

RL78/G12

Timer Array Unit (PWM Output) CC-RL

R01AN2841EJ0200 Rev. 2.00 Nov.11, 2015

Introduction

This application note describes the PWM output function of the timer array unit (TAU). This unit changes the PWM output duty ratio and inverts the LED indication at 500 ms intervals.

Target Device

RL78/G12

When applying the sample program covered in this application note to another microcomputer, modify the program according to the specifications for the target microcomputer and conduct an extensive evaluation of the modified program.

Contents

1.	Specifications	3
2.	Operation Check Conditions	5
3.	Related Application Note	5
4.	Description of the Hardware	6
4.1	Hardware Configuration Example	6
4.2	List of Pins to be Used	6
5.	Description of the Software	7
5.1	Operation Outline	7
5.2	List of Option Byte Settings	8
5.3	List of Constant	8
5.4	List of Variables	8
5.5	List of Functions (Subroutines)	8
5.6	Function (Subroutine) Specifications	g
5.7	Flowcharts	10
5.7.	1 CPU Initialization Function	11
5.7.	2 I/O Port Setup	12
5.7.	3 Clock Generation Circuit Setup	13
5.7.	4 Timer Array Unit Setup	14
5.7.	5 Main Processing	27
5.7.	6 Timer Array Unit Startup	28
5.7.	7 INTTM0 Interrupt Processing	31
6.	Sample Code	32
7	Documents for Reference	32

1. Specifications

This application note describes the PWM output function which is realized using channel 0 as the master and channel 1 as the slave in simultaneous channel operation mode. The brightness of the LEDs is controlled by connecting the PWM output to LED2 (for PWM output). Timing signals with fixed cycle time (500 ms) are created by counting the number of timer interrupts (INTTM00) generated by channel 0. Using these timing signals, the duty ratio of the PWM output is changed and the output of LED1 (for updating) is inverted.

Table 1.1 shows the required peripheral function and its use. Figure 1.1 presents an overview of the PWM output operation. Table 1.2 shows the relation between PWM output duty ratios and LED brightnesses. Figure 1.2 is a simplified timing chart which summarizes the PWM output operation.

Table 1.1 Required Peripheral Function and Its Use

Peripheral function	Use		
Timer array unit 0	This unit is used to realize the PWM function by operating		
	channel 0 and channel 1 together and deliver a PWM		
	output from the TO01 pin.		

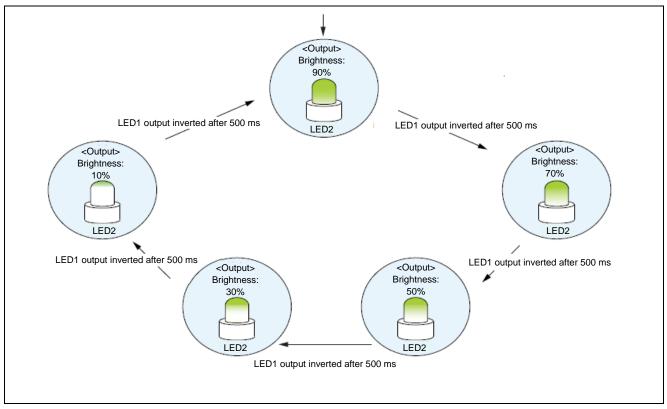


Figure 1.1 Overview of PWM Output Operation

Table 1.2 Relation between PWM Output Duty Ratios and LED Brightnesses

Duty ratio	LED2 brightness
10%	90%
30%	70%
50%	50%
70%	30%
90%	10%

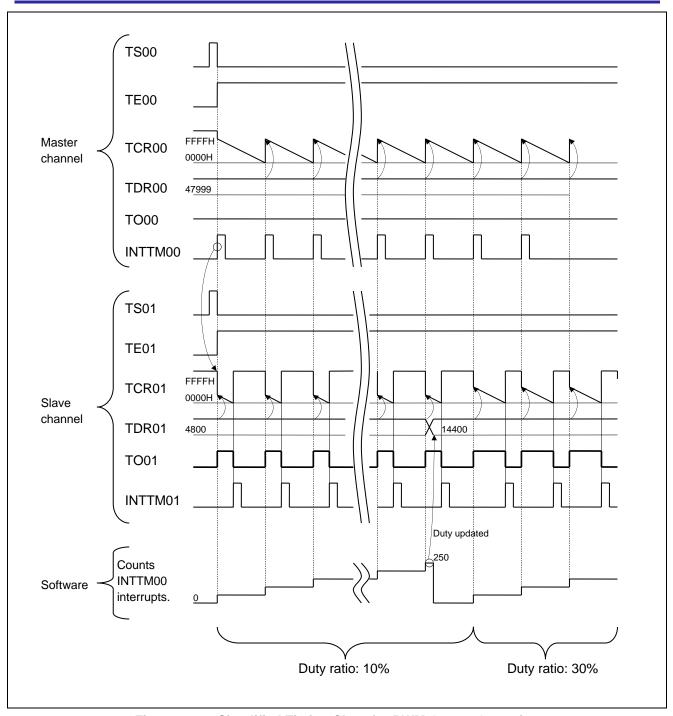


Figure 1.2 Simplified Timing Chart for PWM Output Operation

2. Operation Check Conditions

The sample code described in this application note has been checked under the conditions listed in the table below.

Table 2.1 Operation Check Conditions

Item	Description
Microcontroller used	RL78/G12 (R5F1026A)
Operating frequency	 High-speed on-chip oscillator (HOCO) clock: 24 MHz CPU/peripheral hardware clock: 24 MHz
Operating voltage	5.0 V (Operation is possible over a voltage range of 2.9 V to 5.5 V.)
	LVD operation (V _{LVD}): Reset mode which uses 2.81 V (2.76 V to 2.87 V)
Integrated development environment (CS+)	CS+ for CC V3.01.00 from Renesas Electronics Corp.
Assembler (CS+)	CC-RL V1.01.00 from Renesas Electronics Corp.
Integrated development environment (e² studio)	e ² studio V4.0.2.008 from Renesas Electronics Corp.
Assembler (e ² studio)	CC-RL V1.01.00 from Renesas Electronics Corp.
Board to be used	RL78/G12 target board (QB-R5F1026A-TB)

3. Related Application Note

The application notes that are related to this application note are listed below for reference.

RL78/G12 Initialization (R01AN2582E) Application Note

4. **Description of the Hardware**

Hardware Configuration Example 4.1

Figure 4.1 shows an example of the hardware configuration used for this application note.

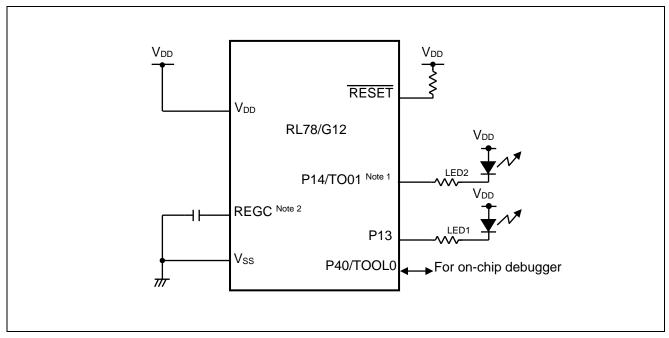


Figure 4.1 **Hardware Configuration**

Notes: 1. For 20-pin and 24-pin products. P16/TO01 for 30-pin products.

2. Only for 30-pin products.

- Cautions: 1. The purpose of this circuit is only to provide the connection outline and the circuit is simplified accordingly. When designing and implementing an actual circuit, provide proper pin treatment and make sure that the hardware's electrical specifications are met (connect the input-only ports separately to V_{DD} or V_{SS} via a resistor).
 - 2. V_{DD} must be held at not lower than the reset release voltage (V_{LVD}) that is specified as LVD.

List of Pins to be Used

Table 4.1 lists the pins to be used and their functions.

Table 4.1 Pins to be Used and Their Functions

Pin Name	I/O	Description
P14/TO01 Note	Output	PWM output (LED2) port
P13	Output	Output port for LED1 indications

Note: For 20-pin and 24-pin products. P16/TO01 for 30-pin products.

Caution: The products to be exemplified hereafter are 20-pin products, unless it is explicitly stated otherwise.

5. Description of the Software

5.1 Operation Outline

The sample program covered in this application note implements PWM by operating channel 0 and channel 1 together, and delivers a PWM output from P14/TO01.

Also, this program detects 250 timer interrupts (INTTM00) with 2-ms cycle time which are generated by channel 0. Then, it changes the PWM output duty ratio and inverts the LED indication at 500 ms intervals.

(1) Initialize the TAU.

<Conditions for setting>

- Set the P14/TO01 pin to a PWM output.
- Set TAU0 channel 0 to 2-ms cycle interval timer mode. Note 1
- Set TAU0 channel 1 to one-count mode.
- Initialize the duty ratio of the PWM output to 10 %. Note 2
- Use timer interrupts (INTTM00) from timer channel 0.
- (2) Operation starts when both the operation enable trigger bits for TAU0 channel 0 and channel 1 are set to 1 simultaneously. The sample program executes a HALT instruction to wait for a timer interrupt (INTTM00) from channel 0.
- (3) After the start of timer operation, channel 0 generates a timer interrupt (INTTM00) at 2 ms intervals.
- (4) When the HALT mode is canceled by a timer interrupt (INTTM00) from channel 0, the sample program starts counting the number of INTTM00 interrupts generated. After channel 0 has generated 250 timer interrupts (i.e., after 500 ms), the sample program updates the channel 1 count value and changes the duty ratio. This duty ratio is increased from 10% to 90% ($10\% \rightarrow 30\% \rightarrow 50\% \rightarrow 70\% \rightarrow 90\%$). It is incremented by 20% each time the number of channel 0 timer interrupts (INTTM00) generated reaches 250 Note 3. (Thus, it is incremented at 500 ms intervals) It is reset to 10% after the duty ratio to be set next exceeds 100%. Note 2
- (5) After processing timer interrupts (INTTM00) from channel 0, the sample program executes another HALT instruction and waits for the next timer interrupt (INTTM00) from channel 0.
- Notes. 1: Constant INTERVAL is defined as 2 (ms) at initial setting (r_init.asm).
 - 2. Constant INITIAL is defined as 10 (%) at initial setting (r_init.asm).
 - 3. Constant INCREMENT is defined as 20 (%) at initial setting (r_init.asm).

5.2 List of Option Byte Settings

Table 5.1 summarizes the settings of the option bytes.

Table 5.1 Option Byte Settings

Address	Value	Description
000C0H	01101110B Disables the watchdog timer.	
		(Stops counting after the release from the reset state.)
000C1H	01111111B LVD reset mode, 2.81 V (2.76 to 2.87 V)	
000C2H	11100000B HS mode, HOCO: 24 MHz	
000C3H	10000101B	Enables the on-chip debugger.

5.3 List of Constant

Table 5.2 lists the constants that are used in this sample program.

Table 5.2 Constant for the Sample Program

Constant	Setting	Description	
INTERVAL	2	Cycle of PWM output in units of ms	
INITIAL	10	Duty ratio of PWM in units of percent	
INCREMENT	20	Increment in duty ratio of PWM in units of percent	
PERIOD	24000 * INTERVAL	Number of clocks corresponding to duty ratio of PWM	
INCDATA	(PERIOD / 100) * INCREMENT	Number of clocks corresponding to increment in duty ratio of PWM	
INITDATA	(PERIOD / 100) * INITIAL	TDR01 setting for a 10% duty ratio	

5.4 List of Variables

Table 5.3 lists the variables that are used in this sample program.

Table 5.3 Variables for the Sample Program

Variable Name	Outline
RTMCNT	Used to detect an elapse of 500 ms by counting occurrence of INTTM00 at an interval of 2 ms

5.5 List of Functions (Subroutines)

Table 5.4 lists the functions (subroutines) that are used in this sample program.

Table 5.4 Functions (Subroutines)

Function	Outline
SSTARTPWM	Timer array unit start processing
INTTM00	TAU0 channel 0 timer interrupt processing



5.6 Function (Subroutine) Specifications

This section describes the specifications for the functions that are used in this sample program.

[Function Name] SSTARTPWM

Synopsis TAU0 channel 0 start processing

Explanation This function starts count operation of channels 0 and 1 and unmasks TAU0 channel 0

interrupts

Arguments None Return value None Remarks None

[Function Name] INTTM00

Synopsis Channel 0 timer interrupt processing

Explanation This function counts the number of INTTM00 interrupts generated. Each time the count

reaches 250, it updates the duty ratio of a PWM output. (Thus, it updates the duty ratio at

500-ms intervals)

Arguments None Return value None Remarks None

5.7 Flowcharts

Figure 5.1 shows the overall flow of the sample program described in this application note.

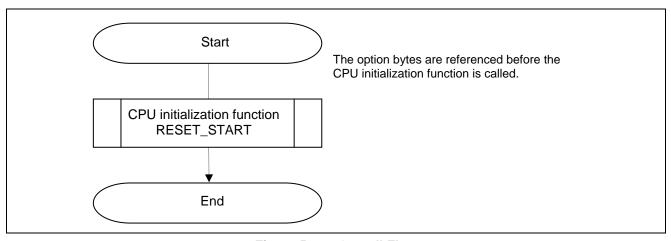


Figure 5.1 Overall Flow

5.7.1 CPU Initialization Function

Figure 5.2 shows the flowchart for the CPU initialization function.

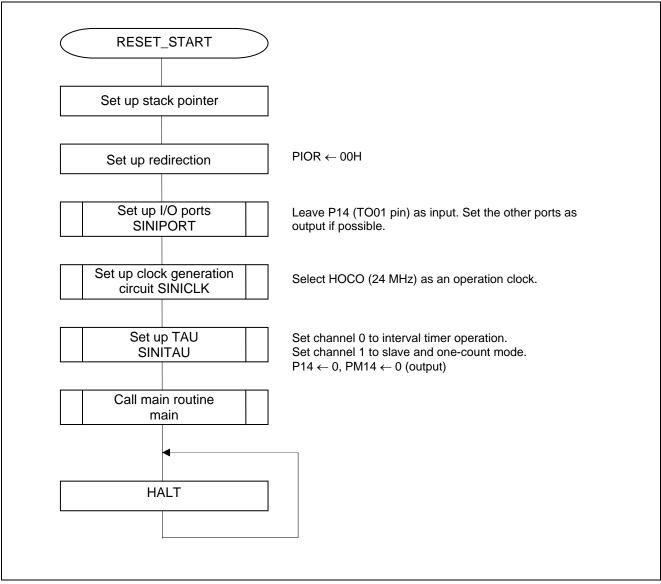


Figure 5.2 CPU Initialization Function

5.7.2 I/O Port Setup

Figure 5.3 shows the flowchart for setting up the I/O ports.

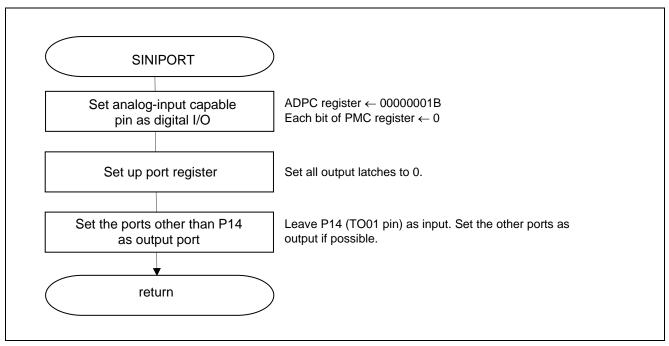


Figure 5.3 I/O Port Setup

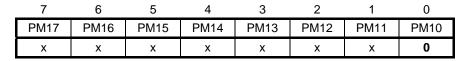
Note: Refer to the section entitled "Flowcharts" in RL78/G12 Initialization Application Note (R01AN1030E) for the configuration of the unused ports.

Caution: Provide proper treatment for unused pins so that their electrical specifications are observed. Connect each of any unused input-only ports to V_{DD} or V_{SS} via a separate resistor.

Setting up the LED pin to indicate updating of the duty ratio

• Port mode register (PM1)
Select I/O mode for PM10.

Symbol: PM1



Bit 0

PM10	PM10 I/O mode selection
0	Output mode (output buffer on)
_	Input mode (output buffer off)

5.7.3 Clock Generation Circuit Setup

Figure 5.4 shows the flowchart for clock generation circuit setup.

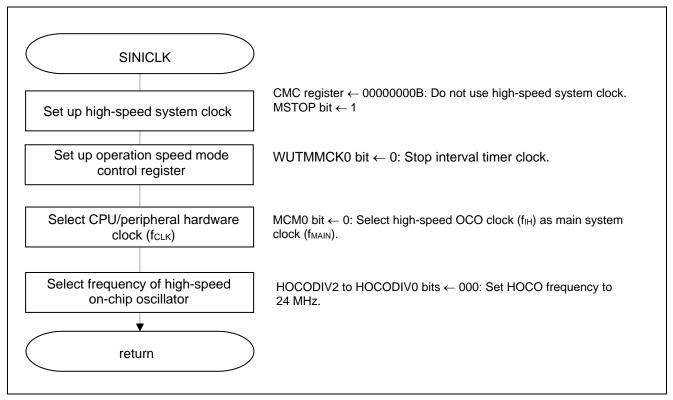


Figure 5.4 Clock Generation Circuit Setup

Caution: For details on the procedure for setting up the clock generation circuit (SINICLK), refer to the section entitled "Flowcharts" in RL78/G12 Initialization Application Note (R01AN2582E).

5.7.4 Timer Array Unit Setup

Figures 5.5 shows the flowcharts for setting up the timer array unit.

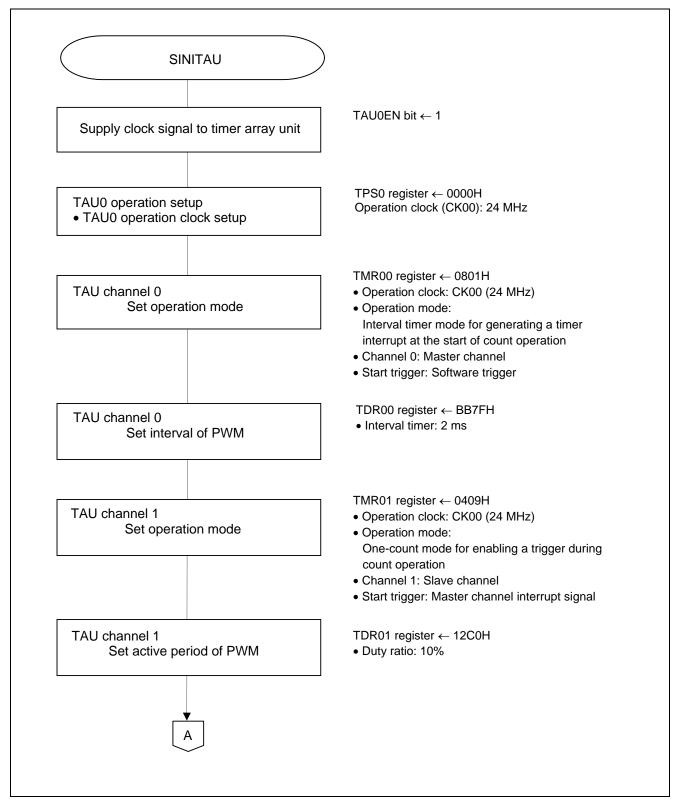


Figure 5.5 Timer Array Unit Setup (1/2)

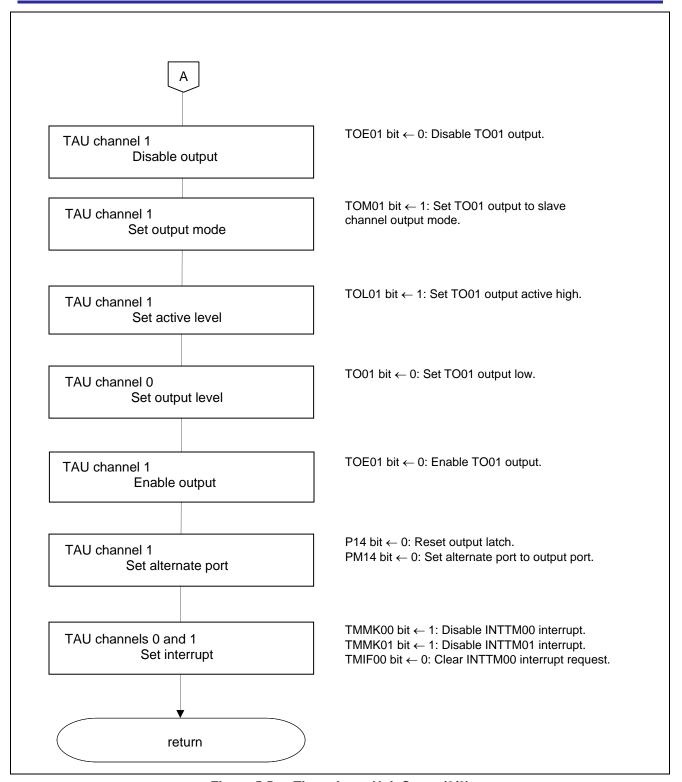


Figure 5.5 Timer Array Unit Setup (2/2)

Starting clock signal supply to the timer array unit $\boldsymbol{0}$

• Peripheral enable register 0 (PER0) Start clock signal supply to the timer array unit 0.

Symbol: PER0

7	6	5	4	3	2	1	0
TMKAE	0	ADCEN	IICA0EN	SAU1EN	SAU0EN	0	TAU0EN
Х	Х	Х	Х	Х	Х	0	1

Bit 0

TAU0EN	Control of timer array unit 0 input clock supply
0	Stops input clock supply.
1	Enables input clock supply.

Symbol: TPS0

	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
	0	0	PRS 031	PRS 030	0	0	PRS 021	PRS 020	PRS 013		PRS 011	PRS 010	PRS 003	PRS 002	PRS 001	PRS 000
ĺ	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	0	0	0	0

Bits 3 to 0

DD0	DD0	DDO	DD0		Sele	ction of ope	ration clock ((CK00)	
PRS 003	PRS 002	PRS 001	PRS 000		f _{CLK} = 2 MHz	f _{CLK} = 5 MHz	f _{CLK} = 10 MHz	f _{CLK} = 20 MHz	f _{CLK} = 24 MHz
0	0	0	0	fcLK	2 MHz	5 MHz	10 MHz	20 MHz	24 MHz
0	0	0	1	f _{CLK} /2	1 MHz	2.5 MHz	5 MHz	10 MHz	12 MHz
0	0	1	0	fclk/2 ²	500 kHz	1.25 MHz	2.5 MHz	5 MHz	6 MHz
0	0	1	1	fclk/23	250 kHz	625 kHz	1.25 MHz	2.5 MHz	3 MHz
0	1	0	0	$f_{CLK}/2^4$	125 kHz	312.5 kHz	625 kHz	1.25 MHz	1.5 MHz
0	1	0	1	fcLK/2 ⁵	62.5 kHz	156.2 kHz	312.5 kHz	625 kHz	0.75 MHz
0	1	1	0	fclk/26	31.25 kHz	78.1 kHz	156.2 kHz	312.5 kHz	375 kHz
0	1	1	1	f _{CLK} /2 ⁷	15.62 kHz	39.1 kHz	78.1 kHz	156.2 kHz	187.5 kHz
1	0	0	0	fclk/28	7.81 kHz	19.5 kHz	39.1 kHz	78.1 kHz	93.75 kHz
1	0	0	1	fclk/29	3.91 kHz	9.76 kHz	19.5 kHz	39.1 kHz	46.88 kHz
1	0	1	0	$f_{CLK}/2^{10}$	1.95 kHz	4.88 kHz	9.76 kHz	19.5 kHz	23.44 kHz
1	0	1	1	f _{CLK} /2 ¹¹	976 Hz	2.44 kHz	4.88 kHz	9.76 kHz	11.72 kHz
1	1	0	0	fcLk/2 ¹²	488 Hz	1.22 kHz	2.44 kHz	4.88 kHz	5.86 kHz
1	1	0	1	fcLk/2 ¹³	244 Hz	610 Hz	1.22 kHz	2.44 kHz	2.93 kHz
1	1	1	0	fcLk/2 ¹⁴	122 Hz	305 Hz	610 Hz	1.22 kHz	1.47 kHz
1	1	1	1	fclk/2 ¹⁵	61 Hz	153 Hz	305 Hz	610 Hz	732 Hz

Setting up the channel 0 operation mode

• Timer mode register 00 (TMR00)

Select an operation clock (f_{MCK}).

Select a count clock.

Select a start trigger and capture trigger.

Select a valid edge for timer input.

Set up the operation mode.

Symbol: TMR00

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
CKS	CKS	0	CCS	MAS	STS	STS	STS	CIS0	CIS0	0	0	MD0	MD0	MD0	MD0
001	000		00	TER	002	001	000	01	00			03	02	01	00
				00											
0	0	0	0	1	0	0	0	0	0	0	0	0	0	0	1

Bits 15 and 14

CKS001	CKS000	Selection of operation clock (f _{MCK}) of channel 0
0	0	Operation clock CK00 set by timer clock select register 0 (TPS0)
0	1	Operation clock CK02 set by timer clock select register 0 (TPS0)
1	0	Operation clock CK01 set by timer clock select register 0 (TPS0)
1	1	Operation clock CK03 set by timer clock select register 0 (TPS0)

Bit 12

CCS00	Selection of count clock (ftclk) of channel 0
0	Operation clock (f _{MCK}) specified by the CKSmn0 and CKSmn1 bits
1	Valid edge of input signal input from the TI00 pin

Bit 11

MASTER00	Selection between using channel 0 independently or simultaneously with another channel (as a slave or master)
	Operates in independent channel operation function or as slave channel in simultaneous channel operation function.
1 1	Operates as master channel in simultaneous channel operation function.

Symbol: TMR00

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
CKS	CKS	0	CCS	MAS	STS	STS	STS	CIS0	CIS0	0	0	MD0	MD0	MD0	MD0
001	000		00	TER	002	001	000	01	00			03	02	01	00
				00											
0	0	0	0	1	0	0	0	0	0	0	0	0	0	0	1

Bits 10 to 8

STS002	STS001	STS000	Setting of start trigger or capture trigger of channel 0
0	0	0	Only software trigger start is valid (other trigger sources are unselected).
0	0	1	Valid edge of the TI00 pin input is used as both the start trigger and capture trigger.
0	1	0	Both the edges of the TI00 pin input are used as a start trigger and a capture trigger.
1	1 0 0		Interrupt signal of the master channel is used (when the channel is used as a slave channel with the simultaneous channel operation function).
Oth	Other than above		Setting prohibited

Bits 7 and 6

CIS001	CIS000	Selection of TI00 pin input valid edge						
0	0	ing edge						
0	1	Rising edge						
1	0	Both edges (when low-level width is measured) Start trigger: Falling edge, Capture trigger: Rising edge						
1	1	Both edges (when high-level width is measured) Start trigger: Rising edge, Capture trigger: Falling edge						

Symbol: TMR00

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
CKS	CKS	0	CCS	MAS	STS	STS	STS	CIS0	CIS0	0	0	MD0	MD0	MD0	MD0
001	000		00	TER	002	001	000	01	00			03	02	01	00
				00											
0	0	0	0	1	0	0	0	0	0	0	0	0	0	0	1

Bits 3 to 0

MD 003	MD 002	MD 001	MD 000	- 1	Related function	TCR counting operation
0	0	0	1/0	Interval timer mode	Interval timer / Square wave output / Divider function / PWM output (master)	Counting down
0	1	0	1/0	Capture mode	Input pulse interval measurement	Counting up
0	1	1	0	Event counter mode	External event counter	Counting down
1	0	0	1/0	One-count mode	Delay counter / One-shot pulse output / PWM output (slave)	Counting down
1	1	0	0	-	Measurement of high-/low-level width of input signal	Counting up
Oth	er tha	an ab	ove	Setting prohibited		

The MD000 bit operation varies depending on the operation mode (see the table below)

The NIB 000 of operation varies depe	maning on	the operation mode (see the table below)
Operation mode (Value set by the MD003 to MD001 bits) (see table above)	MD000	TCR counting operation
• Interval timer mode (0, 0, 0) • Capture mode (0, 1, 0)	0	Timer interrupt is not generated when counting is started (timer output does not change, either).
	1	Timer interrupt is generated when counting is started (timer output also changes).
• Event counter mode (0, 1, 1)	0	Timer interrupt is not generated when counting is started (timer output does not change, either).
• One-count mode (1, 0, 0)	0	Start trigger is invalid during counting operation. At that time, interrupt is not generated, either.
	1	Start trigger is valid during counting operation. At that time, interrupt is also generated.
• Capture & one-count mode (1, 1, 0)	0	Timer interrupt is not generated when counting is started (timer output does not change, either). Start trigger is invalid during counting operation. At that time interrupt is not generated, either.
Other than above		Setting prohibited

Setting up the PWM output pulse cycle time

• Timer data register 00 (TDR00) Configure the PWM output pulse cycle time.

Symbol: TDR00

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0

Pulse cycle time = (TDR00 setting + 1) x Count clock cycle time 2 [ms] = (1/24 [MHz]) x (TDR00 setting + 1)

⇒ TDR00 setting = 47999

Setting up the channel 1 operation mode

• Timer mode register 01 (TMR01)

Select an operation clock (fMCK).

Select a count clock.

Select the 16/8-bit timer.

Select a start trigger and capture trigger.

Select a valid edge for timer input.

Set up the operation mode.

Symbol: TMR01

_	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
	CKS	CKS	0	CCS	SPLI	STS	STS	STS	CIS0	CIS0	0	0	MD0	MD0	MD0	MD0
	011	010		01	T01	012	011	010	11	10			13	12	11	10
	0	0	0	0	0	1	0	0	0	0	0	0	1	0	0	1

Bits 15 and 14

CKS011	CKS010	Channel 1 operation clock (fmck) selection
0	0	Operation clock CK00 set by timer clock select register 0 (TPS0)
0	1	Operation clock CK02 set by timer clock select register 0 (TPS0)
1	0	Operation clock CK01 set by timer clock select register 0 (TPS0)
1	1	Operation clock CK03 set by timer clock select register 0 (TPS0)

Bit 12

CCS01	Selection of count clock (ftclk) of channel 1
0	Operation clock (f _{MCK}) specified with the CKS010 and CKS011 bits
1	Valid edge of the input signal from the TI01 pin

Bit 11

SPLIT01	Selection of 8 or 16-bit timer operation for channel 1
o	Operates as 16-bit timer (Operates in independent channel operation function or as slave channel in simultaneous channel operation function.)
1	Operates as 8-bit timer.

Symbol: TMR01

	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
-	CKS	CKS	0	CCS	SPLI	STS	STS	STS	CIS0	CIS0	0	0	MD0	MD0	MD0	MD0
	011	010		01	T01	012	011	010	11	10			13	12	11	10
ſ	0	0	0	0	0	1	0	0	0	0	0	0	1	0	0	1

Bits 10 to 8

STS012	STS011	STS010	Setting of start trigger or capture trigger of channel 1					
0	0	0	Only software trigger start is valid (other trigger sources are unselected).					
0	0	1	Valid edge of the TI01 pin input is used as both the start trigger and capture trigger.					
0	1	0	Both the edges of the TI01 pin input are used as a start trigger and a capture trigger.					
1	0		Interrupt signal of the master channel is used (when the channel is used as a slave channel with the simultaneous channel operation function).					
Othe	ers than al	oove	Setting prohibited					

Bits 7 and 6

CIS011	CIS010	Selection of TI01 pin input valid edge							
0	0	ling edge							
0	1	ng edge							
1		Both edges (when low-level width is measured)							
ı		Start trigger: Falling edge, Capture trigger: Rising edge							
4	4	Both edges (when high-level width is measured)							
I	ı	Start trigger: Rising edge, Capture trigger: Falling edge							

Symbol: TMR01

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
CKS	CKS	0	CCS	SPLI	STS	STS	STS	CIS0	CIS0	0	0	MD0	MD0	MD0	MD0
011	010		01	T01	012	011	010	11	10			13	12	11	10
0	0	0	0	0	1	0	0	0	0	0	0	1	0	0	1

Bits 3 to 0

MD0 13	MD0 12	MD 011	MD 010	- 1	Related function	TCR counting operation				
0	0	0	1/0	Interval timer mode	Interval timer / Square wave output / Divider function / PWM output (master)	Counting down				
0	1	0	1/0	Capture mode	Input pulse interval measurement	Counting up				
0	1	1	0	Event counter mode	External event counter	Counting down				
1	0	0	1/0		Delay counter / One-shot pulse output / PWM output (slave)	Counting down				
1	1	0	0	'	Measurement of high-/low-level width of input signal	Counting up				
Other than above			ove	Setting prohibited	. 0					

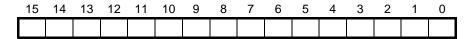
The MD010 bit operation varies depending on the operation mode (see the table below)

Operation mode (Value set by the MD013 to MD011 bits) (see table above)	MD010	TCR counting operation
Interval timer mode (0, 0, 0)Capture mode (0, 1, 0)	0	Timer interrupt is not generated when counting is started (timer output does not change, either).
	1	Timer interrupt is generated when counting is started (timer output also changes).
• Event counter mode (0, 1, 1)	0	Timer interrupt is not generated when counting is started (timer output does not change, either).
• One-count mode (1, 0, 0)	0	Start trigger is invalid during counting operation. At that time, interrupt is not generated, either.
	1	Start trigger is valid during counting operation. At that time, interrupt is also generated.
Capture & one-count mode (1, 1, 0)	0	Timer interrupt is not generated when counting is started (timer output does not change, either). Start trigger is invalid during counting operation. At that time interrupt is not generated, either.
Other than above		Setting prohibited

Configuring the PWM output duty ratio

• Timer data register 01 (TDR01) Configure the PWM output duty ratio.

Symbol: TDR01



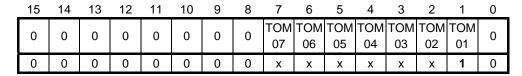
Duty ratio = (TDR01 setting)/(TDR00 setting + 1) x 100 10 [%] = (TDR01 setting)/(63999 + 1) x 100

⇒ TDR01 setting = 6400

Setting up the timer output mode

• Timer output mode register 0 (TOM0) Set up the timer output mode for each channel.

Symbol: TOM0



Bit 1

TOM01	Channel 1 timer output mode control
()	Master channel output mode. (Output is toggled with the timer interrupt request signal (INTTM01).)
1	Slave channel output mode. (Output is set with the master channel's timer interrupt request signal (INTTM01) and reset with the slave channel's timer interrupt request signal (INTTM0p).)

Configuring the output level for the timer output pin

• Timer output level register 0 (TOL0)

Configure the output level for the timer output pin for each channel.

Symbol: TOL0

 15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
0	0	0	0	0	0	0	0	TOL 07	TOL 06	TOL 05	TOL 04	TOL 03	TOL 02	TOL 01	0
0	0	0	0	0	0	0	0	Х	Х	Х	Х	Х	Х	0	0

Bit 1

TOL01	Channel 1 timer output level control						
0	Positive logic output (active-high)						
1	Negative logic output (active-low)						

Configuring the output value for the timer output pin

• Timer output register 0 (TO0) Configure the output value for the timer output pin for each channel.

Symbol: TO0

_	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
	0	0	0	0	0	0	0	0	TO07	TO06	TO05	TO04	TO03	TO02	TO01	TO00
	0	0	0	0	0	0	0	0	х	х	х	х	Х	х	0	Х

Bit 1

TO01	Channel 1 timer output
0	Timer output value is 0
1	Timer output value is 1

Enabling the timer output

• Timer output enable register 0 (TOE0) Enable/disable the timer output for each channel.

Symbol: TOE0

	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
	0	0	0 0	0 0	_	0	0	0	TOE							
	U	0	0	O	0	0	O	O	07	06	05	04	03	02	01	OE TOE 01 00
1	0	0	0	0	0	0	0	0	Х	Х	Х	Х	Х	Х	1	0

Bit 1

TOE01	Timer output enable/disable of channel 1							
	The TO01 operation stopped by count operation (timer channel output bit).							
	Writing to the TO01 bit is enabled.							
0	The TO01 pin functions as data output, and it outputs the level set to the TO01							
	bit.							
	The output level of the TO01 pin can be manipulated be software.							
	The TO01 operation enabled by count operation (timer channel output bit).							
	Writing to the TO01 bit is disabled (writing is ignored).							
1	The TO01 pin functions as timer output, and the TOE01 bit is set or reset							
-	depending on the timer operation.							
	The TO01 pin outputs the square-wave or PWM depending on the timer							
	operation.							

Bit 0

TOE00	Timer output enable/disable of channel 0							
0	The TO00 operation stopped by count operation (timer channel output bit). Writing to the TO00 bit is enabled. The TO00 pin functions as data output, and it outputs the level set to the TO00 bit. The output level of the TO00 pin can be manipulated be software.							
1	The TO00 operation enabled by count operation (timer channel output bit). Writing to the TO00 bit is disabled (writing is ignored). The TO00 pin functions as timer output, and the TOE00 bit is set or reset depending on the timer operation. The TO00 pin outputs the square-wave or PWM depending on the timer operation.							

Setting up the PWM output pin

- Port mode register (P1) Select the PM14 output latch.
- Port mode register (PM1) Select the PM14 I/O mode.

Symbol: P1

7	6	5	4	3	2	1	0
P17 Note 1	P16 Note 1	P15 Note 1	P14 Note 2	P13	P12	P11	P10
Х	Х	Х	0	Х	Х	Х	Х

Bit 4

P14 Note 2	P14 I/O mode selection Note 2					
0	Output mode (output buffer on)					
1	Input mode (output buffer off)					

Symbol: PM1

	7	6	5	4	3	2	1	0
Р	M17 Note 1	PM16 Note 1	PM15 Note 1	PM14 Note 2	PM13	PM12	PM11	PM10
	Х	Х	Х	0	Х	Х	Х	Х

Bit 4

PM14 Note 2	PM14 I/O mode selection Note 2					
0	Output mode (output buffer on)					
1	Input mode (output buffer off)					

Notes: 1. Only for 30-pin products.

2. For 20- and 24-pin products. PM and PM16 for 30-pin products.

Configuring the timer count end interrupts

- Interrupt request flag register (IF0H) Clear the interrupt request flag.
- Interrupt mask flag register (MK0H) Mask interrupts.

Symbol: IF0H

	7	6	5	4	3	2	1	0
	TMIF01	TMIF00	IICAIF0	TMIF03H	TMIF01H	SREIF0	SRIF0	STIF0
							CSIIF01	CSIIF00
							IICIF01	IICIF00
Ì	Х	0	X	Х	Х	Х	Х	Х

Bit 6

TMIF00	Interrupt request flag
0	No interrupt request signal is generated
1	Interrupt request is generated, interrupt
	request status

Symbol: MK0H

7	6	5	4	3	2	1	0
TMMK01	TMMK00	IICAMK0	TMMK03H	TMMK01H	SREMK0	SRMK0	STMK0
						CSIMK01	CSIMK00
						IICMK01	IICMK00
1	1	Х	Х	Х	Х	Х	Х

Bits 7 and 6

TMMK01 TMMK00	Interrupt processing control	
0	Enables interrupt processing.	
1	Disables interrupt processing.	

5.7.5 Main Processing

Figure 5.6 shows the flowchart for main processing.

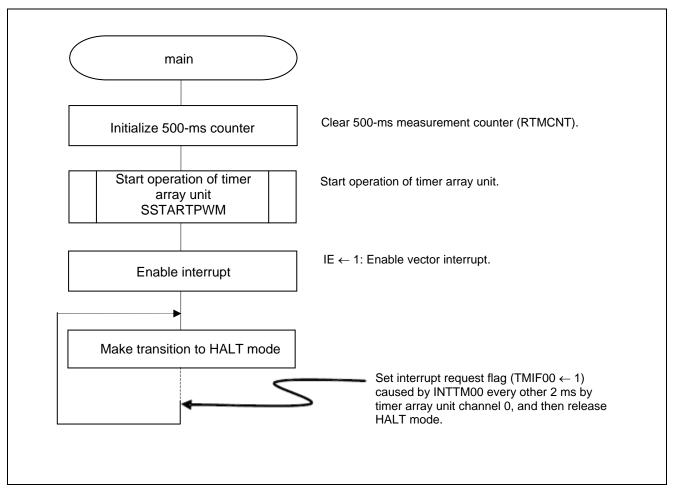


Figure 5.6 Main Processing

5.7.6 Timer Array Unit Startup

Figure 5.7 shows the flowchart for starting the operation of the timer array unit.

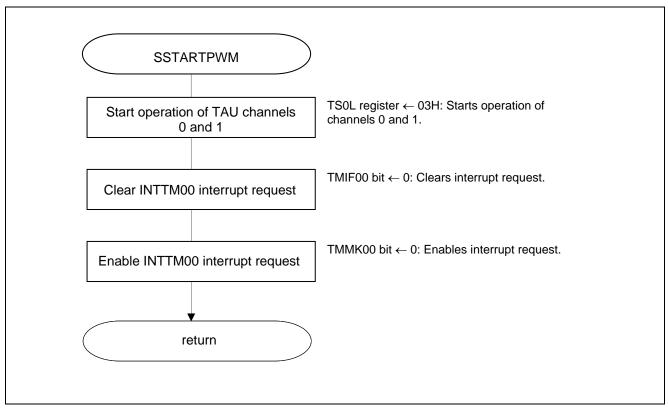


Figure 5.7 Timer Array Unit Startup

Configuring the timer startup

• Timer channel start register 0 (TS0/TS0L) Enable count operation of channel 0 and channel 1.

Symbol: TS0

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
0	0	0	0	TSH 03	0	TSH 01	0	TS0 7	TS0 6	TS0 5	TS0 4	TS0 3	TS0 2	TS0 1	TS0 0
0	0	0	0	Х	0	Х	0	Х	Х	Х	Х	Х	Х	1	1

Bit 1

TS01	Operation enable (start) trigger of channel 1
0	No trigger operation
	The TE01 bit is set to 1 and the count operation becomes enabled.
1	The TCR01 register count operation start in the count operation enabled
	state varies depending on each operation mode.

Bit 0

TS00	Operation enable (start) trigger of channel 0
0	No trigger operation
1	The TE00 bit is set to 1 and the count operation becomes enabled. The TCR00 register count operation start in the count operation enabled state varies depending on each operation mode.

Configuring the timer count end interrupts

- Interrupt request flag register (IF0H) Clear the interrupt request flag.
- Interrupt mask flag register (MK0H) Mask interrupts.

Symbol: IF0H

7	6	5	4	3	2	1	0
TMIF01	TMIF00	IICAIF0	TMIF03H	TMIF01H	SREIF0	SRIF0	STIF1
						CSIIF01	CSIIF00
						IICIF01	IICIF00
Х	0	Х	Х	Х	Х	Х	Х

Bit 6

TMIF00	Interrupt request flag
0	No interrupt request signal is generated
	Interrupt request is generated, interrupt request status

Symbol: MK0H

	7	6	5	4	3	2	1	0
TMI	MK01	TMMK00	IICAMK0	TMMK03H	TMMK01H	SREMK0	SRMK0	STMK0
							CSIMK01	CSIMK00
							IICMK01	IICMK00
	Х	0	Х	Х	Х	Х	Х	Х

Bit 6

TMMK00	Interrupt processing control
0	Enables interrupt processing.
1	Disables interrupt processing.

5.7.7 INTTM0 Interrupt Processing

Figure 5.8 shows the flowchart for INTTM0 interrupt processing.

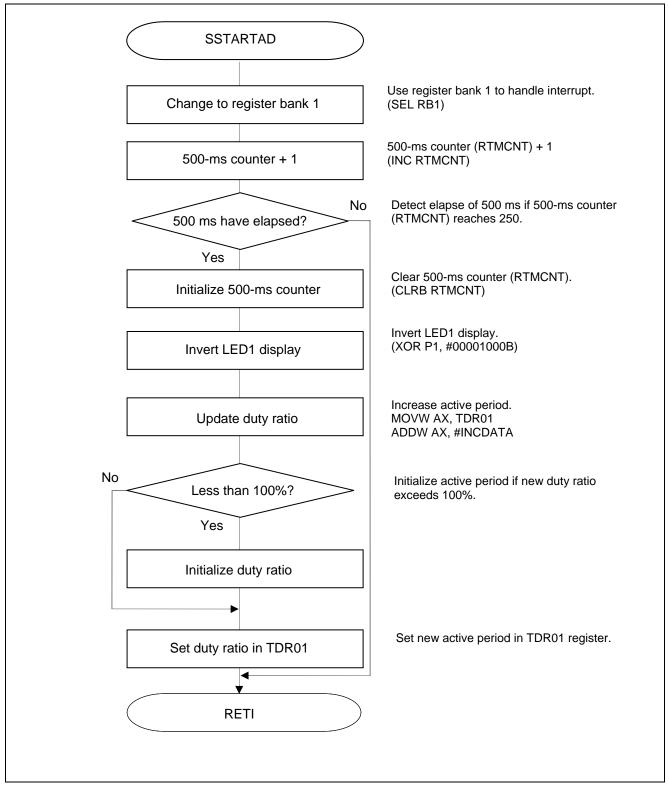


Figure 5.8 INTTM0 Interrupt Service Routine

6. Sample Code

The sample code is available on the Renesas Electronics Website.

7. Documents for Reference

RL78/G12 User's Manual: Hardware Rev.2.00 (R01UH0200E)

RL78 Family User's Manual: Software Rev.2.00 (R01US0015E)

(The latest versions of the documents are available on the Renesas Electronics Website.)

Technical Updates/Technical Brochures

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http://www.renesas.com/index.jsp

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Revision Record	RL78/G12 Timer Array Unit (PWM Output) CC-RL
-----------------	----------------------------------------------

Dov	Dot Doto		Description
Rev. Date		Page	Summary
1.00	Jun.19, 2015	_	First edition issued
2.00	Nov.11, 2015	5	Table 2.1: Added e ² studio
		13	MCM0 bit was fixed of set value

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1. Handling of Unused Pins

Handle unused pins in accordance with the directions given under Handling of Unused Pins in the manual

34 The input pins of CMOS products are generally in the high-impedance state. In operation with an unused pin in the open-circuit state, extra electromagnetic noise is induced in the vicinity of LSI, an associated shoot-through current flows internally, and malfunctions occur due to the false recognition of the pin state as an input signal become possible. Unused pins should be handled as described under Handling of Unused Pins in the manual.

2. Processing at Power-on

The state of the product is undefined at the moment when power is supplied.

- 3/4 The states of internal circuits in the LSI are indeterminate and the states of register settings and pins are undefined at the moment when power is supplied.
 In a finished product where the reset signal is applied to the external reset pin, the states of pins are not guaranteed from the moment when power is supplied until the reset process is completed.
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- 3. Prohibition of Access to Reserved Addresses

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3/4 The reserved addresses are provided for the possible future expansion of functions. Do not access these addresses; the correct operation of LSI is not guaranteed if they are accessed.

4. Clock Signals

After applying a reset, only release the reset line after the operating clock signal has become stable. When switching the clock signal during program execution, wait until the target clock signal has stabilized.

When the clock signal is generated with an external resonator (or from an external oscillator) during a reset, ensure that the reset line is only released after full stabilization of the clock signal. Moreover, when switching to a clock signal produced with an external resonator (or by an external oscillator) while program execution is in progress, wait until the target clock signal is stable.

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