

# Sample Drivers for R8C/M11A

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Rev.1.00

Application Note: <Sample Drivers for R8C/M11A>

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This document is designed to describe an outline of various sample driver software created for R8C/M11A.

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### 1. File Composition of Sample Driver Software

- This document of sample driver software consists of a source list and directions (\* pdf format) for each function. On decompression of a downloaded file, a “source” folder and a “doc” folder are generated. In the sub folders in the “source” folder, source lists of each function are stored. In the sub folders in the “doc” folder, directions for each function are stored.

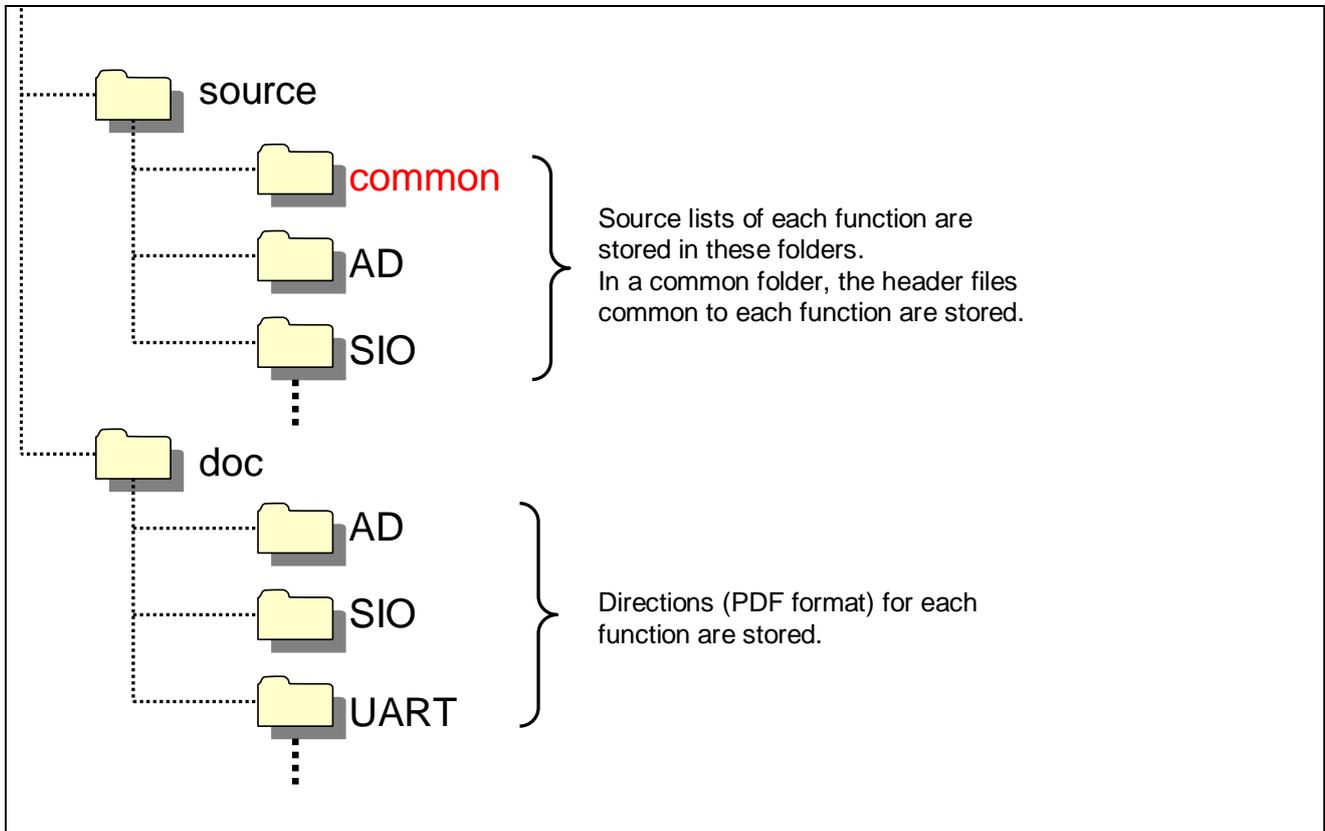


Figure 1 File Composition

## 2. Lists of Sample Driver Software

- The tables below show the lists of sample driver software described in this document.

**Table 2-1 A List of Sample Driver Software (1)**

Types of Drivers		Process Summary	ROM (byte)	RAM (byte)	Function Name	Source file	
Voltage Monitor 1 Interrupt		Voltage Monitor 1 Interrupt Setting	145	0	R.VDET1_Create	r.vdet1_create.c	
KEY ON WAKE UP (KI1-KI3)		KI1-KI3 Key Input Interrupt Setting	205	0	R.KWAKE_Create	r.kwake_create.c	
Clock Synchronous Serial 0 Transmission		SI/O0 Setting for Transmission	308	8	R.SIO0_Create_Transmit	r.sio0_create_transmit.c	
		SI/O0 Transmit Execution	118	0	R.SIO0_Control_Transmit	r.sio0_control_transmit.c	
Clock Synchronous Serial 0 Reception		SI/O0 Setting for Reception	300	8	R.SIO0_Create_Receive	r.sio0_create_receive.c	
		SI/O0 Receive Execution	128	0	R.SIO0_Control_Receive	r.sio0_control_receive.c	
UART0 Transmission		UART0 Setting for Transmission	341	16	R.UART0_Create_Transmit	r.uart0_create_transmit.c	
		UART0 Transmit Execution	148	0	R.UART0_Control_Transmit	r.uart0_control_transmit.c	
UART0 Reception		UART0 Setting for Reception	325	20	R.UART0_Create_Receive	r.uart0_create_receive.c	
		UART0 Receive Execution	193	0	R.UART0_Control_Receive	r.uart0_control_receive.c	
Timer RJ (2)	Timer Mode	Timer Mode Setting	72	0	R.TMR_RJ2_Create_Timer	r.tmr_rj2_create_timer.c	
		Starting and Stopping Timer	71	0	R.TMR_RJ2_Control_Timer	r.tmr_rj2_control_timer.c	
	Event Counter Mode	Event Counter Mode Setting	320	0	R.TMR_RJ2_Create_ECnt	r.tmr_rj2_create_ecnt.c	
		Starting and Stopping Event Counter Mode	76	0	R.TMR_RJ2_Control_ECnt	r.tmr_rj2_control_ecnt.c	
	Pulse Width Measurement Mode	Pulse Width Measurement Mode Setting	209	0	R.TMR_RJ2_Create_PWidth	r.tmr_rj2_create_pwidth.c	
		Starting and Stopping Pulse Width Measurement	71	0	R.TMR_RJ2_Control_PWidth	r.tmr_rj2_control_pwidth.c	
	Pulse Period Measurement Mode	Pulse Period Measurement Mode Setting	209	0	R.TMR_RJ2_Create_PPeriod	r.tmr_rj2_create_pperiod.c	
		Starting and Stopping Pulse Period Measurement	71	0	R.TMR_RJ2_Control_PPeriod	r.tmr_rj2_control_pperiod.c	
	Pulse Output Mode	Pulse Output Mode Setting	173	0	R.TMR_RJ2_Create_POutput	r.tmr_rj2_create_poutput.c	
		Pulse Output Process	96	0	R.TMR_RJ2_Control_POutput	r.tmr_rj2_control_poutput.c	
	Timer RB (2)	Timer Mode	Timer Mode Setting	91	0	R.TMR_RB2_Create_Timer	r.tmr_rb2_create_timer.c
			Starting and Stopping Timer	92	0	R.TMR_RB2_Control_Timer	r.tmr_rb2_control_timer.c
Programmable Waveform Mode		Programmable Waveform Generation Mode Setting	127	0	R.TMR_RB2_Create_PWave	r.tmr_rb2_create_pwave.c	
		Programmable Waveform Generation Process	107	0	R.TMR_RB2_Control_PWave	r.tmr_rb2_control_pwave.c	
Programmable One-Shot Generation Mode		Programmable One-Shot Generation Mode Setting	222	0	R.TMR_RB2_Create_POneshot	r.tmr_rb2_create_poneshot.c	
		Programmable One-Shot Generation Process	38	0	R.TMR_RB2_Control_POneshot	r.tmr_rb2_control_poneshot.c	
Programmable Wait One-Shot Generation Mode	Programmable Wait One-Shot Generation Mode Setting	214	0	R.TMR_RB2_Create_PWOneshot	r.tmr_rb2_create_pwoneshot.c		
	Programmable Wait One-Shot Generation Process	65	0	R.TMR_RB2_Control_PWOneshot	r.tmr_rb2_control_pwoneshot.c		
Timer RC	Common for All Modes		344	0	R.TMR_RC_Create	r.tmr_rc_create.c	
	Shared Register Setting Process		59	0	R.TMR_RC_Create_Reg	r.tmr_rc_create_reg.c	
	Timer RC Execution Process		152	0	R.TMR_RC_Control	r.tmr_rc_control.c	
	Timer Mode (Input Capture)		454	0	R.TMR_RC_Create_ICap	r.tmr_rc_create_icap.c	
	Timer Mode (Output Compare)		486	0	R.TMR_RC_Create_OCmp	r.tmr_rc_create_ocmp.c	
	PWM Mode		250	0	R.TMR_RC_Create_Pwm	r.tmr_rc_create_pwm.c	
	PWM2 Mode		199	0	R.TMR_RC_Create_Pwm2	r.tmr_rc_create_pwm2.c	
	A/D Conversion		43	4	R.ADC_Read	r.adc_read.c	
AD Conversion	Basic Setting		128	0	R.ADC_Create	r.adc_create.c	
	One-Shot Mode		168	0	R.ADC_Control_Oneshot	r.adc_control_oneshot.c	
	Repeat Mode		171	0	R.ADC_Control_Repeat	r.adc_control_repeat.c	
	Single Sweep Mode		153	0	R.ADC_Control_SSweep	r.adc_control_ssweep.c	
	Repeat Sweep Mode		153	0	R.ADC_Control_RSweep	r.adc_control_rsweep.c	
	A/D Data Read Process		43	4	R.ADC_Read	r.adc_read.c	
Comparator B1 Interrupt		Comparator B1 Setting	167	0	R.CMP_B1_Create	r.cmp_b1_create.c	
		Comparator B1 Control	40	0	R.CMP_B1_Control	r.cmp_b1_control.c	
INT0 Interrupt		INT0 Setting	75	0	R.INT0_Create	r.int0_create.c	
		INT0 Control	64	0	R.INT0_Control	r.int0_control.c	
INT1 Interrupt		INT1 Setting	75	0	R.INT1_Create	r.int1_create.c	
		INT1 Control	64	0	R.INT1_Control	r.int1_control.c	
INT2 Interrupt		INT2 Setting	71	0	R.INT2_Create	r.int2_create.c	
		INT2 Control	64	0	R.INT2_Control	r.int2_control.c	

### 3. Usage Outlines of Sample Driver Software

- Source lists of each function are attached to this document.  
A source file of the function to be used can be diverted without any change.  
Header files (\*.h) required for use of each function are stored in the same folders where each function is stored.  
Common header files such as a definition file of a special function register, etc. are stored in a .source/common folder.  
For the details of how to use each function, please refer to the descriptions of each function before actual use.

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## Revision Record

Rev.	Date	Description	
		Page	Summary
1.00	Jan.31, 2011	—	First edition issued

## General Precautions in the Handling of MPU/MCU Products

The following usage notes are applicable to all MPU/MCU products from Renesas. For detailed usage notes on the products covered by this manual, refer to the relevant sections of the manual. If the descriptions under General Precautions in the Handling of MPU/MCU Products and in the body of the manual differ from each other, the description in the body of the manual takes precedence.

### 1. Handling of Unused Pins

Handle unused pins in accord with the directions given under Handling of Unused Pins in the manual.

- The input pins of CMOS products are generally in the high-impedance state. In operation with an unused pin in the open-circuit state, extra electromagnetic noise is induced in the vicinity of LSI, an associated shoot-through current flows internally, and malfunctions occur due to the false recognition of the pin state as an input signal become possible. Unused pins should be handled as described under Handling of Unused Pins in the manual.

### 2. Processing at Power-on

The state of the product is undefined at the moment when power is supplied.

- The states of internal circuits in the LSI are indeterminate and the states of register settings and pins are undefined at the moment when power is supplied.

In a finished product where the reset signal is applied to the external reset pin, the states of pins are not guaranteed from the moment when power is supplied until the reset process is completed.

In a similar way, the states of pins in a product that is reset by an on-chip power-on reset function are not guaranteed from the moment when power is supplied until the power reaches the level at which resetting has been specified.

### 3. Prohibition of Access to Reserved Addresses

Access to reserved addresses is prohibited.

- The reserved addresses are provided for the possible future expansion of functions. Do not access these addresses; the correct operation of LSI is not guaranteed if they are accessed.

### 4. Clock Signals

After applying a reset, only release the reset line after the operating clock signal has become stable.

When switching the clock signal during program execution, wait until the target clock signal has stabilized.

- When the clock signal is generated with an external resonator (or from an external oscillator) during a reset, ensure that the reset line is only released after full stabilization of the clock signal. Moreover, when switching to a clock signal produced with an external resonator (or by an external oscillator) while program execution is in progress, wait until the target clock signal is stable.

### 5. Differences between Products

Before changing from one product to another, i.e. to one with a different type number, confirm that the change will not lead to problems.

- The characteristics of MPU/MCU in the same group but having different type numbers may differ because of the differences in internal memory capacity and layout pattern. When changing to products of different type numbers, implement a system-evaluation test for each of the products.

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