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M32C/82,83 Group

Variable-length clocked synchronous serial communication by using Intellingent I/O Group 2

1. Abstract

This application note describes the variable-length clock serial I/O (synchronous serial I/O) operation of Intelligent I/O Group 2.

2. Introduction

This application note is applied to the M32C/83 group microcomputer.

This program can also be used when operating other microcomputers within M16C family, provided they have the same SFR (Special Function Registers) as the M32C/83 group. However, some functions may have been modified. Refer to the User's Manual for details. Use functions covered in this Application Note only after careful evaluation.

3. Detailed description

This application example offers features of the variable-length serial I/O shown in Table 1.

The transmit data is output from pin ISTxD2, and the transfer clock is output from pin ISCLK2. Also the receive data is input from ISRxD2.

| Item | Definition | Selection in this | |
|--------------------------------|------------------------------------|-------------------|--|
| | | example | |
| Transfer clock | Internal Clock | Yes | |
| | External Clock | | |
| Transfer format | LSB First | Yes | |
| | MSB First | | |
| Polarity Selection of pins TxD | Non Reverse Output | Yes | |
| and RxD | Reverse Output | | |
| Transmit Interrupt Factor | When register G2TB becomes empty | | |
| | When the transmission is completed | Yes | |

Table 1 Clock Synchronous Serial I/O Option Features and Selected Features

(1) Transfer speed definition when using Channel 0

This example uses Channel 0 in the wave generation function. Select "Use the output of the communication function" for this operation. Base Timer is reset when the set value of register G2P00 matches the content of Base Timer. The transfer speed (the period of the transfer clock) is defined by the following equation. Here "fBT2" and "n" represents the count source of Base Timers and value of register G2P00 respectively.

Transfer Speed = $fBT2 / \{2x(n+2)\}$

When using in transmitting only, the transfer clock must be 6 divide or greater of Base Timer clock (n=1 or greater).



When using in transmitting and receiving, the transfer clock must be 20 divide or greater of Base Timer clock (n=8 or greater).

For example, when fBT2=30MHz, the max transfer speed is 5Mbps in transmitting and 1.5 Mbps in transmitting and receiving.

(2) How to generate the transfer clock by using Channel 2

This example uses Channel 2 in the phase-delayed waveform output mode of the wave generation function. The set value of register G2P02 must be "(n+2)/2" when register G2P00 is set to "n".



3.1 Register setting

This section shows the setting procedures and setting values to proceeds section "3. Detailed Description". For detail configuration of each register, please refer to M32C/83 Group HARDWARE MANUAL.

(1) Disabling an Interrupt

Set I flag=0. Or set bits ILV2 to $0=000_2$ in register IIOkIC (k=0 to 11) where the interrupt request of the Intelligent I/O is assigned.

(2) IPS register



(5) G2BCR1 register This setting is used to generate a 0 0 0 0 0 1 0 transfer clock. Set the RST1 bit to "1" (reset the Base Timer by matching with G2PO0 register) Don't use. Set to "0". RST1 Base timer reset cause select bit 1 Resets the timer by matching the register G2PO0 and base timer Don't use. Set to "002". BTS Set the bit to "1" (start the Base Base timer start bit Timer counting) after setting Resets the base timer Group 2 Intelligent I/O related UD1 to 0 Up-down control bit register. Up count mode Don't use. Set to "0". (6) G2POCR0 register 0 0 0 0 1 1 1 This setting enables the transmit data to be output from the pin ISTxD2. Operation mode select bit MOD2 to 0 Uses the output of the communication function Don't use. Set to "002". G2PO0 register value reload timing select bit RLD This setting enables the value in Reload when writing G2PO0 register to be effective after writing to this register. Don't use. Set to "002". (7) G2POCR1 register 0 0 0 0 0 1 1 1 This setting enables the transfer MOD2 to 0 clock to be output from the pin Operation mode select bit ISCLK2. Uses the output of the communication function Don't use. Set to "000002". (8) G2POCR2 register b7 b0 0 1 0 The transfer clock is generated by the phase-delayed waveform Operation mode select bit MOD2 to 0 output mode. Selects the phase-delayed waveform output mode Don't use. Set to "002". G2PO2 register value reload timing select bit RLD This setting enables the setting Reload when writing value in the GiPO2 register to be effective after writing to this Don't use. Set to "002". register.







fBT2 /{2 x (n+2)} n=1 to FFFD₁₆



(14) G2MR register





Don't use. Set to "0".

Initializes an interrupt request register

Set IIOkIR register to " 00_{16} ". If the register holds a value other than 00_{16} , bit IR in register IIOkIC will not be set to "1" even when an interrupt request is generated. (No interrupt operation possible)

(17) IIOkIE register (k=5 to 6)



(18) IIOkIC register (k=5 to 6)



(19) PSC register, PSLa register (a=0,1), PSb register (b=0,1,7) Set the ISTxD2, ISCLK2 pin.

(20) Enabling an interrupt (I flag ="1")

(21) G2BCR1 register





3.2 Precaution on Interrupts

You must clear register II0kIR to 00₁₆ during the respective interrupt routine. If you skip this procedure, bit IR in register II0kIC will not be set to "1" when the respective Intelligent I/O generates the interrupt request, resulting in no interrupt being invoked.

3.3 Timing Diagram

The following time chart shows the serial I/O operation in this example.



Clear to "0" by program

n: setting value of G2PO0 m: setting value of G2PO2



4. The example of a reference program

/ / FILE NAME : rej05b0396 src.c */ /* Version : 1.00 /* FUNCTION :Variable-length clocked synchronous */ serial communication by using Intelligent I/O Group 2 */ /*********************************/ include file */ ***************************/ #include <stdio.h> #include "sfr32c83.h" /*******************************/ Function difinition */ ****** void receive_int(void); #pragma INTERRUPT receive_int void trans_int(void); #pragma INTERRUPT trans_int /***************************/ **Global Variable Definition** */ /****************************/ static char rec buff; static unsigned short send_bits = 0; /**********************************/ /* */ main Function /****************************/ void main(void){ _asm(" fclr i"); /* Disable the interrupt */ /* main clock set */ /* protect off */ prc0 = 1;mcd = 0x12;/* main clock : no division */ /* protect on */ prc0 = 0;/* assigns ISRxD2 to P71 */ ips = 0x00;/* base clock initial set */ g2bcr0 = 0x7f;/* Supply clock with BTSR register */ /* b0,b1: count source f1 b2 to b6 : count source division ratio : No division */ btsr = 0x00;/* Reset the base timer */ g2bcr1 = 0x02;/* iio group0 initial set */ g2pocr0 = 0x07; /* ISTxD2 select */ g2pocr1 = 0x07; /* ISCLK2 select */ /* tarnsmit clock */ g2pocr2 = 0x02;g2po0 = 1000-2; /* BRG = fTB / [(998+2)*2] */ g2po2 = 1; /* ch0 ch1 ch2 enable */ g2fe = 0x07;g2bcr1 = 0x12;/* Start the base timer counting */ g2cr = 0x00;/* Disable the communications */ g2mr = 0x81;/* Clocked synchronous serial, LSB first */

```
/* iio group0 interrupt initial set */
```

| iio5ie = 0x01; iio6ie = 0x01; iio5ir = 0x00; | /* Use the interrupt request for an interrupt */ /* Use the interrupt request for an interrupt */ | | |
|--|--|--|--|
| iio 6 ir = 0x00; iio 5 ie = 0x11; iio 6 ie = 0x11; iio 5 ic = 0x03; iio 6 ic = 0x03; | /* Enable interrupt to gr1 sio receive */ /* Enable interrupt to gr1 sio trans */ /* Select interrupt priority level */ /* Select interrupt priority level */ | | |
| /* port set */ psc = 0x01; psl1 = 0x00; psl0 = 0x10; ps0 = 0x10; psl0 = 0x10; psl0 = 0x10; ps0 = 0x10; /* interrupt enable */ _asm("fset i"); | | | |
| /* sio initial setting */ g2bcr1 = 0x02; g2bcr0 = 0x7f; | /* Start the base timer counting */ /* b0,b1: count source f1 b2to b6: count source division ratio : No division */ | | |
| g2bcr1 = 0x12; g2cr = 0x11; | /* Start the base timer counting */ /* transmit / receive */ | | |
| g2tb = 0x0200; | /* 2Bit Write the transmit data */ | | |
| while(1); | | | |
| } /* iio interrupt */ void receive_int(void){ iio5ir = 0x00; rec_buff = g2rb; } | /* Clear interrupt request */ /* Receive the transmit data */ | | |
| void trans_int(void){ int wait; static char send_data; | | | |
| iio6ir = 0x00; send_data ++; | /* Clear interrupt request */ | | |
| <pre>/* Change the transmit data length */ if(send_bits == 0x600){ send_bits = 0x200; }else{ send_bits = 0x600; }</pre> | | | |
| /* Weight to measure with oscilloscope is usually unneeded. */ for(wait=0; wait < 2000; wait ++); | | | |
| g2tb = send_bits + send_data; /* Write the transmit data */ | | | |
| /* end program */ | | | |

5. Example Waveform and Result

The transmit clock is output from a pin ISCLK2 (P64) and the transmit data is output from a pin ISTxD2 (P70) by using the Intelligent I/O Group 2.

Conditions: Supply voltage = 5V,

Main clock (Xin) = 10MHz

Base Timer Count Source (fBT2) = 30MHz (f1 no division)

Transmission speed : 50kbps (10MHz / 200 : register G2P00 value = 98) \rightarrow 20 μ / bit



Measurement result from oscilloscope

6. Reference

HADWARE MANUAL Refer to the M32C/ 83 group HARDWARE MANUAL.

7. Web-site and contact for support

Renesas Web-site

http://www.renesas.com

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REVISION HISTORY

| Rev. Issue date | Revised | | | |
|-----------------|--------------|-------|---|--|
| | Page | Point | | |
| 1.00 | Jan 30, 2004 | - | First edition issued | |
| 1.01 | Sep.16,2004 | 2, 4 | Inverted waveform output mode \rightarrow phase-delayed waveform mode | |



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