

Application Note

V850E/RS1TM

32-Bit Single-Chip Microcontrollers
CSI3 Serial Interface and DMA Application

 $\mu PD70F3403, \, \mu PD70F3402$

NOTES FOR CMOS DEVICES -

(1) PRECAUTION AGAINST ESD FOR SEMICONDUCTORS

Note:

Strong electric field, when exposed to a MOS device, can cause destruction of the gate oxide and ultimately degrade the device operation. Steps must be taken to stop generation of static electricity as much as possible, and quickly dissipate it once, when it has occurred. Environmental control must be adequate. When it is dry, humidifier should be used. It is recommended to avoid using insulators that easily build static electricity. Semiconductor devices must be stored and transported in an anti-static container, static shielding bag or conductive material. All test and measurement tools including work bench and floor should be grounded. The operator should be grounded using wrist strap. Semiconductor devices must not be touched with bare hands. Similar precautions need to be taken for PW boards with semiconductor devices on it.

(2) HANDLING OF UNUSED INPUT PINS FOR CMOS

Note:

No connection for CMOS device inputs can be cause of malfunction. If no connection is provided to the input pins, it is possible that an internal input level may be generated due to noise, etc., hence causing malfunction. CMOS devices behave differently than Bipolar or NMOS devices. Input levels of CMOS devices must be fixed high or low by using a pull-up or pull-down circuitry. Each unused pin should be connected to VDD or GND with a resistor, if it is considered to have a possibility of being an output pin. All handling related to the unused pins must be judged device by device and related specifications governing the devices.

(3) STATUS BEFORE INITIALIZATION OF MOS DEVICES

Note:

Power-on does not necessarily define initial status of MOS device. Production process of MOS does not define the initial operation status of the device. Immediately after the power source is turned ON, the devices with reset function have not yet been initialized. Hence, power-on does not guarantee out-pin levels, I/O settings or contents of registers. Device is not initialized until the reset signal is received. Reset operation must be executed immediately after power-on for devices having reset function.

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Introduction

Readers This application note is intended for users who want to understand the func-

tions of the V850E/RS1.

Purpose This application note presents the hardware application note of the

V850E/RS1.

Organization This system specification describes the following sections:

Library handling

· Reprogramming the device

Watchdog-handling

· Hardware requirements

· Used device resources

Legend Symbols and notation are used as follows:

Weight in data notation: Left is high-order column, right is low order column

Active low notation : \overline{xxx} (pin or signal name is over-scored) or

/xxx (slash before signal name)

Memory map address: : High order at high stage and low order at low stage

Note : Explanation of (Note) in the text

Caution : Information requiring particular attention

Remark : Supplementary explanation to the text

Numeric notation : Binary... xxxx or xxxB

Decimal... xxxx

Hexadecimal... xxxxH or 0x xxxx

Prefixes representing powers of 2 (address space, memory capacity)

K (kilo): $2^{10} = 1024$

M (mega): $2^{20} = 1024^2 = 1,048,576$ G (giga): $2^{30} = 1024^3 = 1,073,741,824$

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Chapter 1 Overview

The V850E/RS1 single chip microcontroller is a member of NEC's V850 32-bit RISC family, which match the performance gains attainable with RISC-based controllers to the needs of embedded control applications.

The V850E CPU offers easy pipeline handling and programming, resulting in compact code size comparable to 16-bit CISC CPUs.

The V850E/RS1 offers an excellent combination of general purpose peripheral functions, like serial communication interfaces (UART, clocked SI, clocked SI with translation buffer), timers and measurement inputs (A/D converter), with dedicated CAN network support. The device offers power-saving modes to manage the power consumption effectively under varying conditions. Thus equipped, the V850E/RS1 is ideally suited for automotive applications.

This application note is written to describe a CSI3 transmit and receive operation procedure using the V850E/RS1 microcontroller. CSI3 interface is a 3-wire serial synchronous interface with a dedicated transmit and receive FIFO buffer of 16 elements. It also provides the chip select for each data to be transmitted and received.

The CSI3 communication is done using two different methods with and without DMA implementation:

- FIFO buffer transfer mode
- Single buffer transfer mode

A timer provides a cycle period of time to send the data frame of 16 elements every 300 μ s. Transfer data length is 8 bits.

Queued CSI serial clock is 4 MHz using below operation mode:

- Master Mode
- Transmit/Receive Mode

The timing measurement highlights:

- Setup Time: time in between chip select active to first rising edge of the serial clock (SCK3)
- Hold Time: time in between the last falling edge of the serial clock (SCK3) and the inactive level of the chip select
- Time to transmit the complete frame of 16 data of 8 bits.

Remark: Other configuration of the CSI3 and DMA interface could be adapted to dedicated customers needs.

Chapter 2 Queued CSI3 Description (CSI30, CSI31)

2.1 Features

- 3-wire serial synchronous transfers
- The following 7 pins are provided to enable a 3-wire serial interface:
 - (a) SO3 (serial data output)
 - (b) SI3 (serial data input)
 - (c) SCK3 (serial clock I/O)
 - (d) CS30 CS33 (Chip Select)
- Master mode and slave mode selectable
- · Serial clock and data phase selectable
- Transfer date length selectable from 8 to 16 bits in 1-bit units
- Data transfer with MSB- for LSB-first selectable
- Three selectable transfer modes:
 - (a) transmit only mode
 - (b) receive only mode
 - (c) transmit/receive mode
- Transmit and receive FIFO (16 elements)
- Selection between single buffer transfer mode and FIFO buffer transfer mode
- Internal baud rate generator
- Programmable baudrate through BRG output (master) or slave clock
- DMA transfer of received data to memory available

Maximum SCK3 frequency: 10 MHz

2.1.1 CSI3 block diagram

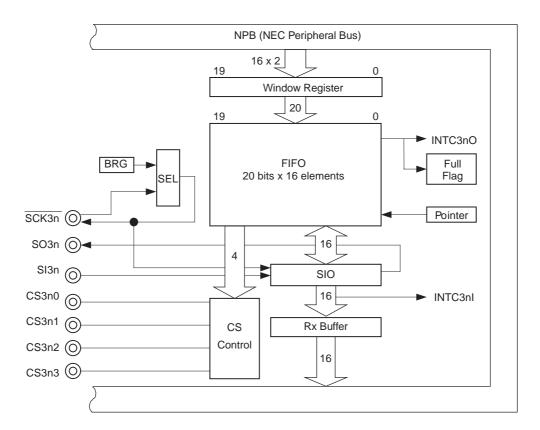


Figure 2-1: Queued CSI Block Diagram

2.1.2 Input/output pins

The table below shows the input/output pins of the CSI3.

Signal I/O Active level Disabled level **Function** name SCK3n I/O Н Serial clock signal SI3n 1 Input serial data signal SO₃n 0 Output serial data signal Note 2 HNote 2 CS3n0 0 Serial peripheral chip select signal Note 2 HNote 2 Serial peripheral chip select signal CS3n1 0 Note 2 HNote 2 CS3n2 0 Serial peripheral chip select signal Note 2 HNote 2 CS3n2 Serial peripheral chip select signal

Table 2-1: Input/Output Pins of the CSI3

Notes: 1. n = 0, 1

2. The active level is programmable for each chip select.

2.2 Queued CSI Control Registers

(1) Register map

The tables below show the Special Function Registers for the Queued CSI modules CSI30 and CSI31.

Table 2-1: CSI30

Pogistor name	Function	Address	Reset Value		R/W		
Register name	Function	Address	Neset value	1-bit	8-bit	16-bit	IN/VV
CSIM0	Queued CSI operation mode register	FFFFFD40H	00H	0	0	-	R/W
CSIC0	Queued CSI clock selection register	FFFFFD41H	07H	0	0	-	R/W
SIRB0	Receive data buffer	FFFFFD42H	0000H	-	-	0	R
SIRB0L	Receive data buffer L	FFFFFD42H	00H	-	0	-	R
SFCS0	Chip Select FIFO buffer	FFFFFD44H	FFFFH	-	-	0	R/W
SFCS0L	Chip Select FIFO buffer L	FFFFFD44H	FFH	-	0	-	R/W
SFDB0	Transmit data FIFO buffer	FFFFFD46H	0000H	-	-	0	R/W
SFDB0L	Transmit data FIFO buffer L	FFFFFD46H	00H	-	0	-	R/W
SFA0	FIFO status register	FFFFFD48H	20H	0	0	-	R/W
CSIL0	Data length select register	FFFFFD49H	00H	0	0	-	R/W
SFN0	Transfer number select register	FFFFFD4CH	00H	0	0	-	R/W

Table 2-2: CSI31

Register name	Function	Address	Reset Value		R/W		
Register flame	Function	Addiess	Neset value	1-bit	8-bit	16-bit	IX/VV
CSIM1	Queued CSI operation mode register	FFFFFD60H	00H	0	0	-	R/W
CSIC1	Queued CSI clock selection register	FFFFFD61H	07H	0	0	-	R/W
SIRB1	Receive data buffer	FFFFFD62H	0000H	-	-	0	R
SIRB1L	Receive data buffer L	FFFFFD62H	00H	-	0	-	R
SFCS1	Chip Select FIFO buffer	FFFFFD64H	FFFFH	-	-	0	R/W
SFCS1L	Chip Select FIFO buffer L	FFFFFD64H	FFH	-	0	-	R/W
SFDB1	Transmit data FIFO buffer	FFFFFD66H	0000H	-	-	0	R/W
SFDB1L	Transmit data FIFO buffer L	FFFFFD66H	00H	-	0	-	R/W
SFA1	Transmit FIFO status register	FFFFFD68H	20H	0	0	-	R/W
CSIL1	Data length select register	FFFFFD69H	00H	0	0	-	R/W
SFN1	Transmit data number select register	FFFFFD6CH	00H	0	0	-	R/W

(2) Queued CSI operation mode registers (CSIM0, CSIM1)

The CSIM registers control the Queued CSI macro's operations.

These registers can be read or written in 1-bit and 8-bit units.

TRMD, DIR, CSIT, CSWE, CSMD bits can only be written when CTXE = 0 and CRXE = 0.

The registers are initialized to 00H at reset.

Figure 2-2: Queued CSI Operation Mode Registers (CSIM0, CSIM1) Format (1/2)

Symbol	7	6	5	4	3	2	1	0	Address	R/W	reset
CSIMn (n = 0, 1)	POWER	CTXE	CRXE	TRMD	DIR	CSIT	CSWE	CSMD	FFFFFD40H, FFFFFD60H	R/W	00H

POWER	Queued CSI operation clock control				
0	Stop macro operation clock (Reset internal control circuits)				
1	Provide macro operation clock				
Clearing POWER = "0" resets the internal circuits asynchronously, stops operation and sets the					

Queued CSI to standby state. Input clock is not provided to internal circuits.

Set POWER = "1" to activate the Queued CSI.

Caution: When changing the POWER bit, do not change any other bit at the same time.

While POWER="0", the only registers that can be accessed are CSIM, SFDB, SFDBL, and SFA.

Set the POWER bit before writing any of the other bits of CSIMn.

CTXE	Transmission enable/disable
0	Transmission disabled
1	Transmission enabled

CRXE	Receive enable/disable
0	Receive disabled
1	Receive enabled

TRMD	Transfer mode select
0	Single buffer transfer mode
1	FIFO buffer transfer mode

Caution: Write is permitted only when CTXE = 0 and CRXE = 0.

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Figure 2-3: Queued CSI Operation Mode Registers (CSIM0, CSIM1) Format (2/2)

DIR	Serial data direction selection
0	Data is sent/received with MSB first
1	Data is sent/received with LSB first

Caution: Write is permitted only when CTXE = 0 and CRXE = 0.

See section **2.3.2** "Serial data direction select function" on page **29** for further details on the DIR bit setting.

CSIT	Interrupt delay mode select (INTC3nl signal)
0	No delay
1	Half clock delay

Caution: Write is permitted only when CTXE = 0 and CRXE = 0.

This bit is only valid in master mode. In slave mode, no delay is generated.

Ī	CSWE	Transmission wait enable/disable select
Ī	0	Transmission wait disable. Not insert 1 clock (SCK3) wait at transmission start.
I	1	Transmission wait enable. Insert 1 clock (SCK3) wait at transmission start.

Caution: Write is permitted only when CTXE = 0 and CRXE = 0.

This bit is only valid in master mode. In slave mode, no wait is generated.

CSMD	Chip Select mode select
0	Chip select inactive level output disable. Do not force chip select inactive state after each transfer of a data element.
1	Chip select inactive level output enable. Hold all chip selects inactive for halt-length SCK3 after each transfer of a data element.

Caution: Write is permitted only when CTXE = 0 and CRXE= 0.

This bit is only valid for CSWE=1.

This bit is only valid in master mode. In slave mode, CS signals are always held at inactive level.

In combination:

CSWE	CSMD	Transmission wait	Chip Select inactive level
0	0	None	Not output
0	1	None	Not output
1	0	One SCK3 length clock wait	Not output
1	1	One SCK3 length clock wait	Output inactive level of half-length SCK3 during first half of transmission wait

See section **2.3.10** "Additional timing and delay selections" on page **37** for further details on the timing selections by CSIT, CSWE, CSMD bits.

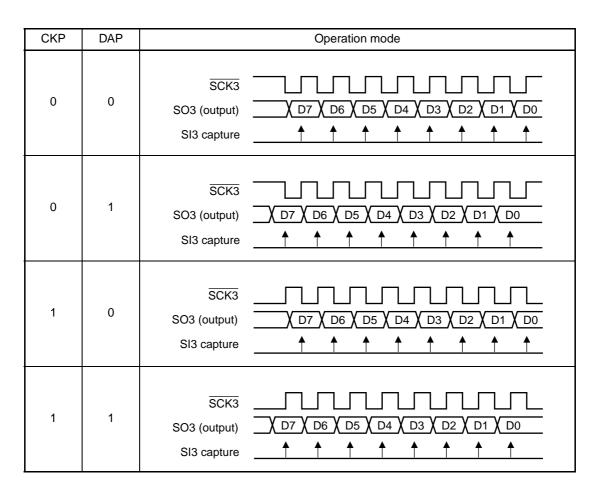
(3) Queued CSI clock selection registers (CSIC0, CSIC1)

The CSIC register is an 8-bit register that is used to control the serial transfer operations. This register can be read or written in 1-bit and in 8-bit units.

Caution: This register can be written only while CSIM register's CTXE = 0 and CRXE = 0.

Figure 2-4: Queued CSI Clock Selection Registers (CSIC0, CSIC1) Format (1/2)

Symbol	7	6	5	4	3	2	1	0	Address	R/W	After reset
CSICn (n = 0, 1)	MDL2	MDL1	MDL0	СКР	DAP	CKS2	CKS1	CKS0	FFFFFD41H, FFFFFD61H	R/W	07H



Caution: Modification of these bits is permitted only when CTXE = 0 and CRXE = 0.

Remark: CKP: Clock phase selection bit

DAP: Data phase selection bit

Figure 2-5: Queued CSI Clock Selection Registers (CSIC0, CSIC1) Format (2/2)

CKS2	CKS1	CKS0	Prescaler output (PRSOUT)	Mode	К
0	0	0	f _{QCSI}	Master Mode	0
0	0	1	f _{QCSI} /2	Master Mode	1
0	1	0	f _{QCSI} /4	Master Mode	2
0	1	1	f _{QCSI} /8	Master Mode	3
1	0	0	f _{QCSI} /16	Master Mode	4
1	0	1	f _{QCSI} /32	Master Mode	5
1	1	0	f _{QCSI} /64	Master Mode	6
1	1	1	SCK3 (input) Note	Slave Mode	-
These bits are used to select the input clock					

Note: SCK3 pin is configured as input mode for serial transfer clock.

f_{OCSI} is the clock supply of the Queued-CSI macro.

Caution: Rewriting these bits is only permitted when CSIE = 0.

See sections **2.3.4** "Slave mode" on page **30** and **2.3.5** "Master mode" on page **31** for further explanation on slave mode and master mode.

MDL2	MDL1	MDL0	Operation clock	N		
0	0	0	BRG disable	_	BRG stop for power saving	
0	0	1	PRSOUT/2	1		
0	1	0	PRSOUT/4	2		
0	1	1	PRSOUT/6	3		
1	0	0	PRSOUT/8	4		
1	0	1	PRSOUT/10	5		
1	1	0	PRSOUT/12	6		
1	1	1	PRSOUT/14	7		
These bits	These bits are used to modulate the selected clock					

Caution: Rewriting these bits is only permitted when CTXE = 0 and CRXE = 0. MDL [2:0] = [0,0,1] is prohibited when CKS [2:0] = [0,0,0].

See section **2.3.6** "**Transmission clock select function**" on page 31 for further explanation on the transfer clock selection.

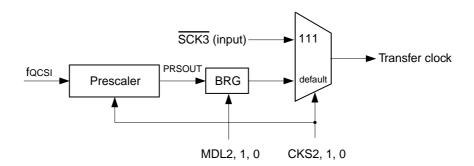
The baudrate for the transmission is calculated with the following formula:

Transmission Baud Rate = f/(N*2(K+1))

where: f: f_{QCSI} frequency,

N = 1 - 7, K = 0 - 6.

Figure 2-6: Queued CSI Baud Rate Block Diagram



(4) Queued CSI macro clock selection (f_{QCSI}): Extension clock select register (EXCKSEL)

The input clock of the CSI3 (f_{QCSI}) is provided either by the extension clock register or the system clock.

This is an 8-bit register that selects the internal clock. This register can be read or written in 8-bit or 1-bit units.

Figure 2-7: Extension Clock Select Register (EXCKSEL) Format

Symbol	7	6	5	4	3	2	1	0	Address	After reset
EXCKSEL	0	0	CB1CKSEL	CB0CKSEL	CS31CKSEL	CS30CKSEL	AF1CKSEL	AF0CKSEL	FFFFF30CH	00H
R/W	R	R/W	R/W	R/W	R/W	R/W	R/W	R/W		

CB1CKSEL	CSIB1 Clock selection
0	Normal clock selection (f _{XX})
1	Extended clock selection (f _{PLL_PCKSEL})

CB0CKSEL	CSIB0 Clock selection		
0	Normal clock selection (f _{XX})		
1	Extended clock selection (f _{PLL_PCKSEL})		

I	CS31CKSEL	CSI31 Clock selection			
Ī	0	Normal clock selection (f _{XX})			
I	1	1 Extended clock selection (f _{PLL_PCKSEL})			

CS30CKSEL	CSI30 Clock selection		
0	Normal clock selection (f _{XX})		
1	Extended clock selection (f _{PLL_PCKSEL})		

AF1CKSEL	CAN1 Clock selection			
0	ormal clock selection (f _{XX})			
1	Extended clock selection (f _{PLL_PCKSEL})			

AF0CKSEL	CAN0 Clock selection
0	Normal clock selection (f _{XX})
1	Extended clock selection (f _{PLL_PCKSEL})

Caution: Before modifying EXCKSEL register value, corresponding peripheral I/O function have to be stopped.

When set to 1 either bit 5 or 4 of EXCKSEL register, be sure to set bit 4 of OCKS2 register (OCKSEN2 bit) to 1.

Remark: See RS1 user's manual for details description (UD16702EE1V0UD00)

(5) Receive data buffer registers (SIRB0, SIRB1)

The SIRB register is a 16-bit register or separated as upper 8 bits (SIRBH) and lower 8 bits (SIRBL), that is used to store receive data. This register can be read in 8-bit or 16-bit units and is initialized to 0000H by reset.

Figure 2-8: Receive Data Buffer Registers (SIRB0, SIRB1) Format

	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	Address	R/W	Initial value
SIRBn (n=0, 1)																	FFFF FD42H, FFFF FD62H	R/W	0000H

SIRB15 - SIRB0	Data received from the SIO serial shift register.

Caution: The receive data buffer register is considered as emptied by the application software whenever the lower 8 bits of the register are read. It is therefore necessary to read SIRBH before SIRBL when 8-bit access is used.

(6) Chip select data buffer registers (SFCS0, SFCS1)

The SFCS register is a 16-bit register, or separated as upper 8 bits (SFCSH) and lower 8 bits (SFCSL), that stores Chip Select data. This register is read/write-enabled and is accessible in 8-bit or 16-bit units. Initial value is FFFFH by reset.

Following the FIFO write pointer, the value written to SFCS is stored in the FIFO data buffer as Chip Select bits. The value is stored to these bits when the transmit data is written to its register (SFDB or SFDBL).

SFCS write is prohibited when POWER = 1 and f_{OCSI} is stopped.

Figure 2-9: Chip Select Data Buffer Registers (SFCS0, SFCS1) Format

	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	Address	R/W	Initial value
SFCSn (n=0, 1)	-	ı	ı	ı	-	ı	ı	ı	1	1	1	-	SFCS 3	SFCS 2	SFCS 1	SFCS 0	FFFF FD44H, FFFF FD64H	R/W	FFFFH

SFCSm	Chip Select Output Selection (m=0 to 3)
0	Output an inactive level at the CS3nm pin during the data transfer
1	Output an active level at the CS3nm pin during the data transfer

Caution: The Chip Select register is stored in the FIFO buffer when the transmit data is written to its register. It is therefore necessary to write the SFCS register before the SFDB (SFDBL) register.

Remark: The active level for each chip select is defined in the CSILn register (CSA[3:0] bits)

(7) Transmission data buffer registers (SFDB0, SFDB1)

The SFDB register is a 16-bit buffer register, or separated as upper 8 bits (SFDBH) and lower 8 bits (SFDBL), that stores transmission data. The SFDB register is read/write-enabled and is accessible in 8-bit or 16-bit units. Initial value is 0000H by reset.

Incrementing and following the FIFO buffer write pointer, the value written to SFDB is stored to the FIFO buffer as transmission data.

SFDB write is prohibited when POWER = 1 and f_{OCSI} is stopped.

Figure 2-10: Transmission Data Buffer Registers (SFDB0, SFDB1) Format

	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	Address	R/W	Initial value
SFDBn (n=0, 1)																	FFFF FD46H, FFFF FD66H	R/W	0000H

SFDB15 - SFDB0 Write data is stored to the FIFO data buffer as transmission data.
A read operation reads out the last stored transmission data.

Caution: The transmit data buffer register is considered as written whenever the lower 8 bits of the register are written. It is therefore necessary to write SFDBH before SFDBL when 8-bit access is used.

(8) FIFO buffer status registers (SFA0, SFA1)

The SFA register is an 8-bit register that shows the FIFO buffer status. The SFA register is read/write-enabled, accessible in 1-bit or 8-bit units. However, the bits SFFUL, SFEMP and CSOT are read only. Initial value is 20H by reset.

SFA read is prohibited when POWER = 1 and f_{QCSI} is stopped.

Figure 2-11: FIFO Buffer Status Registers (SFA0, SFA1) Format (1/2)

Symbol	7	6	5	4	3	2	1	0	Address	R/W	After reset
SFAn (n = 0, 1)	FPCLR	SFFUL	SFEMP	CSOT	SFP3	SFP2	SFP1	SFP0	FFFFFD48H, FFFFFD68H	R/W	20H

FPCLR	FIFO buffer pointer clear command						
0	No operation						
1	Clear all FIFO pointers to "0"						

Remark: Read value is always "0".

Figure 2-12: FIFO Buffer Status Registers (SFA0, SFA1) Format (2/2)

SFFUL	FIFO buffer full status flag
0	FIFO buffer is not full
1	FIFO buffer is full

Remark: Read only

SFEMP	FIFO buffer empty status flag
0	FIFO buffer is not empty
1	FIFO buffer is empty

Remark: Read only

	CSOT	Transmission status flag						
	0	Idle state						
Ī	1	Transmission in on going or preparing						

Remarks: 1. Read only bit.

- 2. This bit is cleared to "0" by POWER = 0 or (CTXE = 0 and CRXE = 0).
- 3. In Single Buffer Transfer Mode, this bit holds "1" from transmission start to FIFO empty.
- **4.** In FIFO Buffer Transfer Mode, this bit holds "1" from transmission start until finish transferring all data to be sent.

SFP3 - SFP0	Transmission data count
Hnnnn	In Single transfer mode, SFP3 - SFP0 indicates the number of remaining transfers in the FIFO. This value can be understood as: (Write FIFO pointer) - (SIO load pointer) SFP3 - SFP0 is read only in Single transfer mode.
	In FIFO transfer mode,SPF3 - SFP0 indicates the number of data transfers completed. In case of SFP3 - SFP0 = 0H: - SFEMP = 0, SFP3 - SFP0 = 0H: Number of receptions completed = 0 - SFEMP = 1, SFP3 - SFP0 = 0H: Number of receptions completed = 16

Remarks: 1. Read only bits.

2. SFP3 - SFP0 holds its value until RESET or FPCLR = 1.

Caution: SFFUL, SFEMP, CSOT and SFP3 - SFP0 are continuously updated with the current status of the Queued CSI. This means that a value read might be outdated shortly after the read was executed.

When writing accidentally a 17th data element in FIFO, an overflow interrupt (INTC3nO) will occur to indicate the error.

(9) Queued CSI data length selection registers (CSIL0, CSIL1)

The CSIL register is an 8-bit register that specifies the active voltage level of the Chip Select pins and the Queued CSI data length.

This register can be read or written in 1-bit and 8-bit units.

This register can be overwritten only while CTXE = 0 and CRXE = 0 (CSIM register). Write operation during CTXE = 1 or CRXE = 1 is prohibited.

Initial value is 00H by reset.

Figure 2-13: Queued CSI Data Length Selection Registers (CSIL0, CSIL1) Format

Symbol	7	6	5	4	3	2	1	0	Address	R/W	After reset
CSILn (n = 0, 1)	CSLV3	CSLV2	CSLV1	CSLV0	CCL3	CCL2	CCL1	CCL0	FFFFFD49H, FFFFFD69H	R/W	00H

CSLV3 - CSLV0	Chip Select active level selection			
0	Chip Select signal is active low			
1	Chip Select signal is active high			

CCL3	CCL2	CCL1	CCL0	Transfer data length			
0	0	0	0	Data length is 16 bits			
0	0	0	1				
0	0	1	0				
0	0	1	1				
0	1	0	0	Setting prohibited			
0	1	0	1				
0	1	1	0				
0	1	1	1				
1	0	0	0	Data length is 8 bits			
1	0	0	1	Data length is 9 bits			
1	0	1	0	Data length is 10 bits			
1	0	1	1	Data length is 11 bits			
1	1	0	0	Data length is 12 bits			
1	1	0	1	Data length is 13 bits			
1	1	1	0	Data length is 14 bits			
1	1	1	1	Data length is 15 bits			

Caution: Rewriting this register is only permitted when CTXE = 0 and CRXE = 0.

See section **2.3.3** "Data length select function" on page **30** for further explanation on the data length selection.

(10) Queued CSI transfer number selection registers (SFN0, SFN1)

The SFN register is an 8-bit register that specifies the number of data elements to be transferred in FIFO buffer transfer mode. It can be read or written in 1-bit and 8-bit units. Initial value is 00H by reset.

Figure 2-14: Queued CSI Transfer Number Selection Registers (SFN0, SFN1) Format

Symbol	7	6	5	4	3	2	1	0			After reset
SFNn (n = 0, 1)	0 ^{Note}	0 ^{Note}	0 ^{Note}	0 ^{Note}	SFN3	SFN2	SFN1	SFN0	FFFFFD4CH, FFFFFD6CH	R/W	00H

Note: Unused bits must be written as 0.

SFN3	SFN2	SFN1	SFN0	Transfer data number
0	0	0	0	Transfer 16 data elements
0	0	0	1	Transfer 1 data element
0	0	1	0	Transfer 2 data elements
0	0	1	1	Transfer 3 data elements
0	1	0	0	Transfer 4 data elements
0	1	0	1	Transfer 5 data elements
0	1	1	0	Transfer 6 data elements
0	1	1	1	Transfer 7 data elements
1	0	0	0	Transfer 8 data elements
1	0	0	1	Transfer 9 data elements
1	0	1	0	Transfer 10 data elements
1	0	1	1	Transfer 11 data elements
1	1	0	0	Transfer 12 data elements
1	1	0	1	Transfer 13 data elements
1	1	1	0	Transfer 14 data elements
1	1	1	1	Transfer 15 data elements

2.3 Explanation of Queued CSI Functions

2.3.1 Transmit buffer

Chip select data and transmission data can be stored to the transmit FIFO buffer continuously by writing to the SFCS register and SFDB register. The Writing FIFO pointer is automatically incremented when data is written to SFDB. The size of the transmit FIFO buffer is 20 bits \times 16 entries.

In slave mode, chip select data does not need to be set.

The transfer start condition (SFEMP = 0) is to write to the lower bits of SFDB register. If the transmission data length is 9 bits or more, data should be written by a 16-bit write to SFDB or by two 8-bit writes to first SFDBH, then SFDBL (in that order). When transmission data length is 8 bits, data should be set by one 8-bit write to SFDBL or by one 16-bit write to SFDB. For the 16-bit write the upper 8 bits are ignored in the 8-bit transmission.

The SFFUL bit in the SFA status register is set "1" after 16 writes have been made to the transmit buffer, assuming the Writing FIFO pointer was reset previously.

When a transmission write is attempted while the FIFO is full (SFFUL=1), the interrupt INTC3nO is generated to indicate an overflow. In that case, the transmission and chip select data are discarded and not stored.

When a transfer cycle is finished and the SIO Loading FIFO pointer is incremented, the FIFO buffer of the previous location is considered empty in case of single buffer transfer mode. Refer to section 2.3.8 on page 34 for more information on FIFO buffer transfer mode.

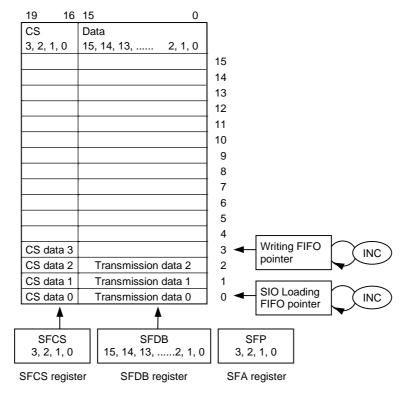
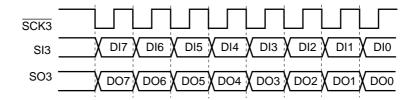


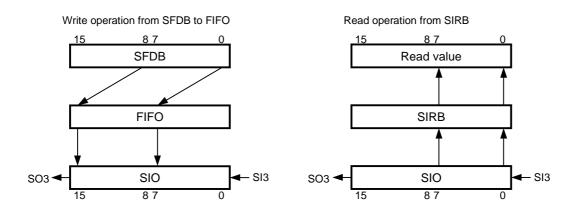
Figure 2-15: Transmit Buffer

2.3.2 Serial data direction select function

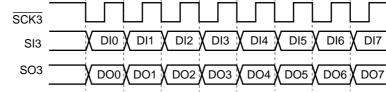
The serial data direction is selectable using the DIR bit in the CSIM register. The examples below show the communication for data length of 8 bit (CCL[3:0] = [1,0,0,0]):

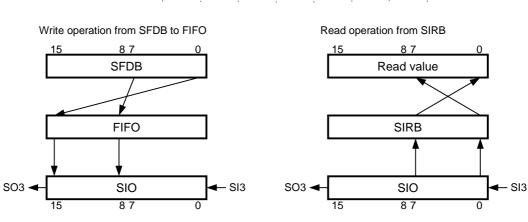
Figure 2-16: Serial Data Direction Select Function
(a) MSB first (DIR = 0)











2.3.3 Data length select function

Transmission data length is selectable from 8 bits to 16 bits using the CCL[3:0] bits in CSIL register. The examples below show the communication with MSB first (DIR = 1):

CCL[3:0] = [0,0,0,0] (data length=16): SCK3 SO3 DI15 DI14 DI13 DI12 DI2 DI0 SI3 CCL[3:0] = [1,1,1,0] (data length=14): SCK3 DO₂ SO₃ SI3 DI13 DI12 DI11 DI10 DI2

Figure 2-17: Data Length Select Function

2.3.4 Slave mode

When the CKS[2:0] bits in CSIC are set to [1,1,1], the Queued CSI operates in slave mode. In slave mode, the SCK3 serial clock pin becomes input and another device is the CSI communication master. The baud rate generator "BRG" is recommended to be disabled by setting bits MDL[2:0] to [0,0,0] when using slave mode. Also, the chip select pin CS3n[3:0] outputs are not available in slave mode, as they are only available in master mode.

The example below shows the communication in slave mode for 8 data bits, CKP=0, DAP=0 and MSB first:

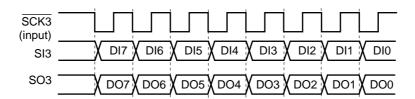


Figure 2-18: Slave Mode

2.3.5 Master mode

When the CKS[2:0] bits in CSIC are not set to [1,1,1], the Queued CSI operates in master mode. In master mode, the $\overline{SCK3}$ pin is configured as output and the serial communication clock is generated by the Queued CSI module. The $\overline{SCK3}$ pin's default value is "1" when CKP = 1, and is default "0" when CKP = 0. The CS3n[3:0] pin outputs are available in master mode.

The example below shows the communication in master mode for 8 data bits, CKP=0, DAP=0 and MSB first:

SCK3 (output) DI6 DI5 DI4 DI3 DI1 DI0 SI3 SO₃ DO7 DO6 DO5 DO4 DO3 DO2 DO1 DO0

Figure 2-19: Master Mode

2.3.6 Transmission clock select function

In Master Mode, the transfer baud rate is selectable using CKS[2:0] bits and MDL[2:0] bits in CSIC register. The baud rate generator "BRG" counts up at each rising edge of f_{OCSI}.

The example below illustrates the baud rate generation for MDL[2:0] = [0,1,0].

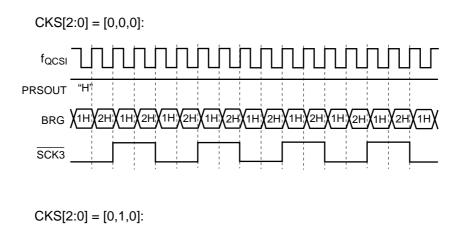
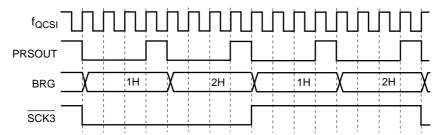


Figure 2-20: Transfer Clock Select Function



2.3.7 Description of the single buffer transfer mode

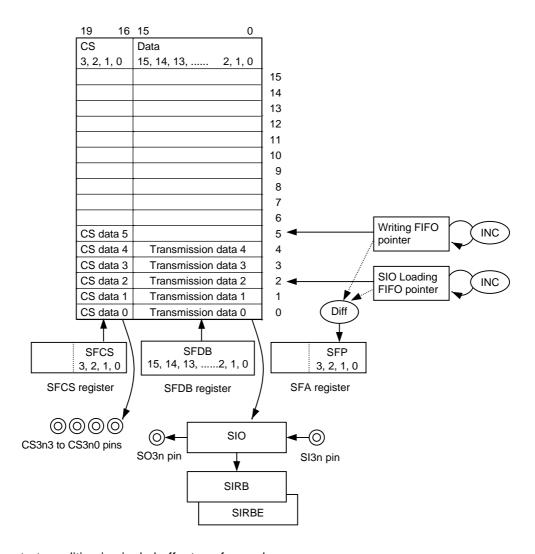


Figure 2-21: Single Buffer Transfer Mode Data Handling

Transfer start condition in single buffer transfer mode:

[CTXE = 1 or CRXE = 1] and [Data exists in FIFO (SFEMP = 0)]

A transfer starts once the transmission data (pointed to by the SIO Loading FIFO pointer) is transferred from the FIFO buffer to the serial shift register SIO. At that time, the transfer status flag CSOT turns to "1". The CS3n[3:0] pins output the chip select data from the FIFO buffer.

At the end of the transfer:

- (A) If SIRB is empty, the received data is stored from SIO to SIRB, and transfer end interrupt signal INTC3nI is generated (in transmit only mode, INTC3nI will be generated only when the FIFO buffer becomes empty). Finally, the SIO loading FIFO pointer is incremented.
- (B) If SIRB is not empty, the storing of receive data, INTC3nI generation and SIO Loading FIFO pointer incrementing wait for the SIRB to be emptied by a software read operation.
- (C) In transmit only mode, if transmission data is available in the FIFO buffer, the next transfer will start immediately, regardless of the SIRB buffer condition.

When a transfer finishes and the FIFO buffer is empty (Writing FIFO pointer = SIO Loading FIFO pointer), CSOT is cleared "0".

SFP[3:0] always show the current value of: (Writing FIFO pointer) - (SIO Loading FIFO pointer).

It is recommended to check that SFFUL = 0 just before data is written to the SFDB register. If SFFUL = 1 when a write to SFDB is attempted, the overflow interrupt INT3nO is generated and the written data is ignored.

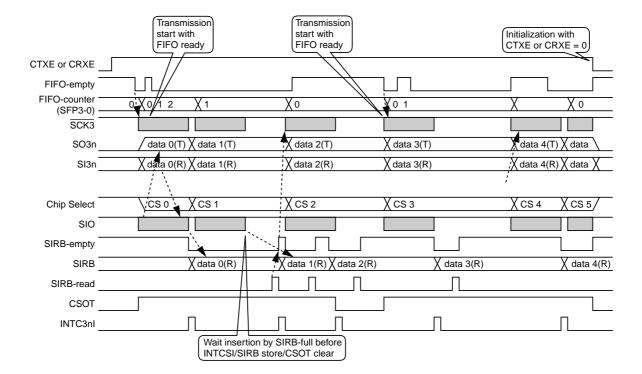


Figure 2-22: Single Buffer Transfer Mode (Master, Transmit/Receive) Timing

2.3.8 Description of the FIFO buffer transfer mode

When the TRMD bit in the CSIM register is set "1", the Queued CSI operates in FIFO buffer transfer mode.

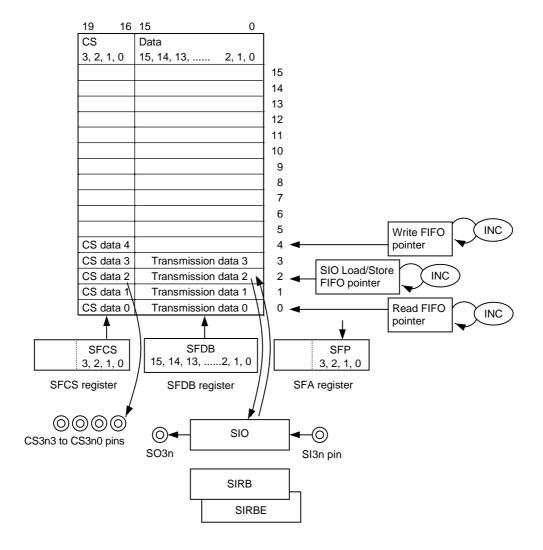


Figure 2-23: FIFO Buffer Transfer Mode Data Handling

Transfer start condition in FIFO buffer transfer mode:

[CTXE = 1 or CRXE = 1] and [Data exists in FIFO (SFEMP = 0)]

The transmission data number must be set in SFN[3:0]. Note that writing a value greater than 16 to the SFN register is prohibited, as the FIFO buffer design can hold up to 16 elements only.

The transfer starts by copying the first data element - pointed to by SIO Load/Store FIFO pointer - to the SIO shift register. At that time the transmission status flag CSOT is set to "1", and the CS3n[3:0] pins output the CS value from the FIFO.

When the transfer of the data element is finished, the received data overwrites the location in the FIFO using the SIO Load/Store FIFO pointer, and the SIO Load/Store FIFO pointer is then incremented.

Chapter 2 Queued CSI3 Description (CSI30, CSI31)

When the transmission/reception counter reaches the value set by SFN[3:0], then CSOT is cleared "0" and the transmission/reception end interrupt signal INTC3nI is generated.

After the interrupt occurred, the received data can be read from SIRB. The Read FIFO pointer is automatically incremented by the SIRB read operation.

All FIFO pointers must be cleared by setting FPCLR = 1 before the next transmit/receive cycle can start.

SFP[3:0] represents the [SIO Load/Store FIFO pointer] and shows the number of transmission/receptions completed. In case of SFP[3:0]=0H, the numbers of transmissions/receptions depends on the setting of the SFEMP bit:

SFEMP=0: 0 transmissions/receptions completed SFEMP=1: 16 transmissions/receptions completed

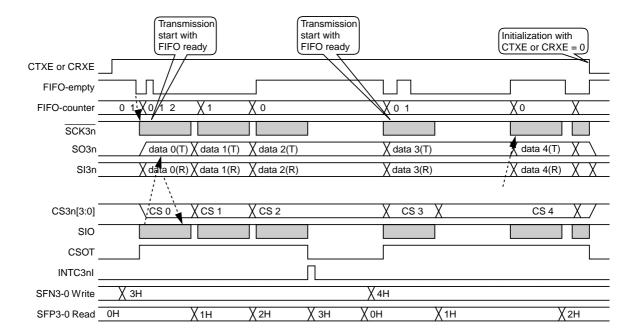


Figure 2-24: FIFO Buffer Transfer Mode (Master. Transmit/Receive) Timing

2.3.9 Description of the operation modes

(1) Transmit only mode

Setting the CSIM register's CTXE =1 and CRXE = 0 places the Queued CSI in transmit only mode. A transmission starts when transmit data is written in the SFDB register. The current condition of the SIRB buffer and SIO register no effect. The data in the SIRB and the SIO buffer is undefined after completion of the transmission.

(2) Receive only mode

Setting the CSIM register's CTXE = 0 and CRXE = 1 places the Queued CSI in receive only mode. A reception starts when dummy data is written in the SFDB register. It is mandatory, though, that the SIRB and SIO are empty. If a receive operation is terminated while the previous receive data remains unread in SIRB, the Queued CSI is placed on wait status until the previous data is completely read and SIRB becomes empty.

(3) Transmit / receive mode

Setting the CSIM register's CTXE = 1 and CRXE = 1 places the Queued CSI in transmit/receive mode. A transfer (meaning transmission and reception) starts when transmit data is written in the SFDB register. Note that an empty SIRB or SIO is mandatory. If a receive operation is terminated while the previous receive data remains unread in SIRB, the Queued CSI is placed on wait status until the previous data is completely read and SIRB becomes empty.

In FIFO buffer transfer mode with slave mode, only the first dummy data write operation is required. There is no need to write chip-select data, as these bits are ignored.

2.3.10 Additional timing and delay selections

(1) Delay selection of receive termination interrupt signal (INTC3nI)

In master mode, the CSIT bit of the CSIM register can be used to delay the generation of the receive termination interrupt signal (INTC3nI) by a half serial clock cycle (SCK3). The CSIT bit takes effect only in the master mode and is ignored in slave mode.

Figure 2-25 below illustrates the CSIT function, assuming a setting of CSIT=1, CSWE=0, CKP=0, DAP=0 and CCL[3:0] = [1,0,0,0].

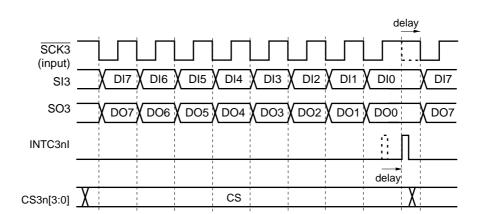


Figure 2-25: Delay Selection of Receive Termination Interrupt (INTC3nl)

(2) Selection of transmit wait enable/disable

In master mode, the CSIM register's CSWE bit setting can be used to delay the start of transmission by one SCK3 clock cycle. The CSWE bit takes effect only in the master mode and is ignored in slave mode.

Figure 2-26 below illustrates the CSWE function, assuming a setting of CSWE=1, CSMD=0, CKP=0, DAP=0 and CCL[3:0] = [1,0,0,0].

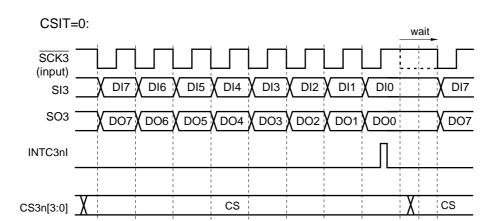
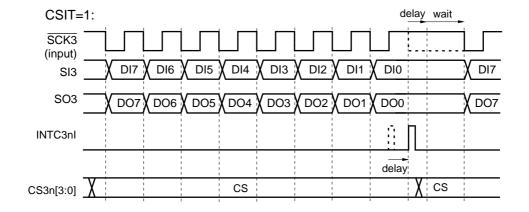


Figure 2-26: Selection of Transmit Wait Enable/Disable



(3) Selection of chip-select mode

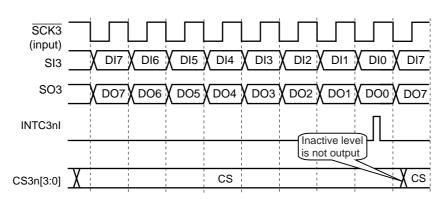
In master mode with CSWE = 1, the CSMD bit setting can be used to output an inactive level at the chip select pins CS3n[3:0] during the delay between data transmissions. The CSMD bit takes effect only in the master mode and is ignored in slave mode.

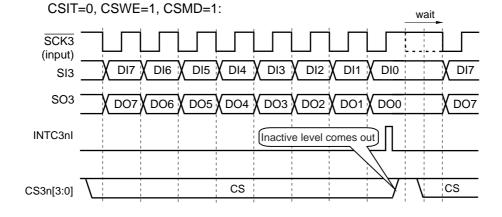
The CSMD bit has no effect while CSWE is set to 0.

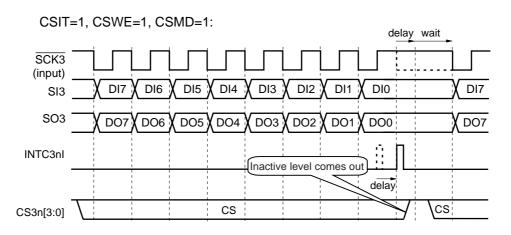
Figure 2-27 below illustrates the CSMD function, assuming a setting of CKP=0, DAP=0 and CCL[3:0] = [1,0,0,0] and the active levels of all chip selects set to "active low".

Figure 2-27: Selection of Chip-Select Mode

CSIT=0, CSWE=0, CSMD=0 or 1:







2.3.11 Default pin levels

(1) SCK3 pin's default level

SCK3 pin's default level with the CSIM register settings POWER = 0 or CTXE / CRXE = 0

CKP	CKS2, CKS1, CKS0	SCK3 default level	
0	1, 1, 1 (slave mode)	1	← Initialization after reset
	Other than 1, 1, 1 (master mode)	1	
1	1, 1, 1 (slave mode)	1	
'	Other than 1, 1, 1 (master mode)	0	

Remark: In slave mode, the SCK3 pin is always set to "1."

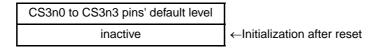
(2) SO3 pin's default level

SO3 pin's default level with the CSIM register settings POWER = 0 or CTXE / CRXE = 0

SO3 pin's default level	
0	←Initialization after reset

(3) CS3n0 to CS3n3 pins' default level

CS3n0 to CS3n3 pins' default level with the CSIM register settings POWER = 0 or CTXE / CRXE = 0 $\,$



2.3.12 Transmit buffer overflow interrupt signal (INTC3nO)

When the transmit FIFO buffer contains 16 elements, writing a 17th chip-select data (SFCS write) or transfer data (SFDB write) results in the generation of the overflow interrupt INTC3nO. For the 17th item, both chip-select and transfer data values are discarded.

The transmit FIFO buffer contains 16 elements if the FIFO pointer value for the write operation equals the FIFO pointer value for the SIO load operation plus 15. When the transfer is completed and the FIFO buffer pointer for the SIO load operation is incremented, space for one element is available again in transmit buffer.

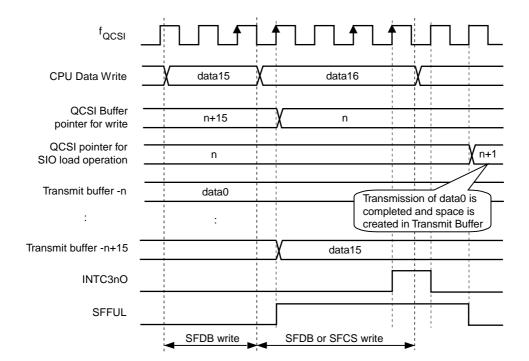


Figure 2-28: Transmit Buffer Overflow Interrupt Signal (INTC3nO)

3.1 Single Buffer Transfer Mode (Master Mode, Transmit/Receive Mode)

MSB first (DIR = 0), no INTC3nl delay (CSIT = 0), transmission wait disabled (CSWE = 0), CS inactive disabled (CSMD = 0), CKP = 1, DAP = 0, transmission data length of 8 bits (CCL[3:0] = [1,0,0,0]), active levels of all chip selects set to "active low":

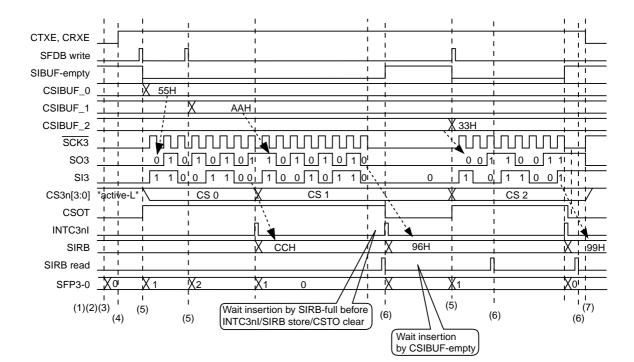


Figure 3-1: Single Buffer Transfer Mode (Master, Transmit/Receive) Timing

- 1. Set the CSIM register's POWER bit to 1 to enable the supply of the Queued CSI operation clock.
- 2. Set the CSIC and CSIL registers to specify the transfer mode.
- 3. Write "1" in the SFA register's FPCLR bit to clear all FIFO pointers.
- 4. Specify the transfer mode using the CSIM register's TRMD, DIR, and CSIT bits; at the same time, set the CTXE and CRXE bits to 1 to enable the transmit/receive operation.
- 5. Make sure that the SFA register's SFFUL bit is set to 0, then write chip-select data and transmission data in the SFCS and SFDB registers in this order.
- 6. Check for a transmission to be finished (e.g. by monitoring the INTC3nl interrupt). If so, read the SIRB register.

Repeat steps (5) and (6) until the last element is send/received and read from the SIRB register.

7. Set the CSIM register's CTXE and CRXE bits to 0 to disable the transmit/receive operation (end of transmit/receive operation).

3.1.1 Single buffer transfer mode application without DMA transfer

Only one cell of the FIFO buffer is used to transmit and receive the data.

Consequently it is useless to select in advance the number of data to be transmitted using SFN register (SFN register is only used is FIFO buffer mode).

Transmission is completed when one transmit/receive transfer of data (8 bits length) has been sent/received.

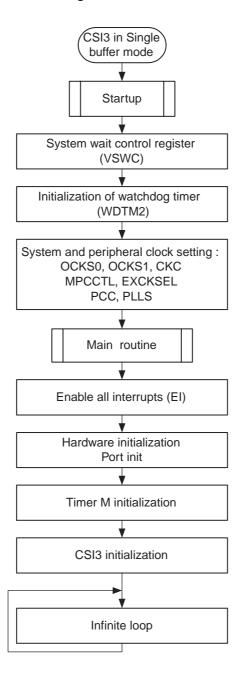
Transmission completed status is detected by monitoring the INTCSI3n interrupt.

The reading of received data is done every interrupt INTCSI3n

DMA transfer is not used.

(1) Single buffer transfer flowchart

Figure 3-2: Single Buffer Transfer Flowchart



(2) System clock and peripheral clock setting (Startup)

This routine sets the clock using the PLLs mode for the CPU, CSI3 and Timer M.

PLL0 and PLL1 output clocks are respectively assigned to the system clock and CSI3.

System clock is used for CPU and timer.

The main resonator oscillates at 8 MHz.

Be sure to set the following registers first when using the V850E/RS1.

- System wait control register (VSWC)
- On-chip Debug Mode control register (OCDM)^{Note}
- Watchdog timer mode register 2 (WDTM2)^{Note}

Note: Refer to 3.4.7 "Caution" in V850E/RS1 user's manual.

(a) NEC peripheral bus wait control

The system wait control register (VSWC) controls wait of bus access to the internal peripheral I/O registers.

Set the value to VSWC register in accordance with the frequency used.

The VSWC register can be read or written in 8-bit units.

In this application the value written to VSWC is 0x12H.

VSWC = 0x12H;

(b) Clock selection register for PLL0 and PLL1 (OCKS0, OCKS1)

Those 8-bit registers control the operation enable and clock input selection for PLL0 and PLL1.

Clock selection register 0: OCKS0 = 0x11H PLL0 input = $f_{XX}/3$ Clock selection register 1: OCKS1 = 0x13H PLL1 input = $f_{XX}/5$

(c) Clock control register (CKC)

This is an 8-bit register that controls system clock (f_{XX}) when it operates on PLL mode (SELPLL bit of MPCCTL register is set to 1). This register can be read or written in 8-bit or 1-bit units. Be sure to clear bits 2 to 7 of the CKC register to 0. In other case the operation is not guaranteed. Data can be written to this register only in combination of specific sequences (refer to 3.2.3 "Special registers" in V850E/RS1 user's manual).

CKC = 0x03Hf_{PLL MCKSEL CKDIV} = f_{PLL}(PLL internal clock)

(d) Main peripheral clock control register (MPCCTL)

This is an 8-bit register that selects the internal clock. Data can be written to this register only in combination of specific sequences (refer to 3.2.3 "Special registers" in V850E/RS1 user's manual). The clock generator flexibility allows to use either simultaneously both PLL or to use only one PLL. Both PLLs can be assigned respectively to the CPU or to the peripherals.

Switch from oscillator clock to PLL clock:

MPCCTL = 0x84HPLL mode ($f_{XX} = f_{PLL \ MCKSEL \ CKDIV}$)

Main clock (f_{PLL MCKSEL}) = PLL0

Peripheral clock = PLL1

(e) Extended clock selection (EXCKSEL)

CSI3, CSIB, and AFCAN peripherals input clocks could be either from the system clock or directly form the PLL output using the extended clock selection.

In this application CSI3 uses the extended clock in order to get a 16 MHz input clock (f_{QCSI}) while the CPU clock is 32 MHz.

EXCKSEL = 0x0CH

CSI30 Clock = f_{PLL_PCKSEL} = 16 MHz CSI31 Clock = f_{PLL_PCKSEL} = 16 MHz

(f) Processor clock control register (PCC)

This 8-bit register controls the CPU clock selection using a prescaler.

Data can be written to this register only in combination of specific sequences (refer to 3.2.3 "Special registers" in V850E/RS1 user's manual).

PCC = 0x00H

 $f_{CPU} = f_{XX} = 32 \text{ MHz}$

(3) Timer M Configuration in interval time mode

Timer M (TMM0) supports only a clear & start mode. It does not support a free-running mode. In the interval timer mode, a match interrupt signal (INTTM0EQ0) is output when the value of the 16-bit counter matches the value of TMM0 compare register 0 (TM0CMP0). At the same time, the counter is cleared to 0000H and starts counting up.

(a) TMM0 timer control register (TM0CTL0)

This register sets the count clocks of 16-bit timer. In this application the count clock is set to f_{XX} . TM0CTL0 = 0x80H

(b) Timer M compare register

In this application a timer interval of $300 \, \mu s$ is needed as time base. The value of compare register can be calculated by the following formula:

Interval Time =
$$\frac{\text{Compare register}}{\text{Internal count clock}}$$

$$300 \, \mu s = \frac{\text{Compare Register TM0CMP0}}{32MHz}$$

TM0CMP0 = 0x2580H

(c) Timer M interrupt mask register is enabled with highest priority

TM0EQIC0 register or IMR1 register could be used to setup the enable interrupt mode. In this application TM0EQIC0 is set:

TM0EQIC0 = 0x00H

(d) Flowchart

Figure 3-3: Timer M Initialization Routine

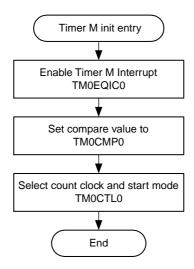
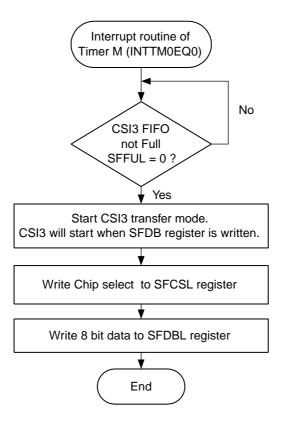


Figure 3-4: Timer M Interrupt Routine



(4) CSIC3 configuration in single buffer mode

3-wire serial I/O mode interface

(a) Queued CSI Clock Selection Registers (CSIC)

The CSIC register is an 8-bit register that is used to control the serial transfer operations (data phase, clock phase, master mode and clock selection).

Caution: This register can be written only while CSIM register's CTXE = 0 and CRXE = 0.

CSIC = 0x39HMaster mode, $\overline{SCK3} = 4 \text{ MHz}$

CKS2, CKS1, CKS0 = 0, 0, 1

MDL2, MDL1, MDL0 = 0, 0, 1

Sampling on first rising edge and idle level is low

CKP, DAP = 1, 1

(b) Queued CSI Data Length Selection Registers (CSIL)

The CSIL register is an 8-bit register that specifies the active voltage level of the Chip Select pins and the Queued CSI data length.

This register can be overwritten only while CTXE = 0 and CRXE = 0 (CSIM register). Write operation during CTXE = 1 or CRXE = 1 is prohibited.

Transfer data length is 8bits and chip select signal is active low.

CSIL = 0x08H

(c) Queued CSI Operation Mode Registers (CSIM)

The CSIM registers control the Queued CSI macro's operations.

TRMD, DIR, CSIT, CSWE, CSMD bits can only be written when CTXE = 0 and CRXE = 0.

- Provide macro operation clock

Power = 1

- interrupt delay mode select (INTC3nl signal)

CSIT = 1; Half clock delay.

- Transmission wait disable. Not insert 1 clock (SCK3) wait at transmission start. CSWE = 0.

- Chip select inactive level output disable. Do not force chip select inactive state after each transfer of a data element.

CSMD = 0

- Single buffer transfer mode

TRMD = 0

 Data is sent/received with MSB first DIR = 0

 Enable transmit and receive mode CTXE, CRXE = 1, 1

(d) FIFO Buffer Status Register (SFA)

The SFA register is an 8-bit register that shows the FIFO buffer status. The SFA register is read/write-enabled, accessible in 1-bit or 8-bit units. However, the bits SFFUL, SFEMP and CSOT are read only. Initial value is 20H by reset.

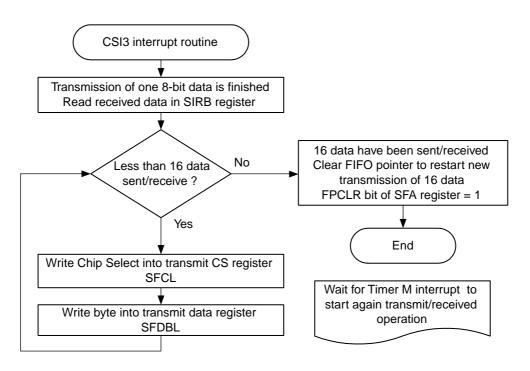
SFA read is prohibited when POWER = 1 and f_{QCSI} is stopped.

 Clear all FIFO pointers FPCLR = 1

FIFO buffer status flag
 SFFUL = 0: FIFO buffer is not full
 SFFUL = 1 FIFO buffer is full

(e) CSI30 interrupt (INTC30I) flowchart

Figure 3-5: CSI3 Interrupt Routine



(5) Port mode initialisation

Table 3-1: Non-Port Pins

Pin Name	I/O	Function	Alternate Function
SI30	Input	Serial receive data input (CSI30)	P54
SI31	Input	Serial receive data input (CSI31)	P00
SO30	O	Serial transmit data output (CSI30)	P55
SO31	Output	Serial transmit data output (CSI31)	P01
SCK30	I/O	Serial clock I/O (CSI30)	P90/TIQ11/TOQ11, P95/RXDA1
SCK31		Serial clock I/O (CSI31)	P02
CS300		Serial chip select output (CSI30)	P91/TIQ12/TOQ12, P96/TXDA1
CS301		Serial chip select output (CSI30)	P92/TIQ13/TOQ13
CS302		Serial chip select output (CSI30)	P93/TIQ10/TOQ10
CS303		Serial chip select output (CSI30)	P94/ASCKA1
CS310	Output	Serial chip select output (CSI31)	P03, P32
CS311		Serial chip select output (CSI31)	P04
CS312		Serial chip select output (CSI31)	P05/INTP2, P37/TIP00/TOP00/ INTP1
CS313		Serial chip select output (CSI31)	P06/INTP3

(a) Port 0 initialisation

CSI31 is not used. All I/O could be set in output mode.

P0 = 0x00H; Reset output latches.

PM0 = 0x00;

PMC0 = 0x00H;

PFC0 = 0x00H;

(b) Port 5 initialisation

P5 = 0x00H; Reset output latches.

PM5 = 0xDFH; P54(SI30) in input mode, P55 (SO30) in output mode.

PMC5 = 0x30H; Select P55 and P54 respectively as serial output and serial input for CSI30.

PFC5 = 0x00; Default value after RESET.

(c) Port 9 initialisation

P9L = 0x00H; Reset output latches.

PM9L = 0x80H; P90 to P96 in output mode.

PMC9L = 0x70H; Specify CSI30 mode for the port.

PFC9L = 0x00H; Specify CSI30 function for the port, P96 = CS300, P95 = $\overline{SCK30}$.

PFCE9L = 0x00H; P90 = SCK30, P91 = CS300, P92 = CS301, P93 = CS302, P94 = CS303.

P9H = 0x00H; Reset output latches.

PM9H = 0xCBH; Port mode register for P98 to P915.

PMC9H = 0x30H; I/O port mode.

PFC9H = 0x20H;

PFCE9H = 0x20H;

(d) Port Function Swap Control Register (PSWAP)

This device has a special purpose register for swapping port function by setting control bit. The Swap function is implemented to allow flexible configuration. PSWAP = 0x02H.

- $P95 = \overline{SCK30}$
- P96 = CS300
- P910 = CS301
- P912 = CS302

(6) Measurement results

Figure 3-6: Single Buffer Transfer Mode: Setup and Hold Time

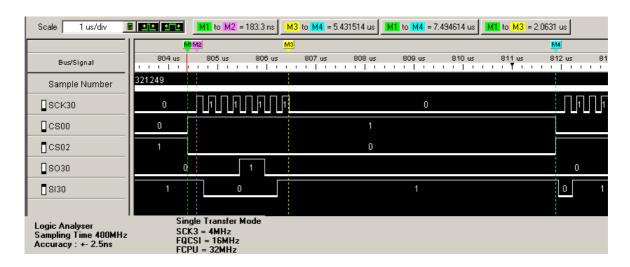
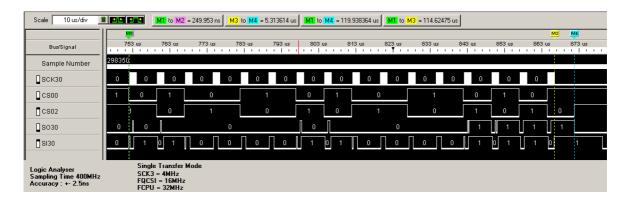


Figure 3-7: Single Buffer Transfer Mode Timing



3.2 FIFO Buffer Transfer Mode (Master Mode, Transmit/Receive Mode)

MSB first (DIR = 0), no INTC3nl delay (CSIT = 0), transmission wait disabled (CSWE = 0), CS inactive disabled (CSMD = 0), CKP = 1, DAP = 0, transmission data length of 8 bits (CCL[3:0] = [1,0,0,0]), active levels of all chip selects set to "active low":

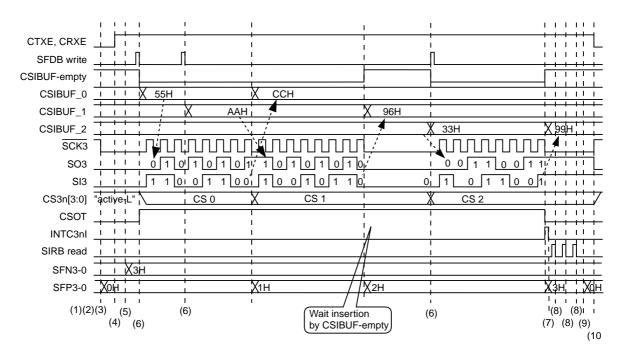


Figure 3-8: FIFO Buffer Transfer Mode (Master, Transmit/Receive) Timing

- 1. Set the CSIM register's POWER bit to 1 to enable the supply of the Queued CSI operation clock.
- 2. Set the CSIC and CSIL registers to specify the transfer mode.
- 3. Write "1" in the SFA register's FPCLR bit to clear all FIFO pointers.
- 4. Specify the transfer mode using the CSIM register's TRMD, DIR, and CSIT bits; at the same time, set the CTXE and CRXE bits to 1 to enable the transmit/receive operation.
- 5. Set the number of transmit/receive data items in the SFN register's SFN[3:0] bits.
- 6. Make sure that the SFA register's SFFUL bit is set to 0, then write chip-select data and transmission data in the SFCS and SFDB registers in this order.
- 7. Wait for the transmissions/receptions to be completed (e.g. by monitoring the INT3C3nl interrupt).
- 8. Read the received data by multiple read of the SIRB register (= sequential read from the FIFO).
- 9. Write "1" in the SFA register's FPCLR bit and clear all FIFO pointers for the next transmission.

To continue transmission/reception, repeat steps (5) - (9).

 Set the CSIM register's CTXE and CRXE bits to 0 to disable the transmit/receive operation (end of transmit/receive operation).

3.2.1 FIFO buffer transfer mode application without DMA transfer

The FIFO buffer is used to transmit and receive the data.

The number of data to be transmitted is selected in advance using SFN register (SFN register is only used is FIFO buffer mode).

Transmission is completed when transmit/receive transfer of 16 data (8 bits length) has been sent/received.

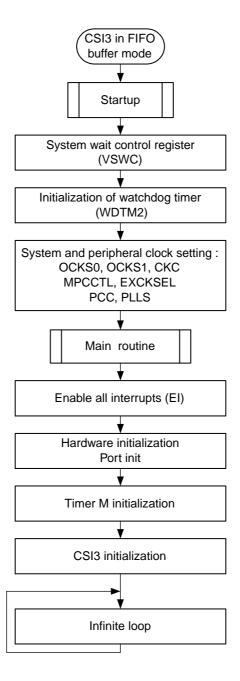
Transmission completed status is detected by monitoring the INTCSI3n interrupt.

The reading of the 16 received data is done every interrupt INTCSI3n

DMA transfer is not used.

(1) FIFO buffer transfer flowchart

Figure 3-9: FIFO Buffer Transfer Flowchart



(2) System clock and peripheral clock setting (Startup)

This routine sets the clock using the PLLs mode for the CPU, CSI3 and Timer M. PLL0 and PLL1 output clocks are respectively assigned to the system clock and CSI3.

System clock is used for CPU and timer. The main resonator oscillates at 8 MHz.

Be sure to set the following registers first when using the V850E/RS1.

- System wait control register (VSWC)
- On-chip Debug Mode control register (OCDM)^{Note}
- Watchdog timer mode register 2 (WDTM2)^{Note}

Note: Refer to 3.4.7 "Caution" in V850E/RS1 user's manual.

(a) NEC peripheral bus wait control

The system wait control register (VSWC) controls wait of bus access to the internal peripheral I/O registers.

Set the value to VSWC register in accordance with the frequency used.

The VSWC register can be read or written in 8-bit units.

In this application the value written to VSWC is 0x12H.

VSWC = 0x12H;

(b) Clock selection register for PLL0 and PLL1 (OCKS0, OCKS1)

Those 8-bit registers control the operation enable and clock input selection for PLL0 and PLL1.

Clock selection register 0: OCKS0 = 0x11H PLL0 input = $f_{\chi\chi}/3$ Clock selection register 1: OCKS1 = 0x13H PLL1 input = $f_{\chi\chi}/5$

(c) Clock control register (CKC)

This is an 8-bit register that controls system clock (f_{XX}) when it operates on PLL mode (SELPLL bit of MPCCTL register is set to 1). This register can be read or written in 8-bit or 1-bit units. Be sure to clear bits 2 to 7 of the CKC register to 0. In other case the operation is not guaranteed. Data can be written to this register only in combination of specific sequences (refer to 3.2.3 "Special registers" in V850E/RS1 user's manual).

CKC = 0x03H $f_{PLL \ MCKSEL \ CKDIV} = f_{PLL}(PLL \ internal \ clock)$

(d) Main peripheral clock control register (MPCCTL)

This is an 8-bit register that selects the internal clock. Data can be written to this register only in combination of specific sequences (refer to 3.2.3 "Special registers" in V850E/RS1 user's manual). The clock generator flexibility allows to use either simultaneously both PLL or to use only one PLL. Both PLLs can be assigned respectively to the CPU or to the peripherals.

Switch from oscillator clock to PLL clock:

MPCCTL = 0x84H $PLL mode (f_{XX} = f_{PLL_MCKSEL_CKDIV})$

Main clock (f_{PLL MCKSEL}) = PLL0

Peripheral clock = PLL1

(e) Extended clock selection (EXCKSEL)

CSI3, CSIB, and AFCAN peripherals input clocks could be either from the system clock or directly form the PLL output using the extended clock selection.

In this application CSI3 uses the extended clock in order to get a 16 MHz input clock (f_{QCSI}) while the CPU clock is 32 MHz.

EXCKSEL = 0x0CH

CSI30 Clock = f_{PLL_PCKSEL} = 16 MHz CSI31 Clock = f_{PLL_PCKSEL} = 16 MHz

(f) Processor clock control register (PCC)

This 8-bit register controls the CPU clock selection using a prescaler.

Data can be written to this register only in combination of specific sequences (refer to 3.2.3 "Special registers" in V850E/RS1 user's manual).

 $\overrightarrow{PCC} = 0x00H$

 $f_{CPU} = f_{XX} = 32 \text{ MHz}$

(3) Timer M configuration in interval time mode

Timer M (TMM0) supports only a clear & start mode. It does not support a free-running mode. In the interval timer mode, a match interrupt signal (INTTM0EQ0) is output when the value of the 16-bit counter matches the value of TMM0 compare register 0 (TM0CMP0). At the same time, the counter is cleared to 0000H and starts counting up.

(a) TMM0 timer control register (TM0CTL0)

This register sets the count clocks of 16-bit timer. In this application the count clock is set to f_{XX} . TM0CTL0 = 0x80H

(b) Timer M compare register

In this application a timer interval of 300µs is needed as time base. The value of compare register can be calculated by the following formula:

$$Interval Time = \frac{Compare register}{Internal count clock}$$

$$300 \ \mu s = \frac{Compare \ Register \ TM0CMP0}{32 \ MHz}$$

TM0CMP0 = 0x2580H

(c) Timer M interrupt mask register is enabled with highest priority

TM0EQIC0 register or IMR1 register could be used to setup the enable interrupt mode. In this application TM0EQIC0 is set:

TM0EQIC0 = 0x00H

(d) Flowchart

Figure 3-10: Timer M Initialization Routine

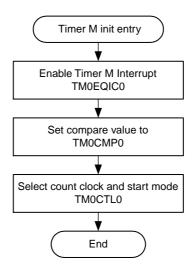
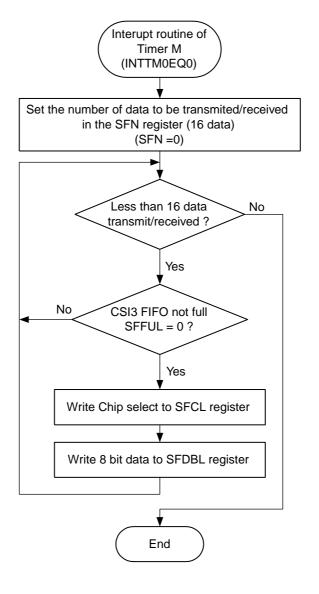


Figure 3-11: Timer M Interrupt Routine



(4) CSIC3 configuration in FIFO buffer mode

3-wire serial I/O mode interface

(a) Queued CSI clock selection registers (CSIC)

The CSIC register is an 8-bit register that is used to control the serial transfer operations (data phase, clock phase, master mode and clock selection).

Caution: This register can be written only while CSIM register's CTXE = 0 and CRXE = 0.

 $\begin{array}{lll} \text{CSIC} = 0\text{x39H} \\ \text{Master mode, } \overline{\text{SCK3}} = 4 \text{ MHz} \\ \text{Sampling on first rising edge and idle level is low} \end{array}$

(b) Queued CSI data length selection registers (CSIL)

The CSIL register is an 8-bit register that specifies the active voltage level of the Chip Select pins and the Queued CSI data length.

This register can be overwritten only while CTXE = 0 and CRXE = 0 (CSIM register). Write operation during CTXE = 1 or CRXE = 1 is prohibited.

Transfer data length is 8bits and chip select signal is active low. CSIL = 0x08H

(c) Queued CSI operation mode registers (CSIM)

The CSIM registers control the Queued CSI macro's operations.

TRMD, DIR, CSIT, CSWE, CSMD bits can only be written when CTXE = 0 and CRXE = 0.

- Provide macro operation clock

Power = 1

- interrupt delay mode select (INTC3nl signal)

CSIT = 1; Half clock delay.

- Transmission wait disable. Not insert 1 clock (SCK3) wait at transmission start. CSWE = 0.
- Chip select inactive level output disable. Do not force chip select inactive state after each transfer of a data element.

CSMD = 0

- FIFO buffer transfer mode

TRMD = 1

- Data is sent/received with MSB first DIR = 0
- Enable transmit and receive mode CTXE, CRXE = 1, 1

(d) FIFO buffer status register (SFA)

The SFA register is an 8-bit register that shows the FIFO buffer status. The SFA register is read/write-enabled, accessible in 1-bit or 8-bit units. However, the bits SFFUL, SFEMP and CSOT are read only. Initial value is 20H by reset.

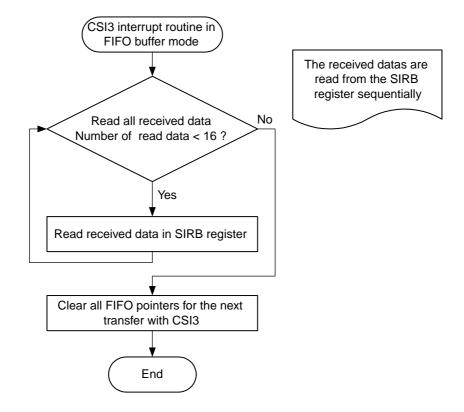
SFA read is prohibited when POWER = 1 and f_{OCSI} is stopped.

 Clear all FIFO pointers FPCLR = 1

FIFO buffer status flag
 SFFUL = 0: FIFO buffer is not full
 SFFUL = 1 FIFO buffer is full

(e) CSI30 interrupt (INTC30I) flowchart

Figure 3-12: CSI3 Interrupt Routine



(5) Port mode initialisation

Table 3-2: Non-Port Pins

Pin Name	I/O	Function	Alternate Function
SI30	Input	Serial receive data input (CSI30)	P54
SI31	input	Serial receive data input (CSI31)	P00
SO30	Output	Serial transmit data output (CSI30)	P55
SO31		Serial transmit data output (CSI31)	P01
SCK30	I/O	Serial clock I/O (CSI30)	P90/TIQ11/TOQ11, P95/RXDA1
SCK31		Serial clock I/O (CSI31)	P02
CS300		Serial chip select output (CSI30)	P91/TIQ12/TOQ12, P96/TXDA1
CS301		Serial chip select output (CSI30)	P92/TIQ13/TOQ13
CS302		Serial chip select output (CSI30)	P93/TIQ10/TOQ10
CS303		Serial chip select output (CSI30)	P94/ASCKA1
CS310	Output	Serial chip select output (CSI31)	P03, P32
CS311		Serial chip select output (CSI31)	P04
CS312		Serial chip select output (CSI31)	P05/INTP2, P37/TIP00/TOP00/ INTP1
CS313		Serial chip select output (CSI31)	P06/INTP3

(a) Port 0 initialisation

CSI31 is not used. All I/O could be set in output mode.

P0 = 0x00H; Reset output latches.

PM0 = 0x00;

PMC0 = 0x00H;

PFC0 = 0x00H;

(b) Port 5 initialisation

P5 = 0x00H; Reset output latches.

PM5 = 0xDFH; P54(Sl30) in input mode, P55 (SO30) in output mode.

PMC5 = 0x30H; Select P55 and P54 respectively as serial output and serial input for CSI30.

PFC5 = 0x00; Default value after RESET.

(c) Port 9 initialisation

P9L = 0x00H; Reset output latches.

PM9L = 0x80H; P90 to P96 in output mode.

PMC9L = 0x70H; Specify CSI30 mode for the port.

PFC9L = 0x00H; Specify CSI30 function for the port, P96 = CS300, P95 = $\overline{SCK30}$.

PFCE9L = 0x00H; P90 = SCK30, P91 = CS300, P92 = CS301, P93 = CS302, P94 = CS303.

P9H = 0x00H; Reset output latches.

PM9H = 0xCBH; Port mode register for P98 to P915.

PMC9H = 0x30H; I/O port mode.

PFC9H = 0x20H;

PFCE9H = 0x20H;

(d) Port function swap control register (PSWAP)

This device has a special purpose register for swapping port function by setting control bit. The Swap function is implemented to allow flexible configuration.

PSWAP = 0x02H.

- P95 = $\overline{SCK30}$
- P96 = CS300
- P910 = CS301
- P912 = CS302

(6) Measurement results

Figure 3-13: FIFO Buffer Transfer Mode: Setup and Hold Time

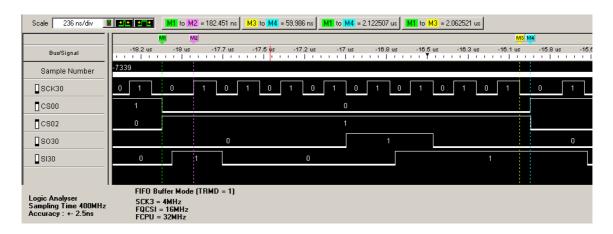
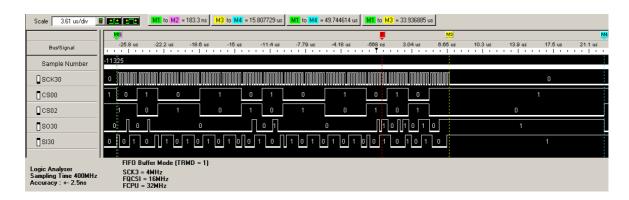


Figure 3-14: FIFO Buffer Transfer Mode Timing



3.3 Single Buffer Transfer Mode with DMA

This chapter describe the implementation of two DMA channels to transmit and to send the data in single buffer transfer mode.

For CSI3n configuration, please refer to chapter 3.1 "Single Buffer Transfer Mode (Master Mode, Transmit/Receive Mode)" on page 42.

For system clock and peripheral clock setting, please refer to "System clock and peripheral clock setting (Startup)" on page 44

For DMA controller registers detail explanations, please refer to V850E/RS1 User's manual (U16702EE1V0UD00), chapter 15 "DMA Functions".

(1) DMA transfer mode

Single transfer mode is used for both DMA channels.

In Single transfer mode, the DMA releases the bus after each transfer. If there is a subsequent DMA transfer request, the transfer is performed again when the bus becomes available again. DMBCn triggers are required to transfer DMBCn elements. This operation continues until the transfer counter is cleared to 0 and the internal TC signal is generated.

When the DMA has released the bus, if another higher priority DMA transfer request is issued, the higher priority DMA request always takes precedence.

(a) DMA source/destination addresses, priority, and transfer size

DMA channel 1 and 2 are respectively used for receive operation (readout SIRBn register) and for transmit operation (write data into SFCSn and SFDBn registers).

DMA channel 1 transfer size is one byte (8-bit). DMA channel 2 transfer size is one word (32-bit). According to CSI3n architecture, the receive register SIRBn must be readout before starting any following transfer. Otherwise the received data will be lost and the CSI3n will not operate correctly. It is important to take care of the priority of each DMA channel to be used, giving the highest priority to the receive function.

The chip select FIFO buffer register (SFCSn) and the transmit data FIFO buffer register (SFDBn) are mapped in a continuous address and are 16bits long. The data to be sent is written to SFCSn register with 32bits access. Upper 16 bits are written to data register (SFDBn) and the lower 16 bits are written to chip select register (SFCSn).

DMA channel priority is fixed as follow:

DMA channel 0 > DMA channel 1 > DMA channel 2 > DMA channel 3 > DMA channel 4 > DMA channel 5.

(b) Interrupt source for DMA trigger

Each DMA could be triggered either by software or peripheral interruptions.

This program provides an example of the DMA and CSI3 operation using the end transmission/reception end interrupt signal INTC3nI to trig both DMA channels. So the first transmission/reception must be started by software every 300 µs.

CSI3 end transmission/reception end interrupt signal INTC3nI is only use to trig the DMA, so the interrupt routine is useless.

(c) End of transmission/reception, Hold time setting for the last transmission/reception

DMA channel 1 interrupt (INTDMA1) routine is used to clear all FIFO pointers. This operation turns the chip select signal to inactive level after the last 16th element has been successfully transmitted/received.

This operation could also be done later into the Timer M interrupt routine. This will provide a longer hold time signal and will save CPU load avoiding an additional interrupt handling procedure.

(d) DMA initialization and CSI3 transfer start

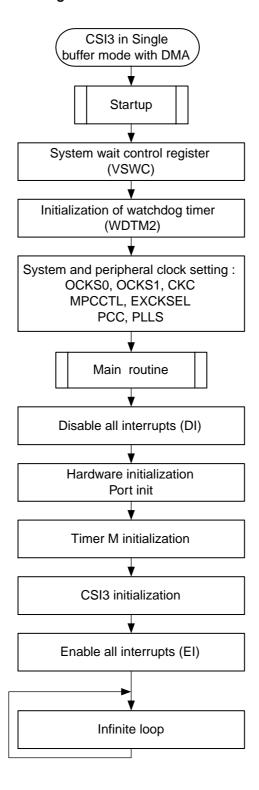
DMA initialization has to be done for each new transfer. Timer M interrupt routine provide such availability every $300 \, \mu s$.

To initiate the transmission of CSI3 interface, chip select and data are respectively written to SFCS0 and SFDB0 register during the Timer M interrupt routine.

Note: n = 0, 1

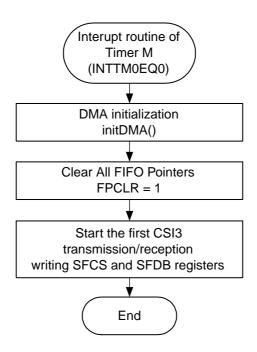
(2) Single buffer transfer flowchart

Figure 3-15: Single Buffer Transfer Flowchart with DMA



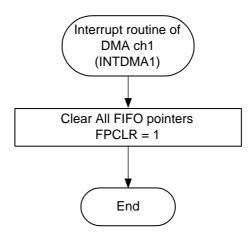
(3) Timer M interrupt routine

Figure 3-16: Timer M Interrupt Routine



(4) DMA channel 1 interrupt routine

Figure 3-17: DMA channel 1 Interrupt Routine



(5) Measurements results

Figure 3-18: Single Buffer Transfer Mode with DMA: Setup and Hold Time

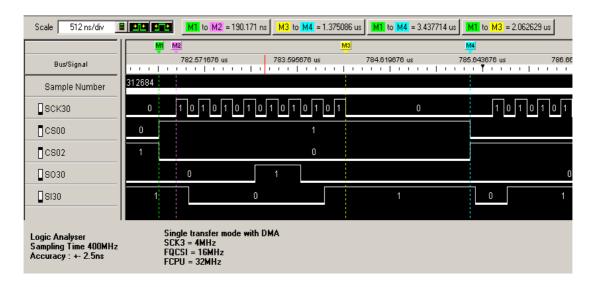
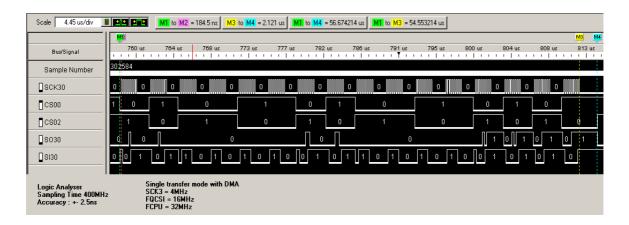


Figure 3-19: Single Buffer Transfer Mode Timing with DMA



3.4 FIFO Buffer Transfer Mode with DMA

This chapter describe the implementation of two DMA channels to transmit and to send the data in FIFO buffer transfer mode.

For CSI3n configuration, please refer to chapter 3.2 "FIFO Buffer Transfer Mode (Master Mode, Transmit/Receive Mode)" on page 51.

For system clock and peripheral clock setting, please refer to "System clock and peripheral clock setting (Startup)" on page 53

For DMA controller registers detail explanations, please refer to V850E/RS1 User's manual (U16702EE1V0UD00), chapter 15 "DMA Functions".

(1) DMA transfer mode

Fixed channel transfer mode is used for both DMA channels.

In "Fixed Channel" transfer mode, the DMA releases the bus after each transfer, but continues to repeat the DMA transfer until the transfer counter is cleared to 0 without requiring a new DMA transfer request.

Only one trigger is required to transfer DMBCn elements

When the DMA has released the bus, if another higher priority DMA transfer request is issued, the higher priority DMA request does not take precedence.

(a) DMA source/destination addresses, priority, and transfer size

DMA channel 1 and 2 are respectively used for receive operation (readout SIRBn register) and for transmit operation (write data into SFCSn and SFDbn registers).

DMA channel 1 transfer size is one byte (8-bit). DMA channel 2 transfer size is one word (32-bit). According to CSI3n architecture, the receive register SIRBn must be readout before starting any following transfer. Otherwise the received data will be lost and the CSI3n will not operate correctly. It is important to take care of the priority of each DMA channel to be used, giving the highest priority to the receive function.

The chip select FIFO buffer register (SFCSn) and the transmit data FIFO buffer register (SFDBn) are mapped in a continuous address and are 16bits long. The data to be sent is written to SFCSn register with 32bits access. Upper 16 bits are written to data register (SFDBn) and the lower 16 bits are written to chip select register (SFCSn).

DMA channel priority is fixed as follow:

DMA channel 0 > DMA channel 1 > DMA channel 2 > DMA channel 3 > DMA channel 4 > DMA channel 5.

(b) Interrupt source for DMA trigger

Each DMA could be triggered either by software or peripheral interruptions.

This program provides an example of the DMA and CSI3 operation using the end transmission/reception end interrupt signal INTC3nI to trig DMA channel 1 and a software trigger for DMA channel 2. So the first transmission/reception is started by software every 300 µs into the Timer M interrupt routine.

CSI3 end transmission/reception end interrupt signal INTC3nI is only use to trig the DMA channel 1, so the interrupt routine is useless.

(c) End of transmission/reception, Hold time setting for the last transmission/reception

DMA channel 1 interrupt (INTDMA1) routine is used to clear all FIFO pointers. This operation turns the chip select signal to inactive level after the last 16th element has been successfully transmitted/received.

This operation could also be done later into the Timer M interrupt routine. This will provide a longer hold time signal and will save CPU load avoiding an additional interrupt handling procedure.

(d) DMA initialization and CSI3 transfer start

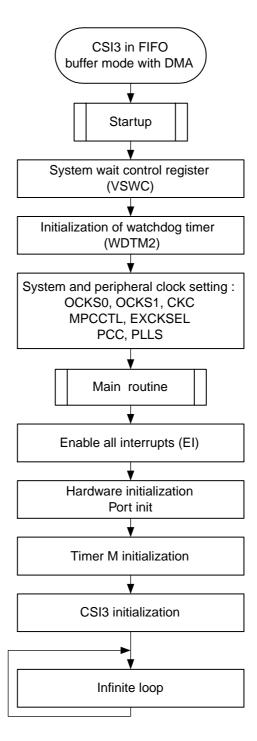
DMA initialization has to be done for each new transfer. Timer M interrupt routine provide such availability every $300 \, \mu s$.

To initiate the first transmission of CSI3 interface, DMA channel 2 is triggered by software in the timer M interrupt routine.

Note: n = 0, 1

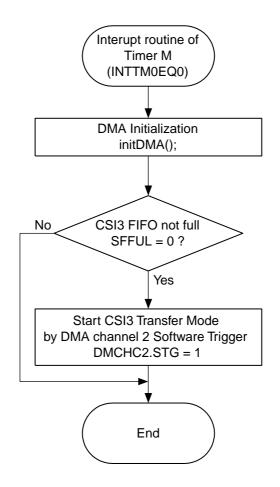
(2) FIFO buffer transfer flowchart

Figure 3-20: FIFO Buffer Transfer Flowchart with DMA



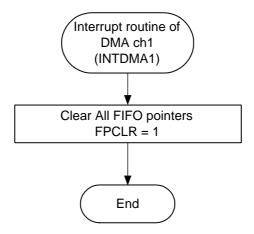
(3) Timer M interrupt routine

Figure 3-21: Timer M Interrupt Routine



(4) DMA channel 1 interrupt routine

Figure 3-22: DMA Channel 1 Interrupt Routine



(5) Measurement results

Figure 3-23: FIFO Buffer Transfer Mode with DMA: Setup and Hold Time

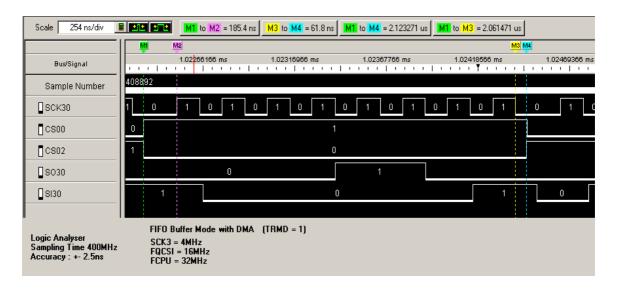
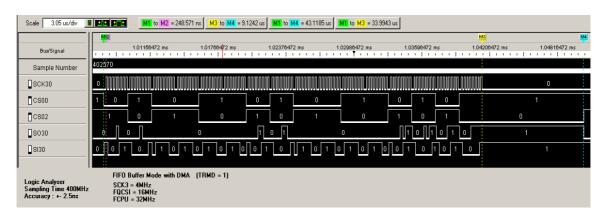


Figure 3-24: FIFO Buffer Transfer Mode Timing with DMA



3.5 Sample Programs

The 4 software examples projects are defined with below mentioned files:

• Startup file: Startup_df3402.850

Header files: df3402.h, df3402extIO.h, df3402.s

· Source file: Main.c

Note: The header files df3402.h, df3402extIO.h and df3402.s are standard files provided by NEC. Please contact your NEC Electronics sales office representative to obtain it.

3.5.1 Single buffer mode without DMA

```
//-----
// PROJECT: V850E/RS1 CSI3 driver in single buffer mode without DMA
// MODULE : Main.c
// VERSION: 1.0
// DATE : 22/06/05
COPYRIGHT
//----
// Copyright (c) 2002 by NEC Electronics (Europe) GmbH, Succursale Française.
// All rights reserved.
// 9, rue Paul Dautier
// 78142 Vélizy Cedex
// France
// Warranty Disclaimer:
// Because the Product(s) is licensed free of charge, there is no warranty of
// any kind whatsoever and expressly disclaimed and excluded by NEC, either
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// infringement of intellectual property, merchantability and/or fitness for
// the particular purpose. NEC shall not have any obligation to maintain,
// service or provide bug fixes for the supplied Product(s) and/or the
// Application.
//
\//\ Each User is solely responsible for determining the appropriateness of
// using the Product(s) and assumes all risks associated with its exercise
// of rights under this Agreement, including, but not limited to the risks
// and costs of program errors, compliance with applicable laws, damage to
// or loss of data, programs or equipment, and unavailability or
// interruption of operations.
// Limitation of Liability:
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// consequential, indirect, or punitive damage (including but not limited to
// lost profits) regardless of whether such liability is based on breach of
// contract, tort, strict liability, breach of warranties, failure of
// essential purpose or otherwise and even if advised of the possibility of
// such damages. NEC shall not be liable for any services or products provided
// by third party vendors, developers or consultants identified or referred
// to the User by NEC in connection with the Product(s) and/or the
// Application.
```

```
//
// Environment: Devices : V850E/RS1
         Assembler : GHS AS-V850
//
                                    Version: 4.0.5
         C-Compiler: GHS CCV850, Multi 2000, V800 Version: 4.0.5
//
//
         Linker : GHS lx, Multi 2000, V800 Version: 4.0.5
         Debugger : GHS Multi 2000, V800
//
                                   Version: 4.0.5
//----
                   Description
// 1.0
       Ferry-Chappuis Released
//-----
/***********************
This software is used to develop the module for the CSI3 in single buffer mode
without DMA interface
************************
Description of the CSI3 mode
CSI30 is using the single buffer transfer mode
in this mode, the CSI30 provides an interruption INTCSI30 each data transfer.
SFN register is not used.
*******************************
/***************************
Includes
************************
#include "Inc\df3402.h"
#include "Inc\df3402extIO.h"
** Declaration of local types **
*******************************
typedef unsigned char uchar;
/************************
** Declaration of variables **
*****************************
int
      mbytes = 0;
uchar
      txdata[16] = \{8,8,0,0,0,0,12,12,0,0,0,0,11,11,15,15\};
      uchar
              0xB, 0xE, 0XB, 0xE, 0XB};
/****************************
** CSI3 registers initialisation for single buffer mode operation
void InitCSI3Single8bits(void)
 /* Configure serial transfer operation */
 /* This register must be initialised in several times because TRMD, DIR, CSIT, CSWE
   and CSMD bits can be written only when CTXE and CRXE are 0 ^{*}/
 _{POWER0} = 1;
 /* CSIL and CSIC registers must be written first because it is possible only if */
 /* CTXE and CRXE bits in CSIM register are 0 */
```

```
/* Configure clock: - Idle level low
                     - sampling edge done on the first edge
                     - prescaler associated to clock, K= 1 (PRSOUT = FQCSI/2), N= 1
                      operation clock = PRSOUT/2)*/
  /* Clock speed = 4MHz*/
  CSIC0 = 0x39;
  /* Configure buffer number to store data and data length
  8-bit data length
  chip select signal is active low */
  CSIL0 = 0x08;
  /* clear FIFO pointer */
  _{\rm FPCLR0} = 1;
  _CSMD0 = 0; /* CS_INACTIVE_DISABLE */
  _CSWE0 = 0; /* WAIT_DISABLE */
  _CSITO = 1; /* HALF_CLK_DELAY */
  __DIR0 = 0;    /* Transfer direction: MSB first */
_TRMD0 = 0;    /* CSI3 in Single buffer transfer mode */
  /* enable the transmission */
  _CRXE0 = 1; /* RX_ENABLE */
  _CTXE0 = 1; /* TX_ENABLE */
}
*************************
void InitPorts(void)
/* Initialise port 0 */
  PΩ
       = 0x00;
  PM0
        = 0x00;
        = 0x00;
  PMC0
        = 0x00;
  PFC0
/* Initialise port 5 */
  Р5
        = 0x00;
  PM5
         = 0xDF;
       = 0x30;
  PMC5
       = 0x00;
  PFC5
/* Initialise port 9 */
/* LSB */
  P9L
         = 0x00;
  PM9L
       = 0x80;
  PMC9L = 0x70;
  PFC9L = 0x00;
  PFCE9L = 0x00;
/* MSB */
  P9H
        = 0x17;
  PM9H = 0xCB;
  PMC9H = 0x30;
  PFC9H = 0x20;
  PFCE9H = 0x20;
/* Initialise PSWAP */
```

```
PSWAP = 0x02;
}
/****************************
Timer M initialisation for compare operation
Compare value to obtain an interruption every 300 µs:
300 \mu s / (1/32 MHz) = 9600 = 0x2580
void InitTimerMCompareOperation(void)
            TMOCTLO = 0x80;
/ \, ^{\star} compare value for generating an interrupt every 300 \mu s \, ^{\star} / \,
            TMOCMPO = 0x2580;
/* interrupt enable and highest level */
            TMOEOICO = 0;
/****************************
InitialiseRegisters()
This function initialises I/O ports and other peripherals of the MCU
*****************************
void InitialiseRegisters(void)
/* Configure IO ports */
            InitPorts();
/* Configure TIMER M compare operation to generate an interrupt every 300 us*/
            InitTimerMCompareOperation();
            InitCSI3Single8bits();
}
/*************************
Interruption function IntTimerM_Compare()
This interrupt function allow to start the CSI3 transfer every 300 µs
******************
void IntTimerM_Compare(void)
#pragma ghs interrupt
/* every 300 μs a new transmission/reception starts */
             mbytes = 0;
/* Clear FIFO buffer full status flag: SFFUL = 0 */
       \_SFFUL0 = 0;
/* Start the first transmission every 300 \mu s by writing the data to SFDB register */
/* Write CS into transmit CS register */
            SFCS0L = csdata[mbytes];
/* Write byte into transmit data register */
            SFDB0L = txdata[mbytes];
}
```

```
/******************************
Interruption function INTC30I() of the CSI3
void INTC30I(void)
#pragma ghs interrupt
/* when transmission is finished, read SIRB register */
  rxdata[mbytes] = SIRB0L;
/* send the next data up mbytes value < 16 */
  mbytes++;
  if (mbytes < 16)
           /* Write CS into transmit CS register */
           SFCS0L = csdata[mbytes];
           /* Write byte into transmit data register */
          SFDB0L = txdata[mbytes];
 }
  else
          /* clear all FIFO pointers to "0" */
          _{\text{FPCLR0}} = 1;
 }
}
void main(void)
/* enable INTC30I interrupt of CSI30 */
  C30IC = 0x00;
  EI();
/* Configuration for:
- port
- CSI3 */
  InitialiseRegisters();
  while(1){};
}
```

3.5.2 Single buffer mode with DMA

```
// PROJECT: V850E/RS1 CSI3 driver single buffer mode with DMA to send and received data
// MODULE : Main.c
// VERSION: 1.0
// DATE : 22/06/05
//----
            COPYRIGHT
//-----
// Copyright (c) 2002 by NEC Electronics (Europe) GmbH, Succursale Française.
// All rights reserved.
// 9, rue Paul Dautier
// 78142 Vélizy Cedex
// France
//-----
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// the particular purpose. NEC shall not have any obligation to maintain,
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// Application.
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// using the Product(s) and assumes all risks associated with its exercise
// of rights under this Agreement, including, but not limited to the risks
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// or loss of data, programs or equipment, and unavailability or
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// lost profits) regardless of whether such liability is based on breach of
// contract, tort, strict liability, breach of warranties, failure of
// essential purpose or otherwise and even if advised of the possibility of
// such damages. NEC shall not be liable for any services or products provided
// by third party vendors, developers or consultants identified or referred
// to the User by NEC in connection with the Product(s) and/or the
// Application.
//
// Environment: Devices : V850E/RS1
           Assembler : GHS AS-V850
                                             Version: 4.0.5
//
           C-Compiler: GHS CCV850, Multi 2000, V800 Version: 4.0.5
//
           Linker : GHS lx, Multi 2000, V800 Version: 4.0.5
//
           Debugger : GHS Multi 2000, V800
                                             Version: 4.0.5
//-----
// Version Author
                       Description
// 1.0 Ferry-Chappuis Released
```

```
/*****************************
Description of CSI3 mode
Single buffer Mode
16 data of 1 byte to be transfer and received.
DMA channel 1 is used for receiving
DMA channel 2 is used for transmitting
Includes
#include "Inc\df3402.h"
#include "Inc\df3402extIO.h"
** Declaration of local types **
typedef unsigned char uchar;
typedef unsigned long ulong;
/************************
** Declaration of variables **
TX_DATA_FIFO 0xFD44;// define address of SFCS0 as destination address
for DMA channel 2
          RX DATA FIFO 0xFD42;// define address of SIRBO as source address for
DMA channel 1
int
      mbytes = 0;
      rxdata[16] ={1,1,1,1,1,1,1,1,1,1,1,1,1,1,1,1,1};
uchar
      txdata[16] = \{8,8,0,0,0,0,12,12,0,0,0,0,11,11,15,15\};
uchar
      csdata[16] = {0xE, 0XB, 0xE, 0xE, 0xB, 0xB, 0xE, 0XB, 0xE, 0xE, 0xB,
                0xB, 0xE, 0XB, 0xE, 0XB);
/* Data + chip select to be sent in 16 data transfer */
/* 32 bit send to SFDB and SFCL registers*/
ulong Txdata32[16] = \{0x0008000E, 0x0008000B, 0x0000000E, 0x0000000E,
                0x0000000B, 0x0000000B, 0x000C000E, 0x000C000B, 0x0000000E, 0x0000000E, 0x0000000B, 0x0000000B, 0x000B000E,
                0x000B000B,0x000F000E, 0x000F000B};
```

```
** CSI3 registers initialisation for single buffer mode operation
void InitCSI3Single8bits(void)
  /* Configure serial transfer operation */
  /* This register must be initialised in several times because TRMD, DIR, CSIT, CSWE
     and CSMD bits can be written only when CTXE and CRXE are 0 ^{*}/
  _{POWER0} = 1;
  /\ast CSIL and CSIC registers must be written first because it is possible only if \ast/
  /* CTXE and CRXE bits in CSIM register are 0 */
  /* Configure clock: - Idle level low
                     - sampling edge done on the first edge
                     - prescaler associated to clock, K= 1 (PRSOUT = FQCSI/2), N= 1
                      operation clock = PRSOUT/2)*/
  /* Clock speed = 4 MHz*/
  CSIC0 = 0x39;
  /* Configure buffer number to store data and data length
  8-bit data length
  chip select signal is active low */
  CSIL0 = 0x08;
  /* clear FIFO pointer */
  _{\text{FPCLR0}} = 1;
  _CSMD0 = 0; /* CS_INACTIVE_DISABLE */
  _CSWE0 = 0; /* WAIT_DISABLE */
  _CSITO = 1; /* HALF_CLK_DELAY */
  _DIRO = 0; /* Transfer direction: MSB first */
  _TRMD0 = 0; /* CSI3 in Single buffer transfer mode */
  /* enable the transmission */
  _CRXE0 = 1; /* RX_ENABLE */
  _CTXE0 = 1; /* TX_ENABLE */
}
```

```
PORTS MANAGEMENT
void InitPorts(void)
/* Initialise port 0 */
      = 0x00;
 P0
      = 0 \times 00;
  PM0
 PMC0 = 0x00;
 PFC0 = 0x00;
/* Initialise port 5 */
  Р5
      = 0x00;
  PM5
       = 0xDF;
  PMC5 = 0x30;
  PFC5 = 0x00;
/* Initialise port 9 */
/* LSB */
  P9L
       = 0x00;
  PM9L = 0x80;
  PMC9L = 0x70;
  PFC9L = 0x00;
 PFCE9L = 0x00;
/* MSB */
       = 0x17;
  Р9Н
  PM9H = 0xCB;
  PMC9H = 0x30;
  PFC9H = 0x20;
  PFCE9H = 0x20;
/* Initialise PSWAP */
  PSWAP = 0x02;
}
/*************************
Timer M initialisation for compare operation
Compare value to obtain an interruption every 300 µs:
300 \mu s / (1/32 MHz) = 9600 = 0x2580
*************************
void InitTimerMCompareOperation(void)
{
           TMOCTL0 = 0x80;
/* compare value for generating an interrupt every 300 \mu s */
           TM0CMP0 = 0x2580;
/* interrupt enable and highest level */
           TMOEOICO = 0;
}
```

```
/******************************
InitialiseRegisters()
This function initialises I/O ports and other peripherals of the MCU
void InitialiseRegisters(void)
/* Configure IO ports */
             InitPorts();
/* Configure TIMER M compare operation to generate an interrupt every 300 µs*/
             InitTimerMCompareOperation();
             InitCSI3Single8bits();
}
   -----*/
/* Initialisation of DMA channel */
/*-----*/
void InitDMA(void)
/* ---- Set DMA Registers ---- */
/* DMA channel 1 used for received data */
/* DMA channel 2 is used to transmit the data: 32 bit into SFCS and SFDB register */
/* The first transfer is started manually into the timer M routine */
/* Both DMA are triggered by the CSI3 interrupt INTC30I (end of transmission)*/
/*-----*/
/* DMA control register (DMC) */
//The DMC register controls the operation and the clock supply of the DMA controller.
//It can be read or written in 8-bit or 1-bit units. Initial value is 00H by reset.
//DMC |STPDIS|IDMEN|STPSET| STPCLR| 0 |0 |0 |POWER
// clear the status flag. All DMA transfer are operational: STPDIS = 0
// NMI interrupts and stops all on-going DMA transfers: IDMEN = 1
// DMA transfer interrupted by software: STPSET = 1
// The clock supply to the DMA controller is started and the DMA operation enabled.
// POWER = 1
   DMC = 0x71;
// INTDMAn timing is based on DMA execution: TCS = 1 is recommended for RS1
// Clear any pending DMA transfer request: FCLR = 1
// DMA channel 1 is disabled EN = 0
   DMCHC1 = 0x04;
   DMCHC2 = 0x04;
   DMSA1H = 0 \times 0.2 FF;
   DMSA2H = 0x02FF;
/* source adress */
   DMSA1L = RX_DATA_FIFO; // source - point to SIRBO address buffer.
   DMSA2L = 0xffff & (unsigned int)(&Txdata32[0x01]); // source - point to transmit buffer
   DMDA1H = 0 \times 0.2 FF;
   DMDA2H = 0x02FF;
/* destination adress */
   DMDA1L = 0xffff & (unsigned int)(rxdata); // destination address is rxdata[]
   DMDA2L = TX_DATA_FIFO; /* SFCS0 destination address */
```

```
// Number of triggers required to transfer DMBC elements
   DMBC1 = 0 \times 000 F; /* 16 data to be received */
   DMBC2 = 0 \times 000E; /* 15 data to be sent with DMA, because first
                      transmission is started manually */
// source address is internal RAM: TS1 TS0 = 1 0;
// Destination address is on chip IO TD1 TD0 = 1 1;
// Source address is incremented SAD = 0
// Destination address is fixed DAD= 1
// transmit 32 bit: DS1 DS0 = 1 0;
// Single transfer mode TM1 TM0 = 0 0;
// Transfer from source to destination TDIR = 0
   DMADC1 = 0xE800; // transfer size 8bit, single transfer mode
    // Transfer from source to destination
   DMADC2 = 0xB280; // 32bit length to transmit the data to SFCS0 register
   DMAIC1 = 0x00; // Highest priority for DMA channel 1
// DMA interrupt trigger
   DTFR1 = 0x29; // DMA channel 1 is triggered on CSI30 interrupt INTC30I
   DTFR2 = 0x29; // DMA channel 2 is triggered on CSI30 interrupt INTC30I
                 /* trigger will load SFCS and SFBD register to send the
                          next data (8bit)*/
   DMCHC1 = 0x21; // DMA transfer is enabled
   DMCHC2 = 0x21;
}
Interruption function IntTimerM_Compare()
This interrupt function allow to start the CSI3 transfer every 300 µs
******************************
void IntTimerM_Compare(void)
#pragma ghs interrupt
   InitDMA();
/* clear FIFO pointer */
   _{\text{FPCLR0}} = 1;
   mbytes = 0;
/* Start the first transmission every 300 µs by writing the data to SFDB register */
/* Write CS into transmit CS register */
   SFCS0L = csdata[mbytes];
/* Write byte into transmit data register */
   SFDB0L = txdata[mbytes];
}
void INTDMA1(void)
#pragma ghs interrupt
/* clear FIFO pointer to make the last chip select inactive*/
   _{\text{FPCLR0}} = 1;
```

3.5.3 FIFO buffer mode without DMA

```
// PROJECT: V850E/RS1 CSI3 driver in FIFO buffer mode without DMA
// MODULE : Main.c
// VERSION: 1.0
// DATE : 22/06/05
//-----
            COPYRIGHT
//-----
// Copyright (c) 2002 by NEC Electronics (Europe) GmbH, Succursale Française.
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// 78142 Vélizy Cedex
// France
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// the particular purpose. NEC shall not have any obligation to maintain,
// service or provide bug fixes for the supplied Product(s) and/or the
// Application.
//
\ensuremath{//} Each User is solely responsible for determining the appropriateness of
// using the Product(s) and assumes all risks associated with its exercise
// of rights under this Agreement, including, but not limited to the risks
// and costs of program errors, compliance with applicable laws, damage to
// or loss of data, programs or equipment, and unavailability or
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// such damages. NEC shall not be liable for any services or products provided
// by third party vendors, developers or consultants identified or referred
// to the User by NEC in connection with the Product(s) and/or the
// Application.
//
// Environment: Devices : V850E/RS1
            Assembler : GHS AS-V850
//
                                             Version: 4.0.5
            C-Compiler: GHS CCV850, Multi 2000, V800 Version: 4.0.5
//
           Linker : GHS lx, Multi 2000, V800 Version: 4.0.5
//
           Debugger : GHS Multi 2000, V800
                                             Version: 4.0.5
//-----
// Version Author Description // 1.0 Ferry-Chappuis Released
/****************************
This software is used to develop the module for the CSI3 in FIFO buffer mode
without DMA interface.
Notes:
In order to send the data 2 chip select are used alternatively.
The received data are read when the end of transmission interrupt INTC30I occurs.
*******************
```

```
/*****************************
Includes
******************
#include "Inc\df3402.h"
#include "Inc\df3402extIO.h"
/****************************
** Declaration of local types **
************************
typedef unsigned char uchar;
typedef unsigned long ulong;
/***************************
** Declaration of variables **
*******************************
           mbytes = 0;
// array for data received / transmitted and chip select
txdata[16] = \{8,8,0,0,0,0,12,12,0,0,0,0,11,11,15,15\};
       uchar
                 0xB, 0xE, 0XB, 0xE, 0XB};
/******************************
CSI3 registers initialisation for single buffer mode operation
This function initialises the selected CSI3 interface
*******************
void InitCSI3FIFO8bits(void)
/* Configure serial transfer operation */
/* This register must be initialised in several times because TRMD, DIR, CSIT, CSWE
    and CSMD bits can be written only when CTXE and CRXE are 0 */
_{\rm POWER0} = 1;
^{\prime \star} CSIL and CSIC registers must be written first because it is possible only if ^{\star\prime}
/* CTXE and CRXE bits in CSIM register are 0 */
/* Configure clock: - Idle level low
                 - sampling edge done on the first edge
                 - prescaler associated to clock, K= 1 (PRSOUT = FQCSI/2), N= 1
                  operation clock = PRSOUT/2)*/
/* Clock speed = 4 MHz*/
CSIC0 = 0x39;
/* Configure buffer number to store data and data length
8-bit data length
chip select signal is active low */
CSIL0 = 0x08;
/* clear FIFO pointer */
_{\text{FPCLR0}} = 1;
```

```
_CSMD0 = 0; /* CS_INACTIVE_DISABLE */
_CSWE0 = 0; /* WAIT_DISABLE */
_CSITO = 1; /* HALF_CLK_DELAY */
_DIRO = 0; /* Transfer direction: MSB first */
_TRMD0 = 1; /* CSI3 in FIFO buffer transfer mode */
 /* enable the transmission */
  _CRXE0 = 1; /* RX_ENABLE */
  _CTXE0 = 1; /* TX_ENABLE */
}
PORTS MANAGEMENT
void InitPorts(void)
/* Initialise port 0 */
  P0
      = 0 \times 00;
       = 0x00;
  PM0
  PMC0 = 0x00;
  PFC0 = 0x00;
/* Initialise port 5 */
  P5
      = 0 \times 00;
       = 0xDF;
  PM5
  PMC5 = 0x30;
  PFC5 = 0x00;
/* Initialise port 9 */
/* LSB */
  P9T.
       = 0x00;
  PM9L = 0x80;
  PMC9L = 0x70;
  PFC9L = 0x00;
  PFCE9L = 0x00;
/* MSB */
       = 0x17;
  Р9Н
        = 0xCB;
  РМ9Н
       = 0x30;
  PMC9H
  PFC9H = 0x20;
PFCE9H = 0x20;
/* Initialise PSWAP */
  PSWAP = 0x02;
}
```

```
/**********************************
Timer M initialisation for compare operation
Compare value to obtain an interruption every 300 µs:
300 \mu s / (1/32 MHz) = 9600 = 0x2580
*************************
void InitTimerMCompareOperation(void)
{
           TMOCTLO = 0x80;
            /* compare value for generating an interrupt every 300 µs */
           TMOCMPO = 0x2580;
            /* interrupt enable and highest level */
           TMOEOICO = 0;
}
Detailed Conception for the function InitialiseRegisters()
*******************
Object : This function initialises I/O ports and other peripherals
          of the MCU
Parameters: none
Return : none
*******************
Inputs validation conditions:
                      void InitialiseRegisters(void)
/* Configure IO ports */
  InitPorts();
/* Configure TIMER M to generate an interrupt every 300 \mu s*/
  InitTimerMCompareOperation();
  InitCSI3FIFO8bits();
}
/*************************
Interruption function IntTimerM_Compare()
This interrupt function allow to start the CSI3 transfer every 300 µs
******************
void IntTimerM_Compare(void)
#pragma ghs interrupt
/* set the number of data in the SFN register */
/* we need to send 16 data */
   SFN0 = 0x00; /* 16 data to be transmitted/received */
   for (mbytes = 0; mbytes < 16;)</pre>
            //test if the FIFO is not full
            if (_SFFUL0 == 0)
               /* Write CS into transmit CS register */
               SFCS0L = csdata[mbytes];
               /* Write byte into transmit data register */
               SFDB0L = txdata[mbytes];
               mbytes++; //increments variable to send next data
}
```

```
/*Interrupt of and of transmission of the CSI3 */
void INTC30I(void)
#pragma ghs interrupt
/* When the transmission of the 16 data is over, the INTC30I occurs
The received data are read from the SIRB register sequentially*/
  for (mbytes = 0; mbytes < 16; mbytes++)</pre>
            rxdata[mbytes] = SIRB0L;
 }
   /* clear FIFO pointer for the next operation with CSI3*/
   SFA0 \mid = 0x80;
}
void main(void)
/* Interrupt configuration */
  C30IC = 0x00;
   /* enable interrupt */
   EI();
/* Configuration for
  - port
  - QSPI */
  InitialiseRegisters();
/* infinite loop */
  while(1)\{\};
```

3.5.4 FIFO buffer mode with DMA

```
// PROJECT: V850E/RS1 CSI3 driver in FIFO buffer mode with DMA
// MODULE : Main.c
// VERSION: 1.0
// DATE : 22/06/05
//----
              COPYRIGHT
//-----
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// 78142 Vélizy Cedex
// France
//-----
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// to the User by NEC in connection with the Product(s) and/or the
// Application.
//
// Environment: Devices : V850E/RS1
            Assembler : GHS AS-V850
                                             Version: 4.0.5
//
            C-Compiler: GHS CCV850, Multi 2000, V800 Version: 4.0.5
//
            Linker : GHS lx, Multi 2000, V800 Version: 4.0.5
//
           Debugger : GHS Multi 2000, V800
                                             Version: 4.0.5
//-----
     ion Author Description
Ferry-Chappuis Released
// Version Author
// 1.0
/***************************
This software is used to develop the module for the CSI3 in FIFO buffer mode
with DMA interface.
Notes:
In order to send the data 2 chip select are used alternatively.
The received data are read when the end of transmission interrupt INTC30I occurs.
*****************************
```

```
/************************
#include "Inc\df3402.h"
#include "Inc\df3402extIO.h"
** Declaration of local types **
typedef unsigned char uchar;
typedef unsigned long ulong;
** Declaration of variables **
*************************
          mbytes = 0;
// array for data received / transmitted and chip select
uchar rxdata[16] = {1,1,1,1,1,1,1,1,1,1,1,1,1,1,1,1};
       txdata[16] = {8,8,0,0,0,0,12,12,0,0,0,0,11,11,15,15};
uchar
       csdata[16] = 0xE, 0XB, 0xE, 0xE, 0xB, 0xB, 0xE, 0XB, 0xE, 0xE, 0xB,
uchar
                 0xB, 0xE, 0XB, 0xE, 0XB);
/* Data + chip select to be sent in 16 data transfer */
/* 32 bit send to SFDB and SFCL registers
    txdata32[16] = \{0x0008000E, 0x0008000B, 0x0000000E, 0x0000000E,
                 0x0000000B, 0x0000000B, 0x0000C000E, 0x000C000B,
                 0x0000000E, 0x0000000E, 0x0000000B, 0x0000000B,
                 0x000B000E, 0x000B000B, 0x000F000E, 0x000F000B};
#define TX_DATA_FIFO 0xFD44;// define address of SFCS0 as destination address for DMA
channel 2
#define RX_DATA_FIFO 0xFD42;// define address of SIRBO as source address for DMA
channel 1
```

```
CSI3 registers initialisation for single buffer mode operation
************************
This function initialises the selected CSI3 interface
*******************
void InitCSI3FIFO8bits(void)
/* Configure serial transfer operation */
/* This register must be initialised in several times because TRMD, DIR, CSIT, CSWE
     and CSMD bits can be written only when CTXE and CRXE are 0 ^{*}/
 _{\rm POWER0} = 1;
 ^{\prime \star} CSIL and CSIC registers must be written first because it is possible only if ^{\star\prime}
/* CTXE and CRXE bits in CSIM register are 0 */
 /* Configure clock: - Idle level low
                     - sampling edge done on the first edge
                     - prescaler associated to clock, K= 1 (PRSOUT = FQCSI/2), N= 1
                       operation clock = PRSOUT/2)*/
/* Clock speed = 4 MHz*/
CSICO = 0x39;
/* Configure buffer number to store data and data length
8-bit data length
chip select signal is active low */
CSIL0 = 0x08;
/* clear FIFO pointer */
_{\rm FPCLR0} = 1;
_CSMD0 = 0; /* CS_INACTIVE_DISABLE */
_CSWE0 = 0; /* WAIT_DISABLE */
_CSITO = 1; /* HALF_CLK_DELAY */
            /* Transfer direction: MSB first */
_{DIR0} = 0;
TRMD0 = 1;
            /* CSI3 in FIFO buffer transfer mode */
  /* enable the transmission */
  _CRXE0 = 1; /* RX_ENABLE */
  _CTXE0 = 1; /* TX_ENABLE */
  /* set the number of data in the SFN register */
  /* we need to send 16 data */
  SFN0 = 0x00; /* 16 data to be transmitted/received */
}
```

```
PORTS MANAGEMENT
void InitPorts(void)
/* Initialise port 0 */
      = 0x00;
  ΡO
      = 0x00;
  PM0
  PMC0 = 0x00;
 PFC0 = 0x00;
/* Initialise port 5 */
  Р5
      = 0x00;
  PM5
       = 0xDF;
      = 0x30;
  PMC5
  PFC5 = 0x00;
/* Initialise port 9 */
/* LSB */
  P9L
       = 0 \times 00;
  PM9L
       = 0x80;
  PMC9L = 0x70;
  PFC9L = 0x00;
  PFCE9L = 0x00;
/* MSB */
      = 0x17;
  P9H
  PM9H = 0xCB;
  PMC9H = 0x30;
  PFC9H = 0x20;
  PFCE9H = 0x20;
/* Initialise PSWAP */
  PSWAP = 0x02;
}
********************
Timer M initialisation for compare operation
Compare value to obtain an interruption every 300 µs:
300 \mu s / (1/32 MHz) = 9600 = 0x2580
void InitTimerMCompareOperation(void)
{
           TMOCTL0 = 0x80;
           /\ast compare value for generating an interrupt every 300 \mu s ^{\ast}/
           TMOCMPO = 0x2580;
           /* interrupt enable and highest level */
           TMOEQICO = 0;
}
```

```
/******************************
InitialiseRegisters()
This function initialises I/O ports and other peripherals of the MCU
void InitialiseRegisters(void)
/* Configure IO ports */
              InitPorts();
/* Configure TIMER M compare operation to generate an interrupt every 300 µs*/
              InitTimerMCompareOperation();
              InitCSI3FIFO8bits();
}
/* ---- Set DMA Registers ---- */
/* DMA channel 1 used for received data */
/* DMA channel 2 is used to transmit the data: 32 bit into SFCS and SFDB register */
^{\prime \star} The data transfer is started using a software trigger of DMA channel 2 in the ^{\star\prime}
/* timer M routine*/
/* DMA channel 1 is triggered by the CSI3 interrupt INTC30I (end of transmission)*/
/* Both DMA are in Fixed channel transfer mode */
/*-----*/
void InitDMA(void)
/* DMA control register (DMC)*/
// The DMC register controls the operation and the clock supply of the DMA controller.
// It can be read or written in 8-bit or 1-bit units. Initial value is 00H by reset.
//DMC |STPDIS | IDMEN | STPSET | STPCLR | 0 | 0 | 0 | POWER
// clear the status flag. All DMA transfer are operational: STPDIS = 0
// NMI interrupts and stops all on-going DMA transfers: IDMEN = 1
// DMA transfer interrupted by software: STPSET = 1
// The clock supply to the DMA controller is started and the DMA operation enabled.
// POWER = 1
   DMC = 0x71;
// INTDMAn timing is based on DMA execution: TCS = 1 is recommended for RS1
// Clear any pending DMA transfer request: FCLR = 1
// DMA channel 1 is disabled EN = 0
   DMCHC1 = 0x04;
   DMCHC2 = 0x04;
   DMSA1H = 0 \times 0.2 FF;
   DMSA2H = 0x02FF;
/* source adress */
   DMSA1L = RX DATA FIFO; // source - point to SIRBO address buffer.
   DMSA2L = 0xffff & (unsigned int)(&Txdata32[0x00]); // source - point to transmit buffer
   DMDA1H = 0x02FF;
   DMDA2H = 0x02FF;
```

```
/* destination adress */
   DMDAlL = 0xffff & (unsigned int)(rxdata); // destination address is rxdata[]
   DMDA2L = TX_DATA_FIFO; /* SFCS0 destination address */
// One trigger is required to transfer DMBC elements
   DMBC1 = 0x000Fi/* 16 data to be received with DMA ch1*/
   DMBC2 = 0 \times 000 \text{ F}; /* 16 data to be sent with DMA ch2 */
// source address is internal RAM: TS1 TS0 = 1 0;
// Destination address is on chip IO TD1 TD0 = 1 1;
// Source address is incremented SAD = 0
// Destination address is fixed DAD= 1
// transmit 32 bit: DS1 DS0 = 1 0;
// Single transfer mode TM1 TM0 = 0 0;
// Transfer from source to destination TDIR = 0
   DMADC1 = 0xE804; // transfer size 8bit, Fixed channel transfer mode
// Transfer from source to destination
   {\tt DMADC2} = 0{\tt xB284}; // 32{\tt bit} length to transmit the data to SFCSO register
    //Fixed channel transfer mode
// Unmasked DMA channel 1 interrupt
   DMAIC1 = 0x00; // Highest priority for DMA channel 1
// DMA interrupt trigger
   DTFR1 = 0x29; // DMA channel 1 is triggered on CSI30 interrupt INTC30I
   DTFR2 = 0x00; // DMA channel 2 is triggered by software
    // trigger will load SFCS and SFBD register to send the data (8bit)
   DMCHC1 = 0x21; // DMA transfer is enabled
   DMCHC2 = 0x21;
}
void INTDMA1(void)
#pragma ghs interrupt
/* clear all FIFO pointers to make the last chip select inactive*/
   _{\text{FPCLR0}} = 1;
/*************************
Interruption function IntTimerM_Compare()
This interrupt function allow to start the CSI3 transfer every 300 µs
************************
void IntTimerM_Compare(void)
#pragma ghs interrupt
{
   InitDMA();
// test if the FIFO buffer is not full
   if (_SFFUL0 == 0)
              // Start DMA channel 2 with software trigger
              DMCHC2 = 0x23; // STG = 1
```

3.5.5 Startup program: Startup df3402.850

Remark: Startup is a common program to every operating mode. In the section "Selection of external interrupt service handler", please take care to enable only the required interrupt service handling used in the appropriate software example programs.

```
__***************************
--*
          Startup_df3402.850 -
_-*
--* NEC V850 microcontroller device uPD70F3402
__*
__*
   GHS Startup Module template
__*
__*
--* Copyright (C) NEC Corporation 2003
--* Startup_df3402.850 created from device file df3400.800 [E1.00e]
--* by DeFiX V1.06a
--* This file is only intended as a sample supplement to NEC tools.
--* Feel free to adapt it to your own needs.
--* This File is provided 'as is' without warranty of any kind.
--* Neither NEC nor their sales representatives can be held liable
--* of any inconvenience or problem caused by its contents.
___***************************
----- Selection of external interrupt service handler
----- User modifiable section
----- Please unable the required interrupt service handler
______
#define RESET ENABLE
                       // Always used
#define INTC301 ENABLE
                      // Always used
                       // Only used in single and FIFO buffer mode without DMA
#define INTC30I_ENABLE
--#define INTC300_ENABLE
#define INTDMA1_ENABLE
                       // Not used
                       // Only used in single and FIFO buffer mode with DMA
.include "df3402.s"
______
----- Basic Initialisation of the controller
----- User modifiable section
-- This startup initialize the PLLO and PLL1
.text
_RESET:
```

```
-- == Initialisation of NPB wait states=====
-- NPB Wait Control: VSWC
-- Operation Frequency (fx) VSWC setting
-- 4 MHz <=fx <= 25 MHz
-- 25 MHz <=fx <= 33 MHz
                  12H
-- 33 MHz <=fx <= 50 MHz
                  14H
______
   movea 0x12,zero,r19
   st.b r19, VSWC[zero]
-- initialisation of the watchdog timer
        | 0 | WDM21 | WDM20 | WDCS24 | WDCS23 | WDCS22 | WDCS21 | WDCS20 |
-- WDM21 WDM20 Selection of operation mode of watchdog timer 2
  0 0 Stops operation
       1 Non-maskable interrupt request mode (generation of INTWDT2)
   0
         Reset mode (generation of WDTRES2)
______
   st.b r0,WDTM2[zero]
-- == Initialisation of CLOCKTREE ======
-- use PLLO for CPU @ Fmax
-- To use PLL
                      =====
-- 1) setting OCKSn register
                      =====
-- 2) setting CKC register
-- 1) setting PLLCTLn register ======
-- 1) setting MPCCTL register
                     ======
-- Clock selection register 0 (OCKS0)
-- OCKSO | 0 | 0 | 0 | OCKSENO | OCKSTHO | 0 | OCKSO1 | OCKSO0 |
-- OCKSENO Specified for execution enable
-- 0 PLL operation Disable
-- 1 PLL operation Enable
-- OCKSTHO Specified for output clock through or divide
-- 0 Output clock is divided clock by setting OCKS01 & OCKS00
       Output clock is through
-- OCKS01 OCKS00 Specified for divider factor
-- 0 0
              fxx/2
  0
       1
              fxx/3
  1
       0
              fxx/4
      1
  1
              fxx/5
______
```

```
movea 0x11,zero,r19
    st.b r19,0CKS0[zero]
-- To obtain 16 MHz with PLL1 we need to configure the following register to the
-- described value
-- OCKS1 divide value = 5 ==> OCKS1 = 0x13
-- CKC divide value = 1 ==> CKC = 0x03
    movea 0x13,zero,r19
    st.b r19,0CKS1[zero]
______
-- Clock control register (CKC)
      |0|0|0|0|0|CKDIV1|CKDIV0|
                  System clock (fXX) select on PLL mode
-- CKDIV1 CKDIV0
   0 0
0 1
1 0
                   Setting prohibit
                   fxx = fPLL(PLL internal clock) / 4
                    fxx = fPLL(PLL internal clock) / 2
   1
          1
                   fxx = fPLL(PLL internal clock)
    movea 0x03,zero,r19
    -- Dummy write to PRCMD register before
    st.b r19,PRCMD[zero]
    st.b r19,CKC[zero]
    nop
    nop
    nop
    nop
    nop
    st.b r0,PLLCTL0[zero]
    st.b r0,PLLCTL1[zero]
______
-- Switch from oscillator clock to PLL clock
-- MPCCTL | SELPLL | 0 | 0 | 0 | MCKSEL | PCKSEL | STPPLL1 | STPPLL0 |
-- SELPLL selection of PLL operation
-- need to write in two times because the SELPLL bit can not be configured
-- at the same time
    movea 0x04,zero,r19
     -- Dummy write to PRCMD register before
    st.b r19,PRCMD[zero]
    st.b
          r19,MPCCTL[zero]
    nop
    nop
    nop
    nop
    nop
```

```
movea 0x84,zero,r19
    st.b r19,PRCMD[zero]
    st.b r19,MPCCTL[zero]
    nop
    nop
    nop
    nop
    nop
__ ______
-- Extension clock select register (EXCKSEL)
-- This is an 8-bit register that selects the internal clock.
-- This register can be read or written in 8-bit or 1-bit units.
--EXCKSEL | 0 | 0 | CB1CKSEL | CB0CKSEL | CS31CKSEL | CS30CKSEL | AF1CKSEL | AF0CKSEL |
-- CS3nCKSEL
                     CSI3n clock selection (n =0, 1)
                    Normal clock selection (fxx)
                    Extended clock selection (f_{PLL\_PCKSEL})
   movea 0x0C,zero,r19
    st.b r19,EXCKSEL[zero]
```

```
-- Processor clock control register initialization (PCC):
         0 | 0 |MFRC| 0 | 0 |CK2| CK1| CK0|
-- MFRC internal main clock feedback resistor
      0 = connected // 1 = disconnected
___
___
    CK2 CK1 CK0
  0 0 0 -> fxx
___
  0 0 1
                  -> fxx/2
  0 1 0
                  -> fxx/4
  -> fxx/8 (reset)
                  -> fxx/16
      0
      0 1
1 0
   1
                  -> fxx/32
   1
                  -> Setting prohibited
       1
           1
                  -> Setting prohibited
    _Select_fxx:
    --clear sys register
   st.b r0,SYS[zero]
   -- Dummy write to PRCMD register before
   st.b r0,PRCMD[zero]
   st.b r0,PCC[zero]
   --movea 0x02,zero,r19
   --st.b r19,PRCMD[zero]
   --st.b r19,PCC[zero]
   nop
   nop
   nop
   nop
   nop
    -- Check that no protection error occurred
    tst1 0,SYS[zero]
    -- Branch back if PRERR bit is 1
    bne _Select_fxx
______
-- adjust PLL lockup time (PLLS)
-- 0x 0 0 0 0 0 0 PLLS1 PLLS0
-- PLLS1 PLLS0-
                  > Lockup time (> 800 µs)
             0 -> 2^10/fx
-- 0
-- 0
             1
                  -> 2^11/fx
-- 1
             0
                   -> 2^12/fx (1024 µs at 4 MHz, 819 µs at 5 MHz)
                   -> 2^13/fx (value after reset)
             1
   movea 0x02,zero,r19
    st.b r19,PLLS[zero]
```

```
-- ------
-- == Initialisation some SYSTEM PARAMETERS for GHS=====
-- Initialisation of the global pointer
   movhi hi(___ghsbegin_sdabase),zero,gp
   movea lo(___ghsbegin_sdabase),gp,gp
   -- Initialisation of the text pointer
   movhi hi(___ghsbegin_robase),zero,tp
        lo(___ghsbegin_robase),tp,tp
   -- Initialisation of the stack pointer
   movhi
        hi(___ghsend_stack-4),zero,sp
   movea
        lo(___ghsend_stack-4),sp,sp
    -- Initialisation of the MM register
    -- Initialisation of the BCC register
   -- Initialisation of the DWC register
    -- Jump to the Initialisation functions of the library,
    -- from there to main()
    jr __start
______
______
---- Add section ".intvect" to your linker command file
----- at address 0x0000
----- i.e..intvect 0x0000:
.section".intvect",.text
----- Initializing of interrupt vector table
----- Please don't modify this section
______
#ifdef RESET_ENABLE
   .offset 0x0000
   .extern _RESET
   jr _RESET
#endif
```

```
#ifdef INTWDT2_ENABLE
    .offset 0x0020
    .extern _INTWDT2
    jr _INTWDT2
#endif
#ifdef NMI2_ENABLE
    .offset 0x0030
    .extern _NMI2
    jr _NMI2
#endif
#ifdef TRAPO_ENABLE
    .offset 0x0040
    .extern _TRAP0
    jr _TRAP0
#endif
#ifdef TRAP1_ENABLE
    .offset 0x0050
    .extern _TRAP1
    jr _TRAP1
#endif
#ifdef DBG0_ENABLE
    .offset 0x0060
    .extern _DBG0
    jr _DBG0
#endif
#ifdef ILGOP_ENABLE
    .offset 0x0060
    .extern _ILGOP
    jr _ILGOP
#endif
#ifdef INTLVI_ENABLE
   .offset 0x0080
    .extern _INTLVI
    jr _INTLVI
#endif
#ifdef INTPO_ENABLE
    .offset 0x0090
    .extern _INTP0
    jr _INTPO
#endif
#ifdef INTP1_ENABLE
    .offset 0x00a0
    .extern _INTP1
    jr _INTP1
#endif
```

```
#ifdef INTP2_ENABLE
    .offset 0x00b0
    .extern _INTP2
    jr _INTP2
#endif
#ifdef INTP3_ENABLE
    .offset 0x00c0
    .extern _INTP3
    jr _INTP3
#endif
#ifdef INTP4_ENABLE
    .offset 0x00d0
    .extern _INTP4
    jr _INTP4
#endif
#ifdef INTP5_ENABLE
    .offset 0x00e0
    .extern _INTP5
    jr _INTP5
#endif
#ifdef INTP6_ENABLE
    .offset 0x00f0
    .extern _INTP6
    jr _INTP6
#endif
#ifdef INTP7_ENABLE
    .offset 0x0100
    .extern _INTP7
    jr _INTP7
#endif
#ifdef INTTQ0OV_ENABLE
    .offset 0x0110
    .extern _INTTQ00V
    jr _INTTQ00V
#endif
#ifdef INTTQ0CC0_ENABLE
    .offset 0x0120
    .extern _INTTQ0CC0
    jr _INTTQ0CC0
#endif
#ifdef INTTQ0CC1_ENABLE
    .offset 0x0130
    .extern _INTTQ0CC1
    jr _INTTQ0CC1
#endif
```

```
#ifdef INTTQ0CC2_ENABLE
    .offset 0x0140
    .extern _INTTQ0CC2
    jr _INTTQ0CC2
#endif
#ifdef INTTQ0CC3_ENABLE
    .offset 0x0150
    .extern _INTTQ0CC3
    jr _INTTQ0CC3
#endif
#ifdef INTTPOOV_ENABLE
    .offset 0x0160
    .extern _INTTP00V
    jr _INTTP00V
#endif
#ifdef INTTPOCCO_ENABLE
    .offset 0x0170
    .extern _INTTP0CC0
    jr _INTTPOCCO
#endif
#ifdef INTTPOCC1_ENABLE
    .offset 0x0180
    .extern _INTTP0CC1
    jr _INTTP0CC1
#endif
#ifdef INTTP10V_ENABLE
    .offset 0x0190
    .extern _INTTP10V
    jr _INTTP10V
#endif
#ifdef INTTP1CC0_ENABLE
   .offset 0x01a0
    .extern _INTTP1CC0
    jr _INTTP1CC0
#endif
#ifdef INTTP1CC1_ENABLE
    .offset 0x01b0
    .extern _INTTP1CC1
    jr _INTTP1CC1
#endif
#ifdef INTTP2OV_ENABLE
    .offset 0x01c0
    .extern _INTTP20V
    jr _INTTP20V
#endif
```

```
#ifdef INTTP2CC0_ENABLE
    .offset 0x01d0
    .extern _INTTP2CC0
    jr _INTTP2CC0
#endif
#ifdef INTTP2CC1_ENABLE
    .offset 0x01e0
    .extern _INTTP2CC1
    jr _INTTP2CC1
#endif
#ifdef INTTP3OV_ENABLE
    .offset 0x01f0
    .extern _INTTP30V
    jr _INTTP30V
#endif
#ifdef INTTP3CC0_ENABLE
    .offset 0x0200
    .extern _INTTP3CC0
    jr _INTTP3CC0
#endif
#ifdef INTTP3CC1_ENABLE
    .offset 0x0210
    .extern _INTTP3CC1
    jr _INTTP3CC1
#endif
#ifdef INTTM0EQ0_ENABLE
    .offset 0x0220
    .extern _INTTM0EQ0
    jr _INTTM0EQ0
#endif
#ifdef INTCBOR_ENABLE
    .offset 0x0230
    .extern _INTCBOR
    jr _INTCBOR
#endif
#ifdef INTCBOT_ENABLE
    .offset 0x0240
    .extern _INTCBOT
    jr _INTCB0T
#endif
#ifdef INTCB1R_ENABLE
    .offset 0x0250
    .extern _INTCB1R
    jr _INTCB1R
#endif
```

```
#ifdef INTCB1T_ENABLE
    .offset 0x0260
    .extern _INTCB1T
    jr _INTCB1T
#endif
#ifdef INTUAOR_ENABLE
    .offset 0x0270
    .extern _INTUAOR
    jr _INTUAOR
#endif
#ifdef INTUAOT_ENABLE
    .offset 0x0280
    .extern _INTUA0T
    jr _INTUAOT
#endif
#ifdef INTUA1R_ENABLE
    .offset 0x0290
    .extern _INTUA1R
    jr _INTUA1R
#endif
#ifdef INTUA1T_ENABLE
    .offset 0x02a0
    .extern _INTUA1T
    jr _INTUA1T
#endif
#ifdef INTAD_ENABLE
    .offset 0x02b0
    .extern _INTAD
    jr _INTAD
#endif
#ifdef INTCOERR_ENABLE
   .offset 0x02c0
    .extern _INTCOERR
    jr _INTCOERR
#endif
#ifdef INTCOWUP_ENABLE
    .offset 0x02d0
    .extern _INTCOWUP
    jr _INTCOWUP
#endif
#ifdef INTCOREC_ENABLE
    .offset 0x02e0
    .extern _INTCOREC
    jr _INTCOREC
#endif
```

```
#ifdef INTCOTRX_ENABLE
    .offset 0x02f0
    .extern _INTCOTRX
    jr _INTCOTRX
#endif
#ifdef INTC30I_ENABLE
    .offset 0x0300
    .extern _INTC30I
    jr _INTC30I
#endif
#ifdef INTC300_ENABLE
    .offset 0x0310
    .extern _INTC300
    jr _INTC300
#endif
#ifdef INTC31I_ENABLE
    .offset 0x0320
    .extern _INTC31I
    jr _INTC31I
#endif
#ifdef INTC310_ENABLE
    .offset 0x0330
    .extern _INTC310
    jr _INTC310
#endif
#ifdef INTCB2R_ENABLE
    .offset 0x0340
    .extern _INTCB2R
    jr _INTCB2R
#endif
#ifdef INTCB2T_ENABLE
    .offset 0x0350
    .extern _INTCB2T
    jr _INTCB2T
#endif
#ifdef INTTQ10V_ENABLE
    .offset 0x0360
    .extern _INTTQ10V
    jr _INTTQ10V
#endif
#ifdef INTTQ1CC0_ENABLE
    .offset 0x0370
    .extern _INTTQ1CC0
    jr _INTTQ1CC0
```

#endif

```
#ifdef INTTQ1CC1_ENABLE
    .offset 0x0380
    .extern _INTTQ1CC1
    jr _INTTQ1CC1
#endif
#ifdef INTTM1EQ0_ENABLE
    .offset 0x0390
    .extern _INTTM1EQ0
    jr _INTTM1EQ0
#endif
#ifdef INTTQ1CC2_ENABLE
    .offset 0x0390
    .extern _INTTQ1CC2
    jr _INTTQ1CC2
#endif
#ifdef INTTM2EQ0_ENABLE
    .offset 0x03a0
    .extern _INTTM2EQ0
    jr _INTTM2EQ0
#endif
#ifdef INTTQ1CC3_ENABLE
    .offset 0x03a0
    .extern _INTTQ1CC3
    jr _INTTQ1CC3
#endif
#ifdef INTUA2R_ENABLE
    .offset 0x03b0
    .extern _INTUA2R
    jr _INTUA2R
#endif
#ifdef INTUA2T_ENABLE
   .offset 0x03c0
    .extern _INTUA2T
    jr _INTUA2T
#endif
#ifdef INTC1ERR_ENABLE
    .offset 0x03d0
    .extern _INTC1ERR
    jr _INTC1ERR
#endif
#ifdef INTC1WUP_ENABLE
    .offset 0x03e0
    .extern _INTC1WUP
    jr _INTC1WUP
#endif
```

```
#ifdef INTC1REC_ENABLE
    .offset 0x03f0
    .extern _INTC1REC
    jr _INTC1REC
#endif
#ifdef INTC1TRX_ENABLE
    .offset 0x0400
    .extern _INTC1TRX
    jr _INTC1TRX
#endif
#ifdef INTDMA0_ENABLE
    .offset 0x0410
    .extern _INTDMA0
    jr _INTDMA0
#endif
#ifdef INTDMA1_ENABLE
    .offset 0x0420
    .extern _INTDMA1
    jr _INTDMA1
#endif
#ifdef INTDMA2_ENABLE
    .offset 0x0430
    .extern _INTDMA2
    jr _INTDMA2
#endif
#ifdef INTDMA3_ENABLE
    .offset 0x0440
    .extern _INTDMA3
    jr _INTDMA3
#endif
#ifdef INTDMA4_ENABLE
    .offset 0x0450
    .extern _INTDMA4
    jr _INTDMA4
#endif
#ifdef INTDMA5_ENABLE
    .offset 0x0460
    .extern _INTDMA5
    jr _INTDMA5
#endif
#ifdef INTFLTMO_ENABLE
    .offset 0x0470
    .extern _INTFLTMO
    jr _INTFLTMO
#endif
```

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