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78K0R/Kx3 Microcontroller

Sample Program

Operation Manual

(Measurement of High-/Low-Level Width of

Input Signal (Timer Array Unit), C Source)

This software is for reference only and NEC Electronics does not guarantee its operation. Thoroughly evaluate this software on your set prior to use.

ZUD-CC-07-0080-E January, 2008

1st Product Solution Group, Multipurpose Microcomputer Systems Division, Microcomputer Operations Unit NEC Electronics Corporation

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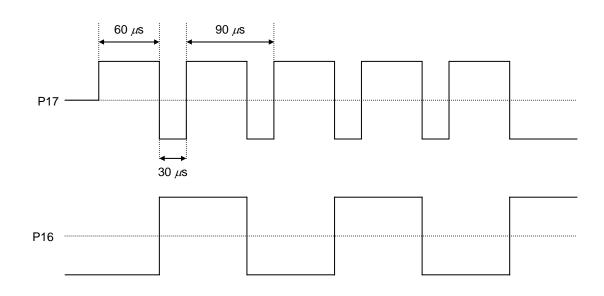
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1. OVERVIEW

This manual explains the sample program functions of measurement of high-/low-level width of input signal for the 78K0R/Kx3 microcontroller.

In this sample program, both the rising and falling edges of P17 are detected by using timer channel 2. Each time the rising edge of P17 is detected and INTTM02 is output, TMR02 is read and the high-level width is measured. The measured high-level width is stored in TDR02.

It is assumed that the pulse interval of the signal input to P17 is 90 μ s (H/L = 60 μ s/30 μ s). P16 is used for checking the operation as it outputs a signal that reverses the high or low level when measuring the high-level width of P17 is completed.



2. RESOURCES USED

Resource	Description	Remark
Main clock specification	Internal high-speed oscillator used (8 MHz (TYP.))	Supplied to CPU and peripheral hardware
	High-speed system clock used (20 MHz)	Oscillated by initial processing
Subclock	XT1 (32.768 kHz)	Oscillated by initial processing
Related hardware	Peripheral enable register 0 (PER0)	Controls the input clock of the timer array
		unit.
	Timer clock select register 0 (TPS0)	Operation clock: CK01, 8 MHz (0.125 μ s)
	Timer mode register 02 (TMR02)	Operation clock: CK01, 8 MHz (0.125 μs)
	Timer data register 02 (TDR02)	Used to store the pulse width.
	Timer output mode register 0 (TOM0)	Channel 0 toggle operation mode
	Timer output level register 0 (TOL0)	Channel 0 positive logic output (active high)
	Timer output register 0 (TO0)	Channel 0 timer output value is "0".
	Timer output enable register 0 (TOE0)	Enables TO02 operation by counting
		operation.
	Timer channel start register 0 (TS0)	
	Timer channel stop register 0 (TTO)	
	Port mode register (PM1)	
	Port register (P1)	
I/O	Input: P17	
	Output: TO02 (P16)	
Interrupt	Timer channel 2	
Others	Not used	

3. SOFTWARE CONFIGURATION

Files

File Name	Processing Outline
K0R_def.h	Definition file
K0R_init.c	Initialization processing
K0R_ext.h	External declaration
K0R_main.c	Main processing
K0R_sfr_set.c	Input signal pulse measurement

4. FUNCTION EXPLANATIONS

[File name]

K0R_main.c

Function

Function Name	Function Name Processing Outline		Return Value
main	Measurement of high-/low-level width of input signal main	None	None
	processing		

Function explanations

Function name	main	
Processing	Processing Measurement of high-/low-level width of input signal main processing	
Argument –		
Return value –		
Description Sets P16 to the output mode.		
	Executes initialization processing and then starts measurement of high-/low-level width of input	
	signal.	
	P16's status is reversed when the interrupt request flag of timer channel 2 is set to ON. Then the	
	interrupt request flag is cleared.	
Remark	_	

[File name]

K0R_sfr_set.c

Functions

Function Name	Processing Outline	Argument	Return Value
STM_LINI	Initializes measurement of high-/low-level width of input signal.	None	None
STM_LSTT	Starts measurement of high-/low-level width of input signal operation.	None	None
STM_LSTP	Stops measurement of high-/low-level width of input signal operation.	None	None

Function explanations

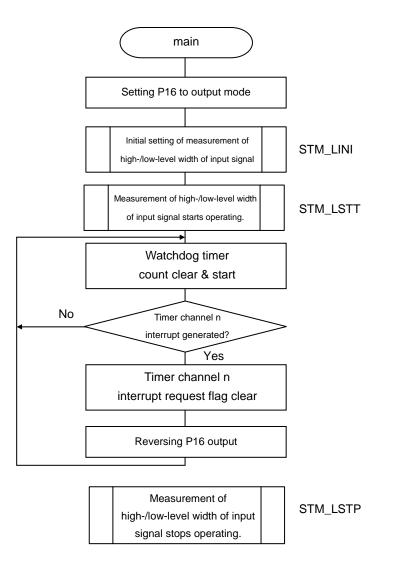
Function name	STM_LINI	
Processing	Initializes measurement of high-/low-level width of input signal.	
Argument –		
Return value	-	
Description	Initializes the timer array unit.	
	Supplies a timer array unit input clock.	
	Initializes timer channel 2.	
	• Operation mode: Operation clock CK01, selection of the valid edge of the TI02 pin input, both edge	
	selection (high-level width measurement), capture & one-count mode	
	Output mode: Toggle operation mode	
Remark	This function is called after reset.	

Function name	STM_LSTT
Processing	Starts measurement of high-/low-level width of input signal operation.
Argument	_
Return value	-
Description	Starts timer channel 2 operation.
Remark	-

Function name	STM_LSTP
Processing	Stops measurement of high-/low-level width of input signal operation.
Argument	-
Return value	-
Description	Stops timer channel 2 operation.
Remark	-

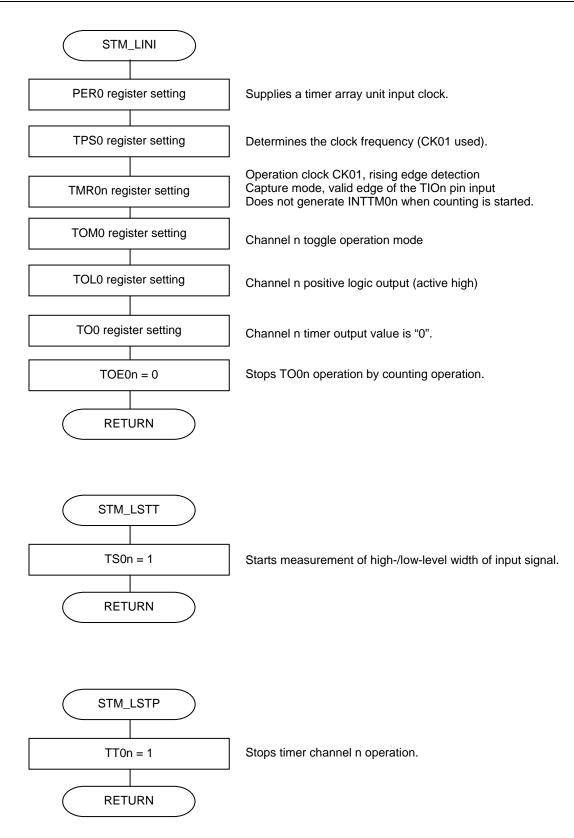
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5. FLOWCHARTS



Remark n = 0 to 7 can be set.

n = 2 for this sample program.



Remark n = 0 to 7 can be set.

n = 2 for this sample program.