

# PTP Clock Manager for Linux Management API

This document lists the functions and type definitions of the C application programming interface to access and configure the PTP Clock Manager (pcm4l) software.

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## 1. Introduction

The file `idtCore/management/include/mngApi/mngApi.h` contains the relevant header definitions to be included by the calling software for the `pcm41` management API functions.

## 2. Type Definitions

The following type definitions are listed in alphabetical order.

### 2.1 T\_CallbackFunctionPointer

`idtCommon/include/messageLog/cmnCallbackLog.h`

```
typedef void (*T_CallbackFunctionPointer)( T_cmnMessageData const * );
```

### 2.2 T\_cmnErrorCode

`idtCommon/include/cmnErrorCode.h`

```
typedef enum
{
    E_cmnErrorCode_OK = 0, /* Command was successful */
    E_cmnErrorCode_ResponseTimeout = 1, /* Response message was not received before
                                         response timeout */
    E_cmnErrorCode_FunctionNotSupported = 2, /* Function not supported */
    E_cmnErrorCode_InvalidMaster = 3, /* Invalid master */
    E_cmnErrorCode_NoTextStringFound = 4, /* No corresponding text string mapped */
    E_cmnErrorCode_NotConfigured = 5, /* Value was not configured */
    E_cmnErrorCode_NotAccepted = 6, /* Action not accepted, function busy */
    E_cmnErrorCode_InvalidValue = 7, /* Value is invalid */
    E_cmnErrorCode_CallbackNotRegistered = 8, /* Callback function is not registered */
    E_cmnErrorCode_TimerFailed = 9, /* Timer failed */
    E_cmnErrorCode_CallbackReturnsFailure = 10, /* Callback function returns failure */
    E_cmnErrorCode_BestMasterNotFound = 11, /* <Best master not found */
    E_cmnErrorCode_FailedToRetrievePortID = 12, /* Failed to retrieve the port ID (clockID) */
    E_cmnErrorCode_InvalidApiCommand = 13, /* Invalid API Command */
    E_cmnErrorCode_GeneralError = 14, /* General Error */
    E_cmnErrorCode_IncorrectParameters = 15, /* Parameters are not correct */
    E_cmnErrorCode_Max
} T_cmnErrorCode;
```

### 2.3 T\_cmnLogDescription

`idtCommon/include/messageLog/cmnMessageLog.h`

```
typedef struct
{
    T_cmnLogId id;
    T_cmnLogType type;
    T_cmnMessageLevelRegister messageLevelMask;
    char description[ CMN_LOGDESCRIPTION_LIMIT ];
} T_cmnLogDescription;
```

### 2.4 T\_cmnLogId

`idtCommon/include/messageLog/cmnMessageLog.h`

```
typedef T_osInt16 T_cmnLogId;
```

## 2.5 T\_cmnMessageLevelRegister

idtCommon/include/cmnTypeDef.h

```
typedef T_osUint16 T_cmnMessageLevelRegister;
```

Bit mask is the same as the JSON “selectionMask”:

```
"selectionMask": "0000000000001111",
| | | | | | | | 0: Sync error
| | | | | | | 1: Sync warning
| | | | | | 2: Sync analysis
| | | | | 3: Error
| | | | 4: Warning
| | | 5: Debug
| | 6:
| 7: Timestamp
```

## 2.6 T\_gnssClockCategory

idtCommon/include/cmnTypeDef.h

```
typedef enum
{
    E_GNSS_CLOCK_CATEGORY_ACTIVE = 1,
    E_GNSS_CLOCK_CATEGORY_VOID   = 2
} T_gnssClockCategory;
```

## 2.7 T\_gnssSmState

idtCore/management/include/mngGnssSupervisor.h

```
typedef enum
{
    E_gnssState_Unqualified,
    E_gnssState_WaitFirstTodRead,
    E_gnssState_Locked,
    E_gnssState_Holdover,
    E_gnssState_Disabled,
    E_gnssState_Max
} T_gnssSmState;
```

## 2.8 T\_ieee1588PortIdentity

```
typedef struct
{
    T_ieee1588ClockIdentity clockIdentity;
    T_osUint16 portNumber;
} T_ieee1588PortIdentity;
```

```
typedef struct
{
    T_osUint8 clockId[ IDT_CLKID_BYTE_SIZE ];
} T_ieee1588ClockIdentity;
```

where IDT\_CLKID\_BYTE\_SIZE = 8

## 2.9 T\_mngApiGnssStatus

idtCore/management/include/mngApi/mngApi.h

```
typedef struct
{
    T_gnssSmState gnssStatus;
} T_mngApiGnssStatus;
```

## 2.10 T\_mngApiLoStatus

idtCore/management/include/mngApi/mngApi.h

```
typedef struct
{
    T_mngApiLoLockStatus lockStatus;
    T_osBool qualifiedHoldover;
    T_srvLoStateId loStateId;
    T_osChar loStateName[ CMN_NAME_MAX_LENGTH ];
} T_mngApiLoStatus;
```

where CMN\_NAME\_MAX\_LENGTH = 60 by default.

## 2.11 T\_mngApiLoLockStatus

idtCore/management/include/mngApi/mngApi.h

```
typedef enum
{
    E_mngApiLoNeverLocked,
    E_mngApiLoFrequencyLockedOnce,
    E_mngApiLoTimeLockedOnce,
    E_mngApiLoLockStatus_Max
} T_mngApiLoLockStatus;
```

## 2.12 T\_mngApiServoMode

idtCommon/management/include/mngApi/mngApi.h

```
typedef enum
{
    E_mngApiServoMode_Time,
    E_mngApiServoMode_Frequency,
    E_mngApiServoMode_Max
} T_mngApiServoMode;
```

## 2.13 T\_srvLoHoldoverType

idtCommon/include/cmnTypeDef.h

```
typedef enum
{
    E_srvLoHoldoverType_Software,
    E_srvLoHoldoverType_Hardware,
    E_srvLoHoldoverType_Max
} T_srvLoHoldoverType;
```

## 2.14 T\_srvLoStateId

idtCommon/include/cmnLoStateId.h

```
typedef enum
{
    E_srvLoInitialState = 0,
    E_srvLoUnqualifiedState = 1,
    E_srvLoLockAcqState = 2,
    E_srvLoFrequencyLockedState = 3,
    E_srvLoTimeLockedState = 4,
    E_srvLoHoldoverInSpecState = 5,
    E_srvLoHoldoverOutOfSpecState = 6,
    E_srvLoFreeRunState = 7,
    E_srvNumberLoStates = 8,
    E_srvLoStateInvalid = 9
} T_T_srvLoStateId;
```

## 2.15 T\_srvOscillatorType

idtCommon/include/cmnOscillatorTypes.h

```
typedef enum
{
    E_srvTcxo,
    E_srvMiniOcxo,
    E_srvOcxo,
    E_srvDocxo
} T_srvOscillatorType;
```

## 2.16 T\_srvPacketRate

typedef T\_osDouble T\_srvPacketRate;

## 2.17 T\_srvPdvValues

idtCommon/include/cmnTypeDef.h

```
typedef struct
{
    T_osDouble downlink;
    T_osDouble uplink;
} T_srvPdvValues;
```

## 2.18 T\_srvPhysicalClockCategory

```
typedef enum
{
    E_CATEGORY1 = 1,
    E_CATEGORY2 = 2,
    E_CATEGORY3 = 3,
    E_CATEGORY4 = 4,
    E_CATEGORY_DNU = 5, /* Do Not Use */
    E_CATEGORY_INVALID = 6
} T_srvPhysicalClockCategory;
```

## 2.19 T\_mngApiAptsStatus

idtCore/management/include/mngApi/mngApi.h

```
typedef struct
{
    T_aptSsmState aptSStatus;
} T_mngApiAptsStatus;
```

## 2.20 T\_aptSsmState

idtCore/management/include/mngAptsSupervisor.h

```
typedef enum
{
    E_aptSState_GnssUnqualified,
    E_aptSState_WaitFirstTodRead,
    E_aptSState_GnssLocked,
    E_aptSState_GnssHoldover,
    E_aptSState_GnssDisabled,
    E_aptSState_Max
} T_aptSsmState;
```

# 3. Management API Functions

The following management API functions are grouped into categories and related functionality.

## 3.1 Holdover

### 3.1.1 mngApi\_GetHoldoverLossPhysicalOosEnable

```
T_cmnErrorCode mngApi_GetHoldoverLossPhysicalOosEnable( T_osBool *holdoverLossPhysicalOosEnable );
```

#### DESCRIPTION

Get the holdover loss of traceability of physical layer out-of-specification enable.

#### ARGUMENTS

##### INPUTS

None

##### OUTPUT

holdoverLossPhysicalOosEnable – E\_osTrue if enabled, E\_osFalse otherwise.

#### RETURN

E\_cmnErrorCode\_OK – On success, else another T\_cmnErrorCode

### 3.1.2 mngApi\_GetHoldoverOutOfSpecUserDefinedFrequencyOffsetEnable

```
T_cmnErrorCode mngApi_GetHoldoverOutOfSpecUserDefinedFrequencyOffsetEnable( T_osBool *enable );
```

#### DESCRIPTION

Get holdover out of specification user defined frequency offset enable.

### ARGUMENTS

#### INPUTS

None

#### OUTPUT

Enable – E\_osTrue - use user defined frequency offset when in out of spec holdover, E\_osFalse - use computed holdover value.

### RETURN

E\_cmnErrorCode\_OK – On success, else another T\_cmnErrorCode

### 3.1.3. mngApi\_SetHoldoverOutOfSpecUserDefinedFrequencyOffsetEnable

```
T_cmnErrorCode mngApi_SetHoldoverOutOfSpecUserDefinedFrequencyOffsetEnable( T_osBool enable );
```

### DESCRIPTION

Set holdover out of specification user defined frequency offset enable.

### ARGUMENTS

#### INPUTS

Enable – E\_osTrue - use user defined frequency offset when in out of spec holdover, E\_osFalse - use computed holdover value.

#### OUTPUT

None

### RETURN

E\_cmnErrorCode\_OK – On success, else another T\_cmnErrorCode

### 3.1.4. mngApi\_GetHoldoverOutOfSpecUserDefinedFrequencyOffsetPpb

```
T_cmnErrorCode mngApi_GetHoldoverOutOfSpecUserDefinedFrequencyOffsetPpb( T_osDouble *offsetPpb );
```

### DESCRIPTION

Get holdover out of spec user defined frequency offset.

### ARGUMENTS

#### INPUTS

None

#### OUTPUT

offsetPpb – frequency offset in parts per billion, 10<sup>9</sup>

### RETURN

E\_cmnErrorCode\_OK – On success, else another T\_cmnErrorCode

### 3.1.5. mngApi\_SetHoldoverOutOfSpecUserDefinedFrequencyOffsetPpb

```
T_cmnErrorCode mngApi_SetHoldoverOutOfSpecUserDefinedFrequencyOffsetPpb( T_osDouble offsetPpb );
```

#### DESCRIPTION

Set holdover out of spec user defined frequency offset.

#### ARGUMENTS

##### INPUTS

offsetPpb – frequency offset in parts per billion, 10<sup>9</sup>

##### OUTPUT

None

#### RETURN

E\_cmnErrorCode\_OK – On success, else another T\_cmnErrorCode

### 3.1.6. mngApi\_GetHoldoverTimeout

```
T_cmnErrorCode mngApi_GetHoldoverTimeout( T_osUint32 *timeout );
```

#### DESCRIPTION

Get the holdover timeout.

#### ARGUMENTS

##### INPUTS

None

##### OUTPUT

timeout – holdover timeout in seconds

#### RETURN

E\_cmnErrorCode\_OK – On success, else another T\_cmnErrorCode

### 3.1.7. mngApi\_SetHoldoverTimeout

```
T_cmnErrorCode mngApi_SetHoldoverTimeout( T_osUint32 const timeout );
```

#### DESCRIPTION

Get the holdover timeout.

#### ARGUMENTS

##### INPUTS

timeout – holdover timeout in seconds

##### OUTPUT

None

#### RETURN

E\_cmnErrorCode\_OK – On success, else another T\_cmnErrorCode

### 3.1.8. mngApi\_GetHoldoverTimerValue

```
T_cmnErrorCode mngApi_GetHoldoverTimerValue( T_osUInt32 *timeRemainingSeconds );
```

#### DESCRIPTION

Get the holdover timer remaining time.

#### ARGUMENTS

##### INPUTS

None

##### OUTPUT

timeRemainingSeconds – holdover timer remaining time in seconds, 0 means timer is not running.

#### RETURN

E\_cmnErrorCode\_OK – On success, else another T\_cmnErrorCode

### 3.1.9. mngApi\_GetHoldoverType

```
T_cmnErrorCode mngApi_GetHoldoverType( T_srvLoHoldoverType *holdoverType );
```

#### DESCRIPTION

Get the holdover type.

#### ARGUMENTS

##### INPUTS

None

##### OUTPUT

holdoverType – holdover type (software/hardware).

#### RETURN

E\_cmnErrorCode\_OK – On success, else another T\_cmnErrorCode

### 3.1.10. mngApi\_SetHoldoverType

```
T_cmnErrorCode mngApi_SetHoldoverType( T_srvLoHoldoverType const holdoverType );
```

#### DESCRIPTION

Set the holdover type.

#### ARGUMENTS

##### INPUTS

holdoverType – holdover type (software/hardware)

##### OUTPUT

None

#### RETURN

E\_cmnErrorCode\_OK – On success, else another T\_cmnErrorCode

### 3.1.11. mngApi\_ForceLoStateHoldover

```
T_cmnErrorCode mngApi_ForceLoStateHoldover( void );
```

#### DESCRIPTION

Force the LO State Machine into Holdover state.

#### ARGUMENTS

##### INPUTS

None

##### OUTPUT

None

#### RETURN

E\_cmnErrorCode\_OK – On success, else another T\_cmnErrorCode

### 3.1.12. mngApi\_ClearForceLoStateHoldover

```
T_cmnErrorCode mngApi_ClearForceLoStateHoldover( void );
```

#### DESCRIPTION

Clear Force Holdover state.

#### ARGUMENTS

##### INPUTS

None

##### OUTPUT

None

#### RETURN

E\_cmnErrorCode\_OK – On success, else another T\_cmnErrorCode

## 3.2 G.8273.2 Physical Layer Assistance

### 3.2.1. mngApi\_GetPhysicalClockCategory

```
T_cmnErrorCode mngApi_GetPhysicalClockCategory( T_srvPhysicalClockCategory *physicalClockCategory );
```

#### DESCRIPTION

Get physical layer clock category.

#### ARGUMENTS

##### INPUTS

None

##### OUTPUT

physicalClockCategory – physical layer clock category

#### RETURN

E\_cmnrErrorcode\_OK – On success  
E\_cmnrErrorcode\_NotAccepted – Otherwise

### 3.2.2. mngApi\_SetPhysicalClockCategory

```
T_cmnrErrorcode mngApi_SetPhysicalClockCategory( T_srvPhysicalClockCategory physicalClockCategory );
```

#### DESCRIPTION

Set physical layer clock category.

#### ARGUMENTS

##### INPUTS

physicalClockCategory – physical layer clock category

##### OUTPUT

None

#### RETURN

E\_cmnrErrorcode\_OK – On success  
E\_cmnrErrorcode\_NotAccepted – Otherwise

### 3.2.3. mngApi\_GetPhysicalClockCategoryThreshold

```
T_cmnrErrorcode mngApi_GetPhysicalClockCategoryThreshold(  
    T_srvPhysicalClockCategory *physicalClockCategoryThreshold );
```

#### DESCRIPTION

Get physical layer clock category threshold.

#### ARGUMENTS

##### INPUTS

None

##### OUTPUT

physicalClockCategory – physical layer clock category threshold

#### RETURN

E\_cmnrErrorcode\_OK – On success  
E\_cmnrErrorcode\_NotAccepted – Otherwise

### 3.2.4. mngApi\_SetPhysicalClockCategoryThreshold

```
T_cmnErrorCode mngApi_SetPhysicalClockCategoryThreshold (
    T_srvPhysicalClockCategory phyClockCategoryThreshold );
```

#### DESCRIPTION

Set physical layer clock category.

#### ARGUMENTS

##### INPUTS

physicalClockCategory – physical layer clock category

##### OUTPUT

None

#### RETURN

E\_cmnErrorCode\_OK – On success  
E\_cmnErrorCode\_NotAccepted – Otherwise

### 3.2.5. mngApi\_GetPhysicalPllWaitToRestoreTimeoutValue

```
T_cmnErrorCode mngApi_GetPhysicalPllWaitToRestoreTimeoutValue (
    T_osUInt16 *physicalPllWaitToRestoreTimeoutValue );
```

#### DESCRIPTION

Get physical PLL wait to restore timeout value.

#### ARGUMENTS

##### INPUTS

None

##### OUTPUT

physicalPllWaitToRestoreTimeoutValue – physical PLL wait to restore timeout value

#### RETURN

E\_cmnErrorCode\_OK – On success  
E\_cmnErrorCode\_NotAccepted – Otherwise

### 3.2.6. mngApi\_SetPhysicalPllWaitToRestoreTimeoutValue

```
T_cmnErrorCode mngApi_SetPhysicalPllWaitToRestoreTimeoutValue (
    T_osUInt16 physicalPllWaitToRestoreTimeoutValue );
```

#### DESCRIPTION

Set physical PLL wait to restore timeout value.

#### ARGUMENTS

##### INPUTS

physicalPllWaitToRestoreTimeoutValue – physical PLL wait to restore timeout value

##### OUTPUT

None

#### RETURN

E\_cmnErrorCode\_OK – On success  
E\_cmnErrorCode\_NotAccepted – Otherwise

## 3.3 GNSS

### 3.3.1. mngApi\_GetGnssClockCategory

```
T_cmnErrorCode mngApi_GetGnssClockCategory( T_gnssClockCategory *gnssClockCategory );
```

#### DESCRIPTION

Get GNSS clock category.

#### ARGUMENTS

##### INPUTS

None

##### OUTPUT

gnssClockCategory – GNSS clock category

#### RETURN

E\_cmnErrorCode\_OK – On success

E\_cmnErrorCode\_NotAccepted – Otherwise

### 3.3.2. mngApi\_SetGnssClockCategory

```
T_cmnErrorCode mngApi_SetGnssClockCategory( T_gnssClockCategory gnssClockCategory );
```

#### DESCRIPTION

Set GNSS clock category.

#### ARGUMENTS

##### INPUTS

gnssClockCategory – GNSS clock category

##### OUTPUT

None

#### RETURN

E\_cmnErrorCode\_OK – On success

E\_cmnErrorCode\_NotAccepted – Otherwise

### 3.3.3. mngApi\_GetGnssClockCategoryThreshold

```
T_cmnErrorCode mngApi_GetGnssClockCategoryThreshold(  
    T_gnssClockCategory *gnssClockCategoryThreshold );
```

#### DESCRIPTION

Get GNSS clock category threshold.

#### ARGUMENTS

##### INPUTS

None

##### OUTPUT

gnssClockCategory – GNSS clock category threshold

#### RETURN

E\_cmnErrorCode\_OK – On success  
E\_cmnErrorCode\_NotAccepted – Otherwise

### 3.3.4. mngApi\_SetGnssClockCategoryThreshold

```
T_cmnErrorCode mngApi_SetGnssClockCategoryThreshold(  
    T_gnssClockCategory gnssClockCategoryThreshold );
```

#### DESCRIPTION

Set GNSS clock category threshold.

#### ARGUMENTS

##### INPUTS

gnssClockCategory – GNSS clock category threshold

##### OUTPUT

None

#### RETURN

E\_cmnErrorCode\_OK – On success  
E\_cmnErrorCode\_NotAccepted – Otherwise

## 3.4 Message Log

### 3.4.1. mngApi\_OpenSyslog

```
T_cmnErrorCode mngApi_OpenSyslog( T_osChar const *syslogIpAddress,  
                                  T_osUint16 udpPort,  
                                  T_cmnMessageLevelRegister messageLevelMask );
```

#### DESCRIPTION

Open syslog socket with IPv4 address and udpPort.

#### ARGUMENTS

##### INPUTS

syslogIpAddress – pointer to string representation of IPv4 address, ex. "123.0.0.1"  
udpPort – UDP port  
messageLevelMask – message level bit field mask, see 2.5

##### OUTPUT

None

#### RETURN

E\_cmnErrorCode\_OK – On success  
E\_cmnErrorCode\_NotAccepted – Otherwise

### 3.4.2. mngApi\_CloseSyslog

```
T_cmnErrorCode mngApi_CloseSyslog( void );
```

#### DESCRIPTION

Close syslog socket.

#### ARGUMENTS

##### INPUTS

None

##### OUTPUT

None

#### RETURN

E\_cmnErrorCode\_OK – Always

### 3.4.3. mngApi\_GetListOfMessageLogs

```
T_cmnErrorCode mngApi_GetListOfMessageLogs( T_cmnLogDescription *messageLogDescriptors,  
                                             T_osUint8 *numberOfMessageLogs );
```

#### DESCRIPTION

Get array of message logs.

Use mngApi\_GetNumberOfMessageLogs to get number of message logs to allocate size of array.

**ARGUMENTS****INPUTS**

messageLogDescriptors – pointer to array of, see 2.3  
numberOfMessageLogs – maximum size of the array messageLogDescriptor points to

**OUTPUT**

numberOfMessageLogs – the number of message logs returned.

**RETURN**

E\_cmnrErrorcode\_OK – On success  
E\_cmnrErrorcode\_NotAccepted – Otherwise

**3.4.4. mngApi\_GetNumberOfMessageLogs**

```
T_cmnrErrorcode mngApi_GetNumberOfMessageLogs( T_osUint8 *numberOfMessageLogs );
```

**DESCRIPTION**

Get number of message logs. Intended to be used to size the T\_cmnrLogDescription array for mngApi\_GetListOfMessageLogs.

**ARGUMENTS****INPUTS**

None

**OUTPUT**

numberOfMessageLogs – the number of active message logs

**RETURN**

E\_cmnrErrorcode\_OK – On success  
E\_cmnrErrorcode\_NotAccepted – Otherwise

**3.4.5. mngApi\_CreateCallbackMessageLog**

```
T_cmnrErrorcode mngApi_CreateCallbackMessageLog (T_CallbackFunctionPointer userCallback,  
                                                T_cmnrMessageLevelRegister const messageLevels,  
                                                T_cmnrLogId *messageLogId );
```

**DESCRIPTION**

Create a callback message log. Calls the user registered callback function with the message log string.

**ARGUMENTS****INPUTS**

userCallback – callback function of type T\_CallbackFunctionPointer  
messageLevels – message level bit field mask, see 2.5

**OUTPUT**

messageLogId – identifier for created message log

**RETURN**

E\_cmnrErrorcode\_OK – On success, else another T\_cmnrErrorcode

### 3.4.6. mngApi\_CreateFileMessageLog

```
T_cmnErrorCode mngApi_CreateFileMessageLog( T_osChar const *fullyQualifiedFilename,
                                             T_cmnMessageLevelRegister const messageLevels,
                                             T_osBool const purge,
                                             T_osUInt32 const maxSize,
                                             T_osUInt8 const archives,
                                             T_cmnLogId *messageLogId );
```

#### DESCRIPTION

Open a message log.

#### ARGUMENTS

##### INPUTS

fullyQualifiedFilename – maximum length, See CMN\_MAX\_FULL\_LOG\_FILE\_NAME\_LIMIT.  
ex. "/createTest1.txt"

messageLevels – message level bit field mask, see 2.5

purge – 0 append to existing file, 1 delete existing files

maxSize – size in bytes, maximum file size before archiving

archive – maximum number of archives

##### OUTPUT

messageLogId – identifier for created message log

#### RETURN

E\_cmnErrorCode\_OK – On success

E\_cmnErrorCode\_NotAccepted – Otherwise

### 3.4.7. mngApi\_DeleteMessageLog

```
T_cmnErrorCode mngApi_DeleteMessageLog( T_cmnLogId messageLogId );
```

#### DESCRIPTION

Delete a message log.

#### ARGUMENTS

##### INPUTS

messageLogId – identifier for created message log

##### OUTPUT

None

#### RETURN

E\_cmnErrorCode\_OK – On success, else another T\_cmnErrorCode

### 3.4.8. mngApi\_GetMessageLogLevel

```
T_cmnErrorCode mngApi_GetMessageLogLevel( T_cmnLogId messageLogId,
                                           T_cmnMessageLevelRegister *messageLevelMask );
```

#### DESCRIPTION

Get message log level.

## ARGUMENTS

### INPUTS

messageLogId – identifier for message log

### OUTPUT

messageLevelMask – message level bit field mask, see 2.5

## RETURN

E\_cmnErrorCode\_OK – On success, else another T\_cmnErrorCode

### 3.4.9. mngApi\_SetMessageLogLevel

```
T_cmnErrorCode mngApi_SetMessageLogLevel( T_cmnLogId messageLogId,
                                           T_cmnMessageLevelRegister messageLevelMask );
```

## DESCRIPTION

Set message log level.

## ARGUMENTS

### INPUTS

messageLogId – identifier for message log.

messageLevelMask – message level bit field mask, see 2.5

### OUTPUT

None

## RETURN

E\_cmnErrorCode\_OK – On success, else another T\_cmnErrorCode

### 3.4.10. mngApi\_GetStdoutMessageLogLevel

```
T_cmnErrorCode mngApi_GetStdoutMessageLogLevel( T_cmnMessageLevelRegister *messageLevelMask );
```

## DESCRIPTION

Get STDOUT message log level.

## ARGUMENTS

### INPUTS

None

### OUTPUT

messageLevelMask – message level bit field mask, see 2.5

## RETURN

E\_cmnErrorCode\_OK – On success, else another T\_cmnErrorCode

### 3.4.11. mngApi\_SetStdoutMessageLogLevel

```
T_cmnErrorCode mngApi_SetStdoutMessageLogLevel( T_cmnMessageLevelRegister messageLevelMask );
```

#### DESCRIPTION

Set STDOUT message log level.

#### ARGUMENTS

##### INPUTS

messageLevelMask – message level bit field mask, see 2.5

##### OUTPUT

None

#### RETURN

E\_cmncnErrorCode\_OK – On success, else another T\_cmncnErrorCode

### 3.4.12. mngApi\_GetSyslogMessageLogLevel

```
T_cmncnErrorCode mngApi_GetSyslogMessageLogLevel( T_cmncnMessageLevelRegister *messageLevelMask );
```

#### DESCRIPTION

Get syslog message log level.

#### ARGUMENTS

##### INPUTS

None

##### OUTPUT

messageLevelMask – message level bit field mask, see 2.5

#### RETURN

E\_cmncnErrorCode\_OK – On success, else another T\_cmncnErrorCode

### 3.4.13. mngApi\_SetSyslogMessageLogLevel

```
T_cmncnErrorCode mngApi_SetSyslogMessageLogLevel( T_cmncnMessageLevelRegister messageLevelMask );
```

#### DESCRIPTION

Set syslog message log level.

#### ARGUMENTS

##### INPUTS

messageLevelMask – message level bit field mask, see 2.5

##### OUTPUT

None

#### RETURN

E\_cmncnErrorCode\_OK – On success, else another T\_cmncnErrorCode

## 3.5 Miscellaneous

### 3.5.1. mngApi\_GetCurrentReferenceMaster

```
T_cmnErrorCode mngApi_GetCurrentReferenceMaster( T_ieee1588PortIdentity *portIdentity );
```

#### DESCRIPTION

Get the current selected reference master.

#### ARGUMENTS

##### INPUTS

None

##### OUTPUT

portIdentity – current LO state reference master

#### RETURN

E\_cmnErrorCode\_OK – On success

E\_cmnErrorCode\_NotConfigured – if no LO state reference master was configured

E\_cmnErrorCode\_ResponseTimeout – if no response received within response timeout period

### 3.5.2. mngApi\_GetEpochTimeSeconds

```
T_cmnErrorCode mngApi_GetEpochTimeSeconds( T_osUInt64 *seconds )
```

#### DESCRIPTION

Get the current seconds portion of the PTP DPLL Time of Day (ToD) counter.

#### ARGUMENTS

##### INPUTS

None

##### OUTPUT

seconds – PTP DPLL ToD counter seconds portion value

#### RETURN

E\_cmnErrorCode\_OK – On success

E\_cmnErrorCode\_ResponseTimeout – if no response received within response timeout period

### 3.5.3. mngApi\_GetLoStatus

```
T_cmnErrorCode mngApi_GetLoStatus( T_mngApiLoStatus *currentLoStatus );
```

#### DESCRIPTION

Get the LO state machine status.

#### ARGUMENTS

##### INPUTS

None

##### OUTPUT

currentLoStatus – pointer to T\_mngApiLoStatus structure

#### RETURN

E\_cmnErrorCode\_OK – On success, else another T\_cmnErrorCode

### 3.5.4. mngApi\_GetServoMode

```
T_cmnErrorCode mngApi_GetServoMode( T_mngApiServoMode *servoMode );
```

#### DESCRIPTION

Get servo mode.

Frequency Reference tracker will return E\_mngApiServoMode\_Frequency, all other reference trackers return E\_mngApiServoMode\_Time.

#### ARGUMENTS

##### INPUTS

None

##### OUTPUT

servoMode – E\_mngApiServoMode\_Time or E\_mngApiServoMode\_Frequency

#### RETURN

E\_cmnErrorCode\_OK – On success

E\_cmnErrorCode\_NotAccepted – Otherwise

### 3.5.5. mngApi\_GetSoftwareVersion

```
T_cmnErrorCode mngApi_GetSoftwareVersion( char const **releaseId,  
                                           char const **commitId );
```

#### DESCRIPTION

Get the software release ID and commit ID strings.

The CMN\_RELEASE\_ID and CMN\_COMMIT\_ID are defined in cmnVersionId.h.

## ARGUMENTS

### INPUTS

None

### OUTPUT

releaseId – pointer to a release ID string, xx.yy.zz

commitId – pointer to a Git commit ID

## RETURN

E\_cmnErrorCode\_OK – On success, else another T\_cmnErrorCode

### 3.5.6. mngApi\_GetUnqualifiedTimeout

```
T_cmnErrorCode mngApi_GetUnqualifiedTimeout( T_osUInt32 *timeout );
```

## DESCRIPTION

Get the holdover unqualified timeout.

Matches the JSON configuration “unqualifiedTimeoutSeconds” holdover value.

## ARGUMENTS

### INPUTS

None

### OUTPUT

timeout – unqualified timeout in seconds

## RETURN

E\_cmnErrorCode\_OK – On success, else another T\_cmnErrorCode

### 3.5.7. mngApi\_GetUnqualifiedTimerValue

```
T_cmnErrorCode mngApi_GetUnqualifiedTimerValue( T_osUInt32 *timeRemainingSeconds );
```

## DESCRIPTION

Get the holdover timer remaining time.

## ARGUMENTS

### INPUTS

None

### OUTPUT

timeRemainingSeconds – holdover timer remaining time in seconds, 0 means timer is not running.

## RETURN

E\_cmnErrorCode\_OK – On success, else another T\_cmnErrorCode

### 3.5.8. mngApi\_SetEpochTimeSeconds

```
T_cmnErrorCode mngApi_SetEpochTimeSeconds( T_osUInt64 const seconds );
```

#### DESCRIPTION

Set seconds portion of the PTP DPLL Time of Day (ToD) counter, the nanoseconds will be unchanged.

- Should only be called when there is no PTP master available
- Frequency lock is maintained while the seconds is updated because the nanoseconds portion is unchanged
- There should be at least 10 seconds between calls to this function

When using AdaptiveTimeAssist and PTP is not present, this function will set the seconds part of the system ToD. The nanoseconds part will come from the external 1 Hz edge. The time stampers will then be aligned to the system ToD.

When using AdaptiveTimeAssist and PTP is present, PTP will be the source of the system ToD. The GNSS measurement channel is controlled by the AdaptiveTimeAssist tracker in pcm4l and should not be modified outside of pcm4l.

#### ARGUMENTS

##### INPUTS

seconds – Epoch time seconds only, nanoseconds will be unchanged

##### OUTPUT

None

#### RETURN

E\_cmnErrorCode\_OK – On success, else another T\_cmnErrorCode

### 3.5.9. mngApi\_SetUnqualifiedTimeout

```
T_cmnErrorCode mngApi_SetUnqualifiedTimeout( T_osUInt32 const timeout );
```

#### DESCRIPTION

Set the holdover unqualified timeout.

Matches the JSON configuration “unqualifiedTimeoutSeconds” holdover value.

#### ARGUMENTS

##### INPUTS

timeout – unqualified timeout in seconds

##### OUTPUT

None

#### RETURN

E\_cmnErrorCode\_OK – On success, else another T\_cmnErrorCode

### 3.5.10. mngApi\_GetGnssStatus

```
T_cmnErrorCode mngApi_GetGnssStatus( T_mngApiGnssStatus *currentGnssStatus );
```

#### DESCRIPTION

Get the GNSS state machine status.

#### ARGUMENTS

##### INPUTS

None

##### OUTPUT

currentGnssStatus – pointer to T\_mngApiGnssStatus structure.

Transient state E\_gnssState\_WaitFirstTodRead reports as E\_gnssState\_Unqualified.

#### RETURN

E\_cmnErrorCode\_OK – On success, else another T\_cmnErrorCode

## 3.6 Reference Trackers

### 3.6.1. mngApi\_ReferenceTracker\_GetCount

```
T_cmnErrorCode mngApi_ReferenceTracker_GetCount( T_osUInt8 *numberOfReferenceTrackers );
```

#### DESCRIPTION

Get number of reference trackers.

#### ARGUMENTS

##### INPUTS

None

##### OUTPUT

numberOfReferenceTrackers – the number of reference trackers

#### RETURN

E\_cmnErrorCode\_OK – On success

E\_cmnErrorCode\_ResponseTimeout – if no response received within response timeout period

### 3.6.2. mngApi\_ReferenceTracker\_GetList

```
T_cmnErrorCode mngApi_ReferenceTracker_GetList( T_cmnReferenceTracker *referenceTrackerList,  
                                                T_osUInt8 *numberOfReferenceTrackers );
```

#### DESCRIPTION

Get list of reference trackers. Use mngApi\_GetNumberOfReferenceTrackers to get number to allocate size of array.

#### ARGUMENTS

##### INPUTS

referenceTrackerList – pointer to array of T\_cmnReferenceTracker

numberOfReferenceTrackers – the maximum size of the array that referenceTrackerList is pointing to.

**OUTPUT**

numberOfReferenceTrackers – the number of message logs in the list

**RETURN**

E\_cmnErrorCode\_OK – On success

E\_cmnErrorCode\_NotAccepted – Otherwise

**3.6.3. mngApi\_ReferenceTracker\_GetDownlinkPacketRate (deprecated)**

```
T_cmnErrorCode mngApi_ReferenceTracker_GetDownlinkPacketRate(  
    T_osUInt16 stackInstNumber,  
    T_srvPacketRate *packetsPerSecond );
```

**DESCRIPTION**

Get the downlink (sync) packet rate.

**ARGUMENTS****INPUTS**

stackInstNumber – stack instance number

**OUTPUT**

packetsPerSecond – packet rate

**RETURN**

E\_cmnErrorCode\_OK – On success, else another T\_cmnErrorCode

**3.6.4. mngApi\_RT\_GetDownlinkPacketRate**

```
T_cmnErrorCode mngApi_RT_GetDownlinkPacketRate(  
    T_osUInt16 stackInstNumber,  
    T_osUInt16 trackerInstNumber,  
    T_srvPacketRate *packetsPerSecond );
```

**DESCRIPTION**

Get the downlink (sync) packet rate.

**ARGUMENTS****INPUTS**

stackInstNumber – stack instance number

trackerInstNumber – tracker instance number

**OUTPUT**

packetsPerSecond – packet rate

**RETURN**

E\_cmnErrorCode\_OK – On success, else another T\_cmnErrorCode

**3.6.5. mngApi\_ReferenceTracker\_GetUplinkPacketRate (deprecated)**

```
T_cmnErrorCode mngApi_ReferenceTracker_GetUplinkPacketRate(  
    T_osUInt16 stackInstNumber,  
    T_srvPacketRate *packetsPerSecond );
```

#### DESCRIPTION

Get the uplink (delay request) packet rate.

#### ARGUMENTS

##### INPUTS

stackInstNumber – stack instance number

##### OUTPUT

packetsPerSecond – packet rate

#### RETURN

E\_cmnrErrorcode\_OK – On success, else another T\_cmnrErrorcode

### 3.6.6. mngApi\_RT\_GetUplinkPacketRate

```
T_cmnrErrorcode mngApi_RT_GetUplinkPacketRate(
    T_osUintr16 stackInstNumber,
    T_osUintr16 trackerInstNumber,
    T_srvPacketRate *packetsPerSecond );
```

#### DESCRIPTION

Get the uplink (delay request) packet rate.

#### ARGUMENTS

##### INPUTS

stackInstNumber – stack instance number

trackerInstNumber – tracker instance number

##### OUTPUT

packetsPerSecond – packet rate

#### RETURN

E\_cmnrErrorcode\_OK – On success, else another T\_cmnrErrorcode

### 3.6.7. mngApi\_ReferenceTracker\_GetFloorDelayEstimateSeconds (deprecated)

```
T_cmnrErrorcode mngApi_ReferenceTracker_GetFloorDelayEstimateSeconds(
    T_osUintr16 stackInstNumber,
    T_osDouble *floorDelayEstimate );
```

#### DESCRIPTION

Get the floor delay estimate, units in seconds.

#### ARGUMENTS

##### INPUTS

stackInstNumber – stack instance number

##### OUTPUT

floorDelayEstimate – floor delay estimate

#### RETURN

E\_cmnrErrorcode\_OK – On success, else another T\_cmnrErrorcode

### 3.6.8. mngApi\_RT\_GetFloorDelayEstimateSeconds

```
T_cmnErrorCode mngApi_RT_GetFloorDelayEstimateSeconds(  
    T_osUInt16 stackInstNumber,  
    T_osUInt16 trackerInstNumber,  
    T_osDouble *floorDelayEstimate );
```

#### DESCRIPTION

Get the floor delay estimate, units in seconds.

#### ARGUMENTS

##### INPUTS

stackInstNumber – stack instance number  
trackerInstNumber – tracker instance number

##### OUTPUT

floorDelayEstimate – floor delay estimate

#### RETURN

E\_cmnErrorCode\_OK – On success, else another T\_cmnErrorCode

### 3.6.9. mngApi\_ReferenceTracker\_SetFloorDelayEstimateSeconds (deprecated)

```
T_cmnErrorCode mngApi_ReferenceTracker_SetFloorDelayEstimateSeconds(  
    T_osUInt16 stackInstNumber,  
    T_osDouble *floorDelayEstimate );
```

#### DESCRIPTION

Set the floor delay estimate, units in seconds.

#### ARGUMENTS

##### INPUTS

stackInstNumber – stack instance number  
floorDelayEstimate – floor delay estimate

##### OUTPUT

None

#### RETURN

E\_cmnErrorCode\_OK – On success, else another T\_cmnErrorCode

### 3.6.10. mngApi\_RT\_SetFloorDelayEstimateSeconds

```
T_cmnErrorCode mngApi_RT_SetFloorDelayEstimateSeconds(  
    T_osUInt16 stackInstNumber,  
    T_osUInt16 trackerInstNumber,  
    T_osDouble *floorDelayEstimate );
```

#### DESCRIPTION

Set the floor delay estimate, units in seconds.

#### ARGUMENTS

##### INPUTS

stackInstNumber – stack instance number  
trackerInstNumber – tracker instance number  
floorDelayEstimate – floor delay estimate

##### OUTPUT

None

#### RETURN

E\_cmnErrorCode\_OK – On success, else another T\_cmnErrorCode

### 3.6.11. mngApi\_ReferenceTracker\_GetHighPrecisionFrequencyCorrectionTime (deprecated)

```
T_cmnErrorCode mngApi_ReferenceTracker_GetHighPrecisionFrequencyCorrectionTime(  
    T_osUInt16 stackInstNumber,  
    T_osDouble *correctionTimeMinutes );
```

#### DESCRIPTION

Get the high precision frequency correction time, units in minutes.  
This parameter is the value set by the JSON configuration file parameter  
“highPrecisionFrequencyCorrectionTimeMinutes”.

#### ARGUMENTS

##### INPUTS

stackInstNumber – stack instance number

##### OUTPUT

correctionTimeMinutes – time in minutes servo will gather timestamps

#### RETURN

E\_cmnErrorCode\_OK – On success, else another T\_cmnErrorCode

### 3.6.12. mngApi\_RT\_GetHighPrecisionFrequencyCorrectionTime

```
T_cmnErrorCode mngApi_RT_GetHighPrecisionFrequencyCorrectionTime(  
    T_osUInt16 stackInstNumber,  
    T_osUInt16 trackerInstNumber,  
    T_osDouble *correctionTimeMinutes );
```

#### DESCRIPTION

Get the high precision frequency correction time, units in minutes.  
This parameter is the value set by the JSON configuration file parameter  
“highPrecisionFrequencyCorrectionTimeMinutes”.

#### ARGUMENTS

##### INPUTS

stackInstNumber – stack instance number  
trackerInstNumber – tracker instance number

##### OUTPUT

correctionTimeMinutes – time in minutes servo will gather timestamps

#### RETURN

E\_cmnErrorCode\_OK – On success, else another T\_cmnErrorCode

### 3.6.13. mngApi\_ReferenceTracker\_SetHighPrecisionFrequencyCorrectionTime (deprecated)

```
T_cmnErrorCode mngApi_ReferenceTracker_SetHighPrecisionFrequencyCorrectionTime(  
    T_osUInt16 stackInstNumber,  
    T_osDouble *correctionTimeMinutes );
```

#### DESCRIPTION

Set the high precision frequency correction time, units in minutes.  
This parameter is the value set by the JSON configuration file parameter  
“highPrecisionFrequencyCorrectionTimeMinutes”.

For an adaptive time reference tracker, a high precision frequency and time estimation and correction will be performed before entering time tracking mode. This parameter determines how long the high precision frequency and time estimation takes. The longer it takes, the more accurate the correction will be. With a good network condition, in other words, low PDV, the value of this parameter could be small, for example, 2. For a large PDV condition, the value should be set to a bigger value, for example, 4 or 8, or even bigger.

#### ARGUMENTS

##### INPUTS

stackInstNumber – stack instance number  
correctionTimeMinutes – time in minutes servo will gather timestamps

##### OUTPUT

None

#### RETURN

E\_cmnErrorCode\_OK – On success, else another T\_cmnErrorCode

### 3.6.14. mngApi\_RT\_SetHighPrecisionFrequencyCorrectionTime

```
T_cmnErrorCode mngApi_RT_SetHighPrecisionFrequencyCorrectionTime(  
    T_osUInt16 stackInstNumber,  
    T_osUInt16 trackerInstNumber,  
    T_osDouble *correctionTimeMinutes );
```

#### DESCRIPTION

Set the high precision frequency correction time, units in minutes.

This parameter is the value set by the JSON configuration file parameter “highPrecisionFrequencyCorrectionTimeMinutes”.

For an adaptive time reference tracker, a high precision frequency and time estimation and correction will be performed before entering time tracking mode. This parameter determines how long the high precision frequency and time estimation takes. The longer it takes, the more accurate the correction will be. With a good network condition, in other words, low PDV, the value of this parameter could be small, for example, 2. For a large PDV condition, the value should be set to a bigger value, for example, 4 or 8, or even bigger.

#### ARGUMENTS

##### INPUTS

stackInstNumber – stack instance number

trackerInstNumber – tracker instance number

correctionTimeMinutes – time in minutes servo will gather timestamps

##### OUTPUT

None

#### RETURN

E\_cmnErrorCode\_OK – On success, else another T\_cmnErrorCode

### 3.6.15. mngApi\_ReferenceTracker\_GetOscillatorType (deprecated)

```
T_cmnErrorCode mngApi_ReferenceTracker_GetOscillatorType(  
    T_osUInt16 stackInstNumber,  
    T_srvOscillatorType *oscillatorType );
```

#### DESCRIPTION

Get the oscillator type.

#### ARGUMENTS

##### INPUTS

stackInstNumber – stack instance number

##### OUTPUT

oscillatorType – oscillator type, see T\_srvOscillatorType

#### RETURN

E\_cmnErrorCode\_OK – On success, else another T\_cmnErrorCode

### 3.6.16. mngApi\_RT\_GetOscillatorType

```
T_cmnErrorCode mngApi_RT_GetOscillatorType(  
    T_osUInt16 stackInstNumber,  
    T_osUInt16 trackerInstNumber,  
    T_srvOscillatorType *oscillatorType );
```

#### DESCRIPTION

Get the oscillator type.

#### ARGUMENTS

##### INPUTS

stackInstNumber – stack instance number  
trackerInstNumber – tracker instance number

##### OUTPUT

oscillatorType – oscillator type, see T\_srvOscillatorType

#### RETURN

E\_cmnErrorCode\_OK – On success, else another T\_cmnErrorCode

### 3.6.17. mngApi\_ReferenceTracker\_SetOscillatorType (deprecated)

```
T_cmnErrorCode mngApi_ReferenceTracker_SetOscillatorType(  
    T_osUInt16 stackInstNumber,  
    T_srvOscillatorType *oscillatorType );
```

#### DESCRIPTION

Set the oscillator type.

#### ARGUMENTS

##### INPUTS

stackInstNumber – stack instance number  
oscillatorType – oscillator type, see T\_srvOscillatorType

##### OUTPUT

None

#### RETURN

E\_cmnErrorCode\_OK – On success, else another T\_cmnErrorCode

### 3.6.18. mngApi\_RT\_SetOscillatorType

```
T_cmnErrorCode mngApi_RT_SetOscillatorType(
    T_osUInt16 stackInstNumber,
    T_osUInt16 trackerInstNumber,
    T_srvOscillatorType *oscillatorType );
```

#### DESCRIPTION

Set the oscillator type.

#### ARGUMENTS

##### INPUTS

stackInstNumber – stack instance number  
 trackerInstNumber – tracker instance number  
 oscillatorType – oscillator type, see T\_srvOscillatorType

##### OUTPUT

None

#### RETURN

E\_cmnErrorCode\_OK – On success, else another T\_cmnErrorCode

### 3.6.19. mngApi\_ReferenceTracker\_GetPdvThreshold (deprecated)

```
T_cmnErrorCode mngApi_ReferenceTracker_GetPdvThreshold(
    T_osUInt16 stackInstNumber,
    T_srvPdvValues *pdvThreshold );
```

#### DESCRIPTION

Get the PDV threshold.

This parameter is used to determine PTSF unusable based on the log variance of the PDV. If the log variance exceeds the PDV threshold, PTSF unusable is set.

#### ARGUMENTS

##### INPUTS

stackInstNumber – stack instance number

##### OUTPUT

pdvThreshold – See T\_srvPdvValues, log variance range is {-100 - 0}

#### RETURN

E\_cmnErrorCode\_OK – On success, else another T\_cmnErrorCode

### 3.6.20. mngApi\_RT\_GetPdvThreshold

```
T_cmnErrorCode mngApi_RT_GetPdvThreshold(
    T_osUInt16 stackInstNumber,
    T_osUInt16 trackerInstNumber,
    T_srvPdvValues *pdvThreshold );
```

#### DESCRIPTION

Get the PDV threshold.

This parameter is used to determine PTSF unusable based on the log variance of the PDV. If the log variance exceeds the PDV threshold, PTSF unusable is set.

**ARGUMENTS****INPUTS**

stackInstNumber – stack instance number  
trackerInstNumber – tracker instance number

**OUTPUT**

pdvThreshold – See T\_srvPdvValues, log variance range is {-100 – 0}

**RETURN**

E\_cmnErrorCode\_OK – On success, else another T\_cmnErrorCode

**3.6.21. mngApi\_ReferenceTracker\_SetPdvThreshold (deprecated)**

```
T_cmnErrorCode mngApi_ReferenceTracker_SetPdvThreshold(  
    T_osUInt16 stackInstNumber,  
    T_srvPdvValues *pdvThreshold );
```

**DESCRIPTION**

Set the PDV threshold.  
This parameter is used to determine PTSF unusable based on the log variance of the PDV. If the log variance exceeds the PDV threshold, PTSF unusable is set.

**ARGUMENTS****INPUTS**

stackInstNumber – stack instance number  
pdvThreshold – See T\_srvPdvValues, log variance range is {-100 – 0}

**OUTPUT**

None

**RETURN**

E\_cmnErrorCode\_OK – On success, else another T\_cmnErrorCode

**3.6.22. mngApi\_RT\_SetPdvThreshold**

```
T_cmnErrorCode mngApi_RT_SetPdvThreshold(  
    T_osUInt16 stackInstNumber,  
    T_osUInt16 trackerInstNumber,  
    T_srvPdvValues *pdvThreshold );
```

**DESCRIPTION**

Set the PDV threshold.  
This parameter is used to determine PTSF unusable based on the log variance of the PDV. If the log variance exceeds the PDV threshold, PTSF unusable is set.

**ARGUMENTS****INPUTS**

stackInstNumber – stack instance number  
trackerInstNumber – tracker instance number  
pdvThreshold – See T\_srvPdvValues, log variance range is {-100 – 0}

**OUTPUT**

None

**RETURN**

E\_cmnErrorCode\_OK – On success, else another T\_cmnErrorCode

**3.6.23. mngApi\_ReferenceTracker\_GetPdvThresholdExceededHysteresis (deprecated)**

```
T_cmnErrorCode mngApi_ReferenceTracker_GetPdvThresholdExceededHysteresis(  
    T_osUInt16 stackInstNumber,  
    T_srvPdvValues *pdvThreshold );
```

**DESCRIPTION**

Get the PDV threshold hysteresis.

Once the PDV threshold is exceeded and PTSF is declared unusable, the PDV log variance must cross below the PDV Threshold minus this value.

**ARGUMENTS****INPUTS**

stackInstNumber – stack instance number

**OUTPUT**

pdvThreshold – See T\_srvPdvValues, log variance range is {0 – 10}

**RETURN**

E\_cmnErrorCode\_OK – On success, else another T\_cmnErrorCode

**3.6.24. mngApi\_RT\_GetPdvThresholdExceededHysteresis**

```
T_cmnErrorCode mngApi_RT_GetPdvThresholdExceededHysteresis(  
    T_osUInt16 stackInstNumber,  
    T_osUInt16 trackerInstNumber,  
    T_srvPdvValues *pdvThreshold );
```

**DESCRIPTION**

Get the PDV threshold hysteresis.

Once the PDV threshold is exceeded and PTSF is declared unusable, the PDV log variance must cross below the PDV Threshold minus this value.

**ARGUMENTS****INPUTS**

stackInstNumber – stack instance number

trackerInstNumber – tracker instance number

**OUTPUT**

pdvThreshold – See T\_srvPdvValues, log variance range is {0 – 10}

**RETURN**

E\_cmnErrorCode\_OK – On success, else another T\_cmnErrorCode

**3.6.25. mngApi\_ReferenceTracker\_SetPdvThresholdExceededHysteresis (deprecated)**

```
T_cmnErrorCode mngApi_ReferenceTracker_SetPdvThresholdExceededHysteresis(  
    T_osUInt16 stackInstNumber,  
    T_srvPdvValues *pdvThreshold );
```

**DESCRIPTION**

Set the PDV threshold hysteresis.  
Once the PDV threshold is exceeded and PTSF is declared unusable, the PDV log variance must cross below the PDV Threshold minus this value.

**ARGUMENTS****INPUTS**

stackInstNumber – stack instance number  
pdvThreshold – See T\_srvPdvValues, log variance range is {0 – 10}

**OUTPUT**

None

**RETURN**

E\_cmnrErrorcode\_OK – On success, else another T\_cmnrErrorcode

**3.6.26. mngApi\_RT\_SetPdvThresholdExceededHysteresis**

```
T_cmnrErrorcode mngApi_RT_SetPdvThresholdExceededHysteresis(  
    T_osUin16 stackInstNumber,  
    T_osUin16 trackerInstNumber,  
    T_srvPdvValues *pdvThreshold );
```

**DESCRIPTION**

Set the PDV threshold hysteresis.  
Once the PDV threshold is exceeded and PTSF is declared unusable, the PDV log variance must cross below the PDV Threshold minus this value.

**ARGUMENTS****INPUTS**

stackInstNumber – stack instance number  
trackerInstNumber – tracker instance number  
pdvThreshold – See T\_srvPdvValues, log variance range is {0 – 10}

**OUTPUT**

None

**RETURN**

E\_cmnrErrorcode\_OK – On success, else another T\_cmnrErrorcode

**3.6.27. mngApi\_ReferenceTracker\_GetStationarityMeasure1LowerBound (deprecated)**

```
T_cmnrErrorcode mngApi_ReferenceTracker_GetStationarityMeasure1LowerBound(  
    T_osUin16 stackInstNumber,  
    T_osDouble *boundary );
```

**DESCRIPTION**

Get the Stationarity Measure 1 Lower bound value

**ARGUMENTS****INPUTS**

stackInstNumber – stack instance number

**OUTPUT**

boundary – {0.00, 1.00}, default 0.60

**RETURN**

E\_cmnErrorCode\_OK – On success, else another T\_cmnErrorCode

**3.6.28. mngApi\_RT\_GetStationarityMeasure1LowerBound**

```
T_cmnErrorCode mngApi_RT_GetStationarityMeasure1LowerBound(  
    T_osUInt16 stackInstNumber,  
    T_osUInt16 trackerInstNumber,  
    T_osDouble *boundary );
```

**DESCRIPTION**

Get the Stationarity Measure 1 Lower bound value

**ARGUMENTS****INPUTS**

stackInstNumber – stack instance number

trackerInstNumber – tracker instance number

**OUTPUT**

boundary – {0.00, 1.00}, default 0.60

**RETURN**

E\_cmnErrorCode\_OK – On success, else another T\_cmnErrorCode

**3.6.29. mngApi\_ReferenceTracker\_SetStationarityMeasure1LowerBound (deprecated)**

```
T_cmnErrorCode mngApi_ReferenceTracker_SetStationarityMeasure1LowerBound(  
    T_osUInt16 stackInstNumber,  
    T_osDouble *boundary );
```

**DESCRIPTION**

Set the Stationarity Measure 1 Lower bound value

The stationarity measure 1 lower and upper are bounds of the ratio of the PDV's second order statistics on the first half observation window and the second half observation window. For ideal stationary case, the stationarity measure 1 should be close to 1.

**ARGUMENTS****INPUTS**

stackInstNumber – stack instance number

boundary – {0.00, 1.00}, default 0.60

**OUTPUT**

None

**RETURN**

E\_cmnErrorCode\_OK – On success, else another T\_cmnErrorCode

### 3.6.30. mngApi\_RT\_SetStationarityMeasure1LowerBound

```
T_cmnErrorCode mngApi_RT_SetStationarityMeasure1LowerBound(
    T_osUInt16 stackInstNumber,
    T_osUInt16 trackerInstNumber,
    T_osDouble *boundary );
```

#### DESCRIPTION

Set the Stationarity Measure 1 Lower bound value

The stationarity measure 1 lower and upper are bounds of the ratio of the PDV's second order statistics on the first half observation window and the second half observation window. For ideal stationary case, the stationarity measure 1 should be close to 1.

#### ARGUMENTS

##### INPUTS

stackInstNumber – stack instance number  
 trackerInstNumber – tracker instance number  
 boundary – {0.00, 1.00}, default 0.60

##### OUTPUT

None

#### RETURN

E\_cmnErrorCode\_OK – On success, else another T\_cmnErrorCode

### 3.6.31. mngApi\_ReferenceTracker\_GetStationarityMeasure1UpperBound (deprecated)

```
T_cmnErrorCode mngApi_ReferenceTracker_GetStationarityMeasure1UpperBound(
    T_osUInt16 stackInstNumber,
    T_osDouble *boundary );
```

#### DESCRIPTION

Get the Stationarity Measure 1 Upper bound value

#### ARGUMENTS

##### INPUTS

stackInstNumber – stack instance number

##### OUTPUT

boundary – {1.00, 1000.00}, default 1.67

#### RETURN

E\_cmnErrorCode\_OK – On success, else another T\_cmnErrorCode

### 3.6.32. mngApi\_RT\_GetStationarityMeasure1UpperBound

```
T_cmnErrorCode mngApi_RT_GetStationarityMeasure1UpperBound(
    T_osUInt16 stackInstNumber,
    T_osUInt16 trackerInstNumber,
    T_osDouble *boundary );
```

#### DESCRIPTION

Get the Stationarity Measure 1 Upper bound value

**ARGUMENTS****INPUTS**

stackInstNumber – stack instance number  
trackerInstNumber – tracker instance number

**OUTPUT**

boundary – {1.00, 1000.00}, default 1.67

**RETURN**

E\_cmnErrorCode\_OK – On success, else another T\_cmnErrorCode

**3.6.33. mngApi\_ReferenceTracker\_SetStationarityMeasure1UpperBound (deprecated)**

```
T_cmnErrorCode mngApi_ReferenceTracker_SetStationarityMeasure1UpperBound(  
    T_osUInt16 stackInstNumber,  
    T_osDouble *boundary );
```

**DESCRIPTION**

Set the Stationarity Measure 1 Upper bound value

The stationarity measure 1 lower and upper are bounds of the ratio of the PDV's second order statistics on the first half observation window and the second half observation window. For ideal stationary case, the stationarity measure 1 should be close to 1.

**ARGUMENTS****INPUTS**

stackInstNumber – stack instance number  
boundary – {1.00, 1000.00}, default 1.67

**OUTPUT**

None

**RETURN**

E\_cmnErrorCode\_OK – On success, else another T\_cmnErrorCode

**3.6.34. mngApi\_RT\_SetStationarityMeasure1UpperBound**

```
T_cmnErrorCode mngApi_RT_SetStationarityMeasure1UpperBound(  
    T_osUInt16 stackInstNumber,  
    T_osUInt16 trackerInstNumber,  
    T_osDouble *boundary );
```

**DESCRIPTION**

Set the Stationarity Measure 1 Upper bound value

The stationarity measure 1 lower and upper are bounds of the ratio of the PDV's second order statistics on the first half observation window and the second half observation window. For ideal stationary case, the stationarity measure 1 should be close to 1.

**ARGUMENTS****INPUTS**

stackInstNumber – stack instance number  
trackerInstNumber – tracker instance number  
boundary – {1.00, 1000.00}, default 1.67

**OUTPUT**

None

**RETURN**

E\_cmnrErrorcode\_OK – On success, else another T\_cmnrErrorcode

**3.6.35. mngApi\_ReferenceTracker\_GetWillCorrectFrequencyAtFirstSnap (deprecated)**

```
T_cmnrErrorcode mngApi_ReferenceTracker_GetWillCorrectFrequencyAtFirstSnap(  
    T_osUin16 stackInstNumber,  
    T_osBool *willCorrect );
```

**DESCRIPTION**

This parameter configures the frequency correction after REA servo performs the first time snap. If the network condition is good, in other words, very little PDV, the accuracy of the first coarse time of day estimation and the LO frequency offset estimation could be good enough and a frequency correction can be performed. On the other hand, if the PDV is large, the initial coarse frequency estimation could have a very large error, thus the frequency correction is preferred to not be made after the first snap

**ARGUMENTS****INPUTS**

stackInstNumber – stack instance number

**OUTPUT**

willCorrect – E\_osTrue or E\_osFalse

**RETURN**

E\_cmnrErrorcode\_OK – On success, else another T\_cmnrErrorcode

**3.6.36. mngApi\_RT\_GetWillCorrectFrequencyAtFirstSnap**

```
T_cmnrErrorcode mngApi_RT_GetWillCorrectFrequencyAtFirstSnap(  
    T_osUin16 stackInstNumber,  
    T_osUin16 trackerInstNumber,  
    T_osBool *willCorrect );
```

**DESCRIPTION**

This parameter configures the frequency correction after REA servo performs the first time snap. If the network condition is good, in other words, very little PDV, the accuracy of the first coarse time of day estimation and the LO frequency offset estimation could be good enough and a frequency correction can be performed. On the other hand, if the PDV is large, the initial coarse frequency estimation could have a very large error, thus the frequency correction is preferred to not be made after the first snap.

**ARGUMENTS****INPUTS**

stackInstNumber – stack instance number

trackerInstNumber – tracker instance number

**OUTPUT**

willCorrect – E\_osTrue or E\_osFalse

**RETURN**

E\_cmnrErrorcode\_OK – On success, else another T\_cmnrErrorcode

### 3.6.37. mngApi\_ReferenceTracker\_SetWillCorrectFrequencyAtFirstSnap (deprecated)

```
T_cmnErrorCode mngApi_ReferenceTracker_SetWillCorrectFrequencyAtFirstSnap(  
    T_osUInt16 stackInstNumber,  
    T_osBool *willCorrect );
```

#### DESCRIPTION

This parameter configures the frequency correction after REA servo performs the first time snap. If the network condition is good, in other words, very little PDV, the accuracy of the first coarse time of day estimation and the LO frequency offset estimation could be good enough and a frequency correction can be performed. On the other hand, if the PDV is large, the initial coarse frequency estimation could have a very large error, thus the frequency correction is preferred to not be made after the first snap.

#### ARGUMENTS

##### INPUTS

stackInstNumber – stack instance number  
willCorrect – E\_osTrue or E\_osFalse

##### OUTPUT

None

#### RETURN

E\_cmnErrorCode\_OK – On success, else another T\_cmnErrorCode

### 3.6.38. mngApi\_RT\_SetWillCorrectFrequencyAtFirstSnap

```
T_cmnErrorCode mngApi_RT_SetWillCorrectFrequencyAtFirstSnap(  
    T_osUInt16 stackInstNumber,  
    T_osUInt16 trackerInstNumber,  
    T_osBool *willCorrect );
```

#### DESCRIPTION

This parameter configures the frequency correction after REA servo performs the first time snap. If the network condition is good, in other words, very little PDV, the accuracy of the first coarse time of day estimation and the LO frequency offset estimation could be good enough and a frequency correction can be performed. On the other hand, if the PDV is large, the initial coarse frequency estimation could have a very large error, thus the frequency correction is preferred to not be made after the first snap.

#### ARGUMENTS

##### INPUTS

stackInstNumber – stack instance number  
trackerInstNumber – tracker instance number  
willCorrect – E\_osTrue or E\_osFalse

##### OUTPUT

None

#### RETURN

E\_cmnErrorCode\_OK – On success, else another T\_cmnErrorCode

### 3.6.39. mngApi\_ReferenceTracker\_GetFfoSlopeLimitPpbPerSecond (deprecated)

```
T_cmnErrorCode mngApi_ReferenceTracker_GetFfoSlopeLimitPpbPerSecond(  
    T_osUInt16 stackInstNumber,  
    T_osDouble *ffoSlopeLimitPpbPerSecond );
```

#### DESCRIPTION

Get the FFO slope limit, measured in parts per billion per second, used during frequency lock and time locked state.

#### ARGUMENTS

##### INPUTS

stackInstNumber – stack instance number

##### OUTPUT

ffoSlopeLimitPpbPerSecond – {0, 100,000}, default -1

#### RETURN

E\_cmnErrorCode\_OK – On success, else another T\_cmnErrorCode

### 3.6.40. mngApi\_RT\_GetFfoSlopeLimitPpbPerSecond

```
T_cmnErrorCode mngApi_RT_GetFfoSlopeLimitPpbPerSecond(  
    T_osUInt16 stackInstNumber,  
    T_osUInt16 trackerInstNumber,  
    T_osDouble *ffoSlopeLimitPpbPerSecond );
```

#### DESCRIPTION

Get the FFO slope limit, measured in parts per billion per second, used during frequency lock and time locked state.

#### ARGUMENTS

##### INPUTS

stackInstNumber – stack instance number

trackerInstNumber – tracker instance number

##### OUTPUT

ffoSlopeLimitPpbPerSecond – {0, 100,000}, default -1

#### RETURN

E\_cmnErrorCode\_OK – On success, else another T\_cmnErrorCode

### 3.6.41. mngApi\_ReferenceTracker\_SetFfoSlopeLimitPpbPerSecond (deprecated)

```
T_cmnErrorCode mngApi_ReferenceTracker_SetFfoSlopeLimitPpbPerSecond(  
    T_osUInt16 stackInstNumber,  
    T_osDouble *ffoSlopeLimitPpbPerSecond );
```

#### DESCRIPTION

Set the FFO slope limit, measured in parts per billion per second, used during frequency lock and time locked state.

#### ARGUMENTS

##### INPUTS

stackInstNumber – stack instance number  
ffoSlopeLimitPpbPerSecond – {0, 100,000}, default -1

##### OUTPUT

None

#### RETURN

E\_cmnErrorCode\_OK – On success, else another T\_cmnErrorCode

### 3.6.42. mngApi\_RT\_SetFfoSlopeLimitPpbPerSecond

```
T_cmnErrorCode mngApi_RT_SetFfoSlopeLimitPpbPerSecond(  
    T_osUInt16 stackInstNumber,  
    T_osUInt16 trackerInstNumber,  
    T_osDouble *ffoSlopeLimitPpbPerSecond );
```

#### DESCRIPTION

Set the FFO slope limit, measured in parts per billion per second, used during frequency lock and time locked state.

#### ARGUMENTS

##### INPUTS

stackInstNumber – stack instance number  
trackerInstNumber – tracker instance number  
ffoSlopeLimitPpbPerSecond – {0, 100,000}, default -1

##### OUTPUT

None

#### RETURN

E\_cmnErrorCode\_OK – On success, else another T\_cmnErrorCode

## 4. Revision History

| Revision | Date         | Description                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        |
|----------|--------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 1.02     | Oct 24, 2024 | Updated software release number to 4.3.2.417904 from 4.3.2.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        |
| 1.01     | Oct 15, 2024 | <p>Supports software release 4.3.2.</p> <ul style="list-style-type: none"><li>▪ Added APIs:<ul style="list-style-type: none"><li>• mngApi_GetPhysicalPIIWaitToRestoreTimeoutValue</li><li>• mngApi_SetPhysicalPIIWaitToRestoreTimeoutValue</li><li>• mngApi_ReferenceTracker_GetFfoSlopeLimitPpbPerSecond</li><li>• mngApi_ReferenceTracker_SetFfoSlopeLimitPpbPerSecond</li><li>• mngApi_GetEpochTimeSeconds</li><li>• mngApi_SetEpochTimeSeconds</li></ul></li><li>▪ Removed APIs:<ul style="list-style-type: none"><li>• mngApi_GetHoldoverEnable</li><li>• mngApi_SetHoldoverEnable</li></ul></li><li>▪ Updated definition of T_srvOscillatorType enumeration<ul style="list-style-type: none"><li>• New enumeration E_srvDocxo replaced E_srvSyncE</li></ul></li><li>▪ Update function prototypes of Reference tracker management API functions<ul style="list-style-type: none"><li>• New additional input parameter trackerInstNumber</li></ul></li><li>▪ Add T_mngApiLoLockStatus and T_srvLoStateld enumeration</li></ul> |
| 1.00     | Jun 21, 2021 | Initial release. Supports software release 4.1.0.77765.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            |

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