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April 1st, 2010
Renesas Electronics Corporation

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H8/300L SLP Series

Handling Multiple Internally Generated Interrupts

Introduction

Multiple-interrupt handling is implemented using internal interrupts generated by Timer A and FH.

Target Device

H8/38024

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1. Specifications

1. Multiple-interrupt handling is implemented using internal interrupts generated by Timer A and FH.
2. By accepting a Timer FH interrupt request in Timer A interrupt handling, the priority of Timer FH interrupt request is set higher than that of Timer A interrupt request by software.
3. The LED is made to blink in the Timer FH interrupt handling.
4. Using the interval function, a Timer A interrupt request is set to be generated every 26.214 ms.
5. Using the interval function, a Timer FH interrupt request is set to be generated every 1.638 ms.
6. The LED is connected to the P92 output pin of port 9.
7. P92 pin is a large-current port.

2. Description of Functions

1. In this sample task, multiple-interrupt handling is implemented using internal interrupts generated by Timer A and FH.
 - A. Internal interrupts are described below.
 - Each on-chip peripheral module has flags to indicate its interrupt request statuses and enable bits to enable or disable the interrupts. For timer A interrupt requests and direct transition interrupt requests generated by execution of a SLEEP instruction, their interrupt request status flags and enable bits are provided in IRR1 and IENR1. When an on-chip peripheral module generates an interrupt request, the corresponding interrupt request status flag is set to 1 and the interrupt request is issued to the CPU. These interrupts can be masked by clearing the corresponding enable bits.
 - All interrupts can be masked by setting the I bit in the CCR to 1.
 - Interrupt operation is described below.
 - (1) If an interrupt occurs with its corresponding bit in the interrupt enable register set to 1, an interrupt request signal is sent to the interrupt controller.
 - (2) On receiving the interrupt request signal, the corresponding interrupt request flag is set.
 - (3) If multiple interrupt requests are generated with their corresponding interrupt request flags set to 1, the interrupt with the highest priority at that time is requested. Other interrupt requests are held pending.
 - (4) The CPU checks the I bit setting in CCR. If the I bit is cleared to 0, the interrupt request is accepted. If the I bit is set to 1, the interrupt request is held pending.
 - (5) If the CPU accepts the interrupt, after processing of the current instruction is completed, both the program counter (PC) and CCR are saved to the stack. This PC value saved in the stack is the address of the first instruction to be executed upon return from interrupt handling.
 - (6) The I bit in CCR is set to 1 to mask all other interrupts.
 - (7) The CPU generates the vector address corresponding to the accepted interrupt, and the interrupt handling routine starts execution from the address indicated in that address.
 - Disabling of interrupts by clearing bits in IENR1 and clearing of bits in IRR1 must be done while interrupts are masked (I bit is set to 1).
 - If the above clearing operations are performed while the I bit is 0, a conflict may arise between the clearing instruction and an interrupt request. In such situation, exception handling for the interrupt will be executed after the execution of the clearing instruction has been completed.
 - The timer A and timer FH interrupt periods in this sample task are calculated by the following equations:

$$\begin{aligned} \text{Timer A interrupt period} &= \frac{1}{\text{System clock} / 512} \times 256 \\ 26.214 \text{ ms} &= \frac{1}{5 \text{ MHz} / 512} \times 256 \\ \\ \text{Timer FH interrupt period} &= \frac{1}{\text{System clock}/32} \times 256 \\ 1.638 \text{ ms} &= \frac{1}{5 \text{ MHz} / 32} \times 256 \end{aligned}$$

2. Table 2.1 shows the function assignments in this sample task. Multiple-interrupt handling for internal interrupts is performed by assigning the functions as shown in table 2.1.

Table 2.1 Assignment of Functions

Pin/Register	Assigned Function
PSS	A 13-bit up counter using the system clock (5 MHz) as input.
TMA	Selects PSS and sets the divide-by-ratio for the prescaler.
TCA	An 8-bit up counter using the system clock (5 MHz)/512 as input.
TCRF	Selects the output level of TCFH and selects the input clock.
TCSRF	Enables TCFH overflow interrupts and selects TCFH clearing by compare-match FH.
TCFH	An 8-bit up counter using the system clock /32 as input.
OCRFH	Timer FH interrupt period
IENTA	Enables Timer A interrupt requests.
IENTFH	Enables Timer FH interrupt requests.
IRRTA	Indicates whether or not a Timer A interrupt request has been issued.
IRRTFH	Indicates whether or not a Timer FH interrupt request has been issued.
Bit I of CCR	Enables/disables all interrupt requests.
P92	LED output

3. Principle of Operation

1. Figure 3.1 illustrates the operation of this sample task. Multiple-interrupt handling for internally generated interrupts is implemented through hardware and software processing as shown in the figure.

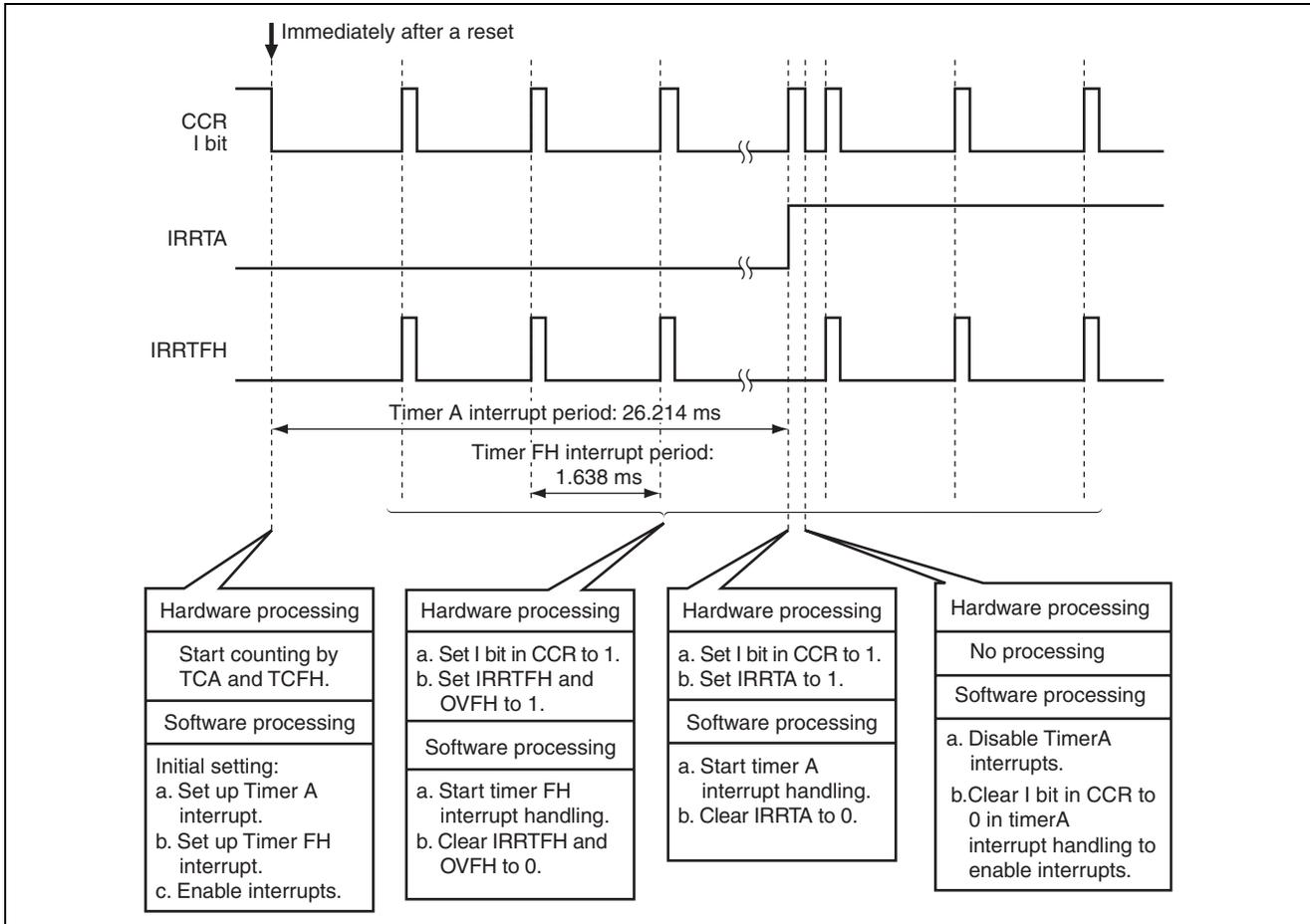


Figure 3.1 Operation Principle of Multiple-Interrupt Handling for Internal Interrupts

4. Description of Software

4.1 Modules

The modules used in this sample task are shown in table 4.1.

Table 4.1 Description of Modules

Module	Label	Function
Main Routine	main	Makes settings for Timer A interrupts, Timer FH interrupts, and port 9 and enables interrupts.
Count	taint	A Timer A interrupt handling routine that enables interrupts, increments the 16-bit counter, and ends when the counter value reached 5000.
LED Control	tfint	A Timer FH interrupt handling routine that makes the LED blink.

4.2 Arguments

This sample task does not use arguments.

4.3 Internal registers

Table 4.2 shows the internal registers involved in this sample task.

Table 4.2 Description of Internal Registers

Register	Function	Address	Setting
TMA	Timer Mode Register A If TMA = H'13, timer A functions as an interval timer, the TCA input clock source is PSS, and the divide-by-ratio for the prescaler is set to 512.	H'FFB0	H'13
TCA	Timer Counter A An 8-bit up counter using clock input of system clock/512	H'FFB1	H'00
TCRF	TOLH Timer Control Register F (Toggle Output Level H) If TOLH = 0, TMOFH pin output level is high. If TOLH = 1, TMOFH pin output level is low.	H'FFB6 Bit 7	0
	CKSH2 Timer Control Register F (Clock Select H)	H'FFB6	CKSH2 = 1
	CKSH1 If CKSH2 = 1, CKSH1 = 0 and CKSH0 = 0, TCFH is incremented by system clock/32.	Bit 6	CKSH1 = 0
TCSRF	OVFH Timer Control/Status Register F (Timer Overflow Flag H) If OVFH = 0, TCFH has not overflowed. If OVFH = 1, TCFH has overflowed.	H'FFB7 Bit 7	0
	CMFH Timer Control/Status Register F (Compare-match Flag H) If CMFH = 0, Compare-match FH has not occurred. If CMFH = 1, Compare-match FH has occurred.	H'FFB7 Bit 6	0

Register	Function	Address	Setting
TCSR.F	OVIEH Timer Control/Status Register F (Timer Overflow Interrupt Enable H) If OVIEH = 0, interrupt request by overflow of TCFH is disabled. If OVIEH = 1, interrupt request by overflow of TCFH is enabled.	H'FFB7 Bit 5	0
TCSR.F	CCLR.H Timer Control/Status Register F (Counter Clear H) If CCLR.H = 0, clearing of TCFH by compare-match FH is disabled. If CCLR.H = 1, clearing of TCFH by compare-match FH is enabled.	H'FFB7 Bit 4	1
TCF.H	Timer Counter FH An 8-bit up counter using system clock/32 as input	H'FFB8	H'00
OCR.F	Output Compare Register FH If OCR.F = H'80, compare-match FH signal is generated when the counter value of TCF.H has reached H'80.	H'FFBA	H'FF
PDR9	P92 Port Data Register 9 (Port Data Register 92) If P92 = 0, the P92 pin output level is low. If P92 = 1, the P92 pin output level is high.	H'FFDC Bit 2	0
IENR1	IEN.TA Interrupt Enable Register 1 (Timer A Interrupt Enable) If IEN.TA = 0, Timer A interrupt request is disabled. If IEN.TA = 1, Timer A interrupt request is enabled.	H'FFF3 Bit 7	1
IENR2	IEN.FH Interrupt Enable Register 2 (Timer FH Interrupt Enable) If IEN.FH = 0, Timer FH interrupt request is disabled. If IEN.FH = 1, Timer FH interrupt request is enabled.	H'FFF4 Bit 3	1
IRR1	IRRTA Interrupt Request Register 1 (Timer A Interrupt Request Flag) If IRRTA = 0, Timer A interrupt request is not issued. If IRRTA = 1, Timer A interrupt request has been issued.	H'FFF6 Bit 7	0
IRR2	IRRTFH Interrupt Request Register 2 (Timer FH Interrupt Request Flag) If IRRTFH = 0, Timer FH interrupt request is not issued. If IRRTFH = 1, Timer FH interrupt request has been issued.	H'FFF7 Bit 3	0

4.4 Description of RAM

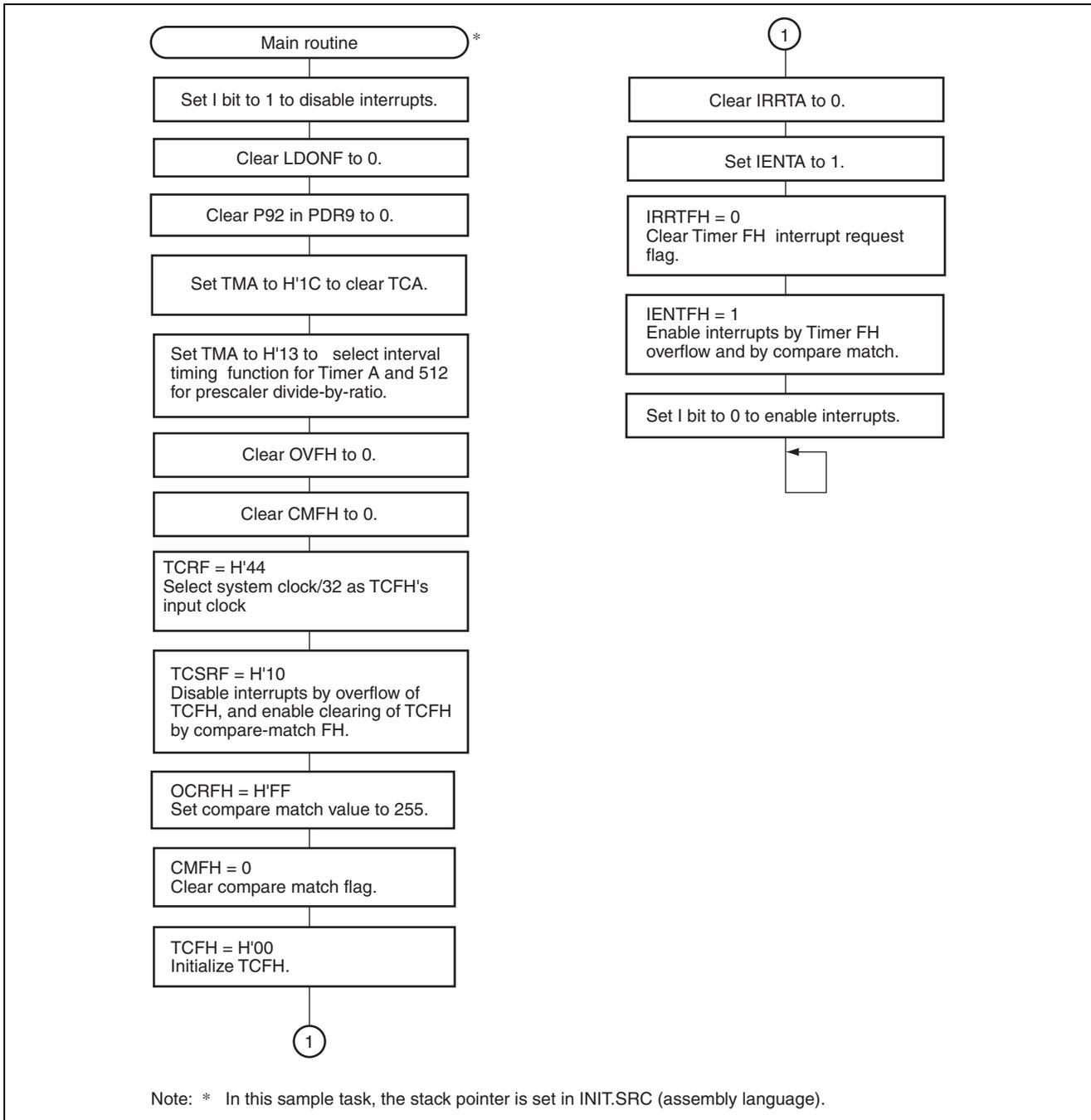
Table 4.3 describes the RAM area used in this sample task.

Table 4.3 Description of RAM

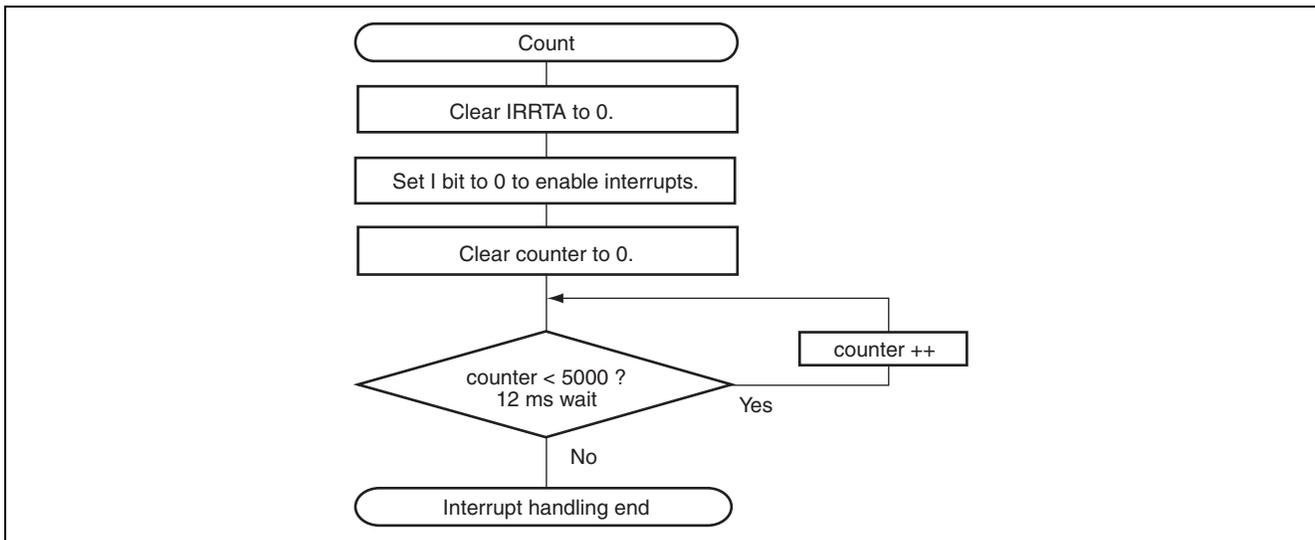
Label	Function	Address	Used in
USR.F	LDON.F Flag to judge ON/OFF of the LED	H'FB82 Bit 0	LED control

5. Flowchart

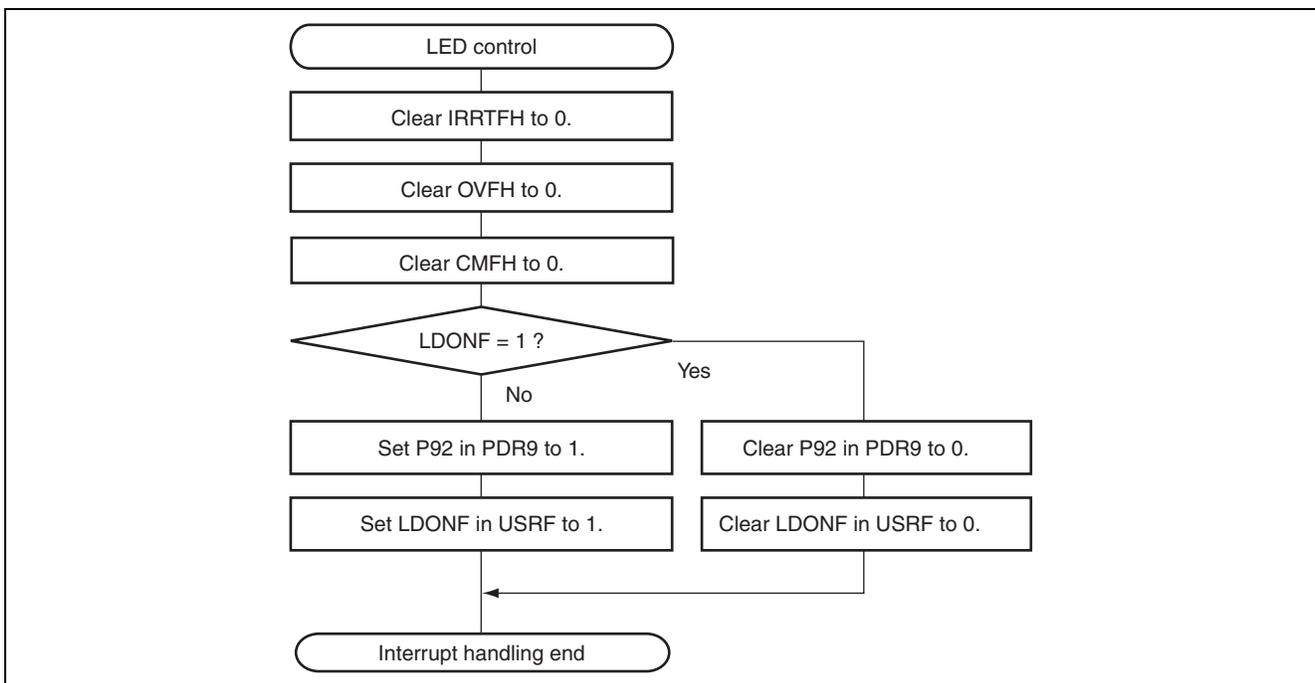
1. Main routine



2. Timer A interrupt handling routine



3. Timer FH interrupt handling routine



6. Program Listing

INIT.SRC (Program listing)

```

.EXPORT  _INIT
.IMPORT  _main
;
.SECTION P, CODE
_INIT:
MOV.W   #H'FF80, R7
LDC.B   #B'10000000, CCR
JMP     @_main
;
.END

/*****
/*
/* H8/300L Super Low Power Series
/* -H8/38024 Series-
/* Application Note
/*
/*
/* 'Multiple Interrupt Operation by Internal
/* Interrupt'
/*
/*
/* Function
/* : Internal Interrupt
/*
/*
/* External Clock : 10MHz
/* Internal Clock : 5MHz
/* Sub Clock      : 32.768kHz
/*
/*
*****/

#include <machine.h>

/*****
/* Symbol Definition
*****/
struct BIT {
    unsigned char  b7:1;    /* bit7 */
    unsigned char  b6:1;    /* bit6 */
    unsigned char  b5:1;    /* bit5 */
    unsigned char  b4:1;    /* bit4 */
    unsigned char  b3:1;    /* bit3 */
    unsigned char  b2:1;    /* bit2 */
    unsigned char  b1:1;    /* bit1 */
    unsigned char  b0:1;    /* bit0 */
};

#define TMA      *(volatile unsigned char *)0xFFB0    /* Timer Mode Register A */
#define TCA      *(volatile unsigned char *)0xFFB1    /* Timer Counter A */
#define TCRF     *(volatile unsigned char *)0xFFB6    /* Timer Control Register F */
#define TCRF_BIT (*(struct BIT *)0xFFB6)            /* Timer Control Register F */
#define TOLH     TCRF_BIT.b7                        /* Toggle Output Level F */
#define CKSH2    TCRF_BIT.b6                        /* Clock Select H2 */

```

```

#define CKSH1      TCRF_BIT.b5          /* Clock Select H1          */
#define CKSH0      TCRF_BIT.b4          /* Clock Select H0          */
#define TCSRFB     *(volatile unsigned char *)0xFFB7 /* Timer Control Status Register F */
#define TCSRFB_BIT (*(struct BIT *)0xFFB7) /* Timer Control Status Register F */
#define OVFH       TCSRFB_BIT.b7        /* Timer Overflow Flag H    */
#define CMFH       TCSRFB_BIT.b6        /* Compare-match Flag H    */
#define OVIEH      TCSRFB_BIT.b5        /* Timer Overflow Interrupt Enable */
#define CCLRH      TCSRFB_BIT.b4        /* Output Select 3         */
#define TCFH       *(volatile unsigned char *)0xFFB8 /* Timer Counter FH        */
#define OCRFH      *(volatile unsigned char *)0xFFBA /* Output Compare Register FH */
#define IENR1_BIT  (*(struct BIT *)0xFFF3) /* Interrupt Enable Register 1 */
#define IENTA      IENR1_BIT.b7         /* Timer A Interrupt Enable  */
#define IENR2_BIT  (*(struct BIT *)0xFFF4) /* Interrupt Enable Register 2 */
#define IENTFH     IENR2_BIT.b3         /* Timer FH Interrupt Enable  */
#define IRR1_BIT   (*(struct BIT *)0xFFF6) /* Interrupt Request Register 1 */
#define IRRTA      IRR1_BIT.b7          /* Timer A Interrupt Request Flag */
#define IRR2_BIT   (*(struct BIT *)0xFFF7) /* Interrupt Request Register 2 */
#define IRRTFH     IRR2_BIT.b3          /* Timer FH Interrupt Request Flag */
#define PDR9_BIT   (*(struct BIT *)0xFFDC) /* Port Data Register 9     */
#define P92        PDR9_BIT.b2         /* Port Data Register 9 bit2 */

#pragma interrupt (taint)
#pragma interrupt (tfint)
/*****
/* Function define
*****/
extern void INIT ( void ); /* SP Set
void main ( void );
void taint ( void );
void tfint ( void );

/*****
/* RAM define
*****/
unsigned char USRF; /* User Flag Area

#define USRF_BIT (*(struct BIT *)&USRF)
#define LDONF USRF_BIT.b0 /* LED On Flag

/*****
/* Vector Address
*****/
#pragma section V1 /* Vector Section Set
void (*const VEC_TBL1[]) (void) = {
    INIT /* 0x0000 Reset Vector
};
#pragma section V2 /* Vector Section Set
void (*const VEC_TBL2[]) (void) = {
    taint /* 0x016 Timer A Interrupt Vector
};
#pragma section V3 /* Vector Section Set
void (*const VEC_TBL3[]) (void) = {
    tfint /* 0x01E Timer F Interrupt Vector
};

```

```

#pragma section                /* P                */
/*****
/* Main Program                */
*****/
void main ( void )
{
    int tmp;

    set_imask_ccr(1);          /* Interrupt Disable          */

    LDONF = 0;                /* Clear LDONF                */
    P92   = 0;                /* Clear P92                  */

    TMA   = 0x1C;             /* TCA Clear                  */
    TMA   = 0x13;             /* Initialize TMA Function &
                               TCA Input Clock Period */

    tmp   = OVFH;
    tmp   = 0;
    OVFH  = tmp;              /* Clear OVFH                 */
    tmp   = CMFH;
    tmp   = 0;
    CMFH  = tmp;              /* Clear CMFH                 */

    TCRF  = 0x44;             /* Initialize Clock Select     */
    TCSRf = 0x10;             /* Initialize Overflow Interrupt */

    OCRFH = 0xFF;             /* Initialize Compare-match FH Value */
    CMFH  = 0;                /* Clear Compare-match Flag FH */
    TCFH  = 0;                /* Compare-match FH Interrupt Enable */

    IRRTA = 0;                /* Clear IRRTA                */
    IENTA = 1;                /* Timer A Interrupt Enable    */

    IRRTFH = 0;              /* Clear IRRTFH               */
    IENTFH = 1;              /* Timer FH Interrupt Enable   */

    set_imask_ccr(0);        /* Interrupt Enable           */

    while(1){
        ;
    }
}

```

```

/*****
/* Timer A Interrupt
/*****
void taint ( void )
{
    unsigned short    counter;

    IRRTA = 0;          /* Clear IRRTA
                        */

    set_imask_ccr(0);  /* Interrupt Enable
                        */

    for(counter = 0; counter < 5000; counter++); /* dummy wait
                                                    */
}

/*****
/* Timer F Interrupt
/*****
void tfint ( void )
{
    int tmp;

    IRRTFH = 0;

    tmp = OVFH;
    tmp = 0;
    OVFH = tmp;        /* Clear OVFH
                        */

    tmp = CMFH;
    tmp = 0;
    CMFH = tmp;        /* Clear CMFH
                        */

    if(LDONF == 1){    /* LDONF = 1 ?
                        */
        P92 = 0;       /* Turn off LED
                        */
        LDONF = 0;     /* Clear LDONF
                        */
    }
    else{
        P92 = 1;       /* urn on LED
                        */
        LDONF = 1;     /* Set LDONF
                        */
    }
}

```

Link address specifications

Section Name	Address
CV1	H'0000
CV2	H'0016
CV3	H'001E
P	H'0100
B	H'FB80

Revision Record

Rev.	Date	Description	
		Page	Summary
1.00	Dec.19.03	—	First edition issued

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