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# MOTOR SOLUTIONS

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User-Friendly Motor Control Development Environment to Shorten Time to Market

## RENESAS MOTOR SOLUTIONS FOR A GREENER SOCIETY

Renesas offers semiconductor products with low environmental impact throughout their life cycle in the interest of coexistence with the planet and harmony between humankind and the environment.

As the scope of motor applications has broadened in recent years, Renesas semiconductor devices for motors have come to be used in a wide variety of fields. Renesas provides customers with optimal motor solutions to help realize a greener society.

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## Powerful Support for Customers' Development Efforts **Motor Solutions**

### **Basic Motor Control Configuration**



### **Motor Solution Classification**

Renesas motor solutions are comprised of devices, hardware, software, and tools.



### High Availability and Easy Operation

- Tools and software can be downloaded free of charge from the web, and anyone can feel free to use them.
- The solution kit can be purchased from an online shop, and you can easily control the motor by using the support tool downloaded from the web.





### **Motor Types and Features**

There are various types of motors and the applications used differ according to their features. Renesas offers solutions for permanent magnet synchronous motors (brushless DC motors), stepping motors and induction motors.

### **Motor Types**

The classification of motors is an example, and various other motors exist.

DC Motor

- Brushed motor
- Brushless DC motor (BLDC)

#### Stepper Motor (Stepping motor)

- Permanent magnet stepper (PM type)
- Variable reactance stepper (VR type)
- Hybrid synchronous stepper (HB type)

#### AC Motor

- Induction motor (Single phase/Three phases)
- Synchronous motor (SPM, IPM, SynRM)
- Commutator motor
- Other Motor
- Ultrasonic motor
- Switched reluctance motor

### **Motor Features**

#### **Brushless DC Motor (BLDC)**

A motor that can rotate without using mechanical contacts (brushes) by using an inverter circuit. A permanent magnet is used for the rotor, and the position of the rotor is detected by a position sensor or sensorless position estimation to control the motor drive. Thanks to its features of small size, high output, high rotation speed and long life, it is used in various applications such as home appliances, OA equipment, automobiles and medical equipment.

 $\Rightarrow$  Renesas offers a variety of brushless DC motor solutions.

### **Stepper Motor**

A motor that rotates based on the pulse signal input to the drive circuit and is mainly used in industrial robots and printers that require position control. There are PM type that uses a permanent magnet for the rotor, VR type that uses a gear-shaped iron core for the rotor, and HB type that has the characteristics of both PM type and VR type. Generally, open loop control which does not require feedback is used, but an increasing number of more advanced applications use sensor output as feedback.

⇒ Renesas offers solutions for stepping motors employing resolver sensors.

#### Induction Motor

It is a motor that rotates by magnetic induction. By directly inputting AC power to the motor, it can rotate without a special drive unit. Vector control using a drive unit such as an inverter enables variable speed operation and high-efficiency operation according to the load. Mainly used in industrial machines such as fans, pumps, conveyors and trains.

⇒ Renesas offers induction motor solutions for applications such as fans and pumps.



Motor structure



Applications





A-phase



Motor structure





Applications

### **Motor Control Method**

Methods for driving motors are introduced below. Renesas provides sample code for 120-degree conducting control (trapezoidal control) and vector control applications. Each sample provides specific features and utilizes a control method suited to a particular application. They can be downloaded from the Renesas website and used as reference when developing your own programs.

### **120-Degree Conducting Control (Square Wave Control)**

Features

- Simple control method with low software load
- It is susceptible to load fluctuation due to the control method that does not detect current
- Precision and efficiency are inferior to vector control

In this control, two of the three coils of the BLDC motor are energized, and six energizing patterns are switched.



#### Features

- Advanced control method that detects current and performs fine control
- Highly accurate and efficient control can be realized
- Complex processing is required, and software load is high

In this control, by energizing all three coils and finely controlling the rotating magnetic field, smoother driving is possible compared to 120-degree conducting control. A feature of vector control is that the three-phase AC values are coordinate-converted into two-phase DC values to facilitate control.



Energizing Mode	Energized Phase	Resultant Flux
1	U→W	<u>به</u> ۲
2	U→V	, Å, 🖌
3	W→V	, 📥 🔶 🔶
4	W→U	,Å. 🔪
5	V→U	Å. 1
6	V→W	☆ →

Image of energization pattern for 120-degree conducting control



Image of coordinate conversion by vector control (3-phase motor)

### Position Sensor of Motor

The required sensor is different between when controlling the "motor speed" like a fan and when controlling the "motor position" like a robot. Each sensor has its own features, and the appropriate sensor is used according to the application. Renesas offers sample code that uses typical types of motor control position sensors, such as Hall sensors, encoders, resolvers, inductive sensors, and magnetic sensors. We also provide sample code for "position sensor-less" control that does not use position sensors.

### **Hall Sensor**

- It is mainly used as an output for switching of energization of 120-degree conducting control with three hall sensors.
- It is also possible to control the motor speed based on the output of hall sensor.
- Because of its low cost, the output may be used for purposes such as functional safety.

### Encoders and Magnetic Sensors

- There are optical encoders that use light emitting and receiving elements and slits, and magnetic sensors that use a custom IC and a magnet for sensing. Among magnetic sensors, the type of angular information output, such as analog output, digital output, or SPI output, differs depending on the product.
- Wide lineup from inexpensive low resolution to expensive high resolution.
- High resolution encoders are used in robots and AC servos.
- There is also an absolute type that can detect the absolute position.

### Resolver

- A sensor that detects the position based on the magnetic fluctuation between the rotor and stator.
- It is highly resistant to external factors such as dust, heat, and vibration, and is mainly used in the automotive and industrial fields.
- A resolver digital converter is used to obtain the analog signal at the output of the resolver and use it for control.
- High accuracy is possible by correcting/removing resolver winding error and output signal noise.

### **Inductive Position Sensors**

- The position is detected by means of electromagnetic induction by using a position sensor employing a coil.
- Resistant to external factors such as dust, heat and vibration.
- There are products that do not use magnets for detection, and products that are made smaller by supplementing the coil with a board pattern.



Motor with hall sensor



Magnetic sensor



Motor with resolver



Induction sensor image

Encoder

### **Renesas Solutions for Motor Types and Control Methods**

Renesas provides kits and motor control sample code for different types of motors and MCUs. Since the sample code available for each kit differs, refer to the appropriate solution in the correspondence table below.

### Renesas Kit by Motor Type

					Vector Control		120-D Conductin			
Motor Type	Name of Kit Used	Reference Page			Encoder	Magnetic Sensor Inductive Sensor	Resolver	Sensorless	Hall	Open-Loop Mode
			Speed Control	Position Control	Speed Control/ Position Control	Speed Control/ Position Control	Speed Control/ Position Control	Speed Control	Speed Control	
	Evaluation System for BLDC Motor + CPU card (P/N: RTK0EMX270S00020BJ)	7	$\checkmark$	-	-	-	-	$\checkmark$	$\checkmark$	-
	Motor Control Evaluation System for RA Family - RA6T1 Group (P/N: RTK0EMA170S00020BJ)	-	$\checkmark$	-	$\checkmark$	-	-	$\checkmark$	$\checkmark$	-
	MCK-RA6T2 (P/N: RTK0EMA270S00020BJ)	8	$\checkmark$	_	-	-	-	$\checkmark$	$\checkmark$	-
	MCK-RA6T3 (P/N: RTK0EMA330S00020BJ)	8	$\checkmark$	-	-	-	-	$\checkmark$	$\checkmark$	-
	MCK-RA4T1 (P/N: RTK0EMA430S00020BJ) []	8	$\checkmark$	-	-	-	-	$\checkmark$	$\checkmark$	-
BLDC motor	MCK-RA8T1 (P/N: RTK0EMA5K0S00020BJ)	8	$\checkmark$	-	-	-	-	$\checkmark$	$\checkmark$	-
	MCK-RX26T (P/N: RTK0EMXE70S00020BJ)	8	$\checkmark$	$\checkmark$	-	-	-	$\checkmark$	$\checkmark$	-
	RL78/G24 Motor Control Evaluation Kit (P/N: RTK0EMG24SS00000BJ)	10	$\checkmark$	-	-	-	-	$\checkmark$	$\checkmark$	-
	RZ/T2M Motor Solution Kit	11	-	-	$\checkmark$	-	-	-	-	-
	<u>MCI-HV-1</u> (P/N: RTK0EM0000B14030BJ) [プ	9	-	$\checkmark$	$\checkmark$	-	-	-	-	-
	RZ/T Series Inverter board (P/N: RTK0EM0000B15010BJ)	12	-	-	$\checkmark$	-	-	-	-	-
AC synchronous motor	RZ/T2M, RZ/T2L, and RZ/N2L Motor Solution Kits (AC 220V Version)	13	-	-	$\checkmark$	-	-	-	-	-
	Evaluation System for Stepping Motor with Resolver (P/N: RTK0EMX270S01020BJ)	15	_	_	-	-	$\checkmark$	-	-	-
Stepping motor	HVPAK <sup>™</sup> SLG47105 DC/Stepper Motor and LED Control Demonstration Board [2]	29	-	-	-	-	-	-	-	$\checkmark$
	HVPAK SLG47105 Evaluation Board []	29	_	-	-	-	_	-	-	$\checkmark$

### Renesas Kit + Motor with Sensor

It is necessary for the customer to prepare a motor with sensor.

				Vector	120-Degree Conducting Control			
Motor Type	Name of Kit Used	Reference Page	Sensorless	Encoder	Magnetic Sensor Inductive Sensor	Resolver	Sensorless	Hall
			Speed Control	Speed Control/ Position Control	Speed Control/ Position Control	Speed Control/ Position Control	Speed Control	Speed Control
	Evaluation System for BLDC Motor + CPU card (P/N: RTK0EMX270S00020BJ)	7	_	$\checkmark$	$\checkmark$	_	_	_
	MCK-RA6T2 (P/N: RTK0EMA270S00020BJ)	8	-	$\checkmark$	$\checkmark$	-	-	-
BLDC	MCK-RA6T3 (P/N: RTK0EMA330S00020BJ)	8	-	$\checkmark$	$\checkmark$	-	—	_
	MCK-RA4T1 (P/N: RTK0EMA430S00020BJ)	8	-	$\checkmark$	$\checkmark$	-	-	-
	MCK-RA8T1 (P/N: RTK0EMA5K0S00020BJ)	8	-	$\checkmark$	$\checkmark$	-	-	-
	MCK-RX26T (P/N: RTK0EMXE70S00020BJ)	8	-	$\checkmark$	-	-	_	_

### Sample Software/Application Note Provided by Renesas

It is necessary for the customer to prepare a motor and an inverter board.

Motor Type	Name of Kit Used			Vector	Control		120-D Conductir	egree Ig Control
		Reference Page	Sensorless	Encoder Magnetic Sensor Resolver		Resolver	Sensorless	Hall
			Speed Control	Speed Control/Position Control	Speed Control/Position Control	Speed Control/Position Control	Speed Control	Speed Control
Induction motor	Evaluation System for ACIM	16	$\checkmark$	-	_	-	-	-

Renesas offers permanent magnet synchronous motor solutions to support customers' evaluation and development. Supported devices differ, so please select a solution that uses the product you are considering.

### Evaluation System for BLDC Motor

Compatible CPU cards, sample code, and a development support tool are provided so you can get started with motor control immediately after purchase.

Features

- Motor control kit that supports up to DC48V input.
- Supports Renesas Motor Workbench for easy debugging.
- Equipped with overcurrent protection function.
- Various motor control MCUs can be evaluated in combination with an optional CPU card.



### Kit specifications

ltem	Specification				
Kit name	Evaluation System for BLDC Motor				
Kit model No.	RTK0EMX270S00020BJ				
Structure	48V 5A Inverter board for BLDC motor				
Structure	BLDC motor (TG-55L-KA)				
	Rated voltage: 48V				
Inverter specification	<ul> <li>Rated current: 5A (continuous)</li> </ul>				
	Protect function: Overcurrent detection, others				

Available Sample Code for Evaluation

			Supported MCUs										
Item		RL78 Family	8 Family RX Family										
		RL78/G1F	RX13T	RX23T	RX24T	RX24U	RX66T	RX72T	RX72M	RA6T1			
120-degree conducting control + speed control (Hall sensor, sensorless)		$\checkmark$	$\checkmark$	$\checkmark$	$\checkmark$	-	-	-	-	~			
· · · · · · · · · · · · · · · · · · ·	Sensorless	$\checkmark$	$\checkmark$	$\checkmark$	$\checkmark$	$\checkmark$	$\checkmark$	$\checkmark$	$\checkmark$	$\checkmark$			
	Encoder (A/B)	-	$\checkmark$	$\checkmark$	$\checkmark$	$\checkmark$	$\checkmark$	$\checkmark$	$\checkmark$	$\checkmark$			
Vector control +	Magnetic sensor	-	$\checkmark$	$\checkmark$	$\checkmark$	$\checkmark$	$\checkmark$	$\checkmark$	$\checkmark$	-			
speed control	Inductive sensor	-	$\checkmark$	$\checkmark$	$\checkmark$	$\checkmark$	$\checkmark$	$\checkmark$	$\checkmark$	-			
	Resolver	-	-	$\checkmark$	$\checkmark$	-	$\checkmark$	$\checkmark$	$\checkmark$	-			
	Encoder (A/B)	-	$\checkmark$	$\checkmark$	$\checkmark$	$\checkmark$	$\checkmark$	$\checkmark$	$\checkmark$	$\checkmark$			
Vector control +	Magnetic sensor	-	$\checkmark$	$\checkmark$	$\checkmark$	$\checkmark$	$\checkmark$	$\checkmark$	$\checkmark$	-			
position control	Inductive sensor	-	$\checkmark$	$\checkmark$	$\checkmark$	$\checkmark$	$\checkmark$	$\checkmark$	$\checkmark$	-			
	Resolver	_	-	$\checkmark$	$\checkmark$	-	$\checkmark$	$\checkmark$	$\checkmark$	-			
Multiple motor con	ntrol	_	_	_	_	_	√ (2 motors: sensorless)	(3 motors: encoder) (4 motors: sensorless)	-	√ (2 motors: sensorless			

#### **Overall Structure**



#### Optional CPU Card for Evaluation System for BLDC Motor

CPU Card	for Motor Control	Part No.
RL78 Family	RL78/G1F	RTK0EML240C03000BJ
	RX13T	RTK0EMXA10C0000BJ
	RX23T	RTK0EM0003C01202BJ
	RX24T	RTK0EM0009C03402BJ
RX Family	RX24U	RTK0EMX590C02000BJ
	RX66T	RTK0EMX870C0000BJ
	RX72T	RTK0EMX990C0000BJ
	RX72M	RTK0EMXDE0C0000BJ
RA Family	RA6T1	RTK0EMA170C0000BJ

Inverter board

\* A kit that includes the RA6T1 CPU card in this inverter board is also available. "Motor Control Evaluation System for RA Family - RA6T1 Group"

### MCK-XXXXX

Note: XXXXX designates the group name of the MCU mounted on the CPU board.

This motor solution includes a CPU board(\*), inverter board, and communication board. Sample code and a development support tool are provided so you can get started with motor control immediately after purchase.

Features

- Equipped with onboard debugger for MCU flash programming.
- Supports 1-shunt and 3-shunt current detection.
- Overcurrent detection function.
- Supports the motor control development support tool "Renesas Motor Workbench" for easy debugging.
- Use of a communication board(\*) provides electrical isolation from the PC for safe evaluation and debugging of motor control applications.

#### Kit specifications

Kit name	MCK-RA6T2	MCK-RA8T1	MCK-RA6T3	<u>MCK-RA4T1</u> ⊡	MCK-RX26T
Kit model No.	RTK0EMA270S00020BJ	RTK0EMA5K0S00020BJ	RTK0EMA330S00020BJ	RTK0EMA430S00020BJ	RTK0EMXE70S00020BJ
	48V 10A inverter board for BLDC motor (MCI-LV-1)	$\leftarrow$	←	←	<i>←</i>
Structure	RA6T2 CPU board (MCB-RA6T2)	RA8T1 CPU board (MCB-RA8T1)	RA6T3 CPU board (MCB-RA6T3)	RA4T1 CPU board (MCB-RA4T1)	RX26T CPU board (MCB-RX26T Type A)
Structure	Communication board (MC-COM)	$\leftarrow$	_	_	Communication board (MC-COM)
	BLDC motor (R42BLD30L3 manufactured by Moons' Industries)	$\leftarrow$	←	←	←
Inverter specification	<ul> <li>Rated voltage: 48V</li> <li>Rated current: 10A (continuous)</li> <li>Protect functions: Overcurrent detection, etc.</li> </ul>	←	←	←	←

Note: Some products do not include a communication board.

In order to safely implement motor control evaluation, either obtain a communication board separately or use a commercially available USB isolator.

#### **Overall Structure**



Available Sample Code for Evaluation

Renesas Motor Workbench

			Supported MCUs								
Item			RX Family								
		RA6T2	RA8T1	RA6T3	RA4T1	RX26T					
120-degree conducting control + speed control (Hall sensor, sensorless)		$\checkmark$	$\checkmark$	$\checkmark$	~	-					
	Sensorless	$\checkmark$	$\checkmark$	$\checkmark$	$\checkmark$	$\checkmark$					
Vector control +	Encoder (A/B)	$\checkmark$	$\checkmark$	$\checkmark$	$\checkmark$	$\checkmark$					
speed control	Inductive sensor	$\checkmark$	$\checkmark$	$\checkmark$	$\checkmark$	-					
	Hall	$\checkmark$	$\checkmark$	-	-	-					
	Sensorless	-	-	-	-	$\checkmark$					
Vector control + position control	Encoder (A/B)	$\checkmark$	$\checkmark$	$\checkmark$	$\checkmark$	$\checkmark$					
	Inductive sensor	$\checkmark$	$\checkmark$	$\checkmark$	$\checkmark$	-					
Multiple motor control				_	_	_					
		(2 motors: sensorless)	(2 motors: sensorless)								



### MCB-XXXXX

Note: XXXXX designates the group name of the MCU mounted on the CPU board.

This CPU board can be used in combination with an inverter board (sold separately) to evaluate BLDC motor control applications employing a Renesas MCU.

Features

Equipped with onboard debugger for MCU flash programming.

Supports signal input from Hall sensors, encoders, and inductive position sensors.

#### Kit specifications

Kit name	MCB-RA6T2	MCB-RA8T1	MCB-RA6T3	MCB-RA4T1	<u>МСВ-RX26T Туре А</u> *2 🖸	MCB-RX26T Type B*2	<u>MCB-RX26T Type C</u> *2 ⊡
Kit model No.	RTK0EMA270C0000BJ	RTK0EMA5K0C00000BJ	RTK0EMA330C00000BJ	RTK0EMA430C00000BJ	RTK0EMXE70C00000BJ	RTK0EMXE70C01000BJ	RTK0EMXE30C00000BJ
MCU	R7FA6T2BD3CFP	R7FA8T1AHECBD	R7FA6T3BB3CFM	R7FA4T1BB3CFM	R5F526TFCDFP	R5F526TFDDFP	R5F526TACDFM
2-motor control support*1	$\checkmark$	$\checkmark$	-	-	$\checkmark$	$\checkmark$	$\checkmark$
Compatible inverter board	MCI-LV-1 (RTK0EM0000S04020BJ) MCI-HV-1 (RTK0EM0000B14030BJ)	(RTK0EM0000S04020BJ)	←	←	←	←	←

\*1: A compatible program is required.
\*2: Please refer to the MCB-RX26T Type A/B/C comparison table on the right.

MCB-RX26T Type A/B/C difference

MCB-RX26T	Туре А	Туре В	Туре С
Trusted Secure IP (TSIP-Lite)	-	$\checkmark$	-
ROM/RAM	64KB/512KB	64KB/512KB	48KB/256KB

### MCI-LV-1

When combined with separately available CPU boards, this BLDC motor drive inverter board kit can be used to evaluate a variety of motor control MCUs.

#### Features

- Supports 1-shunt and 3-shunt current detection.
- Overcurrent detection function. Includes BLDC motor.



#### Kit specifications

ltem	Specification		
Kit name	MCI-LV-1		
Kit model No.	RTK0EM0000S04020BJ		
Churchard	48V 10A BLDC motor inverter board		
Structure	BLDC motor (R42BLD30L3 manufactured by Moons' Industries)		
	Rated voltage: 48V		
Inverter specification	<ul> <li>Rated current: 10A (continuous)</li> </ul>		
	<ul> <li>Safety functions: Overcurrent detection, etc.</li> </ul>		

### MC-COM

The communication board for serial communication with a Renesas MCU. It provides an electrically isolated environment to enable safe evaluation and debugging of motor control applications.

Features

- Supports the motor control development support tool "Renesas Motor Workbench".
- CPU board by manufacturers other than Renesas can be used by embedding code from libraries supported by Renesas Motor Workbench in the user's motor control software.



#### Kit specifications

ltem	Specification
Kit name	MC-COM
Kit model No.	RTK0EMXC90S0000BJ
Isolation device used	Si8622BC-B-IS (Skyworks Solutions Inc.) or
	IS07421FED (Texas Instruments)
	RX13T/23T/24T/24U/66T/72T/72M CPU Card
Compatible CDU beards	RA6T1 CPU Card
Compatible CPU boards	MCB-RA6T2/RA6T3/RA4T1/RA8T1
	MCB-RX26T Туре А/Туре В/Туре С

### MCI-HV-1

This inverter board allows for easy evaluation of motor control using high-voltage (100/200V) BLDC/Induction motors by combining with a compatible CPU board.

#### Features

- Support input supply voltage range (AC100-240V 50/60Hz or DC141-390V)
- Equipped with PFC control circuit
- Supports 1-shunt and 3-shunt current detection
- Overcurrent detection, overvoltage protection and overtemperature detection

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			101
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			2-)
	1006.01	114 VA	

#### Specifications

ltem	Specification		
Name	MCI-HV-1		
Part No.	RTK0EM0000B14030BJ		
0	100-240V 50/60Hz 10A BLDC motor inverter board		
Structure	Connectors and cables		
Compatible CPU board	MCB-RA6T2		
Inverter specification	<ul> <li>Rated Input: AC100-200V, 50/60Hz 10A DC141-390V, 10A</li> <li>Rated Output: 500W (AC100V) 1kW (AC200-240V) 2kW (DC390V)</li> <li>Detection Function: Phase voltage, Phase current, Bus voltage, Input voltage, PFC current, temperature</li> <li>PFC: Max output 1kW, Single/Interleave control</li> <li>Current detection: 1-/3-Shant</li> <li>Protection function: Overcurrent detection, Short circuit prevention, Overheat detection, Over voltage prevention, Inrush current prevention</li> <li>Support sensor: Hall sensor, Encoder</li> <li>Isolation: Sensor I/F, Comm I/F (Both are Reinforced insulation)</li> </ul>		
Sample code	<ul> <li>RA6T2 Sensorless Vector Control of PM Motor by High-Voltage Inverter</li> <li>RA6T2 Sensorless Vector Control for IPMSM over the Whole Speed Range</li> </ul>		

### RL78/G24 Motor Control Evaluation Kit

The RL78/G24 Motor Control Evaluation Kit is a permanent magnet synchronous motor (brushless DC motor) control evaluation kit that is equipped with an RL78/G24 microcontroller, which allows easy evaluation of motor control.

Features

- Equipped with 16-bit RL78/G24 microcontroller
- Controlled by Hall sensor and Encoder with BLDC motor, or Sensorless control by phase voltage or sensing current
- Supports 1-shunt 2-shunt and 3-shunt current detection
- Zero-crossing detection with built-in compilator
- Supports the motor control development support tool "Renesas Motor Workbench" for easy debugging
- By replacing it with a compatible CPU card, you can evaluate motor control with other MCUs

#### Kit specifications

ltem	Specification				
Kit name	RL78/G24 Motor Control Evaluation Kit				
Kit model No.	RTK0EMG24SS00000E	3J			
	Inverter Board (RTK0EMGPLVB00000BJ)     RL78/G24 CPU Card (RTK0EMG240C0000BJ)				
Structure	Communication Board (RTK0EMXC90Z00000BJ)				
	<ul> <li>Permanent Magnet Synchronous Motor (TG-55L-KA)</li> </ul>				
	Various cables, screws, spacers				
	Rated voltage	48V			
Inverter specifications	Rated current	10A (continuous)			
	Protect functions	Overcurrent detection, etc.			
	MCU: R7F101GLG2DFB				
	Gate Driver: HIP2101IBZ				
Target Devices	MOSFET: RJK0703DPP-A0				
	Regulator: ISL8560IRZ,ISL85003FRZ				
	Operational amplifiers: READ2302GSP				

#### Compatible CPU Board

RL78 Family		Part No.
	RL78/G24	RTK0EMG240C00000BJ
	RL78/G1F	RTK0EML240C03000BJ







### **RZ/T2M Motor Solution Kit**

- Motor position and speed control software is available to enable initial evaluation when developing equipment incorporating industrial motors.
- ✓ Circuit diagrams are available in addition to software that runs on-board and PC software to help reduce the time required for development.

#### Features

- Ability to combine RZ/T2M  $\Delta \Sigma$  interface and Renesas  $\Delta \Sigma$  modulator for high-precision current sensing.
- A current sensing reference circuit for the motor's U-, V-, and W-phase lines and a sample program are available.
- Supports incremental and absolute encoders. (Supported encoder interfaces: BiSS<sup>®</sup> C, HIPERFACE DSL<sup>®</sup>, EnDat<sup>®</sup> 2.2, FA-CODER<sup>®</sup> and A-format<sup>®</sup>).
- A servo control sample program that operates via an industrial Ethernet link (EtherCAT, CiA402) is available.
- The board is populated with the RX72N and a monitoring IC, and a reference circuit and sample program\* are provided for a functional safety system implementing redundant monitoring functionality using the RZ/T2M and RX72N.

#### Kit specifications

Item	Specification					
Kit name	RZ/T2M Motor Solution Kit 🖸					
	RZ/T2M motor solution board					
Structure	RZ/T2M controlle	RZ/T2M controller board				
Structure	<ul> <li>Low-voltage sing</li> </ul>	Low-voltage single-shaft drive inverter board				
	Brushless DC motor (FH6S20E-X81) (with incremental encoder)					
	Rated voltage	24V DC				
	Rated current	2A (effective value)				
	Current detection	Current transducer, ∑∆ modulator (RV1S9353A)				
Board specifications	Safety functions	Overcurrent detection, bus voltage detection, overvoltage detection,				
board opcontoutions	Salety functions	undervoltage detection, external switch detection				
	Position detection	Incremental/absolute encoder				
	Communication	2 Ethernet ports, CAN, UART, USB				
	functions	Z EURINEL PUILS, GAIN, DANT, USD				

### General Configuration

	Controller board
Hardware	Inverter board
	BLDC motor (with incremental encoder)
	Permanent magnet synchronous motor vector control software with current sensor and encoder
Software	functions (and EtherCAT and functional safety platform software)
	PC software (Motion Control Utility)
Documentation	Startup Manual
	Firmware manual
	Motor Solution Board Hardware Manual
	Circuit diagrams, Gerber data, BOM list

#### **Supported Devices**

Category	Part No.	Key Features			
MPU/MCU RZ/T2M RX72N		Arm®-based High-end 32-bit MPU, Real-time control + Industrial Ethernet, FuSa			
		32-bit MCU with Enhanced DSP, FPU and TFU			
	RV1S9207A	0.6A Output Current, High CMR, IGBT Gate Drive, Photocoupler			
Analog	RV1S9353A	Optically Isolated $\Delta \Sigma$ Modulator			
	ISL3178	High ESD Protected RS-485/RS-422 Transceivers			
Davisar	ISL80030	2.7V to 5Vin, 3A Sync Buck			
Power	ISL8117	Synchronous Step-Down PWM Controller			

Link for RZ/T2M Motor Solution Kit: https://www.renesas.com/rzt2m-motor-solution-kit

\* For functional safety system evaluation, it is necessary to download the SIL3 System Software Kit and FSoE Solution Kit via the inquiry form on the Renesas website at the link below.

URL: Industrial Functional Safety — Technical Information Request Form | Renesas Electronics (renesas.com)



Available for loan free of charge. Please contact a Renesas Electronics distributor or sales office for details.

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Motion Control Utility

### Solutions for 9-axis Motor Control (BLDC Motor)

### RZ/T2H 9-axis Motor Control Demonstration

If you want to control up to 9motors simultaneously, this is the best solution.

Features

- Up to 9 axis motor control by RZ/T2H
- Enable to control each axis as speed/position control
- Support FA-CODER as encoder I/F
- Inverter board supports absolute/incremental type encoder
- Enable to operate each axis individually using Motion Control Utility that is motor control development support tool by Renesas
- Offering 9 axis motor control sample code and app note from Renesas website

#### Kit specifications

Item	Specification			
Kit name	RZ/T2H 9-axis Motor Control Demonstration			
Structure	<u>RZ/T2H Evaluation Board</u> <sup>[2]</sup> <u>Bus Board for RZ/T2H</u> <sup>[2]</sup> <u>RZ/T Series Inverter Board</u> <sup>[2]</sup> BLDC Motor with Encoder (FA-CODER <sup>®</sup> )			
	Rated voltage	24V DC		
	Rated current	4A (effective value)		
Inverter specifications	Current detection	3-shunt delta-sigma modulator		
	Safety functions	Overcurrent detection		
	Position detection	Incremental Encoder x1, Absolute encoder x2		
	Sample Code: RZ/T2H 9-axis Motor Control Program			
Software	Support RZ Smart Configuration			
	PC software (Motion Control Utility)			



Demo set up



Motion Control Utility



#### Link for resources

Evaluation Board Kit for RZ/T2H: <u>renesas.com/rzt2h-evkit</u> Bus Board for RZ/T2H: <u>renesas.com/busb-rzt2h-b</u> RZ/T Series Inverter Board: <u>renesas.com/invb-lv-rzt-i</u>

From left: Evaluation Board Kit for RZ/T2H, Bus Board for RZ/T2H and RZ/T Series, Inverter Board

#### **Supported Devices**

Category	Part No.	Key Features			
MPU/MCU	RZ/T2H	1200MHz Arm® Quad Cortex®-A55 and Arm® Dual Cortex®-R52, Real-time control + Industrial Ethernet			
	RV1S9061A	15Mbps IPM Drive Photocouplers			
	RV1S9355A	Optically Isolated $\Delta \sum$ Modulator			
	ISL3172EIBZ	RS-485/RS-422 Transceivers			
	ISL32179EFRZ	RS-422 Transmitters			
Amelen	ISL32177EFRZ	RS-485/RS-422 Receivers			
Analog	RV1S9213ACCSP-10YV#	OPTO COUPLER IN 5PIN SSOP			
	PS2733-1-A	OPTOISOLATOR 2.5KV DARL 4SMD			
	PS2561DL-1	OPTOISOLATOR 5KV TRANS 4SMD			
	PS8101-AX	OPTOISO 3.75KV PUSH PULL 6SO			
	PS2761B-1	OPTOISOLATOR 3.75KV TRANS 4SOP			
Devee	DA9061-16AM1	PMIC for Applications Requiring up to 6 A			
Power	RAA211450GSP#HA0	4.5V to 42V, 5A, DC/DC Synchronous Step-Down Regulator			
	AT25SF128A-SHB-T	IC FLASH 128MBIT SPI/QUAD 8SOIC			
Memory	R1EX24016ASAS	IC EEPROM 16KBIT I2C 400KHZ 8SOP			

### **Solutions for AC Synchronous Motors**

### RZ/T2M, RZ/T2L, and RZ/N2L Motor Solution Kits (AC 220V Version)

These solution kits simplify the initial and ongoing development of servo systems and motion controllers employing the RZ/T2M, RZ/T2L, and RZ/N2L. Each comprises a control board populated with the RZ/T2M, RZ/T2L, or RZ/N2L, an inverter board capable of driving a 220V AC synchronous motor, a motor for use in evaluation, a utility tool for adjusting motor parameters and motion control operation, control software, and more. The utility tool runs on a PC and allows operation of the motor with position and speed control by means of control commands sent via UART or RS-485. Alternatively, the motor can be operated via EtherCAT using CiA 402 profiles.

#### Features

- Compatible with power supplies from 100 to 250V AC.
- Compatible with absolute encoders from Tamagawa Seiki.
- A Renesas delta-sigma (Δ∑) modulator can be connected to the delta-sigma (Δ∑) interface for highly precise current sensing.
- Either UART or RS-485 can be used for data transfer with the utility tool.
- A sample program is provided for servo control via industrial Ethernet (EtherCAT or CiA 402).\*1
- Motor control using CiA 402 profiles (pp, csp, and csv<sup>\*2</sup>) is supported.
- \*1: An EtherCAT master such as TwinCAT® 3 must be provided by the customer. \*2: pp: position profile, csp: cyclic synchronous position, csv: cyclic synchronous velocity

#### Kit specifications

ltem	Specification			
Kit name	AC Servo Solution Kit 🖸			
Structure	Controller board (populated with RZ/T2M, RZ/N2L, or RZ/T2L)     Single-axis drive inverter board			
	AC synchronous motor (BN	ЛО602В1PD-A02) (with Tamagawa Seiki absolute encoder)		
	Rated voltage	100 to 250V AC		
	Rated current	1.5A (effective value)		
Board	Current detection	∑∆Modulator (RV1S9353A)		
specifications	Safety functions	Overcurrent detection, bus voltage detection		
	Position detection	Absolute encoder		
	Communication functions	EtherCAT ports x2, CAN, UART, USB, RS485		
Software	AC synchronous motor vector control software with encoder function (and EtherCAT communication functionality)			
	PC software (Motion Control Utility)			
D	Startup Manual (Motion Control Utility and EtherCAT)			
	Firmware manual			
Documentation	Hardware manual			
	Circuit diagrams, Gerber data, BOM list			



Available for loan free of charge. Please contact a Renesas Electronics distributor or sales office for details.



Motion Control Utility

#### **Supported Devices**

Category	Part No.	Key Features		
	RZ/T2M	800MHz dual core Arm®-based High-end 32-bit MPU, Real-time control + Industrial Ethernet		
MPU/MCU	RZ/T2L	800MHz single core Arm <sup>®</sup> -based High-end 32-bit MPU, Real-time control + Industrial Ethernet		
	RZ/N2L	400MHz single core Arm <sup>®</sup> -based High-end 32-bit MPU, Real-time control + Industrial Ethernet		
	RV1S9061A	15Mbps IPM Drive Photocouplers		
	RV1S9353A	Optically Isolated $\Delta \Sigma$ Modulator		
	ISL3172EIBZ	RS-485/RS-422 Transceivers		
	ISL32179EFRZ	RS-422 Transmitters		
	ISL32177EFRZ	RS-485/RS-422 Receivers		
Analog	RV1S9213ACCSP-10YV#	OPTO COUPLER IN 5PIN SSOP		
	PS2733-1-A	OPTOISOLATOR 2.5KV DARL 4SMD		
	PS2561DL-1	OPTOISOLATOR 5KV TRANS 4SMD		
	PS8101-AX	OPTOISO 3.75KV PUSH PULL 6SO		
	PS2761B-1	OPTOISOLATOR 3.75KV TRANS 4SOP		
Davisar	DA9061-16AM1	PMIC for Applications Requiring up to 6 A		
Power	RAA211450GSP#HA0	4.5V to 42V, 5A, DC/DC Synchronous Step-Down Regulator		
	AT25SF128A-SHB-T	IC FLASH 128MBIT SPI/QUAD 8SOIC		
Memory	R1EX24016ASAS	IC EEPROM 16KBIT I2C 400KHZ 8SOP		

### **Solutions for Stepping Motor**

Resolver motor control solutions featuring superlative cost performance

### **Resolver Motor Control Solutions**

These resolver-based motor control solutions are motor control systems for industrial and consumer applications realized by combining resolver-to-digital converter (RDC) ICs and RX Family microcontrollers (MCUs). It is possible to easily control a resolver-based stepping motor or brushless DC motor using the driver software of the microcontroller. Solution kits, sample code, development support tools, and application notes for motors with resolvers are provided, so motor control using resolvers can be started immediately.

Features

- High-precision motor control is possible even in the harsh environments with heat, dust, or vibration.
- Realize high-precision control at low cost using a new type of resolver control with higher cost performance.
- Resolver signal gain, phase, and angle error are automatically corrected through the driver API that can be used in combination with an RX MCU to achieve high precision.

#### System configuration



- In resolver-based motor control solutions, the RDC IC and RX MCU process signals from the resolver as angle information, and the RX MCU controls the motor. A dedicated driver for the RDC IC is provided on the RX MCU, and resolver processing can be easily performed using the API.
- Using a portion of the MCU functions makes it possible to simplify the RDC IC and thereby lower its cost.

### Motor Control Solutions for Stepping Motors with Resolvers



- Stepping motors with resolvers and resolver motor control solutions developed by collaboration between MinebeaMitsumi Inc. and Renesas make it possible to servo control the stepping motor which is normally controlled by the open loop.
- This solution realizes many advantages such as low noise, low vibration, low power consumption and maximization of motor torque.
- ICs, software, development kits, and development support tools for resolver control and motor control are available.

#### **Solution Contents**

Stepping motor with resolver: New motor manufactured by MinebeaMitsumi Inc. RX24T/RX66T/RX72T/RX72M: MCU for motor control

Resolver-to-digital converter: IC that converts resolver output into digital signal Solution kit: All items necessary for controlling a stepping motor with resolver are provided Support tool: Development support tool essential for motor control debugging

For simple, highly integrated open-loop stepper motors- info can be found at pages 28-29.

### **Solutions for Stepping Motor**

### **Evaluation System for Stepping Motor with Resolver**



Evaluation System for Stepping Motor with Resolver

Kit specifications

ΓŻ

ltem		Specification		
Kit name	Evaluation System for Stepping Motor with Resolver			
Kit model No.	RTK0EMX270S01020BJ			
	48V 2A Inverter board for s	tepping motor		
Structure	RX24T with RDC IC CPU card			
	Stepping motor with Resolver (Minebea Mitsumi)			
	Rated voltage: 48V			
Inverter specification	<ul> <li>Rated current: 2A (RMS)</li> </ul>			
inverter specification	Detect function: Phase current, Bus voltage			
	Protect function: Overcurrent protection			
Sample Code		Supported MCUs		
Vector control + S	peed control (Resolver)	RX24T, RX66T, RX72T, RX72M		
Vector control + Position control (Resolver)		RX24T, RX66T, RX72T, RX72M		

- Supports RS485, CAN, pulse train command, general-purpose input/output for external device communication as the I/F specification of the kit.
- Equipped with on-board emulator circuit (flash programming circuit).

### **Supported Devices**

#### MCUs

Part No.	Operating Frequency	Key Features
RX24T	80MHz	32-bit MCU, FPU* <sup>1</sup> , 5V operation, PGA* <sup>2</sup> , 2 motor control
RX66T	160MHz	32-bit MCU, FPU* <sup>1</sup> , 5V operation, PGA* <sup>2,3</sup> , 4 motor control, Security module
RX72T	200MHz	32bit MCU, FPU* <sup>1</sup> , 5V operation, PGA* <sup>2,3</sup> , Built-in TFU* <sup>4</sup> , 4 motor control, Security module
RX72M	240MHz	32-bit MCU, Double precision FPU* <sup>1</sup> , Built-in TFU* <sup>4</sup> , Security module, EtherCAT® compatible

\*1: Floating Point Unit \*2: Programmable Gain Amplifier \*3: Pseudo-Differential PGA \*4: Arithmetic Unit for Trigonometric Functions

#### Analog, Power devices

Category	Part No.	Key Features	
RDC-IC RAA3064002GFP (85°C) RAA3064003GFP (105°C)		Single-phase induced/Two phase output Excitation frequency: 5/10/20kHz, 2.5Vp-p	
Motor Driver	HIP4082IBZT 80V, 1.25A Peak Driver		
MOSFET	RJK0854DPB	Nch Power MOSFET, 80V/25A, $R_{DS(on)} = 13 \text{ m}\Omega$ max, surface-mount device (LFPAK)	
WIUSPEI	RJK1054DPB	Nch Power MOSFET, 100V/20A, $R_{DS(on)} = 22 \text{ m}\Omega \text{ max}$ , surface-mount device (LFPAK)	
RS-485/RS-422 ISL3156E RS-485/RS-422 transceiver, 4.5 to 5.5V operation, fail-safe		RS-485/RS-422 transceiver, 4.5 to 5.5V operation, fail-safe	

### **Recommended Devices**

#### HVPAK

Category	Part No.	Key Features
Motor Driver	SLG47105, SLG47115	Configurable H-/Half Bridge with up to 3 A/ 26.4 V with additional programmable mixed signal functionality and $l^2C$

### Solutions for AC Induction Motor

Three-phase induction motor solution provides inverter control software to be embedded in a motor control MCU. By providing an inverter control software with a high level of development difficulty, you can easily and reasonably develop a customer-specific inverter. \* This solution uses an inverter board made by a partner and does not provide a kit from Renesas.

### **Evaluation System for ACIM**

Renesas can provide CPU cards, sample code, application notes, development support tools, and can control induction motors in combination with partner-made inverter hoads

Features

- Equipped with speed sensorless vector control function can remove speed sensor to reduce BOM cost and improve reliability.
- Compatible with Renesas Motor Workbench (motor control development support tool), for easy debugging.
- Built-in over current/over voltage/over temperature protection function, enables safe evaluation.
- Various motor control MCUs can be evaluated in combination with an optional CPU card.
- High voltage inverter board is compatible with AC85 to 265Vrms input(Need to be purchased separately from Desk Top Lab Co.,Ltd).

#### **Evaluation Environment Specifications**

### **Overall Structure**



**Solutions Using Magnetic Sensors** 

### **Motor Control with Magnetic Sensor**

A motor control solution for applications using a BLDC motor with a magnetic sensor.

Renesas have released sample software and application notes that can correct the sensor output, which can be used as a reference for motor control using magnetic sensors. Renesas does not supply the BLDC motor with magnetic sensor used in this solution.

#### Features

- Sample code and application notes supporting magnetic sensors with analog output, digital output, and SPI output are provided.
- The sample code implements an error correction function for analog output signals
- Compatible with Renesas Motor Workbench, a motor control development support tool, for easy debugging.
- Equipped with protection functions such as overcurrent and overvoltage detection for safe evaluation.
- The TAD2141 and TAS2143 magnetic sensors manufactured by TDK Corporation were used to confirm the operation of the sample code.

#### **Overall Structure**



Support Tool **Benesas Motor Workbench** 

(included with Evaluation System for BLDC Motor)

**Evaluation Environment Specifications** 

Specification		
Evaluation System for BLDC Motor		
RX13T/23T/24T/24U/66T/72T/72M CPU card		
BLDC motor with magnetic sensor		
Rated voltage: 48V		
<ul> <li>Rated current: 5A (RMS)</li> </ul>		
Protect function: Overcurrent detection, others		

Laboratories Inc. (T1102)

Sample Software	Supported MCUs			
Vector control + Speed control (Magnetic sensor)	RX13T* <sup>1</sup> , RX23T* <sup>2</sup> , RX24T, RX24U,			
vector control + speed control (wagnetic sensor)	RX66T, RX72T, RX72M			
Vector control + Position control (Magnetic sensor)	RX13T*1, RX23T*2, RX24T, RX24U,			
vector control + Position control (waynetic sensor)	RX66T, RX72T, RX72M			
*1: Digital output only				

\*2: Digital or SPI output only

### **Solutions Using Inductive Position Sensors**

IPS2200 (Inductive Position Sensor)

This is thin, lightweight and cost effective with stray magnetic field immunity and contributes to the design for industrial motor. This is ideal for industrial and medical motor commutation and robot application.

Features

- For control of electrical motor (especially BLDC motor)
- Power-supply voltage: 3.3V or 5V
- Support up to 250,000 rpm, low latency (<10µs)</p>
- Magnet-free, thin, lightweight and low-cost solution
- High stray magnetic field immunity
- Sine/cosine (analog) output
- Support multiple pole pairs
- Operating temperature: -40°C to +125°C
- TSSOP-16
- This is a sensor detecting the position of the target metal based on the electromagnetic induction of the coil.
- The sensing element of IPS2200 enables to match the number of target sectors to pole pairs of the motor to maximize accuracy. Sectors can be mounted both to shaft axis (on-axis) and shaft side (off-axis) of the motor, which increases the degree of freedom of the design.
- This is thin and lightweight with one-tenth thickness and one-hundredth weight of the existing resolvers at maximum.



Multi-pole

Degree of freedom for mounting method and design of pole number

1-pole

### IPS2550STKIT

This is the kit for IPS2550, which includes the detection part of the position sensor and the interface board with PC. By combining with the dedicated GUI, you can easily visualize the angle.

\* This kit does not include a motor.

This kit is not designed to perform motor control but to check the output information from the position sensor



### Inductive Sensor Processing IC (IPS2550 Series)

Part No.	Operation Voltage	Operation Temperature	Rated Speed	Output Type	Safety Function	Package	Provide
IPS2550DE1R	3.0V to 3.6V or 4.5V to 5.5V	$Ta = -40^{\circ}C \text{ to } +160^{\circ}C$	Max. 600.000 rpm (Electric angle)	sin/cos (Differential or single ended)	Overvoltage detection, reverse polarity detection, short circuit protection	TSSOP-16 Pin (4.4mm × 5.0mm)	13" reel - 4000 IC/reel

### Whole Speed Range Sensorless Vector Control Solution for IPM Motors

This solution implements sensorless vector control of a salient IPM motor (IPMSM) from zero speed at the rated torque.

This solution includes Inverter board, CPU cards, sample code, application notes as well as development support tool. This solution is ideal for applications involving load torque at zero speed (start) or low speed and applications requiring energy efficiency in the low-speed range, such as Home appliance, E-bike, Electric Wheelchair, or Power tools.

#### Features

- Supports IPM motors. (Ordinary SPM motors and non-salient motors are not supported.)
- Eliminates need for magnetic pole position sensor for reduced BOM cost and better reliability.
- The sensorless algorithm enables output of the rated torque from zero speed or low speed.
- Compatible with Motor Control Development Support Tool Renesas Motor Workbench.
- Overcurrent, overvoltage, and overheating protection functions enable safety evaluation.
- Three inverter board options for High Voltage and Low Voltage motor control as below table.
- Sample Code available: implementing high-voltage motor control (PFC control, Vibration suppression function, etc.) and control method (vector control, etc.) along with application note that describe control method explanation and how to implement to MCU \*.
- Can be used for IPM motor control when used in combination with the DC 311V input high-voltage inverter board (which must be purchased separately from Desk Top Laboratories Inc.).
- \* Please make sure to confirm sample program and application note are targeting MCI-HV-1 (RTK0EM0000B14030BJ) and MCB-RA6T2 before use.

#### **Operation Overview**



### **Evaluation Environment Specifications**

Item		Specification				
	Inverter Board	<u>MCI-LV-1</u> * 디	<u>MCI-HV-1</u> ⊡	T1102 (Inverter board made by Desk Top Laboratories Inc. 亿)		
Structure	CPU Board	MCB-RX26T TypeA* □	MCB-R6T2	RX66T CPU card		
	Communication Board	<u>мс-сом</u> * ГZ	<u>мс-сом</u> 🗗	$\leftarrow$		
	Rated Voltage	DC24V	AC240V, DC390V	AC220V DC311V		
	Rated Current	AC10A	AC10A	AC15A		
Inverter specification	Protect Function	Overcurrent detection	Overcurrent detection, Overheat detection, Overvoltage protection, Short-circuit prevention, Inrush current prevention	Overcurrent detection, others		
Sample code		Sensorless Vector Control for IPMSM over the	RA6T2 Sensorless Vector Control for IPMSM over	RX Family Sensorless Vector Control for IPMSM		
		Whole Speed Range for MCK	the Whole Speed Range	over the Whole Speed Range Rev.1.00		

\* MCI-LV-1, MCB-RX26T TypeA and MC-COM are included in MCK-RX26T.

#### **System Configuration**



### **Digital Control Solution for 3-Level Inverter Power Supplies**

This solution implements digital control for 3-phase DC/AC inverter power supplies for solar power conditioners, uninterruptible power supplies, and industrial applications. The inverter circuit employs low-loss silicon carbide (SiC) power elements and a 3-Level (T-type) circuit topology, making possible more compact and lightweight filter reactors that improve system efficiency and eliminate unwanted harmonic components.

Features

- Supports both 2-Level and 3-Level PWM operating modes.
- Supports switching frequencies from 20 to 50kHz, making possible higher power density and more compact and lightweight filter reactors (magnetic components).
- Simultaneous output of the 12 PWM gate signals required for 3-Level inverter operation is generated by synchronous operation of 6 channels of the RX66T's on-chip GPT timer.
- Application notes, sample code,\* a development tool, and circuit data\* are available so you can get started right away with application development.
- \* Provided separately.



Circuit configuration of 3-Level (T-type) inverter

#### **Overall Structure**



Support Tool Renesas Motor Workbench

inverter demo board

#### **Evaluation Environment Specifications**

Item	Specification
Structure	T-type 3-Level DC/AC Inverter demo board
Structure	RX66T CPU card I
	Input voltage: 600 to 850Vdc
	<ul> <li>Output voltage: 400Vrms, 3-phase, 50/60Hz</li> </ul>
	<ul> <li>Output capacity: 10kW</li> </ul>
Inverter specification	Power factor: 0.8
	Inverter switching frequency: 20 to 50kHz
	<ul> <li>Cooling method: natural or forced air cooling</li> </ul>
	PWM type: 2-Level or 3-Level

### Renesas Motor Workbench

When developing motor control software, if operation of the program is halted for debugging while the MCU is connected, control of the inverter circuit stops. This poses the danger of a large current flow occurring. Renesas provides a development support tool to deal with such situations.

#### **Product Summary**

- Analyzer function: Dynamic reading/writing of variables and waveform display while operating the motor.
- Tuner function: Automatic identification of motor parameters and control gains required for vector control.
- Easy GUI function: Makes it quick and easy for anyone to implement motor speed and position control by means of intuitive operations.
- Servo function: Implements an adjustment function for the motor's embedded position control system. (Supports adjustment of position control parameters, inertia estimation, origin return operation, and point-to-point control.)
- RMW-DLL: Functions needed for debugging are provided as APIs, allowing connection to a GUI developed to the user's specifications.
- Built-in communication library: In addition to the standard library, a communication library for simple debugging using a commercially available serial-USB conversion cable or the like is provided.

Renesas Motor Workbench provides powerful support for developers of motor control applications, allowing operation of motor control programs from a PC and extraction of data within programs.

#### Example usage scenario

Evaluation System for BLDC Motor / for Stepping Motor with Resolver



Support Tool Renesas Motor Workbench





### Renesas Motor Workbench Functions

#### Analyzer

Extensive functions include trigger, zoom, and commander transmission etc., useful for debugging and evaluation. Also usable as user I/F.

#### Easy GUI

Meters and waveform displays allow you to confirm the motor's operating status at a glance, greatly simplifying the debugging process.







Vector control at ease without know-how. Fine adjustment at ease with manual adjustment function, as well as quick result check.

#### Servo

Tuner

Provides a custom GUI for adjusting position control parameters, inertia estimation, and operation of the actual system.



DLL Excel VBA Makes it possible to use the functions of Renesas Motor Workbench via a GUI matching the user's specifications.



### Analyzer

#### Functions

- Dynamically write/read variables while driving a motor
- Dynamically display waveform while driving a motor
- Specify trigger and each display settings with the waveform display
- The commander function allows creation and transmission of sequences for changing variables of your choice.
- The user button function lets you change a user-defined group of variables with a single click.

#### User's voice

- Very useful, you can observe variables inside MCU.
- Amazed at the debugging function without the need to stop CPU. The tool to enable safe analysis operation.



Display variables for 8 channels (can specify scale and off-set settings etc. per channel)

#### **Tuner**

#### Functions

- Automatically measure motor-unique parameters (resistance, inductance, induced voltage constant variable, and inertia)
- Automatically adjust the PI control gain of current/speed/position
- Automatically adjust the expected gain for sensorless vector control
- Manual tuning to finely adjust each PI control
- Output results in pdf and motor-driver header files







Check adjustment results right away with the analyzer Output adjustment results in pdf and motor header files available on the Web

Finely adjust the PI gain of current/speed/position



### User's voice

- Great help, as I had much trouble in adjusting parameters.
- I could start motor right away after purchase.
- Convenient enough just to be able to use motor parameter.



**Tuner Implementation Using Non-Renesas Kit** 

Using the tuner project included with the sample code, you can implement a tuner using a kit from a manufacturer other than Renesas.

Motor

### Easy GUI

Implements a GUI that allows more intuitive operation of the motor.

- Ability to set instruction values by manipulating sliders.
- Ability to configure instruction value profiles.
- Display of rotation speed, current values, etc., on meters.
- Switches for function switching.
- Waveform display of changes in values of variables.
- Ability to display a variety of parameters.

#### DLL

Variable read and write functions executed by the RMW (GUI) are provided in a DLL, making it possible to create tools using Excel VBA or as .NET applications.







The download package contains both a standard communication library and a built-in communication library. Embedding the built-in communication library in the motor control program allows you to perform simple debugging using a USB-serial conversion board instead of a communication board compatible with Renesas Motor Workbench. Supported MCUs are the RA6T2, RA6T3, and RA4T1 (with support for additional MCUs planned for future release.). Note: The number of points of waveform display data that can be displayed using the Analyzer module is limited.

Using MC-COM communication board: 100,000 data points Using built-in communication library: 1,000 data points (RA6T2),

500 data points (RA6T3 and RA4T1)

### Servo

GUI for servo control

- Motor axis connected load inertia estimation function.
- Servo setting configuration function covering position control type, fixed frequencies, etc.
- Function for configuring the origin return method, return speed, etc.
- Function for point-to-point (PTP) single-axis operation.

### Other

- Function for displaying variable uses.
- Function for outputting variables adjusted using the Analyzer module to a folder of your choice in sample code header file format.
- Navigation function with GUI support.
- Improved variable search function.

### New Functions of Renesas Motor Workbench 3.2

#### **Tuner for RL78**

Tuner support RL78 device (Target is BLDC motor). All tuner functions are available with RL78/G24 Motor Control Evaluation Kit.

### **Tuner support MCI-HV-1**

Tuner support Renesas Flexible Motor Control Inverter Board for 100V/200V Three-Phase BLDC/ Induction Motor. All tuner functions are available with MCI-HV-1.

#### **Remove authentication function**

Authentication function was removed from Renesas Motor workbench 3.2. You don't need to import the latest authentication file.









RL78/G24 Motor Control Evaluation Kit



MCI-HV-1



#### **Specification**

	ltem	Specification
All	Supported MCU	RX13T, RX23T, RX24T, RX24U,RX26T, RX66T, RX72T, RX72M, RA6T1, RA6T2, RA6T3, RA4T1,RA8T1, RL78/G24. RL78/G1F, RL78/G14 supports the analyzer function only.
	Usage environment (OS)	Windows 10 or Windows 11
	Peripherals, port	UART 1 ch, DMA (DTC) Port: TXD, RXD
	Communication I/F	USB2.0 (Communication Device Class)
Communication Communication board		The following kits have communication circuits.  • Evaluation System for BLDC Motor  • Evaluation System for Stepping Motor with Resolver For MCK-XXXXX or user board  • MC-COM  • W2002 (Desk Top Laboratories Inc.*)
	Waveform display	8 channels (scale and off-set setting per channel), zoom function (2 windows), Trigger mode selectable from Single/Auto/Normal, save waveform data in a csv format
Analyzer	Write/ Read variable	Ability to select up to 255 variables simultaneously, useful functions that simplify debugging (user buttons, commander function, rename function)
	Number of waveform display data points	100,000 data points (using standard library)
	Input information	Rated voltage and number of pole pairs of motor to be measured
Tuner	Output information	Motor-unique parameter (Resistance, Inductance, Magnet flux, Rotor inertia) and Control gain output Output file format: pdf file, header file*1
Servo	Supported functions	Inertia estimation function (rotor + load), servo adjustment function, origin return processing, PTP control

\*1: Corresponds to sample files for motor control sample code released by Renesas. Refer to the user's manual of Renesas Motor Workbench for details...

	Item		Specification
		Usage environment	Windows 10 only, .NET Framework 4.6.1 or later
			Visual Studio 2015 or later, Excel
			Serial data connection, reading and writing variables, scope function

lte	em	Specification
	Supported MCUs	RA6T2, RA6T3, RA4T1
Built-in communication	Communication board	Commercially available USB-serial conversion cable or board
library	Number of analyzer	RA6T2: 1,000 data points
	waveform display data points	RA6T3/RA4T1: 500 data points

### Environment Used

- Evaluation System for BLDC Motor
- Evaluation System for Stepping Motor with Resolver
- MCK-XXXXX (Bundled MC-COM is used.)
- MCI-HV-1 + MCB-RA6T2



Simply connect the kit with the sample code programmed to it to a PC using a USB cable, then launch Renesas Motor Workbench to get started.

Communication boards

Renesas Electronics MC-COM







• Evaluation system for XXXXX



• MCK-XXXXX, MCH-HV-1 or user environment



Note: A communication board is required when using a user environment.

Desk Top Lab

### QE for Motor

QE for Motor is a motor control software development support tool that enables users to develop motor control software by performing operations arranged into a workflow. It is an extension to the e<sup>2</sup> studio integrated development environment e<sup>2</sup> studio that can be downloaded at no charge.



#### Motor Control Software Configuration GUI



#### Features

- Simply follow a workflow in QE for Motor to seamlessly implement the steps required to evaluate motor control software.
- Information on motor control solutions is available on the Renesas website.
- You can configure settings of sample code middleware and drivers used for motor control via a GUI displaying a motor control block diagram.
- You can launch the Tuner and Analyzer modules of Renesas Motor Workbench from QE for Motor with a single click to easily generate parameter files and evaluate software.
- Supported MCUs RA Family: RA4T1, RA6T1, RA6T2, RA6T3, RA8T1
  - RX Family: RX26T

RL78 Family: RL78/G1F, RL78/G24

### Motor Driver Generator Function of Smart Configurator for RX

The Motor component of Smart Configurator for the RX Family can generate drivers suitable for motor control for peripheral functions such as the multi-function timer pulse unit and A/D converter module, and you can use it without needing to be aware of the minute details of peripheral settings. This function is available in the e<sup>2</sup> studio integrated development environment and in RX Smart Configurator (standalone version).

#### Timer (MTU/GPT) Settings

Period set	ing						
Timer Ope	ration Period	100	μs	Y	Actual frequ	ency 10.000	0 HHz)
Counter di	ock division rate	1					
TGRA regi	ster volue	7200					
Dead time		10	pe au	~	Actual volue	c 100	
Output Pa	be and A/D Con	version Trigge	Setting				
A/D Come	raion Tripper Ski	poing Disable	e skipping fu	nction	2		
	esion Tripper Int						
		Carter	Control (A/D	Conversion	Tripper)		-
Pins Ac	Sire Level			constant Al-	Tégger)	K	
			Å	conserver Al re		A	
EUp La	in v		Å	conserver Al re 	Tegger)		
Up La	14 V 14 V		Å	constant Al s	Tegger)		
EUp La EUs La EVp La	14 V 14 V		Å				
EUp La EUs La EVp La			Å				

#### **Configurable Settings**

- Complementary PWM mode (MTU3 or GPT) or triangle-wave PWM mode (GPT)
- Switching frequency
- Dead time duration
- A/D conversion start trigger settings
- PWM signal output polarity
- Motor connection pin selection

Features

- By configuring settings in a simple GUI, you can generate driver source code for the timer (multi-function timer pulse unit (MTU) or general PWM timer (GPT)) and 12-bit A/D converter (S12AD) peripheral modules that perform pulse output and current measurement essential for motor control. Complex settings such as timer pulse output settings (complementary PWM mode settings) and settings to trigger A/D conversion by timer events are configured automatically by the generated drivers.
- It is easy to change settings for the peripheral function channels or pins used for motor control from within Smart Configurator.

Supported MCUs: RX13T, RX23T, RX24T, RX24U, RX26T, RX66T, RX72T, and RX72M Supported motors: 3-phase brushless DC motors and 2-phase stepping motors

Timer Setting A/D Converter Set	ting
A/D Conversion Setting	
Detected Input Pin	Analog Input Channel
🗹 lu	AN000(sample-and-hold used) ~
⊡ lv	AN001(sample-and-hold used)
🗹 lw	AN002(sample-and-hold used) ~
☑ Vdc	AN103
214	41004

12-Bit A/D Converter (S12AD) Settings

☑ Vdc	AN103	~
₩ Vu	AN004	~
Vv	AN005	~
Vw	AN006	~
A/D Conversion End Interrupt Priority Level	Level 15 (highest)	~
Call user function from interrupt handler		
Function Name	AdFunction	

#### Configurable Settings

A/D converter pin selection for motor control

### Interrupt priority level selection

#### Sensor Settings

figure				
Sensor Setting				
Sensor enable Enable magnet i	<ul> <li>Ouctrue latigit@reams</li> </ul>			
Timer Setting A/D Converter Se	tting Sensor Setting			
Megnet Setting				
Phase counter for magnet	MTUD-MTU1		~	
Phase counter input pins	MTCLKA (A-phase) - MTCLKB (	8-phase)	~	
Phase counter capture clock	PCLK	<ul> <li>Rking edge</li> </ul>	<ul> <li>Count</li> </ul>	frequency: 80.0 MH
Magnet multiplication	4 (Phase Counting Model)		~	
	A-phase S-phase TOIT view			
Enable Magnet Interrupt (	1GRB Input Capture Interrupti			
Priority	Level 13 ~			

**Configurable Settings** 

- Motor component setting support Encoder and Hall sensor
- Motor component setting support Magnetic sensor (digital output) for RX24T

### Motor Driver Generation Function of RZ Flexible Software Package (FSP)

Using the FSP versions available for the RZ/T2M, RZ/T2L, and RZ/N2L, you can generate drivers suitable for motor control for peripheral functions such as timers, A/ D converters, and the delta-sigma ( $\Delta \Sigma$ ) interface, all without needing to think about detailed peripheral settings. This function is available in the e2 studio integrated development environment and in the version of Smart Configurator (standalone product) with support for software from IAR Systems.

The FSP can generate the following types of motor drivers.

- 3-phase PWM output timer for GPT
- 3-phase PWM output timer for MTU3
- A/D converter
- Delta-sigma ( $\Delta \Sigma$ ) interface
- Phase counting mode using GPT
- Phase counting mode using MTU3

Settings

- Left-right symmetric/asymmetric triangle-wave **PWM** settings
- Carrier period
- Dead time
- A/D conversion start trigger settings
- PWM signal output polarity
- Motor connection pin selection
- Single- or double-buffer selection

Features

- By configuring settings in a simple GUI, you can generate driver source code for the multi-function timer pulse unit 3 (MTU3) and general PWM timer (GPT) that generate PWM output, and for the 12-bit A/D converter (ADC12) and delta-sigma ( $\Delta\Sigma$ ) interface (DSMIF) that perform current measurement, both of which are necessary for motor control.
- Smart Configurator lets you easily change settings to configure items such as the peripheral function channels and pins used for motor control.

Supported MPUs: RZ/T2M, RZ/T2L, and RZ/N2L

### Flexible Software Package (RA Family)

The Renesas Flexible Software Package (FSP) is an enhanced software package designed to provide easy-to-use, scalable, high-quality software for embedded system designs using Renesas RA Family Microcontrollers. With the support of Arm® TrustZone® and other advanced security features, FSP provides a quick and versatile way to build secure, connected IoT devices using production-ready drivers, Azure® RTOS, FreeRTOS™, and other middleware stacks.

FSP uses an open software ecosystem and provides flexibility in using bare-metal programming, included Azure RTOS or FreeRTOS, your preferred RTOS, legacy code, and third-party ecosystem solutions.

The combination of the flexible open architecture of the FSP plus the wide choice of 3rd party solutions as part of the Arm ecosystem increases the range of choice for application development. This means that developers can choose the software model that best suits their needs while utilizing Renesas's excellent Arm-based silicon solutions as well as speed up the implementation time of complex areas like connectivity and security.

Azure	RTOS		Fre	eRTOS		Storage		Capacitive Touch	
Connectivity NetX Duo & Add-ons, BLE, WIFI	USB USBX (CDC, N HID, Audio, C		USB USB Middleware (CDC, MSC, HID)	USB Middleware		Virtual EEPROM Block Media - USB, SDHI, SPI		Buttons, Sliders, Wheels Self & Mutual	
Security NetX Crypto HW Acceleration NetX Secure Secure HW Acceleration NetX Secure			Security PSA Crypto HW Acceleration Mbed TLS		VIFI,	Security		Controls & Sensors	
Graphics GUIX GUIX Studio	Trace TraceX	and the second s		FAT	Secure Bootloader (MCUboot), TF-M FSP Crypto APIs TinyCrypt	M	Motor Cntrl Algorithm Sensor APIs		
Real-Time	05		Н	ardware Abstr	raction Layer	(HAL) Drivers			
Azure RTO		ADC	1/0 Ports	Clock Accuracy Circuit	Clock Generation Circuit	SD.MMC Host Interface	UART	Low Voltage Detection	
ThreadX	5	DAC	Sigma Delta ADC	External Interrupt	Realtime Clock	USBHS/ USBFS	SPI	Low Power Modes	
	-11	CRC	Operational Amplifier/ IIRFA	2D Drawing Engine	Event Link Controller	GLCDC/ Segment LCDC	12C/13C	Encryption/ Decryption (SCE)	
FreeRTOS		DOC	Parallel Data Capture	Cap Touch Driver	Timers/ Motor Cntrl	DMA Controller	128	Hashing (SCE)	
	_	QSPI	Comparators	JPEG Codec	Watchdog	Flash	Ethernet/ PTPC	CAN-FD	

#### **Benefits**

- Provides an easy-to-use, scalable, high-quality software for embedded system designs using the Renesas RA Family of Arm microcontrollers
- Includes best-in-class HAL drivers with high performance and low memory footprint
- Middleware stacks with Azure RTOS and FreeRTOS integration are included to ease the implementation of complex modules like communication and security
- The e<sup>2</sup> studio IDE provides support with intuitive configurators and intelligent code generation to make programming and debugging easier and faster
- Uses an open software ecosystem and provides flexibility in using bare-metal programming, included Azure RTOS and FreeRTOS, your preferred RTOS, legacy code, and third-party ecosystem solutions
- Integrated package with all required components for easy setup and starting development (single installer with e<sup>2</sup> studio, CMSIS packs, tool chain and SEGGER J-Link drivers)
- Complete source code available through GitHub



### **RAA227063 3-Phase Smart Gate Drivers**

### RAA227063 Smart 3-Phase

System Integration (Smart Gate Driver with Built-in Power Supply for System and High Accuracy Amp for 3-Shunt)



### **Development Tool**

Easy to Connect with Renesas CPU Card, Start to Evaluate by Sample Firmware of Renesas MCU

- PCB size: 14.1cm x 16.0cm
- Power input: 4.5V to 60V, motor driving MOSFETs are rated at 80V 132A.
- MCU connectors are compatible to Renesas RL78/G1F, RX23T, and RA6T1 CPU card interface. (Has interface to MCU for motor current & voltage sensing, PWM signals, fault condition, enable IC, SPI connection, etc.)



CPU Card (RL78/G1F, RX23T, RA6T1)



EVB for RAA227063 (RTK227063DE000BU)

Product	PKG	Operating Voltage (V)	Applications
RAA227063*1	48 Ld QFN	4.5 to 60V	Power tool, Gardening tool, Cord-less vacuum cleaner,
nAAZZ7005	(7mm × 7mm)	4.5 10 00 V	Cooling-fan, Water pump, Air pump, AGV, Robotics, etc.

\*1: RAA2270634GNP#MA0: Reel 250pcs Ta= -40 to 125 °C RAA2270634GNP#HA0: Reel 4k pcs Ta= -40 to 125 °C

### **Inquiry window**

Please contact customer support via the website for further information. https://www.renesas.com

### RAA306012 3-Phase Smart Gate Drivers

### RAA306012 3-Phase Smart Gate Driver

System Integration (Smart Gate Driver with Built-in Power Supply for System and High Accuracy Amp for 3-Shunt)

Features

- Wide VIN range: 4.5V to 65V (78V abs max)
- Switching frequency range up to 200kHz
- 3-Phase drive for BLDC application
  - Peak current 0.64A/1.28A (source/sink) with adjustable drive strength
- Supports up to 16 adjustable levels of drive strength through SPI
- Adjustable and adaptive dead-time control
- Low power consumption sleep mode with less than 28uA quiescent current to maximize battery life in portable applications.
- Includes complete system power supply with efficient architecture
- Support back-EMF sensing to support BLDC motor sensor-less operation
- Extensive fault protection: UV/OV, VDS OCP, Current sense OCP, etc.
- Package: 48 Ld QFN (7mm x 7mm, 0.5mm pitch)

#### Benefits

- Allows to Scale the MCU to Address the Application Specifications
   Renesas MCU: RL78, RX32T, RA6T1, RA2L1, etc.
- Integration of Analog Power Components Saves Board Space and Allows for Easy Tuning



### **Development Tool**

- Starter Kit is used to evaluate a BLDC motor system using the RAA306012 and RX13T&RL78/G1F(MCUs).
- Easy to start motor control evaluation with the RAA306012
- The reference firmware is written to the control board of the set. By connecting the attached small motor to the board and supplying power, evaluation can be started immediately.
- Board with high expandability and operability (size: 160mm × 210mm)
- The board is easy to operate, and switches, potentiometers, LEDs, and thermistors are mounted, their functions can be used by using the user program.



Part No.	Package	Operating Voltage (V)	Applications
RAA306012	48Ld QFN (7mm × 7mm)	4.5 to 65V	Power tool, Gardening tool, Cord-less vacuum cleaner, Cooling-fan, Water pump, Air pump, AGV, Robotics, etc.

### **Inquiry window**

Please contact customer support via the website for further information. https://www.renesas.com

### **HVPAK**<sup>TM</sup>

Programmable Mixed-Signal Matrix with High Voltage Features (up to 26.4 V and up to 3 A per output)

The HVPAK SLG47105 and SLG47115 combine GreenPAK<sup>™</sup> mixed-signal logic and H-/Half-bridge functionality. The HVPAK advanced PWM macrocells allow driving multiple motors or inductive loads with different PWM frequencies and duty cycles. Low (70 nA) current consumption in the standby mode together with a compact 2 mm x 3 mm size provide even more benefits. This highly versatile device allows a wide variety of mixed-signal functions to be designed alongside high-voltage capabilities.

### **HVPAK** Capabilities



### **HVPAK Value**



### **Development and Evaluation Tools**



HVPAK Socket Adapters (SLG47105V-SKT and SLG47115V-SKT) \* works together with SLG4DVKADV



HVPAK Evaluation Board (SLG47105V-EVB and SLG47115V-EVB) \* works together with SLG40VKADV

Download <u>Go Configure™ Software Hub | Renesas</u> to create your HVPAK designs. This is free GUI-based software. Useful Resources: <u>Documentation & Downloads Search | Renesas</u>

### Solutions for DC / Stepper Motors, Solenoid, LED, and DC-DC

### HVPAK SLG47105 Demo Board

The HVPAK Demo Board allows to get acquainted with SLG47105's functionality, especially the H-Bridge and Half-Bridge functions, and demonstrates the power part of the chip. This board is designed for hands-on and visually shows the SLG47105 chip's capability to handle both DC and Stepper Motors, as well as LEDs. The chip on the Board is already programmed with a versatile project, allowing to control different loads and switch between modes.

To launch the board, it is necessary just to connect it to any power source using a USB cable. Additionally, it is possible to emulate any custom project on this board using <u>Go Configure™ Software Hub</u>.



### **HVPAK Evaluation Boards**

#### SLG47105V-EVB and SLG47115V-EVB

The HVPAK evaluation boards have been developed for testing designs with all features and high current loads. You can emulate/program the HVPAK chip using this evaluation board with the GreenPAK Advanced Development Board. Just connect the evaluation board to the Advanced Development Board and use a USB cable to power them.

The <u>Go Configure™ Software Hub</u> will identify the boards and let you emulate/program the part. To start the evaluation, you need to separately power the HV part. Then, you can test your design using the measuring equipment.



### **Recommended Products: MCUs and MPUs**

### RL78 Family

Part No.	Pin Number	ROM (KB)	RAM (KB)	Operating Frequency	Power-supply Voltage
	30 to 64	16 to 64	2.5 to 5.5		1.6 to 5.5V
RL78/G14	50 10 04	96 to 512	12 to 48	32MHz	
	80 to 100	30 10 312	1Z LU 48		
RL78/G1F	24 to 64	32/64	5.5	32MHz	1.6 to 5.5V
RL78/G1G	30 to 44	8/16	1.5	24MHz	2.7 to 5.5V
RL78/G1M	20	4/8	0.512/1	20MHz	2.0 to 5.5V
RL78/G24	20 to 64	64/128	12	48MHz	1.6 to 5.5V

### RX Family

Part No.	Pin Number	ROM (KB)	RAM (KB)	Operating Frequency	Power-supply Voltage
RX13T	32 to 48	64 to 128	12	32MHz	2.7 to 5.5V
RX23T	48 to 64	64 to 128	12	40MHz	2.7 to 5.5V
RX24T	64 to 100	128 to 512	16 to 32	80MHz	2.7 to 5.5V
RX24U	100 to 144	256 to 512	32	80MHz	2.7 to 5.5V
RX26T	48 to 100	128 to 512	48 to 64	120MHz	2.7 to 5.5V
RX66T	48 to 144	256 to 1024	64 to 128	160MHz	2.7 to 5.5V
RX72T	100 to 144	512 to 1024	128	200MHz	2.7 to 5.5V
RX72M	176/224	2048 to 4096	1024	240MHz	2.7 to 3.6V

### **RZ** Family

Part No.	Pin Number	ROM (KB)	RAM (KB)	Operating Frequency	Power-supply Voltage
RZ/T2M	128/176/225/320	0	576 to 2624	800MHz	3.0 to 3.6V
RZ/T2L	196	0	1600	800MHz	3.0 to 3.6V
RZ/T1	176/320	0	544 to 1568	600MHz	3.0 to 3.6V
RZ/T1-M	112	0	544 to 1568	450MHz	3.0 to 3.6V
RZ/T2H	729	0	2048	1200MHz	3.135 to 3.465V

## RA Family

Part No.	Pin Number	ROM (KB)	RAM (KB)	Operating Frequency	Power-supply Voltage
RA4T1	32/48/64	128/256	40	100MHz	2.7 to 3.6V
RA6T1	64/100	256/512	64	120MHz	2.7 to 3.6V
RA6T2	48/64/100	256/512	64	240MHz	2.7 to 3.6V
RA6T3	32/48/64	256	40	200MHz	2.7 to 3.6V
RA8T1	100/144/176/224	1024/2048	1024	480MHz	1.68 to 3.6V

### **Recommended Products: Motor Sensor Processing IC, Motor Control IC**

	Res	Resolver Driving Block			Converter Block		Amplifier Circuit Block	Control Block					Operating	
Part No.	Input	Excitation Signal Output	Over Temperature Detection Circuit	Differential Amplifier Circuit	Signal Conversion Circuit	Disconnection Detection Circuit	Differential Amplifier Circuit	Communication Function	Operating Frequency	Conversion Error	Power-supply Voltage	Power-supply Current	Ambient Temperature	Package
RAA3064002GFP	Square wave:	Alternating current:		Gain Variable: 2, 4, 8, 16.5	Angle error correction function, Internal circuit	Detect disconnection	2 ch (Support differential	SPI interface	4MHz	±0.2°	VDD = 4.5-5.5V,	Maximum operating	-40 to +85°C	LQFP-48pin
RAA3064003GFP	5/10/20 kHz	35mAp-p (Max.)	Built-in	2, 4, 8, 10.5 times	error correction function	from signal amplitude	innut) (Gain	(Max. 1MHz)	4IVIHZ	±0.2°	IOVDD = AVDD	current: 20 mA (Typ.)	-40°C +105°C	(7mm × 7mm

### **RDC IC (Resolver to Digital Converter)**

### Inductive Sensor Processing IC (IPS2550 Series)

Part No.	Operation Voltage	Operation Temperature	Rated Speed	Output Type	Safety Function	Package	Provide
IPS2550DE1R	3.0V to 3.6V or 4.5V to 5.5V	$Ta = -40^{\circ}C \text{ to } +160^{\circ}C$	Max. 600.000 rpm (Electric angle)	sin/cos (Differential or single ended)	Overvoltage detection, reverse polarity detection, short circuit protection	TSSOP-16 Pin (4.4mm × 5.0mm)	13" reel - 4000 IC/reel

### HVPAK™

Programmable Mixed-Signal Matrix with High Voltage Features - DC/Stepper Motor, Solenoid, Valve, LED Control, DC-DC

Part No.	SLG47105V	SLG47115V
# of Pins / # of GPIO	20/8 + 4 x HD	20/8 + 2 x HD
Operating Voltage, VDD (V)	2.3 to 5.5	2.3 to 5.5
Dual Supply, VDD2 (V)	3.0 to 13.2	4.5 to 26.4
ACMPs	4	3
Voltage Reference	Trimmed	Trimmed
Combo Function Macro-cells	12 Total	12 Total
Multi-Function Macro-cells	5 Total	5 Total
PWMs	2	2
Counters/Delays	5	5
DFF / Latch	15	15
3-Output Pipe Delay	16-stage	16-stage
Programmable Delay	Yes	Yes
Internal Oscillator (Hz)	2k/25M	2k/25M
Temp Sensor	Yes	Yes
Communication Interface	l <sup>2</sup> C	I <sup>2</sup> C
STQFN Package Size (mm)	2.0×3.0	2.0×3.0

### **Recommended Products: Power Management**



### ISOLATED non-ISOLATED

\* Used for Step-down from 200V to 24V and so on.

### **PWM Controller**

Part No.	Description	Control Mode	UVLO Rising (V)	UVLO Falling (V)	Vbias max (V)	No Load Operating Current (mA)	PWM Output Number	Error Amplifier	FET Driver lout max (A)	Switching Frequency (Hz)	Maximum Duty Cycle (%)	Package
ISL6840	Industry standard single end	Peak current mode	7	6.6	20	3.3	1	Built-in	1	4k to 2M	96	8Ld MSOP, 8Ld DFN
ISL6726	Active clamp · forward	Current mode	7.65	6.23	22	10	1	-	2	10k to 1M	80	20Ld QSOP
ISL8840A to ISL8845A	High performance · Industry standard single end	Peak current mode	7, 8.4, 14.3	6.6 to 8.8	30	2.9	1	Built-in	1	2k to 2M	48, 96	8Ld SOIC, 8Ld MSOP

### DC/DC

Part No.	Vin (V)	Vout (V)	lout (A)	Fsw (Hz)	PWM/PFM	Efficiency (%)	On Resistance typ (mΩ)	Operating Temperature Range	Package
ISL85009	3.8 to 18V	0.8 to Vin*92%	9	300k/600k	Yes	Max. 95	High: 17 Low: 8.5	-40 to 125°C	15-TQFN
ISL85014	3.8 to 18V	0.8 to Vin*92%	14	300k/600k	Yes	Max. 95	High: 15 Low: 6.5	-55 to 150°C	15-TQFN
ISL85412	3.5 to 40V	0.6 to 34	0.15	700k	Yes	Max. 92	High: 900 Low: 500	-40 to 125°C	12-DFN
ISL85413	3.5 to 40V	0.6 to 34	0.3	700k	Yes	Max. 92	High: 900 Low: 500	-40 to 125°C	12-DFN
ISL85415	3 to 36V	0.6 to 34	0.5	300k to 2M	Yes	Max. 94	High: 450 Low: 250	-40 to 125°C	12-DFN
ISL85418	3 to 40V	0.6 to 34	0.8	300k to 2M	Yes	Max. 96	High: 250 Low: 90	-40 to 125°C	12-DFN
ISL85410	3 to 40V	0.6 to 34	1.0	300k to 2M	Yes	Max. 96	High: 250 Low: 90	-40 to 125°C	12-DFN
ISL854102	3 to 40V	0.6 to 34	1.2	300k to 2M	Yes	Max. 93	High: 250 Low: 90	-40 to 125°C	12-DFN
RAA211412	5.8 to 45V	0.8 and up	1.0	630k	-	Max. 90	High: 600	-40 to 125°C	6-TSOT23
RAA211605	4.5 to 60V	0.8 and up	0.5	450k	-	Max. 93	High: 600	-40 to 125°C	6-TSOT23
RAA211650	4.5 to 60V	0.8 and up	5.0	200k to 2.5M	-	Max. 90	High: 90 Low: 37	-40 to 125°C	28-QFN
RAA211651	4.5 to 60V	0.8 and up	5.0	565k	-	Max. 93	High: 90 Low: 37	-40 to 125°C	28-QFN

### **Recommended Products: Power Management**

### LDO

Part No.	Description	Vin (V)	Vout (V)	Reference Voltage Accuracy (%) Full Temperature Range	Current Limit lout (typ) (mA)	Dropout Voltage typ (mV)	PSRR@ 1kHz (dB)	lq (µA) typ	Output Noise (typ) (µV/rms)	Package
RAA214220	150mA, 20V, low Iq	2.5 to 20	ADJ	+2.0/-2.0	220	225@150mA	92@100Hz	38	150@10mA	3-SOT23
ISL80136	50mA, 40V, low lq	6 to 40	ADJ	1.223V +/-1.0	118	120@50mA	58@100Hz	18	26@10mA	8-EPSOIC
ISL80138	150mA, 40V, low Iq	6 to 40	ADJ	1.223V +/-1.0	410	295@150mA	66@100Hz	18	26@10mA	14-HTSSOP
ISL80410	150mA, 40V, low Iq	6 to 40	ADJ	1.223V +/-1.0	410	295@150mA	66@100Hz	90	26@10mA	8-EPSOIC
RAA214401	150mA, 40V, low Iq	4.5 to 40	3.3	+2.7/-3.1	150min	1370@150mA	52	3.6	237@10mA	3-SOT23

### **Recommended Products: Gate Driver, MOSFET, Peripheral IC**

GreenPAK™

Programmable Mixes-Signal Matrix (fully customizable solution, low power, compact size, cost-optimized, programmed at factory)

### GreenPAK<sup>™</sup> with Low Drop Out Regulators (LDO)

ltem	SLG51000	SLG51001	SLG51002	SLG51003	SLG46580	SLG46582	SLG46583	SLG46585
eneral Parameters								
Memory Type	OTP	OTP	OTP	OTP	OTP	OTP	OTP	OTP
# of Pins / # of GPIOs	20 / 6	16 / 4	25 / 6	14 / 5	20 / 9	20 / 9	20 / 9	29 / 7
Operating Voltage (V)	2.8 - 5.0	2.8 - 5.0	2.8 - 5.0	2.8 - 5.0	2.3 - 5.5	2.3 - 5.5	2.3 - 5.5	2.5 - 5.5
Communication Interface Type	I <sup>2</sup> C	I <sup>2</sup> C	I <sup>2</sup> C	I <sup>2</sup> C				
Communication Interface Voltage	1.2V - 1.8V	1.2V - 1.8V	1.2V - 1.8V	1.2V - 5.0V	1.2V - 5.5V	1.2V - 5.5V	1.2V - 5.5V	1.2V - 5.5V
GPIO Voltage	1.2V - 1.8V	1.2V - 1.8V	1.2V - 5.0V	1.2V - 5.0V	1.2V - 5.5V	1.2V - 5.5V	1.2V - 5.5V	1.2V - 5.5V
Package Type	WLCSP	WLCSP	WLCSP	TQFN	TQFN	TQFN	TQFN	TQFN
	1.675 x 2.075 x 0.465,	1.675 x 1.675 x 0.465,	1.992 x 1.992 x 0.44,	2.0 x 2.2 x 0.55,	2 x 3 x 0.55,	2 x 3 x 0.55,	2 x 3 x 0.55,	3 x 3 x 0.55,
Package Size (mm)	0.4 pitch	0.4 pitch	0.35 pitch	0.4 pitch	0.4 pitch	0.4 pitch	0.4 pitch	0.4 pitch
Operating temperature (°C)	-40 to +85	-40 to +85	-40 to +85	-40 to +85				
ombinatorial Logic								
Analog Comparators	-	-	-	-	4	4	4	4
Max. Look Up Tables (LUTs) / DFF	12 / -	12 / -	8 / 8	8 / 8	15 / 9	15 / 9	15 / 9	16 / 9
Pipe Delay	-	-	-	-	16 - stage	16 - stage	16 - stage	16 - stage
Internal Oscillator (Hz)	8M	8M	8M	8M	1.73k / 25k / 2M	25k / 2M	25k / 2M	25k / 2M
Max. Counters/Delays	-	-	1/4	1 / 4	5	5	5	5
Combination Function Macro-cells	-	-	8	7	4	15	15	15
State Machine	Power Sequencer	Power Sequencer	Power Sequencer	-	8-state ASM	8-state ASM	8-state ASM	8-state ASM
Flexible Timing & Event-Triggered Sequencer	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes
ower Parameters								
# LDOs	7	6	8	3	4	2	2	4
VIN total range	0.8V - 5.0V	0.8V - 5.0V	0.8V - 5.0V	0.8V - 5.0V	2.3V - 5.5V	2.3V - 5.5V	2.3V - 5.5V	2.5V - 5.5V
VOUT total range	0.5V - 3.75V	0.5V - 3.75V	0.5V - 3.75V	0.5V - 3.75V	0.9V to 4.35V	0.9V to 4.35V	0.9V to 4.35V	0.9V to 4.2V
Output Current Max (A)	0.8	1	1.3	0.8	0.15	0.3	0.6	0.15
Max lout_LD01 (mA)	475 (High PSRR)	475 (High PSRR)	500	475 (High PSRR)	150	300	600	150
Max lout_LD02 (mA)	475 (High PSRR)	500	500	500	150	300	-	150
Max lout_LD03 (mA)	500	500	500	800	150	-	-	150
Max lout_LDO4 (mA)	500	500	500	-	150	-	-	150
Max lout_LD05 (mA)	800	500	500	-	-	-	-	-
Max lout_LD06 (mA)	800	1000	1 A	-	-	-	-	_
Max lout_LD07 (mA)	500	-	1 A	-	-	-	-	-
Max lout LD08 (mA)	_	-	1.3 A	_	-	-	_	_
# of Load Switches	2	1	5	1	R	2	1	1
Vdropout	80mV @ 0.8A (LV LDO)	100mV @1A (LV LDO)	130mV @ 1.3A (LV LDO)	100mV @ 0.8A (LV LDO)	250mV	250mV	250mV	250mV
PSRR		87dB @ 100kHz (HP LDO)		87dB @ 100kHz (HP LDO)	50dB @ 100Hz to 100kHz	50dB @ 100Hz to 100kHz	50dB @ 100Hz to 100kHz	50dB @ 100Hz to 100
Output Noise		13µV @ 10Hz to 100kHz	152µV @ 10Hz to 100kHz	18µV @ 10Hz to 100kHz			75µV @ 10Hz to 100kHz	
	(HP LDO)	(HP LDO)	(HV LDO)	(HP LDO)	Over-current &	Over-current &	Over-current &	Over-current &
Current limit	Startup & Functional	Startup & Functional	Startup & Functional	Startup & Functional	Short-Circuit Detection	Short-Circuit Detection	Short-Circuit Detection	Short-Circuit Detecti
	(Programmable)	(Programmable)	(Programmable)	(Programmable)	Current Limit	Current Limit	Current Limit	Current Limit
	500 001		500 001 575 111		ESD, OCL, SCD, OTP,	ESD, OCL, SCD, OTP,	ESD, OCL, SCD, OTP,	ESD, OCL, SCD, OT
Protection Features	ESD, OCL, OTP, UVLO	Read Lock	Read Lock	Read Lock	Read Lock			

### Power GreenPAK<sup>™</sup>

User-programmable ASICs (Also available programmed at the factory.)

#### Power GreenPAK<sup>™</sup> with Load Switches

ltem	SLG51000	SLG51001	SLG51002	SLG51003	SLG46116/7	SLG46127	SLG46517	SLG46867
General Parameters								
Memory Type	OTP	OTP	OTP	OTP	OTP	OTP	OTP	OTP
# of Pins / # of GPIOs	20 / 6	16 / 4	25 / 6	14 / 5	14 / 7	16 / 6	28 / 16	20 /12
Operating Voltage (V)	2.8 - 5.0	2.8 - 5.0	2.8 - 5.0	2.8 - 5.0	1.71 - 5.5	1.71 - 5.5	1.71 - 5.5	2.3 - 5.5
Communication Interface Type	I <sup>2</sup> C	I <sup>2</sup> C	I <sup>2</sup> C	I <sup>2</sup> C	-	-	I <sup>2</sup> C	I <sup>2</sup> C
Communication Interface Voltage	1.2V - 1.8V	1.2V - 1.8V	1.2V - 1.8V	1.2V - 5.0V	-	-	1.2V - 5.0V	1.2V - 5.0V
GPIO Voltage	1.2V - 1.8V	1.2V - 1.8V	1.2V - 5.0V	1.2V - 5.0V	1.71 - 5.5 V	1.2V - 5.0V	1.2V - 5.0V	1.2V - 5.0V
Package Type	WLCSP	WLCSP	WLCSP	TQFN	TQFN	TQFN	TQFN	ΤΩΓΝ
Package Size (mm)	1.675 x 2.075 x 0.465,	1.675 x 1.675 x 0.465,	1.992 x 1.992 x 0.44,	2.0 x 2.2 x 0.55,	1.6 x 2.5 x 0.55,	1.6 x 2.0 x 0.55,	2.0 x 3.0 x 0.55,	1.6 x 3.0 x 0.4,
Fackage Size (IIIII)	0.4 pitch	0.4 pitch	0.35 pitch	0.4 pitch	0.4 pitch	0.4 pitch	0.4 pitch	0.4 pitch
Operating temperature (°C)	-40 to +85	-40 to +85	-40 to +85	-40 to +85	-40 to +85	-40 to +85	-40 to +85	-40 to +85
Combinatorial Logic								
Analog Comparators	-	-	-	-	2	2	4	4
Max. Look Up Tables (LUTs) / DFF	12 /	12 /	8 / 8	8 / 8	10 / 4	10 / 4	17 / 8	23 / 21
Pipe Delay	-	-	-	-	8-stage	8-stage	16-stage	16-stage
Internal Oscillator (Hz)	8M	8M	8M	8M	25k / 2M	25k / 2M	25k / 2M / 25M	25k / 2M / 25M
Max. Counters/Delays	-	-	1/4	1/4	4	4	7	8
Combination Function Macro-cells	-	-	7	7	6	6	17	15
State Machine	Power Sequencer	Power Sequencer	Power Sequencer	-	-	-	8-state ASM	-
Power Parameters								
# of Load Switches	2	1	5	1	1 Total	2 Total	2 Total	2 x PFET
Load Switch Type (PMOS / NMOS)	2 x NMOS	1 x NMOS	3 x NMOS, 2 x PMOS	1 x NMOS	1 x PMOS	2 x PMOS	2 x PMOS	2 x PMOS
Max lout	0.8A	1A	1.3A	0.8A	1.25A	2A	2A	2A
RON	40mΩ	40mΩ	40mΩ	40mΩ	28.5mΩ	44mΩ	44mΩ	44mΩ
Programmable Current Limit	Yes	Yes	Yes	Yes	_	-	-	-
Slew Rate	Yes	Yes	Yes	Yes	Fixed	-	-	-
# of LDOs	7	6	8	3	-	-	-	-
Protection Features	ESD, OCP, OTP, UVLO	ESD, OCP, OTP, UVLO	ESD, OCP, OTP, UVLO	ESD, OCP, OTP, UVLO	ESD, Read Lock	ESD, Read Lock	ESD, Read Lock	ESD, Read Lock
Discharge Resistance	Fixed	Fixed	Programmable	Programmable	W/O Fixed	-	-	-

### High-Voltage GreenFET Load Switch



Package Size



### **Dual-Channel GreenFET Load Switch**





Package Size

### Gate Driver: 3-Phase Product Family

Part No.	Description	Maximum Boot Strap Voltage (V)	Maximum Bias Voltage (V)	Input Lines/ Output Lines	Peak Pull-Up/ Pull-Down Current (A)	Turn On/Off Propagation Delay (nS)	Rise/Fall Time (nS)	Input Logic	Package	Remarks
RAA227063	60V smart 3-phase gate driver	74	14	6/6	1/2	40/40	Programmable drive control	TTL (VIL / V\IH 1.21 / 1.57)	QFN-48	Buck Boost 500mA LDO (5V or 3.3V) 200mA
RAA306012	65V smart 3-phase gate driver	78	17	6/6	0.64/1.28	40/40	Programmable drive control	TTL (VIL / V\IH 1.21 / 1.57)	QFN-48	Buck Boost 500mA LDO (5V or 3.3V) 100mA
HIP4083	80V, 300mA peak, for 3-phase	95	15	3/3	0.24/0.3	60/65	35/30	TTL/CMOS	SOC-16P DIP-16	Integrated output level shift circuit
HIP4086/A	80V, 500mA peak, for 3-phase	95	15	6/6	0.5	45/30	20/10	TTL/CMOS	SOC-24 PDIP-24	Part No. without A: Integrated charge pump.

### Gate Driver: Full-Bridge Product Family

		Maximum	Maximum	Input Lines/	Peak	Turn On/Off			Pacl	kage
Part No.	Description	Boot Strap Voltage (V)	Bias Output Voltage (V) Lines		Pull-Up/ Pull-Down Current (A)	Propagation Delay (nS)	Rise/Fall Time (nS)	Input Logic	PDIP	SOIC
HIP4080A	80V, 2.5A peak, high-frequency dead time control, built-in input comparator	95	15	1/4	2.6/2.4	40/50	10/10	Logic Thresholds Compatible with 5V to 15V Logic level	20-pin	20-pin
HIP4081A	80V, 2.5A peak, high-frequency dead time control	95	15	4/4	2.6/2.4	35/45	10/10	Logic Thresholds Compatible with 5V to 15V Logic level	20-pin	20-pin
ISL83202	55V, 1A peak	70	15	4/4	1/1	75/55	9/9	Logic Thresholds Compatible with 5V to 15V Logic level	16-pin	16-pin

### Gate Driver: Half-Bridge Product Family

Part No.	Maximum Boot Strap Voltage (V)	Maximum Bias Voltage (V)	Input Lines/ Output Lines	Peak Pull-Up/ Pull-Down Current (A)	Turn On/Off Propagation Delay (nS)	Rise/Fall Time (nS)	Input Logic	Package	Remarks
HIP2210	115	18	1/2	3/4	30/30	20/20	Tri state	10-TDFN	Tri-state, adjustable input threshold, adjustable dead time
HIP2211	115	18	2/2	3/4	15/15	20/20	CMOS	8-SOIC, 10-TDFN, 8-DFN	_
HIP2100	114	14	2/2	2/2	20/20	10/10	CMOS	8-EPSOIC, 8-SOIC, 16-QFN	_
HIP2101	114	14	2/2	2/2	25/25	10/10	TTL/CMOS	8-EPSOIC, 8-SOIC 16-QFN, 12-DFN	_
ISL2100A	114	14	2/2	2/2	39/31	10/10	CMOS	8-SOIC, 9-DFN	Equivalent to HIP2100 with input hysteresis added.
ISL2101A	114	14	2/2	2/2	39/31	10/10	TTL	8-SOIC, 9-DFN	Equivalent to HIP2101, but with ability to swing input up to the bias voltage
ISL2110A	114	14	2/2	3/4	38/32	9/7.5	CMOS	8-SOIC, 12-DFN	_
ISL2111A/B	114	14	2/2	3/4	38/32	9/7.5	TTL	8-SOIC, 10-TDFN 12-DFN, 8-DFN	_
HIP2103	66	16	2/2	1/2	28/30	20/17	CMOS	8-DFN	_
HIP2104	66	-	2/2	1/2	23/27	21/17	CMOS	12-DFN	VBAT = 60V, 75mA, built-in LDO

### Other Drivers and Detectors









Part No.	Vin (max) (V)	Input Lines/ Output Lines	Peak Current (A)	Turn On/Off Propagation Delay (nS)	Rise/Fall Time (nS)	Input Logic	Package	Remarks
ISL89163	16	2/2	6	25/25	25/25	TTL/CMOS	8-EPSOIC, 8-TDFN	Non-inverting/non-inverting driver
ISL89164	16	2/2	6	25/25	25/25	TTL/CMOS	8-EPSOIC, 8-TDFN	Inverting/inverting driver
ISL89165	16	2/2	6	25/25	25/25	TTL/CMOS	8-EPSOIC, 8-TDFN	Inverting/non-inverting driver
ISL89410	18	2/2	4	18/20	10/13	CMOS	8-PDIP, 8-SOIC	Non-inverting/non-inverting driver High-voltage-tolerance version of EL7202
ISL89411	18	2/2	4	18/20	10/13	CMOS	8-PDIP, 8-SOIC	Inverting/inverting driver High-voltage-tolerance version of EL7212
ISL89412	18	2/2	4	18/20	10/13	CMOS	8-PDIP, 8-SOIC	Inverting/non-inverting driver High-voltage-tolerance version of EL7222
RAA226110	18	1/1	0.3/0.75/2	20/20	2/2	-	16-QFN	For GaN FETs

### Gate Driver: Low-Side Product Family

### Power MOSFETs

Part No.	Nch/Pch	Resisting Pressure	Current	ON Resistance (max)	Package
RJK2075DPA	Nch Single	200V	20A	69mΩ	WPAK
RJK2076DPA	Nch Single	200V	20A	85mΩ	WPAK
RJK1054DPB	Nch Single	100V	20A	22mΩ	LFPAK
RJK0854DPB	Nch Single	80V	25A	13mΩ	LFPAK
UPA3753GR	Nch Dual	60V	5A	72mΩ	SOP-8
RJK0454DPB	Nch Single	40V	40A	4.9mΩ	LFPAK
RJK0455DPB	Nch Single	40V	45A	3.8mΩ	LFPAK
RJK0456DPB	Nch Single	40V	50A	3.2mΩ	LFPAK
RJK0349DSP-01	Nch Single	30V	20A	$5.0 \mathrm{m}\Omega$	SOP-8
UPA2736GR	Pch Single	-30V	-14A	13.5mΩ	SOP-8
UPA2814T1S	Pch Single	-30V	-24A	14.5mΩ	HWSON-8

### Peripheral IC: RS-485 Transceiver

Device	Duplex	VCC	Data Rate	Fail-Safe Fractional Unit Load	Fractional	Tx Vod		Tx Out / Rx In			Temp		
		(V)	(Mbps)		(V)	нвм	IEC61000-4-2 ESD Contact	IEC61000-4-4 EFT	Hot Plug	(°C)	Package		
ISL3159E	Half	4.5 to 5.5				Min. 2.1	±16.5kV	±8kV			-40 to 85	8L SOIC/MSOP	
ISL3179E		3.0 to 3.6	40	Open, Short , Idle 160	160	Min. 1.5	±16.5kV	±9kV		- Y	-40 to 125	10L DFN	
ISL3160E	Full	4.5 to 5.5				Min. 2.1	±10kV	±5kV			-40 to 125	14L SOIC	
ISL3180E		3.0 to 3.6				Min. 1.5	±12kV	±5kV			-40 to 85		
RAA788152 / 55 / 58	- Half - Full -	Half	4.5 to 5.5	0.115 / 1 / 20			Min. 2.4	±16.5kV	±9kV	±5kV			8L SOIC/MSOP
RAA788172 / 75 / 78		3.0 to 3.6	0.25 / 0.5 / 20	Open,	256	Min. 1.5	±15kV	±8kV	±3kV	Y	-40 to 85	BL SUIC/IVISUP	
RAA788150 / 53 / 56		4.5 to 5.5	0.115 / 1 / 20	Short , Idle	Idle 200	Min. 2.4	±16.5kV	±9kV	±5kV			10L MSOP	
RAA788170 / 72 / 76		3.0 to 3.6	0.25 / 0.5 / 20			Min. 1.5	±15kV	±8kV	±3kV			14L SOIC	

Device	Duplex	VCC (V)	Data Rate (Mbps)	Fail-Safe	Devices on Bus	Wide VCM (V)	Protection Tx Out/Rx In	Hot Plug	Temp (°C)	Package					
ISL32452E/55E/58E	Half			0.25 / 1 / 20							8L SOIC / 8L MSOP				
ISL32457E		3.0 to 5.5	0.25 / 20			±20	±60V Fault Protected ±15k or 16.5kV HBM ESD	N	-40 to 85	8L SOIC					
ISL32459E			0.25720	Open, Short, Idle	128										
ISL32496E	Full	Full	454455	A E to E E	A E to E E	4 E 40 E E	4.5 to 5.5	0.25 / 1 / 15	luic		. 05	±60V Fault Protected	V	-40 to 85	10L MSOP / 14L SOIC
ISL32492E/95E/98E	Half	4.0100.0	0.25 / 1 / 15			±25 ±15k or 16.5kV HBM ESD	T	-40 10 65	8L SOIC / MSOP						

### 36V/144W BLDC Motor Controller

This design features a 32-bit MCU optimized for fieldoriented control (FOC) of a single BLDC motor. The MCU includes a best-in-class floating point unit (FPU) and built-in peripherals for motor control, allowing for a compact and cost-effective motor controller. The system is powered off a standard 24VDC input and receives precise position feedback from an inductive position sensor.



### **BLDC Traction Motor Drive**

The combination of a high-performance MCU and a 3-phase smart driver delivers optimal processing speed and power efficiency, catering to traction motors with small form factor limitations and varied power requirements. The integrated power management allows the driver and MCU to be powered directly from the battery, reducing overall circuitry. Programmability enables customers to optimize the inverter power stage for different power levels by adjusting MOSFETs and tuning slew rate, dead time, and gate drive via software. By using two inductive position sensors, customers can replace large, costly optical encoders. These sensors provide absolute position information and incremental position sensing with up to 17 bits of resolution, utilizing the MCU's advanced ADC capabilities.

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### High Power, Compact BLDC Motor Control

The smart gate driver IC is designed for 3-phase sensorless Brushless DC (BLDC) motor applications. It integrates three half-bridge smart gate drivers capable of powering N-channel MOSFET bridges with voltages ranging from 4.5V to a maximum of 60V, featuring 1A drive and 2A sinking current capability. This setup enables control of high-current GaN MOSFETs. The IC includes a buck-boost converter to supply power to the MCU and incorporates three differential amplifiers with adjustable gain for precise ground-side shunt current sensing, feeding data to the MCU's ADC input. The MCU enhances data communication through CAN FD and I3C protocols and features a specialized ADC for motor control, supporting calculation-intensive algorithms for smoother motor tuning. The use of GaN high voltage MOSFETs allows for high current switching without bulky heatsinks, optimizing the system for compact, highefficiency applications.



### Motor Control with Resolver

In this design, Renesas provides a stepping motor solution with resolver position control and an alternate BLDC motor solution. The stepping motor solution realizes a high-performance motor drive unit for office automation and industrial applications such as scanners, multi-function printers and automated cash deposit machines. While the BLDC motor solution realizes a high-performance motor drive unit for Automatic Guided Vehicle (AGV), small vehicle, service robot, and assisted bicycle applications.

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### Motor Control System with Industrial Network and Functional Safety

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Renesas provides a comprehensive system for industrial motor control, integrating an MPU and MCU for mutual monitoring, along with power supply ICs, delta-sigma  $(\Delta \Sigma)$  modulators, and other essential devices. This combination of components enables a streamlined and high-performance approach to motor control, industrial networking, and functional safety, ensuring efficient and reliable operations in industrial environments.



### AC Drive & General Purpose Inverter System

This system provides a basic configuration and essential components for AC drives and general purpose (GP) inverters, serving as a variable-speed controller to precisely regulate shaft rotation speed in induction and synchronous motors. It is widely used in industrial machinery such as conveyors, cranes, elevators, fans, pumps, and compressors. Due to its versatile application scenarios, the system supports multiple optional functions to meet diverse industrial requirements, ensuring adaptability and efficiency in various settings.



### **Absolute Inductive Position Sensor**

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This simple and cost-effective design utilizes off-theshelf components like a standard PCB, a Renesas position sensor, passive components, and a metal piece as a target. The sensing element consists of a set of coils on the PCB rather than inside the Renesas IC, allowing the sensor system to be tailored to specific customer applications. This flexibility enables the sensor system to be customized to the customer's needs. It uses dual inductive position sensors (IPS) for absolute position detection, optimizes coil size, and aligns with market trends such as 35mm motors.



AC Servo

This Renesas AC servo solution integrates motor control and EtherCAT design to support high-speed and highprecision motor control through synchronizing timesensitive industrial Ethernet communications. This solution is composed of three blocks: system control, power drive and motor encoder, which are physically isolated while maintaining a high degree of interconnect. By utilizing the high-performance RZ/T2L, RZ/T2M or RZ/N2L microprocessor, this monolithic solution design outperforms traditional two-chip platforms on performance and cost.





This design features an MCU optimized for single motor field-oriented control (FOC) of a BLDC motor. The MCU has a best-in-class built-in floating point unit (FPU) and various peripheral functions, allowing for a compact, low BOM cost motor controller board. This design is intended for an un-isolated environment where the user cannot make direct contact with the controller. The system offers remote control via an ultra-low power Wi-Fi + Bluetooth® Low Energy (LE) module, providing flexibility and advanced connectivity for modern industrial applications.



### **3-Phase RISC-V Motor Controller**

This simplified 3-phase motor control system features a cost-optimized RISC-V 32MHz 32-bit ASSP, with rich analog IP and support for temperatures up to 125°C. The ASSP is a pre-programmed motor control solution, allowing users to store specific motor characteristics in device flash via a GUI interface. Additional input channels accommodate signals from a motor position encoder and Hall sensors. A Pmod<sup>™</sup> interface with I<sup>2</sup>C and serial ports enables connection to external environmental sensors or wireless connectivity modules.



### Servo Motor Control for Robot Limbs

This system enables motor control for angular motion with adequate torque and speed. It also monitors the status of multiple motors via 1-wire through UART from the host MCU, which allows users to reduce the harness in a system and to control robot limbs such as for service robots, manipulators and Automatic Guided Vehicles (AGV). The SLG47115 HVPAK<sup>™</sup> programmable mixedsignal matrix has high-voltage H-bridge functionality in a tiny 2mm x 3mm QFN package which contributes to minimizing the size of the servo motor.

### DC Motor Driver Pmod

This implementation of the HVPAK<sup>™</sup> programmable mixed-signal matrix over Pmod<sup>™</sup> provides flexibility for users to control and configure the HVPAK motor drive using any MCU/MPU. There are multiple protection sections implemented to use it as a standalone motor drive as well. The motors, the DC motor with direction and speed control as well as the stepper motor with micro-steps are easily configurable. This will reduce the development and turnaround time of any customer.





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