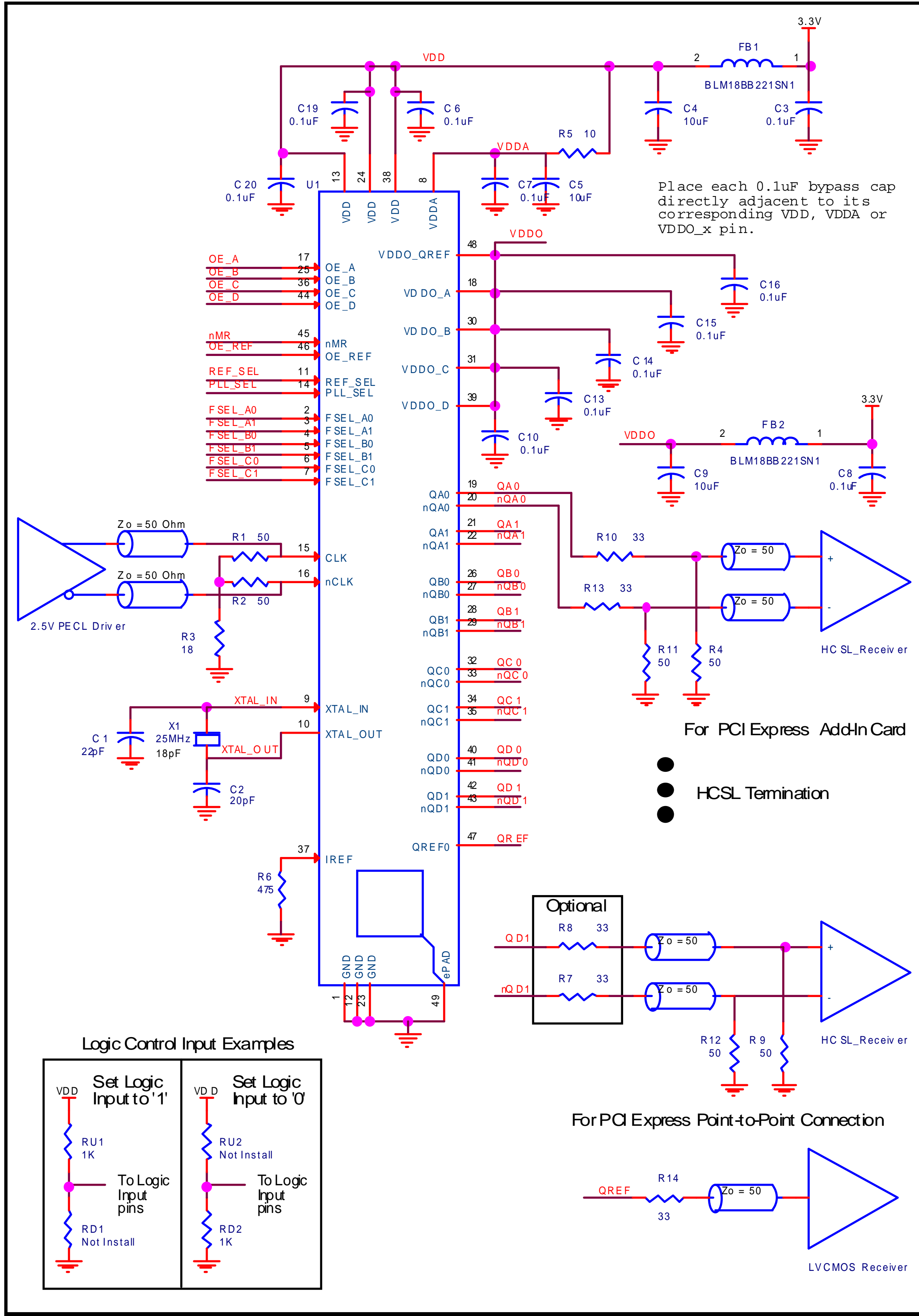

Figure 7. 8413S09 Schematic Example

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Power Considerations

This section provides information on power dissipation and junction temperature for the 8413S09. Equations and example calculations are also provided.

1. Power Dissipation.

The total power dissipation for the8413S09 is the sum of the core power plus the analog power plus the power dissipated into the load. The following is the power dissipation for V_{DD} = 3.3V + 5% = 3.465V, which gives worst case results.

NOTE: Please refer to Section 3 for details on calculating power dissipated into the load.

- Power $(core)_{MAX} = V_{DD_MAX} * (I_{DD} + I_{DDA})$= 3.465V * (85mA + 16mA) = **350mW**
- Power $(HCSL)_{MAX}$ = (3.465V – 17mA * 50) 17mA = **44.5mW** per output
- Total Power $(HCSL)_{MAX}$ = 44.5mW * 8 = **356mW**

LVCMOS Driver Power Dissipation

- Output Impedance R_{OUT} Power Dissipation due to Loading 50Ω to $V_{DD}/2$
  Output Current $I_{OUT} = V_{DD_MAX} / [2 * (50\Omega + R_{OUT})]$ = 3.465V / [2 * (50Ω + 15Ω)] = **26.7mA**
- Power Dissipation on the R_{OUT} per LVCMOS output
  Power (LVCMOS) = $R_{OUT} * (I_{OUT})^2 = 15\Omega * (26.7mA)^2$ = **10.7mW per output**
- Total Power Dissipation on the R_{OUT}
  Total Power (R_{OUT}) = 10.7mW * 1 = **10.7mW**

Total Power Dissipation

- **Total Power**
  = Power (core) + Total Power (HCSL) + Total Power (R_{OUT})
  = 350mW + 356mW + 10.7mW
  = 716.7mW

2. Junction Temperature.

Junction temperature, Tj, is the temperature at the junction of the bond wire and bond pad directly affects the reliability of the device. The maximum recommended junction temperature is 125°C. Limiting the internal transistor junction temperature, Tj, to 125°C ensures that the bond wire and bond pad temperature remains below 125°C.

The equation for Tj is as follows: $Tj = \theta_{JA} * Pd_total + T_A$

Tj = Junction Temperature

θ_{JA} = Junction-to-Ambient Thermal Resistance

Pd_total = Total Device Power Dissipation (example calculation is in section 1 above)

T_A = Ambient Temperature

In order to calculate junction temperature, the appropriate junction-to-ambient thermal resistance θ_{JA} must be used. Assuming no air flow and a multi-layer board, the appropriate value is 30.5°C/W per Table 8 below.

Therefore, Tj for an ambient temperature of 85°C with all outputs switching is:

85°C + 0.717W * 30.5°C/W = 106.9°C. This is below the limit of 125°C.

This calculation is only an example. Tj will obviously vary depending on the number of loaded outputs, supply voltage, air flow and the type of board (multi-layer).

Table 8. Thermal Resistance θ_{JA} for 48 Lead VFQFN, Forced Convection

θ_{JA} vs. Air Flow			
Meters per Second	**0**	**1**	**2.5**
Multi-Layer PCB, JEDEC Standard Test Boards	30.5°C/W	26.7°C/W	23.9°C/W

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3. Calculations and Equations.

The purpose of this section is to calculate power dissipation on the IC per HCSL output pair.

HCSL output driver circuit and termination are shown in *Figure 8.*

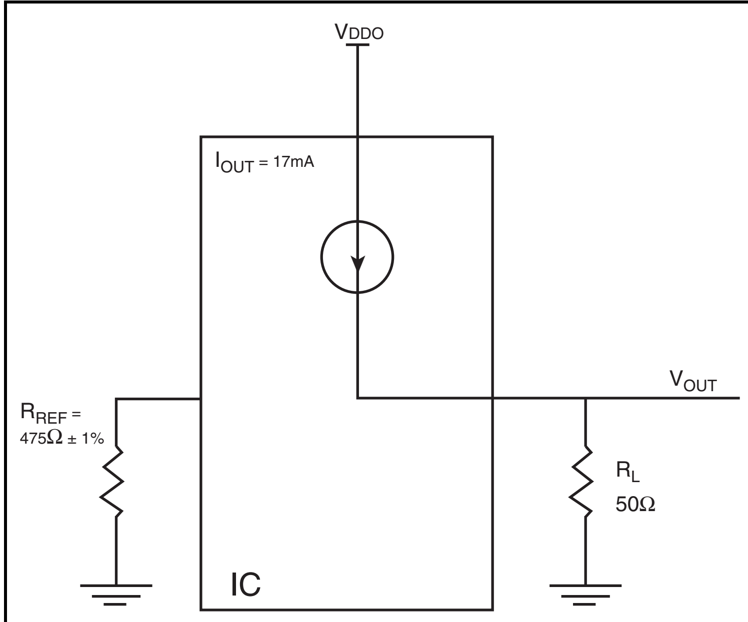

Figure 8. HCSL Driver Circuit and Termination

HCSL is a current steering output which sources a maximum of 17mA of current per output. To calculate worst case on-chip power dissipation, use the following equations which assume a 50Ω load to ground.

The highest power dissipation occurs when V_{DDO_MAX}.

Power $= (V_{DDO_MAX} - V_{OUT}) * I_{OUT}$
since $V_{OUT} = I_{OUT} * R_L$

Power $= (V_{DDO_MAX} - I_{OUT} * R_L) * I_{OUT}$

$= (3.465V - 17mA * 50\Omega) * 17mA$

Total Power Dissipation per output pair = **44.5mW**

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Reliability Information

Table 9. θ_{JA} vs. Air Flow Table for a 48 Lead VFQFN

θ_{JA} vs. Air Flow			
Meters per Second	**0**	**1**	**2.5**
Multi-Layer PCB, JEDEC Standard Test Boards	30.5°C/W	26.7°C/W	23.9°C/W

Transistor Count

The transistor count for 8413S09 is: 10,297

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Ordering Information

Table 11. Ordering Information

Part/Order Number	Marking	Package	Shipping Packaging	Temperature
8413S09BKILF	ICS8413S09BIL	48 Lead VFQFN, Lead-Free	Tray	-40°C to 85°C
8413S09BKILFT	ICS 8413S09BIL	48 Lead VFQFN, Lead-Free	Tape & Reel	-40°C to 85°C

NOTE: Parts that are ordered with a "LF" suffix to the part number are the Pb-Free configuration and are RoHS compliant.

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Revision History Sheet

Rev	Table	Page	Description of Change	Date
B	T1	1 2 4	New pin assignment format - no changes to pins. Corrected block diagram. Pin Description Table - corrected pin 45 (nMR) description. Updated header/footer throughout the datasheet.	1/27/15

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