

A Note on Using Real-Time OS M3T-MR32R

--On Entering a Task for the Call or Acceptance of a Rendezvous or the Acquisition of a Variable-Size Memory Pool into a SUSPEND State--

Please take note of the following problem in using the M3T-MR32R real-time OS:

- On entering a task for the call or acceptance of a rendezvous or the acquisition of a variable-size memory pool into a SUSPEND state

1. Versions Concerned

M3T-MR32R V.3.00 Release 1 through V.3.50 Release 2

2. Description

When such a task as the call or acceptance of a rendezvous or the acquisition of a variable-size memory pool is entered into a SUSPEND state by an `isus_tsk` system call, the task will not go to a WAIT-SUSPEND state.

3. Conditions

This problem occurs if the following conditions are all satisfied:

- (1) A task issues any of the following system calls; then goes to a WAIT state:
`acp_por`, `tacp_por`, `cal_por`, `tcal_por`, `get_blk`, and `tget_blk`
- (2) An `isus_tsk` system call is issued inside the interrupt handler invoked during the execution of the system call issued in (1).
- (3) The task that is the object of `isus_tsk` in (2) is the one that issued a system call in (1).

4. Workaround

This problem can be circumvented either of the following ways:

- (1) Before and after issuing the system call stated in Condition (1) above, disable and enable an interrupt respectively.

Example:

```
-----  
void task(INT stacd)  
{  
    .....  
  
    /* Disable an interrupt */  
  
    asm(" mvfc    R0,PSW¥n"  
        " and3    R0,R0,#0xFFBF¥n"  
        " mvtc    R0,PSW¥n");  
  
    ercd = cal_por((VP)msg,&size,ID_por2,0x1,7);  
  
    /* Enable the interrupt */  
    asm(" mvfc    R0,PSW¥n"  
        " or3     R0,R0,#0x0040¥n"  
        " mvtc    R0,PSW¥n");  
  
    .....  
}  
-----
```

- (2) Perform the following steps to enter a task into a SUSPEND state:
1. Issue an ista_tsk system call to invoke the task to enter into SUSPEND state.
 2. Issue a sus_tsk system call from the invoked task mentioned above.

Example:

```
-----  
void handler(void)  
{  
    .....  
  
    /* Comment out isus_tsk, issue ista_tsk to invoke ta  
       to enter into SUSPEND state, and pass ID of  
       objective task to ista_tsk as startup code */  
  
    /* isus_tsk( ID_task1 ); */  
    ista_tsk( ID_DoSuspend,(INT)ID_task1 );  
  
    .....  
}
```

```
}
```

```
void DoSuspend(INT tskid)
```

```
{
```

```
    sus_tsk(tskid);
```

```
}
```

```
-----
```

5. Schedule of Fixing the Problem

We plan to fix this problem in our next release of the product.

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