

**RL78/G13** 

Timer Array Unit (Interval Timer)

R01AN0456EJ0200 Rev. 2.00 Dec. 27, 2013

### Introduction

This application note describes the interval timer function of the timer array unit (TAU). This unit inverts the LED indication each time a timer interrupt occurs. Also, it changes the timer interrupt cycle time based on the number of times the switch is pressed.

# **Target Device**

RL78/G13

When applying the sample program covered in this application note to another microcomputer, modify the program according to the specifications for the target microcomputer and conduct an extensive evaluation of the modified program.



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# 1. Specifications

This application note shows example settings for using timer interrupts (INTTM00) from the interval timer and interrupts (INTP0) generated on pin input edge detection. The TAU inverts the LED indication each time a timer interrupt (INTTM00) occurs. Also, this unit changes the timer interrupt (INTTM00) cycle time based on the number of times the switch (SW) is pressed.

Table 1.1 lists the peripheral functions to be used and their uses. Figure 1.1 shows the timer and its interrupt operation.

Table 1.1 Peripheral Functions to be Used and Their Uses

Peripheral Function	Use
Timer array unit (channel 0)	Time interval control for inversion of the P10 pin output (LED indication)
P10	Output port for LED indications
P137/INTP0	Switch input for changing the timer interrupt (INTTM00) cycle time



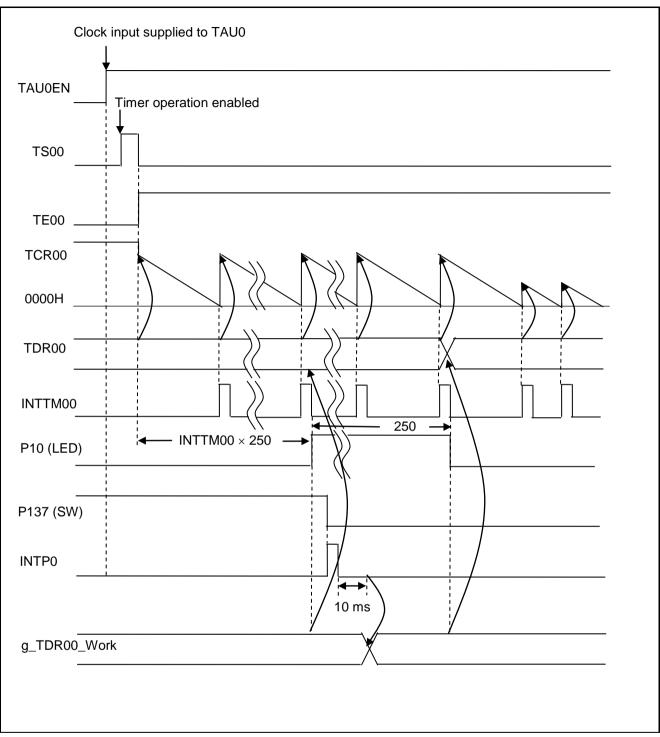


Figure 1.1 Overview of Timer Operation and Interrupts

# 2. Operation Check Conditions

The sample code contained in this application note has been checked under the conditions listed in the table below.

**Table 2.1 Operation Check Conditions** 

Item	Description
Microcontroller used	RL78/G13 (R5F100LEA)
Operating frequency	High-speed on-chip oscillator (HOCO) clock: 32 MHz
	CPU/peripheral hardware clock: 32 MHz
Operating voltage	5.0V (can run on a voltage range of 2.9 V to 5.5 V.)
	LVD operation (VLVI): Reset mode 2.81 V (2.76 V to 2.87 V)
Integrated development	CubeSuite+ V1.00.01 from Renesas Electronics Corp.
environment (CubeSuite+)	
C compiler (CubeSuite+)	CA78K0R V1.20 from Renesas Electronics Corp.
Integrated development	e2studio V2.0.1.3 from Renesas Electronics Corp.
environment (e2studio)	
C compiler (e2studio)	KPIT GNURL78-ELF Toolchain V13.02 from Renesas Electronics Corp.
Integrated development	IAR Embedded Workbench for Renesas RL78 V1.30.2
environment (IAR)	
C compiler (IAR)	IAR C/C++ Compiler for Renesas RL78 V1.30.2

# 3. Related Application Note

The application note that is related to this application note is listed below for reference.

• RL78/G13 Initialization (R01AN0451EJ0100) Application Note



## 4. Description of the Hardware

## 4.1 Hardware Configuration Example

Figure 4.1 shows an example of hardware configuration that is used for this application note.

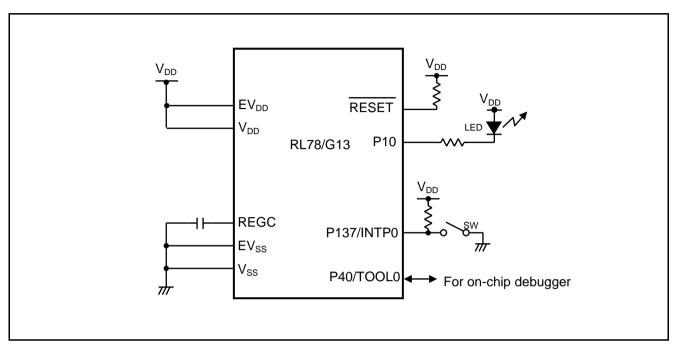


Figure 4.1 Hardware Configuration

- Cautions: 1. The purpose of this circuit is only to provide the connection outline and the circuit is simplified accordingly. When designing and implementing an actual circuit, provide proper pin treatment and make sure that the hardware's electrical specifications are met (connect the input-only ports separately to  $V_{DD}$  or  $V_{SS}$  via a resistor).
  - 2. Connect any pins whose name begins with  $EV_{SS}$  to  $V_{SS}$  and any pins whose name begins with  $EV_{DD}$  to  $V_{DD}$ , respectively.
  - 3.  $V_{DD}$  must be held at not lower than the reset release voltage  $(V_{LVI})$  that is specified as LVD.

#### 4.2 List of Pins to be Used

Table 4.1 lists the pins to be used and their functions.

Table 4.1 Pins to be Used and Their Functions

Pin Name I/O		Description		
P10	Output	Output port for LED indications		
P137/INTP0 Input		Switch (SW) input pin (external interrupt request input pin)		



#### 5. **Description of the Software**

#### 5.1 **Operation Outline**

This application note describes how to set up the interval timer function of TAU0.

This setup is followed by operation for counting the number of timer interrupts (INTTM00) generated by the interval timer. Each time the count reaches 250, the LED indication is inverted. The timer interrupt (INTTM00) cycle time is changed according to the number of times the switch is pressed. The LED on/off cycle time is changed as follows.

 $500 \text{ ms} \rightarrow 250 \text{ ms} \rightarrow 125 \text{ ms} \rightarrow 62.5 \text{ ms} \rightarrow 500 \text{ ms} \rightarrow \dots$ 

- (1) Initialize the TAU.
- Use the interval timer mode as the timer operation mode.
- Initialize timer data register 00 (TDR00) to 2 ms.
- Set the timer output enable register to disable operation.
- Use timer interrupts (INTTM00) from timer channel 0.
- (2) Initialize the external edge detection interrupt.
- Select a falling edge as the valid edge for INTP0.
- Use INTP0 interrupts.
- (3) Execute a HALT instruction to wait for timer interrupts (INTTM00).
- (4) After the HALT mode is cancelled by a timer interrupt (INTTM00), the number of INTTM00 interrupts generated is counted.
- (5) When the timer interrupt count reaches 250, the LED indication is inverted. The value (g\_TDR00\_Work) in RAM for the timer data register is set in the timer data register (TDR00).
- (6) INTP0 interrupt processing changes the switch input count (INTP0 interrupt count) and g\_TDR00\_Work value.

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#### 5.2 **List of Option Byte Settings**

Table 5.1 summarizes the settings of the option bytes.

Table 5.1 **Option Byte Settings** 

Address Value		Description		
000C0H/010C0H	01101110B	Disables the watchdog timer.		
		(Stops counting after the release from the reset state.)		
000C1H/010C1H	01111111B	LVD reset mode, 2.81 V (2.76 V to 2.87 V)		
000C2H/010C2H	11101000B	HS mode, HOCO: 32 MHz		
000C3H/010C3H	10000100B	Enables the on-chip debugger.		

#### 5.3 **List of Constants**

Table 5.2 lists the constants that are used in this sample program.

Table 5.2 **Constants for the Sample Program** 

Constant	Setting	Description
_01_INTP0_EDGE_FALLING_SEL	01h	Selects a falling edge as the valid edge of INTP0.
g_DTR000_Data[]	(64000-1)	TDR00 settings by number of times the switch is
	(32000-1)	pressed
	(16000-1)	
	(8000-1)}	
g_10msCount[]	(5+1)	10 ms timer count values by number of times the
	(10+1)	switch is pressed
	(20+1)	
	(40+1)	

#### 5.4 **List of Variables**

Table 5.3 lists the global variable that is used by this sample program.

Table 5.3 **Global Variables for the Sample Program** 

Type	Variable Name	Contents	Function Used
sreg uint8_t	g_SW_Counter	Switch press count	R_INTC0_Interrupt()
			main()
			R_InvertLED()
sreg uint16_t	g_TDR00_Work	Value which is set in TDR00 each	R_INTC0_Interrupt()
		time the timer interrupt count reaches	main()
		250.	R_InvertLED()

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## 5.5 List of Functions

Table 5.4 lists the functions that are used by this sample program.

Table 5.4 Functions

Function Name	Outline
R_TAU0_Channel0_Start	Starts operation of TAU0 channel 0.
R_TAU0_Channel0_Interrupt()	Processes timer interrupts on TAU0 channel 0.
R_InvertLED()	Counts the number of INTTM00 interrupts generated. Inverts the LED indication each time the interrupt count reaches 250.
R_INTC0_Start	Enables INTP0 interrupts.
R_INTC0_Interrupt	Processes INTP0 interrupts.

# 5.6 Function Specifications

This section describes the specifications for the functions that are used in the sample code.

[Function Name] R_TAU0_Channel0_Start					
Synopsis	TAU0 channel 0 operation start				
Header	#include "r_cg_macrodriver.h"				
	#include "r_cg_timer.h"				
	#include "r_cg_userdefine.h"				
Declaration	void R_TAU0_Channel0_Start(void)				
Explanation	This function unmasks TAU0 channel 0 interrupts and starts count operation.				
Arguments	None				
Return value	None				
Remarks	None				

[Function Name] R_TAU0_Channel0_Interrupt()				
Synopsis	TAU0 channel 0 timer interrupt processing			
Header	r_cg_macrodriver.h			
	r_cg_timer.h			
	r_cg_userdefine.h			
Declaration	interrupt void R_TAU0_Channel0_Interrupt(void)			
Explanation	This function calls the function which will invert the LED indication.			
Arguments	None			
Return value	None			
Remarks	None			

[Function Name] R\_InvertLED()

Synopsis LED indication inversion processing

**Header** r\_cg\_macrodriver.h

r\_cg\_cgc.h
r\_cg\_port.h
r\_cg\_intc.h
r\_cg\_timer.h
r\_cg\_userdefine.h

**Declaration** void R\_InvertLED( void )

**Explanation** This function counts 250 timer interrupts (INTTM00) and then inverts the LED

indication (for port latch inversion). It also changes the TDR00 setting to the value

specified with g\_TDR00\_Work.

Arguments None Return value None Remarks None

[Function Name] R\_INTC0\_Start

Synopsis INTP0 interrupt enable

**Header** r\_cg\_intc.h

**Declaration** void R\_INTC0\_Start(void)

**Explanation** This function clears the interrupt request flag. It enables INTP0 interrupts and starts

taking in the switch input.

Arguments None
Return value None
Remarks None

[Function Name] R\_INTC0\_Interrupt()

Synopsis INTP0 interrupt processing

**Header** r\_cg\_macrodriver.h

r\_cg\_intc.h

r\_cg\_userdefine.h

**Declaration** \_\_interrupt void R\_INTC0\_Interrupt(void)

**Explanation** This function processes INTP0 interrupts as they occur.

It waits 10 ms and then scans P13.7 (SW input pin). When the switch is pressed, this

function changes the g\_TDR00\_Work value.

Arguments None
Return value None
Remarks None



### 5.7 Flowcharts

Figure 5.1 shows the overall flow of the sample program described in this application note.

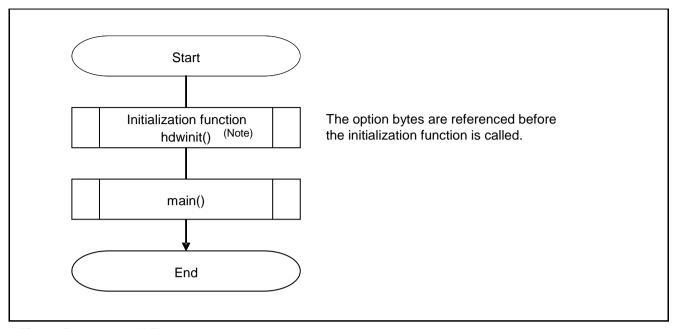


Figure 5.1 Overall Flow

#### 5.7.1 Initialization Function

Figure 5.2 shows the flowchart for the initialization function.

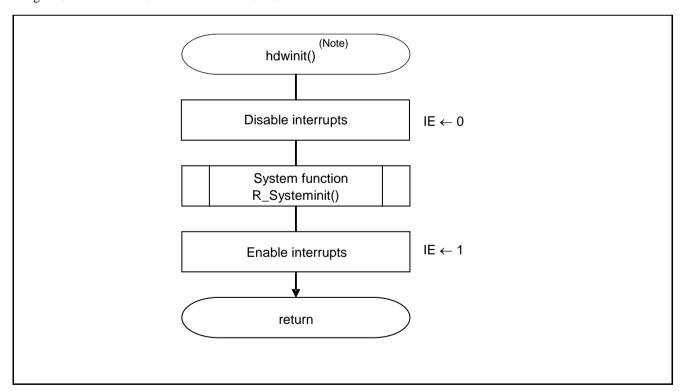


Figure 5.2 Initialization Function

Note: The \_\_low\_level\_init function initializes the system in the IAR Workbench IDE-Oriented sample code.



# 5.7.2 System Function

Table 5.3 shows the flowchart for the system function.

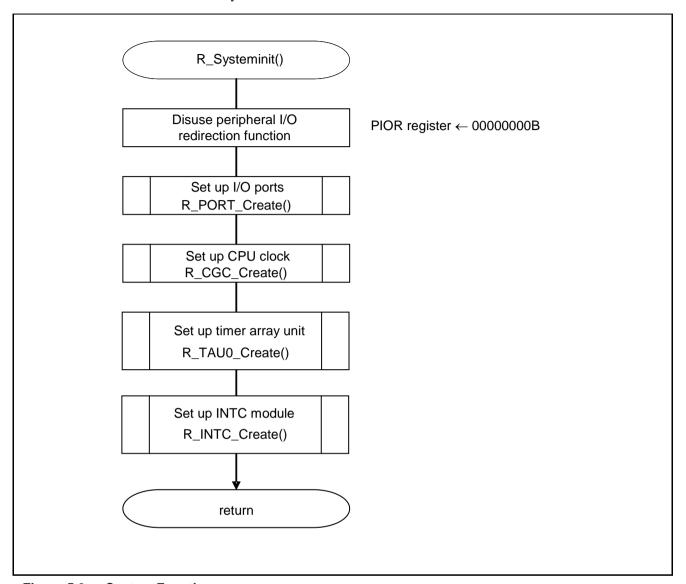


Figure 5.3 System Function



### 5.7.3 I/O Port Setup

Table 5.4 shows the flowchart for I/O port setup.

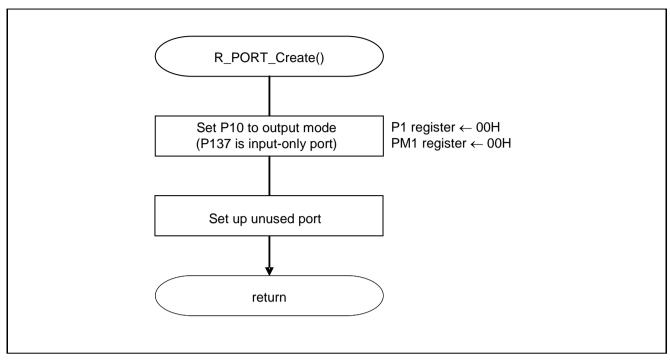


Figure 5.4 I/O Port Setup

Note: Refer to the section entitled "Flowcharts" in RL78/G13 Initialization Application Note (R01AN0451EJ0100) for the configuration of the unused ports.

Caution: Provide proper treatment for unused pins so that their electrical specifications are observed. Connect each of any unused input-only ports to VDD or VSS via a separate resistor.

Setting up the LED port

• Port mode register 1 (PM1) Select I/O mode for the port.

Symbol: PM1

7	6	5	4	3	2	1	0
PM17	PM16	PM15	PM14	PM13	PM12	PM11	PM10
0	0	0	0	0	0	0	0

Bit 0

PM10	P10 pin I/O mode selection		
0	Output mode (output buffer on)		
1	Input mode (output buffer off)		

Caution: For details on the register setup procedures, refer to RL78/G13 User's Manual: Hardware.

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# 5.7.4 CPU Clock Setup

Figure 5.5 shows the flowchart for setting up the CPU clock.

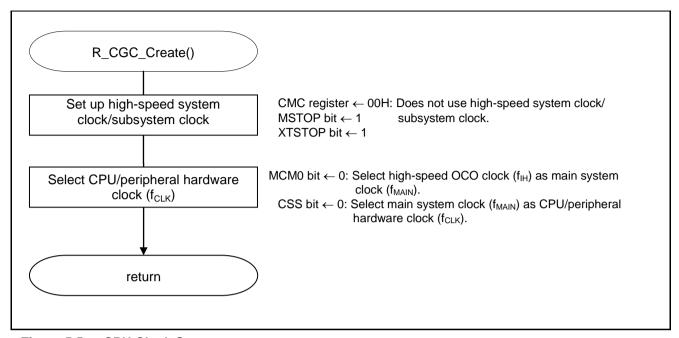


Figure 5.5 CPU Clock Setup

Caution: For details on the procedure for setting up the CPU clock (R\_CGC\_Create ()), refer to the section entitled "Flowcharts" in RL78/G13 Initialization Application Note (R01AN0451EJ0100).



## 5.7.5 Timer Array Unit Setup

Figure 5.6 shows the flowchart for setting up the timer array unit.

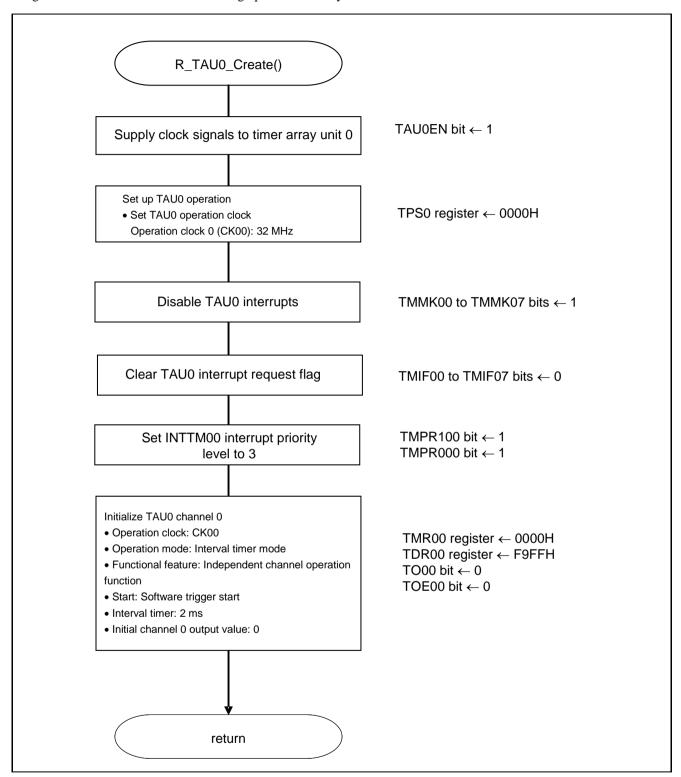


Figure 5.6 Timer Array Unit Setup

Starting clock signal supply to the timer array unit 0

• Peripheral enable register 0 (PER0) Start supplying clock signals to the timer array unit 0.

Symbol: PER0

7	6 5		4	3	2	1	0
RTCEN	IICA1EN	ADCEN	IICA0EN	SAU1EN	SAU0EN	TAU1EN	TAU0EN
Х	Х	Х	Х	Х	Х	Х	1

#### Bit 0

TAU0EN	Control of timer array unit 0 input clock supply
0	Stops input clock supply.
1	Enables input clock supply.

Caution: For details on the register setup procedures, refer to RL78/G13 User's Manual: Hardware.



Configuring the timer clock frequency

• Timer clock select register 0 (TPS0) Select an operation clock for timer array unit 0.

Symbol: TPS0

_	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
	0	0	PRS	PRS	0	0	PRS	PRS	PRS					PRS	PRS	PRS
		0	031	030	U		021	020	013	012	011	010	003	002	001	000
	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	0	0	0	0

Bits 3 to 0

PR	PR	PR	PR		Operation clock (CK00) selection										
S00 3	S00 2	S00 1	S00 0		f <sub>CLK</sub> = 2 MHz	f <sub>CLK</sub> = 5 MHz	f <sub>CLK</sub> = 10 MHz	f <sub>CLK</sub> = 20 MHz	f <sub>CLK</sub> = 32 MHz						
0	0	0	0	f <sub>CLK</sub>	2 MHz	5 MHz	10 MHz	20 MHz	32 MHz						
0	0	0	1	f <sub>CLK</sub> /2	1 MHz	2.5 MHz	5 MHz	10 MHz	16 MHz						
0	0	1	0	f <sub>CLK</sub> /2 <sup>2</sup>	500 kHz	1.25 MHz	2.5 MHz	5 MHz	8 MHz						
0	0	1	1	f <sub>CLK</sub> /2 <sup>3</sup>	250 kHz	625 kHz	1.25 MHz	2.5 MHz	4 MHz						
0	1	0	0	f <sub>CLK</sub> /2 <sup>4</sup>	125 kHz	312.5 kHz	625 kHz	1.25 MHz	2 MHz						
0	1	0	1	f <sub>CLK</sub> /2 <sup>5</sup>	62.5 kHz	156.2 kHz	312.5 kHz	625 kHz	1 MHz						
0	1	1	0	f <sub>CLK</sub> /2 <sup>6</sup>	31.25 kHz	78.1 kHz	156.2 kHz	312.5 kHz	500 kHz						
0	1	1	1	f <sub>CLK</sub> /2 <sup>7</sup>	15.62 kHz	39.1 kHz	78.1 kHz	156.2 kHz	250 kHz						
1	0	0	0	f <sub>CLK</sub> /2 <sup>8</sup>	7.81 kHz	19.5 kHz	39.1 kHz	78.1 kHz	125 kHz						
1	0	0	1	f <sub>CLK</sub> /2 <sup>9</sup>	3.91 kHz	9.76 kHz	19.5 kHz	39.1 kHz	62.5 kHz						
1	0	1	0	f <sub>CLK</sub> /2 <sup>10</sup>	1.95 kHz	4.88 kHz	9.76 kHz	19.5 kHz	31.25 kHz						
1	0	1	1	f <sub>CLK</sub> /2 <sup>11</sup>	976 Hz	2.44 kHz	4.88 kHz	9.76 kHz	15.63 kHz						
1	1	0	0	f <sub>CLK</sub> /2 <sup>12</sup>	488 Hz	1.22 kHz	2.44 kHz	4.88 kHz	7.81 kHz						
1	1	0	1	f <sub>CLK</sub> /2 <sup>13</sup>	244 Hz	610 Hz	1.22 kHz	2.44 kHz	3.91 kHz						
1	1	1	0	f <sub>CLK</sub> /2 <sup>14</sup>	122 Hz	305 Hz	610 Hz	1.22 kHz	1.95 kHz						
1	1	1	1	f <sub>CLK</sub> /2 <sup>15</sup>	61 Hz	153 Hz	305 Hz	610 Hz	976 Hz						

Caution: For details on the register setup procedures, refer to RL78/G13 User's Manual: Hardware.

Setting up channel 0 operation mode

• Timer mode register 00 (TMR00) Select an operation clock (f<sub>MCK</sub>). Select a count clock. Select the software trigger start. Set up the operation mode.

Symbol: TMR00

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
CKS	CKS	0	CCS	MAS	STS	STS	STS	CIS0	CIS0	0	0	MD0	MD0	MD0	MD0
001	000		00	TER	002	001	000	01	00			03	02	01	00
				00											
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0

### Bits 15 and 14

CKS001	CKS00 0	Channel 0 operation clock (f <sub>MCK</sub> ) selection
0	0	Operation clock CK00 set by timer clock select register 0 (TPS0)
0	1	Operation clock CK02 set by timer clock select register 0 (TPS0)
1	0	Operation clock CK01 set by timer clock select register 0 (TPS0)
1	1	Operation clock CK03 set by timer clock select register 0 (TPS0)

### Bit 12

CCS00	Channel 0 count clock (f <sub>TCLK</sub> ) selection
0	Operation clock (f <sub>MCK</sub> ) specified by the CKS000 and CKS001 bits
1	Valid edge of input signal input from the TI00 pin

#### Bit 11

MASTER00	Selection between using channel 0 independently or simultaneously with another channel (as a slave or master)
	Operates in independent channel operation function or as slave channel in simultaneous channel operation function.
1	Operates as master channel in simultaneous channel operation function.

Caution: For details on the register setup procedures, refer to RL78/G13 User's Manual: Hardware.

Symbol: TMR00

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
CKS	CKS	0	CCS	MAS	STS	STS	STS	CIS0	CIS0	0	0	MD0	MD0	MD0	MD0
001	000		00	TER	002	001	000	01	00			03	02	01	00
				00											
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0

### Bits 10 to 8

STS002	STS001	STS000	Setting of start trigger or capture trigger of channel 0
0	0	0	Only software trigger start is valid (other trigger sources are unselected).
0	0	1	Valid edge of the TI00 pin input is used as both the start trigger and capture trigger.
0	1	0	Both the edges of the TI00 pin input are used as a start trigger and a capture trigger.
1 0 0		0	Interrupt signal of the master channel is used (when the channel is used as a slave channel with the simultaneous channel operation function).
Other than above		ove	Setting prohibited

Bits 7 to 6

CIS001	CIS000	Selection of TI00 pin input valid edge
0	0	Falling edge
0	1	Rising edge
1		Both edges (when low-level width is measured)
ı	U	Start trigger: Falling edge, Capture trigger: Rising edge
1	1	Both edges (when high-level width is measured)
'	'	Start trigger: Rising edge, Capture trigger: Falling edge

Caution: For details on the register setup procedures, refer to RL78/G13 User's Manual: Hardware.



Symbol: TMR00

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
CKS	CKS	0	CCS	MAS	STS	STS	STS	CIS0	CIS0	0	0	MD0	MD0	MD0	MD0
001	000		00	TER	002	001	000	01	00			03	02	01	00
				00											
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0

Bits 3 to 0

MD 003	MD 002			mode of	Related function	TCR counting operation			
0	0	0	1/0	Interval timer mode	Interval timer / Square wave output / Divider function / PWM output (master)	Counting down			
0	1	0	1/0	Capture mode	Input pulse interval measurement	Counting up			
0	1	1	0	Event counter mode	External event counter	Counting down			
1	0	0	1/0	One-count mode	Delay counter / One-shot pulse output / PWM output (slave)	Counting down			
1	1	0	0	Capture & one-count mode	Measurement of high-/low-level width of input signal	Counting up			
Oth	er tha	an ab	ove	Setting prohibited					

The MD000 bit operation varies depending on the operation mode (see the table below)

Operation mode (selected with MD003 to MD001) (See the table above)	MD000	TCR counting operation
<ul> <li>Interval timer mode (0, 0, 0)</li> <li>Capture mode (0, 1, 0)</li> </ul>	0	Timer interrupt is not generated when counting is started (timer output does not change, either).
	1	Timer interrupt is generated when counting is started (timer output also changes).
• Event counter mode (0, 1, 1)	0	Timer interrupt is not generated when counting is started (timer output does not change, either).
• One-count mode (1, 0, 0)	0	Start trigger is invalid during counting operation. At that time, interrupt is not generated, either.
	1	Start trigger is valid during counting operation. At that time, interrupt is also generated.
Capture/one-count mode (1, 1, 0)	0	Timer interrupt is not generated when counting is started (timer output does not change, either). Start trigger is invalid during counting operation. At that time, interrupt is not generated, either.
Other than above	•	Setting prohibited

Caution: For details on the register setup procedures, refer to RL78/G13 User's Manual: Hardware.



Configuring the interval timer cycle time

• Timer data register 00 (TDR00) Configure the interval timer compare value.

Symbol: TDR00

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0

Timer interrupt (INTTM00) occurrence =  $(TDR00 \text{ setting} + 1) \times Count \text{ clock cycle time}$ 

### Enabling the timer output

• Timer output enable register 0 (TOE0) Enable/disable the timer output for each channel.

Symbol: TOE0

_	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
ĺ	0	0	0	0	0	0	0	0	TOE							
	U	O	U	U	0	O	U		07	06	05	04	03	02	01	00
	0	0	0	0	0	0	0	0	Х	Х	Х	Х	Х	Х	Х	0

Bit 0

TOE00	Timer output enable/disable of channel 0						
0	The TO00 operation stopped by count operation (timer channel output bit). Writing to the TO00 bit is enabled.  The TO00 pin function as data output, and it outputs the level set to the TO00 bit.						
	The output level of the TO00 pin can be manipulated be software.						
1	The TO00 operation enabled by count operation (timer channel output bit).  Writing to the TO00 bit is disabled (writing is ignored).  The TO00 pin functions as timer output, and the TOE00 bit is set or reset depending on the timer operation.  The TO00 pin outputs the square-wave or PWM depending on the timer operation.						

Caution: For details on the register setup procedures, refer to RL78/G13 User's Manual: Hardware.

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## 5.7.6 INTPO Initialization

Figure 5.7 shows the flowchart for INTP0 initialization.

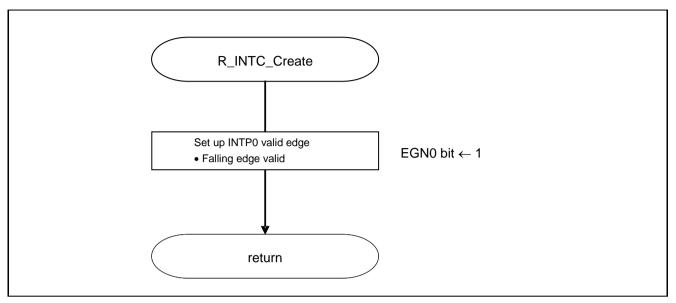


Figure 5.7 INTC Module Setup

Setup for INTP0 pin edge detection

- External interrupt rising edge enable register (EGP0)
- External interrupt falling edge enable register (EGN0) Select a valid edge for INTP0

Symbol: EGP0

7	6	5	4	3	2	1	0
EGP7	EGP6	EGP5	EGP4	EGP3	EGP2	EGP1	EGP0
Х	х	х	х	х	Х	Х	0

Symbol: EGN0

7	6	5	4	3	2	1	0
EGN7	EGN6	EGN5	EGN4	EGN3	EGN2	EGN1	EGN0
Х	Х	Х	Х	Х	Х	Х	1

EGP0	EGN0	INTP0 pin valid edge selection				
0	0	Edge detection disabled.				
0	1	alling edge				
1	0	Rising edge				
1	1	Both rising and falling edges				

Caution: For details on the register setup procedures, refer to RL78/G13 User's Manual: Hardware.

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## 5.7.7 Main Processing

Figure 5.8 shows the flowchart for main processing.

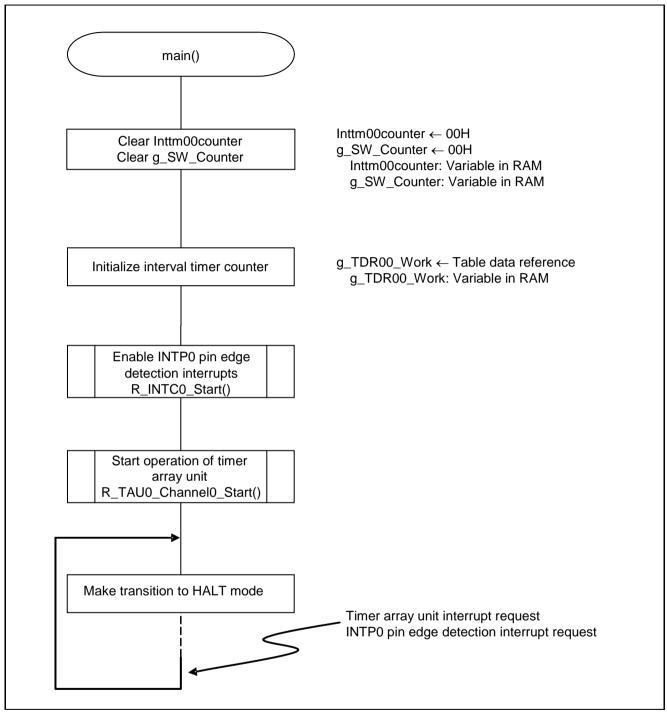


Figure 5.8 Main Processing

#### 5.7.8 **INTP0 Operation Start**

Figure 5.9 shows the flowchart for starting INTPO operation.

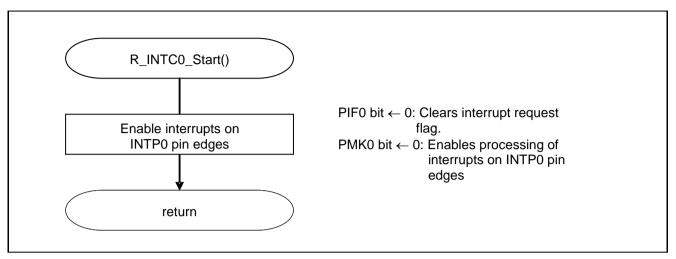


Figure 5.9 **INTP0 Operation Start** 

Setup for INTP0 Interrupts

- Interrupt request flag register (IF0L) Clear interrupt request flag.
- Interrupt mask flag register (MK0L) Clear interrupt mask.

Symbol: IF0L

7	6	5	4	3	2	1	0
PIF5	PIF4	PIF3	PIF2	PIF1	PIF0	LVIIF	WDTIIF
Х	х	Х	Х	Х	0	Х	Х

Bit 2

PIF0	Interrupt request flag
0	No interrupt request signal is generated
1	Interrupt request is generated, interrupt request status

Symbol: MK0L

7	6	5	4	3	2	1	0
PMK5	PMK4	PMK3	PMK2	PMK1	PMK0	LVIMK	WDTIMK
Х	Х	Х	Х	Х	0	Х	Х

Bit 2

PMK0	Interrupt processing control
0	Enables interrupt processing.
1	Disables interrupt processing.

Caution: For detailed information about setting the registers, see RL78/G13 User's Manual: Hardware.

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# 5.7.9 Timer Array Unit 0 Operation Start

Figure 5.10 shows the flowchart for starting timer array unit operation.

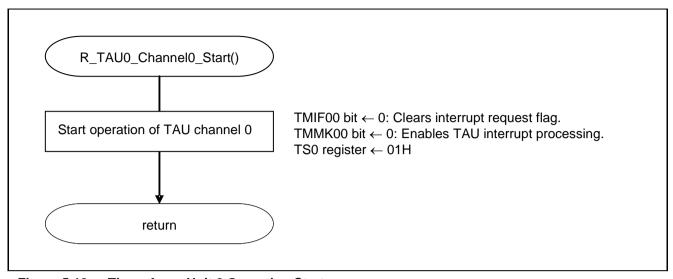


Figure 5.10 Timer Array Unit 0 Operation Start

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## Configuring the timer interrupt

- Interrupt request flag register (IF1L) Clear the interrupt request flag.
- Interrupt mask flag register (MK1L) Enable interrupt processing.

## Symbol: IF1L

7	6	5	4	3	2	1	0
TMIF03	TMIF02	TMIF01	TMIF00	IICAIF0	SREIF1	SRIF1	STIF1
					TMIF03H	CSIIF11	CSIIF10
						IICIF11	IICIF10
Х	Х	Х	0	Х	Х	Х	Х

### Bit 4

TMIF00	Interrupt request flag
0	No interrupt request signal is generated.
1	Interrupt request is generated, interrupt
1	request status

## Symbol: MK1L

_	7	6	5	4	3	2	1	0
	TMMK03	TMMK02	TMMK01	TMMK00	IICAMK0	SREMK1	SRMK1	STMK1
						TMMK03H	CSIMK11	CSIMK10
							IICMK11	IICMK10
	Х	Х	Х	0	Х	Х	Х	Х

Bit 4

TMMK00	Interrupt processing control
0	Enables interrupt processing.
1	Disables interrupt processing.

Caution: For details on the register setup procedures, refer to RL78/G13 User's Manual: Hardware.

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# 5.7.10 INTTM00 Interrupt Processing

Figure 5.11 shows the flowchart for INTTM00 interrupt processing.

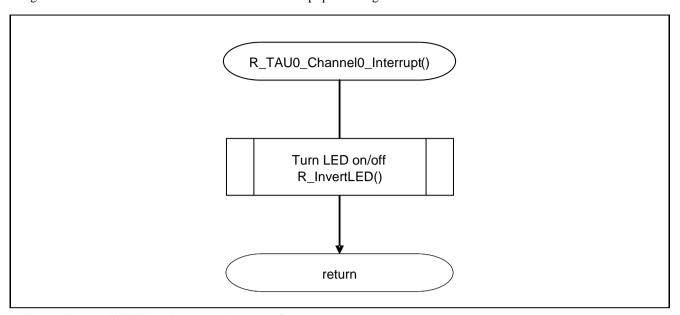


Figure 5.11 INTTM00 Interrupt Processing

# 5.7.11 LED Turn-On/Off Processing

Figure 5.12 shows the flowchart for LED turn-on/off processing.

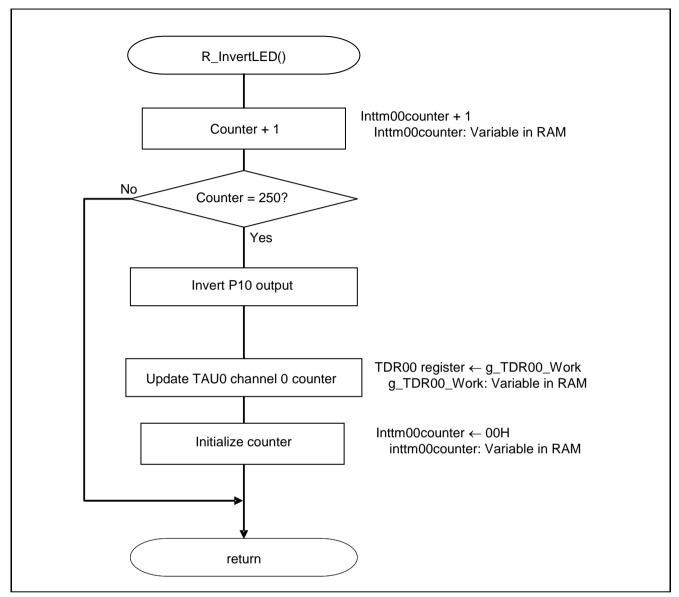


Figure 5.12 Checking Whether 500 ms Have Elapsed

## 5.7.12 INTP0 Interrupt Processing

Figures 5.13 and 5.14 show the flowchart for INTP0 interrupt processing.

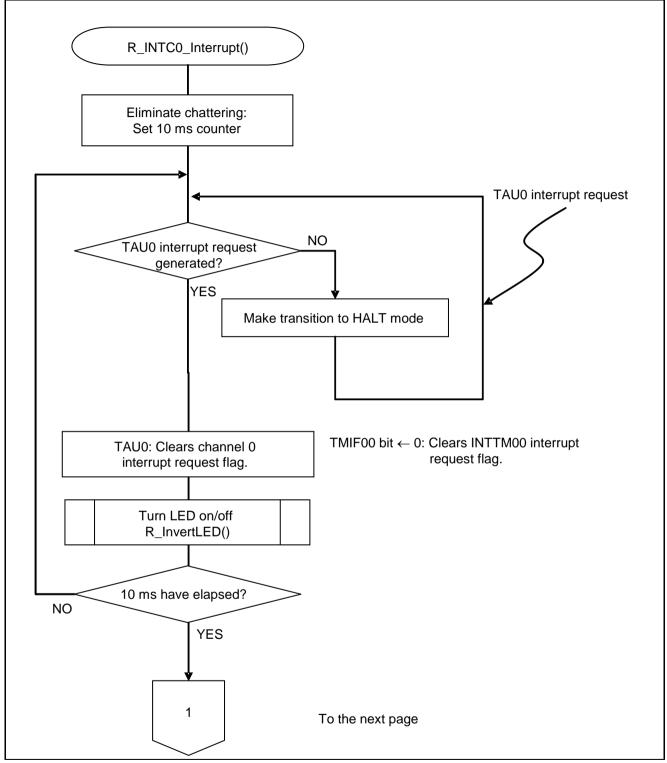


Figure 5.13 INTP0 Interrupt Processing (1/2)

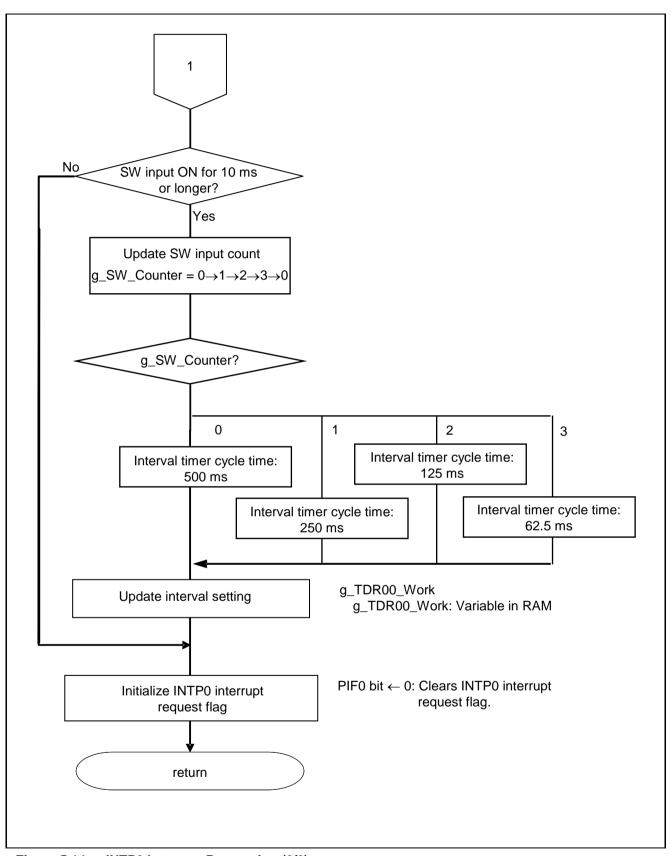


Figure 5.14 INTP0 Interrupt Processing (2/2)

## 6. Sample Code

The sample code is available on the Renesas Electronics Website.

#### 7. Documents for Reference

User's Manual:

RL78/G13 User's Manual: Hardware (R01UH0146EJ) RL78 Family User's Manual: Software (R01US0015EJ)

The latest version can be downloaded from the Renesas Electronics website.

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REVISION HISTORY	RL78/G13 Timer Array Unit (Interval Timer)
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Rev.	Date	Description		
Rev.	Date	Page	Summary	
1.00	Sep. 30, 2011	_	First edition issued	
2.00	Dec. 27, 2013	5 Table 2.1: Added e2studio and IAR information		
		11	Added note	
			Figure 5.2: Fixed typo in function name	
		12	Figure 5.3: Fixed typo in function name	

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## **General Precautions in the Handling of MPU/MCU Products**

The following usage notes are applicable to all MPU/MCU products from Renesas. For detailed usage notes on the products covered by this manual, refer to the relevant sections of the document as well as any technical updates that have been issued for the products.

#### 1. Handling of Unused Pins

Handle unused pins in accord with the directions given under Handling of Unused Pins in the manual.

The input pins of CMOS products are generally in the high-impedance state. In operation with unused pin in the open-circuit state, extra electromagnetic noise is induced in the vicinity of LSI, an associated shoot-through current flows internally, and malfunctions occur due to the false recognition of the pin state as an input signal become possible. Unused pins should be handled as described under Handling of Unused Pins in the manual.

#### 2. Processing at Power-on

The state of the product is undefined at the moment when power is supplied.

- The states of internal circuits in the LSI are indeterminate and the states of register settings and pins are undefined at the moment when power is supplied.
  In a finished product where the reset signal is applied to the external reset pin, the states of pins are not guaranteed from the moment when power is supplied until the reset process is completed.
  In a similar way, the states of pins in a product that is reset by an on-chip power-on reset function are not guaranteed from the moment when power is supplied until the power reaches the level at which resetting has been specified.
- 3. Prohibition of Access to Reserved Addresses

Access to reserved addresses is prohibited.

— The reserved addresses are provided for the possible future expansion of functions. Do not access these addresses; the correct operation of LSI is not guaranteed if they are accessed.

### 4. Clock Signals

After applying a reset, only release the reset line after the operating clock signal has become stable. When switching the clock signal during program execution, wait until the target clock signal has stabilized.

- When the clock signal is generated with an external resonator (or from an external oscillator) during a reset, ensure that the reset line is only released after full stabilization of the clock signal. Moreover, when switching to a clock signal produced with an external resonator (or by an external oscillator) while program execution is in progress, wait until the target clock signal is stable.
- 5. Differences between Products

Before changing from one product to another, i.e. to one with a different part number, confirm that the change will not lead to problems.

The characteristics of MPU/MCU in the same group but having different a different part number may differ in terms of the internal memory capacity and layout pattern, and other factors, which can affect the ranges of electrical characteristics, such as characteristic values, operating margins, immunity to noise, and amount of radiated noise. When changing to products with a different part number, implement a system-evaluation test for the given product.

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