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April 1st, 2010
Renesas Electronics Corporation

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SH7144/45 Group

2-Phase Encoder Count

1. Specifications

Two external clocks are input to channel 1 (ch1), and a counter is incremented or decremented according to the phase difference of the pulses, as shown in figure 1. The ch1 count is measured in synchronization with a measurement times set in ch0 (measurement times 1 and 2), and the result is set in RAM.

H'0000 is set as the timer counter initial value, and counting can be performed from -2,147,483,648 to 2,147,483,647 using a software counter.

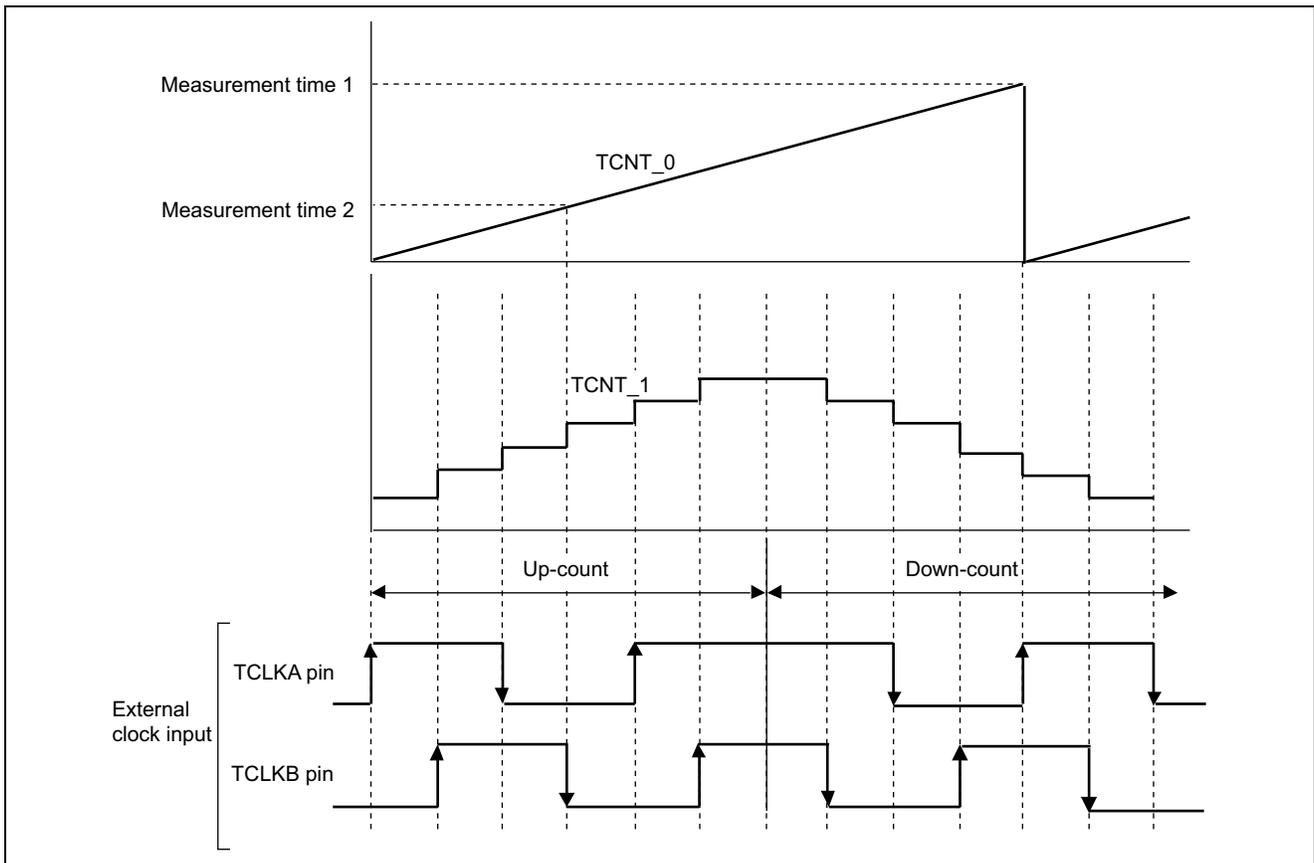


Figure 1 2-Phase Encoder Counter Capture

2. Functions Used

In this sample task, measurement times are set in TGRA/B_0 using an MTU ch1 up/down-counter.

Using a TGRA/B_0 output compare as a trigger, the TCNT_1 value for the control period is captured by ch1 input capture. In addition, the ch1 counter input clock width is captured using ch0 input capture.

Figure 2 shows a block diagram of ch0. In ch0, a ch1 input capture trigger is output every measurement time using the following functions. In ch1, the TCNT_1 value is measured when an input capture signal is input.

- A function that outputs pulses automatically by hardware without software intervention (output compare)
- A function that performs pulse input edge detection, and captures a timer value in an internal register (input capture)

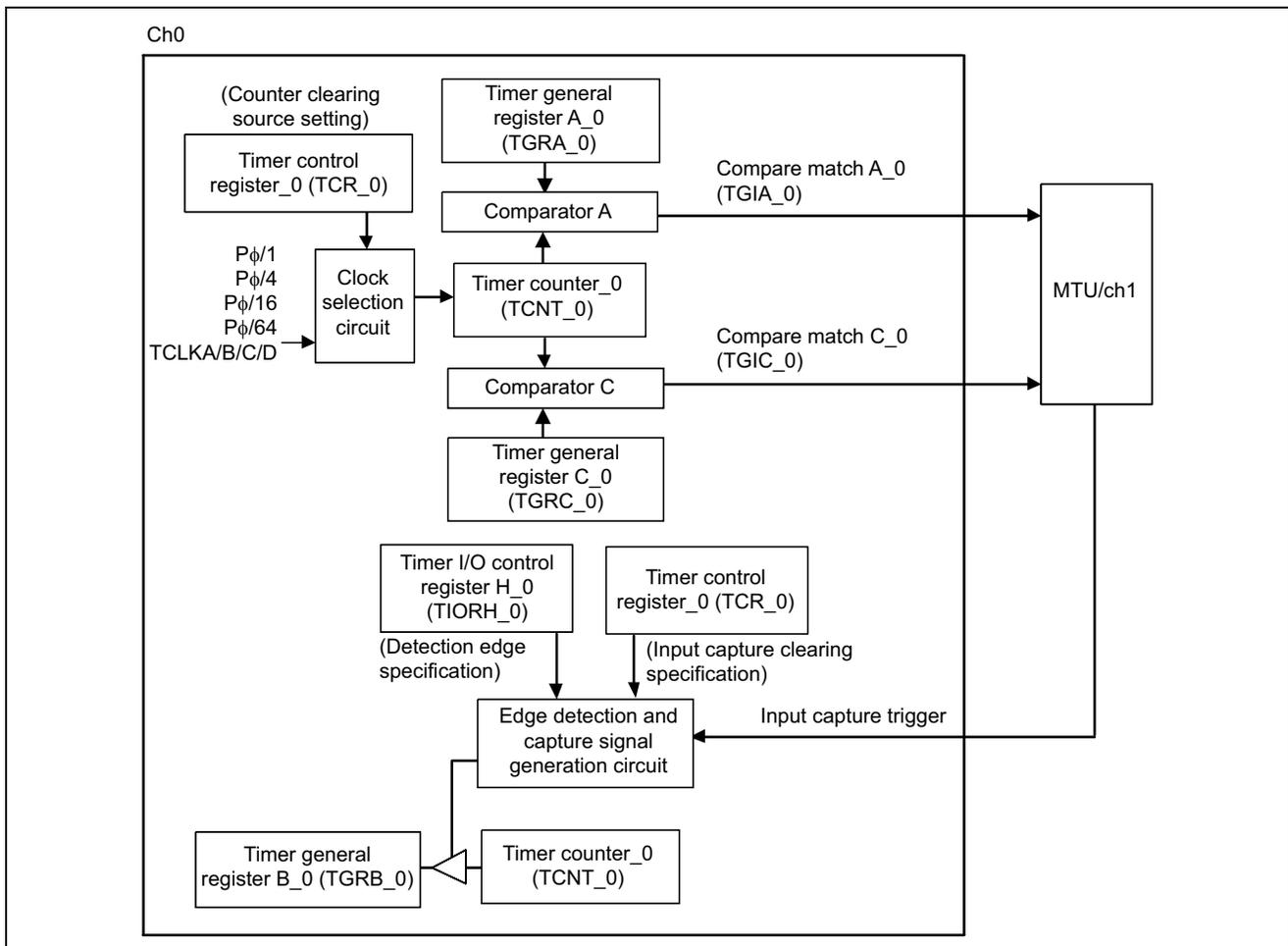


Figure 2 Block Diagram of MTU/ch0

Figure 3 shows a block diagram of ch1. In ch1, a timer counter is incremented/decremented using the following functions. The counter value when an input capture signal rising edge is detected is taken as the measurement result.

- A function that detects the phase difference between two external clocks, and increments/decrements a timer counter (phase counting mode)
- A function that performs pulse input edge detection, and captures a timer value in an internal register (input capture)
- A function that initiates interrupt handling when input capture occurs
- A function that clears the timer counter when a pulse input edge is detected
- A function that initiates interrupt handling when timer counter overflow or underflow is detected

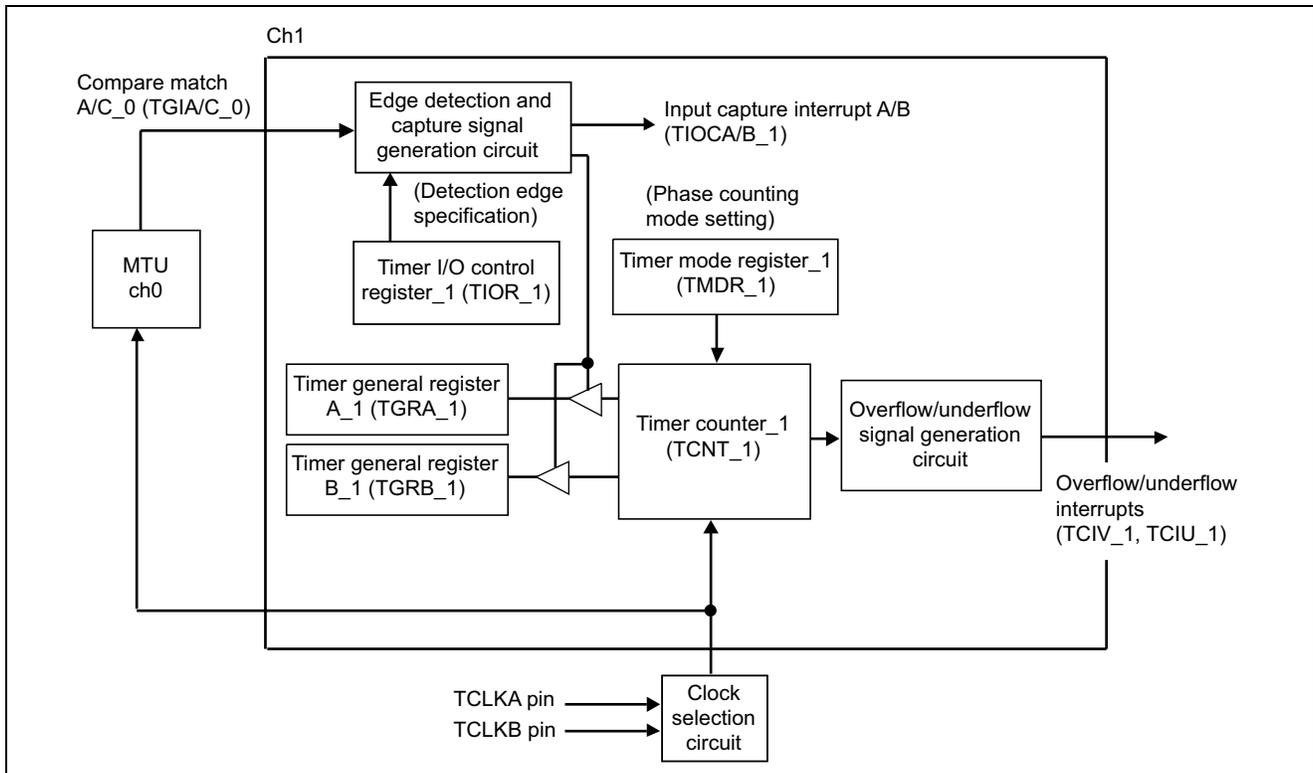


Figure 3 Block Diagram of MTU/ch1

Table 1 shows the function assignments used in this sample task. MTU functions are assigned as shown in the table to detect the phase difference between two 2-phase encoder pulses, and increment/decrement a counter.

Table 1 Function Assignments

Pin or Register Name	Function Assignment
TCLKA	External clock input pins
TCLKB	
TSTR	Enabling/disabling of MTU ch0, ch1 timer counter operation
TCR_0	Selection of counter clock and counter clearing source
TIORH_0	TIOC0A output compare setting. Setting of TIOC0B for input capture on TCNT_1 increment/decrement
TIORL_0	TIOC0C output compare setting
TGRA_0	Measurement time 1 setting
TGRB_0	Count result stored on input capture B
TGRC_0	Measurement time 2 setting
TMDR_1	Sets phase counting mode for MTU/ch1
TCR_1	Selection of counter clock and counter clearing source
TIOR_1	Setting of TIOC1A/B for input capture on TGRA_0, TGRC_0 output compare occurrence
TIER_1	Enables TIOC1A/B, TCIU_1, TCIV_1 interrupts
TGRA_1	Count result storage on input capture
TGRB_1	

3. Principles of Operation

Figure 4 illustrates the principles of operation. A counter is incremented or decremented by SH7145 hardware and software processing.

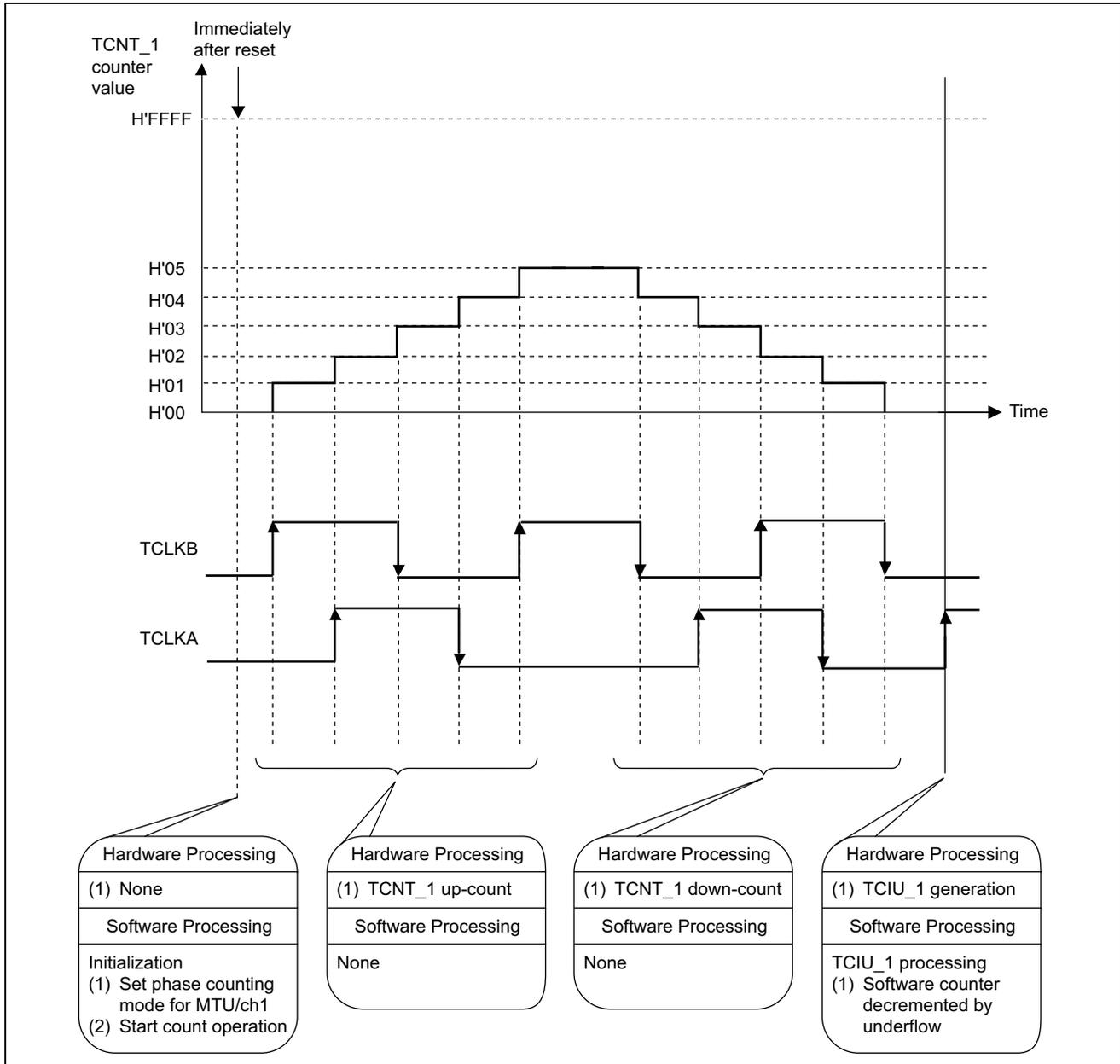


Figure 4 Principles of Operation in Phase Counting Mode (1)

The TCNT_1 count is measured on MTU/ch0 output compare occurrence by means of SH7145 hardware and software processing as shown in figure 5.

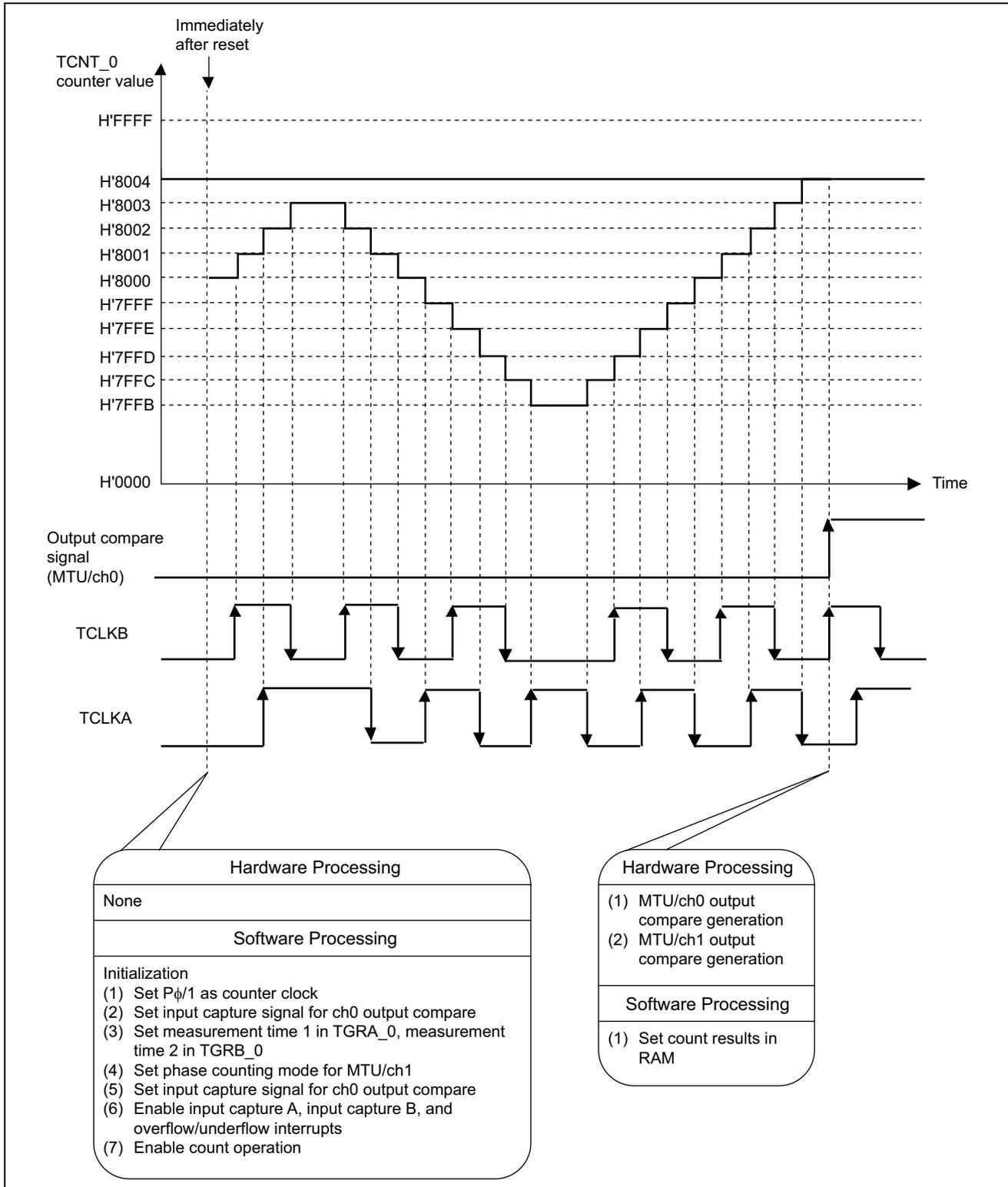


Figure 5 Principles of Operation in Phase Counting Mode (2)

4. Software

(1) Modules

Module Name	Label	Function Assignment
Main routine	en2	Initialization of MTU, etc.
Counter value measurement 1	phacnt1	Initiated by TGIA_1. Sets up/down-count result in RAM based on TGRA_1 value. Sets counter period result in RAM based on TGRB_0 value
Counter value measurement 2	phacnt2	Initiated by TGIB_1. Sets up/down-count result in RAM based on TGRB_1 value
Overflow	ovf1	Initiated by TGIV_1. Software counter incrementing
Underflow	unf1	Initiated by TGIU_1. Software counter decrementing

(2) Arguments

Label or Register Name	Function Assignment	Data Length	Module	Input/Output
msr_tim1 msr_tim2	Used to set timer value for counter measurement time Measurement time is calculated using following equation: Measurement time (ns) = timer value × φ period (25.0 ns at 40.0 MHz operation)	Word	Main routine	Input
cnt_data1 cnt_data2	Used to set up/down-count results	Longword	Counter value measurement 1 Counter value measurement 2	Output
p_cycle	Used to set count period result	Longword	Counter value measurement 2	

(3) Internal Registers Used

Register Name	Function	Address	Set Value
P_STBY.MSTCR2	MTU module standby mode clearing	H'FFFF861E	H'd0fd
P_PORTA.PACRL2	Sets PA6 as TCLKA input pin, PA7 as TCLKB input pin	H'FFFF838E	H'5000
P_MTU0.TCR_0	Selection of counter clock and counter clearing source	H'FFFF8260	H'20
P_MTU0.TIORH_0	TIOC0A output compare setting. Setting of TIOBC0B for input capture on TCNT_1 increment/decrement	H'FFFF8262	H'f0
P_MTU0.TIORL_0	TIOC0C output compare setting	H'FFFF8263	H'00
P_MTU0.TGRA_0	Measurement time 1 setting	H'FFFF8268	msr_tim1
P_MTU0.TGRC_0	Measurement time 2 setting	H'FFFF826C	msr_tim2
P_MTU1.TMDR_1	Sets phase counting mode	H'FFFF8281	H'04
P_MTU1.TIOR_1	Setting of TIOC1A/B for input capture on TGRA_0, TGRC_0 output compare occurrence	H'FFFF8282	H'ff
P_MTU1.TIER_1	Enables interrupts by TGIA/B, TCIU_1, TCIV_1	H'FFFF8284	H'73
P_INTC.IPRD	Sets 15 as MTU0, MTU1 interrupt priority level	H'FFFF834E	H'00ff

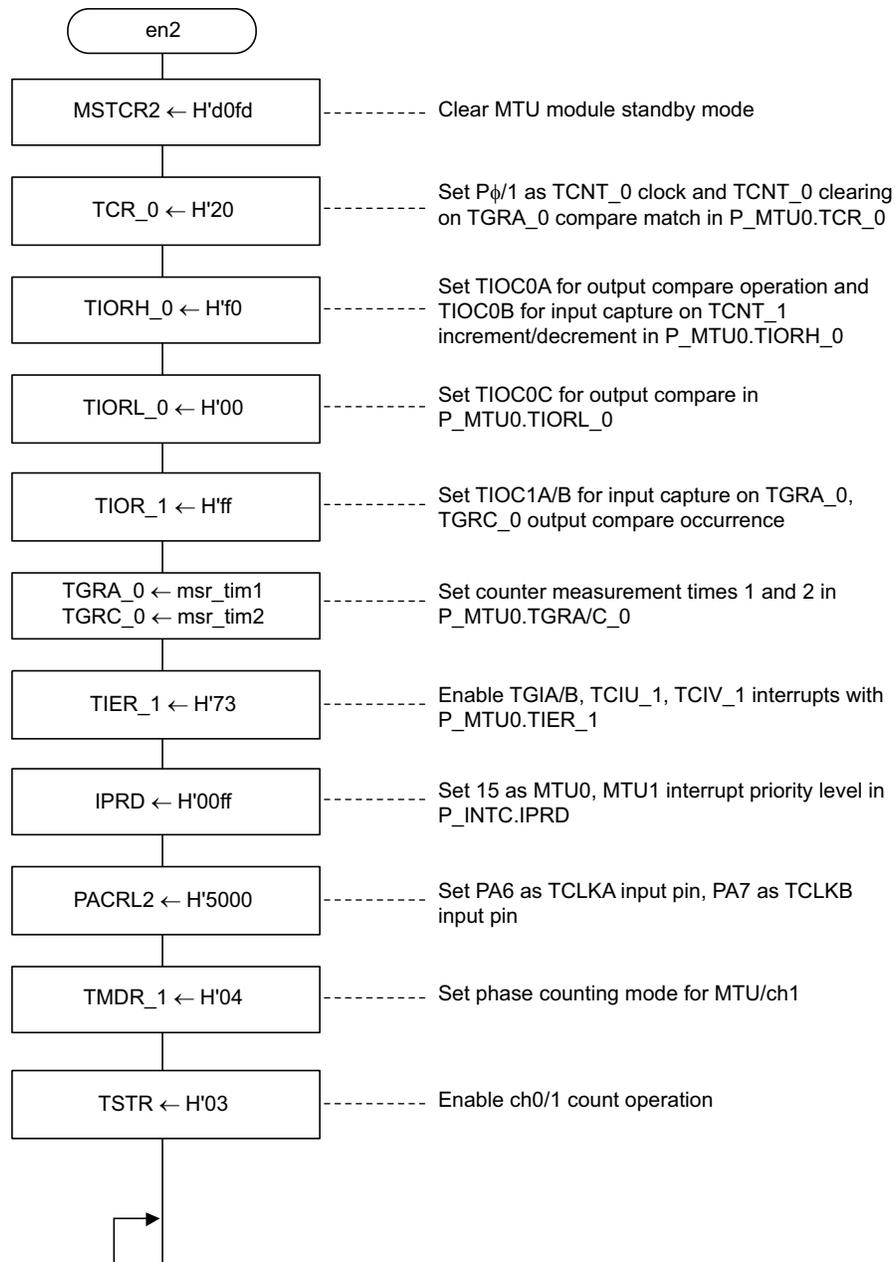
(4) RAM Used

Module	Label	Function Assignment
Counter value measurement 1, 2	wrk	Used as work area for data setting
All modules	cnt	Software counter

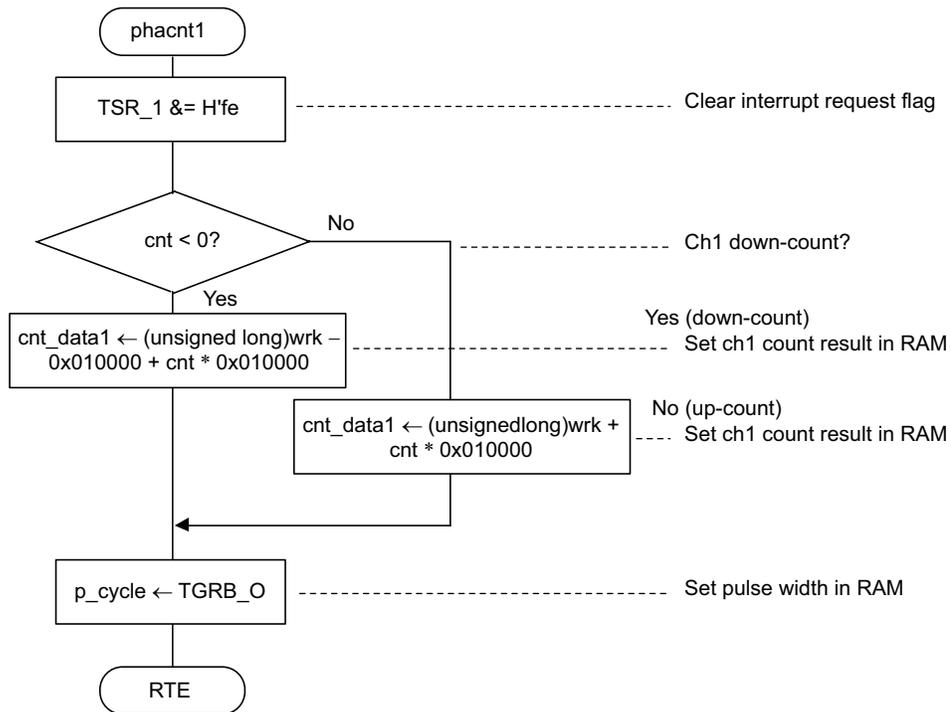
Note: SH7145 header file names are used for register label names.

5. Flowcharts

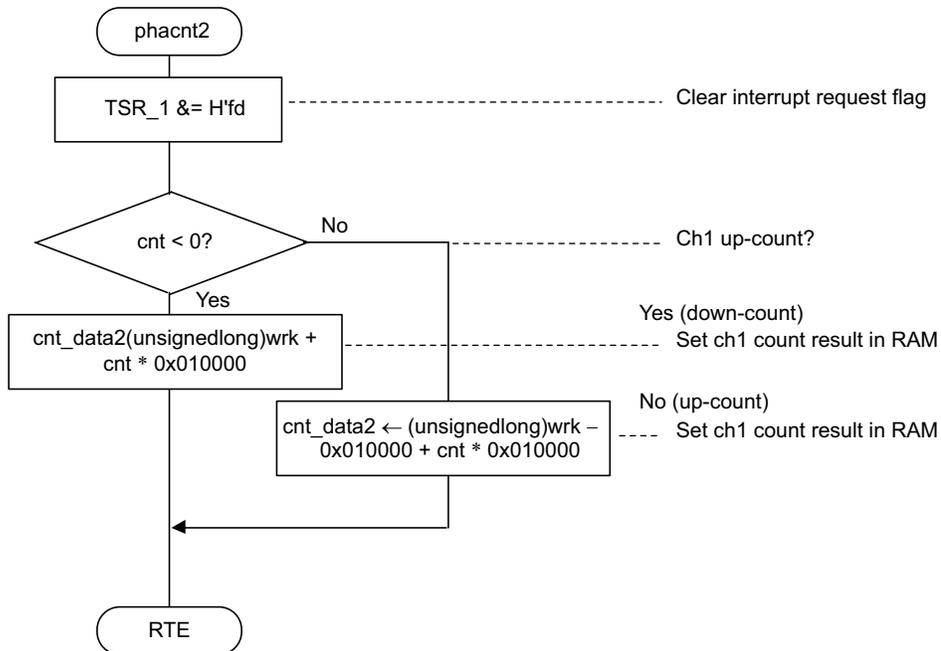
(1) Main routine



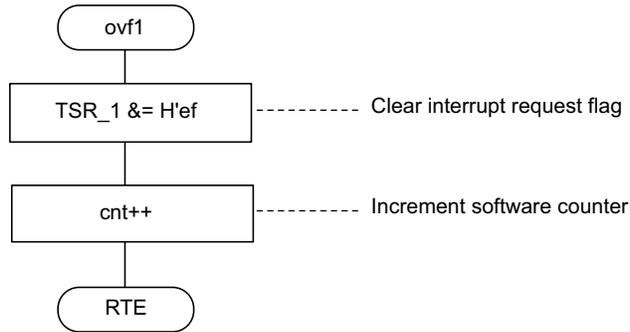
(2) Counter value measurement 1



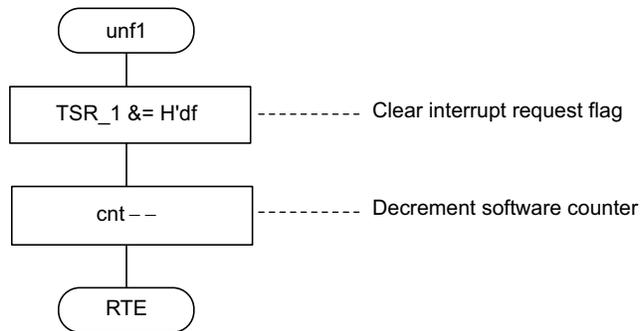
(3) Counter value measurement 2



(4) Overflow



(5) Underflow



6. Program Listing

```

/*-----*/
/*                               INCLUDE FILE                               */
/*-----*/
#include <machine.h>
#include "iodefine_7145F.h"
/*-----*/
/*                               PROTOTYPE                               */
/*-----*/
void en2(void);
#pragma interrupt(phacnt1,phacnt2,ovf1,unf1)
/*-----*/
/*                               RAM ALLOCATION                               */
/*-----*/
#define msr_tim1      (*(unsigned short *)0xffffe000)
#define msr_tim2      (*(unsigned short *)0xffffe002)
#define cnt_data2     (*(signed long *)0xffffe004)
#define cnt_data1     (*(signed long *)0xffffe008)
#define p_cycle       (*(unsigned long *)0xffffe00c)
#define cnt           (*(signed long *)0xffffe010)
#define wrk           (*(unsigned short *)0xffffe014)
/*-----*/
/*                               MAIN PROGRAM                               */
/*-----*/
void en2(void)
{
    P_STBY.MSTCR2.WORD = 0xd0fd;      /* MTU module stop mode clear */
    P_MTU0.TCR0.BYTE = 0x20;         /* timer clear output compare TGRA_0 */
    P_MTU0.TIORH0.BYTE = 0xf0;       /* output compare TIOC0B */
    P_MTU0.TIORL0.BYTE = 0x00;       /* output compare TIOC0C */
    P_MTU1.TIOR1.BYTE = 0xff;        /* input capture TIOC1A,B */
    P_MTU1.TIER1.BYTE = 0x73;        /* enable TGIA,TGIB,TCIU,TCIV */
    P_MTU0.TGRC0 = msr_tim2;         /* set position cycle */
    P_MTU0.TGRA0 = msr_tim1;         /* set speed cycle */
    INTC.IPRD.WORD = 0x00ff;         /* set interrupt level=15 */
    P_PORTA.PACRL2.WORD = 0x5000;    /* TCLKA,TCLKB select */
    P_MTU1.TMDR1.BYTE = 0x04;        /* set phase counting model */
    P_MTU34.TSTR.BYTE = 0x03;        /* start MTU/ch0,1 */
    set_imask(0x0);                 /* set imask level=0 */
    while(1);                        /* loop */
}

void phacnt1(void)
{
    P_MTU1.TSR1.BYTE &= 0xfe;        /* clear flag */
    wrk = P_MTU1.TGRA1;
    if(cnt < 0)                      /* down count? */
        cnt_data1 = (unsigned long)wrk-0x010000+cnt*0x010000; /* set sp */
    else
        cnt_data1 = (unsigned long)wrk+cnt*0x010000;         /* set sp */
    p_cycle = P_MTU0.TGRB0;          /* set width pulse */
}

```

```
void phacnt2(void)
{
    P_MTU1.TSR_1.BYTE &= 0xfd;          /* clear flag */
    wrk = P_MTU1.TGRB_1;
    if(cnt < 0)
        cnt_data2 = (unsigned long)wrk+cnt*0x010000;    /* set po */
    else
        cnt_data2 = (unsigned long)wrk-0x010000+cnt*0x010000; /* set po */
}

void ovf1(void)
{
    P_MTU1.TSR_1.BYTE &= 0xef;          /* clear flag */
    cnt++;                               /* count up */
}

void unfl(void)
{
    P_MTU1.TSR_1.BYTE &= 0xdf;          /* clear flag */
    cnt--;                               /* count down */
}
```

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