

AN-1066 Voltage Slope Direction Determination Circuit Author: Yurii Shchebel

Date: May 14, 2015

Introduction

This application note shows how to use a single GreenPAK IC to design a circuit to determine whether the input voltage is rising, falling, or constant in time.

Voltage slope direction determination circuit design

In this circuit, the ADC is connected to the SPI block. DCMP takes data from ADC and SPI. Signals from DCMP go to LUTs, DFF, P DLY, and DLYs, which are used to avoid glitches and form output signals.

Block configuration is presented in figures 2-10 below.

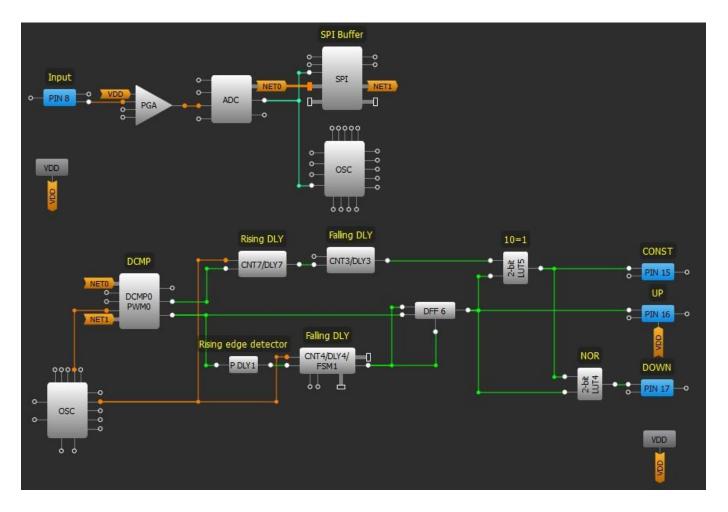


Figure 1. Voltage slope direction definer circuit schematic

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Voltage Slope Direction Determination Circuit

	PIN 8			
I/0 selection:	Analog input/output			
Input mode: OE = 0 Output mode:	Analog input			
OE = 1	Analog output			
Resistor:	(Floating			
Resistor value:	Floating 🗘			
	PIN 15			
I/O selection:	Digital output			
Input mode: OE = 0	None 🔷			
Output mode: OE = 1	1x push pull			
Resistor:	Floating \$			
Resistor value:	Floating 🔷			
PIN 16				
I/O selection:	Digital output			
I/O selection: Input mode: OE = 0	Digital output \$ None \$			
Input mode:				
Input mode: OE = 0 Output mode:	None 🔷			
Input mode: OE = 0 Output mode: OE = 1	None Ix push pull			
Input mode: OE = 0 Output mode: OE = 1 Resistor:	None \$ 1x push pull \$ Floating \$			
Input mode: OE = 0 Output mode: OE = 1 Resistor:	None \$ 1x push pull \$ Floating \$ Floating \$			
Input mode: OE = 0 Output mode: OE = 1 Resistor: Resistor value:	None 1x push pull 1x push pull Floating Floating PIN 17			
Input mode: OE = 0 Output mode: OE = 1 Resistor: Resistor value: I/O selection: Input mode:	None 1x push pull 1x push pull Floating Floating PIN 17 Digital output			
Input mode: OE = 0 Output mode: OE = 1 Resistor: Resistor value: I/O selection: Input mode: OE = 0 Output mode:	None 1x push pull 1x push pull Floating Floating Floating PIN 17 Digital output None			

Figure 2. Pins properties

		2-bit	LUT5		
IN3	IN2	IN1	INO	0	UT
0	0	0	0	0	\$
0	0	0	1	0	\$
0	0	1	0	1	\$
0	0	1	1	0	\$
		2-bit	LUT4		
IN3	IN2	IN1	INO	0	UT
0	0	0	0	1	\$
0	0	0	1	0	•
0	0	1	0	0	\$
0	0	1	1	0	\$

Figure 3. LUTs properties

DF	F/LATCH6	
Mode:	DFF	\$
nSET/nRESET option:	nRESET	\$
Initial polarity:	Low	\$
Q output polarity:	Non-inverted (Q)	•

Figure 4. DFF properties

	PGA	
Power on signal:	Power on	¢
Gain:	x1	\$
ADC mode:	Single-end	\$
Con	nections	
Channel selector:	VDD	•
IN+ Channel 1:	PIN 8	\$
IN+ Channel 2:	None	\$
IN- Channel:	None	\$

Figure 5. PGA properties

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Voltage Slope Direction Determination Circuit

ADC		
Mode:	Single-end	1\$
Vref:	Bandgap (1 V)	\$
Force analog part:	Disable	•
Analog part speed selection:	5 kHz	•
Clock for ADC divide by:	16	\$
ADC data sync with SPI clock:	Disable	\$
PWM & ADC clock source :	RC OSC	\$
Sample speed:	1.5625 kHz	ormula

Figure 6. ADC properties

	SPI	
Mode:	ADC/FSM buffer	¢
Clock phase (CPHA):	0	\$
Clock polarity (CPOL):	0	\$
Byte selection:	[15:0]	\$
ADC data sync with SPI clock:	Disable	\$
PWM data sync with SPI clock:	Disable	\$
FSM data sync with SPI clock:	Disable	\$
Cor	inections	
PAR input data source:	ADC	\$
Serial data:	Disable (Matrix <-	> \$

Figure 7. SPI properties

DCMP0/PWM0		
DCMP/PWM power register:	Power on	\$
Function selection:	DCMP	•
PD sync to clock:	Off	•
Clock source:	OSC X CLK	\$
Clock invert:	Disable	\$
PWM & ADC clock source :	RC OSC	\$
PWM data sync with SPI clock:	Disable	•
Duty cycle:	0% - 99.6%	\$
PWM deadband time:	10 ns	\$
Register 0: MTRX SEL: (0:0)	0	*
Register 1: MTRX SEL: (0:1)	0	*
Register 2: MTRX SEL: (1:0)	0	*
Register 3: MTRX SEL: (1:1)	0	*
Cor	nections	
IN+ selector:	ADC [7:0]	
IN- selector:	SPI [7:0]	\$

Figure 8. DCMP properties

P DLY1		
Mode:	Rising edge detecte	
Delay:	4 Cells	
Output mode:	Non-delayed	

Figure 9. P DLY properties

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14-bit CNT3/DLY3			
Mode:	Delay 🗘		
Counter data:			
Dalau Kana	(Range: 1 - 16383) 48.1000 ms Formula		
Delay time:	46.1000 ms <u>Formula</u>		
Edge select:	Falling		
Q mode:	None 🗍 🌩		
DFF bypass enable:	None 🔷		
Co	nnections		
FSM data:	None		
Clock:	СLК 🔷		
Clock source:	OSC Freq.		
8-bit CM	T4/DLY4/FSM1		
Mode:	Delay		
Counter data:	200		
	(Range: 1 - 255)		
Delay time:	32.4000 ms Formula		
Edge select:	Falling 🔷		
Q mode:	Reset 🔷		
DFF bypass enable:	None 🔷		
FSM data sync with SPI clock:	Disable 🔷		
Co	nnections		
FSM data:	Counter data		
Clock:	CLK /4		
Clock source:	CLK Freq. / 4		
8-00	CNT7/DLY7		
Mode:	Delay 🗢		
Counter data:	75		
	(Range: 1 - 255)		
Delay time:	12.4000 ms Formula		
Edge select:	Rising		
Q mode:	None 😫		
DFF bypass enable:	None \$		
Connections			
FSM data:	None \$		
Clock:	CLK /4		
Clock source:	CLK Freq. / 4		

Figure 10. DLYs properties

Voltage slope direction determination circuit analysis

The Analog signal comes from Input 8 to the PGA block with 1x gain. It then goes to the ADC input. The ADC operates in single-ended mode and converts the analog signal to an 8-bit digital code. The ADC transfers the parallel signal to the SPI block, configured as ADC/FSM Buffer, where digital code can be stored and won't change until the next CLK clock comes to SPI SCLK input. The DCMP is used to compare current and previous ADC data, which is stored in the SPI block. SPI takes the CLK from ADC INT OUT, because only one pulse is needed to reload the SPI Buffer code and the DCMP for the 8-bit code comparison. In addition, the ADC INT OUT signal is coordinated in time with the ADC parallel data (see figure 11).

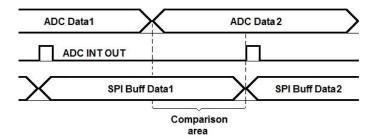


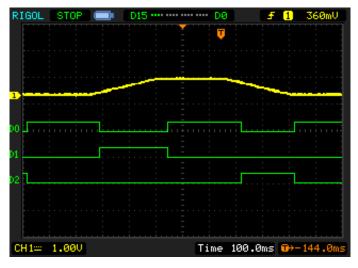
Figure 11. ADC and SPI Buffer timing diagram

If the voltage is rising, then the ADC Data2 8-bit code is greater than the ADC Data1 code (SPI Buffer Data1). In this situation we will receive pulses from the DCMP OUT+ (OUT+ will go high in Comparison area (see Figure 11)). Rising edge detector (P DLY), Falling edge DLY and DFF6 are used to check if pulses from DCMP are regularly repeated. If they are, UsilP output will go high.

If voltage is constant we will receive a high level signal from the DCMP EQ output. Rising edge DLY7 and Falling edge DLY3 are used to eliminate short pulses on this output. UP output priority is higher than CONSTANT output thanks to 2-bit LUT5. So if UP output is high, CONSTANT output will stay low.



If CONSTANT output is low and UP output is low, DOWN output goes high.



⁽CH1 – Input voltage; D0 – CONST; D1 – UP; D2 – DOWN)

Figure 12. Voltage slope direction definer functional diagram (First case)

Conclusion

A simple device that can detect whether an input voltage is rising, falling, or constant can be easily implemented using ADC, SPI, DCMP, and some additional blocks, which helps to form the output signals. All this functionality is contained in a single SLG46620 IC.

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