

Description

The 9ZXL0851 is a low-power 8-output differential buffer that meets all the performance requirements of the Intel DB1200ZL specification. It is suitable for PCI-Express Gen1–3 or QP/UPI applications, and uses a fixed external feedback to maintain low drift for critical QPI/UPI applications.

Applications

Buffer for Romley, Grantley and Purley Servers, SSD drives and PCIe

Output Features

- 8 LP-HCSL Output Pairs w/integrated terminations ($Z_o = 85\Omega$)

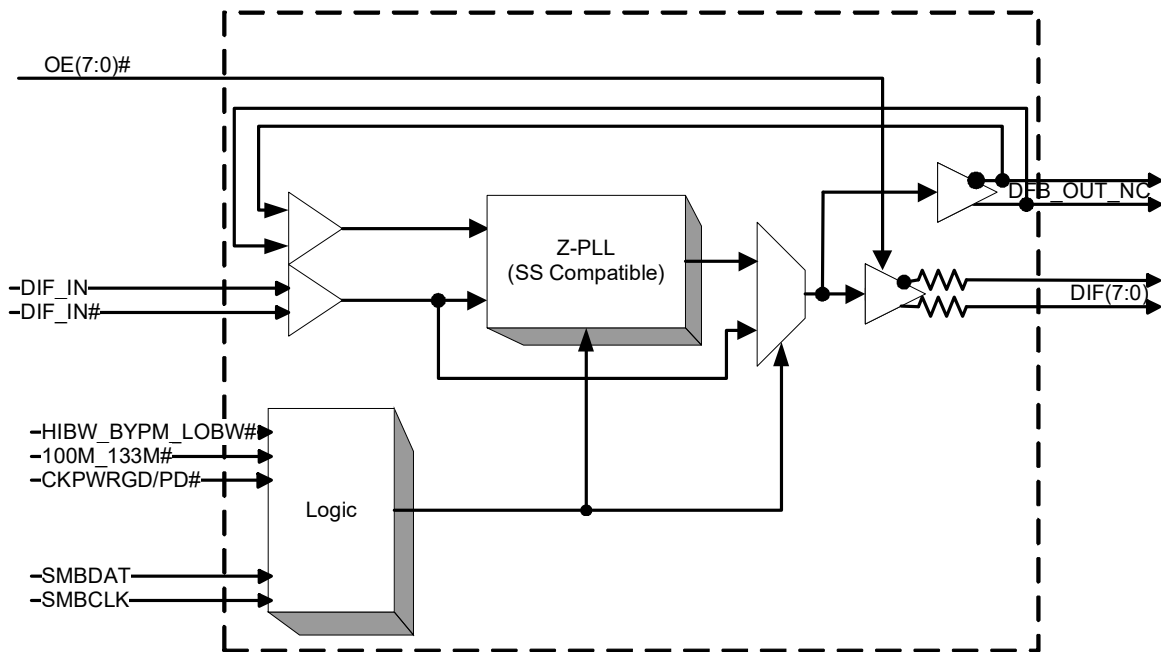
Features

- LP-HCSL outputs with $Z_o = 85\Omega$; save power and board space - no termination resistors required.
- Space-saving 48-pin VFQFPN package
- Fixed feedback path for 0ps input-to-output delay
- 8 OE# pins; hardware control of each output
- PLL or bypass mode; PLL can dejitter incoming clock
- 100MHz or 133MHz PLL mode operation; supports PCIe and QPI applications
- Selectable PLL bandwidth; minimizes jitter peaking in downstream PLLs
- Spread spectrum compatible; tracks spreading input clock for low EMI
- 25MHz PFT clock delay management

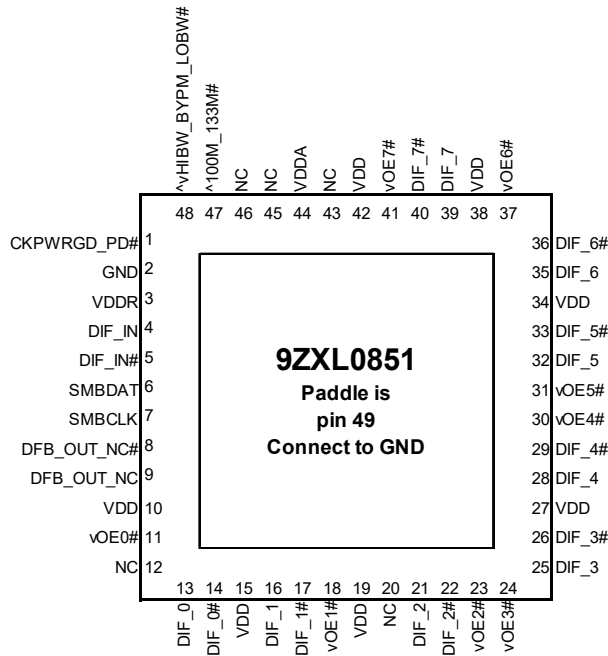
Key Specifications

- Cycle-to-cycle jitter < 50ps
- Output-to-output skew < 65ps
- Input-to-output delay variation < 50ps
- PCIe Gen3 phase jitter < 1.0ps RMS
- QPI/UPI 9.6GT/s 12UI phase jitter < 0.2ps RMS

Block Diagram



Pin Configuration



48-pin VFQFPN, 6x6 mm, 0.4mm pitch

Note: Pins with ^ prefix have internal 120kOhm pull-up
 Pins with v prefix have internal 120kOhm pull-down
 Pins with ^v prefix have internal 120kOhm pull-up/pull-down (biased to VDD/2)

Power Management Table

| CKPWRGD_PD# | DIF_IN/ DIF_IN# | SMBus EN bit | DIF(7:0)/ DIF(7:0)# | PLL STATE IF NOT IN BYPASS MODE |
|-------------|--------------------|-----------------|------------------------|--|
| 0 | X | X | Low/Low | OFF |
| 1 | Running | 0 | Low/Low | ON |
| | | 1 | Running | ON |

Functionality at Power-up (PLL mode)

| 100M_133M# | DIF_IN MHz | DIF(7:0) |
|------------|---------------|----------|
| 1 | 100.00 | DIF_IN |
| 0 | 133.33 | DIF_IN |

PLL Operating Mode Readback Table

| HiBW_BypM_LoBW# | Byte0, bit 7 | Byte 0, bit 6 |
|-----------------|--------------|---------------|
| Low (Low BW) | 0 | 0 |
| Mid (Bypass) | 0 | 1 |
| High (High BW) | 1 | 1 |

Power Connections

| Pin Number | | Description |
|---------------------------|-----|--------------|
| VDD | GND | |
| 44 | 49 | Analog PLL |
| 3 | 2 | Analog Input |
| 10,15,19, 27,34,38, 42 | 49 | DIF clocks |

Tri-Level Input Thresholds

| Level | Voltage |
|-------|--------------|
| Low | <0.8V |
| Mid | 1.2<Vin<1.8V |
| High | Vin > 2.2V |

SMBus Address

| Address | + Read/Write bit |
|---------|------------------|
| 1101100 | x |

PLL Operating Mode

| HiBW_BypM_LoBW# | MODE |
|-----------------|-----------|
| Low | PLL Lo BW |
| Mid | Bypass |
| High | PLL Hi BW |

NOTE: PLL is OFF in Bypass Mode

Pin Descriptions

| PIN # | PIN NAME | TYPE | DESCRIPTION |
|-------|-------------|------|--|
| 1 | CKPWRGD_PD# | IN | 3.3V Input notifies device to sample latched inputs and start up on first high assertion, or exit Power Down Mode on subsequent assertions. Low enters Power Down Mode. |
| 2 | GND | GND | Ground pin. |
| 3 | VDDR | PWR | 3.3V power for differential input clock (receiver). This VDD should be treated as an analog power rail and filtered appropriately. |
| 4 | DIF_IN | IN | 0.7 V Differential True input |
| 5 | DIF_IN# | IN | 0.7 V Differential Complementary Input |
| 6 | SMBDAT | I/O | Data pin of SMBUS circuitry, 5V tolerant |
| 7 | SMBCLK | IN | Clock pin of SMBUS circuitry, 5V tolerant |
| 8 | DFB_OUT_NC# | OUT | Complementary half of differential feedback output, provides feedback signal to the PLL for synchronization with input clock to eliminate phase error. This pin should NOT be connected on the circuit board, the feedback is internal to the package. |
| 9 | DFB_OUT_NC | OUT | True half of differential feedback output, provides feedback signal to the PLL for synchronization with the input clock to eliminate phase error. This pin should NOT be connected on the circuit board, the feedback is internal to the package. |
| 10 | VDD | PWR | Power supply, nominal 3.3V |
| 11 | vOE0# | IN | Active low input for enabling DIF pair 0. This pin has an internal pull-down. 1 =disable outputs, 0 = enable outputs |
| 12 | NC | N/A | No Connection. |
| 13 | DIF_0 | OUT | 0.7V differential true clock output |
| 14 | DIF_0# | OUT | 0.7V differential Complementary clock output |
| 15 | VDD | PWR | Power supply, nominal 3.3V |
| 16 | DIF_1 | OUT | 0.7V differential true clock output |
| 17 | DIF_1# | OUT | 0.7V differential Complementary clock output |
| 18 | vOE1# | IN | Active low input for enabling DIF pair 1. This pin has an internal pull-down. 1 =disable outputs, 0 = enable outputs |
| 19 | VDD | PWR | Power supply, nominal 3.3V |
| 20 | NC | N/A | No Connection. |
| 21 | DIF_2 | OUT | 0.7V differential true clock output |
| 22 | DIF_2# | OUT | 0.7V differential Complementary clock output |
| 23 | vOE2# | IN | Active low input for enabling DIF pair 2. This pin has an internal pull-down. 1 =disable outputs, 0 = enable outputs |
| 24 | vOE3# | IN | Active low input for enabling DIF pair 3. This pin has an internal pull-down. 1 =disable outputs, 0 = enable outputs |
| 25 | DIF_3 | OUT | 0.7V differential true clock output |
| 26 | DIF_3# | OUT | 0.7V differential Complementary clock output |
| 27 | VDD | PWR | Power supply, nominal 3.3V |
| 28 | DIF_4 | OUT | 0.7V differential true clock output |
| 29 | DIF_4# | OUT | 0.7V differential Complementary clock output |
| 30 | vOE4# | IN | Active low input for enabling DIF pair 4. This pin has an internal pull-down. 1 =disable outputs, 0 = enable outputs |
| 31 | vOE5# | IN | Active low input for enabling DIF pair 5. This pin has an internal pull-down. 1 =disable outputs, 0 = enable outputs |

Pin Descriptions (cont.)

| PIN # | PIN NAME | TYPE | DESCRIPTION |
|-------|-------------------|---------------|--|
| 32 | DIF_5 | OUT | 0.7V differential true clock output |
| 33 | DIF_5# | OUT | 0.7V differential Complementary clock output |
| 34 | VDD | PWR | Power supply, nominal 3.3V |
| 35 | DIF_6 | OUT | 0.7V differential true clock output |
| 36 | DIF_6# | OUT | 0.7V differential Complementary clock output |
| 37 | vOE6# | IN | Active low input for enabling DIF pair 6. This pin has an internal pull-down. 1 =disable outputs, 0 = enable outputs |
| 38 | VDD | PWR | Power supply, nominal 3.3V |
| 39 | DIF_7 | OUT | 0.7V differential true clock output |
| 40 | DIF_7# | OUT | 0.7V differential Complementary clock output |
| 41 | vOE7# | IN | Active low input for enabling DIF pair 7. This pin has an internal pull-down. 1 =disable outputs, 0 = enable outputs |
| 42 | VDD | PWR | Power supply, nominal 3.3V |
| 43 | NC | N/A | No Connection. |
| 44 | VDDA | PWR | 3.3V power for the PLL core. |
| 45 | NC | N/A | No Connection. |
| 46 | NC | N/A | No Connection. |
| 47 | ^100M_133M# | IN | 3.3V Input to select operating frequency. This pin has an internal pull-up resistor. See Functionality Table for Definition |
| 48 | ^vHIBW_BYPM_LOBW# | LATCHED IN | Trilevel input to select High BW, Bypass or Low BW mode. See PLL Operating Mode Table for Details. |
| 49 | GND | PWR | Ground |

Absolute Maximum Ratings

Stresses above the ratings listed below can cause permanent damage to the 9ZXL0851. These ratings, which are standard values for Renesas commercially rated parts, are stress ratings only. Functional operation of the device at these or any other conditions above those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods can affect product reliability. Electrical parameters are guaranteed only over the recommended operating temperature range.

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS | NOTES |
|----------------------|--------------------|----------------------------|---------|-----|-----------------------|-------|-------|
| 3.3V Supply Voltage | VDD, VDDA, VDDR | VDD for core logic and PLL | | | 4.6 | V | 1,2 |
| Input Low Voltage | V _{IL} | | GND-0.5 | | | V | 1 |
| Input High Voltage | V _{IH} | Except for SMBus interface | | | V _{DD} +0.5V | V | 1 |
| Input High Voltage | V _{IHSMB} | SMBus clock and data pins | | | 5.5V | V | 1 |
| Storage Temperature | T _s | | -65 | | 150 | °C | 1 |
| Junction Temperature | T _j | | | | 125 | °C | 1 |
| Input ESD protection | ESD prot | Human Body Model | 2000 | | | V | 1 |

¹Guaranteed by design and characterization, not 100% tested in production.

²Operation under these conditions is neither implied nor guaranteed.

Electrical Characteristics—DIF_IN Clock Input Parameters

T_A = T_{COM}; Supply Voltage V_{DD} = 3.3 V +/-5%

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS | NOTES |
|----------------------------------|--------------------|---|-----|-----|-----|-------|-------|
| Input Crossover Voltage - DIF_IN | V _{CROSS} | Crossover Voltage | 150 | | 900 | mV | 1 |
| Input Swing - DIF_IN | V _{SWING} | Differential value | 300 | | | mV | 1 |
| Input Slew Rate - DIF_IN | dv/dt | Measured differentially | 0.4 | | 8 | V/ns | 1,2 |
| Input Leakage Current | I _{IN} | V _{IN} = V _{DD} , V _{IN} = GND | -5 | | 5 | uA | |
| Input Duty Cycle | d _{tin} | Measurement from differential waveform | 45 | | 55 | % | 1 |
| Input Jitter - Cycle to Cycle | J _{DIFIn} | Differential Measurement | 0 | | 125 | ps | 1 |

¹Guaranteed by design and characterization, not 100% tested in production.

²Slew rate measured through +/-75mV window centered around differential zero.

Electrical Characteristics–Input/Supply/Common Parameters

T_A = T_{COM}; Supply Voltage V_{DD} = 3.3 V +/-5%

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS | NOTES |
|-------------------------------|-----------------------|--|-----------|--------|-----------------------|--------|-------|
| Ambient Operating Temperature | T _{COM} | Commercial range | 0 | | 70 | °C | 1 |
| Input High Voltage | V _{IH} | Single-ended inputs, except SMBus, low threshold and tri-level inputs | 2 | | V _{DD} + 0.3 | V | 1 |
| Input Low Voltage | V _{IL} | Single-ended inputs, except SMBus, low threshold and tri-level inputs | GND - 0.3 | | 0.8 | V | 1 |
| Input Current | I _{IN} | Single-ended inputs, V _{IN} = GND, V _{IN} = V _{DD} | -5 | | 5 | µA | 1 |
| | I _{INP} | Single-ended inputs V _{IN} = 0 V; Inputs with internal pull-up resistors V _{IN} = V _{DD} ; Inputs with internal pull-down resistors | -200 | | 200 | µA | 1 |
| Input Frequency | F _{ibyp} | V _{DD} = 3.3 V, Bypass mode | 25 | | 150 | MHz | 2 |
| | F _{ipll} | V _{DD} = 3.3 V, 100MHz PLL mode | 25 | 100.00 | 110 | MHz | 2 |
| | F _{ipll} | V _{DD} = 3.3 V, 133.33MHz PLL mode | 120 | 133.33 | 147 | MHz | 2 |
| Pin Inductance | L _{pin} | | | | 7 | nH | 1 |
| Capacitance | C _{IN} | Logic Inputs, except DIF_IN | 1.5 | | 5 | pF | 1 |
| | C _{INDIF_IN} | DIF_IN differential clock inputs | 1.5 | | 2.7 | pF | 1,4 |
| | C _{OUT} | Output pin capacitance | | | 6 | pF | 1 |
| Clk Stabilization | T _{STAB} | From V _{DD} Power-Up and after input clock stabilization or de-assertion of PD# to 1st clock | | 0.250 | 1 | ms | 1,2 |
| Input SS Modulation Frequency | f _{MODIN} | Allowable Frequency (Triangular Modulation) | 30 | | 33 | kHz | 1 |
| OE# Latency | t _{LATOE#} | DIF start after OE# assertion DIF stop after OE# deassertion | 4 | | 12 | cycles | 1,3 |
| Tdrive_PD# | t _{DRVPD} | DIF output enable after PD# de-assertion | | | 300 | µs | 1,3 |
| Tfall | t _F | Fall time of control inputs | | | 10 | ns | 1,2 |
| Trise | t _R | Rise time of control inputs | | | 10 | ns | 1,2 |
| SMBus Input Low Voltage | V _{ILSMB} | | | | 0.8 | V | 1 |
| SMBus Input High Voltage | V _{IHSMB} | | 2.1 | | V _{DD} SMB | V | 1 |
| SMBus Output Low Voltage | V _{OLSMB} | At I _{PULLUP} | | | 0.4 | V | 1 |
| SMBus Sink Current | I _{PULLUP} | At V _{OL} | 4 | | | mA | 1 |
| Nominal Bus Voltage | V _{DD} SMB | 3V to 5V +/- 10% | 2.7 | | 5.5 | V | 1 |
| SCLK/SDATA Rise Time | t _{RSMB} | (Max V _{IL} - 0.15) to (Min V _{IH} + 0.15) | | | 1000 | ns | 1 |
| SCLK/SDATA Fall Time | t _{FSMB} | (Min V _{IH} + 0.15) to (Max V _{IL} - 0.15) | | | 300 | ns | 1 |
| SMBus Operating Frequency | f _{MAXSMB} | Maximum SMBus operating frequency | | | 100 | kHz | 1,5 |

¹ Guaranteed by design and characterization, not 100% tested in production.

² Control input must be monotonic from 20% to 80% of input swing.

³ Time from deassertion until outputs are > 200mV.

⁴ DIF_IN input.

⁵ The differential input clock must be running for the SMBus to be active.

Electrical Characteristics–DIF 0.7V Low Power Differential Outputs

T_A = T_{COM}; Supply Voltage V_{DD} = 3.3 V +/-5%

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS | NOTES |
|------------------------|------------|---|------|-----|------|-------|---------|
| Slew rate | Trf | Scope averaging on | 1 | | 4 | V/ns | 1, 2, 3 |
| Slew rate matching | ΔTrf | Slew rate matching, Scope averaging on | | | 20 | % | 1, 2, 4 |
| Voltage High | VHigh | Statistical measurement on single-ended signal using oscilloscope math function. (Scope averaging on) | 660 | | 850 | mV | 1 |
| Voltage Low | VLow | | -150 | | 150 | | 1 |
| Max Voltage | Vmax | Measurement on single ended signal using absolute value. (Scope averaging off) | | | 1150 | mV | 1 |
| Min Voltage | Vmin | | -300 | | | | 1 |
| Vswing | Vswing | Scope averaging off | 300 | | | mV | 1, 2 |
| Crossing Voltage (abs) | Vcross_abs | Scope averaging off | 300 | | 550 | mV | 1, 5 |
| Crossing Voltage (var) | Δ-Vcross | Scope averaging off | | | 140 | mV | 1, 6 |

¹Guaranteed by design and characterization, not 100% tested in production. C_L = 2pF with R_S = 27Ω for Z_o = 85Ω differential trace impedance).

² Measured from differential waveform.

³ Slew rate is measured through the Vswing voltage range centered around differential 0V. This results in a +/-150mV window around differential 0V.

⁴ Matching applies to rising edge rate for Clock and falling edge rate for Clock#. It is measured using a +/-75mV window centered on the average cross point where Clock rising meets Clock# falling. The median cross point is used to calculate the voltage t

⁵ Vcross is defined as voltage where Clock = Clock# measured on a component test board and only applies to the differential rising edge (i.e. Clock rising and Clock# falling).

⁶ The total variation of all Vcross measurements in any particular system. Note that this is a subset of Vcross_min/max (Vcross absolute) allowed. The intent is to limit Vcross induced modulation by setting Δ-Vcross to be smaller than Vcross absolute.

Electrical Characteristics–Current Consumption

T_A = T_{COM}; Supply Voltage V_{DD} = 3.3 V +/-5%

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS | NOTES |
|-------------------|-----------------------|------------------------------------|-----|-----|-----|-------|-------|
| Operating Current | I _{DDVDD} | 133MHz, VDD rail | | | 135 | mA | 1 |
| | I _{DDVDDA} | 133MHz, VDDA + VDDR rail, PLL Mode | | | 20 | mA | 1 |
| Powerdown Current | I _{DDVDDPD} | Power Down, VDD Rail | | | 1.2 | mA | 1 |
| | I _{DDVDDAPD} | Power Down, VDDA Rail | | | 5 | mA | 1 |

¹Guaranteed by design and characterization, not 100% tested in production.

² C_L = 2pF with R_S = 27Ω for Z_o = 85Ω differential trace impedance

Electrical Characteristics—Skew and Differential Jitter Parameters

$T_A = T_{COM}$; Supply Voltage $V_{DD} = 3.3\text{ V} \pm 5\%$

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS | NOTES |
|------------------------|-----------------|--|------|-----|-----|---------|-----------|
| CLK_IN, DIF[x:0] | t_{SPO_PLL} | Input-to-Output Skew in PLL mode nominal value @ 25°C, 3.3V | -100 | | 100 | ps | 1,2,4,5,8 |
| CLK_IN, DIF[x:0] | t_{PD_BYP} | Input-to-Output Skew in Bypass mode nominal value @ 25°C, 3.3V | 2.5 | | 4.5 | ns | 1,2,3,5,8 |
| CLK_IN, DIF[x:0] | t_{DSPO_PLL} | Input-to-Output Skew Variation in PLL mode across voltage and temperature | -50 | | 50 | ps | 1,2,3,5,8 |
| CLK_IN, DIF[x:0] | t_{DSPO_BYP} | Input-to-Output Skew Variation in Bypass mode across voltage and temperature | -250 | | 250 | ps | 1,2,3,5,8 |
| CLK_IN, DIF[x:0] | t_{DTE} | Random Differential Tracking error between two 9ZX devices in Hi BW Mode | | | 5 | ps (ms) | 1,2,3,5,8 |
| CLK_IN, DIF[x:0] | t_{DSSSTE} | Random Differential Spread Spectrum Tracking error between two 9ZX devices in Hi BW Mode | | | 75 | ps | 1,2,3,5,8 |
| DIF[x:0] | t_{SKEW_ALL} | Output-to-Output Skew across all outputs (Common to Bypass and PLL mode) | | | 65 | ps | 1,2,3,8 |
| PLL Jitter Peaking | $j_{peak-hibw}$ | LOBW#_BYPASS_HIBW = 1 | 0 | | 2.5 | dB | 7,8 |
| PLL Jitter Peaking | $j_{peak-lobw}$ | LOBW#_BYPASS_HIBW = 0 | 0 | | 2 | dB | 7,8 |
| PLL Bandwidth | pll_{HIBW} | LOBW#_BYPASS_HIBW = 1 | 2 | | 4 | MHz | 8,9 |
| PLL Bandwidth | pll_{LOBW} | LOBW#_BYPASS_HIBW = 0 | 0.7 | | 1.4 | MHz | 8,9 |
| Duty Cycle | t_{DC} | Measured differentially, PLL Mode | 45 | | 55 | % | 1 |
| Duty Cycle Distortion | t_{DCD} | Measured differentially, Bypass Mode @100MHz | -2 | | 2 | % | 1,10 |
| Jitter, Cycle to cycle | $t_{jyc-cyc}$ | PLL mode | | | 50 | ps | 1,11 |
| | | Additive Jitter in Bypass Mode | | | 50 | ps | 1,11 |

Notes for preceding table:

- ¹ $C_L = 2\text{pF}$ with $R_S = 27\Omega$ for $Z_o = 85\Omega$ differential trace impedance. Input to output skew is measured at the first output edge following the corresponding input.
- ² Measured from differential cross-point to differential cross-point. This parameter can be tuned with external feedback path, if present.
- ³ All Bypass Mode Input-to-Output specs refer to the timing between an input edge and the specific output edge created by it.
- ⁴ This parameter is deterministic for a given device.
- ⁵ Measured with scope averaging on to find mean value.
- ⁶ t is the period of the input clock.
- ⁷ Measured as maximum pass band gain. At frequencies within the loop BW, highest point of magnification is called PLL jitter peaking.
- ⁸ Guaranteed by design and characterization, not 100% tested in production.
- ⁹ Measured at 3 db down or half power point.
- ¹⁰ Duty cycle distortion is the difference in duty cycle between the output and the input clock when the device is operated in bypass mode.
- ¹¹ Measured from differential waveform.

Electrical Characteristics—Phase Jitter Parameters

T_A = T_{COM}; Supply Voltage V_{DD} = 3.3 V +/-5%

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS | Notes |
|---------------------------------------|-------------------------|--|-----|-----|-----|----------|---------|
| Phase Jitter, PLL Mode | t _{jphPCIeG1} | PCIe Gen 1 | | | 86 | ps (p-p) | 1,2,3 |
| | t _{jphPCIeG2} | PCIe Gen 2 Lo Band 10kHz < f < 1.5MHz | | | 3 | ps (rms) | 1,2 |
| | | PCIe Gen 2 High Band 1.5MHz < f < Nyquist (50MHz) | | | 3.1 | ps (rms) | 1,2 |
| | t _{jphPCIeG3} | PCIe Gen 3 (PLL BW of 2-4MHz, CDR = 10MHz) | | | 1 | ps (rms) | 1,2,4 |
| | t _{jphQPI_SMI} | QPI & SMI (100MHz or 133MHz, 4.8Gb/s, 6.4Gb/s 12UI) | | | 0.5 | ps (rms) | 1,5 |
| | | QPI & SMI (100MHz, 8.0Gb/s, 12UI) | | | 0.3 | ps (rms) | 1,5 |
| | | QPI & SMI (100MHz, 9.6Gb/s, 12UI) | | | 0.2 | ps (rms) | 1,5 |
| Additive Phase Jitter, Bypass mode | t _{jphPCIeG1} | PCIe Gen 1 | | | 10 | ps (p-p) | 1,2,3 |
| | t _{jphPCIeG2} | PCIe Gen 2 Lo Band 10kHz < f < 1.5MHz | | | 0.3 | ps (rms) | 1,2,6 |
| | | PCIe Gen 2 High Band 1.5MHz < f < Nyquist (50MHz) | | | 0.6 | ps (rms) | 1,2,6 |
| | t _{jphPCIeG3} | PCIe Gen 3 (PLL BW of 2-4MHz, 2-5MHz, CDR = 10MHz) | | | 0.2 | ps (rms) | 1,2,4,6 |
| | t _{jphQPI_SMI} | QPI & SMI (100MHz or 133MHz, 4.8Gb/s, 6.4Gb/s 12UI) | | | 0.2 | ps (rms) | 1,5,6 |
| | | QPI & SMI (100MHz, 8.0Gb/s, 12UI) | | | 0.1 | ps (rms) | 1,5,6 |
| | | QPI & SMI (100MHz, 9.6Gb/s, 12UI) | | | 0.1 | ps (rms) | 1,5,6 |

¹ Applies to all outputs.

² See <http://www.pcisig.com> for complete specs.

³ Sample size of at least 100K cycles. This figures extrapolates to 108ps pk-pk at 1M cycles for a BER of 1⁻¹².

⁴ Subject to final ratification by PCI SIG.

⁵ Calculated from Intel-supplied clock jitter tool v1.6.3.

⁶ For RMS figures, additive jitter is calculated by solving the following equation: (Additive jitter)² = (total jitter)² - (input jitter)².

Clock Periods–Differential Outputs with Spread Spectrum Disabled

| SSC OFF | Center Freq. MHz | Measurement Window | | | | | | | Units | Notes |
|---------|------------------|------------------------|-----------------------------|-----------------------------|----------------------|-----------------------------|-----------------------------|------------------------|-------|-------|
| | | 1 Clock | 1us | 0.1s | 0.1s | 0.1s | 1us | 1 Clock | | |
| | | -c2c jitter AbsPer Min | -SSC Short-Term Average Min | - ppm Long-Term Average Min | 0 ppm Period Nominal | + ppm Long-Term Average Max | +SSC Short-Term Average Max | +c2c jitter AbsPer Max | | |
| DIF | 100.00 | 9.94900 | | 9.99900 | 10.00000 | 10.00100 | | 10.05100 | ns | 1,2,3 |
| | 133.33 | 7.44925 | | 7.49925 | 7.50000 | 7.50075 | | 7.55075 | ns | 1,2,4 |

Clock Periods–Differential Outputs with Spread Spectrum Enabled

| SSC ON | Center Freq. MHz | Measurement Window | | | | | | | Units | Notes |
|--------|------------------|------------------------|-----------------------------|-----------------------------|----------------------|-----------------------------|-----------------------------|------------------------|-------|-------|
| | | 1 Clock | 1us | 0.1s | 0.1s | 0.1s | 1us | 1 Clock | | |
| | | -c2c jitter AbsPer Min | -SSC Short-Term Average Min | - ppm Long-Term Average Min | 0 ppm Period Nominal | + ppm Long-Term Average Max | +SSC Short-Term Average Max | +c2c jitter AbsPer Max | | |
| DIF | 99.75 | 9.94906 | 9.99906 | 10.02406 | 10.02506 | 10.02607 | 10.05107 | 10.10107 | ns | 1,2,3 |
| | 133.00 | 7.44930 | 7.49930 | 7.51805 | 7.51880 | 7.51955 | 7.53830 | 7.58830 | ns | 1,2,4 |

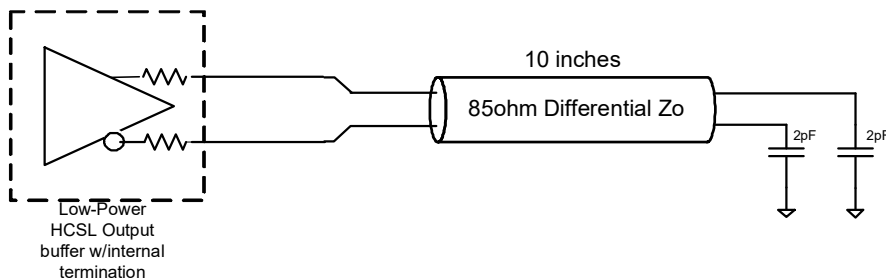
Notes:

- ¹Guaranteed by design and characterization, not 100% tested in production.
- ²All Long Term Accuracy specifications are guaranteed with the assumption that the input clock complies with CK420BQ/CK410B+ accuracy requirements (+/-100ppm). The 9ZXL0851 itself does not contribute to ppm error.
- ³ Driven by SRC output of main clock, 100 MHz PLL Mode or Bypass mode
- ⁴ Driven by CPU output of main clock, 133 MHz PLL Mode or Bypass mode

Test Loads

Differential Output Terminations

| DIF Zo (Ω) | Rs (Ω) |
|------------|--------|
| 100 | 7 |
| 85 | 0 |



General SMBus Serial Interface Information for 9ZXL0851

How to Write

- Controller (host) sends a start bit
- Controller (host) sends the write address
- Renesas clock will **acknowledge**
- Controller (host) sends the beginning byte location = N
- Renesas clock will **acknowledge**
- Controller (host) sends the byte count = X
- Renesas clock will **acknowledge**
- Controller (host) starts sending Byte N through Byte N+X-1
- Renesas clock will **acknowledge** each byte **one at a time**
- Controller (host) sends a Stop bit

| Index Block Write Operation | | |
|-----------------------------|-----------|--------------------------|
| Controller (Host) | | Renesas (Slave/Receiver) |
| T | starT bit | |
| Slave Address | | |
| WR | WRite | |
| | | ACK |
| Beginning Byte = N | | |
| | | ACK |
| Data Byte Count = X | | |
| | | ACK |
| Beginning Byte N | | |
| | | ACK |
| O | X Byte | |
| O | | O |
| O | | O |
| Byte N + X - 1 | | |
| | | ACK |
| P | stoP bit | |

How to Read

- Controller (host) will send a start bit
- Controller (host) sends the write address
- Renesas clock will **acknowledge**
- Controller (host) sends the beginning byte location = N
- Renesas clock will **acknowledge**
- Controller (host) will send a separate start bit
- Controller (host) sends the read address
- Renesas clock will **acknowledge**
- Renesas clock will send the data byte count = X
- Renesas clock sends Byte N+X-1
- Renesas clock sends **Byte 0 through Byte X (if X_(H) was written to Byte 8)**
- Controller (host) will need to acknowledge each byte
- Controller (host) will send a not acknowledge bit
- Controller (host) will send a stop bit

| Index Block Read Operation | | |
|----------------------------|-----------------|-------------------|
| Controller (Host) | | Renesas |
| T | starT bit | |
| Slave Address | | |
| WR | WRite | |
| | | ACK |
| Beginning Byte = N | | |
| | | ACK |
| RT | Repeat starT | |
| Slave Address | | |
| RD | ReaD | |
| | | ACK |
| | | Data Byte Count=X |
| ACK | | |
| | | Beginning Byte N |
| ACK | | |
| O | X Byte | |
| O | | O |
| O | | O |
| O | | O |
| | | Byte N + X - 1 |
| N | Not acknowledge | |
| P | stoP bit | |

SMBusTable: PLL Mode, and Frequency Select Register

| Byte 0 | Pin # | Name | Control Function | Type | 0 | 1 | Default |
|--------|-------|------------|------------------------------|------|---------------------------------------|---------------|---------|
| Bit 7 | 48 | PLL Mode 1 | PLL Operating Mode Rd back 1 | R | See PLL Operating Mode Readback Table | | Latch |
| Bit 6 | 48 | PLL Mode 0 | PLL Operating Mode Rd back 0 | R | See PLL Operating Mode Readback Table | | Latch |
| Bit 5 | | | Reserved | | | | 0 |
| Bit 4 | | | Reserved | | | | 0 |
| Bit 3 | | PLL SW_EN | Enable S/W control of PLL BW | RW | HW Latch | SMBus Control | 0 |
| Bit 2 | | PLL Mode 1 | PLL Operating Mode 1 | RW | See PLL Operating Mode Readback Table | | 1 |
| Bit 1 | | PLL Mode 0 | PLL Operating Mode 0 | RW | See PLL Operating Mode Readback Table | | 1 |
| Bit 0 | 47 | 100M 133M# | Frequency Select Readback | R | 133MHz | 100MHz | Latch |

Note: Setting bit 3 to '1' allows the user to override the Latch value from pin 5 via use of bits 2 and 1. Use the values from the PLL Operating Mode Readback Table. Note that Bits 7 and 6 will keep the value originally latched on pin 5. A warm reset of

SMBusTable: Output Control Register

| Byte 1 | Pin # | Name | Control Function | Type | 0 | 1 | Default |
|--------|-------|----------|--|------|---------|--------|---------|
| Bit 7 | 32/33 | DIF_5_En | Output Control - '0' overrides OE# pin | RW | Low/Low | Enable | 1 |
| Bit 6 | 28/29 | DIF_4_En | Output Control - '0' overrides OE# pin | RW | | | 1 |
| Bit 5 | 25/26 | DIF_3_En | Output Control - '0' overrides OE# pin | RW | | | 1 |
| Bit 4 | 21/22 | DIF_2_En | Output Control - '0' overrides OE# pin | RW | | | 1 |
| Bit 3 | | | Reserved | | | | 1 |
| Bit 2 | 16/17 | DIF_1_En | Output Control - '0' overrides OE# pin | RW | Low/Low | Enable | 1 |
| Bit 1 | 13/14 | DIF_0_En | Output Control - '0' overrides OE# pin | RW | | | 1 |
| Bit 0 | | | Reserved | | | | 1 |

SMBusTable: Output Control Register

| Byte 2 | Pin # | Name | Control Function | Type | 0 | 1 | Default |
|--------|-------|----------|--|------|---------|--------|---------|
| Bit 7 | | | Reserved | | | | 0 |
| Bit 6 | | | Reserved | | | | 0 |
| Bit 5 | | | Reserved | | | | 0 |
| Bit 4 | | | Reserved | | | | 0 |
| Bit 3 | | | Reserved | | | | 1 |
| Bit 2 | 39/40 | DIF_7_En | Output Control - '0' overrides OE# pin | RW | Low/Low | Enable | 1 |
| Bit 1 | | | Reserved | | | | 1 |
| Bit 0 | 35/36 | DIF_6_En | Output Control - '0' overrides OE# pin | RW | Low/Low | Enable | 1 |

SMBusTable: Reserved Register

| Byte 3 | Pin # | Name | Control Function | Type | 0 | 1 | Default |
|--------|-------|------|------------------|------|---|---|---------|
| Bit 7 | | | Reserved | | | | 0 |
| Bit 6 | | | Reserved | | | | 0 |
| Bit 5 | | | Reserved | | | | 0 |
| Bit 4 | | | Reserved | | | | 0 |
| Bit 3 | | | Reserved | | | | 0 |
| Bit 2 | | | Reserved | | | | 0 |
| Bit 1 | | | Reserved | | | | 0 |
| Bit 0 | | | Reserved | | | | 0 |

SMBusTable: Reserved Register

| Byte 4 | Pin # | Name | Control Function | Type | 0 | 1 | Default |
|--------|-------|------|------------------|------|---|---|---------|
| Bit 7 | | | Reserved | | | | 0 |
| Bit 6 | | | Reserved | | | | 0 |
| Bit 5 | | | Reserved | | | | 0 |
| Bit 4 | | | Reserved | | | | 0 |
| Bit 3 | | | Reserved | | | | 0 |
| Bit 2 | | | Reserved | | | | 0 |
| Bit 1 | | | Reserved | | | | 0 |
| Bit 0 | | | Reserved | | | | 0 |

SMBusTable: Vendor & Revision ID Register

| Byte 5 | Pin # | Name | Control Function | Type | 0 | 1 | Default |
|--------|-------|------|------------------|------|--------------|---|---------|
| Bit 7 | - | RID3 | REVISION ID | R | A rev = 0000 | | X |
| Bit 6 | - | RID2 | | R | | | X |
| Bit 5 | - | RID1 | | R | | | X |
| Bit 4 | - | RID0 | | R | | | X |
| Bit 3 | - | VID3 | VENDOR ID | R | - | - | 0 |
| Bit 2 | - | VID2 | | R | - | - | 0 |
| Bit 1 | - | VID1 | | R | - | - | 0 |
| Bit 0 | - | VID0 | | R | - | - | 1 |

SMBusTable: DEVICE ID

| Byte 6 | Pin # | Name | Control Function | Type | 0 | 1 | Default |
|--------|-------|-------------------|------------------|------|----------------------------------|---|---------|
| Bit 7 | - | Device ID 7 (MSB) | | R | 0851 is 184 Decimal or 8B Hex | | 1 |
| Bit 6 | - | Device ID 6 | | R | | | 0 |
| Bit 5 | - | Device ID 5 | | R | | | 0 |
| Bit 4 | - | Device ID 4 | | R | | | 0 |
| Bit 3 | - | Device ID 3 | | R | | | 1 |
| Bit 2 | - | Device ID 2 | | R | | | 0 |
| Bit 1 | - | Device ID 1 | | R | | | 1 |
| Bit 0 | - | Device ID 0 | | R | | | 1 |

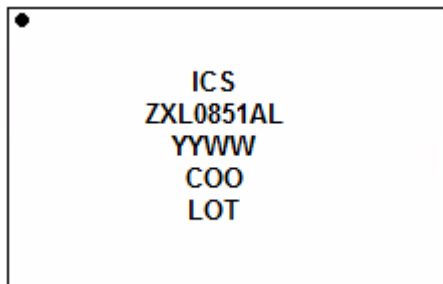
SMBusTable: Byte Count Register

| Byte 7 | Pin # | Name | Control Function | Type | 0 | 1 | Default |
|--------|-------|------|---|------|---|---|---------|
| Bit 7 | | | Reserved | | | | 0 |
| Bit 6 | | | Reserved | | | | 0 |
| Bit 5 | | | Reserved | | | | 0 |
| Bit 4 | - | BC4 | Writing to this register configures how many bytes will be read back. | RW | Default value is 8 hex, so 9 bytes (0 to 8) will be read back by default. | | 0 |
| Bit 3 | - | BC3 | | RW | | | 1 |
| Bit 2 | - | BC2 | | RW | | | 0 |
| Bit 1 | - | BC1 | | RW | | | 0 |
| Bit 0 | - | BC0 | | RW | | | 0 |

SMBusTable: Reserved Register

| Byte 8 | Pin # | Name | Control Function | Type | 0 | 1 | Default |
|--------|-------|------|------------------|------|---|---|---------|
| Bit 7 | | | Reserved | | | | 0 |
| Bit 6 | | | Reserved | | | | 0 |
| Bit 5 | | | Reserved | | | | 0 |
| Bit 4 | | | Reserved | | | | 0 |
| Bit 3 | | | Reserved | | | | 0 |
| Bit 2 | | | Reserved | | | | 0 |
| Bit 1 | | | Reserved | | | | 0 |
| Bit 0 | | | Reserved | | | | 0 |

Marking Diagram



- Line 2: truncated part number.
 - “L” denotes RoHS compliant package.
- Line 3: “YYWW” is the last two digits of the year and week that the part was assembled.
- Line 4: “COO” denotes country of origin.
- Line 5: “LOT” denotes the lot number.

Package Outline Drawings

The package outline drawings are appended at the end of this document and accessible from the link below. The package information is the most current data available.

www.renesas.com/us/en/document/psc/package-outline-drawing-package-code-ndg48p1-48-vfqfpn-60-x-60-x-09-mm-bod-y-04-mm

Ordering Information

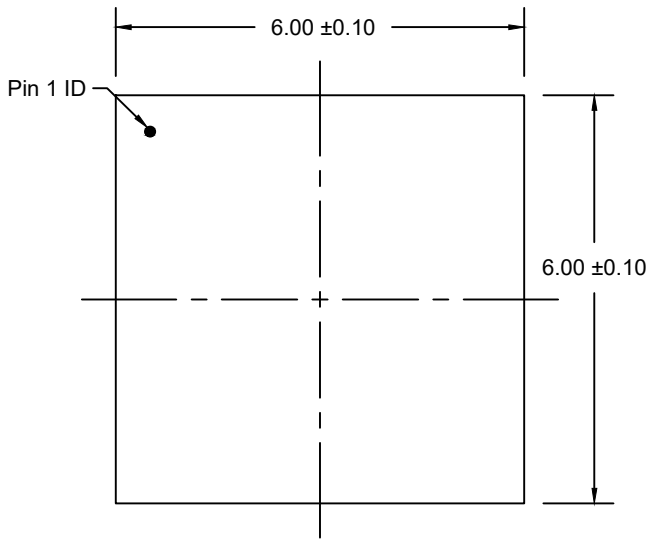
| Part / Order Number | Shipping Package | Package | Temperature |
|---------------------|------------------|-----------|-------------|
| 9ZXL0851AKLF | Trays | 48-VFQFPN | 0 to +70°C |
| 9ZXL0851AKLFT | Tape and Reel | 48-VFQFPN | 0 to +70°C |

“LF” suffix to the part number are the Pb-Free configuration and are RoHS compliant.

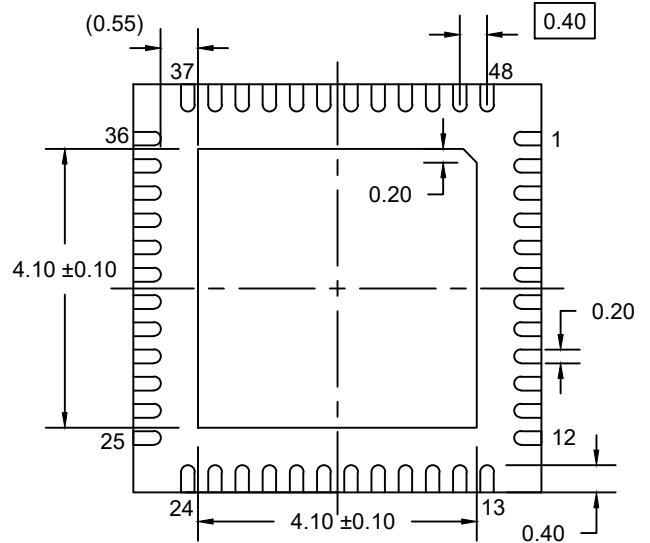
“A” is the device revision designator (will not correlate with the datasheet revision).

Revision History

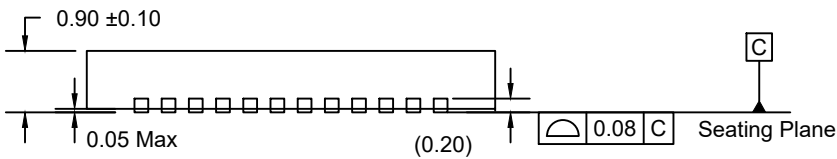
| Revision Date | Description |
|-------------------|--|
| March 28, 2013 | Initial release |
| November 20, 2015 | 1. Updated QPI references to QPI/UPI 2. Updated DIF_IN table to match PCI SIG specification, no silicon change |
| March 10, 2021 | 1. Updated input frequency minimum values from 33MHz to 25MHz. 2. Added "25MHz PFT clock delay management" bullet to Features section on cover page. 3. Reformatted headers and footers to Renesas. 4. Updated Marking Diagram and Package Outline Drawings sections. |
| February 6, 2023 | Updated POD link. |



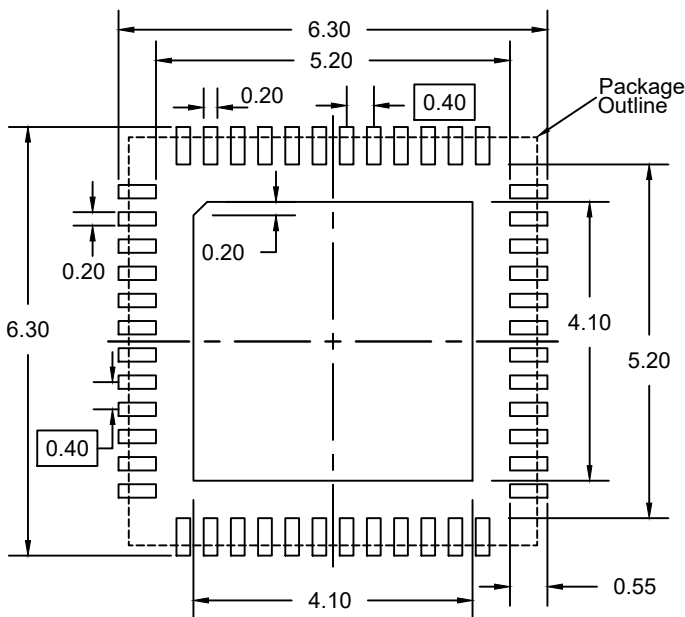
TOP VIEW



BOTTOM VIEW



SIDE VIEW



RECOMMENDED LAND PATTERN
(PCB Top View, NSMD Design)

NOTES:

1. JEDEC compatible.
2. All dimensions are in mm and angles are in degrees.
3. Use ± 0.50 mm for the non-toleranced dimensions.
4. Numbers in () are for references only.

IMPORTANT NOTICE AND DISCLAIMER

RENESAS ELECTRONICS CORPORATION AND ITS SUBSIDIARIES (“RENESAS”) PROVIDES TECHNICAL SPECIFICATIONS AND RELIABILITY DATA (INCLUDING DATASHEETS), DESIGN RESOURCES (INCLUDING REFERENCE DESIGNS), APPLICATION OR OTHER DESIGN ADVICE, WEB TOOLS, SAFETY INFORMATION, AND OTHER RESOURCES “AS IS” AND WITH ALL FAULTS, AND DISCLAIMS ALL WARRANTIES, EXPRESS OR IMPLIED, INCLUDING, WITHOUT LIMITATION, ANY IMPLIED WARRANTIES OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE, OR NON-INFRINGEMENT OF THIRD PARTY INTELLECTUAL PROPERTY RIGHTS.

These resources are intended for developers skilled in the art designing with Renesas products. You are solely responsible for (1) selecting the appropriate products for your application, (2) designing, validating, and testing your application, and (3) ensuring your application meets applicable standards, and any other safety, security, or other requirements. These resources are subject to change without notice. Renesas grants you permission to use these resources only for development of an application that uses Renesas products. Other reproduction or use of these resources is strictly prohibited. No license is granted to any other Renesas intellectual property or to any third party intellectual property. Renesas disclaims responsibility for, and you will fully indemnify Renesas and its representatives against, any claims, damages, costs, losses, or liabilities arising out of your use of these resources. Renesas' products are provided only subject to Renesas' Terms and Conditions of Sale or other applicable terms agreed to in writing. No use of any Renesas resources expands or otherwise alters any applicable warranties or warranty disclaimers for these products.

(Disclaimer Rev.1.0 Mar 2020)

Corporate Headquarters

TOYOSU FORESIA, 3-2-24 Toyosu,
Koto-ku, Tokyo 135-0061, Japan
www.renesas.com

Contact Information

For further information on a product, technology, the most up-to-date version of a document, or your nearest sales office, please visit:
www.renesas.com/contact/

Trademarks

Renesas and the Renesas logo are trademarks of Renesas Electronics Corporation. All trademarks and registered trademarks are the property of their respective owners.