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Renesas Electronics Corporation

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M16C/Tiny Series

Operation of Serial I/O (Transmission in Clock-Synchronous Serial I/O Mode)

1. Abstract

In transmitting data in clock-synchronous serial I/O mode, choose functions from those listed in Table 1. Operations of the checked items are described below.

Table 1. Chosed Functions

Item	Set-up		Item	Set-up	
	Yes			Yes	
Transfer clock source	Yes	Internal clock (f1/f2/f3/f32)	Transmission interrupt factor	Yes	Transmission buffer empty
		External clock (CLKi pin)			Transmission complete
CTS function	Yes	CTS function enabled	Output transfer clock to multiple pins (Note 1)	Yes	Not selected
		CTS function disabled			Selected
CLK polarity	Yes	Output transmission data at the falling edge of the transfer clock	Data logic select (Note 2)	Yes	No reverse
		Output transmission data at the rising edge of the transfer clock			Reverse
Transfer format	Yes	LSB first	TxD, RxD I/O polarity reverse function (Note 2)	Yes	No reverse
		MSB first			Reverse
Transfer format	Yes	LSB first	UART1 pin remapping function (Note 3)	Yes	UART1 pins assigned to P67 to P64
				MSB first	

Note 1: This can be selected only when UART1 is used in combination with the internal clock. When this function is selected, UART1 CTS/RTS function can not be utilized. Set the UART1 CTS/RTS disable bit to "1".

Note 2: UART2 only

Note 3: It is possible to select it only with M16C/26A, M16C/28, and M16C/29.

2. Introduction

The explanation of this issue is applied to the following condition:

Applicable MCU: M16C/26, M16C/26A, M16C/28, M16C/29 Group

This program can also be used when operating other microcomputers within the M16C family, provided they have the same SFR (Special Function Registers) as the M16C/26, M16C/26A, M16C/28, M16C/29 microcomputers. However, some functions may have been modified.

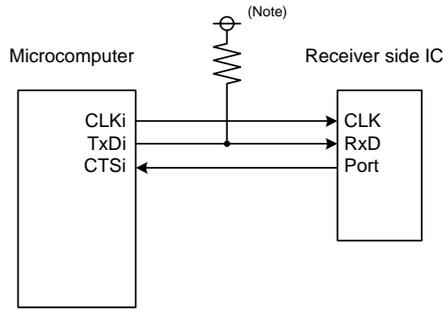
Refer to the User's Manual for details. Use functions covered in this Application Note only after careful evaluation.

3. Operation of Serial I/O

- (1) Setting the transmit enable bit to “1” and writing transmission data to the UARTi transmit buffer register makes data transmissible status ready.
- (2) When input to the $\overline{\text{CTS}}_i$ pin goes to “L” level, transmission starts (the $\overline{\text{CTS}}_i$ pin must be controlled on the reception side).
- (3) In synchronization with the first falling edge of the transfer clock, transmission data held in the UARTi transmit buffer register is transmitted to the UARTi transmit register. At this time, the UARTi transmit interrupt request bit goes to “1”. Also, the first bit of the transmission data is transmitted from the TxDi pin. Then the data is transmitted bit by bit from the lower order in synchronization with the falling edges.
- (4) When transmission of 1-byte data is completed, the transmit register empty flag goes to “1”, which indicates that transmission is completed. The transfer clock stops at “H” level.
- (5) If the next transmission data is set in the UARTi transmit buffer register while transmission is in progress (before the eighth bit has been transmitted), the data is transmitted in succession.

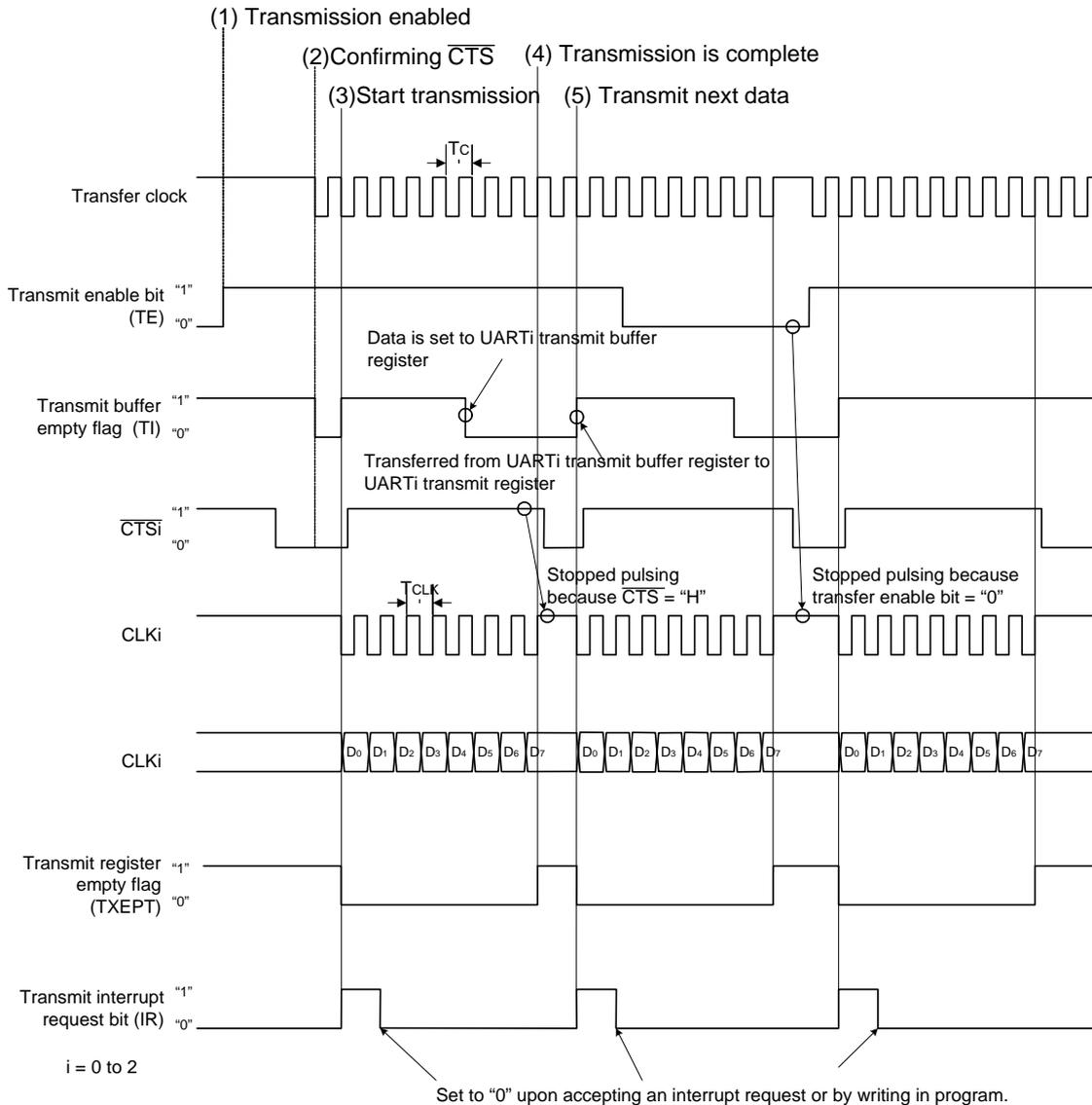
Figure 1 shows the operation timing.

Example of wiring



Note : Since TXD2 pin is N-channel open drain, this pin needs pull-up resistor (M16C/26).

Example of operation



Shown in () are bit symbols.

The above timing applies to the following settings:

- Internal clock is selected.
- CTS function is selected.
- CLK polarity select bit = "0".
- Transmit interrupt cause select bit = "0".

$$T_c = T_{CLK} = 2(n + 1) / f_i$$

fi: frequency of BRGi count source (f1, f2, f8, f32)
n: value set to BRGi

Set to "0" upon accepting an interrupt request or by writing in program.

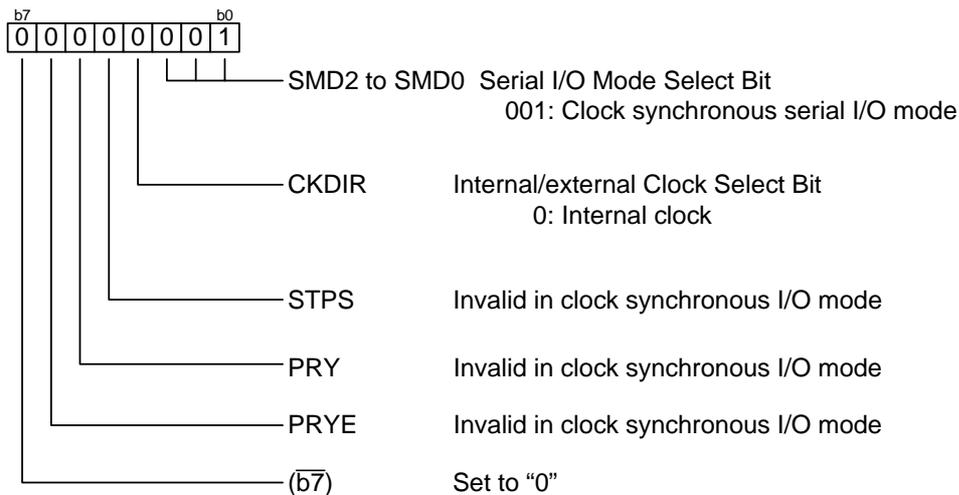
Figure 1. Operation Timing of Transmission in Clock-Synchronous Serial I/O Mode

3.1 Register Setting

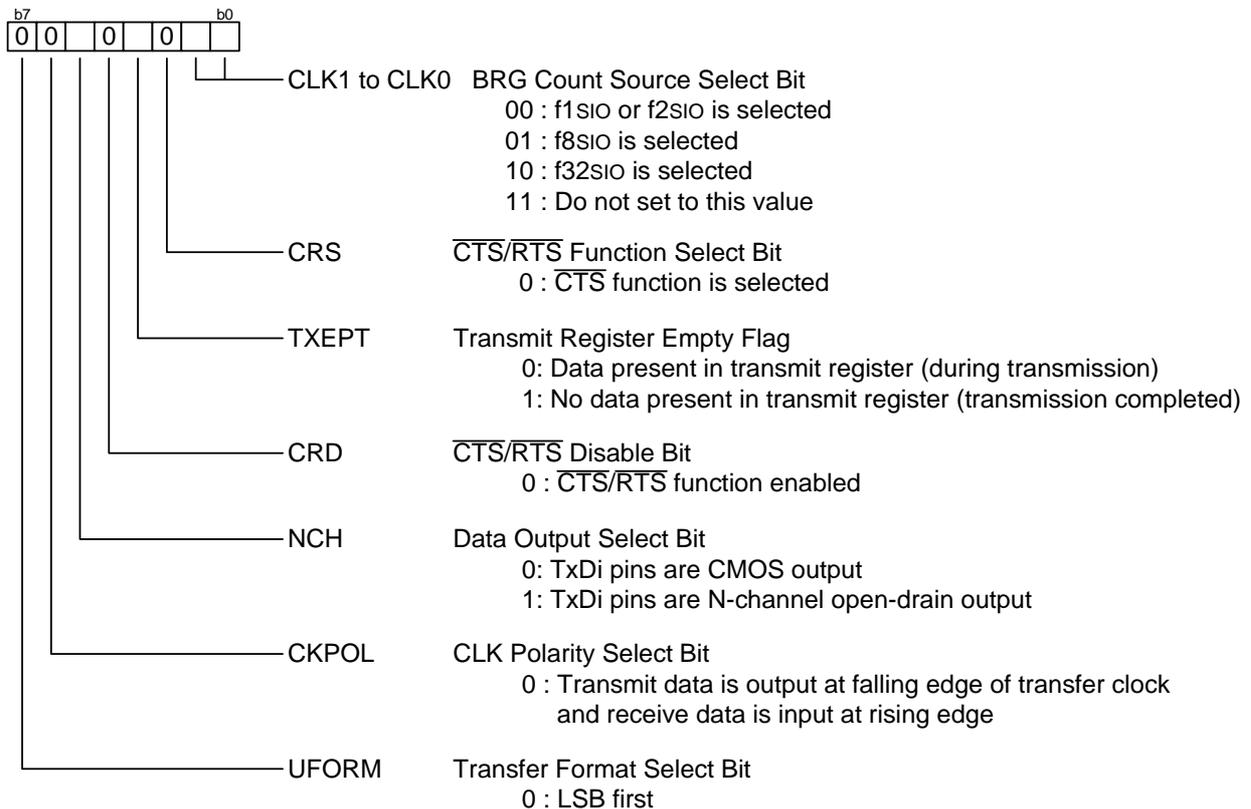
To enable the operation defined in “Section 3. Operation of timer A”, the following register settings must be taken place step by step. For detail configuration of each register, please refer to M16C/26 Group hardware manual, M16C/26A Group hardware manual, M16C/28 Group hardware manual, M16C/29 Group hardware manual.

3.1.1 UART0, 1

(1) Setting UART_i transmit/receive mode register (i=0, 1)

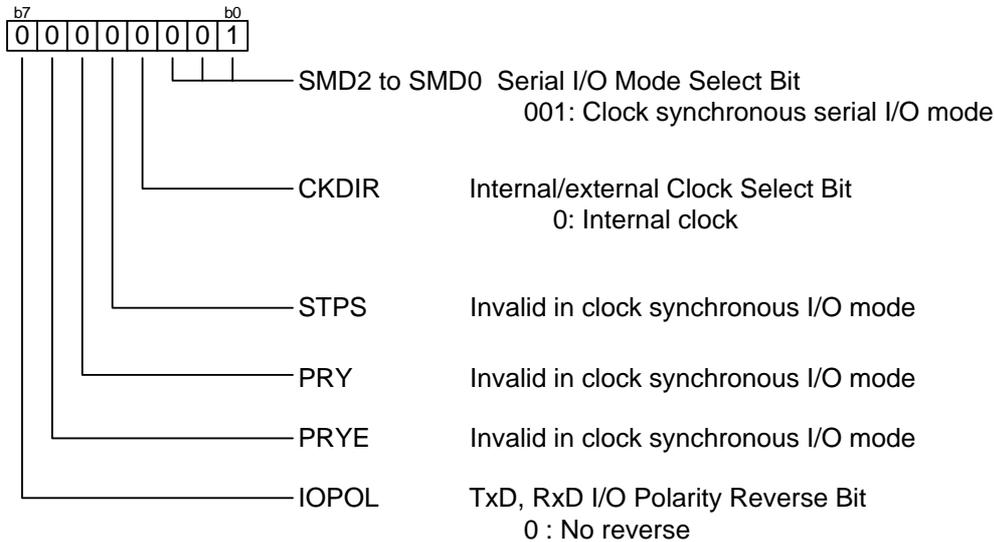


(2) Setting UART_i transmit/receive control register 0 (i=0,1)

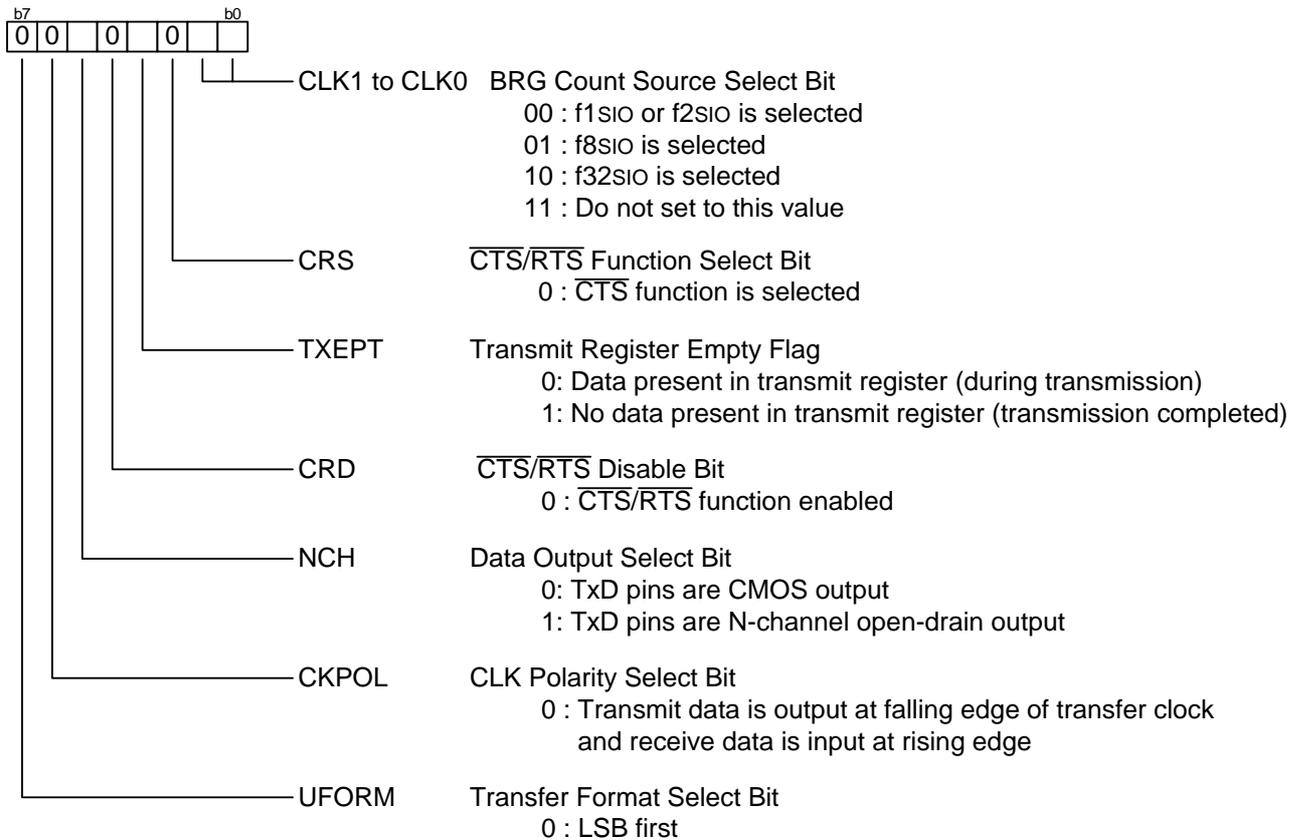


3.1.2 UART2

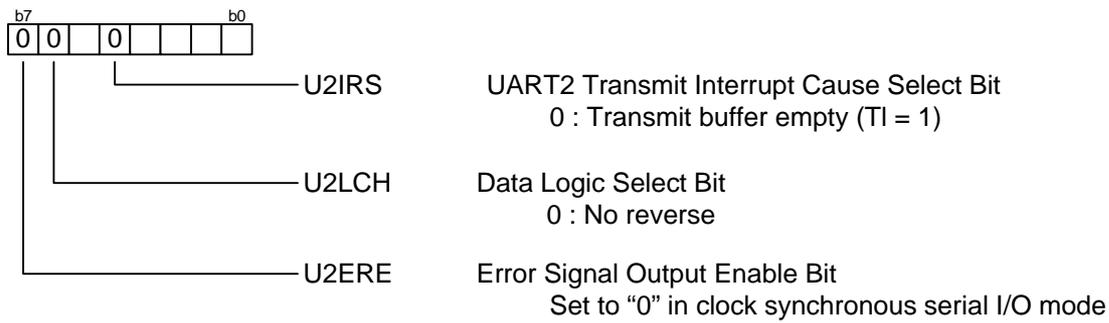
(1) Setting UART2 transmit/receive mode register



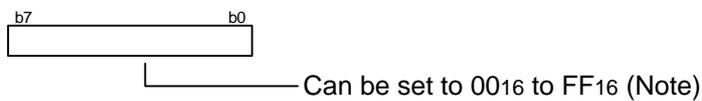
(2) Setting UART2 transmit/receive control register 0



(3) Setting UART2 transmit/receive control register 1

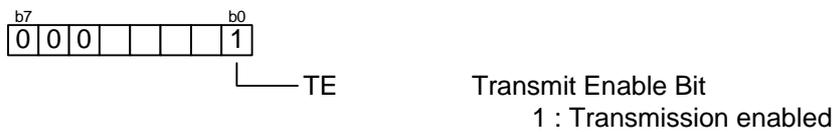


(4) Setting UART2 baud rate generation register

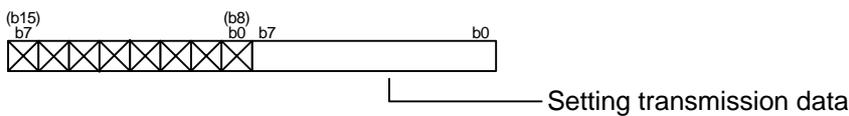


Note: Write to UART2 baud rate generation register when transmission/reception is halted.

(5) Transmission enabled (UART2 transmit/receive control register 1)

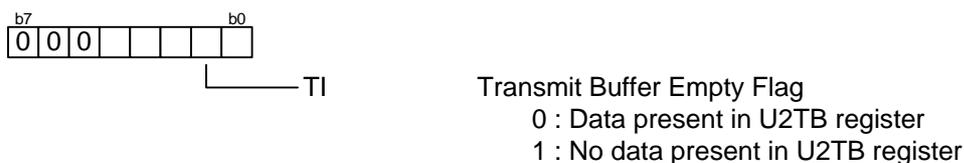


(6) Writing transmit data (UART2 transmit buffer register)



Start transmission When CTS_i input level = "L"

(7) Checking the status of UART2 buffer register



It returns to (6) when continuously transmitting.

4. Sample Program

4.1 UART0

```

/*****
 *
 *   FILE NAME :
 *   CPU       : M16C/Tiny series
 *   Function  : Operation of UART0
 *              (Clock synchronous serial I/O transfer)
 *   Version   : 1.00
 *
 *   Copyright (C)2004, Renesas Technology Corp.
 *   Copyright (C)2004, Renesas Solutions Corp.
 *
 *****/
/*****
 *   include file
 *****/
#include "sfr28.h"

/*****
 *   Function Definition
 *****/

/*****
 *   main
 *****/
void main(void) {

    unsigned short  trans_data = 0;

    pd6_0 = 0;

    u0mr = 0x01; /* UART0 transmit/receive mode register setting
                  Clock synchronous serial I/O mode
                  Internal clock select
                  */

    u0c0 = 0x00; /* UART0 transmit/receive control register 0 setting
                  ~CTS function select
                  ~CTS/~RTS function enabled
                  TxD0 pin is CMOS output
                  Transmission data is output at falling edge of transfer
                  clock and reception data is input at rising edge
                  LSB first
                  */

    ucon = 0x00; /* UART transmit/receive control register 2 setting
                  UART0 transmit interrupt cause is selected to "Transmit buffer empty(TI=1)"
                  ~CTS/~RTS shared pin
                  */

    u0brg = 10-1; /* Setting UART0 bit rate generator (1MHz @20MHz f1) */

    u0c1 = 0x01; /* UART transmit/receive control register 1 setting
                  Transmit enabled
                  */

    while (1) {

        u0tb = trans_data; /* Writing transmit data */

        while (!ti_u0c1) { /* Check & wait the status of UART0 transmit buffer empty flag */
        }

        trans_data++;
        trans_data = 0xFF & trans_data;

    }
}

```

4.1.1 UART2

```

/*****
*
* FILE NAME :
* CPU : M16C/Tiny series
* Function : Operation of UART2
*           (Clock synchronous serial I/O transfer)
* Version  : 1.00
*
* Copyright (C)2004, Renesas Technology Corp.
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*
*****/
/*****
* include file
*****/
#include "sfr28.h"

/*****
* Function Definition
*****/

/*****
* main
*****/
void main(void) {

    unsigned short  trans_data = 0;

    pd7_3 = 0;

    u2mr = 0x01; /* UART2 transmint/receive mode register setting
                  Clock synchronous serial I/O mode
                  Internal clokc select
                  */

    u2c0 = 0x00; /* UART2 transmint/receive control register 0 setting
                  ~CTS function select
                  ~CTS/~RTS function enabled
                  TxD0 pin is CMOS output
                  Transmission data is output at falling edge of transfer
                  clock and reception data is input at rising edge
                  LSB first
                  */

    u2c1 = 0x00; /* UART2 transmint/receive control register 1 setting
                  UART2 tansmit interrupt cause is selected to "Transmit buffer empty(TI=1)"
                  ~CTS/~RTS shared pin
                  */

    u2brg = 10-1; /* Setting UART2 bit rate generator (1MHz @20MHz f1) */

    u2c1 = 0x01; /* UART transmint/receive control register 1 setting
                  Transmit enabled
                  */

    while (1) {

        u2tb = trans_data; /* Writing transmit data */

        while (!ti_u2c1) { /* Check & wait the status of UART2 transmit buffer empty flag */
        }

        trans_data++;
        trans_data = 0xFF & trans_data;
    }
}

```

5. Reference

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Hardware Manual

M16C/26, M16C/26A, M16C/28, M16C/29 Group Hardware Manual

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REVISION HISTORY

Rev.	Date	Description	
		Page	Summary
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