
RX64M, RX71M Group

R01AN2608EJ0103

Rev.1.03

Feb 29, 2016

TCP/IP Protocol Stack Based Network Solution for Industrial Applications

RX Driver Package Application

Introduction

This document is an application note of the industrial network solution using TCP/IP protocol stack (referred to as “M3S-T4-Tiny”).

This application note includes sample code for a main program that uses Network Middleware Modules (DHCP client, DNS client, HTTP server, FTP server), when used in combination with the RX64M, RX71M Group RX Driver Package, allows the construction of various network systems.

Target Device

RX64M Group (Renesas Starter Kit+ RX64M)

RX71M Group (Renesas Starter Kit+ RX71M)

RX Driver Package Used

RX64M, RX71M Group RX Driver Package Ver.1.02 (R01AN2606EJ)

When using this application note with your product, careful evaluation is recommended.

And when using this application note with other Renesas MCUs, careful evaluation is recommended after making modifications to comply with the alternate MCU.

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1. Overview

1.1 This Application Note

This application note describes the procedure for main program evaluation by combining the Board Support Package (referred to as “BSP”), USB driver (Host Mass Storage Class Driver “USB HMSC” and “Basic Firmware”), M3S-TFAT-Tiny FAT file system (referred to as “TFAT”), Ethernet driver, TCP/IP protocol stack (M3S-T4-Tiny), and Network Middleware of FIT modules included in the RX64M, RX71M Group RX Driver Package.

This application note operates on the Renesas Starter Kit+ for RX64M, Renesas Starter Kit+ for RX71M (referred to as “RSK” in the remainder of this document).

1.2 Operating Environment

This application note operates in the following environment.

Table 1-1 Operating Environment

Microcontroller	RX64M Group
Evaluation board	Renesas Starter Kit+ RX64M http://www.renesas.com/products/tools/introductory_evaluation_tools/renesas_starter_kits/rsk_rx64m/index.jsp
Integrated development environment (IDE)	e ² studio, V4.1.0 or later
Cross tools	RX Family C/C++ Compiler Package V2.03.00 or later
Emulator	E1 (included in the Renesas Starter Kit+ for RX64M), E20
RX Driver Package	RX64M, RX71M Group RX Driver Package Ver1.02 (R01AN2606EJ)*

Table 1-2 Operating Environment

Microcontroller	RX71M Group
Evaluation board	Renesas Starter Kit+ RX71M http://www.renesas.com/products/tools/introductory_evaluation_tools/renesas_starter_kits/rsk_rx71m/index.jsp
Integrated development environment (IDE)	e ² studio, V4.1.0 or later
Cross tools	RX Family C/C++ Compiler Package V2.03.00 or later
Emulator	E1 (included in the Renesas Starter Kit+ for RX71M), E20
RX Driver Package	RX64M, RX71M Group RX Driver Package Ver1.02 (R01AN2607EJ)*

Note: * Operation of this application note has been verified when the modules in the RX Driver Package mentioned above are incorporated. If any of the modules used in this application note are replaced with a different module, the user must verify the operation.

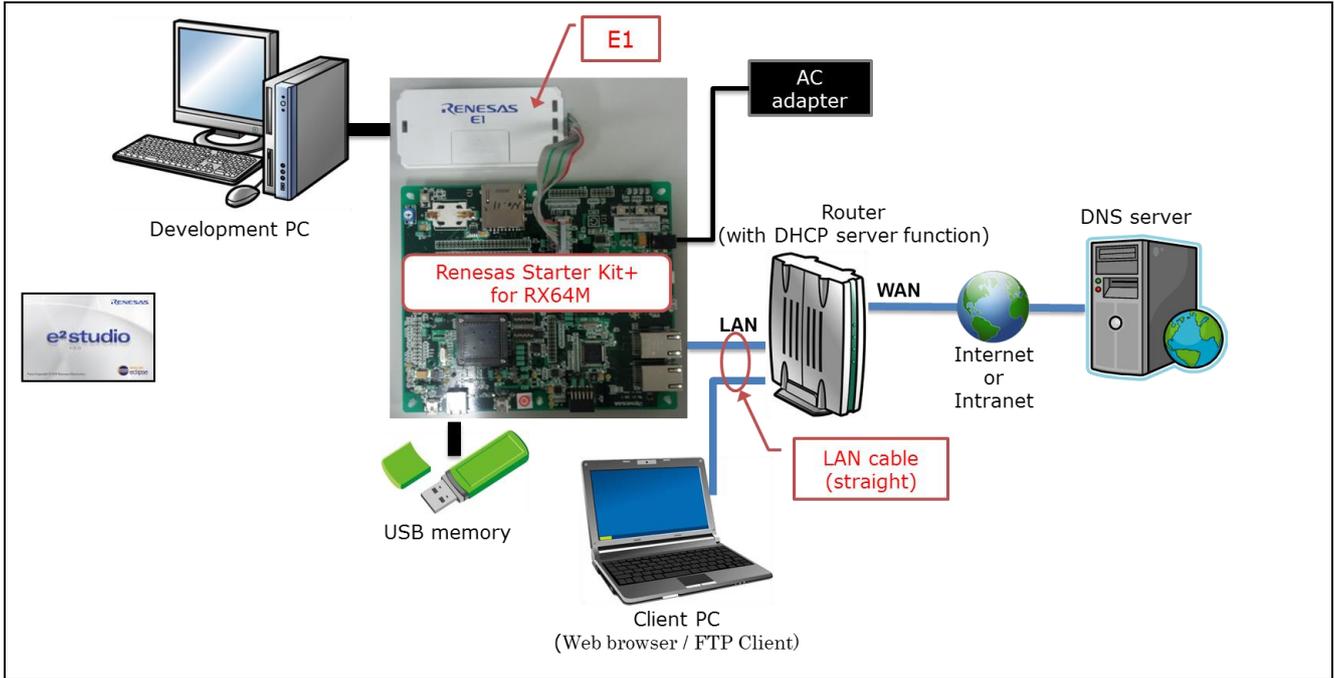


Figure 1-1 Sample Operating Environment

1.3 Module Structure

This section shows the structure of the modules used by this application note and a list of those modules.

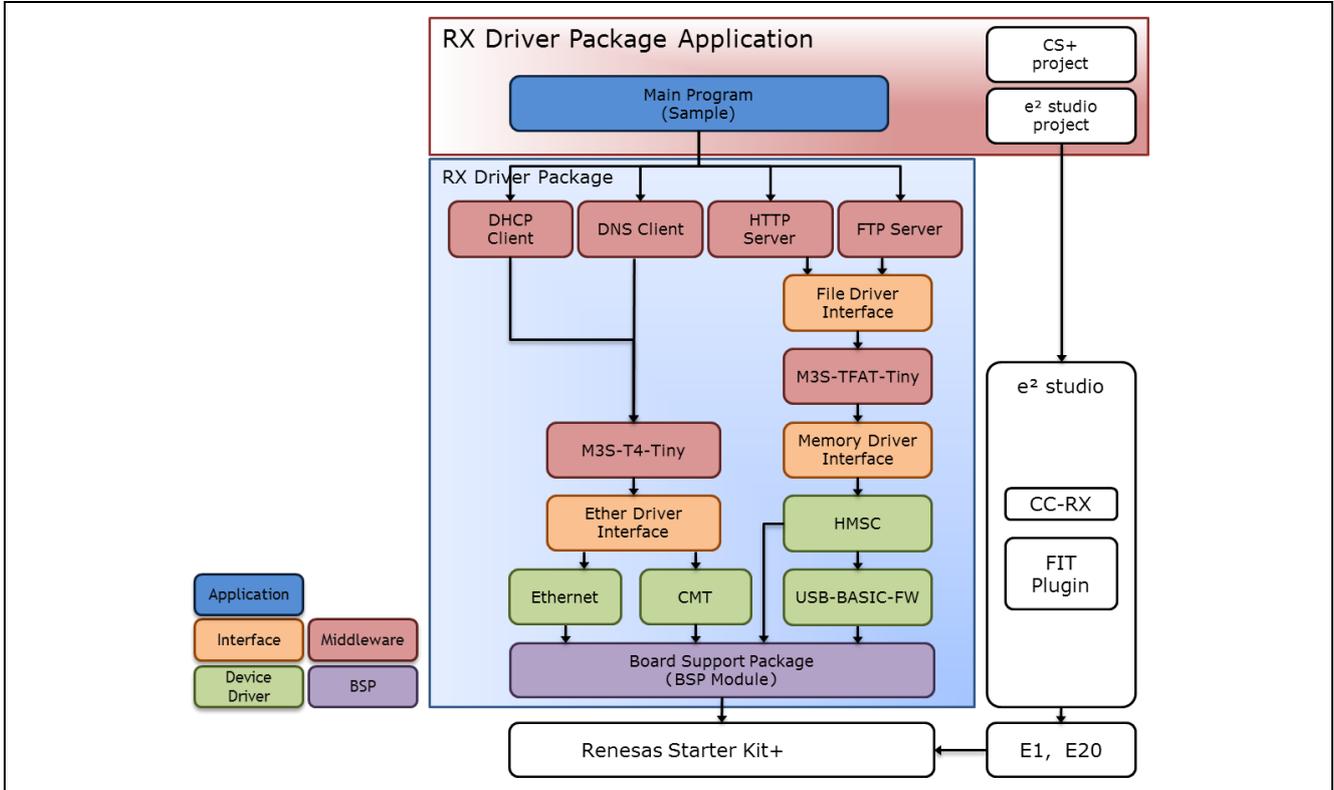


Figure 1-2 Module Structure

Table 1-3 Modules

Type	Module	FIT Module Name	Rev.
Board Support Package	Board Support Package (BSP)	r_bsp	3.00
Device Driver	Compare Match Timer (CMT)	r_cmt_rx	2.60
Device Driver	USB Basic Firmware	r_usb_basic	1.10
Device Driver	USB Host Mass Storage Class	r_usb_hmsc	1.10
Device Driver	Ethernet controller (ETHERC)	r_ether_rx	1.02
Middleware	TCP/IP M3S-T4-Tiny for Embedding (Note 1)	r_t4_rx	2.02
Interface	Interface conversion module for Ethernet Driver and Embedded System M3S-T4-Tiny	r_t4_driver_rx	1.02
Middleware	DHCP client using the embedded TCP/IP M3S-T4-Tiny Module	r_t4_dhcp_client_rx	1.03
Middleware	DNS client using the embedded TCP/IP M3S-T4-Tiny Module	r_t4_dns_client_rx	1.02
Middleware	FTP server using the embedded TCP/IP M3S-T4-Tiny Module	r_t4_ftp_server_rx	1.03
Middleware	Web server using the embedded TCP/IP M3S-T4-Tiny Module	r_t4_http_server_rx	1.04
Interface	File driver for FTP server and Web server Module	r_t4_file_driver_rx	1.01
Middleware	M3S-TFAT-Tiny (FAT file system)	r_tfat_rx	3.02
Interface	M3S-TFAT-Tiny Memory Driver Interface Module	r_tfat_driver_rx	1.02
Application	Main program	src	1.01

Note 1: This package contains the TCP/IP M3S-T4-Tiny evaluation version. For commercial version, refer to the following URL.

<http://www.renesas.com/mw/t4>

1.4 File Structure

This section describes the file structure used in this application note.

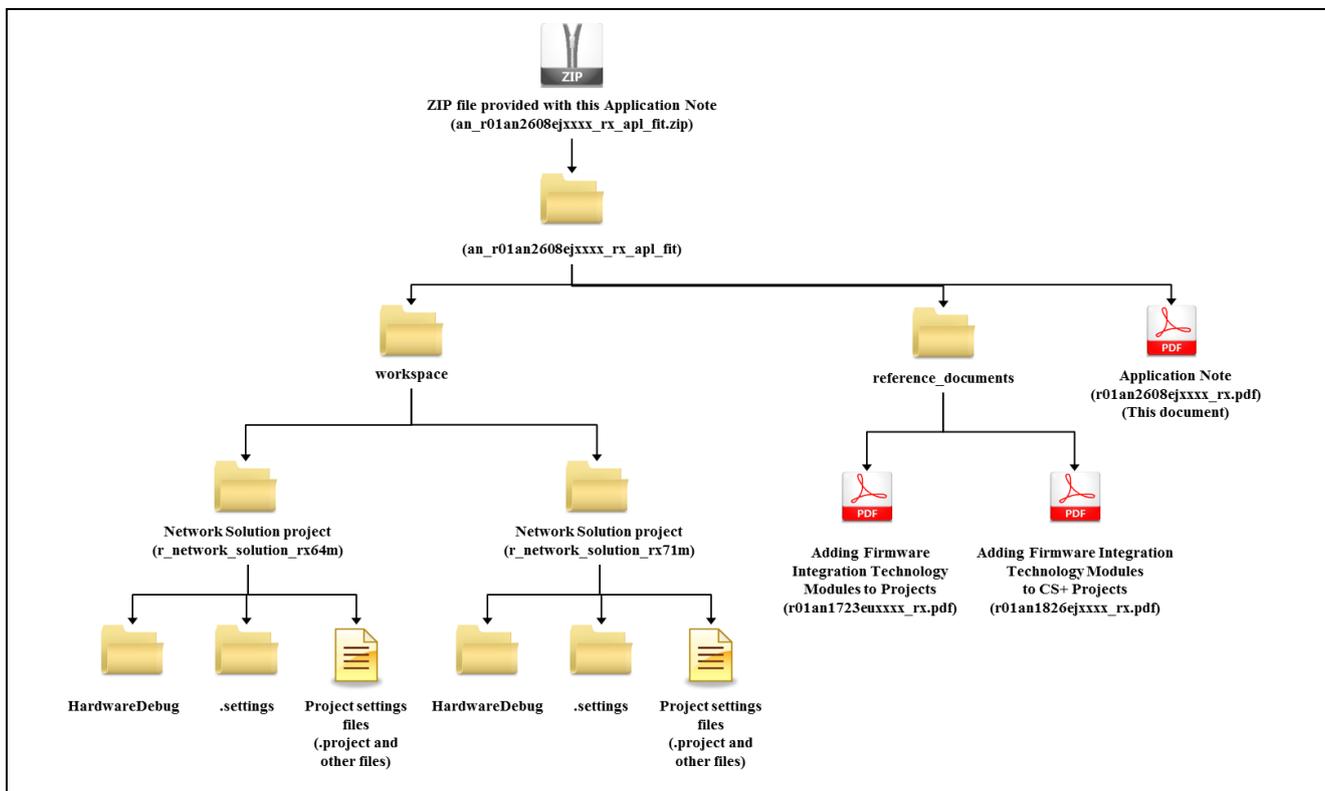


Figure 1-3 File Structure

When the ZIP file provided with this application note is decompressed, a folder with the same name is created and the various folders and files are created within that folder.

”Network Solution project (r_network_solution_rx64m)” or ”Network Solution project (r_network_solution_rx71m)” under the “workspace” folder is the project that built this application. Operation of the application can be verified by importing the project to the e² studio workspace.

Documents that describe using the FIT modules in various development environments are included in the **reference_documents** folder. The document “Adding Firmware Integration Technology Modules to Projects” (R01AN1723EU) describes the method for including the FIT modules, as a FIT plugin, in an e² studio project. The document “Adding Firmware Integration Technology Modules to CS+ Projects” (R01AN1826EJ) describes the method for including the FIT modules in a CS+ project.

1.5 Projects

This application note includes an e² studio project for building and evaluating this application. These projects register both a build structure that stores the build settings and a debug structure that stores debug settings.

The table below lists the build structure and debug structure registered in these projects.

Table 1-4 Project Settings

	Structure	Description
Build structure	HardwareDebug (Debug on hardware)	This structure is used to generate a load module with debugging information included. Main settings
Debug structure	HardwareDebug (E1)	Used for hardware debugging over an E1 emulator using a load module generated by HardwareDebug (Debug on hardware).

The table below lists the target-specific setting.

Table 1-5 Target-specific setting

Items	Setting
Tool chain version	v2.03.00
Debug Hardware	E1 (RX)
Data endian	Little-endian data
Select Target	R5F564MLCxFC (RX64M LQFP 176pin) or R5F571MLCxFC (RX71M LQFP 176pin)
Renesas RTOS Support (Note 1)	None

Note 1: For use, OS environment download is required.

2. Acquiring a Development Environment

2.1 Acquire e² studio

Access the following URL and download the e² studio.

http://www.renesas.com/e2studio_download

This document requires you to use e² studio V4.1.0 or later. If the version older than V4.1.0 is used, some functions of the e² studio may not be available. For download, obtain the latest version of the e² studio on the website.

2.2 Acquire a Compiler Package

Access the following URL and download the RX Family C/C++ Compiler Package.

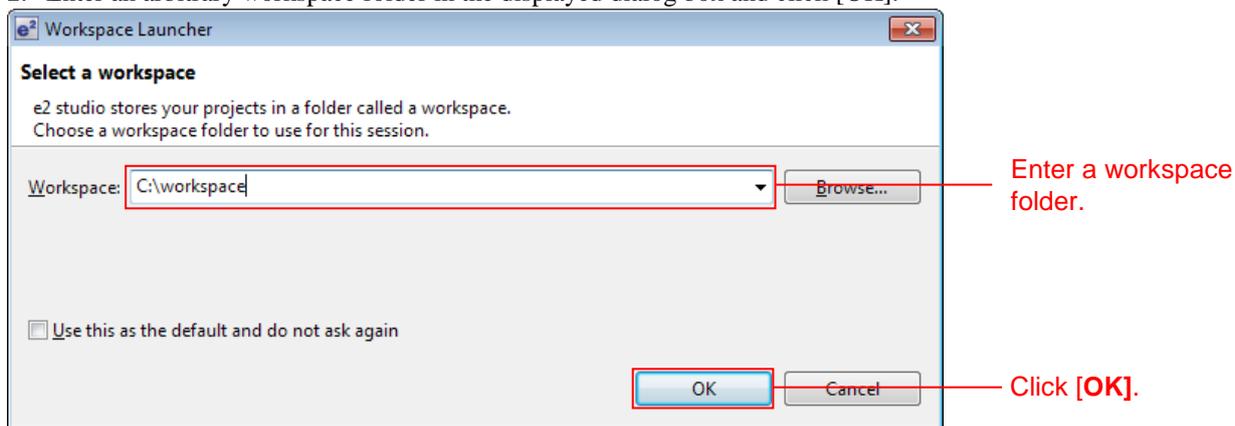
http://www.renesas.com/e2studio_download

3. Building a Project

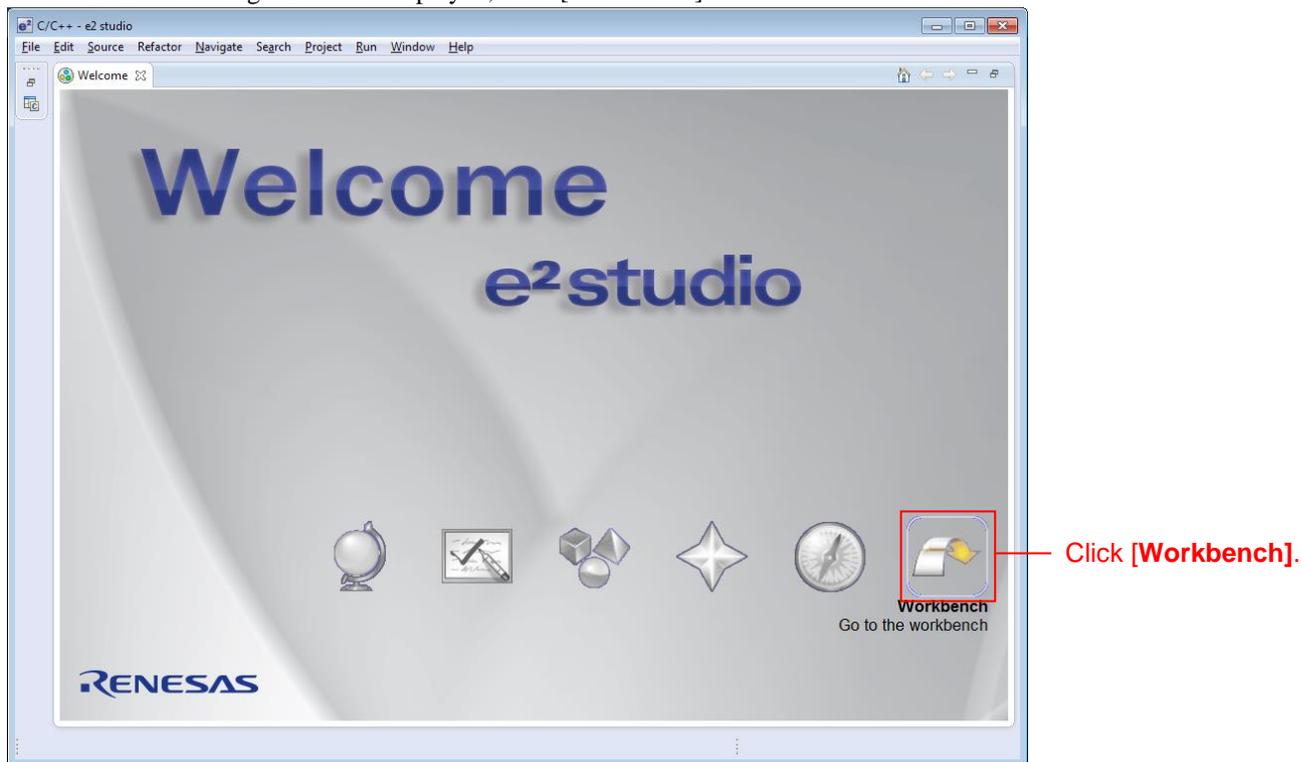
This application note includes environment-built project. The procedure to import a Project using e² studio Smart browser is described below.

3.1 Create a Workspace

1. Start e² studio.
2. Enter an arbitrary workspace folder in the displayed dialog box and click [OK].



3. When the following window is displayed, click [Workbench].

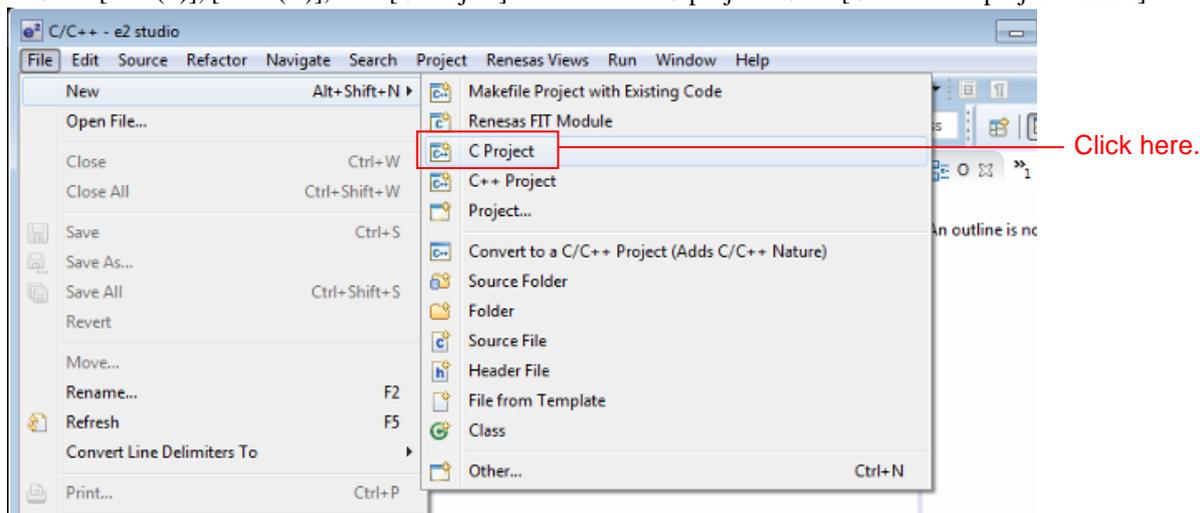


3.2 Create a Project

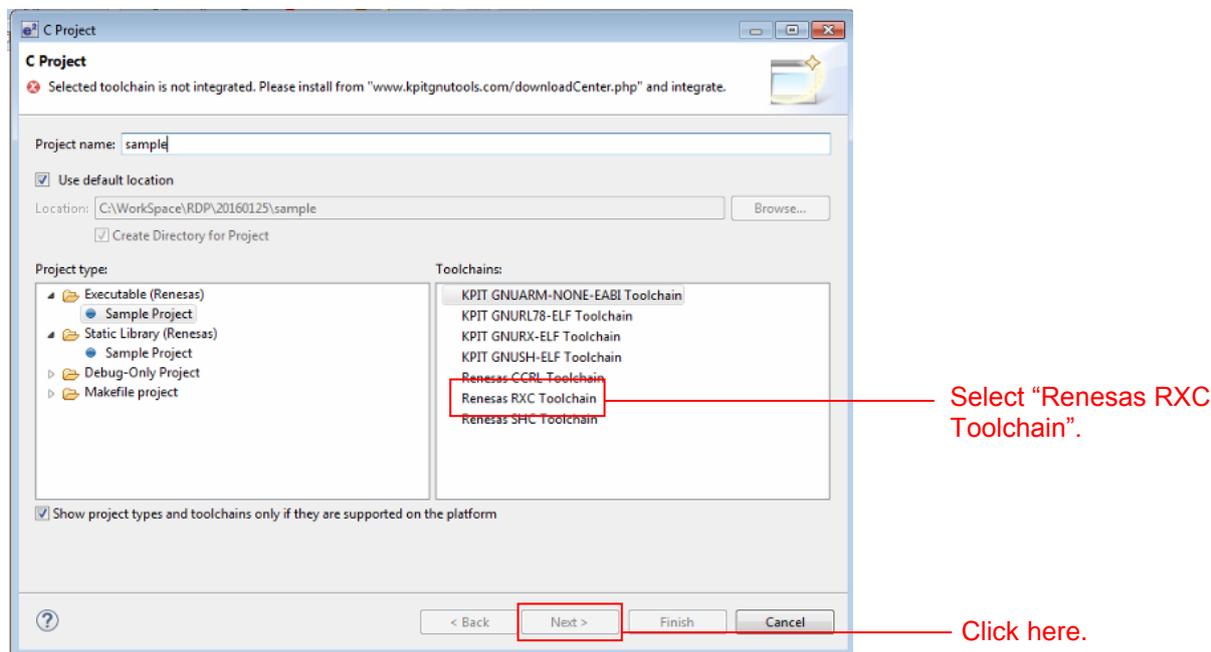
When using the Smart browser function, the target project or file needs to be selected. To use this function, create the project that specified the target device (Note 1).

Note 1 : The project to be created here is a dummy to use the Smart browser. For the setting of a Project to be imported, refer to Table 1-5 Target-specific setting.

1. Click [File (F)], [New (N)], then [C Project] to create new C project. Start [Create New project wizard].

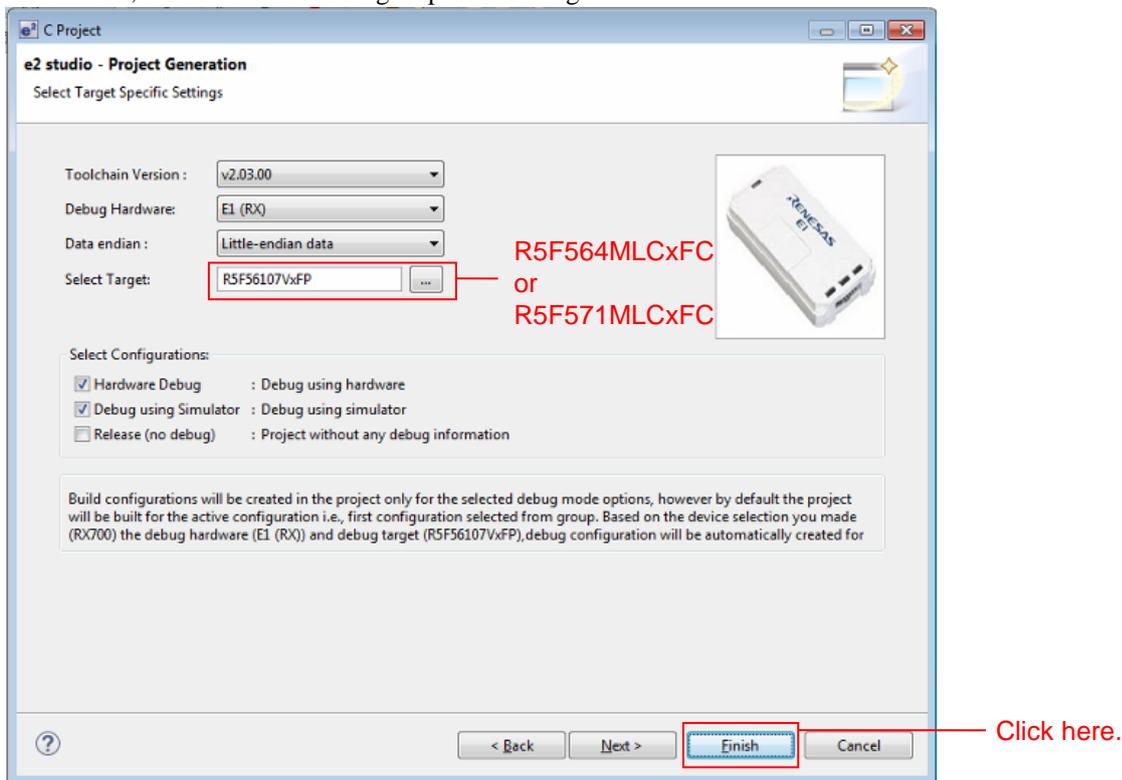


2. Input any project name and select [Renesas RXC Toolchain]. Click [Next (N)].

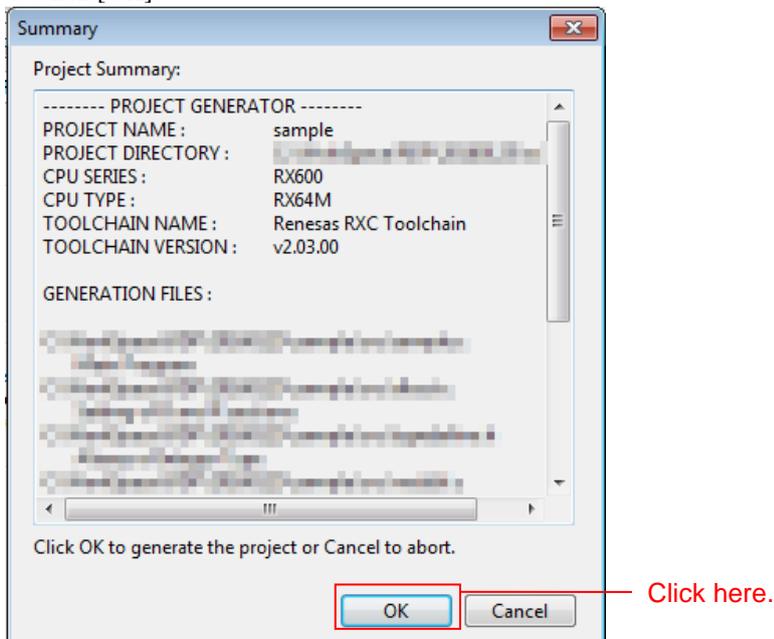


3. Set Select Target ; for RX64M :R5F564Mxxxxx, for RX71M :R5F571Mxxxxx. For other items, any setting is OK (Note 1). When the setting is completed, click [Finish(F)].

Note 1 : Setting for dummy project. For the setting of the project environment to be imported using the smart browser, refer to Table 1-5 Target-specific setting.



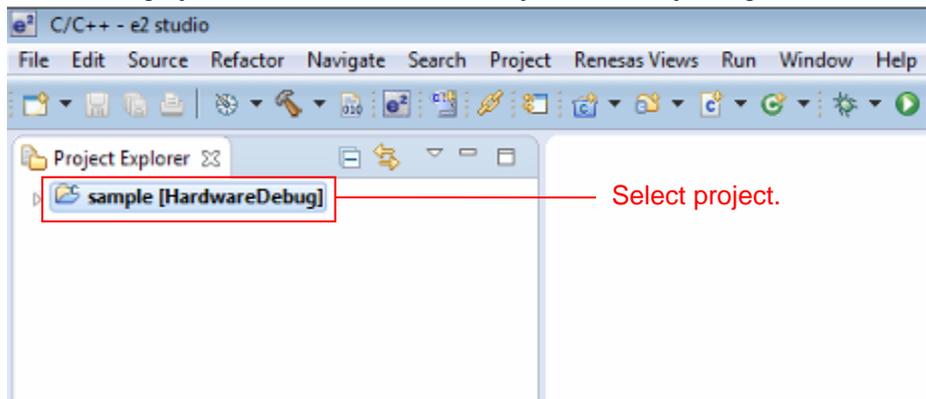
4. Click [OK].



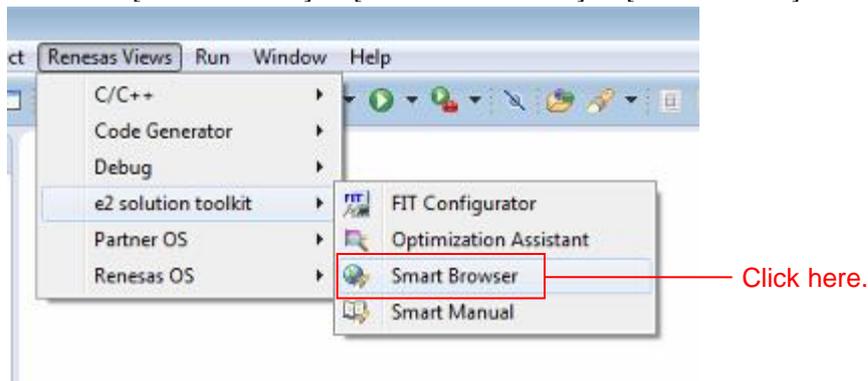
3.3 Import a Project

Import the project of Main program in the workspace created.

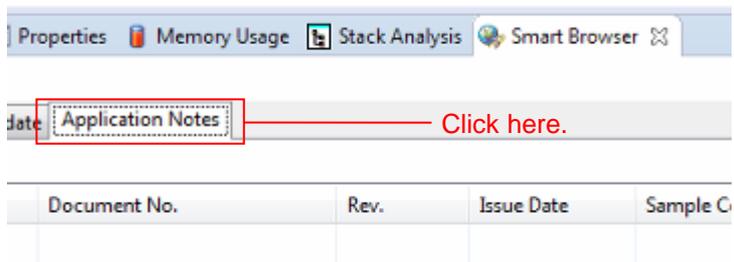
1. Select the project created in "3.2 Create a Project" from Project explorer.



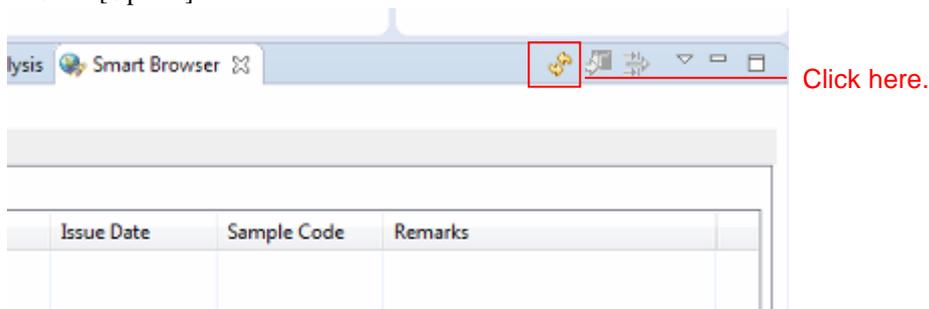
2. Click on [Renesas Views] → [e2 Solution Tool kit] → [Smart browser] to start the Smart browser.



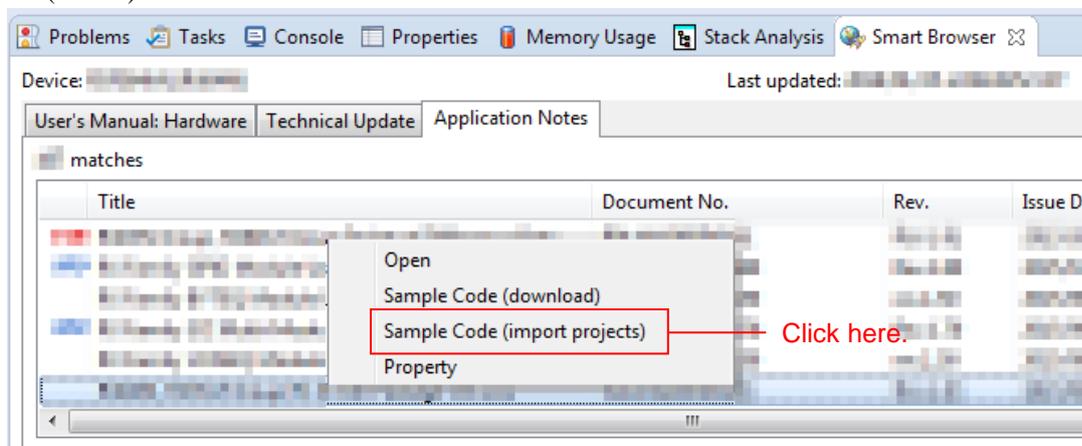
3. Click on the [Application Note] on the [Smart browser] tabbed page.



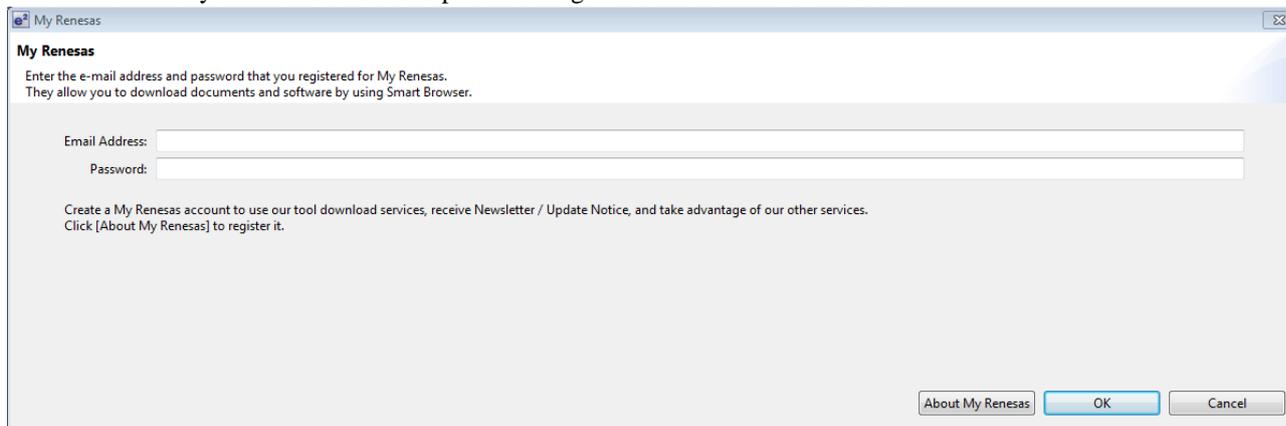
4. Click [Update].



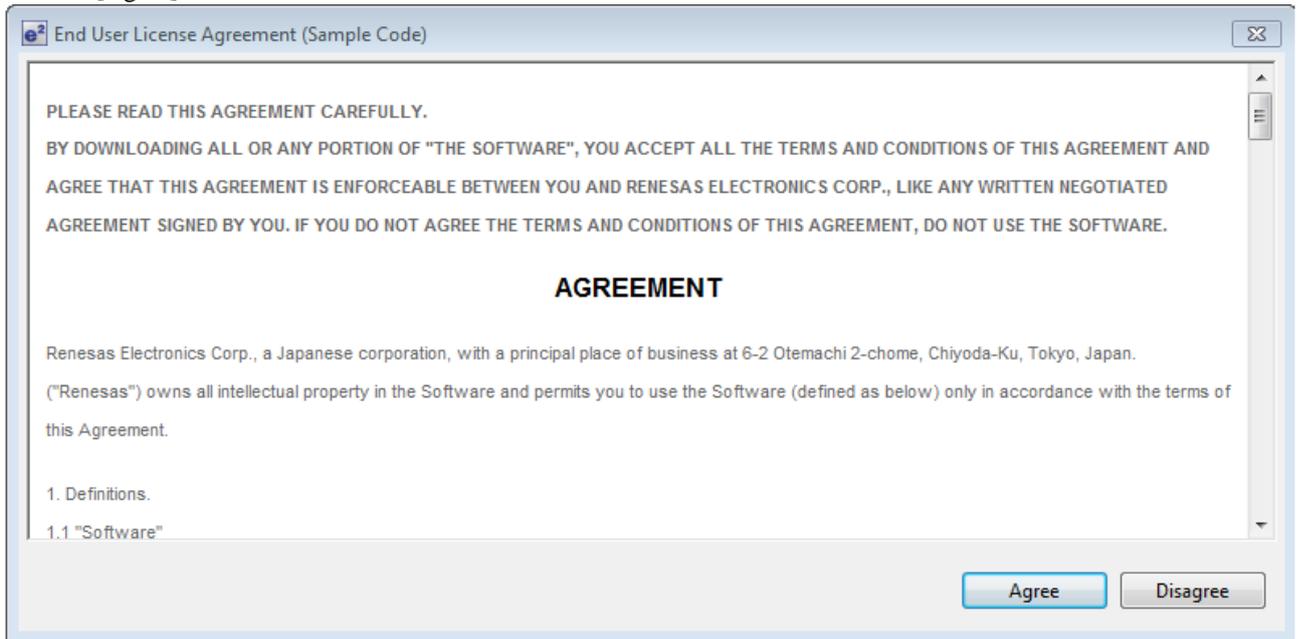
5. Select the application note and right-click. Then, click on [Sample code (Project import)] in the context menu (Note 1).



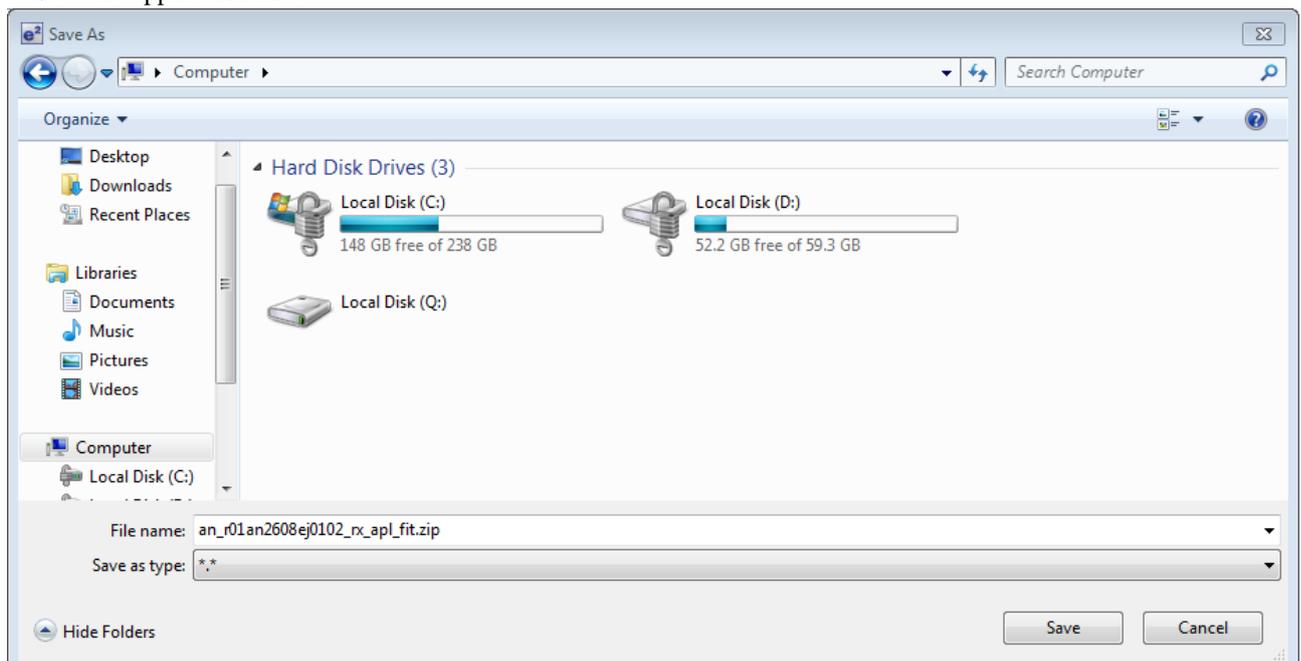
Note 1: If authentication by My Renesas has never been performed, "My Renesas" dialog opens when downloading the file. Enter your mail address and password registered in the Renesas website.



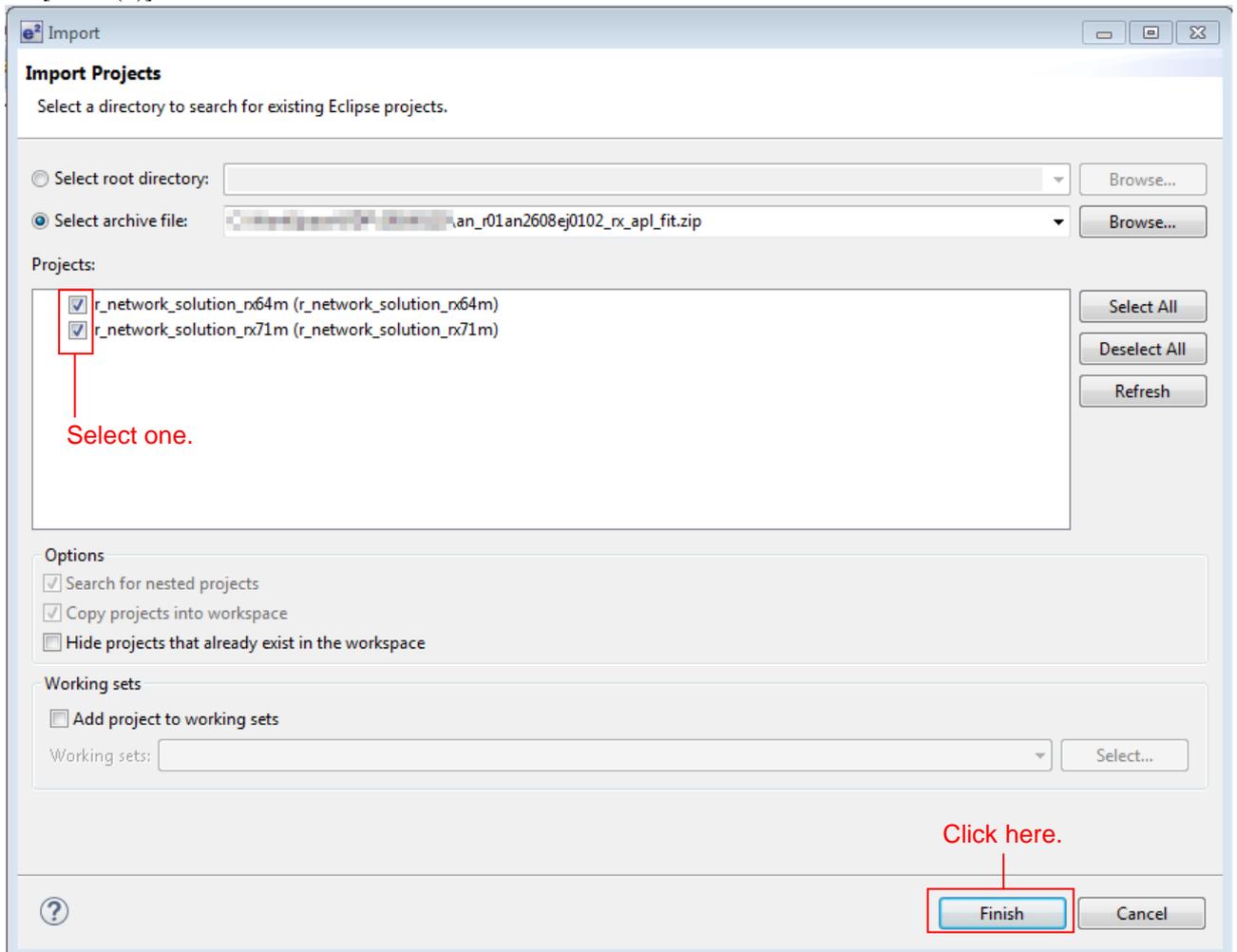
6. Click [Agree].



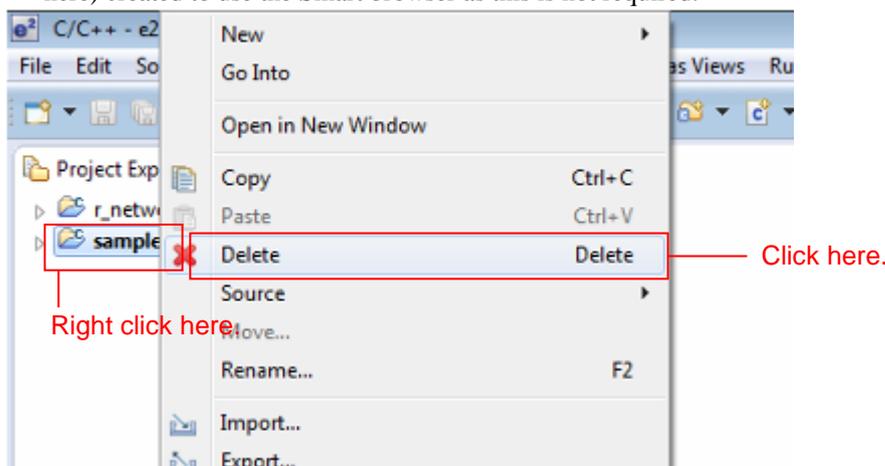
7. Save the application note.



8. Select either [r_network_solution_rx64m] or [r_network_solution_rx71m] displayed in [Project(P)], and click [Finish(F)].



9. The figure below shows when [r_network_solution_rx64m] is selected. Delete the project (shown as “sample” here) created to use the Smart browser as this is not required.



3.4 Modify Configuration

In this project, the configuration file setting and project setting for each FIT module are changed to configure the application. The detail is shown as follows.

Refer to this information when building new project. To use the project imported, go to “4. Verify Operation”.

3.4.1 Change Configuration

The configuration files for each FIT module configuring this application require modification.

Refer to the manuals and other files in the doc folder for each FIT module for details on the items and the settings in the configuration files.

The places to be changed in the configuration files are shown below.

(1) Change Interrupt Stack Size

In this application, the TCP/IP processing is performed from the Ethernet controller's interrupt handler. This requires about 2.5 KB of interrupt stack.

Modify the interrupt stack size defined in the `r_bsp` configuration file as shown below.

`r_config/r_bsp_config.h`

```
/* Interrupt Stack size in bytes. The Renesas RX toolchain sets the stack size using
the #pragma stacksize directive.
 * If the interrupt stack is the only stack being used then the user will likely want
to increase the default size
 * below.
 */
#pragma stacksize si=0x1000
```

(2) Change Compare Match Timer Driver Settings

Set interrupt priority of compare match timer lower than interrupt priority of the USB driver (IPR=3).

`r_config/r_cmt_rx_config.h`

```
/* The interrupt priority level to be used for CMT interrupts. */
#define CMT_RX_CFG_IPR (2)
```

(3) Change USB Driver Settings

Set channel 0 to Unused (USB_NOUSE_PP) and set channel 1 to Host (USB_HOST_PP).

r_config/r_usb_basic_config.h

```
/*
    Select USB mode to USB IP(USBb)

    USB_HOST_PP : USB Host Mode
    USB_PERI_PP : USB Peripheral Mode
    USB_NOUSE_PP : Not Used (USBb)
*/
#define USB_FUNCSEL_USBIP0_PP    USB_NOUSE_PP

/*
    Select USB mode to USB IP(USBAA/USBA)

    USB_HOST_PP : USB Host Mode
    USB_PERI_PP : USB Peripheral Mode
    USB_NOUSE_PP : Not Used (USBAA/USBA)
*/
#define USB_FUNCSEL_USBIP1_PP    USB_HOST_PP
```

r_config/r_usb_hmsc_config.h

```
#define USB_MEDIA_INITIALIZE(data1)    R_tfat_disk_initialize((uint8_t)data1)
```

(4) Change T4 Settings

Change the T4 settings as shown below.

Comment out the `t4_callback` function external reference declaration and add a new external reference declaration for the `http_callback`, `ftp_callback`, `ftp_data_callback` and `dns_callback` function.

r_t4_rx/src/config_tcpudp.c

```
#include "r_t4_itcpip.h"
//extern ER t4_callback(ID cepid, FN fncd , VP p_parblk);
extern ER http_callback(ID cepid, FN fncd , VP p_parblk);
extern ER ftp_callback(ID cepid, FN fncd , VP p_parblk);
extern ER ftp_data_callback(ID cepid, FN fncd , VP p_parblk);
extern ER dns_callback(ID cepid, FN fncd , VP p_parblk);
```

Change the TCP reception point setting as shown below.

r_t4_rx/src/config_tcpudp.c

```
/** Definition of TCP reception point (only port number needs to be set) */
T_TCP_CREP tcp_crep[18] =
{
    /* HTTP server use setting below. */
    { 0x0000, { 0, 80 }},
    /* FTP server use setting below. */
    { 0x0000, { 0, 21 }},
    { 0x0000, { 0, 20 }}, /* The port number in the active mode is 20, and the
port number in the passive mode is 1024. */
    { 0x0000, { 0, 21 }},
    { 0x0000, { 0, 20 }}, /* The port number in the active mode is 20, and the
port number in the passive mode is 1025. */
    { 0x0000, { 0, 21 }},
    { 0x0000, { 0, 20 }}, /* The port number in the active mode is 20, and the
port number in the passive mode is 1026. */
    { 0x0000, { 0, 21 }},
    { 0x0000, { 0, 20 }}, /* The port number in the active mode is 20, and the
port number in the passive mode is 1024. */
    { 0x0000, { 0, 21 }},
    { 0x0000, { 0, 20 }}, /* The port number in the active mode is 20, and the
port number in the passive mode is 1025. */
    { 0x0000, { 0, 21 }},
    { 0x0000, { 0, 20 }}, /* The port number in the active mode is 20, and the
port number in the passive mode is 1026. */
};
```

Change the TCP communication end point setting as shown below.

r_t4_rx/src/config_tcpudp.c

```

/** Definition of TCP communication end point
    (only receive window size needs to be set) */
T_TCP_CCEP tcp_ccep[18] =
{
    /* { attribute of TCP communication end point,
        top address of transmit window buffer, size of transmit window buffer,
        top address of receive window buffer, size of receive window buffer,
        address of callback routine }

        */
    /* HTTP server use setting below. */
    { 0, 0, 0, 0, 1460, http_callback },
    { 0, 0, 0, 0, 1460, http_callback },
    { 0, 0, 0, 0, 1460, http_callback },
    { 1, 0, 0, 0, 1460, http_callback },
    { 1, 0, 0, 0, 1460, http_callback },
    { 1, 0, 0, 0, 1460, http_callback },
    /* FTP server use setting below. */
    { 0, 0, 0, 0, 128, ftp_callback },          /* FTP control connection */
    { 0, 0, 0, 0, 1460, ftp_data_callback },    /* FTP data connection */
    { 0, 0, 0, 0, 128, ftp_callback },          /* FTP control connection */
    { 0, 0, 0, 0, 1460, ftp_data_callback },    /* FTP data connection */
    { 0, 0, 0, 0, 128, ftp_callback },          /* FTP control connection */
    { 0, 0, 0, 0, 1460, ftp_data_callback },    /* FTP data connection */
    { 1, 0, 0, 0, 128, ftp_callback },          /* FTP control connection */
    { 1, 0, 0, 0, 1460, ftp_data_callback },    /* FTP data connection */
    { 1, 0, 0, 0, 128, ftp_callback },          /* FTP control connection */
    { 1, 0, 0, 0, 1460, ftp_data_callback },    /* FTP data connection */
    { 1, 0, 0, 0, 128, ftp_callback },          /* FTP control connection */
    { 1, 0, 0, 0, 1460, ftp_data_callback },    /* FTP data connection */
};

```

Change the 2MSL Wait Time from 1 min. to 10 ms.

r_t4_rx/src/config_tcpudp.c

```

/** 2MSL wait time (unit:10ms) */
const UH _tcp_2msl[] =
{
    (1),      /* 10 ms */
    (1),      /* 10 ms */
};

```

Change the UDP communication end point setting as shown below.

r_t4_rx/src/config_tcpudp.c

```
/** Definition of UDP communication end point */
T_UDP_CCEP udp_ccep[1] =
{
    /* only setting port number */
    { 0x0000, { 0, 1365 }, dns_callback },
};
```

(5) Change HTTP Server Settings

Set the MAX_CGI_FILE to 2.

r_config/r_t4_http_server_rx_config.h

```
// If user uses CGI function, please specify cgi file name, and number of cgi files.
#define MAX_CGI_FILE 2
```

Change the CGI_FILE_NAME_TABLE_LIST as shown below.

r_config/r_t4_http_server_rx_config.h

```
/*#define CGI_FILE_NAME_TABLE_LIST */
/* {"cgi_smpl.cgi", NULL}, */
extern ER cgi_sample_function(ID cepid, void *res_info);
extern ER cgi_dns_demo_function(ID cepid, void *res_info);
extern ER cgi_dns_demo_pending_release(ID cepid, void *res_info);
#define CGI_FILE_NAME_TABLE_LIST
    {"cgi_smpl.cgi", cgi_sample_function, NULL},
    {"dns_demo.cgi", cgi_dns_demo_function, cgi_dns_demo_pending_release},
```

Change the number of communication endpoints used in the HTTP server to 6 to match tcp_ccep table of r_t4_rx/src/config_tcpudp.c.

r_config/r_t4_http_server_rx_config.h

```
// set same value number of CEPID in config_tcpudp.c
#define HTTP_TCP_CEP_NUM 6
```

(6) Change DNS client Settings

Change IP address of the DNS server used to verify the operation (Following is example).

r_config/r_t4_dns_client_rx_config.h

```
/*
*****
Configuration Options
*****
// #define DNS_IP_ADDR_1 172,30,11,5 /* DNS server IP address (primary) */
// #define DNS_IP_ADDR_2 10,29,72,33 /* DNS server IP address (secondary) */
#define DNS_IP_ADDR_1 10,164,247,5 /* DNS server IP address (primary) */
#define DNS_IP_ADDR_2 10,29,72,33 /* DNS server IP address (secondary) */
*/
```

(7) Change FTP server Settings

Change the position of the TCP communication end point used in FTP server to match TCP communication end point setting of the T4.

r_config/r_t4_ftp_server_rx_config.h

```
#include "r_t4_http_server_rx_config.h"
/*
*****
Configuration Options
*****
#define FTP_TCP_CEP_NUM 12 // Adapt myself to the communication endpoint
number of config_tcpudp.c

#define FTP_START_TCP_CEP HTTP_TCP_CEP_NUM // starting position of the
communication endpoint in config_tcpudp.c
*/
```

(8) Change File driver for FTP server and Web server Settings

Change the setting to use the USB.

r_config/r_t4_file_driver_rx_config.h

```
/* Only one is effective.
   (priority is given to SERVER_FILE_DRV_USE_EXTERNAL)

   Setting to 1 : used
           0 : unused
*/
#define SERVER_FILE_DRV_USE_EXTERNAL (1) // USB, SD card etc
#define SERVER_FILE_DRV_USE_INTERNAL (0) // internal-RAM / external-SDRAM
```

(9) Change M3S-TFAT-Tiny Memory Driver Settings

Change the setting to use the USB.

r_config/r_tfat_driver_rx_config.h

```
/* Number of logical drives to be used.
   Setting to 0 : unused memory
           other : number of logical drives
   (USB and SDHI can be used together.)
*/
#define TFAT_USB_DRIVE_NUM (1)
#define TFAT_SDHI_DRIVE_NUM (0)
#define TFAT_USB_MINI_DRIVE_NUM (0)

/* allocate a drive number
   <valid define>
   TFAT_CTRL_USB : for USB
   TFAT_CTRL_SDHI : for SDHI
   NULL : unallocated drive

   MAX 10 drives(TFAT module spec)

   ex.)
   #define TFAT_DRIVE_ALLOC_NUM_0 TFAT_CTRL_USB
   #define TFAT_DRIVE_ALLOC_NUM_1 TFAT_CTRL_SDHI
   #define TFAT_DRIVE_ALLOC_NUM_2 TFAT_CTRL_SDHI
   #define TFAT_DRIVE_ALLOC_NUM_3 TFAT_CTRL_USB
*/
#define TFAT_DRIVE_ALLOC_NUM_0 TFAT_CTRL_USB
#define TFAT_DRIVE_ALLOC_NUM_1 NULL
```

(10) Change Ethernet Settings

Change the PHY IC channel used to control the PHY IC form Ethernet controller to ch0.

r_config/r_ether_rx_config.h

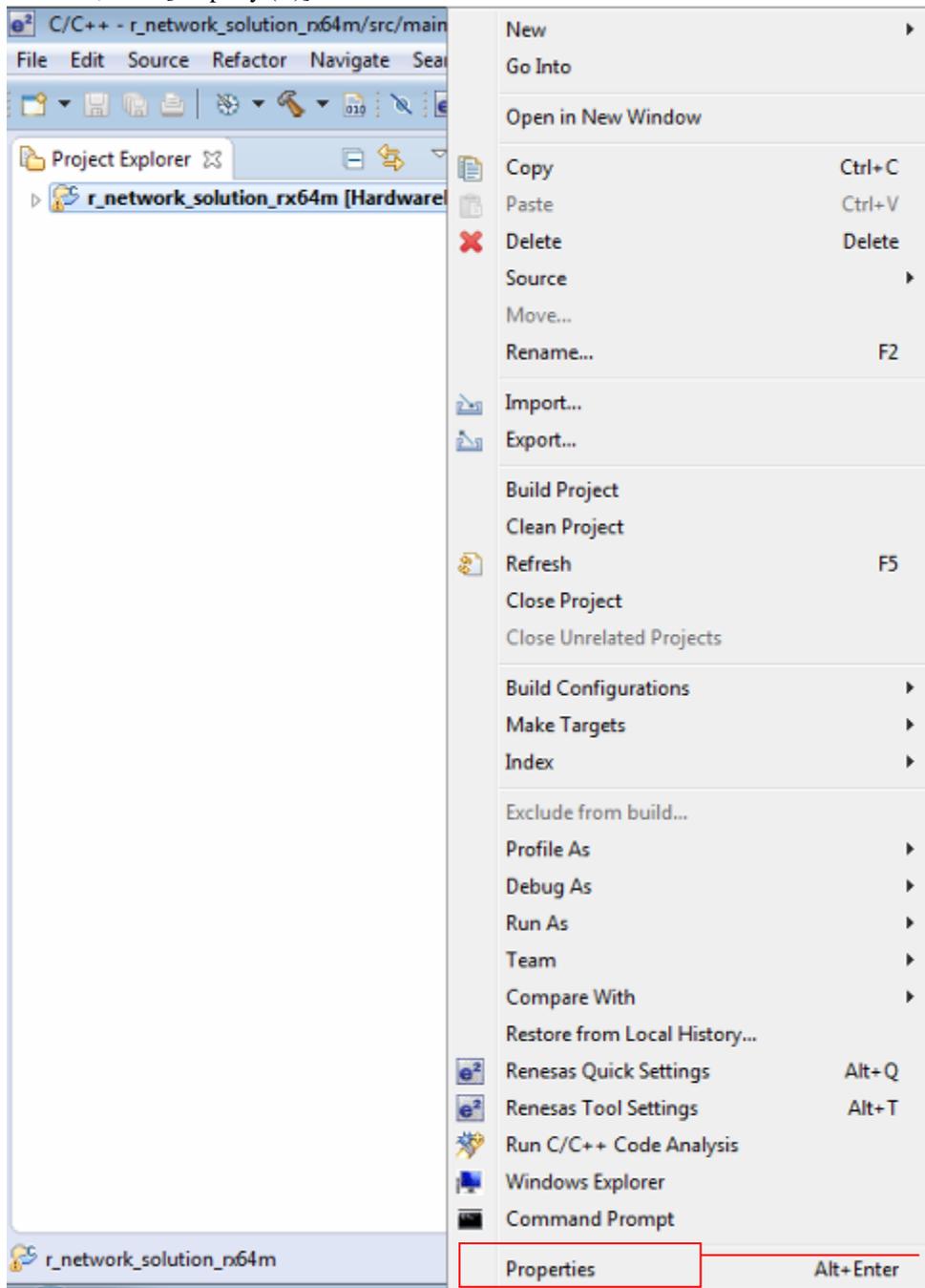
```
/* The register bus of PHY0/1 for ETHER0/1 select
   0 = The access of the register of PHY uses ETHER0.
   1 = The access of the register of PHY uses ETHER1.
*/
#define ETHER_CFG_CH0_PHY_ACCESS      (0)
#define ETHER_CFG_CH1_PHY_ACCESS      (0)
```

3.4.2 Change Project Setting

The setting when building is changed from default setting to the content shown in Table 3-1 Changed build setting.

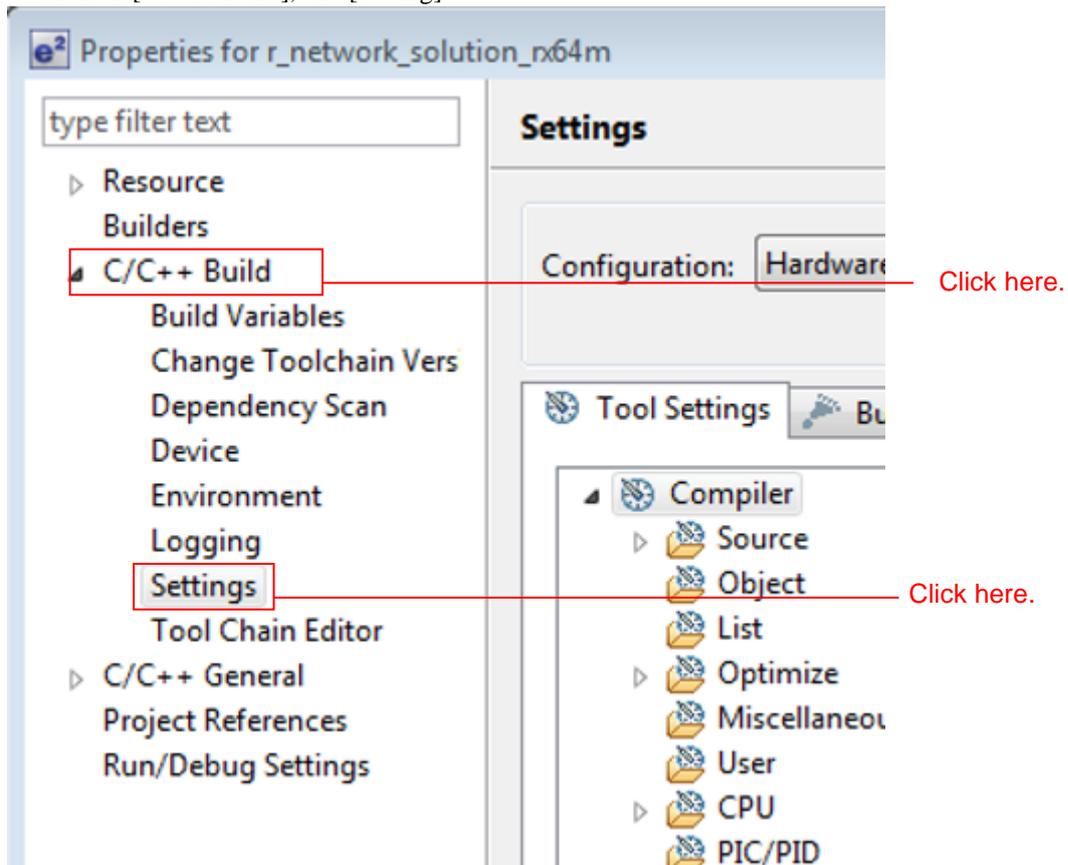
To check the project setting, use the following procedure.

1. Select the project for the e² studio ([r_network_solution_rx64m] or [r_network_solution_rx71m]) and right-click. Then, click [Property (R)].



Click here.

2. Click on [C/C++ Build], and [Setting].



3. Refer to the contents of Table 3-1 Changed build setting on the [Tool Setting] tab.

Table 3-1 Changed build setting

Items	Changed contents	Description
Compiler - Source	Add include path to "Include file directory"	Set an include path that requires the setting for each FIT module. It is automatically set when including each FIT module using "FIT Configurator".
Linker - Input	For Little endian : Add "\${workspace_loc}/\${ProjName}/r_tfa_t_rx/lib/tfat_rx600_little.lib)" (Note 1) For Big endian: Add "\${workspace_loc}/\${ProjName}/r_tfa_t_rx/lib/tfat_rx600_big.lib)" (Note 1)	Setting is required when using TFAT. (required when using FAT file system driver) It's not automatically set even when using "FIT Configurator". Setting by the user is required when creating new project. (Note 2)
	For Little endian: Add "\${workspace_loc}/\${ProjName}/r_t4_rx/lib/T4_Library_rxv2_ether_little.lib)" (Note 1) For Big endian: Add "\${workspace_loc}/\${ProjName}/r_t4_rx/lib/T4_Library_rxv2_ether_big.lib)" (Note 1)	Setting is required when using Ethernet. It's not automatically set even when using "FIT Configurator". Setting by the user is required when creating new project. (Note 2)
Linker - Section	Add B_ETHERNET_BUFFERS_1 section, B_RX_DESC_1 section, and B_TX_DESC_1 section to RAM capacity	Setting is required when using Ethernet. It's not automatically set even when using "FIT Configurator". Setting by the user is required when creating new project.

<Setting examples>

Address	Section name
0x00000000	B_ETHERNET_BUFFERS_1
	B_RX_DESC_1
	B_TX_DESC_1
	SU
	SI
	B_1
	R_1

(Note 1) The setting change is required when creating the project that includes each FIT module. For the setting, refer to the manuals, etc. in the doc folder of each FIT module.

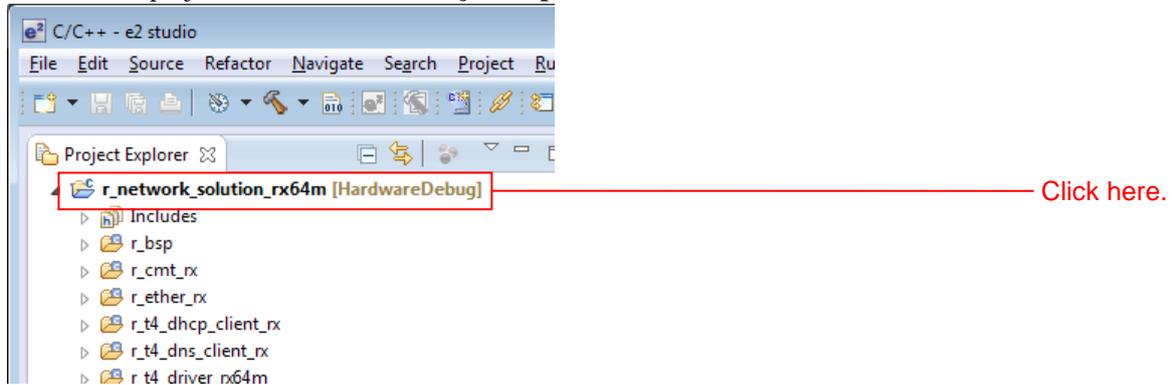
(Note 2) Automatic setting is available in e² studio V4.1 or later. However, as the FIT module used this time does not meet the specification, the automatic setting function is not available. This will be supported in the latest FIT module.

4. Verify Operation

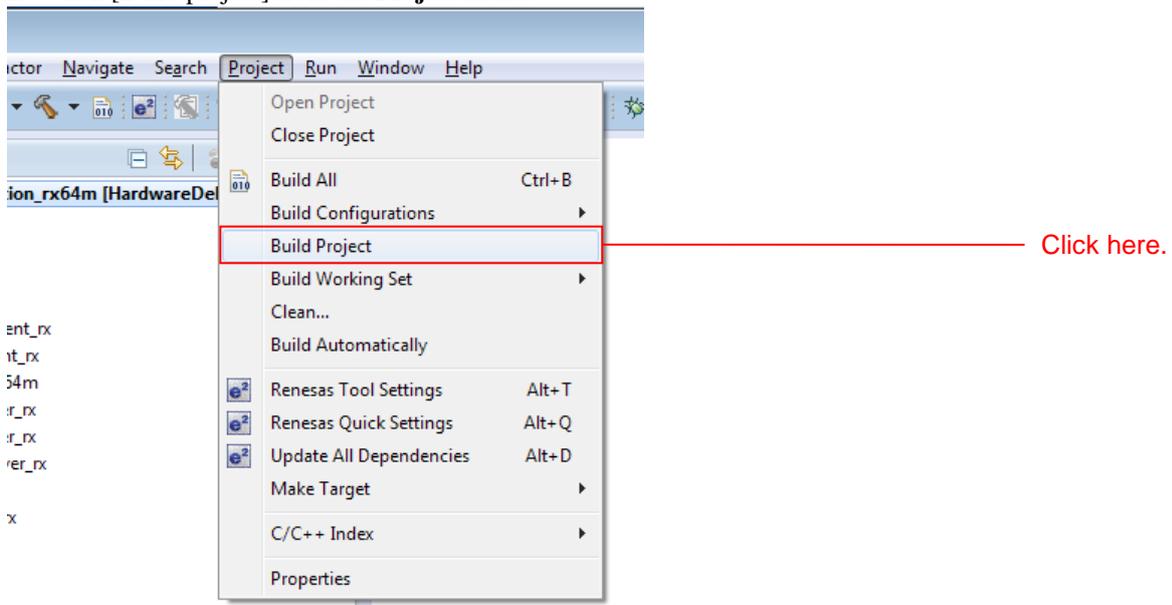
4.1 Build the Project

Use the following procedure to build the project and generate a load module.

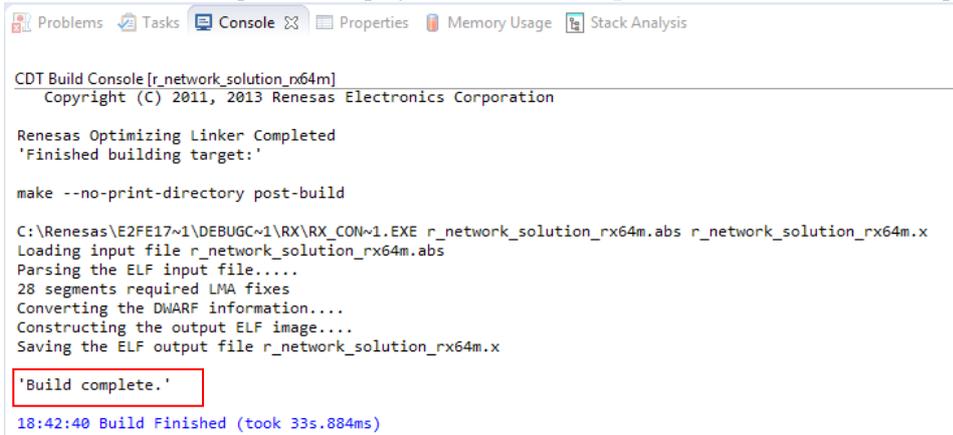
1. Click the project to build from the **Project Explorer**.



2. Click [Build project] from the **Project** menu.



3. When “Build complete” is displayed on the **Console panel**, the build will have completed.



```
Problems Tasks Console Properties Memory Usage Stack Analysis
CDT Build Console [r_network_solution_rx64m]
Copyright (C) 2011, 2013 Renesas Electronics Corporation

Renesas Optimizing Linker Completed
'Finished building target:'

make --no-print-directory post-build

C:\Renesas\E2FE17~1\DEBUGC~1\RX\RX_CON~1.EXE r_network_solution_rx64m.abs r_network_solution_rx64m.x
Loading input file r_network_solution_rx64m.abs
Parsing the ELF input file....
28 segments required LMA fixes
Converting the DWARF information...
Constructing the output ELF image...
Saving the ELF output file r_network_solution_rx64m.x

'Build complete.'
```

18:42:40 Build Finished (took 33s.884ms)

4.2 Prepare for Debugging

4.2.1 Configure Hardware

The evaluation board must be configured before starting debugging.

A table of the required equipment and its configuration are shown below.

Table 4-1 Hardware Configuration

No.	Device	Supplementary Information
1	Development PC	PC used for development
2	Evaluation board Renesas Starter Kit+ for RX64M or Renesas Starter Kit+ for RX71M	
3	USB memory	Memory that is formatted as either FAT or FAT32.
4	Client PC (Web browser / FTP Client)	The development PC can be used for this function.
5	DHCP server, DNS server	When verify operation of the DHCP client and DNS client.
6	One of the following must be provided as a network environment. <ul style="list-style-type: none"> • Router × 1 • Switching hub × 1 • LAN cable (straight or cross) × 1 to 3 	For example of the network environment, Please refer to the following.

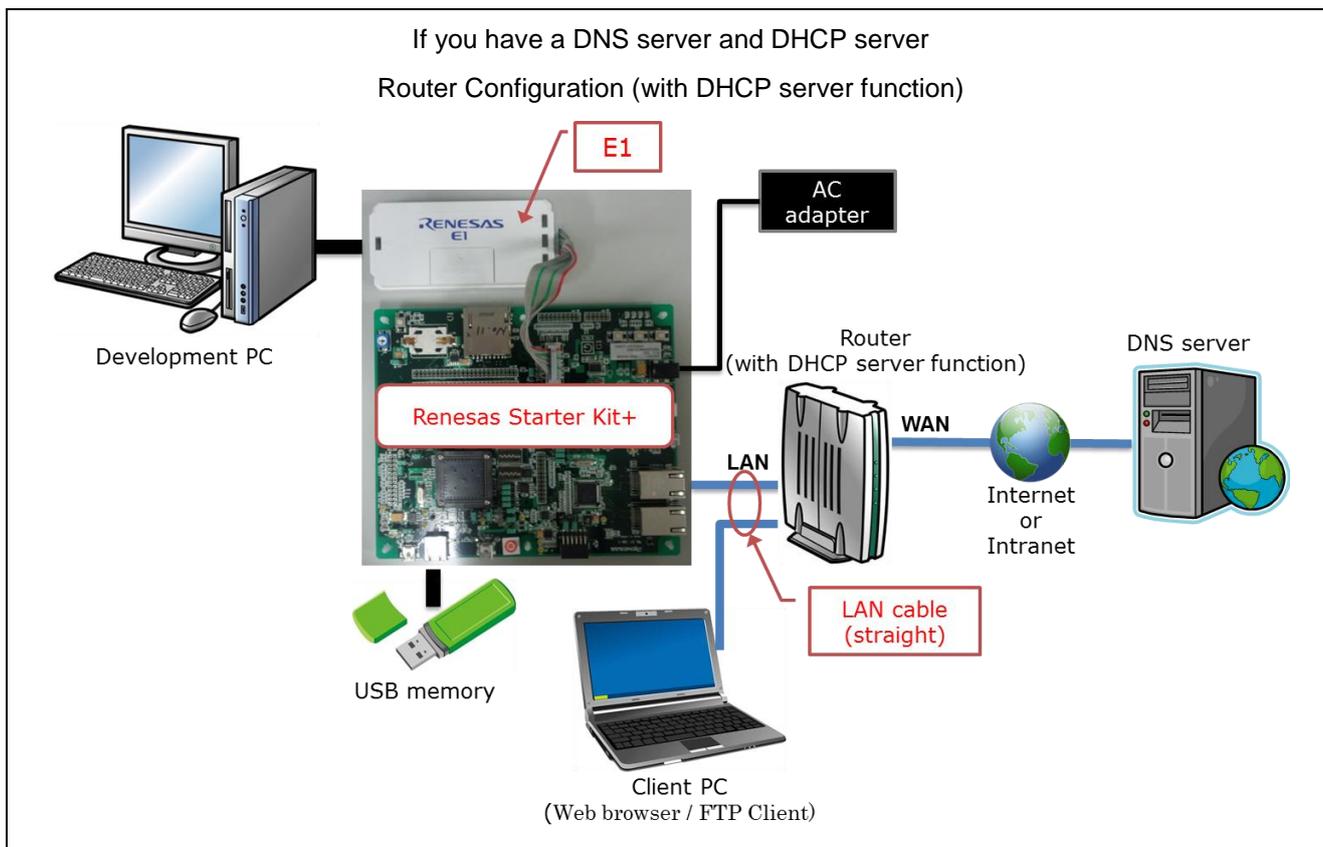


Figure 4-1 DNS server and DHCP server - Router Configuration (with DHCP server function)

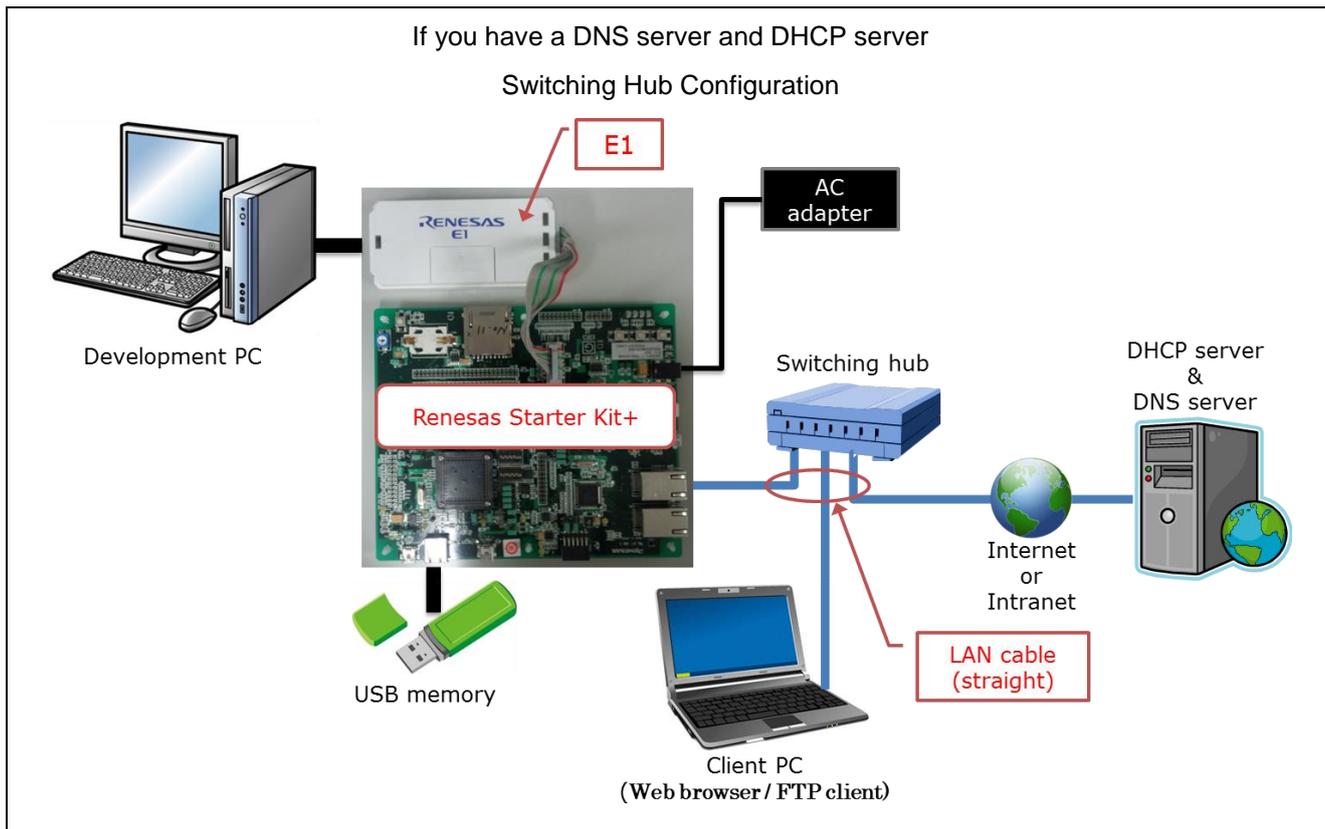


Figure 4-2 DNS server and DHCP server – Switching Hub Configuration

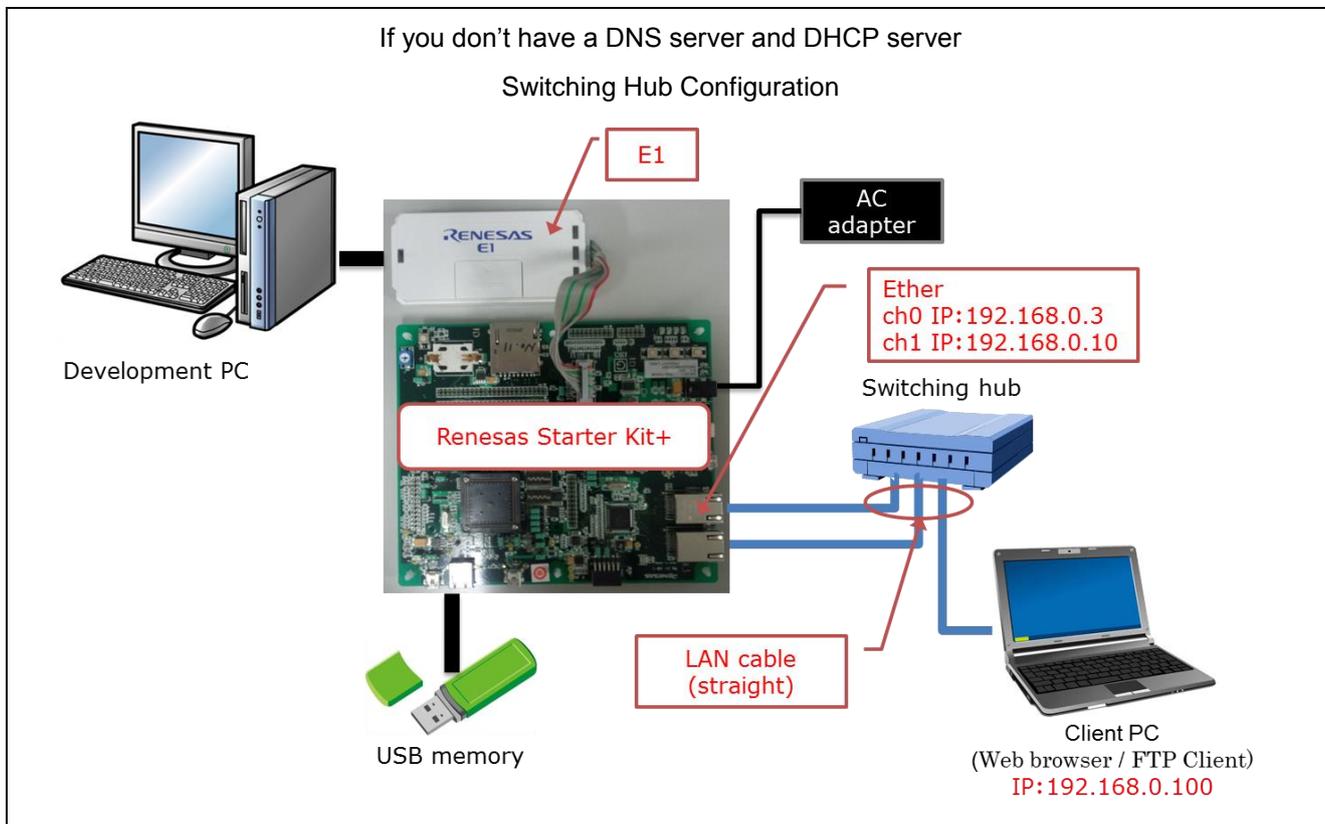


Figure 4-3 No DNS server and No DHCP server – Switching Hub Configuration

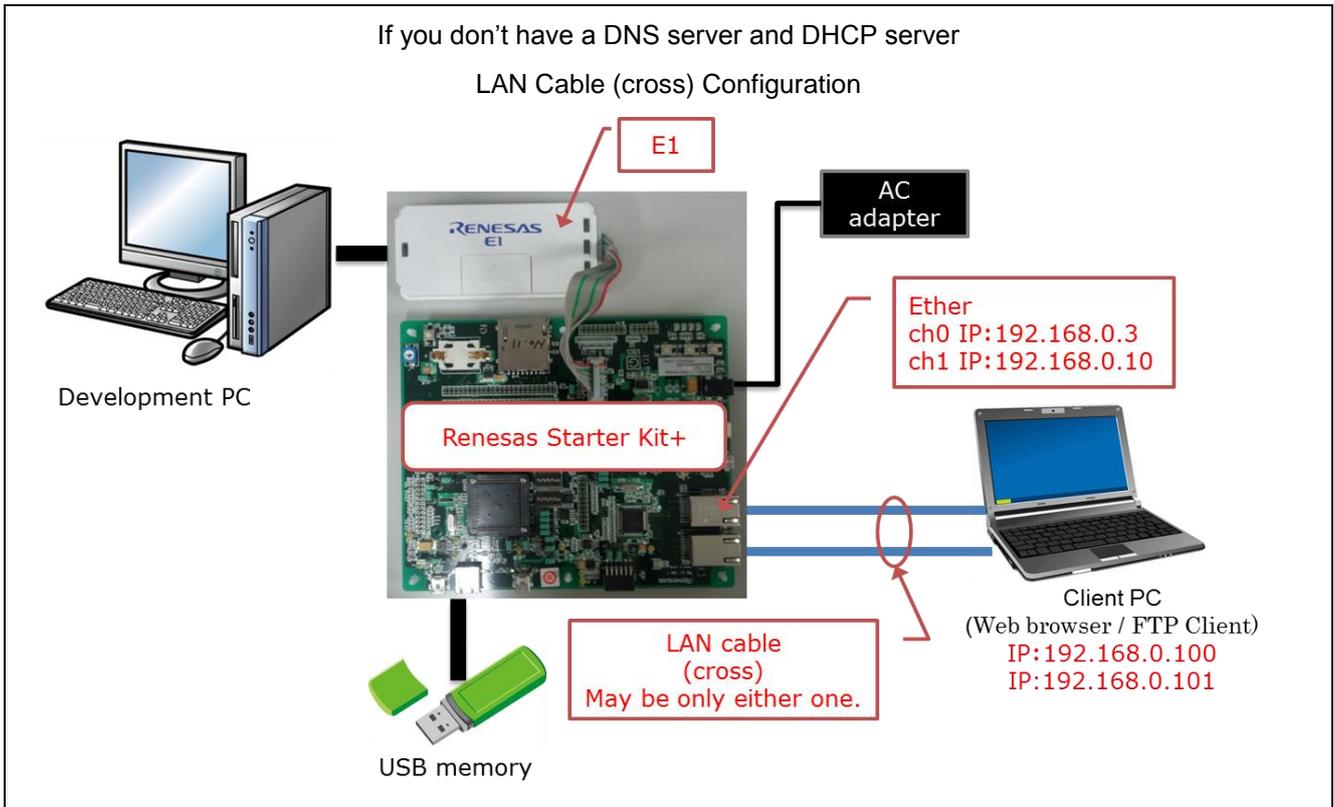


Figure 4-4 No DNS server and No DHCP server – LAN Cable (cross) Configuration

4.2.2 Set Up the Evaluation Board

The evaluation board settings required to operate this application are shown below.

(1) Set Up USB Configuration

1. Set the USB ch0 mode (host/peripheral). Set jumpers J2 and J6 to match the setting of USB_FUNCSEL_USBIP0_PP in r_usb_config.h.
2. Set the USB ch1 mode (host/peripheral). Set jumpers J7 and J9 to match the setting of USB_FUNCSEL_USBIP1_PP in r_usb_config.h.

Table 4-2 Jumper Settings

No.	Setting	Jumper	Setting contents	The setting used to verify the operation
1	When use USB0 in host mode. (USB_FUNCSEL_USBIP0_PP = USB_HOST_PP)	J2	Short 1 to 2.	Unused
		J6	Short 2 to 3.	Unused
	When use USB0 in peripheral mode. (USB_FUNCSEL_USBIP0_PP = USB_PERI_PP)	J2	Short 2 to 3.	Unused
		J6	Short 1 to 2.	Unused
2	When use USB1 in host mode. (USB_FUNCSEL_USBIP1_PP = USB_HOST_PP)	J7	Short 1 to 2.	Used
		J9	Short 2 to 3.	Used
	When use USB1 in peripheral mode. (USB_FUNCSEL_USBIP1_PP = USB_PERI_PP)	J7	Short 2 to 3.	Unused
		J9	Short 1 to 2.	Unused

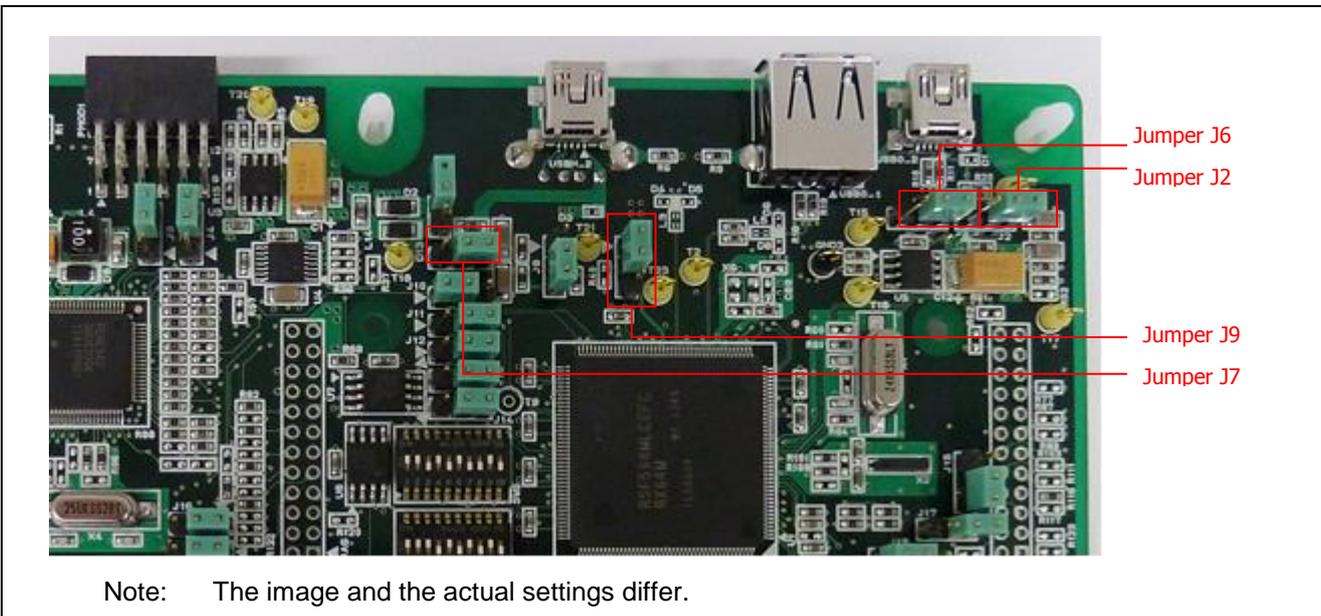


Figure 4-5 Renesas Starter Kit+ for RX64M Jumper Locations [USB]

(2) Set Up Ethernet Configuration

- Specify the PHY IC channel used to control the PHY IC from the Ethernet controller.
Set jumpers J3 and J4 to match the settings of ETHER_CFG_CH0_PHY_ACCESS and ETHER_CFG_CH1_PHY_ACCESS in r_ether_rx_config.h.
- If Ethernet controller (ET0) is used, set the switches and jumpers.
- If Ethernet controller (ET1) is used, set the jumpers.

Table 4-3 Ethernet Setting list

No.	Setting contents	Jumper & Switch		The setting used to verify the operation
		No.	Setting contents	
1	Control PHY IC with ch0	J3	Short 1 to 2	Used
		J4	Short 1 to 2	
	Control PHY IC with ch1	J3	Short 2 to 3	Unused
		J4	Short 2 to 3	
2	When use Ethernet Controller (ET0)	J10	Short 1 to 2	Used
		J11	Short 2 to 3	
		J12	Short 2 to 3	
		J13	Short 2 to 3	
		J14	Short 2 to 3	
		SW5	1 On	
			2 On	
			3 Off	
			4 On	
			5 Off	
			6 On	
			7 Off	
			8 Off	
			9 On	
			10 Off	
		SW6	1 On	
			2 On	
			3 On	
			4 Off	
			5 On	
			6 Off	
			7 On	
			8 Off	
			9 On	
			10 Off	
		SW7	1 On	
			2 Off	
			3 Off	
			4 On	
			5 Off	
6 Off				
7 On				
8 Off				
9 On				
10 Off				
3	When use Ethernet Controller (ET1)	J16	Short 1 to 2	Unused
		J18	Short 1 to 2	
		J20	Short 1 to 2	

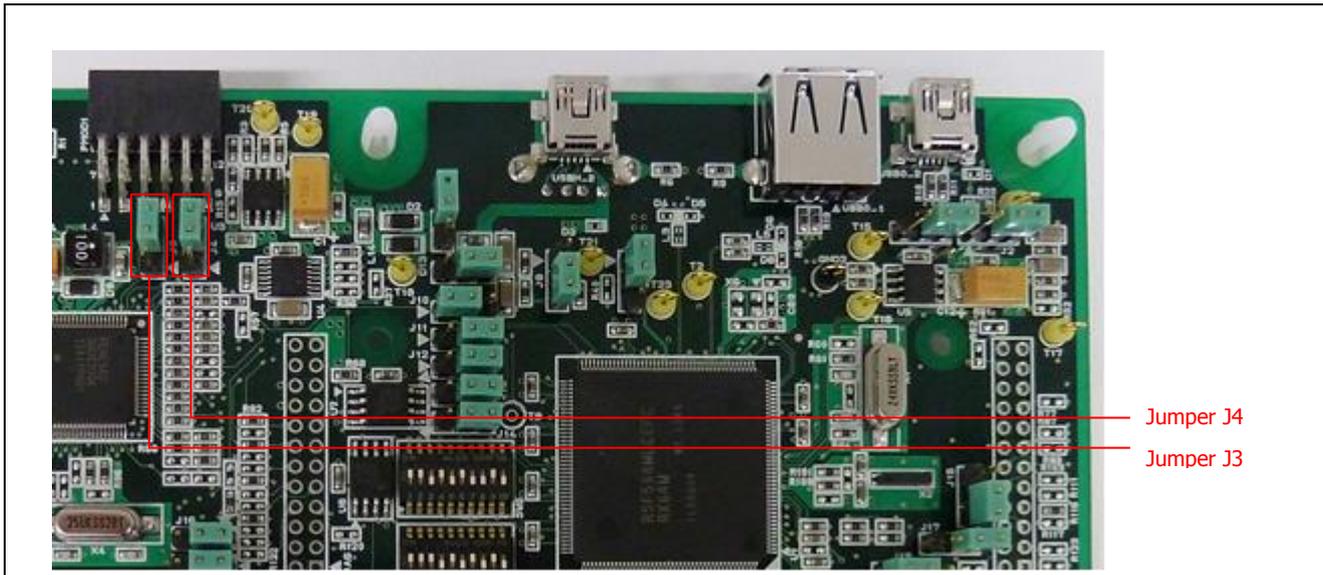


Figure 4-6 Renesas Starter Kit+ for RX64M/RX71M Jumper locations [Ethernet Controller PHY IC]

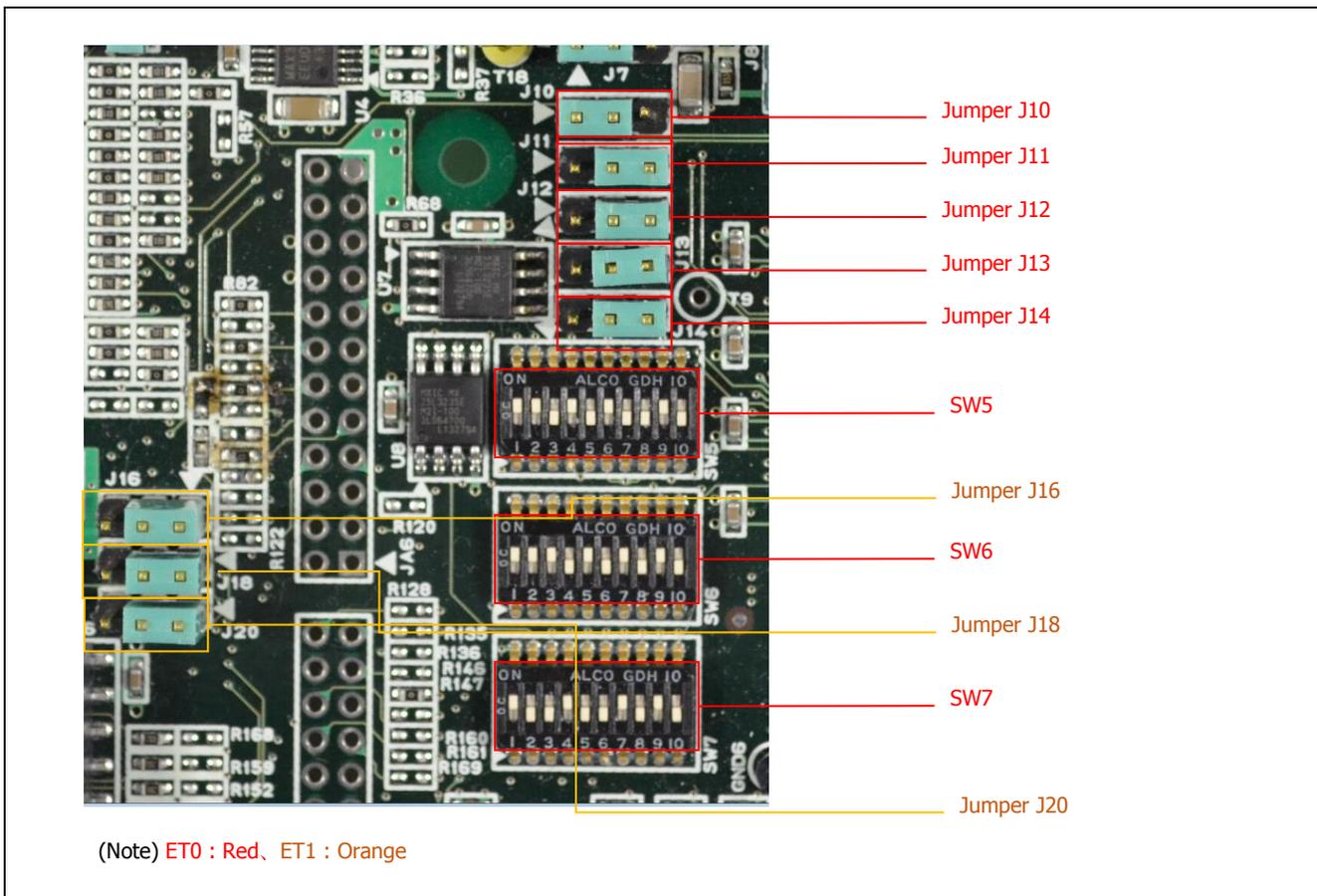
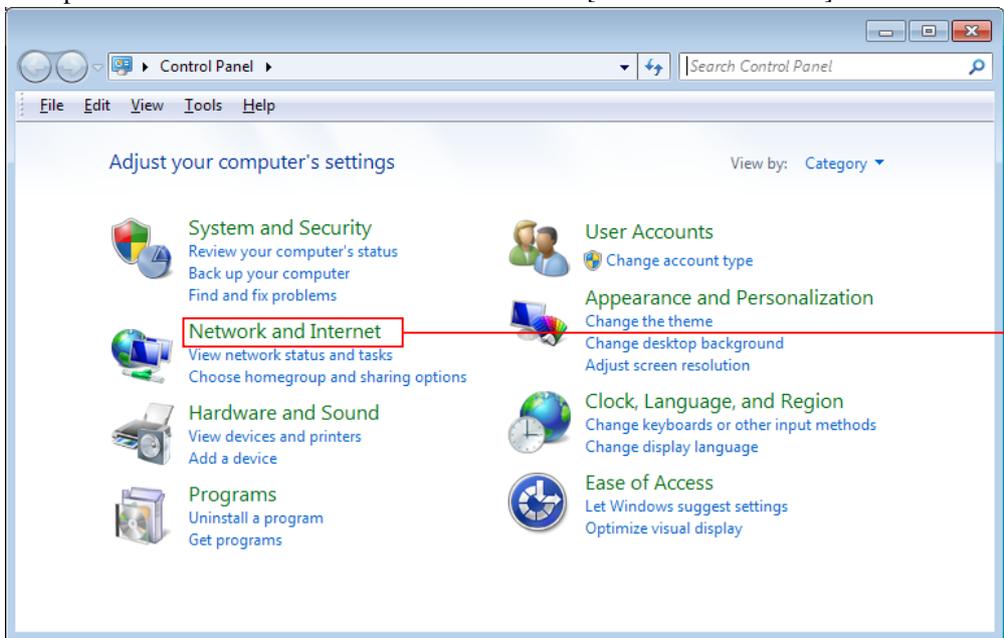


Figure 4-7 Renesas Starter Kit+ for RX64M/RX71M Jumper locations [Ethernet Controller ET0/ET1]

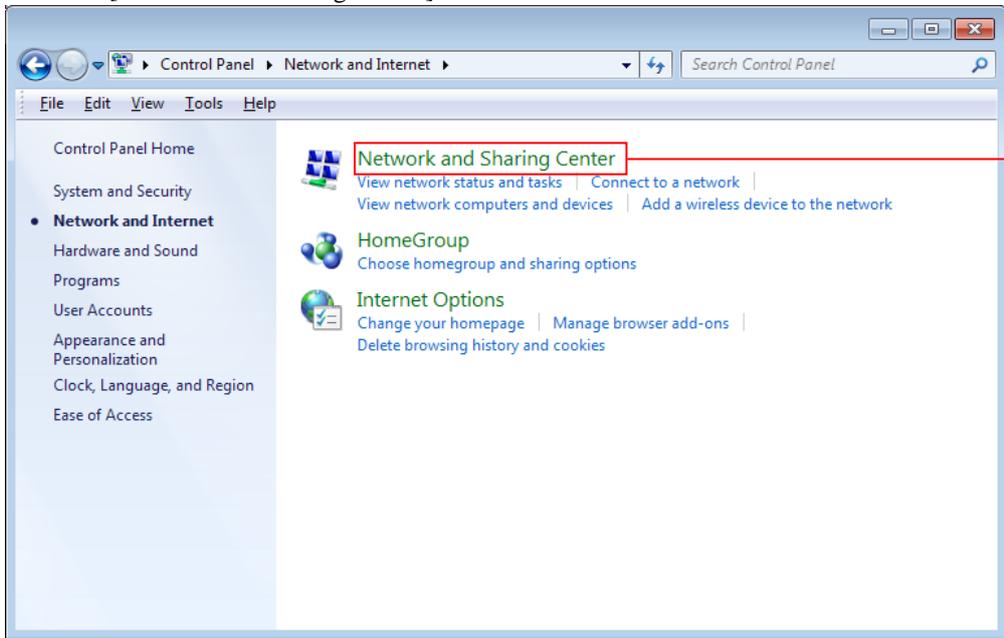
4.2.3 Set Up Client PC

Set up the network on the client PC. This section shows the procedure when using Windows 7 as an example.

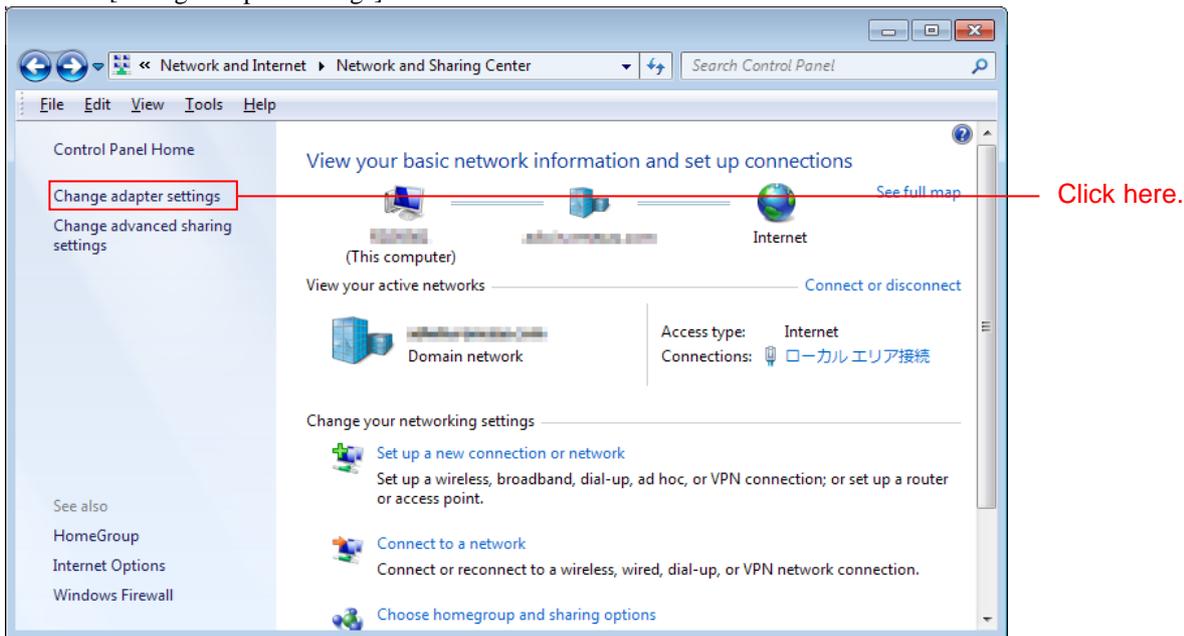
1. Open the Control Panel on the client PC and click [Network and Internet].



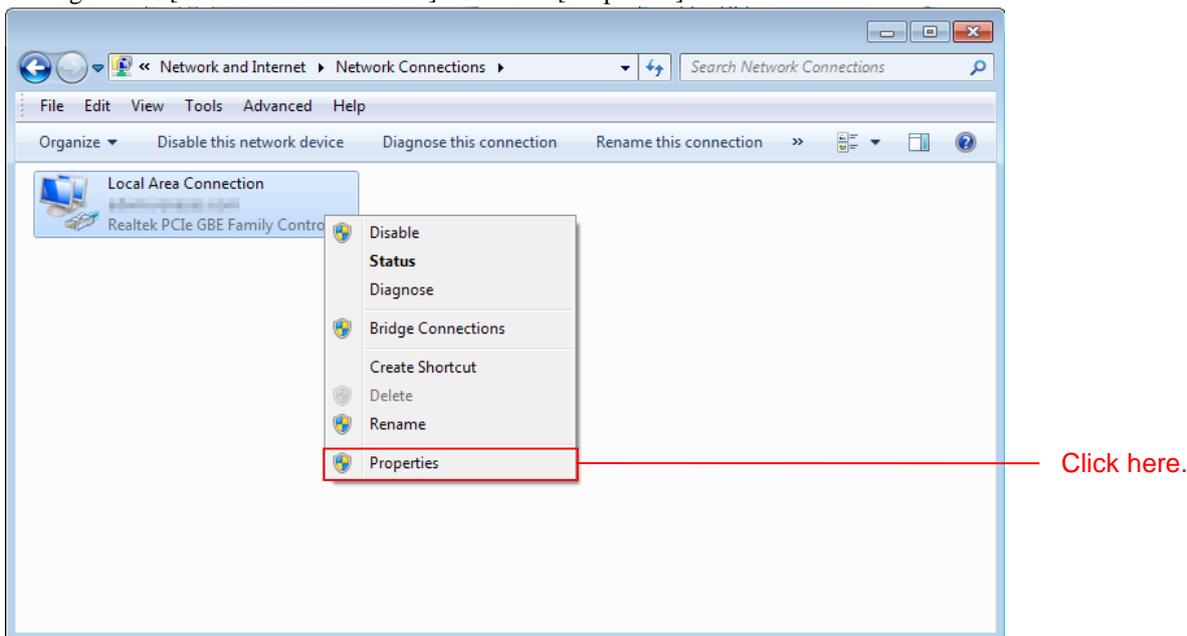
2. Click [Network and Sharing Center].



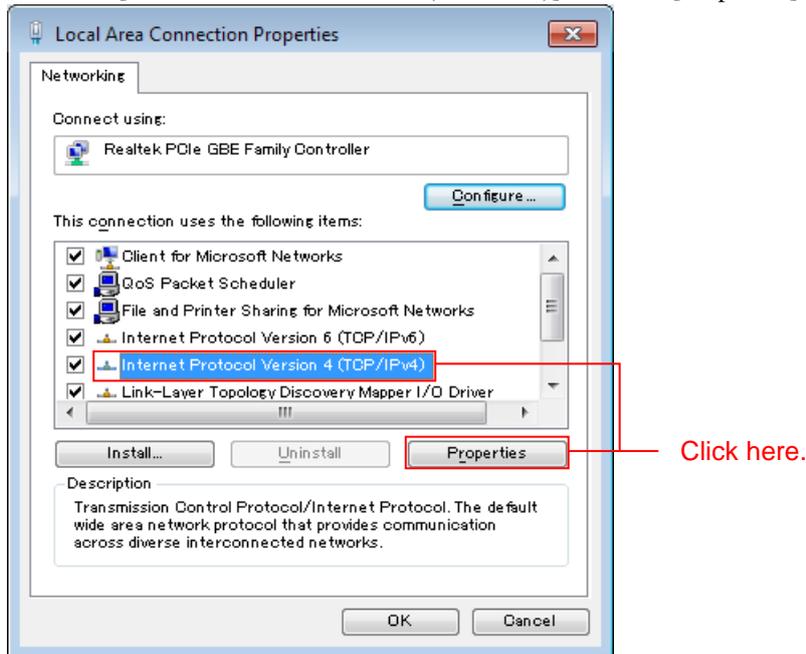
3. Click [Change adapter settings].



4. Right click [Local Area Connection] and select [Properties].

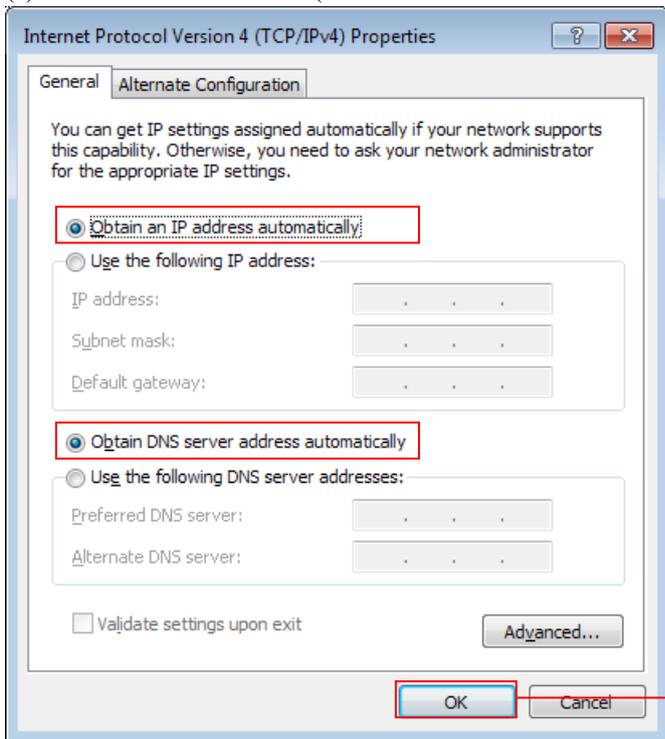


5. Select [Internet Protocol Version 4 (TCP/IPv4)] and click [Properties].



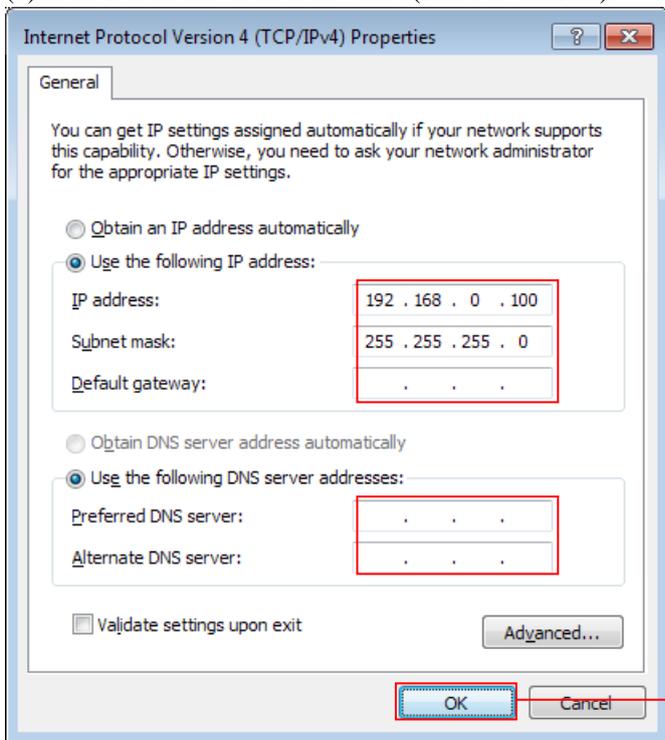
6. The IP address and other settings will be displayed. Set these as shown below and click [OK] depending on the existence of a DHCP server.

(a) If exist the DHCP server (Obtain an IP address automatically).



Click here.

(b) If the DHCP server does not exist (Fixed IP address).

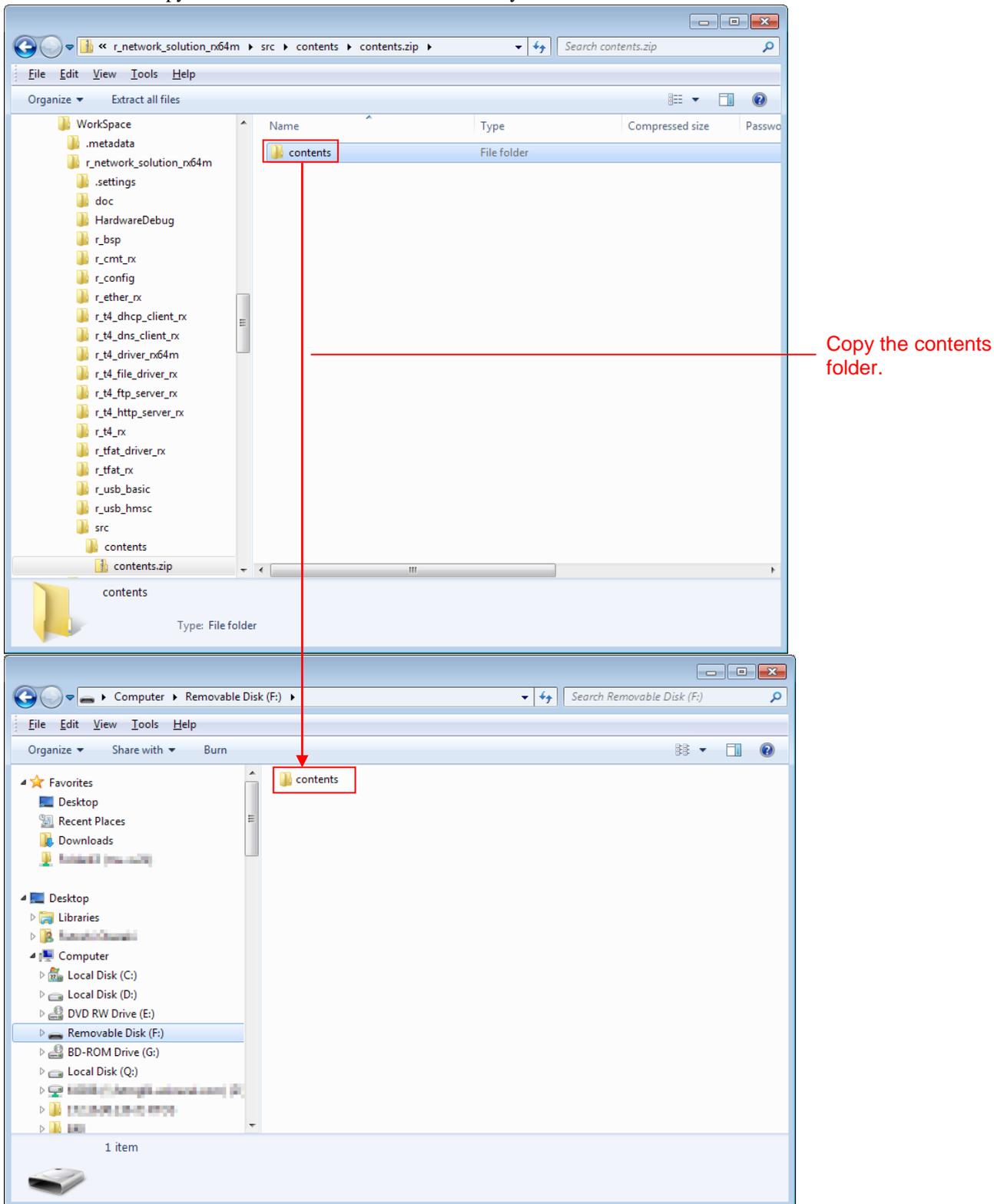


Click here.

4.2.4 Prepare USB Memory

Store the HTML content on the USB memory.

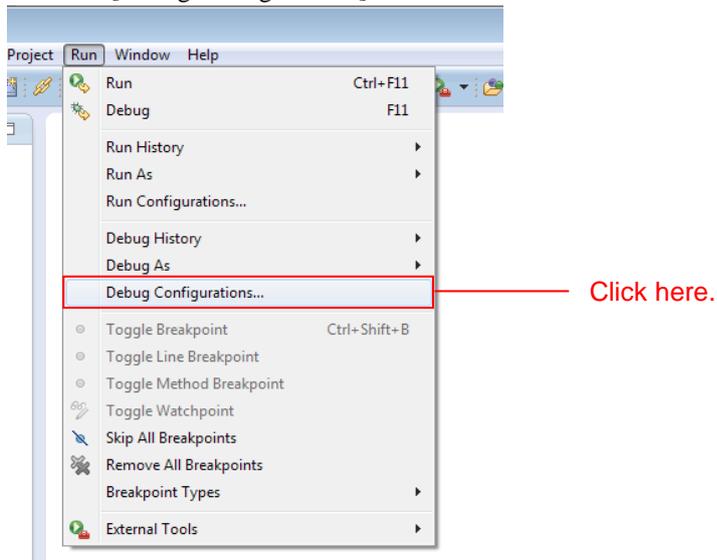
1. Open the **src** folder in the project, then open the **contents** folder in the folder. Open the **contents.zip** file in the **contents** folder. Copy the **contents** folder to the USB memory.



4.3 Debug the Project

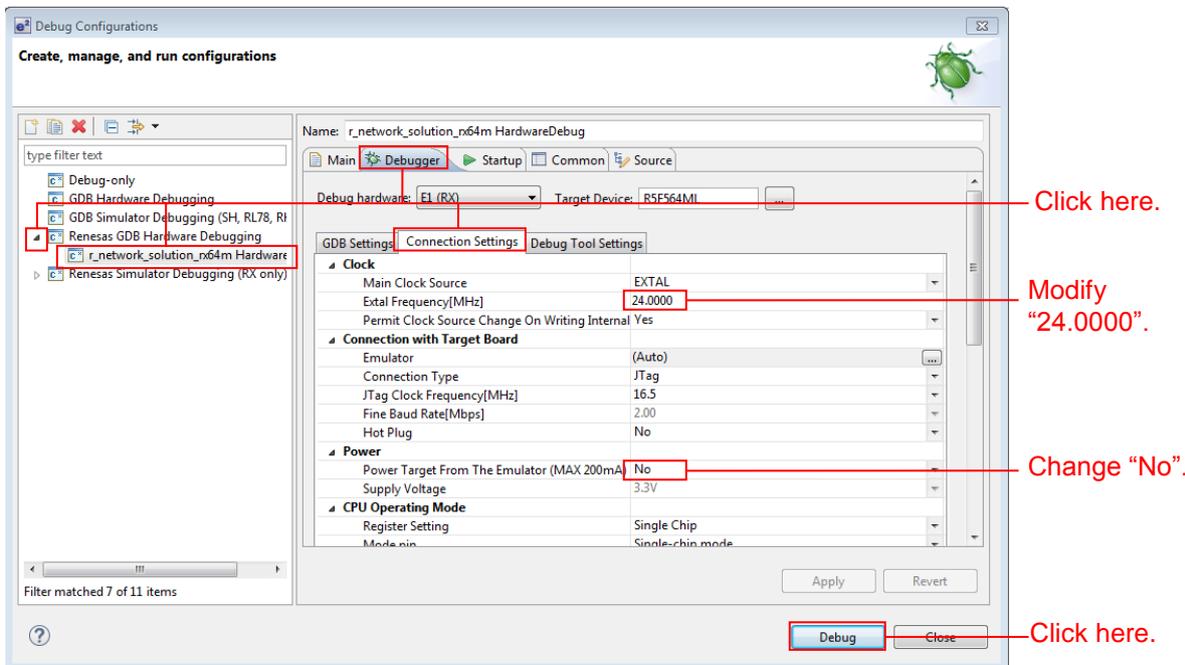
Use the following procedure to start debugging the project.

1. Connect the development PC to the E1 emulator with a USB cable.
2. Connect the evaluation board (Renesas Starter Kit+ for RX64M or Renesas Starter Kit+ for RX71M) to the adapter and turn on the power.
3. Click [Debug Configurations] in the e² studio **Run** menu.

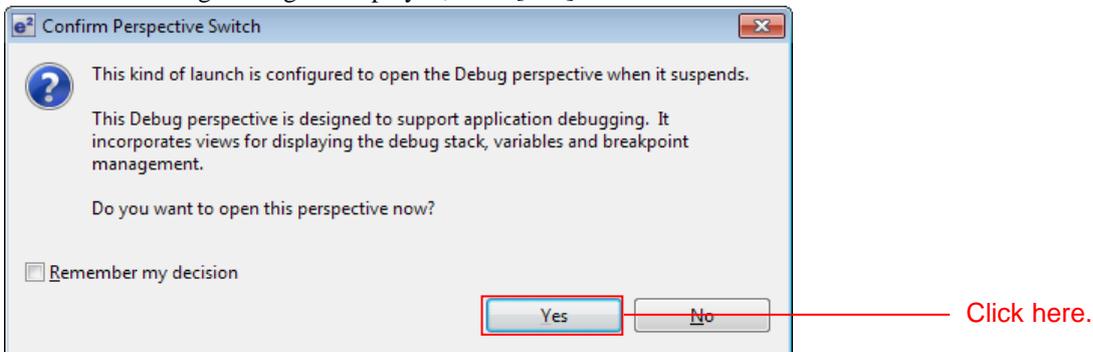


- 4. Click on [r_network_solution_rx64m HardwareDebug] or [r_network_solution_rx71m HardwareDebug] under [Renesas GDB Hardware Debugging] and click on [Debug].
Click on the [Debugger] tab, and the [Connection Setting] tab.
Change [EXTAL frequency] to 24.0000, then, [Power target from the emulator] to [No (Note 1)].
When completed, click on [Debug (D)].

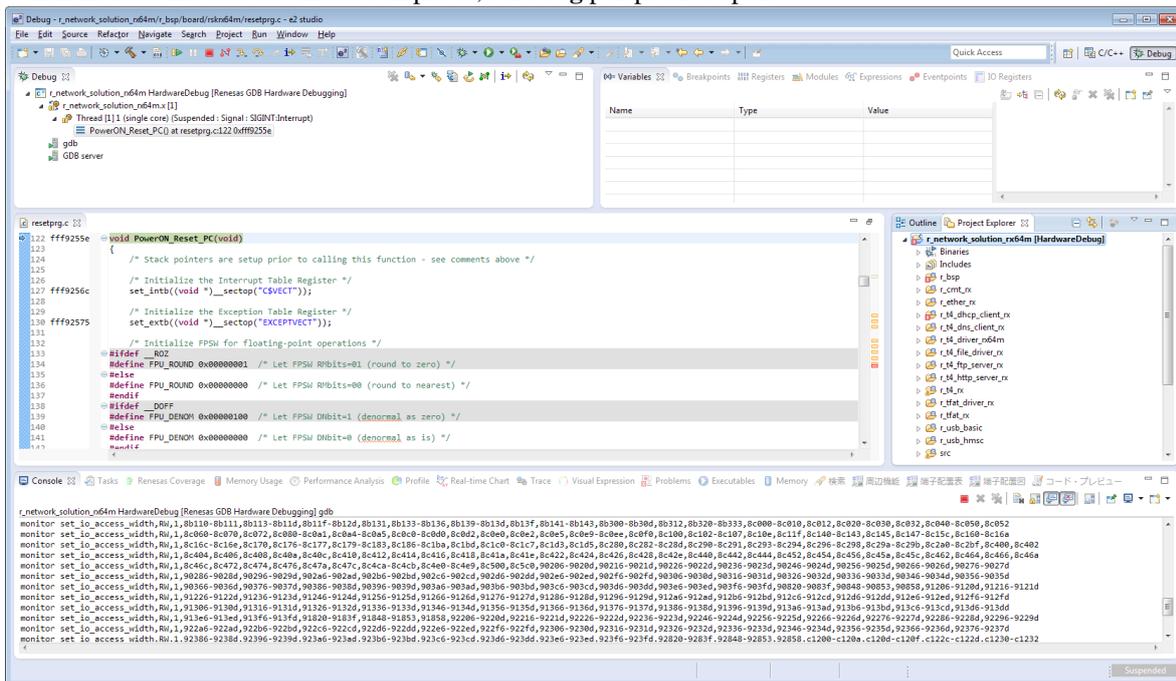
Note 1 : The setting is used when using an external power supply. Select [Yes] for Power target from the emulator.



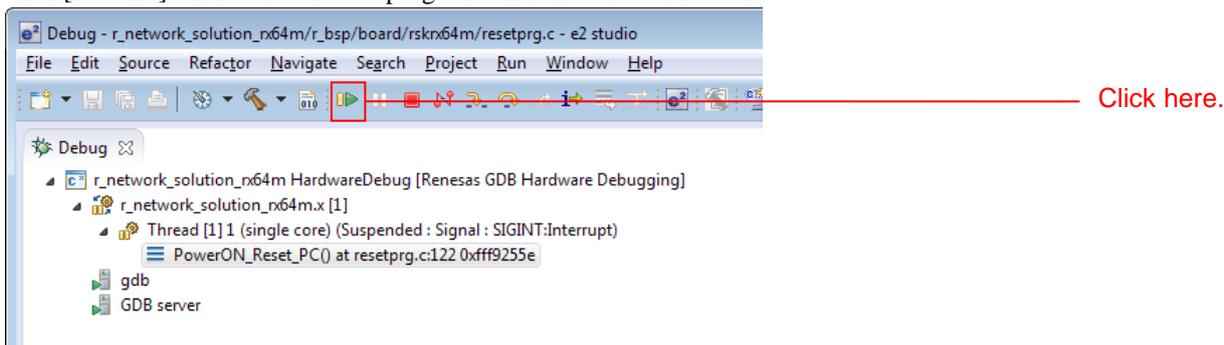
When the following message is displayed, click [Yes].



When the load module download completes, a **Debug** perspective opens.



5. Click [Resume] on the toolbar. The program will be executed and a break will occur at the start of the main function.



6. After the break at the start of the main function, click [Resume] on the tool bar again.

4.3.1 Verify operation of the HTTP server

1. Start a web browser on the client PC and enter the following address according to which port the LAN cable is connected.

Ethernet Port Number	DHCP server	Web Server Address
0	Not existing	http://192.168.0.3 (can be changed in the configuration file.)
	Existing	Obtain from DHCP server
1	Not support	http://192.168.0.10

Note: Note that the http server address can be changed in the configuration file.

The procedure for confirmation about IP address obtained from the DHCP server is shown below.

When complete the connection, open the **src/main.c**.

Set the breakpoint to the **nop()** function in main().

```

150
151 ffc024a8  if (!r_dhcp_open(&dhcp, (unsigned char*)tcpudp_work, &myethaddr[0][0]))
152 {
153 ffc024c5      set_tcpudp_env(&dhcp);
154 }
155 ffc024c8      CloseTimer();
156
157 ffc024cc  if (NULL != &dhcp)
158 {
159 ffc024d0      nop();
160 }
161
162
163 ffc024d1      /* Get the size of the work area used by the T4 (RAM size). */
164 ffc024d5      ramsize = tcpudp_get_ramsize();
165              if (ramsize > (sizeof(tcpudp_work)))
166 {
167              /* Then reserve as much memory array for the work area as the size
168              indicated by the returned value. */
169              for( ;; );
170 }
171
172              /* Initialize the TCP/IP */
    
```

Execute a Program to confirm the program stopped at the set breakpoint.
Then, confirm the variables "dhcp" in the watch window.

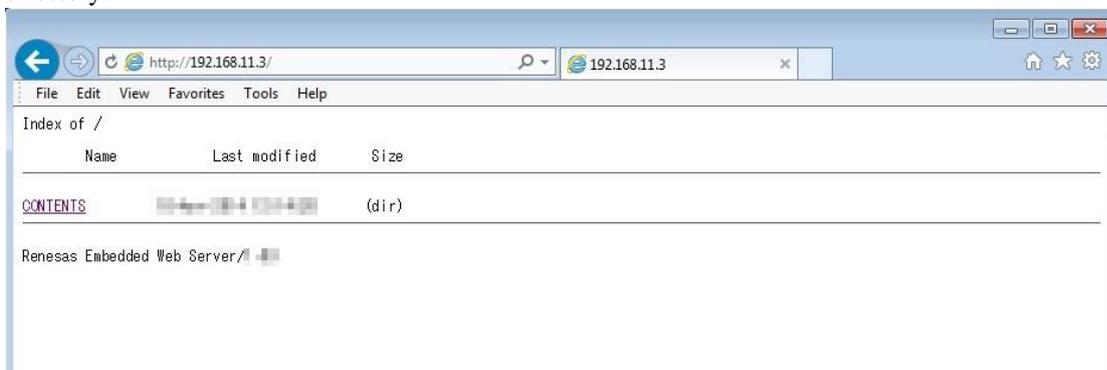
The information set to each member of the variables "dhcp" :

- ipaddr : IP address
- maskaddr : Subnetmask
- gwaddr : Gateway address
- dnsaddr : Primary DNS server IP address
- dnsaddr2 : Secondary DNS server address

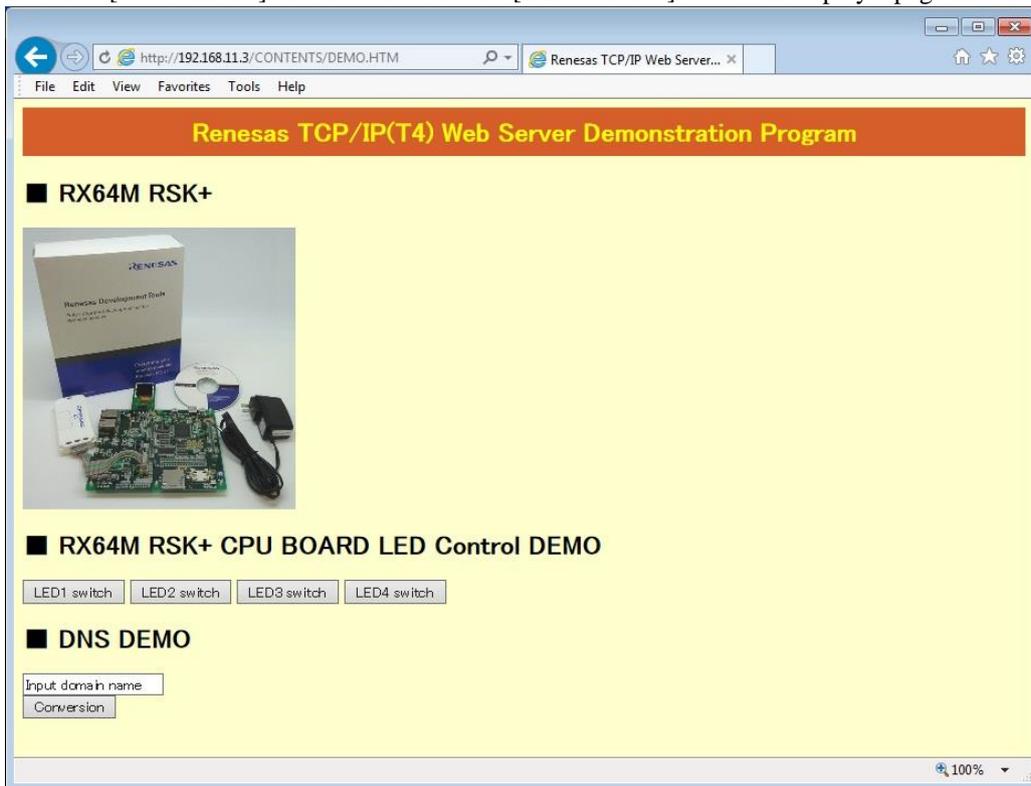
dhcp	DHCP	{...}
ipaddr	uint8_t [4]	0x2802
ipaddr[0]	uint8_t	192 '9'
ipaddr[1]	uint8_t	168 '4'
ipaddr[2]	uint8_t	0 '0'
ipaddr[3]	uint8_t	3 '003'
maskaddr	uint8_t [4]	0x2806
gwaddr	uint8_t [4]	0x280a
dnsaddr	uint8_t [4]	0x280e
dnsaddr2	uint8_t [4]	0x2812
domain	char [20]	0x2816
macaddr	uint8_t [6]	0x282a

A list of files in the root directory on the USB memory is displayed.

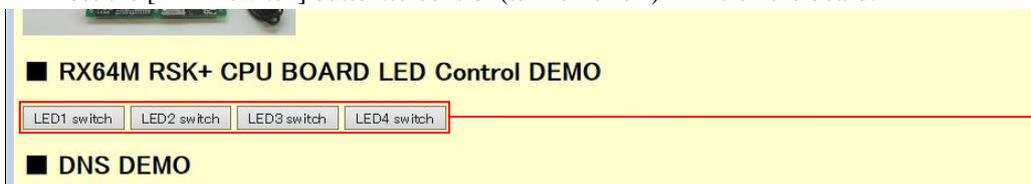
The file name is listed in the Name field, the last update date is listed in the Last modified field. For size, if it is directories, (dir) is listed and the size is shown in bytes. Click on [Parent Directory] to move to the next higher directory.



2. Click [CONTENTS] and then click the file [DEMO.HTM]. This will display a page like the one shown below.

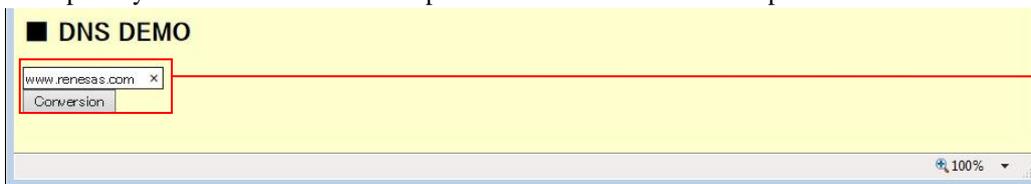


3. Confirm LED control using CGI function
Press the [LEDx switch] button to control (turn on or off) LEDs on the board.



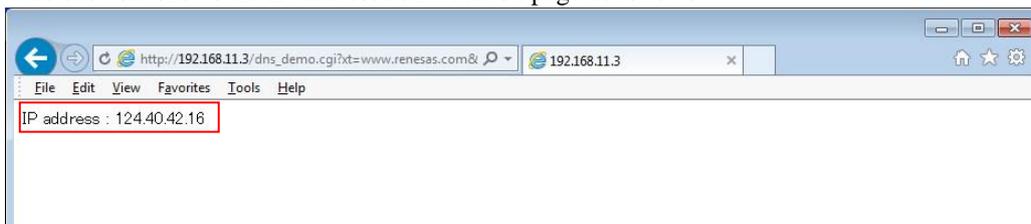
Click here.

4. Confirm DNS client function using CGI function
Input any domain name into the "Input domain name" text box and push "Conversion" button.



Input domain name and Click here.

Web browser shows the IP address confirmation page as follows.

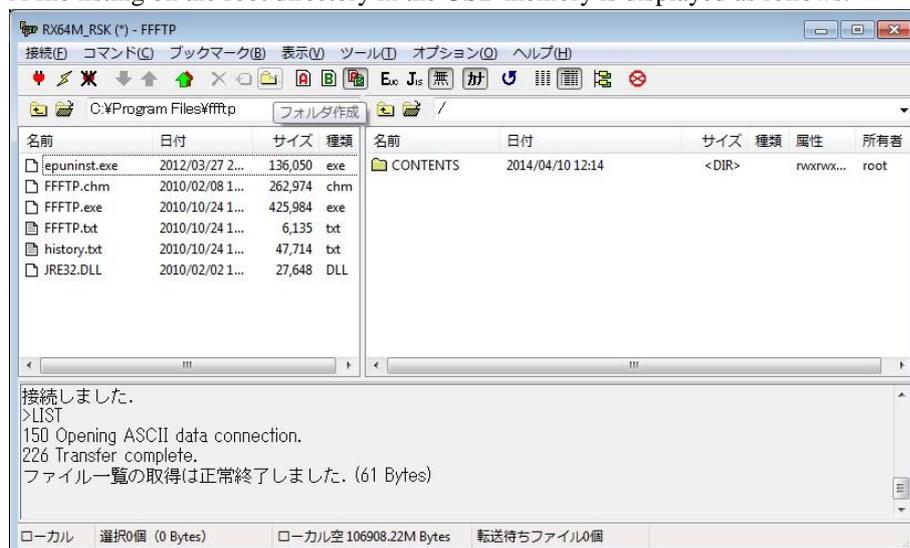


4.3.2 Verify operation of the FTP server

1. Start FTP client software (e.g. FFFTP).
2. Use the user name and password that is defined to "r_t4_ftp_server_rx_config.h", connect to IP address below.

Ethernet Port Number	DHCP server	FTP Server Address
0	Not existing	http://192.168.0.3 (can be changed in the configuration file.)
	Existing	Obtain from DHCP server
1	Not support	Not support

A file listing on the root directory in the USB memory is displayed as follows.



Note: This shows the example using the FTP Client software (Japanese version).

5. Network Middleware Specifications

For the specifications of the DHCP client, DNS client, HTTP server and FTP server, refer to the document attached to each FIT module.

6. Main Program Specifications

6.1 Files

The main program is included in the project. The source files of the main program is included in the `src` folder. The files of the main program are listed below.

Table 6-1 Main Program Files

Folder Name	File Name	Description
src	main.c	Main source file
	led.c	LED initialization processing source file
	led.h	LED initialization processing header file
	r_http_server_cgi_sample.c	CGI sample source file
	r_sys_time.c	HTTP server system timer source file
	r_sys_time.h	HTTP server system timer header file
	r_usb_hmsc_api.c	USB driver call processing source file
	r_usb_hmsc_api.h	USB driver call processing header file
src/contents	contents.zip	ZIP file of HTML content to be stored in the USB memory

6.2 Modules

The following table lists the modules in the main program.

Table 6-2 Main Program Modules

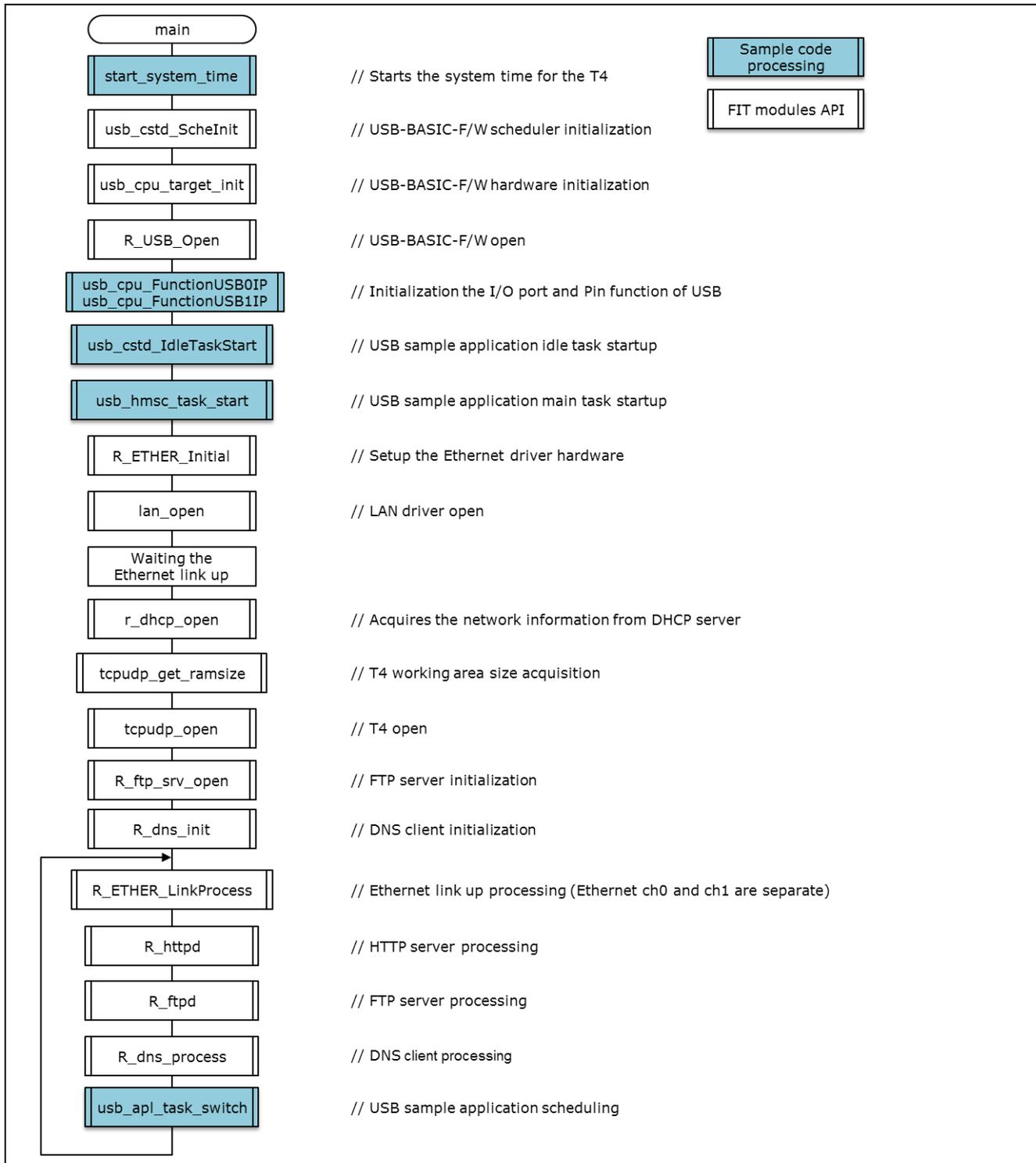
File Name	Module Name	Description
main.c	main	Main processing for the main program Calls initialization processing for each of the FIT modules and drives the main processing for the DNS client, HTTP server, FTP server, USB driver, and Ethernet driver (uses an infinite loop to implement periodic activation).
	set_tcpudp_env	Setting the network information which obtained from DHCP server to the environment variable of T4.
	usb_cpu_FunctionUSB0IP	Port initialization and Pin setting of USB ch0.
	usb_cpu_FunctionUSB1IP	Port initialization and Pin setting of USB ch1.
r_usb_hmsc_api.c	usb_cstd_IdleTaskStart	Starts the idle task used in low-power mode.
	usb_cstd_IdleTask	Idle task used in low-power mode. Performs no processing in host operation.
	usb_hmsc_task_start	HMSC driver activation processing. Performs USB IP initialization and class driver registration.
	usb_apl_task_switch	Performs task scheduling for the USB drivers in non-OS environments.
	usb_hapl_task_start	Starts the HMSC driver application task.
	usb_hmsc_DummyFunction	HMSC driver dummy function
	usb_hmsc_DriveOpen	HMSC driver open processing
	usb_hapl_registration	Registers HMSC drivers.
	usb_hmsc_apl_init	Initializes HMSC driver application task internal variables.
	usb_hmsc_StrgCommandResult	R_usb_hmsc_StrgDriveSearch() callback processing
	usb_hmsc_SampleAplTask	HMSC driver application task processing. Detects USB memory and mounts the file system.
led.c	led_init	Initialization of LEDs
r_http_server_cgi_sample.c	-	Please refer to the attached document to HTTP server module (RX Family Web server using the embedded TCP/IP M3S-T4-Tiny Module Firmware Integration Technology / R20AN0075EJ).
r_sys_time.c	get_sys_time	Please refer to the attached document to HTTP server module (RX Family Web server using the embedded TCP/IP M3S-T4-Tiny Module Firmware Integration Technology / R20AN0075EJ).
	start_system_time	Start the timer for HTTP server.
	update_sys_time	Interrupt handler of the timer for HTTP server.
	stop_system_time	Stop the timer for HTTP server.

6.3 Flowcharts

This section shows the flowcharts for the modules in the main program.

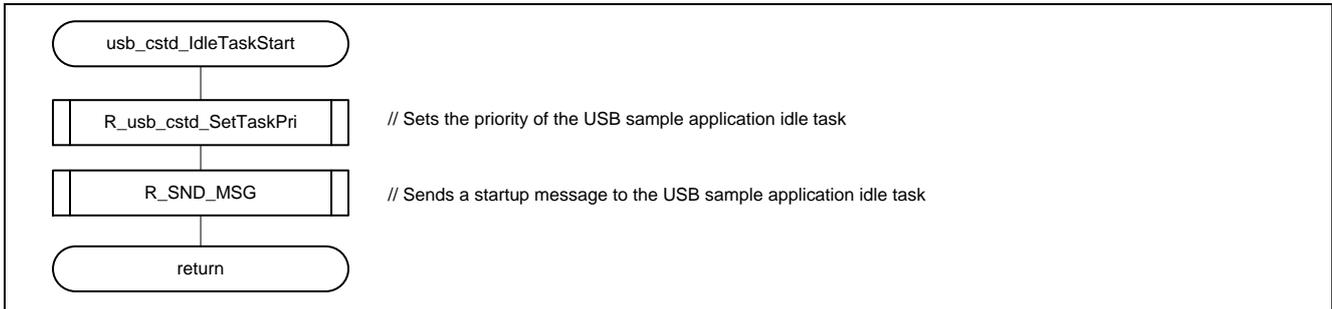
(1) main()

This is the main() function and is first called from the startup routine for the board support package (BSP module). It initializes the drivers and T4 and then periodically calls Ethernet driver link up processing, DNS client, HTTP server and FTP server main processing, and USB driver scheduling from an infinite loop.



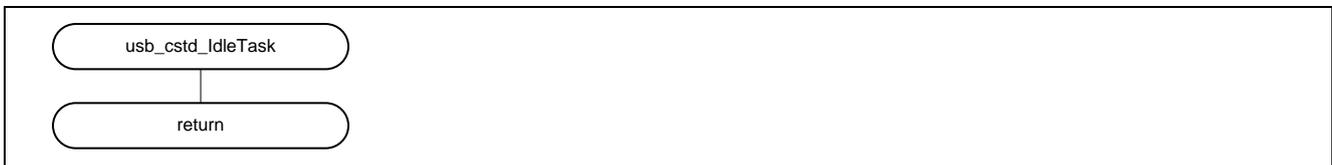
(2) usb_cstd_IdleTaskStart

Starts the USB driver processing idle task.



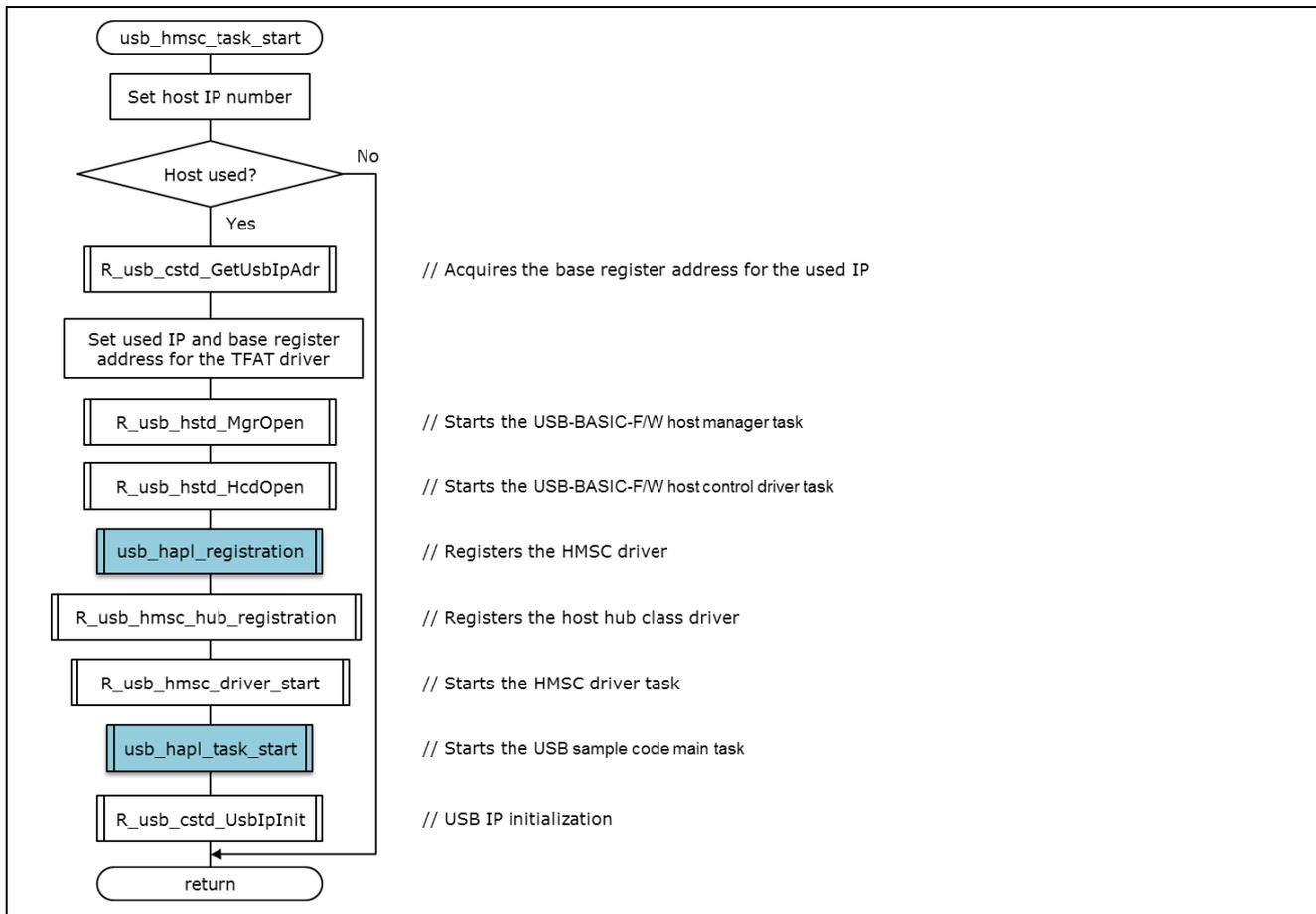
(3) usb_cstd_IdleTask

This is the USB driver processing idle task.



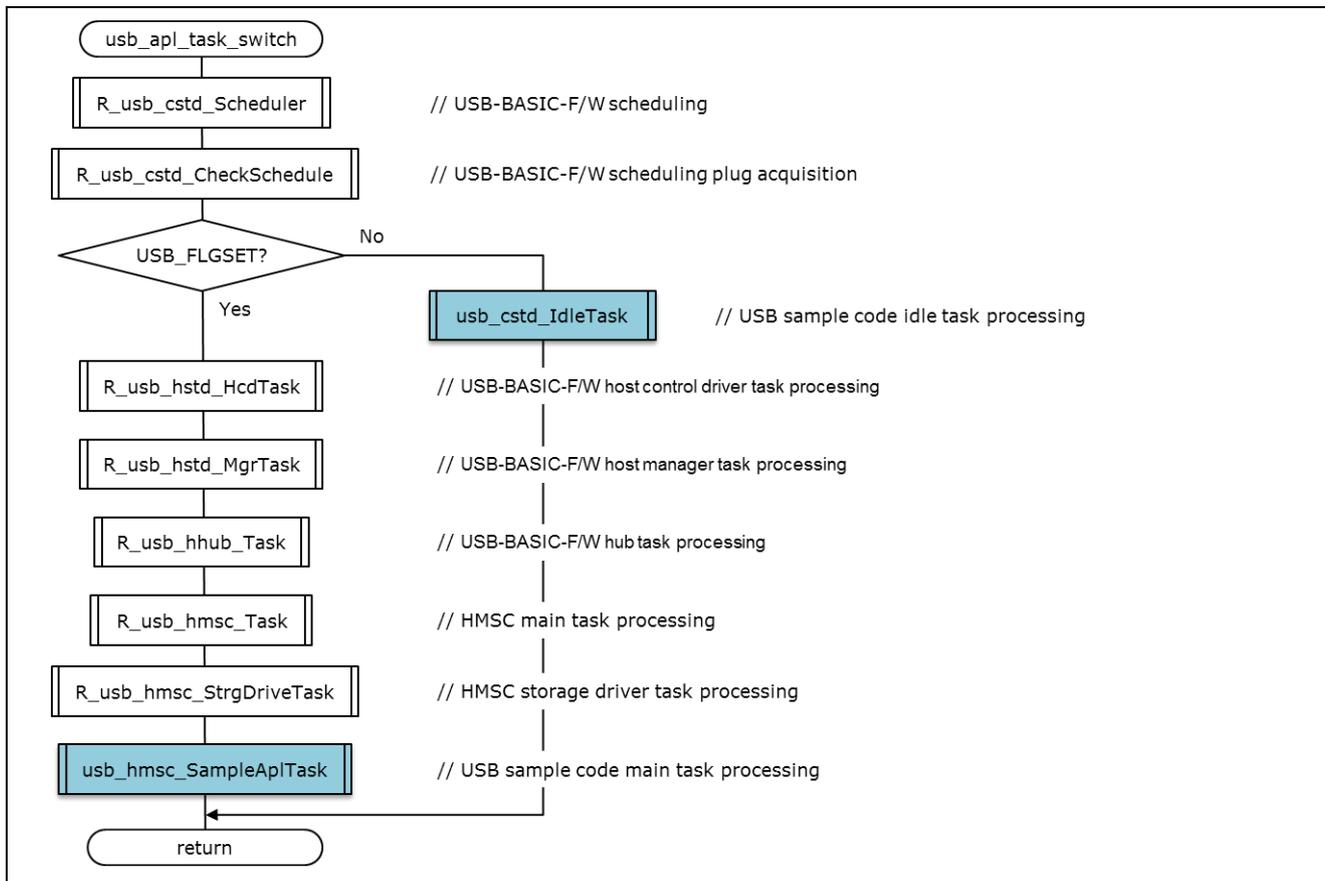
(4) usb_hmsc_task_start

Starts the various tasks within the USB driver, registers class drivers, and starts the USB memory mount processing task.



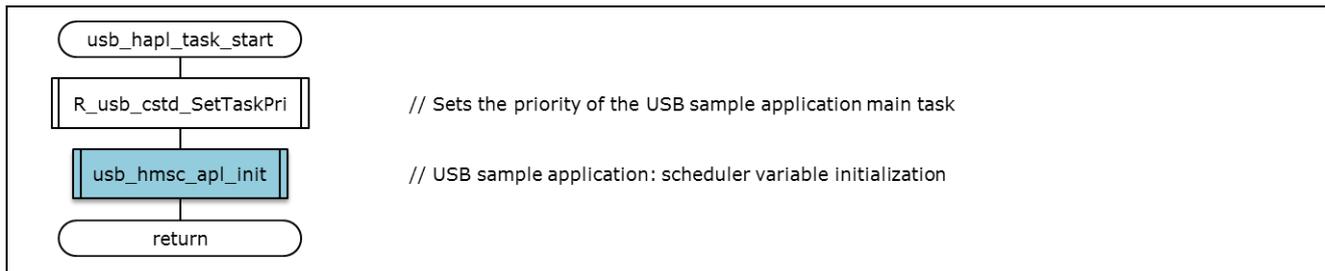
(5) usb_apl_task_switch

Performs the USB driver scheduling.



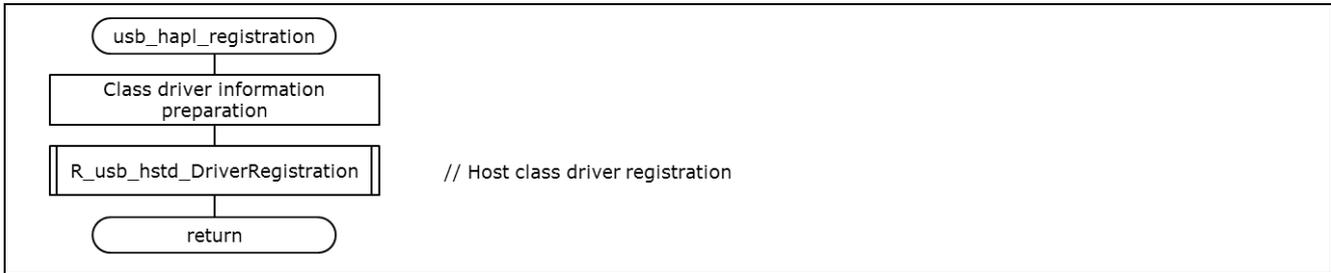
(6) usb_hapl_task_start

Initializes the USB memory mount processing task.



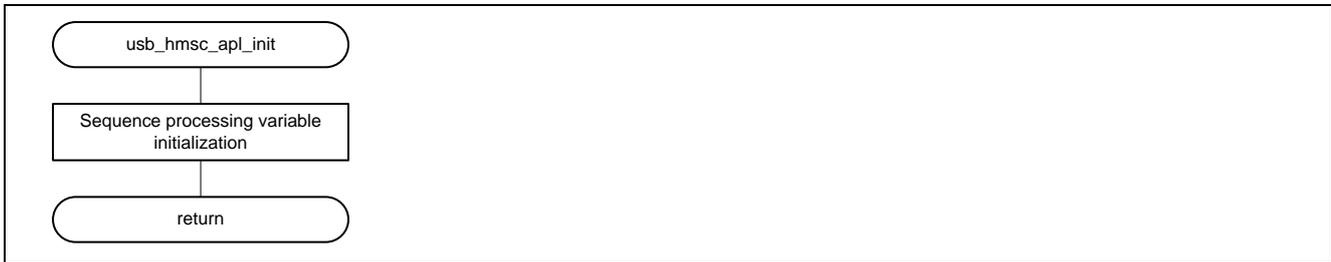
(7) usb_hapl_registration

Performs the class driver registration processing.



(8) usb_hmsc_apl_init

Initializes the sequence processing variables for the USB memory mount processing task.



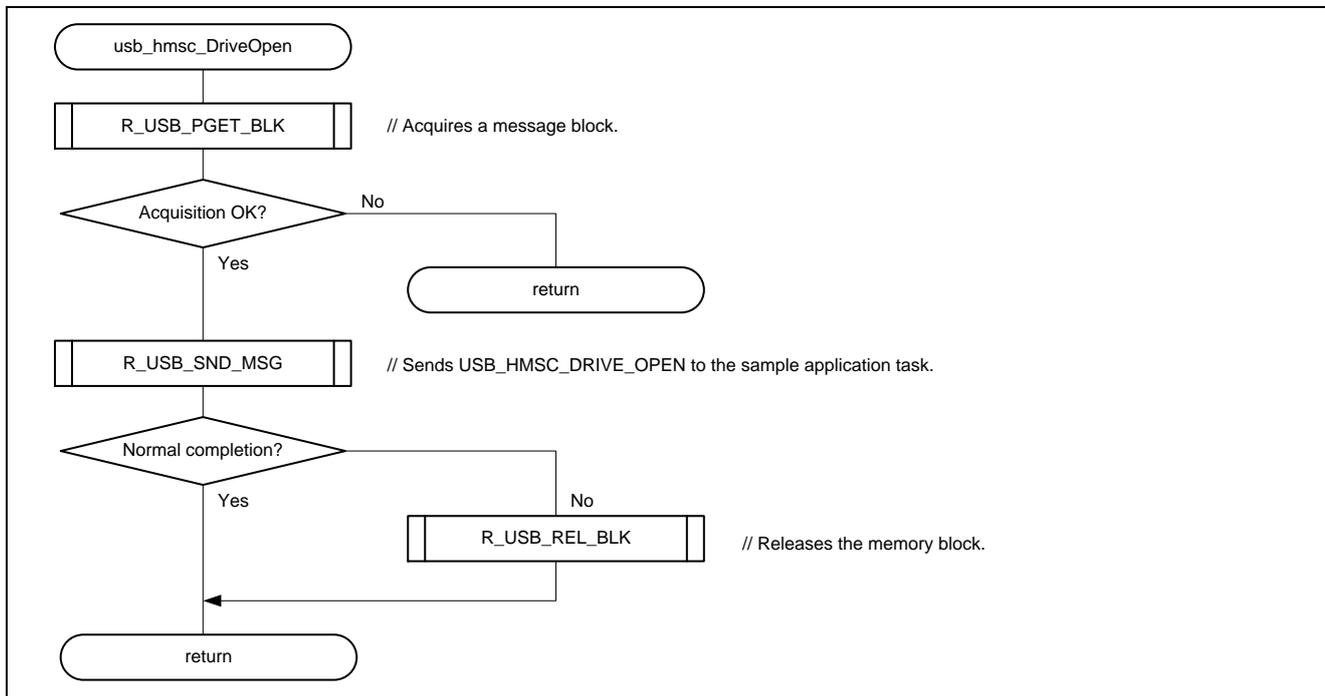
(9) usb_hmsc_DummyFunction

Dummy function for suspend and resume specified at class driver registration.



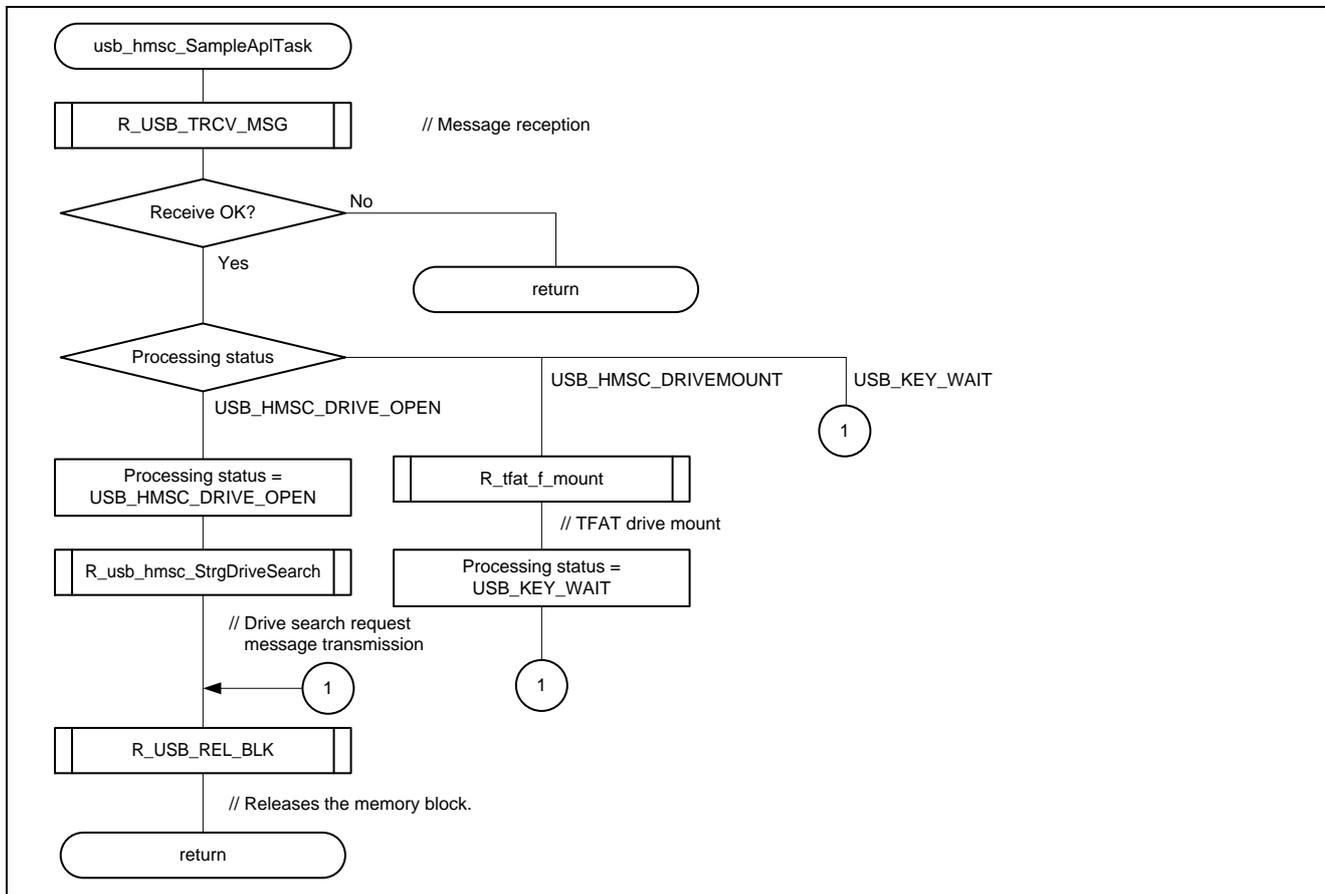
(10) usb_hmsc_DriveOpen

This is the callback function called from the USB driver when USB memory is inserted. It sends a USB_HMSC_DRIVE_OPEN message for the sample application task.



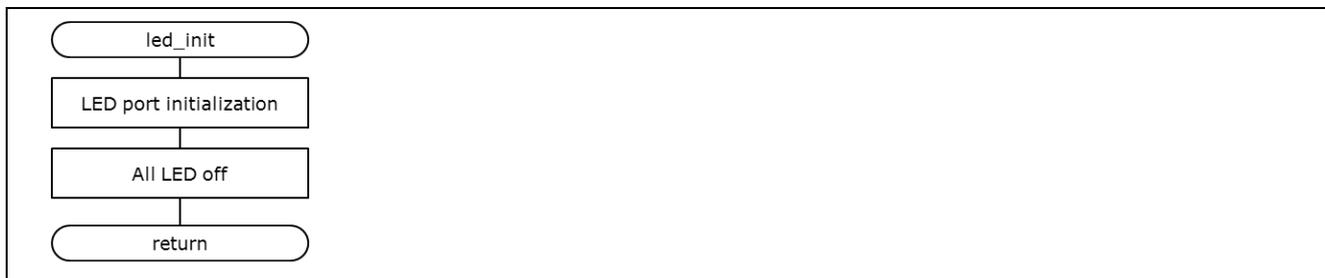
(11) usb_hmsc_SampleAplTask

This function performs the sample application task processing. It receives the USB_HMSC_DRIVE_OPEN message issued from the usb_hmsc_DriveOpen function and detects a mountable drive. Also, it receives the USB_HMSC_DRIVEMOUNT message issued from the usb_hmsc_StrgCommandResult function and performs a mount for the file system.



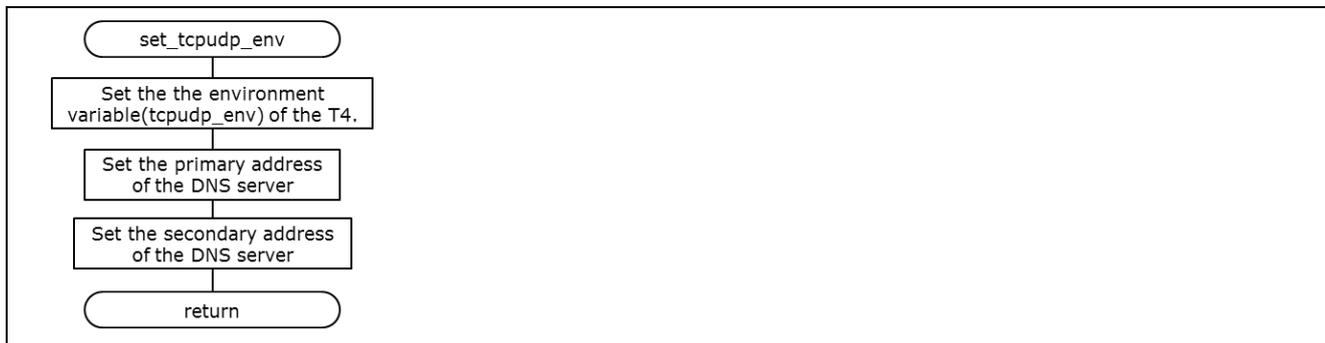
(12) led_init

This function performs the initialization process for using the LED on the Renesas Starter Kit + for RX64M or the Renesas Starter Kit + for RX71M.



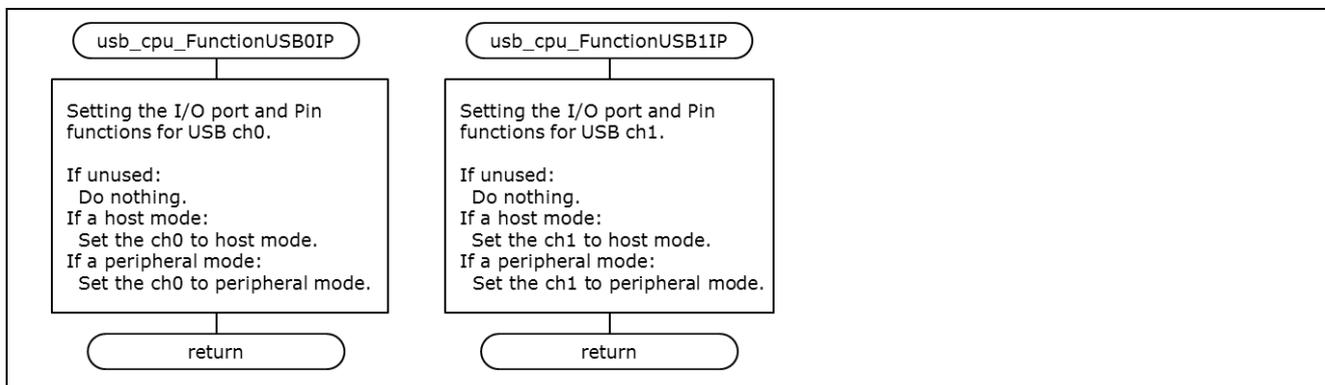
(13) set_tcpudp_env

Setting the network information which obtained from DHCP server to the environment variable of T4.



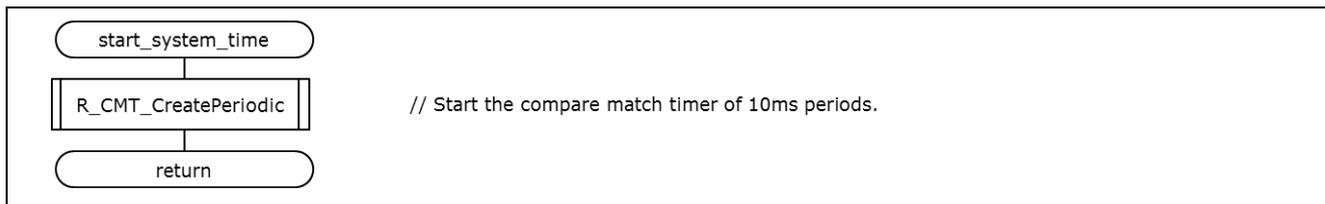
(14) usb_cpu_FunctionUSB0IP, usb_cpu_FunctionUSB1IP

Performs I/O port and Pin functions initialization for using the USB ch0 and ch1.



(15) start_system_time

Start the compare match timer (10ms interval) for the system time of HTTP server.



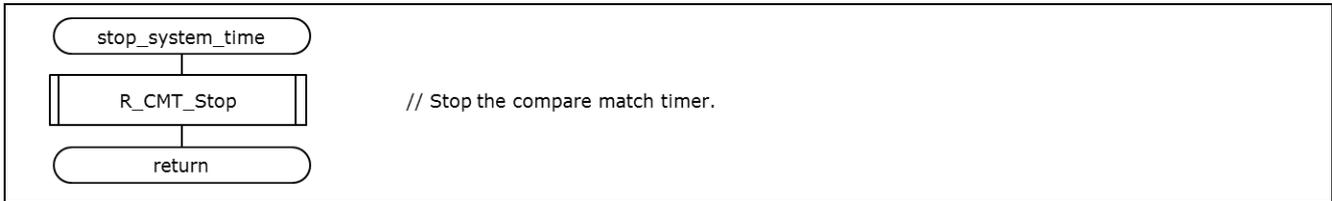
(16) update_sys_time

This function is an interrupt handler that counts up of the system time of HTTP server.



(17) stop_system_time

Stop the compare match timer for the system time of HTTP server.



7. User-Defined Functions

The user defined functions must be coded by the user to match the user system environment. Some of the user-defined functions are required by the FIT modules.

This package includes the following user-defined function samples. See the corresponding FIT module manual or other documentation for specifications of these user-defined functions.

Table 7-1 User-Defined Functions

User-Defined Function	File Name	FIT Module Name	Document Name/Catalog Number
System timer interface	r_sys_time.c	r_t4_http_server_rx	RX Family Web server using the embedded TCP/IP M3S-T4-Tiny Module Firmware Integration Technology / R20AN0075EJ (4.2 System Timer)

8. Supplement

8.1 USB Driver Limitations

When both USB channels ch0 and ch1 are set to host mode, only ch0 can recognize USB memory. To use ch1 in host mode, set ch0 to either unused or peripheral mode. For the setting examples, refer to “3.4.1(3) Change USB Driver Settings.

8.2 This Application Limitations

After program operation, if the USB memory is removed it will not be recognized if it is reinserted. The program should be restarted.

8.3 FTP Server and DHCP Client Limitations

FTP server and DHCP client can be operated at Ethernet ch0 only.

8.4 Notes on Using the Free Evaluation Version of the RX Family C/C++ Compiler Package

There is a usage period limitation and certain usage limitations on the free evaluation version of the RX Family C/C++ Compiler Package. If the usage period exceeds, load modules may not be generated correctly due to the usage limitations.

See the page on evaluation software on the Renesas web site at the link below.

http://www.renesas.com/products/tools/evaluation_software/index.jsp

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Revision History

Rev.	Date	Page	Description	
			Summary	
1.00	Sep 1, 2014	—	First edition issued	
1.03	Feb 29, 2016	—	Added DHCP client, DNS client and FTP server. Added RX71M. Changed an application note to R01AN2608EJ	

General Precautions in the Handling of MPU/MCU Products

The following usage notes are applicable to all MPU/MCU products from Renesas. For detailed usage notes on the products covered by this document, refer to the relevant sections of the document as well as any technical updates that have been issued for the products.

1. Handling of Unused Pins

Handle unused pins in accordance with the directions given under Handling of Unused Pins in the manual.

- The input pins of CMOS products are generally in the high-impedance state. In operation with an unused pin in the open-circuit state, extra electromagnetic noise is induced in the vicinity of LSI, an associated shoot-through current flows internally, and malfunctions occur due to the false recognition of the pin state as an input signal become possible. Unused pins should be handled as described under Handling of Unused Pins in the manual.

2. Processing at Power-on

The state of the product is undefined at the moment when power is supplied.

- The states of internal circuits in the LSI are indeterminate and the states of register settings and pins are undefined at the moment when power is supplied.
In a finished product where the reset signal is applied to the external reset pin, the states of pins are not guaranteed from the moment when power is supplied until the reset process is completed. In a similar way, the states of pins in a product that is reset by an on-chip power-on reset function are not guaranteed from the moment when power is supplied until the power reaches the level at which resetting has been specified.

3. Prohibition of Access to Reserved Addresses

Access to reserved addresses is prohibited.

- The reserved addresses are provided for the possible future expansion of functions. Do not access these addresses; the correct operation of LSI is not guaranteed if they are accessed.

4. Clock Signals

After applying a reset, only release the reset line after the operating clock signal has become stable. When switching the clock signal during program execution, wait until the target clock signal has stabilized.

- When the clock signal is generated with an external resonator (or from an external oscillator) during a reset, ensure that the reset line is only released after full stabilization of the clock signal. Moreover, when switching to a clock signal produced with an external resonator (or by an external oscillator) while program execution is in progress, wait until the target clock signal is stable.

5. Differences between Products

Before changing from one product to another, i.e. to a product with a different part number, confirm that the change will not lead to problems.

- The characteristics of an MPU or MCU in the same group but having a different part number may differ in terms of the internal memory capacity, layout pattern, and other factors, which can affect the ranges of electrical characteristics, such as characteristic values, operating margins, immunity to noise, and amount of radiated noise. When changing to a product with a different part number, implement a system-evaluation test for the given product.

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