Abstract
This document describes the setting method to perform A/D conversion on analog voltage using the R8C/35C Group A/D converter in repeat sweep mode.

Product
R8C/35C Group

When using this application note with other Renesas MCUs, careful evaluation is recommended after making modifications to comply with the alternate MCU.
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1. Specifications

A/D conversion is performed on analog voltage input from two analog input pins using the A/D converter in repeat sweep mode. A/D converted values are stored to the variables in the A/D conversion interrupt handling.

Table 1.1 lists the Peripheral Function and Its Application. Figure 1.1 shows a Block Diagram.

**Table 1.1 Peripheral Function and Its Application**

<table>
<thead>
<tr>
<th>Peripheral Function</th>
<th>Application</th>
</tr>
</thead>
<tbody>
<tr>
<td>A/D converter</td>
<td>Perform A/D conversion on analog input voltage.</td>
</tr>
</tbody>
</table>

**Figure 1.1 Block Diagram**
2. Operation Confirmation Conditions

The sample code accompanying this application note has been run and confirmed under the conditions below.

Table 2.1 Operation Confirmation Conditions

<table>
<thead>
<tr>
<th>Item</th>
<th>Contents</th>
</tr>
</thead>
<tbody>
<tr>
<td>MCU used</td>
<td>R8C/35C Group</td>
</tr>
<tr>
<td>Operating frequencies</td>
<td>• High-speed on-chip oscillator clock: 40 MHz (typical)</td>
</tr>
<tr>
<td></td>
<td>• System clock: 20 MHz</td>
</tr>
<tr>
<td></td>
<td>• CPU clock: 20 MHz</td>
</tr>
<tr>
<td>Operating voltage</td>
<td>5.0 V (2.7 to 5.5 V)</td>
</tr>
<tr>
<td>Integrated development environment</td>
<td>Renesas Electronics Corporation</td>
</tr>
<tr>
<td></td>
<td>High-performance Embedded Workshop Version 4.07</td>
</tr>
<tr>
<td>C compiler</td>
<td>Renesas Electronics Corporation</td>
</tr>
<tr>
<td></td>
<td>M16C Series, R8C Family C Compiler V.5.45 Release 01</td>
</tr>
<tr>
<td>Compile options</td>
<td>-D__UART0__ -c -finfo -dir &quot;$(CONFIGDIR)&quot; -R8C</td>
</tr>
<tr>
<td></td>
<td>(Default setting is used in the integrated development environment)</td>
</tr>
</tbody>
</table>

3. Hardware

3.1 Pins Used

Table 3.1 lists the Pins Used and Their Functions.

Table 3.1 Pins Used and Their Functions

<table>
<thead>
<tr>
<th>Pin Name</th>
<th>I/O</th>
<th>Function</th>
</tr>
</thead>
<tbody>
<tr>
<td>P0_7/AN0</td>
<td>Input</td>
<td>A/D converter input (AN0)</td>
</tr>
<tr>
<td>P0_6/AN1</td>
<td>Input</td>
<td>A/D converter input (AN1)</td>
</tr>
</tbody>
</table>
4. Software

4.1 Operation Overview

A/D conversion is alternately performed on analog voltage input from AN0 and AN1 using the A/D converter in repeat sweep mode.

Settings
- Use pins P0_7/AN0 and P0_6/AN1 for analog input.
- Use repeat sweep mode for the A/D operating mode.
- Use fAD divided by 2 for operating clock fAD and f1 for the fAD clock source.
- Use 10 bits for the resolution.
- Use a software trigger for the A/D conversion start condition.
- Use the A/D conversion interrupt.
- Disable the A/D open-circuit detection assist function.

(1) Perform the initial setting of the A/D converter.
(2) Set the ADST bit in the ADCON0 register to 1 (A/D conversion started) to start A/D conversion.
(3) When A/D conversion on analog voltage input from AN0 and AN1 is completed, the IR bit in the ADIC register automatically becomes 1 (interrupt request), an A/D conversion interrupt is generated. The converted results on voltage input from AN0 is transferred to the AD0 register and the converted results on voltage input from AN1 is transferred to the AD1 register.
(4) Store the A/D converted value to the variable in the A/D conversion interrupt handling.
(5) Wait for the A/D conversion interrupt again.

Figure 4.1 shows the Timing Diagram in Repeat Sweep Mode.

![Figure 4.1 Timing Diagram in Repeat Sweep Mode](image-url)
4.2 Required Memory Size

Table 4.1 lists the Required Memory Size.

<table>
<thead>
<tr>
<th>Memory Used</th>
<th>Size</th>
<th>Remarks</th>
</tr>
</thead>
<tbody>
<tr>
<td>ROM</td>
<td>203 bytes</td>
<td>In the r01an0383_src.c module</td>
</tr>
<tr>
<td>RAM</td>
<td>4 bytes</td>
<td>In the r01an0383_src.c module</td>
</tr>
<tr>
<td>Maximum user stack usage</td>
<td>13 bytes</td>
<td></td>
</tr>
<tr>
<td>Maximum interrupt stack usage</td>
<td>4 bytes</td>
<td></td>
</tr>
</tbody>
</table>

The required memory size varies depending on the C compiler version and compile options.

4.3 Variable

Table 4.2 lists the Global Variable.

<table>
<thead>
<tr>
<th>Type</th>
<th>Variable Name</th>
<th>Contents</th>
<th>Function Used</th>
</tr>
</thead>
<tbody>
<tr>
<td>unsigned short</td>
<td>ad_data[2]</td>
<td>A/D converted result</td>
<td>_ad_converter</td>
</tr>
</tbody>
</table>

4.4 Functions

Table 4.3 lists the Functions.

<table>
<thead>
<tr>
<th>Function Name</th>
<th>Outline</th>
</tr>
</thead>
<tbody>
<tr>
<td>mcu_init</td>
<td>System clock setting</td>
</tr>
<tr>
<td>ad_init</td>
<td>Initial setting of A/D converter</td>
</tr>
<tr>
<td>_ad_converter</td>
<td>A/D conversion interrupt handling</td>
</tr>
</tbody>
</table>
## 4.5 Function Specifications

The following tables list the sample code function specifications.

### mcu_init

<table>
<thead>
<tr>
<th>Outline</th>
<th>System clock setting</th>
</tr>
</thead>
<tbody>
<tr>
<td>Header</td>
<td>None</td>
</tr>
<tr>
<td>Declaration</td>
<td>void mcu_init(void)</td>
</tr>
<tr>
<td>Description</td>
<td>Set the system clock.</td>
</tr>
<tr>
<td>Argument</td>
<td>None</td>
</tr>
<tr>
<td>Returned value</td>
<td>None</td>
</tr>
<tr>
<td>Remark</td>
<td>—</td>
</tr>
</tbody>
</table>

### ad_init

<table>
<thead>
<tr>
<th>Outline</th>
<th>Initial setting of A/D converter</th>
</tr>
</thead>
<tbody>
<tr>
<td>Header</td>
<td>None</td>
</tr>
<tr>
<td>Declaration</td>
<td>void ad_init(void)</td>
</tr>
<tr>
<td>Description</td>
<td>Perform initial setting to use the A/D converter in repeat sweep mode.</td>
</tr>
<tr>
<td>Argument</td>
<td>None</td>
</tr>
<tr>
<td>Returned value</td>
<td>None</td>
</tr>
<tr>
<td>Remark</td>
<td>—</td>
</tr>
</tbody>
</table>

### _ad_converter

<table>
<thead>
<tr>
<th>Outline</th>
<th>A/D conversion interrupt handling</th>
</tr>
</thead>
<tbody>
<tr>
<td>Header</td>
<td>None</td>
</tr>
<tr>
<td>Declaration</td>
<td>void _ad_converter(void)</td>
</tr>
<tr>
<td>Description</td>
<td>Use the A/D converter in repeat sweep mode and store the A/D converted value to the variable.</td>
</tr>
<tr>
<td>Argument</td>
<td>None</td>
</tr>
<tr>
<td>Returned value</td>
<td>None</td>
</tr>
<tr>
<td>Remark</td>
<td>—</td>
</tr>
</tbody>
</table>
4.6 Flowcharts

4.6.1 Main Processing

Figure 4.2 shows the Main Processing.

![Flowchart of Main Processing](image)

**Note:**
1. After setting the ADST1 bit to 1, wait for three cycles of the A/D conversion start delay time.
2. There is no delay time after second A/D conversions.
### 4.6.2 System Clock Setting

Figure 4.3 shows the System Clock Setting.

![Figure 4.3 System Clock Setting](image)

- **mcu_init**
- Enable writing to registers
- Start low-speed on-chip oscillator
- Set high-speed on-chip oscillator
- Start high-speed on-chip oscillator
- Wait until oscillation stabilizes
- Set system clock
- Set CPU clock
- Disable writing to registers
- return

**PRC register**
- PRC0 bit ← 1 : Enable writing to registers CM0, CM1, OCD, FRA0, and FRA2.

**CM1 register**
- CM14 bit ← 0 : Start low-speed on-chip oscillator.

**FRA2 register ← 00h**
- Bits FRA22 to FRA20 = 000b : Divide-by-2 mode

**FRA0 register**
- FRA00 bit ← 1

**FRA0 register**
- FRA01 bit ← 1 : Select high-speed on-chip oscillator.

**OCD register**
- OCD2 bit ← 1 : Select on-chip oscillator clock.

**CM1 register**
- Bits CM17 and CM16 ← 00b : Select CPU clock no division.

**CM0 register**
- CM06 bit ← 0 : Enable bits CM16 and CM17 in the CM1 register.

**PRC register**
- PRC0 bit ← 0 : Disable writing to registers CM0, CM1, OCD, FRA0, and FRA2.
### 4.6.3 Initial Setting of A/D Converter

Figure 4.4 shows the Initial Setting of A/D Converter.

- **ad_init**
- Store port P0 direction register value
- Enable writing to registers
- Set port P0_6 and P0_7 to input mode
- Disable A/D conversion interrupt
- Stop A/D conversion
- Enable writing to registers
- Cut off on-chip reference voltage and analog input
- Disable writing to registers
- Set A/D mode register
- Wait for 3 cycles of φAD
- Set registers associated with A/D converter
- Wait for 1 cycle of φAD
- Enable A/D conversion interrupt
- return

**Figure 4.4 Initial Setting of A/D Converter**

- **work ← PD0 & 0x3f**: Read the PD0 register.
- **PRC2 bit ← -1**: Enable writing to the PD0 register.
- **PD0 register ← work**
  - Bits PD0_7 and PD0_6 = 00b
- **ADIC register ← 00h**
  - Bits ILVL2 to ILVL0 = 001b: Level 0 (disable interrupts)
- **ADCON0 register ← 00h**
  - ADST bit = 0
- **PRC3 bit ← 1**: Enable writing to the OCVREFCR register.
- **OCVREFCR register**
  - OCVREFAN bit ← 0
- **PRC3 bit ← 0**: Disable writing to the OCVREFCR register.
- **ADMOD register ← 32h**
  - Bits CKS1 and CKS0 = 10b: fAD divided by 2
  - Bits MD2 to MD0 = 110b: Repeat sweep mode
  - Bits ADCAP1 to ADCAP0 = 00b: Select software trigger
- **ADCON1 register ← 30h**
  - ADEX0 bit = 0: Do not select extended analog input pins.
  - BITS bit = 1: 10-bit mode
  - ADSTBY bit = 1: A/D operation enabled
  - ADDDAEN bit = 0: A/D open-circuit detection assist function
- **ADCON0 register**
  - ADST bit = 0
- **PRC register**
  - PRC3 bit = 0: Disable writing to the OCVREFCR register.
4.6.4 A/D Conversion Interrupt Handling

Figure 4.5 shows the A/D Conversion Interrupt Handling.

Figure 4.5 A/D Conversion Interrupt Handling
5. **Sample Code**

Sample code can be downloaded from the Renesas Electronics website.

6. **Reference Documents**

R8C/35C Group User’s Manual: Hardware Rev.1.00
The latest version can be downloaded from the Renesas Electronics website.

Technical Update/Technical News
The latest information can be downloaded from the Renesas Electronics website.

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http://www.renesas.com/

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<table>
<thead>
<tr>
<th>Rev.</th>
<th>Date</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>1.00</td>
<td>July 20, 2011</td>
<td>— First edition issued</td>
</tr>
<tr>
<td>1.01</td>
<td>Sep. 29, 2011</td>
<td>4 Table 2.1 errors revised</td>
</tr>
</tbody>
</table>

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General Precautions in the Handling of MPU/MCU Products

The following usage notes are applicable to all MPU/MCU products from Renesas. For detailed usage notes on the products covered by this manual, refer to the relevant sections of the manual. If the descriptions under General Precautions in the Handling of MPU/MCU Products and in the body of the manual differ from each other, the description in the body of the manual takes precedence.

1. Handling of Unused Pins
   Handle unused pins in accord with the directions given under Handling of Unused Pins in the manual.
   - The input pins of CMOS products are generally in the high-impedance state. In operation with an unused pin in the open-circuit state, extra electromagnetic noise is induced in the vicinity of LSI, an associated shoot-through current flows internally, and malfunctions occur due to the false recognition of the pin state as an input signal become possible. Unused pins should be handled as described under Handling of Unused Pins in the manual.

2. Processing at Power-on
   The state of the product is undefined at the moment when power is supplied.
   - The states of internal circuits in the LSI are indeterminate and the states of register settings and pins are undefined at the moment when power is supplied.
     In a finished product where the reset signal is applied to the external reset pin, the states of pins are not guaranteed from the moment when power is supplied until the reset process is completed.
     In a similar way, the states of pins in a product that is reset by an on-chip power-on reset function are not guaranteed from the moment when power is supplied until the power reaches the level at which resetting has been specified.

3. Prohibition of Access to Reserved Addresses
   Access to reserved addresses is prohibited.
   - The reserved addresses are provided for the possible future expansion of functions. Do not access these addresses; the correct operation of LSI is not guaranteed if they are accessed.

4. Clock Signals
   After applying a reset, only release the reset line after the operating clock signal has become stable. When switching the clock signal during program execution, wait until the target clock signal has stabilized.
   - When the clock signal is generated with an external resonator (or from an external oscillator) during a reset, ensure that the reset line is only released after full stabilization of the clock signal. Moreover, when switching to a clock signal produced with an external resonator (or by an external oscillator) while program execution is in progress, wait until the target clock signal is stable.

5. Differences between Products
   Before changing from one product to another, i.e. to one with a different part number, confirm that the change will not lead to problems.
   - The characteristics of MPU/MCU in the same group but having different part numbers may differ because of the differences in internal memory capacity and layout pattern. When changing to products of different part numbers, implement a system-evaluation test for each of the products.
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