RL78/G15
Timer Array Unit (PWM output)

Introduction

This application note describes how to use the PWM output function of the timer array unit (TAU). This unit changes the duty cycle of the PWM output pulse cycle and inverts the LED indication at 500 ms intervals.

Target Device
RL78/G15

When applying the sample program covered in this application note to another microcomputer, modify the program according to the specifications for the target microcomputer and conduct an extensive evaluation of the modified program.
Contents

1. Specifications .......................................................................................................................... 3
   1.1 Overview of Specifications .................................................................................................. 3
   1.2 Outline of Operation .......................................................................................................... 5

2. Operation Confirmation Conditions ..........................................................................................6

3. Hardware Descriptions ...........................................................................................................7
   3.1 Example of Hardware Configuration ....................................................................................7
   3.2 List of Pins to be Used ....................................................................................................... 7

4. Software Explanation ............................................................................................................. 8
   4.1 Setting of Option Byte ....................................................................................................... 8
   4.2 List of Constants ............................................................................................................... 8
   4.3 List of Functions ............................................................................................................... 8
   4.4 Specification of Functions ................................................................................................ 8
   4.5 Flowcharts ....................................................................................................................... 9
      4.5.1 Main Processing ......................................................................................................... 9
      4.5.2 TAU0 Channel 0 Timer Interrupt Processing .............................................................. 10

5. Sample Code ......................................................................................................................... 11

6. Reference Documents ........................................................................................................... 11

Revision History ........................................................................................................................ 12
1. Specifications

1.1 Overview of Specifications

This application note describes the PWM output function which is realized using timer array unit 0 (TAU0) channel 0 as the master and channel 3 as the slave in simultaneous channel operation mode. The brightness of the LEDs is controlled by connecting the PWM output to LED1 (for PWM output). Timing signals with fixed cycle time (500 ms) are created by counting the number of timer interrupts (INTTM00) generated by channel 0. Using these timing signals, the duty cycle of the PWM output pulse cycle is changed and the output of LED2 (for duty cycle updating) is inverted.

Table 1-1 lists the peripheral function to be used and its use. Figure 1-1 shows an overview of PWM output operation. Table 1-2 lists the relation between PWM output duty cycles and LED brightnesses. Figure 1-2 shows a simplified timing chart for PWM output operation.

Table 1-1 Peripheral Function and Use

<table>
<thead>
<tr>
<th>Peripheral Function</th>
<th>Use</th>
</tr>
</thead>
<tbody>
<tr>
<td>Timer array unit 0 (TAU0) channel 0, channel 3</td>
<td>This unit is used to realize the PWM function by operating channel 0 and channel 3 together and deliver a PWM output from the TO03 pin.</td>
</tr>
</tbody>
</table>

Figure 1-1 Overview of PWM Output Operation

![Figure 1-1 Overview of PWM Output Operation](image)

Table 1-2 Relation between PWM Output Duty Cycles and LED Brightnesses

<table>
<thead>
<tr>
<th>Duty cycle</th>
<th>LED1 brightness</th>
</tr>
</thead>
<tbody>
<tr>
<td>10%</td>
<td>90%</td>
</tr>
<tr>
<td>30%</td>
<td>70%</td>
</tr>
<tr>
<td>50%</td>
<td>50%</td>
</tr>
<tr>
<td>70%</td>
<td>30%</td>
</tr>
<tr>
<td>90%</td>
<td>10%</td>
</tr>
</tbody>
</table>
Figure 1-2 Simplified Timing Chart for PWM Output Operation

Master channel
- TS00
- TE00
- TCR00
- TDR00
- TO00
- INTTM00

Slave channel
- TS03
- TE03
- TCR03
- TDR03
- TO03

Software
- Counts INTTM00 interrupts

Duty cycle: 10%
Duty cycle: 30%
Duty factor updated

Counts: 31999
Counts: 28800

1.2 Outline of Operation

The sample program covered in this application note implements PWM by operating channel 0 and channel 3 together and delivers a PWM output from P20/(TO03).

Also, this program counts 250 timer interrupts (INTTM00) with 2 ms cycle time which are generated by channel 0. Then, it changes the duty cycle of the PWM output pulse cycle and inverts the LED indication at 500 ms intervals.

(1) Initialize the TAU.
- Set TAU0 channel 0 (master channel) to interval timer mode.
- Set TAU0 channel 3 (slave channel) to one-count mode.
- Set PWM output pulse cycle to 2 ms.
- Set the output level of TO03 pin to active-low.
- Set the low-level output width of TO03 pin to 90% of the PWM output pulse cycle.
- Set the TO03 pin to a PWM output.
- Set the initial output value of TO03 pin to 1.
- Use timer interrupts (INTTM00) from timer channel 0.

(2) Initialize the I/O port.
- P21 pin: Set as an output port.

(3) Operation starts when both trigger bits to enable operation for TAU0’s channel 0 and channel 3 are set to 1 simultaneously. The sample program executes a HALT instruction to wait for a timer interrupt (INTTM00) from channel 0.

(4) After the start of timer operation, channel 0 generates a timer interrupt (INTTM00) at 2 ms intervals.

(5) When the HALT mode is canceled by a timer interrupt (INTTM00) from channel 0, the sample program starts counting the number of INTTM00 interrupts generated. After channel 0 has generated 250 timer interrupts (i.e., after 500 ms), the sample program changes the duty cycle by updating timer data register (TDR03) of channel 3. This duty cycle is increased from 10% to 90% (10% → 30% → 50% → 70% → 90%). It is incremented by 20% each time the number of channel 0 timer interrupts (INTTM00) generated reaches 250. (Thus, it is incremented at 500 ms intervals). It is reset to 10% after it becomes 90%.

(6) After processing timer interrupts (INTTM00) from channel 0, the sample program executes another HALT instruction and waits for the next timer interrupt (INTTM00) from channel 0.
2. Operation Confirmation Conditions

The operation of the sample code provided with this application note has been tested under the following conditions.

Table 2-1 Operation Confirmation Conditions

<table>
<thead>
<tr>
<th>Item</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>MCU used</td>
<td>RL78/G15 (R5F12068)</td>
</tr>
<tr>
<td>Board used</td>
<td>RL78/G15-20p Fast Prototyping Board (RTK5RLG150CLG00000BJ)</td>
</tr>
<tr>
<td>Operating frequency</td>
<td>High-speed on-chip oscillator clock ($f_{IH}$): 16 MHz</td>
</tr>
<tr>
<td>Operating voltage</td>
<td>5.0 V (can be operated at 2.4 V to 5.5 V)</td>
</tr>
<tr>
<td></td>
<td>SPOR operations ($V_{SPOR}$)</td>
</tr>
<tr>
<td></td>
<td>At rising edge TYP. 2.57V (2.44 V to 2.68 V)</td>
</tr>
<tr>
<td></td>
<td>At falling edge TYP. 2.52V (2.40 V to 2.62 V)</td>
</tr>
<tr>
<td>Integrated development</td>
<td>CS+ for CC 8.09.00 from Renesas Electronics Corp.</td>
</tr>
<tr>
<td>environment (CS+)</td>
<td></td>
</tr>
<tr>
<td>C compiler (CS+)</td>
<td>CC-RL V1.12.00 from Renesas Electronics Corp.</td>
</tr>
<tr>
<td>Integrated development</td>
<td>e2studio V2023-01 (23.1.0) from Renesas Electronics Corp.</td>
</tr>
<tr>
<td>environment (e2studio)</td>
<td></td>
</tr>
<tr>
<td>C compiler (e2studio)</td>
<td>CC-RL V1.12.00 from Renesas Electronics Corp.</td>
</tr>
<tr>
<td>Integrated development</td>
<td>IAR Embedded Workbench for Renesas RL78 V5.10.1 from IAR Systems Corp.</td>
</tr>
<tr>
<td>environment (IAR)</td>
<td></td>
</tr>
<tr>
<td>C compiler (IAR)</td>
<td>IAR C/C++ Compiler for Renesas RL78 V5.10.1.2667 from IAR Systems Corp.</td>
</tr>
<tr>
<td>Smart configurator (SC)</td>
<td>V1.50 from Renesas Electronics Corp.</td>
</tr>
<tr>
<td>Board support package</td>
<td>V1.40 from Renesas Electronics Corp.</td>
</tr>
</tbody>
</table>
3. Hardware Descriptions

3.1 Example of Hardware Configuration

Figure 3-1 shows an example of the hardware configuration used in the application note.

![Figure 3-1 Hardware Configuration](image)

Note. This simplified circuit diagram was created to show an overview of connections only. When actually designing your circuit, make sure the design includes appropriate pin handling and meets electrical characteristic requirements (connect each input-only port to VDD or VSS through a resistor).

3.2 List of Pins to be Used

Table 3-1 lists the pins to be used and their functions.

<table>
<thead>
<tr>
<th>Pin name</th>
<th>I/O</th>
<th>Function</th>
</tr>
</thead>
<tbody>
<tr>
<td>P20 / (TO03)</td>
<td>Output</td>
<td>PWM output port (controls LED1)</td>
</tr>
<tr>
<td>P21</td>
<td>Output</td>
<td>Output port for LED indications (controls LED2)</td>
</tr>
</tbody>
</table>

Caution1. The P20 and P21 pins are only available on 20-pin products. When using 8-, 10-, or 16-pin products, change the PWM output port and the output port for LED indication to other pins.

Caution2. In this application note, only the used pins are processed. When actually designing your circuit, make sure the design includes sufficient pin processing and meets electrical characteristic requirements.
4. Software Explanation

4.1 Setting of Option Byte

Table 4-1 shows the option byte settings. Set the values that are most suited to your system as necessary.

Table 4-1 Option Byte Settings

<table>
<thead>
<tr>
<th>Address</th>
<th>Setting Value</th>
<th>Contents</th>
</tr>
</thead>
<tbody>
<tr>
<td>000C0H</td>
<td>11101111B</td>
<td>Disables the watchdog timer. (Counting stopped after reset)</td>
</tr>
<tr>
<td>000C1H</td>
<td>11111110B</td>
<td>SPOR detection voltage: reset mode</td>
</tr>
<tr>
<td></td>
<td></td>
<td>At rising edge TYP. 2.57 V (2.57 V to 2.68 V)</td>
</tr>
<tr>
<td></td>
<td></td>
<td>At falling edge TYP. 2.52 V (2.40 V to 2.62 V)</td>
</tr>
<tr>
<td>000C2H</td>
<td>11101000B</td>
<td>High-speed on-chip oscillator clock (fIH): 16 MHz</td>
</tr>
<tr>
<td>000C3H</td>
<td>10000101B</td>
<td>Enables on-chip debugging</td>
</tr>
</tbody>
</table>

4.2 List of Constants

Table 4-2 shows the constants that are used in this sample program.

Table 4-2 Constants for the Sample Program

<table>
<thead>
<tr>
<th>Constant</th>
<th>Setting</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>_7080_TAU0_TDR03_VALUE</td>
<td>7080H</td>
<td>Initial setting value of TDR03</td>
</tr>
</tbody>
</table>

4.3 List of Functions

Table 4-3 shows a list of functions.

Table 4-3 Functions

<table>
<thead>
<tr>
<th>Function name</th>
<th>Outline</th>
</tr>
</thead>
<tbody>
<tr>
<td>r_Config_TAU0_0_interrupt()</td>
<td>TAU0 channel 0 timer interrupt processing</td>
</tr>
</tbody>
</table>

4.4 Specification of Functions

The function specifications of the sample code are shown below.

r_Config_TAU0_0_interrupt()

Outline   TAU0 channel 0 timer interrupt processing
Header  r_cg_macodriver.h, r_cg_userdefine.h, Config_TAU0_0.h
Declaration static void __near r_Config_TAU0_0_interrupt(void)
Description This function counts the number of INTTM00 interrupts generated. Each time the count reaches 250, it updates the duty cycle of the PWM output pulse cycle. (Thus, it updates the duty cycle at 500 ms intervals.)
Argument  None
Return Value None
4.5 Flowcharts
4.5.1 Main Processing

Figure 4-1 shows the flowchart of the main processing.

Figure 4-1 Main Processing

```
main

Start operation of TAU0 channel 0 and channel 3
R_Config_TAU0_0_Start()

Enable interrupts

IE ← 1

: while(1) loop

HALT

TAU0 channel 0 timer interrupt (INTTM00)
```
4.5.2 TAU0 Channel 0 Timer Interrupt Processing

Figure 4-2 shows the flowchart of TAU0 channel 0 timer interrupt processing.

Figure 4-2 TAU0 Channel 0 Timer Interrupt Processing

```
r_Config_TAU0_0_interrupt

Counter + 1

NO

500 ms have elapsed ?

YES

Counter = 0

Invert P21 output

Read current duty cycle

Current duty cycle ?

Less than 90%

Initialize duty cycle to 10%

Update duty cycle

return

90% or more

Increase duty cycle by 20%

temp_duty ← TDR03 register

tm00_count = 0

tm00_count + 1

TDR03 register ← temp_duty
```
5. Sample Code
   Sample code can be downloaded from the Renesas Electronics website.

6. Reference Documents
   RL78/G15 User’s Manual: Hardware (R01UH0959J)
   RL78 family user's manual software (R01US0015J)
   The latest versions can be downloaded from the Renesas Electronics website.

   Technical update
   The latest versions can be downloaded from the Renesas Electronics website.

All trademarks and registered trademarks are the property of their respective owners.
## Revision History

<table>
<thead>
<tr>
<th>Rev.</th>
<th>Date</th>
<th>Description</th>
<th>Page</th>
<th>Summary</th>
</tr>
</thead>
<tbody>
<tr>
<td>1.00</td>
<td>Apr.17,2023</td>
<td></td>
<td>-</td>
<td>First Edition</td>
</tr>
</tbody>
</table>
General Precautions in the Handling of Microprocessing Unit and Microcontroller Unit Products

The following usage notes are applicable to all Microprocessing unit and Microcontroller unit products from Renesas. For detailed usage notes on the products covered by this document, refer to the relevant sections of the document as well as any technical updates that have been issued for the products.

1. Precaution against Electrostatic Discharge (ESD)
   A strong electrical field, when exposed to a CMOS device, can cause destruction of the gate oxide and ultimately degrade the device operation. Steps must be taken to stop the generation of static electricity as much as possible, and quickly dissipate it when it occurs. Environmental control must be adequate. When it is dry, a humidifier should be used. This is recommended to avoid using insulators that can easily build up static electricity. Semiconductor devices must be stored and transported in an anti-static container, static shielding bag or conductive material. All test and measurement tools including work benches and floors must be grounded. The operator must also be grounded using a wrist strap. Semiconductor devices must not be touched with bare hands. Similar precautions must be taken for printed circuit boards with mounted semiconductor devices.

2. Processing at power-on
   The state of the product is undefined at the time when power is supplied. The states of internal circuits in the LSI are indeterminate and the states of register settings and pins are undefined at the time when power is supplied. In a finished product where the reset signal is applied to the external reset pin, the states of pins are not guaranteed from the time when power is supplied until the reset process is completed. In a similar way, the states of pins in a product that is reset by an on-chip power-on reset function are not guaranteed from the time when power is supplied until the power reaches the level at which resetting is specified.

3. Input of signal during power-off state
   Do not input signals or an I/O pull-up power supply while the device is powered off. The current injection that results from input of such a signal or I/O pull-up power supply may cause malfunction and the abnormal current that passes in the device at this time may cause degradation of internal elements. Follow the guideline for input signal during power-off state as described in your product documentation.

4. Handling of unused pins
   Handle unused pins in accordance with the directions given under handling of unused pins in the manual. The input pins of CMOS products are generally in the high-impedance state. In operation with an unused pin in the open-circuit state, extra electromagnetic noise is induced in the vicinity of the LSI, an associated shoot-through current flows internally, and malfunctions occur due to the false recognition of the pin state as an input signal become possible.

5. Clock signals
   After applying a reset, only release the reset line after the operating clock signal becomes stable. When switching the clock signal during program execution, wait until the target clock signal is stabilized. When the clock signal is generated with an external resonator or from an external oscillator during a reset, ensure that the reset line is only released after full stabilization of the clock signal. Additionally, when switching to a clock signal produced with an external resonator or by an external oscillator while program execution is in progress, wait until the target clock signal is stable.

6. Voltage application waveform at input pin
   Waveform distortion due to input noise or a reflected wave may cause malfunction. If the input of the CMOS device stays in the area between \( V_{IL} \) (Max.) and \( V_{IH} \) (Min.) due to noise, for example, the device may malfunction. Take care to prevent chattering noise from entering the device when the input level is fixed, and also in the transition period when the input level passes through the area between \( V_{IL} \) (Max.) and \( V_{IH} \) (Min.).

7. Prohibition of access to reserved addresses
   Access to reserved addresses is prohibited. The reserved addresses are provided for possible future expansion of functions. Do not access these addresses as the correct operation of the LSI is not guaranteed.

8. Differences between products
   Before changing from one product to another, for example to a product with a different part number, confirm that the change will not lead to problems. The characteristics of a microprocessing unit or microcontroller unit products in the same group but having a different part number might differ in terms of internal memory capacity, layout pattern, and other factors, which can affect the ranges of electrical characteristics, such as characteristic values, operating margins, immunity to noise, and amount of radiated noise. When changing to a product with a different part number, implement a system-evaluation test for the given product.
1. Descriptions of circuits, software and other related information in this document are provided only to illustrate the operation of semiconductor products and application examples. You are fully responsible for the incorporation or any other use of the circuits, software, and information in the design of your product or system. Renesas Electronics disclaims any and all liability for any losses and damages incurred by you or third parties arising from the use of software, circuits, or information.

2. Renesas Electronics hereby expressly disclaims any warranties against and liability for infringement or any other claims involving patents, copyrights, or other intellectual property rights of third parties, by or arising from the use of Renesas Electronics products or technical information described in this document, including but not limited to, the product data, drawings, charts, programs, algorithms, and application examples.

3. No license, express, implied or otherwise, is granted hereby under any patents, copyrights or other intellectual property rights of Renesas Electronics or others.

4. You shall be responsible for determining which licenses are required from any third parties, and obtaining such licenses for the lawful import, export, manufacture, sales, utilization, distribution or other disposal of any products incorporating Renesas Electronics products, if required.

5. You shall not alter, modify, copy, or reverse engineer any Renesas Electronics product, whether in whole or in part. Renesas Electronics disclaims any and all liability for any losses or damages incurred by you or third parties arising from such alteration, modification, copying or reverse engineering.

6. Renesas Electronics products are classified according to the following two quality grades: “Standard” and “High Quality”. The intended applications for each Renesas Electronics product depends on the product’s quality grade, as indicated below.
   - “Standard”: Computers; office equipment; communications equipment; test and measurement equipment; audio and visual equipment; home electronic appliances; machine tools; personal electronic equipment; industrial robots; etc.
   - “High Quality”: Transportation equipment (automobiles, trains, ships, etc.); nuclear power control systems; aircraft control systems; key plant systems; military equipment; etc.

7. No semiconductor product is absolutely secure. Notwithstanding any security measures or features that may be implemented in Renesas Electronics hardware or software products, Renesas Electronics shall have absolutely no liability arising out of any vulnerability or security breach, including but not limited to: unauthorized access or control of a Renesas Electronics product or a system that uses a Renesas Electronics product. "RENESSAS ELECTRONICS DOES NOT WARRANT OR GUARANTEE THAT RENESAS ELECTRONICS PRODUCTS, OR ANY SYSTEMS CREATED USING RENESAS ELECTRONICS PRODUCTS WILL BE INVULNERABLE OR FREE FROM CORRUPTION, ATTACK, VIRUSES, INTEREERENCE, HACKING, DATA LOSS OR THEFT, OR OTHER SECURITY INTRUSION ("Vulnerability Issues"). RENESAS ELECTRONICS DISCLAIMS ANY AND ALL RESPONSIBILITY OR LIABILITY ARISING FROM OR RELATED TO ANY VULNERABILITY ISSUES. FURTHERMORE, TO THE EXTENT PERMITTED BY APPLICABLE LAW, RENESAS ELECTRONICS DISCLAIMS ANY AND ALL WARRANTIES, EXPRESS OR IMPLIED. WITH RESPECT TO THIS DOCUMENT AND ANY RELATED OR ACCOMPANYING SOFTWARE OR HARDWARE, INCLUDING BUT NOT LIMITED TO THE IMPLIED WARRANTIES OF MERCHANTABILITY, OR FITNESS FOR A PARTICULAR PURPOSE.

8. When using Renesas Electronics products, refer to the latest product information (data sheets, user’s manuals, application notes, “General Notes for Handling and Using Semiconductor Devices” in the reliability handbook, etc.), and ensure that usage conditions are within the ranges specified by Renesas Electronics with respect to maximum ratings, operating power supply voltage range, heat dissipation characteristics, installation, etc. Renesas Electronics disclaims any and all liability for any malfunctions, failure or accident arising out of the use of Renesas Electronics products outside of such specified ranges.

9. Although Renesas Electronics endeavors to improve the quality and reliability of Renesas Electronics products, semiconductor products have specific characteristics, such as the occurrence of failure at a certain rate and malfunctions under certain use conditions. Unless designated as a high reliability product or a product for harsh environments in a Renesas Electronics data sheet or other Renesas Electronics document, Renesas Electronics products are not subject to radiation resistance design. You are responsible for implementing safety measures to guard against the possibility of bodily injury, injury or damage caused by fire, and/or danger to the public in the event of a failure or malfunction of Renesas Electronics products, such as safety design for hardware and software, including but not limited to redundancy, fire control and malfunction prevention, appropriate treatment for aging degradation and any other appropriate measures. Because the evaluation of microcomputer software alone is very difficult and impractical, you are responsible for evaluating the safety of the final products or systems manufactured by you.

10. Please contact a Renesas Electronics sales office for details as to environmental matters such as the environmental compatibility of each Renesas Electronics product. You are responsible for carefully and sufficiently investigating applicable laws and regulations that regulate the inclusion or use of controlled substances, including without limitation, the EU RoHS Directive, and using Renesas Electronics products in compliance with all these applicable laws and regulations. Renesas Electronics disclaims any and all liability for damages or losses occurring as a result of your noncompliance with applicable laws and regulations.

11. Renesas Electronics products and technologies shall not be used for or incorporated into any products or systems whose manufacture, use, or sale is prohibited under any applicable domestic or foreign laws or regulations. You shall comply with any applicable export control laws and regulations promulgated and administered by the governments of any countries asserting jurisdiction over the parties or transactions.

12. It is the responsibility of the buyer or distributor of Renesas Electronics products, or any other party who distributes, disposes of, or otherwise sells or transfers the product to a third party, to notify such third party in advance of the contents and conditions set forth in this document.

13. This document shall not be reproduced, reprinted or duplicated in any form, in whole or in part, without prior written consent of Renesas Electronics.

14. Please contact a Renesas Electronics sales office if you have any questions regarding the information contained in this document or Renesas Electronics products.

(Note1) “Renesas Electronics” as used in this document means Renesas Electronics Corporation and also includes its directly or indirectly controlled subsidiaries.

(Note2) “Renesas Electronics product(s)” means any product developed or manufactured by or for Renesas Electronics.

Corporate Headquarters
TOYOSU FORESIA, 3-2-24 Toyosu,
Koto-ku, Tokyo 135-0061, Japan
www.renesas.com

Contact information
For further information on a product, technology, the most up-to-date version of a document, or your nearest sales office, please visit: www.renesas.com/contact/.

© 2021 Renesas Electronics Corporation. All rights reserved.

Trademarks
Renesas and the Renesas logo are trademarks of Renesas Electronics Corporation. All trademarks and registered trademarks are the property of their respective owners.