

RX62T

MTU3 Complementary PWM Mode

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Introduction

The RX62T Group has on-chip Multi-Function Timer Pulse Unit 3 (MTU3), which comprises eight 16-bit timer channels.

Target Device

RX62T

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1. Specification

- Comprises eight 16-bit channels
- Operating frequency is 8 to100 MHz
- [Channels 0 to 4, 6, and 7]
- Waveform output on compare match
- Input capture function
- Counter-clearing operation
- Simultaneous writing to multiple timer counters (TCNT)
- Simultaneous clearing on compare match or input capture
- Simultaneous input and output to registers in synchronization with counter operations
- Up to 12-phase PWM output in combination with synchronous operation
- [Channels 0, 3, 4, 6, and 7]
- Buffer operation specifiable
- [Channels 3, 4, 6, and 7]
- Through interlocked operation of channels 3 and 4 or 6 and 7, output of positive and negative signals in six phases (for a total of 12 phases) in Complementary -PWM and reset-PWM operation
- In Complementary PWM mode, transfer of values from buffer registers to temporary registers on peaks and troughs of the timer-counter values or writing to the buffer registers (MTU3_4.TGRD and MTU3_7.TGRD)
- Double-buffering selectable in Complementary PWM mode
- [Channels 3 and 4]
- Through interlocking with channel 0, a mode for driving AC synchronous motors (brushless DC motors) by using Complementary PWM output and reset PWM output is settable and allows the selection of two types of waveform output (chopping or level)
- [Channels 1 and 2]
- Independently specifiable phase-counting mode
- Capable of cascade-connected operation
- [Channel 5]
- Capable of operation as a dead-time compensation counter

Figure 1-1 is the block diagram of Multi-Function Timer Pulse Unit 3 (MTU3).

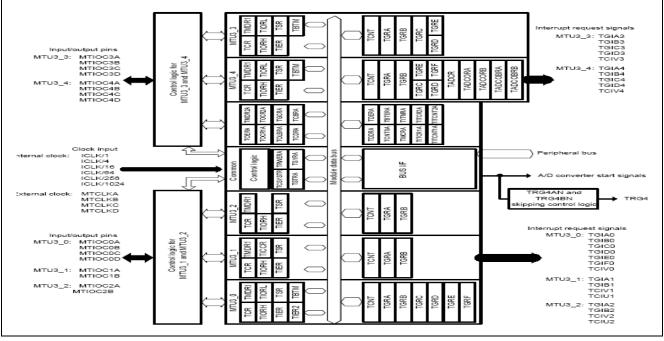


Figure 1-1 Block diagram for MTU3



Table 1-1 Specifications of Multi-Function Timer Pulse Unit 3 (MTU3) Register

<u>г</u>	
TSTR	Timer start register
TOERA	Timer output master enable register A
TGCRA	Timer gate control register A
TOCR1A	Timer output control register 1A
TOCR2A	Timer output control register 2A
TCDRA	Timer cycle data register A
TDDRA	Timer dead time data register A
TCNTSA	Timer subcounter A
TCBRA	Timer cycle buffer register A
TITCR1A	Timer interrupt skipping set register 1A
TITCR2A	Timer interrupt skipping set register 2A
TITCNT1A	Timer interrupt skipping counter 1A
TITCNT2A	Timer interrupt skipping counter 2A
TBTERA	Timer buffer transfer set register A
TOLBRA	Timer output level buffer register A
TCR	Timer control register
TMDR1	Timer mode register 1
TMDR2A	Timer mode register 2A
TIORH	Timer I/O control register H
TIORL	Timer I/O control register L
TIER	Timer interrupt enable register
TCNT	Timer counter
TGRA	Timer general register A
TGRB	Timer general register B
TGRC	Timer general register C
TGRD	Timer general register D
TGRE	Timer general register E
TGRF	Timer general register F
TSR	Timer status register
TDERA	Timer dead time enable register A
ТВТМ	Timer buffer operation transfer mode register
TADCR	Timer A/D converter start request control register
TADCORA	Timer A/D converter start request cycle set register A
TADCORB	Timer A/D converter start request cycle set register B
TADCOBRA	Timer A/D converter start request cycle set buffer register A
TADCOBRB	Timer A/D converter start request cycle set buffer register B



2. Multi-Function Timer Pulse Unit 3 for Complementary PWM Mode

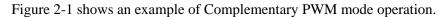
2.1 Example of Complementary PWM mode operation

In Complementary PWM mode, three phases of non-overlapping positive and negative PWM waveforms (six phases in total) can be output by combining channels 3 and 4 and channels 6 and 7. PWM waveforms without non-overlapping interval are also available.

In Complementary PWM mode, MTIOC3B, MTIOC3D, MTIOC4A, MTIOC4B, MTIOC4C, MTIOC4D, MTIOC6B, MTIOC6D, MTIOC7A, MTIOC7B, MTIOC7C, and MTIOC7D pins function as PWM output pins, and the MTIOC3A and MTIOC6A pins can be set for toggle output synchronized with the PWM cycle.

MTU3_3.TCNT, MTU3_4.TCNT, MTU3_6.TCNT, and MTU3_7.TCNT function as up/down-counters.

A function to directly cut off the PWM output by using an external signal is supported as a port function.



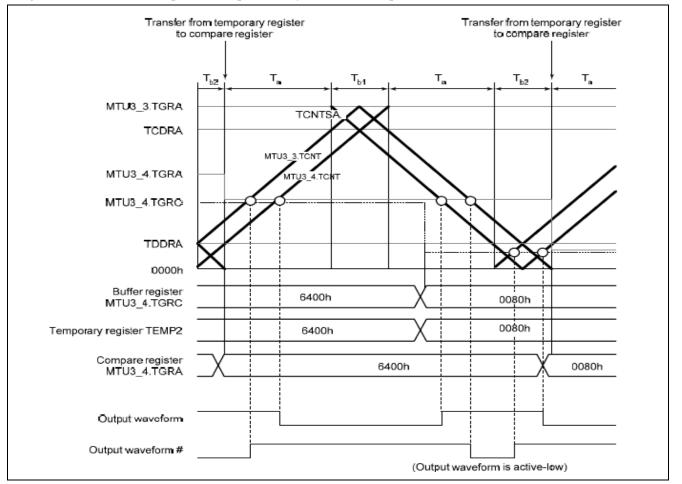


Figure 2-1 Example of Complementary PWM mode operation



2.2 Example of Procedure for Setting Complementary PWM Mode

Figure 2-2 shows an example of the procedure for setting Complementary PWM mode.

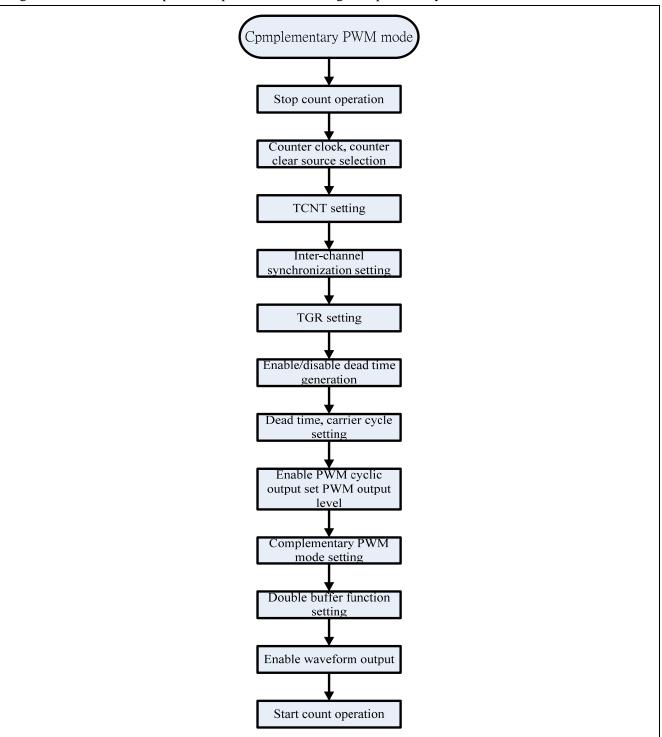


Figure 2-2 Example of Procedure for Setting Complementary PWM Mode



3. Multi-Function Timer Pulse Unit 3 Software Register Setting

Timer Control Register (TCR):

TCR controls the TCNT operation for each channel. The MTU3 has a total of ten TCR registers, one each for channels 0 to 4, 6, and 7. TCR values should be specified only while TCNT operation is stopped.

				CKEG[1:0]			TPSC[2:0]		3	
V	alue after reset:	0	0	0	0	0	0	0	0	
Bit	Symbol	Bit Name		Des	cription					R/W
b2 to b0	TPSC[2:0]	Time Prescaler	Select	See	tables 15.7 t	to 15.10.				R/W
b4, b3	CKEG[1:0]	Clock Edge Sel	lect	b4 b	3					R/W
				0 0:	Count at risi	ng edge				
				0 1:	Count at fall	ing edge				
				1 x:	Count at bot	h edges				
b7 to b5	CCLR[2:0]	Counter Clear		See	tables 15.5	and 15.6.				R/W
Legend]										
: Don't ca	are									

Figure 3-1 TCR Setting

Timer General Register (TGR):

TGR is a 16-bit readable/writable register.

TGRA, TGRB, TGRC, and TGRD function as either output compare or input capture registers. TGRC and TGRD for channels 0, 3, 4, 6, and 7 can also be designated for operation as buffer registers. TGR buffer register combinations are TGRA and TGRC, and TGRB and TGRD.

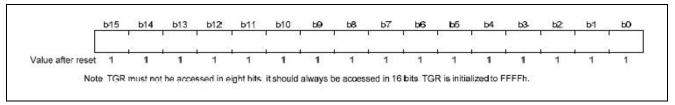


Figure 3-2 TGR Setting

Timer Dead Time Enable Registers (TDERA and TDERB):

TDERA and TDERB control dead time generation in Complementary PWM mode. The MTU3 has one TDER each for channel 3 and channel 6. TDERA and TDERB should be modified only while TCNT stops.



	_	b7	b6	b5	b4	b3	b2	b1	b0	
			-	-	-	-	- 1	-	-	TDER
V	alue after re	eset:	0	0	0	0	0	0	0	1
Bit	Symbol	Bit Name	e		Descrip	tion				R/W
Bit b0	Symbol TDER	1000-000-000-000-0	e ne Enable		the state of the	tion ad tim <mark>e is</mark> ge	enerated			
Bit		1000-000-000-000-0	Contraction of the local sectors of the local secto		0: No de					R/W



Timer Output Control Registers (TOCRA):

TOCR1A and TOCR1B enable or disable PWM-synchronized toggle output in Complementary PWM mode and reset-synchronized PWM mode, and control inversion of PWM output level.

		_	b7	b6	b5	b4	b3	b2	b1	bO	
		[—	PSYE	I	—	TOCL	TOCS	OLSN	OLSP	
Va	lue after re	eset	0	0	0	0	0 *	0	0	0	
Bit	Symbol	Note: Bit Nan	written	t can be set to ' to the bit.	Descrip	020	power-on re:	set. After 1 i	is written. O c	R/W	
bO	OLSP	Output Level Select P *2			See tabl	R/W					
b1	OLSN	Output Level Select N *2			See table 15.39.						
b2	TOCS	TOC Select			0: TOCF	R/W					
b3	TOCL	TOC Register Write Protection *1			CL TOC Register Write Protection *1 0: Write access to the TOCS, OLSN, and OLSP bits is enabled 1: Write access to the TOCS, OLSN, and OLSP bits is disabled						
	20 - 20 -	(Reserv	/ed)		These b	. R/W					
b5, b4		PWM Synchronous Output Enable			0: Toggle output is disabled						
	PSYE	PWM S	ynchronou	s Output Enable	o. roggi	e eacharte .					
b5, b4 b6	PSYE	PWM S	ynchronou	s Output Enable		e output is e				0.000	

Figure 3-4 TOCRA Setting

Timer Mode Register (TMDR):

TMDR1 specifies the operating mode of each channel. The MTU3 has a total of seven TMDR1 registers, one each for channels 0 to 4, 6, and 7. TMDR1 values should be specified only while TCNT operation is stopped.



		b7	b6	b5	ь4	Ь3	Ь2	b1	ьо	
Value after reset:		-		BFB	BFA		MD[3:0]		
		0	0	0	0	0	0	0	0	
Bit	Symbol	Bit Name		Descripti	on					R/W
b3 to b0	MD[3:0]	Mode Select	ode Select These bits specify the timer operating mode. See table 15.12 for details.							
b4	BFA	Buffer Operation	A	0: TGRA	and TGRC of	perate norma	ally			R/W
5				1: TGRA	and TGRC us	sed together	for buffer op	eration		
b5	BFB	Buffer Operation	B	0: TGRB	and TGRD of	perate norma	ally			R/W
		Str.		1: TGRB	and TGRD us	sed together	for buffer op	eration		
b6	BFE	Buffer Operation E 0: MTU3_0.TGRE and MTU3_0.TGRF operate normally							R/W	
				1: MTU3_	0.TGRE and	MTU3_0.TO	GRF used tog	ether for buf	fer	
				operati	on					
b7		(Reserved)		This bit is	always read	as 0. The w	rite value sho	ould be 0.		R/W

Figure 3-5 TMDR Setting

Timer Output Master Enable Register (TOER):

TOERA enables or disables output settings for output pins MTIOC4D, MTIOC4C, MTIOC3D, MTIOC4B, MTIOC4A, and MTIOC3B.

TOERB enables or disables output settings for output pins MTIOC7D, MTIOC7C, MTIOC6D, MTIOC7B, MTIOC7A, and MTIOC6B.

These pins do not output correctly if the TOER bits have not been set. In channels 3, 4, 6, and 7, set TOER prior to setting TIOR.

			b7	b6	b5	b4	b3	b2	b1	b0
					OE4D	OE4C	OE3D	OE4B	OE4A	OE3B
	Value after rese	t:	1	1	0	0	0	0	0	0
Bit	Symbol	Bit N	ame		Des	cription				R/W
00	OE3B	Maste	er Enable M	TIOC3B		TU3 output i TU3 output i				R/W
b1	OE4A	Maste	er Enable M	TIOC4A	0: MTU3 output is disabled * 1: MTU3 output is enabled					R/W
o2	OE4B	Master Enable MTIOC4B 0: MTU3 output is disabled * 1: MTU3 output is enabled					R/W			
03	OE3D	Master Enable MTIOC3D			0: MTU3 output is disabled * 1: MTU3 output is enabled					R/W
b 4	OE4C	Master Enable MTIOC4C			0: MTU3 output is disabled * 1: MTU3 output is enabled			R/W		
5	OE4D	Maste	er Enable M ⁻	TIOC4D		TU3 output i TU3 output i				R/W
b7, b6		(Rese	erved)		The	se bits are al	ways read as	s 1. The write	e value shoui	ld be 1. R/W

Figure 3-6 TOER Setting



4. Experiment Result

Fig. 4-1 to Fig. 4-3 the f_{sw} is 20 kHz, dead_time is 2 *us*. Fig. 4-1 is MTU3 for 25% duty; Fig. 4-2 is MTU3 for 50% duty; and Fig. 4-3 is MTU3 for 75% duty.

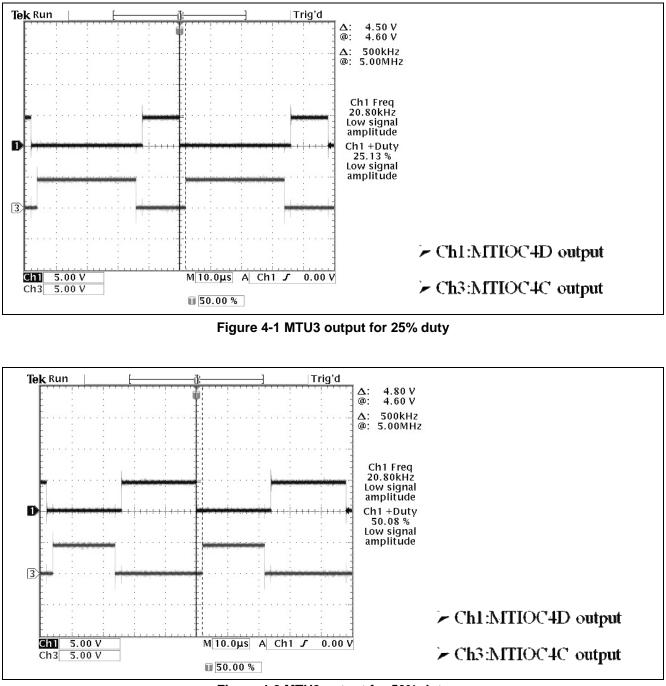


Figure 4-2 MTU3 output for 50% duty





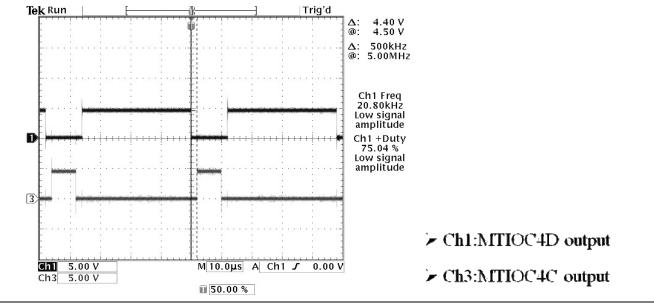


Figure 4-3 MTU3 output for 75% duty

5. Conclusion

From experimental result, we can use Multi-Function Timer Pulse Unit 3 for Complementary PWM control.

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Revision Record

		Descript	ion
Rev.	Date	Page	Summary
1.00	May. 10. 11	_	First edition issued
1.01	July.12.11		Document number was changed from R01AN0255 to R01AN0731

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- 2. Processing at Power-on

The state of the product is undefined at the moment when power is supplied.

- The states of internal circuits in the LSI are indeterminate and the states of register settings and pins are undefined at the moment when power is supplied.
 In a finished product where the reset signal is applied to the external reset pin, the states of pins are not guaranteed from the moment when power is supplied until the reset process is completed.
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