

User Manual

DA16600 Example Application Manual

UM-WI-018

Abstract

DA16200/DA16600 is a highly integrated ultra-low-power Wi-Fi system on a chip (SoC) and allows users to develop the Wi-Fi solution on a single chip. This document is an SDK guide document intended for developers who want to program using the DA16200 chipset. And it describes the SDK API and peripheral device drivers and interfaces.

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1 Terms and Definitions

| | |
|-------|---|
| AP | Access Point |
| API | Application Programming Interface |
| BD | Bluetooth Device |
| COM | Communication Port |
| CTS | Clear to Send |
| DHCP | Dynamic Host Configuration Protocol |
| DPM | Dynamic Power Management |
| EVB | Evaluation Board |
| FW | Firmware |
| HW | Hardware |
| GAP | Generic Access Profile |
| GATT | Generic Attribute Profile |
| GPIO | General Purpose Input / Output |
| GTL | Generic Transport Layer |
| HTTP | Hypertext Transfer Protocol |
| HTTPS | Hypertext Transfer Protocol Secure |
| I2C | Inter-Integrated Circuit (bus) |
| IDE | Integrated Development Environment |
| iOS | iPhone Operating System |
| IoT | Internet of Things |
| JLINK | JTAG Link |
| JSON | JavaScript Object Notation |
| JTAG | Joint Test Action Group |
| LED | Light emitting diode |
| LAN | Local Area Network |
| OTA | Over the Air |
| OTP | One Time Programmable |
| PC | Personal Computer |
| POR | Power on Reset |
| PWM | Pulse Width Modulation |
| RBP | Raspberry Pi |
| RF | Radio Frequency |
| RTOS | Real Time Operating System |
| RTS | Request to Send |
| SDK | Software Development Kit |
| SoC | System on Chip |
| SPI | Serial Peripheral Interface |
| SVC | Service |
| SW | Software |
| TCP | Transmission Control Protocol |
| UART | Universal Asynchronous Receiver/Transmitter |
| UDP | User Datagram Protocol |
| USB | Universal Serial Bus |

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| | |
|-------|-------------------------------|
| UUID | Universally Unique Identifier |
| Wi-Fi | Wireless Fidelity |
| XIP | Execute in Place |

2 References

- [1] UM-WI-002, DA16200 SDK Programmer Guide
- [2] UM-B-143, Dialog External Processor Interface
- [3] UM-B-117, DA14531 Getting Started Guide
- [4] UM-B-119, DA14531 SW Platform Reference
- [5] UM-WI-044, DA16600 Provisioning the Mobile App for Android/iOS
- [6] UM-WI-035, DA16200 SDK Memory Map

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3 Introduction

The Dialog DA16600 module is also known as "Combo". The terms "Combo" and "DA16600" may be used interchangeably in this document. The Dialog DA16600 module is comprised of the DA16200 (Wi-Fi) and DA14531 (Bluetooth® LE) SoCs. This document describes the test steps and code walkthroughs of several Combo example applications.

3.1 DA16600 Module Evaluation Board

Figure 1 shows the hardware configuration of the DA16600 EVB.

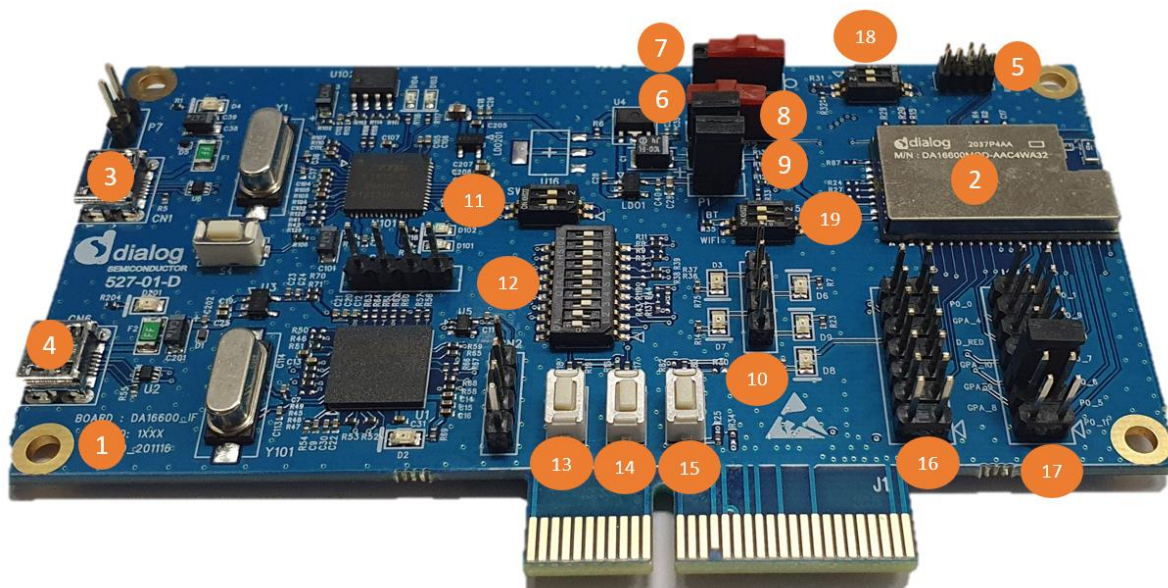



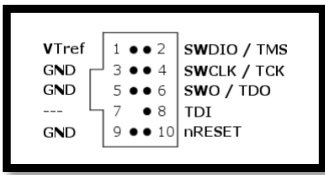
Figure 1: DA16600 EVB

Refer to the following description for the components on the DA16600 EVB components:

Table 1: Components Description on the DA16600 EVB

| ID | Name | Description |
|----|-----------------|--|
| 1 | Main board | DA16600 module EVB (DA16600MOD-AAC) |
| 2 | DA16600MOD-AAC | Dialogs Wi-Fi and Bluetooth® LE Module |
| 3 | USB Port (WiFi) | Provides UART0 for debug and UART1 for test |
| 4 | USB Port (BLE) | Connect directly to DA14531 for debug only Note: Do not use this port during normal operation |
| 5 | JTAG Connector | Connector for IARs I-jet JTAG Debugger |

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| ID | Name | Description |
|----|------------------|--|
| | |   <p>Note: Pin 7 on the I-Jet debugger cable is keyed with a white plug so pin 7 must be removed on EVB</p> |
| 6 | RTC Wake up2 key | Switch to wake up the board from Sleep mode |
| 7 | RTC Power key | Switch to turn the EVB on and off |
| 8 | Jumper (P2) | Jumper to measure the current used by the Wi-Fi device For normal operation, this jumper must be shorted |
| 9 | Jumper (P1) | Jumper to measure the current used by the Bluetooth® LE device For normal operation, this pin must be shorted |
| 10 | Connector CN4 | GPIO test purpose connector To test GPIO in J2 and J14, connect to LED by this connector |
| 11 | Switch SW3 | Switch to connect directly to DA14531 and use UART to check Bluetooth® LE performance Set this switch off for normal operation |
| 12 | Switch SW7 | Multipurpose switch Set this switch off for normal operation |
| 13 | Switch S2 | Factory reset button using GPIOA7 To enable this button, set Pin2 of SW7 to on |
| 14 | Switch S1 | WPS button using GPIOA6 To enable this button, set Pin1 of SW7 to on |
| 15 | Switch S3 | The reset button of DA14531 in test mode |
| 16 | Connector J2 | GPIO connector |
| 17 | Connector J14 | GPIO connector |
| 18 | Switch SW4 | Switch to control RF switch in DA16600MOD at test mode |
| 19 | Switch SW5 | Switch to check the current consumption using a power meter kit |

3.2 Example 1: Bluetooth® LE Assisted Wi-Fi Provisioning

This example demonstrates how the DA16600 can be used in a product such as a "Wi-Fi door lock" where the Wi-Fi is the main communication interface to the server and the Bluetooth® LE interface only assists with the "Wi-Fi Provisioning" during the product's initial "Out-of-Box" setup.

NOTE

This example requires a Bluetooth® LE peer provisioning application described in Ref. [5], it is to configure the DA16600 Wi-Fi parameters including the Wi-Fi home router's SSID and password and the server's

NOTE

connection information. See Section 6.4.1.5 and Ref. [5] for details on the provisioning protocol required for the mobile app.

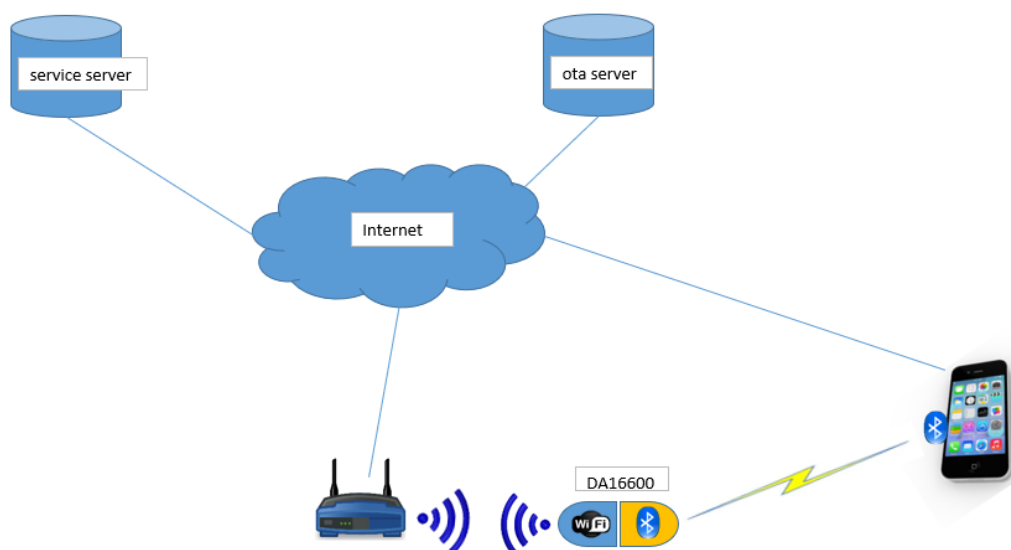


Figure 2: Bluetooth® LE Assisted Wi-Fi Provisioning

3.3 Example 2: Bluetooth® LE Firmware OTA Download via Wi-Fi

Once the Wi-Fi has been successfully provisioned and is up and running as described in [Example 1](#), the DA16600 device can receive notifications over Wi-Fi from a remote service server indicating that there is new Wi-Fi or Bluetooth® LE firmware available for the DA16600. Upon receipt of the notification, the DA16600 can securely download the new firmware from an OTA server via Wi-Fi, store the firmware in its flash memory and then trigger the firmware update.

3.4 Example 3: Gas Leak Detection Sensor

This example demonstrates how a DA16600 can wirelessly interact with a standalone Gas Leak Detection Sensor via Bluetooth® LE and communicate events to a server over Wi-Fi.

A virtual gas density check sensor is attached to the Bluetooth® LE wireless interface of the DA16600. The DA16600 is operating in low-power mode and periodically checks the gas density level at a time interval defined by the user. When a certain gas density level value is reached, the Wi-Fi device is activated and a "gas leak" event is created and sent to the Wi-Fi device. The Wi-Fi device then posts the "gas leak" event to a cloud server where a user is notified, and action can be taken.

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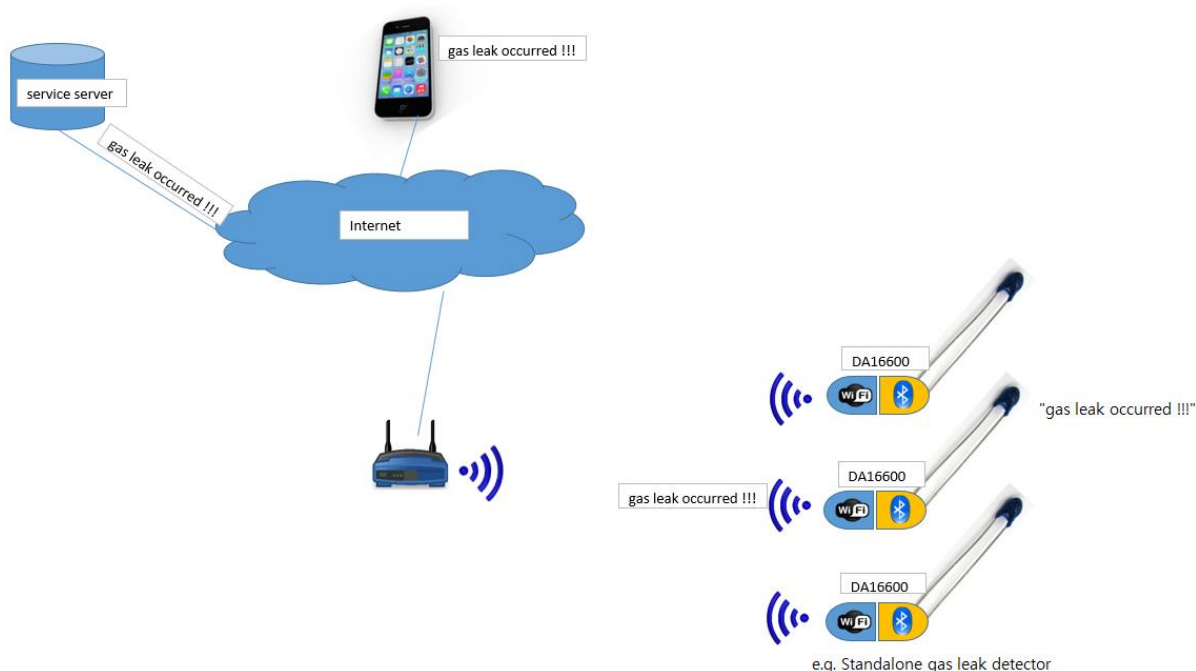


Figure 3: Standalone Gas Leak Detection Sensor

3.5 Example 4: DA14531 Peripheral Driver Examples

This example shows how the DA16200 uses peripheral devices which are connected to the DA14531. An application running in the DA16200 can configure and run peripheral driver functions through GTL.

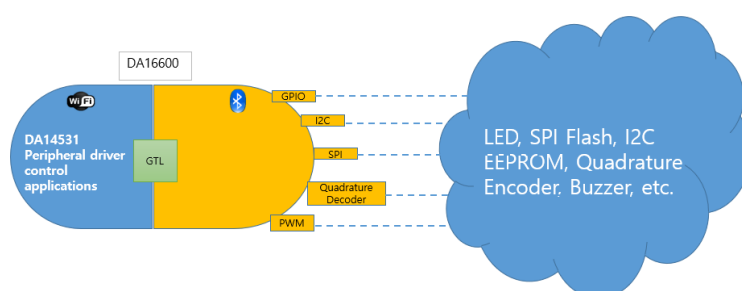


Figure 4: DA14531 Peripheral Device Control

3.6 Example 5: TCP DPM Client

This example demonstrates how the DA16600 module runs a TCP client in a low-power mode where the DA16200 stays in DPM mode and the DA14531 stays in Extended sleep mode.

A key feature of the DA16600 module is that while in sleep mode it can receive and process a Wi-Fi packet from a network peer or Bluetooth® LE data from a Bluetooth® LE peer. After either a Wi-Fi packet or Bluetooth® LE data has been handled, the DA16600 enters sleep mode again to save power.

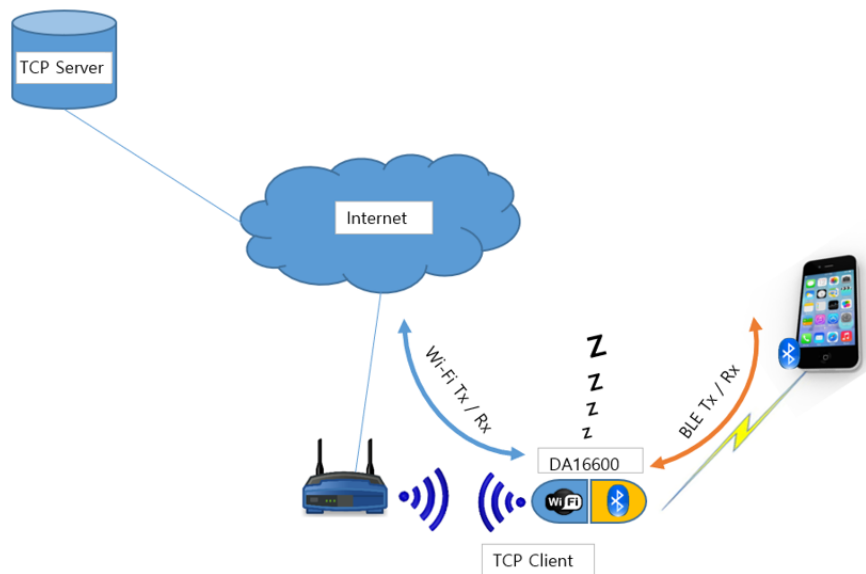


Figure 5: DA16600 DPM Communication

3.7 Example 6: IoT Sensor Gateway

In this example, the DA16600 plays the role of a gateway device for multiple Bluetooth® LE temperature sensors. A Bluetooth® LE sensor posts the current temperature value periodically via the notify function of Bluetooth® LE. The Bluetooth® LE chip of the DA16600 gathers the information and asks Wi-Fi to (periodically) post notifications to a service server in the cloud.

| NOTE |
|--|
| DA14531 can maintain a maximum of three connections. |

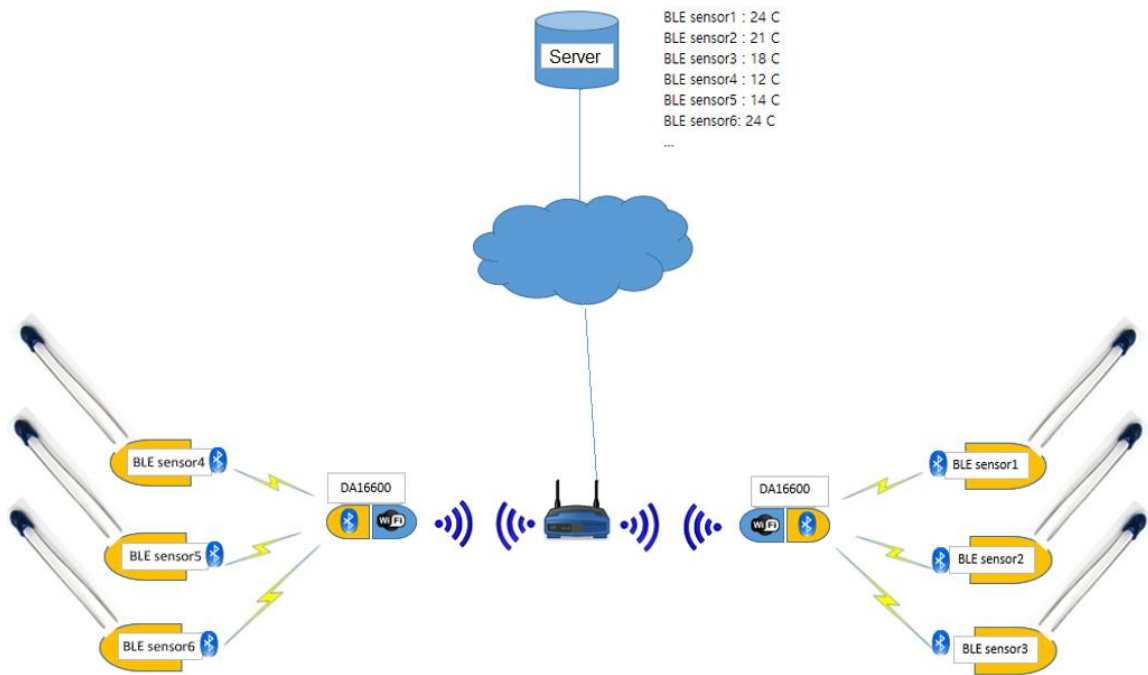


Figure 6: IoT Sensor Gateway

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4 Software Build and Flashing Guide

The DA16600 module includes two SoC chips (DA16200 and DA14531). The firmware images of each SoC are stored in the SPI flash (SFLASH onwards) of the DA16600 module. The SFLASH is only accessible by DA16200. There is no separate flash memory installed that DA14531 can access directly. This means that a firmware image for DA14531 should be written in the SFLASH of the DA16200 and transferred to DA14531 at runtime by DA16200.

The list of firmware images needed to run each SoC chip:

DA16200: Wi-Fi chip

- Three image files:
 - **BOOT** image: secondary bootloader
 - **SLIB** image: RF RAM library and TIM image (which is for the low-power operation of DA16200)
 - **RTOS** image: main operation software into which user applications are built
- Code storage memory
 - SFLASH of DA16200

DA14531: Bluetooth® LE chip

- Single image file:
 - Main image: main operation software into which user applications are built
- Code storage memory
 - SFLASH of DA16200 or OTP memory (32 kB allocated for OTP image)
 - OTP memory can be used to burn a default image. If an OTA firmware update is needed, then the SFLASH of the DA16200 should be used

4.1 SFLASH Memory Map

The SFLASH memory map is described in Section 3.2 of Ref. [6]. And here are some more details.

```
[DA16600_SDK_ROOT]\core\hal\inc\da16200_map.h

/* User Area #1 */
#define SFLASH_USER_AREA_1_START      0x00390000
#define SFLASH_USER_AREA_1_END        0x003FD600

/* User Firmware */ ← DA14531 firmware is stored
#define SFLASH_USER_FW_1      SFLASH_USER_AREA_1_START      /* 0x390000 - 448kbyte */
#define SFLASH_BLE_FW_START (SFLASH_USER_AREA_1_START+0x2000) /* 0x00392000 64KB */
```

The map has two image banks allocated for each type of DA16200 image (RTOS and SLIB), and for the DA14531 image. Two slots are used for an OTA operation taking turns.

There are two user areas: one is 364 kB, the other is 448 kB.

The next sections describe how to build software for the DA16200 and the DA14531.

4.2 Build the DA16200 Software

In the DA16600 SDK, use the IAR IDE to open the IAR workspace file (~SDK/apps/da16600/get_started/DA16xxx.eww).

For information on how to install and use the IAR IDE on your PC, see Section 2.2 in Ref. [1]. You can configure the software before you start to build. Open the file

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"~SDK/apps/dal6600/get_started/inc/ble_combo_features.h" to configure an example application.

To test **Example 1**, **2**, or **3**, make the following changes in **ble_combo_features.h** to build "DA16200_SW_1". If security needs to be enabled, then enable `_WIFI_SVC_SECURITY__` as well ("A16200_SW_1b"):

- DA16200_SW_1
 - Enable `__COMBO_SAMPLE_BLE_PERI_WIFI_SVC__`
 - Disable the other sample defines (`__COMBO_SAMPLE_XXX`)
- DA16200_SW_1b
 - Enable `__COMBO_SAMPLE_BLE_PERI_WIFI_SVC__`
 - Enable `__WIFI_SVC_SECURITY__`
 - Disable the other sample defines (`__COMBO_SAMPLE_XXX`)

NOTE

The difference between DA16200_SW_1b and DA16200_SW_1 is when a Bluetooth® LE peer mobile application tries to connect to the DA16600 (with DA16200_SW_1b), a pairing procedure is requested.

Two pairing modes are depending on your mobile phone's Bluetooth authentication capability configuration:

- **Legacy Pairing:** the mobile application may show an input box and ask you to enter a passkey that can be found on the display of the DA16600 HW, and then you need to enter the exact passkey on your smartphone to successfully connect to the DA16600
- **Secure Connection Pairing (SC Pairing):** the mobile application may show a PIN code on your mobile and ask you to compare the pin code with the one printed on the display of the DA16600 HW. If the pin codes match, click the **OK** button to connect the DA16600 to your mobile application

The DA16600 example currently can save bond information for up to ten Bluetooth® LE peers.

Once bond information is put in your mobile phone, your mobile phone's Bluetooth® LE peer application can connect to the DA16600 without the need to repeat the pairing process. If either party lost the pairing credential, the pairing process starts again when you reconnect.

For **Example 4**, make the following changes to build **DA16200_SW_2**:

- Enable `__COMBO_SAMPLE_BLE_PERI_WIFI_SVC_PERIPHERAL_SAMPLE__`
- Disable the other sample defines (`__COMBO_SAMPLE_XXX`)

For **Example 5**, make the following changes to build **DA16200_SW_3**:

- Enable `__COMBO_SAMPLE_BLE_PERI_WIFI_SVC_TCP_DPM_SAMPLE__`
- Disable the other sample defines (`__COMBO_SAMPLE_XXX`)

For **Example 6**, make the following changes to build **DA16200_SW_4**:

- Enable `__COMBO_SAMPLE_BLE_CENT_SENSOR_GW__`
- Disable the other sample defines (`__COMBO_SAMPLE_XXX`)

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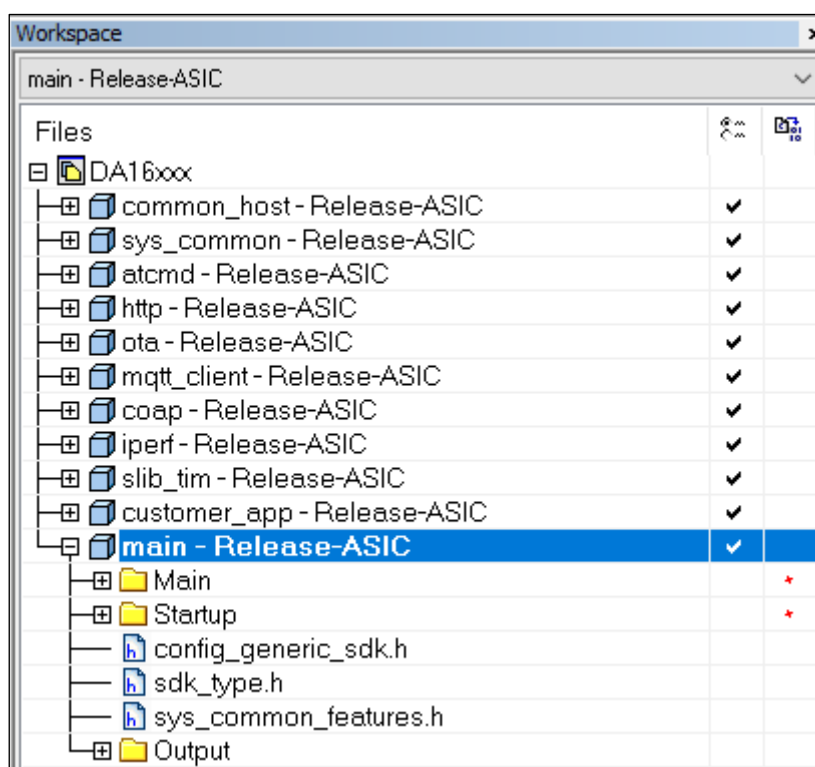


Figure 7: Project View

To build the software for the first time, select all projects, right-click, and then select **Rebuild All**. For the second and next builds, rebuild only projects that were changed. For example, if the "main" project was changed, then rebuild "main". If you work with other examples, you should rebuild both "customer_app" and "main" projects.

After the build, the folder "[DA16600_SDK_ROOT]\img" should have the following three DA16200 images:

- DA16200_**SLIB**-GEN01-01-XXXXX-000000.img
- DA16200_**RTOS**-GEN01-01-XXXXX-000000.img
- DA16200_**BOOT**-GEN01-01-XXXXX-000000_W25Q32JW.img
or DA16200_**BOOT**-GEN01-01-XXXXX-000000_AT25SL321.img

4.3 Build DA14531 Software

The DA14531 software (Bluetooth® LE SW) used in the DA16600 SDK is based on the DA14531 SDK version 6.0.14.1114. To build the DA14531 software for the examples, you need a DA14531 SDK 6.0.14.1114 that is specifically adapted for DA16600. This SDK is available in ~SDK\util\da14531_sdk*.zip.

Depending on which example you want to test, you need to use a different example Bluetooth® LE target project.

NOTE

The example projects mentioned below are not included in the original 6.0.14.1114. The projects below (Prj1_proxr and Prj2_proxm) are created and modified for the four examples of DA16600.

For **Examples 1, 2, and 3**, use the **Prj1_proxr** project:

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- [DA14531_SDK_ROOT]\projects\target_apps\ble_examples\prox_reporter_sensor_ext_coex\Keil_5\prox_reporter_ext.uvprojx

For **Example 4**, use the **Prj2_proxm** project:

- [DA14531_SDK_ROOT]\projects\target_apps\ble_examples\prox_monitor_aux_ext_coex\Keil_5\prox_monitor_ext.uvprojx

4.3.1 Install Keil

For information on the Keil installation, see the corresponding section in http://lpcss-docs.dialog-semiconductor.com/UM-B-117-DA14531-Getting-Started-With-The-Pro-Development-Kit/05_Software_Development_Tools/Software_Development_Tools.html.

NOTE

The Keil IDE download URL is <https://www.keil.com/download/product/>.

4.3.2 Build a Project

To build a project in Keil:

1. In Keil, go to **Project > Open Project**, and then select the ".uvprojx" file.
Keil opens the project. For example, open [DA14531_SDK_ROOT]\projects\target_apps\ble_examples\prox_reporter_sensor_ext_coex\Keil_5\prox_reporter_ext.uvprojx.
2. Go to **Project > Clear Targets**.
3. Click **Rebuild**.

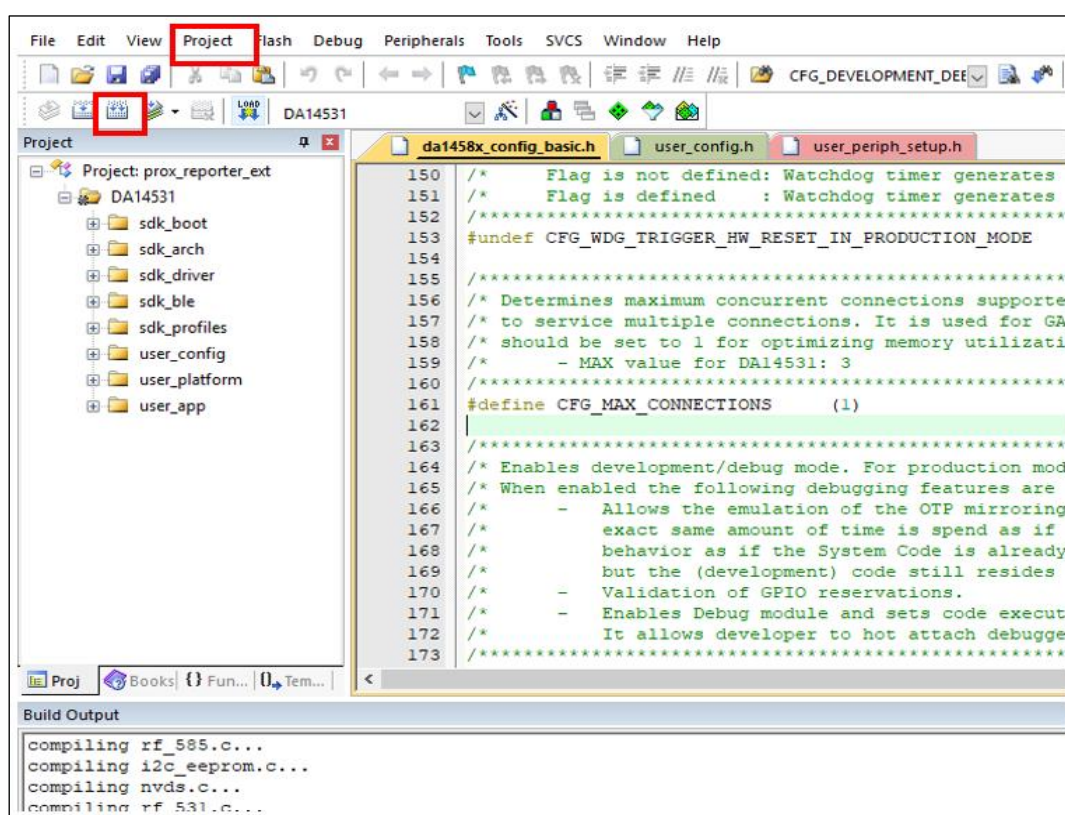


Figure 8: Keil – Build

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NOTE

To quickly test an example without building the DA14531 software, use the pre-built DA14531 image. See the folder "[DA16600_SDK_ROOT]\img\DA14531_...\":

- DA14531_1 ← Prj1_proxr
- DA14531_2 ← Prj2_proxm

If you want to run multiple DA16600 boards at the same time (with the same example project), you need to build the DA14531 projects with different BD addresses. Ensure that each DA16600 board's BD address is unique to avoid an address conflict. You can change the BD address of the DA14531 in the **da1458x_config_advanced.h** file (search for **CFG_NVDS_TAG_BD_ADDRESS** at the bottom of the source).

After **Prj1_proxr** or **Prj2_proxm** is built with the Keil IDE, there is a **.bin** file in directory "[DA14531_SDK_ROOT]\projects\target_apps\ble_examples\prox_reporter_sensor_ext_coex\Keil_5\out_DA14531\Objects\".

4.4 Program SFLASH and Run

4.4.1 Create a DA14531 Image from .bin

After code build, the images can be found in the following folder:

[DA14531_SDK_ROOT]\projects\target_apps\ble_examples\prox_reporter_sensor_ext_coex\Keil_5\out_img\.

or

[DA14531_SDK_ROOT]\projects\target_apps\ble_examples\prox_monitor_aux_ext_coex\Keil_5\out_img\.

The images required in the examples are generated automatically by **create_img.bat** in the Keil project folder above. But to create images manually, you can use the tool named **mkimage.exe** available in the "~SDK\util\ble_img_creator\" folder of the DA16600 SDK.

NOTE

The **mkimage.exe** included in the DA16600 SDK is built in Visual Studio 2019 release mode. Therefore, if you run **mkimage.exe** from the command prompt window and get some errors like "... *vcruntime140.dll is missing* ...", then install Microsoft Visual C++ Redistributable for Visual Studio 2015, 2017 and 2019 (see <https://support.microsoft.com/en-us/help/2977003/the-latest-supported-visual-c-downloads>).

If your PC still does not run **mkimage.exe**, you can also build the tool. The tool **mkimage.exe** can be built in either GCC or MSVC environments.

The **mkimage** tool source folder is: [DA14531_SDK_ROOT]\utilities\mkimage\.

For **GCC**: for example, Linux, Cygwin, and so on.

[DA14531_SDK_ROOT]\utilities\mkimage\gcc: run "make" at the prompt.

For **Windows**: for example, Visual Studio

[DA14531_SDK_ROOT]\utilities\mkimage\ : add **mkimage.c** to a win32 console application project and build.

4.4.1.1 Use mkimage.exe

There are two types of **.img** files to be created with **mkimage.exe**:

- **multi-part format**: used in a normal development phase and in production

| | |
|-------------------------|-------------------------|
| ble_multi_part_header_t | + // multi-part header |
| ble_img_hdr_t | + // bank1: fw_1 header |
| ble_fw1_bin | + // fw_1 bin |
| ble_img_hdr_t | + // bank2: fw_2 header |

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```
ble_fw2_bin + // fw_2_bin
ble_product_header_t // product header: bank1/bank2 offset
```

- **single-part format:** used for an OTA firmware update. A new version of a firmware image should be created in a single-part format and published on an OTA Server

```
ble_multi_part_header_t +
ble_img_hdr_t +
ble_fw_bin (new version)
```

The SFLASH programming procedure is explained in the next section.

4.4.1.2 Create a Multi-Part Image

In Section 4.4.1, the multi-part image is generated already but it can be created in two ways using:

- Option 1 – the Python script included in SDK
- Option 2 – raw commands in command prompt

Option 1

If you have Python 3.6.x installed on your PC, you can create an image following these steps:

1. Make a temporary folder (for example, C:\temp). Locate and copy the following files from "~SDK\util\ble_img_creator\" to the temporary folder:
 - mkimage.exe
 - app_version.h
 - mkimage_multi.py
2. Copy the DA14531 bin file to the temporary folder.
3. Open **app_version.h**, and change the version to your version, and then save it.
For example: change `#define SDK_VERSION "6.0.14.1114.1"` to `#define SDK_VERSION "6.0.14.1114.2"`
4. In Windows Explorer, double-click **mkimage_multi.py**, and then follow the instruction.
 - a. If you want to give your name to .img, type the name in the command prompt window, then press **Enter**.

The following image is created: **da14531_multi_part_proxr.img**.

NOTE

- The number of characters in the version string (in app_version.h) is less than or equal to 15
- If you build DA14531 SDK, synchronize the version string in
"[DA14531_SDK_ROOT]\projects\target_apps\ble_examples\prox_reporter_sensor_ext_coex\include\app_version.h" with "[DA16600_SDK_ROOT]\util\ble_img_creator\ app_version.h"

Option 2

To create a multi-part image in a command prompt:

1. Create a folder (for example, C:\temp_folder) and copy the following files in that folder:
 - ~SDK\util\ble_img_creator\mkimage.exe
 - ~SDK\util\ble_img_creator\app_version.h
 - ~SDK\apps\da16600\get_started\img\DA14531_1\pxr_sr_coex_ext_531_6_0_14_1114.bin
- In this demo, a "Prj1_proxr" image is created.

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NOTE

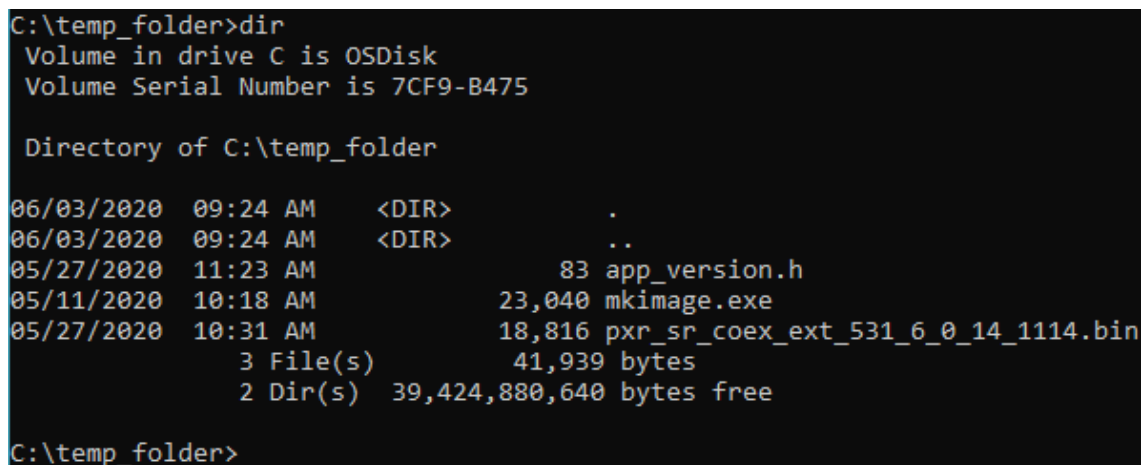
The version string in "~SDK\util\ble_img_creator\ app_version.h" should be the same as that of "[DA14531_SDK_ROOT]\projects\target_apps\ble_examples\prox_reporter_sensor_ext_coex\include\app_version.h".

Instead of using the pre-compiled .bin ("~SDK\apps\da16600\get_started\img\DA14531_1\pxr_sr_coex_ext_531_6_0_14_1114.bin"), you can use one built in Keil.

2. Open the **app_version.h** file and change the version as follows:

```
app_version.h
#define SDK_VERSION "6.0.14.1114.1"
...
```

This version is written to **ble_img_hdr_t** of a multi-part image.



```
C:\temp_folder>dir
Volume in drive C is OSDisk
Volume Serial Number is 7CF9-B475

Directory of C:\temp_folder

06/03/2020  09:24 AM    <DIR>          .
06/03/2020  09:24 AM    <DIR>          ..
05/27/2020  11:23 AM                83 app_version.h
05/11/2020  10:18 AM            23,040 mkimage.exe
05/27/2020  10:31 AM            18,816 pxr_sr_coex_ext_531_6_0_14_1114.bin
               3 File(s)              41,939 bytes
               2 Dir(s)  39,424,880,640 bytes free

C:\temp_folder>
```

Figure 9: Bluetooth® LE FW Image Generation – Preparation

3. At the command prompt, type the following commands in the following order:
 - a. `mkimage single pxr_sr_coex_ext_531_6_0_14_1114.bin app_version.h pxr_sr_coex_ext_531_6_0_14_1114_1.img.`
 - b. `mkimage single pxr_sr_coex_ext_531_6_0_14_1114.bin app_version.h pxr_sr_coex_ext_531_6_0_14_1114_2.img.`
 - c. `mkimage multi spi pxr_sr_coex_ext_531_6_0_14_1114_2.img 0x20 pxr_sr_coex_ext_531_6_0_14_1114_1.img 0x8000 0xFF20 da14531_multi_part_proxr.img.`

Figure 10 shows how to create a demo multi-part image.

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```
C:\temp_folder>mkimage single pxr_sr_coex_ext_531_6_0_14_1114.bin app_version.h pxr_sr_coex_ext_531_6_0_14_1114.1.img
C:\temp_folder>mkimage single pxr_sr_coex_ext_531_6_0_14_1114.bin app_version.h pxr_sr_coex_ext_531_6_0_14_1114.2.img
C:\temp_folder>mkimage multi spi pxr_sr_coex_ext_531_6_0_14_1114.2.img 0x20 pxr_sr_coex_ext_531_6_0_14_1114.1.img 0x8000 0xFF20 da14531_multi_part_proxr.img
Creating image 'da14531_multi_part_proxr.img'...
[00000000] Padding (FF's)
[00000020] 'pxr_sr_coex_ext_531_6_0_14_1114.2.img'
[000040e0] Padding (FF's)
[00008000] 'pxr_sr_coex_ext_531_6_0_14_1114.1.img'
[0000c9c0] Padding (FF's)
[0000ff20] Product header

C:\temp_folder>dir
Volume in drive C is OSDisk
Volume Serial Number is 7CF9-B475

Directory of C:\temp_folder

06/03/2020  10:18 AM  <DIR>          .
06/03/2020  10:18 AM  <DIR>          ..
05/27/2020  11:23 AM             83 app_version.h
06/03/2020  10:18 AM    65,336 da14531_multi_part_proxr.img
05/11/2020  10:18 AM    23,040 mkimage.exe
05/27/2020  10:31 AM    18,816 pxr_sr_coex_ext_531_6_0_14_1114.bin
06/03/2020  10:18 AM    18,880 pxr_sr_coex_ext_531_6_0_14_1114.1.img
06/03/2020  10:18 AM    18,880 pxr_sr_coex_ext_531_6_0_14_1114.2.img
               6 File(s)      145,035 bytes
               2 Dir(s)  39,428,968 bytes free

C:\temp_folder>
```

Figure 10: Bluetooth® LE FW Image Generation – Multi-Part Image

4.4.1.3 Create a Single Image

You can create a single image in two ways using:

- Option 1 – the Python script included in SDK
- Option 2 – raw commands in command prompt

Option 1

If you have Python 3.6.x installed on your PC, you can create an image following these steps:

1. In Python 3.6.x, go to "`~\SDK\util\ble_img_creator\`" with the following files:
 - `mkimage.exe`
 - `app_version.h`
 - **`mkimage_single.py`**
2. Copy the DA14531 bin file to "`~\SDK\util\ble_img_creator\`".
3. Open **`app_version.h`**, change the version to your version, and then save it.
For example: `#define SDK_VERSION "6.0.14.1114.1"` → `#define SDK_VERSION "6.0.14.1114.2"`
4. In Windows Explorer, double-click **`mkimage_single.py`**, and then follow the instructions.
 - a. If you want to give your name to .img, type the name in the command prompt window, then press ENTER.

The following image is created: **`da14531_pxr_single.img`**

Option 2

If you want to create two single images (ver2 and ver3) using a command prompt, do the following:

1. Create two copies of **`app_version.h`** and rename them to **`app_version_2.h`** and **`app_version_3.h`** correspondingly.
2. Edit the two files as follows:
 - a. `App_version_2.h`:
`#define SDK_VERSION "v_6.0.14.1114.2"`
 - b. `App_version_3.h`:
`#define SDK_VERSION "v_6.0.14.1114.3"`

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3. At the command prompt, type the following commands in the following order (see [Figure 11](#)):
 - a. `mkimage single_ota pxx_sr_coex_ext_531_6_0_14_1114.bin app_version_2.h pxx_sr_coex_ext_531_6_0_14_1114_single_v2.img`
 - b. `mkimage single_ota pxx_sr_coex_ext_531_6_0_14_1114.bin app_version_3.h pxx_sr_coex_ext_531_6_0_14_1114_single_v3.img`

```
C:\temp_folder>
C:\temp_folder>mkimage single_ota pxx_sr_coex_ext_531_6_0_14_1114.bin app_version_2.h pxx_sr_coex_ext_531_6_0_14_1114_single_v2.img
C:\temp_folder>mkimage single_ota pxx_sr_coex_ext_531_6_0_14_1114.bin app_version_3.h pxx_sr_coex_ext_531_6_0_14_1114_single_v3.img
C:\temp_folder>dir
Volume in drive C is OSDisk
Volume Serial Number is 7CF9-B475

Directory of C:\temp_folder

06/03/2020  10:36 AM  <DIR>          .
06/03/2020  10:36 AM  <DIR>          ..
05/27/2020  11:23 AM             83 app_version.h
06/03/2020  10:30 AM             85 app_version_2.h
06/03/2020  10:30 AM             85 app_version_3.h
06/03/2020  10:18 AM      65,336 da14531_multi_part_proxr.img
05/11/2020  10:18 AM      23,040 mkimage.exe
05/27/2020  10:31 AM      18,816 pxx_sr_coex_ext_531_6_0_14_1114.bin
06/03/2020  10:18 AM      18,880 pxx_sr_coex_ext_531_6_0_14_1114_1.img
06/03/2020  10:18 AM      18,880 pxx_sr_coex_ext_531_6_0_14_1114_2.img
06/03/2020  10:27 AM      18,912 pxx_sr_coex_ext_531_6_0_14_1114_single.img
06/03/2020  10:36 AM      18,912 pxx_sr_coex_ext_531_6_0_14_1114_single_v2.img
06/03/2020  10:36 AM      18,912 pxx_sr_coex_ext_531_6_0_14_1114_single_v3.img
               11 File(s)      201,941 bytes
               2 Dir(s)  39,411,638,272 bytes free

C:\temp_folder>
```

Figure 11: Bluetooth® LE FW Image Generation – Single Image

4.4.2 Program SFLASH

To program SFLASH:

1. Make sure that the following four images are ready:
 - DA16200_**BOOT**-GEN01-01-XXXXXX-000000_W25Q32JW.img
(or DA16200_**BOOT**-GEN01-01-XXXXXX-000000_AT25SL321.img)
 - DA16200_**SLIB**-GEN01-01-XXXXXX-000000.img
 - DA16200_**RTOS**-GEN01-01-XXXXXX-000000.img
 - **da14531_multi_part_proxr.img**
2. Put a micro-USB cable in USB socket **B** of the EVB (see [Figure 1](#)).
The recommendation is to put the other end of this USB cable in a USB hub with a power switch attached per port and connect that USB hub to the PC to make a “power cycle” of the board easy during the test.
3. Run **Tera Term**.
Windows will detect two USB ports (for example, COM11 and COM12).
4. Connect Tera Term to the lowest of the two COM port numbers that were detected (for example, COM11, which is UART0 of DA16200).
5. Make sure that the baud rate is 230400.
6. Press **Enter** several times to check that you are online with the DA16600 EVB.
7. Type `reset` and then press **Enter**.
You will see the `[MROM]` prompt.
8. Before you type any commands, copy the location path to the folder where the four firmware images are stored (BOOT, SLB, RTOS, and bin.out) in advance, so that you do not get a timeout error while running the `loady` command. If you select a file too slow, the Tera Term's ymodem transfer progress dialog box is stuck or not working, then you need to re-run the `loady` command.

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9. Type `loady boot` and press **Enter**.
10. Go to **File > Transfer > YMODEM > Send** to quickly find file **DA16200_BOOT-GEN01-01-XXXXX-000000_W25Q32JW.img** (or **DA16200_BOOT-GEN01-01-XXXXX-000000_AT25SL321.img**) (see Figure 12).
You can also use this shortcut key: keep the **Alt** key pressed and type **F, T, Y, S**.

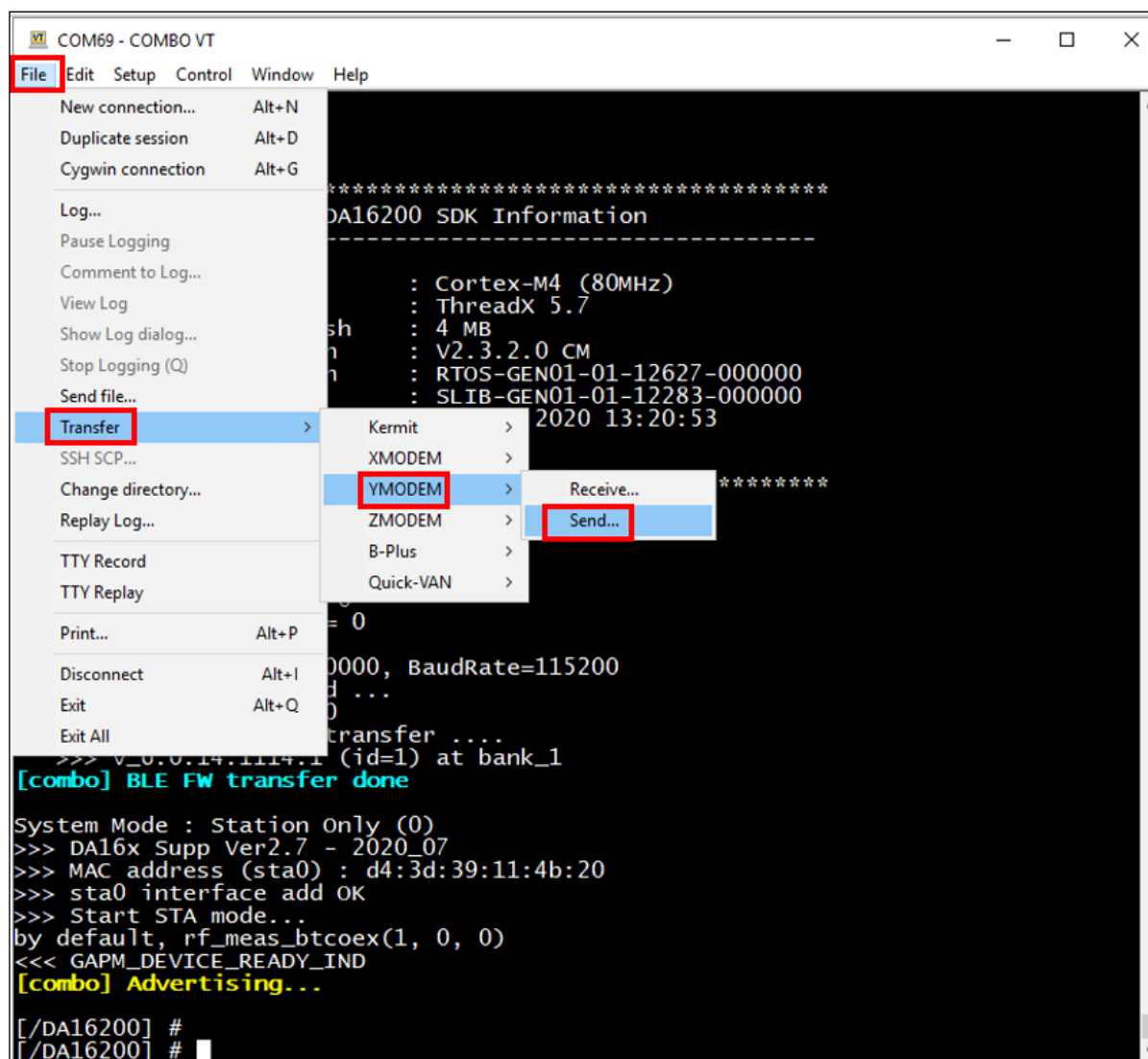


Figure 12: Tera Term

The download (to serial flash) of the selected image file takes time.

11. Similar to step 10, type `loady 18a000`, press **Enter**, and then select **DA16200_SLIB-GEN01-01-XXXXX-000000.img**.
12. Similar to steps 10, type `loady a000`, press **Enter**, and then select **DA16200_RTOS-GEN01-01-XXXXX-000000.img**.
This ymodem transfer takes the longest time to complete.
13. Similar to step 10, type `loady 392000 1000 bin`, press **Enter**, and then select **da14531_multi_part_proxr.img**.

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NOTE

Next time, when you want to, for example, download only one image file (RTOS, SLIB, or the da14531 image), you must always download the BOOT image first (`loady boot`), and then run either `loady a000 / loady 18a000 / loady 392000 1000 bin`. If you do not download the BOOT image beforehand, your image (RTOS/SLIB/Bluetooth® LE image) may not be correctly programmed.

14. After all images are transferred to SFLASH, type `boot`, and then press **Enter**.

Some debug messages are printed in Tera Term.

15. Press **Enter** several times until the prompt `[/DA16200] #` shows.

IMPORTANT

Switch off and switch on the USB port (if a user USB hub has a power switch per port, then toggle it) or remove the USB cable completely and then put it back in. This is needed to change the DA14531 to Bootloader mode and wait to get an image from the DA16200.

16. Wait until your Tera Term is connected to COM11. (Or simply reconnect with serial. This step is not needed if you are not going to use Tera Term during the test.)

NOTE

Once Tera Term is connected, you can type `reboot` in the Tera Term console if you want to check early boot messages.

Now you are ready to do the test.

4.5 Run DA16600 with JTAG

After the steps in Section 4.4 are done, you are ready to run the example applications that are described in Section 5.

You can also use JTAG to run DA16600. Because DA16600 has two chips – Wi-Fi (DA16200) and Bluetooth® LE (DA14531) – and each chip has its own JTAG port.

4.5.1 Run DA16200 with JTAG

See the DA16200 SDK Programmer Guide [1] Appendix D "How to use I-Jet Debugger".

The JTAG cable should be connected to jumper **B** (J7) of the DA16600 EVB (Figure 1).

If you want to do debugging, enter the `[MROM]` prompt in Tera Term (Figure 14), and then click the debug start button (button 3 in Figure 13, which is taken from the DA16200 SDK Programmer Guide).

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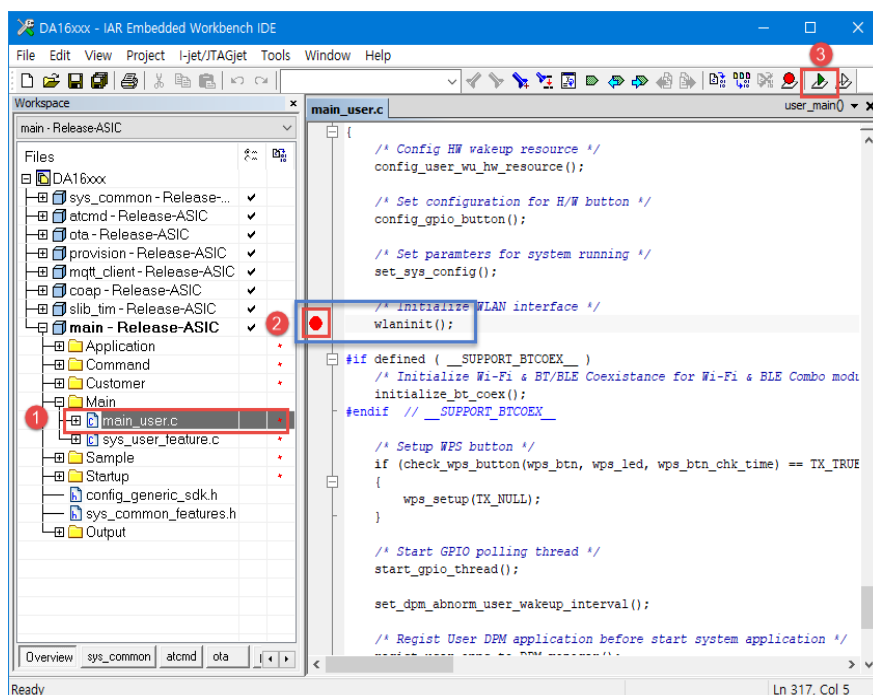


Figure 13: Run DA16200 by JTAG

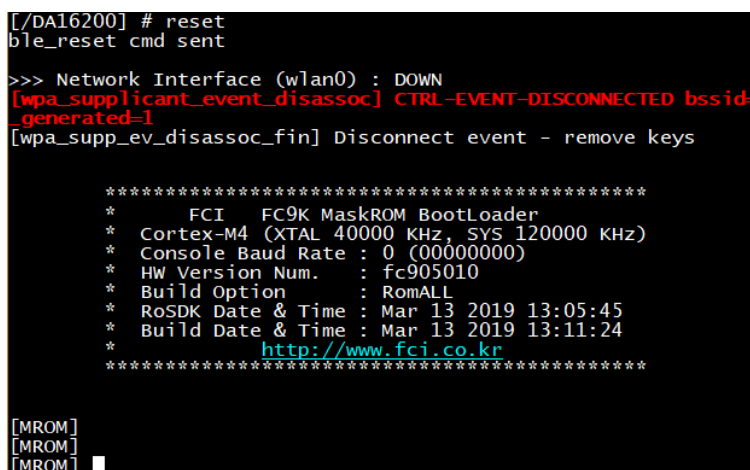


Figure 14: Run DA16200 by JTAG – MROM

If you want to boot the DA16600 EVB in "non" JTAG mode again after J-Tag is used, then SPI re-programming with three DA16200 images is required. This is because the memory map is different for JTAG boot and normal boot – as DA16200 is using XIP: J-tag writes code in SFLASH by own memory map which is not the same as the DA16600's memory map (see Sections 4.1 and 4.4.2).


4.5.2 Run DA14531 with JTAG

To load a DA14531 image (.bin) with the JTAG function in the Keil IDE:

NOTE

The default DA16200 software loads and transfers a DA14531 image to DA14531 at boot. Disable this Bluetooth® LE image transfer feature before starting the procedure.

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1. Build the DA16600 SDK with `__DA14531_BOOT_FROM_UART__` disabled (see `~SDK/apps/da16600/get_started/inc/ble_combo_features.h`), and program SFLASH with the three DA16200 images (BOOT, SLB, and RTOS).
The DA14531 image does not need to be programmed.
2. Make sure DA16600 EVB's DIP switch configuration (SW7 and SW3) looks like [Figure 26](#).
3. Connect a USB cable to USB Port **C** (DA14531 JTAG Port) of the DA16600 EVB. See [Figure 1](#).
4. Connect a USB cable to USB Port **B** of the DA16600 EVB for a Tera Term connection.
5. Switch **ON** (in a USB hub) the two USB cable connections.
6. Run the Keil IDE and open a DA14531 project.
7. Click the  icon shown in [Figure 15](#).

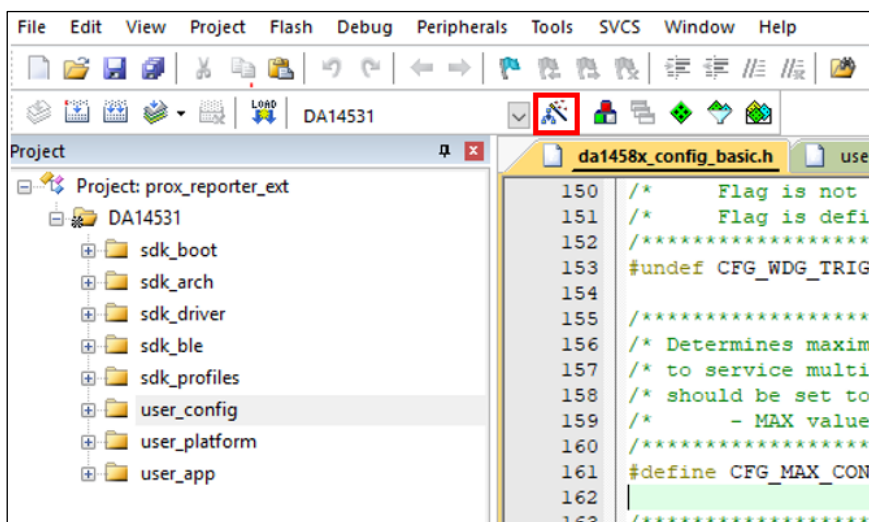


Figure 15: Keil – Option

8. Select the **Debug** tab and click **Settings**. See [Figure 16](#).

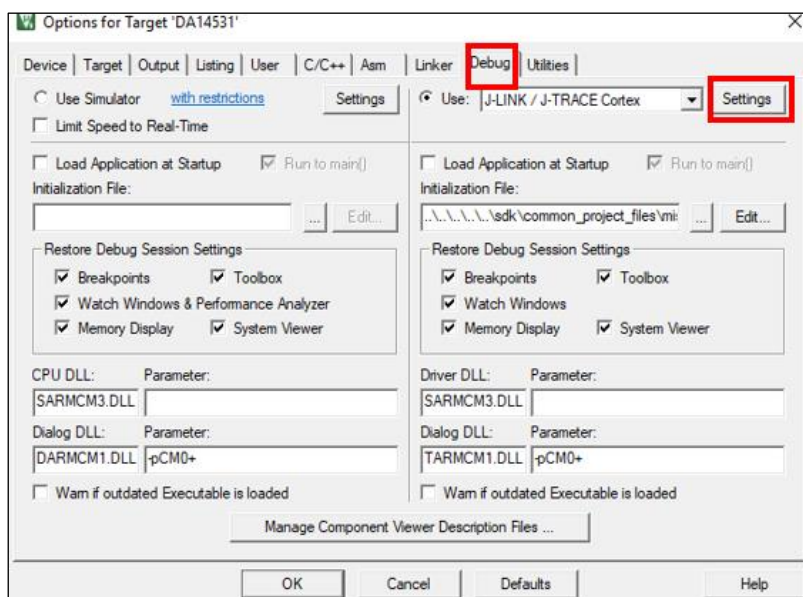


Figure 16: Keil – Debug

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9. Make sure that the fields **SN** and **SWD** have valid values. See [Figure 17](#).

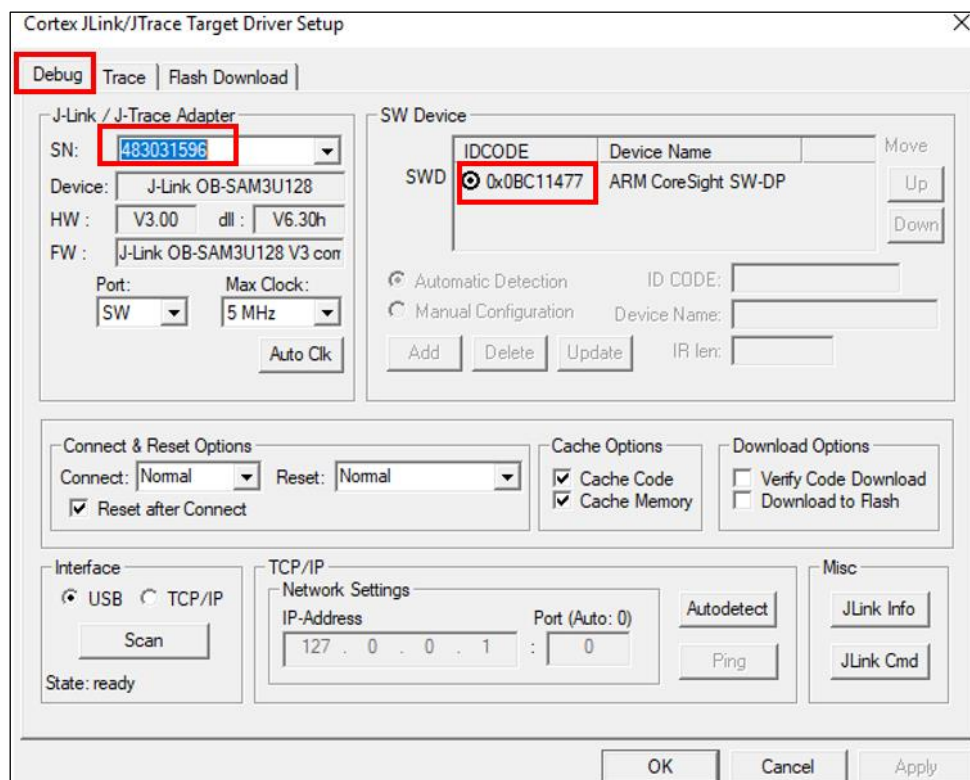


Figure 17: Keil/JTAG Device

NOTE

If there is no valid value for **SN** or **SWD**, then this means that the JTAG/JLINK firmware does not exist or is not enabled in the JTAG chip of the DA16600, or the JTAG is not working for some reason.
In this case, contact Dialog Semiconductor to update your JTAG firmware on the DA16600 EVB.

10. If the DA14531 JTAG is successfully recognized, click **OK**.
11. Switch **OFF** the power to the two USB cables.
12. Switch **ON** the power to the two USB cables.
13. In Tera Term (to which the lower number COM port is connected), make sure that the DA16200 boots successfully. If successful, you will see messages as shown in [Figure 18](#).

```
>>> UART1 : Clock=80000000, BaudRate=115200
>>> UART1 : DMA Enabled ...
wakeup_src = 17
BLE_BOOT_MODE_0
```

Figure 18: Tera Term – DA16200 Waiting for DA14531 to Connect

14. Enable JTAG SWD pins by changing a compiler flag:


```
[DA14531_SDK_ROOT]\projects\target_apps\ble_examples\prox_reporter_sensor_ext_coex
\include\ext_host_ble_aux_task.h
...
#undef __DISABLE_J-TAG_SWD_PINS_IN_BLE__
...
```

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15. After the build is done, click the **Start Debugger** button. See [Figure 19](#).

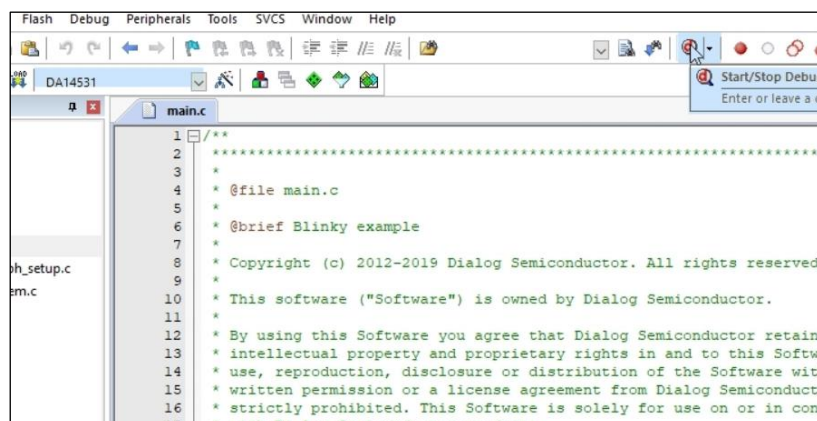


Figure 19: Keil – Start Debugger

16. Click **OK**.

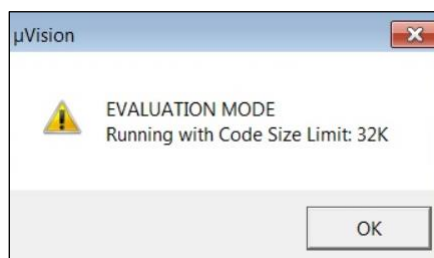


Figure 20: Keil – Evaluation Mode Dialog Box

17. Click the **Run** button. See [Figure 21](#).

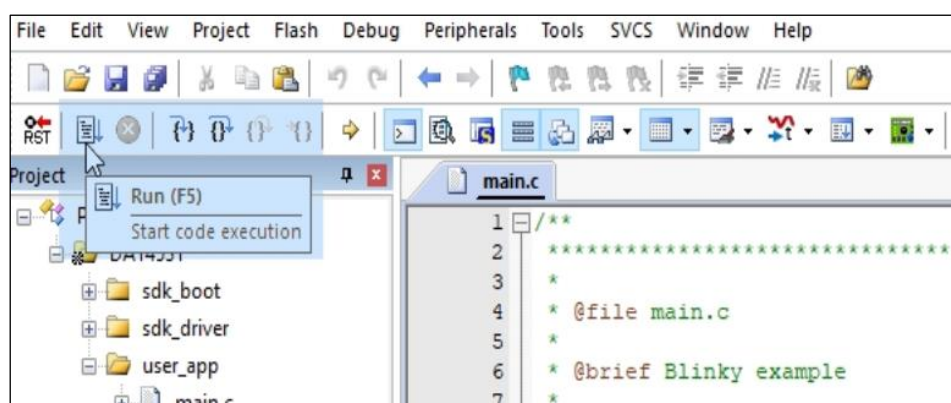


Figure 21: Keil – Run

If you see the message shown in [Figure 22](#) being printed in Tera Term, then the DA14531 is successfully started.

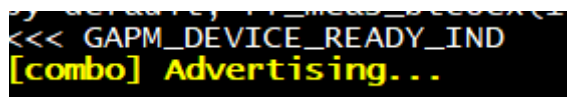


Figure 22: Tera Term – Advertising Successful

Now the DA16600 starts Bluetooth® LE advertising and can allow a Bluetooth® LE peer to connect to the DA16600.

5 DA16600 Example Test Procedure

5.1 Test Environment Setup

The following items are used in the example test:

- Wi-Fi Access Point
- Bluetooth® LE Peers
- PC: to Control Bluetooth® LE Peers and DA16600 Boards
- DA16600 EVB Boards

5.1.1 Wi-Fi Access Point

Any Wi-Fi routers are acceptable. The Wi-Fi Access Point is called **MyAP** from here onwards.

5.1.2 Bluetooth® LE Peers

Bluetooth® LE peers are used for all the examples. Several types of Bluetooth® LE peers are used, listed in the following sub-sections.

5.1.2.1 Bluetooth® LE Mobile App

Dialog provides a sample mobile application (Android/iOS App) called "Wi-Fi Provisioning" to test examples 1 to 4. This mobile application is used to give Wi-Fi provision information (Wi-Fi router connection information plus any customer proprietary information to configure the DA16600) to the DA16600 board.

NOTE

You can also download (from App Store) and use a general-purpose Bluetooth® LE mobile application that supports a GATT Client (that can read/write a GATT characteristic of a GATT Server). If you understand the Wi-Fi SVC GATT Server database structure and JSON application protocols (see Section 6.4.1.5), you can use a general Bluetooth® LE Mobile App as well to send a command.

5.1.2.2 Bluetooth® LE Sensors

Two or three Bluetooth® LE peer devices are needed to test example 4 (sensor gateway).

These Bluetooth® LE peer devices should implement a simple GATT server application as described in Figure 48 to be able to work with the sensor gateway application of DA16600.

For example, as Raspberry Pi 3 is common and capable of Bluetooth® LE communication, it is used in the example test. If you have another Bluetooth® LE development board/device to act as a peer, write a simple GATT server as described in Figure 48.

Suppose we have two Bluetooth® LE sensors ready and called **RBP3_1** and **RBP3_2**. Connect both RBP3s to MyAP (with the LAN interface of RBP3). Now RBP3_1 and RBP3_2 are on the same local network as MyAP.

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In RBP3_1, we run a UDP server application as well to communicate with the Wi-Fi part of the DA16600. If you have another UDP test client/utility, use whatever network utility you like.

NOTE

The version of Bluetooth® LE Stack and Python used in RBP3: bluez-5.51, python 3.7.3.

5.1.3 PC: to Control Bluetooth® LE Peers and DA16600 Boards

1. Use a LAN cable to connect your PC to **MyAP**.
2. Use PuTTY to open two ssh windows (to RBP3_1) ← **login as root**.
3. Enter `cd /home/pi` for both two ssh windows (let us say **ssh_win_1**, **ssh_win_2**).
4. Use PuTTY to open one ssh window to RBP3_2 ← **login as root**.
5. Enter `cd /home/pi` for the ssh window (let us say **ssh_win_3**).
6. Open one Tera Term window and connect to the COM port (the lower port number of the two, with baud rate 230400) of the DA16600. Let us call this Tera Term window **da16_tera_win** from here onwards.
7. Open another Tera Term window and connect to the other COM port (the higher port number of the two, with baud rate 115200) of the DA16600. Let us call this Tera Term window **da14_tera_win** from here onwards. (this Tera Term is connected to UART2 of DA14531 chip)

5.1.4 DA16600 EVB Boards

- **DA16600_EVB_1** to program DA16200_SW_1 + DA14531_IMG (Prj1_proxr)
(Depending on an example, replace DA16200_SW_1 with DA16200_SW_1 / DA16200_SW_2 / DA16200_SW_3)
- **DA16600_EVB_2** to program DA16200_SW_4 + DA14531_IMG (Prj2_proxm)

5.2 Example 1: Bluetooth® LE Assisted Wi-Fi Provisioning

A Bluetooth® LE mobile application is used for the Wi-Fi provisioning test. This mobile application is a Bluetooth® LE application and can talk to the DA14531 of the DA16600 EVB board to do Wi-Fi provisioning.

1. Power **ON** DA16600_EVB_1.
 - a. Do a POR boot (plug out, and then plug in the USB cable).
 - b. After boot, run the command `factory` to clear any existing NVRAM content.
The command `factory` also triggers a reboot after NVRAM is cleared.
 - c. Make sure that "*Advertising ...*" is printed on **da16_tera_win**.
2. Run the provisioning mobile Wi-Fi provisioning App as shown in [Figure 23](#) that can be found and installed from the Google Play Store or iOS App Store.



Figure 23: Provisioning App (Android)

3. Configure Wi-Fi as shown in Section 5.1 of the Ref. [5].
4. If a user clicks **Start DA16600-based > Start > Select 'DA16600-BLE' > Start Wi-Fi network scan > select [MyAP name]** (input Password if need) > **Connect to [MyAP name]**, then the provisioning information is transferred to DA16600, which saves the information into NVRAM and reboots. After rebooted, Wi-Fi is connected to the selected AP.

To remove the provisioning information:

1. Establish a Bluetooth® LE connection again with DA16600_EVB_1.
2. Click the **Reset the device** button.

NOTE

As an alternative, you also can use the command `factory` to clear any provisioning information.

Now you can start provisioning again.

5.3 Example 2: Bluetooth® LE Firmware OTA Download via Wi-Fi

- DA16200_SW_1: make sure that the DA16200 RTOS image is built with `__FORCE_LOADY_BANK_1_BLE_BOOT__ disabled`
- For this test, make sure that an HTTP(s) server is running on the MyAP network

You can set up a simple HTTP server. For example:

1. Install an HTTP server on a PC with Apache as a web server that is connected to MyAP. See <https://httpd.apache.org/> to download Apache and for instructions.
 2. Copy file `pxr_sr_coex_ext_ver3_single.img` to the `htdocs` folder of the Apache server. This assumes that you have generated a ver3 image as well in Section 4.4.1.
 3. Make sure that the PC is connected to MyAP, and make sure that the `.img` file is downloadable via a web browser with the link http://192.168.0.230/pxr_sr_coex_ext_ver3_single.img.
- `da16_tera_win`

```
// User command in bold font, commentary / messages to note in blue font

// Add one NVRAM parameter as below. This may be a part of provision information or
// hardcoded in source depending on implementation.

[/DA16200] # nvram
           Command-List is changed, "NVRAM"
```

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```
[/DA16200/NVRAM] setenv URI_BLE http://192.168.0.230/pxr_sr_coex_ext_ver3_single.img
[/DA16200/NVRAM] reboot
...
Reboot...

ble_reset cmd sent

Wakeup source is 0x00

*****
*                               DA16200 SDK Information
* -----
*
* - CPU Type           : Cortex-M4 (80MHz)
* - OS Type            : ThreadX 5.7
* - Serial Flash       : 4 MB
* - SDK Version        : V2.3.2.0 CM
* - F/W Version        : RTOS-GEN01-01-12616-000000
*                     : SLIB-GEN01-01-12283-000000
* - F/W Build Time     : Sep 22 2020 18:46:28
* - Boot Index         : 0
*
*****

gpio wakeup enable 00010000

System Mode : Station Only (0)
>>> DA16XXX supplicant Ver1.00-20170213-01
>>> MAC address (sta0) : d4:3d:39:10:f4:92
>>> sta0 interface add OK
>>> Start STA mode...
by default, rf_meas_btcoex(1, 0, 0)

>>> UART1 : Clock=80000000, BaudRate=115200
>>> UART1 : DMA Enabled ...
wakeup_src = 17
BLE_BOOT_MODE_0
BLE FW VER to transfer ....
>>> v_6.0.14.1114.2 (id=1) at bank_1 // During boot, the latest DA14531 firmware
is loaded (from either bank_1 or bank_2). The current version of Bluetooth® LE FW:
6.0.14.1114.2. the current bank: bank_1
>>> Selected BSS 88:36:6c:4e:a1:28 ssid='N604R MIKE' (-89)
BLE FW transfer done // Bluetooth® LE FW transferred successfully to DA14531 via
UART
<<< GAPM_DEVICE_READY_IND
Advertising... // Bluetooth® LE starts advertising ...
[wpa_scan_res_match] skip- blacklisted (count=1 limit=0)

!!! No proper APs found - It will be try again !!!

>>> Selected BSS 88:36:6c:4e:a1:28 ssid='N604R_MIKE' (-55)
>>> Network Interface (wlan0) : UP
>>> Associated with 88:36:6c:4e:a1:28

Connection COMPLETE to 88:36:6c:4e:a1:28

-- DHCP Client WLAN0: SEL
```

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```
-- DHCP Client WLAN0: REQ
-- DHCP Client WLAN0: BOUND
    Assigned addr   : 192.168.0.28 // DA16200 attached to MyAP network
    netmask        : 255.255.255.0
    gateway        : 192.168.0.1
    DNS addr       : 168.126.63.1

    DHCP Server IP  : 192.168.0.1
    Lease Time      : 02h 00m 00s
    Renewal Time    : 01h 00m 00s
iot_sensor connected to server

[/DA16200] #
[/DA16200] #
[/DA16200] #
[/DA16200] #
...
[/DA16200/NVRAM] # getenv // check nvram by making sure valid URI_BLE exists

Total length (271)
N0_Profile (STR,02) ..... 1
N0_ssid (STR,13) ..... "N604R_MIKE"
N0_psk (STR,12) ..... "N12345678"
N0_key_mgmt (STR,08) ..... WPA-PSK
SYSMODE (STR,02) ..... 0
0:NETMODE (STR,02) ..... 1
UART1_FLOWCTRL (STR,02) ..... 1
UART1_BAUDRATE (STR,07) ..... 115200
ble_fw_act_bank (STR,02) ..... 1
provisioned (STR,02) ..... 1
URI_BLE (STR,53) ..... http://192.168.0.230/pxr_sr_coex_ext_ver3_single.img
```

- Bluetooth® LE Mobile App

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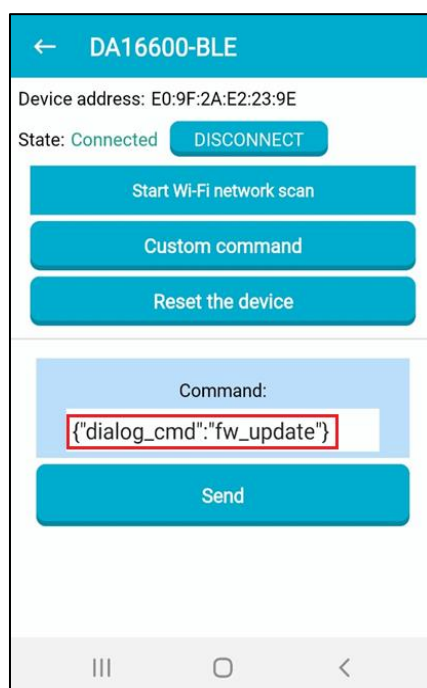


Figure 24: Provisioning Application – Custom Command

- Bluetooth® LE Mobile Application > Scan > Connect to "DA16600" > tap **Custom command** (see Figure 24), fill in the command **{\"dialog_cmd\": \"fw_update\"}** and tap **Send**
- To enter the command easily, open a notepad on your smartphone to type the command, and then copy and paste the command on the Bluetooth® LE Mobile Application
- da16_tera_win
The following is happening on DA16600_EVB_1 when command "fw_update" is received:
 - An attempt is made to connect to an OTA server (**192.168.0.230**) to download a DA14531 firmware file

```
// User command in bold font, commentary / messages to note in blue font
...
[/DA16200/NVRAM] #
[/DA16200/NVRAM] # <<< GAPC_CONNECTION_REQ_IND // indication of connection req from a
Bluetooth® LE peer (mobile application)
peer bd addr type = 0x1 (0x0:public, 0x1:random)
connection event intval = 36, connection latency = 0

#####
#   DA14531 Proxr IoT Sensor demo application   #
#####

Connected to Device // connected to a peer

BLE Peer BDA: 45:23:32:3c:f9:61 Bonded: NO
GATTC_EXC_MTU_CMD (GATTC_MTU_EXCH) sent !
...
<<< GATTC_WRITE_REQ_IND
start_handle = 33
param->handle = 34
Receive - FW_UPDATE
COMBO_WIFI_CMD_FW_BLE_DOWNLOAD received // "fw_update" received
```


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```
[ota_fw_update_combo] uri_slib =
[ota_fw_update_combo] uri_rtos =
[ota_fw_update_combo] uri_ble = http://192.168.0.230/pxr_sr_coex_ext_ver3_single.img
[BLE_OTA] New FW: ver = v_6.0.14.1114.3, timestamp = 1587376260
[BLE_OTA] bank_1 (act): ver = v_6.0.14.1114.2, timestamp = 1588134660
[BLE_OTA] bank_2 : ver = v_6.0.14.1114.1, timestamp = 1588134660
...
>> HTTP(s) Client Downloading... 100 %(17232/17232 Bytes)
...
- OTA Update : <BLE_FW> Download - Success

[BLE_OTA] CASE_1: BLE FW Update Only ...
ble_reset cmd sent
- OTA Update (BLE FW) : 0 seconds left to REBOOT....

>>> Network Interface (wlan0) : DOWN
[wpa_supplicant_event_disassoc] CTRL-EVENT-DISCONNECTED bssid=88:36:6c:4e:a1:28
reason=3 locally_generated=1
[wpa_supp_ev_disassoc_fin] Disconnect event - remove keys

Wakeup source is 0x00 // rebooted ...

*****
*                               DA16200 SDK Information
* -----
*
* - CPU Type           : Cortex-M4 (80MHz)
* - OS Type            : ThreadX 5.7
* - Serial Flash       : 4 MB
...
*****
gpio wakeup enable 00010000

System Mode : Station Only (0)
>>> DA16XXX supplicant Ver1.00-20170213-01
>>> MAC address (sta0) : d4:3d:39:10:f4:92
>>> sta0 interface add OK
>>> Start STA mode...
by default, rf_meas_btcoex(1, 0, 0)

>>> UART1 : Clock=80000000, BaudRate=115200
>>> UART1 : DMA Enabled ...
wakeup_src = 17
BLE_BOOT_MODE_0
BLE_FW VER to transfer ....
>>> v_6.0.14.1114.3 (id=2) at bank_2 // new Bluetooth® LE FW boots from bank_2
(bank_1 has the previous fw version)
BLE FW transfer done
<<< GAPM_DEVICE_READY_IND
Advertising...
>>> Selected BSS 88:36:6c:4e:a1:28 ssid='N604R_MIKE' (-42)
...
```

5.4 Example 3: Gas Leak Detection Sensor

- ssh_win_1

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```
// User command in bold font, commentary / messages to note in blue font
```

```
// Type in the following command to start the UDP server
```

```
root@raspberrypi:/home/pi# python udp_server.py  
UDP Server: waiting for a message ... at 172.16.30.136:10954
```

- **da16_tera_win**

For Test Example 3, the provisioning command JSON string "select_ap" of the Provisioning App (see Section 6.4.1.5) should have the following data:

- "dpm_mode": 1
- "svr_addr": "172.16.30.136"
- "svr_port": 10954

```
// User command in bold font, commentary / messages to note in blue font
```

```
Rebooted ...
```

```
...
```

```
[/DA16200] # ble
```

```
Command-List is changed, "ble"
```

```
[/DA16200/ble] # iot_sensor start
```

```
[ConsoleEvent] user command exists in queue
```

```
[/DA16200/ble] # APP_GAS_LEAK_SENSOR_START_CFM
```

```
sleep (rtm ON) entered // Wi-Fi enters sleep (while in sleep, keyboard input is not  
working, wait for some minutes)
```

```
...
```

```
Wakeup source is 0x90 // Wi-Fi wakes up
```

```
gpio wakeup enable 00000402
```

```
[combo][iot_sensor]
```

```
is_provisioned = 1
```

```
is_sensor_started = 1
```

```
[combo] dpm_boot_type = 2
```

```
[combo] BLE_BOOT_MODE_1
```

```
>>> TIM STATUS: 0x00000000
```

```
by default, rf_meas_btcoex(1, 0, 0)
```

```
>>> Network Interface (wlan0) : DOWN
```

```
[wpa_supplicant_event_disassoc] CTRL-Event-DISCONNECTED bssid=2c:4d:54:dc:c8:90  
reason=3 locally_generated=1
```

```
OK
```

```
OK
```

```
-- DHCP Client WLAN0: REQ(4)
```

```
>>> Network Interface (wlan0) : UP
```

```
>>> Associated with 2c:4d:54:dc:c8:90
```

```
<<< APP_GAS_LEAK_EVT_IND
```

```
gas leak occurred !!!
```

```
[UMAC DPM] beacon int(100) , dtim_period(3)
```

```
Connection COMPLETE to 2c:4d:54:dc:c8:90
```

```
L2 Packet process completed, Set DPM Sleep !!!
```

```
-- DHCP Client WLAN0: BOUND(5)
```

```
Assigned addr : 192.168.0.205
```

```
Lease Time : 24h 00m 00s
```

```
Renewal Time : 20h 00m 00s
```

```
[dpm_save_dhpcp_info] DHCP Cancel
```

```
[combo] iot_sensor connected to server
```

```
>>> [msg_sent] : gas leak occurred, plz fix it !!! // Wi-Fi posts a message to server
```

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```
sleep (rtm ON) entered // Wi-Fi enters sleep again after message posting
```

- ssh_win_1

```
// User command in bold font, commentary / messages to note in blue font
UDP Server: waiting for a message ... at 172.16.30.136:10954
>>> sensor_connected
>>> [Gas Leak Sensor]: gas_leak occurred, go home and fix it!!!
```

The following is happening:

- If you run the command "iot_sensor start", the command is sent over (via GTL) to DA14531 which starts a timer task that is supposed to read a gas leak density sensor periodically
- If the DA14531 reads that the density is above the threshold "gas leak" level, then DA14531 wakes up DA16200 and sends the event ("gas leak occurred!") to DA16200
The DA16200, on receipt of the alert from the DA14531, sends an alert message to a UDP server where you can see the alert message printed

5.5 Example 4: DA14531 Peripheral Driver Example

5.5.1 Test Environment Setup

- DA16600 EVB Configuration
You can use three configurations to test a sample:
 - Configuration_1

| SW7 | | GPIO PINs | |
|-----|-----|-----------|----------|
| 1 | ON | P0_2 | gpio |
| 2 | ON | P0_9 | UART2_Rx |
| 3 | ON | P0_8 | gpio |
| 4 | ON | P0_11 | gpio |
| 5 | OFF | P0_10 | gpio |
| 6 | ON | | |
| 7 | OFF | | |
| 8 | OFF | | |
| 9 | OFF | | |
| 10 | OFF | | |

| SW3 | |
|-----|-----|
| 1 | OFF |
| 2 | OFF |

Figure 25: DA16600 EVB Config. 1

- Configuration_2

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| SW7 | | GPIO PINs | |
|-----|-----|-----------|----------|
| 1 | ON | P0_2 | gpio |
| 2 | ON | P0_9 | CHX_B |
| 3 | ON | P0_8 | CHX_A |
| 4 | ON | P0_11 | gpio |
| 5 | OFF | P0_10 | gpio |
| 6 | OFF | p0_5 | UART2_Rx |
| 7 | OFF | | |
| 8 | OFF | | |
| 9 | OFF | | |
| 10 | OFF | | |

| SW3 | |
|-----|----|
| 1 | ON |
| 2 | ON |

Figure 26: DA16600 EVB Config. 2

- Configuration_3

| SW7 | | GPIO PINs | |
|-----|-----|-----------|----------|
| 1 | ON | P0_2 | gpio |
| 2 | ON | P0_9 | UART2_Rx |
| 3 | OFF | P0_8 | gpio |
| 4 | OFF | P0_11 | gpio |
| 5 | OFF | P0_10 | gpio |
| 6 | ON | | |
| 7 | OFF | | |
| 8 | OFF | | |
| 9 | OFF | | |
| 10 | OFF | | |

| SW3 | |
|-----|-----|
| 1 | OFF |
| 2 | OFF |

Figure 27: DA16600 EVB Config. 3

- DA16200 image download for test
Program SFLASH with the 4 images below. See Section 4.4.2
 - DA16200_SW_2 (build SDK):
 - DA16200_SLIB-GEN01-01-XXXXXX-000000.img
 - DA16200_RTOS-GEN01-01-XXXXXX-000000.img
 - DA16200_BOOT-GEN01-01-XXXXXX-000000_W25Q32JW.img
(or DA16200_BOOT-GEN01-01-XXXXXX-000000_AT25SL321.img)
 - DA14531 image (pre-built image):
 - [DA16600_SDK_ROOT]\img\DA14531_1\da14531_multi_part_proxr.img
- Tera Term: open two Tera Term windows
 - Teraterm_1 (da16_tera_win): connect to COMxx (lower one) with 230400 as baud rate. This is debug console of DA16200. The user command is entered here
 - Teraterm_2 (da14_tera_win): connect to COMxx (higher one) with 115200 as baud rate. This is debug console of DA14531. Test progress are printed
- List of DA14531 Peripheral Driver samples
Once DA16600 EVB is powered on, type the following commands to see which samples are available.

```
// User command in bold font, commentary / messages to note in blue font
```

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```

...
System Mode : Station Only (0)
>>> DA16XXX supplicant Ver1.00-20170213-01
>>> MAC address (sta0) : d4:3d:39:11:4b:20
>>> sta0 interface add OK
>>> Start STA mode...
by default, rf_meas_btcoex(1, 0, 0)
wakeup_type=0

>>> UART1 : Clock=80000000, BaudRate=115200
>>> UART1 : DMA Enabled ...
BLE_BOOT_MODE_0
BLE FW VER to transfer ....
    >>> v_6.0.14.1114.1 (id=1) at bank_1
>>> Selected BSS 90:9f:33:66:26:52 ssid=xxxxxxx' (-43)
>>> Network Interface (wlan0) : UP
>>> Associated with 90:9f:33:66:26:52

Connection COMPLETE to 90:9f:33:66:26:52

-- DHCP Client WLAN0: SEL
-- DHCP Client WLAN0: REQ
BLE FW transfer done
<<< GAPM_DEVICE_READY_IND
Advertising...
-- DHCP Client WLAN0: BOUND
    Assigned addr   : 192.168.0.24
    netmask         : 255.255.255.0
    gateway         : 192.168.0.1
    DNS addr        : 210.220.163.82

    DHCP Server IP  : 192.168.0.1
    Lease Time      : 02h 00m 00s
    Renewal Time    : 01h 00m 00s

[/DA16200] #
[/DA16200] # ble
    Command-List is changed, "ble"
[/DA16200/ble] # help

-----
Current CMD-List is "ROOT/ble"
-----

...
- Sub-Commands - : -----
net                : Network commands
nvram              : nvram commands
sys                : system commands
user               : User commands
ble                : Combo BLE App commands

-----

ble                : BLE application command
-----
ble_gapm_reset     : Reset BLE GAPM
ble_fw_ver         : Get BLE FW version

```

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```
ble_disconnect : Disconnect BLE connection
peri           : Run peripheral driver sample

[/DA16200/ble] # peri

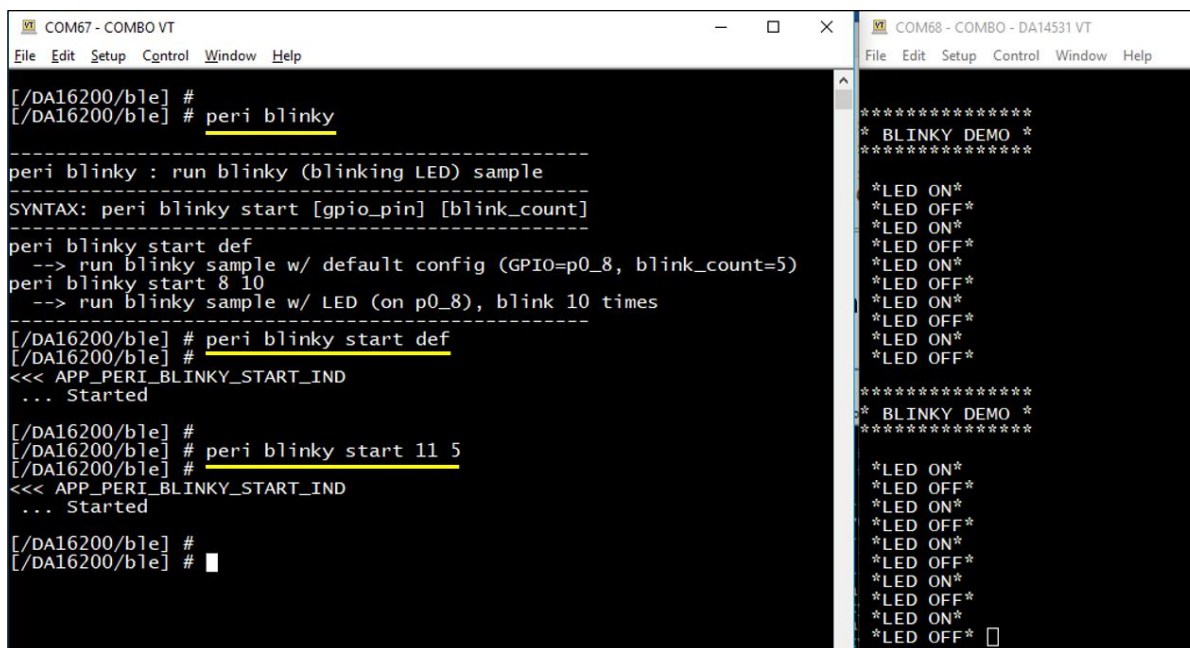
-----
peri : Run DA14531 Peripheral Driver Sample
      type a command below
-----

[01] peri blinky      : blinking LED sample
[02] peri systick     : systick timer sample
[03] peri timer0_gen  : timer0 general sample
[04] peri timer0_buz  : timer0 PWM buzzer sample
[05] peri timer2_pwm  : timer2 PWM LED array sample
[06] peri batt_lvl    : battery level read sample
[07] peri i2c_eeprom  : I2C EEPROM read/write sample
[08] peri spi_flash   : SPI_flash read/write sample
[09] peri quad_dec    : Quadrature Decoder sample
[10] peri gpio        : GPIO contorl(High/Low)
-----

[/DA16200/ble] #
```

5.5.2 User Commands

- peri blinky
 - This sample is using 1 GPIO to blink the LED that is connected to the GPIO
 - DA16600 EVB Configuration:
 - Configuration_1
 - By default, P0_8 is used to connect to LED. Connect J14:P0_8 to any pins in CN4
 - Run command as in [Figure 28](#). The LED connected to the GPIO specified will blink



```
COM67 - COMBO VT
File Edit Setup Control Window Help

[/DA16200/ble] #
[/DA16200/ble] # peri blinky

-----
peri blinky : run blinky (blinking LED) sample
SYNTAX: peri blinky start [gpio_pin] [blink_count]
-----
peri blinky start def
--> run blinky sample w/ default config (GPIO=p0_8, blink_count=5)
peri blinky start 8 10
--> run blinky sample w/ LED (on p0_8), blink 10 times

[/DA16200/ble] # peri blinky start def
[/DA16200/ble] #
<<< APP_PERI_BLINKY_START_IND
... Started

[/DA16200/ble] #
[/DA16200/ble] # peri blinky start 11 5
[/DA16200/ble] #
<<< APP_PERI_BLINKY_START_IND
... Started

[/DA16200/ble] #
[/DA16200/ble] #
```

```
COM68 - COMBO - DA14531 VT
File Edit Setup Control Window Help

*****
* BLINKY DEMO *
*****

*LED ON*
*LED OFF*
*LED ON*
*LED OFF*
*LED ON*
*LED OFF*
*LED ON*
*LED OFF*
*LED ON*
*LED OFF*

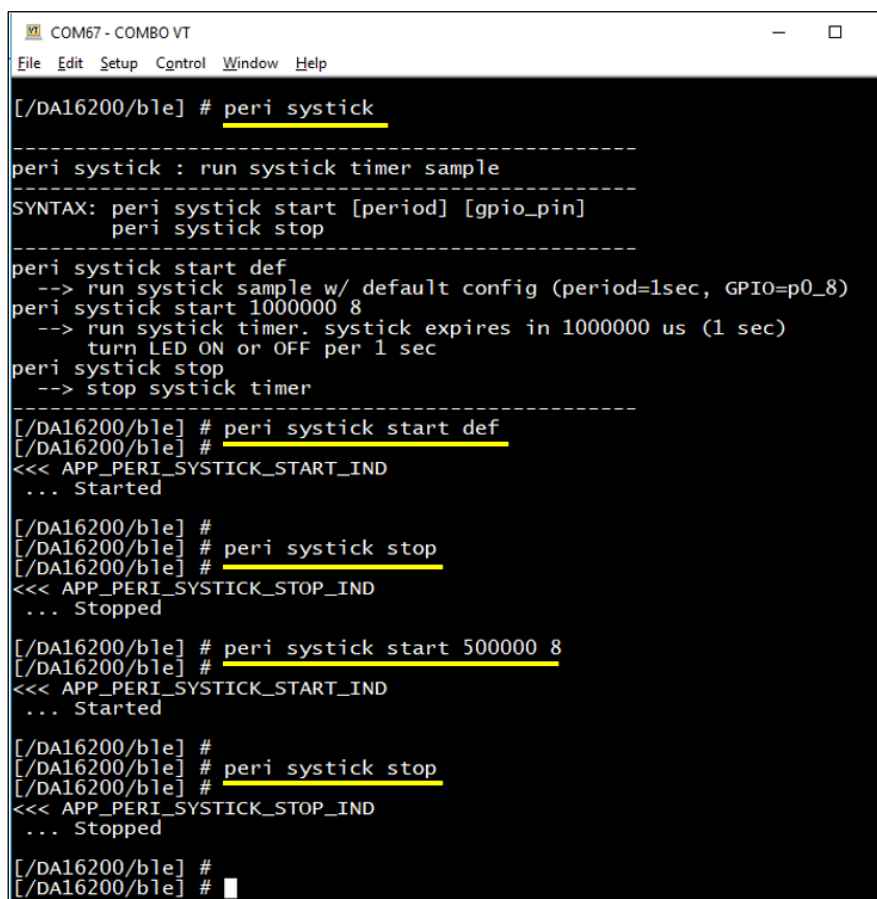
*****
* BLINKY DEMO *
*****

*LED ON*
*LED OFF*
*LED ON*
*LED OFF*
*LED ON*
*LED OFF*
*LED ON*
*LED OFF*
*LED ON*
*LED OFF*
*LED ON*
*LED OFF*
```

Figure 28: Peri Blinky

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- peri systick
 - This sample uses a systick timer of DA14531
 - This sample is using 1 GPIO to change the state of the LED that is connected to the GPIO
 - DA16600 EVB Configuration:
 - Configuration_1
 - By default, P0_8 is used to connect to LED. Connect J14:P0_8 to any pins in CN4
 - Run command as in [Figure 29](#). Whenever systick timer is expired, it toggles the LED state



```

COM67 - COMBO VT
File Edit Setup Control Window Help

[/DA16200/ble] # peri systick

-----
peri systick : run systick timer sample
-----
SYNTAX: peri systick start [period] [gpio_pin]
        peri systick stop
-----

peri systick start def
--> run systick sample w/ default config (period=1sec, GPIO=p0_8)
peri systick start 1000000 8
--> run systick timer. systick expires in 1000000 us (1 sec)
    turn LED ON or OFF per 1 sec
peri systick stop
--> stop systick timer
-----

[/DA16200/ble] # peri systick start def
[/DA16200/ble] #
<<< APP_PERI_SYSTICK_START_IND
... Started

[/DA16200/ble] #
[/DA16200/ble] # peri systick stop
[/DA16200/ble] #
<<< APP_PERI_SYSTICK_STOP_IND
... Stopped

[/DA16200/ble] # peri systick start 500000 8
[/DA16200/ble] #
<<< APP_PERI_SYSTICK_START_IND
... Started

[/DA16200/ble] #
[/DA16200/ble] # peri systick stop
[/DA16200/ble] #
<<< APP_PERI_SYSTICK_STOP_IND
... Stopped

[/DA16200/ble] #
[/DA16200/ble] # █
  
```

Figure 29: Peri Systick

- peri timer0_gen
 - The TIMER0 general example demonstrates how to configure TIMER0 to count a specified amount of time and generate an interrupt. A LED is changing state upon each timer interrupt. This sample is using 1 GPIO that is connected to an LED to show how TIMER0 can be used
 - DA16600 EVB Configuration:
 - Configuration_1
 - By default, P0_8 is used to connect to LED. Connect J14:P0_8 to any pins in CN4
 - Run command as in [Figure 30](#) and check LED

DA16600 Example Application Manual

```

COM67 - COMBO VT
File Edit Setup Control Window Help

[/DA16200/ble] # peri timer0_gen
-----
peri timer0_gen : run timer0 general sample
SYNTAX: peri timer0_gen start
(interactive config menu follows)
-----
[/DA16200/ble] # peri timer0_gen start
Sample Configuration Menu
-----
GPIO PIN number 0 ?
  1. p0_2
  2. p0_8
  3. p0_10
  4. p0_11
Type [Q]uit or [ENTER] for default (p0_8) :

Test duration (in sec) ?
Type [Q]uit or [ENTER] for default (10 sec) :

Timer0/Timer2 input clock division factor ?
  0. TIM0_2_CLK_DIV_1
  1. TIM0_2_CLK_DIV_2
  2. TIM0_2_CLK_DIV_4
  3. TIM0_2_CLK_DIV_8
Type [Q]uit or [ENTER] for default (TIM0_2_CLK_DIV_8) :

timer0 clock source ?
  0. TIM0_CLK_32K
  1. TIM0_CLK_FAST
Type [Q]uit or [ENTER] for default (TIM0_CLK_FAST) :

timer0 pwm mode ?
  0. PWM_MODE_ONE
  1. PWM_MODE_CLOCK_DIV_BY_TWO
Type [Q]uit or [ENTER] for default (PWM_MODE_ONE) :

Timer0 clock div ?
  0. TIM0_CLK_DIV_BY_10
  1. TIM0_CLK_NO_DIV
Type [Q]uit or [ENTER] for default (TIM0_CLK_DIV_BY_10) :

ON COUNTER reload value ?
(e.g.) reload value for 100ms (T = 1/200kHz * RELOAD_100MS = 0,000005
* 20000 = 100ms)
Type [ENTER] only for default (RELOAD_100MS = 20000) :

Configuration Summary
-----
gpio pin = 8
test duration = 10 sec
Timer0/Timer2 input clock division factor = TIM0_2_CLK_DIV_8
timer0 clock source = TIM0_CLK_FAST
timer0 pwm mode = PWM_MODE_ONE
timer0 clock division = TIM0_CLK_DIV_BY_10
timer0 ON COUNTER reload value = 20000
-----
SAMPLE CONFIGURATION CONFIRM ? [Yes/No/Quit] : y

[/DA16200/ble] #
<<< APP_PERI_TIMER0_GEN_START_IND
... Started

[/DA16200/ble] #

COM68 - COMBO - DA14531 VT
File Edit Setup Control Window Help

*****
* TIMER0 GENERAL TEST *
*****

LED will change state every second.
Test will run for: 0A seconds.

TIMER0 started!
TIMER0 stopped!

End of test

```

Figure 30: Peri Timer0_gen

- peri timer0_buz
 - This is TIMER0 (PWM0, PWM1) example that demonstrates how to configure TIMER0 to produce PWM signals. A melody is produced on an externally connected buzzer if connected
 - This sample is using 2 GPIOs that are connected to an external buzzer
 - DA16600 EVB Configuration:
 - Configuration_1
 - By default, P0_8 and P0_11 are used to connect to a buzzer. Connect J14:P0_8, and J14:P0_11 to a buzzer
 - Run command as in [Figure 31](#) and [Figure 32](#)

DA16600 Example Application Manual

```

COM67 - COMBO VT
File Edit Setup Control Window Help

[/DA16200/ble] #
[/DA16200/ble] # peri timer0_buz

-----
peri timer0_buz : run timer0 buzzer sample
SYNTAX: peri timer0_buz start
(interactive config menu follows)
-----
[/DA16200/ble] # peri timer0_buz start
Sample Configuration Menu

Choose two GPIO PINs (on which LEDs connected) for PWM control

GPIO PIN number for PWM0 () ?
1. p0_2
2. p0_8
3. p0_10
4. p0_11
Type [Q]uit or [ENTER] for default (p0_8) :

GPIO PIN number for PWM1 () ?
1. p0_2
2. p0_8
3. p0_10
4. p0_11
Type [Q]uit or [ENTER] for default (p0_11) :

Buzzer Test Counter (BTC)?
e.g.) BTC = 50 -> 320ms * 50 = 16 sec. 320ms is based on sample t0 buzz
er config
Type [Q]uit or [ENTER] for default (BTC=50) :

Timer0/Timer2 input clock division factor ?
0. TIM0_2_CLK_DIV_1
1. TIM0_2_CLK_DIV_2
2. TIM0_2_CLK_DIV_4
3. TIM0_2_CLK_DIV_8
Type [Q]uit or [ENTER] for default (TIM0_2_CLK_DIV_8) :

timer0_pwm mode ?
0. PWM_MODE_ONE
1. PWM_MODE_CLOCK_DIV_BY_TWO
Type [Q]uit or [ENTER] for default (PWM_MODE_ONE) :

Timer0 clock div ?
0. TIM0_CLK_DIV_BY_10
1. TIM0_CLK_NO_DIV
Type [Q]uit or [ENTER] for default (TIM0_CLK_NO_DIV) :

ON COUNTER reload value ?
Type [ENTER] only for default (1000) :

M (High) COUNTER reload value ?
Type [ENTER] only for default (500) :

N (Low) COUNTER reload value ?
Type [ENTER] only for default (200) :

-----
Configuration Summary
-----
pwm0_pin = 8
pwm1_pin = 11
buzzer test counter = 50
Timer0/Timer2 input clock division factor = TIM0_2_CLK_DIV_8
timer0 clock source = TIM0_CLK_FAST
timer0_pwm mode = PWM_MODE_ONE
timer0 clock division = TIM0_CLK_NO_DIV
timer0 ON COUNTER reload value = 1000
timer0 M (HIGH) COUNTER reload value = 500
timer0 N (LOW) COUNTER reload value = 200
-----
SAMPLE CONFIGURATION CONFIRM ? [Yes/No/Quit] : y

[/DA16200/ble] #
<<< APP_PERI_TIMER0_BUZ_START_IND
... Started
[/DA16200/ble] #

```

Figure 31: Peri Timer0_buz 1/2

```

COM68 - COMBO - DA14531 VT
File Edit Setup Control Window Help

*****
* TIMER0 PWM TEST *
*****

TIMER0 starts!
You can hear the sound produced by PWM0 or PWM1
if you attach a buzzer on pins P0_8 or P0_11 respectively.
Playing melody. Please wait...
*****
TIMER0 stopped!

End of test

```

Figure 32: Peri Timer0_buz 2/2

- peri timer2_pwm
 - The TIMER2 (PWM2, PWM3, PWM4) example demonstrates how to configure TIMER2 to produce PWM signals. The PWM outputs are used to change the brightness of the LEDs in this example
 - This sample is using 3 GPIOs that are connected to an LED segment array to show how TIMER2 PWM can be used
 - DA16600 EVB Configuration:
 - Configuration_1
 - By default, P0_8, P0_11, and P0_2 are used to connect to an LED segment array. Connect J14:P0_8, J14:P0_11, and J2:P0_2 (pin at the bottom left of J2) to a LED segment array
 - Run command as in [Figure 33](#)

```

COM67 - COMBO VT
File Edit Setup Control Window Help

[/DA16200/b1e] #
[/DA16200/b1e] # peri timer2_pwm

-----
peri timer2_pwm : run timer0 pwm sample
SYNTAX: peri timer2_pwm start
(interactive config menu follows)
-----
[/DA16200/b1e] # peri timer2_pwm start
Sample Configuration Menu

-----
Choose 3 GPIO PINs (on which LEDs connected) for PWM control
GPIO PIN number for PWM_2 () ?
1. p0_2
2. p0_8
3. p0_10
4. p0_11
Type [Q]uit or [ENTER] for default (p0_8) :

GPIO PIN number for PWM_3 () ?
1. p0_2
2. p0_8
3. p0_10
4. p0_11
Type [Q]uit or [ENTER] for default (p0_11) :

GPIO PIN number for PWM_4 () ?
1. p0_2
2. p0_8
3. p0_10
4. p0_11
Type [Q]uit or [ENTER] for default (p0_2) :

Timer0/Timer2 input clock division factor ?
0. TIM0_2_CLK_DIV_1
1. TIM0_2_CLK_DIV_2
2. TIM0_2_CLK_DIV_4
3. TIM0_2_CLK_DIV_8
Type [Q]uit or [ENTER] for default (TIM0_2_CLK_DIV_8) :

timer2 pause (by HW) ?
0. TIM2_HW_PAUSE_OFF
1. TIM2_HW_PAUSE_ON
Type [Q]uit or [ENTER] for default (TIM2_HW_PAUSE_OFF) :

timer2 PWM Frequency ? (see range below)
- [2 Hz, 16 kHz], if Timer2 input clock frequency is 32 kHz,
- [125 Hz, 1 MHz], if Timer2 input clock frequency is 2 MHz,
- [245 Hz, 2 MHz], if Timer2 input clock frequency is 4 MHz,
- [489 Hz, 4 MHz], if Timer2 input clock frequency is 8 MHz,
- [977 Hz, 8 MHz], if Timer2 input clock frequency is 16 MHz
Type [Q]uit or [ENTER] for default (500 Hz) :

Configuration Summary
-----
pwm2_pin           = 8
pwm3_pin           = 11
pwm4_pin           = 2
Timer0/Timer2 input clock division factor = TIM0_2_CLK_DIV_8
timer2 pause (by HW) = TIM2_HW_PAUSE_OFF
timer2 PWM Frequency = 500 Hz
-----
SAMPLE CONFIGURATION CONFIRM ? [Yes/No/Quit] : y

[/DA16200/b1e] #
<<< APP_PERI_TIMER2_PWM_START_IND
... Started

COM68 - COMBO - DA14531 VT
File Edit Setup Control Window Help

*****
* TIMER2 TEST *
*****

TIMER2 started!
TIMER2 stopped!
End of test

```

Figure 33: Peri Timer2_pwm

- peri batt_lvl
 - The Battery example demonstrates how to read the level of battery that is connected to DA14531
 - DA16600 EVB Configuration:
 - Configuration_1
 - Run command as in [Figure 34](#)

```

COM67 - COMBO VT
File Edit Setup Control Window Help

[/DA16200/b1e] # peri batt_lvl

-----
peri batt_lvl : read level of the battery
that is connected to DA14531
SYNTAX: peri batt_lvl get
-----
[/DA16200/b1e] # peri batt_lvl get
[/DA16200/b1e] #
<<< APP_PERI_BATT_LVL_IND
battery type = ALKALINE
battery level = 0
[/DA16200/b1e] #

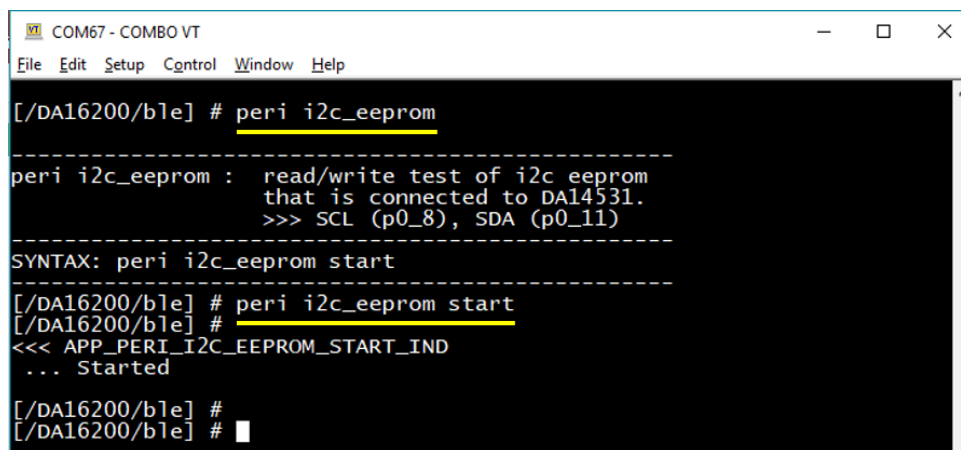
```

Figure 34: Peri Batt_lvl

- peri i2c_eeprom
 - The I2C EEPROM example demonstrates how to initiate, read, write, and erase an I2C EEPROM memory. This example works if the user connects an external memory
 - DA16600 EVB Configuration:
 - Configuration_1

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- By default, P0_8 (SCL) and P0_11 (SDA) are used. Connect J14:P0_8, J14:P0_11 to an external I2C_EEPROM
- Run command as in Figure 35 and Figure 36



```

COM67 - COMBO VT
File Edit Setup Control Window Help

[/DA16200/ble] # peri i2c_eeprom

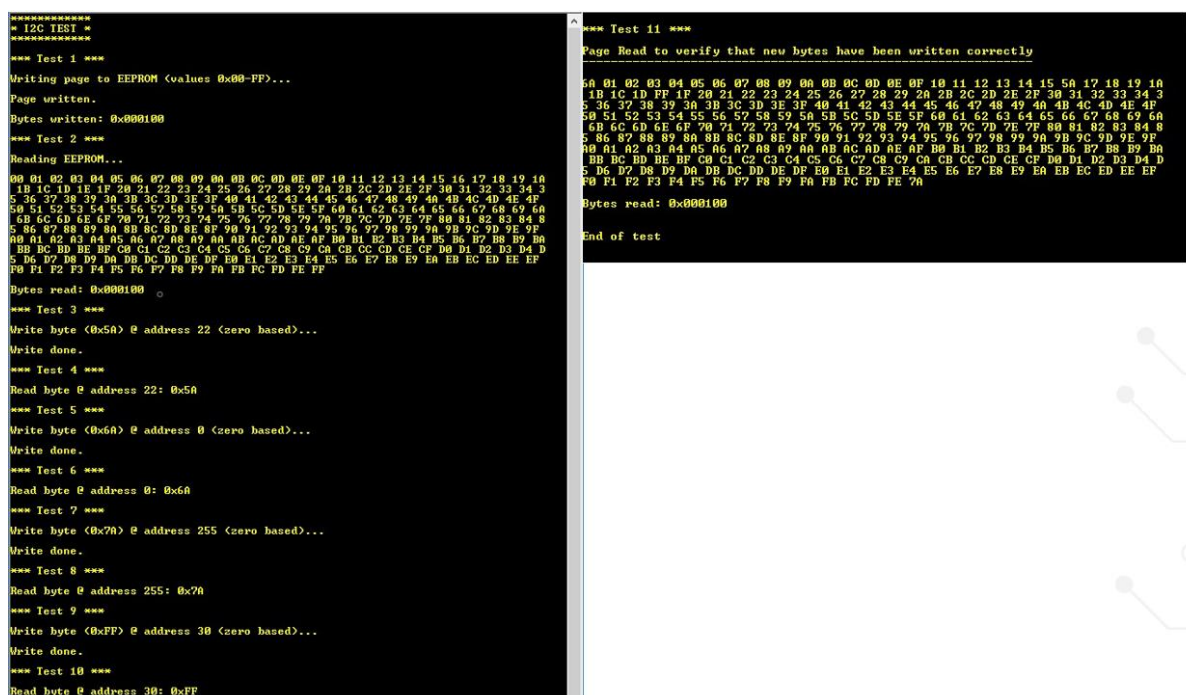
-----
peri i2c_eeprom : read/write test of i2c eeprom
                  that is connected to DA14531.
                  >>> SCL (p0_8), SDA (p0_11)
-----

SYNTAX: peri i2c_eeprom start

[/DA16200/ble] # peri i2c_eeprom start
[/DA16200/ble] #
<<< APP_PERI_I2C_EEPROM_START_IND
... Started

[/DA16200/ble] #
[/DA16200/ble] # █
  
```

Figure 35: Peri I2c_eeprom



```

*****
* I2C TEST *
*****

*** Test 1 ***
Writing page to EEPROM (values 0x00-FF)...
Page written.
Bytes written: 0x000100

*** Test 2 ***
Reading EEPROM...
00 01 02 03 04 05 06 07 08 09 0A 0B 0C 0D 0E 0F 10 11 12 13 14 15 16 17 18 19 1A
1B 1C 1D 1E 1F 20 21 22 23 24 25 26 27 28 29 2A 2B 2C 2D 2E 2F 30 31 32 33 34 3
3 36 37 38 39 3A 3B 3C 3D 3E 3F 40 41 42 43 44 45 46 47 48 49 4A 4B 4C 4D 4E 4F
50 51 52 53 54 55 56 57 58 59 5A 5B 5C 5D 5E 5F 60 61 62 63 64 65 66 67 68 69 6A
6B 6C 6D 6E 6F 70 71 72 73 74 75 76 77 78 79 7A 7B 7C 7D 7E 7F 80 81 82 83 84 8
5 86 87 88 89 8A 8B 8C 8D 8E 8F 90 91 92 93 94 95 96 97 98 99 9A 9B 9C 9D 9E 9F
A0 A1 A2 A3 A4 A5 A6 A7 A8 A9 AA AB AC AD AE AF B0 B1 B2 B3 B4 B5 B6 B7 B8 B9 BA
BB BC BD BE BF C0 C1 C2 C3 C4 C5 C6 C7 C8 C9 CA CB CC CD CE CF D0 D1 D2 D3 D4 D
5 D6 D7 D8 D9 DA DB DC DD DE DF E0 E1 E2 E3 E4 E5 E6 E7 E8 E9 EA EB EC ED EE EF
F0 F1 F2 F3 F4 F5 F6 F7 F8 F9 FA FB FC FD FE FF
Bytes read: 0x000100

*** Test 3 ***
Write byte (0x5A) @ address 22 (zero based)...
Write done.

*** Test 4 ***
Read byte @ address 22: 0x5A

*** Test 5 ***
Write byte (0x6A) @ address 0 (zero based)...
Write done.

*** Test 6 ***
Read byte @ address 0: 0x6A

*** Test 7 ***
Write byte (0x7A) @ address 255 (zero based)...
Write done.

*** Test 8 ***
Read byte @ address 255: 0x7A

*** Test 9 ***
Write byte (0xFF) @ address 30 (zero based)...
Write done.

*** Test 10 ***
Read byte @ address 30: 0xFF

*** Test 11 ***
Page Read to verify that new bytes have been written correctly
5A 01 02 03 04 05 06 07 08 09 0A 0B 0C 0D 0E 0F 10 11 12 13 14 15 5A 17 18 19 1A
1B 1C 1D 1E 1F 20 21 22 23 24 25 26 27 28 29 2A 2B 2C 2D 2E 2F 30 31 32 33 34 3
3 36 37 38 39 3A 3B 3C 3D 3E 3F 40 41 42 43 44 45 46 47 48 49 4A 4B 4C 4D 4E 4F
50 51 52 53 54 55 56 57 58 59 5A 5B 5C 5D 5E 5F 60 61 62 63 64 65 66 67 68 69 6A
6B 6C 6D 6E 6F 70 71 72 73 74 75 76 77 78 79 7A 7B 7C 7D 7E 7F 80 81 82 83 84 8
5 86 87 88 89 8A 8B 8C 8D 8E 8F 90 91 92 93 94 95 96 97 98 99 9A 9B 9C 9D 9E 9F
A0 A1 A2 A3 A4 A5 A6 A7 A8 A9 AA AB AC AD AE AF B0 B1 B2 B3 B4 B5 B6 B7 B8 B9 BA
BB BC BD BE BF C0 C1 C2 C3 C4 C5 C6 C7 C8 C9 CA CB CC CD CE CF D0 D1 D2 D3 D4 D
5 D6 D7 D8 D9 DA DB DC DD DE DF E0 E1 E2 E3 E4 E5 E6 E7 E8 E9 EA EB EC ED EE EF
F0 F1 F2 F3 F4 F5 F6 F7 F8 F9 FA FB FC FD FE FF
Bytes read: 0x000100

End of test
  
```

Figure 36: Peri I2c_eeprom Read/Write

- peri spi_flash
 - The SPI Flash memory example demonstrates how to initiate, read, write, and erase an SPI Flash memory with the SPI Flash driver
 - The following is the pre-defined characteristics configured in the DA14531 image:
 - #define SPI_MS_MODE SPI_MS_MODE_MASTER
 - #define SPI_CP_MODE SPI_CP_MODE_0
 - #define SPI_WSZ SPI_MODE_8BIT

DA16600 Example Application Manual

- #define SPI_CS SPI_CS_0
- #define SPI_FLASH_DEV_SIZE (256 * 1024)
- DA16600 EVB Configuration:
 - Configuration_3
 - By default, 4 GPIO pins are used; SPI_EN (J14: p0_8), SPI_CLK (J14:p0_11), SPI_DO (p0_2: pin at J2 Left-bottom), SPI_DI (p0_10: J2 Right-bottom)
- DA14531 image used:
 - Download the following image for this test
 [DA16600_SDK_ROOT]\img\DA14531_1\peri_spi_flash\
 da14531_multi_part_proxr.s.img
 - If you do not use the image above, you will get the message as in [Figure 37](#)

```
[/DA16200/ble] # peri_spi_flash start
Please use a DA14531 img ver 6.0.14.1114.1.s
[/DA16200/ble] #
[/DA16200/ble] #
```

Figure 37: Peri Spi_flash – Wrong Image Warning

- After booting with a correct Bluetooth® LE test image, you can find the following version string printed at boot as in [Figure 38](#)

```
System Mode : Station Only (0)
>>> DA16XXX supplicant Ver1.00-20170213-01
>>> MAC address (sta0) : d4:3d:39:11:4b:20
>>> sta0 interface add OK
>>> Start STA mode...
by default, rf_meas_btcoex(1, 0, 0)
wakeup_type=0

>>> UART1 : clock=80000000, BaudRate=115200
>>> UART1 : DMA Enabled ...
BLE_BOOT_MODE 0
BLE FW VER to transfer ...
>>> v.6.0.14.1114.1.s (id=1) at bank_1
>>> Selected BSS 90:9f:33:66:26:52 ssid='mike.sj.home.2G' (-54)
>>> Network Interface (wlan0) : UP
>>> Associated with 90:9f:33:66:26:52

Connection COMPLETE to 90:9f:33:66:26:52

-- DHCP Client WLAN0: SEL
-- DHCP Client WLAN0: REQ
BLE FW transfer done
<<< GAPM_DEVICE_READY_IND
Advertising...
-- DHCP Client WLAN0: BOUND
Assigned addr : 192.168.0.24
netmask : 255.255.255.0
gateway : 192.168.0.1
```

Figure 38: Correct Image Version for Peri Spi_flash Sample

- Run command as in [Figure 39](#) and [Figure 40](#)


```
COM67 - COMBO VT
File Edit Setup Control Window Help

[/DA16200/b1e] #
[/DA16200/b1e] # peri spi_flash
-----
peri spi_flash : read/write test of spi_flash
                  that is connected to DA14531.
                  >>> SPI_EN (p0_8), SPI_CLK (p0_11)
                  >>> SPI_D0 (p0_2), SPI_DI (p0_10)
-----
SYNTAX: peri spi_flash start
-----
[/DA16200/b1e] # peri spi_flash start
[/DA16200/b1e] #
<<< APP_PERI_SPI_FLASH_START_IND
... Started

[/DA16200/b1e] #
```

[illegible]

- peri_quad_dec
 - The Quadrature decoder example demonstrates how to configure and read from the quadrature decoder peripheral. This example works if the user connects an external quad encoder device
 - DA16600 EVB Configuration:
 - Configuration_2
 - By default, 2 GPIO pins are used; CHX_A (J14: p0_8), CHX_B (J14: p0_9)
 - DA14531 image used:
 - Download the image below for this test
[DA16600_SDK_ROOT]\img\DA14531_1\peri_quad_dec\da14531_multi_part_proxr_q.img
 - If you do not use the image above, you will get the message as in [Figure 41](#)

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```
[/DA16200/ble] #
[/DA16200/ble] # peri quad_dec start
Please use a DA14531 img ver 6.0.14.1114.1.q
[/DA16200/ble] #
```

Figure 41: Peri Quad_dec – Wrong Image Warning

- After booting with a correct Bluetooth® LE test image, you can find the following version string printed at boot as in [Figure 42](#)

```
System Mode : Station Only (0)
>>> DA16XXX supplicant Ver1.00-20170213-01
>>> MAC address (sta0) : d4:3d:39:11:4b:20
>>> sta0 interface add OK
>>> Start STA mode...
by default, rf_meas_btcoex(1, 0, 0)
wakeup_type=0

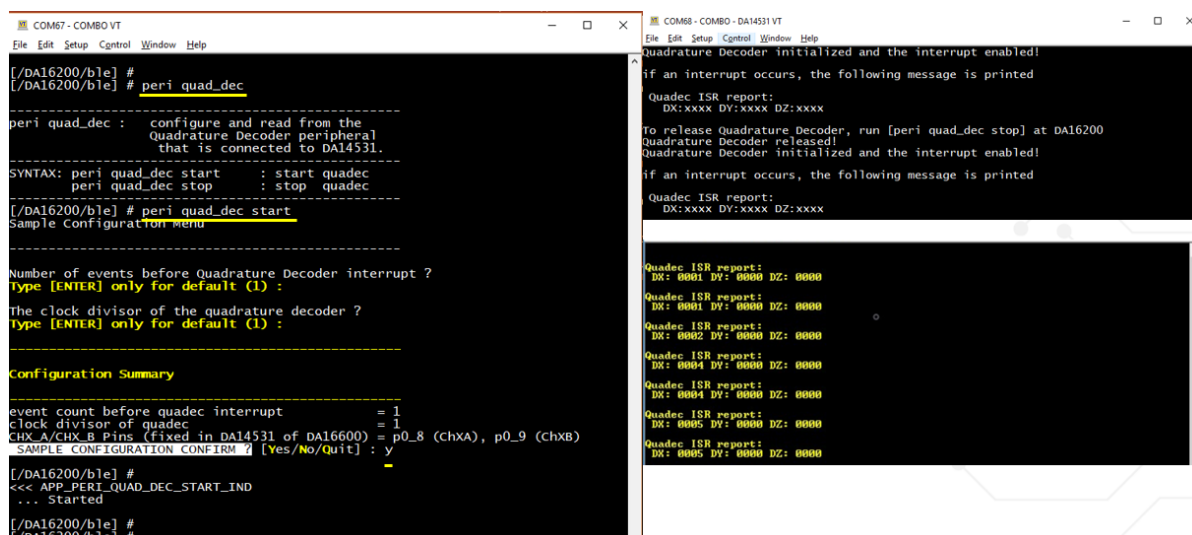
>>> UART1 : Clock=80000000, BaudRate=115200
>>> UART1 : DMA Enabled ...
BLE FW VER to transfer ...
>>> v_6.0.14.1114.1.q (id=1) at bank_1
>>> Selected BSS 90:9f:33:66:26:52 ssid='mike.sj.home.2G' (-49)
>>> Network Interface (wlan0) : UP
>>> Associated with 90:9f:33:66:26:52

Connection COMPLETE to 90:9f:33:66:26:52

-- DHCP Client WLAN0: SEL
-- DHCP Client WLAN0: REQ
BLE FW transfer done
<<< GAPM_DEVICE_READY_IND
Advertising...
-- DHCP Client WLAN0: BOUND
Assigned addr : 192.168.0.24
netmask : 255.255.255.0
gateway : 192.168.0.1
DNS addr : 210.220.163.82
```

Figure 42: Correct Image Version for Peri Quad_dec Sample

- Run command as in [Figure 43](#) and [Figure 44](#)



```
[/DA16200/ble] #
[/DA16200/ble] # peri quad_dec

-----
peri quad_dec : configure and read from the
                Quadrature Decoder peripheral
                that is connected to DA14531.
-----
SYNTAX: peri quad_dec start : start quadec
       peri quad_dec stop  : stop quadec
-----
[/DA16200/ble] # peri quad_dec start
Sample Configuration Menu
-----
Number of events before Quadrature Decoder interrupt ?
Type [ENTER] only for default (1) :
The clock divisor of the quadrature decoder ?
Type [ENTER] only for default (1) :

Configuration Summary
-----
event count before quadec interrupt = 1
clock divisor of quadec = 1
CHX_A/CHX_B Pins (fixed in DA14531 of DA16600) = p0_8 (ChxA), p0_9 (ChxB)
SAMPLE CONFIGURATION CONFIRM ? [Yes/No/Quit] : y

[/DA16200/ble] #
<<< APP_PERI_QUAD_DEC_START_IND
... Started
[/DA16200/ble] #
```

```
COM68 - COMBO - DA14531 VT
File Edit Setup Control Window Help
Quadrature Decoder initialized and the interrupt enabled!
if an interrupt occurs, the following message is printed
Quadec ISR report:
DX:xxxx DY:xxxx DZ:xxxx
To release Quadrature Decoder, run [peri quad_dec stop] at DA16200
Quadrature Decoder released!
Quadrature Decoder initialized and the interrupt enabled!
if an interrupt occurs, the following message is printed
Quadec ISR report:
DX:xxxx DY:xxxx DZ:xxxx

Quadec ISR report:
DX: 0001 DY: 0000 DZ: 0000
Quadec ISR report:
DX: 0001 DY: 0000 DZ: 0000
Quadec ISR report:
DX: 0002 DY: 0000 DZ: 0000
Quadec ISR report:
DX: 0004 DY: 0000 DZ: 0000
Quadec ISR report:
DX: 0005 DY: 0000 DZ: 0000
Quadec ISR report:
DX: 0005 DY: 0000 DZ: 0000
```

Figure 43: Peri Quad_dec – Start

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```

[/DA16200/b1e] #
[/DA16200/b1e] #
[/DA16200/b1e] #
[/DA16200/b1e] # peri quad_dec stop
[/DA16200/b1e] #
<<< APP_PERI_QUAD_DEC_STOP_IND
... Stopped

[/DA16200/b1e] #
[/DA16200/b1e] # █

```

```

Quadrature Decoder released!

```

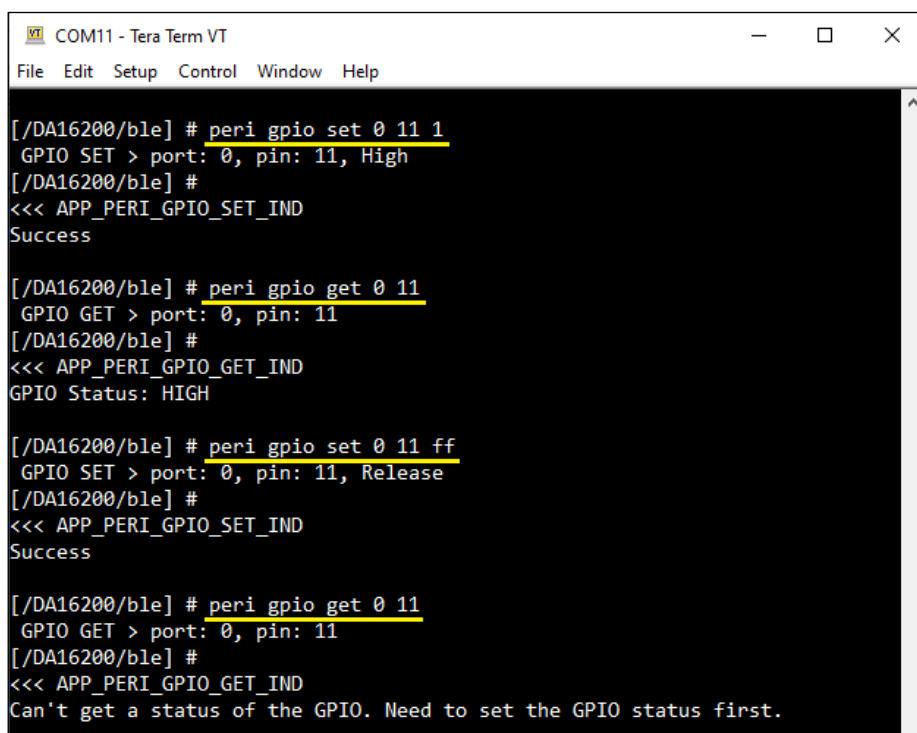
Figure 44: Peri Quad_dec – Stop

After all tests, revert to Configuration_1 for the next sample test.

- peri gpio
 - The GPIO example demonstrates how to set/get the state of a GPIO of DA14531. If you set the state of a GPIO of DA14531 to either HIGH or LOW, the state will be kept although DA14531 is in sleep. If you do not want to control the GPIO state of DA14531 anymore, then you need to set the GPIO to 0xFF
 - DA16600 EVB Configuration:
 - Configuration_1
 - See the Section 6.4.4.3 to check available GPIOs in DA14531
 - DA14531 image used:
 - Download the image below for this test.
 - ~SDK\apps\da16600\get_started\img\DA14531_1\ da14531_multi_part_proxr.img.
 - Run command as below:
 - SYNTAX: SET

- peri gpio set port_no pin_no 1 | 0 | FF : 1(High), 0(Low), FF(Release)
 - ex) peri gpio set 0 8 1 ; Set GPIO0_8 to High
 - SYNTAX: GET

- peri gpio get port_no pin_no
 - ex) peri gpio get 0 8 ; Get GPIO0_8 status



```

COM11 - Tera Term VT
File Edit Setup Control Window Help

[/DA16200/ble] # peri gpio set 0 11 1
GPIO SET > port: 0, pin: 11, High
[/DA16200/ble] #
<<< APP_PERI_GPIO_SET_IND
Success

[/DA16200/ble] # peri gpio get 0 11
GPIO GET > port: 0, pin: 11
[/DA16200/ble] #
<<< APP_PERI_GPIO_GET_IND
GPIO Status: HIGH

[/DA16200/ble] # peri gpio set 0 11 ff
GPIO SET > port: 0, pin: 11, Release
[/DA16200/ble] #
<<< APP_PERI_GPIO_SET_IND
Success

[/DA16200/ble] # peri gpio get 0 11
GPIO GET > port: 0, pin: 11
[/DA16200/ble] #
<<< APP_PERI_GPIO_GET_IND
Can't get a status of the GPIO. Need to set the GPIO status first.
  
```

Figure 45: Peri GPIO Set/Get

5.6 Example 5: TCP DPM Client

5.6.1 Test Environment Setup

- Wi-Fi Router: MyAP
- TCP Client
 - H/W: **DA16600_EVB_1**
 - S/W: program SFLASH with **DA16200_SW_3** + **da14531_multi_part_proxr.img**
- Two Tera Term windows: **da16_tera_win**, and **da14_tera_win**
- TCP Server: any TCP Server utility is OK, for example, IONINJA, or an Android/iOS TCP network tool

5.6.2 Test Steps

- TCP Server machine (Windows utility/mobile application)
 - Connect to MyAP (either through a wired port or Wi-Fi port – wired connection preferred)
 - Run TCP Server tool (with the port number set to 10194)
 - Take note of TCP Server information: IP = 192.168.0.230, Port = 10194
- TCP Client
 - **da16_tera_win**
 - type "factory" > type "y"
 - Run Wi-Fi Provisioning to connect to MyAP. See Section 5.2
 - type


```
nvrnv.setenv TCPC_SERVER_IP 192.168.0.230
```

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```
nvrnm.setenv TCPC_SERVER_PORT 10194
```

```
– type "dpm on"
```

DA16600_EVB_1 is rebooted and enters DPM Sleep as in [Figure 46](#).

```
BLE_BOOT_MODE_0
BLE FW VER to transfer ....
>>> v.6.0.14.1114.1 (id=1) at bank_1
>>> Selected BSS 90:9f:33:66:26:52 ssid='mike.sj.home.2G' (-32)
>>> Network Interface (wlan0) : UP
>>> Associated with 90:9f:33:66:26:52

Connection COMPLETE to 90:9f:33:66:26:52

-- DHCP Client WLAN0: SEL
-- DHCP Client WLAN0: REQ
BLE FW transfer done
<<< GAPM_DEVICE_READY_IND
Advertising...
-- DHCP Client WLAN0: BOUND
    Assigned addr : 192.168.0.24
    netmask       : 255.255.255.0
    gateway       : 192.168.0.1
    DNS addr      : 210.220.163.82

    DHCP Server IP : 192.168.0.1
    Lease Time     : 02h 00m 00s
    Renewal Time   : 01h 40m 00s
[tcp_client_dpm_sample] Start TCP Client Sample
[tcp_client_dpm_sample_load_server_info] TCP Server Information(192
.168.0.230:10194)
[tcp_client_dpm_sample_init_callback] Boot initialization
[dpmTcpClientManager] Started dpmTcpClientManager session no:1
[runTcpClient] TCP Client Start (name:DPM_SESS1_TRD svrIp:192.168.0
.230 svrPort:10194 local_port:10192)
[tcp_client_dpm_sample_connect_callback] TCP Connection Result(0x0)

UART-RTS: pulldown retained in sleep ...
[runTcpClient] Connected server_ip:192.168.0.230 server_port:10194
ka_interval:0

>>> Start DPM Power-Down !!!
```

Figure 46: TCP Client in DPM Sleep

- TCP Server Tool
 - Send a text to TCP Client
- TCP Client
 - TCP Client wakes up, receives, processes data, and enters sleep

```
UART-RTS: pulldown retained in sleep ...
[runTcpClient] Connected server_ip:192.168.0.230 server_port:10194
ka_interval:0

>>> Start DPM Power-Down !!!

Wakeup source is 0x82
gpio wakeup enable 04010001

>>> TIM STATUS: 0x00000001
>>> TIM : UC
by default, rf_meas_btcoex(1, 0, 0)
[tcp_client_dpm_sample] Start TCP Client Sample
wakeup_type=2
BLE_BOOT_MODE_1
[tcp_client_dpm_sample_wakeup_callback] DPM Wakeup
[dpmTcpClientManager] Started dpmTcpClientManager session no:1
[runTcpClient] TCP Client Start (name:DPM_SESS1_TRD svrIp:192.168.0
.230 svrPort:10194 local_port:10192)
=====> Received Packet(5)
<===== Sent Packet(5)
UART-RTS: pulldown retained in sleep ...

>>> Start DPM Power-Down !!!
rwnx send set ps m
```

Figure 47: TCP Client – Wakeup from DPM Sleep

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- Wi-Fi Provisioning while DA16600 is in sleep mode
 - Wi-Fi Provisioning APP: Start > Connect to "DA16600" > DA16600 wakes up and connects to Wi-Fi Provisioning, then do provision to an AP if needed

5.7 Example 6: IoT Sensor Gateway

- ssh_win_2 (RBP3_1)
 - root@raspberrypi:/home/pi# **sh ./run-iot-sensor.sh**
 - >> sensor_1 starts running
- ssh_win_3 (RBP3_2)
 - root@raspberrypi:/home/pi# **sh ./run-iot-sensor.sh**
 - >> sensor_2 starts running

NOTE

With the above you started two Bluetooth® LE temperature sensors (RBP3_1 and RBP3_2). Two sensors (sensor_1 and sensor_2) are now advertising, which means waiting to be connected by a GAP Central which is DA16600_EVB_2.

- Instead of the RBP3_1 and RBP3_2, extra two DA16600 boards – **DA16600_EVB_1** that programmed DA16200_SW_1 and DA14531_IMG (Prj1_proxr) – can be used for this test as IoT sensor devices as well.
This is described in Section 5.1.4, the images are used for Example 1,2, or 3.
- da16_tera_win
 - Power off DA16600_EVB_1 and power ON DA16600_EVB_2
 - Connect Tera Term to DA16600_EVB_2 (sensor_gateway)
 - By default, the sensor gateway is running as "Bluetooth® LE GAP Central" that scans neighbor GAP Peripheral devices
 - Once the scan is finished, enter "Provisioning" mode as shown below
NOTE: wait until ">>> Please connect or rescan. Type in" is fully displayed before you do this action

```
// User command in bold font, commentary / messages to note in blue font
...

#####
# DA14531 Proxm Sensor Gateway demo application  #
#####

# No.  bd_addr          Name                Rssi          #
#  1   d9:6c:3f:82:7b:1c  Mi Band 3          -61 dB        #
#  2   b8:27:eb:e8:8e:24  sensor_1           -56 dB        #
>>> Please connect or rescan. Type in "[/DA16xxx/ble] # proxm_sensor_gw" for cmd
options // LE scan finished

[/DA16200] #
[/DA16200] # ble
      Command-List is changed, "ble"
[/DA16200/ble] # proxm_sensor_gw provision_mode
[/DA16200/ble] # [ConsoleEvent] user command exists in queue
CONSOLE_ENABLE_WFSVC_CMD
[ConsoleEvent] user command handled
Advertising... // starts Bluetooth® LE advertising ...
```

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- Now DA16600_EVB_2 (sensor_gateway) is in advertising mode (GAP Peripheral). Follow instructions from Section 5.2 to do provisioning
- When DA16200 is provisioned, DA16600_EVB_2 is rebooted and gets back to GAP Central mode, and LE Scanning starts automatically
- Gateway device in Bluetooth® LE scanning

```
// User command in bold font, commentary / messages to note in blue font

...

#####
#   DA14585 Proximity Monitor demo application   #
#####

# No.  bd_addr                Name                Rssi                #
#  1   b8:27:eb:e8:8e:24      sensor_1          -48 dB              #
#  2   b8:27:eb:c6:be:74      sensor_2          -42 dB              #
#  3   ec:b3:07:60:6a:a4      Mi Smart Band 4    -62 dB              #
#  4   80:ea:ca:80:00:01      Dialog SOC Demo    -58 dB              #
Scanning... Please waitGAPM_ADV_REPORT_IND
>>> Please connect or rescan. Type in "[/DA16xxx/ble] # proxm_sensor_gw" for cmd
options

[/DA16200/] # ble
    Command-List is changed, "ble"
[/DA16200/ble] #
[/DA16200/ble] # proxm_sensor_gw
Usage: BLE PROXM & Sensor Gateway Sample Application command
Name
    proxm_sensor_gw - Proximity Monitor and Sensor GW cmd
SYNOPSIS
    proxm_sensor_gw [OPTION]
OPTION DESCRIPTION
    scan
        Scan BLE peers around
    show_conn_dev
        shows connected BLE peers with status
    rd_rssi_conn_dev
        read rssi for all connected devices
    read_temp
        read temperature sensor values from all connected devices
    conn [1~9]
        connect to a ble peer from the scan list
        choose index from the scan list
    peer [1~9] [A|B|...|Z]
        take an action on a connected BLE peer
        -----proxm cmd -----
        A: Read Link Loss Alert Level
        B: Read Tx Power Level
        C: Start High Level Immediate Alert
        D: Start Mild Level Immediate Alert
        E: Stop Immediate Alert
        F: Set Link Loss Alert Level to None
        G: Set Link Loss Alert Level to Mild
        H: Set Link Loss Alert Level to High
        I: Show device info
        -----custom cmd -----
```

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```

J: Enable iot sensor's temperature posting
K: Disable iot sensor's temperature posting
-----common cmd -----
Z: Disconnect from the device

exit
all peers are disconnected
[/DA16200/ble] # proxm_sensor_gw conn 1
...
[/DA16200/ble] # proxm_sensor_gw conn 2
...

#####
##### Connected Devices #####
#####

# No. Model No.      BDA          Bonded RSSI   LLA  TX_PL  Temp
# * 1 iot_sensor    b8:27:eb:c6:be:74  NO
#   2 iot_sensor    b8:27:eb:e8:8e:24  NO
#   3              -- Empty Slot --
#
#####

[/DA16200/ble] # proxm_sensor_gw peer 1 J
...

[/DA16200/ble] # proxm_sensor_gw peer 2 J
...
#####
##### Connected Devices #####
#####

# No. Model No.      BDA          Bonded RSSI   LLA  TX_PL  Temp
# * 1 iot_sensor    b8:27:eb:c6:be:74  NO              35
#   2 iot_sensor    b8:27:eb:e8:8e:24  NO              13
#   3              -- Empty Slot --
#
#####

```

NOTE

Depending on your RF signal environment, sensor_1 or sensor_2 may not easily get connected. In such a case, run the scan again and try to connect.

- ssh_win_2

```

...
Registering GATT application...
GetManagedObjects
GATT application registered
temperature value: 33 // command "J" let sensor start temperature posting
temperature value: 31

```

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```
temperature value: 0
temperature value: 25
...
```

- ssh_win_3

```
...
Registering GATT application...
GetManagedObjects
GATT application registered
temperature value: 8 // command "J" let sensor start temperature posting
temperature value: 12
temperature value: 37
temperature value: 2
temperature value: 32
temperature value: 19
temperature value: 30
temperature value: 37
temperature value: 4
temperature value: 28
temperature value: 39
...
```

- ssh_win_1

```
...
root@raspberrypi:/home/pi# python udp_server.py
UDP Server: waiting for a message ... at 172.16.30.136:10954
...
>>> iot_sensor[1], temperature value = 32
>>> iot_sensor[2], temperature value = 17
>>> iot_sensor[1], temperature value = 17
>>> iot_sensor[2], temperature value = 21
...
```

The following is happening:

- DA16600_EVB_2 acts as Bluetooth® LE GAP Central. You will see it start LE scanning when it is booted
- We have two Bluetooth® LE (virtual) temperature sensors running: sensor_1 (RBP3_1) and sensor_2 (RBP3_2). And act as GAP Peripheral devices
- DA16600_EVB_2 finds two sensors during LE Scan
- If you run **proxm_sensor_gw conn 1**, DA16600_EVB_2 initiates connection to sensor_1. Same way, you also initiate a connection to sensor_2
- Once a connection is made, depending on the RF environment, you may need to try the scan command **proxm_sensor_gw scan** several times to get sensor 1 or 2 correctly listed
- When two sensors are connected, you can now set each sensor to start reading and posting temperature values with command **proxm_sensor_gw peer [1/2] J**
- An RBP3 Sensor has a simple GATT service running as shown in [Figure 48](#)

```

class TestService(Service):
    """
    Dummy test service that provides characteristics and descriptors that
    exercise various API functionality.

    """
    TEST_SVC_UUID = '12345678-1234-5678-1234-56789abcdef0'

    def __init__(self, bus, index):
        Service.__init__(self, bus, index, self.TEST_SVC_UUID, True)
        self.add_characteristic(TestCharacteristic(bus, 0, self))
        #self.add_characteristic(TestEncryptCharacteristic(bus, 1, self))
        #self.add_characteristic(TestSecureCharacteristic(bus, 2, self))

class TestCharacteristic(Characteristic):
    """
    Dummy test characteristic. Allows writing arbitrary bytes to its value, and
    contains "extended properties", as well as a test descriptor.

    """
    TEST_CHRC_UUID = '12345678-1234-5678-1234-56789abcdef1'

    def __init__(self, bus, index, service):
        Characteristic.__init__(
            self, bus, index,
            self.TEST_CHRC_UUID,
            ['read', 'notify'],
            service)
        self.notifying = False
        self.value = 24 # room temperature
        self.add_descriptor(TestDescriptor(bus, 0, self))
        Glib.timeout_add(5000, self.force_change_temp) # in mili-second

    def notify_temp_value(self):

```

Figure 48: Sensor_1/2 Bluetooth® LE Peer Sample Implementation (in Python)

- Sensor Service detail: implement the following GATT service on your Bluetooth® LE device
 - SVC: UUID = '12345678-1234-5678-1234-56789abcdef0'
 - Temperature characteristic: UUID = '12345678-1234-5678-1234-56789abcdef1', Permission = READ | NOTIFY, Value size = 1 byte
 - If subscription (on CCCD) is requested by a peer, periodic notification starts every five sec (the temperature value is notified every five seconds)
- Every five seconds, sensor_1 and sensor_2 each posts the current temperature to the sensor_gateway (DA16600_EVB_2)
- In the meantime, sensor_gateway is programmed to post one temperature message per every tenth message from a sensor, so you can see the UDP Server print the message received from DA16600_EVB_2 at ssh_win_1

6 Code Walkthrough

6.1 SDK Source Structure

In the DA16600, the Wi-Fi (DA16200) and Bluetooth® LE (DA14531) chips are connected via four-wire UART (Tx, Rx, RTS, and CTS, the baud rate is 115200 by default) and communicate with each other over Dialog Semiconductor's proprietary GTL interface. In the GTL architecture, a Bluetooth® LE application is running on the external host (DA16200).

As the GTL architecture is used in DA16600, a user application developer should understand and know how to use the user APIs for both external host platforms (DA16200) and Bluetooth® LE platform (DA14531). Read the Programmer Guides for both platforms to get familiar with user APIs:

[1]: DA16200 SDK Programmer Guide

[2]: UM-B-143, Dialog External Processor Interface

[3]: DA14531 Getting Started Guide

[4]: DA14531 SW Platform Reference

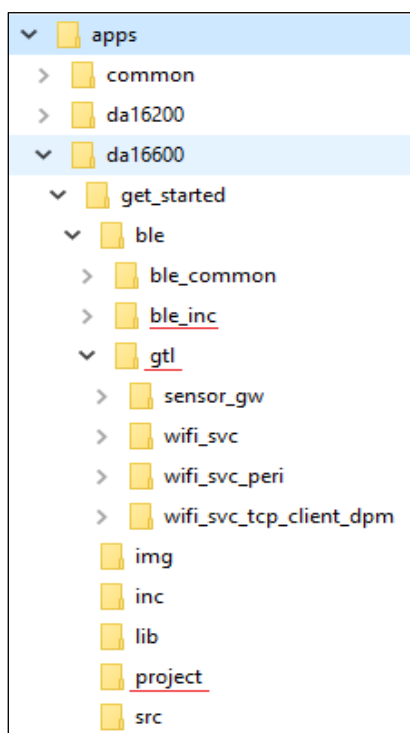


Figure 49: Source Folder Structure

- **ble_inc** folder contains the header files for the DA14531 SDK
You can get the DA14531 SDK version being used at **ble_inc**. If you need to migrate to a newer DA14531 SDK version, update the header files in this folder with those of the newer DA14531 SDK. Note that some header files may need to be modified for the host platform (DA16200)
- **gtl** folder contains four example applications:
 - **wifi_svc**: GAP Peripheral example application based on a Bluetooth® LE example "proximity reporter" ([DA14531_SDK_ROOT] projects\host_apps\windows\proximity\reporter\)
This sample includes two applications:

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- **Wi-Fi Provisioning application:** GATT Server implementation to communicate with Bluetooth® LE peer applications (Wi-Fi Provisioning Mobile APP)
- **Gas leak detection sensor application** works with a gas leak sensor (virtual) that is locally connected to the DA14531 chip. When a gas leak event occurs, this application posts a message to a network server in TCP/IP network
- **wifi_svc_tcp_client_dpm:** GAP Peripheral example application based on a Bluetooth® LE example "proximity reporter" ([DA14531_SDK_ROOT] projects\host_apps\windows\proximity \reporter\)
This sample includes two applications:
 - **Wi-Fi Provisioning application:** GATT Server implementation to communicate with Bluetooth® LE peer applications (Wi-Fi Provisioning Mobile APP)
 - **TCP Client DPM application:** a pure TCP/IP network application that communicates with a TCP Server in the network connected
- **wifi_svc_peri:** GAP Peripheral example application based on a Bluetooth® LE example "proximity reporter" ([DA14531_SDK_ROOT] projects\host_apps\windows\proximity \reporter\)
This sample includes two applications
 - **Wi-Fi Provisioning application:** GATT Server implementation to communicate with Bluetooth® LE peer applications (Wi-Fi Provisioning Mobile APP)
 - **DA14531 Peripheral driver sample:** this application configures and runs some peripheral devices locally attached to DA14531
- **sensor_gw:** GAP Central example application based on a Bluetooth® LE example "proximity monitor" (projects\host_apps\windows\proximity\monitor\). This is a GATT Client application used in example 4
- **project** folder contains the project-related files to build with IAR tool.

6.2 Startup and GTL Initialization

```
// code highlighted in bold font, commentary in blue font

int system_start(void) {
...
    /* combo: init four-wire UART, dpm_boot_type, ble_boot_mode, download ble fw.
    dpm_boot_type identifies system state like NO_DPM/DPM/DPM_WAKEUP/... ble_boot_mode
    decides whether or not ble downloading is needed or not. */
    combo_init();
    ...
    Wlaninit(); // wlan is initialized.
    ...
    start_sys_apps();
    ...
    start_user_apps();
}

// When external host (DA16200) boots, BLE user application thread defined in
user_apps_table[ ] is run with user defined config
```

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```
// user_apps.c
...
const app_thread_info_t    user_apps_table[] = {
...
{ APP_GTL_INIT,            gtl_init,            2048, OAL_PRI_APP(1), FALSE,        FALSE,
  UNDEF_PORT,              RUN_STA_MODE  },
...
}
// see DA16200 Programmer Guide [1] > Section 2.4

// wifi_svc_app.c
void gtl_init(ULONG arg) {
...
host_uart_init(); // UART init
...
boot_ble_from_uart(); // transfer ble firmware to DA14531
...
tx_thread_create(...,gtl_main, ...) // the main gtl message handler
...
}

void gtl_main(ULONG arg)
{
...
tx_thread_create(...,gtl_host_ifc_mon, ...) // a thread monitoring GTL message Rx
...
While(1) {

  BleReceiveMsg(); // this function is the main GTL message handler, ensure that
  HandleBleMsg() is invoked to check which GTL message is explicitly handled.
}
}
```

6.3 DA16600 Application Development

The four Bluetooth® LE example applications (**Gas leak sensor**, **TCP Client**, **DA14531 Peri Driver**, and **Sensor Gateway**) are based on the two basic external host examples included in the DA14531 SDK:

- [DA14531_SDK_ROOT]\projects\host_apps\windows\proximity\monitor
- [DA14531_SDK_ROOT]\projects\host_apps\windows\proximity\reporter

The Bluetooth® LE application flow (initialization and operation) is the same as for those examples.

A DA16600 user application (that may want to use both Wi-Fi and Bluetooth® LE functions) needs the development of functions that use both Wi-Fi APIs and Bluetooth® LE APIs.

To develop a function that talks to a Bluetooth® LE Peer (for example, can talk to the Provisioning Mobile Application), the application should be developed based on UM-B-143, Dialog External Processor Interface [2].

To develop a local function (for example, driver function) in DA14531 (for example, to handle a custom GTL message that should be handled in DA14531), the user also needs to understand the local APIs of the DA14531. See Section 2 of Ref. [4]. Software Platform Overview, or the API documentation included in the DA14531 SDK.

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To develop a function that talks to a networked TCP/UDP peer (for example, can talk to RBP3's UDP Server Application), the application should be developed based on the DA16200 SDK Programmer Guide [1].

6.4 Examples

6.4.1 Bluetooth® LE Assisted Wi-Fi Provisioning

6.4.1.1 Application Build and Run

```
// code highlighted in bold font, commentary in blue font

// NOTE: Wi-Fi Provisioning (Bluetooth® LE GATT Service) application/service is
// included in all the examples. Below we explain the code using one (/wifi_svc) of
// examples.

apps/da16600/get_started/inc/ble_combo_features.h
...
#define COMBO_SAMPLE_BLE_PERI_WIFI_SVC
#undef WIFI_SVC_SECURITY // if you enable this option, when a peer tries to
// access one of your characteristics (1 time), a pop-up window asking pin code is
// shown at a peer app side.
...
#undef COMBO_SAMPLE_BLE_CENT_SENSOR_GW
...
```

6.4.1.2 Application Initialization

```
// code highlighted in bold font, commentary in blue font

/*
There are two main user threads created ...
- To read GTL messages from UART: gtl_host_ifc_mon
- To handle a GTL message: gtl_main
*/

// wifi_svc_app.c
void gtl_main(ULONG arg)
{
...
    status = tx_thread_create(tx_gtl_host_ifc_mon, // GTL message reader thread
                             "gtl_host_ifc_mon",
                             gtl_host_ifc_mon,
                             NULL,
                             gtl_host_ifc_mon_stack,
                             GTL_HOST_IFC_MON_STACK_SZ,
                             OAL_PRI_APP(0),
                             OAL_PRI_APP(0),
                             TX_NO_TIME_SLICE,
                             TX_AUTO_START);
...

    // GTL message handler loop
    while(1)
    {
        BleReceiveMsg(); // once a GTL message is available in the queue, this loop
    }
}
```

```

// resumes and handles it.
    }
...
void gtl_host_ifc_mon(ULONG arg)
{
    UARTProc();
}

void UARTProc(void)
{
    ...
    while(1)
    {
        tmp = getchar_uart1(OAL_SUSPEND); // waiting for data from DA14531
        ...
        switch(bReceiveState)
        {
            case 0: // Receive FE_MSG
                if(tmp == FE_MSG_PACKET_TYPE)
                {
                    bReceiveState = 1;
                    ...
                    // once a known type of message - GTL type - is received, it is
                    // EnQueued (GtlRxQueue)
                    SendToMain((unsigned short) (wReceive232Pos-1), &bReceive232ElementArr[1]);
                }
            ...
        }
    }
}

void BleReceiveMsg(void)
{
    ...
    msg = (ble_msg*) DeQueue(&GtlRxQueue); // a message is dequeued
    ...
    HandleBleMsg(msg); // main GTL message handler function
    ...
}

void HandleBleMsg(ble_msg *blemsg)
{
    // for each GTL message type, a handler defined is invoked. This message type is
    // defined in DA14531 SDK headers.
    ...
    case GAPM_CMP_EVT:
        HandleGapmCmpEvt(blemsg->bType, (struct gapm_cmp_evt *)blemsg->bData, blemsg->
        >bDstid, blemsg->bSrcid);
        ...
    case GAPM_DEVICE_READY_IND:
        DBG_INFO("<<< GAPM_DEVICE_READY_IND \n");
        gapm_device_ready_ind_handler(blemsg->bType, (struct gap_ready_evt *)blemsg->
        >bData, blemsg->bDstid, blemsg->bSrcid);
        break;
    ...
}

```

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6.4.1.3 GTL Message Flow

Initialization until Advertising

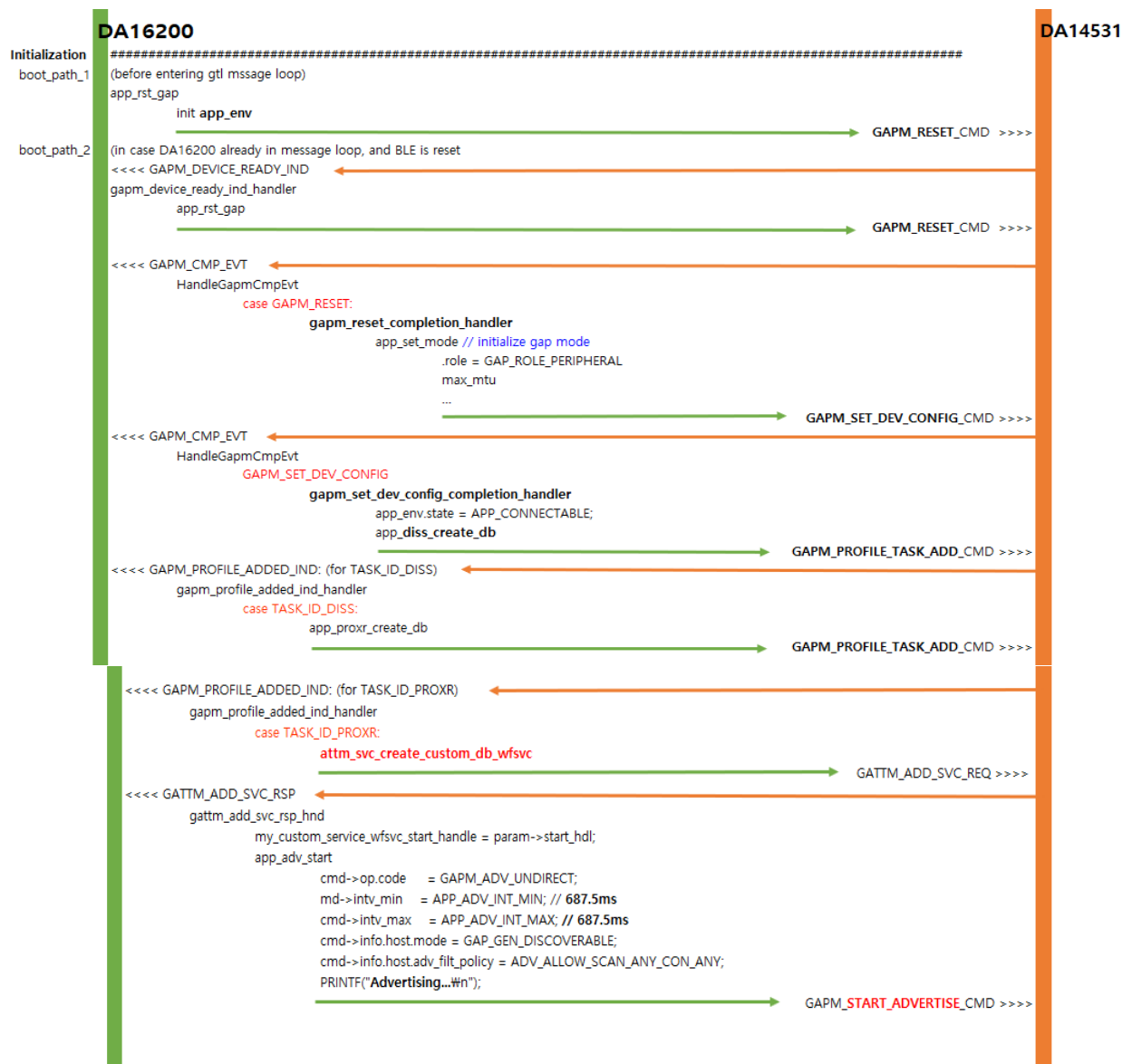


Figure 50: GTL Message Sequence Chart – Initialization

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Connection Request and Characteristic "Write" Request

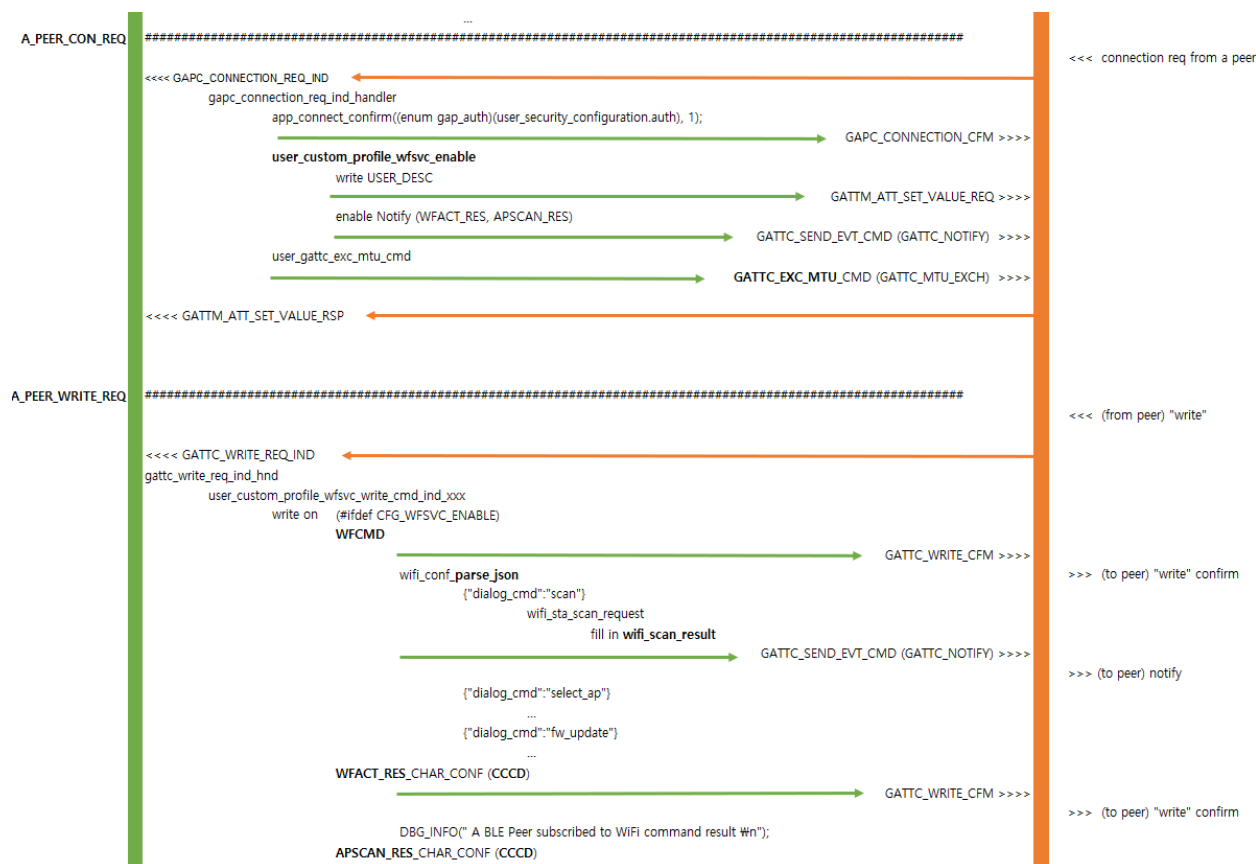


Figure 51: GTL Message Sequence Chart – Connect and Write

Characteristic "Read" Request

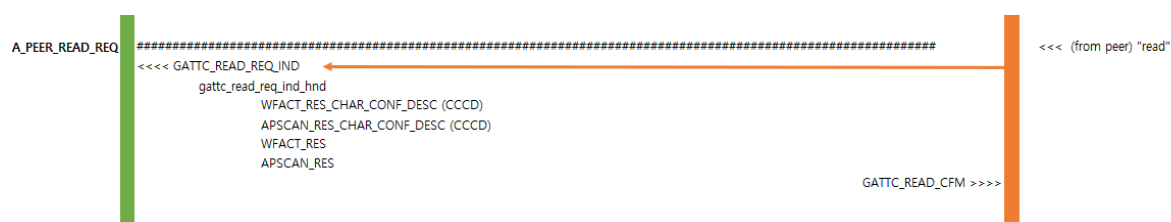


Figure 52: GTL Message Sequence Chart – Read

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6.4.1.4 Wi-Fi Service GATT Database Design

The sample "Wi-Fi Service" GATT Server database is designed as in Table 2. This is just a sample database design, so SDK users that depend on their application use cases may want to create a different design. See file `wifi_svc_user_custom_profile.c/h` for more details.

Table 2: Wi-Fi SVC GATT Service Design

| Att Idx | | Att Type | UUID | Prop. (R/W) | Value Size | RI | User Desc. | Value to Read/Write |
|---------------|---------------------|--------------------|-------------------------------------|-----------------------------|------------|----|------------|---|
| Wi-Fi Service | | | 9161b201-1b4b-4727-a3ca-47b35cdf5c1 | | | | | |
| 1 | Wi-Fi cmd | Declaration | | | | | | |
| 2 | | Value | 9161b202-1b4b-4727-a3ca-47b35cdf5c1 | Write | 244 | - | | <pre>{ "dialog_cmd": "scan" } { "dialog_cmd": "select_ap", "SSID": "linksys", "security_type": 3, ... } See the function wifi_conf_parse_json() for more details</pre> |
| 3 | | Description (user) | | Read | | N | Wi-Fi Cmd | |
| 4 | Wi-Fi action result | Declaration | | | | N | | |
| 5 | | value | 9161b203-1b4b-4727-a3ca-47b35cdf5c1 | Read Notify | 2 | Y | | <pre>// Wi-Fi Action Result enum WIFI_ACTION_RESULT { COMBO_WIFI_CMD_SCAN_AP_SUCCESS = 1, COMBO_WIFI_CMD_SCAN_AP_FAIL, COMBO_WIFI_CMD_FW_BLE_DOWNLOAD_SUCCESS, COMBO_WIFI_CMD_FW_BLE_DOWNLOAD_FAIL, ... }; See the "enum WIFI_ACTION_RESULT" for more details</pre> |
| 6 | | Description (cccd) | | Read Write Write w/o. | | Y | | |
| 7 | | Description (user) | | Read | | N | | |

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| Att Idx | | Att Type | UUID | Prop. (R/W) | Value Size | RI | User Desc. | Value to Read/Write |
|---------|----------------|--------------------|-------------------------------------|-------------|------------|----|---------------------|---------------------|
| 8 | AP Scan result | Declaration | | | | N | Wi-Fi Action Result | |
| 9 | | Value | 9161b204-1b4b-4727-a3ca-47b35cdf5c1 | Read | 244 | Y | | |
| 10 | | Description (user) | | Read | | N | AP Scan Result | |

6.4.1.5 Application Protocol Between a Bluetooth® LE Peer and Wi-Fi SVC Application

Based on the Wi-Fi SVC GATT Database described in the previous section, the following protocols are used between the Wi-Fi SVC application and the Provisioning Mobile App application.

- Characteristic: "Wi-Fi Cmd" (244 bytes), **WRITE**

- "scan" command can be sent by a Bluetooth® LE Peer that wants the DA16600 device to scan Wi-Fi routers

```
{
  "dialog_cmd": "scan"
}
```

- "select_ap" command can be sent by a Bluetooth® LE Peer to tell the DA16600 device which AP to connect to (plus other customer proprietary information, if needed, such as customer server information)

Upon receipt of this command, DA16600 stores the credentials in permanent storage (NVRAM) and reboots

```
{
  "dialog_cmd": "select_ap",
  "SSID": "linksys",
  "security_type": 3, /* 0 = none, 1 = WEP, 2 = WPA, 3 = WPA2 */
  "DHCP": 0, /* 0 = Static IP, 1 = DHCP, 2 = RFC3927 */
  "password": "123456789",
  "ipv4_address": "192.168.20.5",
  "mask": "255.255.255.0",
  "gateway": "192.168.20.1",
  "dns_address": "8.8.8.8",
  "dpm_mode": 0 // for Demo 3, the value should be 1
  ...
  // additional paramters if needed
  "svr_addr": "172.16.0.100", // should be valid for Demo 3
  "svr_port": 10925, // should be valid for Demo 3
  ...
}
```

- "fw_update" command can be sent by a Bluetooth® LE Peer to tell DA16600 to download new firmware from a specified OTA server

```
{
  "dialog_cmd": "fw_update"
}
```

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- "factory_reset" command can be sent by a Bluetooth® LE Peer to tell DA16600 to remove the Wi-Fi network profile saved. The DA16600 EVB will reboot after the reset

```
{
  "dialog_cmd": "factory_reset"
}
```

- "reboot" command can be sent by a Bluetooth® LE Peer to tell DA16600 to reboot. On reboot, if a valid network profile exists, the DA16200 connects to the specified AP

```
{
  "dialog_cmd": "reboot"
}
```

- "wifi_status" command can be sent by a Bluetooth® LE Peer to find out the Wi-Fi connection status (connected or disconnected). The Bluetooth® LE peer can be notified of, or read, the status via the "Wi-Fi Action Result" characteristic

```
{
  "dialog_cmd": "wifi_status"
}
```

- "disconnect" command can be sent by a Bluetooth® LE Peer to disconnect a Wi-Fi connection from the currently connected AP. If the Bluetooth® LE Peer wants to reconnect to the same AP, it should send the command "reboot" to have the DA16600 EVB connect to the AP

```
{
  "dialog_cmd": "disconnect"
}
```

- If you want to add a new custom command, use the following
 - enum WIFI_CMD // define a new custom command
 - user_custom_profile_wfsvc_write_cmd_ind_xxx() // add the handler of the command
 - wifi_conf_parse_json // add the parser of the command

- Characteristic: "Wi-Fi Action Result" (two bytes), **READ, NOTIFY**

- A Bluetooth® LE Peer is supposed to enable notification on this characteristic on connection
- Then the Bluetooth® LE Peer is notified of the result of a Wi-Fi command sent

```
// Wi-Fi Action Result
enum WIFI_ACTION_RESULT {
  COMBO_WIFI_CMD_SCAN_AP_SUCCESS = 1,
  COMBO_WIFI_CMD_SCAN_AP_FAIL,

  COMBO_WIFI_CMD_FW_BLE_DOWNLOAD_SUCCESS,
  COMBO_WIFI_CMD_FW_BLE_DOWNLOAD_FAIL,

  COMBO_WIFI_CMD_INQ_WIFI_STATUS_CONNECTED,
  COMBO_WIFI_CMD_INQ_WIFI_STATUS_NOT_CONNECTED,

  COMBO_WIFI_PROV_DATA_VALIDITY_CHK_ERR,
  COMBO_WIFI_PROV_DATA_SAVE_SUCCESS,

  COMBO_WIFI_CMD_MEM_ALLOC_FAIL,

  COMBO_WIFI_CMD_UNKNOWN_RCV
};
```

- Especially on receipt of "COMBO_WIFI_CMD_SCAN_AP_SUCCESS", a Bluetooth® LE Peer is supposed to initiate a "READ" request on the characteristic "AP Scan Result". Usually, the total list of AP Scan results is about 2 kB in size, therefore the Bluetooth® LE Peer should initiate a "READ" request on the characteristic multiple times until all SSIDs are fully read

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- Characteristic: "AP Scan Result" (244 bytes), **READ**
 - When a Bluetooth® LE Peer gets the first read response (with payload), the payload included in the "read" response includes a 4 bytes 'application-specific custom' header (that you can modify freely to your application needs). See below the sample payload structure.
 - [H_1][H_2][JSON_STR]
 - H_1: first two bytes of the header, includes the **remaining length** of the total JSON_STR
 - H_2: the second two bytes of the header, includes the **total length** of JSON_STR.
Normally the total size is over 2 kB
 - JSON_STR: JSON encoded "AP Scan result"
 - Upon receipt of a read response, a Bluetooth® LE Peer is supposed to keep triggering "read" requests on this characteristic until H_1 becomes 0. The read response message that contains 0 as H_1 contains the final fragment of JSON_STR
 - Next, a Bluetooth® LE Peer needs to combine and parse the whole JSON_STR to get the necessary information (in this case, the list of Wi-Fi routers)

Example

```
[
{
  "SSID": "MyAP", // SSID of an AP
  "security_type": 3 // 0=none, 1=WEP, 2=WPA, 3=WPA2
  "signal_strength": 56 // in dBm
},
{
  "SSID": "MyAP2", // SSID of an AP
  "security_type": 0 // 0=none, 1=WEP, 2=WPA, 3=WPA2
  "signal_strength": 24 // in dBm
},
{
  "SSID": "MyAP3", // SSID of an AP
  "security_type": 3 // 0=none, 1=WEP, 2=WPA, 3=WPA2
  "signal_strength": 67 // in dBm
},
...
]
```

Depending on how a Bluetooth® LE Peer App is implemented, a Bluetooth® LE Peer App may let the user select an AP from the list and send a "write" request with {"dialog_cmd": "**select_ap**", ...} on the characteristic "Wi-Fi Cmd".

6.4.2 Bluetooth® LE Firmware OTA Download via Wi-Fi

OTA FW Download Service (Wi-Fi download of FW) is supported and enabled in all examples.

Depending on the customer use scenario, there may be a few ways to trigger an OTA FW Download Service. For example:

- Option 1: using a networked peer (a mobile application that is connected to the Internet or a customer cloud server application on the Internet)
- Option 2: using a Bluetooth® LE Peer

In this example, Option 2 is demonstrated.

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NOTE

Option 1 can be used for unattended/automatic OTA operation. It works as follows:

As a DA16600 device (DA16200 Wi-Fi chip included) is 'always' in a connected state with a Wi-Fi router, which has the Internet connection, a Service Server/Cloud Server can talk with this device when there is a new firmware available on an OTA Server. A Service Server, if needed, can contact a user via 4G/Wi-Fi (in the form of a push message) for firmware update confirmation. Upon receipt of 'user confirmation', the Service Server may ask the DA16600 device to download a new firmware by giving an HTTP(s) URI to an OTA Server. Once the new firmware is received, that firmware is stored in the SFLASH of the DA16600 device, and the DA16600 device restarts to boot with the new software.

For **Option 2**, a Bluetooth® LE Peer App should 'write' the following command on the characteristic "Wi-Fi Cmd" to trigger an OTA FW update:

```
{
  "dialog_cmd": "fw_update"
}
```

Upon receipt of the command, GATTC_WRITE_REQ_IND is sent to the external host (DA16200), and then a handler is invoked.

```
// code highlighted in bold font, commentary in blue font

uint8_t user_custom_profile_wfsvc_write_cmd_ind_xxx(ke_msg_id_t const msgid,
                                                    struct gattc_write_req_ind const *param,
                                                    ke_task_id_t const dest_id,
                                                    ke_task_id_t const src_id)
{
  ...
  /* Parse JSON */
  if (wifi_conf_parse_json(value, &cmd) != 0) {
    DBG_INFO(" UNKNOWN COMMAND!!! \n");
    wfsvc_wifi_cmd_result_notify_user(COMBO_WIFI_CMD_UNKNOWN_RCV);
    goto finish;
  }
  ...
  else if (cmd == COMBO_WIFI_CMD_FW_UPDATE) {
    DBG_INFO(" COMBO_WIFI_CMD_FW_BLE_DOWNLOAD received \n");

    // download DA14531 image from the URL to a special area in sflash

    /* DEMO - TEST CODE */
    ota_fw_update_combo();

    // notify wifi-cmd execution result

    wfsvc_wifi_cmd_result_notify_user(COMBO_WIFI_CMD_FW_BLE_DOWNLOAD_SUCCESS);
  }
  ...
}

UINT ota_fw_update_combo(void)
{
  ...
  status = ota_update_start_download(fw_conf); // API for OTA FW Download service
  ...
}
```

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```
// OTA_update_start_download() function creates an OTA thread - thread function :
ota_update_http_client_update_proc() - which handles http connection, http
download, and firmware renewing process.
```

6.4.3 Gas Leak Detection Sensor

For this example, the same application is used. For information on build and run, see Section 6.4.1.

NOTE

The Gas Leak Detection Sensor application does not need a connection with a Bluetooth®LE Peer.

6.4.3.1 User Interface

Normally, a user may want to use a Mobile Phone (a network peer that is always connected to a Service Server or Cloud Server which is then connected to a gas leak sensor) to control a Wi-Fi IoT device (gas leak sensor). But in this example, DA16200 console commands are used as a sensor controller. See Section 5.4 to know which commands to use (for example, `iot_sensor start`).

6.4.3.2 Operation

When the command **lot_sensor start** or **iot_sensor stop** is used, the following function is invoked:

```
void ConsoleSendSensorStart(void)
{
    console_msg *pmsg = (console_msg *) malloc(sizeof(console_msg));
    pmsg->type = CONSOLE_IOT_SENSOR_START;
    EnQueueToConsoleQ(pmsg);
}
...
void ConsoleEvent(void)
{
    ...
    switch(msg->type)
    {
        case CONSOLE_IOT_SENSOR_START:
            if (app_env.iot_sensor_state == IOT_SENSOR_INACTIVE) {
                app_sensor_start();
            }
        case CONSOLE_IOT_SENSOR_STOP:
            if (app_env.iot_sensor_state == IOT_SENSOR_ACTIVE) {
                app_sensor_stop();
            }
        default:
            break;
    }
    ...
}

void app_sensor_start(void) {
    // Allocate a message for DA14531 (BLE_AUX task - which is a user task)
    void *cmd = BleMsgAlloc(APP_GAS_LEAK_SENSOR_START, TASK_ID_EXT_HOST_BLE_AUX,
TASK_ID_GTL, 0);
    // Send the message
    BleSendMsg(cmd);
}
```

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```
// the message " APP_GAS_LEAK_SENSOR_START" is sent to Bluetooth® LE (DA14531) which
starts sensor reading task (periodically reads a gas-leak sensor).
```

For the external host (DA16200) to be able to talk to the Bluetooth® LE (DA14531) with application messages, the following should be implemented on both Wi-Fi and Bluetooth® LE SDKs:

- For both DA16200 SDK and DA14531 SDK, define custom messages
 - DA16600 SDK – send a custom user-defined message via the GTL interface with TASK_ID_EXT_HOST_BLE_AUX as the destination task
 - DA14531 SDK – enable the BLE AUX task (TASK_ID_EXT_HOST_BLE_AUX) to receive a user-defined custom message
- Develop the message handlers

```
// code highlighted in bold font, commentary in blue font

// Define application-specific messages for your application

// app.h (in DA16600 SDK) and ext_host_ble_aux_task.h (in DA14531 SDK)
...
// the exact same enum should exist on DA14531 SDK
typedef enum {
...

    APP_BLE_SW_RESET,

    APP_GAS_LEAK_SENSOR_START,
    APP_GAS_LEAK_SENSOR_START_CFM,
    APP_GAS_LEAK_SENSOR_STOP,
    APP_GAS_LEAK_SENSOR_STOP_CFM,
    APP_GAS_LEAK_EVT_IND,
    APP_GAS_LEAK_SENSOR_RD_TIMER_ID,

    APP_CUSTOM_COMMANDS_LAST,
} ext_host_ble_aux_task_msg_t;
...

// DA16600 SDK: Develop a function to send the message
void app_sensor_start(void) {
    // Allocate a message for BLE_AUX
    void *cmd = BleMsgAlloc(APP_GAS_LEAK_SENSOR_START, TASK_ID_EXT_HOST_BLE_AUX,
TASK_ID_GTL, 0);
    // Send the message
    BleSendMsg(cmd);
}

// DA14531 SDK: enable BLE AUX task
// user_proxr.c
...
void user_on_init(void)
{
...
    ext_host_ble_aux_init();
    ext_host_ble_aux_task_init();
...
}

// DA14531 SDK: develop message handlers
```


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```
// ext_host_ble_aux_task.c

int ext_host_ble_aux_task_handler (ke_msg_id_t const msgid,
                                   void const *param,
                                   ke_task_id_t const dest_id,
                                   ke_task_id_t const src_id)
{
    ...
    if (msg->dest_id == TASK_EXT_HOST_BLE_AUX)
    {
        switch (msgid)
        {
            ...

            case APP_GAS_LEAK_SENSOR_START:
                app_gas_leak_sensor_start_cfm_send();
                break;

            case APP_GAS_LEAK_SENSOR_STOP:
                app_gas_leak_sensor_stop_cfm_send();
                break;

            ...
        }
    }

    void app_gas_leak_sensor_start_cfm_send(void)
    {
        ke_timer_set(APP_GAS_LEAK_SENSOR_RD_TIMER_ID, TASK_EXT_HOST_BLE_AUX,
                     APP_GAS_LEAK_SENSOR_RD_INTERVAL);

        app_gas_leak_sensor_start_cfm_t *req =
            (app_gas_leak_sensor_start_cfm_t*)ke_msg_alloc(APP_GAS_LEAK_SENSOR_START_CFM,
                  TASK_GTL, TASK_EXT_HOST_BLE_AUX, sizeof(app_gas_leak_sensor_start_cfm_t));
        req->status = APP_NO_ERROR;
        ke_msg_send(req);
    }
}
```

When the gas leak sensor starts, DA16600 enters sleep. Later, if a gas leak event occurs, DA14531 wakes up DA16200 which then sends a message to a server and enters sleep again.

```
int system_start(void)
{
    ...
    sleep2_monitor_start(); // start sleep2_monitor. Sleep2 monitor is used to
    // synchronize sleep between gas leak sensor app and wifi provisioning app,
    ...
}

void gtl_init(ULONG arg)
{
    ...
    sleep2_monitor_regi(SLEEP2_MON_NAME_PROV, __func__, __LINE__); // register gas leak
    // application to sleep2_monitor
    ...
}

int app_sensor_event_ind_hnd(ke_msg_id_t msgid,
                             app_gas_leak_evt_ind_t *param,
                             ke_task_id_t dest_id,
```

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```

                                ke_task_id_t src_id)
{
...
    sleep2_monitor_set_state(SLEEP2_MON_NAME_IOT_SENSOR,
                            SLEEP2_CLR, __func__, __LINE__); // when gas leak happens, tell
sleep2_monitor to hold entering sleep
..
...
iot_sensor_data_info.is_gas_leak_happened = TRUE; // set "gas leak happened" flag
..
}

void udp_client(char *ip_addr_str, int udp_server_port)
{
...
    while (1)
    {
        ...
        if (iot_sensor_data_info.is_gas_leak_happened == FALSE)
        {
            OAL_MSLEEP(100);
            continue; // busy loop on gas leak sensor event
        }
        ...
        // gas leak occurred
        ...
        /* send gas leak message to server */
        status = nx_udp_socket_send(udp_client_sock,
                                    udp_client_pkt,
                                    udp_server_ip_addr,
                                    udp_server_port);

        ...
        sleep2_monitor_set_state(SLEEP2_MON_NAME_IOT_SENSOR,
                                SLEEP2_SET, __func__, __LINE__); // job done. tell
sleep2_monitor to enter sleep
...
    }
}

```

6.4.4 DA14531 Peripheral Driver Example

6.4.4.1 Build

```

// Enable the sample feature below and disable the other samples, and build SDK

apps\da16600\get_started\inc\ble_combo_features.h
...
#define __COMBO_SAMPLE_BLE_PERI_WIFI_SVC_PERIPHERAL_SAMPLE__
...

```

6.4.4.2 Example Code Flow

```

// code highlighted in bold font, commentary in blue font

// Take TIMER0_BUZ (Buzzer playback sample) as an example flow (the other samples
have the same flow sequence)

```

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```
apps\da16600\get_started\ble\gtl\wifi_svc\inc\app.h

...

// GTL messages are defined for TIEMRO_BUZ
typedef enum
{
...
    APP_PERI_BLINKY_START,
    APP_PERI_BLINKY_START_IND,
    APP_PERI_BLINKY_RUN_TIMER_ID,

    APP_PERI_SYSTICK_START,
    APP_PERI_SYSTICK_START_IND,
    APP_PERI_SYSTICK_RUN_TIMER_ID,
    APP_PERI_SYSTICK_STOP,
    APP_PERI_SYSTICK_STOP_IND,

    APP_PERI_TIMER0_GEN_START,
    APP_PERI_TIMER0_GEN_START_IND,
    APP_PERI_TIMER0_GEN_RUN_TIMER_ID,

    APP_PERI_TIMER0_BUZ_START,
    APP_PERI_TIMER0_BUZ_START_IND,
    APP_PERI_TIMER0_BUZ_RUN_TIMER_ID,
...
    APP_CUSTOM_COMMANDS_LAST,
} ext_host_ble_aux_task_msg_t;

apps\da16600\get_started\ble\gtl\wifi_svc_peri\src\wifi_svc_peri_console.c
// user command "ble.peri timer0_buz start" brings an interactive setup menus
void cmd_peri_sample(int argc, char *argv[])
{
...
// collect timer0_buz driver configuration info (to fill in the structure below)
from user
/*
// timer0_buz
typedef struct app_peri_timer0_buz_start
{
    uint8_t t0_pwm0_port;
    uint8_t t0_pwm0_pin;
    uint8_t t0_pwm1_port;
    uint8_t t0_pwm1_pin;

    uint16_t buz_tst_counter;

    tim0_2_clk_div_t t0_t2_in_clk_div_factor;
    TIM0_CLK_SEL_t   t0_clk_src;
    PWM_MODE_t       t0_pwm_mod;
    TIM0_CLK_DIV_t   t0_clk_div;

    int t0_on_reld_val;
    int t0_high_reld_val;
    int t0_low_reld_val;
} app_peri_timer0_buz_start_t;
```

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```

*/

...

// send the sample configuration info to DA14531
app_peri_timer0_buz_start_send(&buz_conf);
...
}

apps\da16600\get_started\ble\gtl\wifi_svc_peri\src\wifi_svc_peri_app.c

// timer0_buzzer -----
void app_peri_timer0_buz_start_send(app_peri_timer0_buz_start_t* config_param)
{
    app_peri_timer0_buz_start_t *req =
    (app_peri_timer0_buz_start_t*)BleMsgAlloc (APP_PERI_TIMER0_BUZ_START,
        TASK_ID_EXT_HOST_BLE_AUX,
        TASK_ID_GTL,
        sizeof(app_peri_timer0_buz_start_t));

    memcpy((void*)req, (void*)config_param, sizeof(app_peri_timer0_buz_start_t));

    BleSendMsg(req);
}

// Now let's look at DA14531 SDK to check how APP_PERI_TIMER0_BUZ_START is handled

[DA14531_SDK_ROOT]\projects\target_apps\ble_examples\prox_reporter_sensor_ext_coex\
include\ext_host_ble_aux_task.h

// same GTL messages are defined in the same order

typedef enum
{
    ...
    APP_PERI_TIMER0_BUZ_START,
    APP_PERI_TIMER0_BUZ_START_IND,
    APP_PERI_TIMER0_BUZ_RUN_TIMER_ID,
    ...
} ext_host_ble_aux_task_msg_t;

[DA14531_SDK_ROOT]\projects\target_apps\ble_examples\prox_reporter_sensor_ext_coex\
src\ext_host_ble_aux_task.c

int ext_host_ble_aux_task_handler (ke_msg_id_t const msgid,
    void const *param,
    ke_task_id_t const dest_id,
    ke_task_id_t const src_id)
{
    ...
    if (msg->dest_id == TASK_EXT_HOST_BLE_AUX)
    {
        switch (msgid)
        {
            ...
            // GTL message handler
            case APP_PERI_TIMER0_BUZ_START:

```

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```

        app_peri_timer0_buz_start_ind_send((app_peri_timer0_buz_start_t*)msg-
        >param);
        break;
...
}

void app_peri_timer0_buz_start_ind_send(app_peri_timer0_buz_start_t* config_data)
{
    // run a timer to start the sample action in 2 seconds
    ke_timer_set(APP_PERI_TIMER0_BUZ_RUN_TIMER_ID, TASK_EXT_HOST_BLE_AUX,
    APP_PERI_SAMPLE_RUN_AFTER);

    memcpy((void*)&conf_buz, (void*)config_data,
    sizeof(app_peri_timer0_buz_start_t));
    clk_div_config.clk_div = conf_buz.t0_t2_in_clk_div_factor;

    // send back the GTL "APP_PERI_TIMER0_BUZ_START_IND" to DA16200 indicating
    timer0_buz sample soon will start. On receipt of this message, DA16200 prints that
    TIMER0_BUZ started.
    app_peri_timer0_buz_start_ind_t *req =
    (app_peri_timer0_buz_start_ind_t*)ke_msg_alloc(APP_PERI_TIMER0_BUZ_START_IND,
    TASK_GTL,
    TASK_EXT_HOST_BLE_AUX,

    sizeof(app_peri_timer0_buz_start_ind_t));
    req->result_code = 0;
    ke_msg_send(req);
}

int ext_host_ble_aux_task_handler (ke_msg_id_t const msgid,
                                void const *param,
                                ke_task_id_t const dest_id,
                                ke_task_id_t const src_id)
{
    ... // timer id handler on expiration
    else if (msgid == APP_PERI_TIMER0_BUZ_RUN_TIMER_ID)
    {
        app_peri_timer0_buz_run();
        return KE_MSG_CONSUMED;
    }
    ...
}

[DA14531_SDK_ROOT]\projects\target_apps\ble_examples\prox_reporter_sensor_ext_coex\
src\peri_test_function.c

// DA14531 TIMER0 PWM driver buzzer implementation
void app_peri_timer0_buz_run(void)
{
    // Configure PWM pin functionality
    GPIO_ConfigurePin((GPIO_PORT)conf_buz.t0_pwm0_port,
    (GPIO_PIN)conf_buz.t0_pwm0_pin, OUTPUT, PID_PWM0, true);
    GPIO_ConfigurePin((GPIO_PORT)conf_buz.t0_pwm1_port,
    (GPIO_PIN)conf_buz.t0_pwm1_pin, OUTPUT, PID_PWM1, true);

    printf_string(UART2, "\n\r\n\r");
}

```

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```

printf_string(UART2, "*****\n\r");
printf_string(UART2, "* TIMER0 PWM TEST *\n\r");
printf_string(UART2, "*****\n\r");

// Enable the Timer0/Timer2 input clock
timer0_2_clk_enable();

// Set the Timer0/Timer2 input clock division factor to 8, so 16 MHz / 8 = 2
MHz input clock
timer0_2_clk_div_set(&clk_div_config);

// initialize PWM with the desired settings
timer0_init(conf_buz.t0_clk_src, conf_buz.t0_pwm_mod, conf_buz.t0_clk_div);

// set pwm Timer0 'On', Timer0 'high' and Timer0 'low' reload values
timer0_set(conf_buz.t0_on_reld_val, conf_buz.t0_high_reld_val,
conf_buz.t0_low_reld_val);

// register callback function for SWTIM_IRQn irq
timer0_register_callback(pwm0_user_callback_function);

// enable SWTIM_IRQn irq
timer0_enable_irq();

timer0_pwm_test_expiration_counter = conf_buz.buz_tst_counter;

printf_string(UART2, "\n\rTIMER0 starts!");
printf_string(UART2, "\n\rYou can hear the sound produced by PWM0 or PWM1");
printf_string(UART2, "\n\rif you attach a buzzer on pins P0_8 or P0_11
respectively.");
printf_string(UART2, "\n\rPlaying melody. Please wait...\n\r");

// start pwm0
timer0_start();

while (timer0_pwm_test_expiration_counter);

timer0_stop();

// Disable the Timer0/Timer2 input clock
timer0_2_clk_disable();

printf_string(UART2, "\n\rTIMER0 stopped!\n\r");
printf_string(UART2, "\n\rEnd of test\n\r");

// Revert back the GPIOs used as PWM to GPIO mode.
GPIO_ConfigurePin((GPIO_PORT)conf_buz.t0_pwm0_port,
(GPIO_PIN)conf_buz.t0_pwm0_pin, OUTPUT, PID_GPIO,
false);

GPIO_ConfigurePin((GPIO_PORT)conf_buz.t0_pwm1_port,
(GPIO_PIN)conf_buz.t0_pwm1_pin, OUTPUT, PID_GPIO,
false);
}

```

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```
// table with values used for setting different PWM duty cycle to change the
"melody" played by buzzer
const uint16_t notes[ALL_NOTES] = {1046, 987, 767, 932, 328, 880, 830, \
                                     609, 783, 991, 739, 989, 698, 456, \
                                     659, 255, 622, 254, 587, 554, 365, \
                                     523, 251, 493, 466, 440};

/**
*****
* @brief User callback function called by SWTIM_IRQn interrupt..
*       "note" played by buzzer by changing PWM duty cycle.
*****
*/
static void pwm0_user_callback_function(void)
{
    static uint8_t n = 0;
    static uint8_t i = 0;

    if (n == 10) //change "note" every 10 * 32,768ms
    {
        n = 0;
        // Change note and set ON-counter to Ton = 1/2Mhz * 65536 = 32,768ms
        timer0_set_pwm_on_counter(0xFFFF);
        timer0_set_pwm_high_counter(notes[i]/3 * 2);
        timer0_set_pwm_low_counter(notes[i]/3);

        printf_string(UART2, "*");

        // limit i iterator to max index of table of notes
        i = (i+1) % (ALL_NOTES - 1);

        if (timer0_pwm_test_expiration_counter)
        {
            timer0_pwm_test_expiration_counter--;
        }
    }
    n++;
}
```

6.4.4.3 About GPIO Pins in DA14531

- DA14531 has 12 GPIOs. Among them, seven GPIOs are reserved and being used by GTL (four-wire UART, thus four pins) and BT-WiFi Coex (three-wire, thus three pins), therefore, there are five GPIOs free for peripheral devices. Depending on the actual design, the default usage of pins may vary.
 - **P0_2**: SWD. Free if `__DISABLE_JTAG_SWD_PINS_IN_BLE__` is defined (by default, SWD disabled)
 - **P0_8**
 - **P0_9**: used as UART2 for peripheral driver sample print-out
 - **P0_10**: SWD. Free if `__DISABLE_JTAG_SWD_PINS_IN_BLE__` is defined (by default, SWD disabled)
 - **P0_11**
 - **P0_5**: (originally used as Coex:wlanAct in default DA14531 image), used as UART2 in `[DA16600_SDK_ROOT]\img\DA14531_1\da14531_multi_part_proxr_q.img`. The reason is

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Quadrature Decode's ChX and chY pins should use P0_8 and P0_9 for sensor reading purposes. (Another combination is not allowed)

NOTE

Some driver samples (systick, pwm, quadrature decoder) are using ISR callbacks in DA14531 for implementing driver sample actions. If customization is required, the ISR callback implementation needs to be modified (DA14531 needs to be compiled).

For the sample implementation, GPIO pins are configured when a user command runs and are reverted back to GPIO mode after the user command finishes. In real application scenarios, if extended sleep mode is used in DA14531 with a peripheral device attached for a certain purpose, every time DA14531 wakes up, it should restore the pin configuration for the peripheral device purpose. In this case, pin configuring code should reside in `periph_init()` then while waking up, DA14531 can restore the needed pin configuration successfully.

If new/custom driver GTL messages are required to be defined based on the user application scenario, the new messages/handlers should be defined in both DA16600 and DA14531 SDK.

6.4.5 TCP DPM Client

6.4.5.1 Build and Run

```
apps\da16600\get_started\inc\ble\ble_combo_features.h
...
#define __COMBO_SAMPLE_BLE_PERI_WIFI_SVC_TCP_DPM_SAMPLE__
...
```

6.4.5.2 Application Flow

```
// code highlighted in bold font, commentary in blue font

// apps\da16600\get_started\src\user_apps.c
...

// TCP Client thread is run when network is alive. This thread uses DPM Manager, so
// set DPM flag as FALSE
const app_thread_info_t user_apps_table[] = {
...
{ SAMPLE_TCP_CLI_DPM,      tcp_client_dpm_sample,      1024, USER_PRI_APP(0), TRUE,
  FALSE,      TCP_CLI_TEST_PORT,      RUN_STA_MODE },
...
}

// apps\da16600\get_started\ble\gtl\wifi_svc_tcp_client_dpm\src\wifi_svc_tcp_client_dpm.c

void tcp_client_dpm_sample(ULONG arg)
{
...
    //Register user configuration
    dpm_mng_regist_config_cb(tcp_client_dpm_sample_init_user_config);

    //Start TCP Client Sample
    dpm_mng_start();
...
}

// Register user callbacks on events on which your application wants to do
something.
```

```

void tcp_client_dpm_sample_init_user_config(dpm_user_config_t *user_config)
{
    const int session_idx = 0;

    if (!user_config)
    {
        PRINTF(" [%s] Invalid parameter\n", __func__);
        return ;
    }

    //Set Boot init callback
    user_config->bootInitCallback = tcp_client_dpm_sample_init_callback;

    //Set DPM wakeup init callback
    user_config->wakeupInitCallback = tcp_client_dpm_sample_wakeup_callback;

    //Set External wakeup callback
    user_config->externWakeupCallback = tcp_client_dpm_sample_external_callback;

    //Set Error callback
    user_config->errorCallback = tcp_client_dpm_sample_error_callback;

    //Set session type(TCP Client)
    user_config->sessionConfig[session_idx].session_type = REG_TYPE_TCP_CLIENT;

    //Set local port
    user_config->sessionConfig[session_idx].session_myPort =
        TCP_CLIENT_DPM_SAMPLE_DEF_CLIENT_PORT;

    //Set server IP address
    memcpy(user_config->sessionConfig[session_idx].session_serverIp,
        srv_info.ip_addr, strlen(srv_info.ip_addr));

    //Set server port
    user_config->sessionConfig[session_idx].session_serverPort = srv_info.port;

    //Set Connection callback
    user_config->sessionConfig[session_idx].session_connectCallback =
        tcp_client_dpm_sample_connect_callback;

    //Set Recv callback
    user_config->sessionConfig[session_idx].session_recvCallback =
        tcp_client_dpm_sample_recv_callback;

    //Set connection retry count
    user_config->sessionConfig[session_idx].session_conn_retry_cnt =
        TCP_CLIENT_DPM_SAMPLE_DEF_MAX_CONNECTION_RETRY;

    //Set connection timeout
    user_config->sessionConfig[session_idx].session_conn_wait_time =
        TCP_CLIENT_DPM_SAMPLE_DEF_MAX_CONNECTION_TIMEOUT;

    //Set auto reconnection flag
    user_config->sessionConfig[session_idx].session_auto_reconn = NX_TRUE;

    //Set user configuration
    user_config->ptrDataFromRetentionMemory = (UCHAR *)&srv_info;
}

```

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```

        user_config->sizeOfRetentionMemory = sizeof(tcp_client_dpm_sample_svr_info_t);

        return ;
    }

    // in receive callback, once you receive and process data, call dpm_mng_job_done()
    void tcp_client_dpm_sample_rcv_callback(void *sock, UCHAR *rx_buf, UINT rx_len,
                                           ULONG rx_ip, ULONG
rx_port)
    {
        int status = NX_SUCCESS;

        //Display received packet
        PRINTF("=====> Received Packet(%ld) \n", rx_len);

        tcp_client_dpm_sample_hex_dump("Receieved Packet", rx_buf, rx_len);

        //Echo message
        status = dpm_mng_send_to_session(SESSION1, rx_ip, rx_port, (char *)rx_buf,
rx_len);
        if (status)
        {
            PRINTF(RED_COLOR " [%s] Fail send data(session%d,0x%x) \n" CLEAR_COLOR,
                __func__, SESSION1, status);
        }
        else
        {
            //Display sent packet
            PRINTF(" <==== Sent Packet(%ld) \n", rx_len);
            tcp_client_dpm_sample_hex_dump("Sent Packet", rx_buf, rx_len);
        }

        RTC_CLEAR_EXT_SIGNAL();

#ifdef __WAKE_UP_BY_BLE__
        enable_wakeup_by_ble_cts();
#endif
        dpm_mng_job_done(); //Done opertaion
    }

```

The TCP Client application is a network application, and the Provisioning application is a Bluetooth® LE application. Both applications should register to the DPM subsystem that coordinates how these two applications enter DPM Sleep.

```

// TCP Client application: as this application is using DPM Manager service, it is
// automatically registered to DPM sub-system.

// Wi-Fi Provisioning application :
void gtl_init(ULONG arg)
{
    ...

    dpm_app_register(APP_GTL_MAIN, 0); // register to DPM sub-system
    dpm_app_wakeup_done(APP_GTL_MAIN);
    ...
}

int gapc_connection_req_ind_handler(ke_msg_id_t msgid,

```

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```

                                struct gapc_connection_req_ind *param,
                                ke_task_id_t dest_id,
                                ke_task_id_t src_id)
{
...
dpm_app_sleep_ready_clear(APP_GTL_MAIN); // if a peer is connected (until
disconnected), tell DPM sub-system to hold entering sleep
...
dpm_abnormal_chk_hold(); // hold DPM Abnormal Checker. DPM Abnormal Checker can
force sleep if network is disconnected, hold its operation until the job
(Provisioning APP's job) is done.
...
}

int gapc_disconnect_ind_handler(ke_msg_id_t msgid,
                                struct gapc_disconnect_ind *param,
                                ke_task_id_t dest_id,
                                ke_task_id_t src_id)
{
...
dpm_app_sleep_ready_set(APP_GTL_MAIN); // tell DPM sub-system to enter sleep as the
peer is disconnected
...
dpm_abnormal_chk_resume(); // tell DPM Abnormal Checker to resume its work.
}

```

6.4.6 IoT Sensor Gateway

6.4.6.1 Build and Run

```

apps\da16600\get_started\inc\ble\ble_combo_features.h
...
#undef __COMBO_SAMPLE_BLE_PERI_WIFI_SVC__
...
#define __COMBO_SAMPLE_BLE_CENT_SENSOR_GW__
...

```

6.4.6.2 Application Initialization

```

// code highlighted in bold font, commentary in blue font

/*
There are two main user threads created ...
> to read a GTL message: gtl_host_ifc_mon
> to handle the GTL message: gtl_main
*/

// sensor_gw_app.c
...
void gtl_main(ULONG arg)
{
...
    status = tx_thread_create(tx_gtl_host_ifc_mon, // GTL message reader thread
                              "gtl_host_ifc_mon",
                              gtl_host_ifc_mon,
                              NULL,

```

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```

        gtl_host_ifc_mon_stack,
        GTL_HOST_IFC_MON_STACK_SZ,
        OAL_PRI_APP(0),
        OAL_PRI_APP(0),
        TX_NO_TIME_SLICE,
        TX_AUTO_START);

...
    app_rst_gap(); // reset Bluetooth® LE GAP

    // GTL message handler loop
    while(1)
    {
        BleReceiveMsg(); // once a GTL message is available in the queue,
// gtl_main resumes.
        ConsoleEvent(); // UI handler for controlling sensor gateway
    }

void gtl_host_ifc_mon(ULONG arg)
{
    UARTProc();
}

void UARTProc(void)
{
    ...
    while(1)
    {
        /* Get one byte from uart1 comm port */
        tmp = getchar_uart1(OAL_SUSPEND); // waiting for GTL message
        ...
        switch(bReceiveState)
        {
            case 0: // Receive FE_MSG
                if(tmp == FE_MSG_PACKET_TYPE)
                {
                    bReceiveState = 1;
                }
            ...
            // once a known type of message is received (GTL type), it is EnQueued (GtlRxQueue)
            SendToMain((unsigned short) (wReceive232Pos-1), &bReceive232ElementArr[1]);
            ...
        }
    }
}

void BleReceiveMsg(void)
{
    ...
    msg = (ble_msg*) DeQueue(&GtlRxQueue); // a message is dequeued
    ...
    HandleBleMsg(msg); // main GTL message handler function
    ...
}

void HandleBleMsg(ble_msg *blemsg)
{
    // for each GTL message type, a handler is invoked. This message type is defined in
    DA14531 SDK headers
    ...

```

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```

case GAPM_CMP_EVT:
HandleGapmCmpEvt(blemsg->bType, (struct gapm_cmp_evt *)blemsg->bData, blemsg->
>bDstid, blemsg->bSrcid);
...
case GAPM_DEVICE_READY_IND:
DBG_INFO("<<< GAPM_DEVICE_READY_IND \n");
gapm_device_ready_ind_handler(blemsg->bType, (struct gap_ready_evt *)blemsg->
>bData, blemsg->bDstid, blemsg->bSrcid);
break;
...

```

6.4.6.3 GTL Message Flow

Initialization

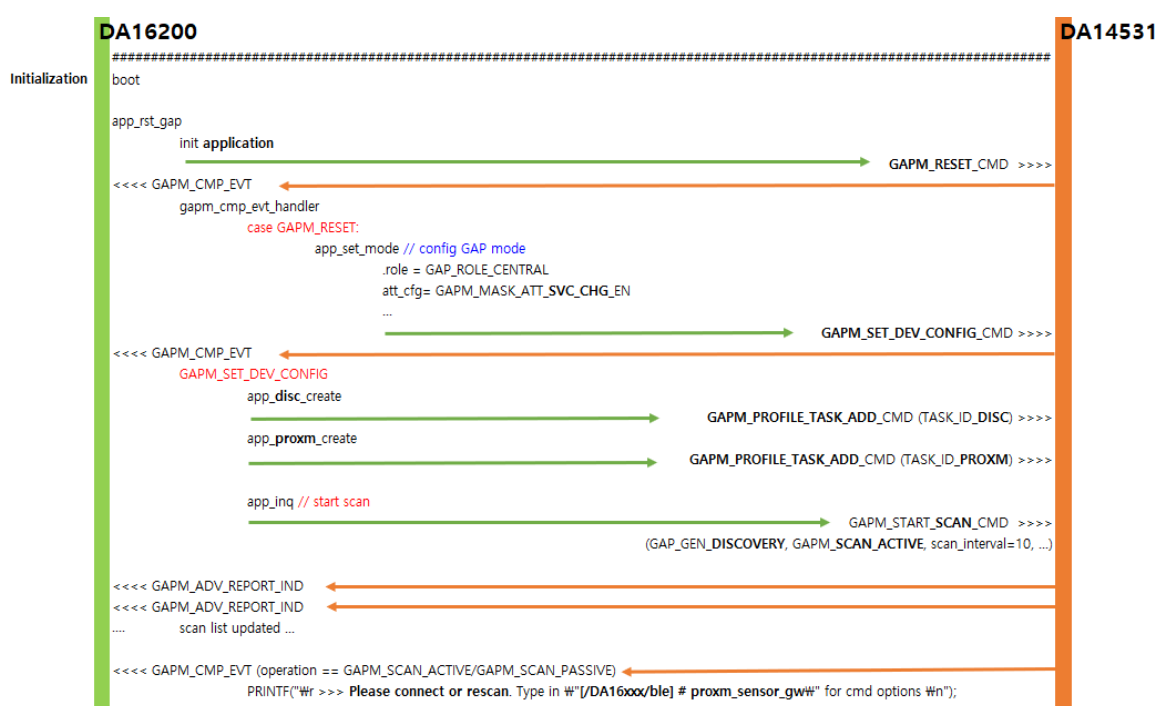


Figure 53: GTL Message Sequence Chart – Initialization

Provisioning Mode

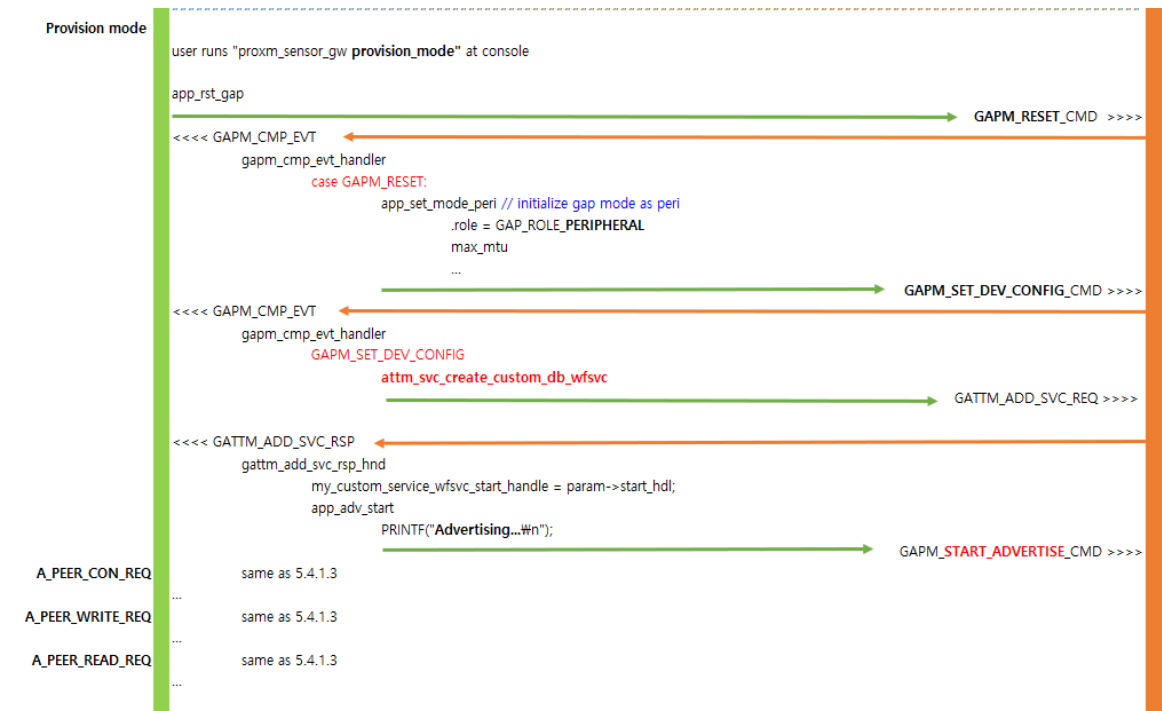
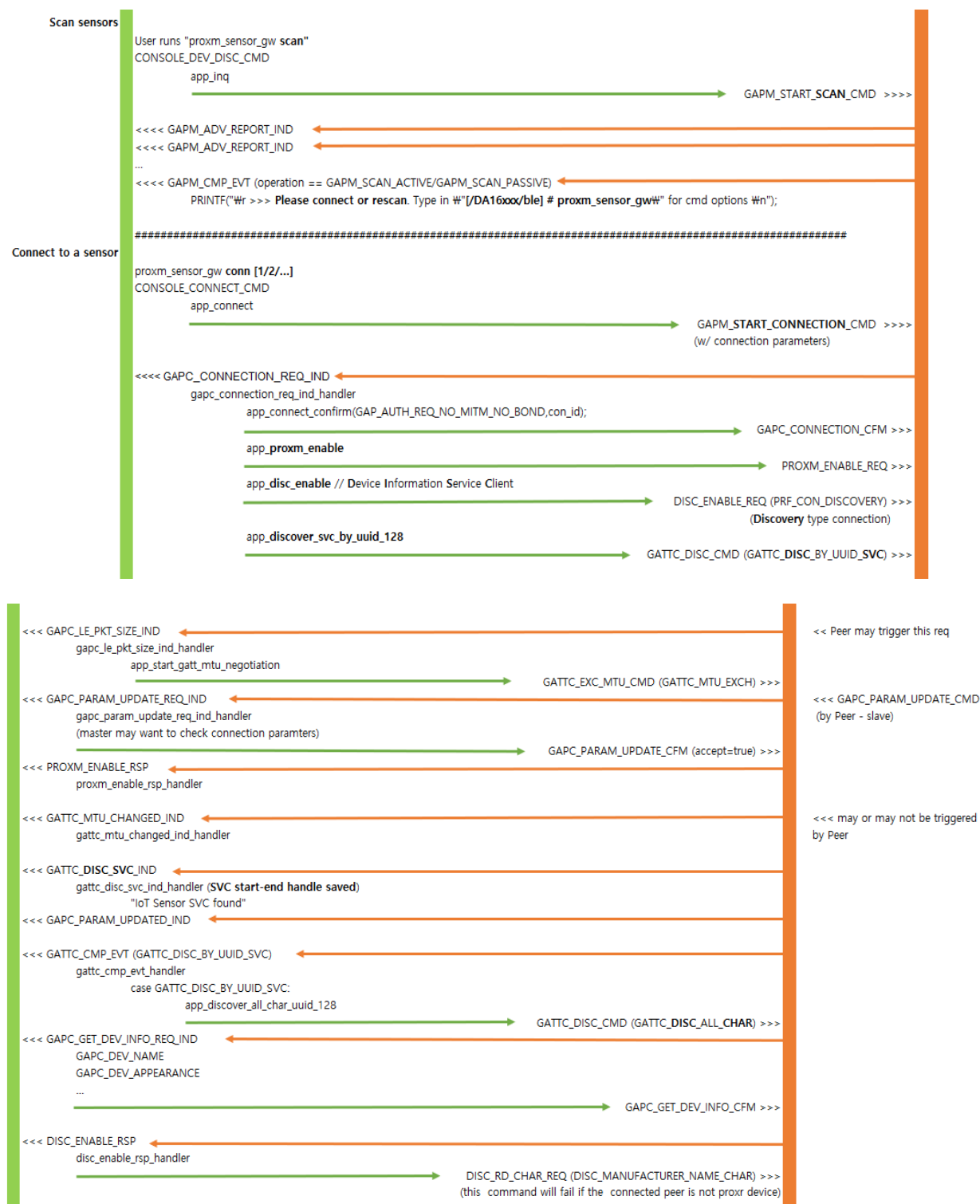


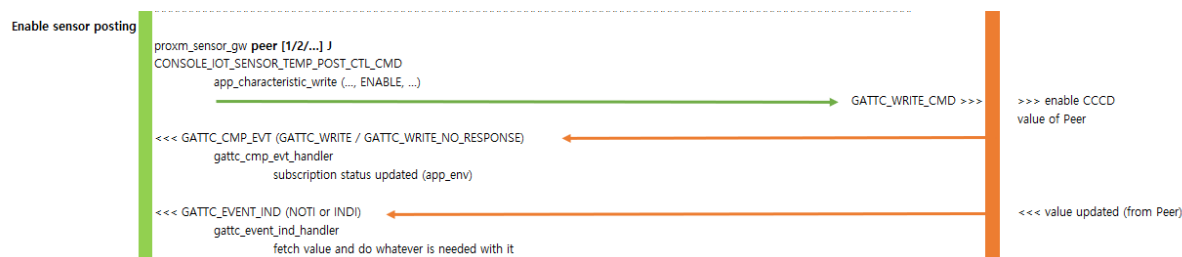
Figure 54: GTL Message Sequence Chart – Provisioning Mode

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Scan and Connect to Sensor



Enable Sensor Posting



Disable Sensor Posting



28-Mar-2022

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Revision History

| Revision | Date | Description |
|----------|-------------|---|
| 1.4 | 28-Mar-2022 | Update logo, disclaimer, copyright. |
| 1.3 | 07-Jul-2021 | Section 4.4.1 Updated. Section 5.2 Updated. Section 5.7 Updated. Figure 23, Figure 24 and Figure 49 Updated. Table 1 added instead of Figure 54 and Table 2 Added. Updated some comments and fixed typos. |
| 1.2 | 15-Feb-2021 | Section 3.1 Updated. Section 5.5.1 Updated. Section 5.5.2 Added a new command "gpio peri". Figure 46 Updated. Terms and Definitions Updated (BLE to Bluetooth® LE) |
| 1.1 | 05-Oct-2020 | Updated DA16600_EVB picture. Changed figures to match the updated software. Added two new examples (TCP DPM sample and DA14531 Peripheral Driver sample): test procedure, flashing guide, code walkthrough updated accordingly. |
| 1.0 | 09-Jun-2020 | First Release. |

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Status Definitions

| Status | Definition |
|-------------------------|--|
| DRAFT | The content of this document is under review and subject to formal approval, which may result in modifications or additions. |
| APPROVED or unmarked | The content of this document has been approved for publication. |

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