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# HEW

## Tool Memory Map (Mapping)

## Introduction

This document explains the need and usage of memory mapping in development tools.

This involved the usage of the compiler, linker, simulator and emulator.

With an understanding of the concept of memory mapping, users will be able to use the tools more effectively.

#### **Target Device**

All



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#### 1. Overview

Memory mapping is a common term used in the development environment. It is used to prevent programmers from making mistake, such as:

- 1. Executing code out of the permitted range in the MCU memory specification
- 2. Accessing of in-correct memory space.
- 3. Code written to read only memory.

Generally user view the memory map of an MCU (Micro-Controller Unit) as:

- 1. Internal memory (inside the MCU)
- 2. External memory (outside the MCU)
- 3. Internal IO area
- 4. Reserved area

whereby the internal & external memory may contain:

- 1. Read only memory (ROM, FLASH, E2PROM...)
- 2. Read Write memory (RAM)

In a development environment, the tools used will guard against any incorrect access to the area.

In general, the tools will disallow

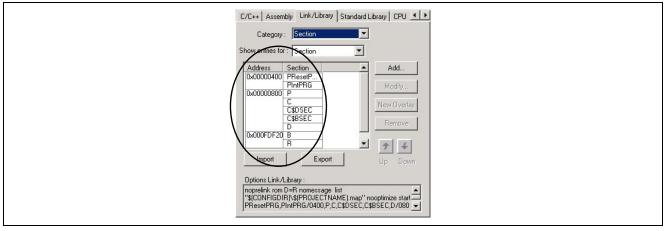
- 1. Write to read-only area
- 2. Access to reserved area



#### 2. Compiler & Linker

The HEW project generator will produce the basic framework based on user's selection. The selection of CPU, mode, stack... will determine the setup of the initial section (or memory map).

Example:



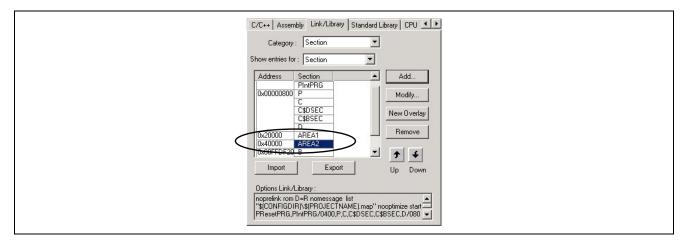


The Linker will try to fix the compiled code into the declared sections. If a fix is not possible, a linker error will be alerted. However a possible fix will only indicate the correctness of the code's syntax, in which the generated object code is able to be loaded into the specified MCU memory.

User may change this generated sections to suit to their application need.

Example:

Addition of specified address to force the code to be located at external area.





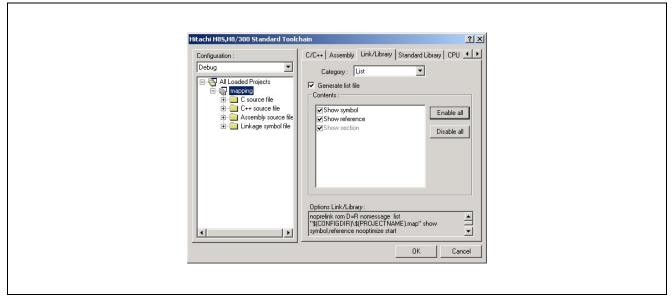
Addition to section

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### HEW Tool Memory Map (Mapping)

PRELIMINARY

The compiler and linker generated the ELF/DWARF II format file (\*.abs) (other formats can be selected). Unlike the s-record (\*.mot) file, which only contains the machine code, this file contains the debugging information. Users may generate the map file [selection made under HEW Option/ Toolchain/ Link/ List] to view the area where the code is loaded. This information can be viewed with the MAP Viewer (Please refer to the HEW User Manual or Application Note "Effective Usage of HEW Map Viewer" for more details)



#### Figure 3 Generation of Map file

The linker has performed the static level of memory mapping check, for preventing the generated code from exceeding the specified section declaration. Next, the generated code will be downloaded to either a simulator or emulator for debugging.

In both simulator and emulator, a dynamic level of memory mapping check is performed.



#### 3. Simulator

As the named implied, a simulator will work "like a MCU" on a PC.

Thus user will have to provide the MCU information to the PC prior to a proper simulation. Before loading of user code, user has to allocated resources for the simulator, such as telling the PC that memory allocation H'0 to H'FFF is ROM, H'FE00H to H'FFFF is RAM... This is to facilitate the guarding process.

In HEW2, this process has been automated, as long as the simulator checkbox in the project generator process is checked. The HEW project generator will allocated the initial resources for the simulator to work on. User may need to further modify it to suit to their application.

In the simulator, the guarding process (memory mapping) is classified into the following terms, which are self-explainable:

- 1. Read
- 2. Write
- 3. Read-Write

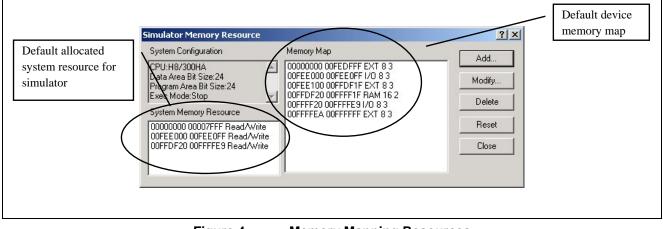


Figure 4

**Memory Mapping Resources** 

The auto generated system memory resource can be further modified to suit the user's need. If the reset button is depressed, all the allocated resource will be removed.

Start Address H'00000000 OK End Address H'00000000 Cancel Access Type C Read C Write © Read/Write	System Memory Resource Modify	<u>?×</u>
	End Address H'00000000	

Figure 5

Modification to memory mapping resource

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## PRELIMINARY HEW Tool Memory Map (Mapping)

This memory mapping guarding tool will prevent user from loading code into unspecified area.

After the code is loaded into the simulator, user can open the status window [View/CPU/Status] memory tab, to view the area where the code is loaded

Item	Status
Memory Mode	None
Target Device Configuration	00000000-00FEDFFF EXT
	OOFEEOOO-OOFEEOFF I/O
	OOFEE100-OOFFDF1F EXT
	00FFDF20-00FFFF1F RAM
	OOFFFF20-OOFFFFE9 I/O
	OOFFFFEA-OOFFFFFF EXT
System Memory Resources	00000000-00007FFF Read/Write
	OOFEE000-OOFEEOFF Read/Write
	00FFDF20-00FFFFE9 Read/Write
Program Name	Memory Loaded Area
ng\Debug\mapping.abs	H,00000000 - H,00000003
	H'0000001C - H'00000047
	H'00000050 - H'00000053
	H'0000005C - H'0000006B
	H'00000070 - H'0000007B
	H'00000080 - H'0000008B
	H'00000090 - H'000000AF
	H'00000D0 - H'000000EF
	H'00000400 - H'00000461
	H'00000800 - H'000008F1
<u>  </u>	•
▲ ► Memory A Platform A Events /	

Figure 6

Memory Status Window



#### 4. Emulator

Unlike the simulator, the emulator uses the actual or bond-out chip to execute the user codes. Thus the memory mapping control will be more sophisticated than the simulator.

In the emulator context, there are three memory areas:

- 1. On Chip Memory
- 2. External Memory
- 3. Emulator Memory

Among these memories, there are three kind of classification:

- 1. Read-only
- 2. Read/Write
- 3. Guarded

Thus user can have nine memory mapping selection based on the above combination:

- 1. On chip read-only
- 2. On chip read/write
- 3. On chip guarded
- 4. External read-only
- 5. External read/write
- 6. External guarded
- 7. Emulator read-only
- 8. Emulator read/write
- 9. Emulator guarded

Technically, On chip guarded, External guarded and Emulator guarded are equivalent.



#### 4.1 On Chip Memory

This memory refers to the available internal memory in the MCU (RAM, ROM & IO).

When access is concerned, this will be 1<sup>st</sup> priority in the emulator.

- If user has physically connected an external memory to address H'0 – H'1FFF which is also the On chip ROM area, the external memory will be ignored (no conflict will happen).

#### 4.2 Emulator Memory

As compared to the actual chip and simulator, emulator memory is considered a new term used. This memory is provided as a temporary mean when the target memory is not available (E.g. Target hardware fabrication is not ready) Thus it is a substitute for External memory.

When access is concerned, this will be 2nd priority in the emulator.

- If a target memory is available and it is mapped to area 2. When the emulator memory is also set to area 2, this emulator memory will be accessed instead of the external memory (no conflict will occur)

#### 4.3 External Memory

This memory refers to the memory mapped to the external area of the MCU

When access is concerned, this will be last priority in the emulator.

#### 4.4 Read-only

When any type of memory is classified as read-only, any attempt to write to this area, will cause a break to the normal execution. This break is named as "write protected break"

#### 4.5 Guarded

An area is guarded if it is a reserved or protected area. Thus any attempt to access (read or write) this area, will generate a break. This break is named as "Guarded break"

#### 4.6 Read/Write

Any other area that are not read-only or guarded is considered as read/write area. It allows program to read or write to the area.



#### 5. New device's memory mapping

The followings give programmer a quick start guide in generating their memory mapping control when the device mapping data is not available yet.

In general, when a new device is introduced, it can fall into few categories

- new core, a new family, a new series

#### Code Writing

The advice is to select the nearest family/series for the project creation, and modify the section & <iodefine.h> file, based on the new device specifications (ROM, RAM & IO address).

Let take an example based on H8S/2215 (assuming it is a new device). From the H8S device introduction and roadmap, programmer can know that H8S/2238 is an ancestor of H8S/2215. The differences between the two devices are:

- ROM & RAM sizes, &
- Addition of USB peripherals.

To begin writing code for the H8S/2215, programmer can

- Generate the code based on H8S/2238.
- Modify the section file for ROM/RAM boundary
- Add the structure definition for all the USB registers, and define the address.

#### Simulator

Since simulator cannot simulate the IO, Programmer can select a close family to simulate the device. The only possible changes are the ROM & RAM boundary address.

#### Emulator

However, complications will arrive in the case of emulator. User has to find out the ability of the emulator to support the new device.

- If its does (when device information is not available), then the user can only use the tool, to emulate the new device to a substantial level.

Example: when selecting H8S/2238 to emulate H8S/2215, user will not be able to emulate the USB peripherals. Other peripherals are performing as it is (IO addresses are identical)

- However if the new device is a mere ROM and RAM size different, user will be able to perform emulation, as long as their program do not exceed the memory size boundary.

Example: H8S/2144 is a smaller version of H8S/2148

In summary, user can perform immediate emulation as long as the generated code is running on the correct core. However it is still advisable to obtain the latest device information from the support groups.



## HEW Tool Memory Map (Mapping)

## **Revision Record**

	Date	Descripti	ion
Rev.		Page	Summary
1.00	September 03	_	First edition issued



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