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M32C/82,83 Group

Variable-length clocked synchronous serial communication by using Intellingent I/O Group 2

Abstract

This application note describes the variable-length clock serial I/O (synchronous serial I/O) operation of Intelligent I/O Group 2.

2. Introduction

This application note is applied to the M32C/83 group microcomputer.

This program can also be used when operating other microcomputers within M16C family, provided they have the same SFR (Special Function Registers) as the M32C/83 group. However, some functions may have been modified. Refer to the User's Manual for details. Use functions covered in this Application Note only after careful evaluation.

3. Detailed description

This application example offers features of the variable-length serial I/O shown in Table 1.

The transmit data is output from pin ISTxD2, and the transfer clock is output from pin ISCLK2. Also the receive data is input from ISRxD2.

Item	Definition	Selection in this	
		example	
Transfer clock	Internal Clock	Yes	
	External Clock		
T	LSB First	Yes	
Transfer format	MSB First		
Polarity Selection of pins TxD	Non Reverse Output	Yes	
and RxD	Reverse Output		
Too a considerate constant Francisco	When register G2TB becomes empty		
Transmit Interrupt Factor	When the transmission is completed	Yes	

Table 1 Clock Synchronous Serial I/O Option Features and Selected Features

(1) Transfer speed definition when using Channel 0

This example uses Channel 0 in the wave generation function. Select "Use the output of the communication function" for this operation. Base Timer is reset when the set value of register G2P00 matches the content of Base Timer. The transfer speed (the period of the transfer clock) is defined by the following equation. Here "fBT2" and "n" represents the count source of Base Timers and value of register G2P00 respectively.

Transfer Speed = $fBT2 / \{2x(n+2)\}$

When using in transmitting only, the transfer clock must be 6 divide or greater of Base Timer clock (n=1 or greater).

When using in transmitting and receiving, the transfer clock must be 20 divide or greater of Base Timer clock (n=8 or greater).

For example, when fBT2=30MHz, the max transfer speed is 5Mbps in transmitting and 1.5 Mbps in transmitting and receiving.

(2) How to generate the transfer clock by using Channel 2

This example uses Channel 2 in the phase-delayed waveform output mode of the wave generation function. The set value of register G2P02 must be "(n+2)/2" when register G2P00 is set to "n".



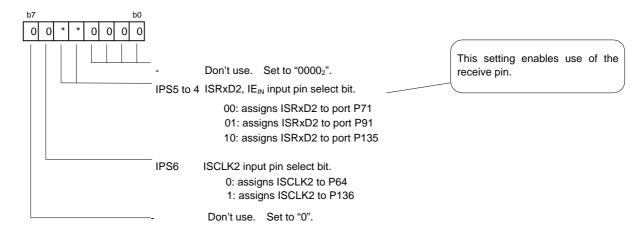
3.1 Register setting

This section shows the setting procedures and setting values to proceeds section "3. Detailed Description". For detail configuration of each register, please refer to M32C/83 Group HARDWARE MANUAL.

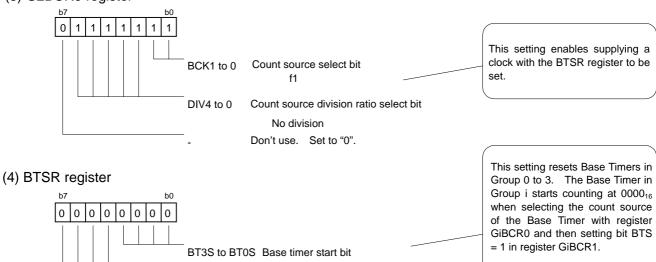
(1) Disabling an Interrupt

Set I flag=0. Or set bits ILV2 to $0=000_2$ in register IIOkIC (k=0 to 11) where the interrupt request of the Intelligent I/O is assigned.

(2) IPS register

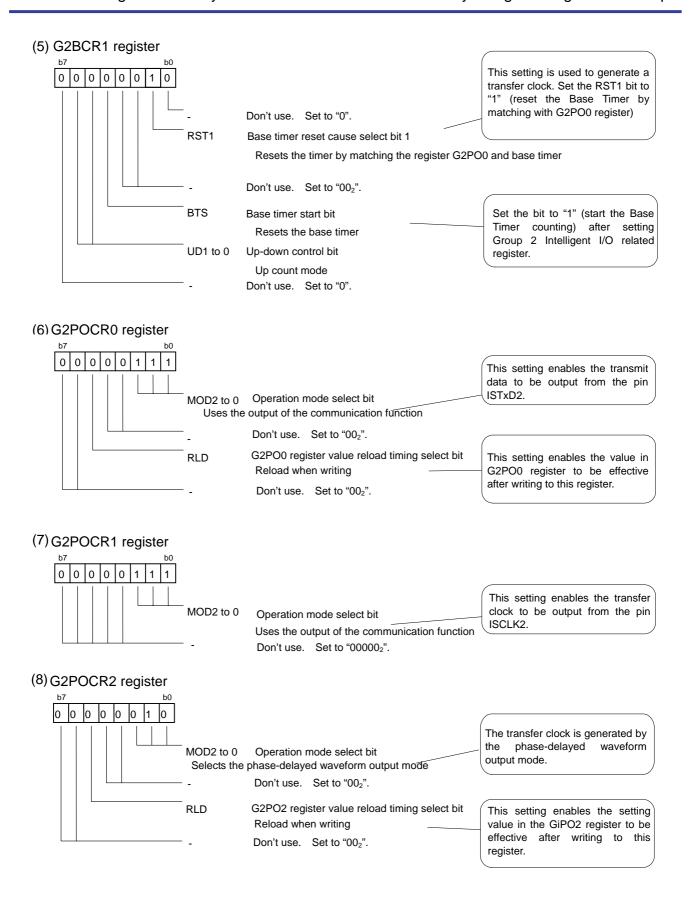


(3) G2BCR0 register



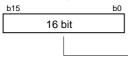
Resets Base Timers in Group 0 to 3.

Don't use. Set to "00002".





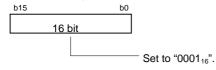




Set the transfer speed

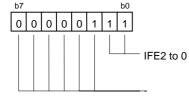
When the setting value is "n", the transfer speed is as follows.

(10) G2PO2 register



Setting to " 0001_{16} " enables the transfer clock to be generated after starting the Base Timer counting in step (12).

(11) G2FE register

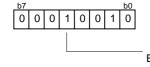


Channel 2 to 0 function enable bit Enables Channel 2 to 0 to function

Don't use. Set to "000002".

Set the IFE bit of unused Channel to "0".

(12) G2BCR1 register

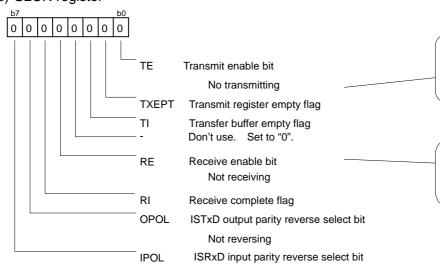


BTS Base timer start bit

Starts counting base timer

Setting the BTS bit to 1 (start the Base Timer counting) enables the transfer clock to be generated.

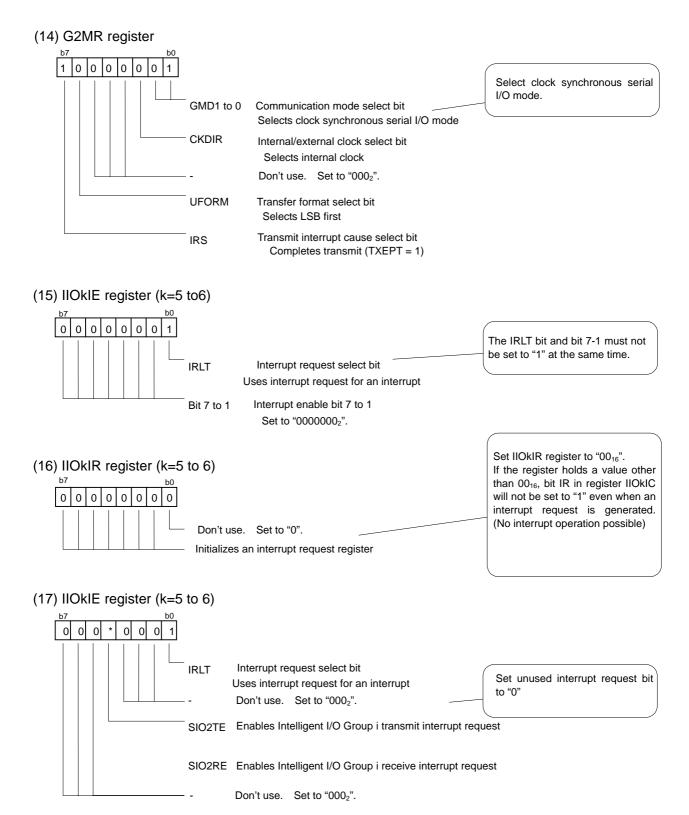
(13) G2CR register



Not reversing

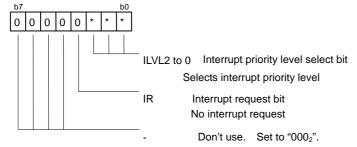
TI, TXEPT and RI bits are read-only. Write-action to these bits effect nothing.

Transmission and Receive Enable bits must be set after setting the other communication related registers.





(18) IIOkIC register (k=5 to 6)



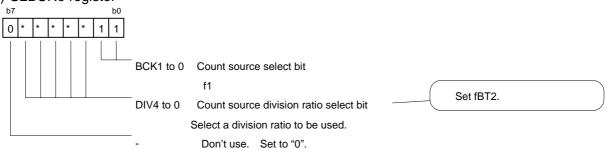
(19) PSC register, PSLa register (a=0,1), PSb register (b=0,1,7) Set the ISTxD2, ISCLK2 pin.

(20) Enabling an interrupt (I flag ="1")

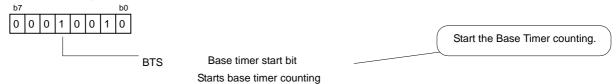
(21) G2BCR1 register



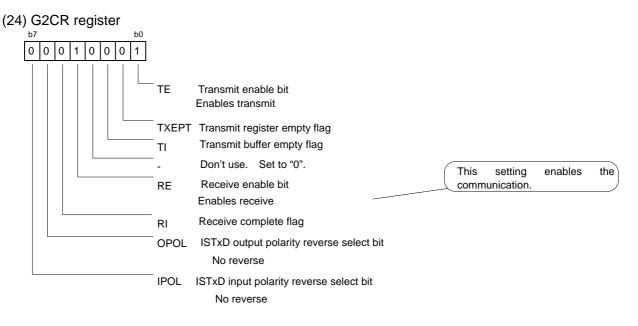
(22) G2BCR0 register

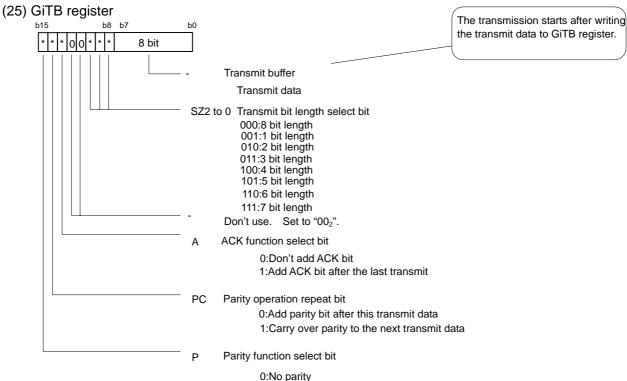


(23) G2BCR1 register









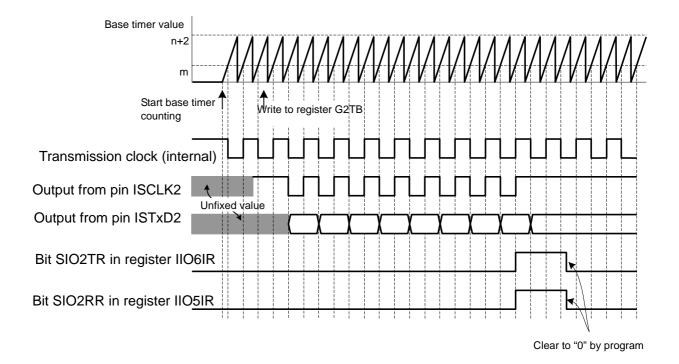
1:Selects parity

3.2 Precaution on Interrupts

You must clear register II0kIR to 00_{16} during the respective interrupt routine. If you skip this procedure, bit IR in register II0kIC will not be set to "1" when the respective Intelligent I/O generates the interrupt request, resulting in no interrupt being invoked.

3.3 Timing Diagram

The following time chart shows the serial I/O operation in this example.



n: setting value of G2PO0 m: setting value of G2PO2

4. The example of a reference program

```
FILE NAME: rej05b0396 src.c
  Version: 1.00
  FUNCTION: Variable-length clocked synchronous */
  serial communication by using Intelligent I/O Group 2 */
   include file
   *********
#include <stdio.h>
#include "sfr32c83.h"
/************************/
   Function difinition
  **********
void receive_int(void);
#pragma INTERRUPT receive_int
void trans_int(void);
#pragma INTERRUPT trans_int
/***********************/
   Global Variable Definition
static char rec buff;
static unsigned short send_bits = 0;
/*************************/
  main Function
/***********************/
void main(void){
   _asm(" fclr i");
                          /* Disable the interrupt */
   /* main clock set */
                           /* protect off */
   prc0 = 1;
   mcd = 0x12;
                           /* main clock : no division */
                           /* protect on */
   prc0 = 0;
                           /* assigns ISRxD2 to P71 */
   ips = 0x00;
   /* base clock initial set */
   g2bcr0 = 0x7f;
                           /* Supply clock with BTSR register */
                            /* b0,b1: count source f1
                               b2 to b6 : count source division ratio : No division */
   btsr = 0x00:
                           /* Reset the base timer */
   g2bcr1 = 0x02;
   /* iio group0 initial set */
   g2pocr0 = 0x07; /* ISTxD2 select */
g2pocr1 = 0x07; /* ISCLK2 select */
                           /* tarnsmit clock */
   g2pocr2 = 0x02;
   g2po0 = 1000-2;
                            /* BRG = fTB / [(998+2)*2] */
   g2po2 = 1;
                           /* ch0 ch1 ch2 enable */
   q2fe = 0x07;
   g2bcr1 = 0x12;
                           /* Start the base timer counting */
   g2cr = 0x00;
                            /* Disable the communications */
   g2mr = 0x81;
                            /* Clocked synchronous serial, LSB first */
```

```
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```

```
/* iio group0 interrupt initial set */
   iio5ie = 0x01;
                              /* Use the interrupt request for an interrupt
   iio6ie = 0x01;
                              /* Use the interrupt request for an interrupt
   iio5ir = 0x00;
   iio6ir = 0x00;
                              /* Enable interrupt to gr1 sio receive */
   iio5ie = 0x11;
                              /* Enable interrupt to gr1 sio trans
   iio6ie = 0x11;
                              /* Select interrupt priority level */
   iio5ic = 0x03;
   iio6ic = 0x03;
                              /* Select interrupt priority level */
   /* port set */
    psc = 0x01;
   psl1 = 0x00;
   psl0 = 0x10;
   ps1 = 0x01;
   ps0 = 0x10;
   psl0 = 0x10;
   ps0 = 0x10;
   /* interrupt enable
                       */
    _asm("fset
   /* sio initial setting */
   g2bcr1 = 0x02;
                                /* Start the base timer counting */
                               /* b0,b1: count source f1
   g2bcr0 = 0x7f;
                                   b2to b6: count source division ratio: No division */
   g2bcr1 = 0x12;
                                /* Start the base timer counting */
   g2cr = 0x11;
                                   transmit / receive
   g2tb = 0x0200;
                                /* 2Bit Write the transmit data */
   while(1);
  iio interrupt */
void receive_int(void){
                             /* Clear interrupt request */
   iio5ir = 0x00;
   rec_buff = g2rb;
                              /* Receive the transmit data */
void trans int(void){
   int wait:
   static char send_data;
   iio6ir = 0x00;
                             /* Clear interrupt request */
   send_data ++;
   /* Change the transmit data length */
   if(send\_bits == 0x600){
        send_bits = 0x200;
   }else{
        send_bits = 0x600;
   /* Weight to measure with oscilloscope is usually unneeded. */
   for(wait=0; wait < 2000; wait ++);
   g2tb = send_bits + send_data; /* Write the transmit data */
     ----- end program */
```

5. Example Waveform and Result

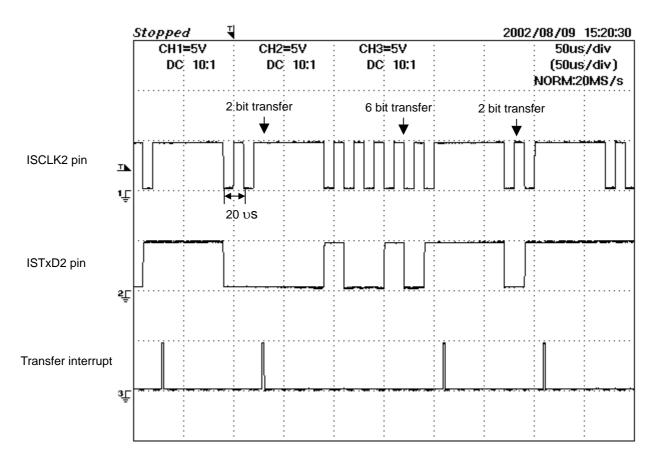
The transmit clock is output from a pin ISCLK2 (P64) and the transmit data is output from a pin ISTxD2 (P70) by using the Intelligent I/O Group 2.

Conditions: Supply voltage = 5V,

Main clock (Xin) = 10MHz

Base Timer Count Source (fBT2) = 30MHz (f1 no division)

Transmission speed : 50kbps (10MHz / 200 : register G2P00 value = 98) \rightarrow 20 μ / bit



Measurement result from oscilloscope



6. Reference

HADWARE MANUAL Refer to the M32C/83 group HARDWARE MANUAL.

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REVISION HISTORY

Rev. Issue date	Revised			
	issue date	Page	Point	
1.00	Jan 30, 2004	1	First edition issued	
1.01	Sep.16,2004	2, 4	Inverted waveform output mode → phase-delayed waveform mode	



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