

# APPLICATION NOTE

### R32C/100 Series

Pulse-Width Measurement Using the Time Measurement Function of Intelligent I/O Groups 0 and 1  $\,$ 

R01AN0096EJ0100 Rev.1.00 Oct. 30, 2010

## 1. Abstract

This document describes pulse-width measurement using the time measurement function of intelligent I/O groups 0 and 1.

## 2. Introduction

The application example described in this document applies to the following microcomputers (MCUs):

MCUs: R32C/116 Group, R32C/117 Group, and R32C/118 Group

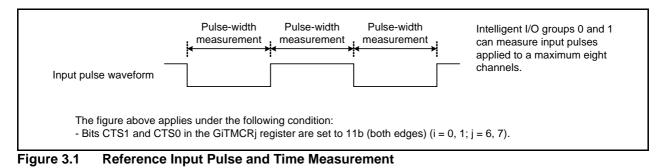
This application note can be used with other R32C/100 Series MCUs which have the same special function registers (SFRs) as the above groups. Check the manuals for any modifications to functions. Careful evaluation is recommended before using the program described in this application note.



## 3. Application Example

Intelligent I/O groups 0 and 1 each consist of one free-running 16-bit base timer and eight 16-bit registers (channels 0 to 7) for time measurement or waveform generation.

Figure 3.1 shows the Reference Input Pulse and Time Measurement.



This section describes how to measure a pulse input applied to the IIO0\_0 pin using time measurement channel 0. Other conditions are as follows:

- Select the time measurement trigger: Both edges of the IIO0\_0 pin
- Intelligent I/O group 0 input pin: Port P1
- Select gating: Gating disabled
- Base timer count source (fBT0): f1 (no division)



#### 3.1 Timing

- (1) When the BT0S bit in the BTSR register is set to 1, the group 0 base timer count starts.
- (2) If a trigger input is applied to the to the IIO0\_0 pin, the interrupt of group 0 time measurement channel 0 (TM00) is generated. The value in the G0TM0 register is read in the interrupt handler. The difference from the value previously read is the measurement time.

Figure 3.2 shows an Operating Example of Pulse-Width Measurement Using the Time Measurement Function.

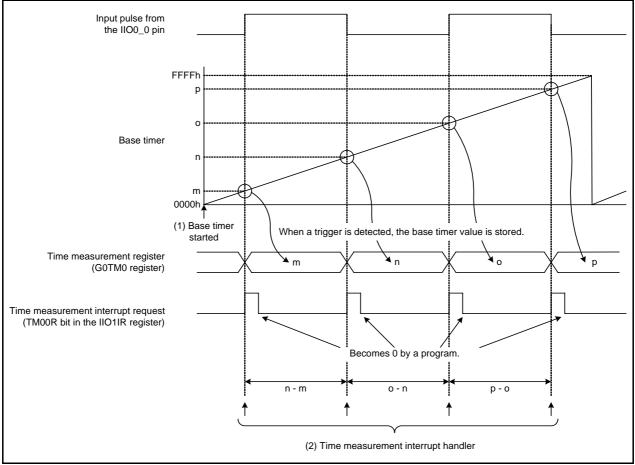


Figure 3.2 Operating Example of Pulse-Width Measurement Using the Time Measurement Function

#### 3.2 Notes on Intelligent I/O

If an interrupt is accepted, the IR bit in the IIOiIC register is automatically set to 0. However, even if an interrupt is accepted, each bit in the IIOiIR register is not automatically set to 0 (i = 0 to 11). They should be set to 0 by either the AND or BCLR instruction. Note that every generated interrupt request is ignored until these bits are set to 0.



#### 3.3 Flowcharts

Figure 3.3 and Figure 3.4 show the Main Function, and Figure 3.5 shows Intelligent I/O Interrupt 1.

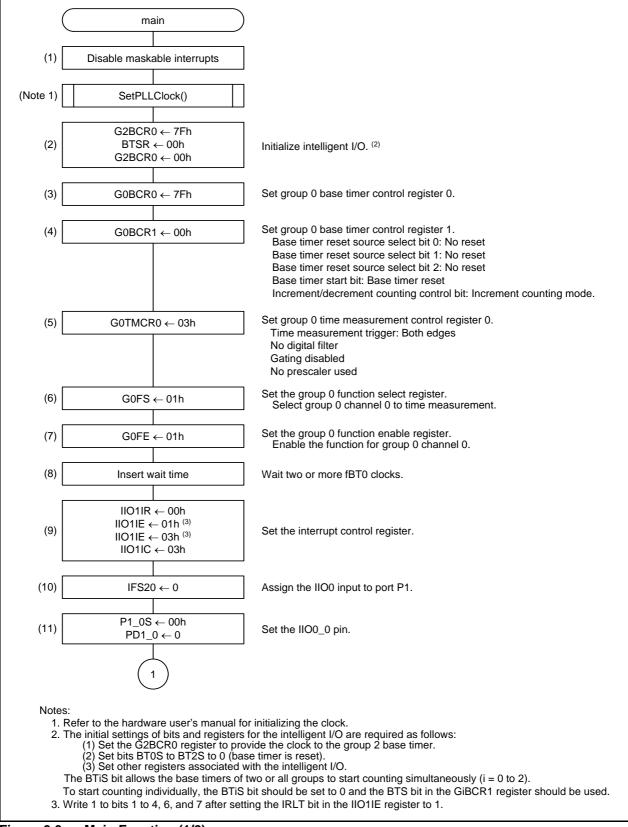


Figure 3.3Main Function (1/2)

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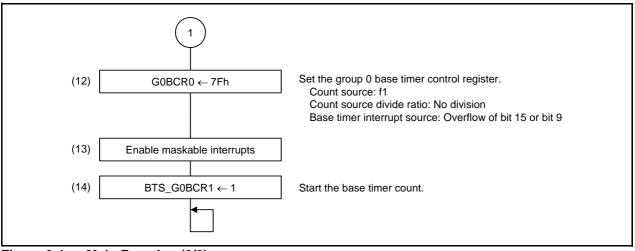


Figure 3.4Main Function (2/2)

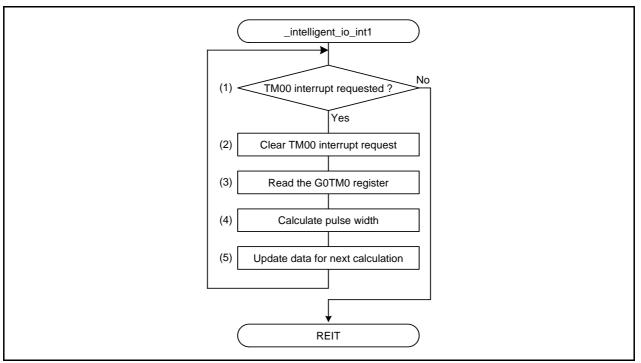


Figure 3.5 Intelligent I/O Interrupt 1



### 4. Sample Program

A sample program can be downloaded from the Renesas Electronics website.

## 5. Reference Documents

User's Manuals R32C/116 Group User's Manual: Hardware Rev.1.00 R32C/117 Group User's Manual: Hardware Rev.1.00 R32C/118 Group User's Manual: Hardware Rev.1.00 The latest versions can be downloaded from the Renesas Electronics website.

Technical Update/Technical News The latest information can be downloaded from the Renesas Electronics website.

C Compiler Manual R32C/100 Series C Compiler Package V.1.02 C Compiler User's Manual Rev.2.00 The latest version can be downloaded from the Renesas Electronics website.

## Website and Support

Renesas Electronics website http://www.renesas.com/

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F	REVISION	HISTORY

### R32C/100 Series Pulse-Width Measurement Using the Time Measurement Function of Intelligent I/O Groups 0 and 1

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		Page	Summary	
1.00	Oct. 30, 2010	-	First edition issued	

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#### General Precautions in the Handling of MPU/MCU Products

The following usage notes are applicable to all MPU/MCU products from Renesas. For detailed usage notes on the products covered by this manual, refer to the relevant sections of the manual. If the descriptions under General Precautions in the Handling of MPU/MCU Products and in the body of the manual differ from each other, the description in the body of the manual takes precedence.

1. Handling of Unused Pins

Handle unused pins in accord with the directions given under Handling of Unused Pins in the manual.

- The input pins of CMOS products are generally in the high-impedance state. In operation with an unused pin in the open-circuit state, extra electromagnetic noise is induced in the vicinity of LSI, an associated shoot-through current flows internally, and malfunctions occur due to the false recognition of the pin state as an input signal become possible. Unused pins should be handled as described under Handling of Unused Pins in the manual.
- 2. Processing at Power-on

The state of the product is undefined at the moment when power is supplied.

- The states of internal circuits in the LSI are indeterminate and the states of register settings and pins are undefined at the moment when power is supplied.
  - In a finished product where the reset signal is applied to the external reset pin, the states of pins are not guaranteed from the moment when power is supplied until the reset process is completed.

In a similar way, the states of pins in a product that is reset by an on-chip power-on reset function are not guaranteed from the moment when power is supplied until the power reaches the level at which resetting has been specified.

3. Prohibition of Access to Reserved Addresses

Access to reserved addresses is prohibited.

- The reserved addresses are provided for the possible future expansion of functions. Do
  not access these addresses; the correct operation of LSI is not guaranteed if they are
  accessed.
- 4. Clock Signals

After applying a reset, only release the reset line after the operating clock signal has become stable. When switching the clock signal during program execution, wait until the target clock signal has stabilized.

- When the clock signal is generated with an external resonator (or from an external oscillator) during a reset, ensure that the reset line is only released after full stabilization of the clock signal. Moreover, when switching to a clock signal produced with an external resonator (or by an external oscillator) while program execution is in progress, wait until the target clock signal is stable.
- 5. Differences between Products

Before changing from one product to another, i.e. to one with a different part number, confirm that the change will not lead to problems.

— The characteristics of MPU/MCU in the same group but having different part numbers may differ because of the differences in internal memory capacity and layout pattern. When changing to products of different part numbers, implement a system-evaluation test for each of the products.

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