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SH7137 Group

Reception of Serial Data by the SCI in Asynchronous Mode

Introduction

This application note describes reception of serial data by using the asynchronous transfer function of the serial communication interface (SCI). This application note is a summary for quick reference of information required in the design of user software.

Target Device

SH7137

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1. Preface

1.1 Specifications

In this sample task, data are received by using the asynchronous serial data communication function of the SCI.

Figure 1 shows an example of connection for reception by the SCI in asynchronous mode.

- SCI 1 is used.
- The communications format has an 8-bit data length, 1 stop bit, and no parity bit.
- The reception interrupt is used to conduct asynchronous communications on SCI 1. That is, the data-transfer controller (DTC) is activated by the receive-data-full interrupt.
- Once 32 bits of data have been received, operation for reception is halted.

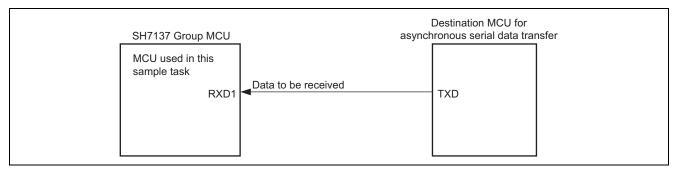


Figure 1 Connection Example for Reception by the SCI in Asynchronous Mode

1.2 Module Used

• Serial communication interface (SCI 1)

1.3 Applicable Conditions

• MCU SH7137

Operating frequency
 Internal clock: 80 MHz

Bus clock: 40 MHz

Peripheral clock: 40 MHz

• C compiler SuperH RISC Engine Family C/C++ Compiler Package Ver.9.11

from Renesas Technology



2. Description of the Sample Application

The sample program uses interrupt sources of the SCI, a receive-data-full interrupt (RXI), and receive error interrupt (ERI) to receive serial data in asynchronous mode.

2.1 Operational Overview of Module Used

In asynchronous mode, each transmitted or received character begins with a start bit and ends with a stop bit. Serial communication is synchronized one character at a time. The transmitting and receiving sections of the SCI are independent, so full duplex communication is possible. Both the transmitter and receiver have a double-buffered structure so that data can be read or written during transmission or reception, enabling continuous data transfer.

In asynchronous serial communication, the communication line is normally held in the mark (high) state. The SCI monitors the line and starts serial communication when the line goes to the space (low) state, indicating a start bit.

One serial character consists of a start bit (low), data (LSB first), parity bit (high or low), and stop bit (high), in that order.

For details on the SCI, see the section on serial communication interface in the SH7137 Group Hardware Manual.

Table 1 gives an overview of communications in asynchronous mode and figure 2 shows a block diagram of the SCI.

Table 1 Overview of Serial Data Communications in Asynchronous Mode

Item	Description
Number of interfaces	3 (SCI0, SCI1, SCI2)
Clock source	For internal clock: Pφ, Pφ/4, Pφ/16, Pφ/64 (Pφ: peripheral clock)
	For external clock: input clock on pin SCK
Data format	Data length: 7 or 8 bits
	Order: LSB first or MSB first
Baud rate	For internal clock: 110 bps to 1.25 Mbps (Pφ = 40 MHz)
	For external clock: up to 625 kbps
	(P = 40 MHz, external input clock of 10.0000 MHz)
Error detection	Framing, parity, and overrun errors
	Break can also be detected.
Interrupt request	Transmit-data-empty interrupt (TXI)
	Receive-data-full interrupt (RXI)
	Receive error interrupt (ERI)
	Transmit end interrupt (TEI)
Clock sources	Internal or external clock
	Internal clock
	When the internal clock has been selected, the clock from the baud-rate generator is used to operate the SCI and a clock signal at 16 times the frequency of the bit rate can be output.
	External clock
	When the external clock has been selected, input of a clock signal at 16 times the frequency of the bit rate is required
	(internal baud rate generator is not used).



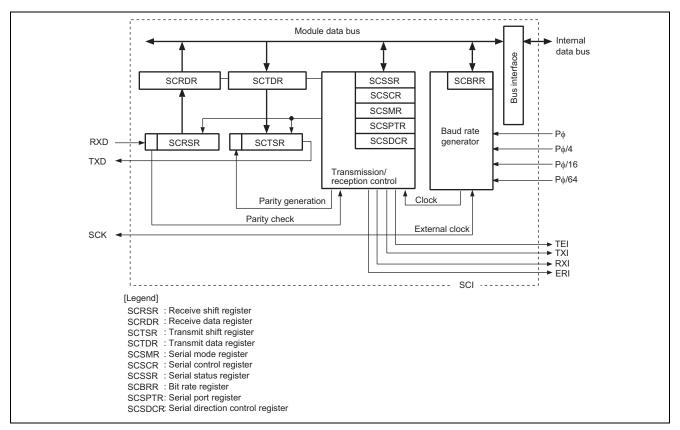


Figure 2 Block Diagram of the SCI



2.2 Operation of the Sample Program

Table 2 gives settings for SCI communications and figure 3 shows the timing of operations for data reception.

Table 2 Settings for Communications Function in the Sample Program

Item	Description
Module	SCI 1
Communications mode	Asynchronous mode
Interrupts	Receive-data-full interrupt (RXI)
	Receive error interrupt (ERI)
Transfer rate	19,200 bps
Number of data to be received and transmitted	32 bytes
Data length	8-bit data
Stop bit	1 stop bit
Parity	None
Bit order	LSB-first

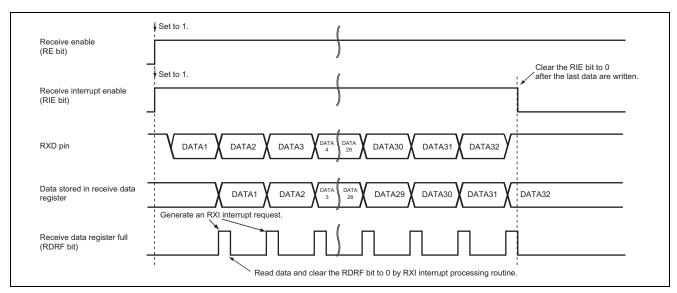


Figure 3 Timing of Operations for Data Reception



2.3 Procedure for Setting Module Used

This section describes the procedure for setting up SCI 1 for asynchronous mode operation.

Figure 4 shows the flow of processing by the sample program, figure 5 shows the flow of settings for release from module-standby mode, figure 6 shows the flow for setting up the pin function controller, and figure 7 shows the flow for initialization of data reception in asynchronous mode. Furthermore, figure 8 shows the flow for handling receive interrupts in asynchronous mode, and figure 9 shows the flow for handling receive error interrupts. For details on the settings of individual registers, see the SH7137 Group Hardware Manual.

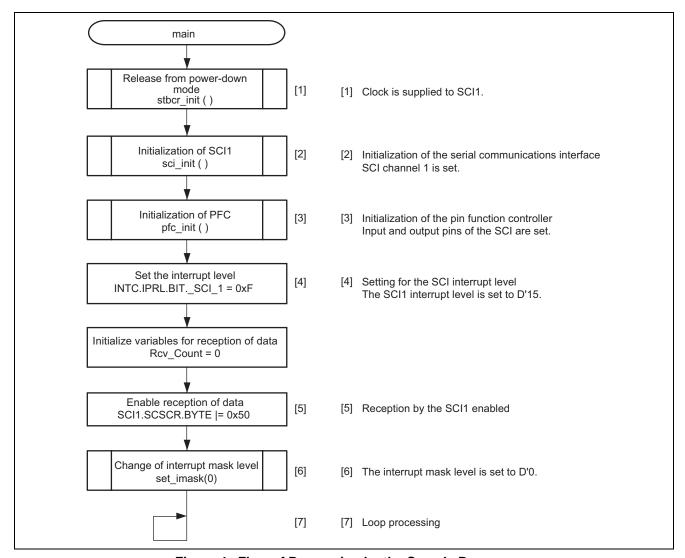


Figure 4 Flow of Processing by the Sample Program



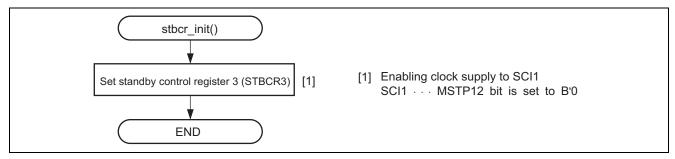


Figure 5 Flow of Settings for Release from Module-Standby Mode

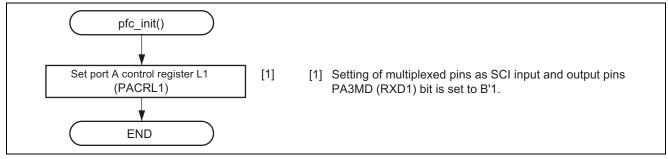


Figure 6 Flow for Setting up the Pin Function Controller

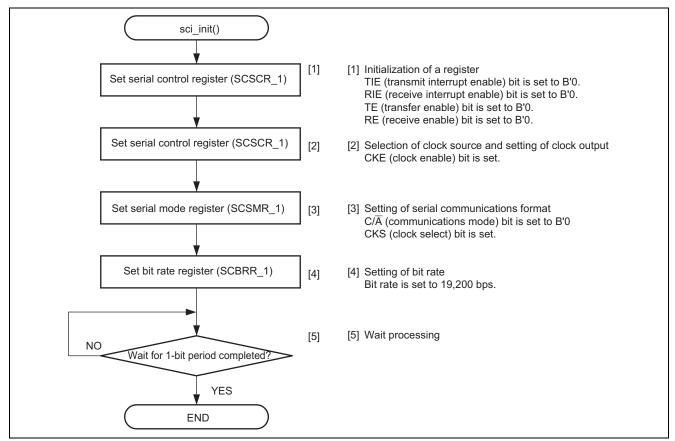


Figure 7 Flow for Initialization of Data Reception in Asynchronous Mode

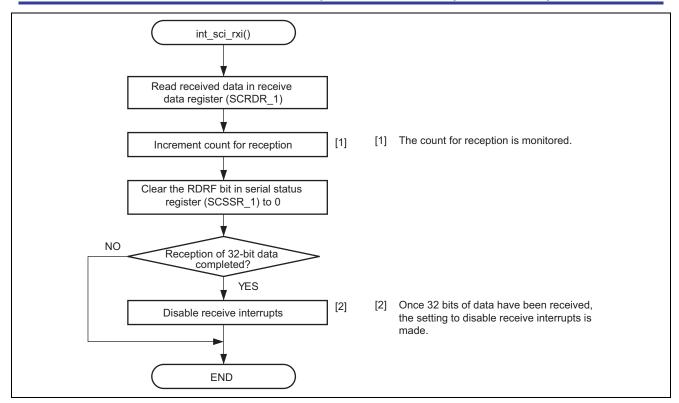


Figure 8 Flow for Handling Receive Interrupts in Asynchronous Mode

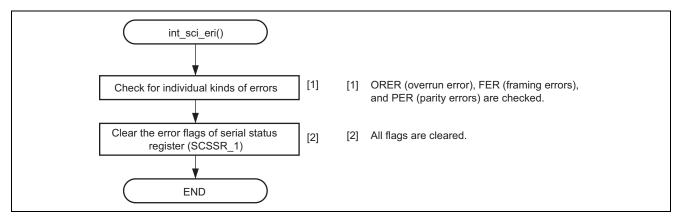


Figure 9 Flow for Handling Receive Error Interrupts



2.4 Processing Sequence of the Sample Program

In this sample program, character strings are received after initialization of SCI 1 for data reception in asynchronous mode.

2.4.1 Clock Pulse Generator (CPG)

Table 3 gives settings for the register of the clock pulse generator the sample program.

 Table 3
 Settings for Register in Clock Pulse Generator

Register Name	Address	Setting	Description
Frequency control register	H'FFFFE800	H'0241	$IFC[2:0] = B'000: \times 1 (I\phi)$
(FRQCR)			BFC[2:0] = B'001: \times 1/2 (B ϕ)
			$PFC[2:0] = B'001: \times 1/2 (P\phi)$
			$MIFC[2:0] = B'000: \times 1 (MI\phi)$
			MPFC[2:0] = B'001: \times 1/2 (MP ϕ)

2.4.2 Standby Control Register

Table 4 gives settings for the standby control register in the sample program.

Table 4 Settings for Standby Control Register

Register Name	Address	Setting	Description
Standby control register 3	H'FFFFE806	H'EF	MSTP12 = B'0: SCI1 operates
(STBCR3)			

2.4.3 Interrupt Controller (INTC)

Table 5 gives settings for the interrupt control register in the sample program.

Table 5 Settings for Interrupt Control Register

Register Name	Address	Setting	Description
Interrupt priority register L	H'FFFFE992	H'0F00	IPR[11:8] = H'F: SCI1 is at a level 15
(IPRL)			

Note: Interrupt priorities of RXI_1 and TXI_1 are in order of offset address in the vector table for interrupts. For details on interrupt priorities, see the description of the interrupt exception handling vector table in the section on the interrupt controller of the SH7137 Group Hardware Manual.

2.4.4 Pin Function Controller (PFC)

Table 6 gives settings for the register of the pin function controller in the sample program.

Table 6 Settings for Pin Function Control Register

Register Name	Address	Setting	Description
Port A control register L1	H'FFFFD116	H'1000	PA3MD[2:0] = B'001: RXD input
(PACRL1)			



2.4.5 Serial Communication Interface

Table 7 gives settings for the registers of the SCI in the sample program.

Table 7 Settings for SCI Register

Register Name	Address	Setting	Description
Serial mode register	H'FFFFC080	H'00	$C/\overline{A} = B'0$: Asynchronous mode
(SCSMR_1)			CHR = B'0: 8-bit data
			PE = B'0: Disables appending and
			checking of parity bits
			STOP = B'0: 1 stop bit
			CKS[1:0] = B'00: Pφ clock
Bit rate register (SCBRR_1)	H'FFFFC082	D'64	Asynchronous mode
			Bit rate: 19,200 (bit/s)*
Serial control register	H'FFFFC084	H'00	Initialization
(SCSCR_1)			TIE = B'0: Disables transmit-data-empty interrupt (TXI) request
			RIE = B'0: Disables receive-data-full
			interrupt (RXI) and receive error interrupt (ERI) requests
			TE = B'0: Disables transmission of data
			RE = B'0: Disables reception of data
			At the time of setting
			Asynchronous mode
			CKE[1:0] = B'00: Internal clock and the
			SCK pin are used as an
		LIITA	input pin
		H'F4	Enabling reception of data RIE = B'1: Enables receive-data-full
			interrupt (RXI) request
			RE = B'1: Enables reception of data
Serial status register	H'FFFFC088	H'84	Initial value
(SCSSR_1)			TDRE = B'1: Transmit-data-empty flag
- /			TEND = B'1: Transmit end flag

Note: * For details on bit rate settings, see the table of bit rates and SCBRR settings in the section of the serial communication interface in the *SH7137 Group Hardware Manual*.



3. Documents for Reference

- Software Manual SH-1/SH-2/SH-DSP Software Manual The most up-to-date version of this document is available on the Renesas Technology Website.
- Hardware Manual SH7137 Group Hardware Manual The most up-to-date version of this document is available on the Renesas Technology Website.



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