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**R8C/LA8A Group**

Timer RH Clock Error Correction Function in Real-Time Clock Mode

R01AN0095EJ0100

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**Abstract**

This document describes the setting method and an application example for a program to correct clock errors using the timer RH clock error correction function in real-time clock mode in the R8C/LA8A Group.

**Product**

MCU: R8C/LA8A Group

When using this application note with other Renesas MCUs, careful evaluation is recommended after making modifications to comply with the alternate MCU.

## Contents

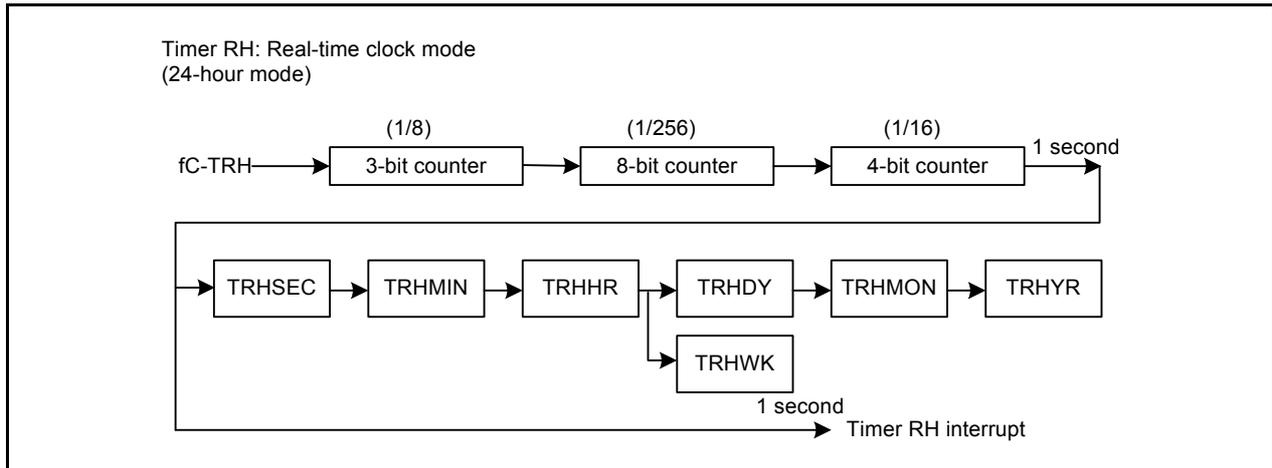
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# 1. Specifications

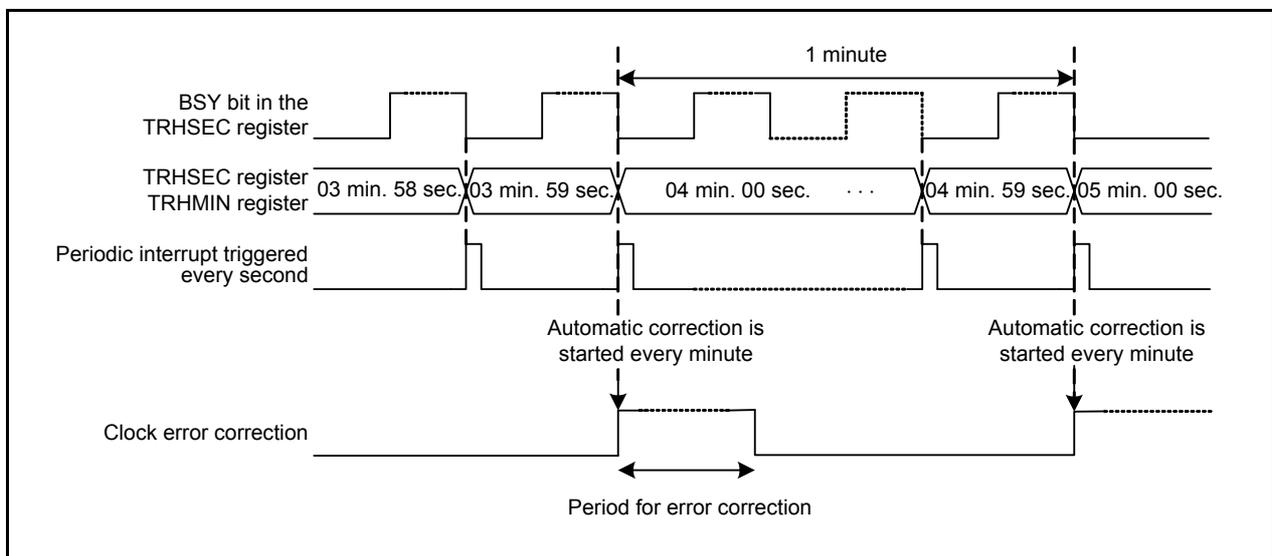
Second, minute, hour, day-of-the-week, date, month, and year (including leap years) data are updated every second. Clock errors generated by frequency deviations of oscillators are corrected every minute. Table 1.1 lists the Peripheral Function and Its Application. Figure 1.1 shows the Block Diagram. Figure 1.2 shows the Operating Example of Automatic Correction Function and Correction to the Minus Side.

**Table 1.1 Peripheral Function and Its Application**

Peripheral Function	Application
Timer RH	Clock (automatic correction function enabled)



**Figure 1.1 Block Diagram**



**Figure 1.2 Operating Example of Automatic Correction Function and Correction to the Minus Side**

## 2. Operation Confirmation Conditions

The sample code accompanying this application note has been run and confirmed under the conditions below.

**Table 2.1 Operation Confirmation Conditions**

Item	Contents
MCU used	R8C/LA8A Group
Operating frequencies	XIN clock: 20 MHz XCIN clock: 32.768 kHz CPU clock: 20 MHz System clock: 20 MHz
Operating voltage	5.0 V (2.7 to 5.5 V)
Integrated development environment	Renesas Electronics Corporation High-performance Embedded Workshop Version 4.07
C compiler	Renesas Electronics Corporation M16C Series, R8C Family C Compiler V.5.45 Release 01 Compile options -D__UART0__ -c -finfo -dir "\$(CONFIGDIR)" -R8C (Default setting is used in the integrated development environment.)

## 3. Software

### 3.1 Operation Overview

Use timer RH in real-time clock mode. Use a periodic interrupt triggered every second to obtain the second data (TRHSEC), minute data (TRHMIN), hour data (TRHHR), day-of-the-week data (TRHWK), date data (TRHDY), month data (TRHMON), and year data (TRHYR). The count starts from Saturday, January 1, 2011, 00:00:00 (initial value) with timer RH operating in 24-hour mode. When the count increments from December 31, 2099, 23:59:59, it becomes January 1, 2000, 00:00:00. fC-TRH frequency deviations are corrected using the clock error correction function (automatic correction) while the real-time clock operates. A +20 ppm error is assumed to be generated for oscillators used as fC-TRH.

#### Settings

- Use the XIN clock (20 MHz) for the CPU clock.
- Use fC-TRH (32.768 kHz) for the count source of timer RH.
- Select 24-hour mode.
- Use the timer RH interrupt (periodic interrupt triggered every second).
- Assume a +20 ppm error for fC-TRH.
- Perform automatic correction (correction to the minus side) every minute.
- Do not use the alarm function.

Figure 3.1 shows an Operating Example of the Real-Time Clock Using the Automatic Correction Function.

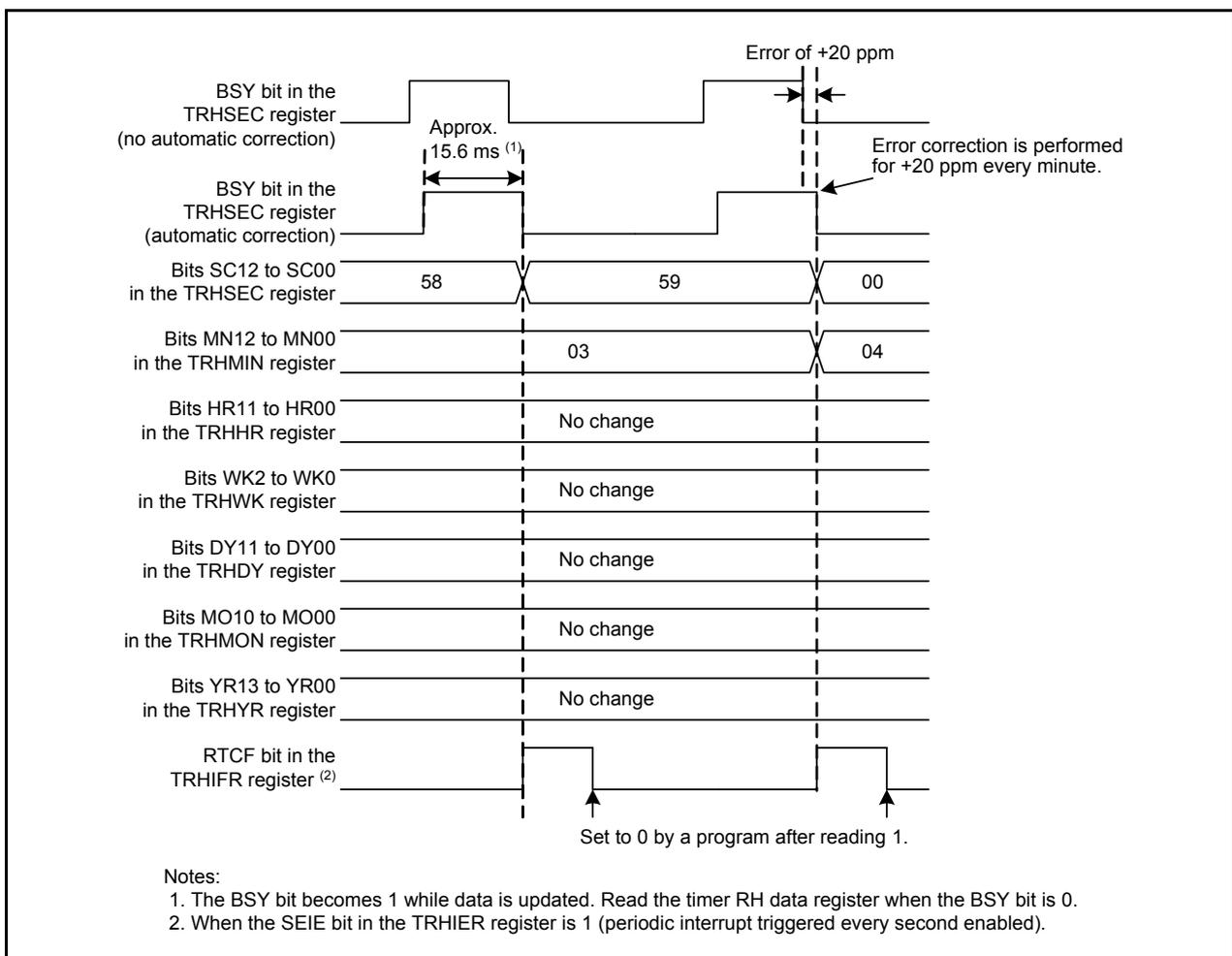


Figure 3.1 Operating Example of the Real-Time Clock Using the Automatic Correction Function

### 3.1.1 Automatic Correction Function

fC-TRH frequency deviations are corrected using the automatic correction function. 32.768 kHz and a +20 ppm for fC-TRH is assumed in this sample program. fC-TRH frequency deviations are corrected to the minus side. Automatic correction is performed every minute.

Settings for corrections are as follows:

- Oscillator frequency = 32.76865536 kHz
- Oscillator frequency error = 20 ppm
- Correction amount = (32.76865536 kHz - 32.768 kHz) × 60 seconds = 39.3216 ≈ 39

Figure 3.2 shows the Automatic Correction Outline.

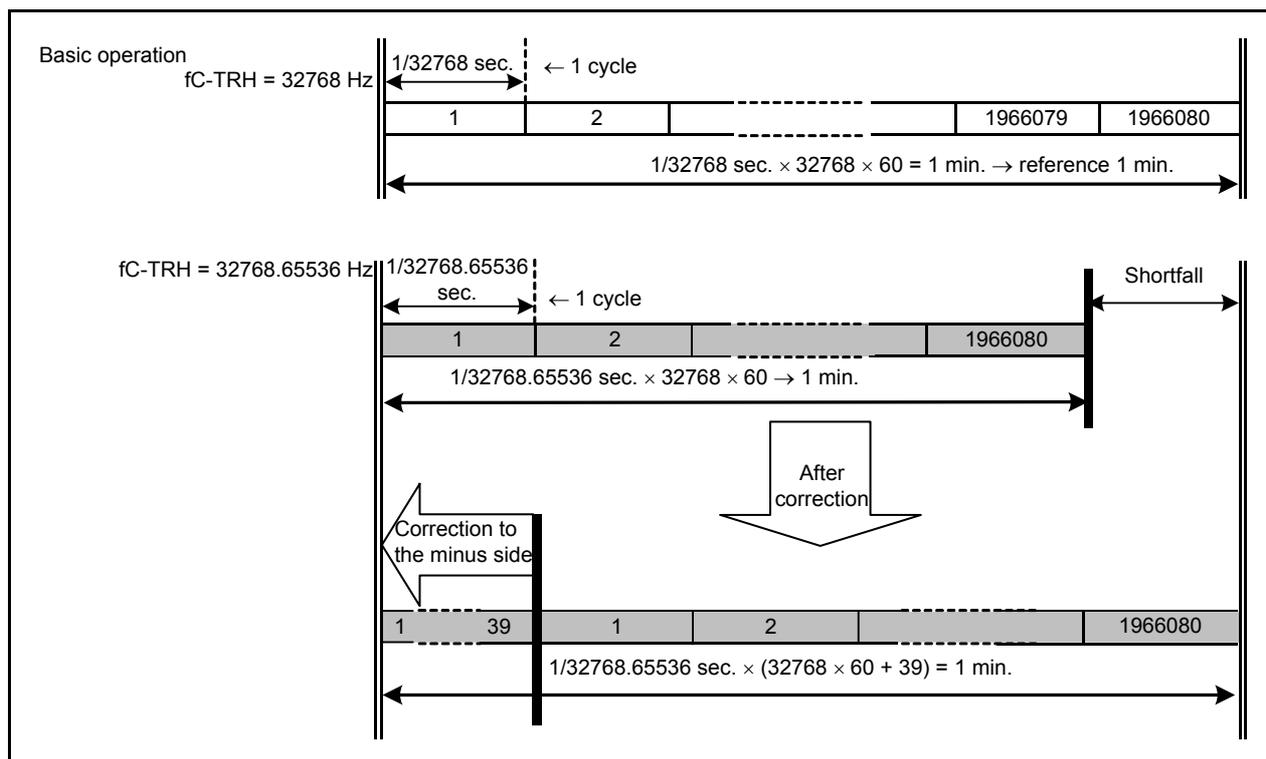


Figure 3.2 Automatic Correction Outline

### 3.2 Required Memory Size

Table 3.1 lists the Required Memory Size.

**Table 3.1 Required Memory Size**

Memory Used	Size	Remarks
ROM	292 bytes	In the r01an0095_src.c module
RAM	9 bytes	In the r01an0095_src.c module
Maximum user stack usage	10 bytes	
Maximum interrupt stack usage	4 bytes	

The required memory size varies depending on the C compiler version and compile options.

### 3.3 Variables

Table 3.2 lists the Global Variables,

**Table 3.2 Global Variables**

Type	Variable Name	Contents	Function Used
unsigned short	year	Year	timer_rh_init _timer_rh
unsigned char	month	Month	timer_rh_init _timer_rh
unsigned char	day	Date	timer_rh_init _timer_rh
enum	wk	Day of the week {Sun = 0, Mon, Tue, Wed, Thu, Fri, Sat}	timer_rh_init _timer_rh
unsigned char	hr	Hour	timer_rh_init _timer_rh
unsigned char	min	Minute	timer_rh_init _timer_rh
unsigned char	sec	Second	timer_rh_init _timer_rh

### 3.4 Functions

Table 3.3 lists the Functions.

**Table 3.3 Functions**

Function Name	Outline
mcu_init	System clock setting
timer_rh_init	Initial setting of timer RH
_timer_rh	Timer RH interrupt handling

### 3.5 Function Specifications

The following tables list the sample code function specifications.

mcu_init	
Outline	System clock setting
Header	None
Declaration	void mcu_init(void)
Explanation	Set the system clock.
Argument	None
Returned value	None
Remark	—

timer_rh_init	
Outline	Initial setting of timer RH
Header	None
Declaration	void timer_rh_init(void)
Explanation	Perform initial setting to use timer RH in real-time clock mode (automatic correction function enabled).
Argument	None
Returned value	None
Remark	—

_timer_rh	
Outline	Timer RH interrupt handling
Header	None
Declaration	void _timer_rh(void)
Explanation	Perform timer RH interrupt handling. Obtain the second, minute, hour, day-of-the-week, date, month, and year data.
Argument	None
Returned value	None
Remark	—

### 3.6 Flowcharts

#### 3.6.1 Main Processing

Figure 3.3 shows the Main Processing.

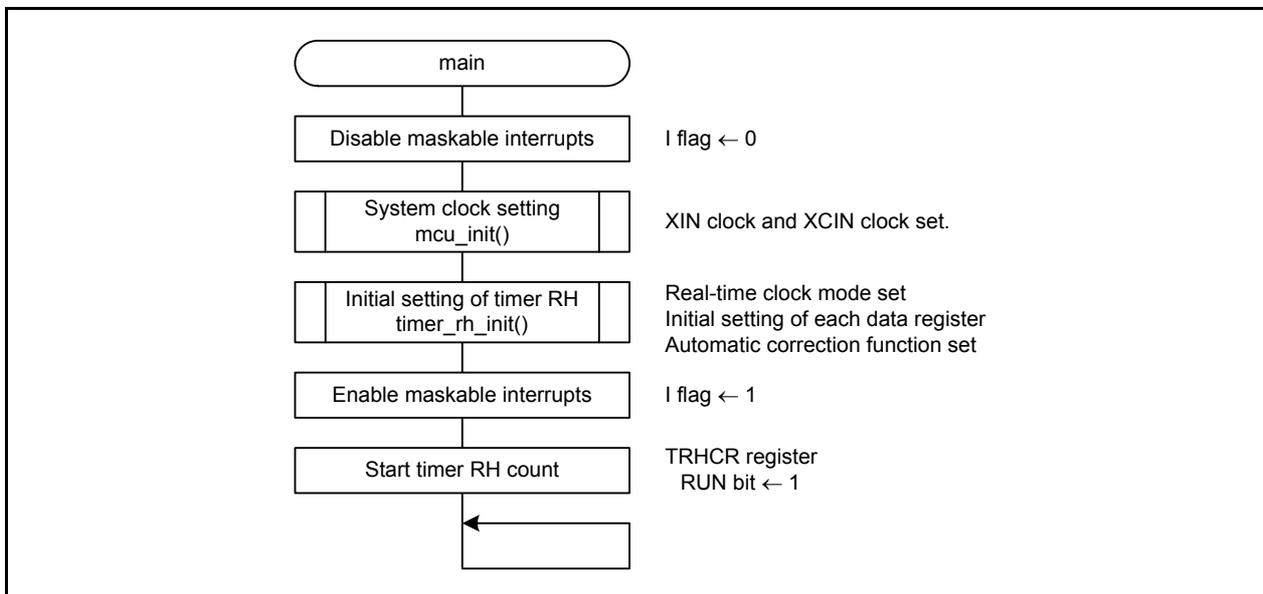


Figure 3.3 Main Processing

### 3.6.2 System Clock Setting

Figure 3.4 shows the System Clock Setting.

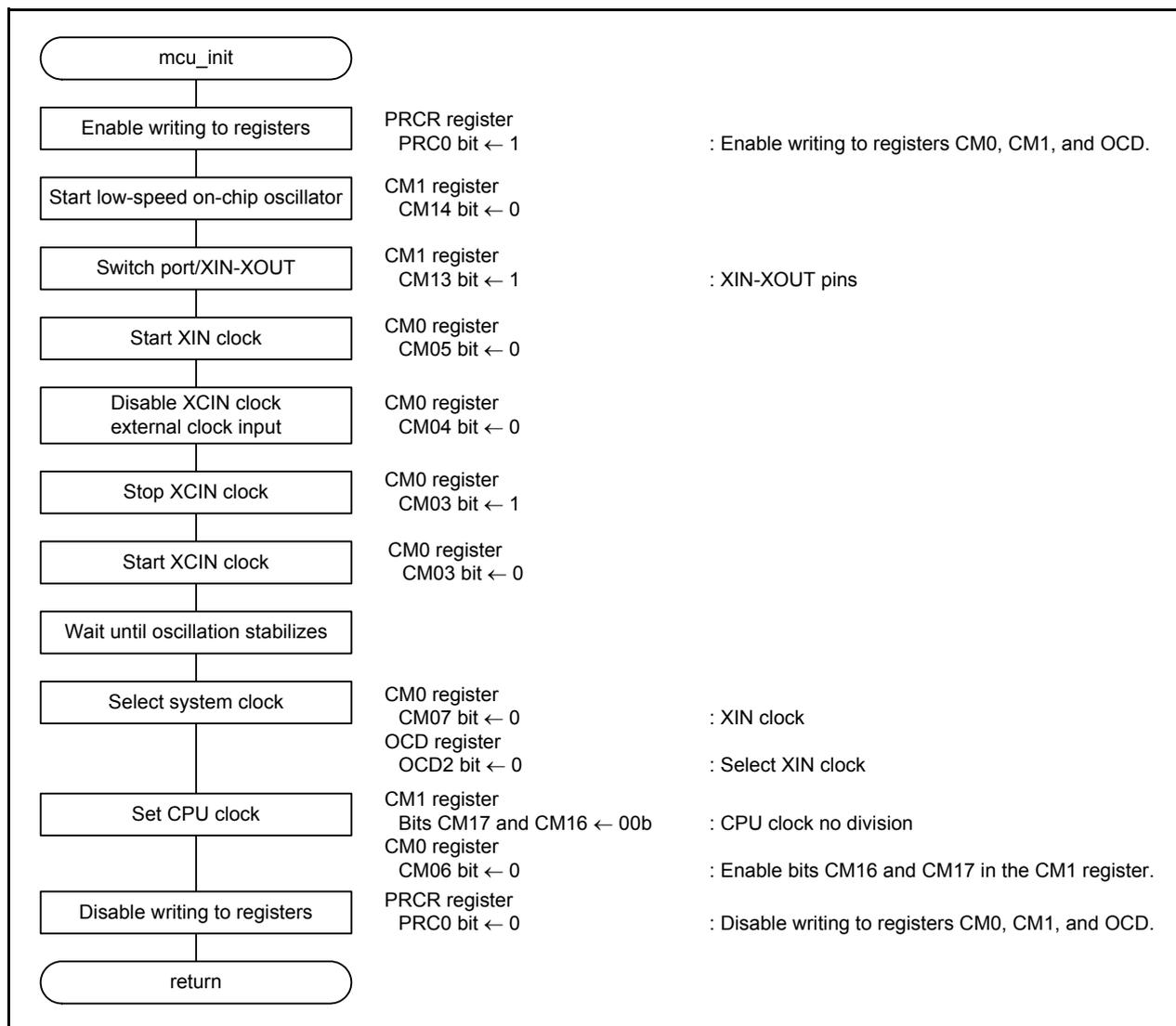


Figure 3.4 System Clock Setting

### 3.6.3 Initial Setting of Timer RH

Figure 3.5 shows the Initial Setting of Timer RH.

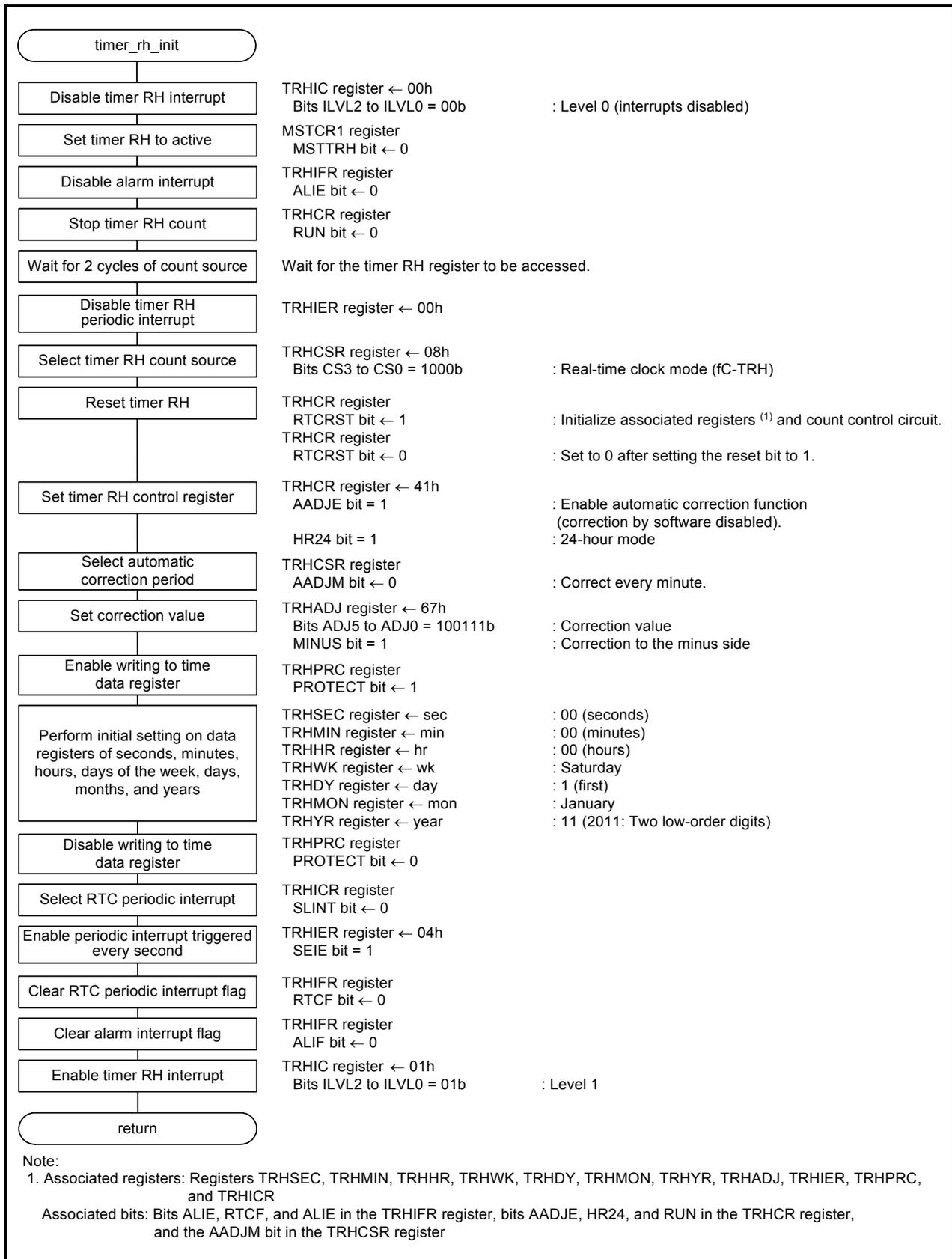


Figure 3.5 Initial Setting of Timer RH

### 3.6.4 Timer RH Interrupt Handling

Figure 3.6 shows the Timer RH Interrupt Handling.

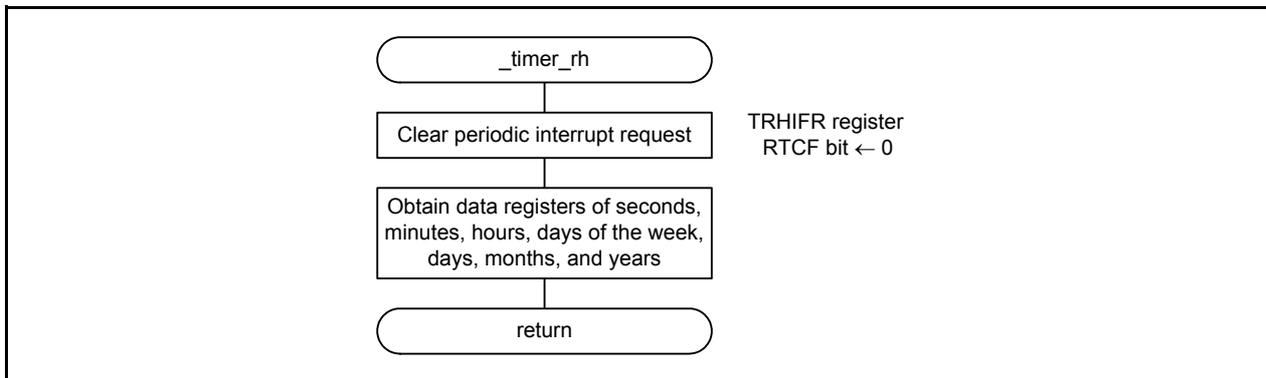


Figure 3.6 Timer RH Interrupt Handling

## 4. Sample Code

Sample code can be downloaded from the Renesas Electronics website.

## 5. Reference Documents

R8C/LA8A Group User's Manual: Hardware Rev.1.02

The latest version can be downloaded from the Renesas Electronics website.

Technical Update/Technical News

The latest information can be downloaded from the Renesas Electronics website.

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Revision History	<b>R8C/LA8A Group</b> <b>Timer RH Clock Error Correction Function in Real-Time Clock Mode</b>
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Rev.	Date	Description	
		Page	Summary
1.00	June 30, 2011	—	First edition issued

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## General Precautions in the Handling of MPU/MCU Products

The following usage notes are applicable to all MPU/MCU products from Renesas. For detailed usage notes on the products covered by this manual, refer to the relevant sections of the manual. If the descriptions under General Precautions in the Handling of MPU/MCU Products and in the body of the manual differ from each other, the description in the body of the manual takes precedence.

### 1. Handling of Unused Pins

Handle unused pins in accord with the directions given under Handling of Unused Pins in the manual.

- The input pins of CMOS products are generally in the high-impedance state. In operation with an unused pin in the open-circuit state, extra electromagnetic noise is induced in the vicinity of LSI, an associated shoot-through current flows internally, and malfunctions occur due to the false recognition of the pin state as an input signal become possible. Unused pins should be handled as described under Handling of Unused Pins in the manual.

### 2. Processing at Power-on

The state of the product is undefined at the moment when power is supplied.

- The states of internal circuits in the LSI are indeterminate and the states of register settings and pins are undefined at the moment when power is supplied.

In a finished product where the reset signal is applied to the external reset pin, the states of pins are not guaranteed from the moment when power is supplied until the reset process is completed.

In a similar way, the states of pins in a product that is reset by an on-chip power-on reset function are not guaranteed from the moment when power is supplied until the power reaches the level at which resetting has been specified.

### 3. Prohibition of Access to Reserved Addresses

Access to reserved addresses is prohibited.

- The reserved addresses are provided for the possible future expansion of functions. Do not access these addresses; the correct operation of LSI is not guaranteed if they are accessed.

### 4. Clock Signals

After applying a reset, only release the reset line after the operating clock signal has become stable. When switching the clock signal during program execution, wait until the target clock signal has stabilized.

- When the clock signal is generated with an external resonator (or from an external oscillator) during a reset, ensure that the reset line is only released after full stabilization of the clock signal. Moreover, when switching to a clock signal produced with an external resonator (or by an external oscillator) while program execution is in progress, wait until the target clock signal is stable.

### 5. Differences between Products

Before changing from one product to another, i.e. to one with a different part number, confirm that the change will not lead to problems.

- The characteristics of MPU/MCU in the same group but having different part numbers may differ because of the differences in internal memory capacity and layout pattern. When changing to products of different part numbers, implement a system-evaluation test for each of the products.

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