



M16C/5LD Group
A/D Converter
Using One-Shot Mode (External Trigger)

R01AN0121EJ0100 Rev.1.00 Mar 15, 2011

1. Abstract

This document describes the setting procedure to use the A/D converter in one-shot mode with an external trigger (input from the ADTRG pin).

2. Introduction

The application example described in this document applies to the following microcomputer (MCU):

• MCU: M16C/5LD Group

This application note can be used with other M16C Family MCUs which have the same special function registers (SFRs) as the above group. Check the manual for any modifications to functions. Careful evaluation is recommended before using the sample code described in this application note.

3. Operation in One-Shot Mode Using an External Trigger

This section describes operation when using the A/D converter in one-shot mode with an external trigger.

- (1) When the ADST bit in the ADCON0 register is set to 1 (A/D conversion start), and input to the ADTRG pin is changed from high to low, A/D conversion starts.
- (2) After completing A/D conversion, the value in the successive conversion register (conversion result) is transferred to the ADi register (i = 0 to 7). At the same time, the IR bit in the ADIC register becomes 1 (interrupt requested), and A/D conversion stops.
- (3) When the input level of the ADTRG pin is changed from high to low, A/D conversion starts again.

When the input level of the ADTRG pin is changed from high to low during A/D conversion, the current A/D conversion is cancelled, then started again.

Figure 3.1 shows Operation Timing in One-Shot Mode Using an External Trigger.

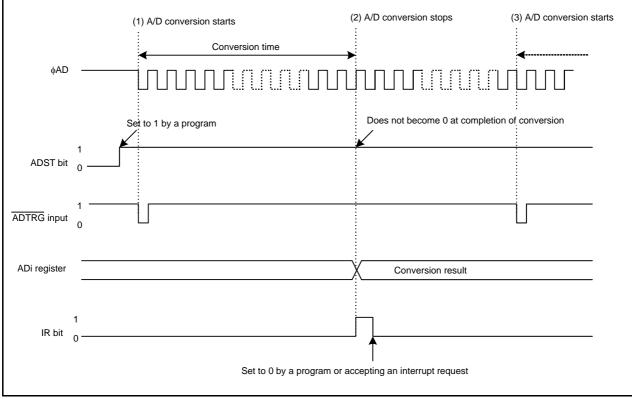


Figure 3.1 Operation Timing in One-Shot Mode Using an External Trigger

4. A/D Conversion Time

This section describes how to calculate A/D conversion time.

4.1 A/D Conversion Cycle

Table 4.1 shows Cycles of A/D Conversion Item. A/D conversion time is described below.

Start processing time depends on which ϕAD is selected.

A/D conversion starts after the start processing time elapses by setting the ADST bit in the ADCON0 register to 1 (A/D conversion start). When reading the ADST bit before starting A/D conversion, 0 (A/D conversion stop) is read. In one-shot mode, the ADST bit becomes 0 at the end processing time and the last A/D conversion result is stored in the ADi register (i = 0 to 7).

One-shot mode:

Start processing time + A/D conversion execution time + end processing time

Table 4.1 Cycles of A/D Conversion Item

A/D Conversion Item		Number of Cycles	
	$\phi AD = fAD$	1 to 2 cycles of fAD	
	φAD = fAD divided by 2	2 to 3 cycles of fAD	
Start processing time	φAD = fAD divided by 3	3 to 4 cycles of fAD	
Start processing time	φAD = fAD divided by 4	3 to 4 cycles of fAD	
	φAD = fAD divided by 6	4 to 5 cycles of fAD	
	φAD = fAD divided by 12	7 to 8 cycles of fAD	
A/D conversion execution time		40 cycles of φAD	
End processing time		2 to 3 cycles of fAD	

4.2 Detecting Completion of A/D Conversion

In one-shot mode, use the IR bit in the ADIC register to detect completion of A/D conversion. When not using an interrupt, set the IR bit to 0 by a program after detection.

When 1 is written to the ADST bit in the ADCON0 register, the ADST bit becomes 1 (A/D conversion start) after start processing time elapses (see Table 4.1 "Cycles of A/D Conversion Item"). Therefore when reading the ADST bit immediately after writing 1, 0 (A/D conversion stop) may be read.

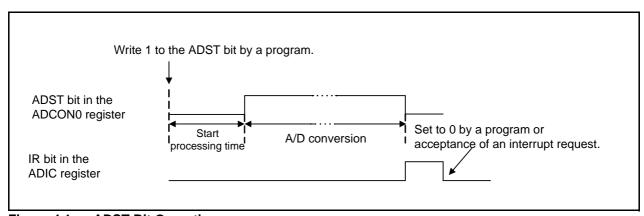


Figure 4.1 ADST Bit Operation

4.3 A/D Operation Clock Frequencies

Table 4.2 lists the A/D Operation Clock Frequencies.

Table 4.2 A/D Operation Clock Frequencies (1, 2)

 $V_{CC} = AV_{CC} = V_{REF} = 3.0$ to 5.5 V, $V_{SS} = AV_{SS} = 0$ V at $T_{opr} = -40$ °C to 85°C unless otherwise specified.

Symbol	Parameter	Measuring Condition	Standard			Unit
Symbol		weasuming Condition	Min.	Тур.	Max.	Offic
φAD A/D α		$4.0 \text{ V} \leq \text{V}_{CC} \leq 5.5 \text{ V}$	2		25	MHz
	A/D operating clock frequency	$3.2~\text{V} \leq \text{V}_{\text{CC}} \leq 4.0~\text{V}$	2		16	MHz
		$3.0 \text{ V} \le \text{V}_{CC} \le 3.2 \text{ V}$	2		10	MHz

Notes:

- 1. Use when $AV_{CC} = V_{CC}$.
- 2. This applies when using one of the A/D converter circuits, with the ADSTBY bit for the unused A/D converter set to 0 (A/D operation stopped (standby)).

5. Settings

Figure 5.1 shows the Setting Procedure in One-Shot Mode Using an External Trigger. Refer to the User's Manual: Hardware for details on registers.

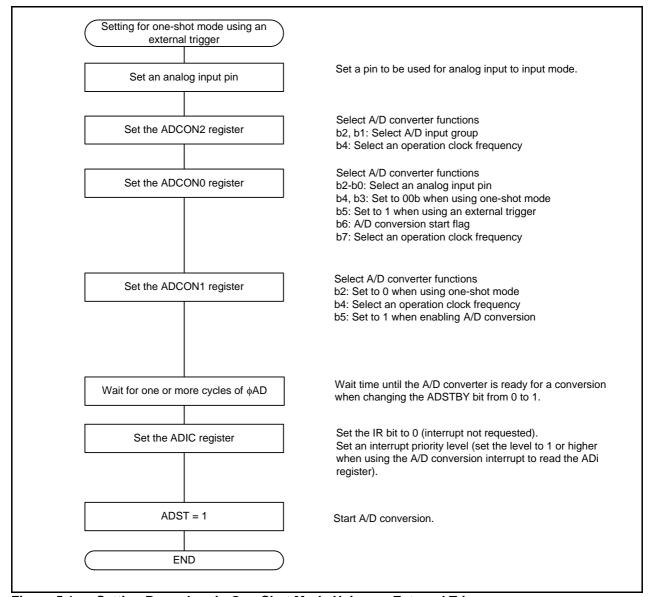


Figure 5.1 Setting Procedure in One-Shot Mode Using an External Trigger

6. Sample Code

A sample code can be downloaded from the Renesas Electronics website. To download, click "Application Notes" in the left-hand side menu of the M16C Family page.

6.1 Sample Code Operation

In one-shot mode, functions listed in Table 6.1 can be selected. The settings used in the sample code are marked with " \checkmark " in the table. The sample code operation is as follows; set the CPU clock as the main clock with no division by executing functions for CPU initialization, transition from 125 kHz on-chip oscillator mode to high-speed mode, and execute the function for A/D conversion in one-shot mode with an external trigger. Then set the I flag to 1 (maskable interrupts enabled). A/D conversion starts when the input level of the $\overline{\text{ADTRG}}$ pin is changed from high to low. Use the A/D conversion interrupt to read the conversion result from the ADi register (i = 0 to 7). Refer to 6.2 Function Tables for details on functions.

Table 6.1 Sample Code Settings

Functions		Settings
A/D converter circuits	✓	AD0
A/D converter circuits		AD1
	✓	f1
		f1 divided by 2
Operating clock		f1 divided by 3
Operating clock WAD		f1 divided by 4
		f1 divided by 6
		f1 divided by 12
		Software trigger
A/D conversion start conditions	✓	Trigger by ADTRG
		Timer Trigger
	✓	1 pin from AN0 to AN7
Analog input pins ⁽¹⁾		1 pin from ANO_0 to ANO_7
		1 pin from AN2_0 to AN2_7

Note:

1. The number of usable analog input pins varies depending on pin numbers of the package used. Refer to the "A/D Converter" in the User's Manual: Hardware for details.

6.2 Function Tables

Function Tables for This Document

Declaration	void ad_oneshot_ext(void)	
Outline	A/D conversion in one-shot mode with an external trigger	
Argument	None	
Variable	None	
Returned value	None	
Function	Set the A/D converter to one-shot mode and set the functions as marked in Table 6.1. Set an analog input pin to AN0, P10 to input mode, and the interrupt priority level of the A/D conversion interrupt to 1.	

Declaration	void _ad_converter(void)
Outline	A/D converter interrupt
Argument	None
Variable	None
Returned value	None
Function	Executed when an A/D conversion interrupt occurs. Execute read_ad_register().

Declaration	unsigned short read_ad_register(unsigned char ch)		
Outline	Read A/D register		
Argument	unsigned char ch	Select the A/D register to be read	
Variable	None		
Returned value	unsigned short read_ad_data	Value read from the A/D register	
Function	Read the A/D register selected with the unsigned char ch argument. Then return the read value as a returned value.		

Other Function Tables

Declaration	void mcu_init(void)
Outline	CPU initialization
Argument	None
Variable	None
Returned value	None
Function Set to single-chip mode. Switch the CPU clock from 125 kHz on-chip oscillator divided-by-8 to 125 kHz on-chip oscillator mode divided-by-1.	

Declaration	void highspeed_from_foco125k(void)	
Outline	Transition from 125 kHz on-chip oscillator mode to high-speed mode	
Argument	None	
Variable	None	
Returned value	None	
Function	Switch the CPU clock from 125 kHz on-chip oscillator mode (fOCO-S divided by 1) to high-speed mode.	

7. Reference Documents

M16C/5LD Group User's Manual: Hardware Rev.1.10

The latest version can be downloaded from the Renesas Electronics website.

Technical Update/Technical News

The latest information can be downloaded from the Renesas Electronics website.

M16C Series/R8C Family C Compiler Package V.5.45 C Compiler User's Manual Rev.3.00 The latest version can be downloaded from the Renesas Electronics website.

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M16C/5LD Group

Revision History Using One-Shot Mode (External Trigger)

Rev. Date	Date	Description	
	Date	Page	Summary
1.00	2011.03.15	_	First edition issued

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General Precautions in the Handling of MPU/MCU Products

The following usage notes are applicable to all MPU/MCU products from Renesas. For detailed usage notes on the products covered by this manual, refer to the relevant sections of the manual. If the descriptions under General Precautions in the Handling of MPU/MCU Products and in the body of the manual differ from each other, the description in the body of the manual takes precedence.

1. Handling of Unused Pins

Handle unused pins in accord with the directions given under Handling of Unused Pins in the manual.

The input pins of CMOS products are generally in the high-impedance state. In operation with an unused pin in the open-circuit state, extra electromagnetic noise is induced in the vicinity of LSI, an associated shoot-through current flows internally, and malfunctions occur due to the false recognition of the pin state as an input signal become possible. Unused pins should be handled as described under Handling of Unused Pins in the manual.

2. Processing at Power-on

The state of the product is undefined at the moment when power is supplied.

The states of internal circuits in the LSI are indeterminate and the states of register settings and pins are undefined at the moment when power is supplied.

In a finished product where the reset signal is applied to the external reset pin, the states of pins are not guaranteed from the moment when power is supplied until the reset process is completed.

In a similar way, the states of pins in a product that is reset by an on-chip power-on reset function are not guaranteed from the moment when power is supplied until the power reaches the level at which resetting has been specified.

3. Prohibition of Access to Reserved Addresses

Access to reserved addresses is prohibited.

 The reserved addresses are provided for the possible future expansion of functions. Do not access these addresses; the correct operation of LSI is not guaranteed if they are accessed.

4. Clock Signals

After applying a reset, only release the reset line after the operating clock signal has become stable. When switching the clock signal during program execution, wait until the target clock signal has stabilized.

— When the clock signal is generated with an external resonator (or from an external oscillator) during a reset, ensure that the reset line is only released after full stabilization of the clock signal. Moreover, when switching to a clock signal produced with an external resonator (or by an external oscillator) while program execution is in progress, wait until the target clock signal is stable.

5. Differences between Products

Before changing from one product to another, i.e. to one with a different part number, confirm that the change will not lead to problems.

— The characteristics of MPU/MCU in the same group but having different part numbers may differ because of the differences in internal memory capacity and layout pattern. When changing to products of different part numbers, implement a system-evaluation test for each of the products.

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Renesas Electronics America Inc. 2880 Scott Boulevard Santa Clara, CA 95050-2554, U.S.A. Tel: +1-408-588-6000, Fax: +1-408-588-6130

Renesas Electronics Canada Limited 1101 Nicholson Road, Newmarket, Ontario L3Y 9C3, Canada Tel: +1-905-898-5441, Fax: +1-905-898-3220

Renesas Electronics Europe Limited
Dukes Meadow, Millboard Road, Bourne End, Buckinghamshire, SL8 5FH, U.K
Tel: +44-1628-565-100, Fax: +44-1628-585-900 Renesas Electronics Europe GmbH

Arcadiastrasse 10, 40472 Düsseldorf, Germany Tel: +49-211-65030, Fax: +49-211-6503-1327

Renesas Electronics (China) Co., Ltd.
7th Floor, Quantum Plaza, No.27 ZhiChunLu Haidian District, Beijing 100083, P.R.China
Tel: +86-10-8235-1155, Fax: +86-10-8235-7679

Renesas Electronics (Shanghai) Co., Ltd.
Unit 204, 205, AZIA Center, No. 1233 Lujiazui Ring Rd., Pudong District, Shanghai 200120, China
Tel: +86-21-5877-1818, Fax: +86-21-6887-7589 / -7898

Renesas Electronics Hong Kong Limited
Unit 1601-1613, 16/F., Tower 2, Grand Century Place, 193 Prince Edward Road West, Mongkok, Kowloon, Hong Kong
Tel: +852-2868-9318, Fax: +852 2886-9022/9044

Renesas Electronics Taiwan Co., Ltd.
7F, No. 363 Fu Shing North Road Taipei, Taiwa
Tel: +886-2-8175-9600, Fax: +886 2-8175-9670

Renesas Electronics Singapore Pte. Ltd. 1 harbourFront Avenue, #06-10, keppel Bay Tower, Singapore 098632 Tel: +65-6213-0200, Fax: +65-6278-8001

Renesas Electronics Malaysia Sdn.Bhd.
Unit 906, Block B, Menara Amcorp, Amcorp Trade Centre, No. 18, Jln Persiaran Barat, 46050 Petaling Jaya, Selangor Darul Ehsan, Malaysia Tel: +60-3-7955-9390, Fax: +60-3-7955-9510

Renesas Electronics Korea Co., Ltd.
11F., Samik Lavied or Bidg., 720-2 Yeoksam-Dong, Kangnam-Ku, Seoul 135-080, Korea Tel: +82-2-558-3737, Fax: +82-2-558-5141

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