

## RX Family

### SCI FIFO Module Using Firmware Integration Technology

---

#### Introduction

This application note describes the SCI FIFO module which uses Firmware Integration Technology (FIT).

This module provides Asynchronous and Master Synchronous support for all channels of the SCI FIFO peripheral. Channels and modes may be configured on an individual basis, with disabled channels and modes allocating no resources.

#### Target Device

The following is a list of devices that are currently supported by this API:

- RX64M Group
- RX71M Group

When using this application note with other Renesas MCUs, careful evaluation is recommended after making modifications to comply with the alternate MCU.

#### Related Documents

- Firmware Integration Technology User's Manual (R01AN1833)
- RX Family Board Support Package Firmware Integration Technology Module (R01AN1685)

## Contents

1. Overview .....	4
1.1 SCIF FIT Module .....	4
1.2 Overview of the SCIF FIT Module .....	4
1.3 API Overview.....	5
2. API Information.....	6
2.1 Hardware Requirements .....	6
2.2 Hardware Resource Requirements .....	6
2.2.1 SCIFA .....	6
2.2.2 GPIO .....	6
2.3 Software Requirements.....	6
2.4 Supported Toolchains .....	6
2.5 Interrupt Vector.....	7
2.6 Header Files .....	7
2.7 Integer Types.....	7
2.8 Configuration Overview .....	8
2.9 Code Size .....	9
2.10 Parameters .....	11
2.11 Return Values.....	11
2.12 Callback Function .....	11
2.13 Adding the FIT Module to Your Project .....	12
2.14 "for", "while" and "do while" statements .....	13
2.15 Limitations .....	14
2.15.1 RAM Location Limitations .....	14
3. API Functions .....	15
3.1 R_SCIF_Open().....	15
3.2 R_SCIF_Close() .....	21
3.3 R_SCIF_Send().....	22
3.4 R_SCIF_Receive() .....	26
3.5 R_SCIF_SendReceive().....	30
3.6 R_SCIF_Control().....	32
3.7 R_SCIF_GetVersion() .....	35
4. Pin Setting .....	36
5. Demo Projects .....	37
5.1 Adding the Demo to a Workspace.....	37
5.2 Downloading Demo Projects .....	37
5.3 Demo for RX64M (scif_demo_rskrx64m).....	38
5.4 Demo for RX71M (scif_demo_rskrx71m).....	39

6. Appendix .....40

6.1 Operating Test Environment ..... 40

6.2 Troubleshooting..... 42

Revision History .....43

## 1. Overview

### 1.1 SCIF FIT Module

The SCIF FIT module can be used by being implemented in a project as an API. See section 2.13 Adding the FIT Module to Your Project for details on methods to implement this FIT module into a project.

### 1.2 Overview of the SCIF FIT Module

This SCI FIFO driver supports the SCIFA peripheral on the RX64M and RX71M. The hardware functionality is detailed in Chapter 41 of the RX64M/RX71M Hardware User's Manual. All basic UART and Master Synchronous mode functionality is supported by this driver. Additionally, the driver supports the following features in Asynchronous mode:

- noise cancellation.
- MSB-first bit order
- flow control with CTS / RTS.

Features not supported by this driver are:

- DRIF interrupt (works only for messages less than threshold number of bytes in length)

This is a multi-channel driver which supports all channels present on the peripheral. Specific channels can be excluded via compile-time equates to reduce driver RAM and ROM usage and code size if desired. These equates are specified in "r\_scif\_rx\_config.h".

An individual channel is initialized in the application by calling R\_SCIF\_Open(). This function applies power to the peripheral and initializes settings particular to the specified mode. A handle is returned from this function to uniquely identify the channel. The handle references an internal driver structure that maintains pointers to the channel's register set, buffers, and other critical information. It is also used as an argument for the other API functions.

This driver is interrupt-driven and non-blocking. For Asynchronous mode, data will be stored in the receive FIFO until an overflow occurs or an R\_SCIF\_Receive() is issued (whichever comes first). Interrupts supported by this driver are TXIF, RXIF, and the GROUPAL0 TEIF, ERIF, and BRIF interrupts.

The TXIF interrupt occurs whenever the configured threshold number of bytes remain in the transmit FIFO. During this interrupt the FIFO is loaded with more bytes from the transmit message until either no more data remains in the message or the transmit FIFO becomes full (whichever comes first). The TEIF interrupt occurs only after the last bit of the last byte from the FIFO has been shifted out of the TSR register. If a callback function is provided in the R\_SCIF\_Open() call, it is called here with a SCIF\_EVT\_TX\_DONE (Asynchronous) or SCIF\_EVT\_XCV\_DONE (Synchronous) event passed to it. The Send() and SendReceive() functions can have two transmit requests outstanding at a time to provide continuous streaming of data. The DONE event does not occur until all outstanding requests have been processed. If it is desired to know when each message completes, no more than one request should be outstanding at a time.

The RXIF interrupt occurs each time the receive FIFO contains the configured number of threshold bytes. During this interrupt, the message buffer is loaded with data from the FIFO until the requested number of bytes have been read or until no more data remains in the FIFO. When the entire number of bytes requested have been read and if a callback function is provided, it is called with a SCIF\_EVT\_RX\_DONE (Asynchronous) or SCIF\_EVT\_XCV\_DONE (Synchronous) event. The Receive() and SendReceive() functions can have two receive requests outstanding at a time to provide continuous streaming of data. The DONE event does not occur until all outstanding requests have been processed. If it is desired to know when each message completes, no more than one request should be outstanding at a time.

In Asynchronous mode, the ERIF interrupt occurs when a framing or parity error is detected by the receiver hardware, and the BRIF interrupt occurs when a Break is received or a receive-FIFO overflow occurs. If a callback function is provided, the interrupt determines which error occurred and notifies the application of the event. Whether a callback function is provided or not, the interrupt clears the error condition by writing "0" to the appropriate FSR or LSR error flag.

### 1.3 API Overview

Table 1.1 lists the API functions included in this module.

**Table 1.1 API Functions**

Function	Description
R_SCIF_Open	Applies power to the SCIF channel, initializes the associated registers, enables interrupts, and provides the channel handle for use with other API functions. Takes an optional callback function pointer for notifying the user at interrupt level whenever a receiver error or other interrupt events have occurred.
R_SCIF_Close	Removes power to the SCIF channel and disables the associated interrupts.
R_SCIF_Send	Queues message for sending on the transmit FIFO. Up to two requests can be outstanding at a time. Transmission begins immediately if transmitter is idle.
R_SCIF_Receive	Queues message for receiving from the receive FIFO. Up to two requests can be outstanding at a time. In Sync mode, driver starts clocking in data immediately if transceiver is idle.
R_SCIF_SendReceive	For Synchronous mode only. Transmits and receives data simultaneously. Up to two requests total (Send(), Receive(), and/or SendReceive()) can be outstanding at a time.
R_SCIF_Control	Handles special hardware or software operations for the SCIF channel.
R_SCIF_GetVersion	Returns at runtime the driver version number.

## 2. API Information

This FIT module has been confirmed to operate under the following conditions.

---

### 2.1 Hardware Requirements

---

The MCU used must support the following functions:

- SCIFA peripheral
- 

### 2.2 Hardware Resource Requirements

---

This section details the hardware peripherals that this driver requires. Unless explicitly stated, these resources must be reserved for the driver and the user cannot use them.

#### 2.2.1 SCIFA

This driver makes use of the SCIFA peripheral. Individual channels may be omitted by this driver by disabling them in the "r\_scif\_rx\_config.h" file.

#### 2.2.2 GPIO

This driver utilizes port pins corresponding to each individual channel. These pins may not be used for GPIO.

---

### 2.3 Software Requirements

---

This driver is dependent upon the following FIT module:

- Renesas Board Support Package (r\_bsp)
- 

### 2.4 Supported Toolchains

---

This driver has been confirmed to work with the toolchain listed in 6.1, Operating Test Environment.

---

## 2.5 Interrupt Vector

For asynchronous mode, when the R\_SCIF\_Open function is executed, interrupts TXIFn, RXIFn, TEIFn, ERIFn, and BRIFn become enabled. When the R\_SCIF\_Send function is executed, the DRIFn interrupt becomes enabled.

For synchronous mode, when the R\_SCIF\_Open function is executed, interrupts TXIFn, RXIFn, and TEIFn become enabled. When the R\_SCIF\_Send function is executed, the DRIFn interrupt becomes enabled.

Table 2.1 shows the interrupt vectors used by the SCI FIFO FIT module.

**Table 2.1 List of Usage of Interrupt Vectors**

Device	Contents
RX64M RX71M	RXIF8 interrupt [channel 8] (vector no.: 100) TXIF8 interrupt [channel 8] (vector no.: 101) RXIF9 interrupt [channel 9] (vector no.: 102) TXIF9 interrupt [channel 9] (vector no.: 103) RXIF10 interrupt [channel 10] (vector no.: 104) TXIF10 interrupt [channel 10] (vector no.: 105) RXIF11 interrupt [channel 11] (vector no.: 114) TXIF11 interrupt [channel 11] (vector no.: 115)  GROUPAL0 interrupt (vector no.: 112) <ul style="list-style-type: none"> <li>• TEIF8 interrupt [channel 8] (group interrupt source no.: 0)</li> <li>• ERIF8 interrupt [channel 8] (group interrupt source no.: 1)</li> <li>• BRIF8 interrupt [channel 8] (group interrupt source no.: 2)</li> <li>• DRIF8 interrupt [channel 8] (group interrupt source no.: 3)</li> <li>• TEIF9 interrupt [channel 9] (group interrupt source no.: 4)</li> <li>• ERIF9 interrupt [channel 9] (group interrupt source no.: 5)</li> <li>• BRIF9 interrupt [channel 9] (group interrupt source no.: 6)</li> <li>• DRIF9 interrupt [channel 9] (group interrupt source no.: 7)</li> <li>• TEIF10 interrupt [channel 10] (group interrupt source no.: 8)</li> <li>• ERIF10 interrupt [channel 10] (group interrupt source no.: 9)</li> <li>• BRIF10 interrupt [channel 10] (group interrupt source no.: 10)</li> <li>• DRIF10 interrupt [channel 10] (group interrupt source no.: 11)</li> <li>• TEIF11 interrupt [channel 11] (group interrupt source no.: 12)</li> <li>• ERIF11 interrupt [channel 11] (group interrupt source no.: 13)</li> <li>• BRIF11 interrupt [channel 11] (group interrupt source no.: 14)</li> <li>• DRIF11 interrupt [channel 11] (group interrupt source no.: 15)</li> </ul>

## 2.6 Header Files

All API calls and their supporting interface definitions are located in r\_scif\_rx\_if.h.

## 2.7 Integer Types

This project uses ANSI C99. These types are defined in stdint.h.

## 2.8 Configuration Overview

The configuration option settings of this module are located in `r_scif_rx_config.h`. The option names and setting values are listed in the table below:

Configuration options in <code>r_scif_rx_config.h</code>		
Definition		Contents
<code>#define SCIF_CFG_PARAM_CHECKING_ENABLE</code>	1	If this equate is set to 1, parameter checking is included in the build. If the equate is set to 0, the parameter checking is omitted from the build. Setting this equate to <code>BSP_CFG_PARAM_CHECKING_ENABLE</code> utilizes the system default setting.
<code>#define SCIF_CFG_ASYNC_INCLUDED</code>	1	These equates are used to include code specific to their mode of operation. A value of 1 means that the supporting code will be included. Use a value of 0 for unused modes to reduce overall code size.
<code>#define SCIF_CFG_SYNC_INCLUDED</code>	0	
<code>#define SCIF_CFG_CH8_INCLUDED</code>	0	Each channel has associated with it transmit and receive pointers, counters, interrupts, and other program and RAM resources. Setting a <code>#define</code> to 1 allocates resources for that channel.
<code>#define SCIF_CFG_CH9_INCLUDED</code>	1	
<code>#define SCIF_CFG_CH10_INCLUDED</code>	0	
<code>#define SCIF_CFG_CH11_INCLUDED</code>	0	
<code>#define SCIF_CFG_CH8_TX_FIFO_THRESHOLD</code>	8	The transmit FIFO is 16 bytes deep. A TXIF interrupt occurs when there are threshold number of bytes remaining in the FIFO, indicating it is time to load more bytes. Valid values are 0 through 15. Ideally, all messages sent are multiples of the threshold value, and the threshold value is small enough such that no gaps occur between bytes during transmission at high bit rates due to reloading the FIFO.
<code>#define SCIF_CFG_CH9_TX_FIFO_THRESHOLD</code>	8	
<code>#define SCIF_CFG_CH10_TX_FIFO_THRESHOLD</code>	8	
<code>#define SCIF_CFG_CH11_TX_FIFO_THRESHOLD</code>	8	
<code>#define SCIF_CFG_CH8_RX_FIFO_THRESHOLD</code>	8	The receive FIFO is 16 bytes deep. An RXIF interrupt occurs when there are threshold number of bytes available in the FIFO, indicating it is time to read more bytes. Valid values are 1 through 16. Ideally, all messages received are multiples of the threshold value, and the threshold value is small enough such that no overflow occurs while receiving at high bit rates due to insufficient time to read the FIFO. In Synchronous mode, these values should match the corresponding <code>TX_FIFO_THRESHOLD</code> for maximum efficiency.
<code>#define SCIF_CFG_CH9_RX_FIFO_THRESHOLD</code>	8	
<code>#define SCIF_CFG_CH10_RX_FIFO_THRESHOLD</code>	8	
<code>#define SCIF_CFG_CH11_RX_FIFO_THRESHOLD</code>	8	

## 2.9 Code Size

The sizes of ROM, RAM and maximum stack usage associated with this module and BSP are listed below.

The ROM (code and constants) and RAM (global data) sizes are determined by the build-time configuration options described in Section 2.8 "Configuration Overview".

The values in the table below are confirmed under the following conditions.

Module Revision: r\_scif\_rx rev2.00, r\_bsp rev5.50

Compiler Version:

- Renesas Electronics C/C++ Compiler Package for RX Family V3.01.00  
(The option of "-lang = c99" is added to the default settings of the integrated development environment.)
- GCC for Renesas RX 8.3.0.201904  
(The option of "-std=gnu99" is added to the default settings of the integrated development environment.)
- IAR C/C++ Compiler for Renesas RX version 4.12.1  
(The default settings of the integrated development environment.)

Configuration Options: Default settings

ROM, RAM and Stack Code Sizes for Renesas Compiler				
Device / Communication Methods / Number of Channels	Category	Memory Used		
		ROM	RAM	STACK*1
RX64M Async only / 1 channel	With Parameter Checking	13,372 bytes	7,769 bytes	220 bytes
	Without Parameter Checking	13,071 bytes		
RX64M Async only / 2 channels	With Parameter Checking	13,551 bytes	7,817 bytes	220 bytes
	Without Parameter Checking	13,250 bytes		
RX64M Sync only / 1 channel	With Parameter Checking	12,225 bytes	7,764 bytes	208 bytes
	Without Parameter Checking	11,995 bytes		
RX64M Sync only / 2 channels	With Parameter Checking	12,366 bytes	7,812 bytes	208 bytes
	Without Parameter Checking	12,136 bytes		
RX64M Async only / 1 channel Sync only / 1 channel	With Parameter Checking	13,886 bytes	7,817 bytes	220 bytes
	Without Parameter Checking	13,535 bytes		

Note 1. The sizes of maximum usage stack of interrupts functions are included.

ROM, RAM and Stack Code Sizes for Renesas Compiler				
Device / Communication Methods / Number of Channels	Category	Memory Used		
		ROM	RAM	STACK*1
RX64M Async only / 1 channel	With Parameter Checking	23,464 bytes	7,588 bytes	-
	Without Parameter Checking	22,880 bytes		
RX64M Async only / 2 channels	With Parameter Checking	23,648 bytes	7,636 bytes	-
	Without Parameter Checking	23,064 bytes		
RX64M Sync only / 1 channel	With Parameter Checking	21,424 bytes	7,584 bytes	-
	Without Parameter Checking	21,032 bytes		
RX64M Sync only / 2 channels	With Parameter Checking	21,528 bytes	7,632 bytes	-
	Without Parameter Checking	21,144 bytes		
RX64M Async only / 1 channel Sync only / 1 channel	With Parameter Checking	24,096 bytes	7,588 bytes	-
	Without Parameter Checking	23,432 bytes		

Note 1. The sizes of maximum usage stack of interrupts functions are included.

ROM, RAM and Stack Code Sizes for Renesas Compiler				
Device / Communication Methods / Number of Channels	Category	Memory Used		
		ROM	RAM	STACK*1
RX64M Async only 1 channel	With Parameter Checking	14,990 bytes	5,267 bytes	244 bytes
	Without Parameter Checking	14,519 bytes		
RX64M Async only 2 channels	With Parameter Checking	15,131 bytes	5,315 bytes	244 bytes
	Without Parameter Checking	14,657 bytes		
RX64M Sync only 1 channel	With Parameter Checking	13,570 bytes	5,266 bytes	240 bytes
	Without Parameter Checking	13,290 bytes		
RX64M Sync only 2 channels	With Parameter Checking	13,673 bytes	5,314 bytes	240 bytes
	Without Parameter Checking	13,393 bytes		
RX64M Async only 1 channel Sync only 1 channel	With Parameter Checking	15,499 bytes	5,315 bytes	244 bytes
	Without Parameter Checking	14,993 bytes		

Note 1. The sizes of maximum usage stack of interrupts functions are included.

---

## 2.10 Parameters

---

The API data structures are located in the file "r\_scif\_rx\_if.h" and discussed in Section 3.

---

## 2.11 Return Values

---

This section describes return values of API functions. This enumeration is located in r\_scif\_rx\_if.h as are the prototype declarations of API functions.

```
typedef enum e_scif_err    // SCIF API error codes
{
    SCIF_SUCCESS=0,
    SCIF_ERR_BAD_CHAN,    // non-existent channel number
    SCIF_ERR_OMITTED_CHAN, // SCI_CHx_INCLUDED is 0 in config.h
    SCIF_ERR_CH_NOT_CLOSED, // channel still running in another mode
    SCIF_ERR_BAD_MODE,    // unsupported mode for channel
    SCIF_ERR_INVALID_ARG, // argument is not valid for parameter
    SCIF_ERR_NULL_PTR,    // received null ptr; missing required argument
    SCIF_ERR_BUSY,        // 2 requests already being processed
    SCIF_ERR_IN_PROGRESS, // request still being processed
} scif_err_t;
```

---

## 2.12 Callback Function

---

In this module, the callback function registered by the user is called when the SCIF interrupt occurs.

The callback function is specified by storing the address of the user function in the argument (p\_callback) of the R\_SCIF\_Open() function.

For details on callback functions, refer to the R\_SCIF\_Open() function in Section 3.

---

## 2.13 Adding the FIT Module to Your Project

---

This module must be added to each project in which it is used. Renesas recommends using "Smart Configurator" described in (1) or (3). However, "Smart Configurator" only supports some RX devices. Please use the methods of (2) or (4) for unsupported RX devices.

- (1) Adding the FIT module to your project using "Smart Configurator" in e<sup>2</sup> studio

By using the "Smart Configurator" in e<sup>2</sup> studio, the FIT module is automatically added to your project. Refer to "Renesas e<sup>2</sup> studio Smart Configurator User Guide (R20AN0451)" for details.

- (2) Adding the FIT module to your project using "FIT Configurator" in e<sup>2</sup> studio

By using the "FIT Configurator" in e<sup>2</sup> studio, the FIT module is automatically added to your project. Refer to "Adding Firmware Integration Technology Modules to Projects (R01AN1723)" for details.

- (3) Adding the FIT module to your project using "Smart Configurator" on CS+

By using the "Smart Configurator Standalone version" in CS+, the FIT module is automatically added to your project. Refer to "Renesas e<sup>2</sup> studio Smart Configurator User Guide (R20AN0451)" for details.

- (4) Adding the FIT module to your project in CS+

In CS+, please manually add the FIT module to your project. Refer to "Adding Firmware Integration Technology Modules to CS+ Projects (R01AN1826)" for details.

## 2.14 "for", "while" and "do while" statements

In this module, "for", "while" and "do while" statements (loop processing) are used in processing to wait for register to be reflected and so on. For these loop processing, comments with "WAIT\_LOOP" as a keyword are described. Therefore, if user incorporates fail-safe processing into loop processing, user can search the corresponding processing with "WAIT\_LOOP".

Target devices describing "WAIT\_LOOP":

- RX64M, RX71M Group

The following shows example of description.

while statement example :

```
/* WAIT_LOOP */
while(0 == SYSTEM.OSCOVFSR.BIT.PLOVF)
{
    /* The delay period needed is to make sure that the PLL has stabilized. */
}
```

for statement example :

```
/* Initialize reference counters to 0. */
/* WAIT_LOOP */
for (i = 0; i < BSP_REG_PROTECT_TOTAL_ITEMS; i++)
{
    g_protect_counters[i] = 0;
}
```

do while statement example :

```
/* Reset completion waiting */
do
{
    reg = phy_read(ether_channel, PHY_REG_CONTROL);
    count++;
} while ((reg & PHY_CONTROL_RESET) && (count < ETHER_CFG_PHY_DELAY_RESET));
/* WAIT_LOOP */
```

## 2.15 Limitations

---

### 2.15.1 RAM Location Limitations

In FIT, if a value equivalent to NULL is set as the pointer argument of an API function, error might be returned due to parameter check. Therefore, do not pass a NULL equivalent value as pointer argument to an API function.

The NULL value is defined as 0 because of the library function specifications. Therefore, the above phenomenon would occur when the variable or function passed to the API function pointer argument is located at the start address of RAM (address 0x0). In this case, change the section settings or prepare a dummy variable at the top of the RAM so that the variable or function passed to the API function pointer argument is not located at address 0x0.

In the case of CCRX project (e<sup>2</sup> studio V7.5.0), the RAM start address is set as 0x4 to prevent the variable from being located at address 0x0. In the case of GCC project (e<sup>2</sup> studio V7.5.0) and IAR project (EWRX V4.12.1), the start address of RAM is 0x0, so the above measures are necessary.

The default settings of the section may be changed due to IDE version upgrade. Please check the section settings when using the latest IDE.

### 3. API Functions

#### 3.1 R\_SCIF\_Open()

This function applies power to the SCIF channel, initializes the associated registers, enables interrupts, and provides the channel handle for use with other API functions.

##### Format

```
scif_err_t R_SCIF_Open(
    uint8_t const      chan,
    scif_mode_t const  mode,
    scif_cfg_t * const p_cfg,
    void (* const p_callback)(void *p_args),
    scif_hdl_t * const p_hdl
);
```

##### Parameters

uint8\_t chan

Channel to initialize; 8-11

scif\_mode\_t const mode

Operational mode (see enumeration below)

scif\_cfg\_t \* const p\_cfg

Pointer to configuration union, structure elements (see below) are specific to mode.

void (\* const p\_callback)(void \*p\_args)

Optional pointer to function called from interrupt when a message send/receive completes or receiver error occurs.

scif\_hdl\_t \* const p\_hdl

Pointer to a handle for channel (value set here)

The following SCIF modes are currently supported by this driver module. The mode specified determines the union structure element used for the p\_cfg parameter.

```
typedef enum e_scif_mode // SCIF operational modes
{
    SCIF_MODE_OFF=0, // channel not in use
    SCIF_MODE_ASYNC, // Asynchronous
    SCIF_MODE_SYNC, // Synchronous
    SCIF_MODE_END_ENUM
} scif_mode_t;
```

The following enumerations indicate configurable options for Asynchronous mode used in its configuration structure. These values correspond to bit definitions in the SCR and SMR registers.

```
typedef enum e_scif_clk
{
    SCIF_CLK_INT      = 0x00, // use internal clock for baud generation
    SCIF_CLK_EXT8X   = 0x03, // use external clock 8x baud rate
    SCIF_CLK_EXT16X  = 0x02  // use external clock 16x baud rate
} scif_clk_t;
```

```
typedef enum e_scif_size
{
    SCIF_DATA_7BIT = 0x40,
    SCIF_DATA_8BIT = 0x00
} scif_size_t;
```

```
typedef enum e_scif_parity_en
{
    SCIF_PARITY_ON   = 0x20,
    SCIF_PARITY_OFF  = 0x00
} scif_parity_en_t;
```

```
typedef enum e_parity_t
{
    SCIF_ODD_PARITY  = 0x10,
    SCIF_EVEN_PARITY = 0x00
} scif_parity_t;
```

```
typedef enum e_scif_stop_t
{
    SCIF_STOPBITS_2 = 0x08,
    SCIF_STOPBITS_1 = 0x00
} scif_stop_t;
```

The complete runtime configurable options for Asynchronous mode are declared in the structure below. This structure is an element of the `p_cfg` parameter.

```
typedef struct st_scif_uart
{
    uint32_t      baud_rate;           // ie 9600, 19200, 115200
    scif_clk_t    clk_src;
    scif_size_t   data_size;
    scif_parity_en_t parity_en;
    scif_parity_t parity_type;
    scif_stop_t   stop_bits;
    uint8_t       txif_priority;       // txif INT priority; 1=low, 15=high
    uint8_t       rxif_priority;       // rxif INT priority; 1=low, 15=high
    uint8_t       group_priority;      // teif, erif, brif INT priority;
                                        // must be greater than rx_priority
} scif_uart_t;
```

The configuration structure for Synchronous mode is as follows:

```
typedef struct st_scif_sync
{
    uint32_t    bit_rate;        // ie 1000000 for 1Mbps
    bool        msb_first;
    uint8_t     int_priority;    // transceiver interrupt priority; 1=low, 15=high
} scif_sync_t;
```

The union for p\_cfg is:

```
typedef union
{
    scif_uart_t    async;
    scif_sync_t    sync;
} scif_cfg_t;
```

### Return Values

<i>SCIF_SUCCESS:</i>	<i>Successful; channel initialized</i>
<i>SCIF_ERR_BAD_CHAN:</i>	<i>Channel number is invalid for part</i>
<i>SCIF_ERR_OMITTED_CHAN:</i>	<i>Corresponding SCIF_CHx_INCLUDED is 0</i>
<i>SCIF_ERR_CH_NOT_CLOSED:</i>	<i>Channel currently in operation; Perform R_SCIF_Close() first</i>
<i>SCIF_ERR_BAD_MODE:</i>	<i>Specified mode not currently supported</i>
<i>SCIF_ERR_NULL_PTR:</i>	<i>p_cfg or p_hdl pointer is NULL</i>
<i>SCIF_ERR_INVALID_ARG:</i>	<i>An element of the p_cfg structure contains an invalid value.</i>

### Properties

Prototyped in file "r\_scif\_rx\_if.h"

### Description

Initializes an SCIF channel for a particular mode and provides a handle in \*p\_hdl for use with other API functions. All applicable interrupts are enabled.

### Example: Asynchronous Mode

```
scif_cfg_t    config;
scif_hdl_t    Console;
scif_err_t    err;

config.async.baud_rate = 115200;
config.async.clk_src = SCIF_CLK_INT;    // use internal clock
config.async.data_size = SCIF_DATA_8BIT;
config.async.parity_en = SCIF_PARITY_OFF;
config.async.parity_type = SCIF_EVEN_PARITY; // ignored (parity is disabled)
config.async.stop_bits = SCIF_STOPBITS_1;
config.async.tx_priority = 2;
config.async.rx_priority = 2;
config.async.rx_err_priority = 3;        // must be higher than rx_priority

err = R_SCIF_Open(SCI_CH9, SCI_MODE_ASYNC, &config, MyCallback, &Console);
```

**Example: Synchronous Mode**

```

scif_cfg_t    config;
scif_hdl_t    syncHandle;
scif_err_t    err;

config.sync.bit_rate = 1000000;           // 1 Mbps
config.sync.msb_first = true;
config.sync.int_priority = 4;
err = R_SCIF_Open(SCI_CH8, SCI_MODE_SYNC, &config, syncCallback, &syncHandle);

```

**Special Notes:**

The driver uses an algorithm for calculating the optimum values for BRR, MDDR, SEMR.ABCS0, SEMR.BGDM and SMR.CKS using BSP\_PCLKA\_HZ as defined in mcu\_info.h of the board support package. This however does not guarantee a low bit error rate for all peripheral clock/ baud rate combinations.

The application must wait one bit-time after calling Open() before sending/receiving to allow the clock to settle.

If an external clock is used in Asynchronous mode, the Pin Function Select and port pins must be initialized first. The following is an example initialization for channel 9:

```

MPC.PB5PFS.BYTE = 0x0A; // Pin Func Select PB5 SCK9; clock as input
PORTB.PDR.BIT.B5 = 0; // set SCK pin direction to input (dflt)
PORTB.PMR.BIT.B5 = 1; // set SCK pin mode to peripheral

```

For initializing the clock in synchronous mode for channel 9:

```

MPC.PB5PFS.BYTE = 0x0A; // Pin Func Select PB5 SCK9; clock as output
PORTB.PDR.BIT.B5 = 1; // set SCK pin direction to output
PORTB.PMR.BIT.B5 = 1; // set SCK pin mode to peripheral

```

The callback function has a single argument. This is a pointer to a structure which is cast to a void pointer (provides consistency with other FIT module callback functions). The structure is as follows:

```

typedef struct st_scif_cb_args // callback arguments
{
    scif_hdl_t    hdl;
    scif_cb_evt_t event;
} scif_cb_args_t;

```

The "hdl" argument is the handle for the channel. The possible events passed are defined in the following enumeration:

```
typedef enum e_scif_cb_evt    // callback function events
{
    // Async Events
    SCIF_EVT_TX_DONE,        // Send() requests processed; last bit transmitted
    SCIF_EVT_RX_DONE,        // Receive() request processed;
                                // some or no data may be in RX FIFO
    SCIF_EVT_RX_BREAK,      // received BREAK condition
    SCIF_EVT_RX_OVERFLOW,   // receiver FIFO overrun error
    SCIF_EVT_RX_FRAMING_ERR, // received framing error
    SCIF_EVT_RX_PARITY_ERR,  // received parity error

    // Sync Events
    SCIF_EVT_XCV_DONE,      // All requests processed
    SCIF_EVT_XCV_ABORTED   // transfer aborted; FIFOs flushed
} scif_cb_evt_t;
```

The events SCIF\_EVT\_FRAMING\_ERR and SCIF\_EVT\_PARITY\_ERR indicate that the next byte to be read from the FIFO has an error. This byte is not passed to the callback function but is loaded into the receive buffer. This is so the bytes read from the FIFO will match the requested count. An example template for an Asynchronous mode callback function is provided here:

```
void MyCallback(void *p_args)
{
    scif_cb_args_t    *args;

    args = (scif_cb_args_t *)p_args;

    switch (args->event)
    {
    case SCIF_EVT_TX_DONE:
        // from TEIF interrupt; all data sent
        nop();
        break;

    case SCIF_EVT_RX_DONE:
        // from final RXIF interrupt; all requested bytes have been received
        // some or no data may be in RX FIFO
        nop();
        break;

    case SCIF_EVT_RX_BREAK:
        // from BRIF interrupt; received BREAK condition
        // error condition is cleared in BRIF routine
        nop();
        break;

    case SCIF_EVT_RX_OVERFLOW:
        // from BRIF interrupt; receiver overrun error occurred
        // error condition is cleared in BRIF routine
        nop();
        break;
    }
```

```
case SCIF_EVT_RX_FRAMING_ERR:
    // from ERIF interrupt; receiver framing error occurred
    // error condition is cleared in ERIF routine
    nop();
    break;

case SCIF_EVT_RX_PARITY_ERR:
    // from ERIF interrupt; receiver parity error occurred
    // error condition is cleared in ERIF routine
    nop();
    break;
};

}
```

An example template for a Synchronous mode callback function is provided here:

```
void syncCallback(void *p_args)
{
    scif_cb_args_t *args;

    args = (scif_cb_args_t *)p_args;

    if (args->event == SCIF_EVT_XCV_DONE)
    {
        // from TEIF interrupt; all data sent
        // data transfer request(s) completed
        nop();
    }
    else if (args->event == SCIF_EVT_XCV_ABORTED)
    {
        // data transfer aborted
        nop();
    }
}
```

---

### 3.2 R\_SCIF\_Close()

---

This function removes power to the SCIF channel and disables the associated interrupts.

#### Format

```
scif_err_t R_SCIF_Close(  
    scif_hdl_t const hdl  
);
```

#### Parameters

hdl  
Handle for channel

#### Return Values

<i>SCIF_SUCCESS:</i>	<i>Successful; channel closed</i>
<i>SCIF_ERR_NULL_PTR:</i>	<i>hdl is NULL</i>

#### Properties

Prototyped in file "r\_scif\_rx\_if.h"

#### Description

Disables the SCIF channel designated by the handle. Does not free any resources but saves power and allows the corresponding channel to be re-opened later, potentially with a different configuration.

#### Example

```
scif_hdl_t Console;  
  
err = R_SCIF_Open(SCI_CH9, SCI_MODE_ASYNC, &config, MyCallback, &Console);  
  
err = R_SCIF_Close(Console);
```

#### Special Notes:

This function will abort any transmission or reception that may be in progress.

---

### 3.3 R\_SCIF\_Send()

---

Queues up to two requests. Begins transmission if transmitter is not already in use.

#### Format

```
scif_err_t R_SCIF_Send(  
    scif_hdl_t const hdl,  
    uint8_t *p_src,  
    uint16_t const length  
);
```

#### Parameters

scif\_hdl\_t hdl  
Handle for channel

uint8\_t \*p\_src  
Pointer to data to transmit

uint16\_t length  
Number of bytes to send

#### Return Values

SCIF_SUCCESS:	Message queued for sending; transmission started if transmitter is idle.
SCIF_ERR_NULL_PTR:	hdl or p_src is NULL
SCIF_ERR_BAD_MODE:	Channel mode not currently supported
SCIF_ERR_INVALID_ARG:	length is 0
SCIF_ERR_BUSY:	Cannot process request. 2+ requests already placed

#### Properties

Prototyped in file "r\_scif\_rx\_if.h"

#### Description

If the driver can process the request, SCIF\_SUCCESS is returned. If there are already two requests outstanding, SCIF\_ERR\_BUSY is returned. If a message is longer than the FIFO size, the driver will automatically reload the FIFO at the interrupt level each time the threshold level (set in config.h) is reached.

When no more data remains to be transmitted, an SCIF\_EVT\_TX\_DONE (Async) or SCIF\_EVT\_XCV\_DONE (Sync) event is passed to the callback function if specified in Open(). If no callback function was provided, the application must poll for completion using a Control() command.

If it is desired to know when each message has completed transmission, do not have more than one Send() request outstanding at a time. This driver is optimized for streaming data and the "done" event is used to indicate transmit completion of all data.

**Example 1: Asynchronous Mode Blocking**

```

uint8_t    g_data_block[128];

scif_cfg_t  config;
scif_hdl_t  hdl;
scif_err_t  err;

err = R_SCIF_Open(SCI_CH9, SCI_MODE_ASYNC, &config, NULL, &hdl);
:

/* Check if transmitter available (and wait if necessary) to send message */
while (R_SCIF_Send(hdl, g_data_block, 128) == SCIF_ERR_TX_BUSY)
{
    /* wait until a send request can be queued */
}

/* Block for message to complete sending */
while (R_SCIF_Control(hdl, SCIF_CMD_CHECK_TX_DONE, NULL) == SCIF_ERR_IN_PROGRESS)
{
    /* do other processing if desired while waiting for send to complete */
}

```

**Example 2: Asynchronous Mode Non-Blocking**

```

uint8_t    g_data_block[128];

scif_cfg_t  config;
scif_hdl_t  hdl;
scif_err_t  err;

err = R_SCIF_Open(SCI_CH9, SCI_MODE_ASYNC, &config, MyCallback, &hdl);
:

/* if know 1 or no requests outstanding, can issue Send() immediately */
R_SCIF_Send(hdl, g_data_block, 128);

void MyCallback(void *p_args)
{
    scif_cb_args_t  *args;

    args = (scif_cb_args_t *)p_args;
    switch (args->event)
    {
        case SCIF_EVT_TX_DONE:
            // all data successfully sent
            break;

        case SCIF_EVT_RX_BREAK:
            // received break; handle error condition
            R_SCIF_Control(args->hdl, SCIF_CMD_RESET_TX, NULL);
            R_SCIF_Control(args->hdl, SCIF_CMD_RESET_RX, NULL);
            break;
    };
}

```

**Example 3: Synchronous Mode Blocking**

```

#define STRING    "Test String"

scif_cfg_t  config;
scif_hdl_t  lcdHandle;
scif_err_t  err;

err = R_SCIF_Open(SCI_CH8, SCI_MODE_SYNC, &config, NULL, &lcdHandle);
:

/* Check if transmitter available (and wait if necessary) to send message */
while (R_SCIF_Send(lcdHandle, STRING1, sizeof(STRING1)) == SCIF_ERR_BUSY)
{
    /* wait until a send request can be queued */
}

/* Block for message to complete sending */
while(R_SCIF_Control(lcdHandle,SCIF_CMD_CHECK_XCV_DONE,NULL) == SCIF_ERR_IN_PROGRESS)
{
    /* do other processing if desired while waiting for send to complete */
}

```

**Example 4: Synchronous Mode Non-Blocking**

```

#define STRING    "Test String"

scif_cfg_t  config;
scif_hdl_t  lcdHandle;
scif_err_t  err;

err = R_SCIF_Open(SCI_CH8, SCI_MODE_SYNC, &config, syncCallback, &lcdHandle);
:

/* if know 1 or no requests outstanding, can issue Send() immediately */
R_SCIF_Send(lcdHandle, STRING1, sizeof(STRING1));

void syncCallback(void *p_args)
{
    scif_cb_args_t  *args;

    args = (scif_cb_args_t *)p_args;

    if (args->event == SCIF_EVT_XCV_DONE)
    {
        // data transfer completed; do any processing here
        // nop();
    }
    else if (args->event == SCIF_EVT_XCV_ABORTED)
    {
        // data transfer aborted; do any processing here
    }
}

```

**Special Notes:**

In synchronous mode, the peripheral drives the clock for Send(), Receive(), and SendReceive() messages. In this mode, at most two transfer requests of any kind can ever be outstanding at a time. Therefore a SCIF\_ERR\_BUSY may be returned even when no Send() message was previously issued.

Do not re-use the same buffer pointed to by *p\_src* until it is known that the previous message the buffer was used for has completed transmission. Doing so could corrupt the data of the message currently being sent. This behavior is different than the standard SCI driver which copies the original buffer into a queue where it waited until it could be transmitted. For high throughput, this driver does not copy data into an intermediate queue and the hardware FIFO is the only temporary storage mechanism.

### 3.4 R\_SCIF\_Receive()

Queues up to two requests. Fetches data from the hardware FIFO. In Synchronous mode, initiates clocking of data if not already in use.

#### Format

```
scif_err_t R_SCIF_Receive(
    scif_hdl_t const    hdl,
    uint8_t            *p_dst,
    uint16_t const     length
);
```

#### Parameters

```
scif_hdl_t const    hdl
    Handle for channel

uint8_t            *p_dst
    Pointer to buffer to load data into

uint16_t const     length
    Number of bytes to read
```

#### Return Values

<i>SCIF_SUCCESS:</i>	<i>Request queued. Clocking begins (Sync) if transceiver idle</i>
<i>SCIF_ERR_NULL_PTR:</i>	<i>hdl value is NULL</i>
<i>SCIF_ERR_BAD_MODE:</i>	<i>Channel mode not currently supported</i>
<i>SCIF_ERR_INVALID_ARG:</i>	<i>length is 0</i>
<i>SCIF_ERR_BUSY:</i>	<i>Cannot process request. 2+ requests already placed</i>

#### Properties

Prototyped in file "r\_scif\_rx\_if.h"

#### Description

If the driver can process the request, SCIF\_SUCCESS is returned. If there are already two requests outstanding, SCIF\_ERR\_BUSY is returned. If a message is longer than the FIFO size, the driver will automatically read from the FIFO at the interrupt level each time the threshold level (set in config.h) is reached. If there is less than the threshold level bytes remaining the driver automatically adjusts the threshold level.

When no more data remains to be received, an SCIF\_EVT\_RX\_DONE (Async) or SCIF\_EVT\_XCV\_DONE (Sync) event is passed to the callback function if specified in Open(). If no callback function was provided, the application must poll for completion using a Control() command. Note that errors which occurred during reception are only reported via the callback function.

If it is desired to know when each message has completed reception, do not have more than one Receive() request outstanding at a time. This driver is optimized for streaming data and the "done" event is used to indicate receive completion of all requested data.

**Example 1: Asynchronous Blocking**

```

uint8_t    g_data_block[128];

scif_cfg_t  config;
scif_hdl_t  hdl;
scif_err_t  err;

err = R_SCIF_Open(SCI_CH9, SCI_MODE_ASYNC, &config, NULL, &hdl);
:

/* Check if receiver available (and wait if necessary) to receive message */
while (R_SCIF_Receive(hdl, g_data_block, 128) == SCIF_ERR_RX_BUSY)
{
    /* wait until a receive request can be queued */
}

/* Block for request to complete */
while (R_SCIF_Control(hdl, SCIF_CMD_CHECK_RX_DONE, NULL) == SCIF_ERR_IN_PROGRESS)
{
    /* do other processing if desired while waiting for receive to complete */
}

```

**Example 2: Asynchronous Non-Blocking**

```

uint8_t    g_data[8];

scif_cfg_t  config;
scif_hdl_t  hdl;
scif_err_t  err;

err = R_SCIF_Open(SCI_CH9, SCI_MODE_ASYNC, &config, MyCallback, &hdl);
:

/* Check if receiver available (and wait if necessary) to receive message.
 * Don't block for request to complete.
 */
while (R_SCIF_Receive(hdl, g_data, 8) == SCIF_ERR_RX_BUSY);
{
    /* wait until receive request can be queued */
}

/* An example of processing receive events */

void MyCallback(void *p_args)
{
    scif_cb_args_t  *args;
    static bool      err_flg=false;
    uint8_t          byte;

    args = (scif_cb_args_t *)p_args;
    switch (args->event)
    {
        case SCIF_EVT_RX_FRAMING_ERR:
        case SCIF_EVT_RX_PARITY_ERR:

```

```

        /* Continue to receive msg, but set flag to indicate error detected */
        err_flg = true;
        break;

    case SCIF_EVT_RX_OVERFLOW:
        /* Overrun occurred. Issue "abort" to sender and reset err_flg to start
         * fresh. Driver automatically resets FIFOs when break is generated.
         */
        R_SCIF_Control(args->hdl, SCIF_CMD_GENERATE_BREAK, NULL);
        err_flg = false;
        break;

    case SCIF_EVT_RX_BREAK:
        /* Received break. Reset transmitter, receiver, and err_flg.
         */
        R_SCIF_Control(args->hdl, SCIF_CMD_RESET_TX, NULL);
        R_SCIF_Control(args->hdl, SCIF_CMD_RESET_RX, NULL);
        err_flg = false;
        break;

    case SCIF_EVT_RX_DONE:
        /* Done receiving message. Issue ACK or NAK based upon err_flg. */
        byte = (err_flg == true) ? NAK : ACK;
        R_SCIF_Send(hdl, &byte, 1);
        err_flg = false;
        break;
};
}

```

### Example 3: Synchronous Mode Blocking

```

uint8_t    g_block[2][128];

scif_cfg_t  config;
scif_hdl_t  hdl;
scif_err_t  err;

err = R_SCIF_Open(SCI_CH9, SCI_MODE_SYNC, &config, NULL, &hdl);
:

/* Issue two Receive() calls and wait for completion */
while (R_SCIF_Receive(hdl, &g_data_block[0], 128) == SCIF_ERR_XCV_BUSY)
{
    /* wait until receive request can be queued */
}

while (R_SCIF_Receive(hdl, &g_data_block[1], 128) == SCIF_ERR_XCV_BUSY)
{
    /* wait until receive request can be queued */
}

// (could replace above requests with single request for 256 with first address)

while (R_SCIF_Control(hdl, SCIF_CMD_CHECK_XCV_DONE, NULL) == SCIF_ERR_IN_PROGRESS)
{
    /* do other processing if desired while waiting for receive to complete */
}

```

**Example 4: Synchronous Mode Non-Blocking**

```
uint8_t    sensor_cmd, sync_buf[10];
scif_cfg_t config;
scif_hdl_t hdl;
scif_err_t err;

err = R_SCIF_Open(SCI_CH9, SCI_MODE_SYNC, &config, syncCallback, &hdl);

/* SEND COMMAND TO SENSOR TO PROVIDE CURRENT READING AND GET DATA */

sensor_cmd = SNS_CMD_READ_LEVEL;

/* FIFOs known to be empty here; can have two outstanding msg requests */
R_SCIF_Send(hdl, &sensor_cmd, 1);
R_SCIF_Receive(hdl, sync_buf, 4);

/* do not wait for reply */
```

**Special Notes:**

In synchronous mode, the peripheral drives the clock for Send(), Receive(), and SendReceive() messages. In this mode, at most two transfer requests of any kind can ever be outstanding at a time. Therefore a SCIF\_ERR\_BUSY may be returned even when no Receive() message was previously issued.

Do not re-use the same buffer pointed to by p\_dst until it is known that the previous message the buffer was used for has been processed. Doing so could corrupt the data of the message previously received.

### 3.5 R\_SCIF\_SendReceive()

For Synchronous mode only. Transmits and receives data simultaneously.

#### Format

```
scif_err_t R_SCIF_SendReceive(
    scif_hdl_t const    hdl,
    uint8_t             *p_src,
    uint8_t             *p_dst,
    uint16_t const     length
);
```

#### Parameters

scif\_hdl\_t const hdl  
Handle for channel

uint8\_t \*p\_src  
Pointer to data to transmit

uint8\_t \*p\_dst  
Pointer to buffer to load data into

uint16\_t length  
Number of bytes to send

#### Return Values

<i>SCIF_SUCCESS:</i>	<i>Data transfer queued and initiated if transceiver idle</i>
<i>SCIF_ERR_NULL_PTR:</i>	<i>hdl value is NULL</i>
<i>SCIF_ERR_BAD_MODE:</i>	<i>Channel mode not Synchronous</i>
<i>SCIF_ERR_INVALID_ARG:</i>	<i>length is 0</i>
<i>SCIF_ERR_BUSY:</i>	<i>Cannot process request. 2+ requests already placed</i>

#### Properties

Prototyped in file "r\_scif\_rx\_if.h"

#### Description

This function transmits and receives data simultaneously if the transceiver is not in use. If the driver can process the request, SCIF\_SUCCESS is returned. If there are already two requests outstanding, SCIF\_ERR\_BUSY is returned. If a message is longer than the FIFO size, the driver will automatically process the FIFO at the interrupt level each time the threshold level (set in config.h) is reached.

When no more data remains to be transmitted and received, an SCIF\_EVT\_XCV\_DONE event is passed to the callback function if specified in Open(). If no callback function was provided, the application must poll for completion using a Control() command.

If it is desired to know when each message has completed transmission/reception, do not have more than one SendReceive() request outstanding at a time. This driver is optimized for streaming data and the "done" event is used to indicate transmit/receive completion of all data.

**Example: Blocking**

```
scif_hdl_t  hdl;
scif_err_t  err;
uint8_t     out_buf[2] = {SF_CMD_READ_STATUS_REG, SCIF_CFG_DUMMY_TX_BYTE };
uint8_t     in_buf[2] = {0x55, 0x55};    // init to illegal values
:

/* Clock two bytes of data. The first byte is a command out (ignore byte in)
 * and the second byte is a response in (dummy byte clocked out)
 */

/* FIFOs known to be empty here */
R_SCIF_SendReceive(hdl, out_buf, in_buf, 2);

while (R_SCIF_Control(hdl, SCI_CMD_CHECK_XCV_DONE, NULL) == SCIF_ERR_BUSY)
{
    /* wait for completion */
}

// reply is in in_buf[1]
```

**Special Notes:**

In synchronous mode, the peripheral drives the clock for Send(), Receive(), and SendReceive() messages. In this mode, at most two transfer requests of any kind can ever be outstanding at a time. Therefore a SCIF\_ERR\_BUSY may be returned even when no SendReceive() message was previously issued.

Do not re-use the same buffers pointed to by *p\_dst* and *p\_dst* until it is known that the previous message the buffer was used for has been processed. Doing so could corrupt the data of the message previously received.

### 3.6 R\_SCIF\_Control()

This function handles special hardware and software operations for the SCIF channel.

#### Format

```
scif_err_t R_SCIF_Control(
    scif_hdl_t const hdl,
    scif_cmd_t const cmd,
    void *p_args
);
```

#### Parameters

```
scif_hdl_t const hdl
    Handle for channel

scif_cmd_t const cmd
    Command to run (see enumeration below)

void *p_args
    Pointer to arguments (see below) specific to command, casted to void *
```

The valid *cmd* values are as follows:

```
typedef enum e_scif_cmd // SCIF Control() commands
{
    // Both modes
    SCIF_CMD_CHANGE_BAUD, // change baud/bit rate

    // Async commands
    SCIF_CMD_EN_FLOW_CTRL, // enable CTS/RTS flow control
    SCIF_CMD_EN_NOISE_CANCEL, // enable noise cancellation
    SCIF_CMD_EN_MSB_FIRST, // transmit/receive MSB first
    SCIF_CMD_GENERATE_BREAK, // generate break condition; resets FIFOs
    SCIF_CMD_TX_BYTES_REMAINING, // number total bytes yet to transmit
    SCIF_CMD_RX_BYTES_PENDING, // number bytes yet to receive
    SCIF_CMD_CHECK_TX_DONE, // see if tx requests complete; SCIF_SUCCESS if yes
    SCIF_CMD_CHECK_RX_DONE, // see if rx request complete; SCIF_SUCCESS if yes
    SCIF_CMD_RESET_TX, // abort transmit requests; reset transmit FIFO
    SCIF_CMD_RESET_RX, // abort receive requests; reset receive FIFO

    // Sync commands
    SCIF_CMD_CHECK_XCV_DONE, // see if Send, Receive, or SendReceive
    // requests are done; SCIF_SUCCESS if yes
    SCIF_CMD_RESET_XCV // abort transfer requests; reset FIFOs
} scif_cmd_t;
```

Most of the commands do not require arguments and take NULL or FIT\_NO\_PTR for *p\_args*. The argument structure for SCIF\_CMD\_CHANGE\_BAUD is shown below. Note that this command may not be used for Asynchronous mode when using an external clock.

```
typedef struct _sci_baud
{
    uint32_t pclk; // PCLKA speed; ie 120000000 (120 MHz)
    uint32_t rate; // ie 9600, 19200, 115200
} sci_baud_t;
```

The argument for `SCIF_CMD_TX_BYTES_REMAINING` and `SCIF_CMD_RX_BYTES_PENDING` is a pointer to a `uint16_t` variable to hold a count value.

The commands `SCIF_CMD_CHECK_TX_DONE`, `SCIF_CMD_CHECK_RX_DONE`, and `SCIF_CMD_CHECK_XCV_DONE` return `SCIF_SUCCESS` when all requests have been transmitted. Otherwise `SCIF_ERR_IN_PROGRESS` is returned.

Note: For `SCIF_CMD_RESET_TX`, if a message transmission is in progress it will be abort immediately. It will not wait until the current byte completes transmission. In this case, it is recommended to wait 1 byte-time before sending again to allow receiver to process likely framing error from last [partial] byte sent.

### Return Values

<code>SCIF_SUCCESS:</code>	<i>Successful; channel initialized</i>
<code>SCIF_ERR_NULL_PTR:</code>	<i>hdl or p_args pointer is NULL (when required)</i>
<code>SCIF_ERR_BAD_MODE:</code>	<i>Channel mode not currently supported</i>
<code>SCIF_ERR_INVALID_ARG:</code>	<i>The cmd value or an element of p_args contains an invalid value.</i>

### Properties

Prototyped in file "r\_scif\_rx\_if.h"

### Description

This function is used for configuring "non-standard" hardware features, changing driver configuration, and obtaining driver status.

### Example 1: Asynchronous

```

scif_hdl_t   Console;
scif_cfg_t   config;
scif_baud_t  baud;
scif_err_t   err;
uint16_t     cnt;
:
R_SCIF_Open(SCI_CH9, SCIF_MODE_ASYNC, &config, MyCallback, &Console);
R_SCIF_Control(Console, SCIF_CMD_EN_NOISE_CANCEL, NULL);
R_SCIF_Control(Console, SCIF_CMD_EN_MSB_FIRST, NULL);
:
/* reset baud rate due to low power mode clock switching */
baud.pclk = 8000000;    // 8MHz
baud.rate = 19200;
R_SCIF_Control(Console, SCIF_CMD_CHANGE_BAUD, &baud);
:
/* after initiating a large transmit, see how many bytes remaining to send */
R_SCIF_Control(Console, SCIF_CMD_TX_BYTES_REMAINING, &cnt);
// for progress bar: (message size - cnt)/(message size) = % complete
:
/* after initiating a large receive, see how many bytes left to receive */
R_SCIF_Control(Console, SCIF_CMD_RX_BYTES_PENDING, &cnt);
// for progress bar: (request size - cnt)/(request size) = % complete
:

```

**Example 2: Synchronous**

```

scif_cfg_t   config;
scif_hdl_t   syncHandle;
scif_err_t   err;

config.sync.bit_rate = 1000000;           // 1 Mbps
config.sync.msb_first = true;
config.sync.int_priority = 4;
err = R_SCIF_Open(SCI_CH8, SCI_MODE_SYNC, &config, syncCallback, &syncHandle);
:

// after starting a large message transfer, abort transfer
R_SCIF_Control(syncHandle, SCIF_CMD_RESET_XCV, NULL);

```

**Special Notes:**

Do not use the value loaded by SCIF\_CMD\_TX\_BYTES\_REMAINING to determine if a message is sent. There still may be bits in the shift register when this commands return a "0". Use SCIF\_CMD\_TX\_DONE for this purpose.

Wait one bit-time after performing a SCIF\_CMD\_CHANGE\_BAUD for the clock to settle at the new speed. The bit time should be measured in terms of the slower bit rate.

Wait two bit-times after performing a SCIF\_CMD\_GENERATE\_BREAK before resuming communications. Any Send() or Receive() calls made during this will get a SCIF\_ERR\_BUSY until the break completes. A break condition lasts 1.5 to 2.0 byte times.

The driver uses an algorithm for calculating the optimum values for BRR, MDDR, SEMR.ABCS0, SEMR.BGDM, SEMR.BRME, SEMR.MDDRS and SMR.CKS. This however does not guarantee a low bit error rate for all peripheral clock/ baud rate combinations.

If the command SCIF\_CMD\_EN\_FLOW\_CTRL is to be used, the Pin Function Select and port pins must be configured first. The following is an example initialization for channel 9:

```

MPC.PB4PFS.BYTE = 0x0B; // Pin Func Select PB4 CTS
PORTB.PDR.BIT.B4 = 0; // set CTS pin direction to input
PORTB.PMR.BIT.B4 = 1; // set CTS pin mode to peripheral

MPC.PB5PFS.BYTE = 0x0B; // Pin Func Select PB5 RTS
PORTB.PDR.BIT.B5 = 1; // set RTS pin direction to output
PORTB.PMR.BIT.B5 = 1; // set RTS pin mode to peripheral

```

---

### 3.7 R\_SCIF\_GetVersion()

---

This function returns the driver version number at runtime.

#### Format

```
uint32_t R_SCIF_GetVersion(  
    void  
);
```

#### Parameters

None

#### Return Values

Version number.

#### Properties

Prototyped in file "r\_scif\_rx\_if.h"

#### Description

Returns the version of this module. The version number is encoded such that the top two bytes are the major version number and the bottom two bytes are the minor version number.

#### Example

```
uint32_t version;  
:  
version = R_SCIF_GetVersion();
```

#### Special Notes:

None

#### 4. Pin Setting

In order to use the SCI FIFO FIT module, it is necessary to allocate the input/output signals of peripheral functions to the pins with the Multi-function Pin Controller (MPC).

Please configure the pins before calling the R\_SCIF\_Open function.

When using e<sup>2</sup> studio, the pin setting function of "FIT Configurator" or "Smart Configurator" can be used. When these functions are used, the source file is output according to the option selected in the Pin Setting window. Then pins are configured by calling the function defined in the output source file.

**Table 4.1 List of Functions Output by FIT Configurator**

MCU	Selected Option	Output Function Name	Remarks
RX64M	SCIF8	R_SCIF_PinSet_SCIF8()	When using SCIF8
RX71M	SCIF9	R_SCIF_PinSet_SCIF9()	When using SCIF9
	SCIF10	R_SCIF_PinSet_SCIF10()	When using SCIF10
	SCIF11	R_SCIF_PinSet_SCIF11()	When using SCIF11

## 5. Demo Projects

Demo projects are complete stand-alone programs. They include function main() that utilizes the module and its dependent modules (e.g.. r\_bsp).

### 5.1 Adding the Demo to a Workspace

Demo projects are found in the FITDemos subdirectory of the distribution file for this application note. To add a demo project to a workspace, select File>Import>General>Existing Projects into Workspace, then click "Next". From the Import Projects dialog, choose the "Select archive file" radio button. "Browse" to the FITDemos subdirectory, select the desired demo zip file, then click "Finish".

### 5.2 Downloading Demo Projects

Demo projects are not included in the RX Driver Package. When using the demo project, the FIT module needs to be downloaded. To download the FIT module, right click on the required application note and select "Sample Code (download)" from the context menu in the Smart Brower >> Application Notes tab.

### 5.3 Demo for RX64M (scif\_demo\_rskrx64m)

This is a simple demo of the SCIF API (`r_scif_rx`) which communicates with a terminal over SCIF channel 8 connected to the USB Virtual COM port. The user is first prompted at the terminal to enter a character, at which point the SCIF module version is transmitted to the terminal over the SCIF channel.

The demo then enters a continuous loop waiting for a character to be entered and then transmitting two 160 byte buffers of char data. When the data has been sent a summary of the number of bytes sent and number of TXIF interrupts required to transmit the data is sent/displayed at the terminal.

This demonstrates how the `SCIF_CFG_CHx_TX_FIFO_THRESHOLD` configuration value in `r_scif_r_config.h` affects the number of interrupts required to process all 320 bytes of data using the SCIF Tx FIFO.

#### Boards Supported

- RSKRX64M

#### Setup and Execution

1. Ensure driver support for channel 8 is enabled in `r_scif_rx_config.h`:

```
#define SCIF_CFG_CH8_INCLUDED (1)
```

2. Prepare the RSKRX64M board:

- Jumpers J12, J14, J16 and J18: OFF
- Connect J12 pin 2 to J16 pin 3 using a jumper wire
- Connect J14 pin 2 to J18 pin 3 using a jumper wire

This connects the CH8 Tx/Rx signals to the virtual COM USB Tx/Rx signals.

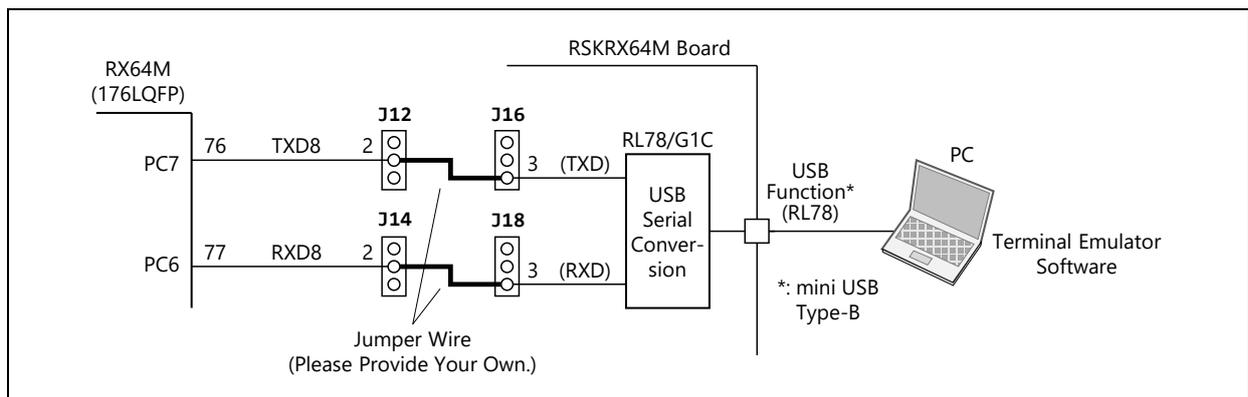


Figure 5.1 Jumper Setting for RSKRX64M Board (Overview)

3. Connect the RSK board serial port to a PC serial port. For this demo the RSKRX64M serial to USB Virtual COM Interface is used. In this case, connect the USB port to a PC with the Renesas USB-serial device driver installed. The USB will enumerate on the PC as a virtual COM port. Note the COM port number.
4. Open a terminal emulation program on the PC, such as "Tera Term", and select the serial COM port assigned to the Virtual COM Interface. Configure the terminal serial settings to match the settings in this sample application:
  - 115200 baud
  - 8-bit data
  - no parity
  - 1 stop bit
  - no flow control
5. Build and download this sample application to the RSK board. Run the application with the debugger.
6. A prompt to "Enter a char>" should now be seen at the terminal indicating that the demo is running.

## 5.4 Demo for RX71M (scif\_demo\_rskrx71m)

This is a simple demo of the SCIF API (`r_scif_rx`) which communicates with a terminal over SCIF channel 8 connected to the USB Virtual COM port. The user is first prompted at the terminal to enter a character, at which point the SCIF module version is transmitted to the terminal over the SCIF channel.

The demo then enters a continuous loop waiting for a character to be entered and then transmitting two 160 byte buffers of char data. When the data has been sent a summary of the number of bytes sent and number of TXIF interrupts required to transmit the data is sent/displayed at the terminal.

This demonstrates how the `SCIF_CFG_CHx_TX_FIFO_THRESHOLD` configuration value in `r_scif_r_config.h` affects the number of interrupts required to process all 320 bytes of data using the SCIF Tx FIFO.

### Boards Supported

- RSKRX71M

### Setup and Execution

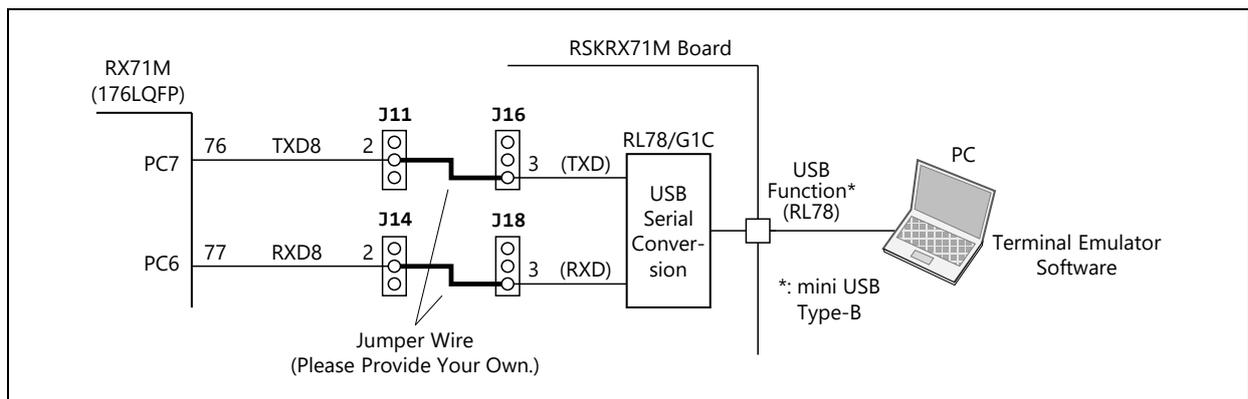
1. Ensure driver support for channel 8 is enabled in `r_scif_rx_config.h`:

```
#define SCIF_CFG_CH8_INCLUDED (1)
```

2. Prepare the RSKRX71M board:

- Jumpers J11, J14, J16 and J18: OFF
- Connect J11 pin 2 to J16 pin 3 using a jumper wire
- Connect J14 pin 2 to J18 pin 3 using a jumper wire

This connects the CH8 Tx/Rx signals to the virtual COM USB Tx/Rx signals.



**Figure 5.2 Jumper Setting for RSKRX71M Board (Overview)**

3. Connect the RSK board serial port to a PC serial port. For this demo the RSKRX71M serial to USB Virtual COM Interface is used. In this case, connect the USB port to a PC with the Renesas USB-serial device driver installed. The USB will enumerate on the PC as a virtual COM port. Note the COM port number.
4. Open a terminal emulation program on the PC, such as "Tera Term", and select the serial COM port assigned to the Virtual COM Interface. Configure the terminal serial settings to match the settings in this sample application:
  - 115200 baud
  - 8-bit data
  - no parity
  - 1 stop bit
  - no flow control
5. Build and download this sample application to the RSK board. Run the application with the debugger.
6. A prompt to "Enter a char>" should now be seen at the terminal indicating that the demo is running.

## 6. Appendix

### 6.1 Operating Test Environment

This section describes for detailed the operating test environments of this module.

**Table 6.1 Operation Confirmation Environment for Rev.1.21**

Item	Contents
Integrated development environment	Renesas Electronics e <sup>2</sup> studio Version 7.1.0
C compiler	Renesas Electronics C/C++ Compiler Package for RX Family V3.00.00 Compiler option: The following option is added to the default settings of the integrated development environment. -lang = c99
Endian	Big endian/little endian
Revision of the module	Rev.1.21

**Table 6.2 Operation Confirmation Environment for Rev.1.22.**

Item	Contents
Integrated development environment	Renesas Electronics e <sup>2</sup> studio Version 7.3.0
C compiler	Renesas Electronics C/C++ Compiler Package for RX Family V3.01.00 Compiler option: The following option is added to the default settings of the integrated development environment. -lang = c99
Endian	Big endian/little endian
Revision of the module	Rev.1.22

**Table 6.3 Confirmed Operation Environment for Rev. 2.00**

Item	Contents
Integrated development environment	Renesas Electronics e <sup>2</sup> studio Version 7.6.0 IAR Embedded Workbench for Renesas RX 4.12.1
C compiler	Renesas Electronics C/C++ Compiler Package for RX Family V3.01.00 Compiler option: The following option is added to the default settings of the integrated development environment. -lang = c99
	GCC for Renesas RX 8.3.0.201904 Compiler option: The following option is added to the default settings of the integrated development environment. -std=gnu99
	IAR C/C++ Compiler for Renesas RX version 4.12.1 Compiler option: The default settings of the integrated development environment.
Endian	Big endian/little endian
Revision of the module	Rev.2.00
Board used	Renesas Starter Kit+ for RX64M (product No.: R0K50564Mxxxxxx) Renesas Starter Kit+ for RX71M (product No.: R0K50571Mxxxxxx)

Table 6.4 Confirmed Operation Environment for Rev. 2.01

Item	Contents
Integrated development environment	Renesas Electronics e <sup>2</sup> studio Version 2020-10 (20.10.0)
C compiler	Renesas Electronics C/C++ Compiler Package for RX Family V3.02.00 Compiler option: The following option is added to the default settings of the integrated development environment. -lang = c99
Endian	Big endian/little endian
Revision of the module	Rev.2.01
Board used	Renesas Starter Kit+ for RX64M (product No.: R0K50564Mxxxxxx) Renesas Starter Kit+ for RX71M (product No.: R0K50571Mxxxxxx)

## 6.2 Troubleshooting

- (1) Q: I have added the FIT module to the project and built it.  
Then I got the error: Could not open source file "platform.h".
- A: The FIT module may not be added to the project properly. Check if the method for adding FIT modules is correct with the following documents:
- When using CS+:  
Application note "Adding Firmware Integration Technology Modules to CS+ Projects (R01AN1826)"
  - When using e<sup>2</sup> studio:  
Application note "Adding Firmware Integration Technology Modules to Projects (R01AN1723)"
- When using a FIT module, the board support package FIT module (BSP module) must also be added to the project. For this, refer to the application note "Board Support Package Module Using Firmware Integration Technology (R01AN1685)".
- (2) Q: I have added the FIT module to the project and built it.  
Then I got the error: This MCU is not supported by the current r\_sci\_iic\_rx module.
- A: The FIT module you added may not support the target device chosen in the user project. Check if the FIT module supports the target device for the project used.
- (3) Q: I have added the FIT module to the project and built it.  
Then I got an error for when the configuration setting is wrong.
- A: The setting in the file "r\_scif\_rx\_config.h" may be wrong. Check the file "r\_scif\_rx\_config.h". If there is a wrong setting, set the correct value for that. Refer to Section 2.8 "Configuration Overview" for details.
- (4) Q: Serial communication does not work.
- A: The terminal settings may not have been made correctly. Terminal settings are required when using this FIT module. For details, refer to Section 2.8 "Configuration Overview".

## Revision History

Rev.	Date	Description			
		Page	Summary		
1.00	Aug. 31, 14	—	Initial Release.		
1.10	Mar. 19, 15	1,3,27,28	Added support for RX71M and RX64M/RX71M demos		
1.20	Mar. 16, 17	—	Fixed bug that caused extra clocks to be sent at high speeds in SYNC mode.		
1.21	Dec. 07, 18	1	Related Documents: Added the following document: "Renesas e <sup>2</sup> studio Smart Configurator User Guide (R20AN0451)"		
		4	2.3 Software Requirements: Revised. 2.4 Limitations: Deleted.		
		5	2.5 Interrupt Vector: Added.		
		8	2.11. Adding the FIT Module to Your Project: Revised.		
		29	4. Demo Projects: Revised.		
		30	4.4 Downloading Demo Projects: Added.		
		31	5.1. Confirmed Operation Environment: Added. 5.2. Troubleshooting: Added.		
		32	Related Technical Updates: Added.		
		Program	Added document number of the application note accompanying the sample program of the FIT module to xml file.		
		1.22	Apr. 01, 19	—	Changes associated with functions: Added support setting function of configuration option Using GUI on Smart Configurator. [Description] Added a setting file to support configuration option setting function by GUI.
1	Changed Introduction.				
4	Added 1.1 SCIF FIT Module.				
5	Moved 1.3 API Overview.				
6	Changed 2 API Information.				
8	Changed 2.6 Header Files. Changed 2.7 Integer Types. Changed 2.8 Configuration Overview.				
9	Changed 2.9 Code Size.				
10	Changed 2.10 Parameters. Changed 2.11 Return Values. Added 2.12 Callback Function.				
11	Changed 2.13 Adding the FIT Module to Your Project.				
12	Added 2.14 "for", "while" and "do while" statements.				
36	Added 4. Pin Setting.				
37	6.1 Operation Confirmation Environment: Added table for Rev.1.22.				
2.00	Nov. 01, 19			—	Supported the following compilers. - GCC for Renesas RX - IAR C/C++ Compiler for Renesas RX
				—	Updated Demo Projects.
		1	Fixed Related Documents.		
		9	Updated 2.9 Code Size.		

Rev.	Date	Description	
		Page	Summary
		14	Added 2.15 Limitations.
		39	6.1 Operation Confirmation Environment: Added table for Rev.2.00.
		Program	Guarantee atomicity in the critical section of the following register control. - Module Stop Control (MSTPCR) - Interrupt Request Enable Control (IEN) - Group Interrupt Request Enable (GENBL)
2.01	Nov. 30, 20	—	Updated the sample code project due to the upgrade of the development environment.
		36	Moved the "Pin Setting" chapter to Chapter 4 to make it the same as the Japanese version.
		39	In the RSKRX71M board settings, J12 was corrected to J11 (due to a typo).

# General Precautions in the Handling of Microprocessing Unit and Microcontroller Unit Products

The following usage notes are applicable to all Microprocessing unit and Microcontroller unit products from Renesas. For detailed usage notes on the products covered by this document, refer to the relevant sections of the document as well as any technical updates that have been issued for the products.

## 1. Precaution against Electrostatic Discharge (ESD)

A strong electrical field, when exposed to a CMOS device, can cause destruction of the gate oxide and ultimately degrade the device operation. Steps must be taken to stop the generation of static electricity as much as possible, and quickly dissipate it when it occurs. Environmental control must be adequate. When it is dry, a humidifier should be used. This is recommended to avoid using insulators that can easily build up static electricity.

Semiconductor devices must be stored and transported in an anti-static container, static shielding bag or conductive material. All test and measurement tools including work benches and floors must be grounded. The operator must also be grounded using a wrist strap. Semiconductor devices must not be touched with bare hands. Similar precautions must be taken for printed circuit boards with mounted semiconductor devices.

## 2. Processing at power-on

The state of the product is undefined at the time when power is supplied. The states of internal circuits in the LSI are indeterminate and the states of register settings and pins are undefined at the time when power is supplied. In a finished product where the reset signal is applied to the external reset pin, the states of pins are not guaranteed from the time when power is supplied until the reset process is completed. In a similar way, the states of pins in a product that is reset by an on-chip power-on reset function are not guaranteed from the time when power is supplied until the power reaches the level at which resetting is specified.

## 3. Input of signal during power-off state

Do not input signals or an I/O pull-up power supply while the device is powered off. The current injection that results from input of such a signal or I/O pull-up power supply may cause malfunction and the abnormal current that passes in the device at this time may cause degradation of internal elements. Follow the guideline for input signal during power-off state as described in your product documentation.

## 4. Handling of unused pins

Handle unused pins in accordance with the directions given under handling of unused pins in the manual. The input pins of CMOS products are generally in the high-impedance state. In operation with an unused pin in the open-circuit state, extra electromagnetic noise is induced in the vicinity of the LSI, an associated shoot-through current flows internally, and malfunctions occur due to the false recognition of the pin state as an input signal become possible.

## 5. Clock signals

After applying a reset, only release the reset line after the operating clock signal becomes stable. When switching the clock signal during program execution, wait until the target clock signal is stabilized. When the clock signal is generated with an external resonator or from an external oscillator during a reset, ensure that the reset line is only released after full stabilization of the clock signal. Additionally, when switching to a clock signal produced with an external resonator or by an external oscillator while program execution is in progress, wait until the target clock signal is stable.

## 6. Voltage application waveform at input pin

Waveform distortion due to input noise or a reflected wave may cause malfunction. If the input of the CMOS device stays in the area between  $V_{IL}$  (Max.) and  $V_{IH}$  (Min.) due to noise, for example, the device may malfunction. Take care to prevent chattering noise from entering the device when the input level is fixed, and also in the transition period when the input level passes through the area between  $V_{IL}$  (Max.) and  $V_{IH}$  (Min.).

## 7. Prohibition of access to reserved addresses

Access to reserved addresses is prohibited. The reserved addresses are provided for possible future expansion of functions. Do not access these addresses as the correct operation of the LSI is not guaranteed.

## 8. Differences between products

Before changing from one product to another, for example to a product with a different part number, confirm that the change will not lead to problems. The characteristics of a microprocessing unit or microcontroller unit products in the same group but having a different part number might differ in terms of internal memory capacity, layout pattern, and other factors, which can affect the ranges of electrical characteristics, such as characteristic values, operating margins, immunity to noise, and amount of radiated noise. When changing to a product with a different part number, implement a system-evaluation test for the given product.

## Notice

1. Descriptions of circuits, software and other related information in this document are provided only to illustrate the operation of semiconductor products and application examples. You are fully responsible for the incorporation or any other use of the circuits, software, and information in the design of your product or system. Renesas Electronics disclaims any and all liability for any losses and damages incurred by you or third parties arising from the use of these circuits, software, or information.
  2. Renesas Electronics hereby expressly disclaims any warranties against and liability for infringement or any other claims involving patents, copyrights, or other intellectual property rights of third parties, by or arising from the use of Renesas Electronics products or technical information described in this document, including but not limited to, the product data, drawings, charts, programs, algorithms, and application examples.
  3. No license, express, implied or otherwise, is granted hereby under any patents, copyrights or other intellectual property rights of Renesas Electronics or others.
  4. You shall not alter, modify, copy, or reverse engineer any Renesas Electronics product, whether in whole or in part. Renesas Electronics disclaims any and all liability for any losses or damages incurred by you or third parties arising from such alteration, modification, copying or reverse engineering.
  5. Renesas Electronics products are classified according to the following two quality grades: "Standard" and "High Quality". The intended applications for each Renesas Electronics product depends on the product's quality grade, as indicated below.
    - "Standard": Computers; office equipment; communications equipment; test and measurement equipment; audio and visual equipment; home electronic appliances; machine tools; personal electronic equipment; industrial robots; etc.
    - "High Quality": Transportation equipment (automobiles, trains, ships, etc.); traffic control (traffic lights); large-scale communication equipment; key financial terminal systems; safety control equipment; etc.
- Unless expressly designated as a high reliability product or a product for harsh environments in a Renesas Electronics data sheet or other Renesas Electronics document, Renesas Electronics products are not intended or authorized for use in products or systems that may pose a direct threat to human life or bodily injury (artificial life support devices or systems; surgical implantations; etc.), or may cause serious property damage (space system; undersea repeaters; nuclear power control systems; aircraft control systems; key plant systems; military equipment; etc.). Renesas Electronics disclaims any and all liability for any damages or losses incurred by you or any third parties arising from the use of any Renesas Electronics product that is inconsistent with any Renesas Electronics data sheet, user's manual or other Renesas Electronics document.
6. When using Renesas Electronics products, refer to the latest product information (data sheets, user's manuals, application notes, "General Notes for Handling and Using Semiconductor Devices" in the reliability handbook, etc.), and ensure that usage conditions are within the ranges specified by Renesas Electronics with respect to maximum ratings, operating power supply voltage range, heat dissipation characteristics, installation, etc. Renesas Electronics disclaims any and all liability for any malfunctions, failure or accident arising out of the use of Renesas Electronics products outside of such specified ranges.
  7. Although Renesas Electronics endeavors to improve the quality and reliability of Renesas Electronics products, semiconductor products have specific characteristics, such as the occurrence of failure at a certain rate and malfunctions under certain use conditions. Unless designated as a high reliability product or a product for harsh environments in a Renesas Electronics data sheet or other Renesas Electronics document, Renesas Electronics products are not subject to radiation resistance design. You are responsible for implementing safety measures to guard against the possibility of bodily injury, injury or damage caused by fire, and/or danger to the public in the event of a failure or malfunction of Renesas Electronics products, such as safety design for hardware and software, including but not limited to redundancy, fire control and malfunction prevention, appropriate treatment for aging degradation or any other appropriate measures. Because the evaluation of microcomputer software alone is very difficult and impractical, you are responsible for evaluating the safety of the final products or systems manufactured by you.
  8. Please contact a Renesas Electronics sales office for details as to environmental matters such as the environmental compatibility of each Renesas Electronics product. You are responsible for carefully and sufficiently investigating applicable laws and regulations that regulate the inclusion or use of controlled substances, including without limitation, the EU RoHS Directive, and using Renesas Electronics products in compliance with all these applicable laws and regulations. Renesas Electronics disclaims any and all liability for damages or losses occurring as a result of your noncompliance with applicable laws and regulations.
  9. Renesas Electronics products and technologies shall not be used for or incorporated into any products or systems whose manufacture, use, or sale is prohibited under any applicable domestic or foreign laws or regulations. You shall comply with any applicable export control laws and regulations promulgated and administered by the governments of any countries asserting jurisdiction over the parties or transactions.
  10. It is the responsibility of the buyer or distributor of Renesas Electronics products, or any other party who distributes, disposes of, or otherwise sells or transfers the product to a third party, to notify such third party in advance of the contents and conditions set forth in this document.
  11. This document shall not be reprinted, reproduced or duplicated in any form, in whole or in part, without prior written consent of Renesas Electronics.
  12. Please contact a Renesas Electronics sales office if you have any questions regarding the information contained in this document or Renesas Electronics products.

(Note1) "Renesas Electronics" as used in this document means Renesas Electronics Corporation and also includes its directly or indirectly controlled subsidiaries.

(Note2) "Renesas Electronics product(s)" means any product developed or manufactured by or for Renesas Electronics.

(Rev.4.0-1 November 2017)

## Corporate Headquarters

TOYOSU FORESIA, 3-2-24 Toyosu,  
Koto-ku, Tokyo 135-0061, Japan  
[www.renesas.com](http://www.renesas.com)

## Trademarks

Renesas and the Renesas logo are trademarks of Renesas Electronics Corporation. All trademarks and registered trademarks are the property of their respective owners.

## Contact information

For further information on a product, technology, the most up-to-date version of a document, or your nearest sales office, please visit:  
[www.renesas.com/contact/](http://www.renesas.com/contact/).