

Interfacing the X5043 Watchdog Timer to Hitachi H8/3000 Microcontrollers

The following code demonstrates how the Intersil X5043 SPI serial EEPROM and watchdog timer could be interfaced to the Hitachi H8/3000 microcontroller family when connected

as shown in Figure 1. The interface uses four of the port pins available on H8 family devices to implement the interface.

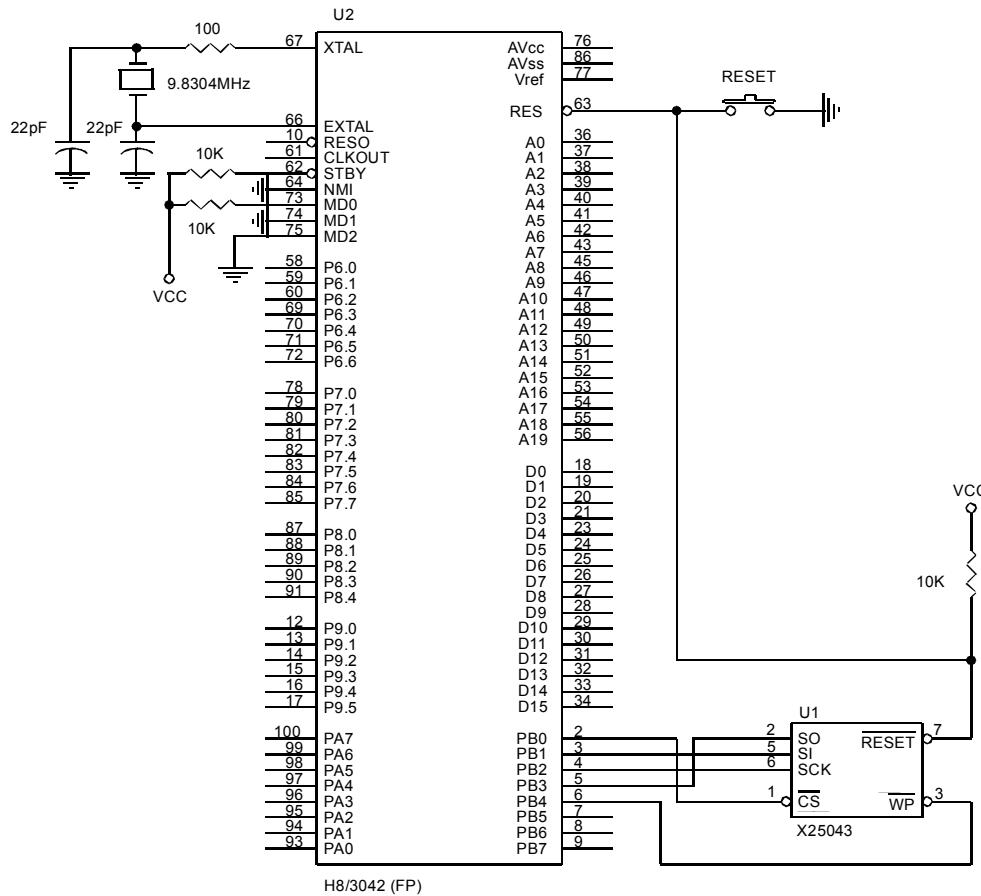


FIGURE 1. TYPICAL HARDWARE CONNECTION FOR INTERFACING AN X5043 TO THE H8/3042 MICROCONTROLLER

```

        .h8300h
        .file "h8x25043.asm"

; h8x25043.asm

; Demonstration code for interfacing Xicor X5043 to Hitachi H8/3042

; Revision: 2.03 02/04/96

; Expects the H8/3042 hard-wired in Mode 1: 8-bit bus-width, Expanded address
; space (0x00000-0xFFFF), Internal ROM disabled, Internal RAM enabled
; (0xFF710-0xFFFF0F), 9.8304 MHx xtal

        .include "h8stddef.inc"           ; H8/3042 standard register definitions

; H8/3042 specific equates

        .equ H8RAMTOP,      0xFFFF0F      ; Highest onboard RAM address (2048 bytes)
        .equ H8RAMBOT,      0xFF710       ; Lowest onboard RAM address
        .equ RXD0,          bit_2         ; Receive data pin of port/SCI
        .equ INTMASK,       0b11000000  ; CCR Interrupt Mask (I and UI bits)

; Xicor X5043 device-specific equates

        .equ CS,             bit_0         ; Port bit for Chip Select input (H8 out)
        .equ SI,             bit_1         ; Port bit for Serial data Input (H8 out)
        .equ SCK,            bit_2         ; Port bit for Serial ClocK input (H8 out)
        .equ SO,             bit_3         ; Port bit for Serial data Output (H8 in)
        .equ WP,             bit_4         ; Port bit for Write Protect input (H8 out)

        .equ XICOR,          PBDR          ; H8/3042 data port assignment (PB)
        .equ XICORDDR,       PBDDR         ; H8/3042 data direction port assignment
        .equ DDRSETUP,       0b11110111  ; Port Data Direction Register setup

        .equ WREN,           0x06          ; WRite ENable latch instruction
        .equ WRDI,           0x04          ; WRite DIable latch instruction
        .equ WRSR,           0x01          ; WRite Status Register instruction
        .equ RDSR,           0x05          ; ReAD Status Register instruction
        .equ WRITE,          0x02          ; WRITE memory instruction
        .equ READ,           0x03          ; READ memory instruction

        .equ STATUSREG,     0x00          ; Status Register

        .equ WIPBIT,          bit_0         ; Write In Progress status bit
        .equ ADDRBIT,         bit_3         ; Read/Write instruction address MSB
        .equ PAGESIZE,        4             ; Bytes per page
        .equ NUMPAGES,        128           ; Number of pages in X25043
        .equ NUMBYTES,        NUMPAGES*PAGESIZE ; Number of bytes in X25043
        .equ MAXPOLL,         100           ; Maximum number of poll attempts for WIP

; Main equates

        .equ STACKTOP,        H8RAMTOP-4   ; Stack initializes here and builds down
        .equ ALLONES,          0b11111111 ; All bits set
        .equ BIGWRITE,         70            ; Test number of bytes to write
        .equ RAMBFR0,          H8RAMBOT    ; Start of read/write buffer in on-board RAM
        .equ RAMBFR1,          H8RAMBOT+PAGESIZE ; Second read/write buffer
        .equ RAMBFR2,          RAMBFR1+BIGWRITE ; Third read/write buffer
        .equ DATABYTE0,        0xF0          ; Test byte 0
        .equ DATABYTE1,        0x0F          ;               1

```

```

.equ  DATABYTE2, 0x55      ; 2/Power-up flag
.equ  DATABYTE3, 0xAA      ; 3/
.equ  PWRUPFLGS, 256*DATABYTE3+DATABYTE2 ; 0xAA55
.equ  XADDRB, 45          ; Test byte write/read address
.equ  XADDRP, 200         ; Test page write/read address
.equ  XADDRBP, 0x195       ; Test block protect read/write address
.equ  XADDRBW, 0x037       ; EEPROM BigWrite destination
.equ  H8RAMLOC0, H8RAMBOT+1047 ; Power-up RAM test location 0
.equ  H8RAMLOC1, H8RAMBOT+1597 ; 1

; Start of code
; .org 0x000000             ; H8/3042 Interrupt vector jump table
; Must reside at address 0x000000

.long 0x00000100          ; 0 RESET
.long _bogus_int           ; 1 reserved
.long _bogus_int           ; 2 reserved
.long _bogus_int           ; 3 reserved
.long _bogus_int           ; 4 reserved
.long _bogus_int           ; 5 reserved
.long _bogus_int           ; 6 reserved
.long _bogus_int           ; 7 external interrupt (NMI)
.long _bogus_int           ; 8 Trap Instruction (4 sources)
.long _bogus_int           ; 9 Trap Instruction (4 sources)
.long _bogus_int           ; 10 Trap Instruction (4 sources)
.long _bogus_int           ; 11 Trap Instruction (4 sources)
.long _bogus_int           ; 12 External Interrupt IRQ0
.long _bogus_int           ; 13 External Interrupt IRQ1
.long _bogus_int           ; 14 External Interrupt IRQ2
.long _bogus_int           ; 15 External Interrupt IRQ3
.long _bogus_int           ; 16 External Interrupt IRQ4
.long _bogus_int           ; 17 External Interrupt IRQ5
.long _bogus_int           ; 18 reserved
.long _bogus_int           ; 19 reserved
.long _bogus_int           ; 20 WOVI Watchdog timer
.long _bogus_int           ; 21 CMI Refresh controller
.long _bogus_int           ; 22 reserved
.long _bogus_int           ; 23 reserved
.long _bogus_int           ; 24 IMIA0 GRA0 compare match/input capture
.long _bogus_int           ; 25 IMIB0 GRB0 compare match/input capture
.long _bogus_int           ; 26 OVI0 overflow 0
.long _bogus_int           ; 27 reserved
.long _bogus_int           ; 28 IMIA1 GRA1 compare match/input capture
.long _bogus_int           ; 29 IMIB1 GRB1 compare match/input capture
.long _bogus_int           ; 30 OVI1 overflow 1
.long _bogus_int           ; 31 reserved
.long _bogus_int           ; 32 IMIA2 GRA2 compare match/input capture
.long _bogus_int           ; 33 IMIB2 GRB2 compare match/input capture
.long _bogus_int           ; 34 OVI2 overflow 2
.long _bogus_int           ; 35 reserved
.long _bogus_int           ; 36 IMIA3 GRA3 compare match/input capture
.long _bogus_int           ; 37 IMIB3 GRB3 compare match/input capture
.long _bogus_int           ; 38 OVI3 overflow 3
.long _bogus_int           ; 39 reserved
.long _bogus_int           ; 40 IMIA4 GRA4 compare match/input capture
.long _bogus_int           ; 41 IMIB4 GRB4 compare match/input capture
.long _bogus_int           ; 42 OVI4 overflow 4
.long _bogus_int           ; 43 reserved
.long _bogus_int           ; 44 DEND0A DMAC group 0
.long _bogus_int           ; 45 DEND0B DMAC group 0
.long _bogus_int           ; 46 DEND1A DMAC group 0

```

```

.long _bogus_int           ; 47 DEND1B  DMAC group 0
.long _bogus_int           ; 48 reserved
.long _bogus_int           ; 49 reserved
.long _bogus_int           ; 50 reserved
.long _bogus_int           ; 51 reserved
.long _bogus_int           ; 52 ERI0 receive error      SCI chan 0
.long _bogus_int           ; 53 RXI0 receive data full   SCI chan 0
.long _bogus_int           ; 54 TXI0 transmit data empty SCI chan 0
.long _bogus_int           ; 55 TEI0 transmit end       SCI chan 0
.long _bogus_int           ; 56 ERI1 receive error      SCI chan 1
.long _bogus_int           ; 57 RXI1 receive data full   SCI chan 1
.long _bogus_int           ; 58 TXI1 transmit data empty SCI chan 1
.long _bogus_int           ; 59 TEI1 transmit end       SCI chan 1
.long _bogus_int           ; 60 ADI  A/D end

_bogus_int:
    orc      #0b11000000,ccr ; Disable interrupts (I and UI)
    rte

; .org      0x000100

_powerup:
    orc      #INTMASK,ccr   ; Initialization
    mov.l   #STACKTOP,er7    ; Disable interrupts (I and UI)
    bsr     _init_xiport:16  ; Initialize the Stack pointer
    bset    #WP,@XICOR      ; Initialize the X25043 I/O port
    bset    #WRP@XICOR      ; Write Protect line high to enable X25043
    bset    #WREN@XICOR     ; writes
    bsr     _wren_cmnd:16   ; Write Protect line high to enable X25043
    mov.b   #0b00110000,r01  ; Enable writing to the X25043 to ...
    bsr     _wrsr_cmnd:16   ; Setup to disable the WDT
    bsr     _wrsr_cmnd:16   ; ... and do so!

_main:
    mov.l   #H8RAMLOC0,er1  ; Point to power-up flag location 0
    mov.b   @er1,r01         ; ... and fetch the flag
    mov.l   #H8RAMLOC1,er2  ; ... the other flag, location 1
    mov.b   @er2,r0h         ; ... fetch it
    mov.w   #PWRUPFLGS,r3   ; Setup flag compare (and re-write)
    mov.b   r3l,@er1         ; Store first flag
    mov.b   r3h,@er2         ; ... and the second
    cmp.w   r0,r3            ; ... and the second
    beq     _skip_wdt        ; (we've powered-up or reset)
                           ; Has the WDT brought us here?
                           ; Yes, skip the Watch Dog Timer exercise

; Exercise the X5043 Watch Dog Timer one time

_wdt_delay:
    bsr     _wren_cmnd:16   ; No, enable writing to the X5043
    mov.b   #0b00100000,r01  ; Setup the WDT for 200ms
    bsr     _wrsr_cmnd:16   ; ... and enable it

_wdtdly_loop:
    mov.w   #30788,r3        ; Setup loop count (100ms @9.8304MHz)
    dec.w   #1,r3             ; Crank the counter
    bne     _wdtdly_loop     ; Done?
    bsr     _wdog_reset:16   ; Kick the dog (verifies WDT reset)

_wdt_wait:
    bra     _wdt_wait:16     ; Spin here until WDT kicks back to reset

; Skip the Watch Dog Timer ... done once, now byte Read/Write exercise

_skip_wdt:

```

```

xor.b      r01,r01          ; Setup null byte to clear power-up flags
mov.l      #H8RAMLOC0,er1    ; Point to power-up flag location 0
mov.b      r01,@er1          ; ... and clear the flag
mov.l      #H8RAMLOC1,er1    ; ... the other flag, location 1
mov.b      r01,@er1          ; ... and clear it (now reset recycles WDT)
bsr       _rdsr_cmnd:16     ; Read the X5043 status register
bsr       _wren_cmnd:16     ; Enable writing to the X5043
mov.b      #DATABYTE0,r01    ; Setup data for single byte write
mov.w      #XADDRB,r1        ; Setup X5043 target address
bsr       _byte_write:16     ; ... and write it
mov.w      #XADDRB,r1        ; Setup X5043 source address
bsr       _byte_read:16      ; ... and fetch it!
bsr       _wren_cmnd:16      ; Enable writing to the X5043
mov.b      #DATABYTE1,r01    ; Setup data for single byte write
mov.w      #XADDRB,r1        ; Setup X5043 target address
bsr       _byte_write:16     ; ... and write it
mov.w      #XADDRB,r1        ; Setup X5043 source address
bsr       _byte_read:16      ; ... and fetch it!

; Page Read/Write exercise

bsr       _wren_cmnd:16      ; Enable writing to the X5043
mov.w      #XADDRP,r1        ; Setup X5043 target page address
mov.l      #_dataset0,er2     ; Point to source data
bsr       _page_write:16     ; ... and write the page
mov.w      #XADDRP,r1        ; Again, setup X5043 source page address
mov.l      #RAMBFR0,er2       ; Point to destination buffer in onboard RAM
mov.w      #PAGESIZE,e1      ; Setup byte read count
bsr       _read_seq:16        ; ... and read the page

; Sequential Read/Write exercise

xor.w      r0,r0              ; Initialize byte sequence (0->BIGWRITE-1)
mov.l      #RAMBFR1,er2       ; ... and point to the destination
._bigwr_setup:
  mov.b      r01,@er2          ; Store a byte in the RAM buffer
  inc.l      #1,er1             ; Bump pointer to next RAM location
  inc.w      #1,r0              ; Count bytes stored/generate next byte
  cmp.w      #BIGWRITE,r0      ; Have we done 'em all?
  blt       _bigwr_setup       ; No, continue

  mov.w      #BIGWRITE,e1      ; Setup X5043 'big write' (count is in e1)
  mov.w      #XADDRBW,r1        ; Enable writing to the X5043
  bsr       _wren_cmnd:16      ; ... and write 'em

  mov.w      #BIGWRITE,e1      ; Setup to read 'em back!
  mov.w      #XADDRBW,r1        ; Point to destination buffer
  mov.l      #RAMBFR2,er2       ; Point to source data
  bsr       _read_seq:16        ; ... and read 'em

; Block Protect exercise

bsr       _wren_cmnd:16      ; Enable writing to the X5043
mov.b      #0b00110100,r01    ; Setup Block Protect upper quarter (0x180+)
bsr       _wrsr_cmnd:16      ; ... and protect it
mov.w      #XADDRBP,r1        ; Setup X25043 source address (protected)
bsr       _byte_read:16      ; ... and fetch it!
not.b     r01                 ; One's complement, for re-write verify
mov.b     r01,r11             ; Temporarily preserve it

```

```

bsr      _wren_cmnd:16 ; Enable writing to the X5043
mov.b   r11,r01          ; Recover data for single byte write
mov.w   #XADDRBP,r1      ; Setup X5043 target address (protected)
bsr      _byte_write:16  ; ... and write it
mov.w   #XADDRBP,r1      ; Setup X5043 source address
bsr      _byte_read:16   ; ... and fetch it!

_end_loop:
bra      _end_loop        ; Terminal infinite loop

; X25043 Interface Subroutines

; Name:      _init_xiport
; Function:  Initializes the H8 I/O port bit directions
; Calls:     None
; Expects:   Nothing
; Returns:   Nothing
; Registers: r01
; Remarks:   Must be called once initially to setup the I/O port

_init_xiport:
    mov.b   #DDRSETUP,r01
    mov.b   r01,@XICORDDR
    bset    #CS,@XICOR       ; Chip Select disable X5043
    bclr    #SI,@XICOR       ; Drop Serial Input to X5043
    bclr    #SCK,@XICOR      ; Drop the clock SCK
    bclr    #WP,@XICOR       ; Write Protect line low, disable writes
    rts

; Name:      _wren_cmnd
; Function:  Sends the command to enable writing to the Xicor X5043 EEPROM
; Calls:     _send_byte
; Expects:   Nothing
; Returns:   Nothing
; Registers: r01
; Remarks:

_wren_cmnd:
    bclr    #SCK,@XICOR      ; SCK low
    bclr    #CS,@XICOR       ; CS low
    mov.b   #WREN,r01         ; Setup Write Enable instruction
    bsr     _send_byte:16
    bclr    #SCK,@XICOR      ; SCK low
    bset    #CS,@XICOR       ; CS high
    rts

; Name:      _wrdi_cmnd
; Function:  Sends the command to disable writing to the Xicor X5043 EEPROM
; Calls:     _send_byte
; Expects:   Nothing
; Returns:   Nothing
; Registers: r01
; Remarks:

_wrdi_cmnd:
    bclr    #SCK,@XICOR      ; SCK low
    bclr    #CS,@XICOR       ; CS low
    mov.b   #WRDI,r01         ; Setup Write Disable instruction
    bsr     _send_byte:16
    bclr    #SCK,@XICOR      ; SCK low
    bset    #CS,@XICOR       ; CS high
    rts

```

```

; Name:      _wrsr_cmnd
; Function:  Sends the command which enables writing to the WD0, WD1, BP0 and
;             BP1 bits of the Xicor X5043 EEPROM status register
; Calls:     _send_byte, _poll_write
; Expects:   Block Protect/Watchdog Timer bits in r01
; Returns:   Nothing
; Registers: r01, e0
; Remarks:

_wrsr_cmnd:
    mov.w      r0,e0          ; Temporarily preserve WDT/BP bits
    bclr      #SCK,@XICOR    ; SCK low
    bclr      #CS,@XICOR     ; CS low
    mov.b      #WRSR,r01      ; Setup Write Status Register instruction
    bsr       _send_byte:16
    mov.w      e0,r0          ; Recover WDT/BP bits
    bsr       _send_byte:16
    bclr      #SCK,@XICOR    ; SCK low
    bset      #CS,@XICOR     ; CS high
    bsr       _poll_write:16
    rts

; Name:      _rdsr_cmnd
; Function:  Sends the command which reads the contents of the Xicor X5043
;             EEPROM status register
; Calls:     _send_byte, _recv_byte
; Expects:   Nothing
; Returns:   Status in r01
; Registers: r01
; Remarks:

_rdsr_cmnd:
    bclr      #SCK,@XICOR    ; SCK low
    bclr      #CS,@XICOR     ; CS low
    mov.b      #RDSR,r01      ; Setup Read Status Register instruction
    bsr       _send_byte:16
    bsr       _recv_byte:16
    bclr      #SCK,@XICOR    ; SCK low
    bset      #CS,@XICOR     ; CS high
    rts

; Name:      _byte_write
; Function:  Writes a single byte to the Xicor X5043 EEPROM memory array
; Calls:     _send_byte, _poll_write
; Expects:   Byte to be sent in r01, address in r1 (0x0000-0x01FF)
; Returns:   Nothing
; Registers: r01, r1, e0
; Remarks:

_byte_write:
    bclr      #SCK,@XICOR    ; SCK low
    bclr      #CS,@XICOR     ; CS low
    mov.w      r0,e0          ; Temporarily preserve the byte
    mov.b      #WRITE,r01      ; Setup Write instruction
    rotr.b    r1h             ; Rotate the address MSB into Carry
    bst       #ADDRBIT,r01     ; Stuff it
    bsr       _send_byte:16
    mov.b      r1l,r01         ; Fetch address LS byte
    bsr       _send_byte:16

```

```

mov.w      e0,r0          ; Recover the byte
bsr        _send_byte:16
bclr      #SCK,@XICOR     ; SCK low
bset      #CS,@XICOR      ; CS high
bsr        _poll_write:16
rts

; Name:      _byte_read
; Function:  Reads a single byte from the Xicor X5043 EEPROM memory array
; Calls:     _send_byte, _recv_byte
; Expects:   Serial EEPROM byte address in r1 (0x0000-0x01FF)
; Returns:   Byte read in r01
; Registers: r01, r1, e0
; Remarks:

_byte_read:
    bclr      #SCK,@XICOR     ; SCK low
    bclr      #CS,@XICOR      ; CS low
    mov.b    #READ,r01        ; Setup Read instruction
    rotr.b   r1h             ; Rotate the address MSB into Carry
    bst      #ADDRBIT,r01      ; Stuff it
    bsr        _send_byte:16
    mov.b    r11,r01          ; Fetch address LS byte
    bsr        _send_byte:16    ; ... and send it
    bsr        _recv_byte:16    ; Receive byte from EEPROM
    bclr      #SCK,@XICOR     ; SCK low
    bset      #CS,@XICOR      ; CS high
    rts

; Name:      _page_write
; Function:  Sends a full page (4 bytes) to the Xicor X5043 EEPROM
; Calls:     _send_byte, _poll_write
; Expects:   Serial EEPROM destination starting address in r1, pointer to
;            source bytes (4) in er2
; Returns:   Nothing
; Registers: r01, r0h, r1, er2
; Remarks:

_page_write:
    bclr      #SCK,@XICOR     ; SCK low
    bclr      #CS,@XICOR      ; CS low
    mov.b    #WRITE,r01        ; Setup Write instruction
    rotr.b   r1h             ; Rotate the address MSB into Carry
    bst      #ADDRBIT,r01      ; Stuff it
    bsr        _send_byte:16
    mov.b    r11,r01          ; Fetch address LS byte
    and.b    #0b11111100,r01    ; Mask drivel to page boundary
    bsr        _send_byte:16
    mov.b    #PAGESIZE,r31

_page_wrloop:
    mov.b    @er2+,r01          ; Fetch byte to send, point to next one
    bsr        _send_byte:16
    dec.b    r31              ; Click off another sent byte
    bne      _page_wrloop
    bclr      #SCK,@XICOR     ; SCK low
    bset      #CS,@XICOR      ; CS high
    bsr        _poll_write:16
    rts

; Name:      _read_seq
; Function:  Reads a sequence of bytes from the Xicor X5043 Serial EEPROM

```

```

; Calls:      _send_byte, _recv_byte
; Expects:    EEPROM source starting address in r1 (0x0000-0x01FF), count of
;             bytes to read in e1, pointer to start of destination storage in er2
; Returns:    Byte array read in memory
; Registers:  r01, r0h, r1, e1, er2
; Remarks:

_read_seq:
    bclr      #SCK,@XICOR      ; SCK low
    bclr      #CS,@XICOR       ; CS low
    mov.b    #READ,r01         ; Setup Read instruction
    rotr.b   r1h               ; Rotate the address MSB into Carry
    bst      #ADDRBIT,r01       ; Stuff it
    bsr      _send_byte:16
    mov.b    r1l,r01           ; Fetch address LS byte
    bsr      _send_byte:16

_read_seqloop:
    bsr      _recv_byte:16
    mov.b    r01,@er2          ; Store EEPROM byte into memory
    inc.l    #1,er2            ; Point to next storage location
    dec.w    #1,e1              ; Click off another byte read
    bne      _read_seqloop
    bclr      #SCK,@XICOR      ; SCK low
    bset      #CS,@XICOR       ; CS high
    rts

; Name:      _write_seq
; Function:   Writes a sequence of bytes to the Xicor X5043 Serial EEPROM
; Calls:      _send_byte, _poll_write, _wren_cmnd
; Expects:    EEPROM destination starting address in r1 (0x0000-0x01FF), count of
;             bytes to write in e1, pointer to start of source storage in er2
; Returns:    Nothing
; Registers:  r01, r0h, r1, e1, er2, r3, e3
; Remarks:   Takes advantage of page write mode to minimize write times

_write_seq:
    bclr      #SCK,@XICOR      ; SCK low
    bclr      #CS,@XICOR       ; CS low
    mov.w    r1,e3             ; preserve EEPROM destination address
    mov.b    #WRITE,r01         ; Setup Write instruction
    rotr.b   r1h               ; Rotate the address MSB into Carry
    bst      #ADDRBIT,r01       ; Stuff it
    bsr      _send_byte:16
    mov.b    r1l,r01           ; Fetch address LS byte
    bsr      _send_byte:16

_write_seqloop:
    mov.b    @er2+,r01          ; Fetch byte to write & point to next one
    bsr      _send_byte:16
    dec.w    #1,e1              ; Click off another byte written
    inc.w    #1,e3              ; Point to next destination address
    mov.w    e3,r3              ; ... and scratchpad it
    and.b    #0b00000011,r31     ; Keep destination address page bits
    beq      _wrseq_pagend     ; '00' means prior address was page end
    or.w     e1,e1              ; Is the byte count zero?
    bne      _write_seqloop    ; No, continue with this page
    bclr      #SCK,@XICOR      ; SCK low
    bset      #CS,@XICOR       ; CS high
    bsr      _poll_write:16
    rts

_wrseq_pagend:
    bclr      #SCK,@XICOR      ; SCK low

```

```

bset      #CS,@XICOR          ; CS high
bsr       _poll_write:16      ; Is the write still in progress in EEPROM?
or.w     e1,e1                ; Is the byte count zero?
beq      _wrseq_done          ; Yes, we're done
bsr       _wren_cmnd:16        ; No, more to do so re-enable writing
mov.w    e3,r1                ; Recover next EEPROM address as expected
bra      _write_seq           ; Back to the EEPROM
_wrseq_done:
rts

; Name:      _send_byte
; Function: Sends a byte to the Xicor X5043 EEPROM, serially shifting MSB
; first
; Calls:     None
; Expects:   Byte to be sent in r01
; Returns:   Nothing
; Registers: r01, r0h
; Remarks:

_send_byte:
    mov.b    #8,r0h            ; Setup bit count
_send_loop:
    bclr    #SCK,@XICOR        ; SCK low
    rotxl.b r01                ; Slip next MSB into Carry
    bst     #SI,@XICOR         ; Copy Carry to I/O port bit
    bset    #SCK,@XICOR        ; SCK high
    dec.b   r0h                ; Click off a bit
    bne     _send_loop          ; Continue if not done
    bclr    #SI,@XICOR         ; SI low
rts

; Name:      _recv_byte
; Function: Receives a byte from the Xicor X5043 EEPROM, serially shifting MSB
; first
; Calls:     None
; Expects:   Nothing
; Returns:   Received byte in r01
; Registers: r01, r0h
; Remarks:

_recv_byte:
    mov.b    #8,r0h            ; Setup bit count
_recv_loop:
    bset    #SCK,@XICOR        ; SCK high
    nop
    nop
    nop                      ; Guarantee limited clock rate
    bclr    #SCK,@XICOR        ; SCK low
    bld     #SO,@XICOR         ; Copy input port bit to Carry
    rotxl.b r01                ; Slip Carry into LSB
    dec.b   r0h                ; Click off a bit
    bne     _recv_loop          ; Continue if not done
rts

; Name:      _poll_write
; Function: Polls for the completion of the non-volatile write cycle by
; examining the Write-In-Progress bit of the status register
; Calls:     _rdsr_cmnd
; Expects:   Nothing
; Returns:   Nothing
; Registers: r11

```

```
; Remarks:  
  
_poll_write:  
    mov.b      #MAXPOLL$ ,r11      ; Setup maximum number of poll attempts  
_poll_loop:  
    bsr        _rdsr_cmnd:16     ; Fetch the X5043 Status Register content  
    btst       #WIPBIT,r01       ; Is the Write-In-Progress bit zero?  
    beq        _poll_loop1      ; Yes, write is complete  
    dec.b      r11             ; No, click off another poll attempt  
    bne        _poll_loop      ; If we haven't exceeded maximum polls ...  
_poll_loop1:  
    rts  
  
; Name:      _wdog_reset  
; Function:   Resets the watchdog timer  
; Calls:      None  
; Expects:    Nothing  
; Returns:    Nothing  
; Registers: None  
; Remarks:  
  
_wdog_reset:  
    bclr      #CS,@XICOR  
    nop  
    nop  
    nop  
    bset      #CS,@XICOR  
    rts  
  
; Data tables  
  
    .align    0  
_dataset0:  
    .byte     DATABYTE0  
    .byte     DATABYTE1  
    .byte     DATABYTE2  
    .byte     DATABYTE3
```

Notice

1. Descriptions of circuits, software and other related information in this document are provided only to illustrate the operation of semiconductor products and application examples. You are fully responsible for the incorporation or any other use of the circuits, software, and information in the design of your product or system. Renesas Electronics disclaims any and all liability for any losses and damages incurred by you or third parties arising from the use of these circuits, software, or information.
2. Renesas Electronics hereby expressly disclaims any warranties against and liability for infringement or any other claims involving patents, copyrights, or other intellectual property rights of third parties, by or arising from the use of Renesas Electronics products or technical information described in this document, including but not limited to, the product data, drawings, charts, programs, algorithms, and application examples.
3. No license, express, implied or otherwise, is granted hereby under any patents, copyrights or other intellectual property rights of Renesas Electronics or others.
4. You shall not alter, modify, copy, or reverse engineer any Renesas Electronics product, whether in whole or in part. Renesas Electronics disclaims any and all liability for any losses or damages incurred by you or third parties arising from such alteration, modification, copying or reverse engineering.
5. Renesas Electronics products are classified according to the following two quality grades: "Standard" and "High Quality". The intended applications for each Renesas Electronics product depends on the product's quality grade, as indicated below.
"Standard": Computers; office equipment; communications equipment; test and measurement equipment; audio and visual equipment; home electronic appliances; machine tools; personal electronic equipment; industrial robots; etc.
"High Quality": Transportation equipment (automobiles, trains, ships, etc.); traffic control (traffic lights); large-scale communication equipment; key financial terminal systems; safety control equipment; etc. Unless expressly designated as a high reliability product or a product for harsh environments in a Renesas Electronics data sheet or other Renesas Electronics document, Renesas Electronics products are not intended or authorized for use in products or systems that may pose a direct threat to human life or bodily injury (artificial life support devices or systems; surgical implants; etc.), or may cause serious property damage (space system; underwater repeaters; nuclear power control systems; aircraft control systems; key plant systems; military equipment; etc.). Renesas Electronics disclaims any and all liability for any damages or losses incurred by you or any third parties arising from the use of any Renesas Electronics product that is inconsistent with any Renesas Electronics data sheet, user's manual or other Renesas Electronics document.
6. When using Renesas Electronics products, refer to the latest product information (data sheets, user's manuals, application notes, "General Notes for Handling and Using Semiconductor Devices" in the reliability handbook, etc.), and ensure that usage conditions are within the ranges specified by Renesas Electronics with respect to maximum ratings, operating power supply voltage range, heat dissipation characteristics, installation, etc. Renesas Electronics disclaims any and all liability for any malfunctions, failure or accident arising out of the use of Renesas Electronics products outside of such specified ranges.
7. Although Renesas Electronics endeavors to improve the quality and reliability of Renesas Electronics products, semiconductor products have specific characteristics, such as the occurrence of failure at a certain rate and malfunctions under certain use conditions. Unless designated as a high reliability product or a product for harsh environments in a Renesas Electronics data sheet or other Renesas Electronics document, Renesas Electronics products are not subject to radiation resistance design. You are responsible for implementing safety measures to guard against the possibility of bodily injury, injury or damage caused by fire, and/or danger to the public in the event of a failure or malfunction of Renesas Electronics products, such as safety design for hardware and software, including but not limited to redundancy, fire control and malfunction prevention, appropriate treatment for aging degradation or any other appropriate measures. Because the evaluation of microcomputer software alone is very difficult and impractical, you are responsible for evaluating the safety of the final products or systems manufactured by you.
8. Please contact a Renesas Electronics sales office for details as to environmental matters such as the environmental compatibility of each Renesas Electronics product. You are responsible for carefully and sufficiently investigating applicable laws and regulations that regulate the inclusion or use of controlled substances, including without limitation, the EU RoHS Directive, and using Renesas Electronics products in compliance with all these applicable laws and regulations. Renesas Electronics disclaims any and all liability for damages or losses occurring as a result of your noncompliance with applicable laws and regulations.
9. Renesas Electronics products and technologies shall not be used for or incorporated into any products or systems whose manufacture, use, or sale is prohibited under any applicable domestic or foreign laws or regulations. You shall comply with any applicable export control laws and regulations promulgated and administered by the governments of any countries asserting jurisdiction over the parties or transactions.
10. It is the responsibility of the buyer or distributor of Renesas Electronics products, or any other party who distributes, disposes of, or otherwise sells or transfers the product to a third party, to notify such third party in advance of the contents and conditions set forth in this document.
11. This document shall not be reprinted, reproduced or duplicated in any form, in whole or in part, without prior written consent of Renesas Electronics.
12. Please contact a Renesas Electronics sales office if you have any questions regarding the information contained in this document or Renesas Electronics products.

(Note 1) "Renesas Electronics" as used in this document means Renesas Electronics Corporation and also includes its directly or indirectly controlled subsidiaries.

(Note 2) "Renesas Electronics product(s)" means any product developed or manufactured by or for Renesas Electronics.

(Rev.4.0-1 November 2017)



SALES OFFICES

Renesas Electronics Corporation

<http://www.renesas.com>

Refer to "<http://www.renesas.com/>" for the latest and detailed information.

Renesas Electronics America Inc.
1001 Murphy Ranch Road, Milpitas, CA 95035, U.S.A.
Tel: +1-408-432-8888, Fax: +1-408-434-5351

Renesas Electronics Canada Limited
9251 Yonge Street, Suite 8309 Richmond Hill, Ontario Canada L4C 9T3
Tel: +1-905-237-2004

Renesas Electronics Europe Limited
Dukes Meadow, Millboard Road, Bourne End, Buckinghamshire, SL8 5FH, U.K.
Tel: +44-1628-651-700, Fax: +44-1628-651-804

Renesas Electronics Europe GmbH
Arcadiastrasse 10, 40472 Düsseldorf, Germany
Tel: +49-211-6503-0, Fax: +49-211-6503-1327

Renesas Electronics (China) Co., Ltd.
Room 1709 Quantum Plaza, No.27 ZhiChunLu, Haidian District, Beijing, 100191 P. R. China
Tel: +86-10-8235-1155, Fax: +86-10-8235-7679

Renesas Electronics (Shanghai) Co., Ltd.
Unit 301, Tower A, Central Towers, 555 Langao Road, Putuo District, Shanghai, 200333 P. R. China
Tel: +86-21-2226-0888, Fax: +86-21-2226-0999

Renesas Electronics Hong Kong Limited
Unit 1601-1611, 16/F., Tower 2, Grand Century Place, 193 Prince Edward Road West, Mongkok, Kowloon, Hong Kong
Tel: +852-2226-6688, Fax: +852-2886-9022

Renesas Electronics Taiwan Co., Ltd.
13F, No. 363, Fu Shing North Road, Taipei 10543, Taiwan
Tel: +886-2-8175-9600, Fax: +886-2-8175-9670

Renesas Electronics Singapore Pte. Ltd.
80 Bendemeer Road, Unit #06-02 Hyflux Innovation Centre, Singapore 339949
Tel: +65-6213-0200, Fax: +65-6213-0300

Renesas Electronics Malaysia Sdn.Bhd.
Unit 1207, Block B, Menara Amcorp, Amcorp Trade Centre, No. 18, Jln Persiaran Barat, 46050 Petaling Jaya, Selangor Darul Ehsan, Malaysia
Tel: +60-3-7955-9390, Fax: +60-3-7955-9510

Renesas Electronics India Pvt. Ltd.
No.777C, 100 Feet Road, HAL 2nd Stage, Indiranagar, Bangalore 560 038, India
Tel: +91-80-67208700, Fax: +91-80-67208777

Renesas Electronics Korea Co., Ltd.
17F, KAMCO Yangjae Tower, 262, Gangnam-daero, Gangnam-gu, Seoul, 06265 Korea
Tel: +82-2-558-3737, Fax: +82-2-558-5338