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# H8SX Family

# Using a Timer-Generated Clock Signal to Drive SCI Transmission and Reception: Interrupt Volume

## Introduction

Compare-match output from 8-bit timer unit 2 is selectable as the clock source for asynchronous mode transfer on serial communications interfaces 5 and 6 (SCI\_5, 6) of the H8SX/1653. In this sample task, data are transmitted and received at 375 kbps when a peripheral clock signal ( $P\phi$ ) running at 16 MHz is input to the timer clock.

## **Target Device**

H8SX/1638, H8SX/1648, H8SX/1653, H8SX/1658R, H8SX/1663, H8SX/1668R Groups

## Preface

Although the writing of this application note is in accord with the hardware manual for the H8SX/1653 Group, the program covered in this application note can be run on the target devices indicated above. However, since some functional modules may be changed for the addition of functionality etc., be sure to perform a thorough evaluation by confirming the details with the hardware manual for the target device.

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## 1. Specifications

Compare-match output of 8-bit timer unit 2 is selectable as the clock source for asynchronous mode transfer over SCI\_5 and SCI\_6 of the H8SX/1653. In this sample task, the timer compare-match output is selected as the base clock for SCI\_5, and data are transmitted and received at 375 kbps with  $P\phi$  running at 16 MHz.

- Figure 1 shows the connections for this sample task.
- Table 1 shows the communications format
- After a power-on reset is applied to the master device, a low-level trigger pulse is output via P13 on the same side, and operations for the simultaneous transmission and reception of 128-byte blocks of data by the master start.
- When the low trigger pulse is input from the master device to the IRQ3 pin on the slave device, the slave starts operations for the simultaneous transmission and reception of 128-byte blocks of data.
- In this sample task, the asynchronous transmission and reception of 128-byte blocks of data is handled by interruptactivated DMAC operation.

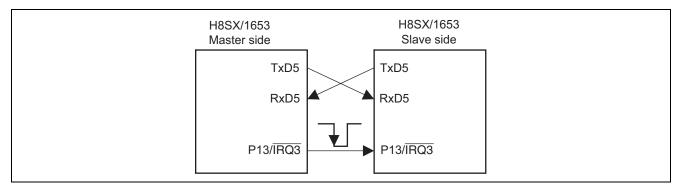


Figure 1 Setup for Asynchronous Communications with Timing from the Timer Clock Input

#### Table 1 Asynchronous Serial Transmission and Reception Format

Format	Setting	
Ρφ	16 MHz	
Serial communications mode	Asynchronous	
Clock source	Timer compare-match output	
Transfer rate	375 kbps	
Data length	8 bits	
Parity bit	None	
Stop bit	1 bit	
Serial/parallel conversion format	LSB first	



## 2. Applicable Conditions

## Table 2 Applicable Conditions

Item	Setting		
Operating frequency	Input clock:	16 MHz	
	System clock:	16 MHz	
	Peripheral module clock (Pø):	16 MHz	
	External bus clock (Bø):	16 MHz	
Operating mode	Mode 6 (MD2 = 1, MD1 = 1, M	D0 = 0)	
	$MD\_CLK = 0$		
Development tool	High-performance Embedded	Workshop Ver. 4.00.02	
C/C++ compiler	From Renesas Technology Corp.		
	H8S, H8/300 Series C/C++ Co	mpiler Ver. 6.01.00	
Compiler options	-cpu = h8sxa:24:md, -code = machinecode, -optimize = 1, -regpar		
	-speed = (register, shift, struct,	expression)	

## Table 3 Section Settings

Address	Section Name	Description
H'001000	Р	Program area
	С	Data table storage
H'FF2000 B		Non-initialized data area (RAM area)



## 3. Description of Modules Used

## 3.1 SCI\_5

In this sample task, SCI\_5 is used for asynchronous serial data transmission. Figure 2 is a block diagram of SCI\_5, and the following is a description of the functions in the diagram.

- Receive Shift Register (RSR\_5)

This register is used to receive serial data. Serial data on RSR\_5 are input via the RxD5 pin. When one frame of data has been received, the data bits are automatically transferred to the Receive Data Register (RDR\_5). RSR\_5 is not accessible by the CPU.

• Receive Data Register (RDR\_5)

Received data are stored in this 8-bit register. After RSR\_5 has received one frame, the data bits are automatically transferred from RSR\_5 to RDR\_5. Since RSR\_5 and RDR\_5 function as a double buffer, continuous reception is possible. RDR\_5 is for reception only, and so is seen as a read-only register by the CPU.

- Transmit Shift Register (TSR\_5) This register is used to transmit serial data. In transmission, data are transferred from the Transmit Data Register (TDR\_5) to TSR\_5, and then output on the TxD5 pin. TSR\_5 is not directly accessible from the CPU.
- Transmit Data Register (TDR\_5)

Data for transmission are stored in this 8-bit register. When SCI\_5 detects that TDR\_5 is empty, data that have been written to TDR\_5 are automatically transferred to TSR\_5. Since TDR\_5 and TSR\_5 function as a double buffer, if the next byte is written to TDR\_5 before transmission of the frame including the byte currently in TSR\_5 is complete, the byte can be transferred to TSR\_5 immediately on completion of the transmission. This allows continual transmission. Although TDR can be read from or written to by the CPU at all times, only write data for transmission data after having confirmed setting of the TDRE bit in the Serial Status Register (SSR\_5) to 1.

- Serial Mode Register (SMR\_5) This 8-bit register is used to select the format of serial data communications and the clock source for the on-chip baud-rate generator.
- Serial Control Register (SCR\_5) This register is used to control transmission, reception, and interrupts, and to select the clock source for transmission and reception.
- Serial Status Register (SSR\_5) This register consists of status flags for SCI\_5 and multiprocessor bits for transmission and reception. TDRE, RDRF, ORER, PER, and FER can only be cleared.
- Smart Card Mode Register (SCMR\_5) This register is used to select the smart-card or normal interface mode for SCMR\_5, and to set up the format for the smart-card mode. For this task, the setting in SCMR\_5 selects the normal asynchronous or clock synchronous mode.
- Serial Extended Mode Register (SEMR\_5)

SEMR\_5 and SEMR\_6 are used to select the clock source for SCI\_5 and SCI\_6 in the asynchronous mode. The base (peripheral) clock is automatically specified when average transfer rate operation is selected. TMO output from timer units 2 and 3 can also be set as the base clock for serial transfer. Otherwise, specific average transfer rates are selectable according to whether the peripheral-clock frequency is 8, 10.667, 12, 16, 24, or 32 MHz. Table 4 shows the relationship between  $P\phi$  and average transfer rate.



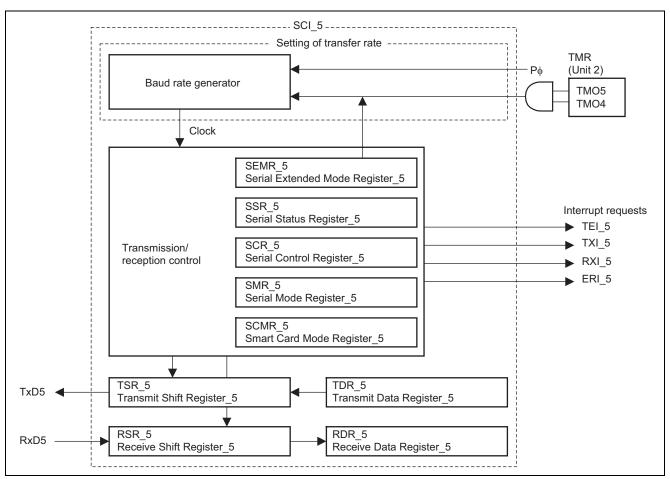


Figure 2 Block Diagram of SCI\_5



## 3.2 Timer Unit 2

In this sample task, the clock source for SCI\_5 is generated from logic values output by timer unit 2 (TMR\_4 and TMR\_5). Figure 3 is a block diagram of timer unit 2 and the following is a description of the functions in the diagram.

- Internal peripheral clock Pφ
   This is the standard operating clock for the internal peripheral functions and is generated by using the clock oscillator.
- Timer counter\_4 (TCNT\_4)
- Timer counter\_5 (TCNT\_5)

Each TCNT is an 8-bit readable/writable register. Bits CKS2 to CKS0 in TCR and bits ICKS1 and ICKS0 in TCCR are used to select the clock signal to drive counting. Clearing of a TCNT register by an external reset input signal, compare match A signal, or compare match B signal is selectable by bits CCLR1 and CCLR0 in the corresponding TCR. The initial value of these registers is H'00.

- Time constant register A\_4 (TCORA\_4)
- Time constant register A\_5 (TCORA\_5) Each TCORA is an 8-bit readable/writable register. The value in TCORA is continually compared with the value in the corresponding TCNT. When a match is detected, the CMFA flag in the corresponding TCSR is set to 1. The settings of bits OS1 and OS0 in TCSR select whether and what kind of timer output is produced on the TMO terminal by this compare-match signal (compare match A). The initial value of these registers is H'FF.
- Time constant register B\_4 (TCORB\_4)
- Time constant register B\_5 (TCORB\_5) Each TCORB is an 8-bit readable/writable register. TCORB is continually compared with the value in the corresponding TCNT. When a match is detected, the CMFB flag in the corresponding TCSR is set to 1. The settings of bits OS3 and OS2 in TCSR select whether and what kind of timer output is produced on the TMO terminal by this compare-match signal (compare match A). The initial value of these registers is H'FF.
- Timer control register\_4 (TCR\_4)
- Timer control register\_5 (TCR\_5) Each TCR selects the TCNT clock source and the condition for clearing the corresponding TCNT, and enables/disables interrupt requests.
- Timer counter control register\_4 (TCCR\_4)
- Timer counter control register\_5 (TCCR\_5) Each TCCR selects the TCNT internal clock source and controls sensing of external resets.
- Timer control/status register\_4 (TCSR\_4)
- Timer control/status register\_5 (TCSR\_5) Each TCSR contains status flags, and controls compare match output.



#### H8SX Family Using a Timer-Generated Clock Signal to Drive SCI Transmission and Reception: Interrupt Volume

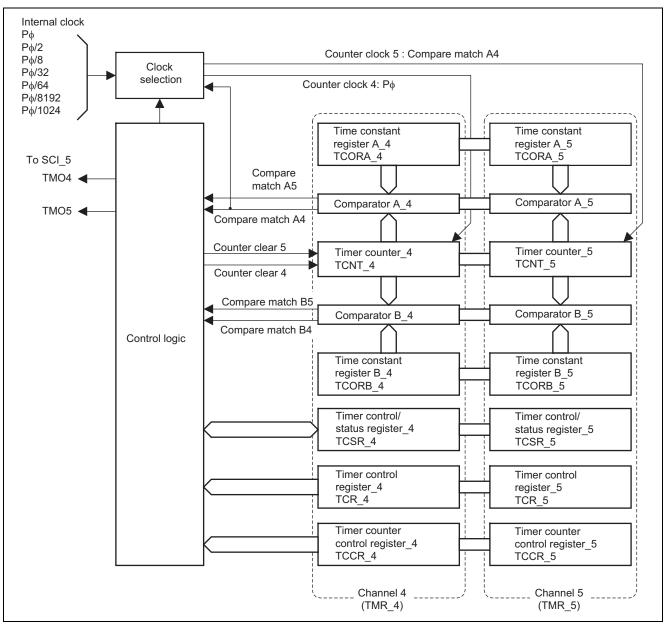


Figure 3 Block Diagram of Timer Unit 2



## 4. Description of Operation

## 4.1 Outline

An outline of operation for this sample task is given in figure 4. 128-byte blocks of data are simultaneously transferred in both directions between the master and slave sides.

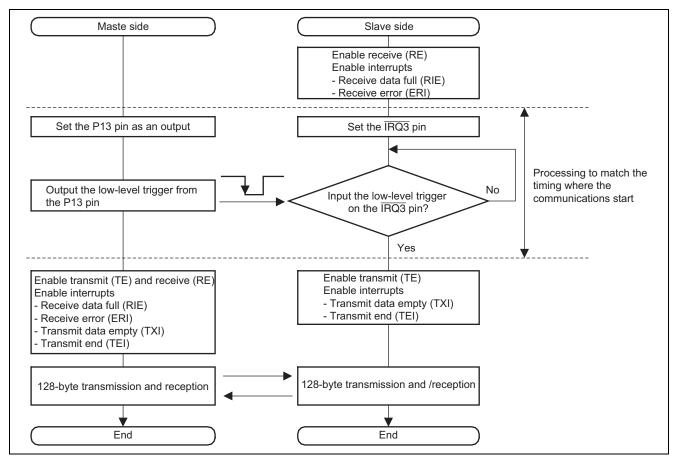


Figure 4 Outline of Operation



## 4.2 Transmission

The timing of transmission operations is illustrated in figure 5. Table 4 is a list of the hardware and software processing at the numbered points in figure 5.

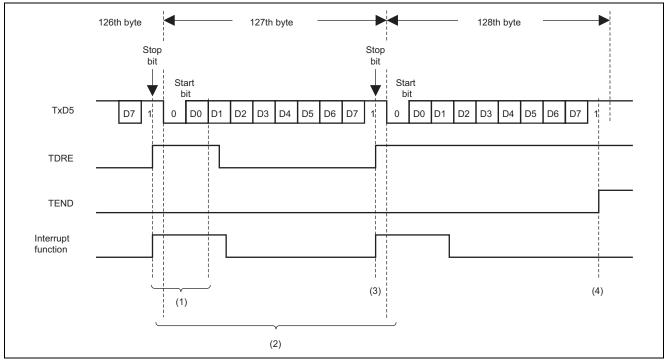


Figure 5 Timing of Transmission

	Hardware Processing	Software Processing
(1)	a. Set TDRE to 1.	TXI interrupt processing
		<ul> <li>a. Write data for transmission to TDR_5.</li> </ul>
		b. Clear TDRE to 0.
(2)	a. Transfer the contents of TDR_5 to TSR_4.	No processing
	b. Output the contents of TSR_5 on the TxD5 pin	
(3)	a. Set TDRE to 1.	TXI interrupt processing
		<ul> <li>a. Write data for transmission to TDR_5.</li> </ul>
		b. Clear TDRE to 0.
		c. Disable TXI interrupts.
(4)	a. Set TDRE to 1.	TEI interrupt processing
	b. Set TEND to 1.	a. Clear TEND to 0.
		b. Clear TE to 0.
		c. Disable TEI interrupts.

#### Table 4 Processing



## 4.3 Reception

The timing of reception operations is illustrated in figure 6. Table 5 is a list of the hardware and software processing at the numbered points in figure 6.

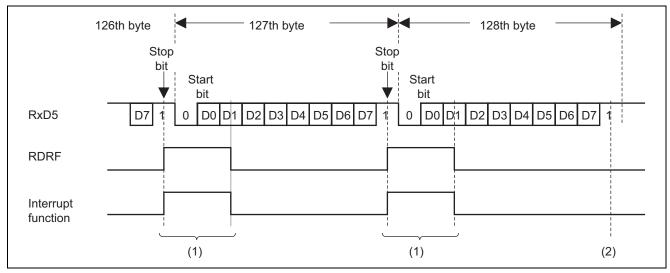


Figure 6 Timing of Reception

#### Table 5 Processing

	Hardware Processing	Software Processing
(1)	<ul><li>a. Set RDRF to 1.</li><li>b. Each time a byte is successfully received in RSR_5, transfer it to RDR_5.</li></ul>	RXI interrupt processing a. Read received data from RDR_5. b. Clear RDRF to 0.
(2)	<ul> <li>a. Set RDRF to 1.</li> <li>b. Each time a byte is successfully received in RSR_5, transfer it to RDR_5.</li> </ul>	RXI interrupt processing a. Read received data from RDR_5. b. Clear RDRF to 0. c. Clear RE to 0. d. Disable RXI and ERI interrupts.



## 4.4 Internal Base Clock Settings for SCK5

An internal 6-MHz base clock is derived from the 16-MHz peripheral clock signal ( $P\phi$ ) and then used to produce an average transfer rate of 375 kbps. The procedure is described below.

- 1. TMR4 Settings
  - Output of an 8-MHz signal as a base clock on TMO4 (refer to figure 7)
  - a. To select incrementation of TCNT\_4 on rising edges of P\$, set CKS2 to CKS0 in TCR\_4 to B'011, and ICKS1 and ICKS0 in TCCR\_4 to B'10.
  - b. Select clearing of TCNT\_4 on matches with TCORA\_4 by setting CCLR1 in TCR\_4 to 0 = B'01.
  - c. To select the output of a 0 on matches with TCORA\_4 and of a 1 on matches with TCORB\_4, set bits OS3 to OS0 in TCSR\_4 to B'1001.
  - d. Set  $TCORA_4 = 1$  and  $TCORB_4 = 0$  to obtain an 8-MHz base clock signal on TMO4.

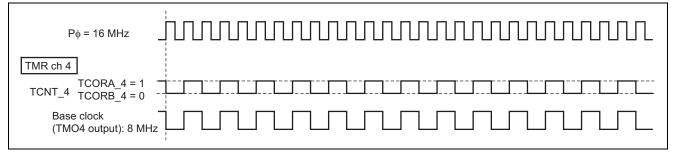


Figure 7 Deriving the Output Waveform on TMO4

#### 2. TMR5 Settings

Output of a clock-enable signal with a duty cycle of 3/4 on TMO5 (refer to figure 8)

- a. To select incrementation of TCNT\_5 on matches of TCNT4 with TCORA\_4 (compare match A), set CKS2 to CKS0 in TCR\_5 to B'100.
- b. To select clearing of TCNT\_5 on matches with TCORA\_5, set bit field CCLR1, 0 in TCR\_5 to B'01.
- c. To select the output of a 0 on matches with TCORA\_5 and of a 1 on matches with TCORB\_5, set bits OS3 to OS0 in TCSR\_5 to B'1001.
- d. When TCORA\_5 = 3 and TCORB\_5 = 0, a clock-enable signal with a duty cycle of 3/4 is output on TMO5.

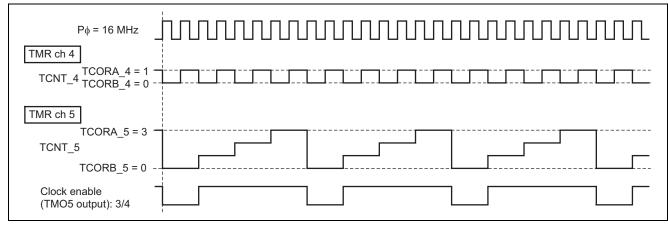


Figure 8 Deriving the Output Waveform on TMO5



3. Internal base clock of SCK5 and average transfer rate

The logical AND of outputs TMO4 and TMO5 provides the internal base-clock (6-MHz) signal for SCK5. Derivation of this waveform is illustrated in figure 9.

When the ABCS bit in SEMR\_5 is 0, one bit of data is transferred every 16 cycles of the internal base clock. This leads to an average transfer rate of 375 kbps, as given by the formula below.

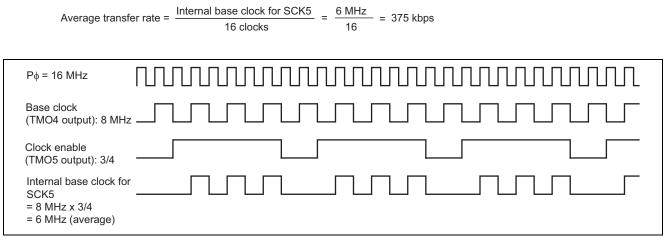
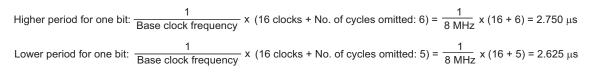


Figure 9 Deriving the Internal Base-Clock Waveform for SCK5

## 4.5 One-bit Period for Communications Data

The one-bit period in this sample task will vary according to the number of base-clock cycles omitted from the bit period. This will be either five or six, so the one-bit period is given by the corresponding formula below.



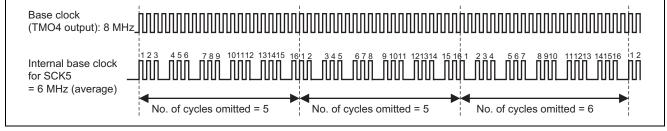


Figure 10 One-Bit Periods for Data Transfer



## 5. Description of Software

## 5.1 List of Functions

Table 6 lists the functions used in this sample task. Figure 11 shows the structure of hierarchy.

#### Table 6List of Functions

Function Name	Description
init	Initialization routine
	Takes the module out of module stopped mode, performs clock settings, and calls the main function
main	Main routine
	Makes initial SCI settings for communications at the transfer rate of 921.569 kbps when operating at $P\phi = 16$ MHz.
rxi5_int	Receive Data Full Interrupt
	Stores the data received from RDR_5 in RAM.
txi5_int	Transmit Data Empty Interrupt
	Gets the data for transmission from RAM, writes the data to TDR_5, and executes transmission.
eri5_int	Receive error interrupt handler
	In cases of error in reception, writes the contents of SSR_5 to RAM and then initializes SSR_5
tei5_int	Transmission end interrupt handler
	Disables TEI interrupt requests. Sets endflg to 1.

init	]	main		
rxi5_int	1			
	1			
txi5_int	]			
eri5_int	]			
tei5_int	]			

Figure 11 Structure of Hierarchy



## 5.2 Vector Table

#### Table 7 Exception Handling Vector Table

Exception Handling Source	Vector Number	Vector Table Address	Vector Table Address Handling Function
Reset	0	H'00000	init
SCI_5 RXI5	220	H'000370	rxi5_init
SCI_5 TXI5	221	H'000374	txi5_init
SCI_5 ERI5	222	H'000378	eri5_init
SCI_5 TEI5	223	H'00037C	tei5_init

## 5.3 RAM Usage

#### Table 8 RAM Usage

Variable	Description	
Name	Description	Used in
endflg	Transmission end flag	main, tei5_int
	0: Transmission in progress	
	1: Transmission ended	
errbuf	Reception error buffer	main, eri5_int
	The contents of SSR_5 are stored here when an	
	overrun, framing, or parity error occurs.	
tcnt	Transmission counter	main, txi5_int
rcnt	Reception counter	main, rxi5_int
rcv_dt[128]	RAM area for storing received data	main, rxi5_int
	Name endflg errbuf tcnt rcnt	Name         Description           endflg         Transmission end flag 0: Transmission in progress 1: Transmission ended           errbuf         Reception error buffer The contents of SSR_5 are stored here when an overrun, framing, or parity error occurs.           tcnt         Transmission counter           rcnt         Reception counter

## 5.4 Data Table

Table 9	Data	Table
---------	------	-------

	Array		
Туре	Name	Description	Used in
unsigned char	trs_dt[128]	ROM area where data for transmission are stored	main, txi5_int
		128 bytes of data: H'00, H'01,, H'7F	

## 5.5 Macro Definitions

.

#### Table 10 Macro Definitions

Identifier	Description	Used in
MASTER	If this is defined, compilation generates the master-side program.	main
SLAVE	If this is defined, compilation generates the slave-side program.	main



## 5.6 Description of Functions

#### 5.6.1 init Function

1. Overview

Initialization routine: Takes the module out of module stop mode, sets the clock, and calls the main function.

- 2. Arguments None
- 3. Return value None
- 4. Description of internal register usage

Usage of internal registers in this task is described below. The given settings are those used in the task and differ from the initial settings.

#### • System clock control register (SCKCR) Address: H'FFFDC4

	Bit			
Bit	Name	Setting	R/W	Description
10	ICK2	0	R/W	System Clock (I
9	ICK1	1	R/W	Selects the frequency of the CPU, DMAC, and DTC module and
8	ICK0	0	R/W	system clock.
				010: Input clock x 1
6	PCK2	0	R/W	Peripheral Module Clock (P
5	PCK1	1	R/W	Selects the frequency of the peripheral module clock.
4	PCK0	0	R/W	010: Input clock x 1
2	BCK2	0	R/W	External Bus Clock (B) Select
1	BCK1	1	R/W	Selects the frequency of the external bus clock.
0	BCK0	0	R/W	010: Input clock x 1

• Registers MSTPCRA, MSTPCRB, and STPCRC control the module stop mode. Setting a bit to 1 makes the corresponding module enter the module stop mode, while clearing the same bit to 0 takes the module out of stop mode.

#### • Module stop control register A (MSTPCRA) Address: H'FFFDC8

	Bit			
Bit	Name	Setting	R/W	Description
15	ACSE	0	R/W	All-Module-Clock-Stop Mode Enable
				Enables/disables all-module-clock-stop mode for reducing current
				drawn by stopping the bus controller and I/O port operations when
				the CPU executes the SLEEP instruction after the module stop mode has been set for all of the on-chip peripheral modules
				controlled by MSTPCR.
				0: All-module-clock-stop mode disabled
				1: All-module-clock-stop mode enabled
13	MSTPA13	0	R/W	DMA controller (DMAC)
12	MSTPA12	1	R/W	Data transfer controller (DTC)
9	MSTPA9	1	R/W	8-bit timers (TMR_3, TMR_2)
8	MSTPA8	1	R/W	8-bit timers (TMR_1, TMR_0)
5	MSTPA5	1	R/W	D/A converter (channel 1, channel 0)
3	MSTPA3	1	R/W	A/D converter (unit 0)
0	MSTPA0	1	R/W	16-bit timer pulse unit (TPU channels 5 to 0)

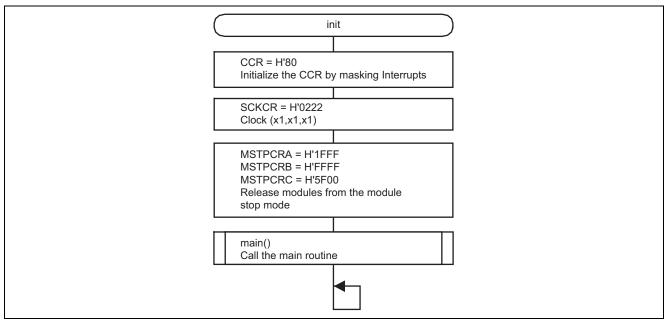


#### • Module stop control register B (MSTPCRB) Address: H'FFFDCA

	Bit			
Bit	Name	Setting	R/W	Description
15	MSTPB15	1	R/W	Programmable pulse generator (PPG)
12	MSTPB12	1	R/W	Serial communications interface_4 (SCI_4)
10	MSTPB10	1	R/W	Serial communications interface_2 (SCI_2)
9	MSTPB9	1	R/W	Serial communications interface_1 (SCI_1)
8	MSTPB8	1	R/W	Serial communications interface_0 (SCI_0)
7	MSTPB7	1	R/W	I <sup>2</sup> C bus interface_1 (IIC_1)
6	MSTPB6	1	R/W	I <sup>2</sup> C bus interface_0 (IIC_0)

• Module stop control register C (MSTPCRC) Address: H'FFFDCC

	Bit			
Bit	Name	Setting	R/W	Description
15	MSTPC15	0	R/W	Serial communications interface _5 (SCI_5), (IrDA)
14	MSTPC14	1	R/W	Serial communications interface _6 (SCI_6)
13	MSTPC13	0	R/W	8-bit timers (TMR_4, TMR_5)
12	MSTPC12	1	R/W	8-bit timers (TMR_6, TMR_7)
11	MSTPC11	1	R/W	Universal serial bus interface (USB)
10	MSTPC10	1	R/W	Cyclic redundancy checker
4	MSTPC4	0	R/W	On-chip RAM_4 (H'FF2000 to H'FF3FFF)
3	MSTPC3	0	R/W	On-chip RAM _3 (H'FF4000 toH'FF5FFF)
2	MSTPC2	0	R/W	On-chip RAM _2 (H'FF6000 to H'FF7FFF)
1	MSTPC1	0	R/W	On-chip RAM _1 (H'FF8000 to H'FF9FFF)
0	MSTPC0	0	R/W	On-chip RAM _0 (H'FFA000 to H'FFBFFF)





## 5.6.2 main Function

#### 1. Overview

Main routine: Sets the timer clock input and SCI, calls functions DMAC0\_trs\_init and DMAC1\_rcv\_init, and transmits and receives a total of 256 bytes of data.

- 2. Arguments None
- 3. Return value None
- Description of internal register usage Usage of internal registers in this task is described below. The given settings are those used in the task and differ from the initial settings.

#### • Port 1 data direction register (P1DDR) Address: H'FFFB80

	Bit			
Bit	Name	Setting	R/W	Description
3	P13DDR	1	W	0: Pin P13 is an input.
				1: Pin P13 is an output.

#### • Port 1 input buffer control register (P1ICR) Address: H'FFFB90

	Bit			
Bit	Name	Setting	R/W	Description
5	P15ICR	1	R/W	<ol> <li>P15 pin input buffer is disabled. Input signal is fixed to the high level.</li> </ol>
				<ol> <li>P15 pin input buffer is valid. The pin state reflects the peripheral modules.</li> </ol>
3	P13ICR	1	R/W	<ol> <li>P13 pin input buffer is disabled. Input signal is fixed to the high level.</li> </ol>
				<ol> <li>P15 pin input buffer is valid. The pin state reflects the peripheral modules.</li> </ol>

#### • Port function control register C (PFCRC) Address: H'FFFBCC

	Bit			
Bit	Name	Setting	R/W	Description
3	ITS3	1	R/W	IRQ3 Pin Selection
				0: Selects IRQ3-A input on pin P13
				1: Selects IRQ3-B input on pin P53

#### • IRQ sense control register L (ISCRL) Address: H'FFFD6A

Bit	Bit Name	Setting	R/W	Description
7	IRQ3SR	0	R/W	IRQ3 Sense Control Rise
6	IRQ3SF	1	R/W	IRQ3 Sense Control Fall
				01: Interrupt requests are sensed on falling edges of the IRQ3 input



#### • Timer control register\_4 (TCR\_4) Address: H'FFEA40

	Bit			
Bit	Name	Setting	R/W	Description
4	CCLR1	0	R/W	Counter Clear 1, 0
3	CCLR0	1	R/W	01: TCNT_4 is cleared on matches with TCORA_4.
2	CKS2	0	R/W	Clock Select 2 to 0
1	CKS1	1	R/W	Refer to table 11.
0	CKS0	1	R/W	011, ICKS 1, 0 = B'10: Counting of rising edges of $P\phi$

#### • Timer control register\_5 (TCR\_5) Address: H'FFEA41

	Bit			
Bit	Name	Setting	R/W	Description
4	CCLR1	0	R/W	Counter Clear 1, 0
3	CCLR0	1	R/W	01: TCNT_5 is cleared on matches with TCORA_5.
2	CKS2	1	R/W	Clock Select 2 to 0
1	CKS1	0	R/W	Refer to table 11.
0	CKS0	0	R/W	100: Counting is driven by matches with TCORA_5 (compare match A).

#### • Timer control/status register\_4 (TCSR\_4) Address: H'FFEA42

	Bit	•		
Bit	Name	Setting	R/W	Description
3	OS3	1	R/W	Output Select 3, 2
2	OS2	0	R/W	Selects how a match between TCORB_4 and TCNT_4 affects the output on the TMO_4 terminal. 10: 1 output
1	OS1	0	R/W	Output Select 1, 0
0	OS0	1	R/W	Selects how a match between TCORA_4 and TCNT_4 affects the output on the TMO_4 terminal. 01: 0 output

#### • Timer control/status register\_5 (TCSR\_5) Address: H'FFEA43

Bit	Bit Name	Setting	R/W	Description
3	OS3	1	R/W	Output Select 3, 2
2	OS2	0	R/W	Selects how a match between TCORB_5 and TCNT_5 affects the output on the TMO_5 terminal. 10: 1 output
1	OS1	0	R/W	Output Select 1, 0
0	OS0	1	R/W	Selects how a match between TCORA_5 and TCNT_5 (compare match A) affects the output on the TMO_5 terminal. 01: 0 output



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Timer constant register A\_4 (TCORA\_4) Address: H'FFEA44

		This is an 8-bit readable/writable register. Its value is continually compared with that in TCNT_4. When a match is detected, the CMFA flag in TCSR_4 is set to 1.
	Setting:	H'01
	Function:	<b>nstant register A_5 (TCORA_5)</b> Address: H'FFEA45 This is an 8-bit readable/writable register. Its value is continually compared with that in TCNT_5. When a match is detected, the CMFA flag in TCSR_5 is set to 1. H'03
•	Function:	<b>nstant register B_4 (TCORB_4)</b> Address: H'FFEA46 This is an 8-bit readable/writable register. Its value is continually compared with that in TCNT_4. When a match is detected, the CMFB flag in TCSR_4 is set to 1. H'00
	Function:	<b>nstant register B_5 (TCORB_5)</b> Address: H'FFEA47 This is an 8-bit readable/writable register. Its value is continually compared with that in TCNT_5. When a match is detected, the CMFB flag in TCSR_5 is set to 1. H'00
	Function:	unter_4 (TCNT_4) Address: H'FFEA48 This is an 8-bit readable/writable register. In this sample task, this register is cleared by the compare match A signal from TMR_4. H'00
	Function:	unter_5 (TCNT_5) Address: H'FFEA49 This is an 8-bit readable/writable register. In this sample task, this register is cleared by the compare match A signal from TMR_5. H'00
	Timer co	unter control register_4 (TCCR_4) Address: H'FFEA4A

	Bit			
Bit	Name	Setting	R/W	Description
1	ICKS1	1	R/W	Internal Clock Select 1, 0
0	ICKS0	0	R/W	Refer to table 11.

## • Timer counter control register\_5 (TCCR\_5) Address: H'FFEA4B

	Bit			
Bit	Name	Setting	R/W	Description
1	ICKS1	1	R/W	Internal Clock Select 1, 0
0	ICKS0	0	R/W	Refer to table 11.



	TCR TCCR				CR	
	Bit 2	Bit 1	Bit 0	Bit 1	Bit 0	
Channel	CKS2	CKS1	CKS0	ICKS1	ICKS0	Description
TMR_4	0	0	0			Clock input prohibited
	0	0	1	0	0	The internal peripheral clock is used; counting is on rising edges of $P\phi/8$ .
				0	1	The internal peripheral clock is used; counting is on rising edges of $P\phi/2$ .
				1	0	The internal peripheral clock is used; counting is on falling edges of $P\phi/8$ .
				1	1	The internal peripheral clock is used; counting is on falling edges of $P\phi/2$ .
	0	1	0	0	0	The internal peripheral clock is used; counting is on rising edges of $P\phi/64$ .
				0	1	The internal peripheral clock is used; counting is on rising edges of $P\phi/32$ .
				1	0	The internal peripheral clock is used; counting is on falling edges of $P\phi/64$ .
				1	1	The internal peripheral clock is used; counting is on falling edges of $P\phi/32$ .
	0	1	1	0	0	The internal peripheral clock is used; counting is of rising edges of $P\phi/8192$ .
				0	1	The internal peripheral clock is used; counting is on rising edges of $P\phi/1024$ .
				1	0	The internal peripheral clock is used; counting is on falling edges of $P\phi/8192$ .
				1	1	The internal peripheral clock is used; counting is on falling edges of $P\phi/1024$ .
	1	0	0		_	Counting is on TCNT_5 overflow signals

#### Table 11 Clock Input for TCNT and Condition for Counting (Units 2 and 3)



		TCR		тс	CR	
	Bit 2	Bit 1	Bit 0	Bit 1	Bit 0	
Channel	CKS2	CKS1	CKS0	ICKS1	ICKS0	Description
TMR_5	0	0	0			Clock input prohibited
	0	0	1	0	0	The internal peripheral clock is used; counting is on rising edges of $P\phi/8$ .
				0	1	The internal peripheral clock is used; counting is on rising edges of $P\phi/2$ .
				1	0	The internal peripheral clock is used; counting is on falling edges of $P\phi/8$ .
				1	1	The internal peripheral clock is used; counting is on falling edges of $P\phi/2$ .
	0	1	0	0	0	The internal peripheral clock is used; counting is on rising edges of $P\phi/64$ .
				0	1	The internal peripheral clock is used; counting is on rising edges of $P\phi/32$ .
				1	0	The internal peripheral clock is used; counting is on falling edges of $P\phi/64$ .
				1	1	The internal peripheral clock is used; counting is on falling edges of $P\phi/32$ .
	0	1	1	0	0	The internal peripheral clock is used; counting is on rising edges of $P\phi/8192$ .
				0	1	The internal peripheral clock is used; counting is on rising edges of $P\phi/1024$ .
				1	0	The internal peripheral clock is used; counting is on falling edges of $P\phi/8192$ .
				1	1	The internal peripheral clock is used; counting is on falling edges of $P\phi/1024$ .
	1	0	0		_	Counting is on TCNT_4 compare match A events



• Serial mode register\_5 (SMR\_5) Address: H'FFF600

	Bit			
Bit	Name	Setting	R/W	Description
7	C/A	0	R/W	Communications Mode
				0: Asynchronous
				1: Clock synchronous
6	CHR	0	R/W	Character Length
				0: Selects 8 bits as the data length
				1: Selects 7 bits as the data length
5	PE	0	R/W	Parity Enable
				0: No parity bit
				1: Parity bit included
3	STOP	0	R/W	Stop Bit Length
				Selects the length of the stop-bit field in transmission.
				0: 1 stop bit
				1: 2 stop bits
				In reception, only the first of the stop bits is checked, and when the
				second stop bit is 0, it is treated as the start bit of the next frame to
				be transmitted.

• Serial control register\_5 (SCR\_5) Address: H'FFF602

Bit	Bit Name	Setting	R/W	Description
7	TIE	0	R/W	Transmit Interrupt Enable
				0: Disables TXI interrupts
				1: Enables TXI interrupts
6	RIE	0	R/W	Receive Interrupt Enable
				0: Disables RXI, ERI interrupts
				1: Enables RXI, ERI interrupts
5	TE	0	R/W	Transmit Enable
				0: Disables transmission
				1: Enables transmission
4	RE	0	R/W	Receive Enable
				0: Disables reception
				1: Enables reception
2	TEIE	0	R/W	Transmit End Interrupt Enable
				0: Disables TEI interrupts
				1: Enables TEI interrupts
1	CKE1	1	R/W	Clock Enable 1, 0
0	CKE0	Х	R/W	Select the clock source
				00: Internal baud rate generator
				1X: Timer clock input or average transfer rate generator

Legend

X: Don't care.



• Serial status register\_5 (SSR\_5) Address: H'FFF604

Bit	Bit Name	Setting	R/W	Description
7	TDRE	Undefined	R/(W)*	Transmit Data Register Empty Indicates whether TDR contains data for transmission [Setting conditions] • Clearing of the TE bit in SCR (to 0)
				<ul> <li>Transfer of data from TDR to TSR [Clearing conditions]</li> </ul>
				<ul> <li>Writing a 0 to TDRE after having read TDRE = 1</li> </ul>
				<ul> <li>Generation of a TXI interrupt request allowing its value DMAC to write data to TDR</li> </ul>
6	RDRF	0	R/(W)*	Receive Data Register Full Indicates whether RDR holds received data
				[Setting condition]
				<ul> <li>The normal end of serial reception and the transfer of received data from RSR to RDR</li> </ul>
				[Clearing conditions]
				<ul> <li>Writing of 0 to RDRF after having read RDRF = 1</li> </ul>
				<ul> <li>Generation of an RXI interrupt request allowing DMAC or DTC to read data from RDR</li> </ul>
				The RDRF flag is not affected and retains its previous value when the RE bit in SCR is cleared to 0. Note that if a next round of serial reception is completed while the RDRF flag remains set
	0050			to 1, an overrun error occurs and the received data are lost.
5	ORER	0	R/(W)*	Overrun Error [Setting condition]
				<ul> <li>Occurrence of an overrun error during reception</li> </ul>
				[Clearing condition]
				<ul> <li>Writing of 0 to ORER after having read ORER = 1</li> </ul>
4	FER	0	R/(W)*	Framing Error [Setting condition]
				Occurrence of a framing error during reception
				[Clearing condition]
				<ul> <li>Writing of 0 to FER after having read FER = 1</li> </ul>
3	PER	0	R/(W)*	Parity Error
				[Setting condition]
				Occurrence of a parity error during reception
				[Clearing condition]
2	TEND	Undefined	R	Writing of 0 to PER after having read PER = 1 Transmit End
2	TEND	Undenned	Γ	[Setting condition]
				<ul> <li>Clearing of the TE bit in SCR (to 0)</li> </ul>
				<ul> <li>TDRE = 1 on transmission of the last bit of a character</li> </ul>
				[Clearing conditions]
				<ul> <li>Writing of 0 to PER after having read PER = 1</li> </ul>
				<ul> <li>Generation of a TXI interrupt request allowing DMAC to write data to TDR</li> </ul>

Note: \* Only 0 can be written here, to clear the flag.



• Smart card mode register\_5 (SCMR\_5) Address: H'FFF606

Bit	Bit Name	Setting	R/W	Description
0	SMIF	0	R/W	Smart Card Interface Mode Select
				<ol> <li>Operation is in the normal asynchronous or clock synchronous mode</li> </ol>
				1: Operation is in smart card interface mode

• Serial extended mode register\_5 (SEMR\_5) Address: H'FFF608

	Bit			
Bit	Name	Setting	R/W	Description
4	ABCS	0	R/W	Asynchronous Mode Base Clock Selection (only valid in the asynchronous mode)
				Selects the base clock for a 1-bit period
				0: The base clock has a frequency 16 times the transfer rate.
				1: The base clock has a frequency 8 times the transfer rate.
3	ACS3	0	R/W	Asynchronous Clock Source Selection
2	ACS2	1	R/W	Selects the clock source in the asynchronous mode: See table 12
1	ACS1	0	R/W	0011: Selects the average transfer rate of 921.569 kbps specifically
0	ACS0	0	R/W	for $P\phi = 16 \text{ MHz}$
				<ul> <li>Note 1: When the average transfer rate is selected, the base clock is automatically set regardless of the ACS bit in the SEMR_5 register (asynchronous base clock selection).</li> <li>Note 2: The setting only has the desired effect when bits ACS3 to ACS0 are in the asynchronous mode (C/Ā bit of SMR register is 0), and the external clock input is selected (CKE1 bit of SCR register is 1).</li> </ul>

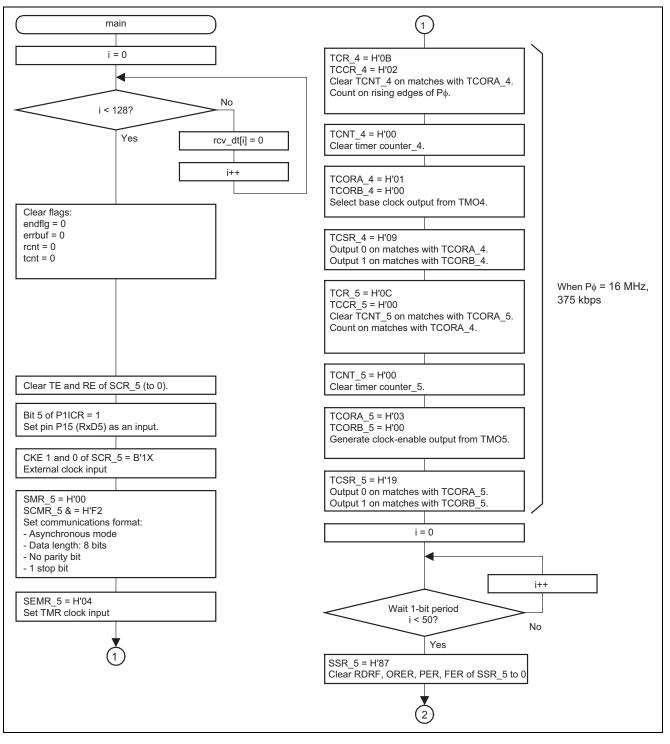


#### ACS3 to 0 **Transfer Rate** Pφ (MHz) **Functions** 0000 (Set by the ABCS bit) The average transfer rate generator is not used. 0001 $1/16^{th}$ of the base clock 10.667 Average transfer rate 115.152 kbps frequency for average-rate transfer 0010 1/8<sup>th</sup> of the base clock 10.667 Average transfer rate 460.606 kbps frequency for average-rate transfer 0011 $1/8^{th}$ of the base clock 16 Average transfer rate 921.569 kbps frequency for average-rate 8 Average transfer rate 460.784 kbps transfer (Set by the ABCS bits) 0100 Selects TMR-clock input: compare-match \_\_\_\_ output of TMR provides the base clock for transfer $1/16^{th}$ of the base clock 0101 16 Average transfer rate 115.196 kbps frequency for average-rate transfer 1/16<sup>th</sup> of the base clock 0110 16 Average transfer rate 460.784 kbps frequency for average-rate transfer 0111 1/8<sup>th</sup> of the base clock 24 Average transfer rate 720 kbps frequency for average-rate transfer 1000 1/16<sup>th</sup> of the base clock 24 Average transfer rate 115.132 kbps frequency for average-rate transfer 1/16<sup>th</sup> of the base clock 1001 24 Average transfer rate 460.526 kbps frequency for average-rate 12 Average transfer rate 230.263 kbps transfer 1/8<sup>th</sup> of the base clock 1010 24 Average transfer rate 720 kbps frequency for average-rate transfer 1011 1/8<sup>th</sup> of the base clock 24 Average transfer rate 921.053 kbps frequency for average-rate 12 Average transfer rate 460.526 kbps transfer 1100 1/16<sup>th</sup> of the base clock 32 Average transfer rate 720 kbps frequency for average-rate transfer

#### Table 12 List of Settings for Asynchronous Clock Source Select

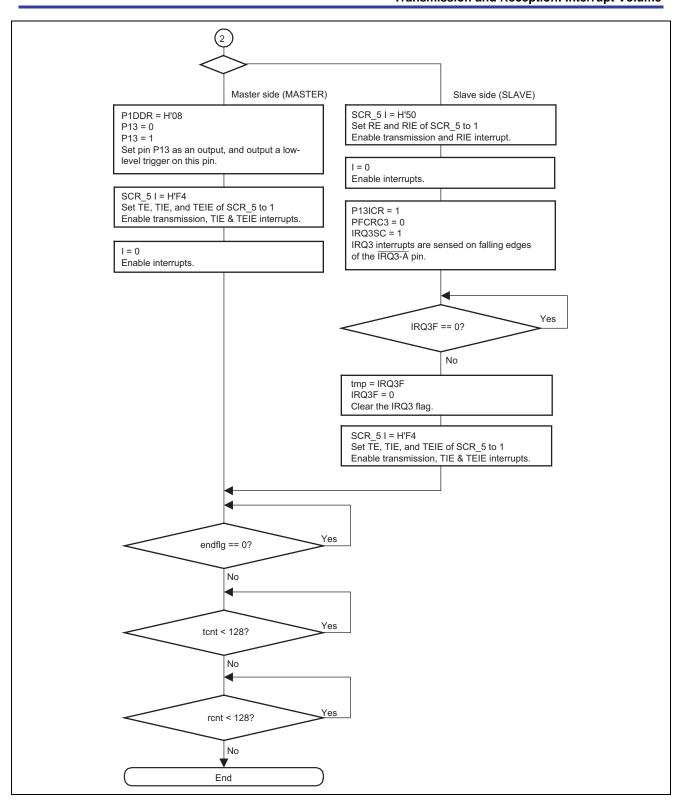


#### H8SX Family Using a Timer-Generated Clock Signal to Drive SCI Transmission and Reception: Interrupt Volume





#### H8SX Family Using a Timer-Generated Clock Signal to Drive SCI Transmission and Reception: Interrupt Volume





## 5.6.3 rxi5\_int Function

- 1. Overview
  - Handler for the receive data full interrupt. Receives one byte.
- 2. Arguments None
- 3. Return value None

4. Description of internal register usage Usage of internal registers in this task is described below. The given settings are those used in the task and differ from the initial settings.

• Serial Control Register\_5 (SCR\_5) Address: H'FFF602

Bit	Bit Name	Setting	R/W	Description
6	RIE	0	R/W	Receive Interrupt Enable 0: Disables RXI, ERI interrupts
				1: Enables RXI, ERI interrupts
4	RE	0	R/W	Receive Enable 0: Disables reception
				1: Enable reception

• Serial Status Register\_5 (SSR\_5) Address: H'FFF604

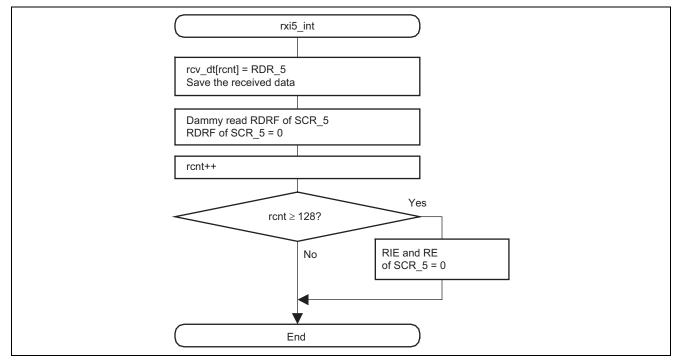
	Bit			
Bit	Name	Setting	R/W	Description
6	RDRF	Undefined	R/(W)*	<ul> <li>Receive Data Register Full</li> <li>Indicates whether RDR holds received data</li> <li>[Setting condition]</li> <li>The normal end of serial reception and the transfer of received data from RSR to RDR</li> <li>[Clearing conditions]</li> <li>Writing of 0 to RDRF after having read RDRF = 1</li> <li>Generation of an RXI interrupt request allowing DMAC or DTC to read data from RDR</li> <li>The RDRF flag is not affected and retains its previous value when the RE bit in SCR is cleared to 0.</li> <li>Note that when the next serial reception is completed while the RDRF flag is being set to 1, an overrun error occurs and the received data are lost.</li> </ul>

Note: \* Only 0 can be written here, to clear the flag.

Function: A read-only 8-bit register for storing received data. Setting: Undefined.

<sup>•</sup> Receive Data Register\_5 (RDR\_5) Address: H'FFF605







## 5.6.4 txi5\_int Function

- 1. Overview
  - Handler for the transmit data empty interrupt. Transfers one byte for transmission.
- 2. Arguments None
- 3. Return value None

4. Description of internal register usage Usage of internal registers in this task is described below. The given settings are those used in the task and differ from the initial settings.

• Serial Control Register\_5 (SCR\_5) Address: H'FFF602

	Bit			
Bit	Name	Setting	R/W	Description
7	TIE	0	R/W	Transmit Interrupt Enable
				0: Disables TXI interrupt requests
				1: Enables TXI interrupt requests

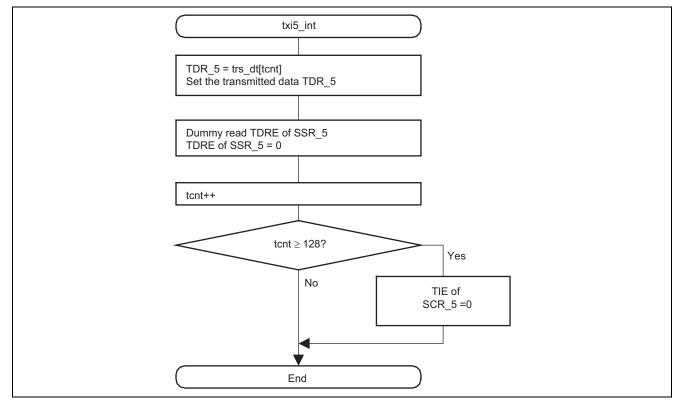
• Transmit Data Register\_5 (TDR\_5) Address: H'FFF603 Function: A readable/writable 8-bit register that holds data for transmission. Setting: trs[tcnt]

• Serial Status Register\_5 (SSR\_5) Address: H'FFF604

Bit	Bit Name	Setting	R/W	Description
7	TDRE	0	R/(W)*	<ul> <li>Transmit Data Register Empty</li> <li>Indicates whether TDR contains data for transmission</li> <li>[Setting conditions]</li> <li>Clearing of the TE bit in SCR (to 0)</li> <li>Transfer of data from TDR to TSR</li> <li>[Clearing conditions]</li> <li>Writing a 0 to TDRE after having read TDRE = 1</li> <li>Generation of a TXI interrupt request allowing DMAC to write data to TDR</li> </ul>

Note: \* Only 0 can be written here, to clear the flag.







## 5.6.5 eri5\_int Function

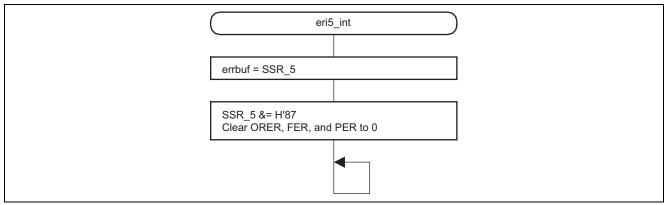
- 1. Overview
  - Handler for reception error interrupts. Transfers one byte to memory.
- 2. Arguments None
- 3. Return value None

4. Description of internal register usage Usage of internal registers in this task is described below. The given settings are those used in the task and differ from the initial settings.

• Serial status register\_5 (SSR\_5) Address: H'FFF604

	Bit			
Bit	Name	Setting	R/W	Description
5	ORER	0	R/(W)*	Overrun Error
				[Setting condition]
				<ul> <li>Occurrence of an overrun error during reception</li> </ul>
				[Clearing condition]
				<ul> <li>Writing of 0 to ORER after having read ORER = 1</li> </ul>
4	FER	0	R/(W)*	Framing Error
				[Setting condition]
				<ul> <li>Occurrence of a framing error during reception</li> </ul>
				[Clearing condition]
				<ul> <li>Writing of 0 to FER after having read FER = 1</li> </ul>
3	PER	0	R/(W)*	Parity Error
				[Setting condition]
				<ul> <li>Occurrence of a parity error during reception</li> </ul>
				[Clearing condition]
				Writing of 0 to PER after having read PER = 1

Note: \* Only 0 can be written here, to clear the flag.

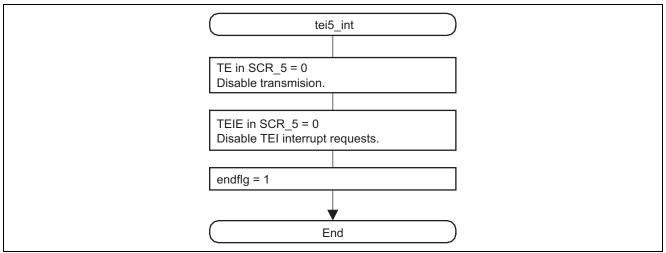




## 5.6.6 tei5\_int Function

- 1. Overview
  - Handler for the transmission end interrupt function. Transfers one byte to memory as a flag.
- 2. Arguments None
- 3. Return value None
- 4. Description of internal register usage Usage of internal registers in this task is described below. The given settings are those used in the task and differ from the initial settings.
- Serial control register\_5 (SCR\_5) Address: H'FFF602

Bit	Bit Name	Setting	R/W	Description
5	TE	0	R/W	Transmit Enable
				0: Disables transmission
				1: Enables transmission
2	TEIE	0	R/W	Transmit End Interrupt Enable
				0: Disables TEI interrupt requests
				1: Enables TEI interrupt requests





## 6. Note on Usage

When the pin of the device functions as an input for the peripheral modules, the corresponding bits of the input buffer control register (PnICR) should be set to 1. For details, see the hardware manual.



## Website and Support

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## **Revision Record**

Rev.	Date	Description			
		Page	Summary		
1.00	Mar.10.06	—	First edition issued		
2.00	Mar.07.08	1, 34	Page 1: Target devices added		
			Page 34: Note on usage added		

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