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April 1st, 2010
Renesas Electronics Corporation

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V850E/IF3, V850E/IG3

32-bit Single-Chip Microcontrollers

Sample Programs for Watchdog Timer

V850E/IF3:
  μPD70F3451
  μPD70F3452

V850E/IG3:
  μPD70F3453
  μPD70F3454
NOTES FOR CMOS DEVICES

1. VOLTAGE APPLICATION WAVEFORM AT INPUT PIN
   Waveform distortion due to input noise or a reflected wave may cause malfunction. If the input of the CMOS device stays in the area between \( V_{IL} \) (MAX) and \( V_{IH} \) (MIN) due to noise, etc., the device may malfunction. Take care to prevent chattering noise from entering the device when the input level is fixed, and also in the transition period when the input level passes through the area between \( V_{IL} \) (MAX) and \( V_{IH} \) (MIN).

2. HANDLING OF UNUSED INPUT PINS
   Unconnected CMOS device inputs can be cause of malfunction. If an input pin is unconnected, it is possible that an internal input level may be generated due to noise, etc., causing malfunction. CMOS devices behave differently than Bipolar or NMOS devices. Input levels of CMOS devices must be fixed high or low by using pull-up or pull-down circuitry. Each unused pin should be connected to \( V_{DD} \) or GND via a resistor if there is a possibility that it will be an output pin. All handling related to unused pins must be judged separately for each device and according to related specifications governing the device.

3. PRECAUTION AGAINST ESD
   A strong electric field, when exposed to a MOS device, can cause destruction of the gate oxide and ultimately degrade the device operation. Steps must be taken to stop generation of static electricity as much as possible, and quickly dissipate it when it has occurred. Environmental control must be adequate. When it is dry, a humidifier should be used. It is recommended to avoid using insulators that easily build up static electricity. Semiconductor devices must be stored and transported in an anti-static container, static shielding bag or conductive material. All test and measurement tools including work benches and floors should be grounded. The operator should be grounded using a wrist strap. Semiconductor devices must not be touched with bare hands. Similar precautions need to be taken for PW boards with mounted semiconductor devices.

4. STATUS BEFORE INITIALIZATION
   Power-on does not necessarily define the initial status of a MOS device. Immediately after the power source is turned ON, devices with reset functions have not yet been initialized. Hence, power-on does not guarantee output pin levels, I/O settings or contents of registers. A device is not initialized until the reset signal is received. A reset operation must be executed immediately after power-on for devices with reset functions.

5. POWER ON/OFF SEQUENCE
   In the case of a device that uses different power supplies for the internal operation and external interface, as a rule, switch on the external power supply after switching on the internal power supply. When switching the power supply off, as a rule, switch off the external power supply and then the internal power supply. Use of the reverse power on/off sequences may result in the application of an overvoltage to the internal elements of the device, causing malfunction and degradation of internal elements due to the passage of an abnormal current.
   The correct power on/off sequence must be judged separately for each device and according to related specifications governing the device.

6. INPUT OF SIGNAL DURING POWER OFF STATE
   Do not input signals or an I/O pull-up power supply while the device is not powered. The current injection that results from input of such a signal or I/O pull-up power supply may cause malfunction and the abnormal current that passes in the device at this time may cause degradation of internal elements.
   Input of signals during the power off state must be judged separately for each device and according to related specifications governing the device.
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INTRODUCTION

Cautions 1. This Application Note explains a case where the V850E/IG3 is used as a representative microcontroller. Use this Application Note for your reference when using the V850E/IF3.


3. The sample programs are provided for reference purposes only and operations are therefore not subject to guarantee by NEC Electronics Corporation. When using sample programs, customers are advised to sufficiently evaluate this product based on their systems, before use.

4. When using sample programs, reference the following startup routine and link directive file and adjust them if necessary.
   • Startup routine: ig3_start.s
   • Link directive file: ig3_link.dir

Target Readers
This Application Note is intended for users who understand the functions of the V850E/IF3 (μPD70F3451, 70F3452), and V850E/IG3 (μPD70F3453, 70F3454), and who design application systems that use these microcontrollers.

Purpose
This manual is intended to give users an understanding of the basic functions of the V850E/IF3 and V850E/IG3, using the application programs.

How to Use This Manual
It is assumed that the reader of this Application Note has general knowledge in the fields of electrical engineering, logic circuits, and microcontrollers.

For details of hardware functions (especially register functions, setting methods, etc.) and electrical specifications

For details of instruction functions
→ See the V850E1 Architecture User’s Manual.

Conventions
Data significance: Higher digits on the left and lower digits on the right
Active low representation: xxx (overscore over pin or signal name)
Memory map address: Higher addresses on the top and lower addresses on the bottom

Note: Footnote for item marked with Note in the text
Caution: Information requiring particular attention
Remark: Supplementary information
Numeric representation: Binary ... xxxx or xxxxB
             Decimal ... xxxx
             Hexadecimal ... xxxxH

Prefix indicating the power of 2 (address space, memory capacity):
K (kilo): $2^{10} = 1,024$
M (mega): $2^{20} = 1,024^2$
G (giga): $2^{30} = 1,024^3$
The function lists are structured as follows.

### Theme

| [Function] | Function description |
| [Function name] | Name of sample function |
| [Argument(s)] | Type and overview of argument(s) |
| [Processing content] | Processing content of sample function |
| [SFR(s) used] | Register name and setting content |
| [call function(s)] | Name and function of call function(s) |
| [Variable(s)] | Type, name, and overview of variable(s) used in sample function |
| [Interrupt(s)] | Name of function |
| [Interrupt source(s)] | Name |
| [File name] | Name of corresponding sample program file |
| [Caution(s)] | Caution(s) upon function usage |

### Interrupt function

| [Function name] | Name of interrupt function |
| [Overview] | Servicing content |
| [Source(s)] | Name of interrupt and conditions for occurrence |
| [call function(s)] | None |
| [Variable(s)] | Name of variable, function |
| [File name] | Name of corresponding sample program file |
| [Caution(s)] | None |
The related documents indicated in this publication may include preliminary versions. However, preliminary versions are not marked as such.

### Documents related to V850E/IF3 and V850E/IG3

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CHAPTER 1 WATCHDOG TIMER

[Functions] The following functions are implemented by mode specification.
• Reset mode:
  Performs reset operation upon overflow of the watchdog timer.
• Non-maskable interrupt request mode:
  Performs a non-maskable interrupt operation upon overflow of the watchdog timer.

[Function name] main
[Argument] None
[Processing content] Starts the watchdog timer.
[SFR used] None
[call function] WDT_clear_stop, WDT_clr_cnt
[Variable] None
[Interrupt] INT_WATCHDOG (in non-maskable interrupt request mode)
[Interrupt source] WDTRES (in reset mode)
INTWDT (in non-maskable interrupt request mode)
[File name] watchdog_timer\MAIN.C
[Caution] None

[Function name] WDT_clear_stop
[Arguments] unsigned char set_WDM Sets the operation mode.
unsigned char set_WDCS Sets the overflow time.
[Processing content] Starts the watchdog timer in the operation mode and upon the overflow time both set by
the argument.
[SFRs used] WDTM Sets the operation mode and overflow time.
WDTE: 0xAC (enables watchdog timer operation)
[call function] None
[Variable] None
[File name] watchdog_timer\watchdog_timer_1.c,
[Caution] The WDTM register can only be written once after reset release.
[Function name] WDT_clr_cnt  
[Argument] None  
[Processing content] Stops the watchdog timer.  
[SFR used] WDTE: 0xAC (Count clear of watchdog timer)  
[call function] None  
[Variable] None  
[File name] watchdog_timer/watchdog_timer_1.c  
[Caution] None

Interrupt function

[Function name] INT_WATCHDOG  
[Overview] Defined by the user.  
[Source(s)] INTWDT Watchdog timer overflow  
[call function] None  
[Variable] None  
[File name] watchdog_timer/watchdog_timer_1.c  
[Caution] None
Figure 1-1. Watchdog Timer (WDT)

- **main**
  - WDT_clear_stop
    - Sets watchdog timer
  - WDT_clr_cnt
    - Clears count of watchdog timer
  - WDTM
    - Sets operation mode and overflow time
  - WDTE ← 0xAC
    - Clears count of watchdog timer
  - ret

- **WDT_clear_stop**
  - WDTM ← set_WDM + set_WDCS
    - Sets operation mode and overflow time
  - ret

- **INT_WDT**
  - (Overflow of watchdog timer)
  - INT_WATCHDOG
    - ret
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