RZ/T2L Group

Encoder I/F A-format sample program

Summary

This document describes the RZ/T2L Encoder I/F A-format™ sample program package.

Functionality Checked Device

RSK+RZT2L Board (RTK9RZT2L0C00000BJ)

Contents

1. Package Contents 2
1.1 Software 2
1.2 Documents 2

2. File Structure 3

3. About A-format Sample Program 4
3.1 Software Information 4
3.1.1 Base OS 4
3.1.2 Memory Size 4
3.2 Hardware Information 5
3.2.1 Device 5
3.2.2 Target Board 5
3.3 Procedures on Development Environments 6
3.3.1 Preparation before Executing the Sample Program 6
3.3.2 EWARM from IAR Systems 6
3.3.3 e² studio from RENESAS 8

Revision History 10

1. Package Contents

This package contains the following contents.

The Configuration Data included in this package supports up to 2 axes, but the sample program supports only 1 axis; to use if with 2 axes, modify the sample program to support 2 axes.

This sample program operation was checked with A-format Ver.2.0 encoder. Operation with A-format Ver.1.0 encoder is not supported.

1.1 Software

- Source Code

No.	name	Version number
1	RZ/T2L A-format sample program	3.0

1.2 Documents

No.	Document name	Version	File name
1	RZ/T2L Group Encoder I/F A-format sample program Release Note	3.00	(j) r11an0678jj0300-rzt2l.pdf (e) r11an0678ej0300-rzt2l.pdf (this document)
2	RZ/T2L Group A-format sample program Application Note	3.00	(j) r11an0677jj0300-rzt2l-a-format.pdf (e) r11an0677ej0300-rzt2l-a-format.pdf

2. File Structure

The file structure and contents of this package are detailed below.

```
Top
├── r11an0678jj0300-rzt2l.pdf
├── r11an0678ej0300-rzt2l.pdf
└── workspace
    ├── Software
    │   ├── iccarm
    │   │   └── RZ_T2L_a_as.zip : RZ/T2L A-format sample program set (IAR)
    │   └── gcc
    │       └── RZ_T2L_a_as.zip : RZ/T2L A-format sample program set (e2 studio)
    └── Documents
        ├── r11an0677jj0300-rzt2l-a-format.pdf
        └── r11an0677ej0300-rzt2l-a-format.pdf
```

The file structure of the RZ_T2L_a_as.zip is shown below.

```
Top folder
├── configuration.xml                    : FSP Configuration data
├── ( Build Tool Dependent Environment File )
└── src
    ├── hal_entry.c                      : A-format sample program
    ├── a_as_main.c                      : A-format sample program
    ├── siochar.c                        : SCI_UART sample program
    ├── siorw.c                          : SCI_UART sample program
    ├── sio_char.h                       : SCI_UART sample program
    └── drv
        └── a_as
            ├── iodefine_a_as.h          : A_AS register definition file
            ├── r_a_as_rzt2.c            : A_AS driver file
            ├── r_a_as_rzt2_config.h     : A_AS driver file
            ├── r_a_as_rzt2_dat.h        : A_AS driver file
            ├── r_a_as_rzt2_if.h         : A_AS driver file
            ├── r_a_as_rzt2_private.h    : A_AS driver file
            └── a_format
                ├── r_a_format_rzt2.c          : A-format driver file
                ├── r_a_format_rzt2_config.h   : A-format driver file
                └── r_a_format_rzt2_private.h  : A-format driver file
```

3. About A-format Sample Program

This section contains information necessary to use the complete set of A-format sample program.

3.1 Software Information

3.1.1 Base OS

This sample program is OS-independent.

3.1.2 Memory Size

Memory size used by this sample program and A-format driver is shown in following table. This table does not include memory size used by Flexible Software Package or C language libraries of the compiler.

Items		Memory Size	
		EWARM [kBytes]	e^2 studio [kBytes]
A-format driver	Code	4.1	3.5
	Data (with initial value)	0.0	0.0
	Data (without initial value)	0.8	0.8
	Constant Data	0.0	0.0
Sample program	Code	4.2	4.8
	Data (with initial value)	0.1	0.0
	Data (without initial value)	0.8	0.8
	Constant Data	1.8	2.2

3.2 Hardware Information

3.2.1 Device

RZ/T2L

3.2.2 Target Board

(1) Board Name

RSK+RZT2L (RTK9RZT2L0C00000BJ)

(2) Setting of the Target Board

The target board configuration is as follows.

SW4-1: ON, SW4-2: ON, SW4-3: OFF

SW4-4: OFF

SW4-5: ON

SW4-6: ON

SW4-7: OFF

SW5-1: OFF, SW5-2: ON, SW5-3: OFF, SW5-4: OFF, SW5-5: OFF

SW6-1: OFF, SW6-2: ON, SW6-3: OFF, SW6-4: OFF

SW6-5: OFF, SW6-6: ON, SW6-7: OFF, SW6-8: OFF

SW8-7: OFF

(3) Used Pins of the Target Board

The correspondence between the pin used as the encoder I/F and the pin header of the target board is as follows.

Channel	Pin name	Pin header	Input/Output	Description
AFMT0	SDAT (ENCIFDI0)	J26 #2	Input	Data input
	REQ (ENCIFDO0)	J26 #1	Output	Data output
	D/R (ENCIFOE0)	J26 #4	Output	Drive/receive control
AFMT1	SDAT (ENCIFDI1)	CN1 #5	Input	Data input
	REQ (ENCIFDO1)	CN1 #4	Output	Data output
	D/R (ENCIFOE1)	CN1 #3	Output	Drive/receive control

3.3 Procedures on Development Environments

3.3.1 Preparation before Executing the Sample Program

This sample program communicates with a PC. The USB connection terminal on the target board is CN16.

The terminal software of the host PC is set as shown in the following table.

Function	Setting
Communication method	Asynchronous Serial transmit/receive
Order of transmission / reception	LSB first
Transfer rate	19200 bps
Character length	8 bits
Stop bit length	1 bit
Parity function	None
Hardware flow control	None

3.3.2 EWARM from IAR Systems

(1) Build Environment

IAR Embedded Workbench for ARM (EWARM)

Version 9.60.3 + patch (EWARM_Patch_for_RZT2H_N2H_rev1.0)

RENESAS FSP Smart Configurator (FSP SC) 2025-04.1

RENESAS Flexible Software Package (FSP) for RZ/T2 v3.0.0

(2) Execution Environment ICE

IAR I-jet

(3) Build Procedure for Sample Programs

The build procedure for the sample program is as follows.

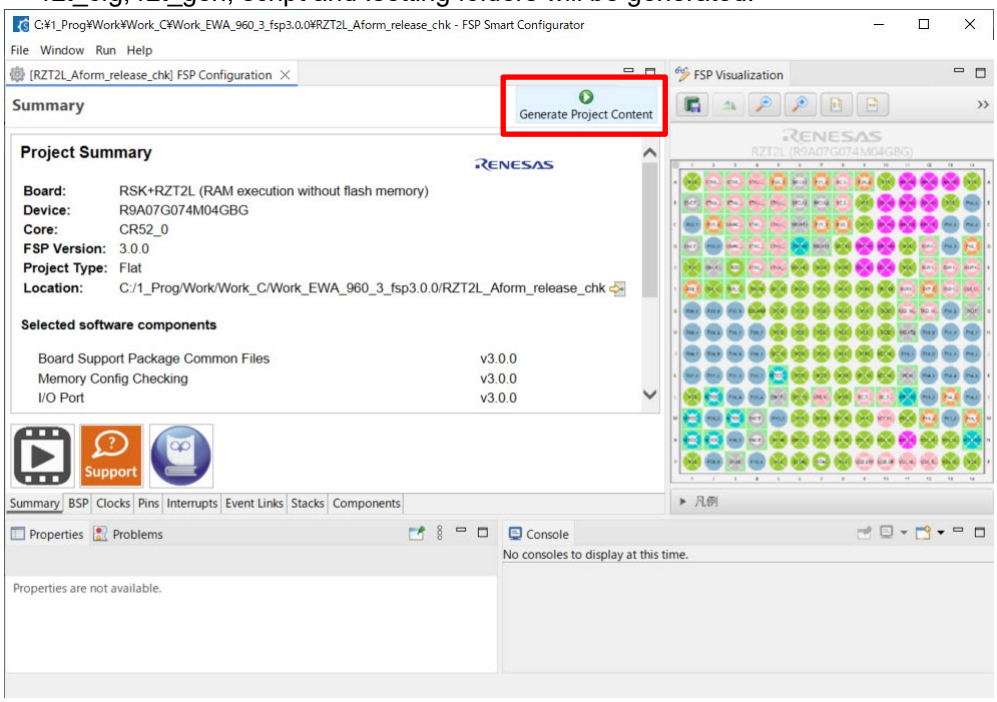
1 Copy the extracted source files to the desired location.
2 Activate EWARM.
3 Select [File] menu -> [Open Workspace].
4 Open the extracted source file RZ_T2L_a_as.eww.
5 Start the FSP Smart Configurator from the [Tools] menu of the EWARM IDE. *

Note: The following procedure adds the activation of the FSP Smart Configurator to the [Tools] menu of the EWARM IDE. Select [Tools] menu -> [Tool Configuration] in the EWARM IDE. Select the [New] button, specify a table string in each field, and press [OK].

Field	String
Menu text	RZ Smart Configurator
command	$RASC_EXE_PATH$
argument	--compiler IAR configuration.xml
Initial directory	$PROJ_DIR$

String for the command is variable holding the path of the Smart Configurator execution file, rasc.exe. If the path written as RASC_EXE_PATH in the buildinfo.ipcf file does not match with your rasc.exe installation path, please edit the buildinfo.ipcf to fit with your installation path.
You can also start the FSP Smart Configurator directly from the command prompt by specifying the folder where it is installed.

6 In the FSP Configuration pane of the Smart Configurator, click Generate Project Content. The rzt, rzt_cfg, rzt_gen, script and .setting folders will be generated.



7 When project generation is complete, close the Smart Configurator.

8 Select [Rebuild ALL] from the [Project] menu of EWARM.
The file Debug\Exe\RZ_T2L_a_as.out is generated.

(4) Sample Program Execution Procedure

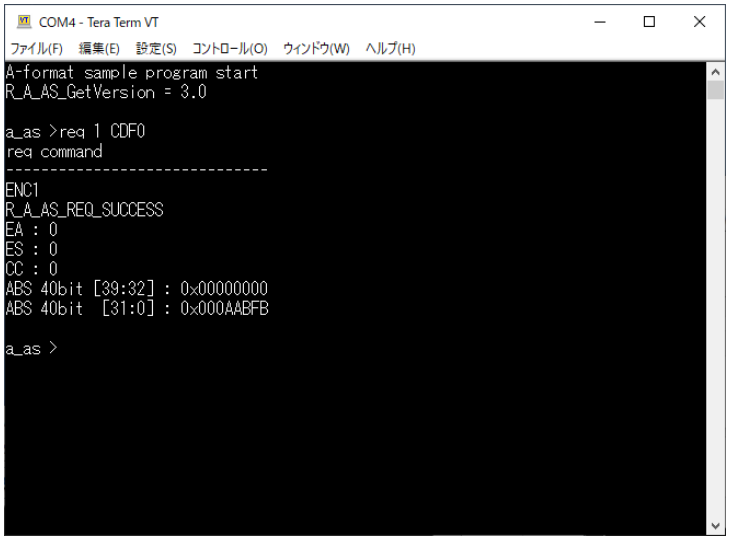
After executing the "build procedure", connect the target board and debugger correctly, and perform the following operations.

1 Select [Project] menu -> [Download and Debug].

2 Select [Debug] menu -> [Execute].

(5) Execution Result of the Sample Program

Run the sample program and enter commands in the terminal software window. For commands, see 4.11.8 console commands in the RZ/T2L Group A-format Sample Program Application Note.



3.3.3 e² studio from RENESAS

(1) Build Environment

RENESAS e² studio 2025-04.1

Toolchain version: GNU ARM Embedded 13.3.1.arm-13-24

RENESAS Flexible Software Package (FSP) for RZ/T2 v3.0.0

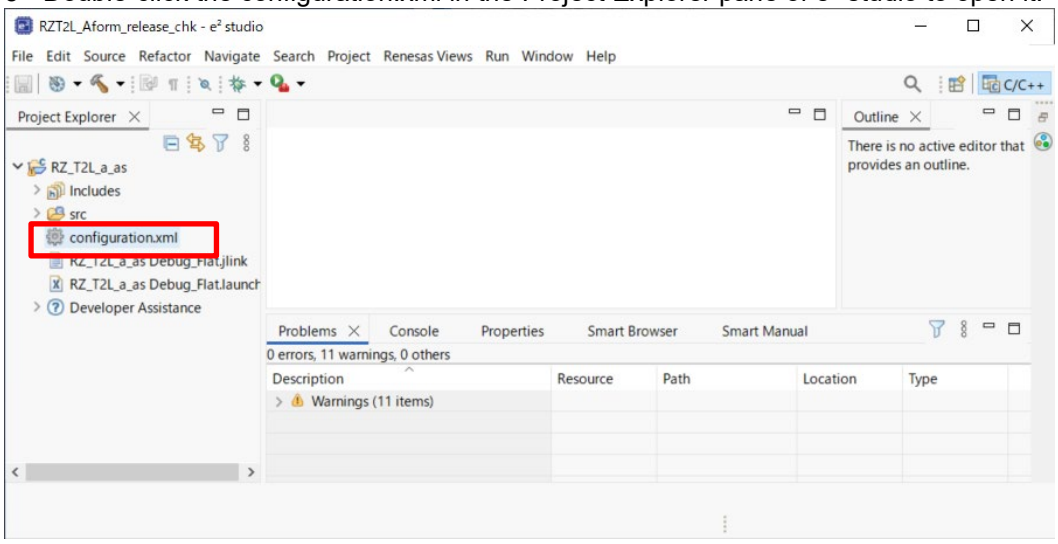
(2) Execution Environment ICE

SEGGER J-Link™ v8.30

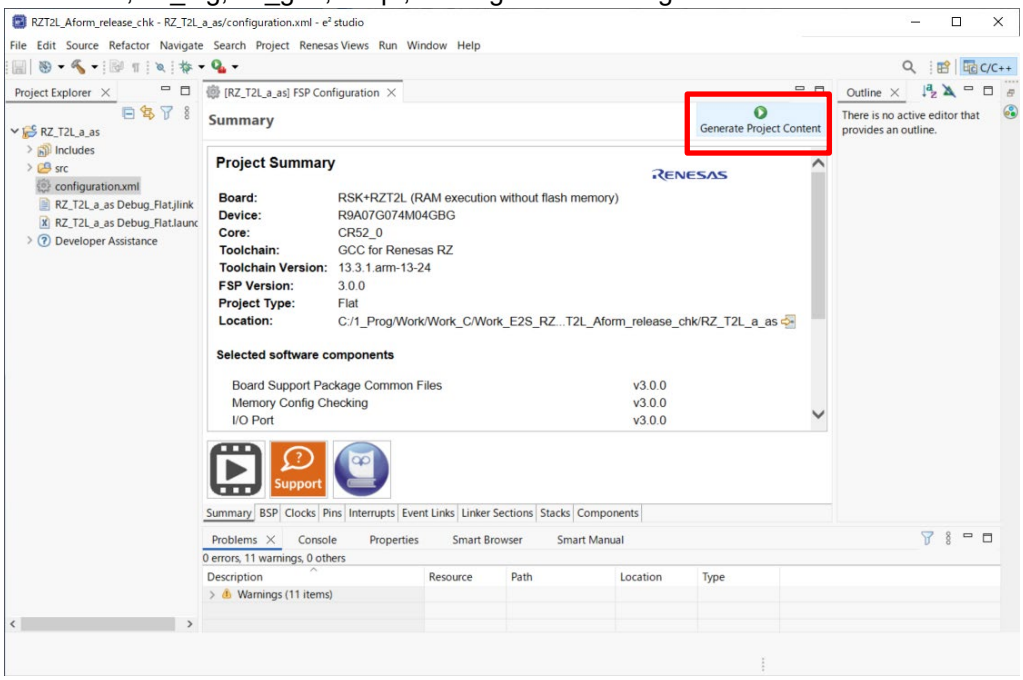
(3) Build Procedure of the Sample Program

The procedure for building the sample program is as follows.

1. Copy the expanded source file to any location.
2. After launching e² studio and moving to the workspace, click the [File] menu -> [Import] and select Existing project to workspace and click [Next].
3. On the project import screen, select the folder where the sample program was expanded as the root directory.
4. Select a project, check Copy Project to Workspace, and click [Finish].
5. Double-click the configuration.xml in the Project Explorer pane of e² studio to open it.



6 Click Generate Project Content in the FSP Configuration pane of e² studio.
The rzt, rzt_cfg, rzt_gen, script, .settings folders are generated.



7 Select [Project] menu -> [Build All]
The Debug\RZ_T2L_a_as.elf file is generated.

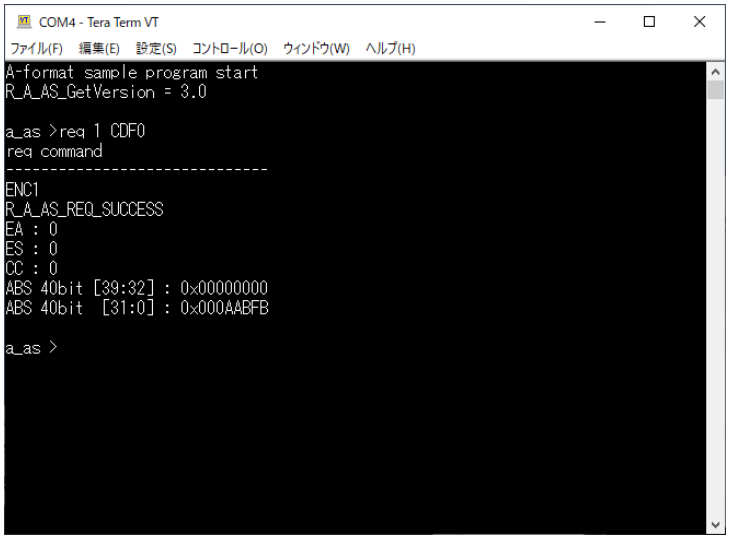
(4) Execution Procedure of the Sample Program

After executing the "build procedure", connect the target board and debugger correctly, and perform the following operations.

1 Select [Run] menu -> [Debug As] -> [Renesas GDB Hardware Debugging].
2 Click [Debug] to start downloading to internal RAM.
3 Click [Run] menu -> [Resume] to run the sample program.

(5) Execution Result of the Sample Program

Run the sample program and enter commands in the terminal software window. For commands, see 4.11.8 console commands in the RZ/T2L Group A-format Sample Program Application Note.



Revision History

Rev.	Date	Description	
		Page	Summary
0.80	Oct.04.22	-	First Edition issued.
0.81	Dec.09.22	-	Change description by supporting RZ/T2L FSP beta.0 version.
1.00	Mar 31.23	-	Change description by using RZ/T2 FSP v1.2.0 (Version number of documents, target board name, build environment, and figures are updated.)
1.10	May 31.23	1, 4 2, 3	Appended section 3.1.2 for memory size information. Updated the release note version number.
1.20	Oct 13.23	2, 3 3 4 6 to 9	Updated the source code and the release note version number. Source code is corrected for preventing command parameter mismatch. Updated file structure. (Removed RZ/T2L Pin Configuration data from zip file.) Updated memory size information. Updated build environment for FSP v1.3.0. Figures are replaced.
2.00	May 17.24	2, 3 4 1, 5 6 to 9	Updated revisions of the application note and the release note. Updated sample program version to 2.0. (Supported FSP v2.0.0. Multiple transmission commands are removed. Usage of the elctimer command is changed.) Updated memory size information. Updated description of the board name. Added SW8-7 description in the setting of the target board. Updated build environment for FSP v2.0.0. Figures are replaced.
3.00	Sep 26.25	1 2, 3 4 6 to 9	Update description of the trademarks. Update revisions of the application note and the release note. Update sample program version to 3.0. (Support FSP v3.0.0.) Update memory size information. Update build environment for FSP v3.0.0. Figures are replaced.

General Precautions in the Handling of Microprocessing Unit and Microcontroller Unit Products

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1. Precaution against Electrostatic Discharge (ESD)
   A strong electrical field, when exposed to a CMOS device, can cause destruction of the gate oxide and ultimately degrade the device operation. Steps must be taken to stop the generation of static electricity as much as possible, and quickly dissipate it when it occurs. Environmental control must be adequate. When it is dry, a humidifier should be used. This is recommended to avoid using insulators that can easily build up static electricity. Semiconductor devices must be stored and transported in an anti-static container, static shielding bag or conductive material. All test and measurement tools including work benches and floors must be grounded. The operator must also be grounded using a wrist strap. Semiconductor devices must not be touched with bare hands. Similar precautions must be taken for printed circuit boards with mounted semiconductor devices.
2. Processing at power-on
   The state of the product is undefined at the time when power is supplied. The states of internal circuits in the LSI are indeterminate and the states of register settings and pins are undefined at the time when power is supplied. In a finished product where the reset signal is applied to the external reset pin, the states of pins are not guaranteed from the time when power is supplied until the reset process is completed. In a similar way, the states of pins in a product that is reset by an on-chip power-on reset function are not guaranteed from the time when power is supplied until the power reaches the level at which resetting is specified.
3. Input of signal during power-off state
   Do not input signals or an I/O pull-up power supply while the device is powered off. The current injection that results from input of such a signal or I/O pull-up power supply may cause malfunction and the abnormal current that passes in the device at this time may cause degradation of internal elements. Follow the guideline for input signal during power-off state as described in your product documentation.
4. Handling of unused pins
   Handle unused pins in accordance with the directions given under handling of unused pins in the manual. The input pins of CMOS products are generally in the high-impedance state. In operation with an unused pin in the open-circuit state, extra electromagnetic noise is induced in the vicinity of the LSI, an associated shoot-through current flows internally, and malfunctions occur due to the false recognition of the pin state as an input signal become possible.
5. Clock signals
   After applying a reset, only release the reset line after the operating clock signal becomes stable. When switching the clock signal during program execution, wait until the target clock signal is stabilized. When the clock signal is generated with an external resonator or from an external oscillator during a reset, ensure that the reset line is only released after full stabilization of the clock signal. Additionally, when switching to a clock signal produced with an external resonator or by an external oscillator while program execution is in progress, wait until the target clock signal is stable.
6. Voltage application waveform at input pin
   Waveform distortion due to input noise or a reflected wave may cause malfunction. If the input of the CMOS device stays in the area between V_{IL} (Max.) and V_{IH} (Min.) due to noise, for example, the device may malfunction. Take care to prevent chattering noise from entering the device when the input level is fixed, and also in the transition period when the input level passes through the area between V_{IL} (Max.) and V_{IH} (Min.).
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