

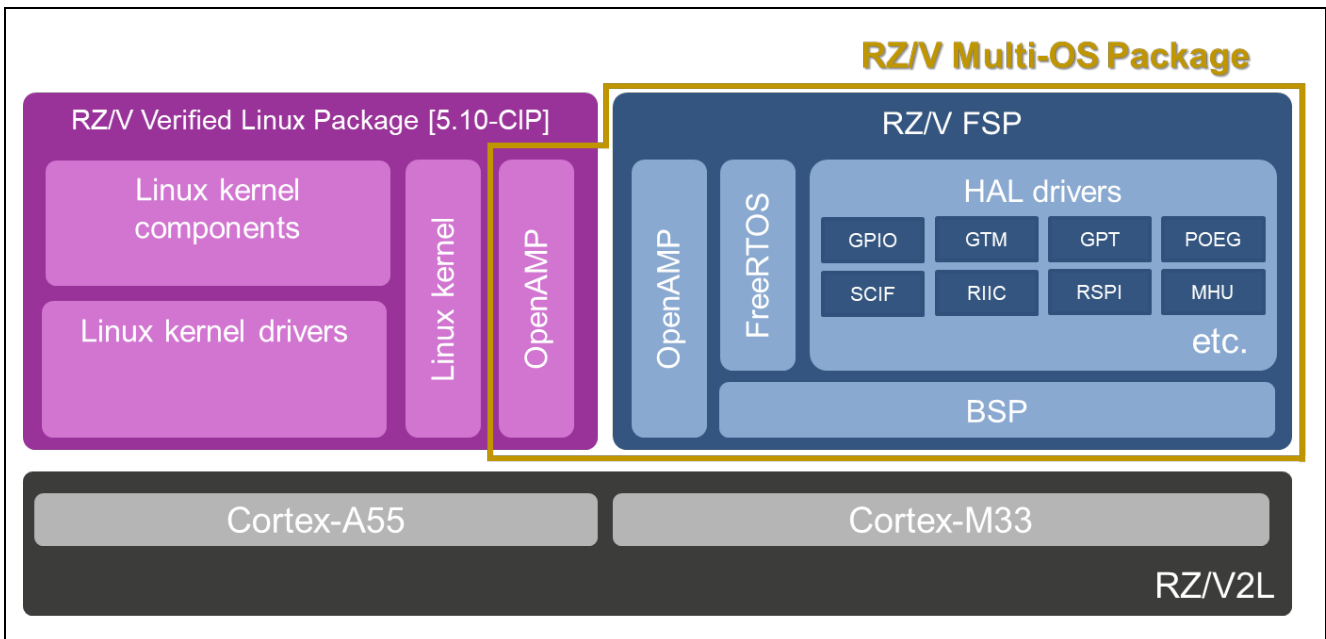
# RZ/V2L

## Release Note for RZ/V Multi-OS Package V1.12

### Introduction

This software package provides user with easy way to establish multi-OS (i.e., CIP Linux running on Cortex®-A55 and FreeRTOS running on Cortex-M33) environment and sample program showing how to implement Inter-Processor Communication between those CPU cores.

This package consists of RZ/V Flexible Software Package (hereinafter referred to as RZ/V FSP) and Inter-Processor Communication Feature Package for RZ/V Verified Linux Package (hereinafter referred to as RZ/V VLP).



Here are brief descriptions of each component of RZ/V Multi-OS Package:

- **RZ/V FSP**  
The software package consisting of production ready peripheral drivers, FreeRTOS and portable middleware stacks and the best in-case HAL drivers with low memory footprint.
- **OpenAMP**  
The framework including the software components needed for Asymmetric Multiprocessing (AMP) systems such as Inter-Processor Communication.

### Target Device

RZ/V2L

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## 1. Specifications

Table 1-1 lists the on-chip peripheral modules to be used in this application.

**Table 1-1. Peripheral module to be used**

Peripheral module	Usage
Message Handling Unit (MHU)	Configures Inter-Processor Interrupt.
Serial Communications Interface with FIFO (SCIFA)	Performs standard serial communications sending and receiving console messages.
Interrupt controller (INTC)	Configures interrupt settings; the processor will receive interrupts during buffered serial communications, and in the MHU module when Inter-Processor Interrupt is fired.
General Purpose Input Output (GPIO)	Configures I/O lines used by serial communications.
General Timer (GTM)	Configures the tick for FreeRTOS.

### 1.1 RZ/V2L reference boards setup

Please refer to SMARC EVK of RZ/V2L Linux Start-up Guide.

## 2. Verified Operation Conditions

**Table 2-1. Verified Operating Conditions**

Item	Contents
Microprocessor used	RZ/V2L
Integrated Development Environment	e <sup>2</sup> studio 2024-01
C compiler	GNU Arm Embedded 9.2.1 2019q4 Compiler Options (except directory path): <ul style="list-style-type: none"> <li>• Release               <ul style="list-style-type: none"> <li>-D_RENESAS_RZV_ -mthumb</li> <li>-mcpu=cortex-m33+nodsp+nofp</li> <li>-fdiagnostics-parseable-fixits -O2</li> <li>-fmessage-length=0 -fsigned-char</li> <li>-ffunction-sections -fdata-sections</li> <li>-Wunused -Wuninitialized -Wall</li> <li>-Wextra -Wmissing-declarations -Wconversion</li> <li>-Wpointer-arith -Wshadow -Wlogical-op</li> <li>-Waggregate-return -Wfloat-equal</li> <li>-Wnull-dereference -g -std=c99 -mcmse</li> </ul> </li> <li>• Hardware Debug               <ul style="list-style-type: none"> <li>-D_RENESAS_RZV_ -mthumb</li> <li>-mcpu=cortex-m33+nodsp+nofp</li> <li>-fdiagnostics-parseable-fixits -Og</li> <li>-fmessage-length=0 -fsigned-char</li> <li>-ffunction-sections -fdata-sections</li> <li>-Wunused -Wuninitialized -Wall -Wextra</li> <li>-Wmissing-declarations -Wconversion</li> <li>-Wpointer-arith -Wshadow -Wlogical-op</li> <li>-Waggregate-return -Wfloat-equal</li> <li>-Wnull-dereference -g -std=c99 -mcmse</li> </ul> </li> </ul>

### 3. Sample Program Setup

#### 3.1 RZ/V2L Flexible Software Package Setup

Please refer to [RZ/V2L Getting Started with Flexible Software Package](#).

#### 3.2 OpenAMP related stuff Integration to RZ/V2L Group Board Support Package

This section describes how to integrate OpenAMP related stuff to RZ/V Verified Linux Package [5.10-CIP] (hereinafter referred to as VLP). For details, please refer to SMARC EVK of RZ/V2L Linux Start-up Guide (r01us0617ej0101-rz-v(Linux Start-up Guide RZV2L.pdf) included in VLP.

1. Install the package needed for building BSP.

```
$ sudo apt-get update
$ sudo apt-get install gawk wget git-core diffstat unzip texinfo \
gcc-multilib build-essential chrpath socat cpio python3 python3-pip \
python3-pexpect xz-utils debiutils iputils-ping python3-git \
python3-jinja2 libegl1-mesa libsdl1.2-dev pylint3 xterm p7zip-full \
libyaml-dev libssl-dev bmap-tools
```

2. Configure your Git.

```
$ git config --global user.email "you@example.com"
$ git config --global user.name "Your Name"
```

3. Create a working directory (e.g., rzv\_vlp\_v3.0.5) at your home directory, and extract BSP there.

```
$ mkdir ~/rzv_vlp_<package version>
$ cd ~/rzv_vlp_<package version>
$ cp ../<package download directory>/*.zip .
$ unzip RTK0EF0045Z0024AZJ-<package version>.zip
$ tar zxvf ./RTK0EF0045Z0024AZJ-<package version>/rzv_vlp_<package version>.tar.gz
```

4. Download Multi-OS Package (r01an6238ej0112-rzv2l-cm33-multi-os-pkg.zip) to working directory and run the commands stated below:

```
$ unzip r01an6238ej0112-rzv2l-cm33-multi-os-pkg.zip
$ tar zxvf r01an6238ej0112-rzv2l-cm33-multi-os-pkg/meta-rz-features_multi-
os_v1.1.2.tar.gz
```

5. Initialize Build Environment

```
$ TEMPLATECONF=$PWD/meta-renesas/meta-rzv2l/docs/template/conf/ \
source poky/oe-init-build-env build
```

6. Add the layers. The steps add the settings to bblayers.conf.

```
$ bitbake-layers add-layer ../meta-rz-features/meta-rz-multi-os/meta-rzv2l
```

7. Start a build by invoking the commands for building VLP. Building an image might take up to a few hours depending on the user's host system performance.

```
$ MACHINE=smarc-rzv2l bitbake core-image-<target>
```

Here, the allowable values for “target” in the command are as follows:

- minimal
- bsp
- Weston
- qt

### 3.3 Note for integration to VLP

On VLP, the peripherals which is NOT used enters Module Standby Mode. That means the peripherals used on CM33 side might NOT become work implicitly. To avoid this situation, we prepare for the patch shown below:

- 0003-clk-renesas-rzv2l-Set-SCIF2-OSTM2.patch

This patch prevents SCIF and GTM(OSTM) used in the rpmsg sample program from entering Module Standby Mode. If you have any other peripherals which should NOT enter Module Standby Mode, please apply the following modification in red to the patch.

```
drivers/clk/renesas/r9a07g044-cpg.c | 2 ++
1 file changed, 2 insertions(+)

diff --git a/drivers/clk/renesas/r9a07g044-cpg.c
b/drivers/clk/renesas/r9a07g044-cpg.c
index e27caa075af7..9e904d2e8180 100644
--- a/drivers/clk/renesas/r9a07g044-cpg.c
+++ b/drivers/clk/renesas/r9a07g044-cpg.c
@@ -449,6 +449,9 @@ static const unsigned int r9a07g044_crit_mod_clks[]
__initconst = {
    MOD_CLK_BASE + R9A07G044_IA55_PCLK,
    MOD_CLK_BASE + R9A07G044_IA55_CLK,
    MOD_CLK_BASE + R9A07G044_DMAC_ACLK,
+   MOD_CLK_BASE + R9A07G044_SCIF2_CLK_PCK,
+   MOD_CLK_BASE + R9A07G044_OSTM2_PCLK,
+   MOD_CLK_BASE + R9A07G044_XXXX,
};
```

The line number should be revised in accordance with the number of lines you added.

With respect to the allowable value for xxxx above, please refer to the source code below:

- [https://github.com/renesas-rz/rz\\_linux-cip/blob/eb22cb243441a34ee89cfd2f002b43bd5d0a84c1/drivers/clk/renesas/r9a07g044-cpg.c#L204-L384](https://github.com/renesas-rz/rz_linux-cip/blob/eb22cb243441a34ee89cfd2f002b43bd5d0a84c1/drivers/clk/renesas/r9a07g044-cpg.c#L204-L384)

### 3.4 Deployment of RZ/V2L BSP

First, you need to deploy Linux kernel, device tree and root filesystem referring to SMARC EVK of RZ/V2L Linux Start-up Guide.

## 4. Sample Program Invocation

### 4.1 Hardware setup

1. Connect J-Link to RZ/V2L SMARC EVK. For details, please refer to [RZ/V2L Getting Started with Flexible Software Package](#).
2. Connect [Pmod USBUART](#) to the Pmod 1 of SMARC Carrier Board as shown below for securing the console for the program running on CM33.

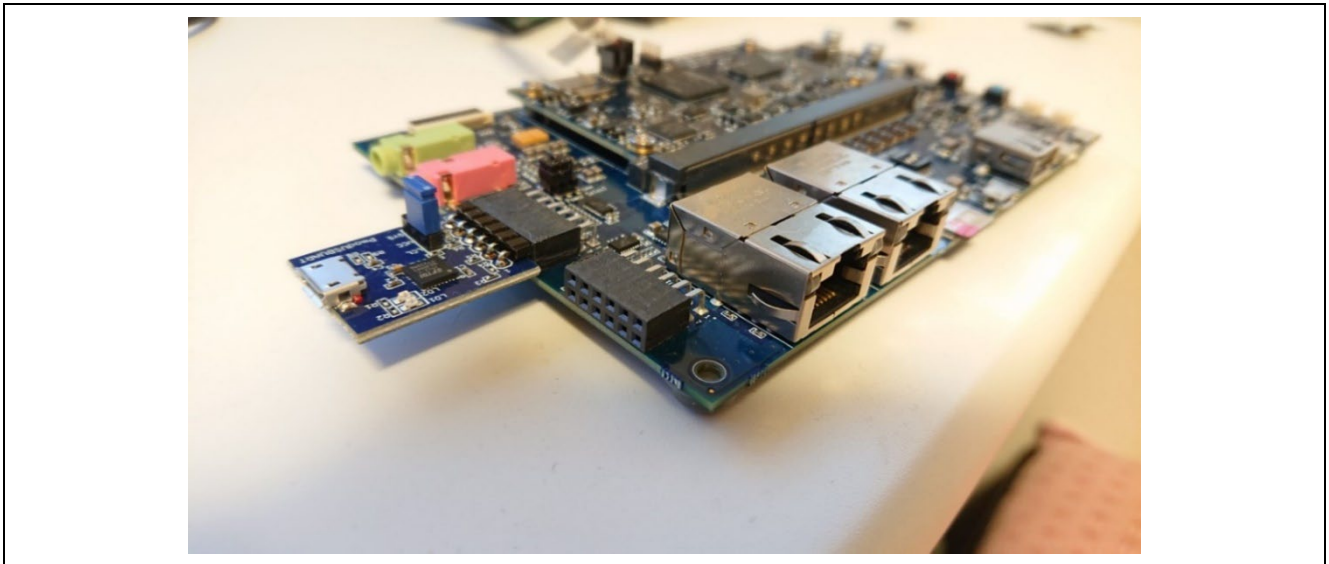


Figure 4-1. Connection between RZ/V2L SMARC EVK and Pmod USBUART

## 4.2 CM33 Sample Program Setup

Please carry out the following procedures for setting up demo program running on CM33.

1. Extract 01an6238ej0112-rzv2l-cm33-multi-os-pkg.zip on your development PC.
2. Extract rzv2l\_cm33\_rpmsg\_demo.zip there.
3. Open e<sup>2</sup> studio 2024-01 and click File > Import.
4. Double-click General and select Existing Projects into Workspace as shown in Figure 4-2:

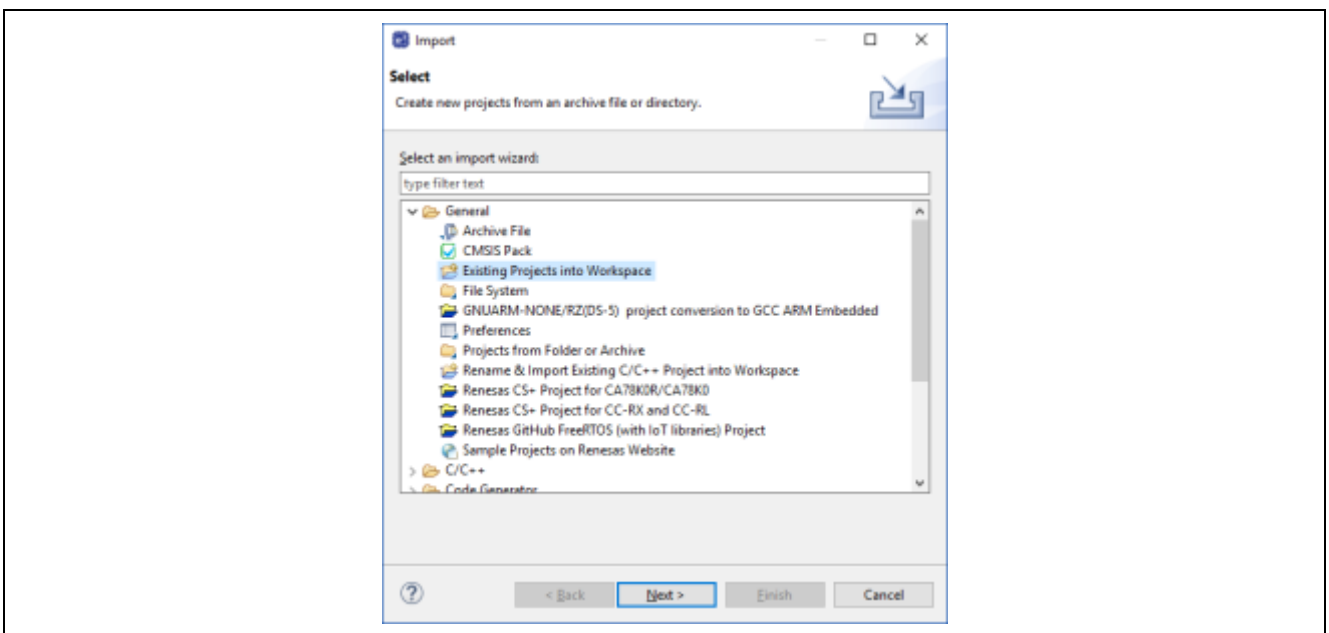


Figure 4-2. Import sample project (1)

5. Input the path to the folder rzv2l\_cm33\_rpmcg\_demo, press Enter key and click Finish button.

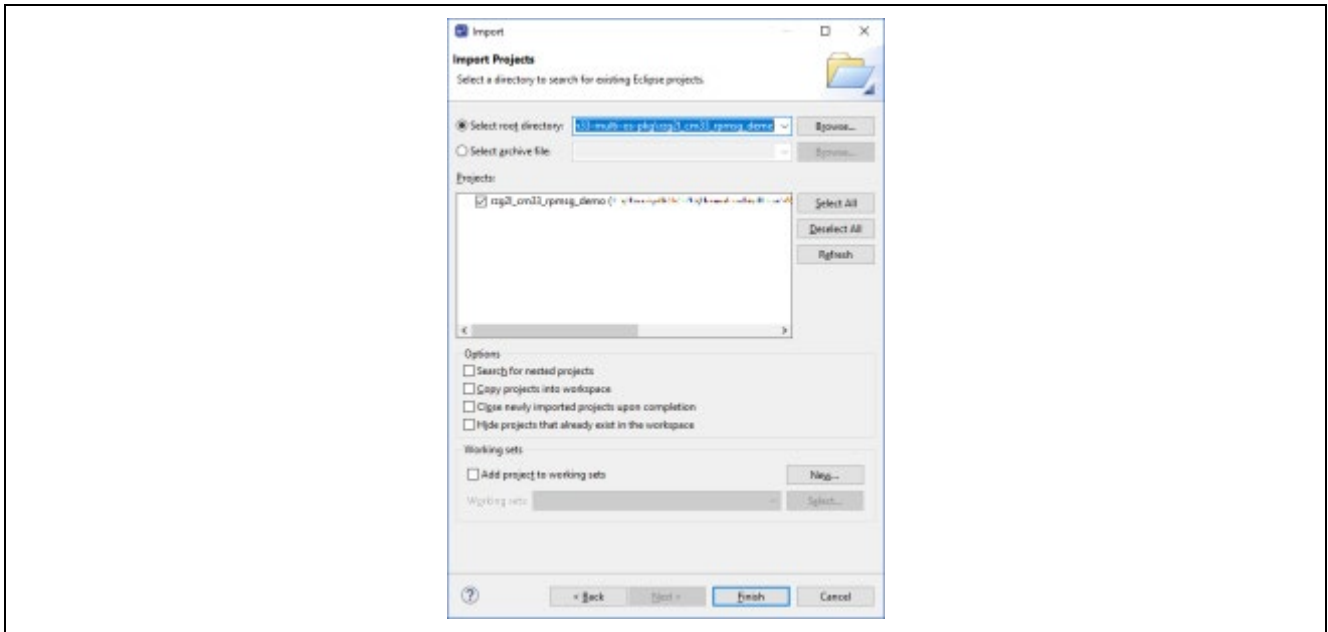
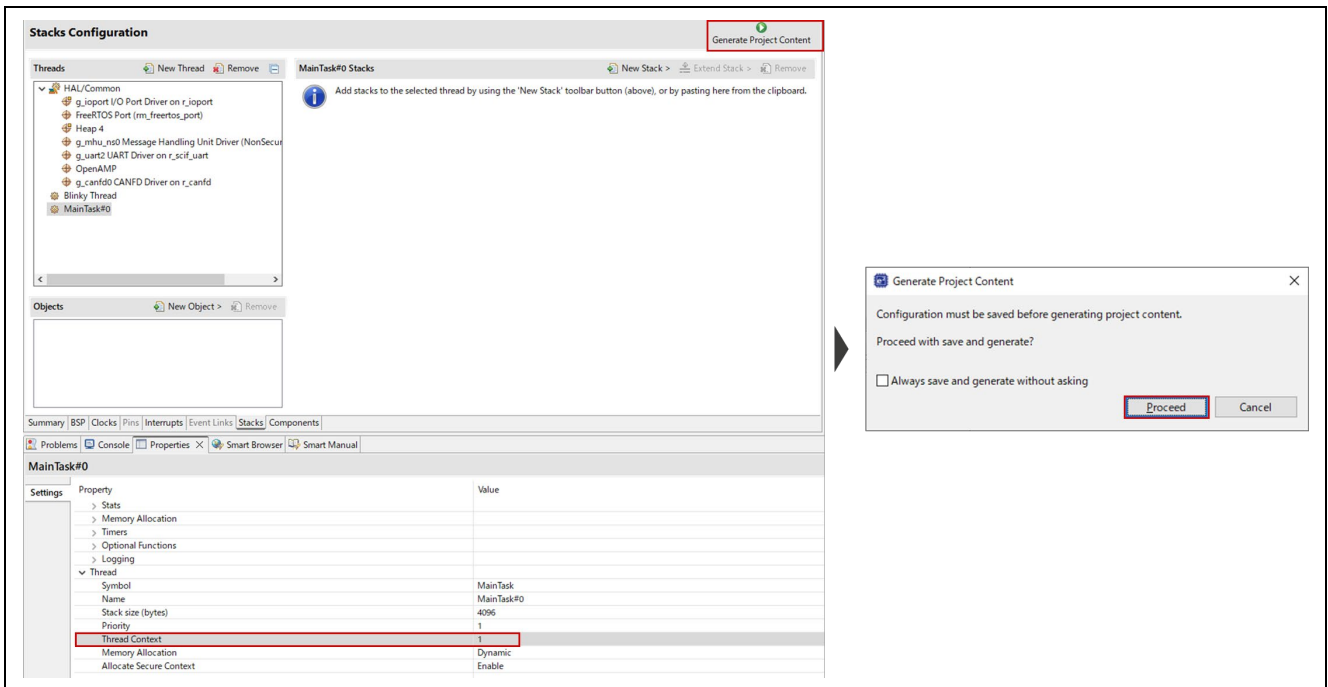


Figure 4-3. Import sample project (2)

6. (Optional) By default RPMcg channel 0 is configured to be used on CM33. If you would like to use channel 1, open the property of MainTask#0 on FSP Smart Configurator, specify 1 for Thread Context, and push **Generate Project Content** button. If **Generate Project Content** pop-up is shown, click **Proceed** to reflect the change to the source code.



7. Build the project from Choose Project > Build Project.
8. If the build is successfully completed, the following files should be generated in Debug and/or Release folder in accordance with the active Build Configuration.
  - rzv2l\_cm33\_rpmsg\_demo.elf
  - rzv2l\_cm33\_rpmsg\_demo\_non\_secure\_code.bin
  - rzv2l\_cm33\_rpmsg\_demo\_non\_secure\_vector.bin
  - rzv2l\_cm33\_rpmsg\_demo\_secure\_code.bin
  - rzv2l\_cm33\_rpmsg\_demo\_secure\_vector.bin

### 4.3 CM33 Sample Program Invocation

#### 4.3.1 CM33 Sample Program Invocation with Segger J-Link

You need to follow the following steps to invoke CM33 sample program with Segger J-Link.

1. Choose rzv2l\_cm33\_rpmsg\_demo Debug\_Flat or rzv2l\_cm33\_rpmsg\_demo Release\_Flat from the drop-down list indicated by a red arrow in Figure 4-4.

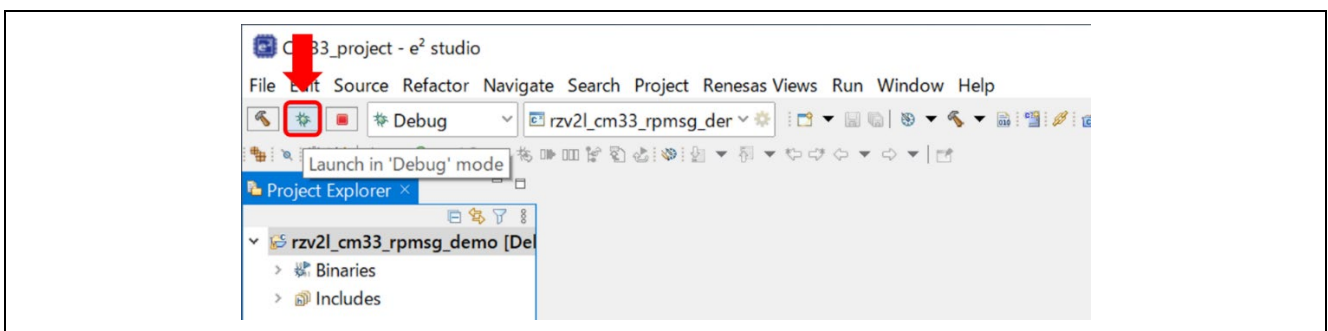


Figure 4-4. Select of Debug Configuration

2. Click the debug button indicated by a red arrow in Figure 4-5.

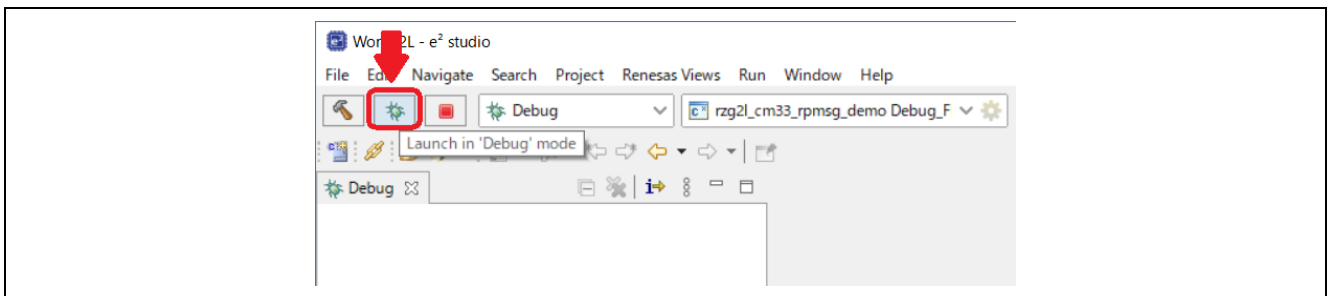


Figure 4-5. Debug Function Launch

If “Confirmation Perspective Switch” window below appears, please press “Switch” to go ahead.

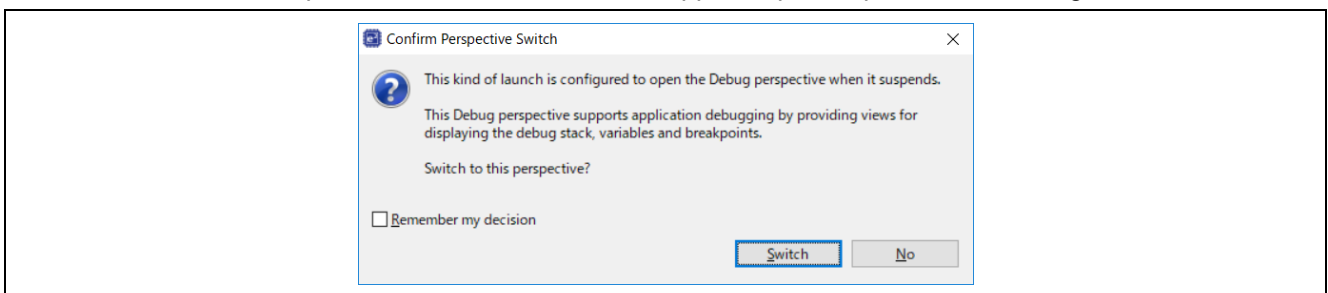


Figure 4-6. Confirmation window to open the Debug perspective



- When the debug perspective is opened, Program Counter (PC) should be located at the top of Warm\_Reset\_S function. Then, you need to press the button indicated by a red arrow in Figure 4-7.

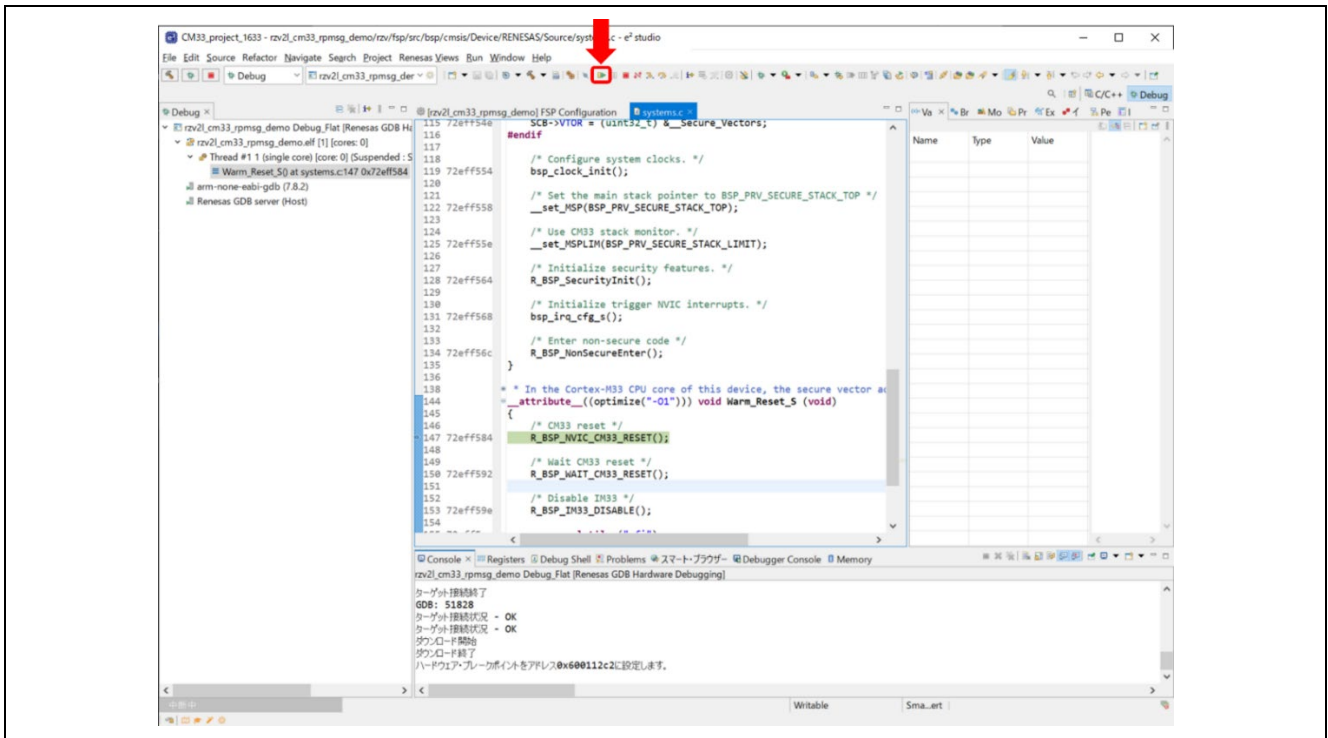


Figure 4-7. How to start to debug sample program (1)

- The program should stop at the top of main function. Thus, please click the same button as the previous step.

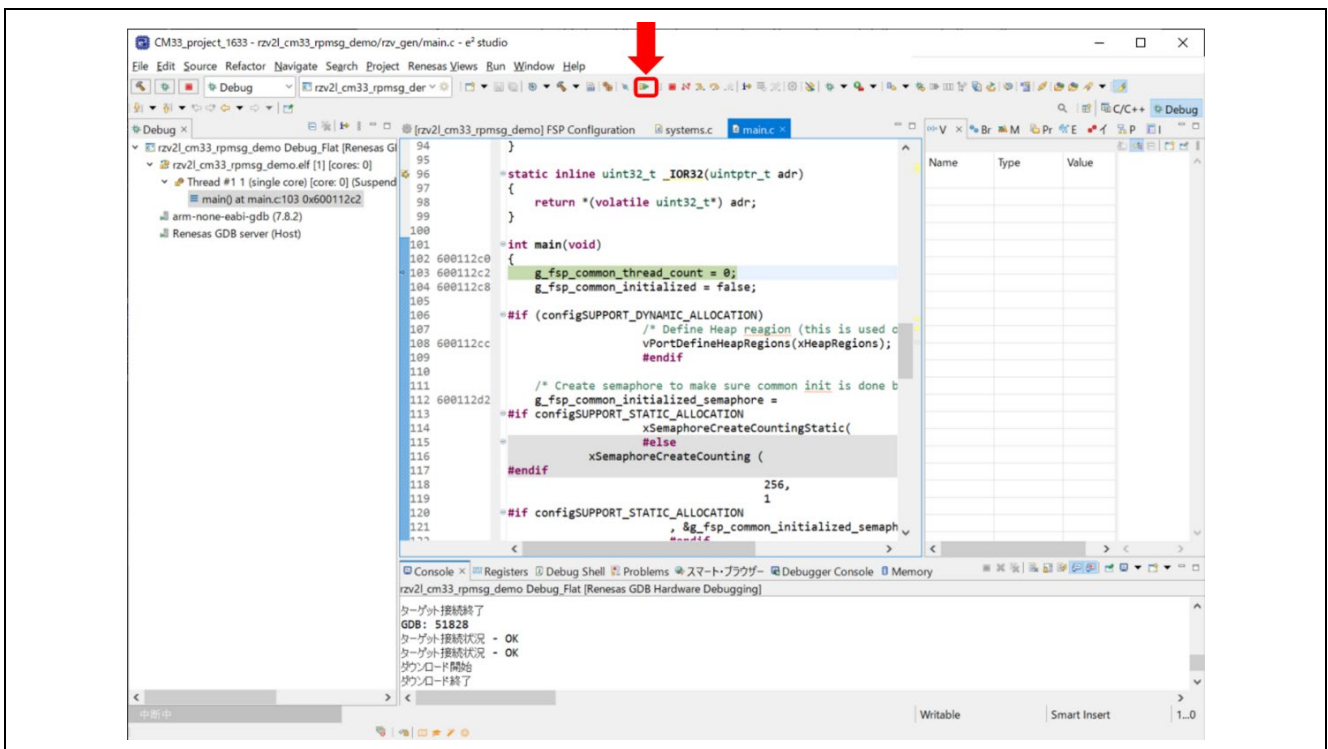


Figure 4-8. How to start to debug sample program (2)

5. Now that CM33 sample program has been started, the following message is shown on the console connected to Pmod USBUART:

```
Successfully probed IPI device
Successfully open uio device: 42F00000.rsctbl.
Successfully added memory device 42F00000.rsctbl.
Successfully open uio device: 43000000.vring-ctl0.
Successfully added memory device 43000000.vring-ctl0.
Successfully open uio device: 43200000.vring-shm0.
Successfully added memory device 43200000.vring-shm0.
Initialize remoteproc successfully.
creating remoteproc virtio
initializing rpmsg vdev
```

CM33 program is waiting for the establishment of rpmsg channel between CM33 and CA55.

#### 4.3.2 CM33 Sample Program Invocation with u-boot

You can invoke CM33 sample program from u-boot by following the procedure described below:

1. Copy the binary files generated at 8 of section 4.2 to microSD card.
2. Insert the microSD card into CN10 of SMARC carrier board.
3. Turn on SMARC EVK by pressing reset button (i.e., SW14)
4. You should now see the following message in the console connected to CN14 of SMARC carrier board:

```
U-Boot 2021.10 (Dec 15 2023 - 06:47:44 +0000)

CPU:   Renesas Electronics CPU rev 1.0
Model: smarc-rzv2l
DRAM:  1.9 GiB
WDT:   watchdog@0000000012800800
WDT:   Started with servicing (60s timeout)
MMC:   sd@11c00000: 0, sd@11c10000: 1
Loading Environment from MMC... OK
In:    serial@1004b800
Out:   serial@1004b800
Err:   serial@1004b800
U-boot WDT started!
Net:   eth0: ethernet@11c20000
Hit any key to stop autoboot: 2
=>
```

Then, you need to hit any key to stop autoboot within 3 sec.

5. Load the binary files listed in 1. from microSD card to RAM by executing the commands below on the console. Here, N denotes the partition number in which you stored those binaries.

```
dcache off
mmc dev 1
fatload mmc 1:N 0x0001FF80 rzv2l_cm33_rpmsg_demo_secure_vector.bin
fatload mmc 1:N 0x42EFF440 rzv2l_cm33_rpmsg_demo_secure_code.bin
fatload mmc 1:N 0x00010000 rzv2l_cm33_rpmsg_demo_non_secure_vector.bin
fatload mmc 1:N 0x40010000 rzv2l_cm33_rpmsg_demo_non_secure_code.bin
cm33 start_debug 0x1001FF80 0x00010000
dcache on
```

6. Now that CM33 program has been started to run. With respect to the behavior of sample program, please see 4.5.

## 4.4 CA55 Sample Program Invocation

You need to follow the procedure shown below to invoke CA55 sample program running on Linux.

1. Boot up Linux by executing the following command on u-boot:

```
run bootcmd
```

2. Login as "root"

```
smarc-rzv2l login: root
```

3. Run CA55 sample program by executing the following command on Linux.

```
root@smarc-rzv2l:~# rpmsg_sample_client
```

4. Then, you can see the following message on the console relative to CN14 of SMARC carrier board. Be sure that you invoke CM33 program in advance.

```
Successfully probed IPI device
metal: info:      metal_uio_dev_open: No IRQ for device 42f00000.rsctbl.
Successfully open uio device: 42f00000.rsctbl.
Successfully added memory device 42f00000.rsctbl.
metal: info:      metal_uio_dev_open: No IRQ for device 43000000.vring-ctl0.
Successfully open uio device: 43000000.vring-ctl0.
Successfully added memory device 43000000.vring-ctl0.
metal: info:      metal_uio_dev_open: No IRQ for device 43200000.vring-shm0.
Successfully open uio device: 43200000.vring-shm0.
Successfully added memory device 43200000.vring-shm0.
metal: info:      metal_uio_dev_open: No IRQ for device 43100000.vring-ctl1.
Successfully open uio device: 43100000.vring-ctl1.
Successfully added memory device 43100000.vring-ctl1.
metal: info:      metal_uio_dev_open: No IRQ for device 43500000.vring-shm1.
Successfully open uio device: 43500000.vring-shm1.
Successfully added memory device 43500000.vring-shm1.
metal: info:      metal_uio_dev_open: No IRQ for device 42f01000.mhu-shm.
Successfully open uio device: 42f01000.mhu-shm.
Successfully added memory device 42f01000.mhu-shm.
Initialize remoteproc successfully.
Initialize remoteproc successfully.

*****
*   rpmsg communication sample program   *
*****

1. communicate with RZ/V2L CM33 ch0
2. communicate with RZ/V2L CM33 ch1

e. exit

please input
>
```

5. Type 1 if RPMsg channel 0 is used on CM33 RPMsg sample program under default setting. Otherwise, type2 for starting the communication.

## 4.5 Overview of Sample Program Behavior

The behavior of sample program is as follows:

1. Wait until a communication channel between CA55 and CM33 is established.
2. Once the communication channel is established, CA55 sample program starts to send the message to CM33 with incrementing its size from the minimum value 17 to the maximum value 488. At that time, the message like the following should be shown in the console connected to CN14 of SMARC carrier board:

```
Sending payload number 148 of size 165
```

3. When CM33 receives the message sent from CA55, the echo reply is sent back to CA55.
4. When CA55 receives the echo reply, the message below should be displayed in the console connected to CN14 of SMARC carrier board:

```
echo test: sent : 165
received payload number 148 of size 165
```

5. After the message which has 488 bytes sized payload is sent from CA55 to CM33 and CM33 sends back the echo reply, the message for terminating the communication channel is sent from CA55 to CM33. Then, CA55 and CM33 sample programs output the following log messages to the corresponding consoles respectively when receiving the termination message.

- Message shown on CA55 side:

```
*****
*   rpmsg communication sample program   *
*****
```

1. communicate with RZ/V2L CM33 ch0
2. communicate with RZ/V2L CM33 ch1

```
e. exit
```

```
please input
>
```

If you would like to quit the application, please type e.

- Termination message on CM33 side

```
De-initializing remoteproc
```

Then, CM33 side re-waits for the establishment of connection channel. You can see the following log on the console a short time later:

```
creating remoteproc virtio
initializing rpmsg vdev
```

## 5. Reference Documents

- R01AN6240: RZ/V2L Getting Started with Flexible Software Package
- R01US0565: RZ/V Verified Linux Package Version 3.0.5 Release Note
- R01US0617: SMARC EVK of RZ/V2L Linux Start-up Guide

## Revision History

Rev.	Date	Description	
		Page	Summary
1.00	Jan.14.22	-	First edition issued.
1.01	Jun.13.22	-	Updated in align with RZ/V2L Linux Package Version 1.0.1.
1.02	Jul.31.22	-	Updated in align with RZ/V2L Verified Linux Package Version 3.0.0
1.10	Jan.31.23	-	Updated in align with RZ/V2L Verified Linux Package Version 3.0.2
1.11	Jul.24.23	-	Updated in align with RZ/V2L Verified Linux Package Version 3.0.4
1.12	Jan.31.24	-	Updated in align with RZ/V2L Verified Linux Package Version 3.0.5

# General Precautions in the Handling of Microprocessing Unit and Microcontroller Unit Products

The following usage notes are applicable to all Microprocessing unit and Microcontroller unit products from Renesas. For detailed usage notes on the products covered by this document, refer to the relevant sections of the document as well as any technical updates that have been issued for the products.

## 1. Precaution against Electrostatic Discharge (ESD)

A strong electrical field, when exposed to a CMOS device, can cause destruction of the gate oxide and ultimately degrade the device operation. Steps must be taken to stop the generation of static electricity as much as possible, and quickly dissipate it when it occurs. Environmental control must be adequate. When it is dry, a humidifier should be used. This is recommended to avoid using insulators that can easily build up static electricity.

Semiconductor devices must be stored and transported in an anti-static container, static shielding bag or conductive material. All test and measurement tools including work benches and floors must be grounded. The operator must also be grounded using a wrist strap. Semiconductor devices must not be touched with bare hands. Similar precautions must be taken for printed circuit boards with mounted semiconductor devices.

## 2. Processing at power-on

The state of the product is undefined at the time when power is supplied. The states of internal circuits in the LSI are indeterminate and the states of register settings and pins are undefined at the time when power is supplied. In a finished product where the reset signal is applied to the external reset pin, the states of pins are not guaranteed from the time when power is supplied until the reset process is completed. In a similar way, the states of pins in a product that is reset by an on-chip power-on reset function are not guaranteed from the time when power is supplied until the power reaches the level at which resetting is specified.

## 3. Input of signal during power-off state

Do not input signals or an I/O pull-up power supply while the device is powered off. The current injection that results from input of such a signal or I/O pull-up power supply may cause malfunction and the abnormal current that passes in the device at this time may cause degradation of internal elements. Follow the guideline for input signal during power-off state as described in your product documentation.

## 4. Handling of unused pins

Handle unused pins in accordance with the directions given under handling of unused pins in the manual. The input pins of CMOS products are generally in the high-impedance state. In operation with an unused pin in the open-circuit state, extra electromagnetic noise is induced in the vicinity of the LSI, an associated shoot-through current flows internally, and malfunctions occur due to the false recognition of the pin state as an input signal become possible.

## 5. Clock signals

After applying a reset, only release the reset line after the operating clock signal becomes stable. When switching the clock signal during program execution, wait until the target clock signal is stabilized. When the clock signal is generated with an external resonator or from an external oscillator during a reset, ensure that the reset line is only released after full stabilization of the clock signal. Additionally, when switching to a clock signal produced with an external resonator or by an external oscillator while program execution is in progress, wait until the target clock signal is stable.

## 6. Voltage application waveform at input pin

Waveform distortion due to input noise or a reflected wave may cause malfunction. If the input of the CMOS device stays in the area between  $V_{IL}$  (Max.) and  $V_{IH}$  (Min.) due to noise, for example, the device may malfunction. Take care to prevent chattering noise from entering the device when the input level is fixed, and also in the transition period when the input level passes through the area between  $V_{IL}$  (Max.) and  $V_{IH}$  (Min.).

## 7. Prohibition of access to reserved addresses

Access to reserved addresses is prohibited. The reserved addresses are provided for possible future expansion of functions. Do not access these addresses as the correct operation of the LSI is not guaranteed.

## 8. Differences between products

Before changing from one product to another, for example to a product with a different part number, confirm that the change will not lead to problems. The characteristics of a microprocessing unit or microcontroller unit products in the same group but having a different part number might differ in terms of internal memory capacity, layout pattern, and other factors, which can affect the ranges of electrical characteristics, such as characteristic values, operating margins, immunity to noise, and amount of radiated noise. When changing to a product with a different part number, implement a system-evaluation test for the given product.

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