RENESAS TOOL NEWS

[Notification]

E2 Emulator for Reducing the Time Required to Solve Problems

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with Speed Performance by Using the CAN Communication Time Measurement Solution

Outline

This document gives an overview of the advanced on-chip debugging emulator (E2 emulator) based on the concept of "improvement of development efficiency", and explains the CAN communication time measurement solution for RH850 family. The E2 emulator allows you to quickly solve problems regarding response times in CAN communications.

1. Overview of the E2 Emulator

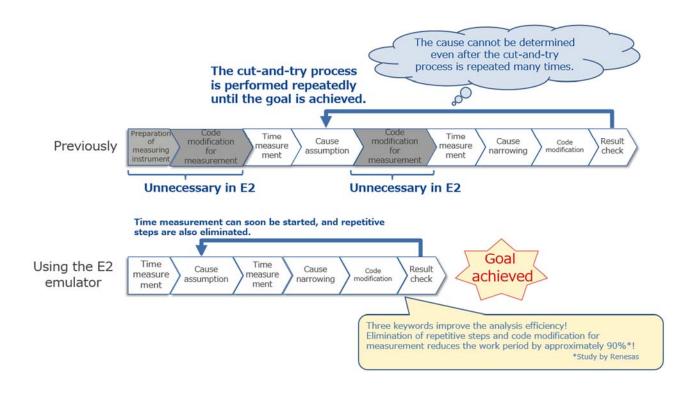
The E2 emulator is an advanced on-chip debugging emulator and flash programmer, and is established based on the concept of "improvement of development efficiency". The maximum download speed is two times faster than the E1 emulator. In addition to the CAN communication time measurement solution explained in this document, the E2 emulator combined with various solutions will further reduce development time.

For details about the E2 emulator, refer to the URL below.

https://www.renesas.com/e2

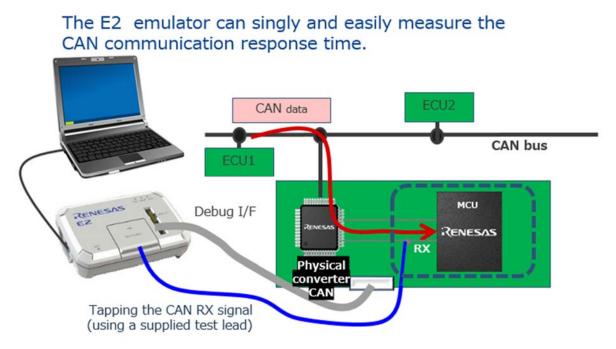
2. CAN Communication Time Measurement Solution

The E2 emulator has three keywords "Easy measurement", "No missing data", and "Quick identification" for improved efficiency of analysis regarding response times in CAN communications.





• Easy measurement

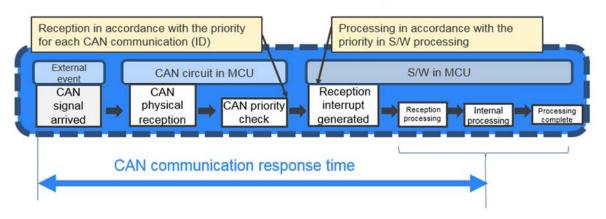


The E2 emulator can singly and easily measure response times, which are important for CAN communications, without using an expensive CAN analyzer.

The measurement method is simply to connect the E2 emulator to the MCU RX signal by using a supplied test lead.

• No missing data

Breaking the program is possible in the case of "set time < CAN communication response time".



If the CAN communication response time specified by the user exceeds a design value, the E2 emulator can stop the program.



• Quick identification

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Checking trace data from the measurement end point to locate a problem

Trace	🛞 🛞 📇 Notation • 🖵	া লয় জিলা	ৰ নাৰ				
Number	Time (h:min:s,ms,µs,ns)		Number/Address	Source/Dis	assemble	y	
1251	00h00min00s000ms000µs000	ns					
1252		main.	#210	PORT. APO	4= 0x0002;		
1252		0x0000	0136a	+186	nov sp, r6		
1252-1		main.		CommandExec(rcv_data);			
1252-1		0x0000	0136c	+188 _CommandExe	jarl _Command	Exec, 1p	
1252-2		main. o	#241	void Comman	dExec(unsigne	d long* rc	
1252-2	00h00min00s000ms000µs087ns		1348	+0 1d. w 0x0(r6), r2		r2	
1254	00h00min00s000ms000µs025						
1255		main.			_data(0)) (
1255		0x0000		+4	cmp 0x5, r2		
1255-1		Dx0000		+6	_data(0)) (
1255-1		main.		+6	bnz _CommandE	xectoxre	
1255-2	00h00min00s000ms000us050			+22	jmp [lp]		
LLOO-L	001100211002000200000		1044	INTRCANSRE			
1256		main.	#224	inst dbtag			
1256	00h00min00s000ms000µs050	ns 0x0000	01370	+192	dbtag 0x21		
1257		main.c	#224	inst dbtag	0x21();		
		• •				M	
LAN	communication h	istory			Y	Measuremen point of the (
[Time]		[Type] [Contents]				communicati	
			-				
0h 00m 00s 251ms 452us 316 CAN		CAN	ID=0x3E6 DLC=0x8 DATA=0xE603000000 response time			e	
0h 00m	00s 251ms 702us 425	CAN	ID=0x3E7 DLC	=0x8 DATA=	0xE703000000	000000 Ack=0	
0h 00m	00s 251ms 946us 958	SWTrace	DBTAG 0x021	/			1

You can quickly locate a problem in the program by finding the end point of the CAN communication response time measurement from the CAN communication history and checking trace data from the measurement end point.

3. How to Purchase the Product

For product ordering, contact your local Renesas Electronics marketing office or distributor with the following information.

For product pricing, make inquiries in the same manner.

Product Name	E2 emulator	
Orderable Part Name	RTE0T00020KCE00000R	



Revision History

		Description		
Rev.	Date	Page	Summary	
1.00	Jul. 01, 2018	-	First edition issued	

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