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SuperH RISC engine C/C++ Compiler Package

APPLICATION NOTE: [Compiler Use guide] #pragma Extension Guide

This document explains the extended #pragma directives available in SuperH RISC engine C/C++ Compiler version 9. Some of these directives can reduce the program size or improve execution speed while others provide useful functions.

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1. Extended #pragma Directives for Reducing Program Size and Improving Execution Speed

This chapter explains extended #pragma directives that can be effective in reducing program size and improving execution speed. Table 1-1 lists the extended #pragma directives explained in this chapter.

Table 1-1 Extended #pragma directives for improving performance

| No. | #pragma | Explanation | Effectiveness on size | Effectiveness on speed | See section |
|-----|--|--|-----------------------|------------------------|-------------|
| 1 | #pragma abs16 #pragma abs20 #pragma abs28 #pragma abs32 | Specifies address range | A+ | B | 1.1 |
| 2 | #pragma inline | Performs inline expansion of functions | C | A+ | 1.2 |
| 3 | #pragma inline_asm | Expands an assembly-language description function | C | A | 1.3 |
| 4 | #pragma regsave #pragma noregsave #pragma noregalloc | Generates or does not generate save and restore code at the start and end of functions | A | A | 1.4 |
| 5 | #pragma global_register | Allocates global variables to registers | B | B | 1.5 |
| 6 | #pragma gbr_base #pragma gbr_base1 | Specifies GBR base variables | A+ | A | 1.6 |

A+: Very effective.

A: Effective.

B: Effective, but must be used with caution.

C: Lowers performance.

Note that the expanded assembly code examples in this document were obtained by specifying `code=asmcode` and `cpu=sh2`. This code might vary depending on the specification of the `cpu` option. It is also subject to change if the compiler is improved in the future. Accordingly, you should use these code examples for reference only.

1.1 Specifies address range

The #pragma `absn` (n : 16, 20, 28, or 32) directive is a declaration that tells the compiler that the variable or function is in the n -bit address area. The default is the 32-bit address area.

For example, #pragma `abs16` specified for a variable or function means that the variable or function is placed in an address area that can be represented by 16 bits. Compared with the default 32-bit addressing, which uses four bytes for an address value, 16-bit addressing uses only two bytes, and therefore reduces program size. Address area specification for variables and functions that are referenced from many locations effectively reduces program size. Note that if a #pragma `absn` directive is specified for a variable or function, the same #pragma `absn` directive must be specified for all occurrences of the variable or function throughout the source code. For example, you must not specify #pragma `abs16` and #pragma `abs32` for separate occurrences of the same variable or function. Renesas recommends that you specify the #pragma `absn` directive in a common header file.

You can specify #pragma `abs20` and #pragma `abs28` for only the SH-2A and SH2A-FPU microcomputers. For details, see *2.1 20-bit Long Immediate Load* in the manual *SuperH RISC engine C/C++ Compiler Package APPLICATION NOTE: [Compiler use guide] SH-2A / SH2A-FPU*.

You can also use an advanced option to specify the address area. If you specify both the advanced option and the #pragma directive that specify the address area, the #pragma directive takes precedence. As an example of use, when the 16-bit address area is specified for a variable or function, you can use the #pragma `abs32` directive to change the address area to the 32-bit address area, which is the default.

Format:

```
#pragma abs16 (identifier [,identifier...])
#pragma abs20 (identifier [,identifier...])
#pragma abs28 (identifier [,identifier...])
#pragma abs32 (identifier [,identifier...])
identifier: variable name | function name
```

Example:

When abs16 is specified for a variable or function, the address storage area of the variable or function changes from a .DATA.L (4 bytes) to a .DATA.W (2 bytes).

| Source code with #pragma abs16 not specified: | Source code with #pragma abs16 specified: |
|---|--|
| <pre>extern int x(void); int y; long z; void f(void) { z = x() + y; }</pre> | <pre>#pragma abs16 (x,y,z) extern int x(void); int y; long z; void f(void) { z = x() + y; }</pre> |
| <p>Expanded assembly code:</p> <pre>_f: STS.L PR,@-R15 MOV.L L11+2,R2 ; _x JSR @R2 NOP MOV.L L11+6,R5 ; _y MOV.L L11+10,R4 ; _z MOV.L @R5,R1 ; y ADD R1,R0 LDS.L @R15+,PR RTS L11: MOV.L R0,@R4 ; z .RES.W 1 .DATA.L _x .DATA.L _y .DATA.L _z</pre> | <p>Expanded assembly code:</p> <pre>_f: STS.L _PR,@-R15 MOV.W L11,R2 ; _x JSR @R2 NOP MOV.W L11+2,R5 ; _y MOV.W L11+4,R4 ; _z MOV.L @R5,R1 ; y ADD R1,R0 LDS.L @R15+,PR RTS L11: MOV.L R0,@R4 ; z .DATA.W _x .DATA.W _y .DATA.W _z</pre> |

Note:

- If you specify abs16, abs20, abs28, or abs32 for a variable or function, use the #pragma section directive to switch the section so that the section is placed in an address area that can be represented by the specified bit addressing during linkage.
- The following table shows the #pragma absn directives and the address ranges in which a section can be placed.

Table 1-2 Address ranges in which the section can be placed

| #pragma | Address range | |
|---------------|---------------|--------------|
| | Beginning | End |
| #pragma abs16 | 0x00000000 | 0x00007FFF |
| | 0xFFFF8000 | 0xFFFFFFFF |
| #pragma abs20 | 0x00000000 | 0x0007FFFF |
| | 0xFFF80000 | 0xFFFFFFFF |
| #pragma abs28 | 0x00000000 | 0x07FFFF7F * |
| | 0xF8000000 | 0xFFFFFFFF |
| #pragma abs32 | 0x00000000 | 0xFFFFFFFF |

* Note that the address is 0x07FFFF7F.

- If you specify `abs16`, place the section in either of the areas shown in the following figure.

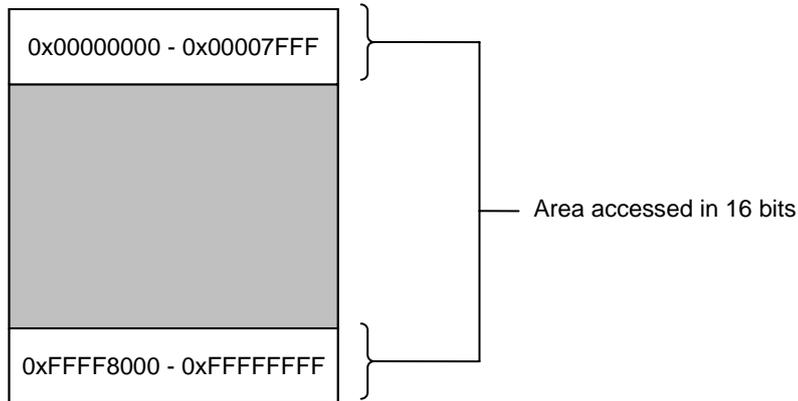


Figure 1-1

- If generation of position-independent code is specified (`pic=1` option) at compile time, function addresses are not generated for the specified bit value because addresses are referenced by relative access.

| Source code: | Expanded assembly code (<code>pic=0</code> specified): | Expanded assembly code (<code>pic=1</code> specified): |
|---|---|--|
| <pre>#pragma abs16 (x,y,z) extern int x(void); int y; long z; void f(void) { z = x() + y; }</pre> | <pre>_f: STS.L PR,@-R15 MOV.W L11,R2 ; _x JSR @R2 NOP MOV.W L11+2,R5 ; _y MOV.W L11+4,R4 ; _z MOV.L @R5,R1 ; y ADD R1,R0 LDS.L @R15+,PR RTS MOV.L R0,@R4 ; z L11: .DATA.W _x .DATA.W _y .DATA.W _z</pre> | <pre>_f: STS.L PR,@-R15 MOV.L L12+6,R3 ; H'FFFFFFFC+_x-L11 L11: BSRF R3 NOP MOV.W L12,R5 ; _y MOV.W L12+2,R2 ; _z MOV.L @R5,R1 ; y ADD R1,R0 LDS.L @R15+,PR RTS MOV.L R0,@R2 ; z L12: .DATA.W _y .DATA.W _z .RES.W 1 .DATA.L H'FFFFFFFC+_x-L11</pre> |

1.2 Performs inline expansion of functions

Inline expansion is a type of optimization that inserts the body of a function at the point at which the function is called. You can use inline expansion when you expect that it will reduce function call overhead, making the program smaller and allowing it to run faster. In particular, inline expansion can be very effective for functions that are called repeatedly in a loop. Since the compiler performs inline expansion before optimizing the source code, note that inline expansion for large functions increases program size, and might reduce the efficiency of compiler optimization. Inline expansion is more effective when it is performed for small functions that are called frequently.

Format:

#pragma inline [(*function-name*[,...][*D*])]

When you specify functions in a `#pragma inline` directive, make sure that the body of each function is defined after the directive.

The compiler also generates external definitions for the functions specified in a `#pragma inline` directive. If these external definitions are not necessary, specify `static` for the function declarations. Since the compiler does not generate the body of a static function when performing inline expansion, specifying `static` might reduce program size.

Whereas automatic inline expansion of the `inline` option specified for a function stops before the specified limit on increase in function size (expressed as a percentage) is reached, automatic inline expansion of the `#pragma inline` directive does not.

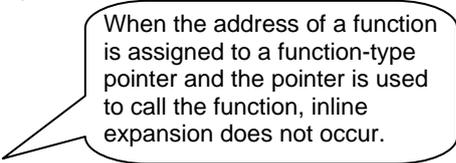
Note that, when `#pragma inline` is specified, inline expansion for a function does not occur if the function satisfies any of the following conditions:

- The function is defined before the `#pragma inline` directive.
- The function has variable parameters.
- The function is called via its address.

```
#pragma inline(func)
static int func (int a, int b)
{
    return (a+b)/2;
}
int x;
void main(void)
{
    int (*func_p)(int,int);

    func_p = func;

    x=func_p(10,20);
}
```



Example: Source before and after inline expansion

Source code:

```
#pragma inline(func)
static int func (int a, int b)
{
    return (a+b)/2;
}
int x;
void main(void)
{
    x=func(10,20);
}
```

Source after expansion:

```
int x;
void main(void)
{
    int func_result;
    {
        int a_1=10, b_1=20;
        func_result=(a_1+b_1)/2;
    }
    x=func_result;
}
```

1.3 Expands an assembly-language description function

Inline expansion for assembly functions is effective when you want to use CPU instructions that C does not support or when you want to improve performance by coding the functions in assembly language rather than in C. In a C source file, you can code functions in assembly language by using the `#pragma inline_asm` directive to declare that the functions are written in assembly language. Such assembly functions are called *inline assembly functions*. In the `#pragma inline_asm` directive, you can also specify a `size=numeric-value` option to specify the size of an assembly function. Specifying this option might improve the efficiency of optimization.

Note that when you specify the size of a function in the `#pragma inline_asm` directive, you must make sure that the size is the same as or larger than the actual object size. If you specify a size smaller than the actual object size, operation of the compiler is not guaranteed.

Format:

```
#pragma inline_asm [(function-name[(size=numeric-value)] [...])]
```

Note the following when you code inline assembly functions:

- Make sure that each label is a local label (begins with a question mark (?) and consists of 16 or fewer characters).
- Do not code an instruction that automatically generates a literal pool. For details, see Example 2.
- Do not code an RTS (return) instruction at the end of a definition.
- Save and restore the contents of guaranteed registers.

Save/restore operations must also be performed even for the registers specified in the `#pragma global_register` directive. Also note that the save/restore operations of the procedure register (PR) must be coded because the contents of the register are overwritten every time a function is called.

```
extern void sub(void);

#pragma inline_asm (func(size=0x14))
static void func(void)
{
    .IMPORT _sub
    STS.L PR,@-R15
    MOV.L ?LOCAL1,R0
    JSR @R0
    NOP
    LDS.L @R15+,PR
    BRA ?LOCAL2
    NOP
    .ALIGN 4
?LOCAL1:
    .DATA.L _sub
?LOCAL2:
}

void g(void)
{
    func(void);
}
```

} Save/restore operations must be coded when a function is called.

A C source file that includes assembly functions must be output in an assembly file format (`code=asmcode`).

Option settings in High-Performance Embedded Workshop (*Renesas IDE* hereafter):

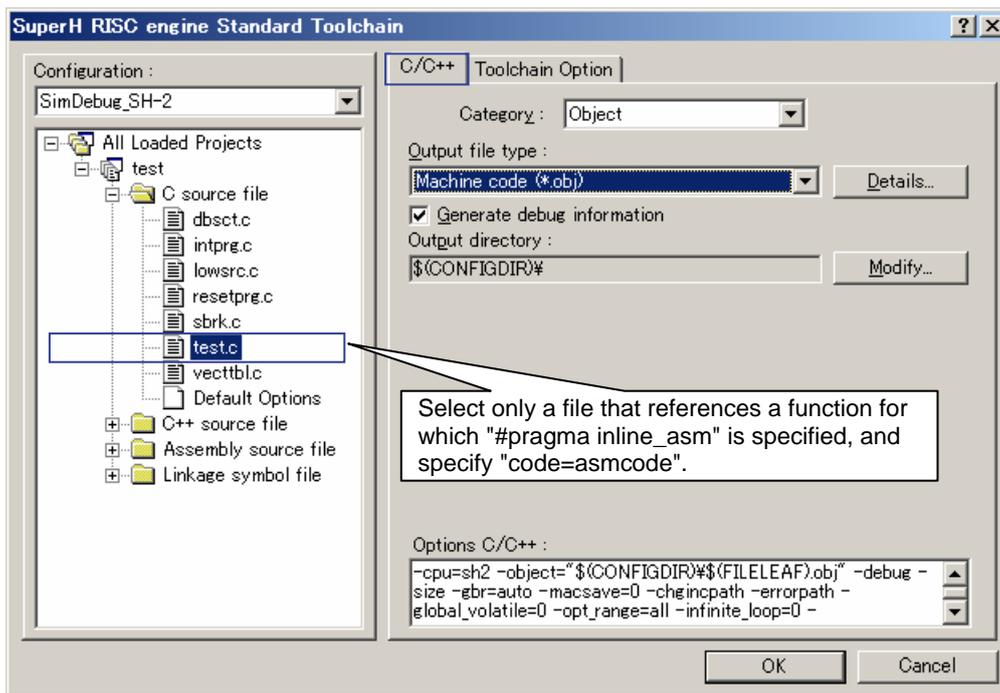


Figure 1-2

If a function specified in the `#pragma inline_asm` directive causes a compilation error when the output of compiler debug information is enabled, the C source program line information is output in Renesas IDE. You cannot use the line information to jump to the assembly program location that caused the error. If you disable output of the compiler debug information, the assembly program line information is displayed in Renesas IDE. Renesas recommends that you disable output of the compiler debug information when you debug a function specified in the `#pragma inline_asm` directive.

Note that the interface between functions must comply with the generation rules for the C or C++ compiler (see Table 1-3 and Table 1-4).

Table 1-3 General rules for assigning arguments in C

| Assignment rules | | |
|---------------------------------|---|---|
| Arguments passed via registers | | Arguments passed via stacks |
| Registers for storing arguments | Supported data types | |
| R4 - R7 | char, unsigned char, bool, short, unsigned short, int, unsigned int, long, unsigned long, float (when the CPU is other than SH-2E, SH2A-FPU, SH-4, or SH-4A), pointer, pointer to a data member, and references | <ul style="list-style-type: none"> Arguments other than those passed via registers Arguments that cannot be stored in registers R4 to R7 because other arguments have already been stored in these registers Arguments that cannot be stored in registers FR4 (DR4) to FR11 (DR10) because other arguments have already been stored in these registers Arguments of types long long and unsigned long long Arguments of types __fixed, long __fixed, __accum, and long __accum |
| FR4 - FR11 ^{#1} | When the CPU is SH-2E: <ul style="list-style-type: none"> float double (with the double=float option specified) When the CPU is SH2A-FPU, SH-4, or SH-4A: <ul style="list-style-type: none"> float (with the fpu=double option specified) double (with the fpu=single option specified) | |
| DR4 - DR10 ^{#2} | When the CPU is SH2A-FPU, SH-4, SH-4A: <ul style="list-style-type: none"> double (without the fpu=single option specified) float (with the fpu=double option specified) | |

Notes: #1: SH-2E, SH2A-FPU, SH-4, and SH-4A registers used for single-precision floating-point numbers

#2: SH2A-FPU, SH-4, and SH-4A registers used for double-precision floating-point numbers

Table 1-4 Return value types and setting location in C programs

| Return value types | Setting location |
|---|--|
| (signed) char, unsigned char, (signed) short, unsigned short, (signed) int, unsigned int, long, unsigned long, pointers, bool, references, pointers to data members | R0: 32 bits The contents of the upper three bytes of (signed) char, or unsigned char and the contents of the upper two bytes of (signed) short or unsigned short are not guaranteed. However, when the <code>rtnext</code> option is specified, sign extension is performed for (signed) char or (signed) short type, and zero extension is performed for unsigned char or unsigned short type. |
| float | FR0: 32 bits (1) For CPU is SH-2E <ul style="list-style-type: none"> Return value is float type. Return value is double type and <code>double=float</code> is specified. (2) For SH2A-FPU, SH-4, or SH-4A <ul style="list-style-type: none"> Return value is float type and <code>fpu=double</code> is not specified. Return value is floating-point type and <code>fpu=single</code> is specified. |
| double and long double | Return value setting area (memory) For SH2A-FPU, SH-4, or SH-4A <ul style="list-style-type: none"> Return value is double type and <code>fpu=single</code> is not specified. Return value is floating-point type and <code>fpu=double</code> is specified. |
| Structure, union, and class types, and pointers to function members | Return value setting area (memory). |
| (signed) long long and unsigned long long | Return value setting area (memory). |
| <code>__fixed</code> , <code>long __fixed</code> , <code>__accum</code> , and <code>long __accum</code> | Return value setting area (memory). |

Example 1: Specifying an inline assembly function

```

Source code:

/* Inline function definition */
/* FILE: inlasm.h */
#pragma inline_asm(rev4b(size=0x04))
static unsigned long rev4b(unsigned long p)
/* Function is declared as static */
{
    ; In a definition, comment lines begin with a semicolon, as in assembly language.
    SWAP.W R4,R0
    SWAP.B R0,R0
    ; Do not specify an RTS instruction at the end of the definition.
}
#pragma inline_asm(ovf)
static unsigned long ovf(void)
{
?LABEL001 ; In an inline assembly function, use local labels.
    ; Local label: String beginning with ? and consisting of 16 or fewer characters
    MOV R4,R0
    :
    CMP/EQ #1,R0
    BT ?LBABEL001
}
    
```

Example 2: Notes on automatic generation of a literal pool

| | |
|--|---|
| <p><u>Incorrect source code:</u></p> <pre> #pragma inline_asm(f) /* Incorrect inline assembly function */ </pre> | <p><u>Correct source code 1:</u></p> <pre> #pragma inline_asm(f(size=0x0c)) /* Correct inline assembly function */ </pre> |
|--|---|

| | |
|---|--|
| <pre>static unsigned long f(void) { MOV.L #H'f0000000,R0 ; This code causes the assembler to ; automatically generate a literal pool. ; As a result, the compiler-generated code ; might not be aligned correctly. }</pre> | <pre>static unsigned long f(void) { MOV.L ?LOCAL1,R0 ; Data is referenced from ; the local label. BRA ?LOCAL2 ; Jumps over data definitions. NOP .ALIGN 4 ?LOCAL1: .DATA.L H'F0000000 ?LOCAL2: }</pre> |
| | <p><u>Correct source code 2:</u></p> <pre>#pragma inline_asm(f(size=0x06)) /* Correct inline assembly function */ static unsigned long f(void) { MOV #-16,R0 ; H'FFFFFFF0 SHLL8 R0 SHLL16 R0 ; No data is referenced from labels. }</pre> |

Example 3: Optimization with the "size" option specified

Evaluation at branches is further optimized by specifying the size.

| | |
|---|---|
| <p><u>Source code ("size" not specified)</u></p> <pre>#include <machine.h> extern int a; #pragma inline_asm (func) static int func(void) { NOP } void g(void) { if (a) { func(); } if (a) { nop(); } }</pre> <p><u>Expanded assembly code:</u></p> <pre>_g: MOV.L L16+2,R6 ; _a MOV.L @R6,R2 ; a TST R2,R2 BF L20 MOV.L L16+6,R3 ; L13 JMP @R3 NOP L20: BRA L15 NOP L16: .RES.W 1 .DATA.L _a .DATA.L L13 L15: NOP .ALIGN 4 MOV.L L18+2,R6 ; _a BRA L17 MOV.L @R6,R2 ; a L18: .RES.W 1 .DATA.L _a L17: TST R2,R2 BT L13</pre> | <p><u>Source code ("size=0x20" specified)</u></p> <pre>#include <machine.h> extern int a; #pragma inline_asm (func(size=0x20)) static int func(void) { NOP } void g(void) { if (a) { func(); } if (a) { nop(); } }</pre> <p><u>Expanded assembly code:</u></p> <pre>_g: MOV.L L15+2,R6 ; _a MOV.L @R6,R2 ; a TST R2,R2 BT L13 NOP .ALIGN 4 MOV.L L15+2,R6 ; _a MOV.L @R6,R2 ; a TST R2,R2 BT L13 NOP L13: RTS NOP L15: .RES.W 1 .DATA.L _a</pre> |
|---|---|

| | |
|---------------------------|--|
| L13: NOP RTS NOP | |
|---------------------------|--|

1.4 Generates or does not generate save and restore code at the start and end of functions

Program execution speed and efficiency of ROM usage can be improved by deleting the register save operation at function entry points and the register restore operation at function exit points. You can use the `#pragma noregsave`, `#pragma noregalloc`, and `#pragma regsave` directives for fine-grained control of the saving and restoring of the guaranteed registers listed in Table 1-5.

Table 1-5 Guaranteed registers that can be controlled by using "`#pragma noregsave`", "`#pragma noregalloc`", and "`#pragma regsave`"

| Register | Explanation |
|---------------|---|
| R8 - R14 | -- |
| FR12 - FR15 | SH-2E, SH2A-FPU, SH-4, and SH-4A registers used for single-precision floating-point numbers |
| DR12 and DR14 | SH2A-FPU, SH-4, and SH-4A registers used for double-precision floating-point numbers |

Specifying `#pragma noregsave` for frequently executed functions can reduce program size and improve execution speed.

- (1) The `#pragma noregsave` directive specifies that guaranteed registers are not saved and restored at the entry and exit points of functions.
- (2) The `#pragma noregalloc` directive is used to create an object that does not save/restore guaranteed registers at function entry/exit points, and does not allocate guaranteed registers across function calls.
- (3) The `#pragma regsave` directive is used to create an object which saves and restores guaranteed-registers at function entry/exit points, and does not allocate guaranteed registers.
- (4) `#pragma regsave` and `#pragma noregalloc` can be specified simultaneously for the same function. Such overlapping specifications causes an object to be created in which all guaranteed-registers are saved and restored at the function entry/exit points, and no guaranteed registers are allocated across function calls.

Table 1-6 Operation of "`#pragma regsave`", "`#pragma noregsave`", and "`#pragma noregalloc`"

| #pragma | Register save/restore operations | Register use |
|---|--|---|
| <code>#pragma noregsave</code> | Guaranteed registers are not saved and restored. | Guaranteed registers are used. |
| <code>#pragma noregalloc</code> | Guaranteed registers are not saved and restored. | Guaranteed registers are not used across multiple function calls. |
| <code>#pragma regsave</code> | Guaranteed registers are saved and restored. | Guaranteed registers are not used across multiple function calls. The frequency of using guaranteed registers within one function is low. |
| <code>#pragma regsave + #pragma noregalloc</code> | Guaranteed registers are saved and restored. | Guaranteed registers are not used across multiple function calls. The frequency of using guaranteed registers within one function is high. |

A function for which `#pragma noregsave` is specified might not operate correctly if it is called from ordinary functions. Make sure that a function for which `#pragma` is specified is called from one of the following types of functions:

- Function for which `#pragma regsave` is specified
- Function for which `#pragma noregalloc` is specified and that is called from a function for which `#pragma regsave` is specified

Before allowing a function for which the `#pragma noregsave`, `#pragma noregalloc`, or `#pragma regsave` directive is specified to be called, make sure that the directive is specified for all instances of the function throughout the project. Renesas recommends that you specify the directive in a common header file.

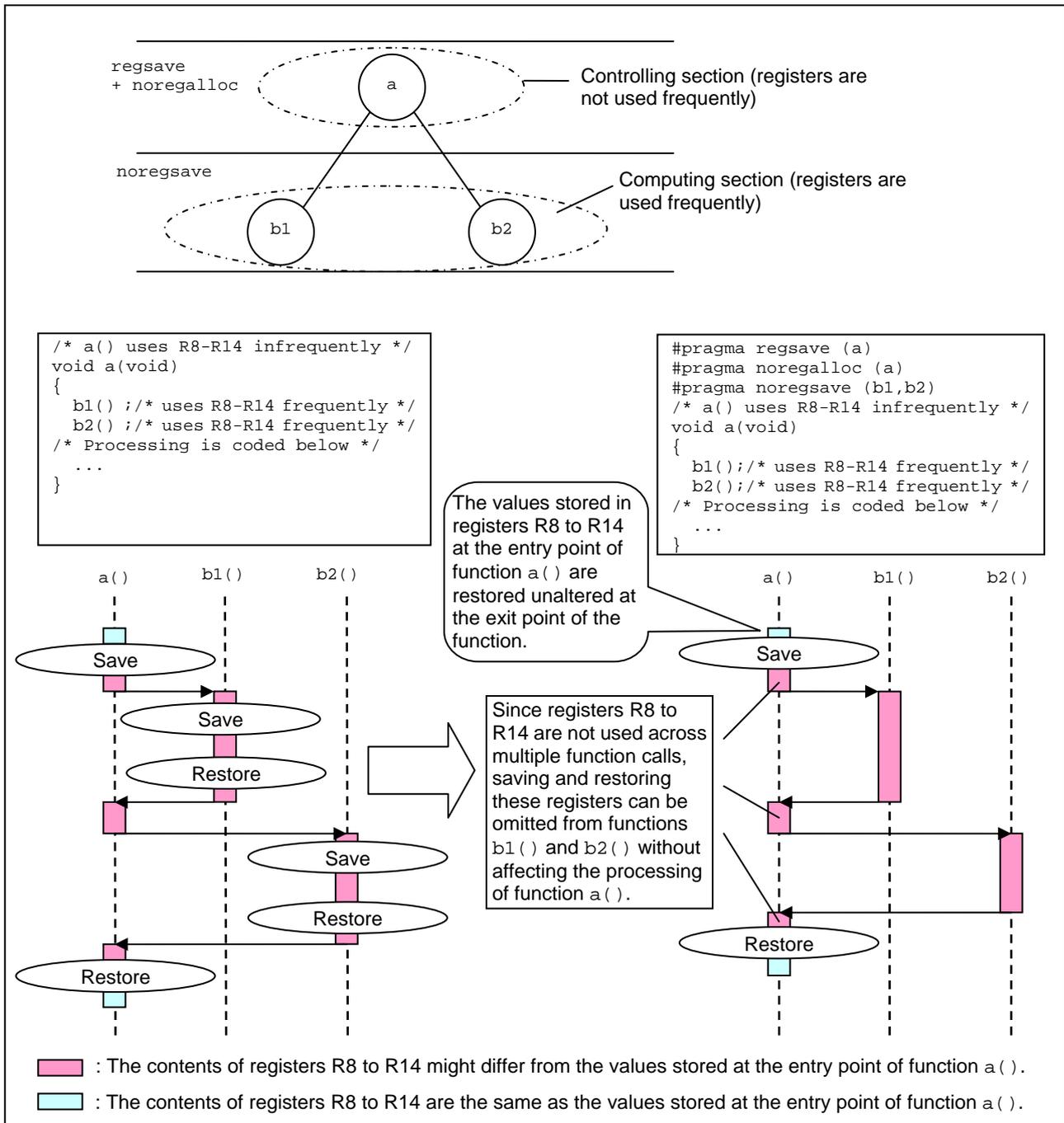


Figure 1-4

Example 3:

When functions `b1()` and `b2()` use guaranteed registers, the contents of these registers are saved at the entry points of the functions and restored at the exit points of the functions. For example, when functions `b1()` and `b2()` are also frequently called from function `c2()`, which is called from function `a()`, the guaranteed registers are also saved and restored frequently, lowering the efficiency of program execution.

If functions `a()` and `c2()` do not use the same guaranteed registers, functions `b()` and `b2()` do not require that these registers be saved and restored. If you specify function `a()` in `#pragma regsave` and `#pragma noregalloc` directives, the contents of the guaranteed registers are saved at the entry point and restored at the exit point of function `a()`, and the guaranteed registers used by function `a()` are not used by other functions. If you specify function `c2()` in the `#pragma noregalloc` directive, the guaranteed registers used by function `c2()` are not used by other functions. If you specify functions `b1()` and `b2()` in the `#pragma regsave` directive, you can suppress saving and restoring of the guaranteed registers used by these functions.

When the directive settings are specified as described above, guaranteed registers are saved and restored for function `a()`, but are not saved and restored for functions `b1()` and `b2()`. Accordingly, you can reduce the frequency of register save and restore operations by changing the register save and restore locations.

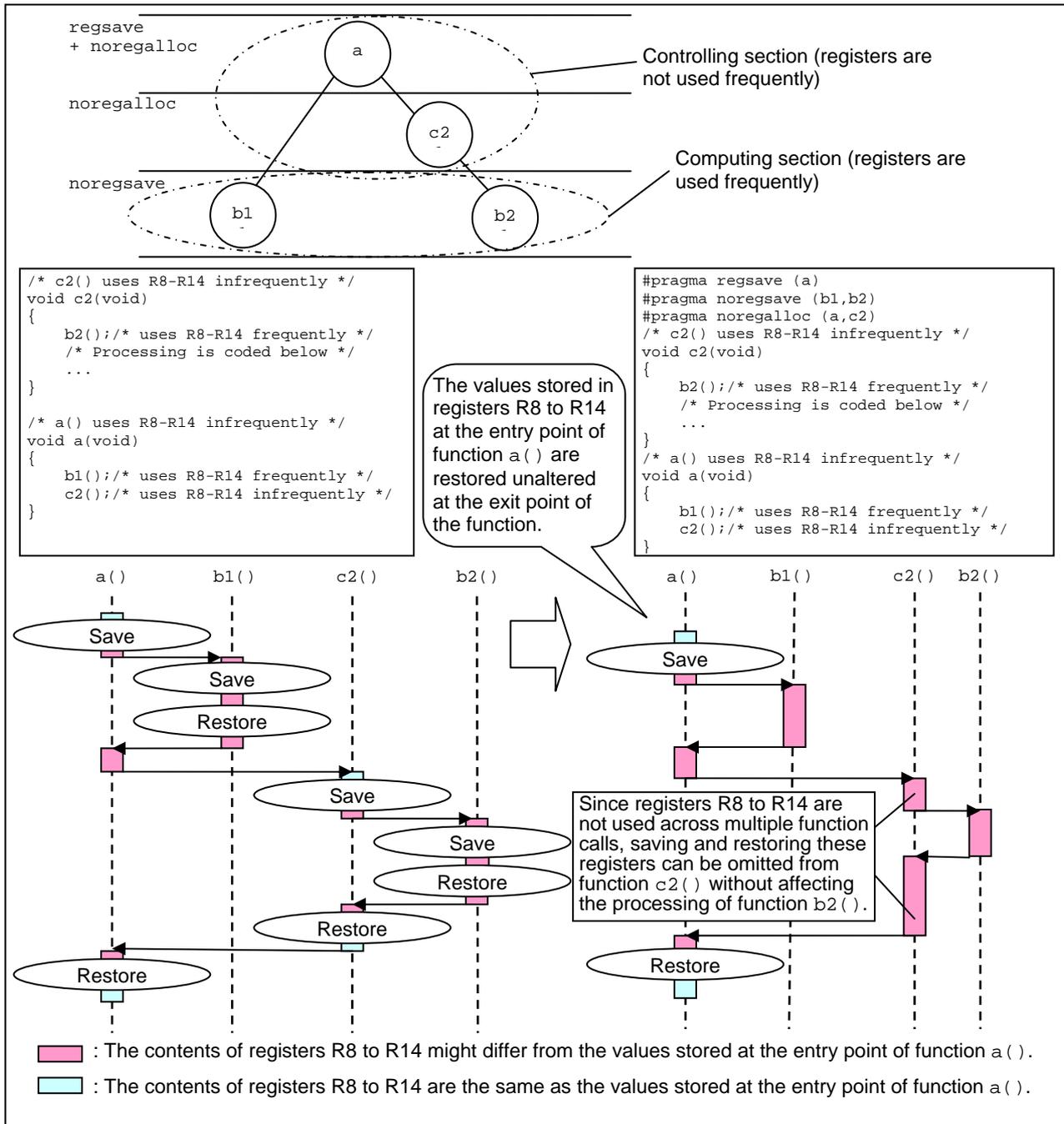


Figure 1-5

1.5 Allocates global variables to registers

You can use the `#pragma global_register` directive to allocate global variables to registers. By allocating global variables to registers, you can reduce the number of load and store instructions.

You must specify the `#pragma global_register` directive in all files. Use the `preinclude` option to specify a header file that contains the `#pragma global_register` declaration. This option specifies the directive in all files. For details about how to specify the option settings in Renesas IDE, see Figure 1-6.

For the standard library as well, you must specify the `#pragma global_register` directive. Use the `preinclude` option to specify a header file that contains the `#pragma global_register` declaration. For details about how to specify the option settings in Renesas IDE, see Figure 1-7.

Format:

`#pragma global_register [(variable-name=register-name[,...][D])]`

- For *variable-name*, you can specify a global variable of the integer, float, or pointer type. If the CPU is not SH2A-FPU, SH-4, or SH-4A, you can specify a global variable of type double when the `double=float` option is specified.
- For *register-name*, you can specify R8 to R14, FR12 to FR15 (when the CPU is SH-2E, SH2A-FPU, SH-4, or SH-4A), DR12, or DR14 (when the CPU is SH2A-FPU, SH-4, or SH-4A).
 - Types of variables that can be allocated to registers FR12 to FR15
 - (i) SH-2E
 - float type
 - double type (when the `double=float` option is specified)
 - (ii) SH2A-FPU, SH-4, and SH-4A
 - float type (when the `fpu=double` option is not specified)
 - double type (when the `fpu=single` option is not specified)
 - Types of variables that can be allocated to registers DR12 to DR14
 - (i) SH2A-FPU, SH-4, and SH-4A
 - float type (when the `fpu=double` option is specified)
 - double type (when the `fpu=single` option is not specified)
- You can neither set initial values for the variables nor use the variables for address reference.
- If the `#pragma global_register` directive settings are the same for all files and the library, correct operation cannot be guaranteed.
- You can specify only static data members. You cannot specify non-static data members.

Option settings in Renesas IDE:

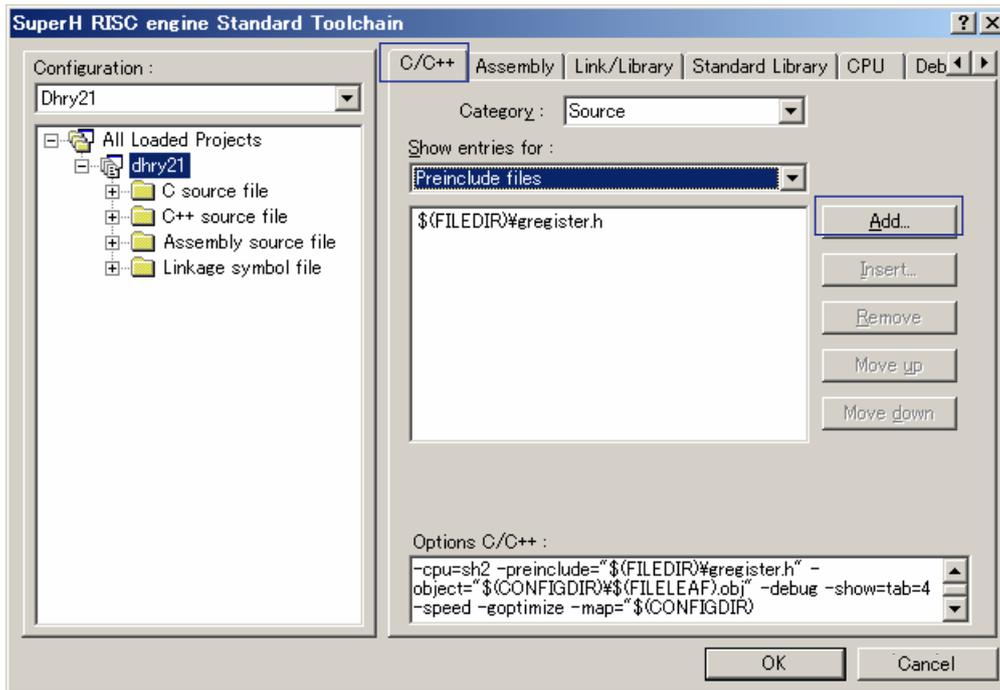


Figure 1-6

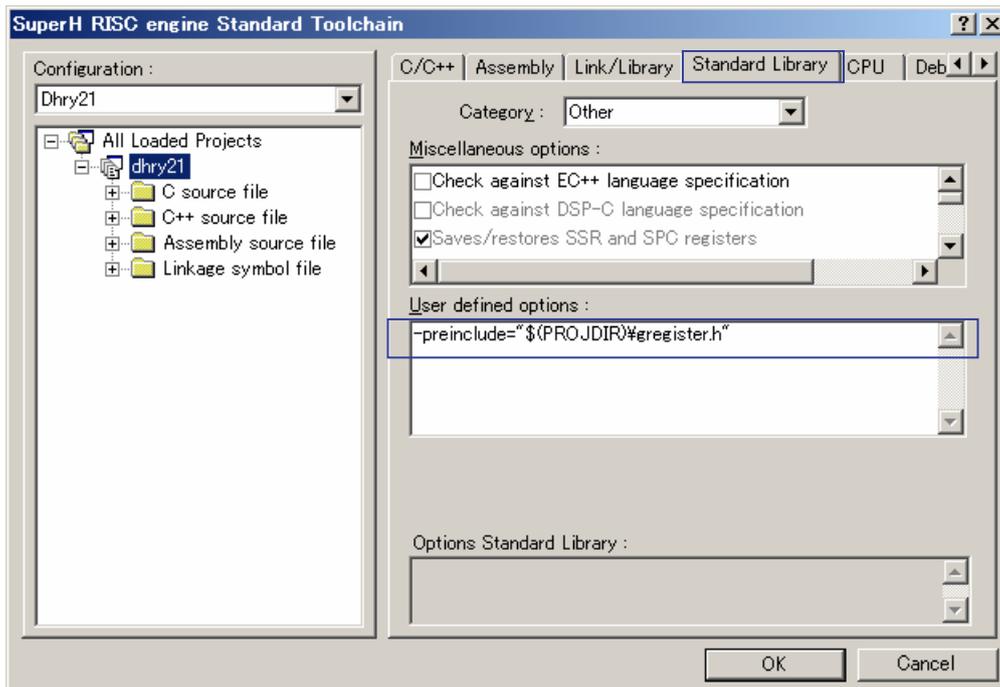


Figure 1-7

Example:

```

Source code:
#pragma global_register(x=R13,y=R14)

int x;
char *y;

void func1(void)
{
    x++;
}

void func2(void)
{
    *y=0;
}

void func(int a)
{
    x = a;
    func1();
    func2();
}
Expanded assembly code:

_func1:
    RTS
    ADD     #1,R13
_func2:
    MOV     #0,R2      ; H'00000000
    RTS
    MOV.B   R2,@R14    ; *(y)
_func:
    STS.L   PR,@-R15
    BSR     _func1
    MOV     R4,R13
    BRA     _func2
    LDS.L   @R15+,PR
    
```

1.6 Specifies GBR base variables

A GBR base variable is a variable for which a GBR base is specified and which can be accessed GBR relative access code. The use of a relative address means that the variable address does not have to be loaded, resulting in a smaller object.

Note, however, that the number and size of variables that can be used as GBR base variables are limited. Specify as GBR base variables only those variables that will be used frequently.

Format:

```
#pragma gbr_base (variable-name [,variable-name...])
#pragma gbr_base1 (variable-name [,variable-name...])
```

The #pragma gbr_base directive allocates the specified variables in the \$G0 section, which occupies relative byte positions 0 to 127 from the address indicated by GBR.

The #pragma gbr_base1 directive allocates the specified variables in the \$G1 section, which occupies relative byte positions 128 to 1020 from the address indicated by GBR. However, in this section, the maximum byte position at which a variable can be allocated depends on the data type. For a variable of type char or unsigned char, the maximum byte position is 255. For a variable of type unsigned short, the maximum byte position is 510. For a variable of type int, unsigned int, long, unsigned long, float, or double, the maximum byte position is 1020.

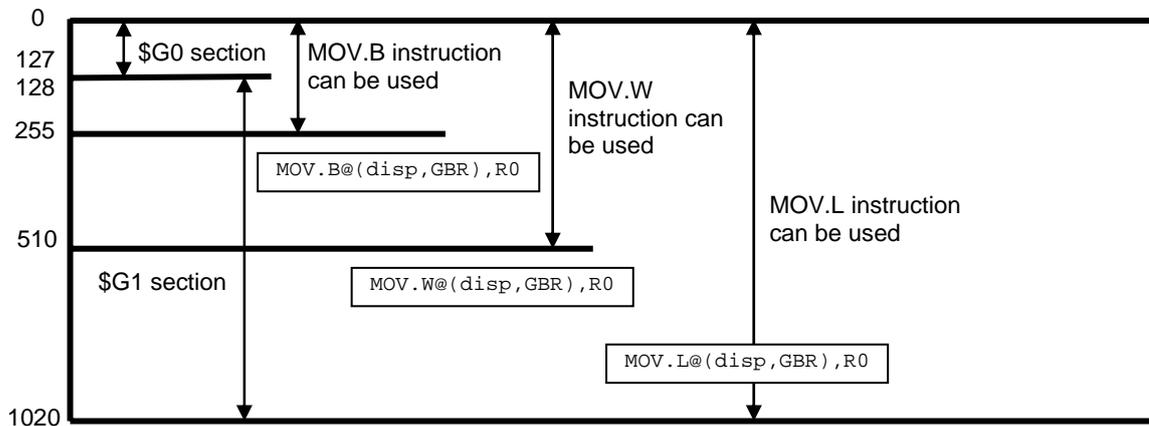


Figure 1-8

Variables that are frequently accessed or used for bitwise operations should be allocated in the \$G0 section if at all possible. An object that accesses data in the \$G0 section is faster and smaller than an object that accesses data in the \$G1 section (see Example 2 below).

The #pragma gbr_base and #pragma gbr_base1 directives allocate the specified variables in the appropriate sections in the order in which the variables are declared. Since alternately declaring variables of different sizes wastes space, as much as possible, try to declare variables of the same size together.

If GBR base variables overflow the appropriate area, the following error occurs during linkage:

```
L2330 (E)Relocation size overflow
```

If this error occurs, delete specification of the relevant variables from the #pragma gbr_base or #pragma gbr_base1 directive.

To use the #pragma gbr_base directive, use a linkage editor to set the \$G0 section. To use the #pragma gbr_base1 directive, use a linkage editor to set the \$G0 and \$G1 sections. When you set the \$G1 section, make sure that the address of the section is the start address of the \$G0 section + 0x80.

Note that the same specification of the #pragma gbr_base and #pragma gbr_base1 directives should be used throughout the project. The preinclude option is useful for ensuring the same specification throughout the project.

The variables specified in the #pragma gbr_base or #pragma gbr_base1 directive are allocated in either the \$G0 or \$G1 section whether or not an initial value is specified. When the compiler generates an object, the compiler treats the \$G0 and \$G1 sections as initialized data. The initialized data (variables) has initial values. Although the initial values

must be prepared in the ROM area, the data must be stored in the RAM area because the data might change during program execution.

Therefore, after an initial value is set in the ROM area, the initial value must be copied from the ROM area to the RAM area. To set an initial value in the ROM area and to access data with an address in the RAM area, you must use a linkage editor to specify the appropriate ROM support option. For the \$G0 and \$G1 sections, you must also add processing that copies the initial data from the ROM area to the RAM area, and use a linkage editor to specify the appropriate ROM support option. For details, see *4.Memory Initialization* in the manual *SuperH RISC engine C/C++ Compiler Package APPLICATION NOTE: [Introduction guide] Sample file Guide for SH-1, SH-2, and SH-2A*.

Make sure that the address of the RAM area for the \$G1 section is the address of the RAM area for the \$G0 section + 0x80.

Before you can use GBR base variables, you must set the start address of the RAM area for copying the \$G0 section in the GBR register. You can use intrinsic function `set_gbr()` to perform this operation.

The following is an example of code that copies the \$G0 section in the ROM area to the \$G1 section in the RAM area.

```

Initialization program:

#include <machine.h>

/* Functions executed before main */
void PowerON_Reset(void)
{
    ...
    set_gbr(__sectop("$RG0")); /* Sets the start address of $RG0 section in the GBR register */
    ...
}
    
```

The following explains the tasks required before you can use the GBR base.

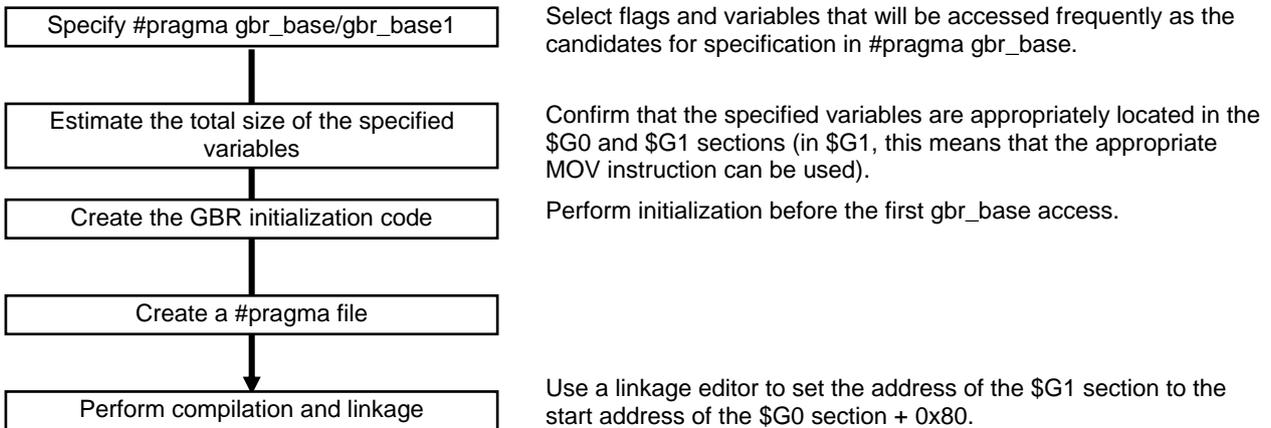


Figure 1-9

If you specify the #pragma gbr_base or #pragma gbr_base1 directive, specify the gbr=user option (Figure 1-10). If you do not specify the option, a warning is output for the directive and specification of the directive is ignored.

Note that if you select **User(gnenrate logic operation)** from the **GBR relative operation** drop-down list, the `gbr=user` and `logic_gbr` options are specified. If these options are specified, GBR relative logical operation instructions might be used for operations that do not use GBR base variables.

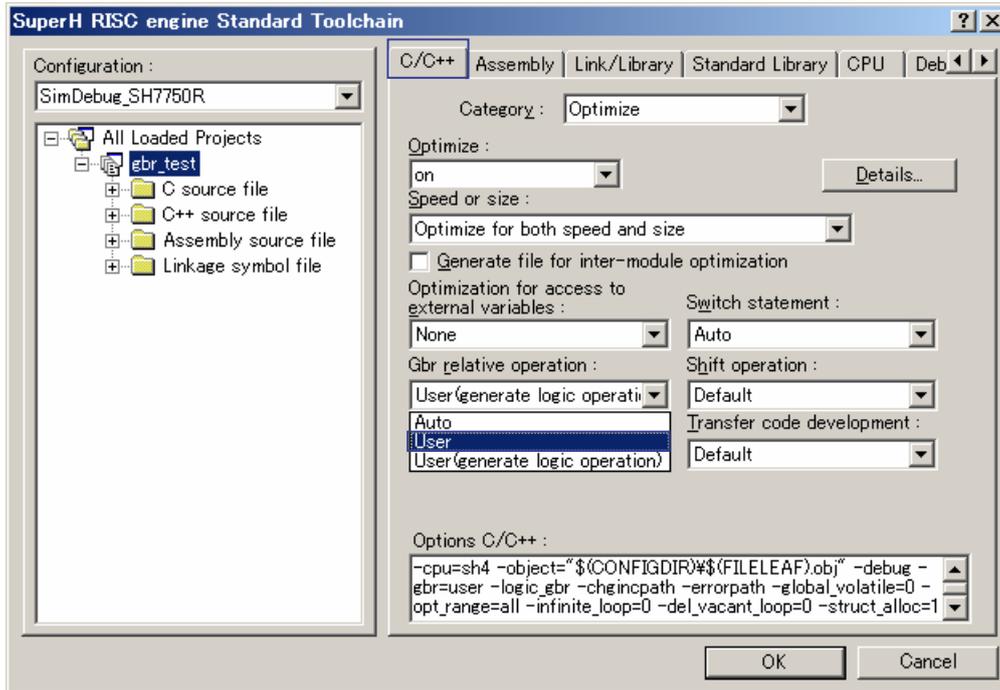


Figure 1-10

Example 1:

The following is an example of code generated when the `gbr=user` compiler option is specified.

| Source code with #pragma gbr_base not specified: | Source code with #pragma gbr_base specified: |
|--|--|
| <pre> struct BitField { unsigned char a:1; unsigned char b:1; unsigned char c:1; unsigned char d:1; unsigned char e:1; unsigned char f:1; unsigned char g:1; unsigned char h:1; } bitf; struct { char c; short s; long l; } x, y; void f (void) { bitf.a = 1; bitf.b = 0; if (bitf.c) { bitf.d = 1; } else { bitf.e = 1; } x.c = y.c; x.s = y.s; x.l = y.l; } </pre> | <pre> struct BitField { unsigned char a:1; unsigned char b:1; unsigned char c:1; unsigned char d:1; unsigned char e:1; unsigned char f:1; unsigned char g:1; unsigned char h:1; } bitf; struct { char c; short s; long l; } x, y; void f (void) { bitf.a = 1; bitf.b = 0; if (bitf.c) { bitf.d = 1; } else { bitf.e = 1; } x.c = y.c; x.s = y.s; x.l = y.l; } </pre> |

| Expanded assembly code: | Expanded assembly code: |
|---|--|
| <pre> _f: MOV.L L14,R5 ; _bitf MOV.B @R5,R0 ; (part of)bitf AND #191,R0 OR #128,R0 TST #32,R0 BT/S L12 MOV.B R0,@R5 ; (part of)bitf BRA L13 OR #16,R0 L12: OR #8,R0 L13: MOV.L L14+4,R7 ; _y MOV.B R0,@R5 ; (part of)bitf MOV.L L14+8,R6 ; _x MOV.B @R7,R1 ; y.c MOV.W @(2,R7),R0 ; y.s MOV.L @(4,R7),R4 ; y.l MOV.B R1,@R6 ; x.c MOV.W R0,@(2,R6) ; x.s RTS MOV.L R4,@(4,R6) ; x.l L14: .DATA.L _bitf .DATA.L _y .DATA.L _x .SECTION B,DATA,ALIGN=4 _bitf: .RES.B 1 ; static: bitf .RES.B 1 .RES.W 1 _x: .RES.L 2 ; static: x _y: .RES.L 2 ; static: y .RES.L 2 </pre> | <pre> _f: MOV #_bitf-(STARTOF \$G0),R0 AND.B #191,@(R0,GBR); (part of)bitf OR.B #128,@(R0,GBR); (part of)bitf MOV.B @(_bitf-(STARTOF \$G0),GBR),R0 ; (part of)bitf TST #32,R0 BT L12 BRA L13 OR #16,R0 L12: OR #8,R0 L13: MOV.B R0,@(_bitf-(STARTOF \$G0),GBR) ; (part of)bitf MOV.B @(_y-(STARTOF \$G0),GBR),R0; y.c MOV.B R0,@(_x-(STARTOF \$G0),GBR); x.c MOV.W @(_y-(STARTOF \$G0)+2,GBR),R0; y.s MOV.W R0,@(_x-(STARTOF \$G0)+2,GBR); x.s MOV.L @(_y-(STARTOF \$G0)+4,GBR),R0; y.l RTS MOV.L R0,@(_x-(STARTOF \$G0)+4,GBR); x.l .SECTION \$G0,DATA,ALIGN=4 _bitf: ; static: bitf .DATAB.B 1,0 .SECTION \$G1,DATA,ALIGN=4 _x: ; static: x .DATAB.L 2,0 _y: ; static: y .DATAB.L 2,0 </pre> |

Example 2 (comparison of gbr_base and gbr_base1):

The following is an example of code generated when the gbr=user compiler option is specified. If #pragma gbr_base is specified to allocate variables in the \$G0 section, literal access does not occur.

| Source code with #pragma gbr_base1 specified: #pragma gbr_base1 (bitf) | Source code with #pragma gbr_base specified: #pragma gbr_base (bitf) |
|---|---|
| <pre> struct BitField { unsigned char a:1; unsigned char b:1; unsigned char c:1; unsigned char d:1; unsigned char e:1; unsigned char f:1; unsigned char g:1; unsigned char h:1; } bitf; void f (void) { bitf.a = 1; bitf.b = 0; } </pre> | <pre> struct BitField { unsigned char a:1; unsigned char b:1; unsigned char c:1; unsigned char d:1; unsigned char e:1; unsigned char f:1; unsigned char g:1; unsigned char h:1; } bitf; void f (void) { bitf.a = 1; bitf.b = 0; } </pre> |
| <p>Expanded assembly code:</p> <pre> _f: MOV.W L11,R0 ; _bitf-(STARTOF \$G0) AND.B #191,@(R0,GBR);(part of)bitf RTS OR.B #128,@(R0,GBR);(part of)bitf L11: .DATA.W _bitf-(STARTOF \$G0) .SECTION \$G1,DATA,ALIGN=4 _bitf: ; static: bitf .DATAB.B 1,0 </pre> | <p>Expanded assembly code:</p> <pre> _f: MOV #_bitf-(STARTOF \$G0),R0 AND.B #191,@(R0,GBR); (part of)bitf RTS OR.B #128,@(R0,GBR); (part of)bitf .SECTION \$G0,DATA,ALIGN=4 _bitf: ; static: bitf .DATAB.B 1,0 </pre> |

2. Other Useful Extended #pragma Directives

This chapter explains extended #pragma directives that provide benefits other than an improvement in performance. Table 2-1 lists the extended #pragma directives explained in this chapter.

Table 2-1 Other useful #pragma directives

| No. | #pragma | Explanation | See section |
|-----|--------------------------------|--|-------------|
| 1 | #pragma section | Switches sections | 2.1 |
| 2 | #pragma bit_order | Switches the order of bit fields | 2.2 |
| 3 | #pragma pack #pragma unpack | Specifies the boundary alignment value for structures, unions, and classes | 2.3 |

2.1 Switches sections

You can use the #pragma section directive to replace section names output by the compiler.

For example, you might want to allocate modules in separate sections, such as internal and external RAM. In this case, assign names to these sections, and use a linkage editor to specify the addresses in the sections at which you want to allocate the modules.

If you specify the #pragma section directive without specifying a section name, the default section name is used.

Format:

#pragma section [{*name*|*numeric-value*}]

Table 2-2 lists the default section names and the format of the new names created by the #pragma section directive.

Table 2-2 Default section names and format of replacement names

| | Section | Specification | Default name | New name |
|---|----------------------------|--------------------|--------------|----------|
| 1 | Program section | #pragma section XX | P | PXX |
| 2 | Const section | | C | CXX |
| 3 | Data section | | D | DXX |
| 4 | Uninitialized data section | | B | BXX |

Instead of the #pragma section directive, you can also use the section option to change the default section names.

Format of the section option:

```
SSection = <sub>[,...]
  <sub>: { Program = section-name |
          Const  = section-name |
          Data   = section-name |
          Bss    = section-name }
```

Option settings in Renesas IDE:

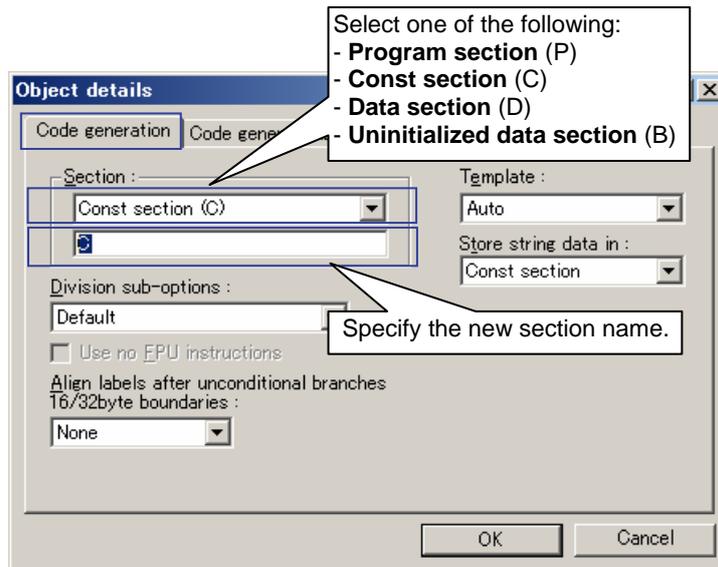
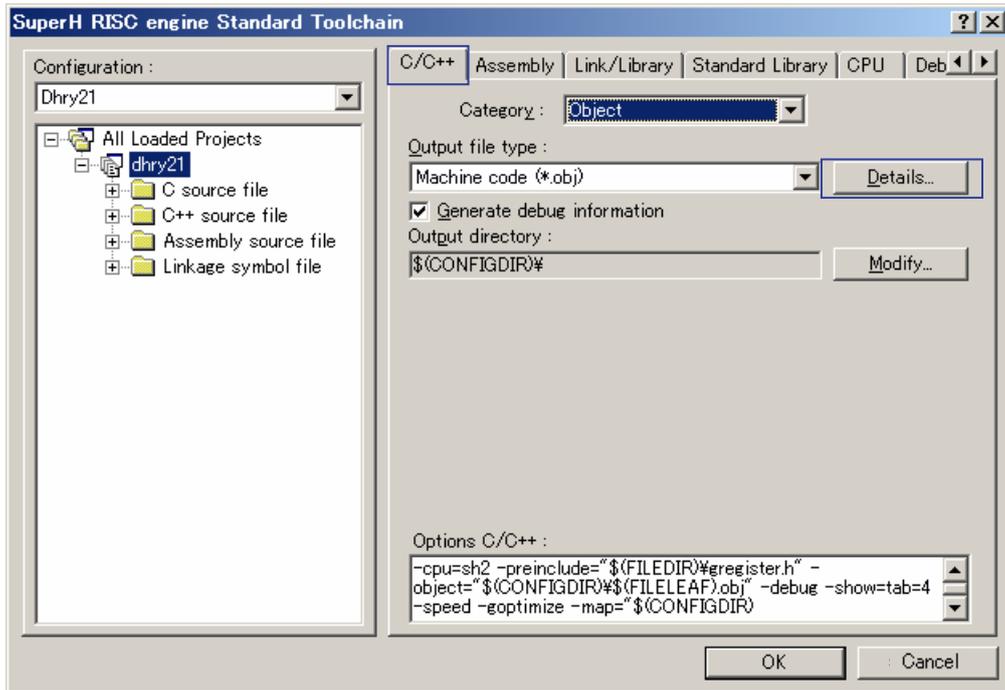


Figure 2-1

Example 1:

```

Source code:

#pragma section abc

int a;          /* a is allocated in section Babc */
const int c=1; /* c is allocated in section Cabc */
void f(void)   /* f is allocated in section Pabc */
{
    a=c;
}

#pragma section

int b;          /* b is allocated in section B */
void g(void)   /* g is allocated in section P */
{
    b=c;
}

```

Example 2:

When section=program=PX, const=CX, bss=BX is specified:

```

Source code:

#pragma section abc

int a;          /* a is allocated in section BXabc */
const int c=1; /* c is allocated in section CXabc */
void f(void)   /* f is allocated in section PXabc */
{
    a=c;
}

#pragma section

int b;          /* b is allocated in section BX */
void g(void)   /* g is allocated in section PX */
{
    b=c;
}

```

2.2 Switches the order of bit fields

You can use the `#pragma bit_order` directive to change the order of bit fields. Since the bit field allocation rule might differ depending on the microcomputer, you can use this functionality to improve portability of programs between different microcomputers.

Instead of using the `#pragma bit_order` directive, you can use an option to change the order of bit fields. If you specify both the `#pragma bit_order` directive and its equivalent option, the directive takes precedence.

Format:

#pragma bit_order [{left|right}]

When `left` is specified, bit field members are assigned from the upper-bit side. When `right` is specified, members are assigned from the lower-bit side. The default is `left`. However, if neither `left` nor `right` is specified in the directive when the option is specified, the option takes effect in the subsequent lines.

Example 1:

This example illustrates how the `#pragma bit_order left` and `#pragma bit_order right` directives allocate members.

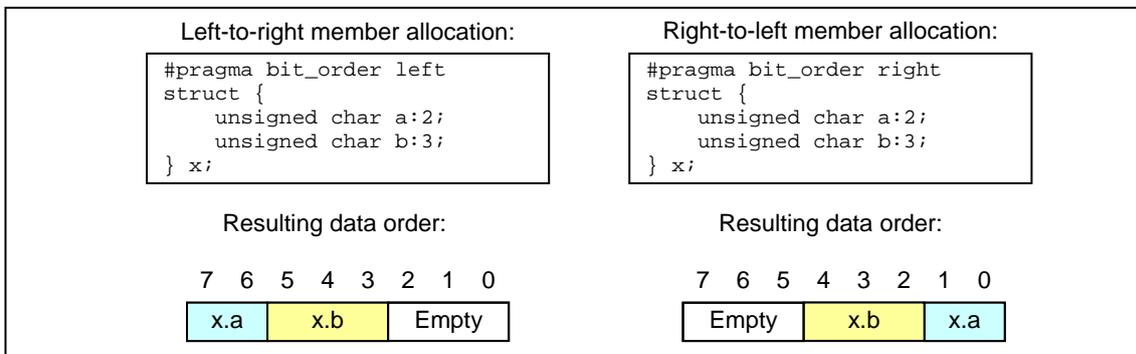


Figure 2-2

Example 2:

If type specifiers of the same size are specified in succession, members are allocated in the same area to the extent possible.

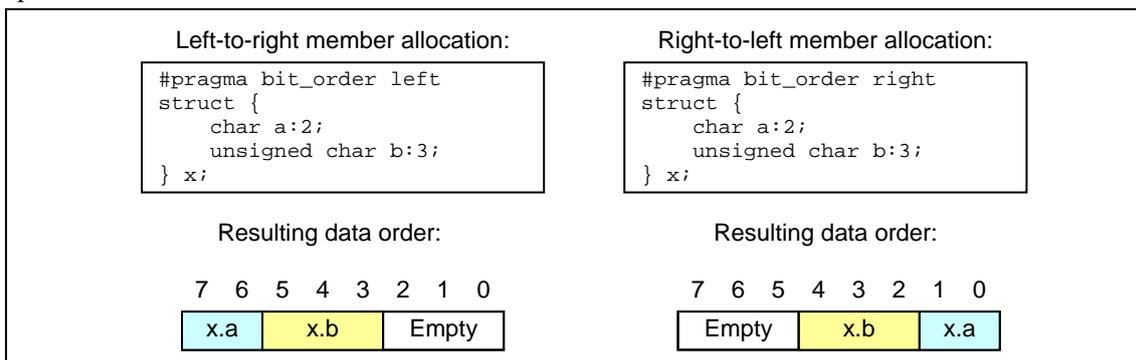


Figure 2-3

Example 3:

If type specifiers of different sizes are specified in succession, members are allocated in different areas.

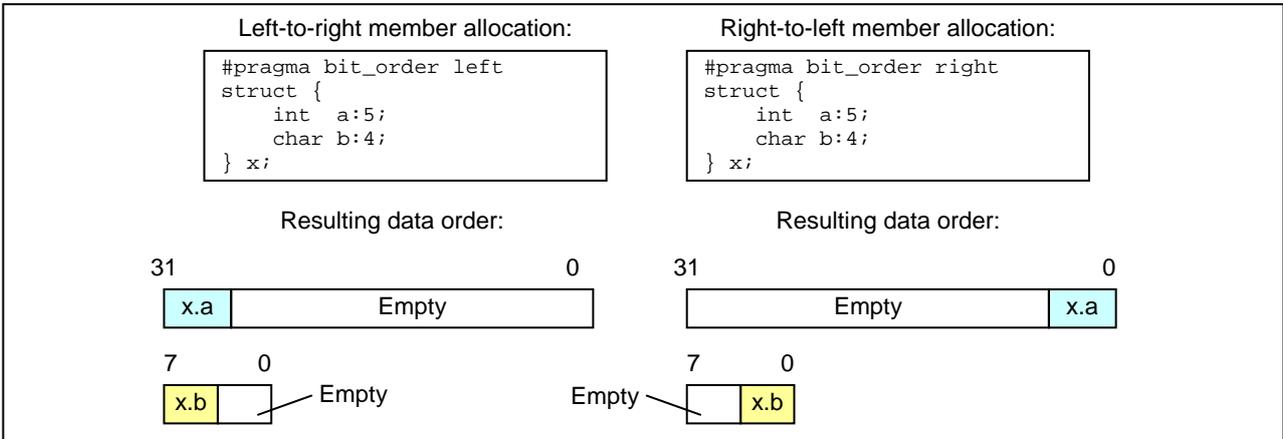


Figure 2-4

Example 4:

Even when type specifiers of the same size are specified in succession, if the remaining area becomes smaller than the next bit field member, the remaining area is not used and the member is allocated in the next area.

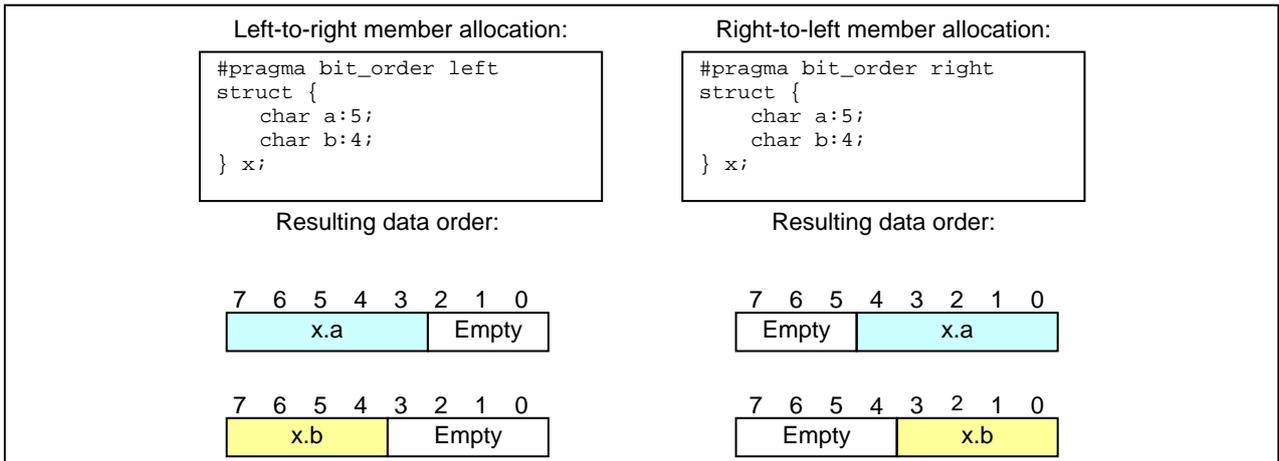


Figure 2-5

2.3 Specifies the boundary alignment value for structures, unions, and classes

For SH microcomputers, when one instruction is used to access a 4-byte data item, the data item must be allocated at an address that is a multiple of four. Similarly, when one instruction is used to access a 2-byte data item, the data item must be allocated at an address that is a multiple of two. Data items allocated in this manner are aligned on the applicable byte boundary.

For example, when data items are allocated at addresses that are a multiple of four, the data items are aligned on a 4-byte boundary. For details about the byte boundary for each data type, see *10.1.2 Internal Data Representation* in the manual *Compiler User Manual*.

If 1-byte, 2-byte, and 4-byte members all exist in a structure, union, or class, each member uses its respective byte boundary, in which case padding areas might arise between members.

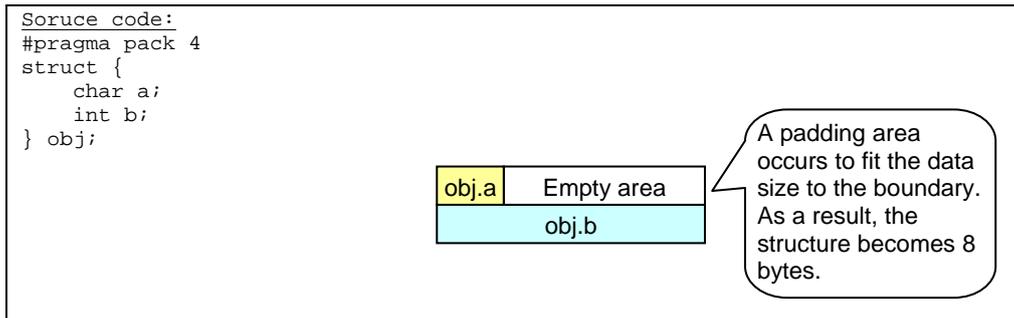


Figure 2-8

In some types of programs, such as communication programs, you might not want structures to have padding areas. In these cases, you can specify the `#pragma pack 1` directive to align structure members on a 1-byte boundary. No padding areas are created in a structure when members are aligned on a 1-byte boundary. Note, however, that because all members in the structure are accessed on a byte basis (byte access), program size might increase. Also note that a member in the structure cannot be accessed by using a pointer. If you attempt to do so, a warning is output.

Instead of using the `#pragma pack` directive, you can also use the `pack` option, which allows you to specify the byte boundary for the structures in each file. If you specify both the `#pragma pack` directive and the `pack` option, the directive takes precedence.

Format:

#pragma pack {1|4}
#pragma unpack

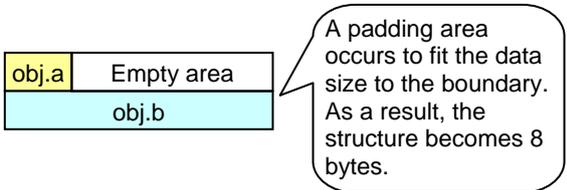
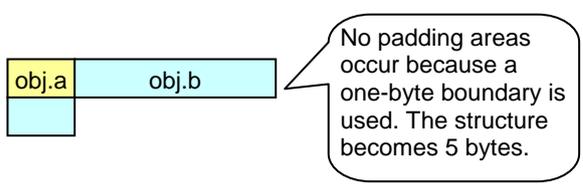
The following table explains how these directives specify the byte boundary.

Table 2-3 Byte boundary for the members of a structure, union, or class

| Extention and Member Type | #pragma pack 1 | #pragma pack 4 | #pragma unpack (or not specified) |
|--|----------------|----------------|-----------------------------------|
| [unsigned]char | 1 | 1 | 1 |
| [unsigned]short or __fixed | 1 | 2 | Same as the pack option |
| [unsigned]int, [unsigned]long, [unsigned]long long, long __fixed, __accum, long, __accum, floating-point type, or pointer type | 1 | 4 | Same as the pack option |
| Structure, union, or class whose byte boundary is 1 | 1 | 1 | 1 |
| Structure, union, or class whose byte boundary is 2 | 1 | 2 | Same as the pack option |
| Structure, union, or class whose byte boundary is 4 | 1 | 4 | Same as the pack option |

Example:

This example shows how structure members are allocated.

| | |
|---|---|
| <pre>Source code with "#pragma pack 4" specified: #pragma pack 4 struct { char a; int b; } obj; int func(void) { return obj.b; } Expanded assembly code: _func: MOV.L L11+2,R6 ; _obj RTS L11: .RES.W 1 .DATA.L _obj .SECTION B,DATA,ALIGN=4 _obj: .RES.L 2</pre> | <pre>Source code with "#pragma pack 1" specified: #pragma pack 1 struct { char a; int b; } obj; int func(void) { return obj.b; } Expanded assembly code: _func: MOV.L L11+2,R3 ; H'00000001+_obj MOV.B @R3+,R2 ; (part of)obj.b MOV.B @R3+,R7 ; (part of)obj.b SHLL8 R2 MOV.B @R3+,R5 ; (part of)obj.b EXTU.B R7,R7 OR R2,R7 SHLL8 R7 EXTU.B R5,R4 MOV.B @R3,R3 ; (part of)obj.b OR R7,R4 SHLL8 R4 EXTU.B R3,R0 RTS OR R4,R0 L11: .RES.W 1 .DATA.L H'00000001+_obj .SECTION B,DATA,ALIGN=4 _obj: .RES.B 5</pre> |
|  |  |

Note:

Care is required for the structure for I/O registers in the `iodef.h` file created in Renesas IDE. If you use the `#pragma pack` directive or its equivalent option to specify a 1-byte boundary, the structure members will not indicate correct addresses. Specify `#pragma pack 4` at the beginning of the `iodef.h` file and `#pragma unpack` at the end of the file.

```
/* iodef.h */
#pragma pack 4

...

#pragma unpack
```

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