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Renesas Electronics Corporation

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M16C/Tiny Series

Operation of Serial I/O (Reception in Clock-Synchronous Serial I/O Mode)

1. Abstract

In receiving data in clock-synchronous serial I/O mode, choose functions from those listed in Table 1. Operations of the checked items are described below.

Table 1. Chosed Functions

Item	Set-up		Item	Set-up	
Transfer clock source		Internal clock (f1/f2/f8/f32)	Continuous receive mode	Yes	Disabled
	Yes	External clock (CLKi pin)			Enabled
RTS function	Yes	RTS function enabled	Output transfer clock to multiple pins (Note 1)	Yes	Not selected
		RTS function disabled			Selected
CLK polarity	Yes	Input reception data at the rising edge of the transfer clock	Data logic select (Note 2)	Yes	No reverse
		Input reception data at the falling edge of the transfer clock	TxD, RxD I/O polarity reverse function (Note 2)		Reverse
Transfer format	Yes	LSB first	UART1 pin remapping function (Note 3)	Yes	UART1 pins assigned to P67 to P64
		MSB first			UART1 pins assigned to P73 to P70

Note 1: This can be selected only when UART1 is used in combination with the internal clock. When this function is selected, UART1 $\overline{\text{CTS}}/\overline{\text{RTS}}$ function can not be utilized. Set the UART1 $\overline{\text{CTS}}/\overline{\text{RTS}}$ disable bit to "1".

Note 2: UART2 only

Note 3: It is possible to select it only with M16C/26A, M16C/28, and M16C/29.

2. Introduction

The explanation of this issue is applied to the following condition:

Applicable MCU: M16C/26, M16C/26A, M16C/28, M16C/29 Group

This program can also be used when operating other microcomputers within the M16C family, provided they have the same SFR (Special Function Registers) as the M16C/26, M16C/26A, M16C/28, M16C/29 microcomputers. However, some functions may have been modified.

Refer to the User's Manual for details. Use functions covered in this Application Note only after careful evaluation.

3. Operation of Serial I/O

- (1) Writing dummy data to the UARTi transmit buffer register, setting the receive enable bit to “1”, and the transmit enable bit to “1”, makes the data receivable status ready. At this time, the output from the $\overline{\text{RTSi}}$ pin goes to “L” level, which informs the transmission side that the data receivable status is ready (output the transfer clock from the IC on the transmission side after checking that the $\overline{\text{RTS}}$ output has gone to “L” level).
- (2) In synchronization with the first falling edge of the transfer clock, the $\overline{\text{RTSi}}$ output goes to “H”, and in synchronization with the first rising edge of the transfer clock, the input signal to the RxDi pin is stored in the highest bit of the UARTi receive register. Then, data is taken in by shifting right the content of the UARTi reception data in synchronization with the rising edges of the transfer clock.
- (3) When 1-byte data lines up in the UARTi receive register, the content of the UARTi receive register is transmitted to the UARTi receive buffer register. The transfer clock stops at “H” level. At this time, the receive complete flag and the UARTi receive interrupt request bit goes to “1”.
- (4) The receive complete flag goes to “0” when the lower-order byte of the UARTi buffer register is read. At this time, The $\overline{\text{RTSi}}$ output goes to “L”.

Figure 1 shows the operation timing.

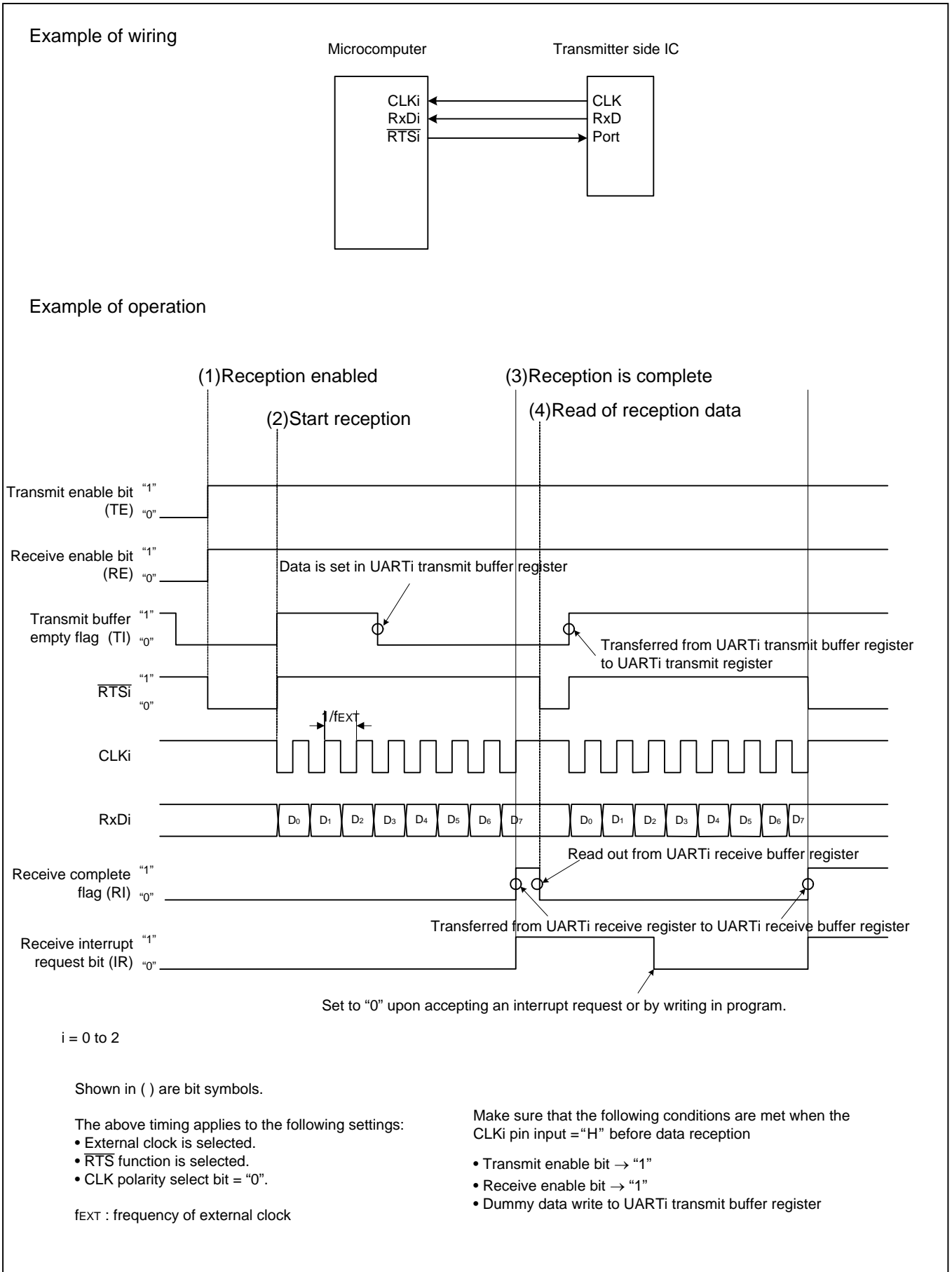


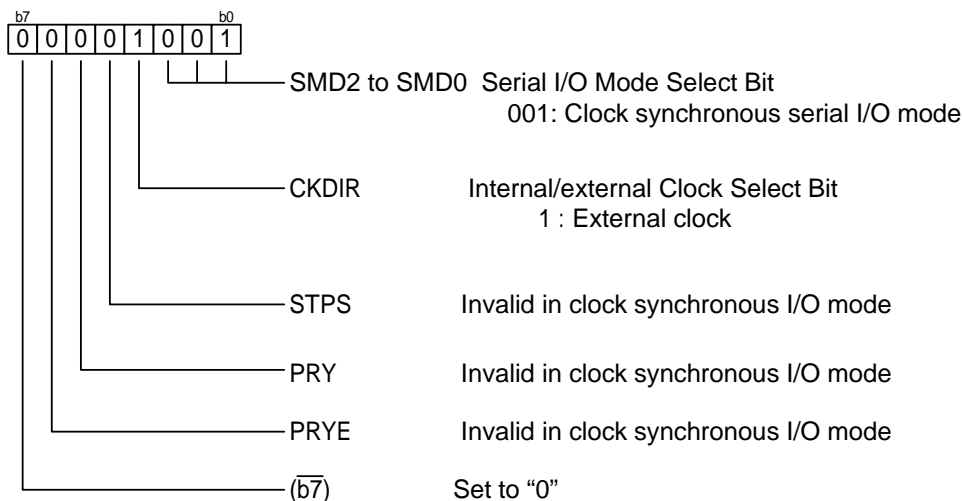
Figure 1. Operation Timing of Reception in Clock-Synchronous Serial I/O Mode

3.1 Register Setting

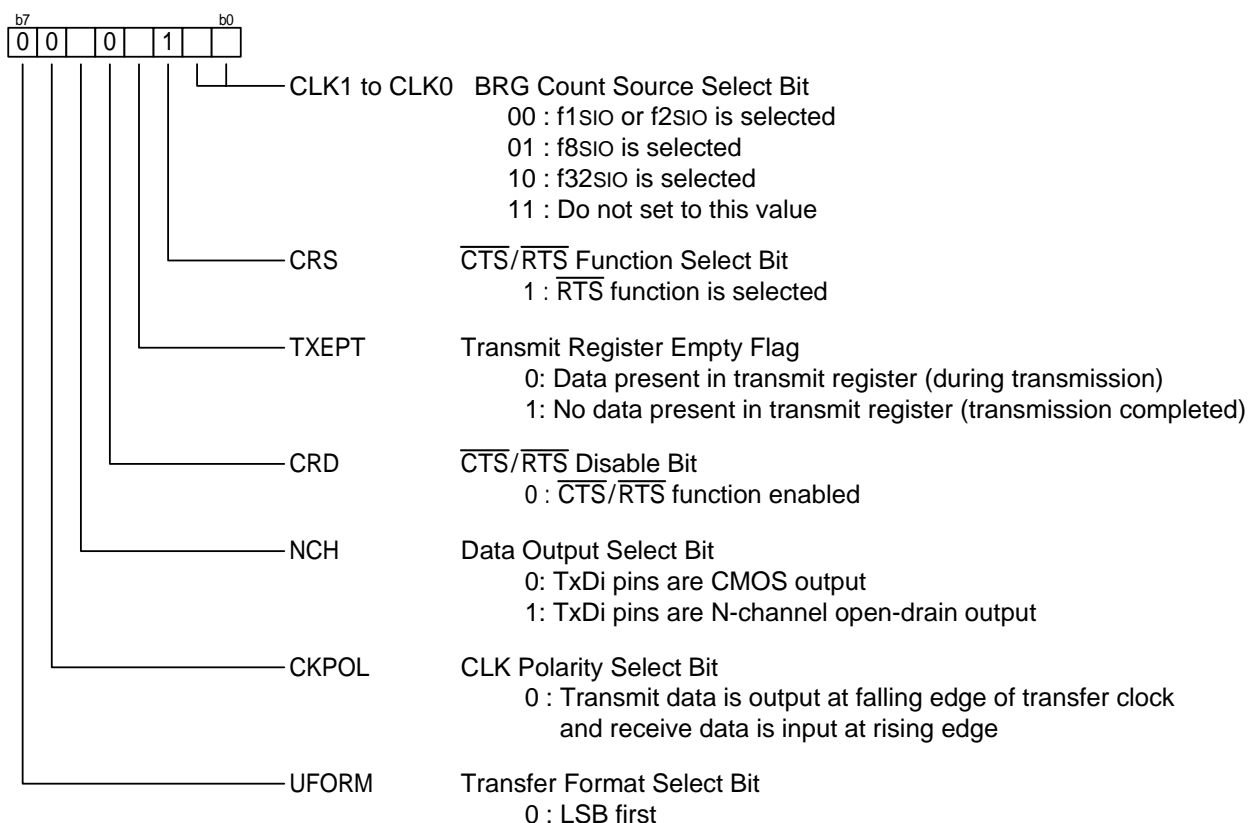
To enable the operation defined in “Section 3. Operation of timer A”, the following register settings must be taken place step by step. For detail configuration of each register, please refer to M16C/26 Group hardware manual, M16C/26A Group hardware manual, M16C/28 Group hardware manual, M16C/29 Group hardware manual.

3.1.1 UART0, 1

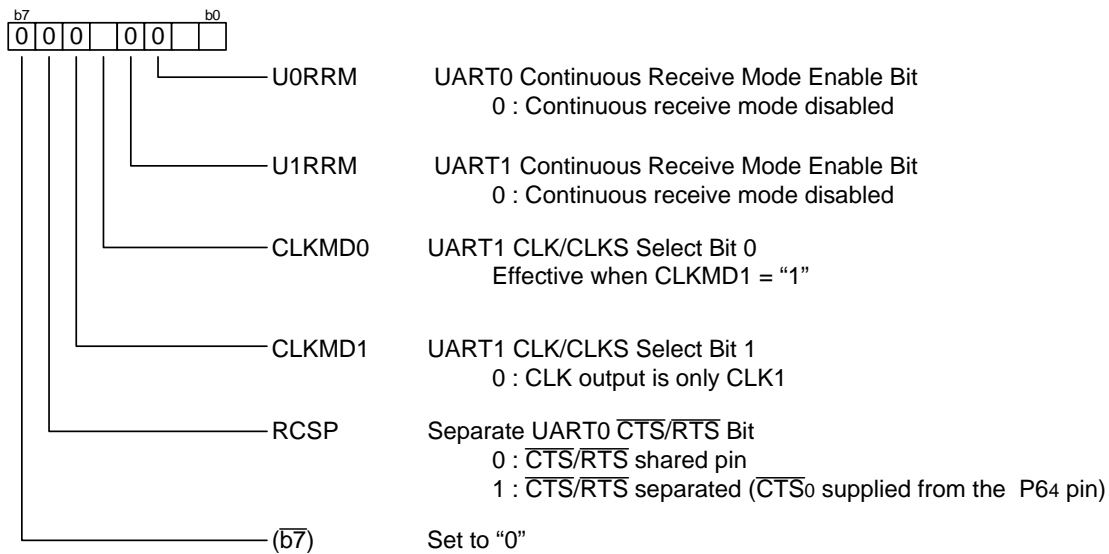
(1) Setting UARTi transmit/receive mode register (i=0, 1)



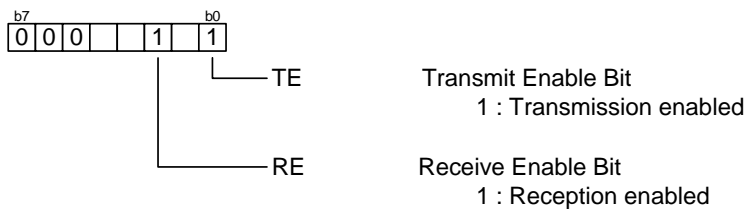
(2) Setting UARTi transmit/receive control register 0 (i=0,1)



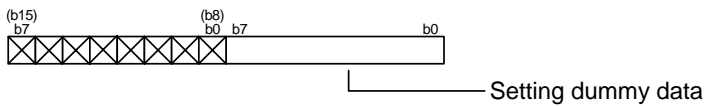
(3) Setting UART transmit/receive control register 2



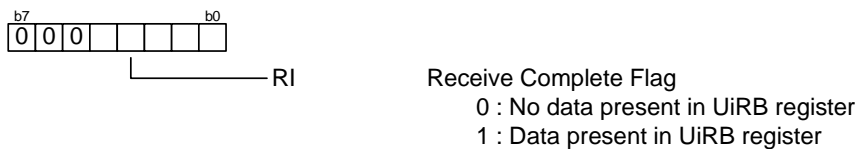
(4) Reception enabled (UARTi transmit/receive control register 1) (i=0,1)



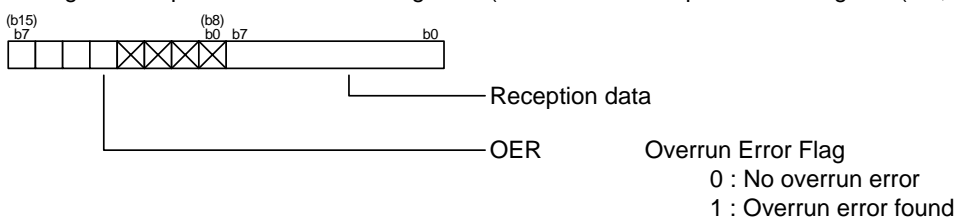
(5) Writing dummy data (UARTi transmit buffer register (i=0,1))



(6) Checking the status of UARTi receive buffer register (i=0,1)

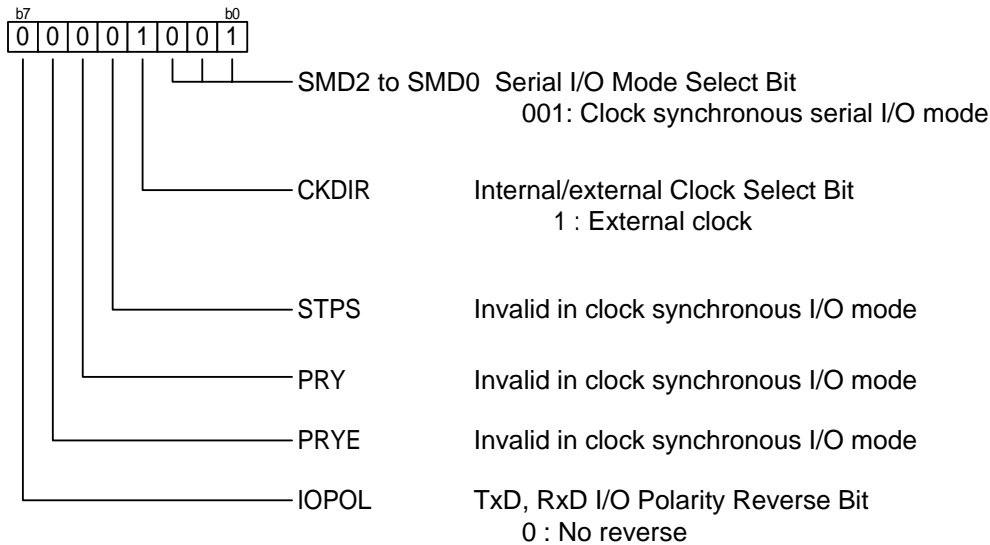


(7) Reading out reception data and checking error (Read UARTi reception buffer register (i=0,1))

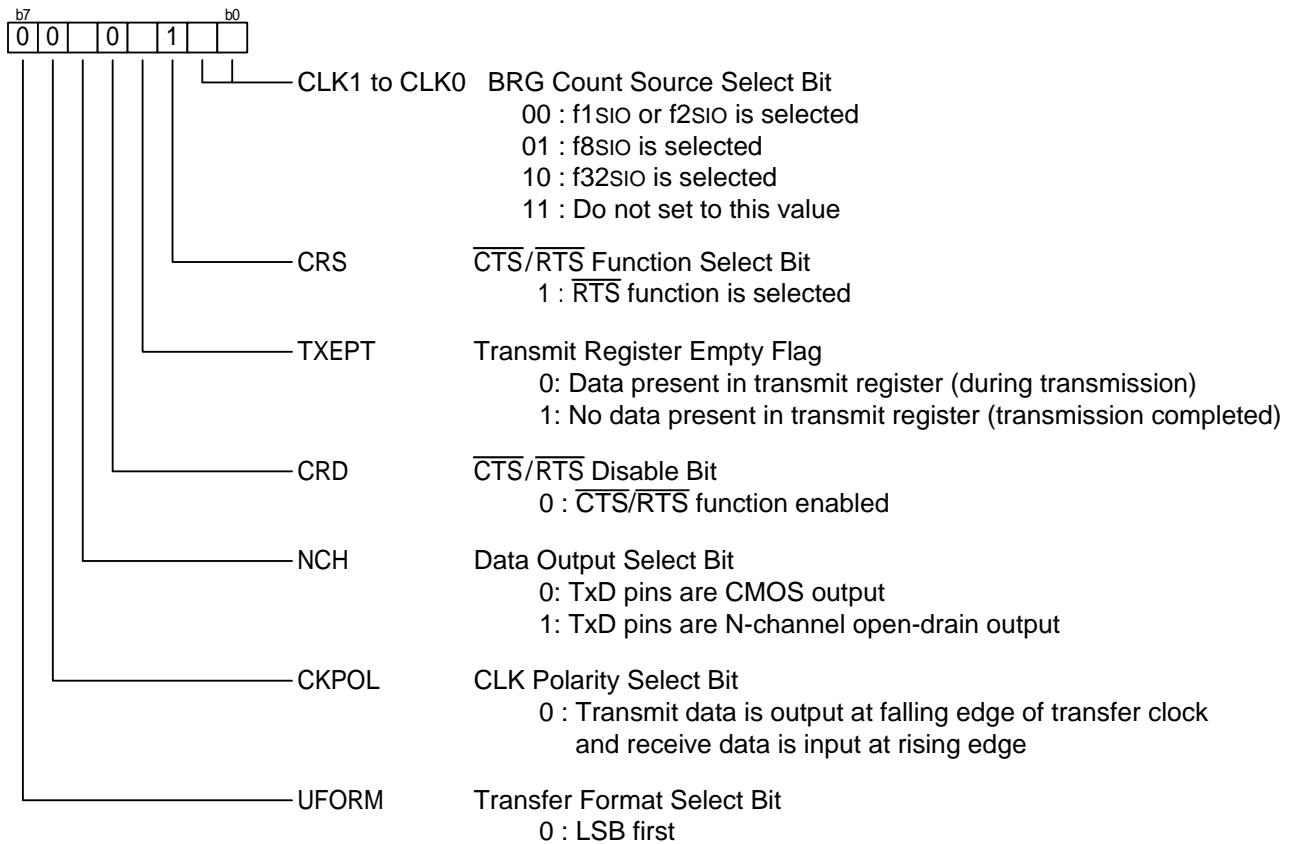


3.1.2 UART2

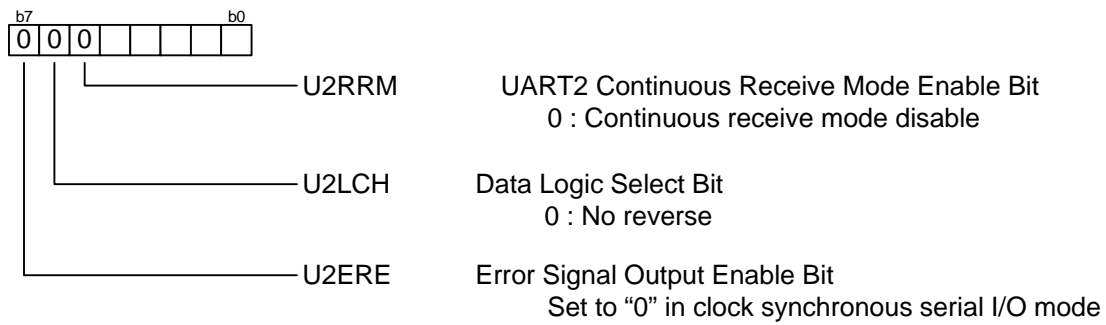
(1) Setting UART2 transmit/receive mode register



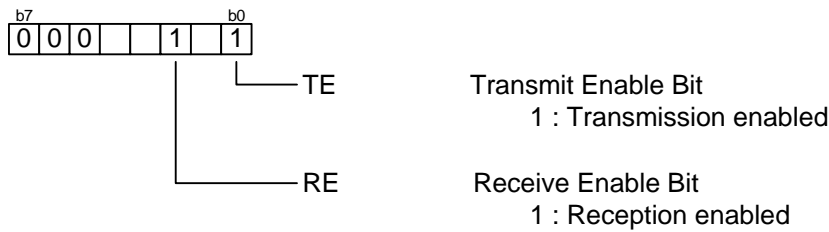
(2) Setting UART2 transmit/receive control register 0



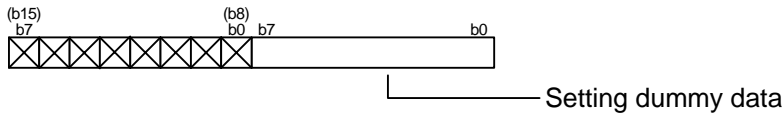
(3) Setting UART2 transmit/receive control register 1



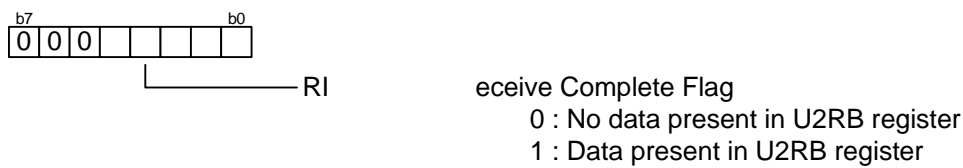
(4) Reception enabled (UART2 transmit/receive control register 1)



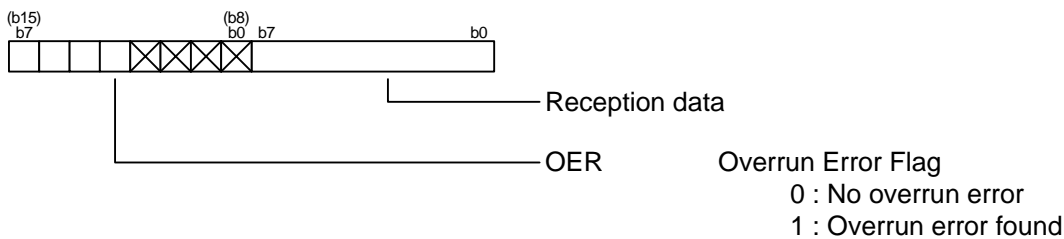
(5) Writing dummy data (UART2 transmit buffer register)



(6) Checking the status of UART2 receive buffer register



(7) Reading out reception data and checking error (Read UART2 reception buffer register)



4. Sample Program

4.1 UART0

```

/*****
 *
 *   FILE NAME :
 *   CPU       : M16C/Tiny series
 *   Function  : Operation of UART0
 *               (Clock synchronous serial I/O receive)
 *   Version   : 1.00
 *
 *   Copyright (C)2004, Renesas Technology Corp.
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 *
 *****/
/*****
 *   include file
 *****/
#include "sfr28.h"

/*****
 *   Function Definition
 *****/

/*****
 *   main
 *****/
    unsigned short  receive_data;

void main(void) {

    unsigned short  dummy_data = 0;

    u0mr = 0x09; /* UART0 transmit/receive mode register setting
                  Clock synchronous serial I/O mode
                  External clock select
                  */

    u0c0 = 0x04; /* UART0 transmit/receive control register 0 setting
                  ~RTS function select
                  ~CTS/~RTS function enabled
                  TxD0 pin is CMOS output
                  Transmission data is output at falling edge of transfer
                  clock and reception data is input at rising edge
                  LSB first
                  */

    ucon = 0x00; /* UART transmit/receive control register 2 setting
                  UART0 transmit interrupt cause is selected to "Transmit buffer empty(TI=1)"
                  ~CTS/~RTS shared pin
                  */

    u0c1 = 0x05; /* UART transmit/receive control register 1 setting
                  Transmit enabled
                  Receive enabled
                  */

    while (1) {

        while (!p6_1) { /* Wait until CLK0 "H" */
        }

        u0tb = dummy_data; /* Writing dummy data */

        while (!ri_u0c1) { /* Check & wait the status of UART0 receive complete flag */
        }

        receive_data = u0rb; /* Receive data read */

    }
}

```

4.1.1 UART2

```

/*****
*
*   FILE NAME :
*   CPU       : M16C/Tiny series
*   Function  : Operation of UART2
*               (Clock synchronous serial I/O receive)
*   Version   : 1.00
*
*   Copyright (C)2004, Renesas Technology Corp.
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*
*****/
/*****
*   include file
*****/
#include "sfr28.h"

/*****
*   Function Definition
*****/

/*****
*   main
*****/
    unsigned short  receive_data;

void main(void) {

    unsigned short  dummy_data = 0;

    u2mr = 0x09; /* UART2 transmint/receive mode register setting
                  Clock synchronous serial I/O mode
                  External clokc select
                  */

    u2c0 = 0x04; /* UART2 transmint/receive control register 0 setting
                  ~RTS function select
                  ~CTS/~RTS function enabled
                  TxD0 pin is CMOS output
                  Transmission data is output at falling edge of transfer
                  clock and reception data is input at rising edge
                  LSB first
                  */

    u2c1 = 0x05; /* UART2 transmint/receive control register 1 setting
                  Transmit enabled
                  Receive enabled
                  */

    while (1) {

        while (!p7_2) { /* Wait until CLK2 "H" */
        }

        u2tb = dummy_data; /* Writing dummy data */

        while (!ri_u2c1) { /* Check & wait the status of UART2 receive complete flag */
        }

        receive_data = u2rb; /* Receive data read */

    }
}

```

5. Reference

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Hardware Manual

M16C/26, M16C/26A, M16C/28, M16C/29 Group Hardware Manual

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REVISION HISTORY

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