

**This document outlines the target devices, simulation functions and cautions of RL78/G11 simulator.**

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## Chapter 1. Target Devices and Supported Simulation Functions

The following target devices are supported by the RL78/G11 simulator.

Device group	Device name
RL78/G11	R5F1051A, R5F1054A, R5F1056A, R5F1057A, R5F1058A,

The RL78/G11 simulator is capable of simulating the following items along with CPU instructions.

- Peripheral modules such as timers, the serial array unit, and the serial interface
- Virtual target board (simulation via the [I/O panel] window)
- MCU pin signal waveforms (simulation via the [Timing chart] window)
- Current drawn

## Chapter 2. Changes

This chapter describes changes from V2.00.00 to V2.00.01.

### 2.1 Improvement to difference of the standby function between the target device and simulator

The simulator had the difference from the target device in the following point to SNOOZE mode of the standby function. It has been improved to be the same operation as the target device.

#### [Target device]

In the case of CSI0 or UART0 data reception, an A/D conversion request by the timer trigger signal (the interrupt request signal (INTIT) or ELC event input), and DTC start source, the STOP mode is exited, the CSI0 or UART0 data is received without operating the CPU, A/D conversion is performed, and DTC starts.

#### [Simulator]

On RL78/G11 peripheral simulator, this function did not work.

## Chapter 3. Points for Caution

This section lists points for caution on using the RL78/G11 simulator. These points for caution are in the following two categories.

- Differences in behavior between the target device and the simulator due to simulator specifications
- Usage of simulation functions (e.g. operations in and configuration of the GUI windows)

### 3.1 Differences between target devices and simulator

#### 3.1.1 Unsupported peripheral functions

The simulator does not support the following peripheral functions of the target device (the following functions are not simulated).

- Simplified I<sup>2</sup>C of Serial Array Unit
- Regulator
- Power-on-reset circuit
- Voltage detector
- Flash self programming function

#### 3.1.2 Peripheral I/O redirection register (PIOR)

If using Peripheral I/O redirection register (PIOR), simulator's alternate pin functions are switched same as target device. Note that the PIOR register setting for serial interface pins should not be changed, because [Serial] window could not communicate with a serial interface, if the port related to the serial interface pins is switched.

In addition, in case of switching alternate pin function, be sure to select port name on the [Select Pin] dialog. Do not use alternate function pin name.

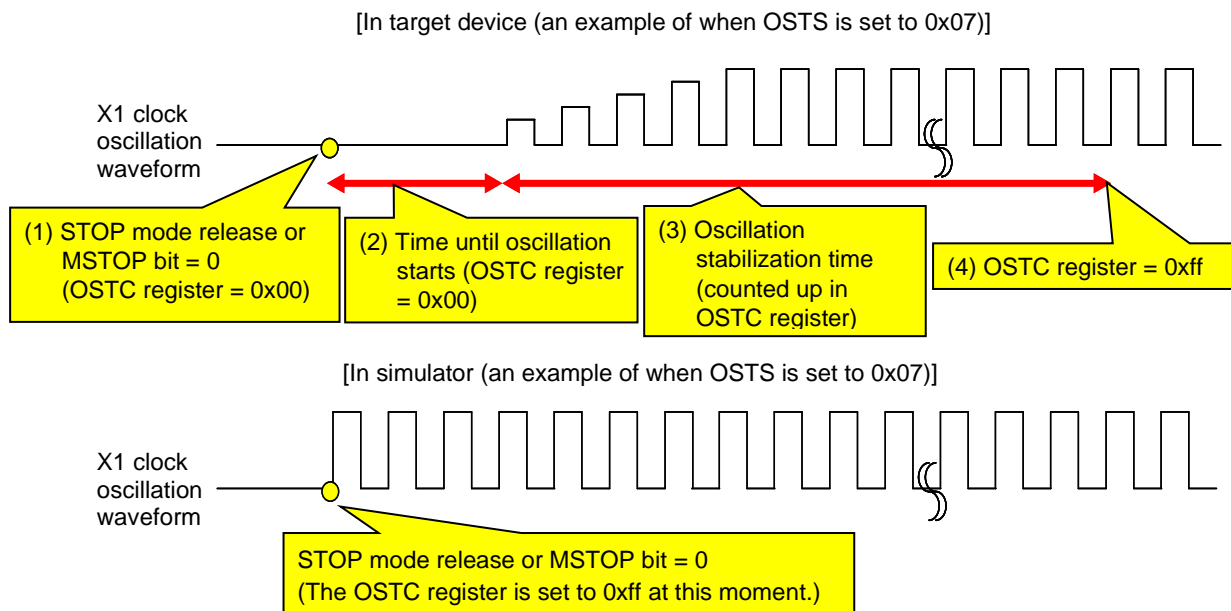
### 3.1.3 Oscillation stabilization time of Clock Generator

Since the simulator does not simulate the clock oscillator oscillation stabilization time, the value remains at 0 second. When the oscillation is started, the OSTC register is set to one of the following values without count up operations.

OSTS Setting Value	OSTC Value
0x0 : $2^8/f_x$	0x80
0x1 : $2^9/f_x$	0xc0
0x2 : $2^{10}/f_x$	0xe0
0x3 : $2^{11}/f_x$	0xf0
0x4 : $2^{13}/f_x$	0xf8
0x5 : $2^{15}/f_x$	0xfc
0x6 : $2^{17}/f_x$	0xfe
0x7 : $2^{18}/f_x$	0xff

The following figure illustrates this operation.

In the target device, the X1 clock oscillation starts after the states (1) to (4) have passed. In the simulator, states (1) through (4) are skipped and instantly the X1 clock oscillation starts.



Therefore, pay attention to the code that waits for oscillation stabilization.

There is no problem if a program is created with the condition that the execution exits the oscillation stabilization wait period when the OSTC register value becomes the maximum value, or when the OSTC register value exceeds the specified value, but if a program is created with the condition that the execution exits the oscillation stabilization wait period when the OSTC register value becomes a value other than the maximum value, the execution enters an infinite loop.

The following shows examples of code that causes/does not cause problems.

(This is an example of when OSTC is set to 0x07)

<u>Correct program example (1)</u>	<u>Correct program example (2)</u>	<u>Example of program that may cause problems</u>
while(OSTC != 0xff)	while(OSTC <= 0xf0)	while(OSTC != 0xf0)
{	{	{
NOP();/* wait */	NOP();/* wait */	NOP();/* wait */
}	}	}

### 3.1.4 SFR with clock generator

The following SFRs which belong to the clock generator are not simulated. Although read/write accesses for each register can be performed normally, the operation does not change even if its value is changed.

- Bit 0 (AMPH) of clock operation mode control register (CMC)
- High-speed internal oscillator trimming register (HIOTRM)

### 3.1.5 Operation clock of timer array unit

Do not specify an operation clock that is 233 Hz or lower. If the operation clock of the timer array unit is 233 Hz or lower, then the timer array unit will not work properly (it will behave as if operating via a clock that is faster than the one selected).

### 3.1.6 Noise filter / digital filter of timer

Although the target device's Timer array unit has a function to turn the noise filter / digital filter on and off in order to reduce noise from the timer input pin, the simulator does not simulate this function because there is no noise in the simulator's signal. (There is no difference in behavior whether filtering is on or off.)

### 3.1.7 Interval interrupt of watchdog timer

The following differences occur between the target device and simulator when using an interval interrupt of watchdog timer.

[Target device]

An interval interrupt is generated when  $75\% + 1/2f_{IL}$  of overflow time is reached.

[Simulator]

An interval interrupt is generated when 75% of overflow time is reached.

### 3.1.8 Operation clock of serial array unit

Do not specify an operation clock that is 233 Hz or lower. If the operation clock of the serial array unit is 233 Hz or lower, then the serial array unit will not operate correctly (it will behave as if operating via a clock that is faster than the one selected).

### 3.1.9 Noise filter of serial array unit

Although the target device's serial array unit has a function to turn the noise filter on and off in order to reduce noise on the input pin, the simulator does not simulate this function because there is no noise in the simulator's signal. (There is no difference in behavior whether filtering is on or off.)

### 3.1.10 SDRmn register of serial array unit

The following differences occur between the target device and simulator when the serial data register (SDRmn) is read during serial operation.

[Target device]

The value is 0.

[Simulator]

The value remains at the moment of serial operation started.

### 3.1.11 Serial interface IICA

IICA supports pin waveform generation and the communication with [Serial] window. The following functions are not supported.

- Digital filter
- Arbitration
- Detection of transmission errors
- Communication reservation

### 3.1.12 Reset

The behavior differs as follows if a reset is generated by the RESET pin.

[Target device]

MCU goes into reset status when the RESET pin goes to low level. Reset status is released when it goes to high level.

[Simulator]

MCU does not go into reset status when the RESET pin goes to low level. When it goes to high level, the simulator momentarily goes into reset status, and then the reset status is released immediately.

### 3.1.13 Reset control flag register (RESF)

The simulator only responds to WDTRF bit of Reset control flag register (RESF).

The simulator does not support TRAP bit and RPERF bit and IAWRF bit and LVIRF bit.

These bits are not changed from the initial value.

### 3.1.14 A/D converter

When VDD, AVREFP signal has no input, the default reference voltage of A/D converter is 5.0V.

For changing the reference voltage, input it to VDD, AVREFP signal by using signal data editor and so on.

The temperature sensor output voltage is always 1.05V.



### 3.1.15 Clock output/buzzer output controller

When selecting  $f_{MAIN}$  as an output clock, [Timing chart] window does not show the clock waveform of PCLBUZn signal.

When selecting  $f_{MAIN}/2$  or slower as an output clock, [Timing chart] window shows the clock waveform.

### 3.1.16 Execution of illegal instructions

If an illegal instruction (instruction code: 0xFF) is executed, the target device will be reset, but the simulator will go into an infinite loop (the illegal instruction will be executed repeatedly).

### 3.1.17 Response time of Data Transfer Controller (DTC)

The transfer speeds of the target device and simulator differ as follows when simulating the Data Transfer Controller.

[Target device]

- has response time from when DTC activation sources are detected until when data transfer starts
- has wait time when access is to Extended Special Function Register (2nd SFR)
- DTC puts the data transfer on hold when the CPU executes the DTC pending instruction
- the access to the data bus from the CPU is put on hold during DTC transfer

[Simulator]

- starts data transfer immediately after DTC activation sources are detected
- has no wait time even when access is to Extended Special Function Register (2nd SFR)
- DTC does not put the data transfer on hold even when the CPU executes the DTC pending instruction
- the access to the data bus from the CPU is not put on hold even during DTC transfer DTC

### 3.1.18 Repeat mode of Data Transfer Controller (DTC)

When selecting Repeat mode of Data Transfer Controller (DTC), if any of the following conditions are satisfied, DTC activation sources are ignored and the data is not transferred. Do not use this under the following conditions.

- Set 00H to DTC transfer count register j "DTCCTj". (Number of transfers: 256 times)
- Set 00H to DTC block size register j "DTBLSj". (Transfer block size: 256 bytes or 512 bytes)
- Set transfer data size as 16 bits by DTC control register j "DTCCRj", and set transfer block size bigger than 256 bytes by DTC block size register j "DTBLSj".

### 3.1.19 Event Link Controller(ELC)

If the event link destination function of Event Link Controller (ELC) is set to any of the following, the simulator starts the operation of the link destination peripheral function immediately after receiving the event (target device starts this operation after several cycles of the event reception).

[Target functions of Event link destination]

- Timer input channel 0 of Timer array unit 0
- Timer input channel 1 of Timer array unit 0

### 3.1.20 D/A converter

When VDD signal has no input, the default reference voltage of D/A converter is 5.0V.

For changing the reference voltage, input it to VDD signal by using signal data editor and so on.

### 3.1.21 Reference voltage of Comparator

When VDD signal has no input, the simulator generates the reference voltage assuming that 5V is input to VDD signal.

For changing the reference voltage, input it to VDD signal by using signal data editor and so on.

### 3.1.22 Response time of Comparator

Since the response time of comparator is not simulated, the value remains at 0 second.

The response time is not changed even if the speed setting is changed by Comparator output control register (COMPOCR).

### 3.1.23 Digital filter of Comparator

The Digital filter operation of Comparator is not supported.

### 3.1.24 Amplified voltage of the Programmable Gain Amplifiers (PGA)

The amplified voltage of the Programmable Gain Amplifiers (PGA) is dependent on the PGAGND pin and the VSS pin voltage in the hardware configuration of the target device, however, the simulator is dependent on the PGAI pin voltage only, and is not related to the PGAGND pin and the VSS pin.

## 3.2 Usage of simulation functions

### 3.2.1 Simulation of current drawn

The following notes apply to the function of measuring current.

- The current is calculated roughly as that drawn by the MCU alone based on the typical values (TYP.) for the actual devices. Note that the current values other than for the MCU are not included.
- The number of change points of measurable current is 200,000. The program stops when the number exceeds 200,000.

### 3.2.2 Simulation speed

The simulation speed of RL78/G11 simulator depends on the number of operating peripheral functions.

If many peripheral functions are operating, the simulation speed becomes from several to ten and several times slower than the actual device. <sup>Note</sup>

With the use of only a few, or even no peripheral functions, the simulation speed may become faster than the actual device.

Note: The measurement environment for simulation speed is as follows.

CPU: 3.20 GHz (Quad-Core); memory: 8 Gbytes; OS: Windows10 64-bit edition

### 3.2.3 Pin waveforms in the [Timing chart] window

The maximum length of a pin waveform is 4096 signal-level changing points. After reaching this maximum length, the data will be overwritten from the oldest value. If this length is not sufficient, use the following methods.

- Reduce the number of registered pins
- Stop the user program at the place where you want to confirm the waveform by using a breakpoint.

### 3.2.4 Controlling windows

The following keyboard operations are not available in the simulator windows ([Signal Data Editor], [I/O panel], and [Serial]) .

- Navigation via tab or arrow keys (←, ↑, →, ↓)
- Deletion via the Del or Backspace keys
- Cut & paste and other operations via the Ctrl + C, V, X, A, or Z keys.

Perform the above operations as follows.

- Navigation:           Navigate by using the mouse.
- Deletion:             Right-click and perform the action from the context menu.
- Cut & paste, etc.:    Right-click and perform the action from the context menu.

### 3.2.5 Closing the [Simulator GUI] window

The [Simulator GUI] window can only be closed by disconnecting from the debugging tool, or by closing CS+ in proper manner. The  button cannot be used.

Additionally, although it appears that the  button can be pressed if Aero is enabled in Windows, pressing this button will not close the [Simulator GUI] window.

### 3.2.6 Disconnecting the debug tool

CS+ may be closed if the debugging tool is disconnected while any of the following dialog boxes is open from the [Simulator GUI] window. Be sure that the following dialog boxes have been closed before disconnecting the simulator.

- |                |                               |
|----------------|-------------------------------|
| •Save As       | •Message (e.g. Error)         |
| •Open          | •Parts Button Properties      |
| •New           | •Analog Button Properties     |
| •Color         | •Parts Key Properties         |
| •Font          | •Parts Level Gauge Properties |
| •Customize     | •Parts Led Properties         |
| •Loop          | •Parts Segment LED Properties |
| •Select Pin    | •Parts Matrix Led Properties  |
| •Search Data   | •Parts Buzzer Properties      |
| •Format (UART) | •Pull up / Pull down          |
| •Format (CSI)  | •Entry Bitmap                 |
| •Format (IIC)  | •Object Properties            |

### 3.2.7 Cautions for setting the Host Machine's language and region

If a Japanese OS is installed on your Host Machine, then if the language or region is set to other than Japanese/Japan, the menus and dialog-box names of the [Simulator GUI] window will be shown in English. Similarly, if a non-Japanese OS is installed on your Host Machine, then if the language or region is set to Japanese/Japan, the menus and dialog-box names of the [Simulator GUI] window will be shown in Japanese.

### 3.2.8 [Serial] window

When using [Serial] window as the data receiver for IICA, only ACK can be generated after receiving the data. NACK cannot be generated.

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## Corporate Headquarters

TOYOSU FORESIA, 3-2-24 Toyosu,  
Koto-ku, Tokyo 135-0061, Japan  
[www.renesas.com](http://www.renesas.com)

## Contact information

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