VFA, CFA, Bipolar or CMOS - Which High-Speed Amplifier Is Best for Your Low-Noise Application?

**Introduction**

Ten years ago, the bandwidth of a state-of-the-art high-speed amplifier was 200MHz. With advancements in fabrication processes, current high-speed amplifiers have broken the GHz barrier. Savvy engineers look for more than speed in making their amplifier selections. The most defining characteristic of a high-speed amplifier is its feedback topology, using voltage feedback or current feedback. The strengths and limitations of each topology reveal its optimal uses.

The basic circuit topologies of voltage-feedback amplifiers (VFAs) and current-feedback amplifiers (CFAs) are presented here. The differences in topology are correlated to noise and distortion performance. Details about these performance limitations accompany typical values. Since both topologies will be presented in their bipolar implementation, a CMOS example is also included for a complete introduction into high-speed amplifier options.

**Voltage-Feedback Amplifier (VFA) Topology**

Voltage-feedback amplifiers are the most common operational amplifier topology. As most of us learned in college circuits classes, there are three stages: differential input stage, gain/level-shift stage, and output stage. Figure 1 presents a simplified schematic of the EL5157, a popular voltage-feedback amplifier.

![Figure 1. VFA Circuit Topology](image)

The input stage is an NPN differential pair in parallel with a PNP pair. The second stage consists of a pull-up current source. Note that any difference (signal or error) in the currents of the signal-path transistors appears across the output impedance of the current source at the high impedance node. The output stage buffers the high impedance node to the output.

**Current-Feedback Amplifier (CFA) Topology**

Current-feedback amplifiers have a very different input structure. In fact, the input stage has a unity gain buffer between its inverting and noninverting inputs. This gives the CFA topology some distinct advantages that will be discussed later. Their popularity lagged voltage-feedback designs until the emergence of the fully complementary bipolar process. Fortunately, these processes are widely available today, so CFAs can exploit the fact that current switching is faster than voltage switching in bipolar circuits (all other things being equal).

A simplified schematic is shown Figure 2. The non-inverting input is high impedance and is buffered to the inverting input (see dashed box). The input impedance of the inverting input is very low and its signal reaches the high impedance node through current mirrors. The high impedance node, Z, is buffered to the output.

![Figure 2. CFA Circuit Topology](image)

A higher-level look at the CFA structure highlights its advantages, so a simplified model is presented in Figure 3. Any voltage difference across the feedback resistor (RF) creates an error current into the inverting input. Since the impedance at the inverting input is low, this feedback is a current. A CFA is also called a transimpedance amplifier.
because any change in the inverting input current results in a change of output voltage. It is noteworthy that the inverting input is capable of sourcing and sinking high transient currents, since it is not limited by a bias current. The current mirrors supply current on demand to the high impedance node from the power supply, giving CFAs high slew rates. A unity-gain buffer completes the circuit, driving the output to the voltage required to minimize the feedback error current.

Op Amp Noise Calculations

A classical noise model of an operational amplifier with feedback is presented in Figure 4. It shows all of the possible noise sources, including thermal noise (also called Johnson noise) voltages for the external feedback and gain resistors. While the resistor noise sources do not change versus frequency, the voltage and current noise sources in association with the op amp have frequency characteristics. Therefore, plots of input voltage and current noise are given in op amp datasheets.

The two main components of noise inside op amps are flicker noise and white noise. Flicker noise, also called 1/f noise because its contribution is inversely proportional to frequency, dominates at low frequencies (less than a few megahertz for CMOS and inside a few kilohertz for bipolar designs). White noise includes contributions of shot noise from bias currents and thermal noise from resistances in devices and other circuit structures. With its flat amplitude characteristic with respect to frequency, white noise dominates at medium and high frequencies. Table 1 lists the types of noises and their mathematical equivalents.

<table>
<thead>
<tr>
<th>TYPE OF NOISE</th>
<th>CALCULATION</th>
</tr>
</thead>
<tbody>
<tr>
<td>Thermal Noise (Johnson Noise)</td>
<td>V_{JN} = \sqrt{4KTR_0f}</td>
</tr>
<tr>
<td>Shot Noise</td>
<td>I_{SN} = \sqrt{2qIDCf}</td>
</tr>
<tr>
<td>Flicker Noise (1/f Noise)</td>
<td>I_{FN} = \sqrt{k_0IDC^aR^bf}</td>
</tr>
</tbody>
</table>

where
- K = Boltzmann’s constant (1.38 x 10^{-23} J/K)
- T = absolute temperature in Kelvin (0°C = 273 Kelvin)
- R = resistance of component/device
- IDC = DC current
- q = charge on an electron (1.6 x 10^{-19} C)
- f = system bandwidth
- f = center frequency of operation
- a = fabrication constant (ranges from 0.5-2)
- b = constant (approximately = 1)

By convention, noise quantities are input-referred. This means the value presented is the amount that would appear at the input to cause the resultant noise at the circuit output. For example, if a noise source exists at the output of an amplifier, it would be divided by the closed-loop gain to become input-referred. With all of the noise referred to the same node, the influence of various noise contributions can be compared and combined.

For the amplifier example in Figure 4, the noise sources can be calculated as shown in Table 2. To facilitate comparison, all noise sources have been presented in terms of voltage.

The third column identifies the voltage gain experienced by each noise source.

<table>
<thead>
<tr>
<th>NOISE SOURCE</th>
<th>NOISE (AS A VOLTAGE)</th>
<th>NOISE GAIN</th>
</tr>
</thead>
<tbody>
<tr>
<td>Input Voltage Noise</td>
<td>V_n</td>
<td>1 + R_F/R_G</td>
</tr>
<tr>
<td>Inverting Input Current Noise</td>
<td>I_{IN} * R_F</td>
<td>1</td>
</tr>
<tr>
<td>Noninverting Input Current Noise</td>
<td>I_{IN} * R_{ninV}</td>
<td>1 + R_F/R_G</td>
</tr>
<tr>
<td>Johnson Noise of R_F</td>
<td>Sqrt(4KT*R_F)</td>
<td>1</td>
</tr>
<tr>
<td>Johnson Noise of R_G</td>
<td>Sqrt(4KT*R_G)</td>
<td>- R_F/R_G</td>
</tr>
<tr>
<td>Johnson Noise of R_{ninV}</td>
<td>Sqrt(4KT*R_{ninV})</td>
<td>1 + R_F/R_G</td>
</tr>
</tbody>
</table>
Noise is a random quantity. The average voltage of a noise source is zero, just as the average voltage of a sine wave is zero. However, the average power is NOT zero. Therefore, when summing the contributions of different noise sources, we add the power of each noise contributor to get the total power. Power is proportional to voltage squared and inversely proportional to the impedance of that node:

\[ P = I \times V = \frac{(V/R)}{V} = \frac{V^2}{R} \]

EQ.1

With all of the noise sources referred to the same node, they will be across the same impedance. Therefore, we can calculate the total noise power at that point. If the related total voltage is desired, the answer lies in the reversal of Equation 1.

These noise sources in Table 2 are uncorrelated and can be summed as described in the preceding paragraphs. Correlated noise sources are generated by a single or dependent source, relating the behavior of one source to another. Since correlated noise sources have related noise behavior, the source powers cannot simply be added.

**VFA and CFA Noise Analysis**

To understand the noise differences between voltage-feedback and current-feedback amplifiers, one only needs to compare the architectural differences between their input stages (shown in Figure 1 and Figure 2.) The VFA input structure is a differential pair. Therefore, in bipolar technologies, the inputs are connected to bases of PNP and/or NPN transistor pairs. The currents through these nodes are small base currents, and since the noise current is proportional to the amount of base current, a low input noise current results.

The current-feedback amplifier, on the other hand, has two inputs connecting to very different structures. The noninverting op amp input connects to the base of bipolar transistors, so the noise current is comparable to the inputs of VFAs. Conversely, the inverting op amp input is the buffer's output, typically NPN and PNP emitters. Since emitter current is much larger than base current (by a factor of beta), the noise is proportionally higher as well. CFA inverting input noise currents typically run in the 20-30pA/√Hz range, compared to the VFA's 1-5pA/√Hz typical range.

This larger noise current is transformed into a voltage through the feedback resistor, \( R_F \). Input-referred noise voltage is a more complicated parameter, being a function of not only the input transistors (primarily transistor base resistance and collector current), but also the type of load driven by the input stage. For our general case, it is sufficient to say that CFAs typically deliver an input noise voltage that is at least on a par with VFAs that haven't been optimized for low noise. Table 3 shows typical noise currents and voltages for a voltage-feedback amplifier, a current-feedback amplifier, and a CMOS amplifier (for comparison).

| TABLE 3. TYPICAL VALUES FOR NOISE QUANTITIES IN VFA, CFA AND CMOS TOPOLOGIES |
|-----------------|-----------------|-----------------|
| VFA            | CFA            | CMOS           |
| Vn             | 0.86nV/√Hz     | 4nV/√Hz        | 20nV/√Hz       |
| In-            | 1.4pA/√Hz      | 20pA/√Hz       | 2fA/√Hz        |
| In+            | 1.4pA/√Hz      | 8pA/√Hz        | 2fA/√Hz        |

In a voltage-feedback amplifier, the circuit has been optimized for sensitivity to the voltage difference at the input. Therefore, the voltage noise contribution is the lowest of the three. The current noise at both inputs is low because the base current into each terminal is small.

For the current-feedback amplifier, the feedback node has emitter current flowing instead of a base current. This larger current will naturally have a larger current noise associated with it.

In the CMOS case, the input is purely capacitive. A simplified schematic is presented in Figure 5. The input is again a differential pair. Since both inputs connect to the gate of MOSFETs which allows virtually zero current flow, only the voltage determines the output signal. This explains the CMOS amplifier's low level of input current noise. The input voltage noise, while higher in the CMOS case, is still within an order of magnitude of the other two examples. So if the voltage gain is low, as in transimpedance amplifiers, then the higher level of noise is inconsequential. A drawback to CMOS amplifiers is that the 1/f knee frequency is inversely proportional to the device channel lengths, so the more advanced the process the higher the frequency of the 1/f knee.
**VFA and CFA Distortion Characteristics**

At low frequencies, voltage-feedback amplifiers provide the lowest distortion. The differential-pair input stage acts much like an electronic see-saw. When provided with negative feedback, the op amp attempts to level the see-saw. Distortion values from the datasheets of typical CFA and VFA amplifiers are provided in Figures 6A and 6B. Of course, there are products on the market that do not follow these curves. Check the datasheet before choosing an amplifier for your application.

2nd and 3rd Harmonic Distortion

The current-feedback amplifier accepts a voltage at the noninverting input and a current at the inverting input. The see-saw effect is still there, but only after Vin+ is translated into a current. This translation is imperfect, introducing errors which appear in the 2nd harmonic distortion. At higher frequencies, the majority of loss comes from slew rate limitations. Since CFAs have higher slew rate than VFAs, they exhibit lower distortion characteristics at high frequencies. Also note that current feedback amplifiers give relatively constant distortion results for different gain settings.
Voltage-Feedback Example Application-
xDSL Line Driver and Receiver

In xDSL systems, communication signals are transmitted through telephone lines that can reach lengths of 20,000 feet. The receiving signal can be as low as 30mV with a 4MHz bandwidth. A low noise amplifier is required to amplify the receive signal. The signal must also be filtered to remove the high frequency noise from the lower frequency transmit signal.

The closed-loop gain of the line receiver is at least 30V/V and the analog-to-digital converter of the driver front end has 14-bit resolution. To fully utilize the full range of the 14-bit ADC, the signal-to-noise ratio of the input must be greater than 84.3dB. For example, a 20mV input signal would require a noise level under 1.2mV. The limit of the amplifier's input voltage noise is then 0.9nV/√Hz with a 4MHz bandwidth. A voltage feedback amplifier is preferred—not only for its low input voltage noise, but also for the fact that VFA's are more flexible in active filter configurations.

Current-Feedback Example Application-
Driving an ADC

An application where CFAs excel is driving high speed, high resolution ADCs, especially for pulsed inputs. A distinct CFA advantage for this application is that the CFA's output rise time remains nearly constant, regardless of the output step size. The slewing current is equivalent to the inverting input current during transients, which is a function of the voltage difference across RF. Therefore the CFA's slew rate actually increases as the step size increases. Whereas a VFA may become slew-rate limited for voltage swings less than 1V, CFAs typically do not reach slew-rate limit for steps less than several volts.

In addition to the CFA's slew-rate advantage, its exceptional bandwidth (be careful, because excess BW still contributes to total noise), distortion, settling time, and relatively low supply current make it a prime contender for ADC drivers. For example, the EL5166 is an excellent choice for driving 14 bit ADCs, due to its 1.4GHz bandwidth, 6000V/µs slew rate, and 70dB second harmonic distortion at 20MHz. With ADC drivers, the load presented by the CFA's feedback network is not usually a concern. This allows the designer to utilize low resistance feedback resistors to minimize noise contribution, while maximizing the CFA's performance.

CMOS Example Application-
Transimpedance Amplifier/Photodetector

Wide bandwidth and low input bias and noise currents make modern high-speed CMOS amplifiers ideal choices for photodiode transimpedance amplifiers. The key elements in a transimpedance design, as shown in Figure 7, are capacitance at the inverting input (including diode capacitance, input capacitance from the amplifier, and parasitic capacitance), the transimpedance gain set by RF, low input current noise to allow wide dynamic range, and sufficient Gain-Bandwidth. With these three variables set, a feedback capacitor in parallel with RF is often needed to control the frequency response and ensure stability.

If the amplifier is a rail-to-rail, single-supply device, the noninverting input can be connected to ground, allowing the output to reach true zero when the photodiode is not exposed to any light. This allows the circuit to avoid the delay the output would need to travel from the negative rail.

To achieve the best performance, components should be selected according to the following guidelines:

1. For lowest overall system noise, select RF to provide all the required gain in the transimpedance stage. Since the CMOS amp has virtually no current noise, a lower value of RF (to lower the noise of the transimpedance stage), would necessitate including additional gain stages, ultimately producing poorer overall noise performance. The noise produced by RF increases as the square root of resistance, whereas the signal value increases linearly, therefore, signal-to-noise ratio is improved when all of the required gain is placed in the transimpedance stage.

2. Minimize capacitance at the inverting input. This capacitance causes the voltage noise of the op amp to be amplified. A low-noise voltage source to reverse-bias a photodiode can significantly reduce its capacitance. Smaller photodiodes have lower capacitance. Use optics to concentrate light on a small photodiode.

3. Limit the circuit bandwidth to only that required, since noise increases with increased bandwidth. Use a capacitor across the feedback resistor to limit bandwidth, even if not required for stability.

4. Circuit board leakage can degrade the performance of an otherwise well-designed amplifier. Clean the circuit board carefully. A circuit board guard trace that encircles the summing junction (inverting input) and is driven at the same voltage can help control leakage.
Conclusion

Both current- and voltage-feedback amplifier topologies are popular choices for high-speed applications. An understanding of the differences in circuit topology along with basic noise and distortion characteristics are crucial for optimal product selection. Table 4 summarizes the discussion and examples presented.

**TABLE 4. SUMMARY OF OP AMP TOPOLOGIES, STRENGTHS, AND APPLICATIONS**

<table>
<thead>
<tr>
<th>TOPOLOGY</th>
<th>STRENGTHS</th>
<th>EXAMPLE USE</th>
</tr>
</thead>
</table>
| VFA      | Input Symmetry  
            Low Input Voltage and Current Noise  
            Low Distortion @ Low Frequency | Communications Systems |
| CFA      | Slew Rate  
            Bandwidth  
            Low Distortion @ High Frequency | ADC Driver |
| CMOS     | Dynamic Range  
            Rail-to-Rail Operation  
            Lowest Input Current Noise | Transimpedance Amplifier/Photodetector |
Notice

1. Descriptions of circuits, software and other related information in this document are provided only to illustrate the operation of semiconductor products and application examples. You are fully responsible for the incorporation or any other use of the circuits, software, and information in the design of your product or system. Renesas Electronics disclaims any and all liability for any losses and damages incurred by you or third parties arising from the use of these circuits, software, or information.

2. Renesas Electronics hereby expressly disclaims any warranties against infringement or any other claims involving patents, copyrights, or other intellectual property rights of third-parties, by or arising from the use of Renesas Electronics products or technical information described in this document, including but not limited to, the product data, drawings, charts, programs, algorithms, and application examples.

3. No license, express, implied or otherwise, is granted hereby under any patents, copyrights or other intellectual property rights of Renesas Electronics or others.

4. You shall not alter, modify, copy, or reverse engineer any Renesas Electronics product, whether in whole or in part. Renesas Electronics disclaims any and all liability for any losses or damages incurred by you or third parties arising from such alteration, modification, copying or reverse engineering.

5. Renesas Electronics products are classified according to the following two quality grades: “Standard” and “High Quality.” The intended applications for each Renesas Electronics product depends on the product’s quality grade, as indicated below.

   - **“Standard”**: Computers, office equipment; communications equipment; test and measurement equipment; audio and visual equipment; home electronic appliances; machine tools; personal electronic equipment; industrial robots; etc.
   - **“High Quality”**: Transportation equipment (automobiles, trains, ships, etc.); traffic control (traffic lights); large-scale communication equipment; key financial terminal systems; safety control equipment; etc.

   Unless expressly designated as a high reliability product or a product for harsh environments in a Renesas Electronics data sheet or other Renesas Electronics document, Renesas Electronics products are not intended or authorized for use in products or systems that may pose a direct threat to human life or bodily injury (artificial life support devices or systems; surgical implants, etc.), or may cause serious property damage (space systems; undersea repeaters; nuclear power control systems; aircraft control systems; key plant systems; military equipment; etc.). Renesas Electronics disclaims any and all liability for any damages or losses incurred by you or any third parties arising from the use of any Renesas Electronics product that is inconsistent with any Renesas Electronics data sheet, user’s manual or other Renesas Electronics document.

6. When using Renesas Electronics products, refer to the latest product information (data sheets, user’s manuals, application notes, “General Notes for Handling and Using Semiconductor Devices” in the reliability handbook, etc.), and ensure that usage conditions are within the ranges specified by Renesas Electronics with respect to maximum ratings, operating power supply voltage range, heat dissipation characteristics, installation, etc. Renesas Electronics disclaims any and all liability for any malfunctions, failure or accident arising out of the use of Renesas Electronics products outside of such specified ranges.

7. Although Renesas Electronics endeavors to improve the quality and reliability of Renesas Electronics products, semiconductor products have specific characteristics, such as the occurrence of failure at a certain rate and malfunctions under certain use conditions. Unless designated as a high reliability product or a product for harsh environments in a Renesas Electronics data sheet or other Renesas Electronics document, Renesas Electronics products are not subject to radiation resistance design. You are responsible for implementing safety measures to guard against the possibility of bodily injury, injury or damage caused by fire, and/or damage to the public in the event of a failure or malfunction of Renesas Electronics products, such as safety design for hardware and software, including but not limited to redundancy, fire control and malfunction prevention, appropriate treatment for age degradation or any other appropriate measures. Because the evaluation of microcomputer software alone is very difficult and impractical, you are responsible for evaluating the safety of the final products or systems manufactured by you.

8. Please contact a Renesas Electronics sales office for details as to environmental matters such as the environmental compatibility of each Renesas Electronics product. You are responsible for carefully and sufficiently investigating applicable laws and regulations that regulate the inclusion or use of controlled substances, including without limitation, the EU RoHS Directive, and using Renesas Electronics products in compliance with all these applicable laws and regulations. Renesas Electronics disclaims any and all liability for damages or losses occurring as a result of your noncompliance with applicable laws and regulations.

9. Renesas Electronics products and technologies shall not be used for or incorporated into any products or systems whose manufacture, use, or sale is prohibited under any applicable domestic or foreign laws or regulations. You shall comply with any applicable export control laws and regulations promulgated and administered by the governments of any countries asserting jurisdiction over the parties or transactions.

10. It is the responsibility of the buyer or distributor of Renesas Electronics products, or any other party who distributes, disposes of, or otherwise sells or transfers the product to a third party, to notify such third party in advance of the contents and conditions set forth in this document.

11. This document shall not be reprinted, reproduced or duplicated in any form, in whole or in part, without prior written consent of Renesas Electronics.

12. Please contact a Renesas Electronics sales office if you have any questions regarding the information contained in this document or Renesas Electronics products.

(Note 1) “Renesas Electronics” as used in this document means Renesas Electronics Corporation and also includes its directly or indirectly controlled subsidiaries.

(Note 2) “Renesas Electronics products” means any product developed or manufactured by or for Renesas Electronics.