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瑞萨电子公司网址：<http://www.renesas.com>

2010年4月1日
瑞萨电子公司

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M16C/65 群

串行 I/O 操作（UART 模式下的发送）

1. 要点

在 UART 模式下发送数据，可以选择如表 1 中所列的各种功能。在表 1 中用符号“○”表示本篇资料所选的项目，图 1 是串行 I/O 的工作时序图。本篇资料的参考例程是使用 UART0 在 UART 模式下发送数据的例子。

2. 说明

本篇资料，适用于 M16C/65 群单片机。

本篇应用说明也适用于 M16C 族中与上面所述的群具有相同 SFR（特殊功能寄存器）定义的产品。关于产品功能的改进，请参看手册中的相关信息。在使用本篇应用说明的程序前，需进行详细的评价。

3. 选定功能

表 1. 选定功能

设定项目	设定内容		设定项目	设定内容	
分频前时钟选择	<input type="radio"/>	f1	发送中断请求产生条件	<input type="radio"/>	发送缓冲器空
		foco-F		<input type="radio"/>	发送结束
外围时钟	<input type="radio"/>	f1SIO	数据逻辑选择功能	<input type="radio"/>	不反转
		f2SIO		<input type="radio"/>	反转
传送时钟源	<input type="radio"/>	内部时钟 (f1SIO/f2SIO/f8SIO/f32SIO)	TxD、RxD 的 I/O 极性反转位	<input type="radio"/>	不反转
		外部时钟 (CLKi 引脚)		<input type="radio"/>	反转
CTS 功能	<input type="radio"/>	CTS 功能允许	CTS /RTS 引脚独立 (注 1)	<input type="radio"/>	复用引脚
		CTS 功能禁止		<input type="radio"/>	独立

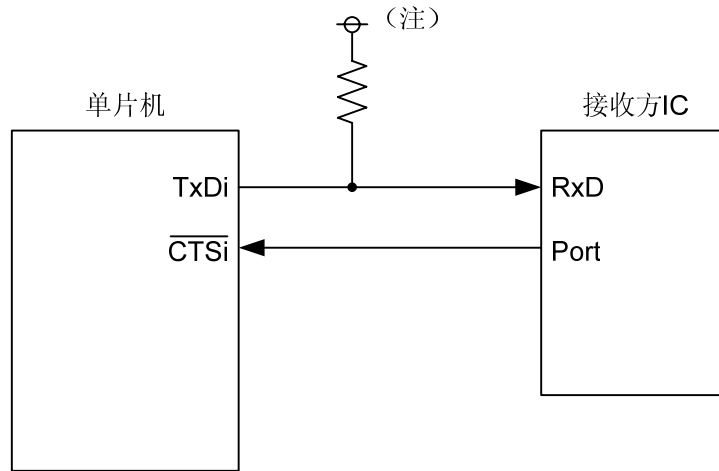
注 1: $\overline{\text{CTS0}}$ / $\overline{\text{RTS0}}$ 独立功能是 $\overline{\text{CTS0}}$ 与 $\overline{\text{RTS0}}$ 引脚功能不复用, 从 P6_0 引脚输出 $\overline{\text{RTS0}}$, 从 P6_4 引脚输出 $\overline{\text{CTS0}}$ 的功能。当选择这个功能时, 不能使用 UART1 的 $\overline{\text{CTS}}$ / $\overline{\text{RTS}}$ 功能, 请将 $\overline{\text{CTS}}$ / $\overline{\text{RTS}}$ 禁止位设置为“1”。

4. 串行 I/O 的操作

- (1) 将发送允许位置为“1”, 将待发送数据写入 UARTi 发送缓冲寄存器中, 进入数据发送状态。
- (2) 当输入到 $\overline{\text{CTS}}_i$ 引脚的电平变为“L”时, 发送开始 ($\overline{\text{CTS}}_i$ 引脚必须由接收方控制)。
- (3) 保存在 UARTi 发送缓冲寄存器的待发送数据被传送到 UARTi 发送寄存器中, 同时, 待发送数据的第一位 (开始位) 从 TxDi 引脚被发送出去。然后, 数据将按照顺序一位一位的被发送出去: LSB、……、MSB、奇偶校验位和停止位。
- (4) 当停止位发送完毕后, 发送寄存器空标志位将被置为“1”, 表明发送结束。同时, UARTi 发送中断请求位也被置为“1”, 传送时钟停止并保持“H”电平。
- (5) 当发送结束时, 如果下一个数据的发送条件也满足, 开始位又将紧随停止位发出, 接着下一个数据将被发送。

使用 UARTi 在 UART 模式下发送数据的工作时序图如下所示:

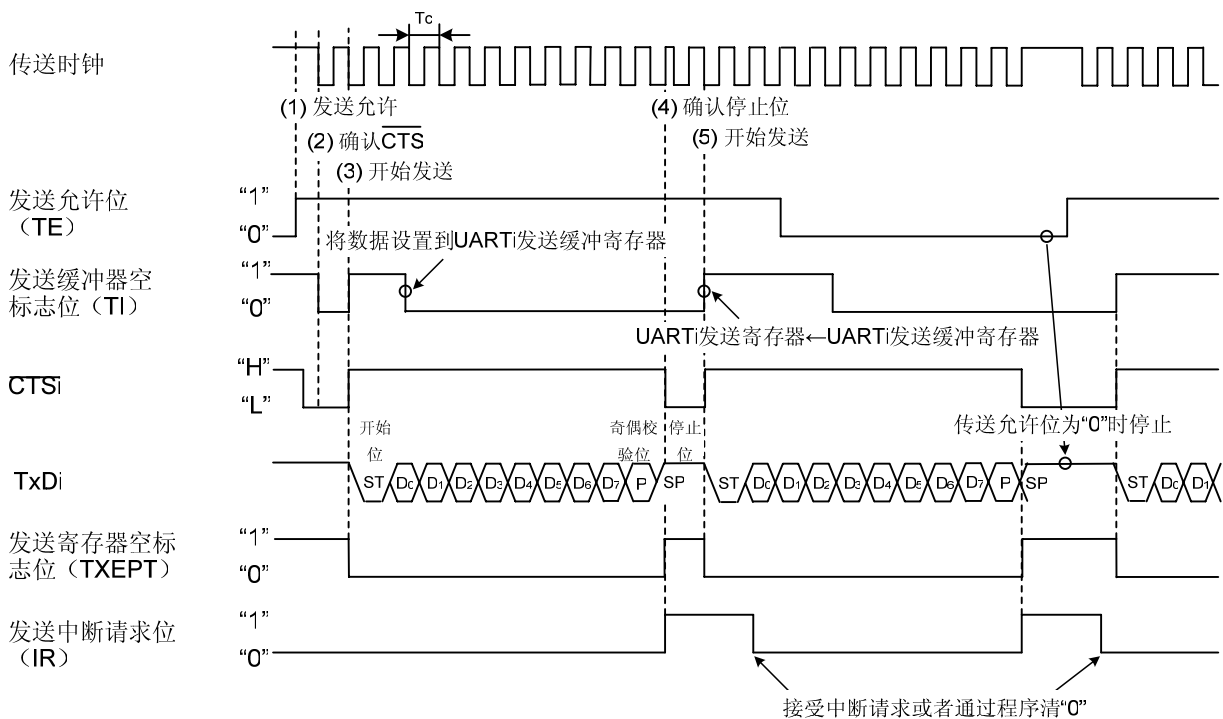
硬件连接示例



注: 由于TxDi引脚为N沟道漏极开路, 所以这个引脚需要上拉电阻。

运行示例

当确认停止位时, 一旦 $\overline{\text{CTS}} = \text{H}$ 就停止传送时钟。
在确认 $\overline{\text{CTS}} = \text{L}$ 后, 再次开始传送时钟, 并立刻开始传送。



() 内标明的是位符号。

此图的设定条件为:

- 允许奇偶检验
- 1个停止位
- 选择CTS功能
- 发送中断源选择位 = "1"

$$T_c = 16(n + 1) / f_i \text{ 或者 } 16(n + 1) / f_{EXT}$$

f_i : BRGi计数源的频率 (f_{1SIO} , f_{2SIO} , f_{8SIO} , f_{32SIO})

n : BRGi寄存器的设定值

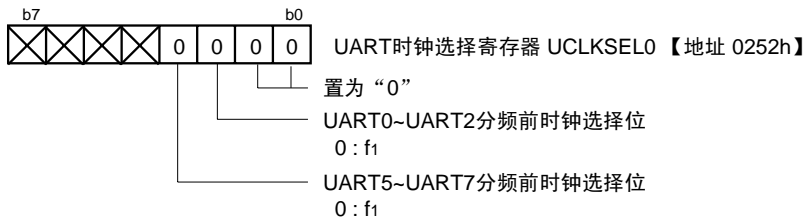
图 1. 使用 UARTi 在 UART 模式下发送数据的工作时序图

5. 寄存器设置

为了能够实现定义在“4. 串行 I/O 的操作”的功能，下列寄存器必须按步骤顺序进行设置。对于每个寄存器的具体结构，请参考 M16C/65 群的硬件手册。

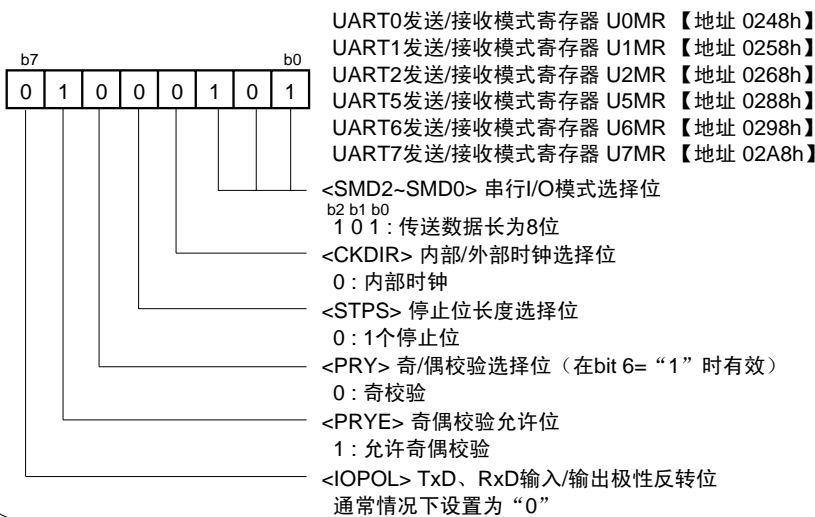
设定UART时钟选择计数器

（请在设定和UART0~UART2、UART5~UART7相关的其它寄存器之前设定OCOSEL0位或者OCOSEL1位。在改变OCOSEL0位或者OCOSEL1位后，请再次设定和UART0~UART2、UART5~UART7相关的其它寄存器。）

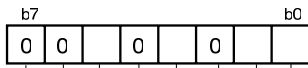


注：请在UART0~UART2、UART5~UART7发送/接收停止时设定OCOSEL0位和OCOSEL1位。

设定UARTi发送/接收模式寄存器（i = 0~2、5~7）



设置UARTi发送/接收控制寄存器 (i = 0~2、5~7)

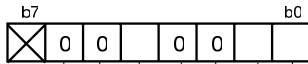


- UART0发送/接收控制寄存器 U0C0 【地址 024Ch】
- UART1发送/接收控制寄存器 U1C0 【地址 025Ch】
- UART2发送/接收控制寄存器 U2C0 【地址 026Ch】
- UART5发送/接收控制寄存器 U5C0 【地址 028Ch】
- UART6发送/接收控制寄存器 U6C0 【地址 029Ch】
- UART7发送/接收控制寄存器 U7C0 【地址 02ACh】

- <CLK1~CLK0> UiBRG计数源选择位
- b1 b0
- 0 0 : f1SIO或f2SIO
- 0 1 : f8SIO
- 1 0 : f32SIO
- 1 1 : 不能设定
- <CRS> CTS/RTS功能选择位 (在bit4=“0”时有效)
- 0 : 选择CTS功能
- <TXEPT> 发送寄存器空标志
- 0 : 发送寄存器中有数据 (在发送中)
- 1 : 发送寄存器中无数据 (发送结束)
- <CRD> $\overline{\text{CTS}}/\overline{\text{RTS}}$ 禁止位
- 0 : 允许CTS/RTS功能
- <NCH> 数据输出选择位
- 0 : TxDi/SDAi、SCLi引脚为CMOS输出
- 1 : TxDi/SDAi、SCLi引脚为N沟道漏极开路
- <CKPOL> 在UART模式时清为“0”
- <UFORM> 传送格式选择位
- 0 : LSB先

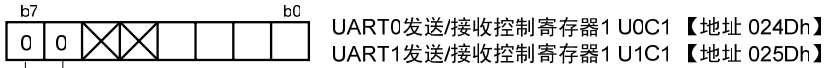
注1: 当PCLKR寄存器的PCLK0位为“1”时, 选择时钟 f1SIO, 当PCLKR寄存器的PCLK0位为“0”时, 选择时钟 f2SIO。
 注2: 请将对应引脚的端口方向位清“0”(输入模式)。

设定UART发送/接收控制寄存器2



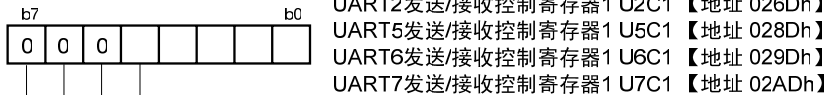
- UART发送/接收控制寄存器2 UCON 【地址 0250h】
- <U0IRS> UART0发送中断源选择位
- 1 : 发送结束 (TXEPT=1)
- <U1IRS> UART1发送中断源选择位
- 1 : 发送结束 (TXEPT=1)
- <U0RRM> 在UART模式时清为“0”
- <U1RRM> 在UART模式时清为“0”
- <CLKMD0> 在UART模式时无效
- <CLKMD1> 在UART模式时清为“0”
- <RCSP> UART0 $\overline{\text{CTS}}/\overline{\text{RTS}}$ 独立位
- 0 : $\overline{\text{CTS}}/\overline{\text{RTS}}$ 复用引脚

设定UARTi发送/接收控制寄存器1 (i = 0~2、5~7)



UART0发送/接收控制寄存器1 U0C1 【地址 024Dh】
 UART1发送/接收控制寄存器1 U1C1 【地址 025Dh】

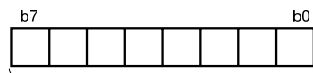
<UiLCH> 数据逻辑选择位
 0: 无反转
 <UiERE> 错误信号输出允许位
 0: 禁止输出



UART2发送/接收控制寄存器1 U2C1 【地址 026Dh】
 UART5发送/接收控制寄存器1 U5C1 【地址 028Dh】
 UART6发送/接收控制寄存器1 U6C1 【地址 029Dh】
 UART7发送/接收控制寄存器1 U7C1 【地址 02ADh】

<UiIRS> UARTi发送中断源选择位
 1: 发送结束 (TXEPT=1)
 <UiRRM> 在UART模式时通常置为“0”
 <UiLCH> 数据逻辑选择位
 0: 无反转
 <UiERE> 错误信号输出允许位
 0: 禁止输出

设定UARTi位速率寄存器 (i = 0~2、5~7)

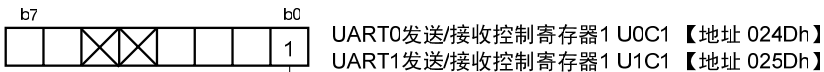


UART0位速率寄存器 U0BRG 【地址 0249h】
 UART1位速率寄存器 U1BRG 【地址 0259h】
 UART2位速率寄存器 U2BRG 【地址 0269h】
 UART5位速率寄存器 U5BRG 【地址 0289h】
 UART6位速率寄存器 U6BRG 【地址 0299h】
 UART7位速率寄存器 U7BRG 【地址 02A9h】

在00h~FFh范围内进行设定 (注1)

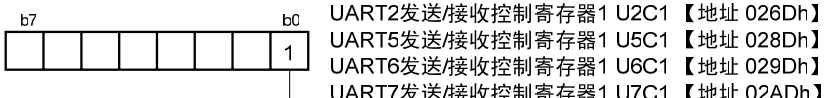
注1: 请在发送/接收停止时对UiBRG寄存器进行写操作。请使用MOV指令写UiBRG寄存器。请在设定UiC0寄存器的CLK1和CLK0位后写UiBRG寄存器。

发送允许



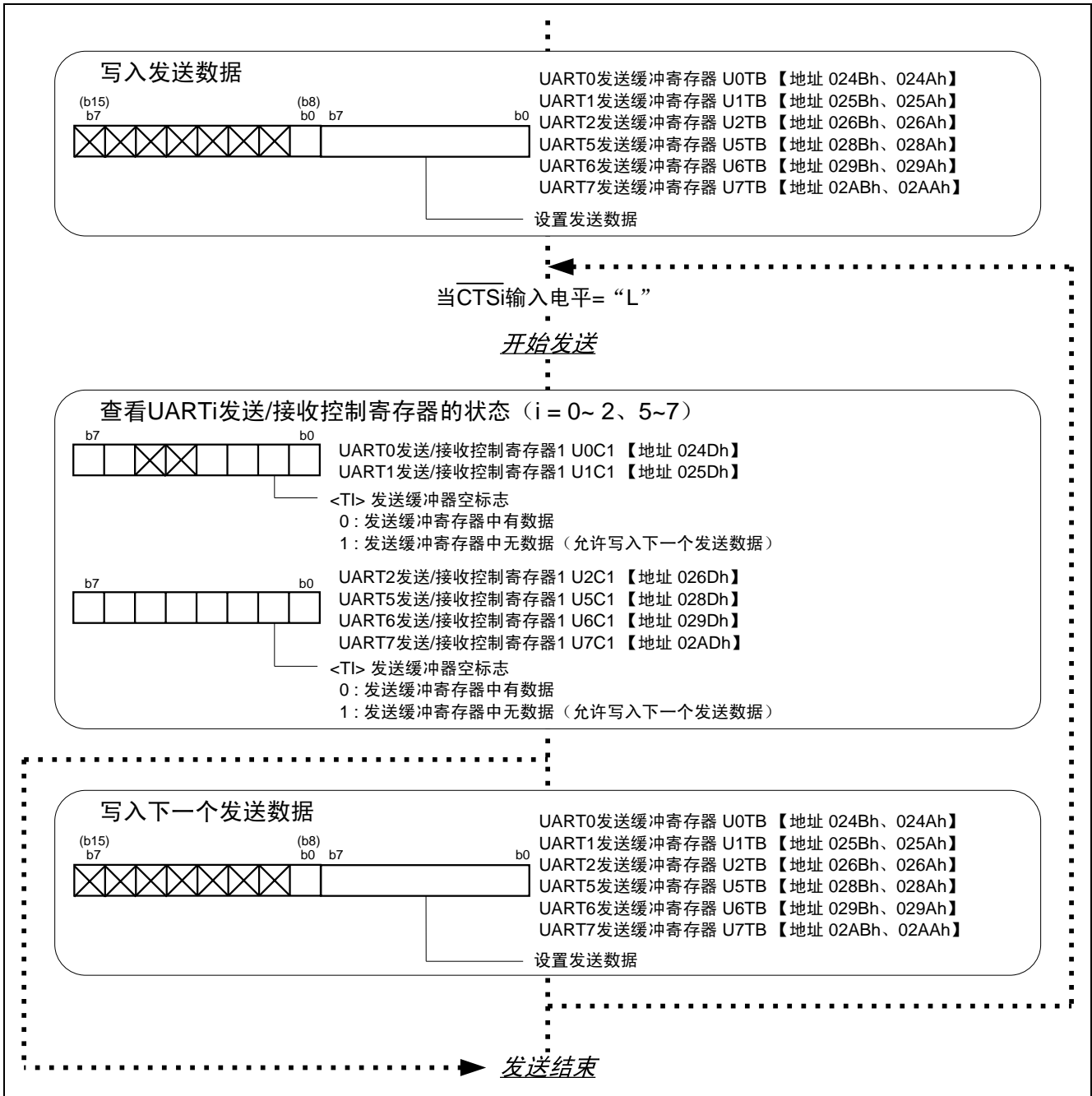
UART0发送/接收控制寄存器1 U0C1 【地址 024Dh】
 UART1发送/接收控制寄存器1 U1C1 【地址 025Dh】

<TE> 发送允许位
 1: 允许发送



UART2发送/接收控制寄存器1 U2C1 【地址 026Dh】
 UART5发送/接收控制寄存器1 U5C1 【地址 028Dh】
 UART6发送/接收控制寄存器1 U6C1 【地址 029Dh】
 UART7发送/接收控制寄存器1 U7C1 【地址 02ADh】

<TE> 发送允许位
 1: 允许发送



6. 参考文献

数据手册

M16C/65 群硬件手册

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 - 1) 生命维持装置。
 - 2) 植埋于人体使用的装置。
 - 3) 用于治疗（切除患部、给药等）的装置。
 - 4) 其他直接影响到人的生命的装置。
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