

RL78/G11

APPLICATION NOTE

R01AN3838EJ0100 Rev. 1.00 May 12, 2017

Timer Array Unit (Interval Timer) CC-RL

Introduction

This application note describes the interval timer function of the timer array unit (TAU). This unit inverts the LED indication each time a timer interrupt occurs. Also, it changes the timer interrupt cycle time based on the number of times the switch is pressed.

Target Device

RL78/G11

When applying the sample program covered in this application note to another microcomputer, modify the program according to the specifications for the target microcomputer and conduct an extensive evaluation of the modified program.



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1. Specifications

This application note shows example settings for using timer interrupts (INTTM00) from the interval timer and interrupts (INTP0) generated on pin input edge detection. The TAU inverts the LED indication each time a timer interrupt (INTTM00) occurs. Also, this unit changes the timer interrupt (INTTM00) cycle time based on the number of times the switch (SW) is pressed.

Table 1.1 lists the peripheral functions to be used and their uses. Figure 1.1 shows the timer and its interrupt operation.

Peripheral Function	Use
Timer array unit (channel 0)	Time interval control for inversion of the P10 pin output (LED indication)
P30	Output port for LED indications
P137/INTP0	Switch input for changing the timer interrupt (INTTM00) cycle time

 Table 1.1
 Peripheral Functions to be Used and Their Uses



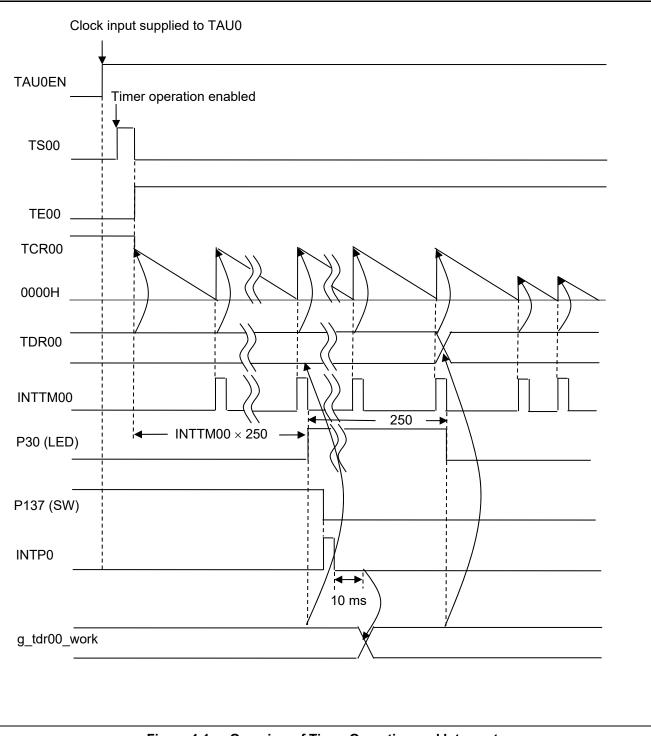


Figure 1.1 Overview of Timer Operation and Interrupts

2. Operation Check Conditions

The sample code contained in this application note has been checked under the conditions listed in the table below.

ltem	Description
Microcontroller used	RL78/G11 (R5F1056A)
Operating frequency	High-speed on-chip oscillator (HOCO) clock: 24 MHz
	CPU/peripheral hardware clock: 24 MHz
Operating voltage	5.0V (can run on a voltage range of 2.7 V to 5.5 V.)
	LVD operation (V_{LVD}): Reset mode 2.75 V (2.75 V to 2.81 V)
Integrated development environment (CS+)	CS+ for CC V4.01.00 from Renesas Electronics Corp.
C compiler (CS+)	CC-RL V1.03.00 from Renesas Electronics Corp.
Integrated development environment (e ² studio)	e ² studio V5.2.0.020 from Renesas Electronics Corp.
C compiler (e ² studio)	CC-RL V1.03.00 from Renesas Electronics Corp.

3. Related Application Note

The application note that is related to this application note is listed below for reference.

• RL78/G13 Initialization (R01AN2575E) Application Note



4. Description of the Hardware

4.1 Hardware Configuration Example

Figure 4.1 shows an example of hardware configuration that is used for this application note.

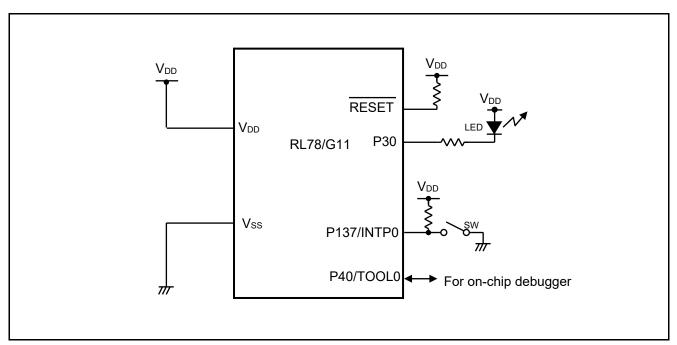


Figure 4.1 Hardware Configuration

- Cautions: 1. The purpose of this circuit is only to provide the connection outline and the circuit is simplified accordingly. When designing and implementing an actual circuit, provide proper pin treatment and make sure that the hardware's electrical specifications are met (connect the input-only ports separately to V_{DD} or V_{SS} via a resistor).
 - 2. V_{DD} must be held at not lower than the reset release voltage (V_{LVD}) that is specified as LVD.

4.2 List of Pins to be Used

Table 4.1 lists the pins to be used and their functions.

 Table 4.1
 Pins to be Used and Their Functions

Pin Name	I/O	Description
P30	Output	Output port for LED indications
P137/INTP0	Input	Switch (SW) input pin (external interrupt request input pin)

5. Description of the Software

5.1 Operation Outline

This application note describes how to set up the interval timer function of TAU0.

This setup is followed by operation for counting the number of timer interrupts (INTTM00) generated by the interval timer. Each time the count reaches 250, the LED indication is inverted. The timer interrupt (INTTM00) cycle time is changed according to the number of times the switch is pressed. The LED on/off cycle time is changed as follows.

 $500 \text{ ms} \rightarrow 250 \text{ ms} \rightarrow 125 \text{ ms} \rightarrow 62.5 \text{ ms} \rightarrow 500 \text{ ms} \rightarrow \dots$

(1) Initialize the TAU.

- Use the interval timer mode as the timer operation mode.
- Initialize timer data register 00 (TDR00) to 2 ms.
- Set the timer output enable register to disable operation.
- Use timer interrupts (INTTM00) from timer channel 0.

(2) Initialize the external edge detection interrupt.

- Select a falling edge as the valid edge for INTP0.
- Use INTP0 interrupts.

(3) Execute a HALT instruction to wait for timer interrupts (INTTM00).

- (4) After the HALT mode is cancelled by a timer interrupt (INTTM00), the number of INTTM00 interrupts generated is counted.
- (5) When the timer interrupt count reaches 250, the LED indication is inverted. The value (g_tdr00_work) in RAM for the timer data register is set in the timer data register (TDR00).
- (6) INTP0 interrupt processing changes the switch input count (INTP0 interrupt count) and g_tdr00_work value.



5.2 List of Option Byte Settings

Table 5.1 summarizes the settings of the option bytes.

Address	Value	Description
000C0H/010C0H	01101110B	Disables the watchdog timer.
		(Stops counting after the release from the reset state.)
000C1H/010C1H	01111111B	LVD reset mode, 2.75 V (2.75 V to 2.81 V)
000C2H/010C2H	11100000B	HS mode, HOCO: 24 MHz
000C3H/010C3H	10000100B	Enables the on-chip debugger.

Table 5.1 Option Byte Settings

5.3 List of Constants

Table 5.2 lists the constants that are used in this sample program.

Constant	Setting	Description
_01_INTP0_EDGE_FALLING_SEL	01h	Selects a falling edge as the valid edge of INTP0.
g_tdr00_data[]	(64000-1)	TDR00 settings by number of times the switch is
	(32000-1)	pressed
	(16000-1)	
	(8000-1)}	
g_10ms_count[]	(5+1)	10 ms timer count values by number of times the
	(10+1)	switch is pressed
	(20+1)	
	(40+1)	

Table 5.2 Constants for the Sample Program

5.4 List of Variables

Table 5.3 lists the global variable that is used by this sample program.

Table 5.3Global Variables for the Sample Program

Туре	Variable Name	Contents	Function Used
saddr uint8_t	g_sw_counter	Switch press count	r_intc0_interrupt() main() r_invert_led()
saddr uint16_t	g_tdr00_work	Value which is set in TDR00 each time the timer interrupt count reaches 250.	r_intc0_interrupt() main() r_invert_led()
saddr uint8_t	g_inttm00counter	The number of timer interrupt generation	main() r_invert_led()



5.5 List of Functions

Table 5.4 lists the functions that are used by this sample program.

Function Name	Outline
R_TAU0_Channel0_Start	Starts operation of TAU0 channel 0.
R_TAU0_Channel0_Interrupt()	Processes timer interrupts on TAU0 channel 0.
r_invert_led()	Counts the number of INTTM00 interrupts generated. Inverts the LED indication each time the interrupt count reaches 250.
R_INTC0_Start	Enables INTP0 interrupts.
r_intc0_interrupt	Processes INTP0 interrupts.

5.6 Function Specifications

This section describes the specifications for the functions that are used in the sample code.

[Function Name] F	R_TAU0_Channel0_Start
Synopsis	TAU0 channel 0 operation start
Header	r_cg_macrodriver.h
	r_cg_tau.h
	r_cg_userdefine.h
Declaration	void R_TAU0_Channel0_Start(void)
Explanation	This function unmasks TAU0 channel 0 interrupts and starts count operation.
Arguments	None
Return value	None
Remarks	None

[Function Name] r_tau0_channel0_interrupt()		
Synopsis	TAU0 channel 0 timer interrupt processing	
Header	r_cg_macrodriver.h	
	r_cg_tau.h	
	r_cg_userdefine.h	
Declaration	static voidnear r_tau0_channel0_interrupt(void)	
Explanation	This function calls the function which will invert the LED indication.	
Arguments	None	
Return value	None	
Remarks	None	



[Function Name] r	_invert_led()
Synopsis	LED indication inversion processing
Header	r_cg_macrodriver.h
	r_cg_cgc.h
	r_cg_port.h
	r_cg_intp.h
	r_cg_tau.h
	r_cg_userdefine.h
Declaration	void r_invert_led(void)
Explanation	This function counts 250 timer interrupts (INTTM00) and then inverts the LED indication (for port latch inversion). It also changes the TDR00 setting to the value specified with g_tdr00_work.
Arguments	None
Return value	None
Remarks	None

[Function Name] R	[Function Name] R_INTC0_Start						
Synopsis	INTP0 interrupt enable						
Header	r_cg_intp.h						
Declaration	void R_INTC0_Start(void)						
Explanation	This function clears the interrupt request flag. It enables INTP0 interrupts and starts taking in the switch input.						
Arguments	None						
Return value	None						
Remarks	None						

[Function Name] r	[Function Name] r_intc0_interrupt()						
Synopsis	INTP0 interrupt processing						
Header	r_cg_macrodriver.h						
	r_cg_intp.h						
	r_cg_userdefine.h						
Declaration	static voidnear r_intc0_interrupt(void)						
Explanation	This function processes INTP0 interrupts as they occur.						
	It waits 10 ms and then scans P13.7 (SW input pin). When the switch is pressed, this						
	function changes the g_tdr00_work value.						
Arguments	None						
Return value	None						
Remarks	None						



5.7 Flowcharts

Figure 5.1 shows the overall flow of the sample program described in this application note.

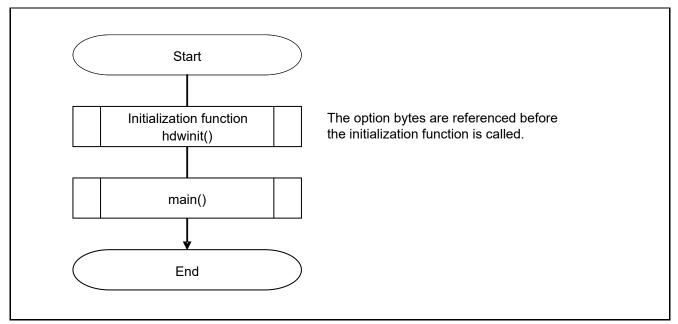


Figure 5.1 Overall Flow

Note: Startup routine is executed before and after the initialization function.

5.7.1 Initialization Function

Figure 5.2 shows the flowchart for the initialization function.

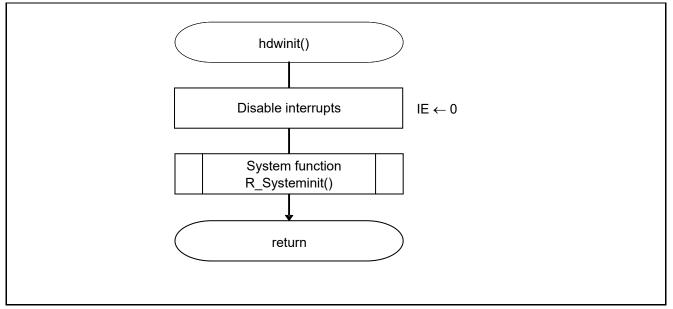


Figure 5.2 Initialization Function

5.7.2 System Function

Table 5.3 shows the flowchart for the system function.

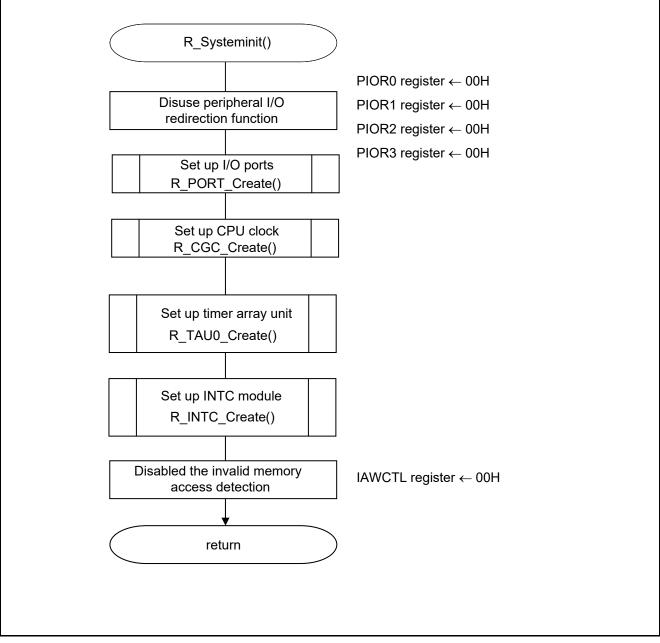
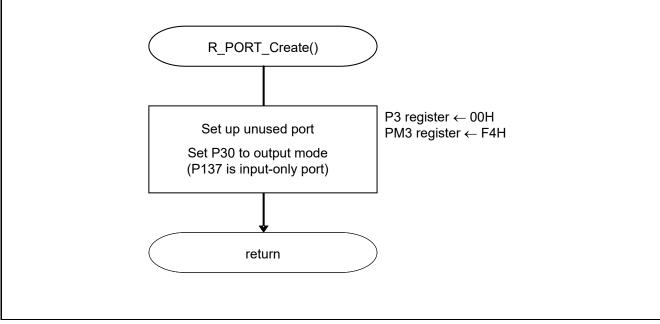


Figure 5.3 System Function

5.7.3 I/O Port Setup

Table 5.4 shows the flowchart for I/O port setup.





Note: Refer to RL78/G11 User's Manual: Hardware for the configuration of the unused ports.

Caution: Provide proper treatment for unused pins so that their electrical specifications are observed. Connect each of any unused input-only ports to V_{DD} or V_{SS} via a separate resistor.

Setting up the LED port

• Port mode register3 (PM3) Select I/O mode for the port.

Symbol: PM3

_	7	6	5	4	3	2	1	0
	1	1	1	1	PM33	PM32	PM31	PM30
I	1	1	1	1	0	1	0	0

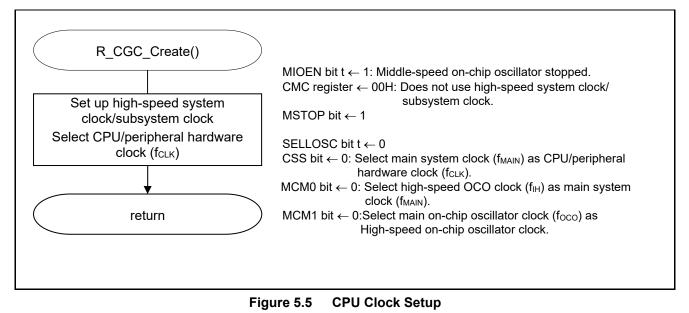
Bit 0

PM30	P30 pin I/O mode selection
0	Output mode (output buffer on)
1	Input mode (output buffer off)



5.7.4 CPU Clock Setup

Figure 5.5 shows the flowchart for setting up the CPU clock.



Caution: For details on the procedure for setting up the CPU clock (R_CGC_Create ()), refer to RL78/G11 User's Manual: Hardware.



5.7.5 Timer Array Unit Setup

Figure 5.6 shows the flowchart for setting up the timer array unit.

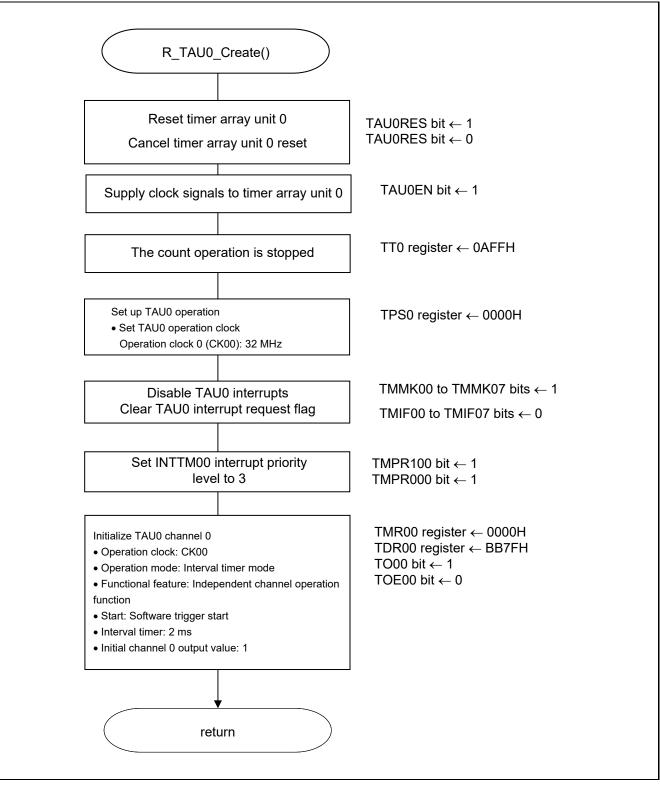


Figure 5.6 Timer Array Unit Setup



Starting clock signal supply to the timer array unit 0

• Peripheral enable register 0 (PER0) Start supplying clock signals to the timer array unit 0.

Symbol: PER0

7	6	5	4	3	2	1	0
0	IICA1EN	ADCEN	IICA0EN	0	SAU0EN	0	TAU0EN
0	х	х	х	0	х	0	1

Bit 0

TAU0EN	Control of timer array unit 0 input clock supply
0	Stops input clock supply.
1	Enables input clock supply.



Configuring the timer clock frequency

• Timer clock select register 0 (TPS0) Select an operation clock for timer array unit 0.

Symbol: TPS0

	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
	0	0	PRS 031	PRS 030	0	0	PRS 021	PRS 020	PRS 013	PRS 012	PRS 011	PRS 010	PRS 003	PRS 002	PRS 001	PRS 000
Ì	х	х	х	х	х	х	х	х	х	х	х	х	0	0	0	0

Bits 3 to 0

PRS	PRS	PRS	PRS		Operation clock (CK00) selection								
003	002	001	000		f _{CLK} =	f _{CLK} =	f _{CLK} =	f _{CLK} =	f _{CLK} =				
					2 MHz	5 MHz	10 MHz	20 MHz	24 MHz				
0	0	0	0	fс∟к	2 MHz	5 MHz	10 MHz	20 MHz	24 MHz				
0	0	0	1	fclк/2	1 MHz	2.5 MHz	5 MHz	10 MHz	12 MHz				
0	0	1	0	$f_{CLK}/2^2$	500 kHz	1.25 MHz	2.5 MHz	5 MHz	6 MHz				
0	0	1	1	fclk/2 ³	250 kHz	625 kHz	1.25 MHz	2.5 MHz	3 MHz				
0	1	0	0	fclk/2 ⁴	125 kHz	312.5 kHz	625 kHz	1.25 MHz	1.5 MHz				
0	1	0	1	fclk/2 ⁵	62.5 kHz	156.2 kHz	312.5 kHz	625 kHz	750 kHz				
0	1	1	0	f _{CLK} /2 ⁶	31.25 kHz	78.1 kHz	156.2 kHz	312.5 kHz	375 kHz				
0	1	1	1	fclk/2 ⁷	15.62 kHz	39.1 kHz	78.1 kHz	156.2 kHz	187.5 kHz				
1	0	0	0	fclk/2 ⁸	7.81 kHz	19.5 kHz	39.1 kHz	78.1 kHz	93.8 kHz				
1	0	0	1	fclk/29	3.91 kHz	9.76 kHz	19.5 kHz	39.1 kHz	46.9 kHz				
1	0	1	0	fclk/2 ¹⁰	1.95 kHz	4.88 kHz	9.76 kHz	19.5 kHz	23.4 kHz				
1	0	1	1	fclk/211	976 Hz	2.44 kHz	4.88 kHz	9.76 kHz	11.7 kHz				
1	1	0	0	$f_{CLK}/2^{12}$	488 Hz	1.22 kHz	2.44 kHz	4.88 kHz	5.86 kHz				
1	1	0	1	fclк/2 ¹³	244 Hz	610 Hz	1.22 kHz	2.44 kHz	2.93 kHz				
1	1	1	0	fclk/214	122 Hz	305 Hz	610 Hz	1.22 kHz	1.46 kHz				
1	1	1	1	f _{CLK} /2 ¹⁵	61 Hz	153 Hz	305 Hz	610 Hz	732 Hz				



Setting up channel 0 operation mode

 $\label{eq:constraint} \begin{array}{ll} \bullet & \mbox{Timer mode register 00 (TMR00)} \\ & \mbox{Select an operation clock } (f_{MCK}). \\ & \mbox{Select ta count clock.} \\ & \mbox{Select the software trigger start.} \\ & \mbox{Set up the operation mode.} \end{array}$

Symbol: TMR00

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
CKS	CKS	0	CCS	0	STS	STS	STS	CIS0	CIS0	0	0	MD0	MD0	MD0	MD0
001	000		00		002	001	000	01	00			03	02	01	00
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0

Bits 15 and 14

CKS001	CKS000	Channel 0 operation clock (f _{MCK}) selection
0	0	Operation clock CK00 set by timer clock select register 0 (TPS0)
0	1	Operation clock CK02 set by timer clock select register 0 (TPS0)
1	0	Operation clock CK01 set by timer clock select register 0 (TPS0)
1	1	Operation clock CK03 set by timer clock select register 0 (TPS0)

Bit 12

CCS00	Channel 0 count clock (fTCLK) selection
0	Operation clock (f_{MCK}) specified by the CKS000 and CKS001 bits
1	Valid edge of input signal input from the TI00 pin

Bit 11

MASTER00	Selection between using channel 0 independently or simultaneously with another channel (as a slave or master)
	Operates in independent channel operation function or as slave channel in simultaneous channel operation function.
1	Operates as master channel in simultaneous channel operation function.



Symbol: TMR00

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
CKS	CKS	0	CCS	0	STS	STS	STS	CIS0	CIS0	0	0	MD0	MD0	MD0	MD0
001	000		00		002	001	000	01	00			03	02	01	00
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0

Bits 10 to 8

STS002	STS001	STS000	Setting of start trigger or capture trigger of channel 0
0	0	0	Only software trigger start is valid (other trigger sources are unselected).
0	0	1	Valid edge of the TI00 pin input is used as both the start trigger and capture trigger.
0	1	0	Both the edges of the TI00 pin input are used as a start trigger and a capture trigger.
1	0	0	Interrupt signal of the master channel is used (when the channel is used as a slave channel with the simultaneous channel operation function).
Oth	er than ab	ove	Setting prohibited

Bits 7 to 6

CIS001	CIS000	Selection of TI00 pin input valid edge
0	0	Falling edge
0	1	Rising edge
1	0	Both edges (when low-level width is measured)
I	0	Start trigger: Falling edge, Capture trigger: Rising edge
1	1	Both edges (when high-level width is measured)
I	I	Start trigger: Rising edge, Capture trigger: Falling edge



Symbol: TMR00

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
CKS	CKS	0	CCS	0	STS	STS	STS	CIS0	CIS0	0	0	MD0	MD0	MD0	MD0
001	000		00		002	001	000	01	00			03	02	01	00
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0

Bits 3 to 0

MD0 03	MD0 02	MD0 01	MD0 00	Operation mode of channel 0	Related function	TCR counting operation
0	0	0	1/0	Interval timer mode	Interval timer / Square wave output / Divider function / PWM output (master)	Counting down
0	1	0	1/0	Capture mode	Input pulse interval measurement	Counting up
0	1	1	0	Event counter mode	External event counter	Counting down
1	0	0	1/0	One-count mode	Delay counter / One-shot pulse output / PWM output (slave)	Counting down
1	1	0	0	1	Measurement of high-/low-level width of input signal	Counting up
Oth	er tha	an abo	ove	Setting prohibited		

The MD000 bit operation varies depending on the operation mode (see the table below)

Operation mode (selected with MD003 to MD001) (See the table above)	MD000	TCR counting operation
 Interval timer mode (0, 0, 0) Capture mode (0, 1, 0) 	0	Timer interrupt is not generated when counting is started (timer output does not change, either).
	1	Timer interrupt is generated when counting is started (timer output also changes).
• Event counter mode (0, 1, 1)	0	Timer interrupt is not generated when counting is started (timer output does not change, either).
• One-count mode (1, 0, 0)	0	Start trigger is invalid during counting operation. At that time, interrupt is not generated, either.
	1	Start trigger is valid during counting operation. At that time, interrupt is also generated.
• Capture/one-count mode (1, 1, 0)	0	Timer interrupt is not generated when counting is started (timer output does not change, either). Start trigger is invalid during counting operation. At that time, interrupt is not generated, either.
Other than above		Setting prohibited



Configuring the interval timer cycle time

• Timer data register 00 (TDR00) Configure the interval timer compare value.

Symbol: TDR00

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0

Timer interrupt (INTTM00) occurrence = $(TDR00 \text{ setting } + 1) \times Count clock cycle time$

Enabling the timer output

• Timer output enable register 0 (TOE0) Enable/disable the timer output for each channel.

Symbol: TOE0

	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
	0	0	0	0	0	0	0	0	0	0	0	0			TOE 01	TOE 00
1	0	0	0	0	0	0	0	0	0	0	0	0	х	х	х	0

Bit 0

TOE00	Timer output enable/disable of channel 0
0	Timer output is disabled. Timer operation is not applied to the TO00 bit and the output is fixed. Writing to the TO00 bit is enabled and the level set in the TO00 bit is output from the TO00 pin.
1	Timer output is enabled. Timer operation is applied to the TO00 bit and an output waveform is generated. Writing to the TO00 bit is ignored.



5.7.6 INTP0 Initialization

Figure 5.7 shows the flowchart for INTP0 initialization.

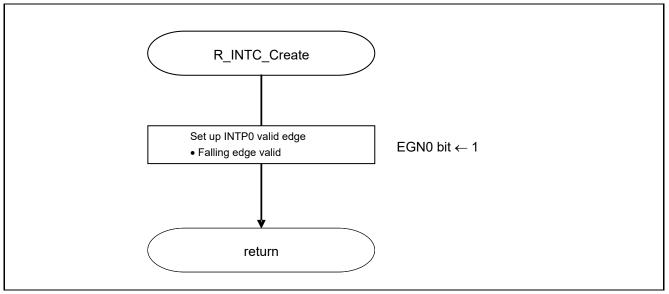


Figure 5.7 INTC Module Setup

Setup for INTP0 pin edge detection

- External interrupt rising edge enable register (EGP0)
- External interrupt falling edge enable register (EGN0) Select a valid edge for INTP0

Symbol: EGP0

7	6	5	4	3	2	1	0
EGP7	EGP6	EGP5	EGP4	EGP3	EGP2	EGP1	EGP0
х	х	х	х	х	х	х	0

Symbol: EGN0

7	6	5	4	3	2	1	0
EGN7	EGN6	EGN5	EGN4	EGN3	EGN2	EGN1	EGN0
х	х	х	х	х	х	х	1

EGP0	EGN0	INTP0 pin valid edge selection			
0	0	Edge detection disabled.			
0	1	Falling edge			
1	0	sing edge			
1	1	Both rising and falling edges			

5.7.7 Main Processing

Figure 5.8 shows the flowchart for main processing.

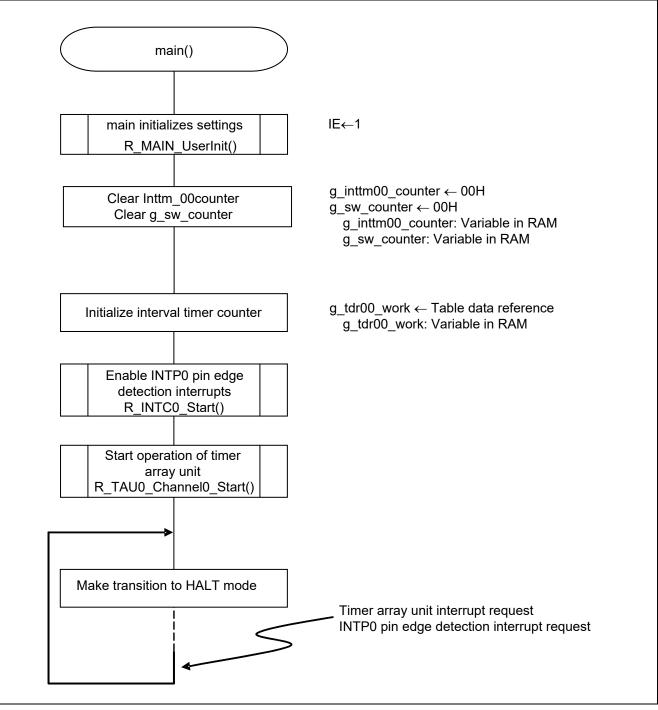


Figure 5.8 Main Processing

5.7.8 Main initializes settings

Figure 5.10 shows the flowchart for the main initializes settings.

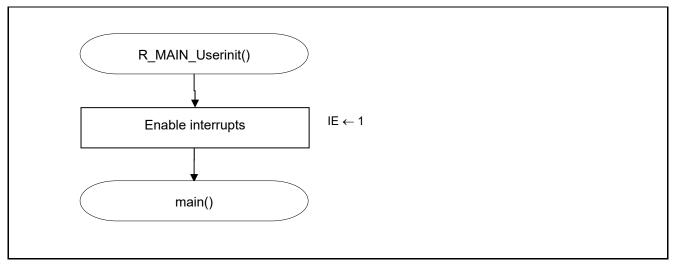
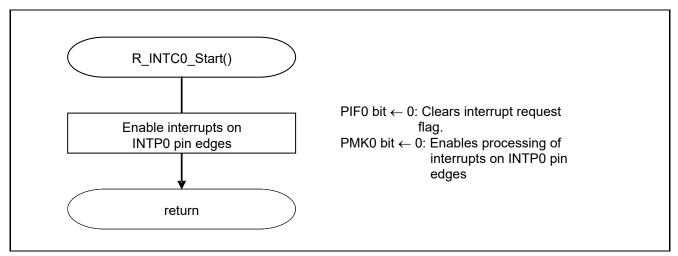


Figure 5.9 Main initializes settings



5.7.9 INTP0 Operation Start

Figure 5.10 shows the flowchart for starting INTP0 operation.





Setup for INTP0 Interrupts

- Interrupt request flag register (IF0L) Clear interrupt request flag.
- Interrupt mask flag register (MK0L) Clear interrupt mask.

Symbol: IF0L

7	6	5	4	3	2	1	0
PIF5	PIF4	PIF3	PIF2	PIF1	PIF0	LVIIF	WDTIIF
х	х	х	х	Х	0	х	х

Bit 2

PIF0	Interrupt request flag				
0	No interrupt request signal is generated				
1	Interrupt request is generated, interrupt request status				

Symbol: MK0L

7	6	5	4	3	2	1	0
PMK5	PMK4	PMK3	PMK2	PMK1	PMK0	LVIMK	WDTIMK
х	х	х	х	х	0	х	х

Bit 2

PMK0	Interrupt processing control
0	Enables interrupt processing.
1	Disables interrupt processing.

Caution: For detailed information about setting the registers, see RL78/G11 User's Manual: Hardware.

5.7.10 Timer Array Unit 0 Operation Start

Figure 5.9 shows the flowchart for starting timer array unit operation.

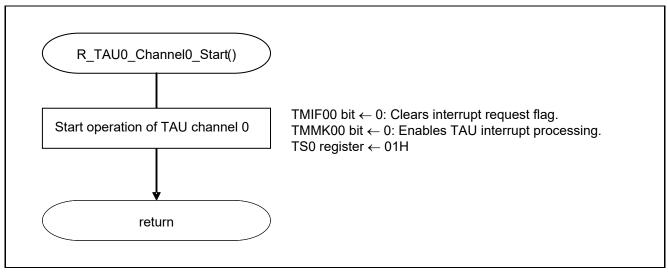


Figure 5.9 Timer Array Unit 0 Operation Start



Configuring the timer interrupt

- Interrupt request flag register (IF0H) Clear the interrupt request flag.
- Interrupt mask flag register (MK0H) Enable interrupt processing.

Symbol: IF0H

7	6	5	4	3	2	1	0
STIF1	TMIF00	SREIF0	0	0	SREIF1	STIF00	PIF6
CSIIF10					CSIIF01	CSIIF00	
IICIF10					IICIF01	IICIF00	
х	0	х	0	0	х	х	x

Bit 6

TMIF00	Interrupt request flag
0	No interrupt request signal is generated.
1	Interrupt request is generated, interrupt
I	request status

Symbol: MK0H

7	6	5	4	3	2	1	0
STMK1	TMMK00	SREMK0	1	1	SRMK0	STMK0	PMK6
CSIMK10					CSIMK01	CSIMK00	
IICMK10					IICMK01	IICMK00	
х	0	х	1	1	х	х	Х

Bit 6

TMMK00	Interrupt processing control			
0	Enables interrupt processing.			
1	Disables interrupt processing.			



5.7.11 INTTM00 Interrupt Processing

Figure 5.10 shows the flowchart for INTTM00 interrupt processing.

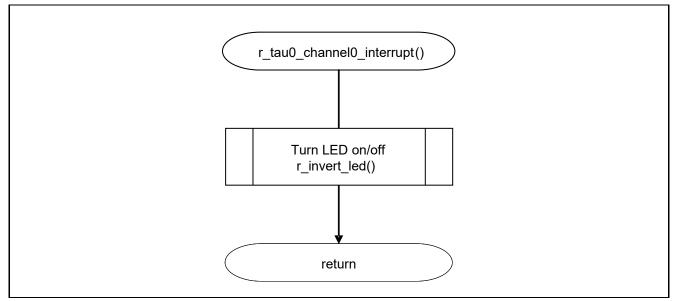


Figure 5.10 INTTM00 Interrupt Processing



5.7.12 LED Turn-On/Off Processing

Figure 5.113 shows the flowchart for LED turn-on/off processing.

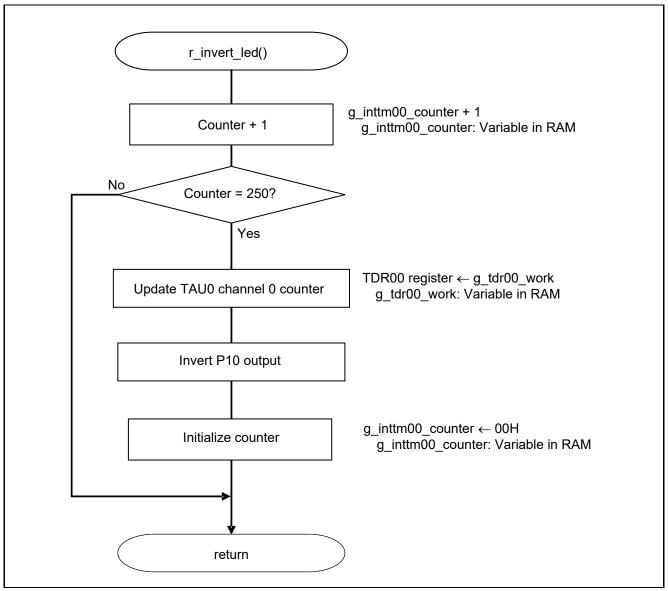


Figure 5.113 Checking Whether 500 ms Have Elapsed



5.7.13 INTP0 Interrupt Processing

Figures 5.14 and 5.15 show the flowchart for INTP0 interrupt processing.

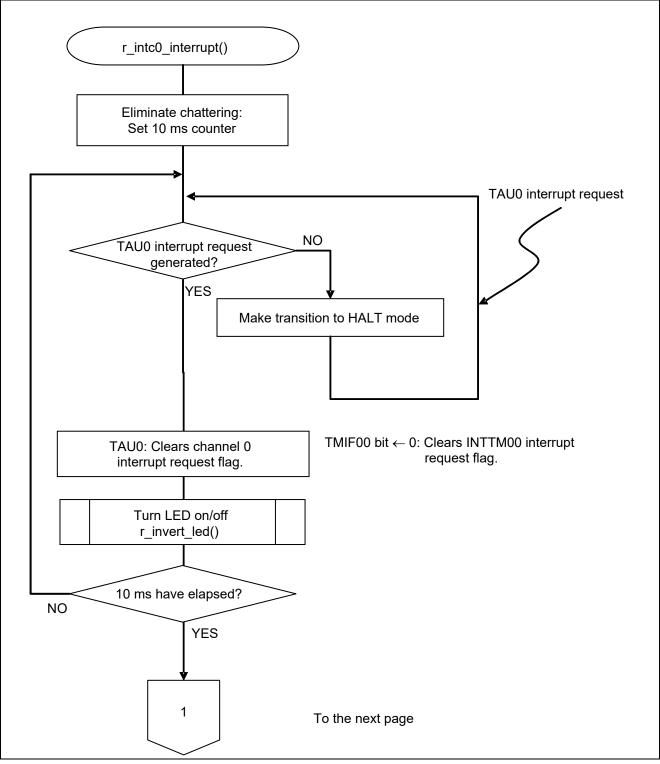


Figure 5.12 INTP0 Interrupt Processing (1/2)

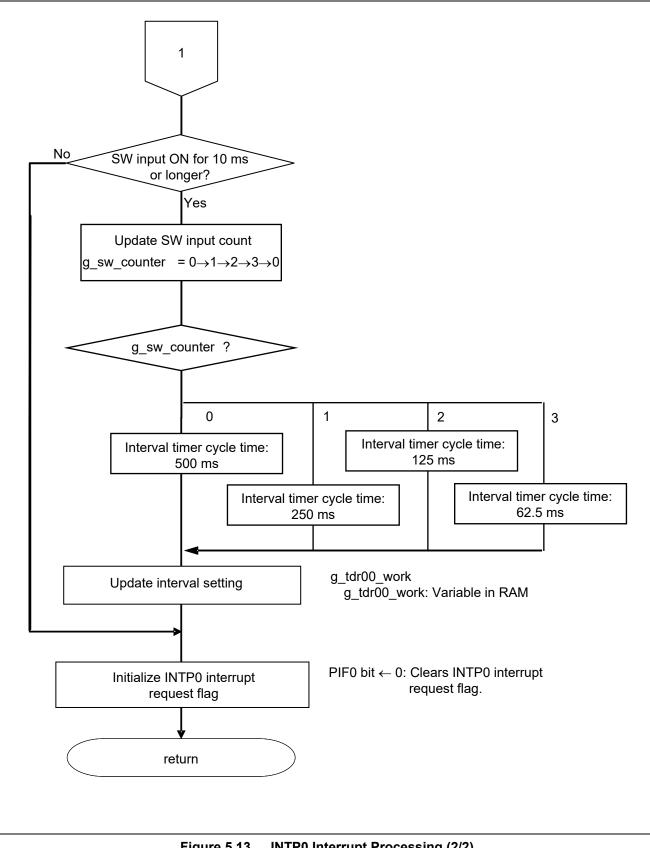


Figure 5.13 **INTP0 Interrupt Processing (2/2)**

6. Sample Code

The sample code is available on the Renesas Electronics Website.

7. Documents for Reference

User's Manual:

RL78/G11 User's Manual: Hardware (R01UH0637EJ) RL78 Family User's Manual: Software (R01US0015EJ) The latest version can be downloaded from the Renesas Electronics website.

Technical Updates/Technical News

The latest information can be downloaded from the Renesas Electronics website.

Website and Support

Renesas Electronics Website http://www.renesas.com/index.jsp

Inquiries http://www.renesas.com/contact/



REVISION HISTORY

RL78/G11 Timer Array Unit (Interval Timer) CC-RL

Rev.	Date	Description				
Rev.	Dale	Page	Summary			
1.00	May. 12, 2017	—	First edition issued			

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General Precautions in the Handling of Microprocessing Unit and Microcontroller Unit Products

The following usage notes are applicable to all Microprocessing unit and Microcontroller unit products from Renesas. For detailed usage notes on the products covered by this document, refer to the relevant sections of the document as well as any technical updates that have been issued for the products.

1. Handling of Unused Pins

Handle unused pins in accordance with the directions given under Handling of Unused Pins in the manual.

- ³⁄₄ The input pins of CMOS products are generally in the high-impedance state. In operation with an unused pin in the open-circuit state, extra electromagnetic noise is induced in the vicinity of LSI, an associated shoot-through current flows internally, and malfunctions occur due to the false recognition of the pin state as an input signal become possible. Unused pins should be handled as described under Handling of Unused Pins in the manual.
- 2. Processing at Power-on

The state of the product is undefined at the moment when power is supplied.

- ³⁄₄ The states of internal circuits in the LSI are indeterminate and the states of register settings and pins are undefined at the moment when power is supplied. In a finished product where the reset signal is applied to the external reset pin, the states of pins are not guaranteed from the moment when power is supplied until the reset process is completed. In a similar way, the states of pins in a product that is reset by an on-chip power-on reset function are not guaranteed from the moment when power is supplied until the power reaches the level at which resetting has been specified.
- 3. Prohibition of Access to Reserved Addresses

Access to reserved addresses is prohibited.

- ³⁄₄ The reserved addresses are provided for the possible future expansion of functions. Do not access these addresses; the correct operation of LSI is not guaranteed if they are accessed.
- 4. Clock Signals

After applying a reset, only release the reset line after the operating clock signal has become stable. When switching the clock signal during program execution, wait until the target clock signal has stabilized.

- When the clock signal is generated with an external resonator (or from an external oscillator) during a reset, ensure that the reset line is only released after full stabilization of the clock signal. Moreover, when switching to a clock signal produced with an external resonator (or by an external oscillator) while program execution is in progress, wait until the target clock signal is stable.
- 5. Differences between Products

Before changing from one product to another, i.e. to a product with a different part number, confirm that the change will not lead to problems.

³⁄₄ The characteristics of Microprocessing unit or Microcontroller unit products in the same group but having a different part number may differ in terms of the internal memory capacity, layout pattern, and other factors, which can affect the ranges of electrical characteristics, such as characteristic values, operating margins, immunity to noise, and amount of radiated noise. When changing to a product with a different part number, implement a system-evaluation test for the given product.

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