

RL78/G13

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Timer Array Unit (Interval Timer) CC-RL

Introduction

This application note describes the interval timer function of the timer array unit (TAU). This unit inverts the LED indication each time a timer interrupt occurs. Also, it changes the timer interrupt cycle time based on the number of times the switch is pressed.

Target Device

RL78/G13

When applying the sample program covered in this application note to another microcomputer, modify the program according to the specifications for the target microcomputer and conduct an extensive evaluation of the modified program.

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1. Specifications

This application note shows example settings for using timer interrupts (INTTM00) from the interval timer and interrupts (INTP0) generated on pin input edge detection. The TAU inverts the LED indication each time a timer interrupt (INTTM00) occurs. Also, this unit changes the timer interrupt (INTTM00) cycle time based on the number of times the switch (SW) is pressed.

Table 1.1 lists the peripheral functions to be used and their uses. Figure 1.1 shows the timer and its interrupt operation.

Table 1.1 Peripheral Functions to be Used and Their Uses

| Peripheral Function | Use |
|------------------------------|--|
| Timer array unit (channel 0) | Time interval control for inversion of the P10 pin output (LED indication) |
| P10 | Output port for LED indications |
| P137/INTP0 | Switch input for changing the timer interrupt (INTTM00) cycle time |

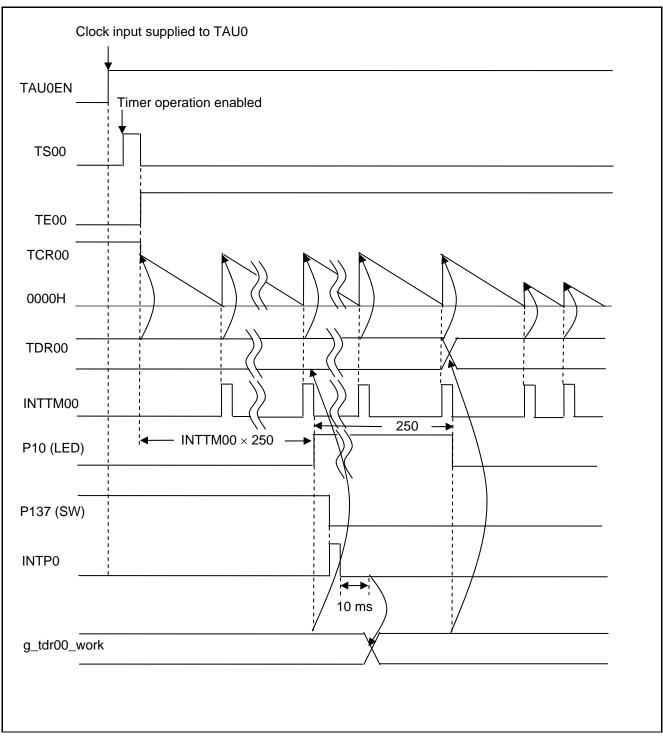


Figure 1.1 Overview of Timer Operation and Interrupts

2. Operation Check Conditions

The sample code contained in this application note has been checked under the conditions listed in the table below.

Table 2.1 Operation Check Conditions

| ltem | Description |
|--|---|
| Microcontroller used | RL78/G13 (R5F100LEA) |
| Operating frequency | High-speed on-chip oscillator (HOCO) clock: 32 MHz |
| | CPU/peripheral hardware clock: 32 MHz |
| Operating voltage | 5.0V (can run on a voltage range of 2.9 V to 5.5 V.) |
| | LVD operation (V _{LVD}): Reset mode 2.81 V (2.76 V to 2.87 V) |
| Integrated development environment (CS+) | CS+ for CC V3.01.00 from Renesas Electronics Corp. |
| C compiler (CS+) | CC-RL V1.01.00 from Renesas Electronics Corp. |
| Integrated development environment (e ² studio) | e ² studio V4.0.0.26 from Renesas Electronics Corp. |
| C compiler (e ² studio) | CC-RL V1.01.00 from Renesas Electronics Corp. |

3. Related Application Note

The application note that is related to this application note is listed below for reference.

• RL78/G13 Initialization (R01AN2575EJ0100) Application Note

4. Description of the Hardware

4.1 Hardware Configuration Example

Figure 4.1 shows an example of hardware configuration that is used for this application note.

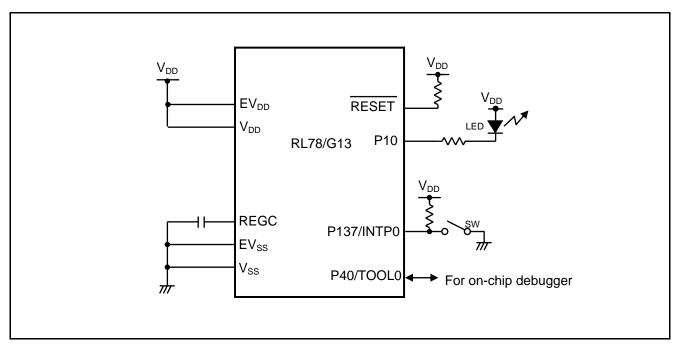


Figure 4.1 Hardware Configuration

Cautions: 1. The purpose of this circuit is only to provide the connection outline and the circuit is simplified accordingly. When designing and implementing an actual circuit, provide proper pin treatment and make sure that the hardware's electrical specifications are met (connect the input-only ports separately to V_{DD} or V_{SS} via a resistor).

- 2. Connect any pins whose name begins with EV_{SS} to V_{SS} and any pins whose name begins with EV_{DD} to V_{DD} , respectively.
- 3. V_{DD} must be held at not lower than the reset release voltage (V_{LVD}) that is specified as LVD.

4.2 List of Pins to be Used

Table 4.1 lists the pins to be used and their functions.

Table 4.1 Pins to be Used and Their Functions

| Pin Name | I/O | Description |
|------------|--------|--|
| P10 | Output | Output port for LED indications |
| P137/INTP0 | Input | Switch (SW) input pin (external interrupt request input pin) |

5. Description of the Software

5.1 Operation Outline

This application note describes how to set up the interval timer function of TAU0.

This setup is followed by operation for counting the number of timer interrupts (INTTM00) generated by the interval timer. Each time the count reaches 250, the LED indication is inverted. The timer interrupt (INTTM00) cycle time is changed according to the number of times the switch is pressed. The LED on/off cycle time is changed as follows.

 $500 \text{ ms} \rightarrow 250 \text{ ms} \rightarrow 125 \text{ ms} \rightarrow 62.5 \text{ ms} \rightarrow 500 \text{ ms} \rightarrow \dots$

- (1) Initialize the TAU.
- Use the interval timer mode as the timer operation mode.
- Initialize timer data register 00 (TDR00) to 2 ms.
- Set the timer output enable register to disable operation.
- Use timer interrupts (INTTM00) from timer channel 0.
- (2) Initialize the external edge detection interrupt.
- Select a falling edge as the valid edge for INTP0.
- Use INTP0 interrupts.
- (3) Execute a HALT instruction to wait for timer interrupts (INTTM00).
- (4) After the HALT mode is cancelled by a timer interrupt (INTTM00), the number of INTTM00 interrupts generated is counted.
- (5) When the timer interrupt count reaches 250, the LED indication is inverted. The value (g_tdr00_work) in RAM for the timer data register is set in the timer data register (TDR00).
- (6) INTP0 interrupt processing changes the switch input count (INTP0 interrupt count) and g_tdr00_work value.

5.2 List of Option Byte Settings

Table 5.1 summarizes the settings of the option bytes.

Table 5.1 Option Byte Settings

| Address | Value | Description |
|---------------|-----------|--|
| 000C0H/010C0H | 01101110B | Disables the watchdog timer. |
| | | (Stops counting after the release from the reset state.) |
| 000C1H/010C1H | 01111111B | LVD reset mode, 2.81 V (2.76 V to 2.87 V) |
| 000C2H/010C2H | 11101000B | HS mode, HOCO: 32 MHz |
| 000C3H/010C3H | 10000100B | Enables the on-chip debugger. |

5.3 List of Constants

Table 5.2 lists the constants that are used in this sample program.

Table 5.2 Constants for the Sample Program

| Constant | Setting | Description |
|----------------------------|-----------|--|
| _01_INTP0_EDGE_FALLING_SEL | 01h | Selects a falling edge as the valid edge of INTP0. |
| g_tdr00_data[] | (64000-1) | TDR00 settings by number of times the switch is |
| | (32000-1) | pressed |
| | (16000-1) | |
| | (8000-1)} | |
| g_10ms_count[] | (5+1) | 10 ms timer count values by number of times the |
| | (10+1) | switch is pressed |
| | (20+1) | |
| | (40+1) | |

5.4 List of Variables

Table 5.3 lists the global variable that is used by this sample program.

Table 5.3 Global Variables for the Sample Program

| Туре | Variable Name | Contents | Function Used |
|----------------|------------------|--|---|
| saddr uint8_t | g_sw_counter | Switch press count | R_INTC0_Interrupt() main() r_invert_led() |
| saddr uint16_t | g_tdr00_work | Value which is set in TDR00 each time the timer interrupt count reaches 250. | R_INTC0_Interrupt() main() r_invert_led() |
| saddr uint8_t | g_inttm00counter | The number of timer interrupt generation | main() r_invert_led() |

5.5 List of Functions

Table 5.4 lists the functions that are used by this sample program.

Table 5.4 Functions

| Function Name | Outline |
|-----------------------------|--|
| R_TAU0_Channel0_Start | Starts operation of TAU0 channel 0. |
| R_TAU0_Channel0_Interrupt() | Processes timer interrupts on TAU0 channel 0. |
| r_invert_led() | Counts the number of INTTM00 interrupts generated. Inverts the LED indication each time the interrupt count reaches 250. |
| R_INTC0_Start | Enables INTP0 interrupts. |
| R_INTC0_Interrupt | Processes INTP0 interrupts. |

5.6 Function Specifications

This section describes the specifications for the functions that are used in the sample code.

| [Function Name] R | [Function Name] R_TAU0_Channel0_Start | | | | |
|-------------------|---|--|--|--|--|
| Synopsis | TAU0 channel 0 operation start | | | | |
| Header | #include "r_cg_macrodriver.h" | | | | |
| | #include "r_cg_timer.h" | | | | |
| | #include "r_cg_userdefine.h" | | | | |
| Declaration | void R_TAU0_Channel0_Start(void) | | | | |
| Explanation | This function unmasks TAU0 channel 0 interrupts and starts count operation. | | | | |
| Arguments | None | | | | |
| Return value | None | | | | |
| Remarks | None | | | | |

| [Function Name] r_tau0_channel0_interrupt() | | | | |
|---|--|--|--|--|
| Synopsis | TAU0 channel 0 timer interrupt processing | | | |
| Header | r_cg_macrodriver.h | | | |
| | r_cg_timer.h | | | |
| | r_cg_userdefine.h | | | |
| Declaration | static voidnear r_tau0_channel0_interrupt(void) | | | |
| Explanation | This function calls the function which will invert the LED indication. | | | |
| Arguments | None | | | |
| Return value | None | | | |
| Remarks | None | | | |

[Function Name] r_invert_led()

Synopsis LED indication inversion processing

Header r_cg_macrodriver.h

r_cg_cgc.h r_cg_port.h r_cg_intc.h r_cg_timer.h r_cg_userdefine.h

Declaration void r_invert_led(void)

Explanation This function counts 250 timer interrupts (INTTM00) and then inverts the LED

indication (for port latch inversion). It also changes the TDR00 setting to the value

specified with g_tdr00_work.

Arguments None
Return value None
Remarks None

[Function Name] R_INTC0_Start

Synopsis INTP0 interrupt enable

Header r_cg_intc.h

Declaration void R_INTC0_Start(void)

Explanation This function clears the interrupt request flag. It enables INTP0 interrupts and starts

taking in the switch input.

Arguments None Return value None Remarks None

[Function Name] r_intc0_interrupt()

Synopsis INTP0 interrupt processing

Header r_cg_macrodriver.h

r_cg_intc.h r_cg_userdefine.h

Declaration static void __near r_intc0_interrupt(void)

Explanation This function processes INTP0 interrupts as they occur.

It waits 10 ms and then scans P13.7 (SW input pin). When the switch is pressed, this

function changes the g_tdr00_work value.

Arguments None Return value None Remarks None

5.7 Flowcharts

Figure 5.1 shows the overall flow of the sample program described in this application note.

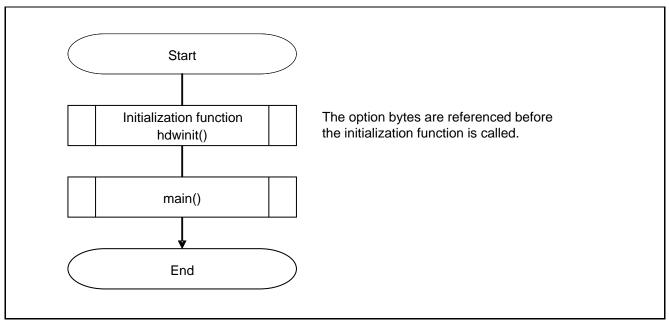


Figure 5.1 Overall Flow

Note: Startup routine is executed before and after the initialization function.

5.7.1 Initialization Function

Figure 5.2 shows the flowchart for the initialization function.

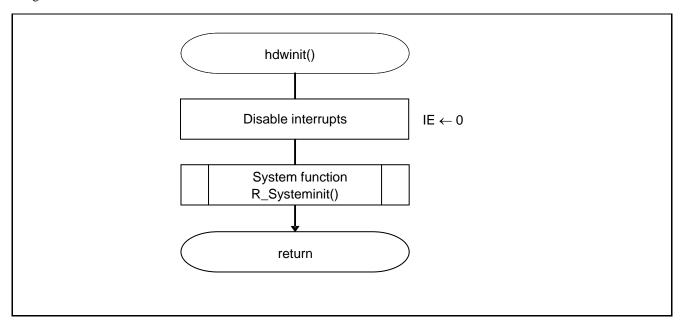


Figure 5.2 Initialization Function

5.7.2 System Function

Table 5.3 shows the flowchart for the system function.

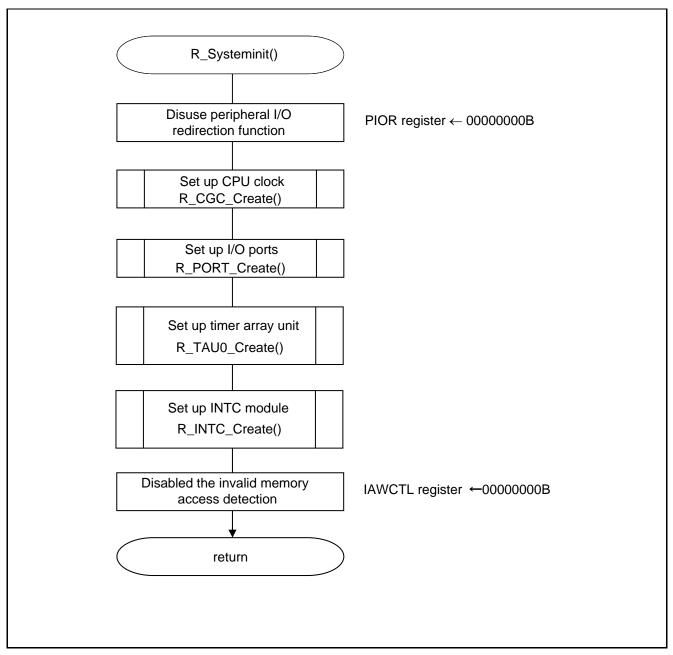


Figure 5.3 System Function

5.7.3 I/O Port Setup

Table 5.4 shows the flowchart for I/O port setup.

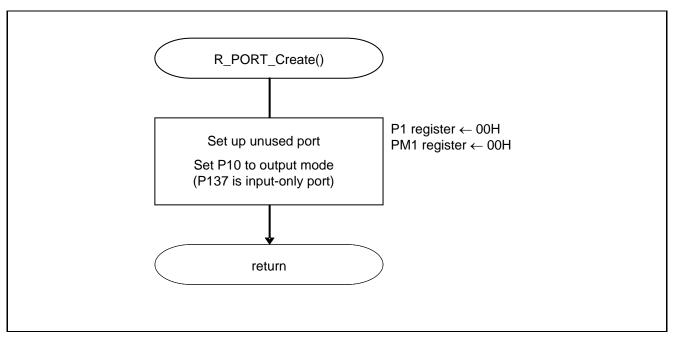


Figure 5.4 I/O Port Setup

Note: Refer to the section entitled "Flowcharts" in RL78/G13 Initialization Application Note (R01AN2575EJ0100) for the configuration of the unused ports.

Caution: Provide proper treatment for unused pins so that their electrical specifications are observed. Connect each of any unused input-only ports to VDD or VSS via a separate resistor.

Setting up the LED port

• Port mode register 1 (PM1) Select I/O mode for the port.

Symbol: PM1

| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|------|------|------|------|------|------|------|------|
| PM17 | PM16 | PM15 | PM14 | PM13 | PM12 | PM11 | PM10 |
| 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bit 0

| PM10 | P10 pin I/O mode selection |
|------|--------------------------------|
| 0 | Output mode (output buffer on) |
| 1 | Input mode (output buffer off) |

5.7.4 CPU Clock Setup

Figure 5.5 shows the flowchart for setting up the CPU clock.

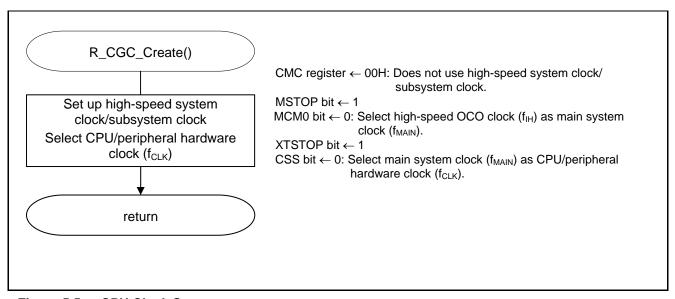


Figure 5.5 CPU Clock Setup

Caution: For details on the procedure for setting up the CPU clock (R_CGC_Create ()), refer to the section entitled "Flowcharts" in RL78/G13 Initialization Application Note (R01AN2575EJ0100).

5.7.5 Timer Array Unit Setup

Figure 5.6 shows the flowchart for setting up the timer array unit.

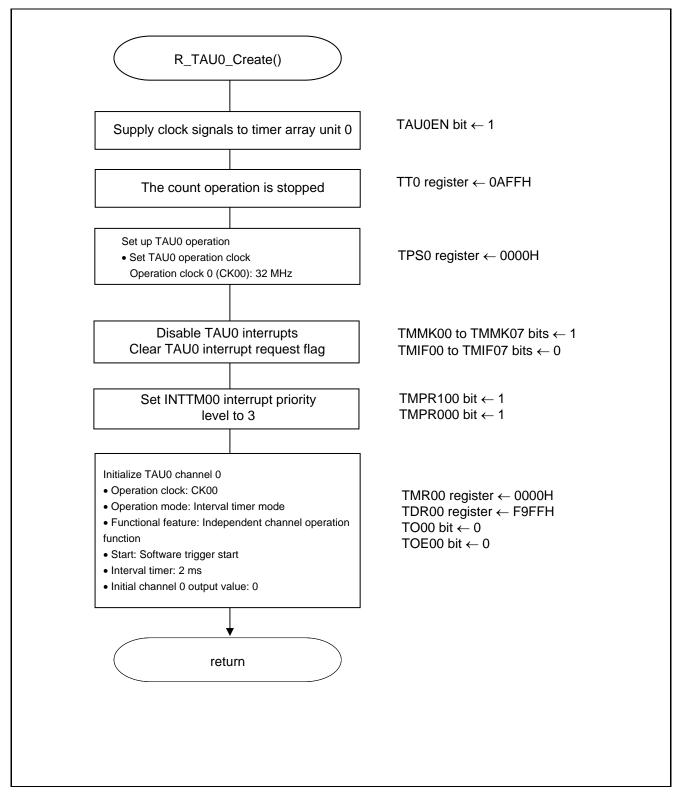


Figure 5.6 Timer Array Unit Setup

Starting clock signal supply to the timer array unit $\boldsymbol{0}$

• Peripheral enable register 0 (PER0) Start supplying clock signals to the timer array unit 0.

Symbol: PER0

| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------|---------|-------|---------|--------|--------|--------|--------|
| RTCEN | IICA1EN | ADCEN | IICA0EN | SAU1EN | SAU0EN | TAU1EN | TAU0EN |
| Х | Х | Х | Х | Х | Х | Х | 1 |

Bit 0

| TAU0EN | Control of timer array unit 0 input clock supply |
|--------|--|
| 0 | Stops input clock supply. |
| 1 | Enables input clock supply. |

Configuring the timer clock frequency

• Timer clock select register 0 (TPS0) Select an operation clock for timer array unit 0.

Symbol: TPS0

| | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|---|----|----|------------|------------|----|----|------------|------------|---|---|------------|---|---|---|------------|------------|
| | 0 | 0 | PRS 031 | PRS 030 | 0 | 0 | PRS 021 | PRS 020 | | | PRS 011 | | | | PRS 001 | PRS 000 |
| Ì | Χ | Х | Х | Х | Х | Х | Х | Х | Х | Х | Х | Х | 0 | 0 | 0 | 0 |

Bits 3 to 0

| PR | PR | PR | PR | | Opera | ation clock | (CK00) se | election | |
|----------|----------|----------|----------|-----------------------------------|-----------------------------|-----------------------------|------------------------------|------------------------------|------------------------------|
| S00 3 | S00 2 | S00 1 | S00 0 | | f _{CLK} = 2 MHz | f _{CLK} = 5 MHz | f _{CLK} = 10 MHz | f _{CLK} = 20 MHz | f _{CLK} = 32 MHz |
| 0 | 0 | 0 | 0 | f _{CLK} | 2 MHz | 5 MHz | 10 MHz | 20 MHz | 32 MHz |
| 0 | 0 | 0 | 1 | f _{CLK} /2 | 1 MHz | 2.5 MHz | 5 MHz | 10 MHz | 16 MHz |
| 0 | 0 | 1 | 0 | f _{CLK} /2 ² | 500 kHz | 1.25 MHz | 2.5 MHz | 5 MHz | 8 MHz |
| 0 | 0 | 1 | 1 | f _{CLK} /2 ³ | 250 kHz | 625 kHz | 1.25 MHz | 2.5 MHz | 4 MHz |
| 0 | 1 | 0 | 0 | f _{CLK} /2 ⁴ | 125 kHz | 312.5 kHz | 625 kHz | 1.25 MHz | 2 MHz |
| 0 | 1 | 0 | 1 | f _{CLK} /2 ⁵ | 62.5 kHz | 156.2 kHz | 312.5 kHz | 625 kHz | 1 MHz |
| 0 | 1 | 1 | 0 | f _{CLK} /2 ⁶ | 31.25 kHz | 78.1 kHz | 156.2 kHz | 312.5 kHz | 500 kHz |
| 0 | 1 | 1 | 1 | f _{CLK} /2 ⁷ | 15.62 kHz | 39.1 kHz | 78.1 kHz | 156.2 kHz | 250 kHz |
| 1 | 0 | 0 | 0 | f _{CLK} /2 ⁸ | 7.81 kHz | 19.5 kHz | 39.1 kHz | 78.1 kHz | 125 kHz |
| 1 | 0 | 0 | 1 | f _{CLK} /2 ⁹ | 3.91 kHz | 9.76 kHz | 19.5 kHz | 39.1 kHz | 62.5 kHz |
| 1 | 0 | 1 | 0 | f _{CLK} /2 ¹⁰ | 1.95 kHz | 4.88 kHz | 9.76 kHz | 19.5 kHz | 31.25 kHz |
| 1 | 0 | 1 | 1 | f _{CLK} /2 ¹¹ | 976 Hz | 2.44 kHz | 4.88 kHz | 9.76 kHz | 15.63 kHz |
| 1 | 1 | 0 | 0 | f _{CLK} /2 ¹² | 488 Hz | 1.22 kHz | 2.44 kHz | 4.88 kHz | 7.81 kHz |
| 1 | 1 | 0 | 1 | f _{CLK} /2 ¹³ | 244 Hz | 610 Hz | 1.22 kHz | 2.44 kHz | 3.91 kHz |
| 1 | 1 | 1 | 0 | f _{CLK} /2 ¹⁴ | 122 Hz | 305 Hz | 610 Hz | 1.22 kHz | 1.95 kHz |
| 1 | 1 | 1 | 1 | f _{CLK} /2 ¹⁵ | 61 Hz | 153 Hz | 305 Hz | 610 Hz | 976 Hz |

Setting up channel 0 operation mode

Timer mode register 00 (TMR00)
 Select an operation clock (f_{MCK}).
 Select a count clock.
 Select the software trigger start.
 Set up the operation mode.

Symbol: TMR00

| 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-----|-----|----|-----|----|-----|-----|-----|------|------|---|---|-----|-----|-----|-----|
| CKS | CKS | 0 | CCS | 0 | STS | STS | STS | CIS0 | CIS0 | 0 | 0 | MD0 | MD0 | MD0 | MD0 |
| 001 | 000 | | 00 | | 002 | 001 | 000 | 01 | 00 | | | 03 | 02 | 01 | 00 |
| 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bits 15 and 14

| CKS001 | CKS00 0 | Channel 0 operation clock (f _{MCK}) selection |
|--------|------------|--|
| 0 | 0 | Operation clock CK00 set by timer clock select register 0 (TPS0) |
| 0 | 1 | Operation clock CK02 set by timer clock select register 0 (TPS0) |
| 1 | 0 | Operation clock CK01 set by timer clock select register 0 (TPS0) |
| 1 | 1 | Operation clock CK03 set by timer clock select register 0 (TPS0) |

Bit 12

| CCS00 | Channel 0 count clock (f _{TCLK}) selection |
|-------|---|
| 0 | Operation clock (f _{MCK}) specified by the CKS000 and CKS001 bits |
| 1 | Valid edge of input signal input from the TI00 pin |

Bit 11

| MASTER00 | Selection between using channel 0 independently or simultaneously with another channel (as a slave or master) |
|----------|--|
| | Operates in independent channel operation function or as slave channel in simultaneous channel operation function. |
| 1 | Operates as master channel in simultaneous channel operation function. |

Symbol: TMR00

| 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-----|-----|----|-----|----|-----|-----|-----|------|------|---|---|-----|-----|-----|-----|
| CKS | CKS | 0 | CCS | 0 | STS | STS | STS | CIS0 | CIS0 | 0 | 0 | MD0 | MD0 | MD0 | MD0 |
| 001 | 000 | | 00 | | 002 | 001 | 000 | 01 | 00 | | | 03 | 02 | 01 | 00 |
| 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bits 10 to 8

| STS002 | STS001 | STS000 | Setting of start trigger or capture trigger of channel 0 |
|--------|-------------|--------|--|
| 0 | 0 | 0 | Only software trigger start is valid (other trigger sources are unselected). |
| 0 | 0 | 1 | Valid edge of the Tl00 pin input is used as both the start trigger and capture trigger. |
| 0 | 1 | () | Both the edges of the TI00 pin input are used as a start trigger and a capture trigger. |
| 1 | 0 | 0 | Interrupt signal of the master channel is used (when the channel is used as a slave channel with the simultaneous channel operation function). |
| Othe | er than abo | ove | Setting prohibited |

Bits 7 to 6

| CIS001 | CIS000 | Selection of TI00 pin input valid edge | | | | | | |
|--|---|---|--|--|--|--|--|--|
| 0 | 0 | Falling edge | | | | | | |
| 0 | 0 1 Rising edge | | | | | | | |
| 1 | 0 | Both edges (when low-level width is measured) | | | | | | |
| I | U | Start trigger: Falling edge, Capture trigger: Rising edge | | | | | | |
| Both edges (when high-level width is measured) | | | | | | | | |
| I | Start trigger: Rising edge, Capture trigger: Falling edge | | | | | | | |

Symbol: TMR00

| 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-----|-----|----|-----|----|-----|-----|-----|------|------|---|---|-----|-----|-----|-----|
| CKS | CKS | 0 | CCS | 0 | STS | STS | STS | CIS0 | CIS0 | 0 | 0 | MD0 | MD0 | MD0 | MD0 |
| 001 | 000 | | 00 | | 002 | 001 | 000 | 01 | 00 | | | 03 | 02 | 01 | 00 |
| 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bits 3 to 0

| MD 003 | MD 002 | | MD 000 | Operation mode of channel 0 | Related function | TCR counting operation | | | |
|-----------|-----------|-------|-----------|-----------------------------------|--|------------------------|--|--|--|
| 0 | 0 | 0 | 1/0 | Interval timer | Interval timer / Square wave output / Divider function / PWM output (master) | Counting down | | | |
| 0 | 1 | 0 | 1/0 | Capture mode | Input pulse interval measurement | Counting up | | | |
| 0 | 1 | 1 | 0 | Event counter mode | External event counter | Counting down | | | |
| 1 | 0 | 0 | 1/0 | One-count mode | Delay counter / One-shot pulse output / PWM output (slave) | Counting down | | | |
| 1 | 1 | 0 | 0 | ' | Measurement of high-/low-level width of input signal | Counting up | | | |
| Oth | er tha | an ab | ove | Setting prohibited | | | | | |

The MD000 bit operation varies depending on the operation mode (see the table below)

| Operation mode (selected with MD003 to MD001) (See the table above) | MD000 | TCR counting operation |
|--|-------|---|
| Interval timer mode (0, 0, 0)Capture mode (0, 1, 0) | 0 | Timer interrupt is not generated when counting is started (timer output does not change, either). |
| | 1 | Timer interrupt is generated when counting is started (timer output also changes). |
| • Event counter mode (0, 1, 1) | 0 | Timer interrupt is not generated when counting is started (timer output does not change, either). |
| • One-count mode (1, 0, 0) | 0 | Start trigger is invalid during counting operation. At that time, interrupt is not generated, either. |
| | 1 | Start trigger is valid during counting operation. At that time, interrupt is also generated. |
| • Capture/one-count mode (1, 1, 0) | 0 | Timer interrupt is not generated when counting is started (timer output does not change, either). Start trigger is invalid during counting operation. At that time, interrupt is not generated, either. |
| Other than above | • | Setting prohibited |

Configuring the interval timer cycle time

• Timer data register 00 (TDR00) Configure the interval timer compare value.

Symbol: TDR00

| 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|----|----|----|----|----|----|---|---|---|---|---|---|---|---|---|---|
| | | | | | | | | | | | | | | | |

Timer interrupt (INTTM00) occurrence = $(TDR00 \text{ setting} + 1) \times Count \operatorname{clock}$ cycle time

Enabling the timer output

• Timer output enable register 0 (TOE0) Enable/disable the timer output for each channel.

Symbol: TOE0

| _ | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|---|----|----|----|----|----|----|---|---|-----|----|----|----|----|----|----|----|
| Ī | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | TOE | | | | | | | |
| L | ŭ | Ŭ | Ů | Ů | Ů | Ů | Ŭ | Ŭ | 07 | 06 | 05 | 04 | 03 | 02 | 01 | 00 |
| | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | Х | Х | Х | Х | Х | Х | Х | 0 |

Bit 0

| TOE00 | Timer output enable/disable of channel 0 |
|-------|--|
| 0 | The TO00 operation stopped by count operation (timer channel output bit). Writing to the TO00 bit is enabled. The TO00 pin function as data output, and it outputs the level set to the TO00 bit. |
| | The output level of the TO00 pin can be manipulated be software. |
| | The TO00 operation enabled by count operation (timer channel output bit). Writing to the TO00 bit is disabled (writing is ignored). |
| 1 | The TO00 pin functions as timer output, and the TOE00 bit is set or reset depending on the timer operation. |
| | The TO00 pin outputs the square-wave or PWM depending on the timer operation. |

5.7.6 INTPO Initialization

Figure 5.7 shows the flowchart for INTP0 initialization.

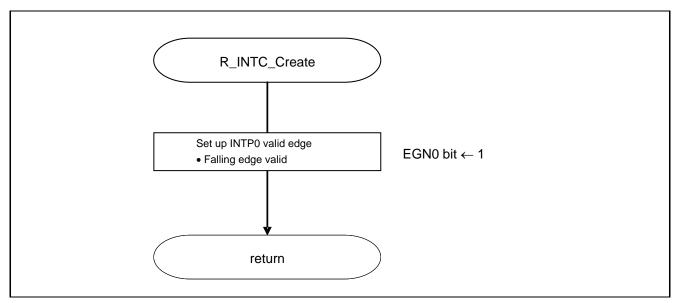


Figure 5.7 INTC Module Setup

Setup for INTP0 pin edge detection

- External interrupt rising edge enable register (EGP0)
- External interrupt falling edge enable register (EGN0) Select a valid edge for INTP0

Symbol: EGP0

| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-----|--------|--------|------|------|------|------|------|
| EGP | 7 EGP6 | 6 EGP5 | EGP4 | EGP3 | EGP2 | EGP1 | EGP0 |
| Х | Х | Х | Х | Х | х | х | 0 |

Symbol: EGN0

| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|------|------|------|------|------|------|------|------|
| EGN7 | EGN6 | EGN5 | EGN4 | EGN3 | EGN2 | EGN1 | EGN0 |
| Х | Х | Х | Х | Х | Х | Х | 1 |

| EGP0 | EGN0 | INTP0 pin valid edge selection | | | | | | |
|------|------|--------------------------------|--|--|--|--|--|--|
| 0 | 0 | Edge detection disabled. | | | | | | |
| 0 | 1 | Falling edge | | | | | | |
| 1 | 0 | Rising edge | | | | | | |
| 1 | 1 | Both rising and falling edges | | | | | | |

5.7.7 Main Processing

Figure 5.8 shows the flowchart for main processing.

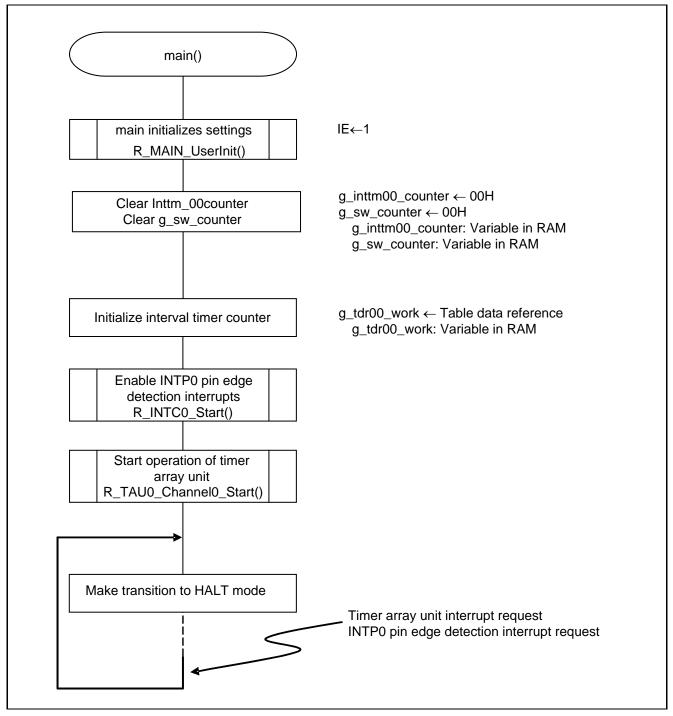


Figure 5.8 Main Processing

5.7.8 Main initializes settings

Figure 5.10 shows the flowchart for the main initializes settings.

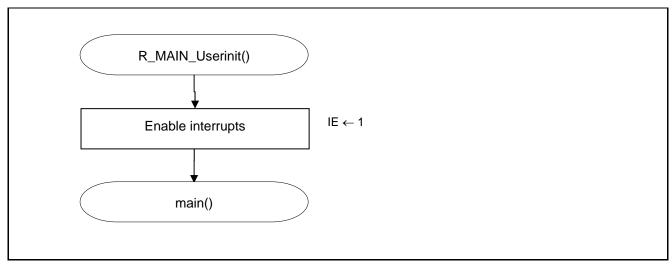


Figure 5.9 Main initializes settings

5.7.9 INTP0 Operation Start

Figure 5.10 shows the flowchart for starting INTP0 operation.

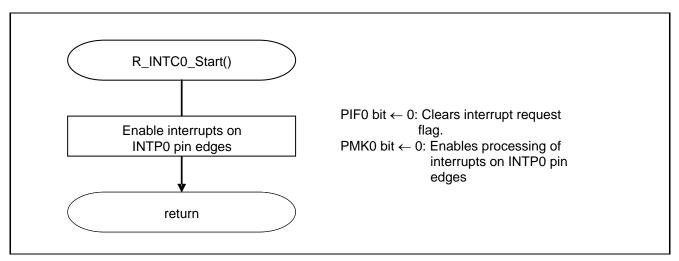


Figure 5.10 INTP0 Operation Start

Setup for INTP0 Interrupts

- Interrupt request flag register (IF0L) Clear interrupt request flag.
- Interrupt mask flag register (MK0L) Clear interrupt mask.

Symbol: IF0L

| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|------|------|------|------|------|------|-------|--------|
| PIF5 | PIF4 | PIF3 | PIF2 | PIF1 | PIF0 | LVIIF | WDTIIF |
| Х | Х | Х | Х | Х | 0 | Х | Х |

Bit 2

| PIF0 | Interrupt request flag | | | | | | |
|------|--|--|--|--|--|--|--|
| 0 | No interrupt request signal is generated | | | | | | |
| 1 | Interrupt request is generated, interrupt request status | | | | | | |

Symbol: MK0L

| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|------|------|------|------|------|------|-------|--------|
| PMK5 | PMK4 | PMK3 | PMK2 | PMK1 | PMK0 | LVIMK | WDTIMK |
| Х | Х | Х | Х | Х | 0 | Х | Х |

Bit 2

| PMK0 | Interrupt processing control |
|------|--------------------------------|
| 0 | Enables interrupt processing. |
| 1 | Disables interrupt processing. |

Caution: For detailed information about setting the registers, see RL78/G13 User's Manual: Hardware.

5.7.10 Timer Array Unit 0 Operation Start

Figure 5.9 shows the flowchart for starting timer array unit operation.

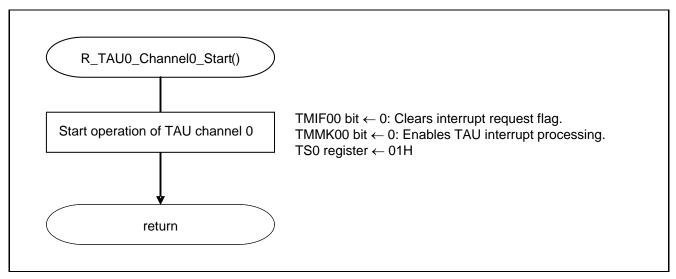


Figure 5.9 Timer Array Unit 0 Operation Start

Configuring the timer interrupt

- Interrupt request flag register (IF1L) Clear the interrupt request flag.
- Interrupt mask flag register (MK1L) Enable interrupt processing.

Symbol: IF1L

| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|--------|--------|--------|---------|---------|---------|---------|
| TMIF03 | TMIF02 | TMIF01 | TMIF00 | IICAIF0 | SREIF1 | SRIF1 | STIF1 |
| | | | | | TMIF03H | CSIIF11 | CSIIF10 |
| | | | | | | IICIF11 | IICIF10 |
| Х | Х | Х | 0 | Х | Х | Х | х |

Bit 4

| TMIF00 | Interrupt request flag | |
|--------|---|--|
| 0 | No interrupt request signal is generated. | |
| 1 | Interrupt request is generated, interrupt | |
| ' | request status | |

Symbol: MK1L

| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|--------|--------|--------|---------|---------|---------|---------|
| TMMK03 | TMMK02 | TMMK01 | TMMK00 | IICAMK0 | SREMK1 | SRMK1 | STMK1 |
| | | | | | ТММК03Н | CSIMK11 | CSIMK10 |
| | | | | | | IICMK11 | IICMK10 |
| Х | Х | Х | 0 | Х | Х | Х | Х |

Bit 4

| TMMK00 | Interrupt processing control | | |
|--------|--------------------------------|--|--|
| 0 | Enables interrupt processing. | | |
| 1 | Disables interrupt processing. | | |

5.7.11 INTTM00 Interrupt Processing

Figure 5.10 shows the flowchart for INTTM00 interrupt processing.

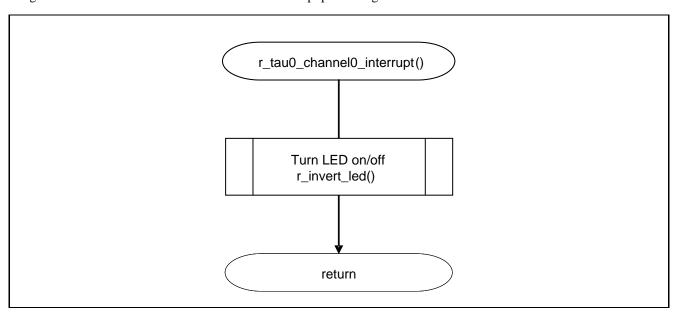


Figure 5.10 INTTM00 Interrupt Processing

5.7.12 LED Turn-On/Off Processing

Figure 5.113 shows the flowchart for LED turn-on/off processing.

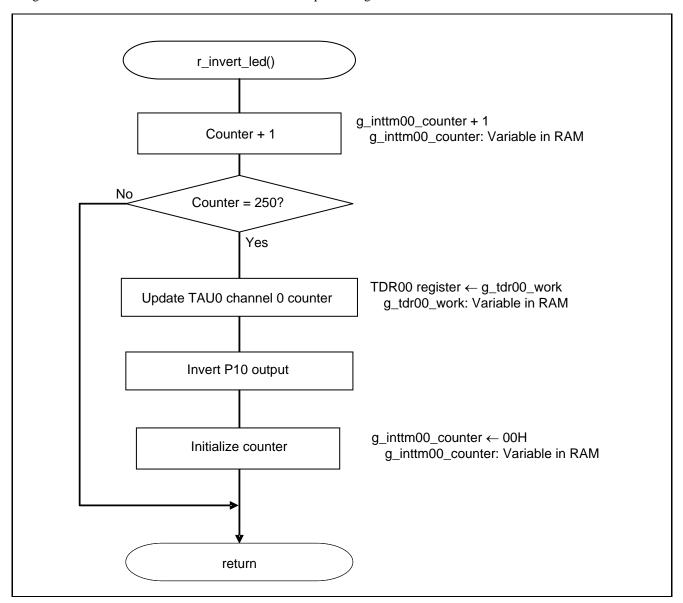


Figure 5.113 Checking Whether 500 ms Have Elapsed

5.7.13 INTP0 Interrupt Processing

Figures 5.14 and 5.15 show the flowchart for INTPO interrupt processing.

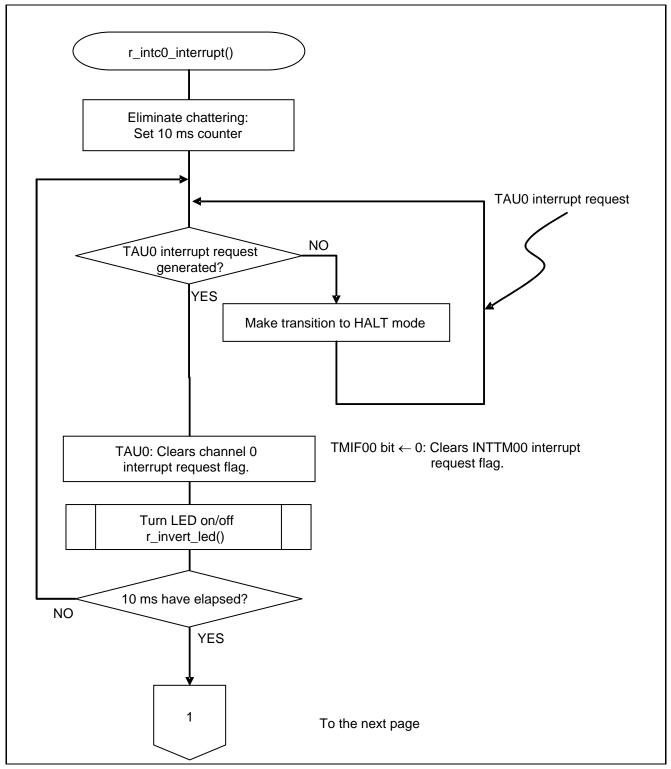


Figure 5.12 INTP0 Interrupt Processing (1/2)

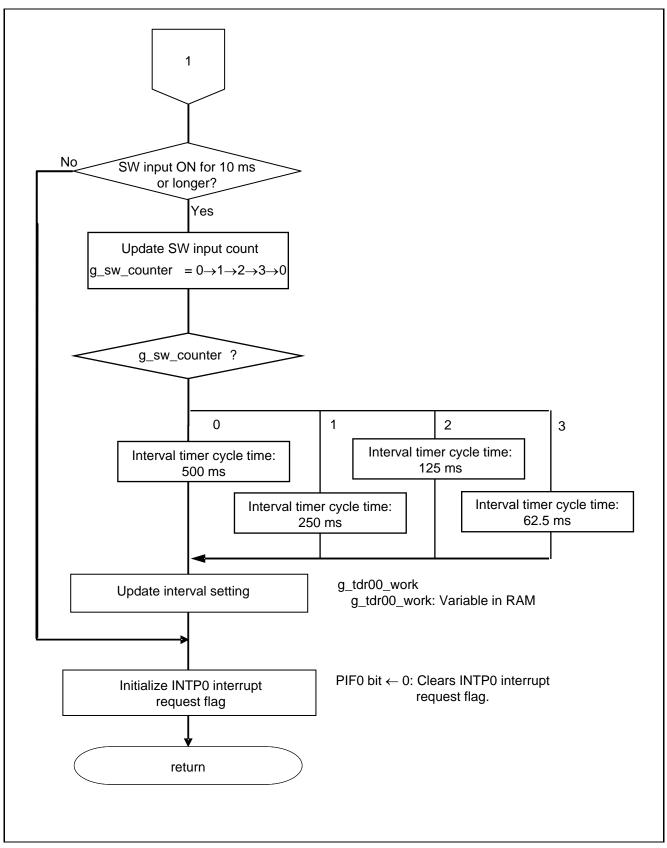


Figure 5.13 INTP0 Interrupt Processing (2/2)

6. Sample Code

The sample code is available on the Renesas Electronics Website.

7. Documents for Reference

User's Manual:

RL78/G13 User's Manual: Hardware (R01UH0146EJ) RL78 Family User's Manual: Software (R01US0015EJ)

The latest version can be downloaded from the Renesas Electronics website.

Technical Updates/Technical News

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| REVISION HISTORY | RL78/G13 Timer Array Unit (Interval Timer) CC-RL |
|------------------|--|
|------------------|--|

| Rev. | Date | Description | | | |
|------|---------------|-------------|--|--|--|
| | | Page | Summary | | |
| 1.00 | Apr. 16, 2015 | _ | First edition issued | | |
| 2.00 | July 01, 2015 | 5 | Table 2.1: Added e ² studio | | |

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Renesas Electronics America Inc. 2801 Scott Boulevard Santa Clara, CA 95050-2549, U.S.A. Tel: +1-408-588-6000, Fax: +1-408-588-6130

Renesas Electronics Canada Limited 9251 Yonge Street, Suite 8309 Richmond Hill, Ontario Canada L4C 9T3 Tel: +1-905-237-2004

Renesas Electronics Europe Limited Dukes Meadow, Millboard Road, Boume End, Buckinghamshire, SL8 5FH, U.K Tel: +44-1628-585-100, Fax: +44-1628-585-900

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Arcadiastrasse 10, 40472 Düsseldorf, Germany Tel: +49-211-6503-0, Fax: +49-211-6503-1327

Renesas Electronics (China) Co., Ltd.
Room 1709, Quantum Plaza, No.27 ZhiChunLu Haidian District, Beijing 100191, P.R.China Tel: +86-10-8235-7679

Renesas Electronics (Shanghai) Co., Ltd.
Unit 301, Tower A, Central Towers, 555 Langao Road, Putuo District, Shanghai, P. R. China 200333
Tel: 486-21-2226-0888, Fax: +86-21-2226-0999

Renesas Electronics Hong Kong Limited
Unit 1601-1611, 16/F., Tower 2, Grand Century Place, 193 Prince Edward Road West, Mongkok, Kowloon, Hong Kong
Tel: +852-2865-6688, Fax: +852 2886-9022

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