

Renesas RA Family

GUIX "Hello World" for EK-RA6M3G

Introduction

This application note describes the process of creating a simple two-screen GUI using Azure RTOS GUIX Studio for the EK-RA6M3G kit. This application demonstrates how easily a user can create and configure a new application using the Renesas Flexible Software Package (FSP).

The Renesas Flexible Software Package includes Azure RTOS ThreadX® real-time operating system, the Azure RTOS GUIX library and hardware drivers unified under a single robust software package. This powerful suite of tools provides a comprehensive integrated framework for rapid development of complex embedded applications.

The Hello World application was developed under e² studio using the Renesas Flexible Software Package.

Required Resources

Development tools and software

- e² studio IDE 2021-04 or greater
- Renesas Flexible Software Package (FSP) v3.1.0 or greater
- Azure RTOS GUIX Studio V6.1.7.0 or greater

Hardware

- Renesas EK-RA6M3G kit (RA6M3 MCU Group)
(<https://www.renesas.com/us/en/products/software-tools/boards-and-kits/eval-kits/ek-ra6m3g.html>)

Reference Manuals

- RA Flexible Software Package Documentation Release v3.1.0
- Azure RTOS GUIX and GUIX Studio v6.1.7.0
- Renesas RA6M3 Group User's Manual Rev.1.00
- EK-RA6M3G-v1.0 Schematics

Provided Software Files

- A Source.zip folder that has a touch_ft5x06 folder and 4 *.c files inside
- hal_entry.c, system_thread_entry.c, touch_thread_entry.c, windows_handler.c

Purpose

This document will guide you through the setup of an Azure RTOS GUIX touch screen interface Hello World application in e² studio. This document will show how to configure the drivers and library included with the FSP. These will allow you to set up the GLCD Controller, the touch screen driver, and semaphores to communicate with application tasks. It also shows the steps necessary to create a simple GUI interface using the Azure RTOS GUIX Studio editor. In addition, this app note will also cover project setup along with basic debugging operations. When it is running, the application will respond to touchscreen actions, presenting a basic graphical user interface (GUI).

Intended Audience

The intended audience is users who want to design GUI applications.

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1. Download and Installing Tools

1.1 Overview

In this section you will copy materials to your PC and install v2021-04/FSP v3.1.0 and Azure RTOS GUIX studio v6.1.7.0.

1.2 Procedural Steps

1. If you already have e2 studio v2021-04 with FSP v3.1.0 or later installed, you can skip this step. Otherwise, you can download it from <https://www.renesas.com/us/en/software-tool/flexible-software-package-fsp>. Detailed installation instructions for the e2 studio and the FSP are available on the Renesas website <https://www.renesas.com/fsp>. Review the release notes for e² studio to ensure that the e² studio version supports the selected FSP version. The starting version of the installer includes all features of the RA MCUs.
2. You can get Azure RTOS GUIX Studio V6.1.7.0 or greater from this [link](#). If it goes well, you will see the window in the next step on the web browser.
Note: Microsoft Store must be working on your PC to install Azure RTOS GUIX studio.
3. Click **Get** to start installing Azure RTOS GUIX studio.

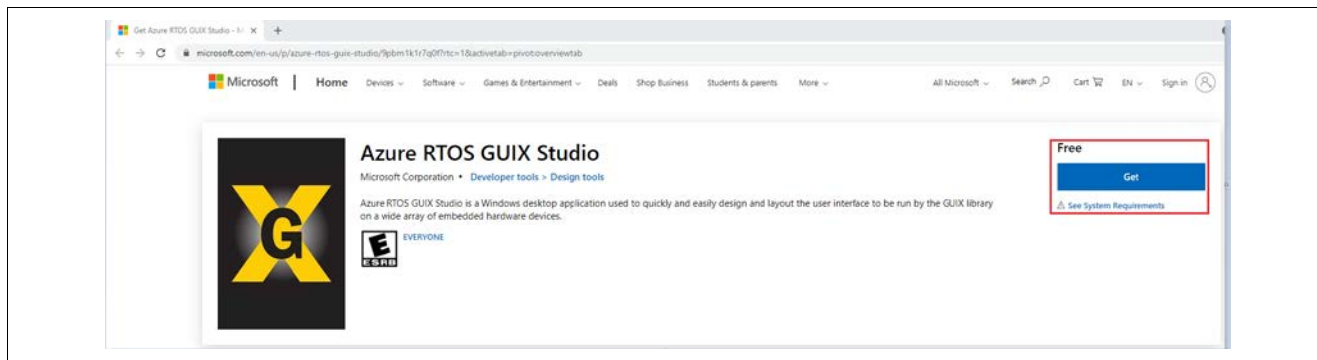


Figure 1. Get Azure RTOS GUIX Studio

4. Click **Open Microsoft store** to continue installing Azure RTOS GUIX studio.

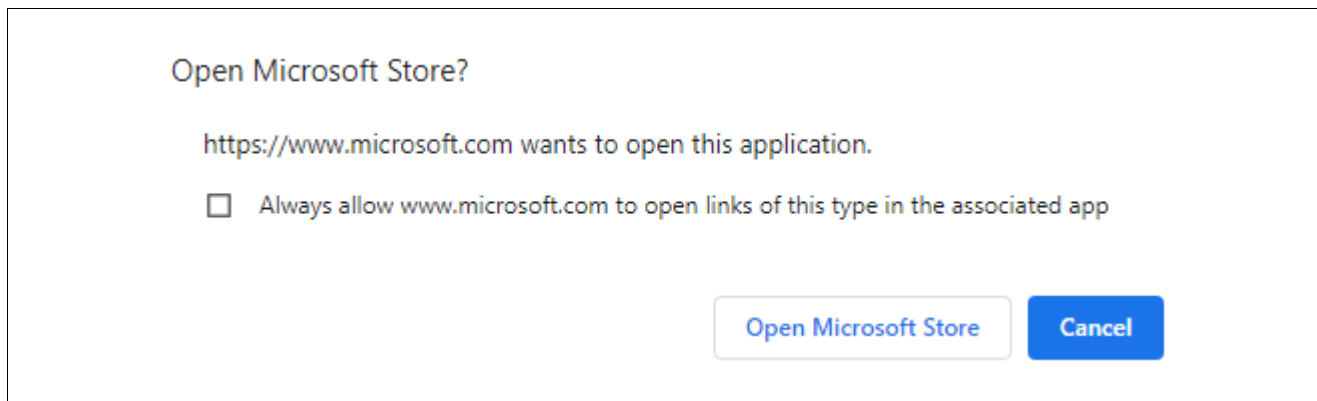


Figure 2. Open Microsoft Store

5. Click **Install** to continue. A window shows up to ask for a Microsoft account, which is seen in the next step.

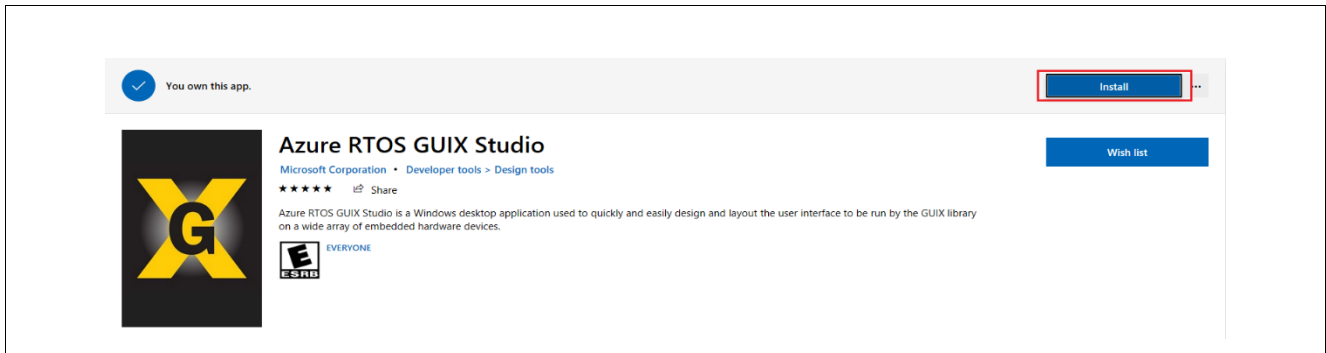


Figure 3. Install

6. Ignore it by clicking **X** on the top-right to close this pop-up window and continue Azure RTOS GUIX studio installation.

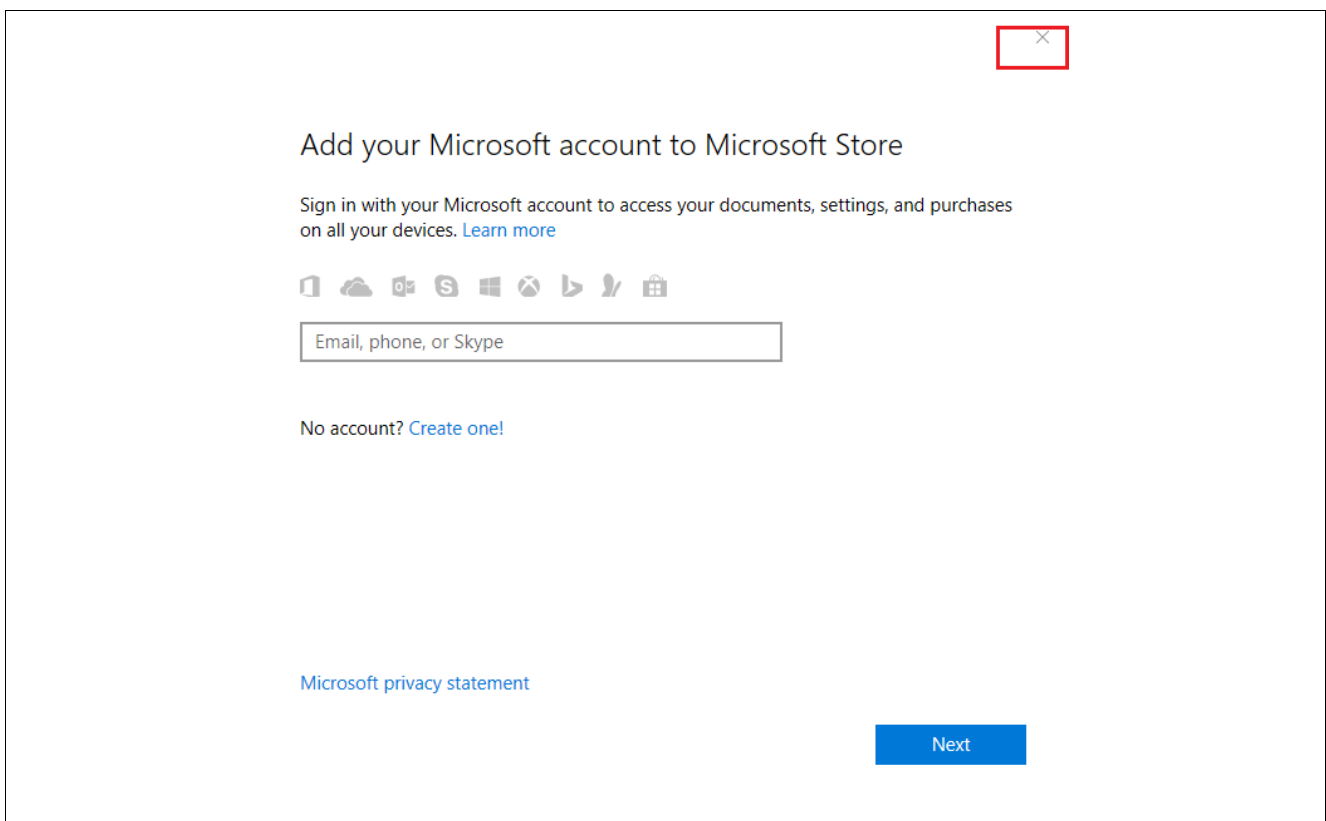


Figure 4. Close Pop-Up

7. It starts downloading and installing Azure RTOS GUIX studio.

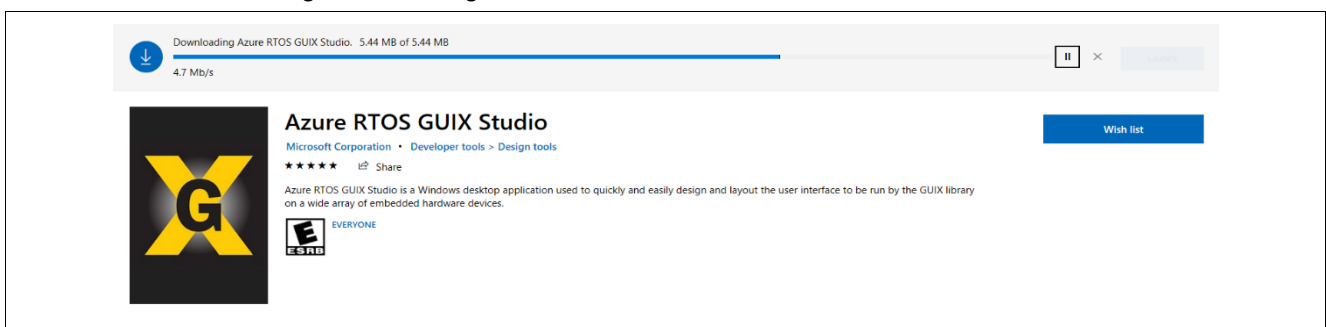


Figure 5. Downloading Azure RTOS GUIX Studio

8. Click **Launch** to launch Azure RTOS GUIX studio.

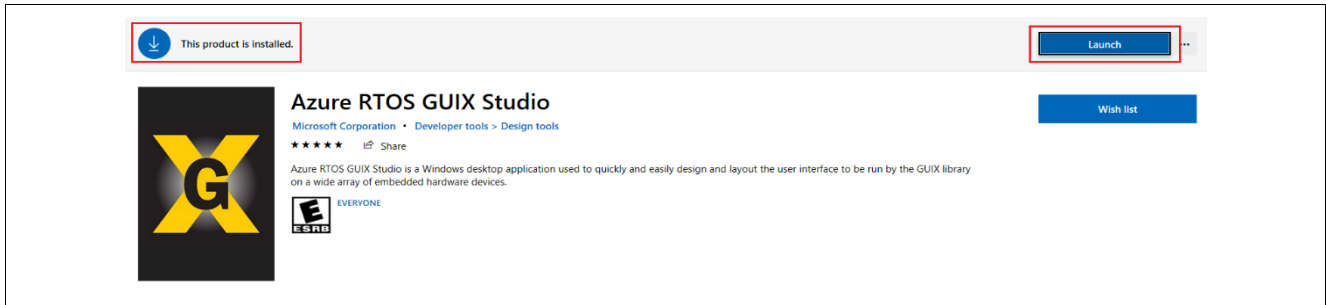


Figure 6. Launching Azure RTOS GUIX Studio

9. Azure RTOS GUIX studio 6.1.7.0 launched.

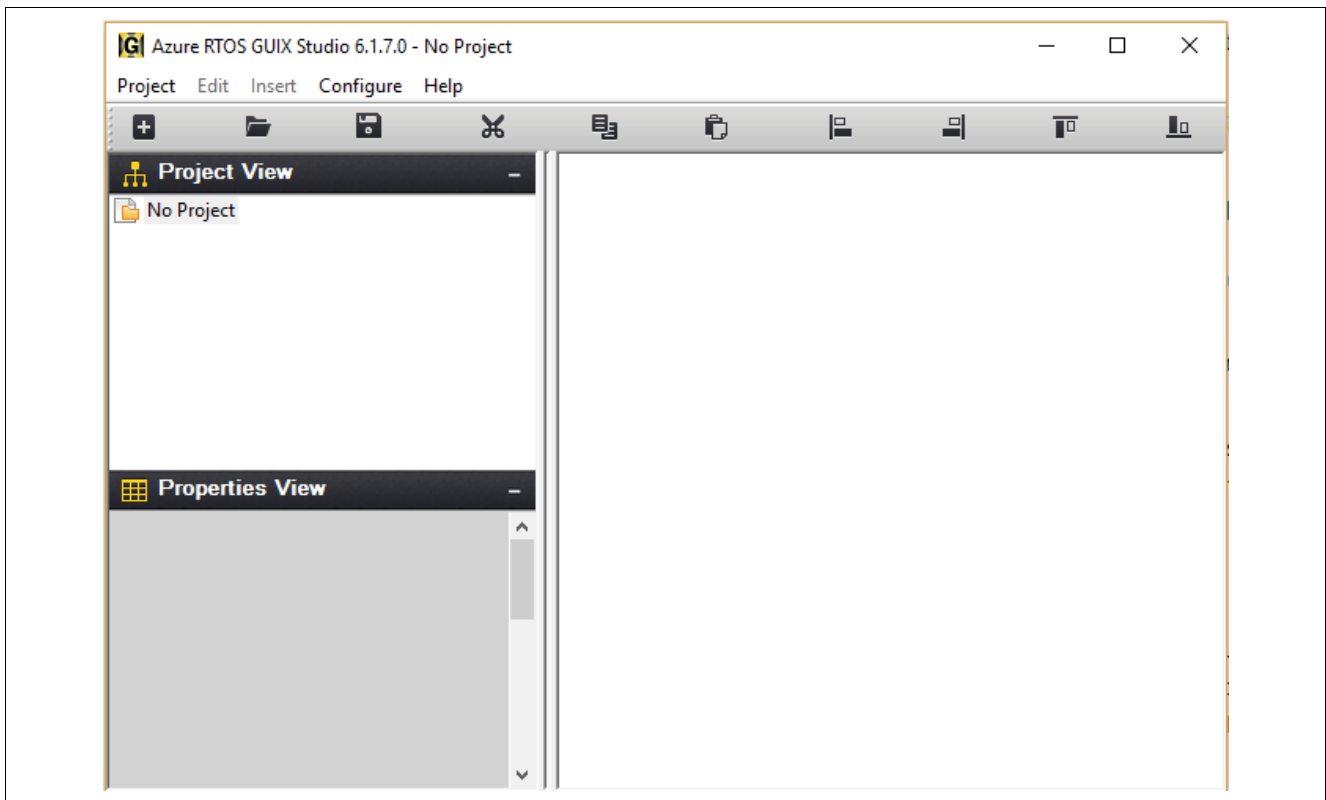


Figure 7. Azure RTOS GUIX Studio

10. Close Azure RTOS GUIX studio, for now, you will open it again later.

2. Create Application Note Project and Enabled Backlight

2.1 Overview

In this section, you will create a project to which you will add pre-written source code and integrate it with a pre-created Azure RTOS GUIX studio project.

2.2 Procedural Steps

1. Create a new **Renesas RA C/C++ project**. Name it **Hello_World_GUIX_EK_RA6M3G**.

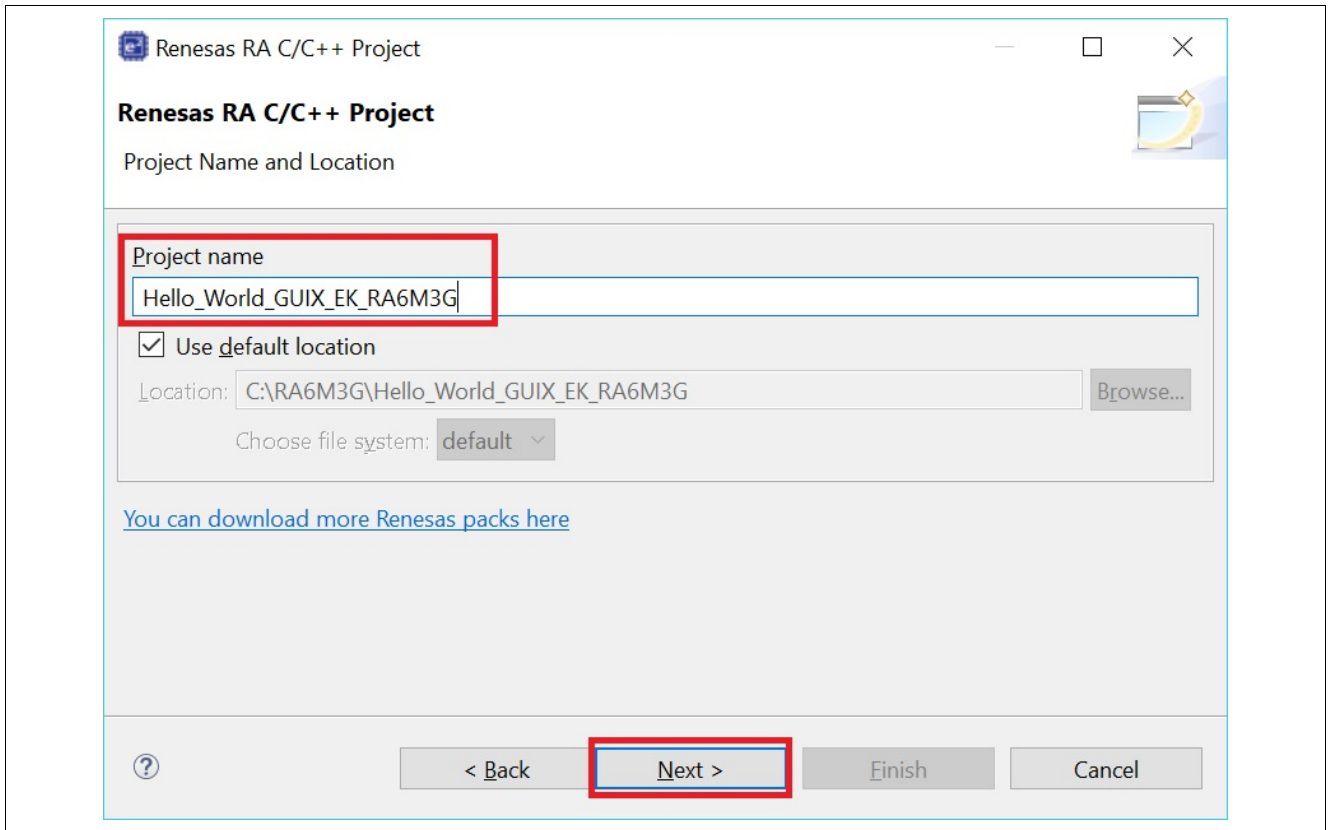


Figure 8. Create New Project

2. Set board to EK-RA6M3.

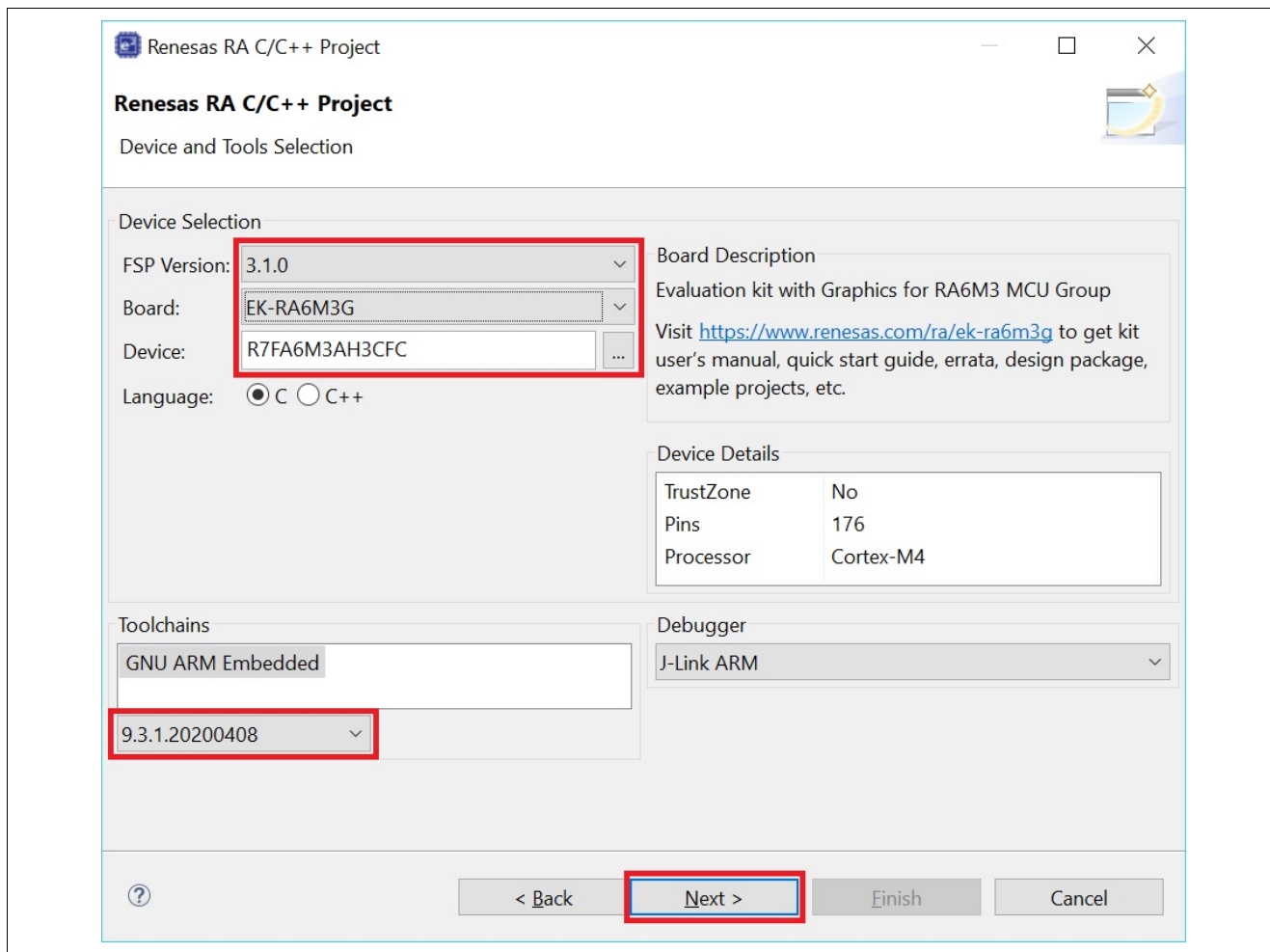


Figure 9. Set Board to EK-RA6M3G

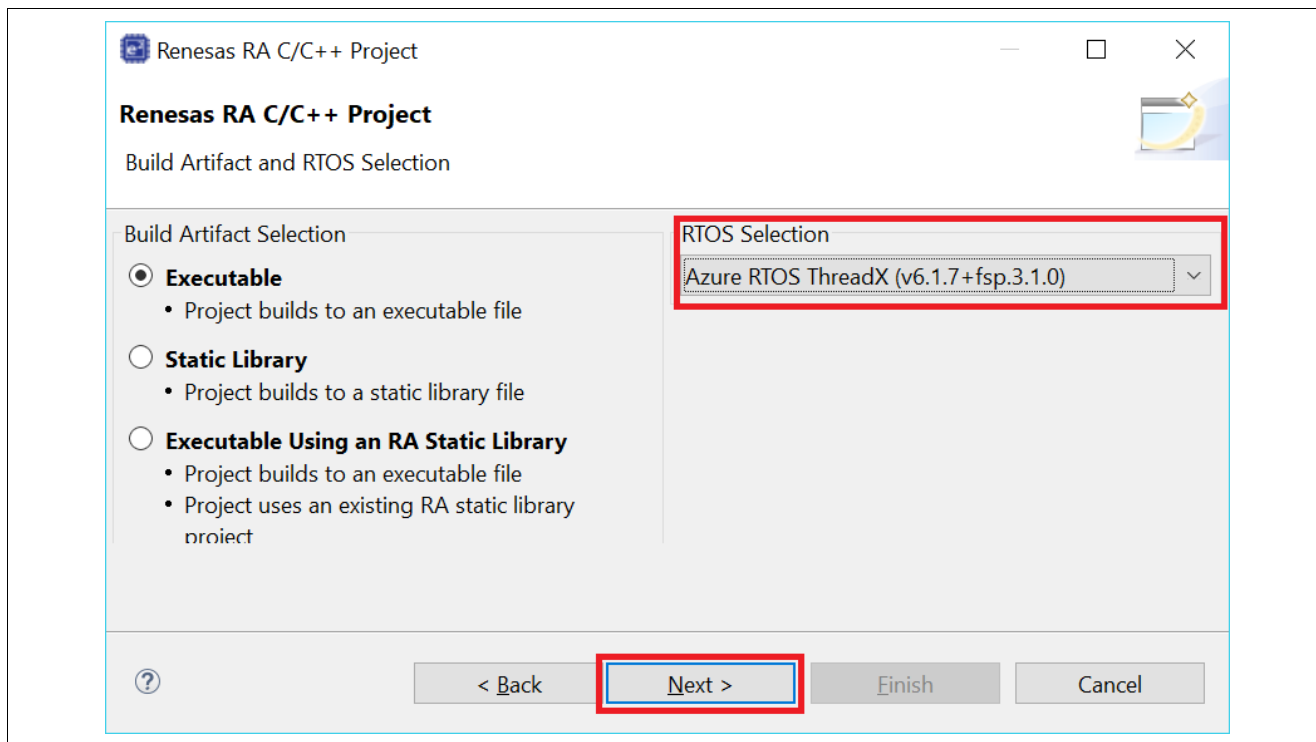
3. Select **Azure RTOS ThreadX (v6.1.8+FSP.3.1.0)**.

Figure 10. Select Azure RTOS ThreadX

4. Use Azure RTOS ThreadX-Minimal template.

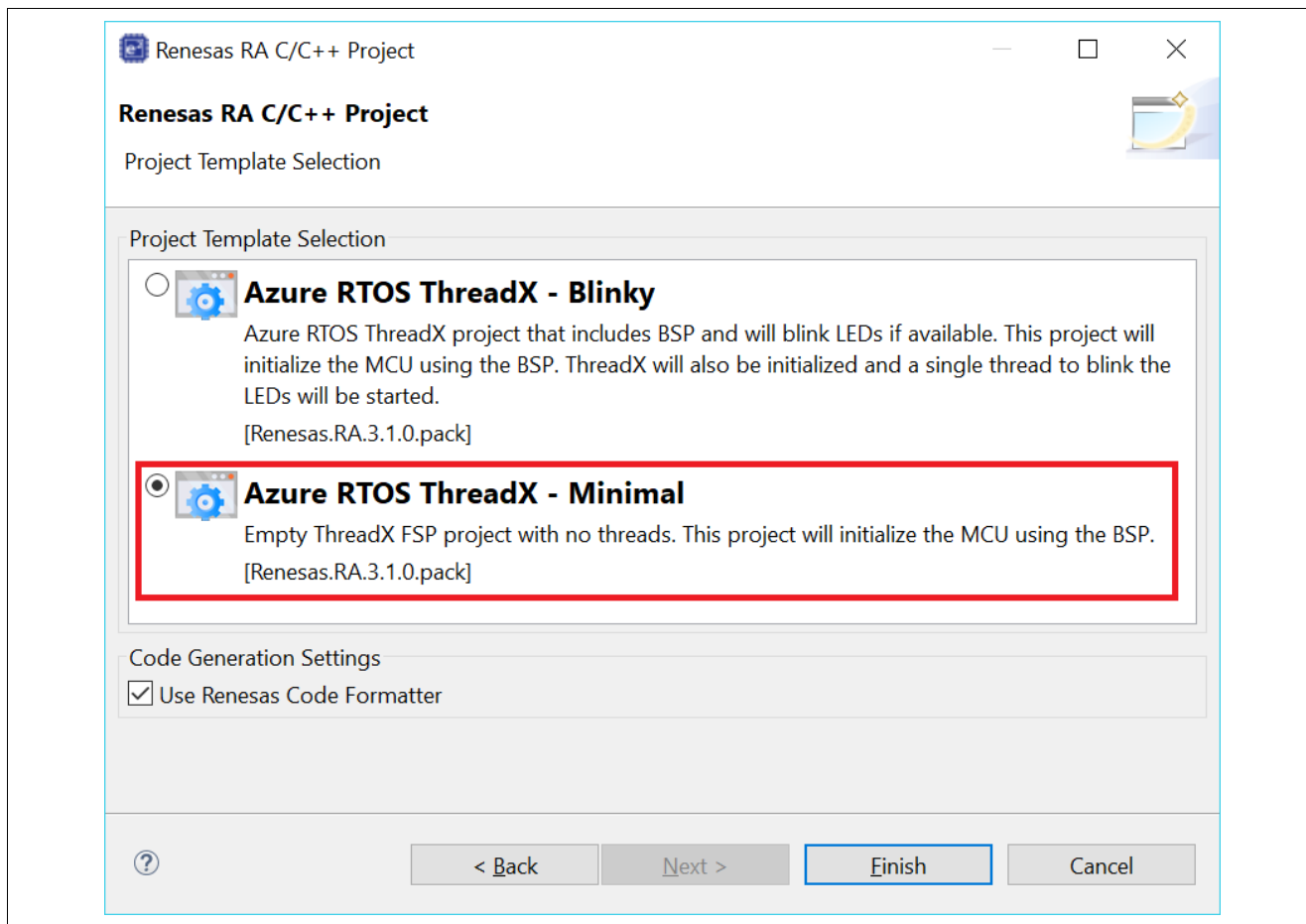


Figure 11. Select Minimal template

5. Open the project configuration and go to the **BSP** tab. Change **Heap size (bytes)** to **0x2000**.

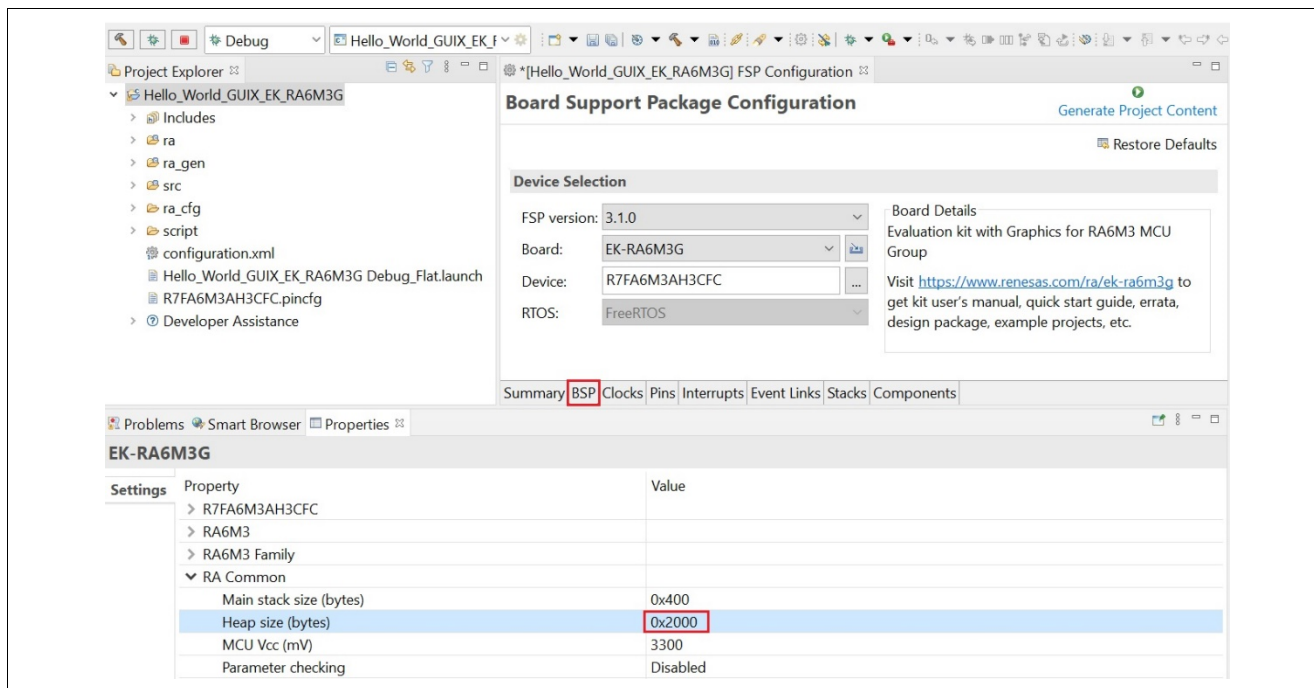


Figure 12. Change Heap Size

6. You can remove **Azure RTOS ThreadX Port** if you want.

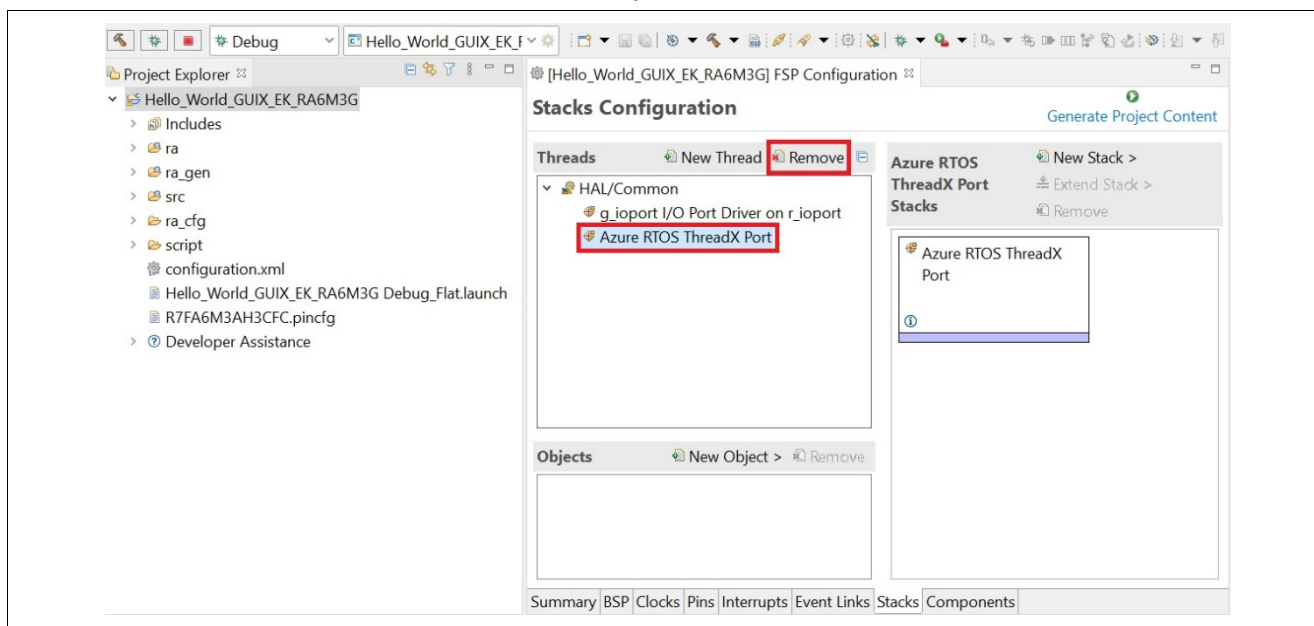


Figure 13. Remove Azure RTOS ThreadX Port

7. Add a **new thread** and name it as **System Thread** with below settings.

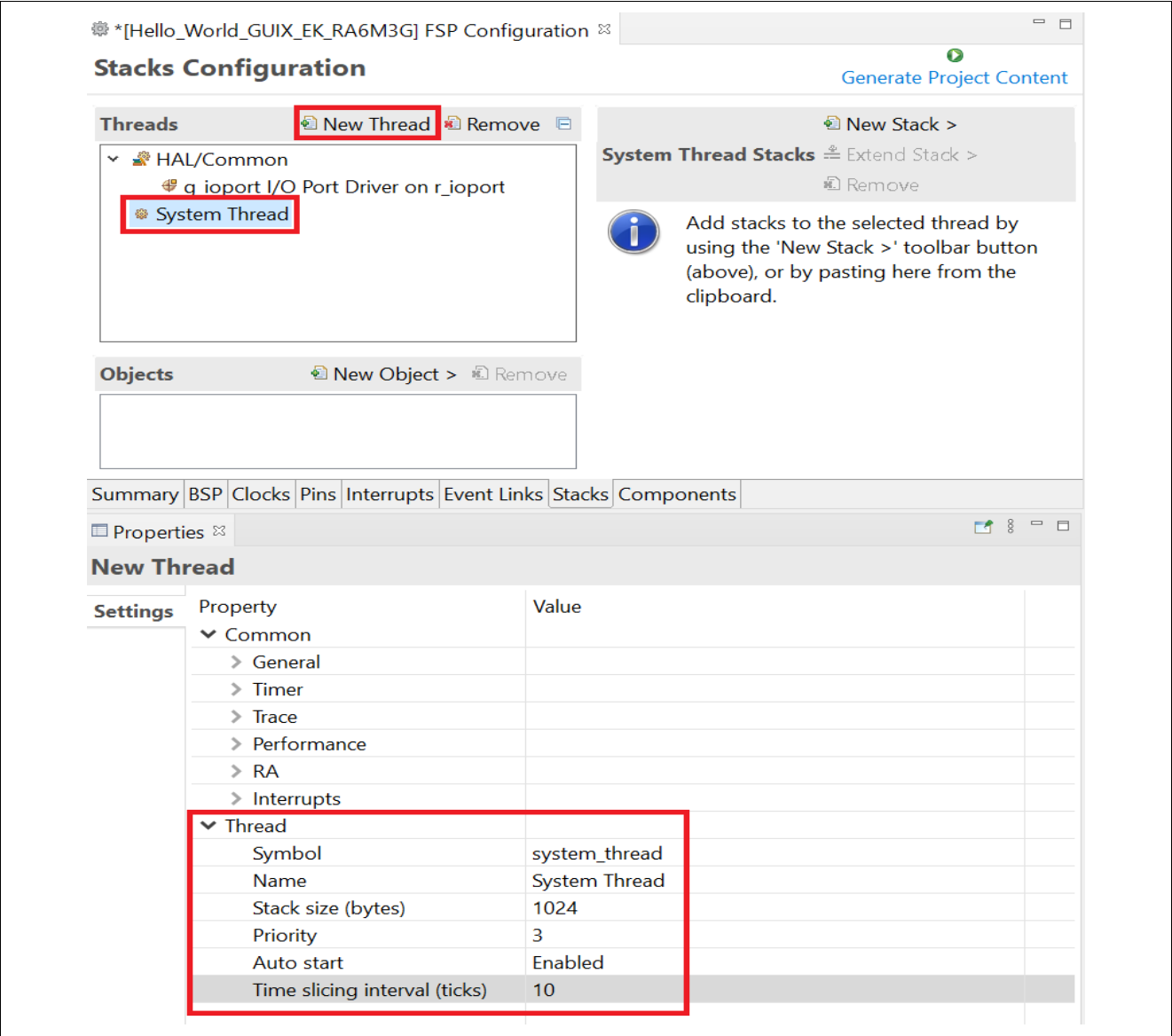


Figure 14. Add System Thread

8. Add Azure RTOS GUIX to system thread.

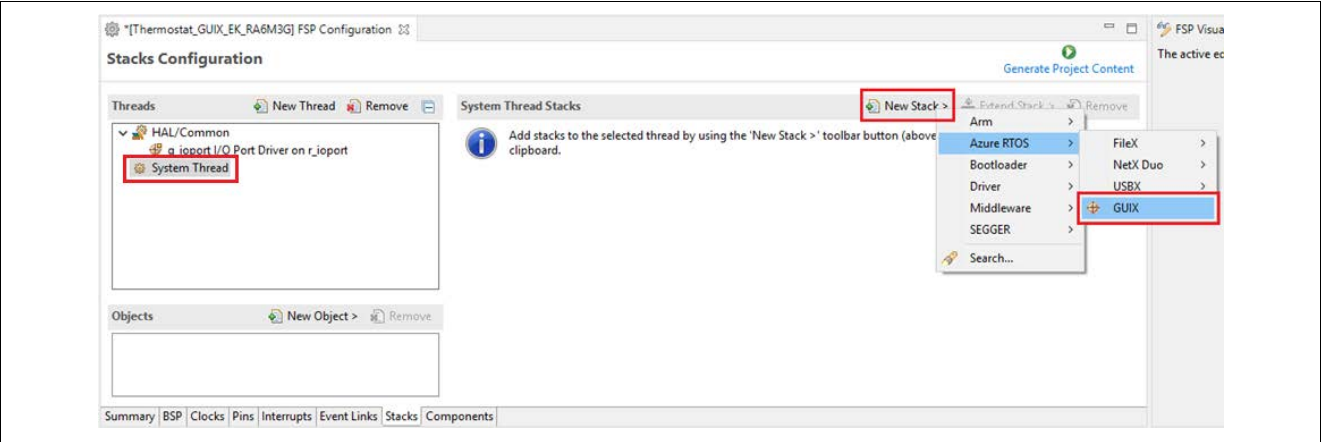


Figure 15. Add Azure RTOS GUIX

9. Add **GUIX** framework for GLCDC configuration.

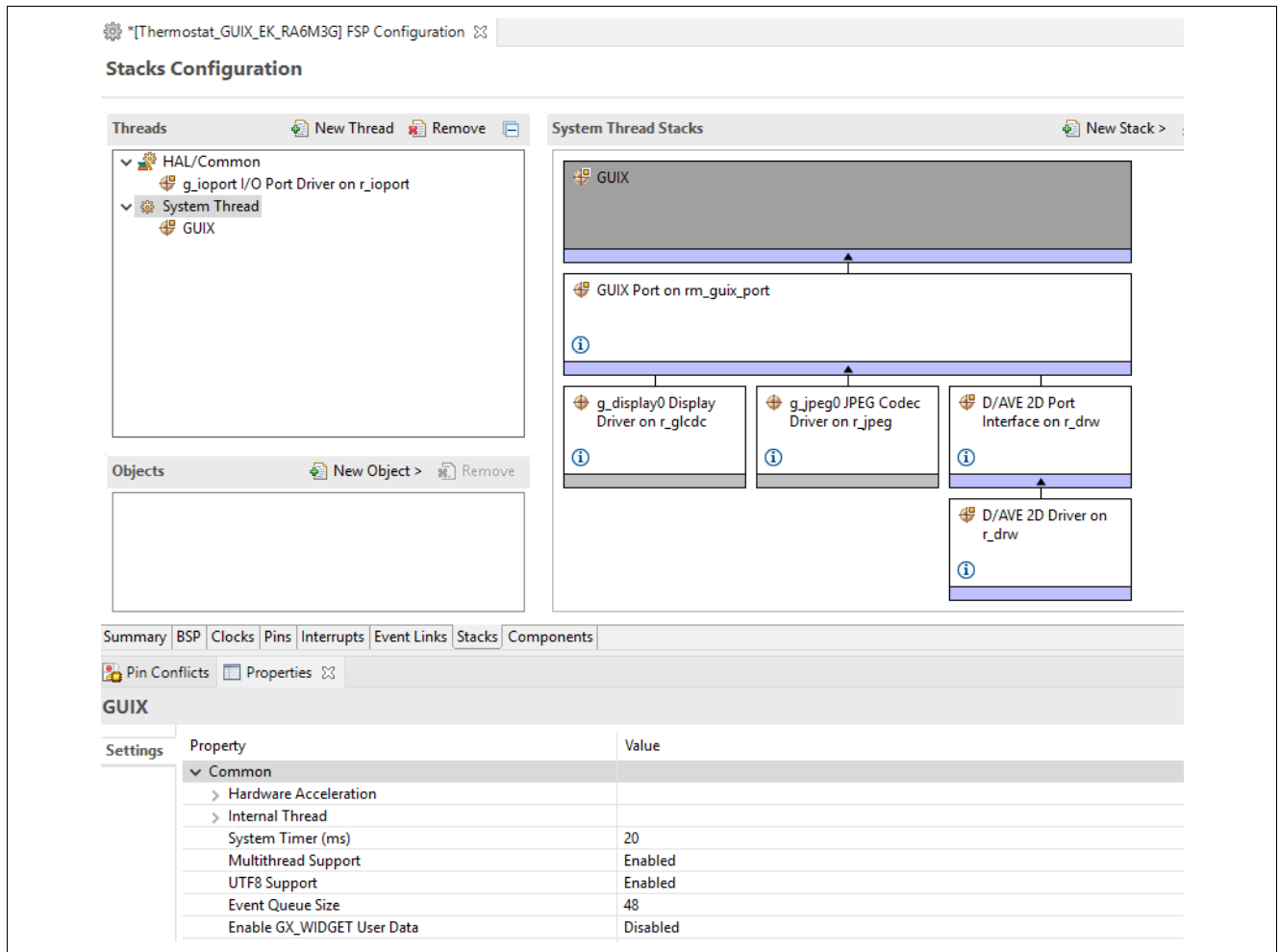


Figure 16. Add GUIX Framework for GLCDC Configuration

10. The **Display Rotation** option is also available for user but in this application, we will not use this option. Skip this setting and keep original setting **None**.

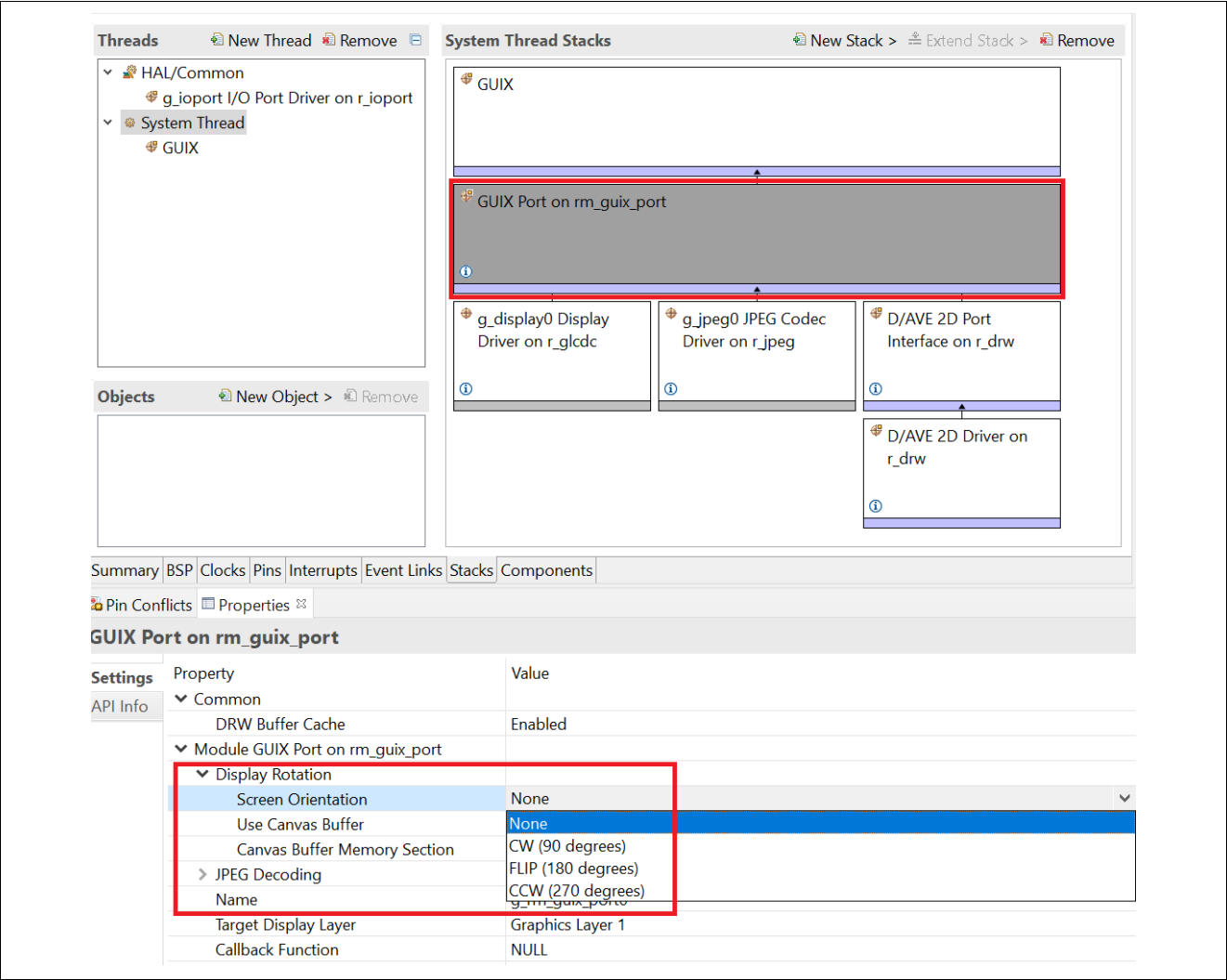


Figure 17. Sreen Orientation

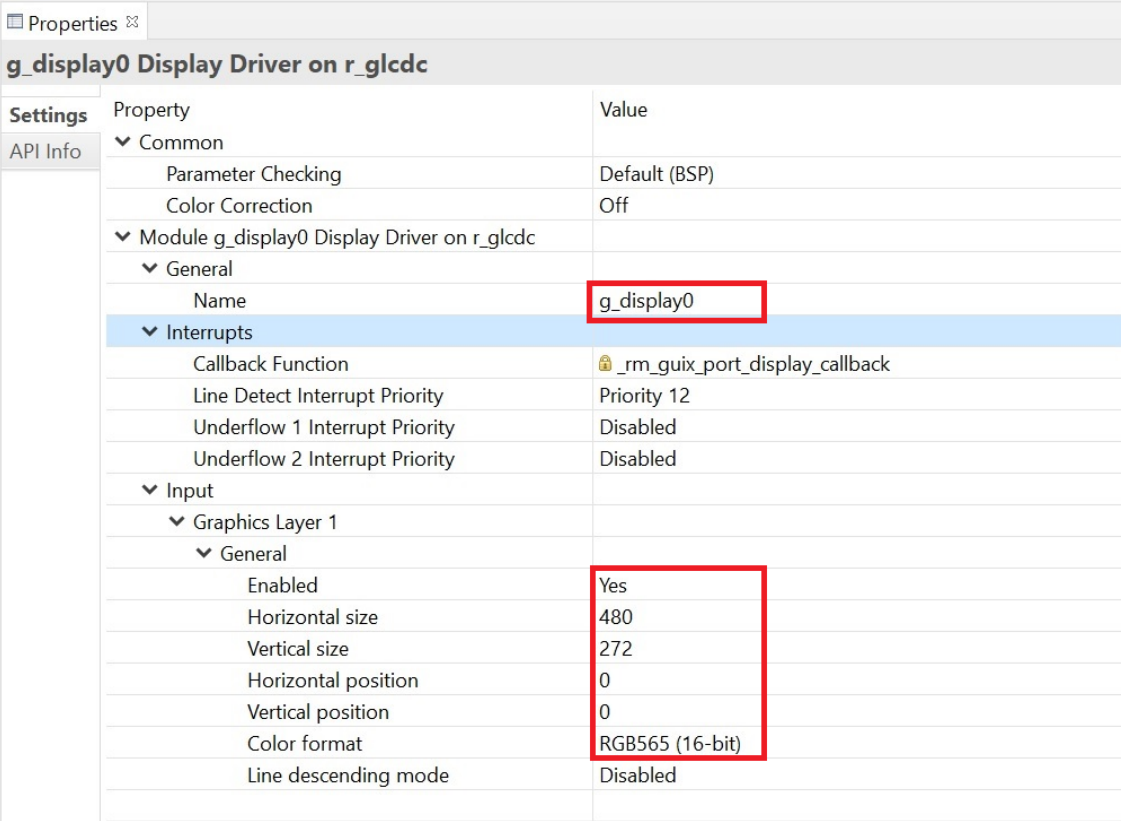
11. Property settings for the **g_display0 Display Driver on r_glcdc**.

The screenshot displays the 'Stacks Configuration' window in the Renesas FSP Configuration tool. The 'GUIX Stacks' section shows a hierarchy of components. The 'g_display0 Display Driver on r_glcdc' component is highlighted with a red box. Below the configuration tree, the 'Settings' tab is open, showing the 'Common' and 'Module g_display0 Display Driver on r_glcdc' sections.

Settings	Property	Value
API Info	Common	
	Parameter Checking	Default (BSP)
	Color Correction	Off
	Module g_display0 Display Driver on r_glcdc	
	> General	
	> Interrupts	
	> Input	
	> Output	
	> CLUT	
	> TCON	
	> Color Correction	
	> Dithering	
	> Pins	

Figure 18. Setting Properties for **g_display0 Display Drive on r_glcdc**

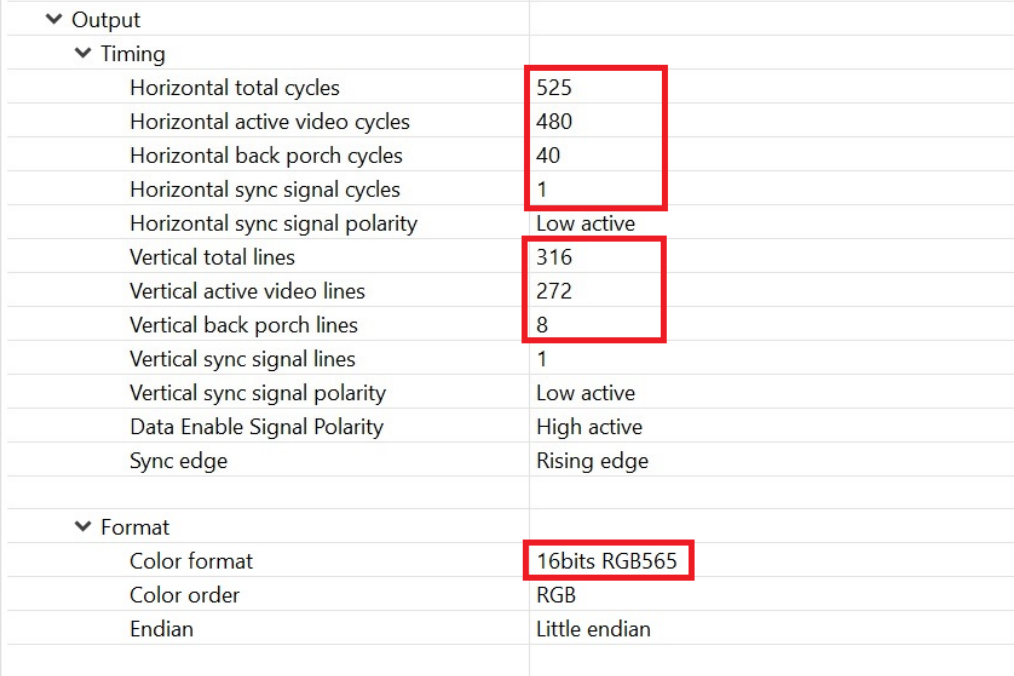
12. Configure the GLCD's **Graphics Layer 1 Properties** as shown.



Property	Value
▼ Common	
Parameter Checking	Default (BSP)
Color Correction	Off
▼ Module g_display0 Display Driver on r_glcdc	
▼ General	
Name	g_display0
▼ Interrupts	
Callback Function	_rm_guix_port_display_callback
Line Detect Interrupt Priority	Priority 12
Underflow 1 Interrupt Priority	Disabled
Underflow 2 Interrupt Priority	Disabled
▼ Input	
▼ Graphics Layer 1	
▼ General	
Enabled	Yes
Horizontal size	480
Vertical size	272
Horizontal position	0
Vertical position	0
Color format	RGB565 (16-bit)
Line descending mode	Disabled

Figure 19. Graphics Layer 1 Properties

13. Configure the **Output** properties as shown.



▼ Output	
▼ Timing	
Horizontal total cycles	525
Horizontal active video cycles	480
Horizontal back porch cycles	40
Horizontal sync signal cycles	1
Horizontal sync signal polarity	Low active
Vertical total lines	316
Vertical active video lines	272
Vertical back porch lines	8
Vertical sync signal lines	1
Vertical sync signal polarity	Low active
Data Enable Signal Polarity	High active
Sync edge	Rising edge
▼ Format	
Color format	16bits RGB565
Color order	RGB
Endian	Little endian

Figure 20. Output Properties

14. Configure the Hsync, Vsync, Data Enable pins, and clock as shown.

▼ TCON	
Hsync pin select	LCD_TCON0
Vsync pin select	LCD_TCON1
Data enable (DE) pin select	LCD_TCON2
Panel clock source	Internal clock (GLCDCLK)
Panel clock division ratio	1/24

Figure 21. TCON Properties

15. In the **Pin Configuration**, first set **Mode** to **Disabled** for the pin P603 to disable LCD panel back light.

*[Hello_World_GUIX_EK_RA6M3G] FSP Configuration

Pin Configuration

Generate Project Content

Select Pin Configuration Export to CSV file Configure Pin Driver Warnings

RA6M3G-EK.pincfg Manage configurations... ☒ Generate data: g_bsp_pin_cfg

Pin Selection

Type filter text

- ▼ P6
 - ✓ P600
 - ✓ P601
 - ✓ P602
 - P603**
 - P604
 - P605
 - P606
 - P607
 - ✓ P608
 - ✓ P609
 - ✓ P610
 - ✓ P611
 - P612
 - ✓ P613
 - ✓ P614
 - P615
- > ✓ P7
- > ✓ P8

Pin Configuration

Cycle Pin Group

Name	Value	Link
Symbolic Name		
Comment		
Mode	Disabled	
Pull up	None	
Drive Capacity	Low	
Output type	CMOS	
▼ Input/Output		
P603	None	→

Module name: P603

Port Capabilities: BUS0: D13_DQ13
GPT7: GTIOCA
SCI9: CTS_RTS_SS

Pin Function Pin Number

Summary BSP Clocks **Pins** Interrupts Event Links Stacks Components

Figure 22. Disable LCD Back light

16. In the **Stacks** tab, select **System Thread** and add in a **New Stack > Driver > Timers > Timer Driver on r_gpt**.

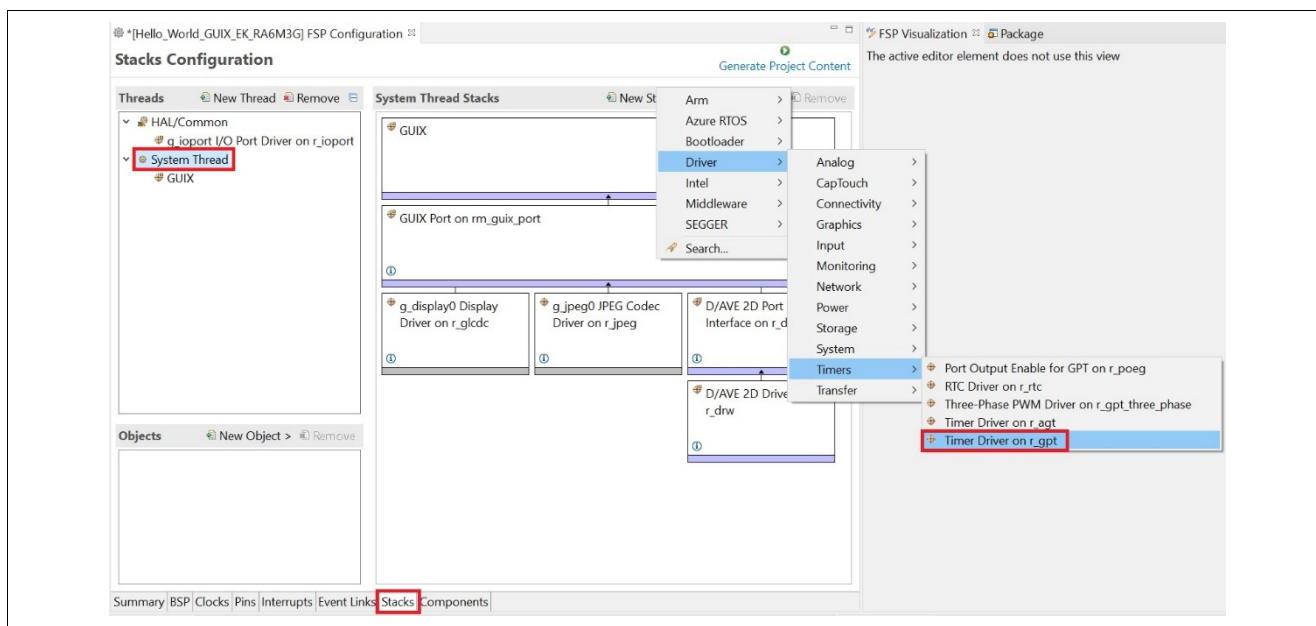


Figure 23. Add Timer Driver on r_gpt

17. Now, set and configure the properties of **Timer Driver on r_gpt**. Select **GTIOCA Output Enable**. Select **GTIOCA** and hit the arrow => for selecting and setting properties of the pin P603 (follow the images below).

The screenshot displays the GUIX configuration tool for the project "[Hello_World_GUIX_EK_RA6M3G] FSP Configuration". The "Stacks Configuration" window is open, showing the "g_timer_PWM Timer Driver on r_gpt" stack. The "Properties" window is also open, showing the settings for the "g_timer_PWM Timer Driver on r_gpt".

The "Properties" window is divided into two tabs: "Settings" and "API Info". The "Settings" tab is active, showing a list of properties and their values. A red box highlights the "GTIOCA Output Enabled" property, which is set to "True".

Property	Value
Parameter Checking	Default (BSP)
Pin Output Support	Enabled
Write Protect Enable	Disabled
Module g_timer_PWM Timer Driver on r_gpt	
General	
Name	g_timer_PWM
Channel	7
Mode	PWM
Period	50000
Period Unit	Nanoseconds
Output	
Custom Waveform	
Duty Cycle Percent (only applicable in PWM mode)	100
GTIOCA Output Enabled	True
GTIOCA Stop Level	Pin Level Low
GTIOCB Output Enabled	False
GTIOCB Stop Level	Pin Level Low
Input	
Interrupts	
Extra Features	
Pins	
GTIOCA	<unavailable>
GTIOCB	<unavailable>

Figure 24. Properties of Timer Driver on r_gpt

18. Set and configure the pin P603 for the LCD_BLEN signal of the LCD panel.

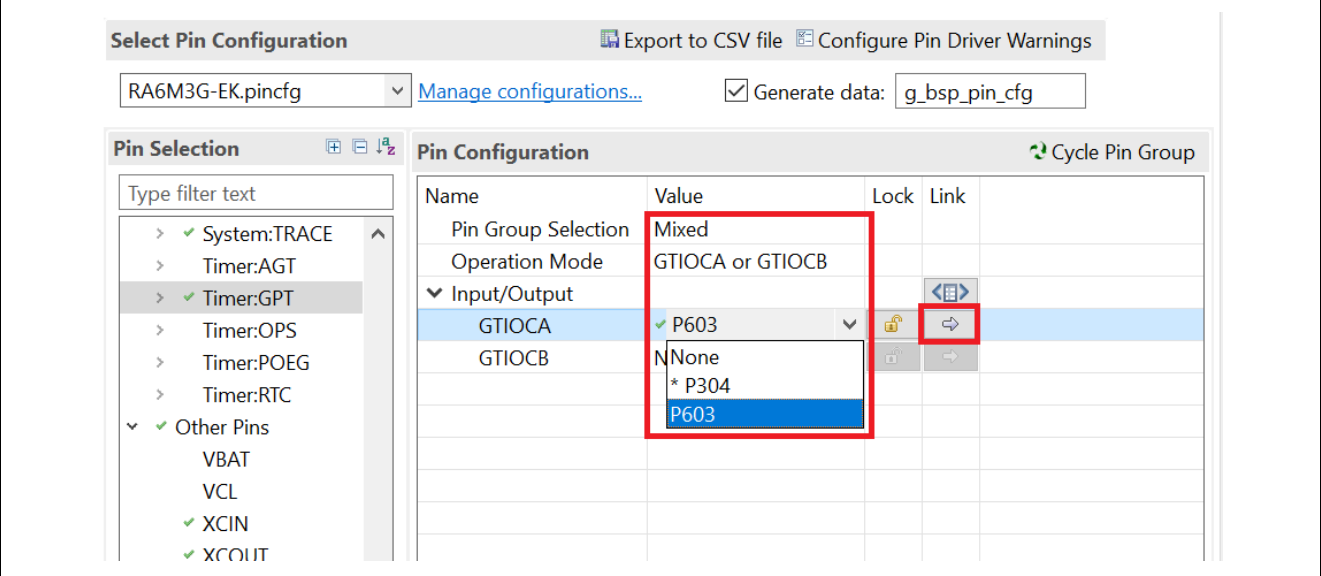


Figure 25. P603 Properties

19. After that you can hit the => sign to see the pin P603 settings.

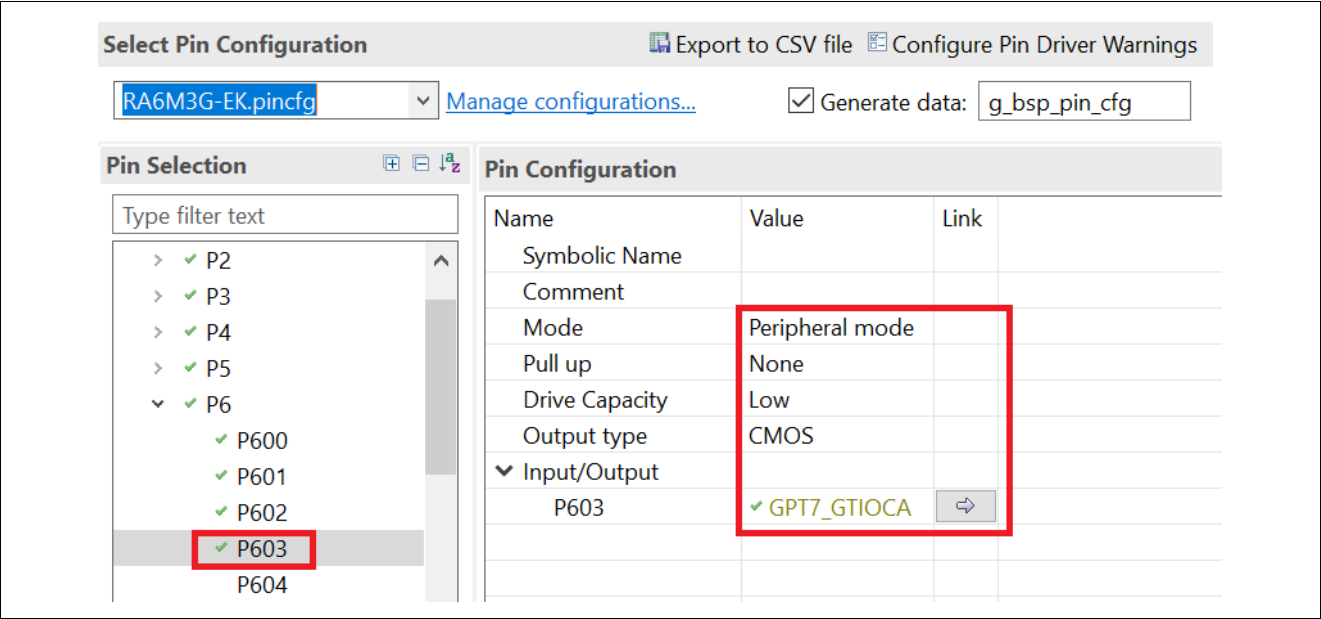


Figure 26. P603 Settings

20. Figure 27 is a schematic of the LCD_BLEN signal.

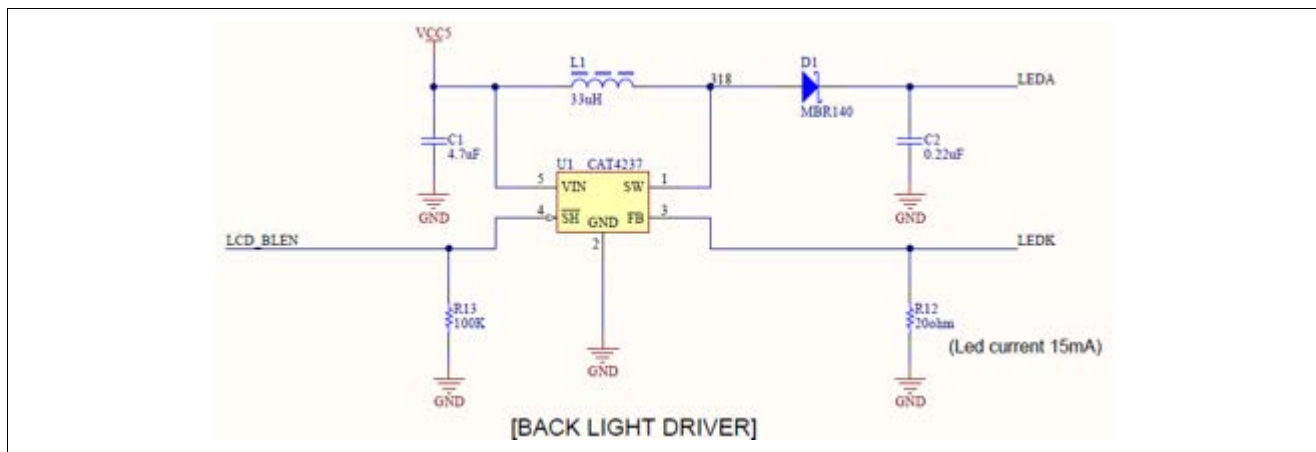


Figure 27. LCD_BLEN Schematic

21. Refer to "system_thread_entry.c" file in "Source.zip" for more information. This function below controls the PWM output.

```

/*****
 * @brief This function is setting up GPT/PWM timer
 * @param[in] None
 * @retval fsp_err_t
 *****/
static fsp_err_t gpt_timer_PWM_setup(void)
{
    fsp_err_t err = FSP_SUCCESS;
    /* Open GPT */
    err = R_GPT_Open(&g_timer_PWM_ctrl, &g_timer_PWM_cfg);
    if(FSP_SUCCESS != err)
    {
        return err;
    }
    /* Enable GPT Timer */
    err = R_GPT_Enable(&g_timer_PWM_ctrl);
    /* Handle error */
    if (FSP_SUCCESS != err)
    {
        return err;
    }
    /* Start GPT timer */
    err = R_GPT_Start(&g_timer_PWM_ctrl);
    if(FSP_SUCCESS != err)
    {
        return err;
    }
    return err;
}

```

3. Add and Configure “Touch Function Driver”

- 1. Add a **New Thread** and name it **Touch Thread** with the setting below.

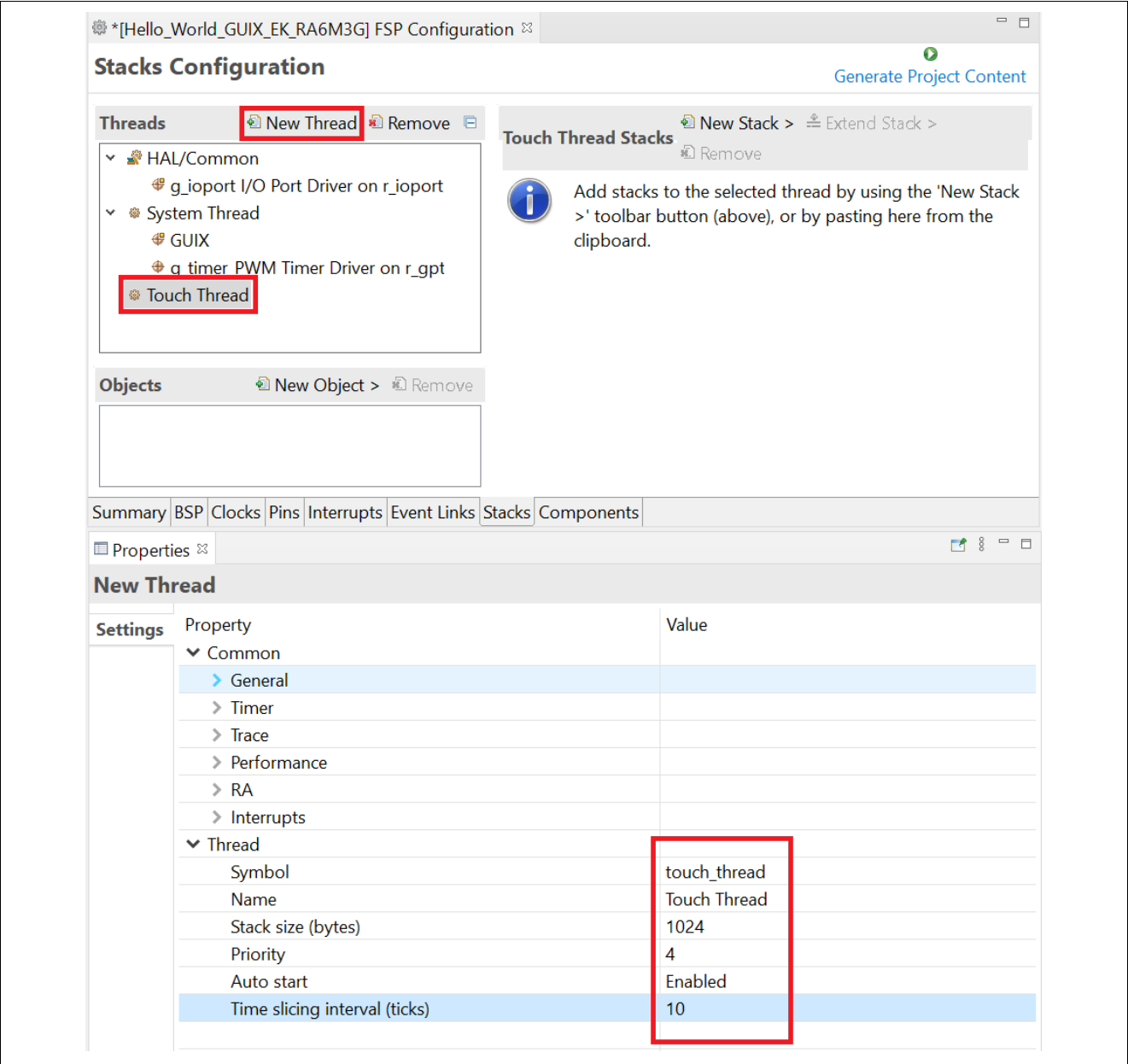


Figure 28. Create Touch Thread

2. Select **Touch Thread** and add new stack **External IRQ Driver on r_icu**. **New Stack > Driver > Input > External IRQ Driver on r_icu**.

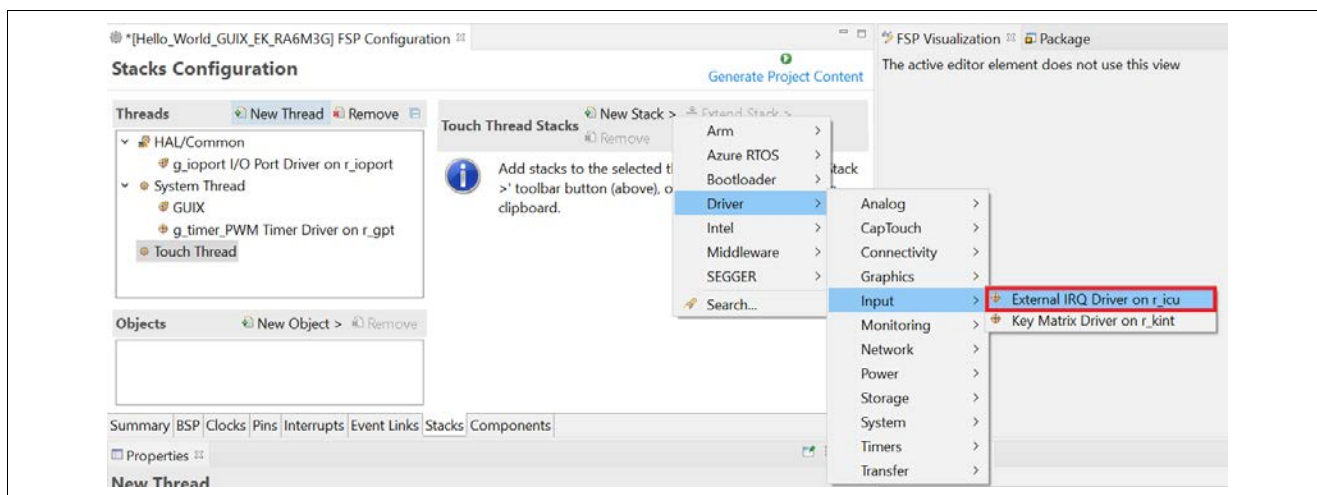


Figure 29. Add External IRQ Driver on r_icu

3. User should disable the pin P206 before we move to the next step. Click the **Pins** tab and follow the image below.

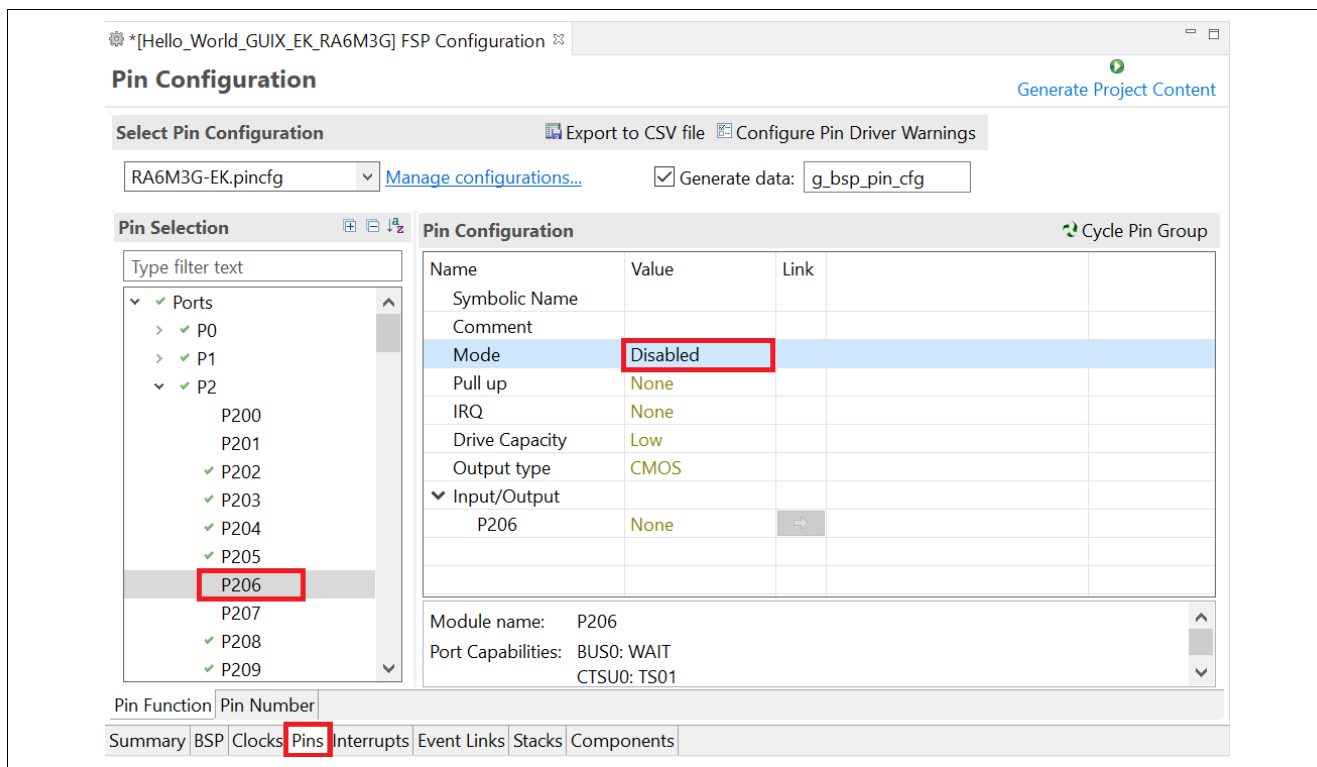


Figure 30. Disable Pin P206

4. Setting the properties for the **External IRQ Driver** on **r_icu**.

***[Hello_World_GUIX_EK_RA6M3G] FSP Configuration**

Stacks Configuration

[Generate Project Content](#)

Threads

- New Thread Remove
- HAL/Common
 - g_ioport I/O Port Driver on r_ioport
- System Thread
 - GUIX
 - g_timer_PWM Timer Driver on r_gpt
- Touch Thread
 - g_touch_irq External IRQ Driver on r_icu**

Objects

- New Object > Remove

g_external_irq0 External IRQ Driver on r_icu Stacks

- New Stack >
- Extend Stack >
- Remove

g_touch_irq External IRQ Driver on r_icu
 ⓘ

Summary BSP Clocks Pins Interrupts Event Links **Stacks** Components

Properties ⓘ

g_touch_irq External IRQ Driver on r_icu

Settings	Property	Value
API Info	▼ Common	
	Parameter Checking	Default (BSP)
	▼ Module g_touch_irq External IRQ Driver on r_icu	
	Name	g_touch_irq
	Channel	0
	Trigger	Falling
	Digital Filtering	Enabled
	Digital Filtering Sample Clock (Only valid when Digital Filtering is Enabled)	PCLK / 64
	Callback	touch_irq_cb
	Pin Interrupt Priority	Priority 5
	▼ Pins	
	IRQ00	P206

Figure 31. Set Properties for External IRQ Driver on r_icu

5. The External Touch IRQ Driver on r_icu will use pin P206. Be sure this pin configuration is set as shown below.

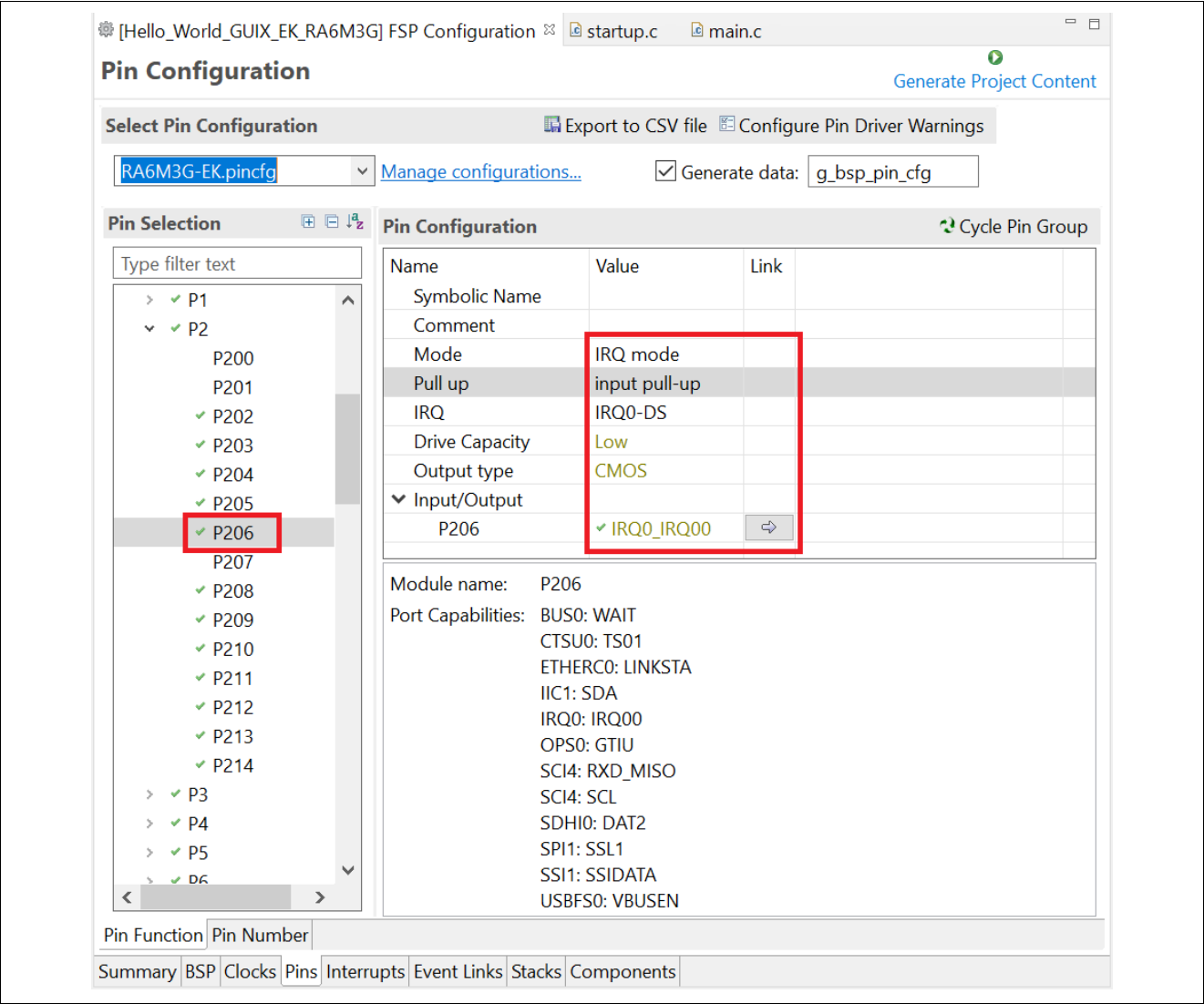


Figure 32. Configure Pin P206

6. Select **Touch Thread** and add a new stack. **New Stack > Driver > Connectivity > I2C Master Driver on r_iic_master** on **r_iic_master**.

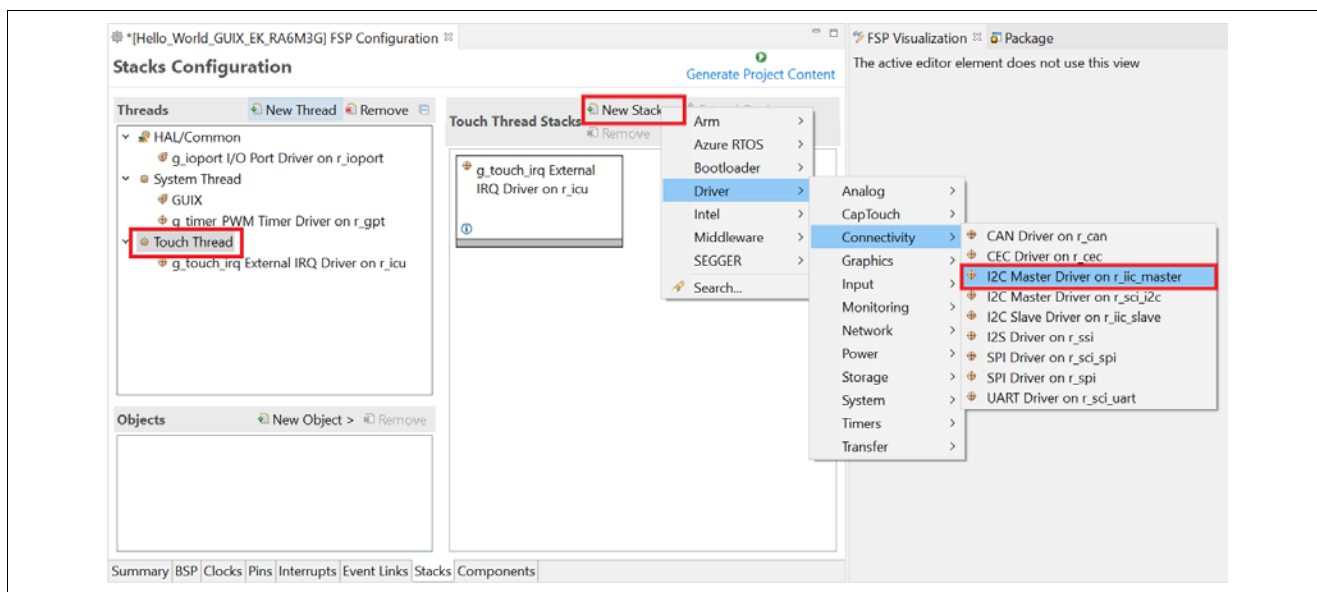


Figure 33. Add I2C Master Driver on r_iic_master

7. Setting the properties for **g_i2c_touch I2C Master Driver on r_iic_master**.

The screenshot displays the FSP Configuration GUI for the project ***[Hello_World_GUIX_EK_RA6M3G]**. The **Threads** list on the left includes HAL/Common, System Thread, and Touch Thread. Under the Touch Thread, the **g_i2c_touch I2C Master Driver on r_iic_master** is selected. The **Stacks Configuration** panel on the right shows the stack **g_i2c_master0 I2C Master Driver on r_iic_master** with the selected driver as a sub-stack. The **Properties** panel at the bottom shows the settings for the selected driver, with a red box highlighting the **DTC on Transmission and Reception** and **Pins** sections.

Property	Value
Parameter Checking	Default (BSP)
DTC on Transmission and Reception	Enabled
10-bit slave addressing	Disabled
Module g_i2c_touch I2C Master Driver on r_iic_master	
Name	g_i2c_touch
Channel	2
Rate	Fast-mode
Rise Time (ns)	120
Fall Time (ns)	120
Duty Cycle (%)	50
Slave Address	0x38
Address Mode	7-Bit
Timeout Mode	Short Mode
Callback	touch_i2c_callback
Interrupt Priority Level	Priority 6
Pins	
SDA	P511
SCL	P512

Figure 34. Set Properties for **g_i2c_touch I2C Master Driver on r_iic_master**

8. Under **g_i2c_touch I2C Master Driver on r_iic_master** add in **Add DTC Driver for Transmission**. Also, set properties for **Add DTC Driver for Transmission**.

The screenshot displays the FSP Configuration tool interface. The top section, 'Stacks Configuration', includes a 'Threads' list on the left and a 'Stacks' list on the right. In the 'Threads' list, 'g_i2c_touch I2C Master Driver on r_iic_master' is highlighted with a red box. In the 'Stacks' list, 'g_i2c_master0 I2C Master Driver on r_iic_master Stacks' is expanded, showing 'g_i2c_touch I2C Master Driver on r_iic_master'. Below this, two buttons are visible: 'Add DTC Driver for Transmission [Optional]' and 'Add DTC Driver for Reception [Optional]'. The 'Add DTC Driver for Transmission [Optional]' button is highlighted with a red box, and a 'New' button is also highlighted. The bottom section, 'Properties', shows the configuration for 'g_transfer0 Transfer Driver on r_dtc IIC2 TXI (Transmit data empty)'. The 'Name' property is set to 'g_transfer2', which is highlighted with a red box.

Threads

- HAL/Common
 - g_ioport I/O Port Driver on r_ioport
- System Thread
 - GUIX
 - g_timer_PWM Timer Driver on r_gpt
- Touch Thread
 - g_touch_irq External IRQ Driver on r_icu
 - g_i2c_touch I2C Master Driver on r_iic_master**

Objects

Stacks Configuration

g_i2c_master0 I2C Master Driver on r_iic_master Stacks

- g_i2c_touch I2C Master Driver on r_iic_master

Add DTC Driver for Transmission [Optional]

Add DTC Driver for Reception [Optional]

New

Transfer Driver on r_dtc

Properties

g_transfer0 Transfer Driver on r_dtc IIC2 TXI (Transmit data empty)

Settings	Property	Value
API Info	Common	
	Parameter Checking	Default (BSP)
	Linker section to keep DTC vector table	.fsp_dtc_vector_table
	Module g_transfer0 Transfer Driver on r_dtc IIC2 TXI (Transmit data empty)	
	Name	g_transfer2
	Mode	Normal
	Transfer Size	1 Byte
	Destination Address Mode	Fixed
	Source Address Mode	Incremented
	Repeat Area (Unused in Normal Mode)	Source
	Interrupt Frequency	After all transfers have completed
	Number of Transfers	0
Number of Blocks (Valid only in Block Mode)	0	
Activation Source	IIC2 TXI (Transmit data empty)	

Figure 35. Add DTC Driver for Transmission

9. Add in **Add DTC Driver for Reception**. Then set properties for **Add DTC Driver for Reception**.

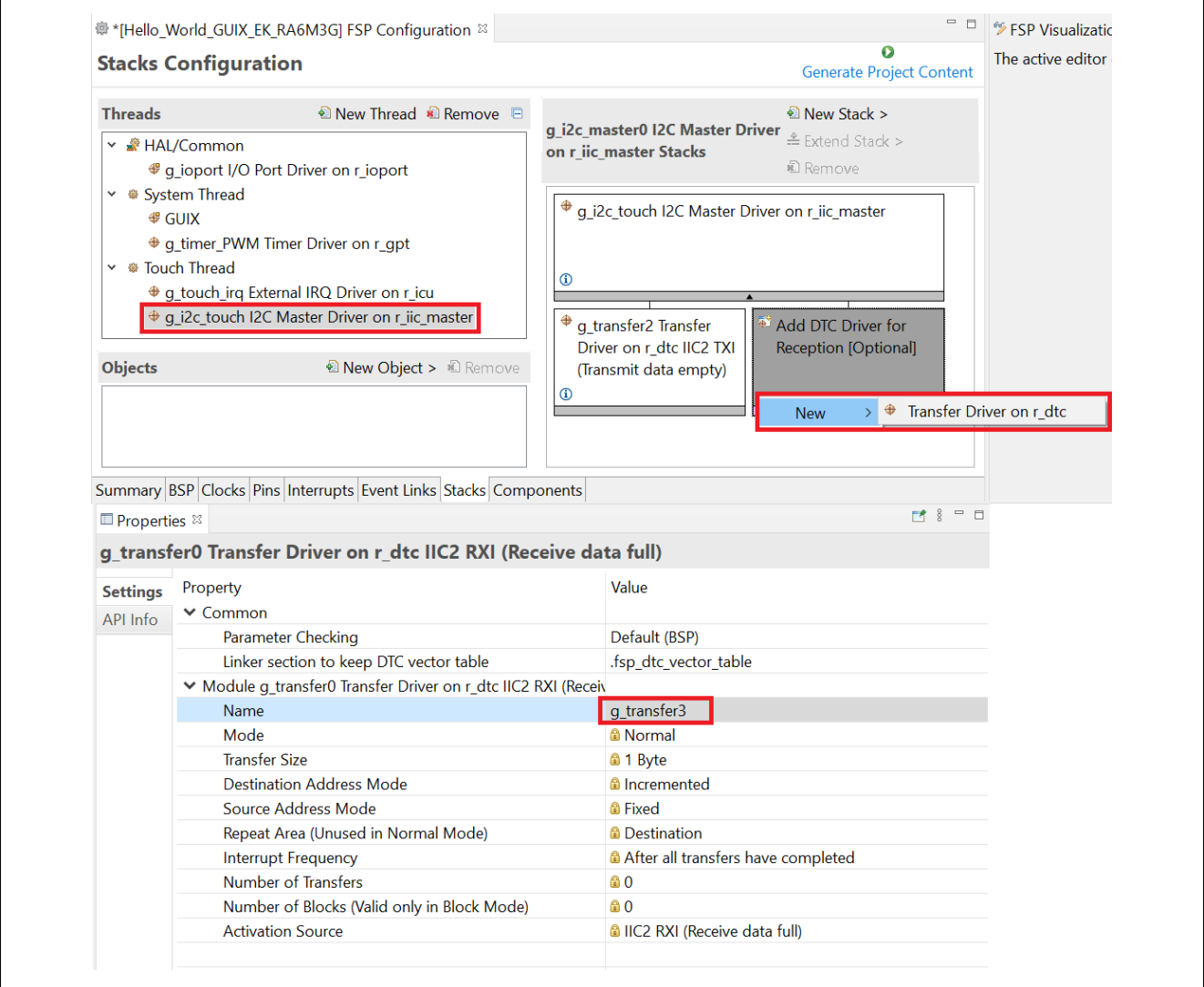


Figure 36. Add DTC Driver for Reception

10. After adding transmission and reception, the configuration looks like below.

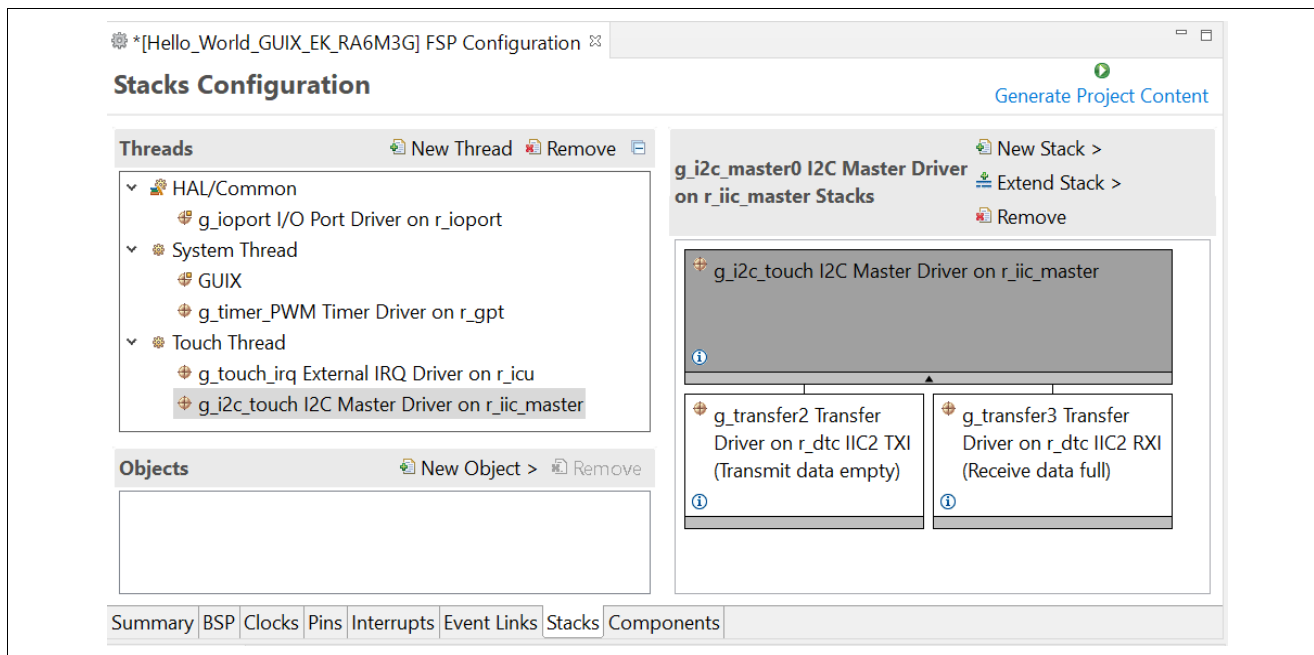


Figure 37. Configuration for Transmission and Reception

11. From the **Objects** window, click on **New Object** and select **Semaphore**. Then set **g_touch_semaphore Semaphore** properties.

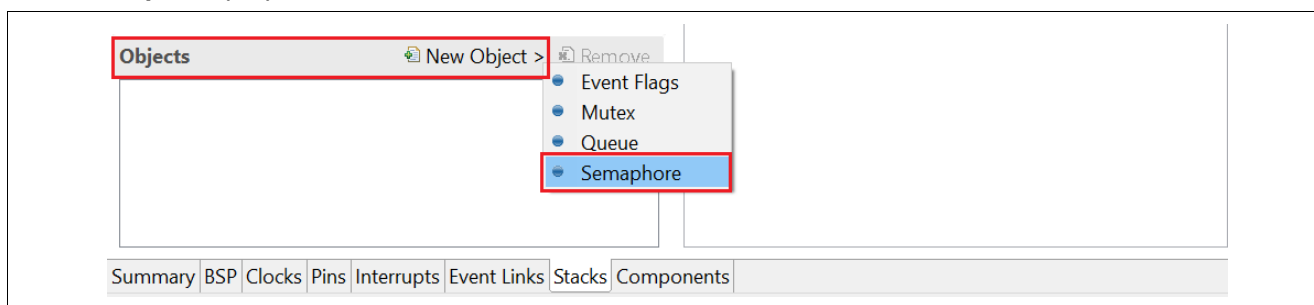


Figure 38. Add Semaphore

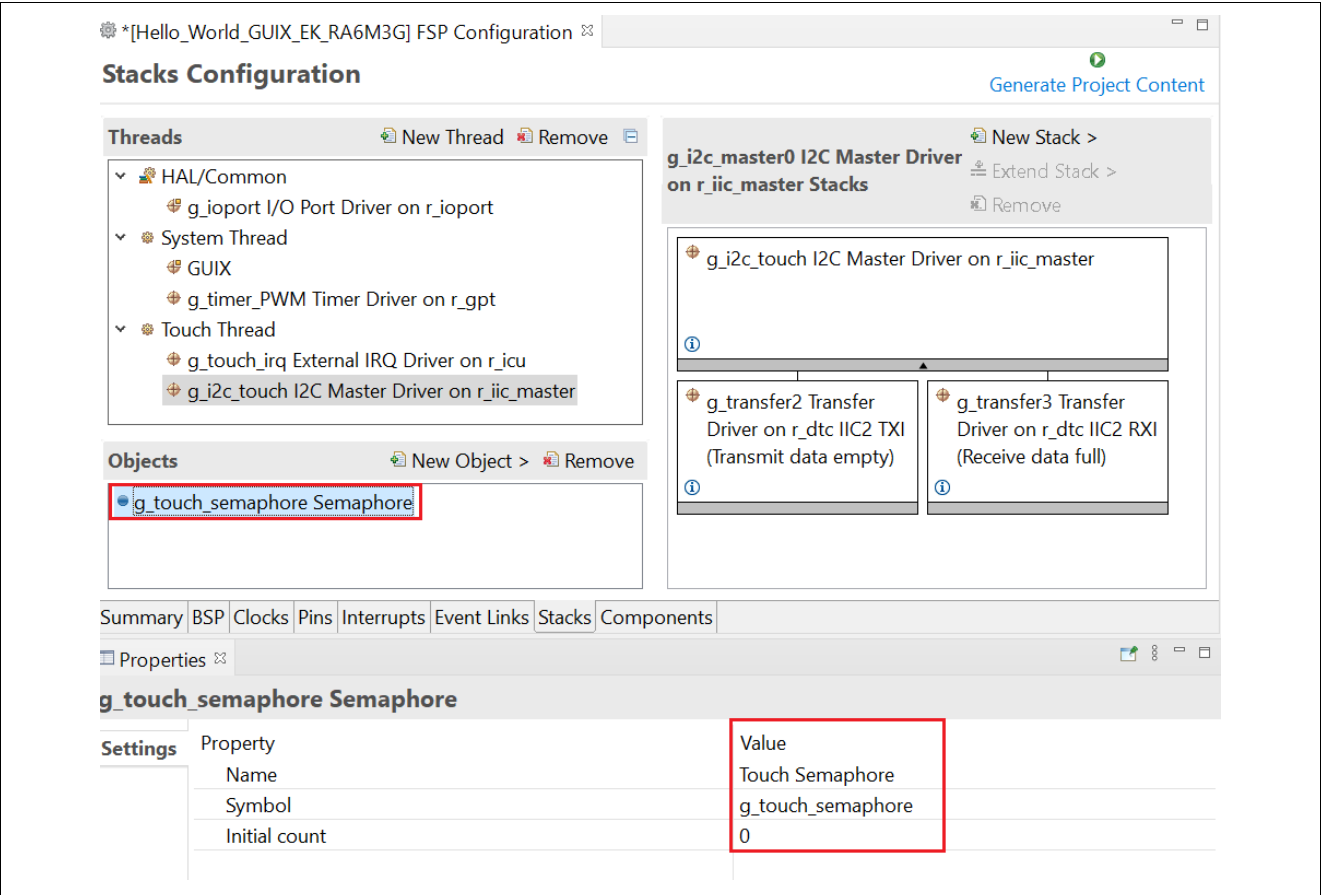


Figure 39. Set g_touch_semaphore Semaphore Properties

12. Again, from the **Objects** window. Click on **New Object** and select **Semaphore**. Then set **g_i2c_semaphore** Semaphore properties.

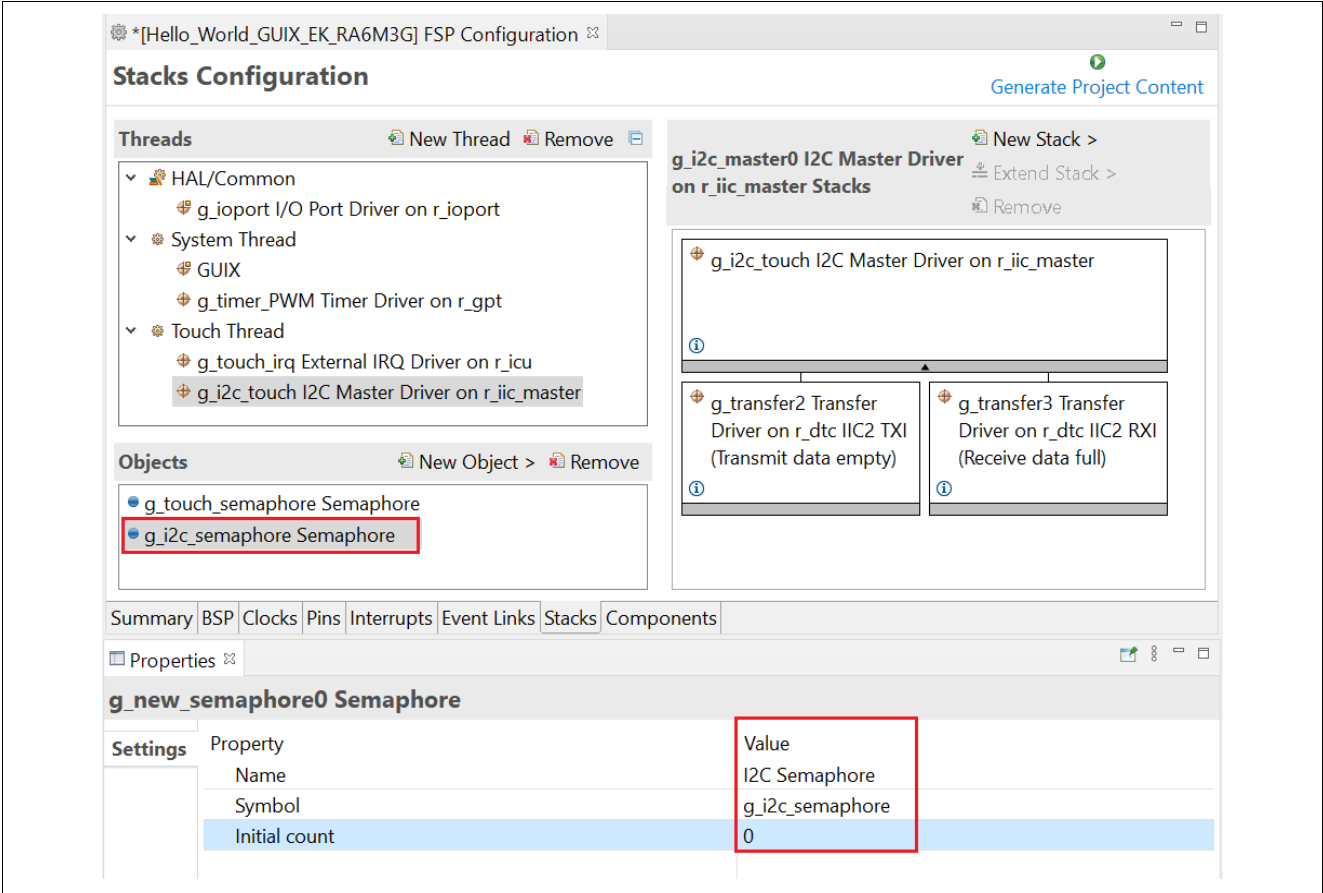


Figure 40. Add Semaphore

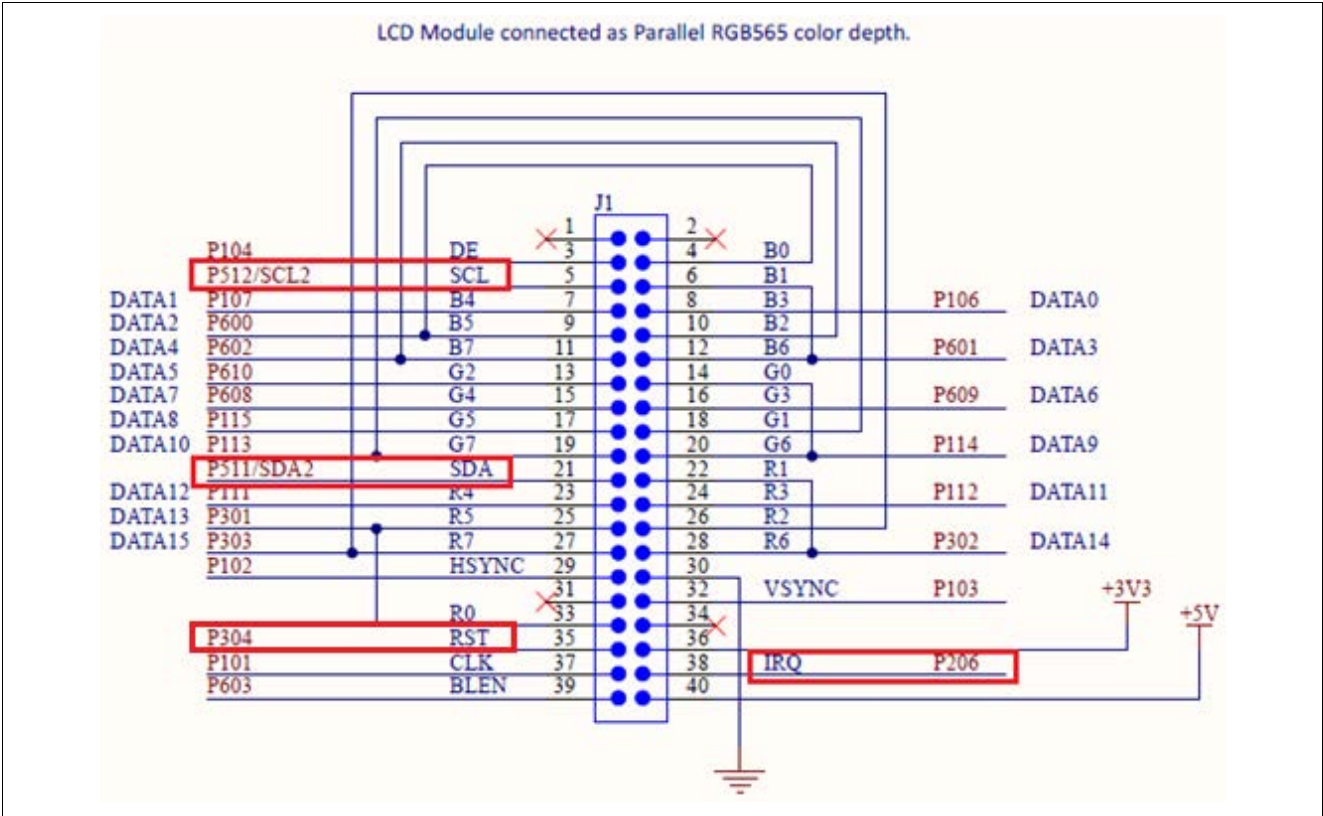


Figure 41. Set g_i2c_semaphore Semaphore Properties

- The pins marked in red above are used for the touch panel controller on the LCD board:
- IRQ0 interrupt (P206) is used to trigger touch events.
 - I2C channel 2 (P512, P511) is used to read and write data to the touch controller.
 - Touch driver folder touch_ft5x06 for touch function is inside the provided Source folder.
 - P304 is used to reset the LCD's touch controller.
13. Since the IRQ0 (P206) needs a pull-up to function properly with the LCD board, don't change the setting that was done by FSP, as shown below.

Pin Configuration

Select Pin Configuration

RA6M3G-EK.pincfg

Export to CSV file

Configure Pin Driver Warnings

Generate data: g_bsp_pin_cfg

Pin Selection

Type filter text

P2

P200

P201

P202

P203

P204

P205

P206

P207

P208

P209

P210

P211

P212

P213

Pin Configuration

Name	Value	Link
Symbolic Name		
Comment		
Mode	Input mode	
Pull up	input pull-up	
IRQ	IRQ0-DS	
Drive Capacity	Low	
Output type	CMOS	
Input/Output		
P206	GPIO	

Module name: P206

Port Capabilities: BUS0: WAIT

CTS0: TS01

Pin Function

Pin Number

Summary

BSP

Clocks

Pins

Interrupts

Event Links

Stacks

Components

Figure 42. P206 Pin Configuration

14. Note: Refer to the `touch_thread_entry.c` file in `Source.zip` for more information. The following code initializes the touch controller and process touch events.

```

/* Touch Thread entry function */
void touch_thread_entry(void)
{
    GX_EVENT gxe = {0};
    UINT status = 0;

    /*
     * Initialize Touch controller:
     * FT5X06 driver
     * IRQ interrupt
     */
    ft5x06_init(&g_i2c_touch, &g_i2c_semaphore, BSP_IO_PORT_03_PIN_04);
    /* Enable touch IRQ */
    R_ICU_ExternalIrqOpen(g_touch_irq.p_ctrl, g_touch_irq.p_cfg);
    R_ICU_ExternalIrqEnable(g_touch_irq.p_ctrl);

    while (1)
    {
        /* Wait for IRQ from touch controller. */
        status = tx_semaphore_get(&g_touch_semaphore, TX_WAIT_FOREVER);
        if (TX_SUCCESS != status)
        {
            APP_ERR_TRAP(FSP_ERR_ASSERTION);
        }

        /* Get touch data from the FT5X06 */
        ft5x06_payload_get(&touch_data);

        if (0U < touch_data.num_points)
        {
            /* Send only the TOUCH event of the first finger to the GUIX Model View Controller. */
            if (TOUCH_EVENT_DOWN == touch_data.point[0].event)
            {
                gxe.gx_event_payload.gx_event_pointdata.gx_point_x = touch_data.point[0].x;
                gxe.gx_event_payload.gx_event_pointdata.gx_point_y = touch_data.point[0].y;
                gxe.gx_event_type = GX_EVENT_PEN_DOWN;
                gx_system_event_send(&gxe);
            }
            else if (TOUCH_EVENT_UP == touch_data.point[0].event && GX_EVENT_PEN_DOWN == gxe.gx_event_type)
            {
                gxe.gx_event_payload.gx_event_pointdata.gx_point_x = touch_data.point[0].x;
                gxe.gx_event_payload.gx_event_pointdata.gx_point_y = touch_data.point[0].y;
                gxe.gx_event_type = GX_EVENT_PEN_UP;
                gx_system_event_send(&gxe);
            }
        }
    }
}

```



15. In RA Configurator, click **Generate Project Content** to generate project content.

4. Create Folders in the Hello_World_GUIX_EK_RA6M3G Project for Azure RTOS GUIX Studio Project

1. Under folder src create a new folder and name it guix_gen. Follow the image below, then click **Finish**.

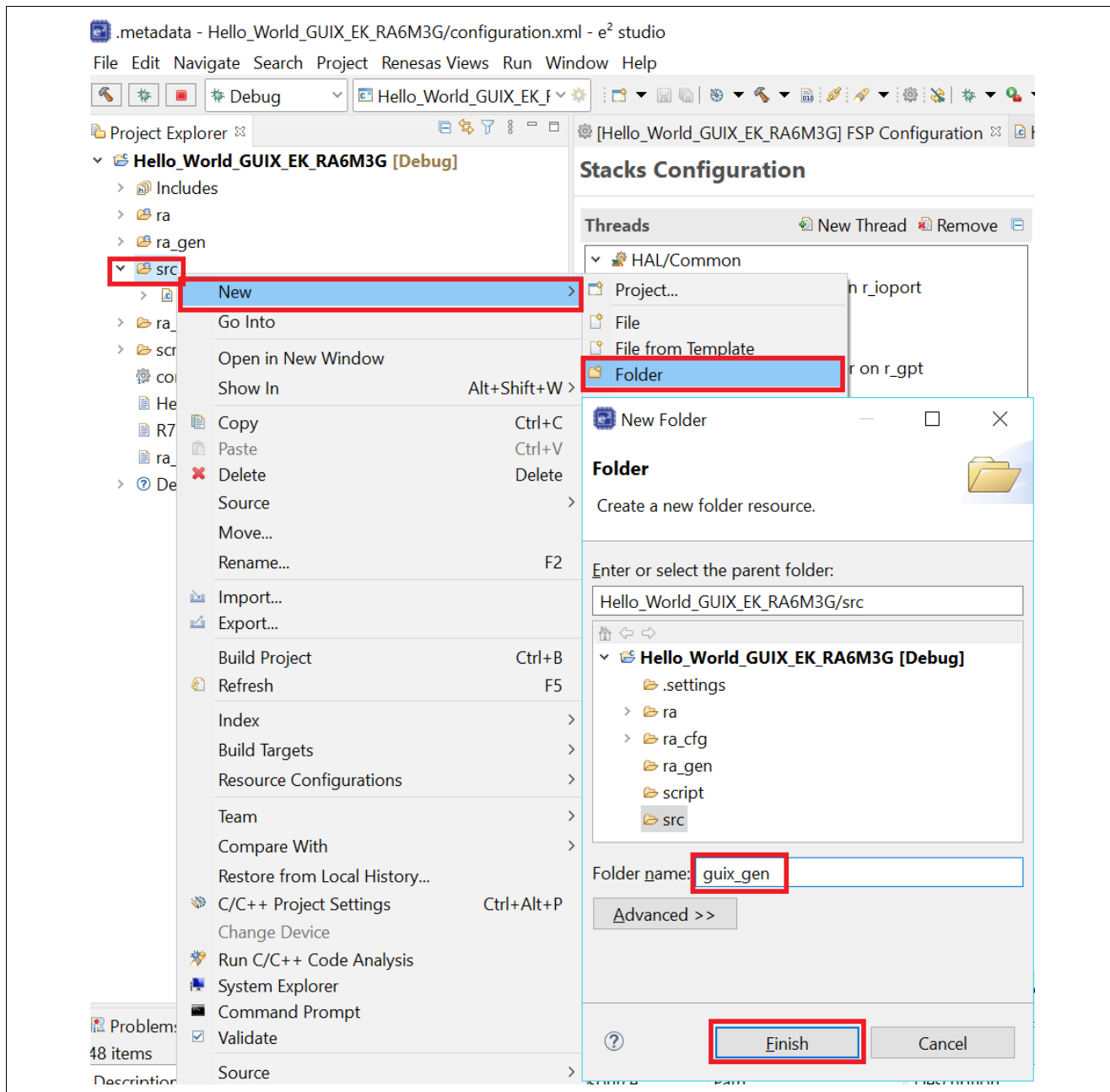


Figure 43. Create guix_gen Folder

- Under folder `src` create a new folder and name it `guix_studio`. Then follow the image below and click **Finish**.

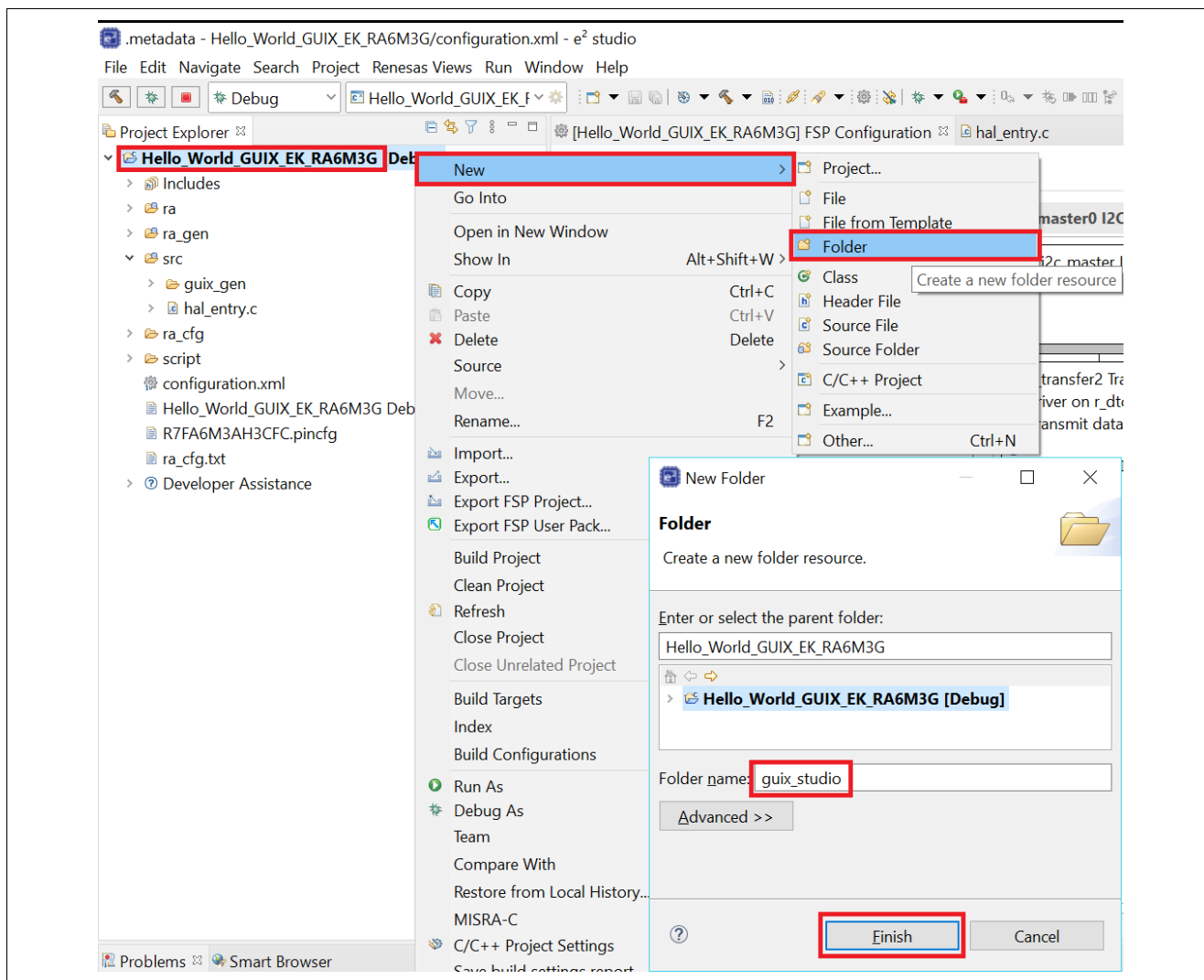


Figure 44. Create `guix_studio` Folder

3. Go to the Hello_World_GUIX_EK_RA6M3G project. Select the guix_studio folder, right-click and select **Resource configuration**, then select **Exclude from Build...** since it contains the Azure GUIX Studio project, which won't be built by FSP.

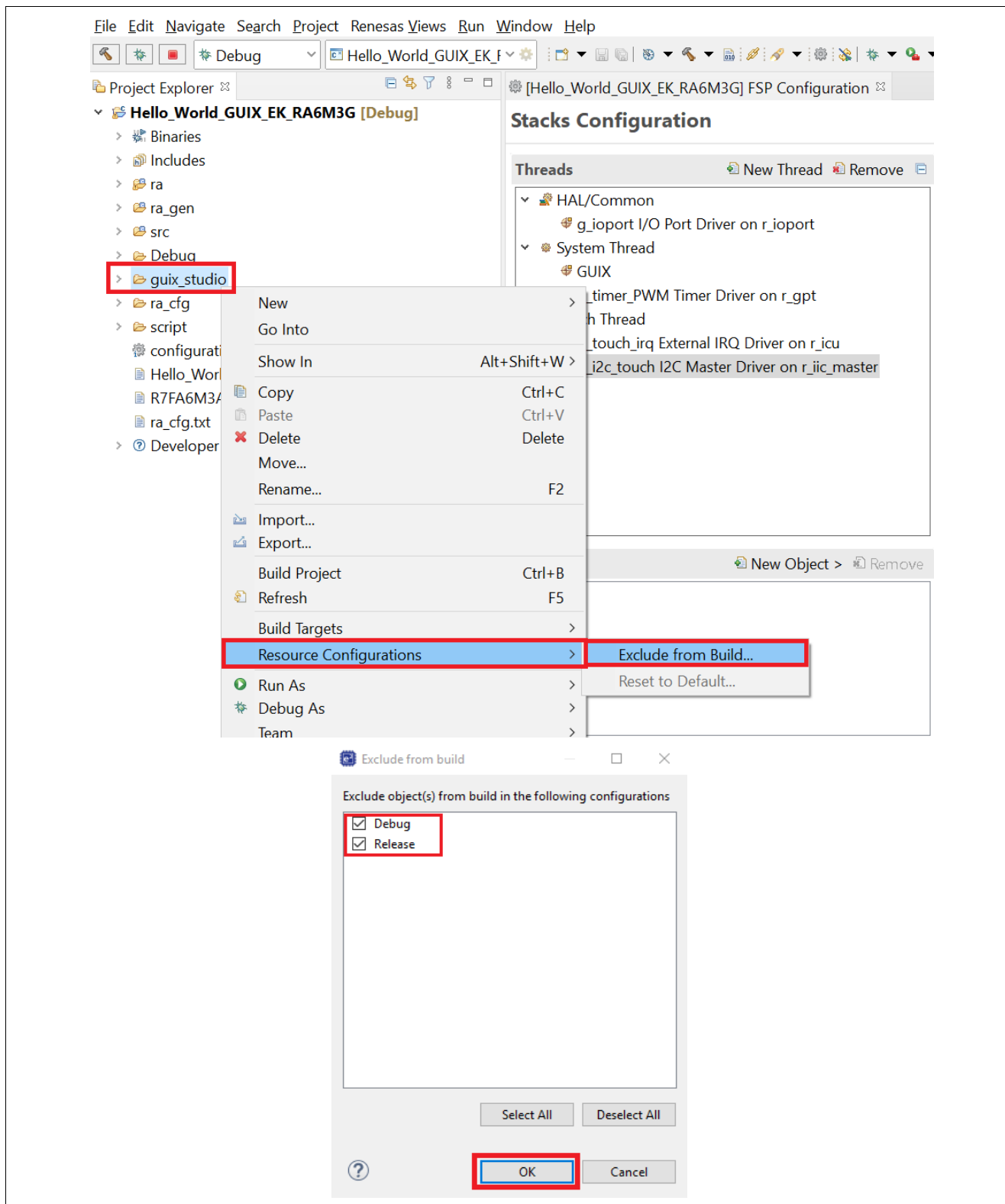


Figure 45. Exclude guix_studio from Build

4. Under folder `guix_studio` that was created earlier, create a new folder and name it `GNU`. Follow the image below, then click **Finish**.

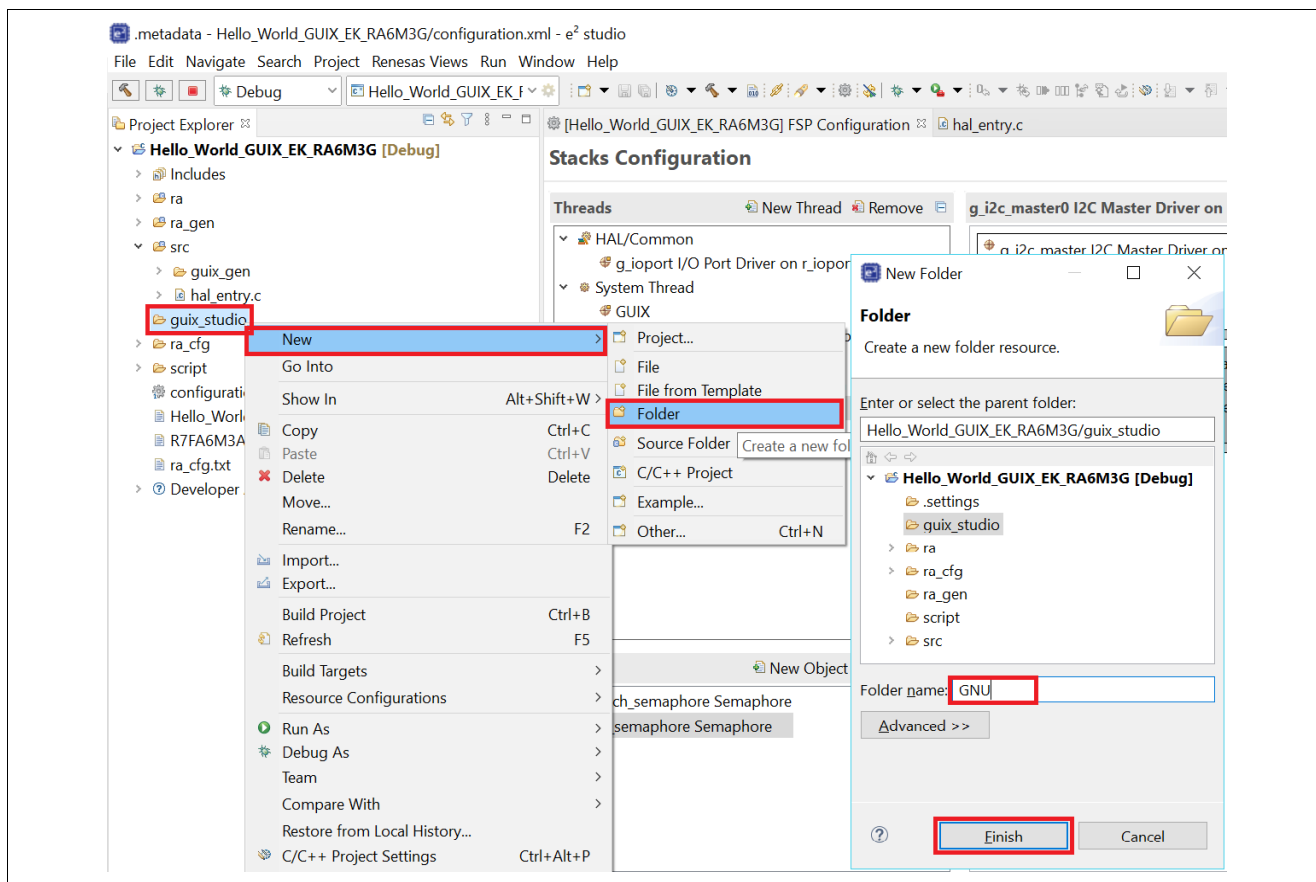


Figure 46. Create GNU Folder

5. After the sub-folder GNU is created, the folder structure should look like the image below.

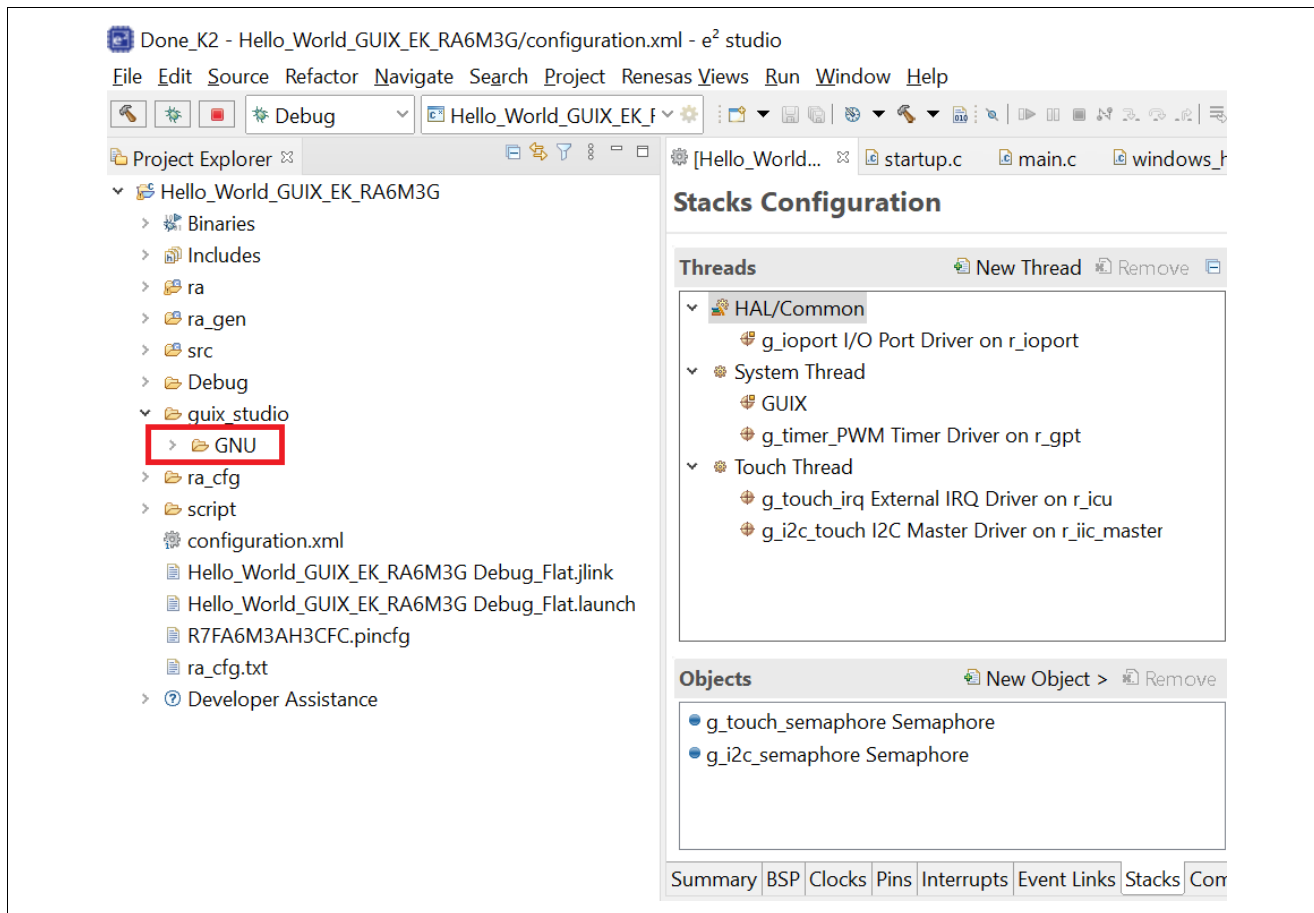


Figure 47. After GNU Folder is Created

6. Unzip and open the provided folder Source.zip. Copy the four *.c files and one folder touch_ft5x06 and paste into the folder src of your project **Hello_World_GUIX_EK_RA6M3G**.
 - Touch_ft5x06 folder
 - hal_entry.c
 - system_thread_entry.c
 - touch_thread_entry.c
 - windows_handler.c

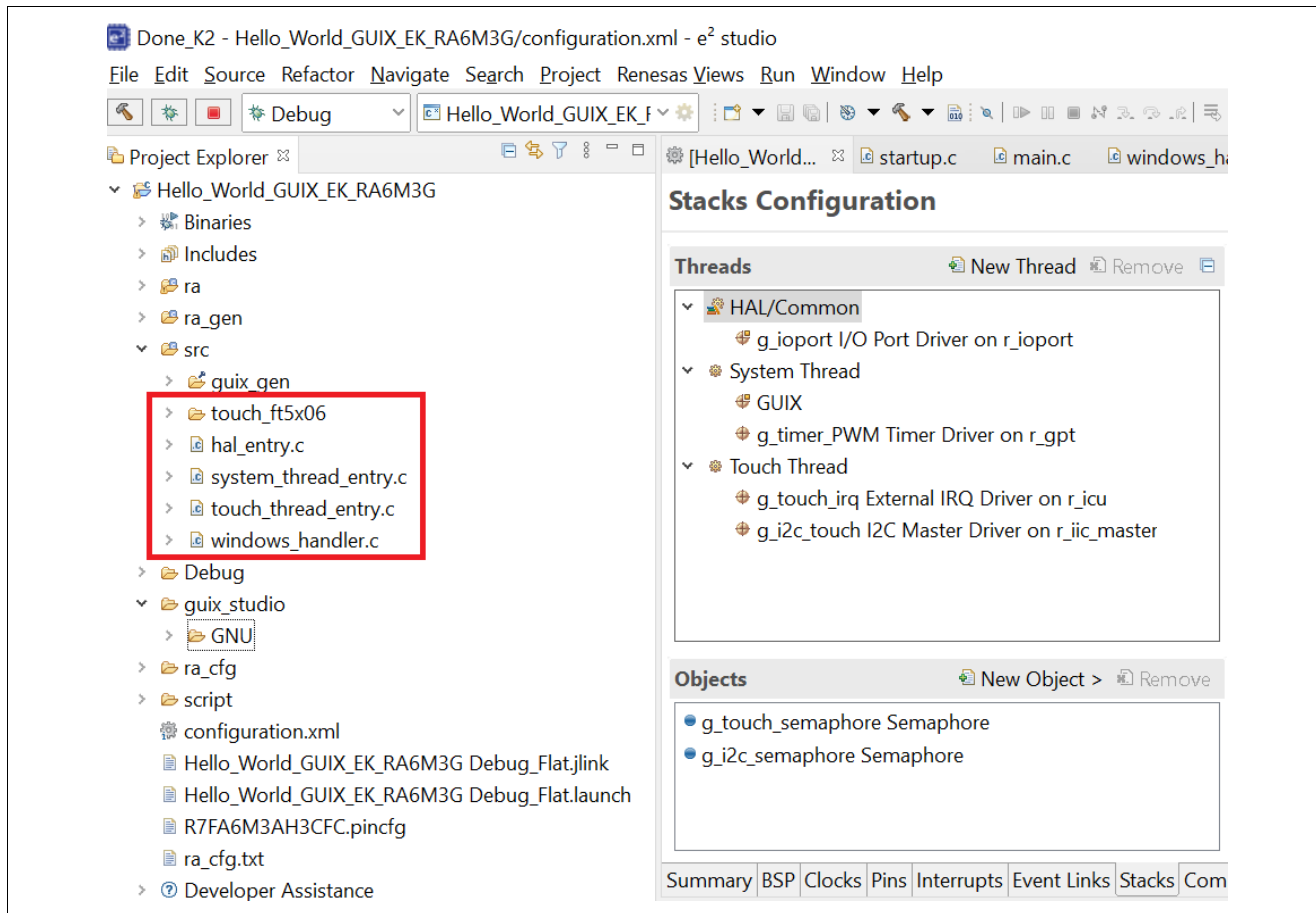


Figure 48. Files Copied from Source.zip

5. Using Azure RTOS GUIX Studio create GUI Windows

1. Open Azure RTOS GUIX Studio v6.1.7 or greater.

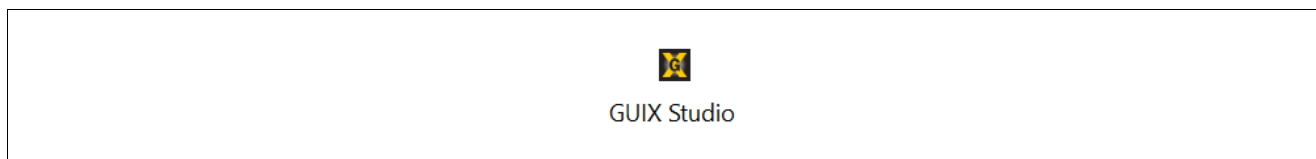


Figure 49. GUIX Studio Icon

2. Create a **New Project** and name it **Hello World**.
 - a. Select **Project**. From the drop-down list, select **New Project**.
 - b. Project Name: **Hello_World**.
 - c. Project Path: Browse to the location of the folder you created in the **Hello_World_GUIX_EK_RA6M3G > guix_studio\GNU** as shown in the image below.
 - d. Hit **OK** button and then the **Save** button to confirm your selections.

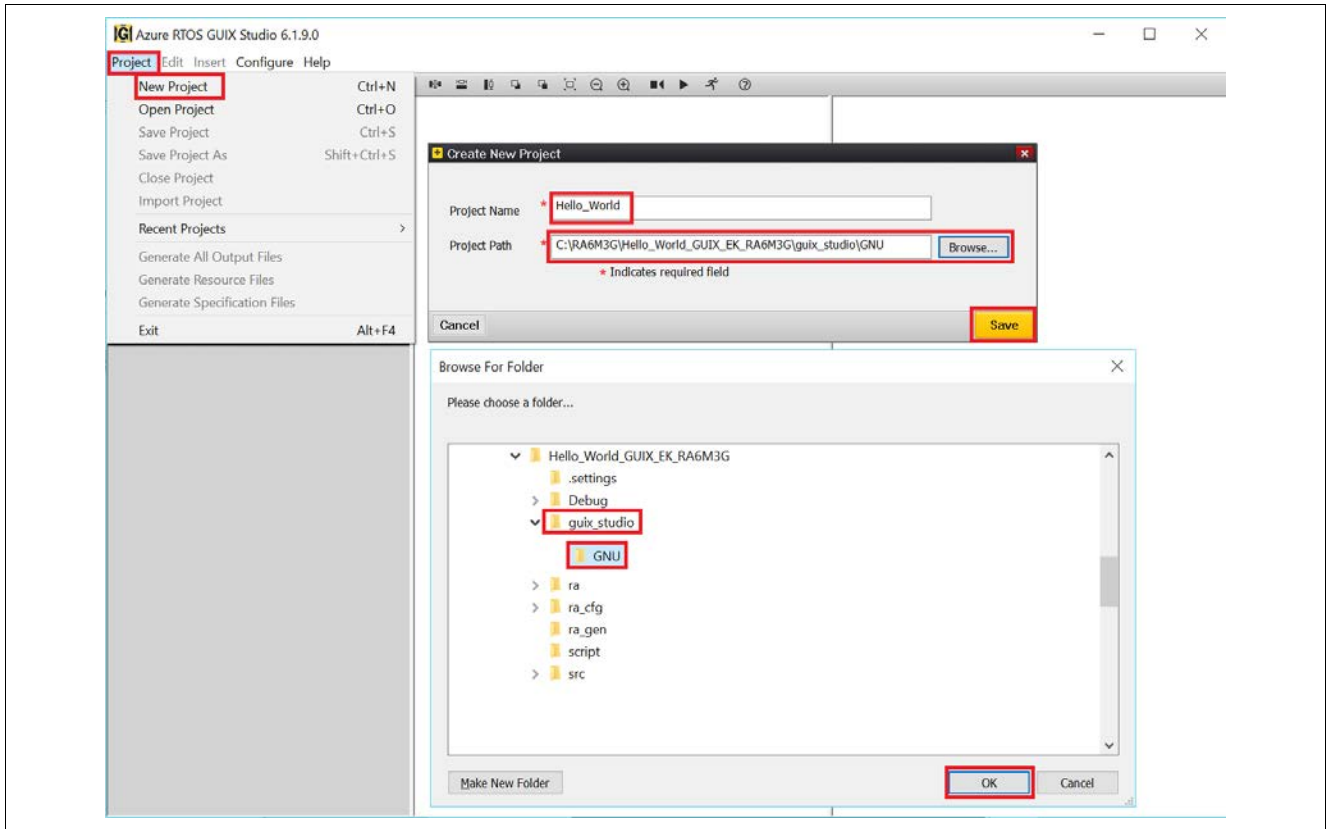


Figure 50. Create Hello World Project

3. A new **Configure Project** window will pop up and you need to set all the options as shown in Figure 51 and Figure 52. Finally, click **Save**.

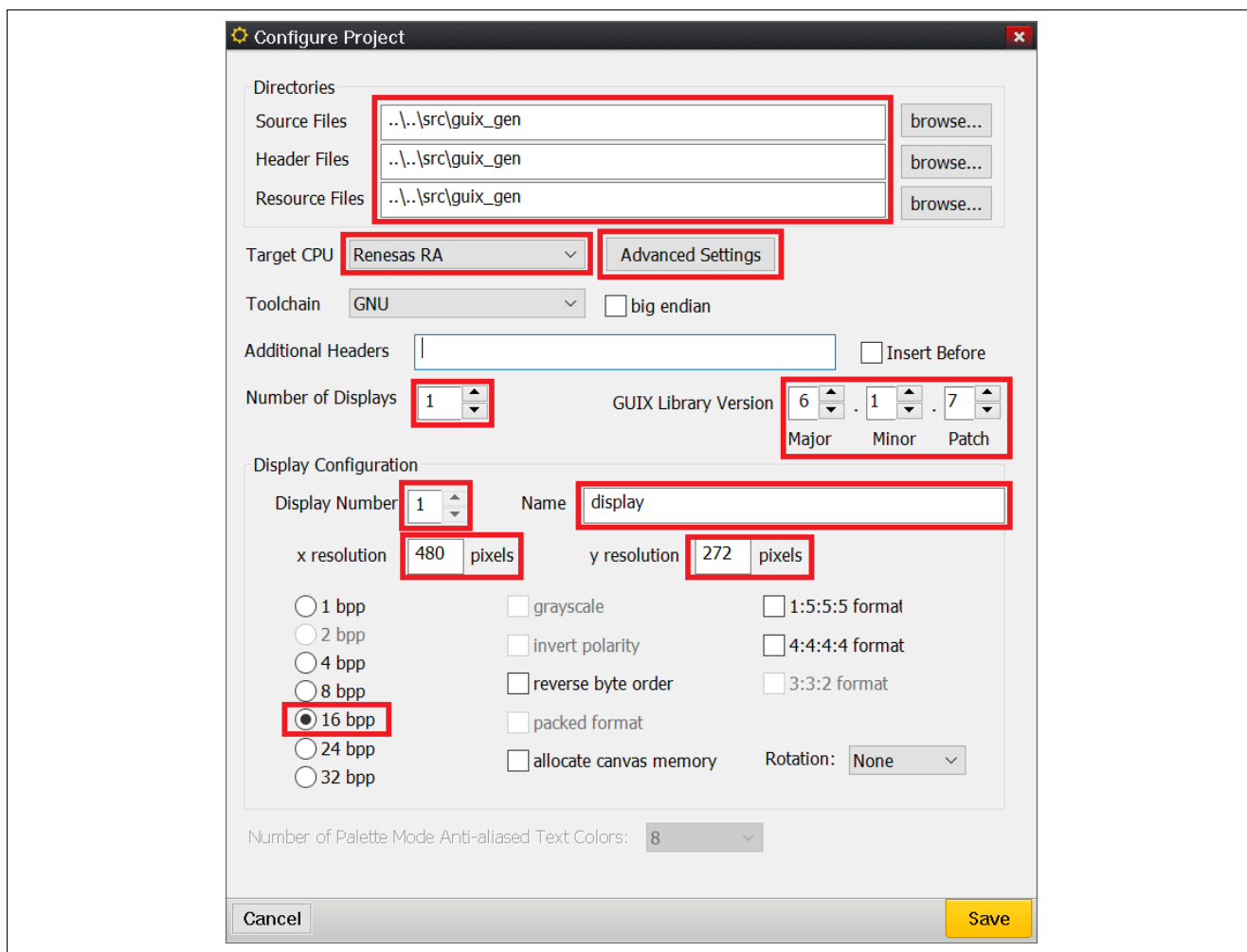


Figure 51. Configure Project

Advanced Settings:

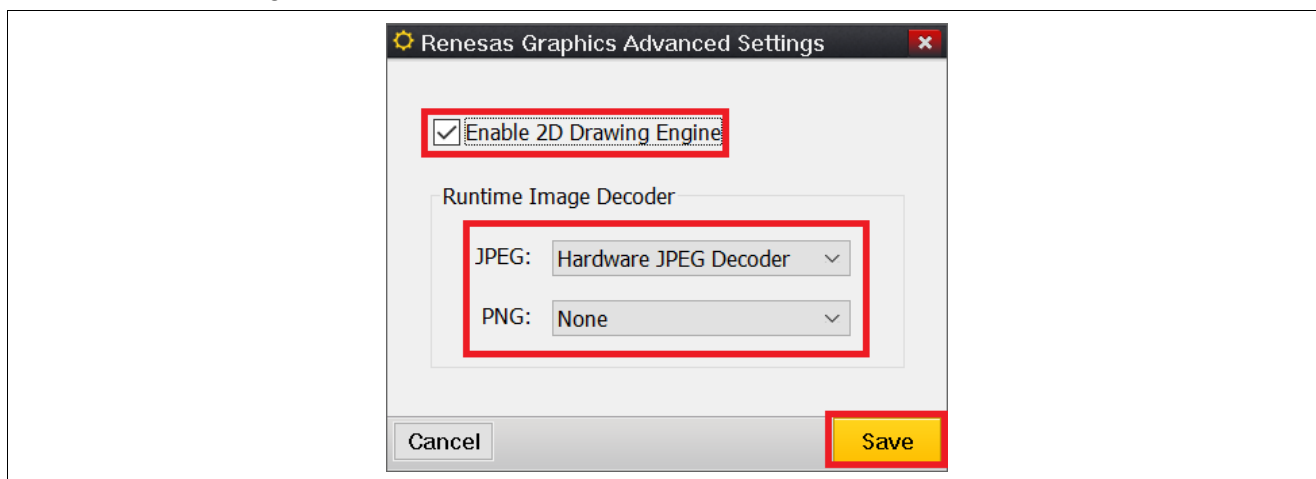


Figure 52. Advanced Settings

5.4 Setting **Properties View** of **Window1**

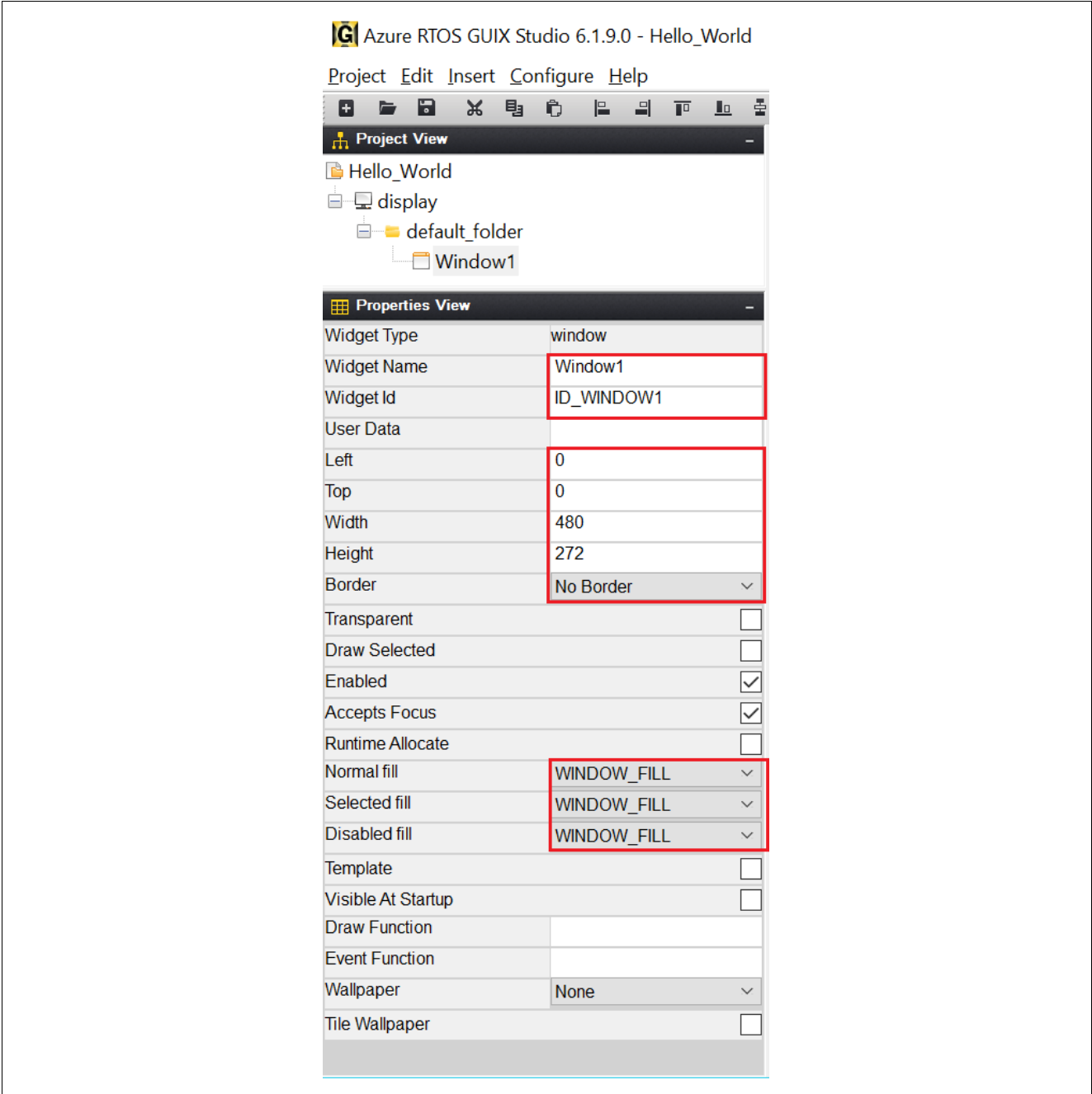


Figure 53. Property View of Window1

4. To add String ID, click on **Strings**. Follow the images below.



Figure 54. Strings

From the **Strings** dropdown, click + **Add New String**.

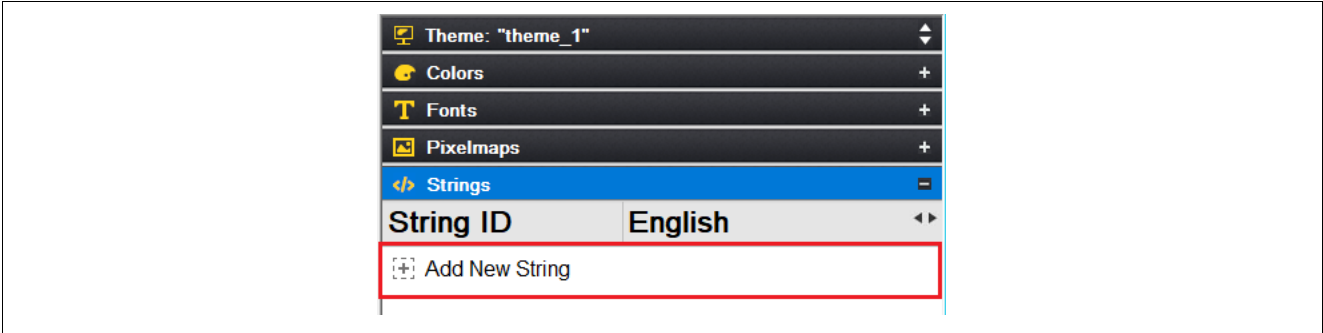


Figure 55. Add New String

A new **String Table Editor** window will pop up. Click the **Add String** button.

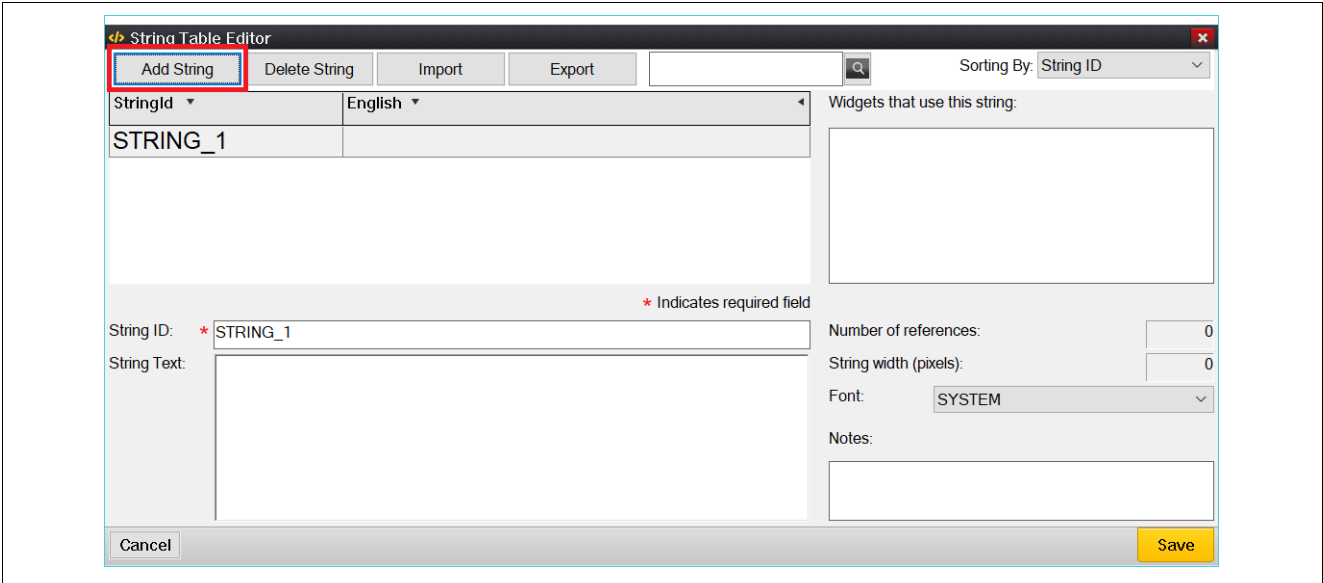


Figure 56. String Table Editor

5. Edit **String ID** and **String Text**.

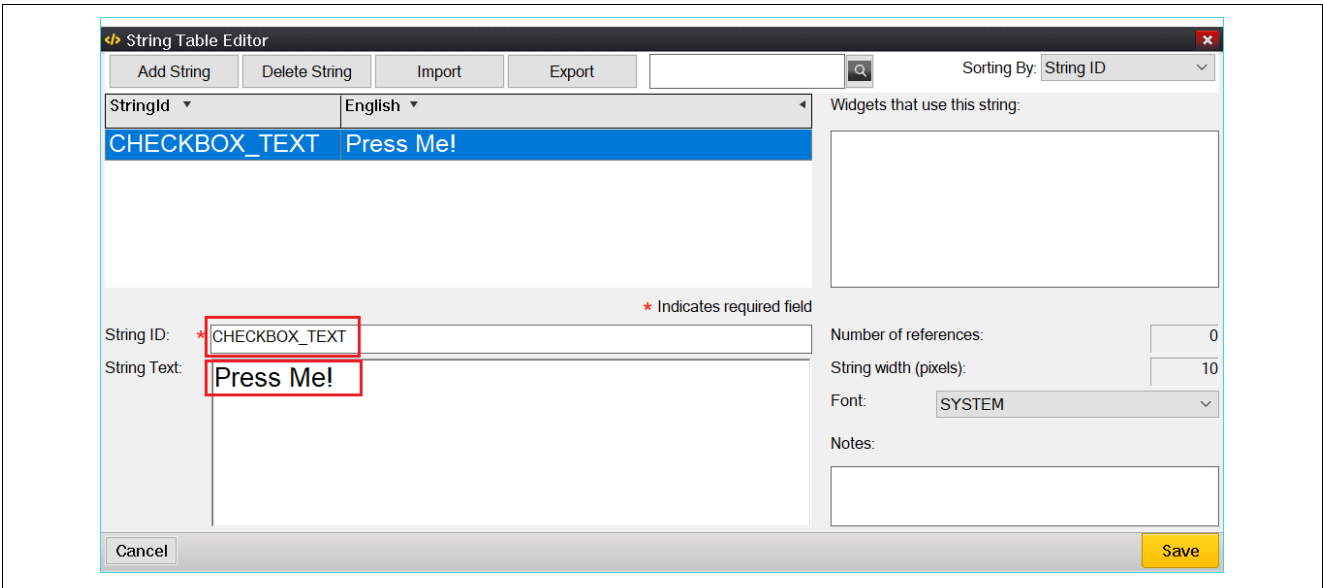


Figure 57. Edit String ID and String Text

6. Continue to click **Adding String**, then edit **String ID** and **String Text** until the table appears like Figure 58. Then click the **Save** button

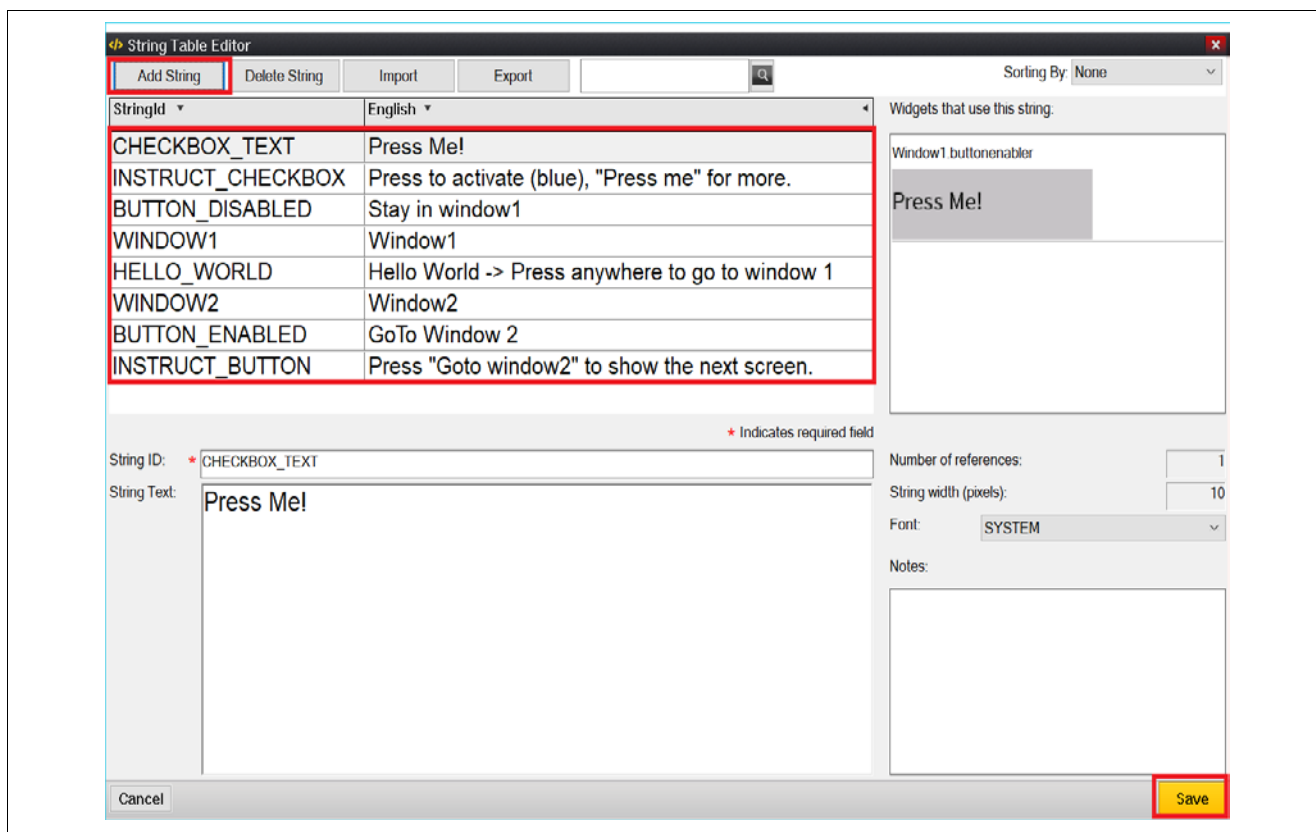


Figure 58. All Strings

- 5.8 Right-click on **Window1** to insert a **Text Button** and follow Figure 59.

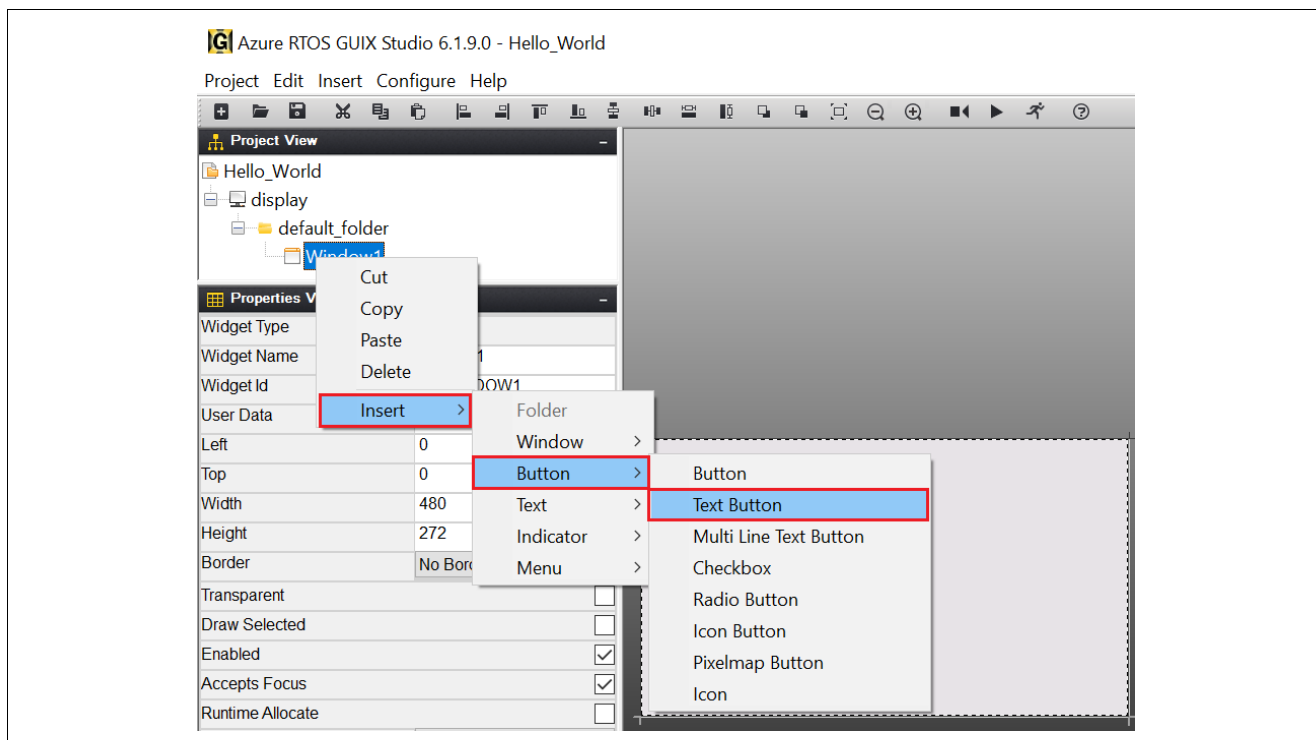


Figure 59. Insert Text Button

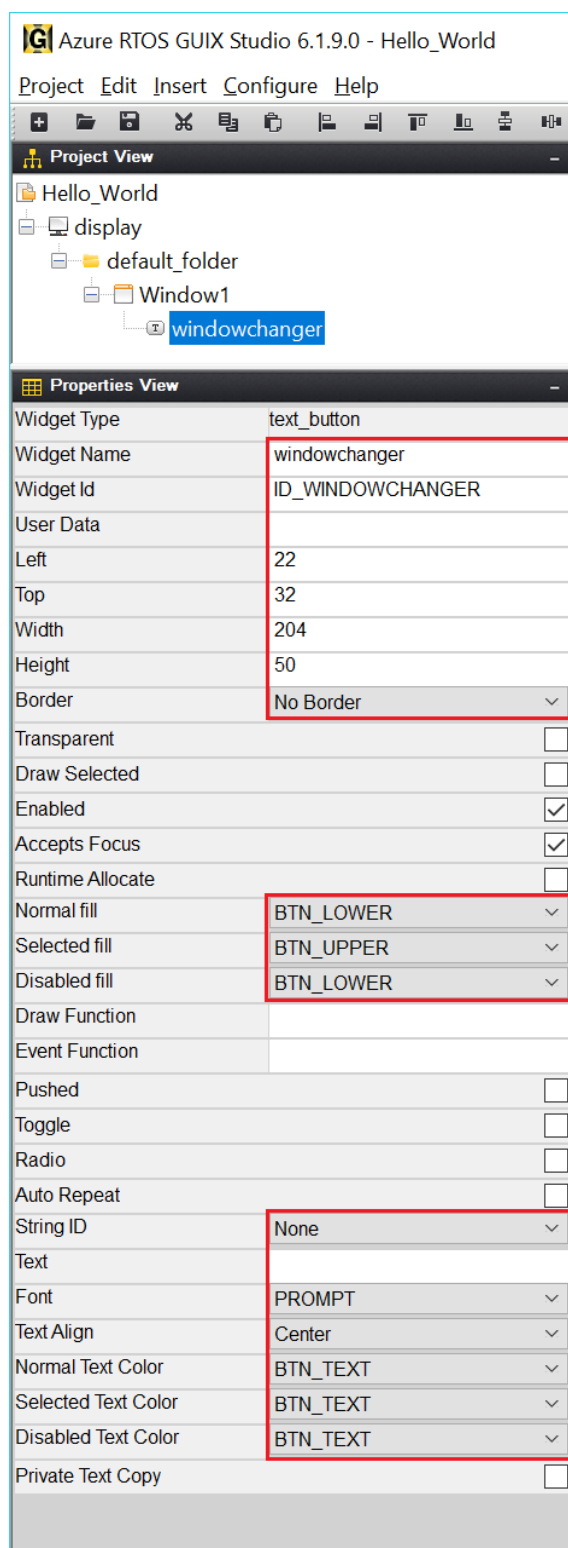
7. Set **Properties View** of "ext_button".

Figure 60. Properties View of text_button

8. Right-click **windowchanger** to insert a **Prompt** and follow Figure 61.

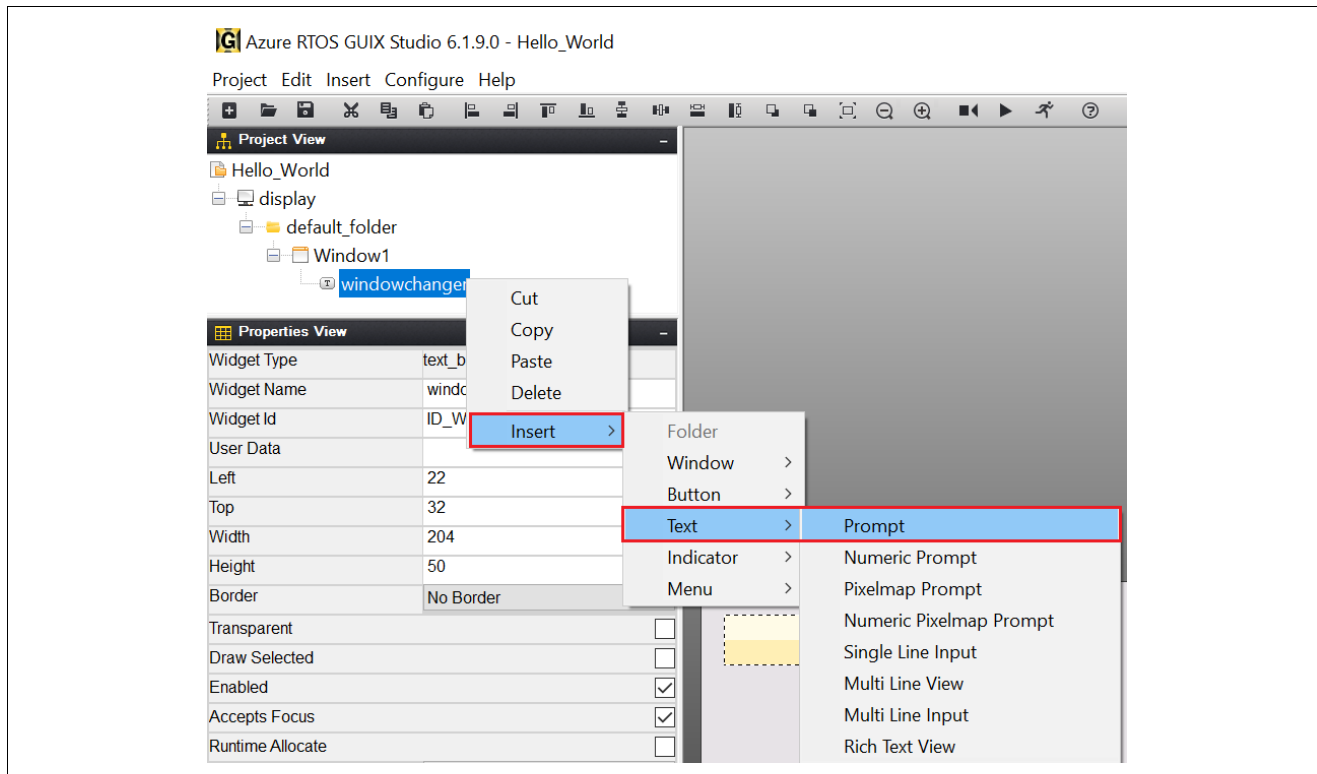


Figure 61. Insert Prompt

9. Set Properties View of prompt.

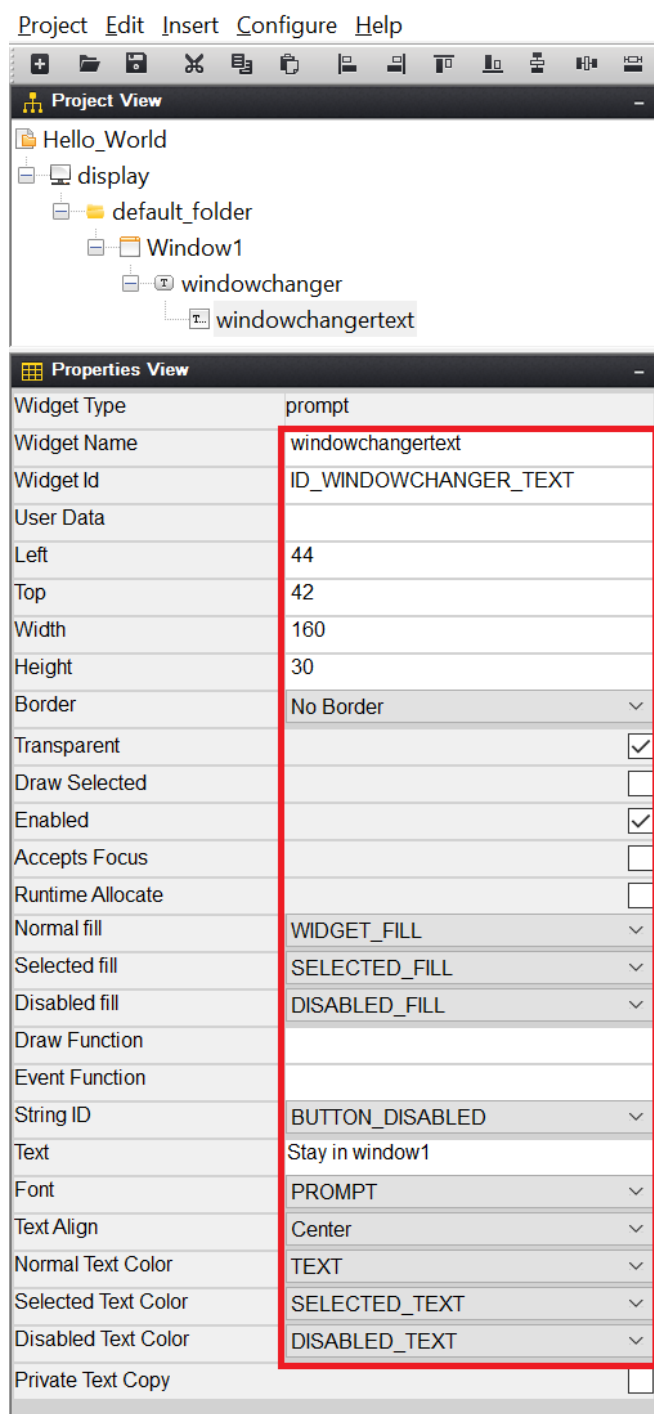


Figure 62. Properties View of prompt

10. Insert new **Button**. Right-click on **windowchangertext** and follow Figure 63.

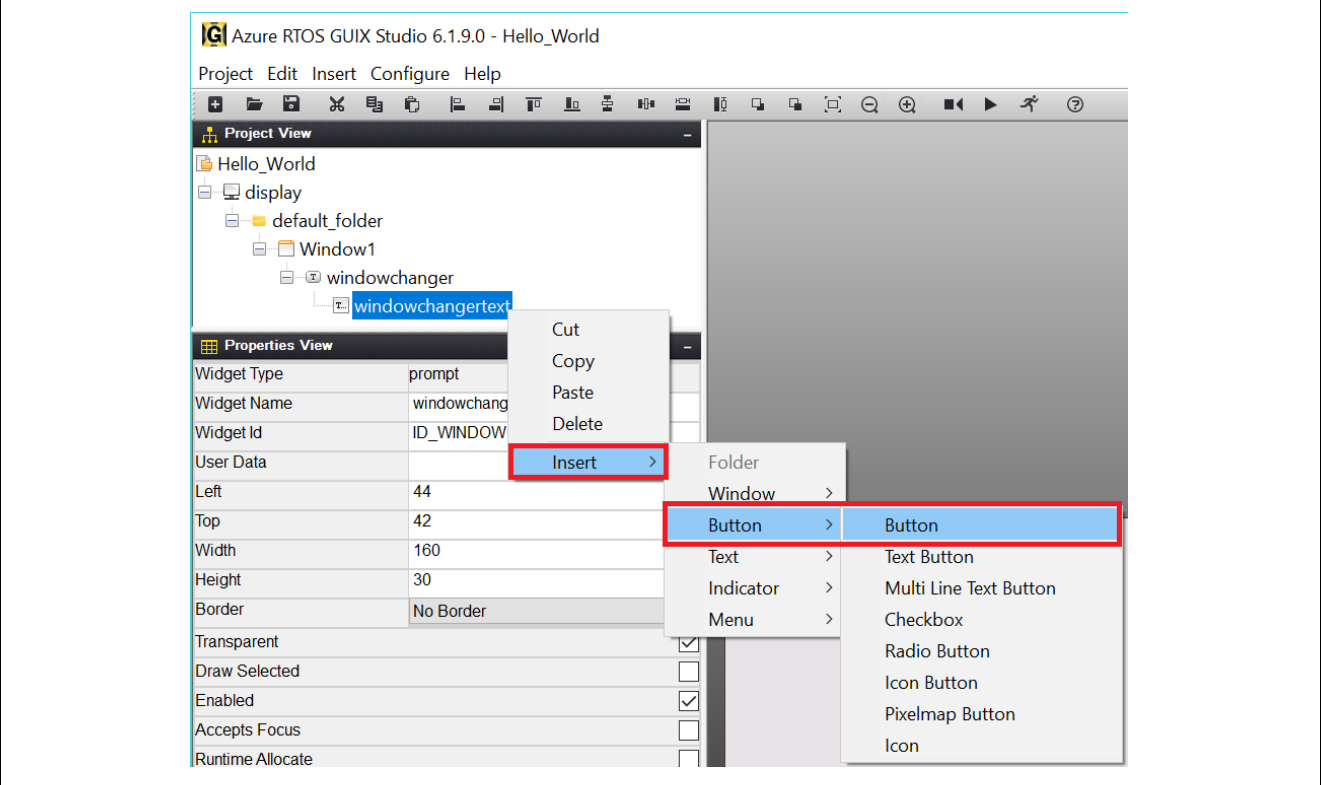


Figure 63. Insert Button

11. Set the **Properties View** of **button**.

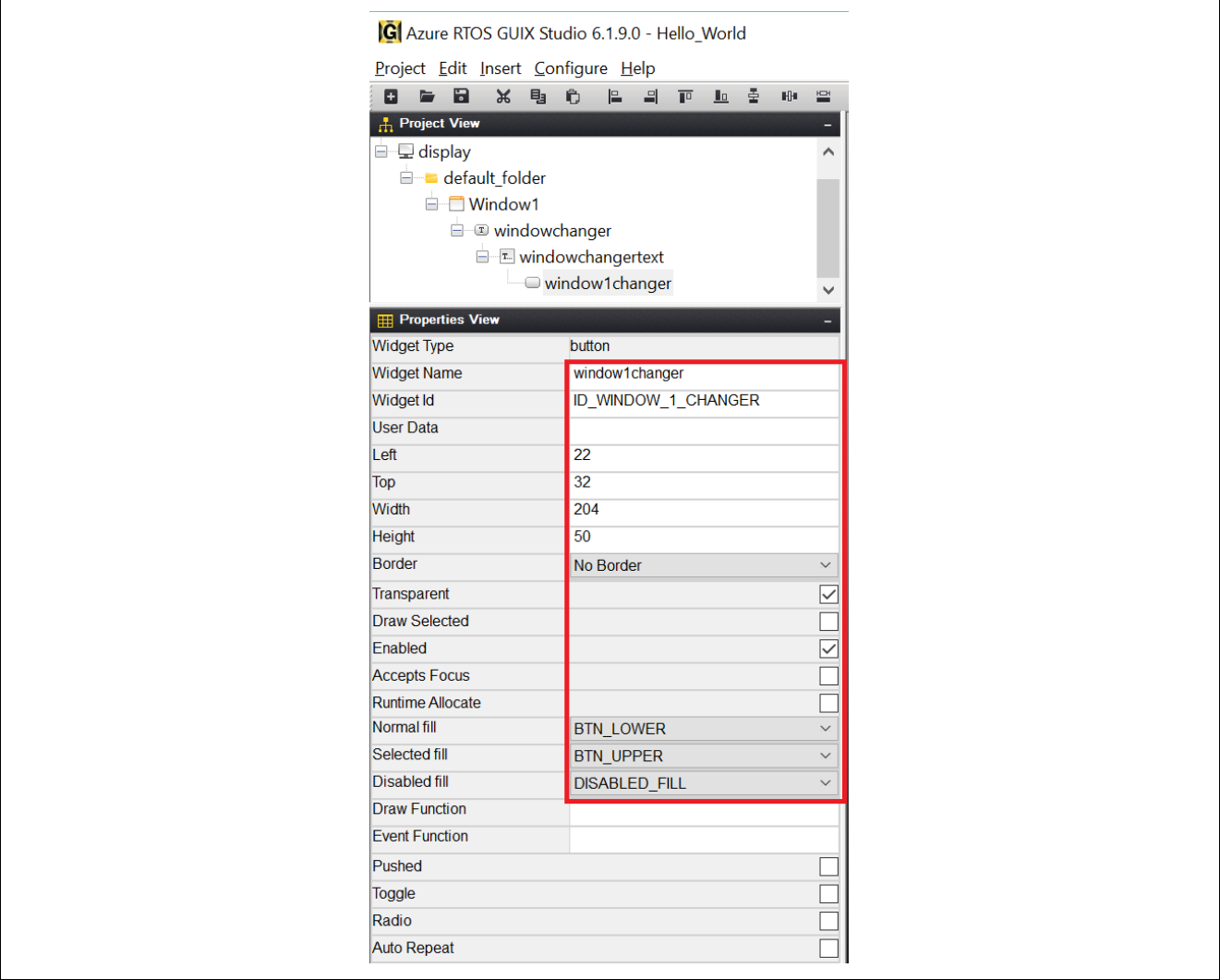


Figure 64. Properties View of button

12. Insert **Checkbox**. Right-click on **Window1** and follow Figure 65.

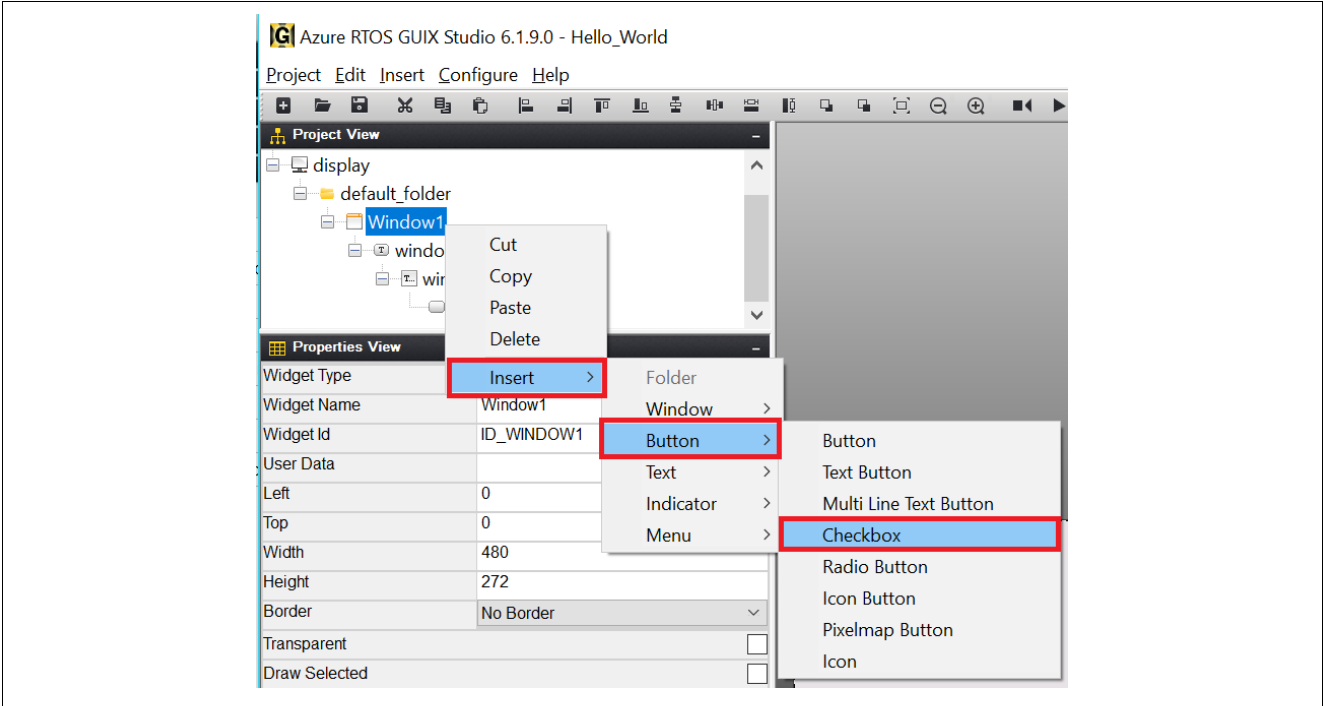


Figure 65. Insert Checkbox

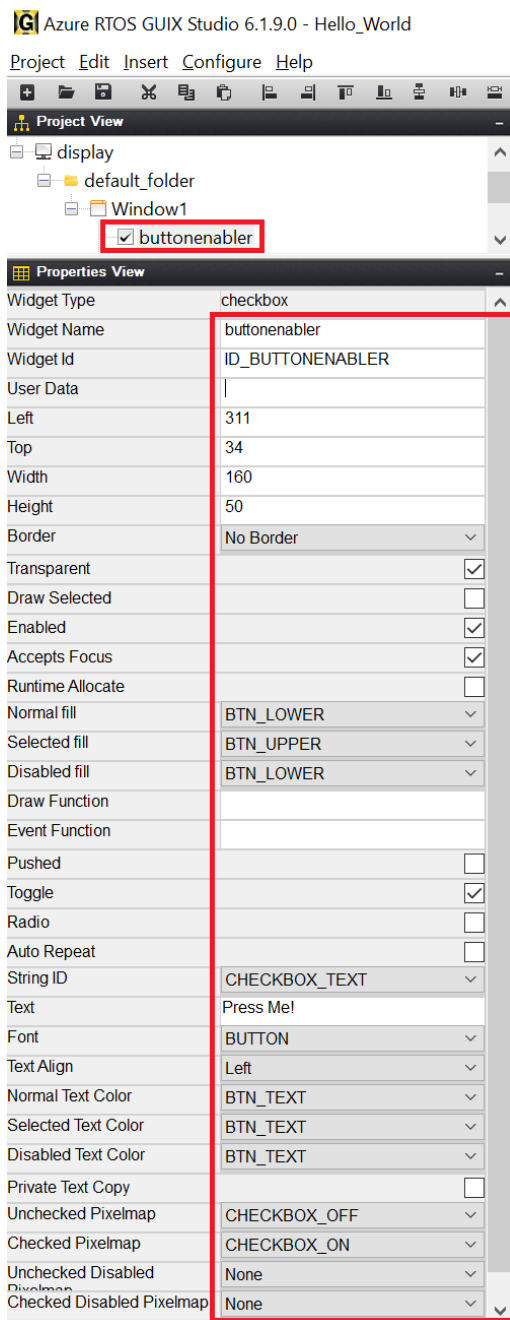
13. Set the **Properties View** of **button**.

Figure 66. Properties View of button

14. Insert **Prompt**. Right click on **Window1** and follow Figure 67. Insert two times to get two prompts.
Prompt and **Prompt1** will show up once you finish.

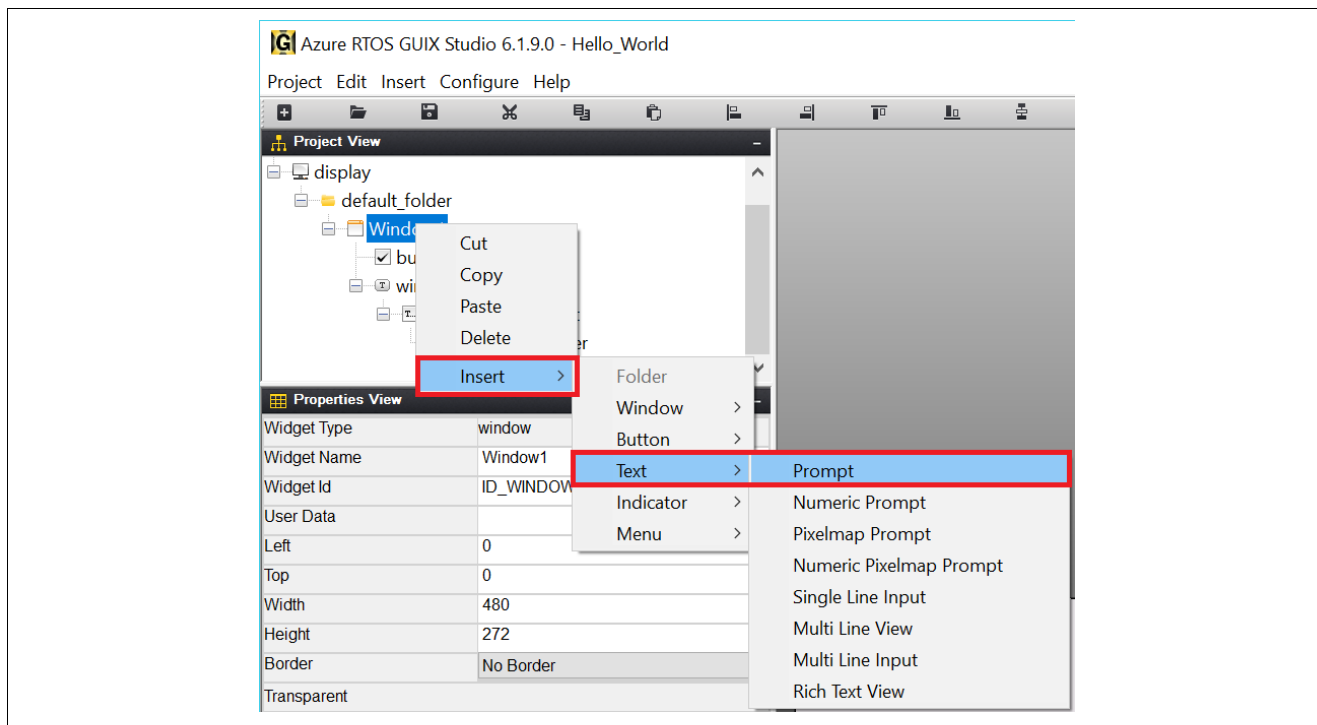


Figure 67. Insert Prompts

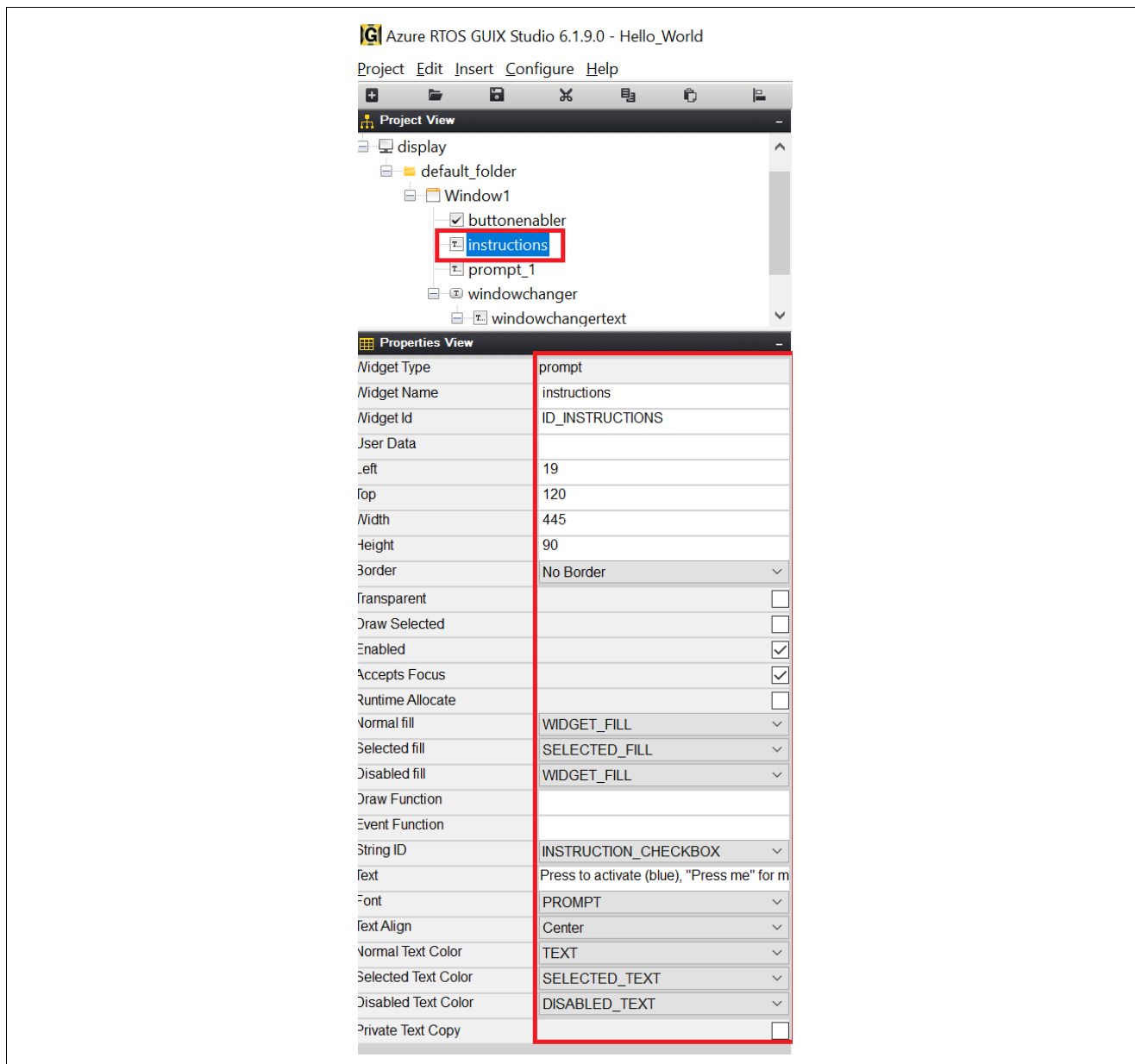
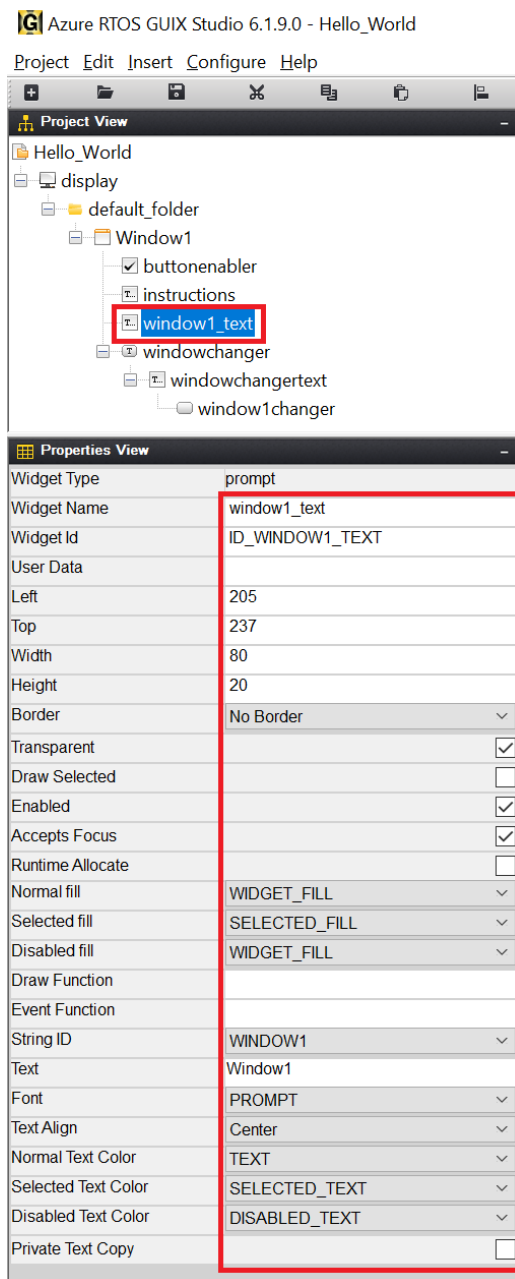
15. Set the **Properties View** of **Prompt**.

Figure 68. Properties View of Prompt

16. Set the **Properties View** of **Prompt1**.**Figure 69. Properties View for Prompt1**

17. After you finished creating **Window1**, it should be like the image below.

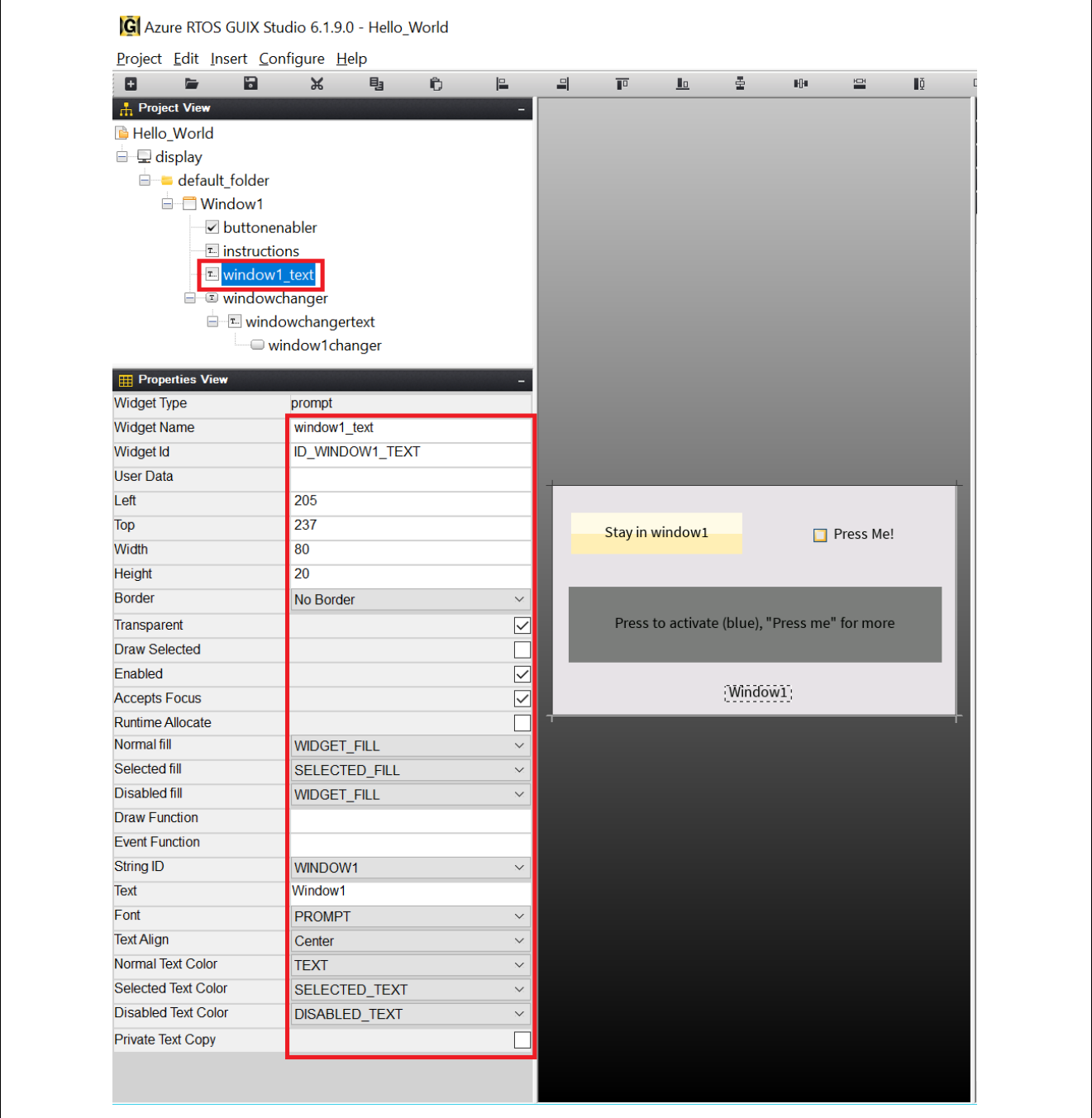


Figure 70. Window1 Created

18. Follow all these concepts to create **Window2**. After you are done, then you should have **Window2** as shown in Figure 71.

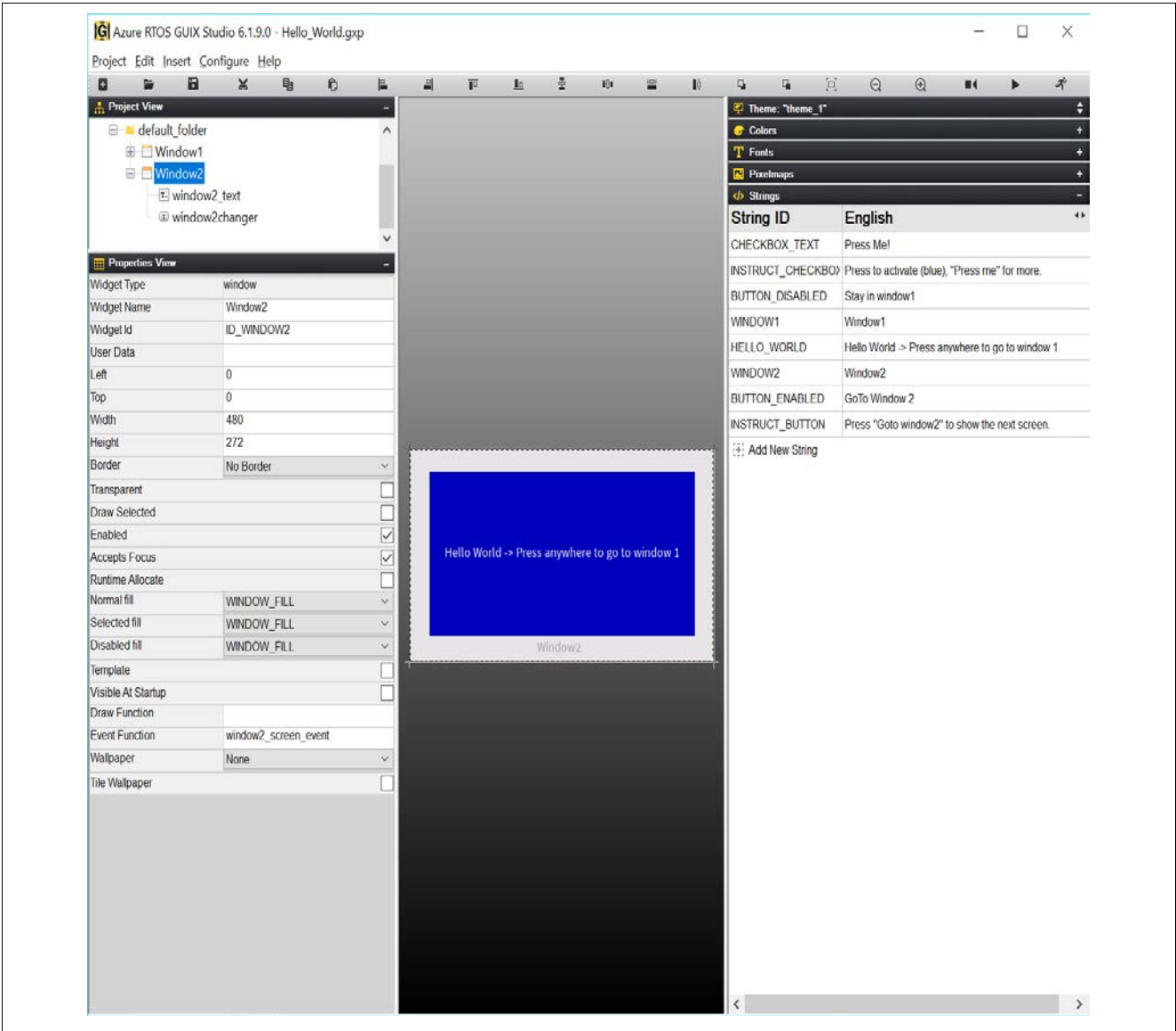


Figure 71. Window2

19. Click on drop-down list **Pixelmaps**, double-click on **CHECKBOX_OFF** and a new window will pop up. Uncheck **Compress Output** then click **Save**. Do the same for **CHECKBOX_ON**.

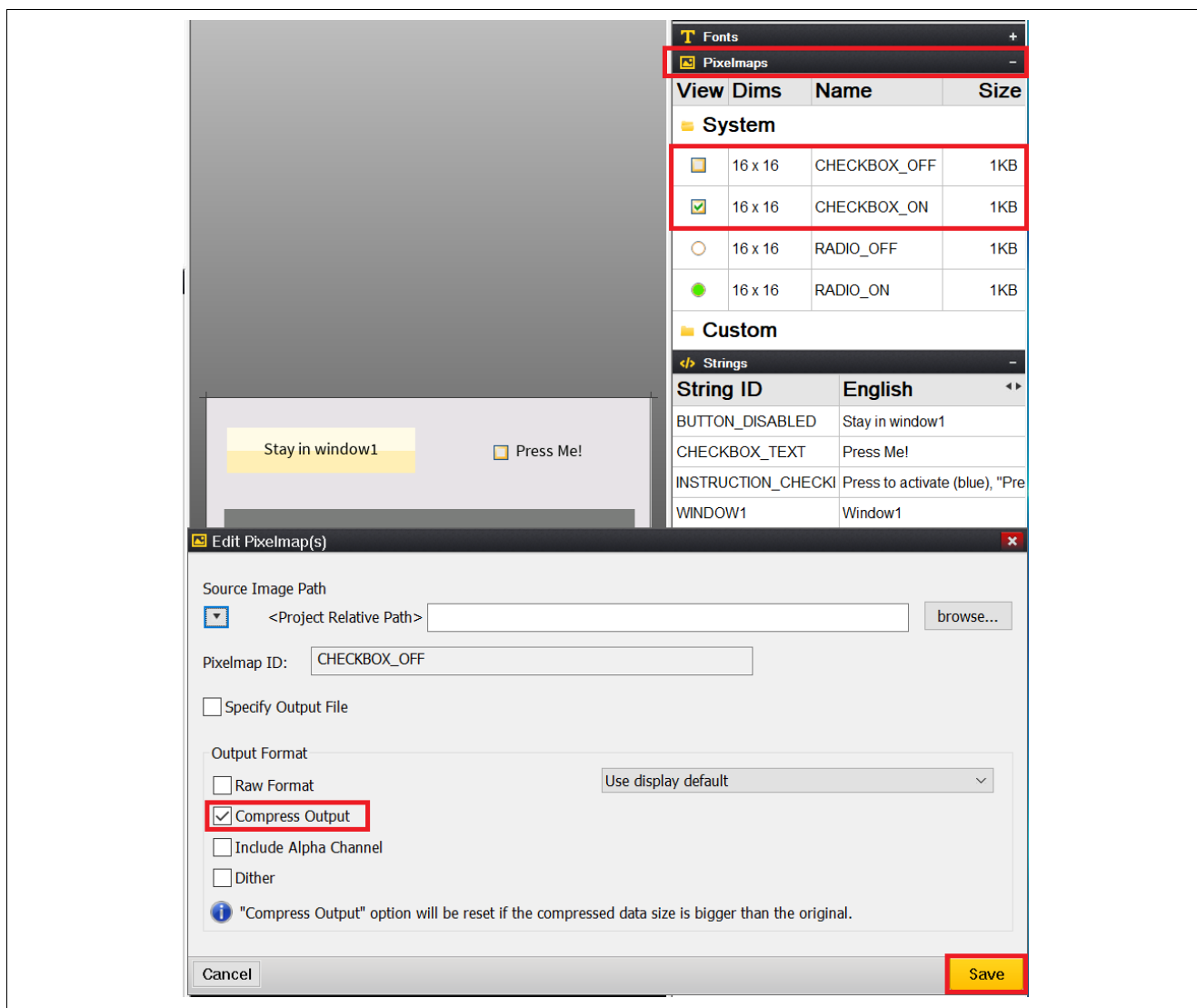


Figure 72. Set Up Pixelmap

20. Now you can click on the **Project** drop down list, **Save Project**, and **Generate All Output Files**. You completed the process of creating and exporting GUIX Hello World into the project.

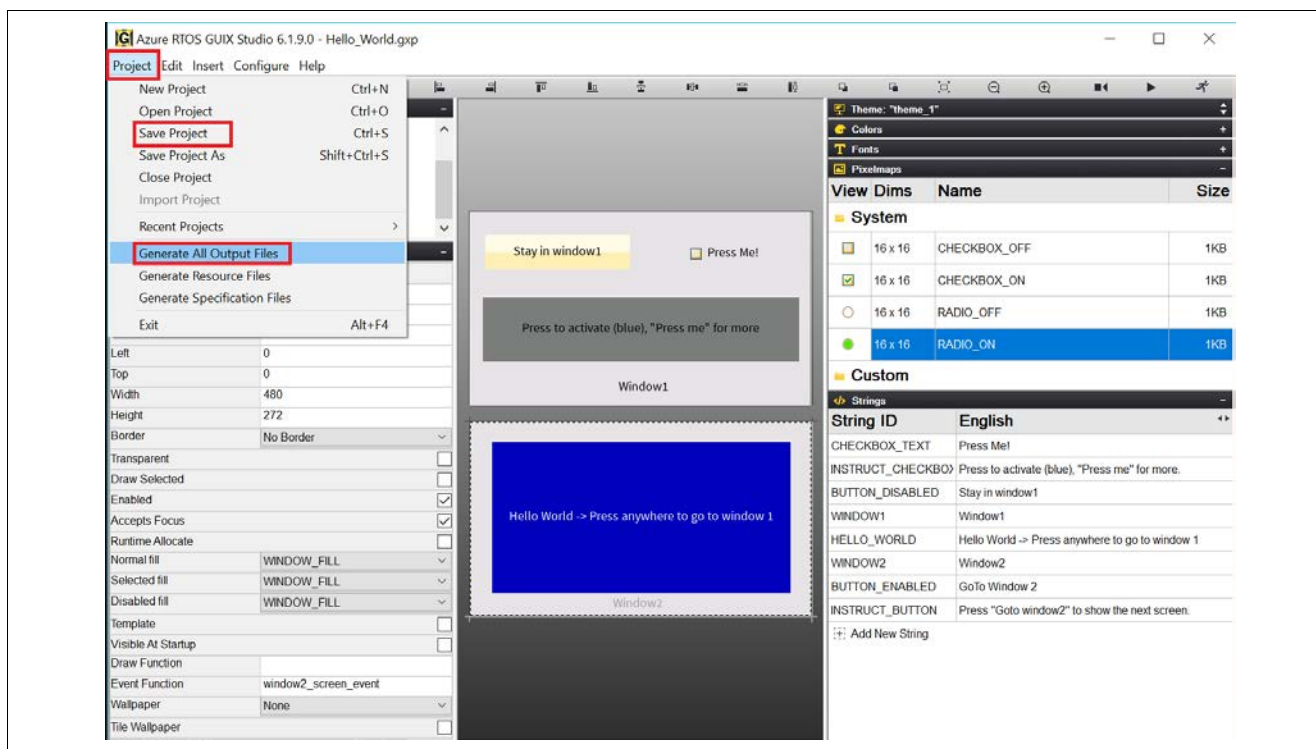


Figure 73. Save and Generate Project

21. Make sure the project is active and click  to build the project. It may take a long time to finish building an Azure RTOS/GUIX project on your PC. Project Hello_World_GUIX_EK_RA6M3G should build with no errors or warnings.

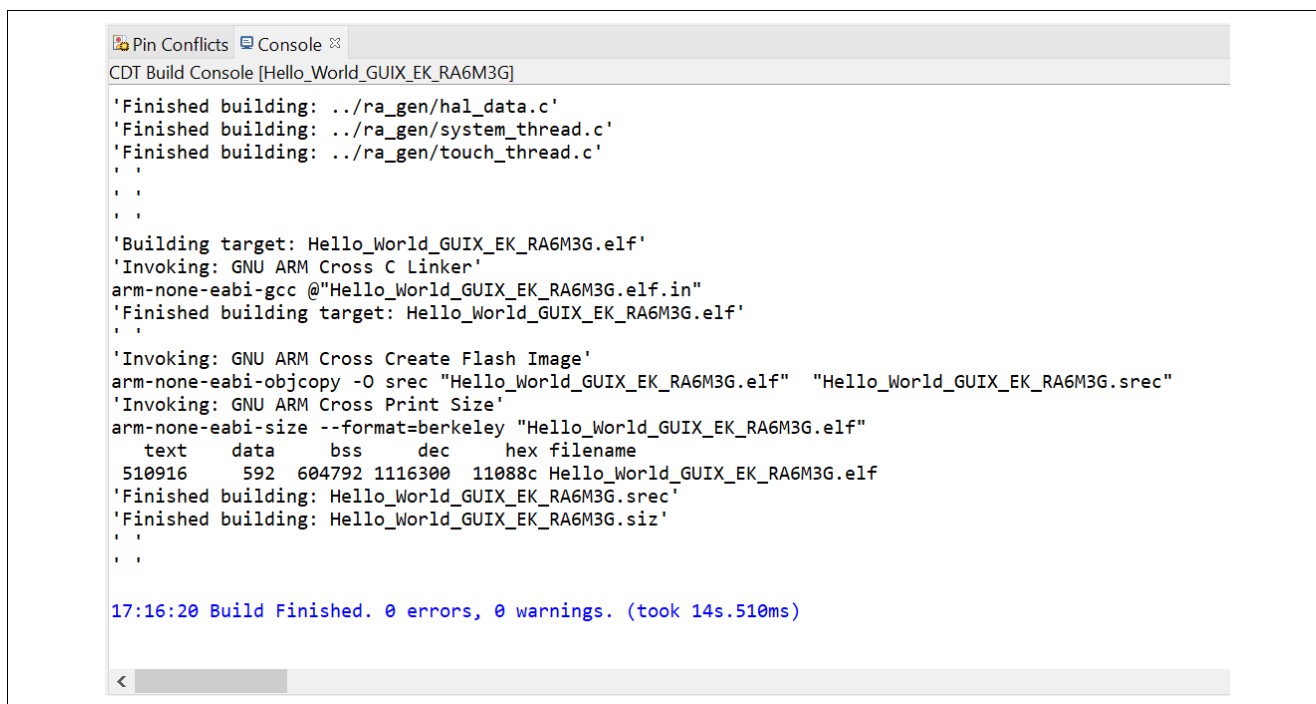


Figure 74. Project Builds Without Errors

22. Using the Micro USB cable, connect to J10 on EK-RA6M3G board and the other end to your PC.
Download and run the Hello_World_GUIX_EK_RA6M3G project.
23. You will see the Window1 display on LCD panel.

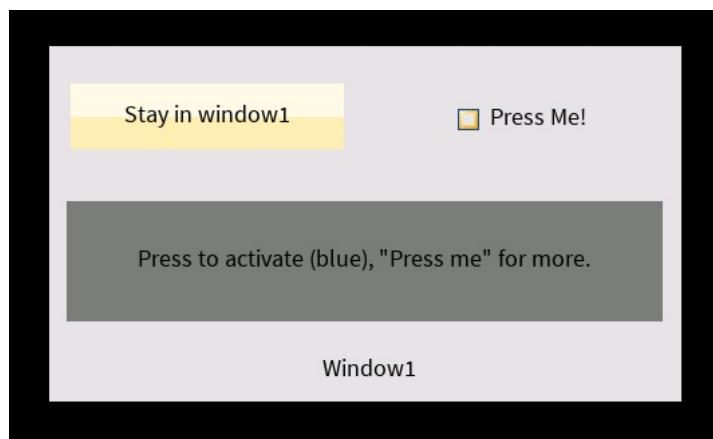


Figure 75. Window1 Display

6. Overview of Full Function Project

6.1 Overview

In this section, you will import and run the complete Hello_World_GUIX_EK_RA6M3G project. You can enable or disable check box function. The text on the button, which is "Stay in window1" or "Go to Window 2", will be updated. Once you press the button, the screen will change from window1 to window2. Follow the text message on the screen, you can change from window2 back to window1.

6.2 Procedural Steps

1. You can try the completed project **Hello_World_GUIX_EK_RA6M3G** for the full function application. Use the **Rename & Import Existing C/C++ Project into Workspace** feature of the **Import** menu to do so since you already had a project with the same in the workspace.

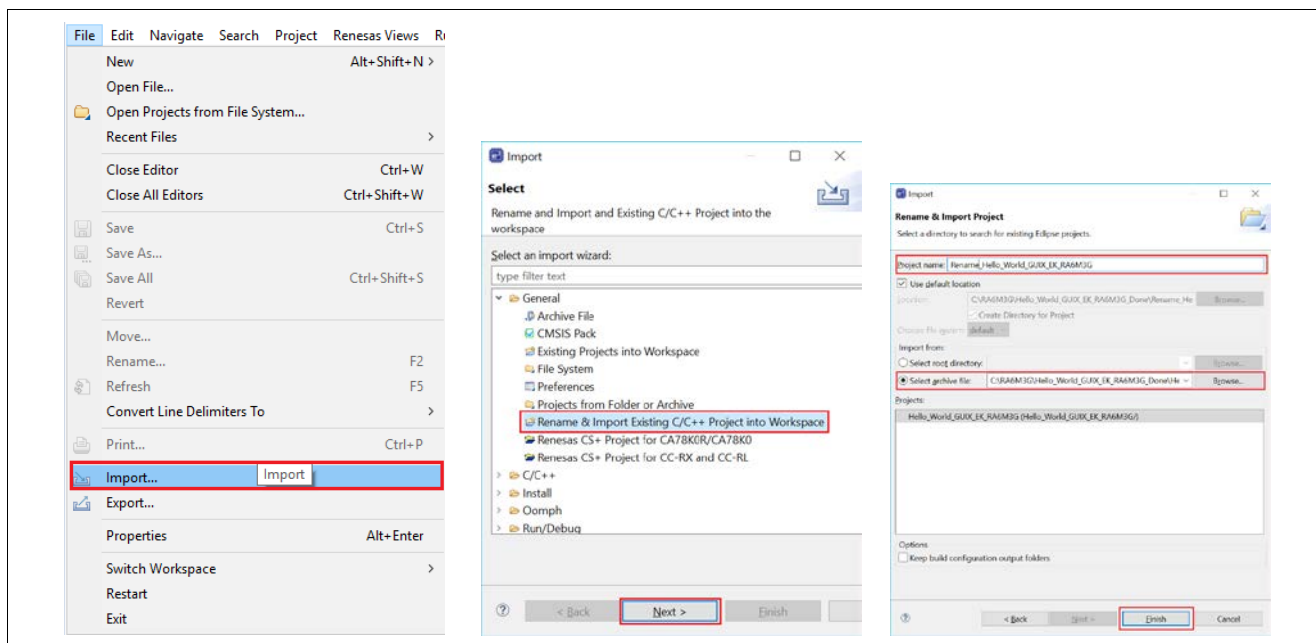


Figure 76. Import Existing Project

Website and Support

Visit the following vanity URLs to learn about key elements of the RA family, download components and related documentation, and get support.

RA Product Information	www.renesas.com/ra
RA Product Support Forum	www.renesas.com/ra/forum
RA Flexible Software Package	www.renesas.com/FSP
Renesas Support	www.renesas.com/support

Revision History

Rev.	Date	Description	
		Page	Summary
1.00	Nov.12.21	—	First release document

General Precautions in the Handling of Microprocessing Unit and Microcontroller Unit Products

The following usage notes are applicable to all Microprocessing unit and Microcontroller unit products from Renesas. For detailed usage notes on the products covered by this document, refer to the relevant sections of the document as well as any technical updates that have been issued for the products.

1. Precaution against Electrostatic Discharge (ESD)

A strong electrical field, when exposed to a CMOS device, can cause destruction of the gate oxide and ultimately degrade the device operation. Steps must be taken to stop the generation of static electricity as much as possible, and quickly dissipate it when it occurs. Environmental control must be adequate. When it is dry, a humidifier should be used. This is recommended to avoid using insulators that can easily build up static electricity.

Semiconductor devices must be stored and transported in an anti-static container, static shielding bag or conductive material. All test and measurement tools including work benches and floors must be grounded. The operator must also be grounded using a wrist strap. Semiconductor devices must not be touched with bare hands. Similar precautions must be taken for printed circuit boards with mounted semiconductor devices.

2. Processing at power-on

The state of the product is undefined at the time when power is supplied. The states of internal circuits in the LSI are indeterminate and the states of register settings and pins are undefined at the time when power is supplied. In a finished product where the reset signal is applied to the external reset pin, the states of pins are not guaranteed from the time when power is supplied until the reset process is completed. In a similar way, the states of pins in a product that is reset by an on-chip power-on reset function are not guaranteed from the time when power is supplied until the power reaches the level at which resetting is specified.

3. Input of signal during power-off state

Do not input signals or an I/O pull-up power supply while the device is powered off. The current injection that results from input of such a signal or I/O pull-up power supply may cause malfunction and the abnormal current that passes in the device at this time may cause degradation of internal elements. Follow the guideline for input signal during power-off state as described in your product documentation.

4. Handling of unused pins

Handle unused pins in accordance with the directions given under handling of unused pins in the manual. The input pins of CMOS products are generally in the high-impedance state. In operation with an unused pin in the open-circuit state, extra electromagnetic noise is induced in the vicinity of the LSI, an associated shoot-through current flows internally, and malfunctions occur due to the false recognition of the pin state as an input signal become possible.

5. Clock signals

After applying a reset, only release the reset line after the operating clock signal becomes stable. When switching the clock signal during program execution, wait until the target clock signal is stabilized. When the clock signal is generated with an external resonator or from an external oscillator during a reset, ensure that the reset line is only released after full stabilization of the clock signal. Additionally, when switching to a clock signal produced with an external resonator or by an external oscillator while program execution is in progress, wait until the target clock signal is stable.

6. Voltage application waveform at input pin

Waveform distortion due to input noise or a reflected wave may cause malfunction. If the input of the CMOS device stays in the area between V_{IL} (Max.) and V_{IH} (Min.) due to noise, for example, the device may malfunction. Take care to prevent chattering noise from entering the device when the input level is fixed, and also in the transition period when the input level passes through the area between V_{IL} (Max.) and V_{IH} (Min.).

7. Prohibition of access to reserved addresses

Access to reserved addresses is prohibited. The reserved addresses are provided for possible future expansion of functions. Do not access these addresses as the correct operation of the LSI is not guaranteed.

8. Differences between products

Before changing from one product to another, for example to a product with a different part number, confirm that the change will not lead to problems. The characteristics of a microprocessing unit or microcontroller unit products in the same group but having a different part number might differ in terms of internal memory capacity, layout pattern, and other factors, which can affect the ranges of electrical characteristics, such as characteristic values, operating margins, immunity to noise, and amount of radiated noise. When changing to a product with a different part number, implement a system-evaluation test for the given product.

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