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Renesas Electronics Corporation

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M16C/80 Group

Solution for External Interrupt Pins Shortage

1.0 Abstract

The following are solution for external interrupt pins shortage using event counter mode of timer A.
Use the following peripheral function:

- Event counter mode of timer A

2.0 Introduction

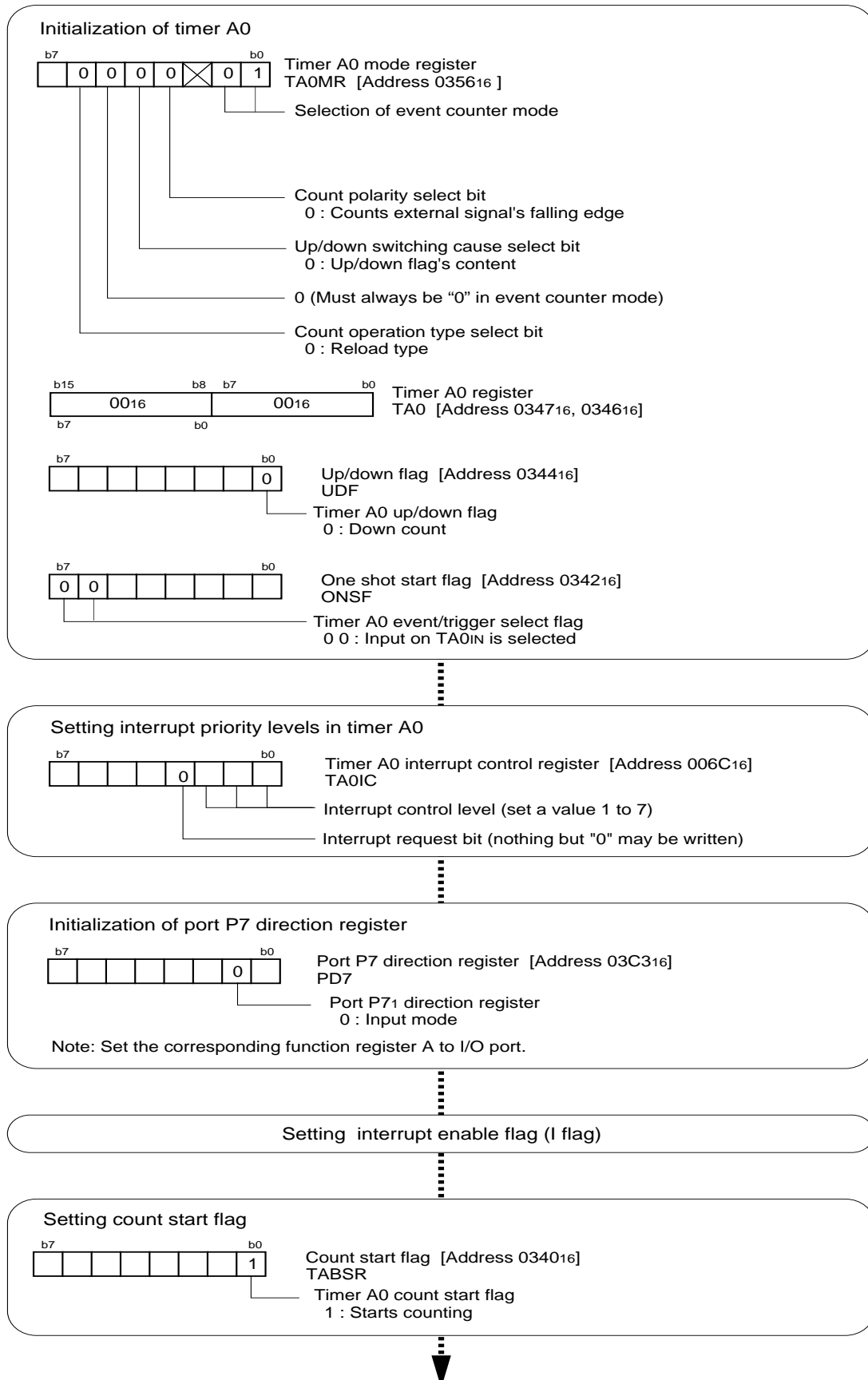
Specifications

- (1) Inputting a falling edge to the TA0_{IN} pin generates a timer A0 interrupt.

Operation

- (1) Set timer A0 to event counter mode, set timer to "0", and set interrupt priority levels in timer A0.
- (2) Inputting a falling edge to the TA0_{IN} pin generates a timer A0 interrupt.

3.0 Set-up procedure



4.0 Programming Code

```

;*****
;
;   M16C/80 Program Collection
;
;   FILE NAME : rjj05b0509_src.a30
;   CPU       : M16C/80 Group
;   FUNCTION  : Timer A Applications
;               (Solution for External Interrupt Pins Shortage)
;   HISTORY   : 2004.03.15 Ver 1.00
;
;   Copyright(C)2003, Renesas Technology Corp.
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;
;*****
;*****
;   Include
;*****
;*****
;   .LIST      OFF          ;Stops outputting lines to the assembler list file
;   .INCLUDE   sfr80100.inc ;Reads the file that defined SFR
;   .LIST      ON          ;Starts outputting lines to the assembler list file
;
;*****
;   Symbol definition
;*****
RAM_TOP      .EQU    000400H ;Start address of RAM
RAM_END      .EQU    002BFFH ;End address of RAM
ROM_TOP      .EQU    0FFC000H ;Start address of ROM
VECT_TOP     .EQU    0FFF5BAH ;Start address of variable vector
FIXED_VECT_TOP .EQU    0FFFFDCH ;Start address of fixed vector
;
;*****
;   Program area
;*****
;=====
;   Start up
;=====
;   .SECTION   PROGRAM, CODE ;Declares section name and section type
;   .ORG      ROM_TOP       ;Declares start address
RESET:
    LDC       #RAM_END+1, ISP ;Sets initial value in stack pointer
;   Sets Processor mode, System clock and Main clock division
    MOV.B     #03H, prcr      ;Removes protect
    MOV.B     #10000000B, pm0 ; Single-chip mode
    MOV.B     #11000000B, pm1 ; Flash memory version
    MOV.B     #00001000B, cm0 ; Xcin-Xcout High
    MOV.B     #00100000B, cm1 ; Xin-Xout High
    MOV.B     #00010010B, mcd ; No division mode
    MOV.B     #00H, prcr      ;Protects all registers
;
    LDC       #VECT_TOP, INTB ;Sets initial value in interrupt table register
;

```

```

;=====
;      TimerA (solution for external interrupt pins shortage)
;=====
;-----
;      Initialization of Timer A0
;-----
;      ; Selecting timer mode and functions
MOV.B   #00000001B, ta0mr
;      |||||++-----;Selection of event counter mode
;      |||||+-----;This bit is invalid in M16C/80 series
;      ||||+-----;Count polarity select bit
;      ||||          (0:Counts external signal's falling edge)
;      |||+-----;Up/down switching cause select bit (0:Up/down flag's content)
;      ||+-----;Must always be "0" in event counter mode
;      |+-----;Count operation type select bit (0:Reload type)
;      +-----;When not using the 2-phase pulse signal processing function,
;              set the select bit to "0"

;      ; Setting Timer A0 register
MOV.W   #0000H, ta0
;      ; Up/down flag
MOV.B   #00000000B, udf
;      +-----;Timer A0 up/down flag (0:Down count)
;      ; One shot start flag
MOV.B   #00000000B, onsf
;      ++-----;Timer A0 event/trigger select flag
;              (00:Input on TA0in is selected)
;      ; Setting interrupt priority levels in timer A0
MOV.B   #00000001B, ta0ic
;      |+++-----;Interrupt control level (Set a value 1 to 7)
;      +-----;Interrupt request bit (This bit can only be accessed for reset(=0) )
;      ; Initialization of port P7 direction register
BCLR    pd7_1          ;Port P71(TA0in) direction register (0:Input mode) (Note)
;      ; (Note) Set the corresponding function register A to I/O port
BCLR    ps1_1          ;Port P71 is I/O port
;
;      ; Setting interrupt enable flag (I flag)
FSET    I
;
;      ; Setting count start flag
MOV.B   #00000001B, tabsr
;      +-----;TimerA0 count start flag (1:Starts counting)

MAIN:
;      ; Inputting a falling edge to the TA0in pin
;      ; generates a timer A0 interrupt
JMP     MAIN

;=====
;      Interrupt program
;=====
INT_TA0:
    REIT
;

```

```

;=====
;      Dummy interrupt processing program
;=====
dummy:
    REIT
;
;*****
;      Setting of variable vector table
;*****
    .SECTION    VECT, ROMDATA
    .ORG        VECT_TOP+(12*4)
;
    .LWORD      INT_TA0      ;TA0 interrupt vector
    .LWORD      dummy        ;TA1 interrupt vector
;
;*****
;      Setting of fixed vector
;*****
    .SECTION    F_VECT, ROMDATA
    .ORG        FIXED_VECT_TOP
;
    .LWORD      dummy        ;Undefined instruction
    .LWORD      dummy        ;Overflow
    .LWORD      dummy        ;BRK instruction execution
    .LWORD      dummy        ;Address match
    .LWORD      dummy        ;
    .LWORD      dummy        ;Watchdog timer
    .LWORD      dummy        ;
    .LWORD      dummy        ;NMI
    .LWORD      RESET        ;Reset
;
    .END

```

5.0 Reference

Renesas Technology Corporation Semiconductor Home page
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Technical Support

E-mail: support_apl@renesas.com

Data Sheet

M16C/80 group Rev. E3
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